

# **RE46C190**

# **CMOS Low Voltage Photoelectric Smoke Detector ASIC with Interconnect and Timer Mode**

#### **Features**

- Two AA Battery Operation
- Internal Power On Reset
- Low Quiescent Current Consumption
- Available in 16L N SOIC
- Local Alarm Memory
- Interconnect up to 40 Detectors
- 9 Minute Timer for Sensitivity Control
- Temporal or Continuous Horn Pattern
- Internal Low Battery and Chamber Test
- All Internal Oscillator
- Internal Infrared Emitter Diode (IRED) driver
- Adjustable IRED Drive current
- Adjustable Hush Sensitivity
- 2% Low Battery Set Point

#### **Description**

The RE46C190 is a low power, low voltage CMOS photoelectric type smoke detector IC. With minimal external components, this circuit will provide all the required features for a photoelectric-type smoke detector.

The design incorporates a gain-selectable photo amplifier for use with an infrared emitter/detector pair.

An internal oscillator strobes power to the smoke detection circuitry every 10 seconds, to keep the standby current to a minimum. If smoke is sensed, the detection rate is increased to verify an Alarm condition. A high gain mode is available for push button chamber testing.

A check for a low battery condition is performed every 86 seconds, and chamber integrity is tested once every 43 seconds, when in Standby. The temporal horn pattern supports the NFPA 72 emergency evacuation signal.

An interconnect pin allows multiple detectors to be connected such that, when one unit alarms, all units will sound.

An internal 9 minute timer can be used for a Reduced Sensitivity mode.

Utilizing low power CMOS technology, the RE46C190 was designed for use in smoke detectors that comply with Underwriters Laboratory Specification UL217 and UL268.

# **PIN CONFIGURATION**



# **TYPICAL BLOCK DIAGRAM**



#### **TYPICAL BATTERY APPLICATION**



- **4:** Schottky diode D1 must have a maximum peak current rating of at least 1.5A. For best results it should have forward voltage specification of less than 0.5V at 1A, and low reverse leakage.
- **5:** Inductor L1 must have a maximum peak current rating of at least 1.5A.

**NOTES:**

## **1.0 ELECTRICAL CHARACTERISTICS**

#### **Absolute Maximum Ratings†**



**† Notice:** Stresses above those listed under "Maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

# <span id="page-4-4"></span>**DC ELECTRICAL CHARACTERISTICS**

**DC Electrical Characteristics:** Unless otherwise indicated, all parameters apply at  $T_A = -10$  to +60°C, V<sub>DD</sub> = 3V, VBST = 4.2V, Typical Application (unless otherwise noted)(**[Note 1](#page-4-0), [Note 2](#page-4-1)**, **[Note 3](#page-4-2)**)



<span id="page-4-1"></span><span id="page-4-0"></span>**Note 1:** Wherever a specific V<sub>BST</sub> value is listed under test conditions, the V<sub>BST</sub> is forced externally with the inductor disconnected and the DC-DC converter NOT running.

**2:** Typical values are for design information only.

<span id="page-4-2"></span>**3:** Limits over the specified temperature range are not production tested and are based on characterization data. Unless otherwise stated, production test is at room temperature with guardbanded limits.

<span id="page-4-3"></span>**4:** Not production tested.

# **DC ELECTRICAL CHARACTERISTICS (CONTINUED)**

**DC Electrical Characteristics:** Unless otherwise indicated, all parameters apply at T<sub>A</sub> = -10 to +60°C, V<sub>DD</sub> = 3V, VBST = 4.2V, Typical Application (unless otherwise noted)(**Note 1, Note 2**, **Note 3**)



**Note 1:** Wherever a specific V<sub>BST</sub> value is listed under test conditions, the V<sub>BST</sub> is forced externally with the inductor disconnected and the DC-DC converter NOT running.

**2:** Typical values are for design information only.

**3:** Limits over the specified temperature range are not production tested and are based on characterization data. Unless otherwise stated, production test is at room temperature with guardbanded limits.

**4:** Not production tested.







**Note 1:** Wherever a specific V<sub>BST</sub> value is listed under test conditions, the V<sub>BST</sub> is forced externally with the inductor disconnected and the DC-DC converter NOT running.

**2:** Typical values are for design information only.

**3:** Limits over the specified temperature range are not production tested and are based on characterization data. Unless otherwise stated, production test is at room temperature with guardbanded limits.

**4:** Not production tested.

# **AC ELECTRICAL CHARACTERISTICS**

AC Electrical Characteristics: Unless otherwise indicated, all parameters apply at  $T_A = -10^\circ$  to +60°C,  $V_{DD} = 3V$ ,  $V_{\text{BST}}$  = 4.2V, Typical Application (unless otherwise noted) (**[Note 1](#page-7-0)** to **[Note 4](#page-7-1)**).



<span id="page-7-0"></span>**Note 1:** See timing diagram for Horn Pattern ([Figure 5-2\)](#page-29-0).

**2:** T<sub>PCLK</sub> and T<sub>IRON</sub> are 100% production tested. All other AC parameters are verified by functional testing.

**3:** Typical values are for design information only.

<span id="page-7-1"></span>**4:** Limits over the specified temperature range are not production tested, and are based on characterization data.

# **AC ELECTRICAL CHARACTERISTICS (CONTINUED)**

**AC Electrical Characteristics:** Unless otherwise indicated, all parameters apply at  $T_A$  = -10° to +60°C, V<sub>DD</sub> = 3V, V<sub>BST</sub> = 4.2V, Typical Application (unless otherwise noted) (Note 1 to Note 4).



**Note 1:** See timing diagram for Horn Pattern (Figure 5-2).

**2:** T<sub>PCLK</sub> and T<sub>IRON</sub> are 100% production tested. All other AC parameters are verified by functional testing.

**3:** Typical values are for design information only.

**4:** Limits over the specified temperature range are not production tested, and are based on characterization data.

# **AC ELECTRICAL CHARACTERISTICS (CONTINUED)**

AC Electrical Characteristics: Unless otherwise indicated, all parameters apply at  $T_A = -10^\circ$  to +60°C, V<sub>DD</sub> = 3V,  $|V_{\text{BST}}| = 4.2V$ , Typical Application (unless otherwise noted) (**Note 1** to **Note 4**).



**Note 1:** See timing diagram for Horn Pattern (Figure 5-2).

**2:** T<sub>PCLK</sub> and T<sub>IRON</sub> are 100% production tested. All other AC parameters are verified by functional testing.

**3:** Typical values are for design information only.

**4:** Limits over the specified temperature range are not production tested, and are based on characterization data.

# **TEMPERATURE CHARACTERISTICS**



# **2.0 PIN DESCRIPTIONS**

The descriptions of the pins are listed in [Table 2-1.](#page-10-0)

<span id="page-10-0"></span>



**NOTES:**

# **3.0 DEVICE DESCRIPTION**

#### **3.1 Standby Internal Timing**

The internal oscillator is trimmed to ±6% tolerance. Once every 10 seconds, the boost converter is powered up, the IRcap is charged from  $V_{BST}$  and then the detection circuitry is active for 10 ms. Prior to completion of the 10 mS period, the IRED pulse is active for a user-programmable duration of 100- 400 µs. During this IRED pulse, the photo diode current is integrated and then digitized. The result is compared to a limit value stored in EEPROM during calibration to determine the photo chamber status. If a smoke condition is present, the period to the next detection decreases, and additional checks are made.

#### <span id="page-12-1"></span>**3.2 Smoke Detection Circuitry**

The digitized photo amplifier integrator output is compared to the stored limit value at the conclusion of the IRED pulse period. The IRED drive is all internal, and both the period and current are user programmable. Three consecutive smoke detections will cause the device to go into Alarm and activate the horn and interconnect circuits. In Alarm, the horn is driven at the high boost voltage level, which is regulated based on an internal voltage reference, and therefore results in consistent audibility over battery life. RLED will turn on for 10 ms at a 2 Hz rate. In Local Alarm, the integration limit is internally decreased to provide alarm hysteresis. The integrator has three separate gain settings:

- Normal and Hysteresis
- Reduced Sensitivity (HUSH)
- High Gain for Chamber Test and Push-to-Test

There are four separate sets of integration limits (all user programmable):

- Normal Detection
- Hysteresis
- HUSH
- Chamber Test and Push-to-Test modes

In addition, there are user selectable integrator gain settings to optimize detection levels (see [Table 4-1\)](#page-14-0).

#### <span id="page-12-2"></span>**3.3 Supervisory Tests**

Once every 86 seconds, the status of the battery voltage is checked by enabling the boost converter for 10 ms and comparing a fraction of the  $V_{DD}$  voltage to an internal reference. In each period of 344 seconds, the battery voltage is checked four times. Three checks are unloaded and one check is performed with the RLED enabled, which provides a battery load. The High Boost mode is active only for the loaded low battery test. In addition, once every 43 seconds the chamber is activated and a High Gain mode and chamber test limits are internally selected. A check of the chamber is made by amplifying background reflections. The Low Boost mode is used for the chamber test.

If either the low battery test or the chamber test fails, the horn will pulse on for 10 ms every 43 seconds, and will continue to pulse until the failing condition passes. If two consecutive chamber tests fail, the horn will pulse on three times for 10 ms, separated by 330 ms every 43 seconds. Each of the two supervisory test audible indicators is separated by approximately 20 seconds.

As an option, a Low Battery Silence mode can be invoked. If a low battery condition exists, and the TEST input is driven high, the RLED will turn on. If the TEST input is held for more than 0.5 second, the unit will enter the Push-to-test operation described in **[Section 3.4 "Push-to-Test Operation \(PTT\)"](#page-12-0)**. After the TEST input is driven low, the unit enters in Low Battery Hush mode, and the 10 ms horn pulse is silenced for 8 hours. The activation of the test button will also initiate the 9 minute Reduced Sensitivity mode described in **[Section 3.6 "Reduced Sensitivity](#page-13-0) [Mode"](#page-13-0)**. At the end of the 8 hours, the audible indication will resume if the low battery condition still exists.

#### <span id="page-12-0"></span>**3.4 Push-to-Test Operation (PTT)**

If the TEST input pin is activated  $(V_{H})$ , the smoke detection rate increases to once every 250 ms after one internal clock cycle. In Push-to-Test, the photo amplifier High Gain mode is selected, and background reflections are used to simulate a smoke condition. After the required three consecutive detections, the device will go into a Local Alarm condition. When the TEST input is driven low  $(V_{|L})$ , the photo amplifier Normal Gain is selected, after one clock cycle. The detection rate continues at once every 250 ms until three consecutive No Smoke conditions are detected. At this point, the device returns to standby timing. In addition, after the TEST input goes low, the device enters the HUSH mode (see **[Section 3.6 "Reduced](#page-13-0) [Sensitivity Mode"](#page-13-0)**).

#### **3.5 Interconnect Operation**

The bidirectional IO pin allows the interconnection of multiple detectors. In a Local Alarm condition, this pin is driven high (High Boost) immediately through a constant current source. Shorting this output to ground will not cause excessive current. The IO is ignored as input during a Local Alarm.

The IO pin also has an NMOS discharge device that is active for 1.3 seconds after the conclusion of any type of Local Alarm. This device helps to quickly discharge any capacitance associated with the interconnect line.

If a remote, active high signal is detected, the device goes into Remote Alarm and the horn will be active. RLED will be off, indicating a Remote Alarm condition. Internal protection circuitry allows the signaling unit to have a higher supply voltage than the signaled unit, without excessive current draw.

The interconnect input has a 336 ms nominal digital filter. This allows the interconnection to other types of alarms (carbon monoxide, for example) that may have a pulsed interconnect signal.

#### <span id="page-13-0"></span>**3.6 Reduced Sensitivity Mode**

A Reduced Sensitivity or Hush mode is initiated by activating the TEST input  $(V_{H})$ . If the TEST input is activated during a Local Alarm, the unit is immediately reset out of the alarm condition, and the horn is silenced. When the TEST input is deactivated  $(V_{II})$ , the device enters into a 9-minute nominal Hush mode. During this period, the HUSH integration limit is selected. The hush gain is user programmable. In Reduced Sensitivity mode, the RLED flashes for 10 ms every 10 seconds to indicate that the mode is active. As an option, the Hush mode will be cancelled if any of the following conditions exist:

- Reduced sensitivity threshold is exceeded (high smoke level)
- An interconnect alarm occurs
- TEST input is activated again

#### **3.7 Local Alarm Memory**

An Alarm Memory feature allows easy identification of any unit that had previously been in a Local Alarm condition. If a detector has entered a Local Alarm, when it exits that Local Alarm, the Alarm Memory latch is set. Initially the GLED can be used to visually identify any unit that had previously been in a Local Alarm condition. The GLED flashes three times spaced 1.3 seconds apart. This pattern will repeat every 43 seconds. The duration of the flash is 10 ms. In order to preserve battery power, this visual indication will stop after a period of 24 hours. The user will still be able to identify a unit with an active alarm memory by pressing the Push-to-Test button. When this button is active, the horn will chirp for 10 ms every 250 ms.

If the Alarm Memory condition is set, then any time the Push-to-Test button is pressed and released, the Alarm Memory latch is reset.

The initial 24 hour visual indication is not displayed if a low battery condition exists.

#### **3.8 End of Life Indicator**

As an option, after every 14 days of continuous operation, the device will read a stored age count from the EEPROM and increment this count. After 10 years of powered operation, an audible warning will occur indicating that the unit should be replaced. This indicator will be similar to the chamber test failure warning in that the horn will pulse on three times for 10 ms separated by 330 ms every 43 seconds. This indicator will be separated from the low battery indicator by approximately 20 seconds.

#### <span id="page-13-1"></span>**3.9 Photo Chamber Long Term Drift Adjustment**

As an option, the design includes a Long Term Drift Adjustment for the photo chamber. If this option is selected, during calibration a normal no-smoke baseline integration measurement is made and stored in EEPROM. During normal operation, a new baseline is calculated by making 64 integration measurements over a period of 8 hours. These measurements are averaged and compared to the original baseline stored during calibration to calculate the long term drift. All four limits stored during calibration are adjusted by this drift factor. Drift sampling is suspended during Hush, Local Smoke and Remote Smoke conditions.

# **4.0 USER PROGRAMMING MODES**

#### <span id="page-14-0"></span>**TABLE 4-1: PARAMETRIC PROGRAMMING**



**Note 1:** GF is the user selectable Photo Integration Gain Factor. Once selected, it applies to all modes of operation. For example, if  $GF = 1$  and integration time is selected to be 100  $\mu s$ , the ranges will be as follows: Normal/Hysteresis = 58 nA, Hush = 116 nA, Chamber Test = 29 nA.

**2:** Nominal measurement resolution in each case will be 1/31 of the maximum input range.

**3:** The same current resolution and ranges applies to the limits.

#### **TABLE 4-2: FEATURES PROGRAMMING**



#### **4.1 Calibration and Programming Procedures**

Eleven separate programming and test modes are available for user customization. To enter these modes, after power-up, TEST2 must be driven to  $V_{DD}$  and held at that level. The TEST input is then clocked to step through the modes. FEED and IO are reconfigured to become test mode inputs, while RLED, GLED and HB become test mode outputs. The test mode functions for each pin are outlined in [Table 4-3](#page-15-0).

When TEST2 is held at  $V_{DD}$ , TEST becomes a tri-state input with nominal input levels at  $V_{SS}$ ,  $V_{DD}$  and  $V_{BST}$ . A TEST clock occurs whenever the TEST input switches from  $V_{SS}$  to  $V_{BST}$ . The TEST Data column represents the state of TEST when used as a data input, which would be either  $V_{SS}$  or  $V_{DD}$ . The TEST pin can therefore be used as both a clock, to change modes, and a data input, once a mode is set. Other pin functions are described in **[Section 4.2 "User](#page-16-0) [Selections"](#page-16-0)**.



<span id="page-15-0"></span>

<span id="page-15-3"></span><span id="page-15-2"></span>**Note 1:** SmkComp (HB) – digital comparator output (high if Gamp < IntegOut; low if Gamp > IntegOut)

**2:** SCMP (HB) – digital output representing comparison of measurement value and associated limit. Signal is valid only after MeasEn has been asserted and measurement has been made. (SCMP high if measured value > limit; low if measured value < limit).

<span id="page-15-1"></span>**3:** LatchLim (IO) – digital input used to latch present state of limits (Gamp level) for later storage. T1-T4 limits are latched, but not stored until ProgEn is asserted in T5 mode.

<span id="page-15-4"></span>**4:** Operating the circuit in this manner with nearly continuous IRED current for an extended period of time may result in undesired or excessive heating of the part. The duration of this step should be minimized.

#### <span id="page-16-0"></span>**4.2 User Selections**

Prior to smoke calibration, the user must program the functional options and parametric selections. This requires that 14 bits, representing selected values, be clocked in serially using TEST as a data input and FEED as a clock input, and then be stored in the internal EEPROM.

The detailed steps are as follows:

<span id="page-16-2"></span>1. Power up with bias conditions as shown in [Figure 4-1.](#page-16-1) At power-up TEST = TEST2 = FEED =  $10 = V_{SS}$ .

<span id="page-16-1"></span>

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- 2. Drive TEST2 input from  $\mathrm{V_{SS}}$  to  $\mathrm{V_{DD}}$  and hold at V<sub>DD</sub> through <mark>Step [5](#page-19-0)</mark> below.
- 3. Using TEST as data and FEED as clock, shift in values as selected from [Register 4-1.](#page-17-0)

**Note:** For test mode T0 only 14 bits (bits 25-38) will be loaded. For test mode T6 all 39 bits (bits 0-38), will be loaded.

#### <span id="page-17-0"></span>**REGISTER 4-1: CONFIGURATION AND CALIBRATION SETTINGS REGISTER**





e<br>B

#### **REGISTER 4-1: CONFIGURATION AND CALIBRATION SETTINGS REGISTER (CONTINUED)**



The minimum pulse width for FEED is 10 µs, while the minimum pulse width for TEST is 100 µs. For example, for the following options, the sequence would be:

data - 0 0 0 1 1 0 0 0 1 0 0 0 0 1 bit - 25 26 27 28 29 30 31 32 33 34 35 36 37 38 Photo Amp Gain Factor = 1 Integration Time  $= 200 \text{ }\mu\text{s}$ IRED Current = 100 mA Low Battery Trip  $= 2.2V$ Long Term Drift, Low Battery Hush and EOL are all disabled Hush Option = Never Cancel Tone Select = Temporal

4. After shifting in data, pull IO input to  $V_{DD}$ , then  $V_{SS}$  (minimum pulse width of 10 ms) to store shift register contents into the memory.

<span id="page-19-0"></span>5. If any changes are required, power down the part and return to Ste[p 1.](#page-16-2) All bit values must be reentered.



*FIGURE 4-2: Timing Diagram for Mode T0.*

As an alternative to [Figure 4-1,](#page-16-1) [Figure 4-3](#page-20-0) can be used to program while in the application circuit. Note that in addition to the five programming supplies, connections to  $V_{SS}$  are needed at TP1 and TP2.



<span id="page-20-0"></span>*FIGURE 4-3: Circuit for Programming in the Typical Application.*

#### <span id="page-21-2"></span>**4.3 Smoke Calibration**

A separate calibration mode is entered for each measurement mode (Normal, Hysteresis, Hush and Chamber Test) so that independent limits can be set for each. In all calibration modes, the integrator output can be accessed at the GLED output.

The Gamp output voltage, which represents the smoke detection level, can be accessed at the RLED output. The SmkComp output voltage is the result of the comparison of Gamp with the integrator output, and can be accessed at HB. The FEED input can be clocked to step up the smoke detection level at RLED. Once the desired smoke threshold is reached, the TEST input is pulsed low to high to store the result.

The procedure is described in the following steps:

- 1. Power up with the bias conditions shown in [Figure 4-1.](#page-16-1)
- 2. Drive TEST2 input from  $V_{SS}$  to  $V_{DD}$  to enter the Programming mode. TEST2 should remain at  $V<sub>DD</sub>$  through Step [8](#page-21-1) described below.
- <span id="page-21-0"></span>3. Apply a clock pulse to the TEST input to enter in T1 mode. This initiates the calibration mode for Normal Limits setting. The Integrator output saw tooth should appear at GLED and the smoke detection level at RLED. Clock FEED to increase the smoke detection level as needed. Once the desired smoke threshold is reached, the IO input is pulsed low to high to enter the result. See typical waveforms in [Figure 4-4](#page-22-0). Operating the circuit in this manner, with nearly continuous IRED current for an extended period of time, may result in undesired or excessive heating of the part. The duration of this step should be minimized.
- 4. Apply a second clock pulse to the TEST input to enter in T2 mode. This initiates the calibration mode for Hysteresis Limits. Clock FEED as in Ste[p 3](#page-21-0) and apply pulse to IO, once desired level is reached.Operating the circuit in this manner, with nearly continuous IRED current for an extended period of time, may result in undesired or excessive heating of the part. The duration of this step should be minimized.
- 5. Apply a clock pulse to the TEST input again to enter in T3 mode and initiate calibration for Hush Limits. Clock FEED as in the steps above and apply a pulse to IO, once the desired level is reached. Operating the circuit in this manner, with nearly continuous IRED current for an extended period of time, may result in undesired or excessive heating of the part. The duration of this step should be minimized.
- 6. Apply a clock pulse to the TEST input a fourth time to enter in T4 mode, and initiate the calibration for Chamber Test Limits. Clock FEED and apply pulse to IO, once desired level is reached. Operating the circuit in this manner, with nearly continuous IRED current for an extended period of time, may result in undesired or excessive heating of the part. The duration of this step should be minimized.
- 7. If the Long Term Drift Adjustment is enabled, after all limits have been set, the long term drift (LTD) baseline measurement must be made. To do this, a measurement must be made under no-smoke conditions. To enable the baseline measurement, pull TEST from  $V_{SS}$  to  $V_{BST}$ again and return to  $V_{SS}$ . Once the chamber is clear, pulse FEED low to high to make the baseline measurement.
- <span id="page-21-1"></span>8. After limits have been set and baseline LTD measurement has been made, pulse IO to store all results in memory. Before this step, no limits are stored in memory.

<span id="page-22-0"></span>

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#### **4.4 Serial Read/Write**

As an alternative to the steps in **[Section 4.3 "Smoke](#page-21-2) [Calibration"](#page-21-2)**, if the system has been well characterized, the limits and baseline can be entered directly from a serial read/write calibration mode.

To enter this mode, follow these steps:

- 1. Set up the application as shown in [Figure 4-1.](#page-16-1)
- 2. Drive TEST2 input from  $V_{SS}$  to  $V_{DD}$  to enter in Programming mode. TEST2 should remain at  $V_{DD}$  until all data has been entered.
- 3. Clock the TEST input to mode T6 (High =  $V_{BST}$ , Low =  $V_{SS}$ , 6 clocks). This enables the serial read/write mode.
- 4. TEST now acts as a data input (High =  $V_{DD}$ , Low =  $V_{SS}$ ). FEED acts as the clock input (High =  $V_{\text{BST}}$ , Low =  $V_{\text{SS}}$ ). Clock in the limits, LTD baseline, functional and parametric options. The data sequence should be as follows:
- 5 bit LTD sample (LSB first)
- 5 bit Chamber Test Limits (LSB first)
- 5 bit Hush Limits (LSB first)
- 5 bit Hysteresis Limits (LSB first),

5 bit Normal Limits (LSB first)

Then, the data sequence follows the pattern described in [Register 4-1](#page-17-0):

- 2 bit Photo Amp Gain Factor 2 bit Integration Time 2 bit IRED current 3 bit Low Battery Trip Point 1 bit Long Term Drift Enable 1 bit Hush Option 1 bit Low Battery Hush Enable
- 1 bit EOL enable
- 1 bit Tone Select

A serial data output is available at HB.

5. After all 39 bits have been entered, pulse IO to store into the EEPROM memory.





*FIGURE 4-5: Timing Diagram for Mode T6.*

#### **4.5 Limits Verification**

After all limits and LTD baseline have been entered and stored into the memory, additional test modes are available to verify if the limits are functioning as expected. [Table 4-4](#page-24-0) describes several verification tests.

#### <span id="page-24-0"></span>**TABLE 4-4: LIMITS VERIFICATION DESCRIPTION**





#### **4.6 Horn Test**

The last test mode allows the horn to be enabled indefinitely for audibility testing. To enter this mode, clock TEST to Mode T11 (11 clocks). The IO pin is configured as horn enable.



# **5.0 APPLICATION NOTES**

#### **5.1 Standby Current Calculation and Battery Life**

The supply current shown in the **[DC Electrical](#page-4-4) [Characteristics](#page-4-4)** table is only one component of the average standby current and, in most cases, can be a small fraction of the total, because power consumption generally occurs in relatively infrequent bursts and depends on many external factors. These include the values selected for IRED current and integration time, the  $V_{\text{BST}}$  and IR capacitor sizes and leakages, the  $V_{\text{BAT}}$ level, and the magnitude of any external resistances that will adversely affect the boost converter efficiency.

A calculation of the standby current for the battery life is shown in [Table 5-1](#page-26-0), based on the following parameters:





#### <span id="page-26-0"></span>**TABLE 5-1: STANDBY CURRENT CALCULATION**

The following paragraphs explain the components in [Table 5-1,](#page-26-0) and the calculations in the example.

#### 5.1.1  $FIXED I<sub>DD</sub>$

The I<sub>DD</sub> is the Supply Current shown in the [DC](#page-4-4) **[Electrical Characteristics](#page-4-4)** table.

#### 5.1.2 PHOTO DETECTION CURRENT

Photo Detection Current is the current draw due to the smoke testing every 10.75 seconds, and the chamber test every 43 seconds. The current for both the IR diode and the internal measurement circuitry comes primarily from  $V_{\text{BST}}$ , so the average current must be scaled for both on-time and boost voltage.

The contribution to  $I_{BAT}$  is determined by first calculating the energy consumed by each component, given its duration. An average power is then calculated based on the period of the event and the boost converter efficiency (assumed to be 85% in this case). An  $I<sub>BAT</sub>$  contribution is then calculated based on this average power and the given  $V_{BAT}$ . For example, the IR drive contribution during chamber test is detailed in [Equation 5-1:](#page-26-1)

#### <span id="page-26-1"></span>**EQUATION 5-1:**

 $\frac{3.6V \times 0.1A \times 200 \mu s}{43s \times 0.85 \times 3V} = 0.657 \mu A$ 

#### 5.1.3 LOW BATTERY CHECK CURRENT

The Low Battery Check Current is the current required for the low battery test. It includes both the loaded (RLED on) and unloaded (RLED Off) tests. The boost component of the loaded test represents the cost of charging the boost capacitor to the higher voltage level. This has a fixed cost for every loaded check, because the capacitor is gradually discharged during subsequent operations, and the energy is generally not recovered. The other calculations are similar to those shown in [Equation 5-1](#page-26-1). The unloaded test has a minimal contribution because it involves only some internal reference and comparator circuitry.

#### 5.1.4 BATTERY LIFE

When estimating the battery life, several additional factors must be considered. These include battery resistance, battery self discharge rate, capacitor leakages and the effect of the operating temperature on all of these characteristics. Some number of false alarms and user tests should also be included in any calculation.

For ten year applications, a 3V spiral wound lithium manganese dioxide battery with a laser seal is recommended. These can be found with capacities of 1400 to 1600 mAh.

#### 5.1.5 FUNCTIONAL TIMING DIAGRAMS



*FIGURE 5-1: RE46C190 Timing Diagram – Standby, No Alarm, Low Supply Test Failure and Chamber Test Failure.*



<span id="page-29-0"></span>*FIGURE 5-2: RE46C190 Timing Diagram – Local Alarm with Temporal Horn Pattern, Local Alarm with International Horn Pattern, Interconnect as Input with Temporal Horn Pattern and Interconnect as Input with International Horn Pattern.*



**NOTES:**

# **6.0 PACKAGING INFORMATION**

# **6.1 Package Marking Information**

16-Lead SOIC (.150")



Example





#### 16-Lead Plastic Small Outline (SL) - Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging





Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. § Significant Characteristic.

3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.

4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-108B

16-Lead Plastic Small Outline (SL) - Narrow, 3.90 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



# RECOMMENDED LAND PATTERN



Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2108A

**NOTES:**

# **APPENDIX A: REVISION HISTORY**

# **Revision A (December 2010)**

• Original Release of this Document.

**NOTES:**

# **PRODUCT IDENTIFICATION SYSTEM**

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.



**NOTES:**

#### **Note the following details of the code protection feature on Microchip devices:**

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
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