Rugged Incremental 50-mm-dia. Rotary Encoder

# E6C3-C

CE

# **Durable and Easy to Use**

- Sealed bearings with IP65 oil resistance.
- Superior shaft loading performance. Radial: 80 N, Thrust: 50 N



Be sure to read *Safety Precautions* on page 4.

# **Ordering Information**

# Encoders [Refer to Dimensions on page 4.]

| Power supply voltage | Output configuration | Resolution<br>(pulses/rotation) |        |       | Connection method   | Model   |
|----------------------|----------------------|---------------------------------|--------|-------|---|---|
| 12 to 24 VDC         | Complementary output | 100,                            | 200,   |       | E6C3-CWZ5GH (resolution) 1M   Example: E6C3-CWZ5GH 100P/R 1M   Pre-wired (1 m)   (See note.)   E6C3-CWZ3EH (resolution) 1M   Example: E6C3-CWZ3EH 100P/R 1M |   |
|                      |                      | 300,                            | 360,   | 500   |   |   |
|                      |                      | 600,                            | 720,   | 800   |   | E6C3-CWZ5GH (resolution) 1M                                   |
|                      |                      | 1,000,                          | 1,024, | 1,200 |   | Example: E6C3-CWZ5GH 100P/R 1M                                |
|                      |                      | 1,500,                          | 1,800, | 2,000 |   |   |
|                      |                      | 2,048,                          | 2,500, | 3,600 |   |   |
| 5 to 12 VDC          | Voltage output       | 100,                            | 200    |       |   | E6C3-CWZ3EH (resolution) 1M                                   |
|                      |                      | 300,                            | 360,   | 500   |   |   |
|                      |                      | 600,                            | 720,   | 800   |   |   |
|                      |                      | 1,000,                          | 1,024, | 1,200 |   | Example: E6C3-CWZ3EH 100P/R 1M                                |
|                      |                      | 1,500,                          | 1,800, | 2,000 |   |   |
|                      |                      | 2,048,                          | 2,500, | 3,600 |   |   |
| 5 to 12 VDC          | Line-driver output   | 100,                            | 200,   |       |   |   |
|                      |                      | 300,                            | 360,   | 500   |   |   |
|                      |                      | 600,                            | 720,   | 800   |   | E6C3-CWZ3XH (resolution) 1M<br>Example: E6C3-CWZ3XH 100P/R 1M |
|                      |                      | 1,000,                          | 1,024, | 1,200 |   |   |
|                      |                      | 1,500,                          | 1,800, | 2,000 |   |   |
|                      |                      | 2,048,                          | 2,500, | 3,600 |   |   |

Note: Models with 2-m cable are also available. When ordering, specify the cable length at the end of the model number (example: E6C3-CWZ5GH 300P/R 2M).

# Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

| Name                   | Model                                       | Remarks                                |  |
|------------------------|---|--|--|
| Couplings              | E69-C08B                                    |  |  |
| Coupings               | E69-C68B Different end diameter (6 to 8 mm) |  |  |
| Flanges                | E69-FCA03                                   |  |  |
| i langes               | E69-FCA04                                   | E69-2 Servo Mounting Bracket provided. |  |
| Servo Mounting Bracket | E69-2                                       | Provided with E69-FCA04 Flange.        |  |

Refer to Accessories for details.

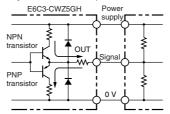
# E6C3-0

# **Ratings and Specifications**

| Item                          | Model  | E6C3-CWZ5GH  | E6C3-CWZ3EH   | E6C3-CWZ3XH  |  |  |  |  |  |
|-------------------------------|--|--|---|--|--|--|--|--|--|
| Power supply voltage          |  | 12 VDC –10% to 24 VDC +15%,<br>ripple (p-p): 5% max.   | 5 VDC –5% to 12 VDC +10%, ripple (p-p): 5% max.                                       |  |  |  |  |  |  |
| Current consum                | ption*1  | 100 mA max.  |   |  |  |  |  |  |  |
| <b>Resolution (puls</b>       | ses/rotation)  | 100, 200, 300, 360, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000, 2,048, 2,500, 3,600                      |   |  |  |  |  |  |  |
| Output phases                 |  | Phases A, B, and Z*5   | Phases A, $\overline{A}$ , B, $\overline{B}$ , Z, and $\overline{Z}$                  |  |  |  |  |  |  |
| Output configuration          |  | Complementary outputs*2  | Voltage output (NPN output)   | Line driver output*3   |  |  |  |  |  |
| Output capacity               |  | Output voltage: VH = Vcc = 3 V min.<br>(IO = 30 mA)<br>VL = 2 V max.<br>(IO = -30 mA)<br>Output current: ±30 mA            | Output resistance: 2 kΩ<br>Output current: 35 mA max.<br>Residual voltage: 0.7 V max. | $\begin{array}{l} \mbox{AM26LS31 equivalent} \\ \mbox{Output current:} & \mbox{High level:} IO = -10 \mbox{ mA} \\ \mbox{Low level:} IS = 10 \mbox{ mA} \\ \mbox{Output voltage:} VO = 2.5 \mbox{V min.} \\ \mbox{VS} = 0.5 \mbox{V max.} \end{array}$ |  |  |  |  |  |
| Maximum respo<br>frequency*4  |  | 125 kHz (65 kHz when using phase Z reset)  |   |  |  |  |  |  |  |
| Phase difference outputs      | e between  | $90^{\circ}\pm45^{\circ}$ between A and B (1/4 T $\pm$ 1/8 T)  |   |  |  |  |  |  |  |
| Rise and fall times of output |  | 1 μs max.<br>(Cable length: 2 m, Output current: 30 mA)  | 1 μs max.<br>(Cable length: 2 m, Output current: 35<br>mA)                            | 1 μs max.<br>(Cable length: 2 m, IO: –10 mA,<br>IS: 10 mA)   |  |  |  |  |  |
| Starting torque 10 n          |  | 10 mN·m max. at room temperature, 30 mN·m max. at low temperature  |   |  |  |  |  |  |  |
| Moment of inert               | ia   | $2.0 \times 10^{-6}$ kg·m <sup>2</sup> max.; $1.9 \times 10^{-6}$ kg·m <sup>2</sup> max. at 500 P/R max.                   |   |  |  |  |  |  |  |
| Shaft loading                 | Radial   | 80 N   |   |  |  |  |  |  |  |
| onarcioading                  | Thrust   | 50 N   |   |  |  |  |  |  |  |
| Maximum permi                 |  | 000 r/min  |   |  |  |  |  |  |  |
| Protection circuits           |  | Power supply reverse polarity protection, Output load short-circuit protection   |   |  |  |  |  |  |  |
| Ambient temper                |  |  |   |  |  |  |  |  |  |
|                               | thumidity range Operating/Storage: 35% to 85% (with no condensation) |  |   |  |  |  |  |  |  |
| Insulation resist             |  | 20 M $\Omega$ min. (at 500 VDC) between current-carrying parts and case  |   |  |  |  |  |  |  |
| Dielectric streng             |  | 500 VAC, 50/60 Hz for 1 min between current-carrying parts and case  |   |  |  |  |  |  |  |
| Vibration resista             |  | Destruction: 10 to 500 Hz, 150 m/s <sup>2</sup> or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions |   |  |  |  |  |  |  |
| Shock resistance              | -  | Destruction: 1,000 m/s <sup>2</sup> 3 times each in X, Y, and Z directions   |   |  |  |  |  |  |  |
| • •                           | gree of protection IEC 60529 IP65, in-house standards: oilproof      |  |   |  |  |  |  |  |  |
| Connection met                |  |  |   |  |  |  |  |  |  |
| Material                      |  |  |   |  |  |  |  |  |  |
| Weight (packed                | state)   | Approx. 300 g  |   |  |  |  |  |  |  |
| Accessories                   | Accessories Instruction manual                                       |  |   |  |  |  |  |  |  |

\*1. An inrush current of approximately 9 A will flow for approximately 0.1 ms when the power is turned ON.

\*2. Complementary Output The complementary output has two output transistors (NPN and PNP) as shown below. These two output transistors alternately turn ON and OFF depending on the high or low output signal. When using them, pull up to the positive power supply voltage level or pull down to 0 V. The complementary output allows flow-in or flow-out of the output current and thus the rising and falling speeds of signals are fast. This allows a long cable distance. They can be connected to open-collector input devices (NPN, PNP)

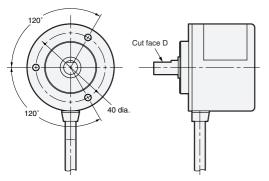


\*3. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. (AM26LS31 equivalent)

\*4. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows: Maximum electrical response speed (rpm) =  $\frac{\text{Maximum response frequency}}{\text{Resolution}} \times 60$ 

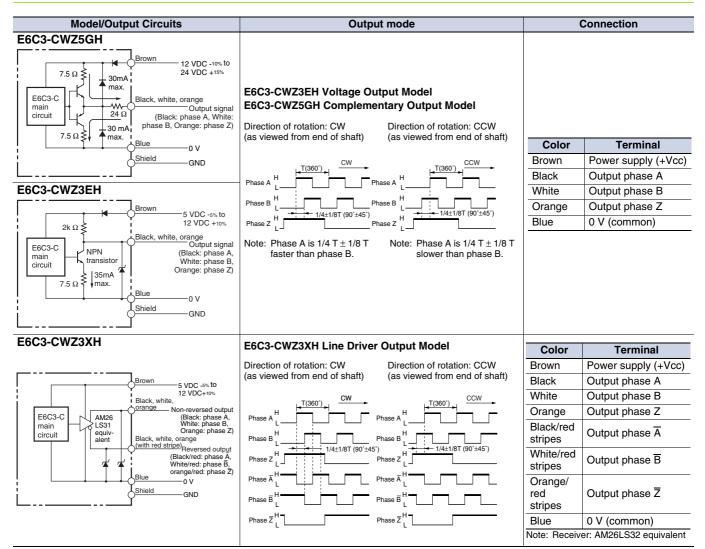
Resolution This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

\*5. The phase Z signal is output when cut face D on the shaft and the cable connection direction are as shown in the following diagram (output position range: ±15°).



# E6C3-C

# I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

2. The phase A, phase B, and phase Z circuits are all identical

3. Normally, connect GND to 0 V or to an external ground.

# **Safety Precautions**

# Refer to Warranty and Limitations of Liability.

# <u> WARNING</u>

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.

## **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

## • Wiring

#### Connections

Cable Extension Characteristics

• When the cable length is extended, the output waveform startup time is lengthened and it affects the phase difference characteristics of phases A and B. Conditions will change according to frequency, noise, and other factors. As a guideline, use a cable length of 10 m\* or less. If the cable must be more than 10 m, use a Model with a Line-driver Output or Complementary Output (max. length for line-driver output: 100 m).

#### \* Recommended Cable Conductor cross section: 0.2 mm<sup>2</sup> Spiral shield

Conductor resistance: 92 Ω/km max. (20°C) Insulation resistance: 5 Ω/km min. (20°C)

- The output waveform startup time changes not only according to the length of the cable, but also according to the load resistance and the cable type.
- Extending the cable length not only changes the startup time, but also increases the output residual voltage.

#### Connection

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

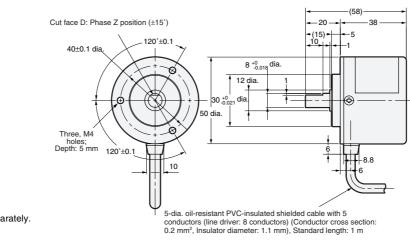
# (Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

## Encoder

#### E6C3-CWZ



The E69-C08B Coupling is sold separately.

## Accessories (Order Separately)

Couplings E69-C08B E69-C68B Flanges E69-FCA03 E69-FCA04

#### Servo Mounting Bracket

E69-2 Refer to *Accessories* for details.

#### **Read and Understand This Catalog**

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

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## OMRON Corporation Industrial Automation Company



#### ООО "ЛайфЭлектроникс"

ИНН 7805602321 КПП 780501001 Р/С 40702810122510004610 ФАКБ "АБСОЛЮТ БАНК" (ЗАО) в г.Санкт-Петербурге К/С 3010181090000000703 БИК 044030703

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