

FEATURES

Low power

Quiescent current per amplifier: 1.0 mA at ± 5 V

Fully specified at +3 V, +5 V, and ± 5 V supplies

High speed and fast settling for ± 5 V

180 MHz, -3 dB bandwidth ($G = +1$, $V_{\text{OUT}} = 20$ mV p-p)

28 MHz, -3 dB bandwidth ($G = +1$, $V_{\text{OUT}} = 2$ V p-p)

225 V/ μs slew rate for 5 V step (rise)

47 ns settling time to 0.1% for 4 V step

Rail-to-rail input and output

Low distortion at ± 5 V (HD2/HD3)

-112 dBc/ -115 dBc at 100 kHz, $V_{\text{OUT}} = 2$ V p-p

-95 dBc/ -79 dBc at 1 MHz, $V_{\text{OUT}} = 2$ V p-p

Low noise

3.1 nV/ $\sqrt{\text{Hz}}$, $f = 100$ kHz

0.7 pA/ $\sqrt{\text{Hz}}$, $f = 100$ kHz

Low input noise voltage 1/f corner: 29 Hz

Low input bias current: -1.2 μA typical

Linear output current: 60 mA (sourcing) for ± 5 V and +5 V

Low input offset voltage: ± 125 μV maximum

Low input offset voltage drift: 3.8 $\mu\text{V}/^\circ\text{C}$ maximum

APPLICATIONS

High speed, battery operated systems

High component density systems

High resolution analog-to-digital converter (ADC) drivers

Portable test instruments

Active filters

GENERAL DESCRIPTION

The ADA4807-1/ADA4807-2 are low power, low noise, rail-to-rail voltage feedback amplifiers with exceptionally high performance. They are designed to have the lowest input noise (3.1 nV/ $\sqrt{\text{Hz}}$ and 0.7 pA/ $\sqrt{\text{Hz}}$) among high speed, rail-to-rail amplifiers in the industry while operating on only 1 mA or less of quiescent supply current, making them ideal for a wide range of applications from battery-powered, portable instrumentation to high speed systems where component density requires lower power dissipation. The ADA4807-1/ADA4807-2 operate over a wide range of supply voltages from ± 1.5 V to ± 5 V, as well as from 3 V to 10 V single supplies, and include a disable feature that allows reduction of the typical quiescent supply current to 2.4 μA or less when asserted.

For systems with high dynamic range signals, the output voltage swings to within 70 mV of each rail, maximizing the output dynamic range, and the full, rail-to-rail input stage permits input operation up to and beyond the supply rails.

PIN CONNECTION DIAGRAMS

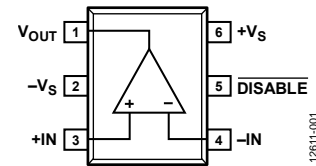


Figure 1. 6-Lead SC70 and 6-Lead SOT-23

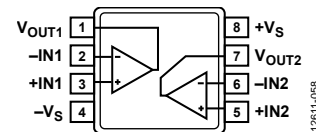


Figure 2. 8-Lead MSOP Pin Configuration

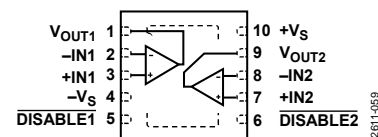


Figure 3. 10-Lead LFCSP Pin Configuration

The ADA4807-1/ADA4807-2 feature high speed performance of 180 MHz small signal -3 dB bandwidth, a 225 V/ μs slew rate, and a settling time of 47 ns to 0.1% (4 V step) with a low input offset voltage of ± 20 μV and 0.7 $\mu\text{V}/^\circ\text{C}$ drift. For ± 5 V supplies, the HD2 is -112 dBc and HD3 is -115 dBc for a 2 V p-p, 100 kHz output signal driving a 1 k Ω load. The low distortion and fast settling time make these amplifiers ideal for driving high speed single-supply precision ADCs with up to 18-bit resolution. The ADA4807-1/ADA4807-2 deliver this excellent performance while consuming 1 mA or less of quiescent current.

The ADA4807-1 (single) is available in space-saving 6-lead SC70 and 6-lead SOT-23 packages. The ADA4807-2 (dual) is available in 10-lead LFCSP and 8-lead MSOP packages. The ADA4807-1/ADA4807-2 operate over the -40°C to $+125^\circ\text{C}$ industrial temperature range.

Table 1. Other Rail-to-Rail Amplifiers

Device	Bandwidth (MHz)	Slew Rate (V/ μs)	Voltage Noise (nV/ $\sqrt{\text{Hz}}$)	Max V_{OS} (mV)
AD8031/AD8032	80	35	15	1.5
AD8027/AD8028	190	90	4.3	0.8
AD8029/AD8030	125	62	16.5	5.0

Rev. A

Document Feedback

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TABLE OF CONTENTS

Features 1

Applications..... 1

General Description 1

Functional Block Diagrams..... 1

Revision History 2

Specifications..... 3

 ±5 V Supply 3

 5 V Supply..... 5

 3 V Supply..... 7

Absolute Maximum Ratings..... 9

 Maximum Power Dissipation 9

 Thermal Resistance 9

 ESD Caution..... 9

Pin Configurations and Function Descriptions 10

Typical Performance Characteristics 12

 Frequency Response..... 12

 Frequency and Supply Current..... 14

 DC and Input Common-Mode Performance 15

 Slew, Transient, Settling Time, and Crosstalk..... 16

 Distortion and Noise..... 17

 Output Characteristics..... 18

 Overdrive Recovery and Power-Up/Power-Down 19

Theory of Operation 20

 DISABLE Circuitry 21

 Input Protection 21

 Noise Considerations..... 21

Applications Information 22

 Capacitive Load Drive 22

 Layout, Grounding, and Bypassing..... 22

Outline Dimensions 23

 Ordering Guide 25

REVISION HISTORY

4/15—Rev. 0 to Rev. A

Added ADA4807-2..... Universal

Changes to Features Section, General Description
Section, and Pin Connection Diagrams Heading 1

Added Figure 2 and Figure 3; Renumbered Sequentially 1

Changes to Table 1..... 3

Changes to Table 2..... 5

Changes to Table 3..... 7

Changes to Table 6 and Figure 4..... 9

Added Figure 7, Figure 8, and Table 8; Renumbered
Sequentially 11

Reorganized Layout, Typical Performance Characteristics
Section..... 12

Added Figure 36 16

Changes to Figure 37 Caption, Figure 38 Caption, Figure 39
Caption, and Figure 40 Caption 17

Changes to Figure 44 and Figure 47 18

Change to Theory of Operation Section 20

Changes to DISABLE Circuitry Section, Table 9, and Noise
Considerations Section 21

Added Figure 65 and Figure 66 23

Changes to Ordering Guide 25

12/14—Revision 0: Initial Version

SPECIFICATIONS

±5 V SUPPLY

$T_A = 25^\circ\text{C}$, $V_S = \pm 5\text{ V}$, $R_{\text{LOAD}} = 1\text{ k}\Omega$ to midsupply, $R_F = 0\ \Omega$, $G = +1$, $-V_S \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$, unless otherwise noted.

Table 2.

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
DYNAMIC PERFORMANCE					
-3 dB Bandwidth	$G = +1$, $V_{\text{OUT}} = 20\text{ mV p-p}$		180		MHz
Slew Rate	$G = +1$, $V_{\text{OUT}} = 2\text{ V p-p}$		28		MHz
Settling Time to 0.1%	$G = +1$, $V_{\text{OUT}} = 5\text{ V step}$, 20% to 80%, rise/fall		225/250		V/ μs
	$G = +1$, $V_{\text{OUT}} = 4\text{ V step}$		47		ns
DISTORTION/NOISE PERFORMANCE					
Second Harmonic	$f_c = 1\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-141		dBc
	$f_c = 100\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-112		dBc
	$f_c = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$, ADA4807-1		-95		dBc
	$f_c = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$, ADA4807-2		-84		dBc
Third Harmonic	$f_c = 1\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-144		dBc
	$f_c = 100\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-115		dBc
	$f_c = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-79		dBc
Peak-to-Peak Noise	$f = 0.1\text{ Hz to }10\text{ Hz}$		160		nV p-p
Input Voltage Noise	$f = 100\text{ kHz}$		3.1		nV/ $\sqrt{\text{Hz}}$
	$f = 1\text{ kHz}$		3.3		nV/ $\sqrt{\text{Hz}}$
	$f = 10\text{ Hz}$		5.8		nV/ $\sqrt{\text{Hz}}$
Input Noise Voltage 1/f Corner			29		Hz
Input Current Noise	$f = 100\text{ kHz}$		0.7		pA/ $\sqrt{\text{Hz}}$
	$f = 10\text{ Hz}$		10		pA/ $\sqrt{\text{Hz}}$
Input Current Noise 1/f Corner			2		kHz
DC PERFORMANCE					
Input Offset Voltage	$-V_S \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$	-125	± 20	+125	μV
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$	-750	± 140	+750	μV
Input Offset Voltage Drift	$-V_S \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		0.7	3.7	$\mu\text{V}/^\circ\text{C}$
Input Bias Current	$-V_S \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$		-1.2	-1.6	μA
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$		530	1000	nA
Input Bias Current Drift	$-V_S \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		2.5	3.6	nA/ $^\circ\text{C}$
Input Offset Current	$-V_S \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$		8	100	nA
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$		25	150	nA
Input Offset Current Drift	$-V_S \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		30	250	pA/ $^\circ\text{C}$
Open-Loop Gain		120	130		dB
INPUT CHARACTERISTICS					
Common-Mode Input Resistance			45		M Ω
Differential Input Resistance			35		k Ω
Common-Mode Input Capacitance			1		pF
Differential Input Capacitance			1		pF
Input Common-Mode Voltage Range			$-V_S - 0.2$ to $+V_S + 0.2$		V
Common-Mode Rejection Ratio (CMRR)	$V_{\text{ICM}} = -3\text{ V to }+2\text{ V}$	96	110		dB
DISABLE CHARACTERISTICS¹					
$\overline{\text{DISABLE}}$ Low Input Voltage	Disabled		<1.3		V
$\overline{\text{DISABLE}}$ High Input Voltage	Enabled		>1.7		V
$\overline{\text{DISABLE}}$ Low Input Current	Disabled		-470		nA
$\overline{\text{DISABLE}}$ High Input Current	Enabled		-3		nA

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
$\overline{\text{DISABLE}}$ On Time	$\overline{\text{DISABLE}}$ input midswing point to >90% of final V_{OUT}		1.3		μs
$\overline{\text{DISABLE}}$ Off Time	$\overline{\text{DISABLE}}$ input midswing point to <10% of enabled quiescent current		850		ns
OUTPUT CHARACTERISTICS					
Saturated Output Voltage Swing					
High	$R_{\text{LOAD}} = 1 \text{ k}\Omega$	$+V_S - 0.08$	$+V_S - 0.04$		V
Low		$-V_S + 0.1$	$-V_S + 0.07$		V
Linear Output Current	Sourcing		60		mA
	Sinking		50		mA
Short-Circuit Current	Sourcing		80		mA
	Sinking		76		mA
Capacitive Load Drive	$C_{\text{LOAD}} = 15 \text{ pF}$		17		% overshoot
POWER SUPPLY					
Operating Range		2.7		11	V
Quiescent Current per Amplifier	Enabled, no load, $T_A = 25^\circ\text{C}$		1.0	1.1	mA
	Disabled, $T_A = 25^\circ\text{C}$		2.4	4.0	μA
Power Supply Rejection Ratio (PSRR)					
Positive	$+V_S = 3 \text{ V to } 5 \text{ V}, -V_S = -5 \text{ V}$	98	107		dB
Negative	$+V_S = 5 \text{ V}, -V_S = -3 \text{ V to } -5 \text{ V}$	98	120		dB

¹ The disable pin is $\overline{\text{DISABLE}}$ on the [ADA4807-1](#) and $\overline{\text{DISABLE1}}$ or $\overline{\text{DISABLE2}}$ for the [ADA4807-2](#) LFCSP package, hereafter referred to as $\overline{\text{DISABLE}}$ for the [ADA4807-1/ADA4807-2](#).

5 V SUPPLY

$T_A = 25^\circ\text{C}$, $V_S = 5\text{ V}$, $R_{\text{LOAD}} = 1\text{ k}\Omega$ to midsupply, $R_F = 0\ \Omega$, $G = +1$, $0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$, unless otherwise noted.

Table 3.

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
DYNAMIC PERFORMANCE					
-3 dB Bandwidth	$G = +1$, $V_{\text{OUT}} = 20\text{ mV p-p}$		170		MHz
	$G = +1$, $V_{\text{OUT}} = 2\text{ V p-p}$		28		MHz
Slew Rate	$G = +1$, $V_{\text{OUT}} = 2\text{ V step}$, 20% to 80%, rise/fall		145/160		V/ μs
Settling Time to 0.1%	$G = +1$, $V_{\text{OUT}} = 2\text{ V step}$		40		ns
DISTORTION/NOISE PERFORMANCE					
Second Harmonic					
	$f_C = 1\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-149		dBc
	$f_C = 100\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-111		dBc
	$f_C = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$, ADA4807-1		-93		dBc
	$f_C = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$, ADA4807-2		-83		dBc
Third Harmonic					
	$f_C = 1\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-153		dBc
	$f_C = 100\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-115		dBc
	$f_C = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-78		dBc
Peak-to-Peak Noise	$f = 0.1\text{ Hz to }10\text{ Hz}$		160		nV p-p
Input Voltage Noise					
	$f = 100\text{ kHz}$		3.1		nV/ $\sqrt{\text{Hz}}$
	$f = 1\text{ kHz}$		3.3		nV/ $\sqrt{\text{Hz}}$
	$f = 10\text{ Hz}$		5.8		nV/ $\sqrt{\text{Hz}}$
Input Noise Voltage 1/f Corner			29		Hz
Input Current Noise	$f = 100\text{ kHz}$		0.7		pA/ $\sqrt{\text{Hz}}$
	$f = 10\text{ Hz}$		10		pA/ $\sqrt{\text{Hz}}$
Input Current Noise 1/f Corner			2		kHz
DC PERFORMANCE					
Input Offset Voltage					
	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$	-125	± 20	+125	μV
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$	-720	± 110	+720	μV
Input Offset Voltage Drift					
	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		0.7	3.7	$\mu\text{V}/^\circ\text{C}$
Input Bias Current					
	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$		-1.2	-2.0	μA
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$		500	1000	nA
Input Bias Current Drift					
	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		2.6	3.8	nA/ $^\circ\text{C}$
Input Offset Current					
	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$		8	100	nA
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$		25	150	nA
Input Offset Current Drift					
	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		30	250	pA/ $^\circ\text{C}$
Open-Loop Gain		113	130		dB
INPUT CHARACTERISTICS					
Common-Mode Input Resistance					
			45		M Ω
Differential Input Resistance					
			35		k Ω
Common-Mode Input Capacitance					
			1		pF
Differential Input Capacitance					
			1		pF
Input Common-Mode Voltage Range					
			$-V_S - 0.2$ to $+V_S + 0.2$		V
CMRR	$V_{\text{ICM}} = 1\text{ V to }3\text{ V}$	96	110		dB
DISABLE CHARACTERISTICS					
$\overline{\text{DISABLE}}$ Low Input Voltage					
	Disabled		<1.3		V
$\overline{\text{DISABLE}}$ High Input Voltage					
	Enabled		>1.8		V
$\overline{\text{DISABLE}}$ Low Input Current					
	Disabled		-360		nA
$\overline{\text{DISABLE}}$ High Input Current					
	Enabled		-1.3		nA
$\overline{\text{DISABLE}}$ On Time					
	$\overline{\text{DISABLE}}$ input midswing point to >90% of final V_{OUT}		450		ns
$\overline{\text{DISABLE}}$ Off Time					
	$\overline{\text{DISABLE}}$ input midswing point to <10% of enabled quiescent current		850		ns

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
OUTPUT CHARACTERISTICS					
Saturated Output Voltage Swing	$R_{LOAD} = 1\text{ k}\Omega$	$+V_S - 0.05$	$+V_S - 0.03$		V
High					
Low		$-V_S + 0.05$	$-V_S + 0.04$		V
Linear Output Current	Sourcing		60		mA
	Sinking		50		mA
Short-Circuit Current	Sourcing		106		mA
	Sinking		101		mA
Capacitive Load Drive	$C_{LOAD} = 15\text{ pF}$		24		% overshoot
POWER SUPPLY					
Operating Range		2.7		11	V
Quiescent Current per Amplifier	Enabled, no load, $T_A = 25^\circ\text{C}$		950	1000	μA
	Disabled, $T_A = 25^\circ\text{C}$		1.3	2.0	μA
PSRR					
Positive	$+V_S = 1.5\text{ V to }3.5\text{ V}, -V_S = -2.5\text{ V}$	98	115		dB
Negative	$+V_S = 2.5\text{ V}, -V_S = -1.5\text{ V to }-3.5\text{ V}$	98	130		dB

3 V SUPPLY

$T_A = 25^\circ\text{C}$, $V_S = 3\text{ V}$, $R_{\text{LOAD}} = 1\text{ k}\Omega$ to midsupply, $R_F = 0\ \Omega$, $G = +1$, $0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$, unless otherwise noted.

Table 4.

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
DYNAMIC PERFORMANCE					
-3 dB Small Signal Bandwidth	$G = +1$, $V_{\text{OUT}} = 20\text{ mV p-p}$		165		MHz
Slew Rate	$G = +1$, $V_{\text{OUT}} = 2\text{ V p-p}$		28		MHz
Settling Time to 0.1%	$G = +1$, $V_{\text{OUT}} = 2\text{ V step, 20% to 80%, rise/fall}$		118/237		V/ μs
	$G = +1$, $V_{\text{OUT}} = 2\text{ V step}$		40		ns
DISTORTION/NOISE PERFORMANCE					
Second Harmonic	$f_C = 1\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-98		dBc
	$f_C = 100\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-85		dBc
	$f_C = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-65		dBc
Third Harmonic	$f_C = 1\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-94		dBc
	$f_C = 100\text{ kHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-91		dBc
	$f_C = 1\text{ MHz}$, $V_{\text{OUT}} = 2\text{ V p-p}$		-68		dBc
Peak-to-Peak Noise	$f = 0.1\text{ Hz to }10\text{ Hz}$		160		nV p-p
Input Voltage Noise	$f = 100\text{ kHz}$		3.1		nV/ $\sqrt{\text{Hz}}$
	$f = 10\text{ kHz}$		3.3		nV/ $\sqrt{\text{Hz}}$
	$f = 10\text{ Hz}$		5.8		nV/ $\sqrt{\text{Hz}}$
Input Noise Voltage 1/f Corner			29		Hz
Input Current Noise	$f = 100\text{ kHz}$		0.7		pA/ $\sqrt{\text{Hz}}$
	$f = 10\text{ Hz}$		10		pA/ $\sqrt{\text{Hz}}$
Input Current Noise 1/f Corner			2		kHz
DC PERFORMANCE					
Input Offset Voltage	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$	-125	± 20	+125	μV
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$	-720	± 125	+720	μV
Input Offset Voltage Drift	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		0.7	3.8	$\mu\text{V}/^\circ\text{C}$
Input Bias Current	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$		-1.2	-2.0	μA
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$		500	1000	nA
Input Bias Current Drift	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		2.7	3.8	nA/ $^\circ\text{C}$
Input Offset Current	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.5\text{ V}$		8	130	nA
	$+V_S - 1.5\text{ V} \leq V_{\text{ICM}} \leq +V_S$		25	150	nA
Input Offset Current Drift	$0\text{ V} \leq V_{\text{ICM}} \leq +V_S - 1.2\text{ V}$, T_{MIN} to T_{MAX}		40	230	pA/ $^\circ\text{C}$
Open-Loop Gain		104	113		dB
INPUT CHARACTERISTICS					
Common-Mode Input Resistance			45		M Ω
Differential Input Resistance			35		k Ω
Common-Mode Input Capacitance			1		pF
Differential Input Capacitance			1		pF
Input Common-Mode Voltage Range			$-V_S - 0.2$ to $+V_S + 0.2$		V
CMRR	$V_{\text{ICM}} = 0.3\text{ V to }1.3\text{ V}$	92	110		dB
DISABLE CHARACTERISTICS					
$\overline{\text{DISABLE}}$ Low Input Voltage	Disabled		<1.1		V
$\overline{\text{DISABLE}}$ High Input Voltage	Enabled		>1.5		V
$\overline{\text{DISABLE}}$ Low Input Current	Disabled		-325		nA
$\overline{\text{DISABLE}}$ High Input Current	Enabled		-500		nA
$\overline{\text{DISABLE}}$ On Time	$\overline{\text{DISABLE}}$ input midswinging point to >90% of final V_{OUT}		450		ns
$\overline{\text{DISABLE}}$ Off Time	$\overline{\text{DISABLE}}$ input midswinging point to <10% of enabled quiescent current		850		ns

Parameter	Test Conditions/Comments	Min	Typ	Max	Unit
OUTPUT CHARACTERISTICS					
Saturated Output Voltage Swing	$R_{LOAD} = 1\text{ k}\Omega$	$+V_S - 0.04$	$+V_S - 0.02$		V
High					
Low		$-V_S + 0.04$	$-V_S + 0.03$		V
Linear Output Current	Sourcing		50		mA
	Sinking		40		mA
Short-Circuit Current	Sourcing		80		mA
	Sinking		70		mA
Capacitive Load Drive	$C_{LOAD} = 15\text{ pF}$		30		% overshoot
POWER SUPPLY					
Operating Range		2.7		11	V
Quiescent Current per Amplifier	Enabled, no load, $T_A = 25^\circ\text{C}$		915	1000	μA
	Disabled, $T_A = 25^\circ\text{C}$		1.0	2.0	μA
PSRR					
Positive	$+V_S = 1.5\text{ V to }3.5\text{ V}, -V_S = -1.5\text{ V}$	97	113		dB
Negative	$+V_S = 1.5\text{ V}, -V_S = -1.5\text{ V to }-3.5\text{ V}$	97	130		dB

ABSOLUTE MAXIMUM RATINGS

Table 5.

Parameter	Rating
Supply Voltage	11 V
Internal Power Dissipation	See Figure 4
Input Voltage (Common Mode)	$\pm V_s \pm 0.2$ V
Differential Input Voltage	± 1.4 V
Output Short-Circuit Duration	Observe power derating curves in Figure 4
Storage Temperature Range (All Packages)	-65°C to +125°C
Lead Temperature (Soldering 10 Sec)	300°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

MAXIMUM POWER DISSIPATION

The maximum power that can be safely dissipated by the ADA4807-1/ADA4807-2 is limited by the associated rise in junction temperature. The maximum safe junction temperature for plastic encapsulated devices is determined by the glass transition temperature of the plastic, approximately 150°C. Exceeding this limit temporarily can cause a shift in parametric performance due to a change in the stresses exerted on the die by the package. Exceeding a junction temperature of 175°C for an extended period can result in device failure.

Although the ADA4807-1/ADA4807-2 are internally short-circuit protected, this may not be sufficient to guarantee that the maximum junction temperature (150°C) is not exceeded under all conditions. To ensure proper operation, it is necessary to observe the power derating curves shown in Figure 4.

THERMAL RESISTANCE

θ_{JA} is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 6. Thermal Resistance

Package Type	θ_{JA}	Unit
6-Lead SC70, 4-Layer Board	209	°C/W
6-Lead SOT-23, 4-Layer Board	223	°C/W
8-Lead MSOP	123	°C/W
10-Lead LFCSP	51	°C/W

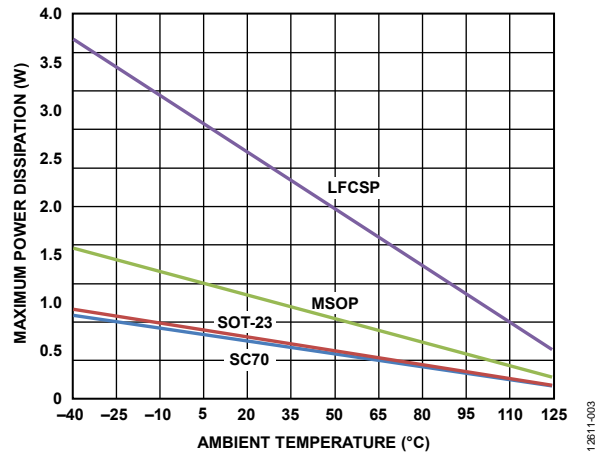


Figure 4. Maximum Power Dissipation vs. Ambient Temperature for a 4-Layer Board

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS



Figure 5. ADA4807-1 6-Lead SC70 Pin Configuration

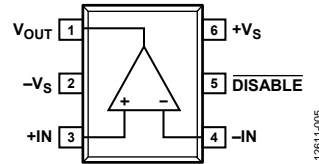


Figure 6. ADA4807-1 6-Lead SOT-23 Pin Configuration

Table 7. ADA4807-1 Pin Function Descriptions

Pin No.	Mnemonic	Description
1	V_{OUT}	Output
2	$-V_S$	Negative Supply
3	+IN	Noninverting Input
4	-IN	Inverting Input
5	$\overline{DISABLE}$	Active Low Power-Down
6	$+V_S$	Positive Supply



NOTES
 1. THE EXPOSED PAD CAN BE CONNECTED TO GROUND OR POWER PLANES, OR IT CAN BE LEFT FLOATING.

12611-060

Figure 7. ADA4807-2 10-Lead LFCSP Pin Configuration



12611-061

Figure 8. ADA4807-2 8-Lead MSOP Pin Configuration

Table 8. ADA4807-2 Pin Function Descriptions

Pin No.		Mnemonic	Description
10-Lead LFCSP	8-Lead MSOP		
1	1	V_{OUT1}	Output 1.
2	2	-IN1	Inverting Input 1.
3	3	+IN1	Noninverting Input 1.
4	4	$-V_S$	Negative Supply.
5	Not applicable	$\overline{DISABLE1}$	Active Low Power-Down 1.
6	Not applicable	$\overline{DISABLE2}$	Active Low Power-Down 2.
7	5	+IN2	Noninverting Input 2.
8	6	-IN2	Inverting Input 2.
9	7	V_{OUT2}	Output 2.
10	8	+ V_S	Positive Supply.
	Not applicable	EPAD	Exposed Pad. For the 10-Lead LFCSP, the exposed pad can be connected to ground or power planes, or it can be left floating.

TYPICAL PERFORMANCE CHARACTERISTICS

FREQUENCY RESPONSE



Figure 9. Small Signal Frequency Response for Various Gains, $R_F = 499\Omega$

12811-006

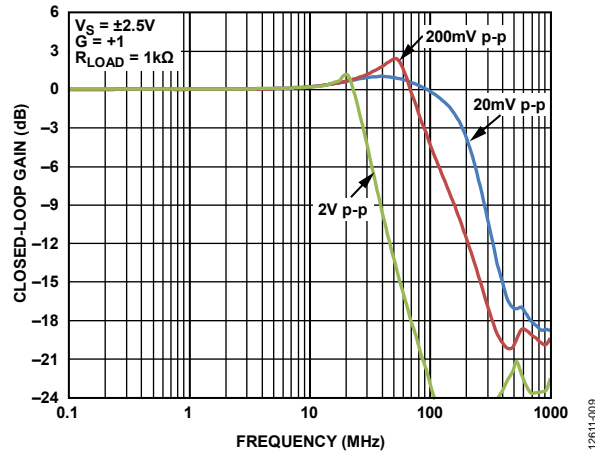


Figure 12. Frequency Response for Various Output Amplitudes

12811-009



Figure 10. Small Signal Frequency Response for Various Supplies

12811-007

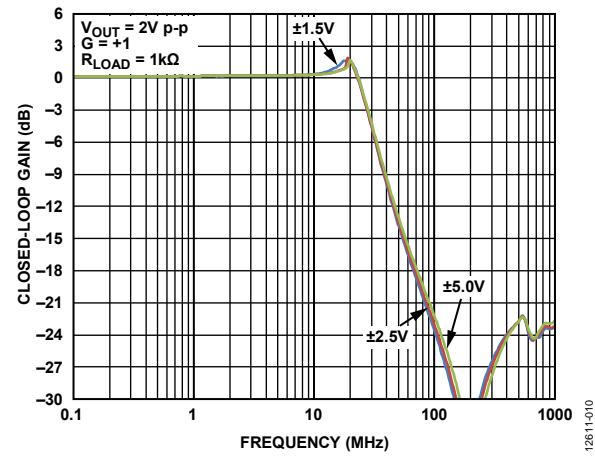


Figure 13. Large Signal Frequency Response for Various Supplies

12811-010

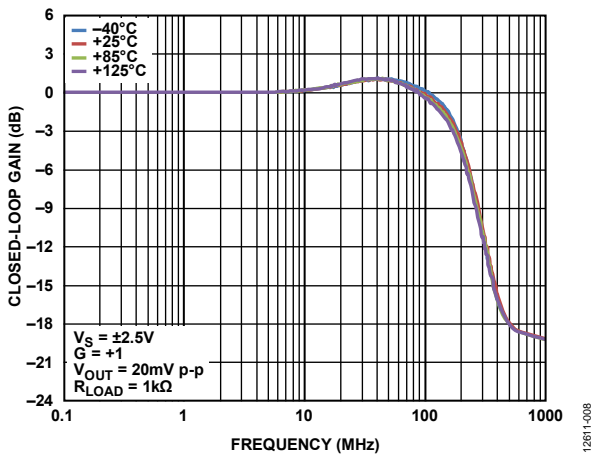


Figure 11. Small Signal Frequency Response for Various Temperatures

12811-008

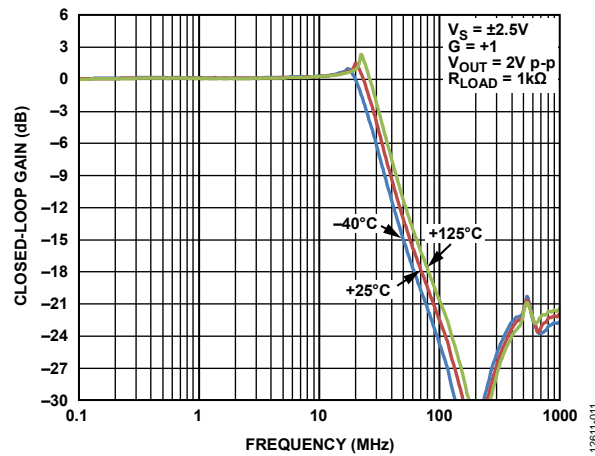


Figure 14. Large Signal Frequency Response for Various Temperatures

12811-011



Figure 15. Small Signal Frequency Response for Various Resistive Loads

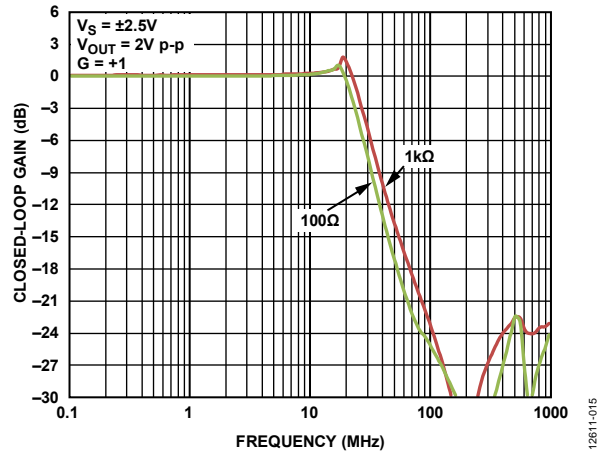


Figure 18. Large Signal Frequency Response for Various Resistive Loads

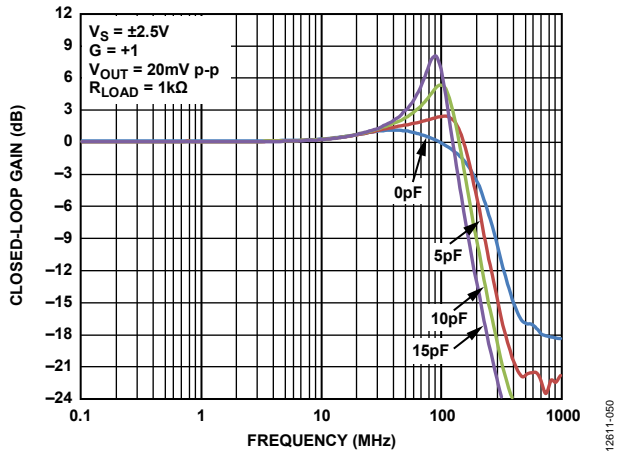


Figure 16. Small Signal Frequency Response for Various Capacitive Loads

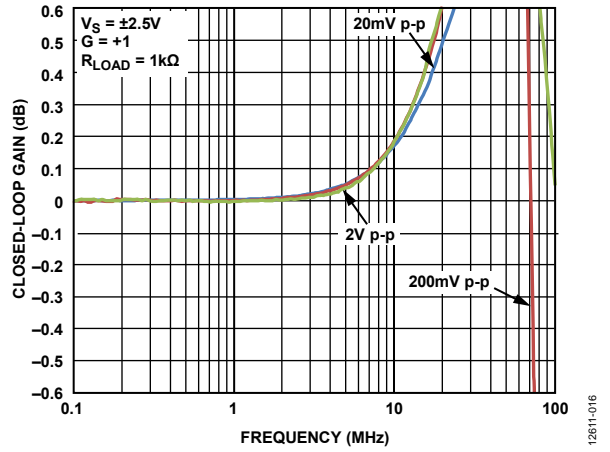


Figure 19. 0.1 dB Flatness Frequency Response for Various Output Amplitudes



Figure 17. Small Signal Frequency Response for Various Input Common-Mode Voltages (V_{CM})

FREQUENCY AND SUPPLY CURRENT



Figure 20. Off Isolation vs. Frequency



Figure 23. CMRR vs. Frequency



Figure 21. Open-Loop Gain and Phase vs. Frequency



Figure 24. PSRR vs. Frequency

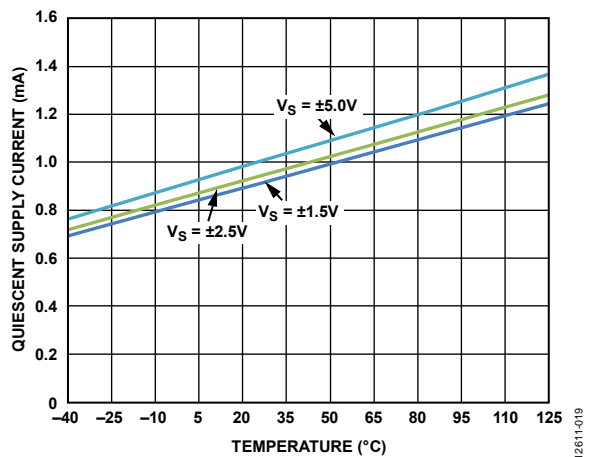


Figure 22. Quiescent Supply Current vs. Temperature

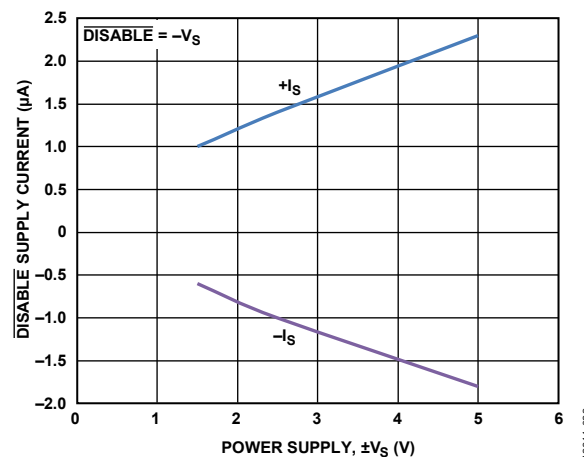


Figure 25. DISABLE Supply Current vs. Power Supply

DC AND INPUT COMMON-MODE PERFORMANCE

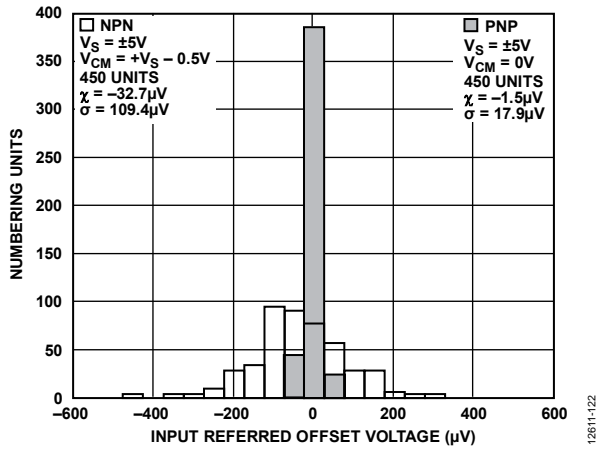


Figure 26. Input Referred Offset Voltage Distribution



Figure 29. Input Referred Offset Voltage vs. Input Common-Mode Voltage

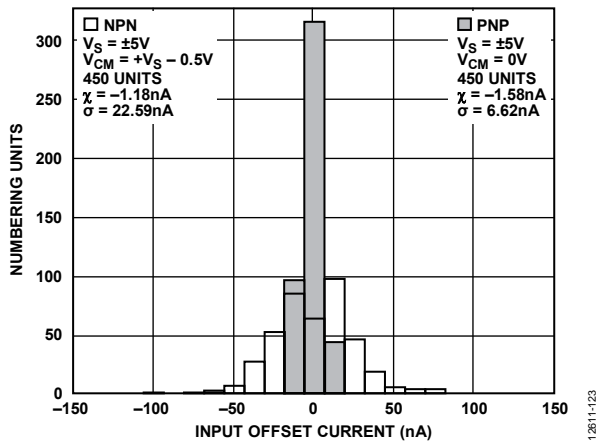


Figure 27. Input Offset Current Distribution

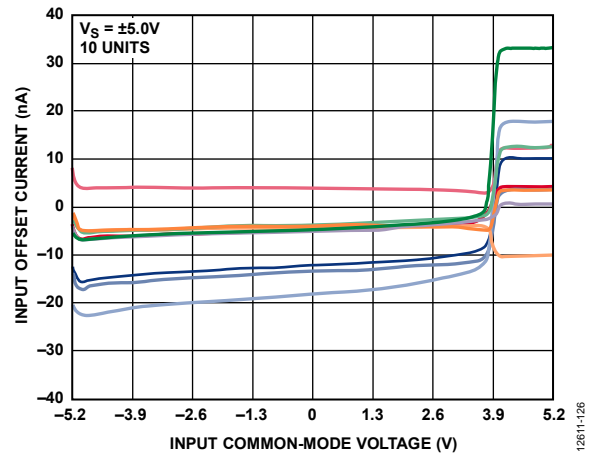


Figure 30. Input Offset Current vs. Input Common-Mode Voltage

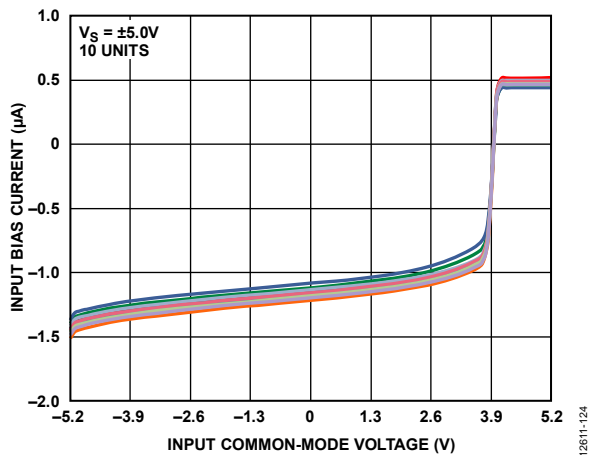


Figure 28. Input Bias Current vs. Input Common-Mode Voltage

12611-122

12611-125

12611-123

12611-126

12611-124

SLEW, TRANSIENT, SETTLING TIME, AND CROSSTALK

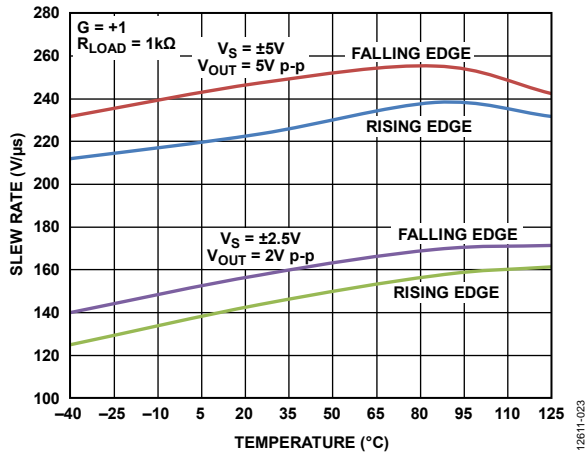


Figure 31. Slew Rate vs. Temperature

12811-023

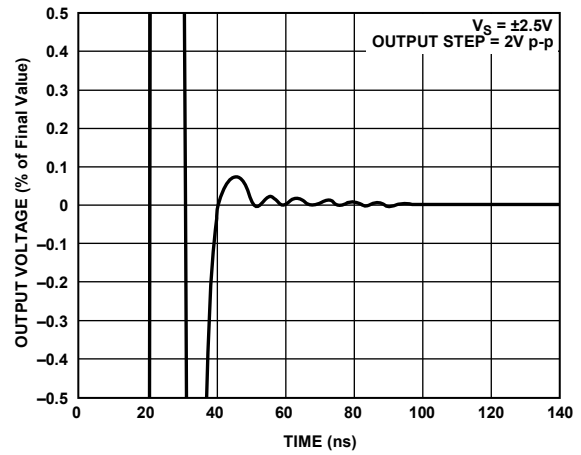


Figure 34. Settling Time to 0.1%

12811-026



Figure 32. Small Signal Transient Response for Various Supplies

12811-024



Figure 35. Small Signal Transient Response for Various Capacitive Loads

12811-027

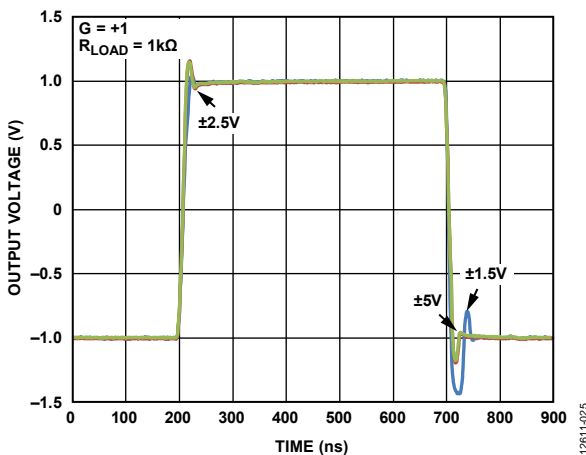


Figure 33. Large Signal Transient Response for Various Supplies

12811-025

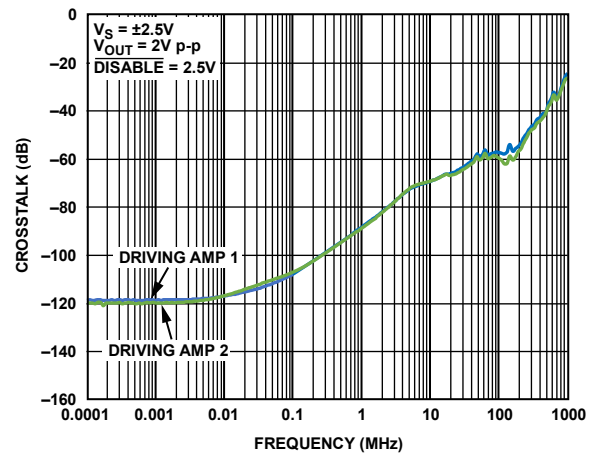


Figure 36. Crosstalk vs. Frequency

12811-036

DISTORTION AND NOISE

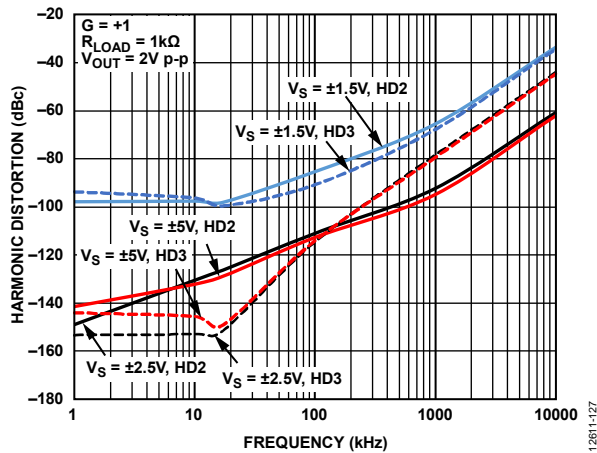


Figure 37. ADA4807-1 Harmonic Distortion vs. Frequency for Various Supplies

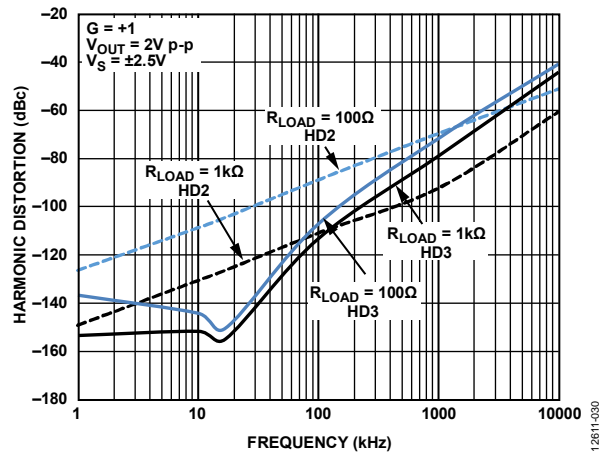


Figure 40. ADA4807-1 Harmonic Distortion vs. Frequency for Various Resistive Loads

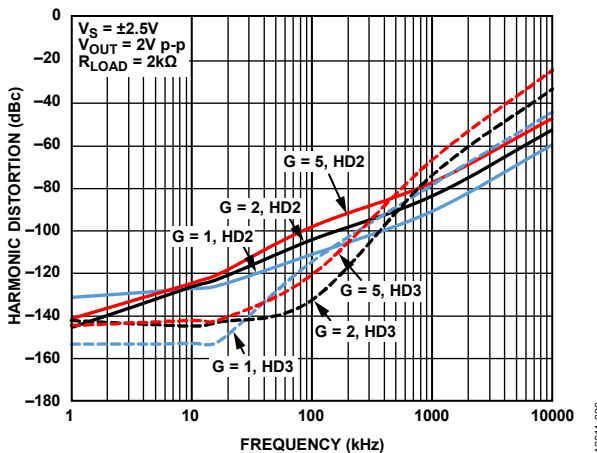


Figure 38. ADA4807-1 Harmonic Distortion vs. Frequency for Various Gains

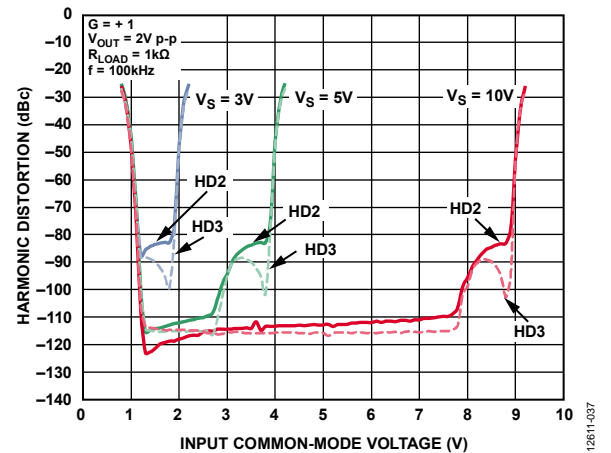


Figure 41. Harmonic Distortion vs. Input Common-Mode Voltage

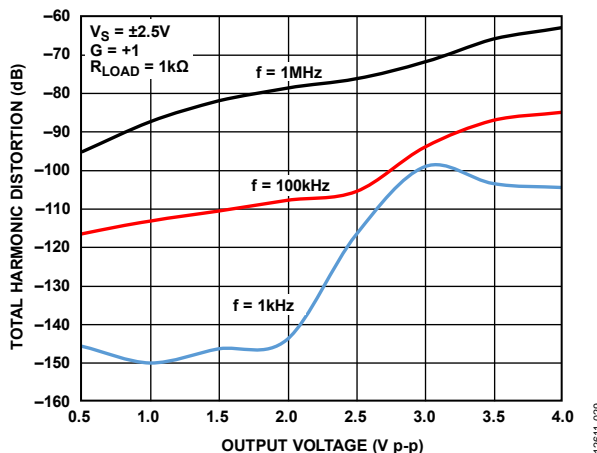


Figure 39. ADA4807-1 Total Harmonic Distortion vs. Output Voltage

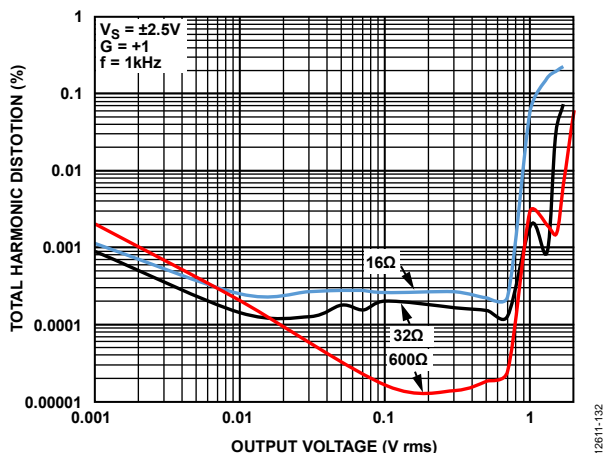


Figure 42. Total Harmonic Distortion vs. Output Voltage for Various Resistive Loads

OUTPUT CHARACTERISTICS



Figure 43. Input Voltage Noise and Current Noise, $V_{CM} = 0\text{ V}$ vs. Frequency



Figure 46. Input Voltage Noise and Current Noise, $V_{CM} = +V_S - 0.5\text{ V}$ vs. Frequency



Figure 44. Positive Rail Output Saturation Voltage ($+V_S - V_{OUT}$) vs. Load Current for Various Temperatures

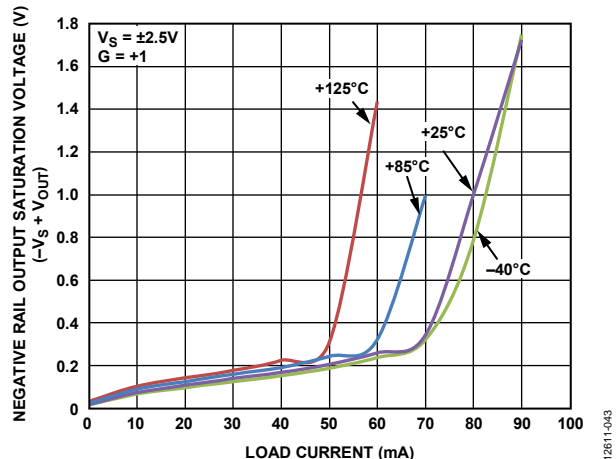


Figure 47. Negative Rail Output Saturation Voltage ($-V_S + V_{OUT}$) vs. Load Current for Various Temperatures

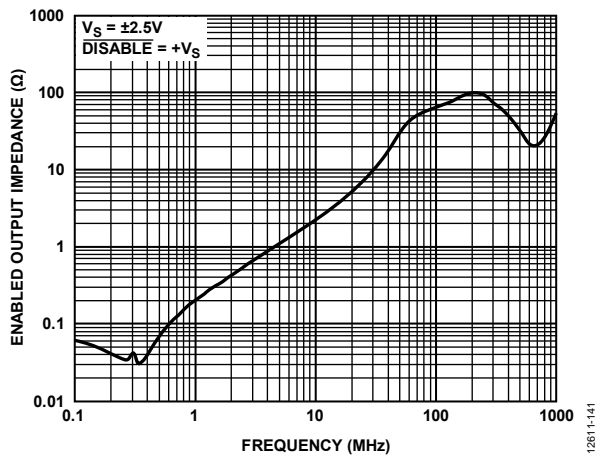


Figure 45. Enabled Output Impedance vs. Frequency

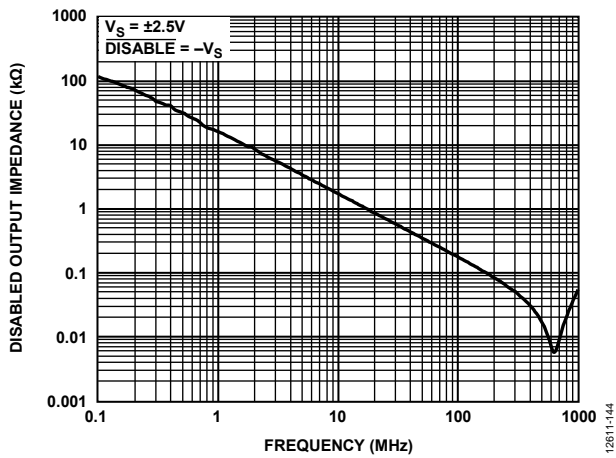


Figure 48. Disabled Output Impedance vs. Frequency

OVERDRIVE RECOVERY AND POWER-UP/POWER-DOWN



Figure 49. Input Overdrive Recovery



Figure 52. Output Overdrive Recovery



Figure 50. Power-Up Time vs. Temperature



Figure 53. Power-Up Time for Various Supplies



Figure 51. Power-Down Time vs. Temperature



Figure 54. Power-Down Time for Various Supplies

THEORY OF OPERATION

The ADA4807-1/ADA4807-2 have a rail-to-rail input stage with an input range that goes 200 mV beyond either rail. A PNP transistor input pair is active for a majority of the input range, while an NPN transistor input pair is active for the common-mode voltages within 1.3 V of the positive rail. The ADA4807-1/ADA4807-2 are fabricated in Analog Devices, Inc., third generation, extra fast complementary bipolar (XFCB) process resulting in exceptionally good distortion, noise, slew rate, and settling characteristics for 1 mA devices. Given traditional rail-to-rail input architecture performance, the input 1/f noise is surprisingly low, and the current noise is only 0.7 pA/√Hz for a 3 nV/√Hz voltage noise. Typical high slew rate devices suffer from increased current noise because of input pair degeneration and higher input stage current. The ADA4807-1/ADA4807-2 exceed current benchmark parameters given the performance of the XFCB process.

The multistage design of the ADA4807-1/ADA4807-2 has excellent precision specifications, such as input drift, offset, open-loop gain, CMRR, and PSRR. Typical harmonic distortion numbers fall in the range of -130 dBc for a 10 kHz fundamental (see Figure 40). This level of performance makes the ADA4807-1/

ADA4807-2 the best choices when driving 18-bit precision converters.

The ADA4807-1/ADA4807-2 are optimized for a low shutdown current (4 μA maximum), in the order of a few microamperes. In power sensitive applications, this can eliminate the use of a power FET and enable time interleaved power saving operation schemes.

The rail-to-rail input stage is useful in many different applications. Although the precision is reduced from input to input, many applications can tolerate this loss when the alternative is no functionality at all. The positive rail input range is indispensable for servo loops with a high-side input range

The ADA4807-1/ADA4807-2 input operates 200 mV beyond either rail. Internal protection circuitry prevents the output from phase inverting when the input range is exceeded. When the input exceeds a diode beyond either rail, internal electrostatic discharge (ESD) protection diodes source or sink current through the input.

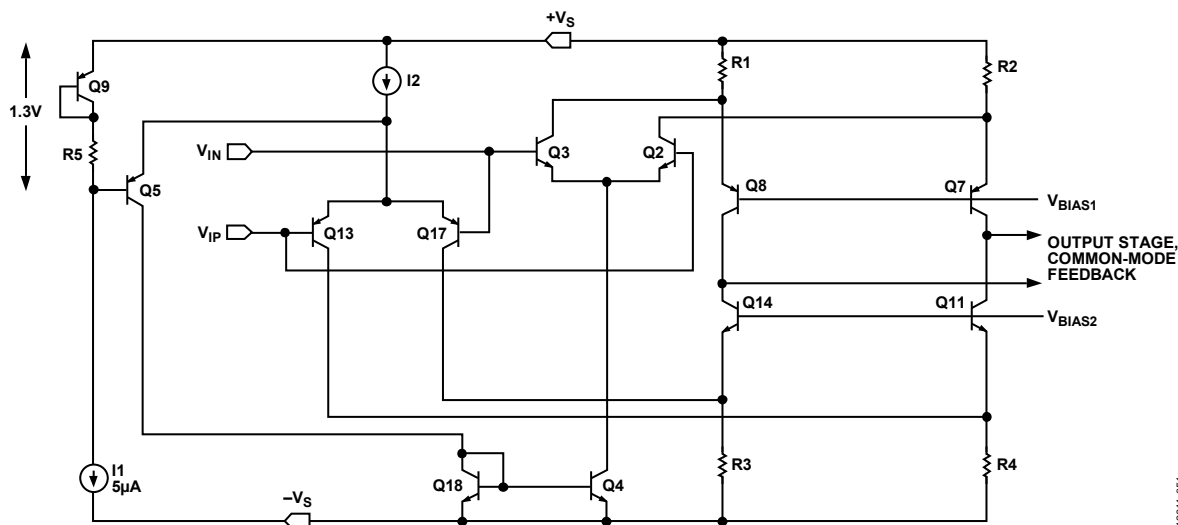


Figure 55. Simplified Schematic

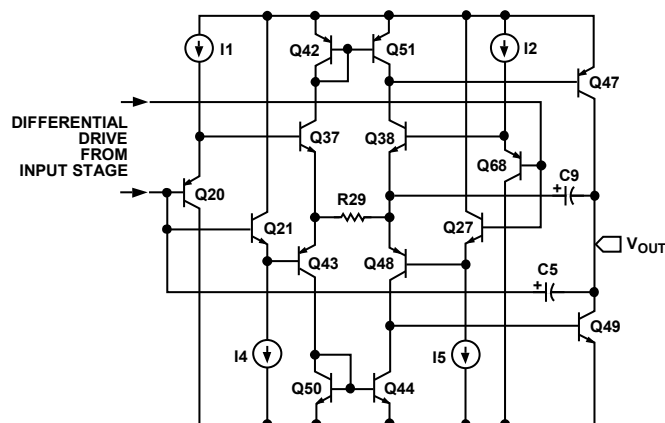


Figure 56. Differential Drive from Input Stage

DISABLE CIRCUITRY

When the **DISABLE** pin is an option, a pull-up resistor is necessary if the logic leakage currents exceed 300 nA. Pulling the **DISABLE** pin to ≥ 3.7 V below $+V_S$ turns the ADA4807-1/ADA4807-2 off, which reduces the supply current to 2.4 μ A for a 10 V voltage supply. Applying ≤ 3.4 V below $+V_S$ on the **DISABLE** pin enables the ADA4807-1/ADA4807-2 with a low quiescent current of 1 mA for a 10 V voltage supply. When the ADA4807-1/ADA4807-2 device is disabled, its output enters a high impedance state. The output impedance decreases as frequency increases. When disabled, a forward isolation of 120 dB is achieved at 100 kHz (see Figure 20). ESD clamps protect the **DISABLE** pin, as shown in Figure 58. Voltages beyond the power supplies cause these diodes to conduct. To avoid excessive current in the ESD diodes, ensure that the voltage to the **DISABLE** pin does not exceed 0.7 V above the positive supply or that it does not fall 0.7 V below the negative supply. If an overvoltage condition is expected, limit the input current to less than 10 mA with a series resistor.



Figure 57. **DISABLE** Trigger Voltage

Table 9. Threshold Voltages for Disabled and Enabled Modes

Mode	+3 V	+5 V	+10 V	± 5 V	+7 V/-2 V
Enabled	1.35 V	1.6 V	6.6 V	1.6 V	+3.6 V
Disabled	1.05 V	1.3 V	6.3 V	1.3 V	+3.3 V

INPUT PROTECTION

The ADA4807-1/ADA4807-2 are fully protected from ESD events, withstanding human body model ESD events of ± 3 kV and charged device model events of ± 1.25 kV with no measured performance degradation. The precision input is protected with an ESD network between the power supplies and diode clamps across the input device pair, as shown in Figure 58. For differential voltages above approximately 1.2 V at room temperature and 0.8 V at 125°C, the diode clamps begin to conduct. Too much current can cause damage due to excessive heating. If large differential voltages must be sustained across the input terminals, it is recommended that the current through the input clamps be limited to less than 10 mA. Series input resistors sized appropriately for the expected differential overvoltage provide the needed protection.

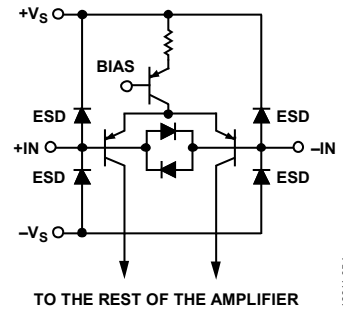


Figure 58. Input Stage and Protection Diodes

NOISE CONSIDERATIONS

Figure 59 illustrates the primary noise contributors for the typical gain configurations. The total output noise (V_{N_OUT}) is the root sum square of all the noise contributions.



Figure 59. Noise Sources in Typical Gain Configurations

Calculate the output noise spectral density using Equation 1. Source resistance noise, amplifier input voltage noise, and the voltage noise from the amplifier input current noise ($I_{N+} \times R_S$) are all subject to the noise gain term $(1 + R_F/R_G)$.

$$V_{N_OUT} = \sqrt{4kTR_F + \left(1 + \frac{R_F}{R_G}\right)^2 \left[4kTR_S + I_{N+}^2 R_S^2 + V_N^2\right] + \left(\frac{R_F}{R_G}\right)^2 4kTR_G + I_{N-}^2 R_F^2} \quad (1)$$

where:

k is Boltzmann's constant.

T is the absolute temperature in degrees Kelvin.

R_F and R_G are the feedback network resistances, as shown in Figure 59.

R_S is the source resistance, as shown in Figure 59.

I_{N+} and I_{N-} represent the amplifier input current noise spectral density in pA/ \sqrt Hz.

V_N is the amplifier input voltage noise spectral density in nV/ \sqrt Hz.

APPLICATIONS INFORMATION

CAPACITIVE LOAD DRIVE

Figure 60 shows the schematic for driving large capacitive loads, and Figure 61 shows the frequency response for a gain of +2. Note that the bandwidth decreases with larger capacitive loads (see Figure 61).

Figure 62 shows the required series resistor (R_{SERIES}) when limiting the peaking to 3 dB for a range of load capacitors (C_{LOAD}) at a gain of 2. From Figure 62, no series resistors are necessary to maintain stability for larger capacitors.

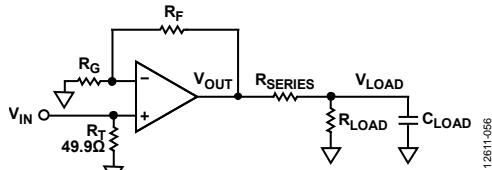


Figure 60. Schematic for Driving Large Capacitive Loads



Figure 61. Frequency Response for Driving Large Capacitive Loads, $R_F = R_G = 249\Omega$



Figure 62. Required Series Resistor (R_{SERIES}) vs. Capacitive Load (C_{LOAD}) at 3 dB Peaking

LAYOUT, GROUNDING, AND BYPASSING

The ADA4807-1/ADA4807-2 are high speed devices. Realizing their superior performance requires attention to the details of high speed printed circuit board (PCB) design.

The first requirement is to use a multilayer PCB with solid ground and power planes that cover as much of the board area as possible.

Bypass each power supply pin directly to a nearby ground plane, as close to the device as possible. Use 0.1 μF high frequency ceramic chip capacitors.

Provide low frequency bulk bypassing using 10 μF tantalum capacitors from each supply to ground.

Stray transmission line capacitance in combination with package parasitics can potentially form a resonant circuit at high frequencies, resulting in excessive gain peaking or possible oscillation. Signal routing must be short and direct to avoid such parasitic effects. Provide symmetrical layout for complementary signals to maximize balanced performance.

Use radio frequency transmission lines to connect the driver and receiver to the amplifier.

Minimize stray capacitance at the input and output pins by clearing the underlying ground and low impedance planes near these pins.

If the driver and receiver are more than one-eighth of the wavelength from the amplifier, minimize the signal trace widths. This nontransmission line configuration requires clearing of the underlying and adjacent ground and low impedance planes near the signal lines.

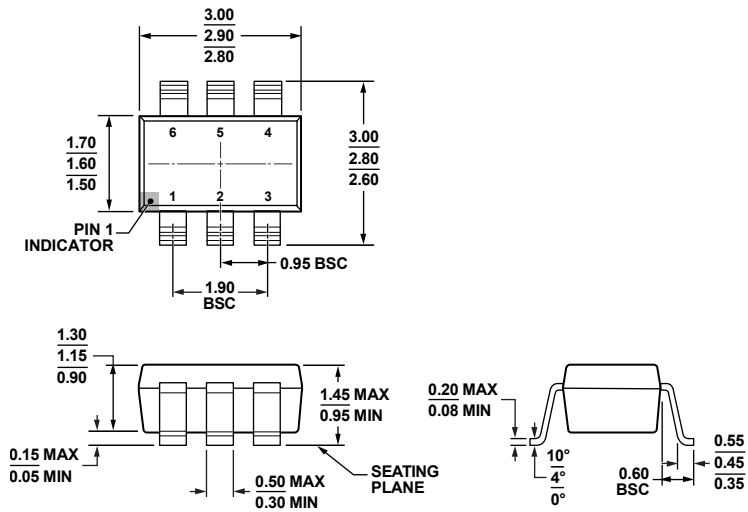
OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-203-AB

Figure 63. 6-Lead Thin Shrink Small Outline Transistor Package [SC70] (KS-6)
Dimensions shown in millimeters

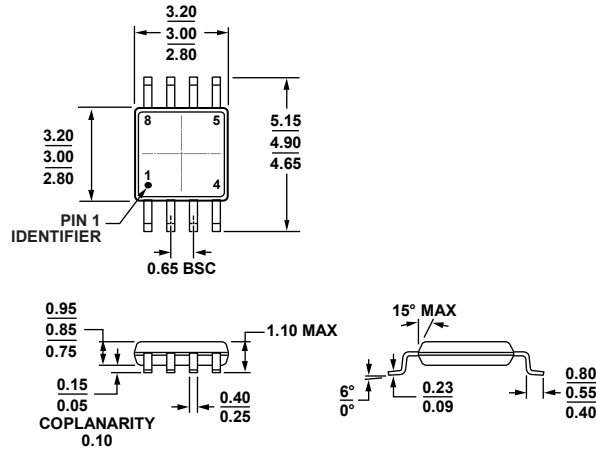
072809-A



COMPLIANT TO JEDEC STANDARDS MO-178-AB

Figure 64. 6-Lead Small Outline Transistor Package [SOT-23] (RJ-6)
Dimensions shown in millimeters

121608-A



COMPLIANT TO JEDEC STANDARDS MO-187-AA

Figure 65. 8-Lead Mini Small Outline Package [MSOP] (RM-8)

Dimensions shown in millimeters

10-07-2009B

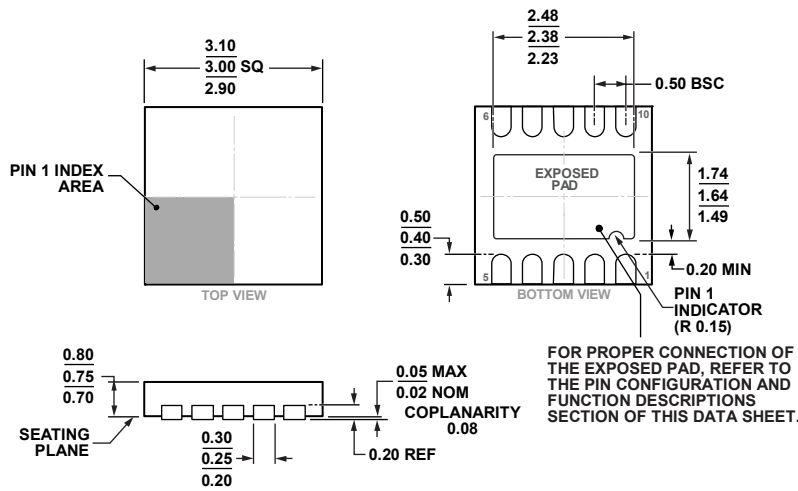


Figure 66. 10-Lead Lead Frame Chip Scale Package [LFCSP_WD] 3 mm x 3 mm Body, Very Very Thin, Dual Lead (CP-10-9)

Dimensions shown in millimeters

02-05-2013-C

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option	Branding
ADA4807-1AKSZ-R2	-40°C to +125°C	6-Lead Thin Shrink Small Outline Transistor Package [SC70]	KS-6	H3J
ADA4807-1AKSZ-R7	-40°C to +125°C	6-Lead Thin Shrink Small Outline Transistor Package [SC70]	KS-6	H3J
ADA4807-1ARJZ-R2	-40°C to +125°C	6-Lead Small Outline Transistor Package [SOT-23]	RJ-6	H3J
ADA4807-1ARJZ-R7	-40°C to +125°C	6-Lead Small Outline Transistor Package [SOT-23]	RJ-6	H3J
ADA4807-2ACPZ-R2	-40°C to +125°C	10-Lead Lead Frame Chip Scale Package [LFCSP_WD]	CP-10-9	H3S
ADA4807-2ACPZ-R7	-40°C to +125°C	10-Lead Lead Frame Chip Scale Package [LFCSP_WD]	CP-10-9	H3S
ADA4807-2ARMZ	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	H3S
ADA4807-2ARMZ-R7	-40°C to +125°C	8-Lead Mini Small Outline Package [MSOP]	RM-8	H3S
ADA4807-1AKSZ-EBZ		Evaluation Board for 6-Lead SC70		
ADA4807-1ARJZ-EBZ		Evaluation Board for 6-Lead SOT-23		
ADA4807-2ACPZ-EBZ		Evaluation Board for 10-Lead LFCSP_WD		
ADA4807-2ARMZ-EBZ		Evaluation Board for 8-Lead MSOP		

¹ Z = RoHS Compliant Part.

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- Подбор аналогов.
- Поставку компонентов в любых объемах, удовлетворяющих вашим потребностям.
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- Работу по проектам и поставку образцов.
- Формирование склада под заказчика.
- Сертификаты соответствия на поставляемую продукцию (по желанию клиента).
- Тестирование поставляемой продукции.
- Поставку компонентов, требующих военную и космическую приемку.
- Входной контроль качества.
- Наличие сертификата ISO.

В составе нашей компании организован Конструкторский отдел, призванный помогать разработчикам, и инженерам.

Конструкторский отдел помогает осуществить:

- Регистрацию проекта у производителя компонентов.
- Техническую поддержку проекта.
- Защиту от снятия компонента с производства.
- Оценку стоимости проекта по компонентам.
- Изготовление тестовой платы монтаж и пусконаладочные работы.



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