## ATV71HD75M3X





#### Main

Range of product	Altivar 71
Product or component type	Variable speed drive
Product specific application	Complex, high-power machines
Component name	ATV71
Motor power kW	75 kWat 200240 V 3 phases
Motor power hp	100 hpat 200240 V 3 phases
Motor cable length	
[Us] rated supply voltage	200240 V (- 1510 %)
Phase	3 phases
Line current	232 Afor 240 V 3 phases 75 kW / 100 hp 271 Afor 200 V 3 phases 75 kW / 100 hp
EMC filter	Without EMC filter
Assembly style	With heat sink
Variant	Reinforced version
Apparent power	96.4 kVAat 240 V 3 phases 75 kW / 100 hp
Prospective line Isc	<= 35 kA, 3 phases
Nominal output current	285 Aat 2.5 kHz 230 V 3 phases 75 kW / 100 hp
Maximum transient current	428 Afor 60 s 3 phases 75 kW / 100 hp 470 Afor 2 s 3 phases 75 kW / 100 hp
Output frequency	0.1500 Hz
Nominal switching frequency	2.5 kHz
Switching frequency	2.58 kHz adjustable 2.58 kHz with derating factor
Asynchronous motor control profile	ENA (Energy adaptation) system for unbalanced loads Flux vector control (FVC) with sensor (current vector) Sensorless flux vector control (SFVC) (voltage or current vector) Voltage/frequency ratio (2 or 5 points)
Type of polarization	No impedance Modbus

### Complementary

Product destination	Asynchronous motors Synchronous motors
Supply voltage limits	170264 V
Supply frequency	5060 Hz (- 55 %)
Network frequency	47.563 Hz
Speed range	1100 asynchronous motor in open-loop mode, without speed feedback 150 synchronous motor in open-loop mode, without speed feedback 11000 asynchronous motor in closed-loop mode with encoder feedback
Speed accuracy	+/- 0.01 % of nominal speed 0.2 Tn to Tn torque variation in closed-loop mode with encoder feedback +/- 10 % of nominal slip 0.2 Tn to Tn torque variation without speed feedback
Torque accuracy	+/- 15 % in open-loop mode, without speed feedback +/- 5 % in closed-loop mode with encoder feedback
Transient overtorque	220 % of nominal motor torque +/- 10 %for 2 s 170 % of nominal motor torque +/- 10 %for 60 s every 10 minutes
Braking torque	<= 150 % with braking or hoist resistor 30 % without braking resistor
Synchronous motor control profile	Vector control without speed feedback

Regulation loop	Adjustable PI regulator
Motor slip compensation	Adjustable Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points) Suppressable
Local signalling	1 LED red presence of drive voltage
Output voltage	<= power supply voltage
Insulation	Electrical between power and control
Type of cable	With a NEMA Type1 kit: 3-strand UL 508 cableat 104 °F (40 °C), copper 75 °C PVC With an IP21 or an IP31 kit: 3-strand IEC cableat 104 °F (40 °C), copper 70 °C PVC Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 70 °C PVC Without mounting kit: 1-strand IEC cableat 113 °F (45 °C), copper 90 °C XLPE/EPR
Electrical connection	AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1LI6, PWR terminal 2.5 mm² / AWG 14 L1/R, L2/S, L3/T, U/T1, V/T2, W/T3 terminal 2 x 100 mm² PA, PB terminal 60 mm² PC/-, PO, PA/+ terminal 2 x 150 mm²
Tightening torque	L1/R, L2/S, L3/T, U/T1, V/T2, W/T3 212.39 lbf.in (24 N.m) / 212 lb.in PA, PB 106.19 lbf.in (12 N.m) / 106 lb.in PC/-, PO, PA/+ 362.83 lbf.in (41 N.m) / 360 lb.in Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, LI1LI6, PWR 5.31 lbf.in (0.6 N.m)
Supply	Internal supply for reference potentiometer (1 to 10 kOhm), 10.5 V DC +/- 5 %, <= 10 mAfor overload and short-circuit protection Internal supply, 24 V DC, voltage limits 2127 V, <= 200 mAfor overload and short-circuit protection
Analogue input number	2
Analogue input type	Al1-/Al1+ bipolar differential voltage +/- 10 V DC, input voltage 24 V max, resolution 11 bits + sign Al2 software-configurable current 020 mA, impedance 242 Ohm, resolution 11 bits Al2 software-configurable voltage 010 V DC, input voltage 24 V max, impedance 30000 Ohm, resolution 11 bits
Sampling duration	Al1-/Al1+ 2 ms, +/- 0.5 ms analog input(s) Al2 2 ms, +/- 0.5 ms analog input(s) Ll1Ll5 2 ms, +/- 0.5 ms discrete input(s) Ll6 (if configured as logic input) 2 ms, +/- 0.5 ms discrete input(s)
Response time	<= 100 ms in STO (Safe Torque Off) AO1 2 ms, tolerance +/- 0.5 ms analog output(s) R1A, R1B, R1C 7 ms, tolerance +/- 0.5 ms discrete output(s) R2A, R2B 7 ms, tolerance +/- 0.5 ms discrete output(s)
Accuracy	Al1-/Al1+ +/- 0.6 % for a temperature variation 60 °C Al2 +/- 0.6 % for a temperature variation 60 °C AO1 +/- 1 % for a temperature variation 60 °C
Linearity error	Al1-/Al1+, Al2 +/- 0.15 % of maximum value AO1 +/- 0.2 %
Analogue output number	1
Analogue output type	AO1 software-configurable current 020 mA, impedance 500 Ohm, resolution 10 bits AO1 software-configurable logic output 10 V <= 20 mA AO1 software-configurable voltage 010 V DC, impedance 470 Ohm, resolution 10 bits
Discrete output number	2
Discrete output type	R1A, R1B, R1C configurable relay logic NO/NC, electrical durability 100000 cycles R2A, R2B configurable relay logic NO, electrical durability 100000 cycles
Minimum switching current	Configurable relay logic 3 mAat 24 V DC
Maximum switching current	R1, R2 on resistive load, 5 Aat 250 V AC, cos phi = 1, R1, R2 on resistive load, 5 Aat 30 V DC, cos phi = 1, R1, R2 on inductive load, 2 Aat 250 V AC, cos phi = 0.4, R1, R2 on inductive load, 2 Aat 30 V DC, cos phi = 0.4,
Discrete input number	7
Discrete input type	LI6: switch-configurable 24 V DC with level 1 PLC, impedance: 3500 Ohm PWR: safety input 24 V DC, impedance: 1500 Ohm conforming to ISO 13849-1 level d
	LI1LI5: programmable 24 V DC with level 1 PLC, impedance: 3500 Ohm LI6: switch-configurable PTC probe 06, impedance: 1500 Ohm
Discrete input logic	LI1LI5 positive logic (source), < 5 V (state 0), > 11 V (state 0) LI1LI5 negative logic (sink), > 16 V (state 0), < 10 V (state 0) LI6 (if configured as logic input) positive logic (source), < 5 V (state 0), > 11 V (state 0) LI6 (if configured as logic input) negative logic (sink), > 16 V (state 0), < 10 V (state 0)
Acceleration and deceleration ramps	Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s



	S, U or customized
Braking to standstill	By DC injection
Protection type	Drive against exceeding limit speed
	Drive against input phase loss  Drive break on the control circuit
	Drive input phase breaks
	Drive line supply overvoltage
	Drive line supply undervoltage
	Drive overcurrent between output phases and earth
	Drive overheating protection Drive overvoltages on the DC bus
	Drive short-circuit between motor phases
	Drive thermal protection
	Motor motor phase break
	Motor thermal protection
culation registance	Motor thermal protection > 1 mOhm at 500 V DC for 1 minute to earth
sulation resistance	Analog input 0.024/50 Hz
requency resolution	Display unit 0.1 Hz
ommunication port protocol	CANopen
	Modbus
onnector type	1 RJ45 Modbus on front face
	1 RJ45 Modbus on terminal
	Male SUB-D 9 on RJ45 CANopen
nysical interface	2-wire RS 485 Modbus
ansmission frame	RTU Modbus
ansmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps CANopen
	4800 bps, 9600 bps, 19200 bps, 38.4 Kbps Modbus on terminal 9600 bps, 19200 bps Modbus on front face
ta format	
ia ioiiilat	8 bits, 1 stop, even parity Modbus on front face 8 bits, odd even or no configurable parity Modbus on terminal
umber of addresses	1247 Modbus
2	1247 Modulus 1127 CANopen
ethod of access	Slave CANopen
arking	CE
perating position	Vertical +/- 10 degree
eight	40.24 in (1022 mm)
epth	14.84 in (377 mm)
Vidth	14.17 in (360 mm)
roduct weight	233.69 lb(US) (106 kg)
ption card	CC-Link communication card
	Controller inside programmable card
	DeviceNet communication card Ethernet/IP communication card
	Fipio communication card
	I/O extension card
	Interbus-S communication card
	Interface card for encoder  Modbus Plus communication card
	Modbus TCP communication card
	Modbus/Uni Tolway communication card

### **Environment**

noise level	69.5 dB conforming to 86/188/EEC				
dielectric strength	2830 V DC between earth and power terminals 4230 V DC between control and power terminals				
electromagnetic compatibility	Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 1.2/50 µs - 8/20 µs surge immunity test conforming to IEC 61000-4-5 level 3				
standards	IEC 60721-3-3 class 3C2 UL Type 1				

Modbus/Uni-Telway communication card

Profibus DP communication card Profibus DP V1 communication card

Overhead crane card



product certifications	CSA C-Tick GOST NOM 117 UL
pollution degree	2 conforming to EN/IEC 61800-5-1 3 conforming to UL 840
IP degree of protection	IP00 conforming to EN/IEC 60529 IP00 conforming to EN/IEC 61800-5-1 IP30 on side parts conforming to EN/IEC 60529 IP30 on side parts conforming to EN/IEC 61800-5-1 IP30 on the front panel conforming to EN/IEC 60529 IP30 on the front panel conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529 IP54 on lower part conforming to EN/IEC 60529 IP554 on lower part conforming to EN/IEC 61800-5-1
vibration resistance	1.5 mm peak to peak (f = 310 Hz) conforming to EN/IEC 60068-2-6 0.6 gn (f = 10200 Hz) conforming to EN/IEC 60068-2-6
shock resistance	7 gn 11 ms conforming to EN/IEC 60068-2-27
relative humidity	595 % without condensation conforming to IEC 60068-2-3 595 % without dripping water conforming to IEC 60068-2-3
ambient air temperature for operation	14122 °F (-1050 °C) without derating
ambient air temperature for storage	-13158 °F (-2570 °C)
operating altitude	<= 3280.84 ft (1000 m) without derating 3280.849842.52 ft (10003000 m) with current derating 1 % per 100 m

## Offer Sustainability

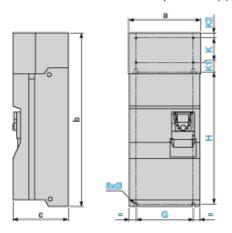
Green Premium product	Green Premium product				
Compliant - since 0946 - Schneider Electric declaration of conformity	Compliant - since 0946 - Schneider Electric declaration of conformity				
Reference not containing SVHC above the threshold	Reference not containing SVHC above the threshold				
Available	Available				
Need no specific recycling operations	Need no specific recycling operations				
WARNING: This product can expose you to chemicals including:	WARNING: This product can expose you to chemicals including:				
Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm.	Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm.				
Bisphenol A (BPA), which is known to the State of California to cause birth defects or other reproductive harm.	Bisphenol A (BPA), which is known to the State of California to cause birth defects or other reproductive harm.				
For more information go to www.p65warnings.ca.gov	For more information go to www.p65warnings.ca.gov				

## Contractual warranty

Warranty period 18 months
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## **UL Type 1/IP 20 Drives**

## Dimensions with or without 1 Option Card (1)





#### Dimensions in mm

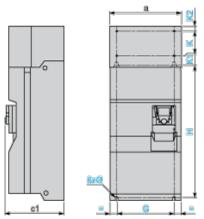
а	b	С	G	Н	K	K1	K2	Ø
360	1022	377	298	758	150	72	30	11.5

#### Dimensions in in.

а	b	С	G	Н	K	K1	K2	Ø
14.17	40.24	14.84	11.73	29.84	5.90	2.83	1.18	0.45

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

#### **Dimensions with 2 Option Cards (1)**



Dimensions in mm

а	c1	G	Н	K	K1	K2	Ø
360	392	298	758	150	72	30	11.5

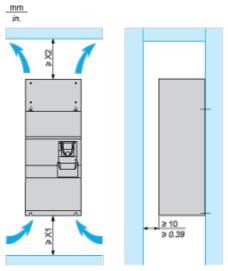
Dimensions in in.

а	c1	G	Н	K	K1	K2	Ø
14.17	15.43	11.73	29.84	5.90	2.83	1.18	0.45

(1) Option cards: I/O extension cards, communication cards or "Controller Inside" programmable card.

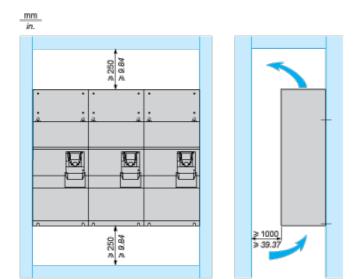
## **Mounting Recommendations**

#### Clearance



X1 in mm	X2 in mm	X1 in in.	X2 in in.
100	100	3.94	3.94

These drives can be mounted side by side, observing the following mounting recommendations:

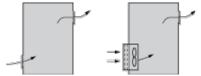


### Specific Recommendations for Mounting the Drive in an Enclosure

#### Ventilation

To ensure proper air circulation in the drive:

- Fit ventilation grilles.
- Ensure that there is sufficient ventilation. If there is not, install a forced ventilation unit with a filter. The openings and/or fans must provide a flow rate at least equal to that of the drive fans (refer to the product characteristics).



- Use special filters with IP 54 protection.
- Remove the blanking cover from the top of the drive.

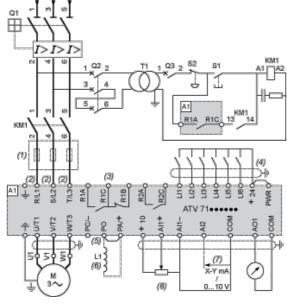
### **Dust and Damp Proof Metal Enclosure (IP 54)**

The drive must be mounted in a dust and damp proof enclosure in certain environmental conditions: dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc.

This enables the drive to be used in an enclosure where the maximum internal temperature reaches 50°C.

# Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply with Upstream Breaking via Contactor



A1 ATV71 drive

#### KM1 Contactor

- L1 DC choke
- Q1 Circuit-breaker
- Q2 GV2 L rated at twice the nominal primary current of T1
- Q3 GB2CB05
- \$1, XB4 B or XB5 A pushbuttons

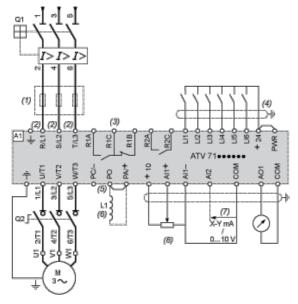
S<sub>2</sub>

- T1 100 VA transformer 220 V secondary
- (1) Line choke (three-phase); mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

# Wiring Diagram Conforming to Standards EN 954-1 Category 1, IEC/EN 61508 Capacity SIL1, in Stopping Category 0 According to IEC/EN 60204-1

#### Three-Phase Power Supply with Downstream Breaking via Switch Disconnector

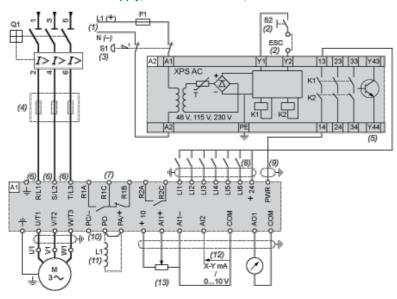


- A1 ATV71 drive
- L1 DC choke
- Q1 Circuit-breaker
- Q2 Switch disconnector (Vario)
- (1) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (2) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (3) Fault relay contacts. Used for remote signalling of the drive status.
- (4) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (5) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (6) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (7) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (8) Reference potentiometer.



# Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 0 According to IEC/EN 60204-1

Three-Phase Power Supply, Low Inertia Machine, Vertical Movement



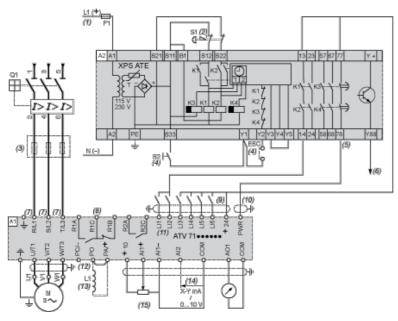
- A1 ATV71 drive
- A2 Preventa XPS AC safety module for monitoring emergency stops and switches. One safety module can manage the "Power Removal" function for several drives on the same machine. In this case, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS AC module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- \$1 Emergency stop button with 2 contacts
- \$2 XB4 B or XB5 A pushbutton
- (1) Power supply: 24 Vdc or Vac, 48 Vac, 115 Vac, 230 Vac.
- (2) S2: resets XPS AC module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (3) Requests freewheel stopping of the movement and activates the "Power Removal" safety function.
- (4) Line choke (three-phase), mandatory for and ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (5) The logic output can be used to signal that the machine is in a safe stop state.
- (6) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (7) Fault relay contacts. Used for remote signalling of the drive status.
- (8) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (9) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm /0.09 in., maximum length 15 m / 49.21 ft. The cable shielding must be earthed.
- (10) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (11) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (12) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (13) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

# Wiring Diagram Conforming to Standards EN 954-1 Category 3, IEC/EN 61508 Capacity SIL2, in Stopping Category 1 According to IEC/EN 60204-1

Three-Phase Power Supply, High Inertia Machine



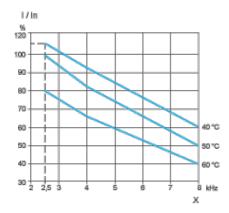


- A1 ATV71 drive
- A2 Preventa XPS ATE safety module for monitoring emergency stops and switches. One safety module can manage the "Power
- (5) Removal" safety function for several drives on the same machine. In this case the time delay must be adjusted on the drive controlling the motor that requires the longest stopping time. In addition, each drive must connect its PWR terminal to its + 24 V via the safety contacts on the XPS ATE module. These contacts are independent for each drive.
- F1 Fuse
- L1 DC choke
- Q1 Circuit-breaker
- \$1 Emergency stop button with 2 N/C contacts
- S2 Run button
- (1) Power supply: 24 Vdc or Vac, 115 Vac, 230 Vac.
- (2) Requests controlled stopping of the movement and activates the "Power Removal" safety function.
- (3) Line choke (three-phase), mandatory for ATV71HC11Y...HC63Y drives (except when a special transformer is used (12-pulse)).
- (4) S2: resets XPS ATE module on power-up or after an emergency stop. ESC can be used to set external starting conditions.
- (5) For stopping times requiring more than 30 seconds in category 1, use a Preventa XPS AV safety module which can provide a maximum time delay of 300 seconds.
- (6) The logic output can be used to signal that the machine is in a safe state.
- (7) For ATV71HC40N4 drives combined with a 400 kW motor, ATV71HC50N4 and ATV71HC40Y...HC63Y, refer to the power terminal connections diagram.
- (8) Fault relay contacts. Used for remote signalling of the drive status.
- (9) Connection of the common for the logic inputs depends on the positioning of the SW1 switch. The above diagram shows the internal power supply switched to the "source" position (for other connection types, refer to the user guide).
- (10) Standardized coaxial cable, type RG174/U according to MIL-C17 or KX3B according to NF C 93-550, external diameter 2.54 mm/0.09 in., maximum length 15 m/49.21 ft. The cable shielding must be earthed.
- (11) Logic inputs LI1 and LI2 must be assigned to the direction of rotation: LI1 in the forward direction and LI2 in the reverse direction.
- (12) There is no PO terminal on ATV71HC11Y...HC63Y drives.
- (13) Optional DC choke for ATV71H•••M3, ATV71HD11M3X...HD45M3X, ATV71•075N4...•D75N4 and ATV71P•••N4Z drives. Connected in place of the strap between the PO and PA/+ terminals. For ATV71HD55M3X, HD75M3X, ATV71HD90N4...HC50N4 drives, the choke is supplied with the drive; the customer is responsible for connecting it.
- (14) Software-configurable current (0...20 mA) or voltage (0...10 V) analog input.
- (15) Reference potentiometer.

All terminals are located at the bottom of the drive. Fit interference suppressors on all inductive circuits near the drive or connected on the same circuit, such as relays, contactors, solenoid valves, fluorescent lighting, etc.

#### **Derating Curves**

The derating curves for the drive nominal current (In) depend on the temperature and the switching frequency. For intermediate temperatures (e.g. 55°C), interpolate between 2 curves.



X Switching frequency



OOO «ЛайфЭлектроникс" "LifeElectronics" LLC

ИНН 7805602321 КПП 780501001 P/C 40702810122510004610 ФАКБ "АБСОЛЮТ БАНК" (ЗАО) в г.Санкт-Петербурге К/С 3010181090000000703 БИК 044030703

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- Подбор аналогов.
- Поставку компонентов в любых объемах, удовлетворяющих вашим потребностям.
- Приемлемые сроки поставки, возможна ускоренная поставка.
- Доставку товара в любую точку России и стран СНГ.
- Комплексную поставку.
- Работу по проектам и поставку образцов.
- Формирование склада под заказчика.
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Конструкторский отдел помогает осуществить:

- Регистрацию проекта у производителя компонентов.
- Техническую поддержку проекта.
- Защиту от снятия компонента с производства.
- Оценку стоимости проекта по компонентам.
- Изготовление тестовой платы монтаж и пусконаладочные работы.



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