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MAX40056F/MAX40056T/ MAX40056U

General Description

The MAX40056 is a bidirectional current-sense amplifier with an input common-mode range that extends from -0.1V to +65V together with protection against negative inductive kickback voltages to -5V. This CSA is well-suited for phase current monitoring of inductive loads, such as motors and solenoids, where pulse width modulation is used to control the drive voltage and current. The MAX40056 uses an improved technique to help reject common-mode input PWM edges with slew rates up to and beyond $\pm 500\text{V}/\mu\text{s}$. Common mode rejection ratio (CMRR) is typically 60dB (50V, $\pm 500\text{V}/\mu\text{s}$ input) and 140dB DC, typical.

The MAX40056 has an internal +1.5V reference for use with a nominal +3.3V power supply. The reference can also be used to drive an adjoining differential ADC. The reference is used to offset the output to indicate the direction of the input sensed current. The REF pin can source current into external loads and helps to avoid the performance compromises resulting from routing reference voltages across noisy PCBs. Alternatively, for higher supply voltages and higher full-scale output swings, the internal reference can be overridden by a higher voltage, external reference.

The internal or external reference can be used to define the trip threshold for the integrated overcurrent comparator. This can provide immediate indication of an overcurrent fault condition.

The MAX40056 operates over the full -40°C to $+125^{\circ}\text{C}$ temperature range and runs from a supply voltage of +2.7V to +5.5V. It is offered in a 2.02mm x 1.4mm 8-pin wafer-level package (WLP) and 8-pin μMAX packages.

Applications

- PWM H-Bridge Motor In-line/In-phase/Winding Current Sensing
- Solenoid Current Sensing
- Current Monitoring of Inductive Loads
- Battery Stack Monitors
- Automotive

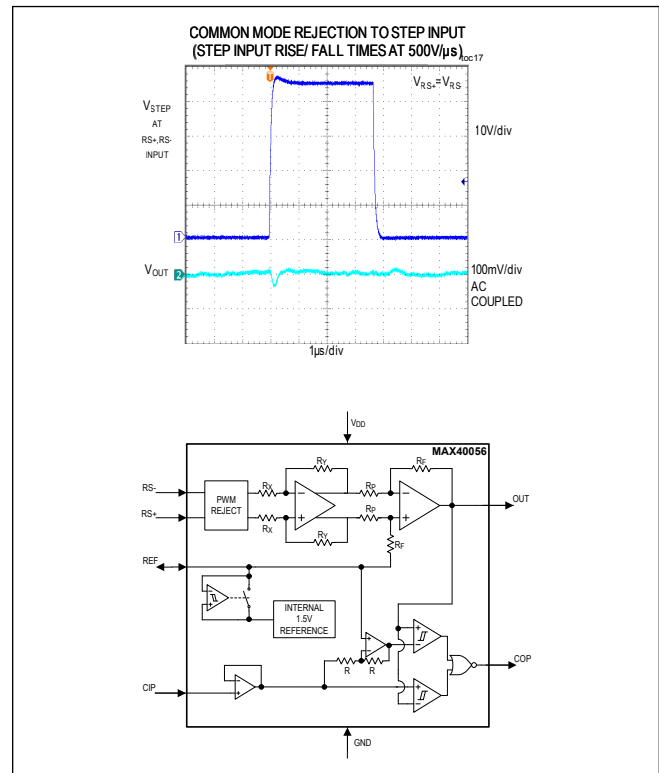
Bidirectional Current Sense Amplifier with PWM-Rejection

Benefits and Features

- Fast, 500ns PWM Edge Recovery from $500\text{V}/\mu\text{s}$ PWM Edges
- 60dB AC CMRR Rejection at 50V, $\pm 500\text{V}/\mu\text{s}$ PWM Edges
- 140dB DC CMRR Rejection
- -0.1V to +65V Input Voltage Range
- -5V to +70V Protective Immunity
- 300kHz, -3dB Bandwidth
- Multiple Gain Options; 10V/V, 20V/V, 50V/V
- Internal, 1% Reference for Bidirectional Offset
- 5 μV (Typ) Input Offset Voltage
- Rail-to-Rail Output
- 2.02mm x 1.4mm WLP-8 and 8-pin μMAX
- -40°C to $+125^{\circ}\text{C}$ Temperature Range

[Ordering Information](#) appears at end of data sheet.

Typical Operating Characteristic and Simplified Block Diagram



Absolute Maximum Ratings

RS+ and RS- to GND	-5V to +70V	Continuous Current in RS+ and RS-.....	10mA
RS+ to RS-	±2V	Continuous Power Dissipation (Multi Layer Board) (T _A = +70°C, derate 4.8mW/°C above +70°C)	390mW
V _{DD} to GND.....	-0.3V to +6V	Operating Temperature Range	-40°C to +125°C
REF, CIP, OUT, COP To GND.....	-0.3V to V _{DD} + 0.3V	Storage Temperature Range	-65°C to +150°C
Continuous Current in REF, CIP	5mA		
Continuous Current in OUT and COP	10mA		

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Package Information

8 μMAX

Package Code	U8+4
Outline Number	21-0036
Land Pattern Number	90-0092
Thermal Resistance, Four-Layer Board:	
Junction-to-Ambient (θ _{JA})	206°C/W
Junction-to-Case Thermal Resistance (θ _{JC})	42°C/W

8 WLP

Package Code	W81B2+1
Outline Number	21-100255
Land Pattern Number	Refer to Application Note 1891
Thermal Resistance, Four-Layer Board:	
Junction-to-Ambient (θ _{JA})	74.65°C/W

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

Electrical Characteristics

($V_{DD} = 3.3V$, $V_{CM} = 48V$, $V_{SENSE} = 20mV$, OUT loading = 10k Ω and 20pF to GND, COP loading = 5k Ω and 10pF to GND, $T_{MIN} = -40^{\circ}C$, $T_{MAX} = 125^{\circ}C$, (Note 1))

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
POWER SUPPLY CHARACTERISTICS						
Supply Voltage	V_{DD}	Guaranteed by PSRR	2.7		5.5	V
Supply Current	I_{DD}			6	9	mA
Power-Up Time	t_{PWR_UP}	Out settle within 1%		400		μs
CURRENT SENSE AMPLIFIER / DC CHARACTERISTICS						
Input Protected CM Range	V_{CM_P}		-5		+70	V
Input Common Mode Range	V_{CM}	$-40^{\circ}C \leq T_A \leq +85^{\circ}C$	-0.3		+65	V
		$-40^{\circ}C \leq T_A \leq +125^{\circ}C$	-0.1		+65	
Input Bias Current	I_{RS+}, I_{RS-}	$V_{SENSE} = 0V$ (Note 2)		3	200	nA
		$V_{SENSE} = 20mV$		20	30	μA
Input Leakage Current	I_{LKG}	$V_{DD} = 0V, 0V \leq V_{RS\pm} \leq 65V$ (Note 2)		3	200	nA
Input Offset Voltage	V_{OS}	$T_A = +25^{\circ}C$		5	20	μV
		$-40^{\circ}C \leq T_A \leq +125^{\circ}C$			300	
Input Offset Drift	TCV_{OS}			0.5		$\mu V/^{\circ}C$
Power Supply Rejection Ratio	PSRR	$2.7V \leq V_{DD} \leq 5.5V$	90	110		dB
Common Mode Rejection Ratio	CMRR	$-0.3V \leq V_{CM} \leq +65V; -40^{\circ}C \leq T_A \leq +85^{\circ}C$	100	140		
		$-0.1V \leq V_{CM} \leq +65V; -40^{\circ}C \leq T_A \leq +125^{\circ}C$	120	140		
Input Capacitance	C_{IN}	RS+ and RS- input		3		pF
Nominal Gain	G_U	MAX40056U		10		V/V
	G_T	MAX40056T		20		
	G_F	MAX40056F		50		
Gain Error	GE_F	$V_{CM} = -0.3V, -40^{\circ}C \leq T_A \leq +85^{\circ}C, -16mV \leq V_{SENSE} \leq +16mV, MAX40056F$		0.05	1.5	%
		$V_{CM} = 48V, -40^{\circ}C \leq T_A \leq +125^{\circ}C, -16mV \leq V_{SENSE} \leq +16mV, MAX40056F$		0.05	0.5	
Output Voltage Swing High	V_{OH}	Sourcing 5mA; $V_{OH} = V_{DD} - V_{OUT}$		45	100	mV
Output Voltage Swing Low	V_{OL}	Sinking 5mA; $V_{OL} = V_{OUT} - GND$		35	70	mV
Output Short-Circuit Current	I_{SC}	Shorted to either V_{DD} or GND		20		mA
CURRENT SENSE AMPLIFIER / AC CHARACTERISTICS						
Signal Bandwidth	BW_{-3dB}	50% of full-scale range		300		kHz
Output Slew Rate	SR	$2V_{PP}$ output square wave, centered at 1.5V		1.5		V/ μs
Amplifier Small-Signal Settling Time (1%)	t_s	$\pm 200mV$ output step		2.5		μs

Electrical Characteristics (continued)

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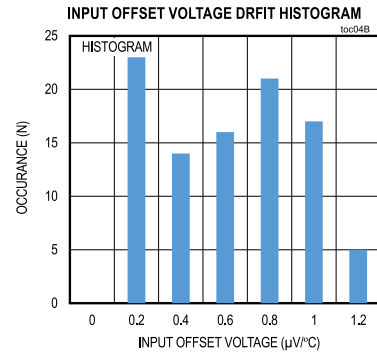
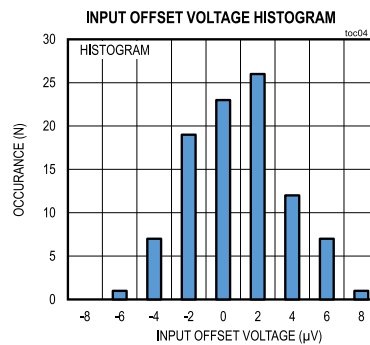
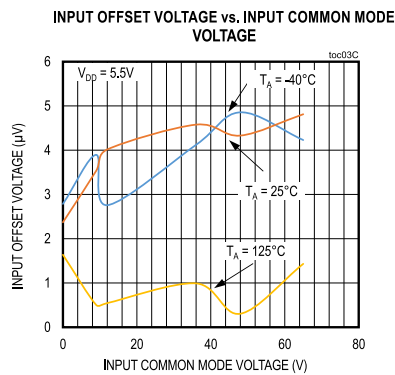
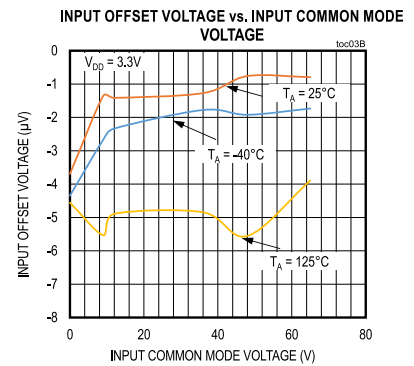
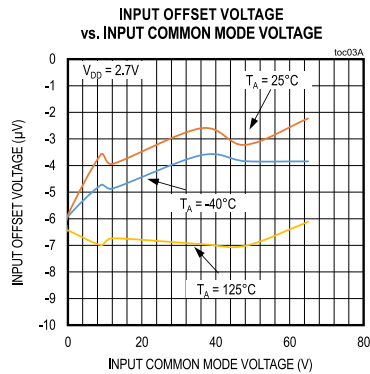
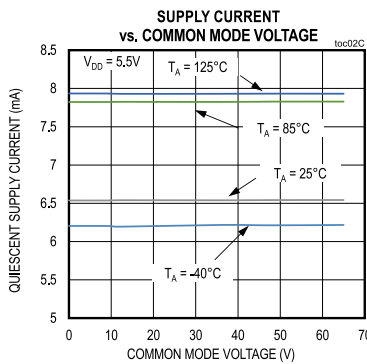
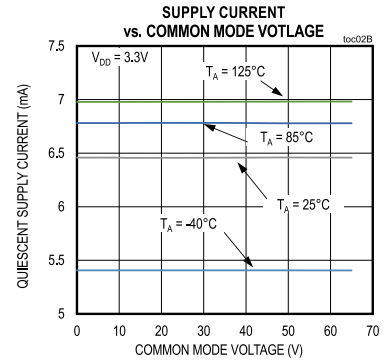
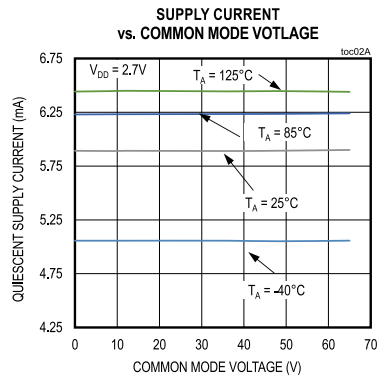
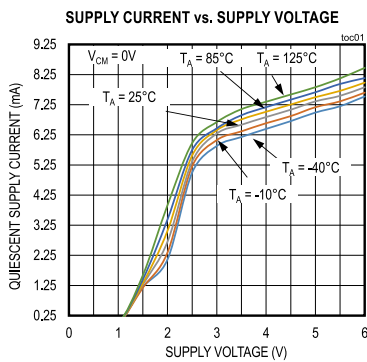
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
PWM Edge Recovery Settling Time	t_{S_PWM}	0V to 50V edges: 500V/ μs rise/fall times, $V_{SENSE} = 0mV$ ($V_{RS+} = V_{RS-}$)		500		ns
AC Common Mode Rejection Ratio	AC CMRR	100mV _{AC} Sine, f = 100kHz		70		dB
AC Power Supply Rejection Ratio	AC PSRR	100mV _{AC} Sine, f = 100kHz		53		dB
Voltage Noise Density	e_n	At 10kHz		150		nV/ \sqrt{Hz}
INTERNAL REFERENCE						
REF Output Voltage	V_{REF}	No load; $-40^{\circ}C \leq T_A \leq +125^{\circ}C$	1.485	1.5	1.515	V
REF Thermal Drift	TCV_{REF}			30		ppm/ $^{\circ}C$
REF Load Regulation	$\Delta V_{REF}/\Delta I_{REF}$	$0\mu A \leq \text{external load} \leq 500\mu A$		30	70	$\mu V/\mu A$
REF Line Regulation	$\Delta V_{REF}/\Delta V_{DD}$	$2.7V \leq V_{DD} \leq 5.5V$		0.1	0.5	mV/V
REF Cap Loading		No sustained oscillation		1		μF
Internal\External Reference Switching Threshold Voltage	V_{REF_TH}	External reference is enabled by overdriving		1.65	1.75	V
INTERNAL COMPARATOR						
CIP Input Resistance	R_{CIP}	Resistance appears to be to V_{REF}		10		G Ω
CIP Input Common Mode Range	V_{CIP_IN}		0.08		MIN ($V_{REF} - 0.08$, $V_{DD} - 1.25$)	V
Input Offset Voltage	V_{OS_CMP}	$80mV \leq V_{CIP} \leq \text{min}$ ($V_{REF} - 80mV$, $V_{DD} - 1.25V$)		10		mV
Hysteresis	V_{HYS}	$80mV \leq V_{CIP} \leq \text{min}$ ($V_{REF} - 80mV$, $V_{DD} - 1.25V$)		40		mV
COP Output Voltage Swing High	V_{OH_CMP}	Sourcing 2mA; $V_{OH_CMP} = V_{DD} - V_{COP}$		0.12	0.3	V
COP Output Voltage Swing Low	V_{OL_CMP}	Sinking 4mA; $V_{OL_CMP} = V_{COP} - GND$		0.12	0.3	V
Propagation Delay	$t_{PDL \rightarrow H}$	200mV overdrive, low-to-high		14		μs
	$t_{PDH \rightarrow L}$	200mV overdrive, high-to-low		12		

Note 1: Limits are 100% tested at $T_A = +25^{\circ}C$. Limits over the operating temperature range and relevant supply voltage range are guaranteed by design and characterization.

Note 2: Guaranteed by design and bench characterization.

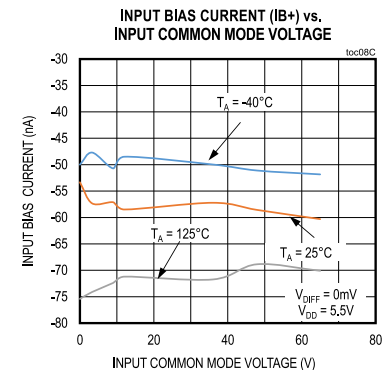
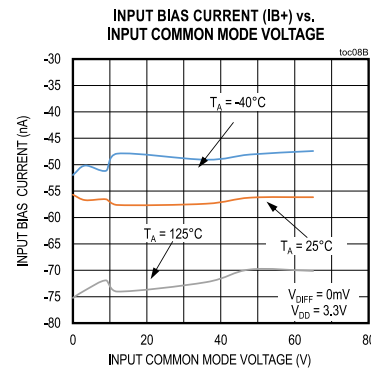
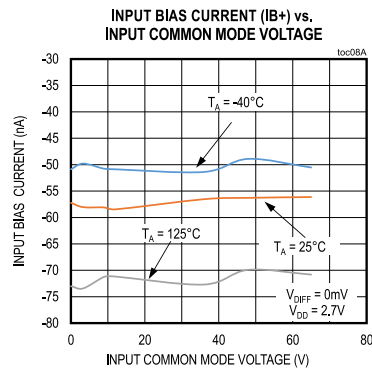
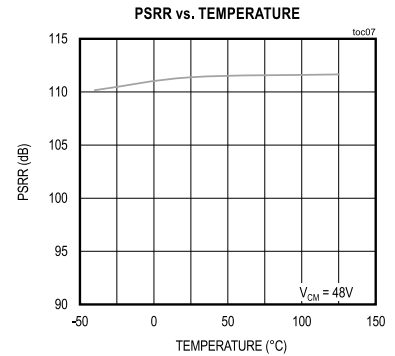
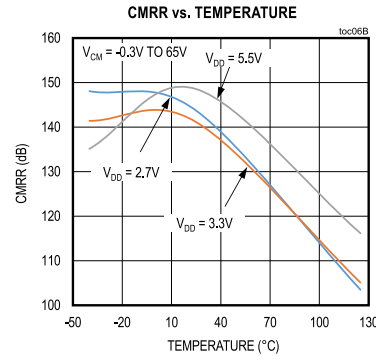
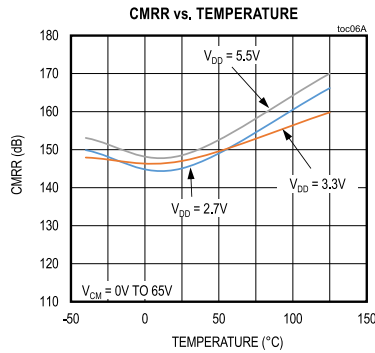
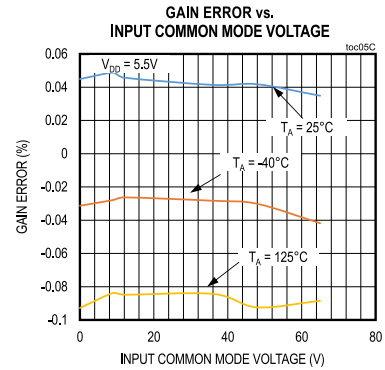
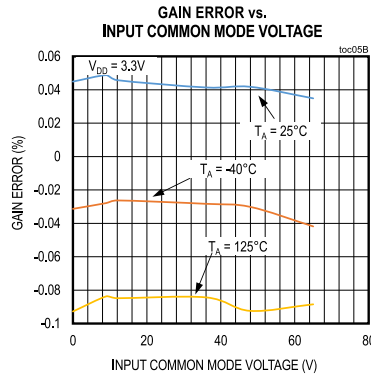
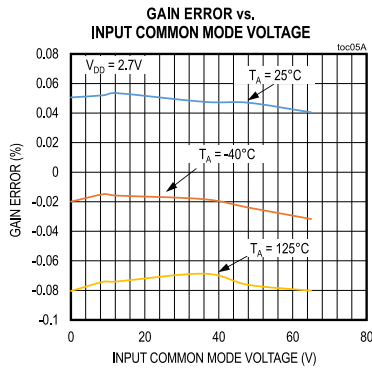
Typical Operating Characteristics

($V_{DD} = 3.3V$, $V_{SENSE} = 20mV$, $V_{CM} = 48V$, OUT LOAD = 10k Ω and 20pF to GND, COP LOAD = 5k Ω and 10pF to GND, $T_A = +25^\circ C$, unless otherwise noted.)



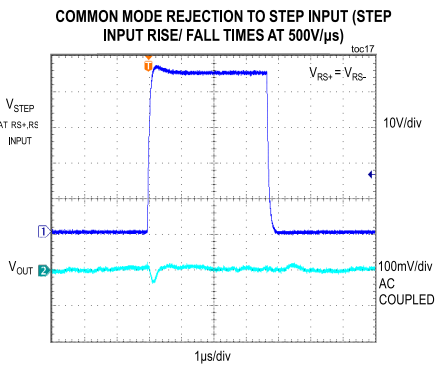
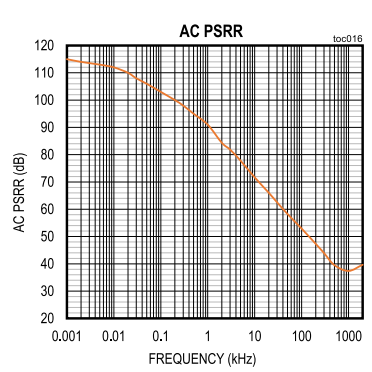
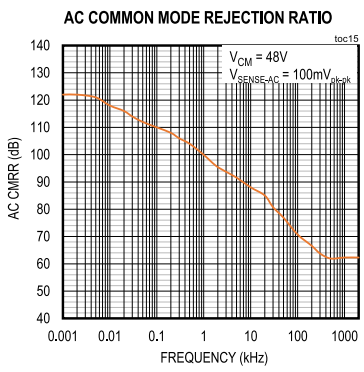
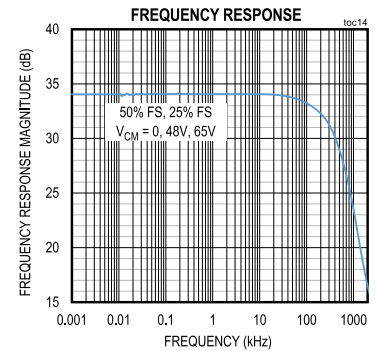
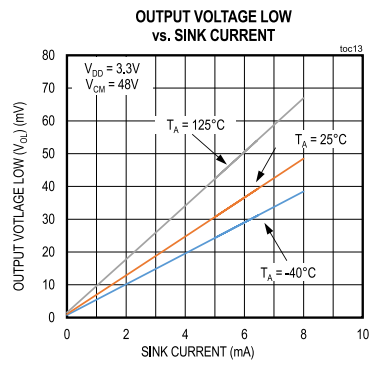
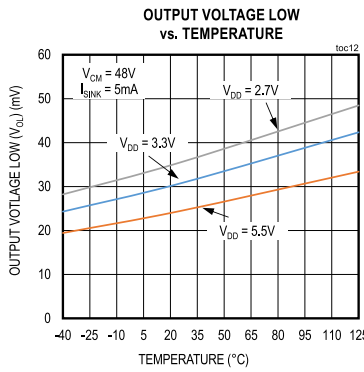
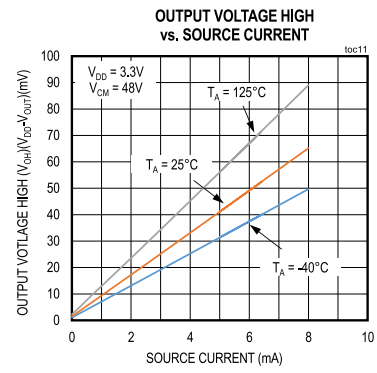
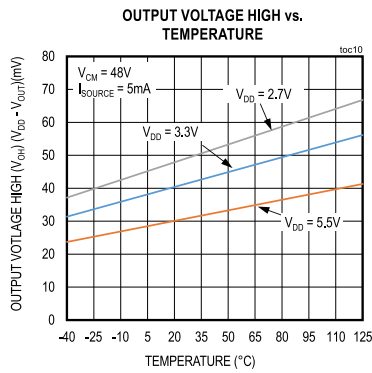
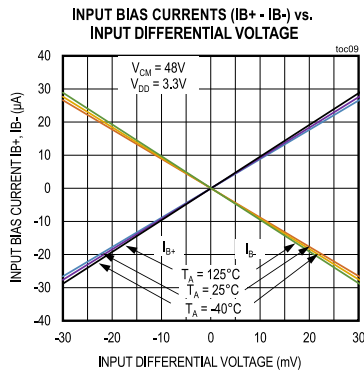
Typical Operating Characteristics (continued)

($V_{DD} = 3.3V$, $V_{SENSE} = 20mV$, $V_{CM} = 48V$, OUT LOAD = 10k Ω and 20pF to GND, COP LOAD = 5k Ω and 10pF to GND, $T_A = +25^\circ C$, unless otherwise noted.)



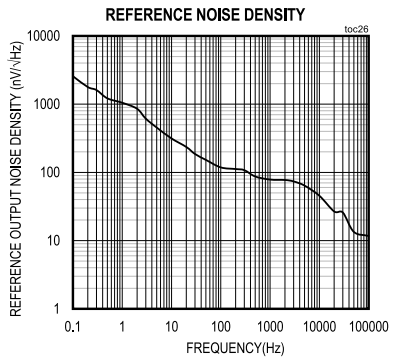
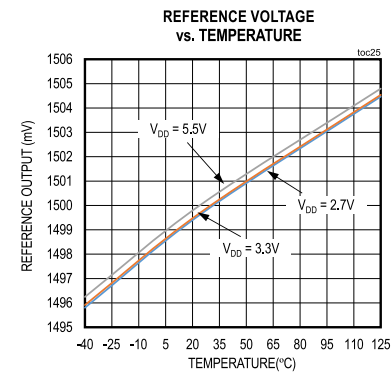
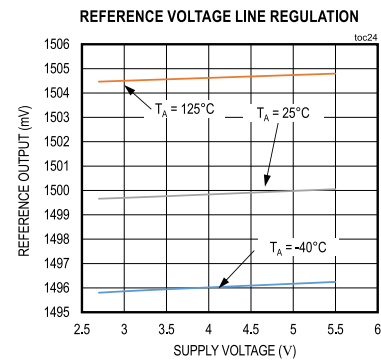
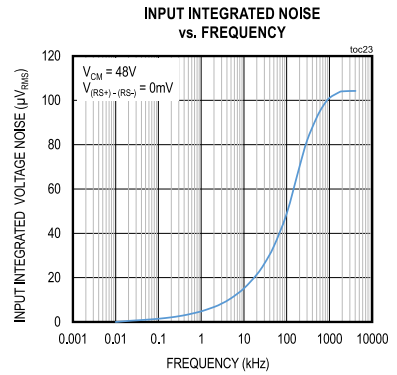
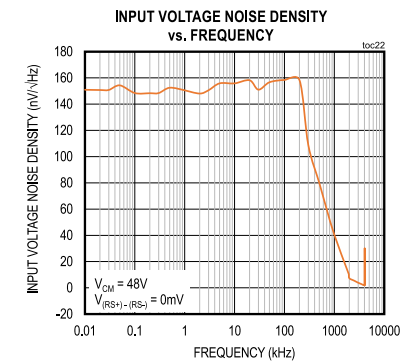
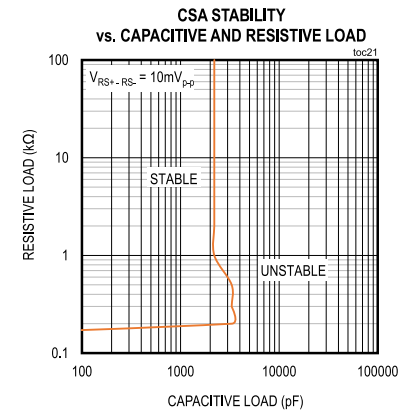
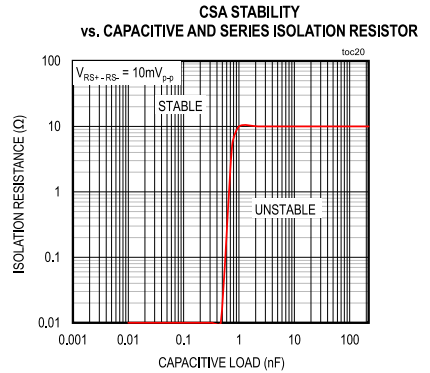
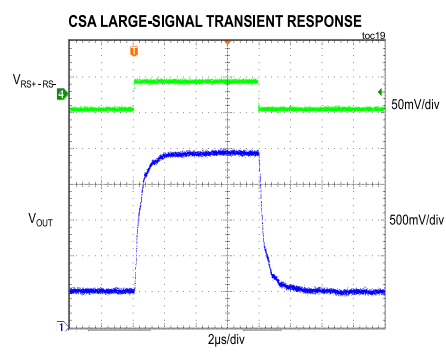
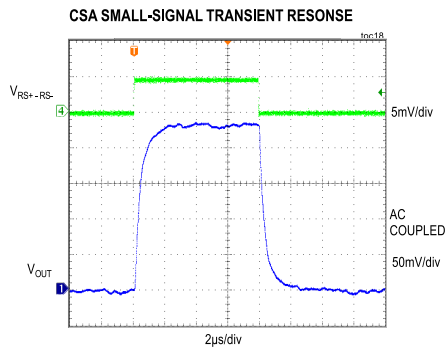
Typical Operating Characteristics (continued)

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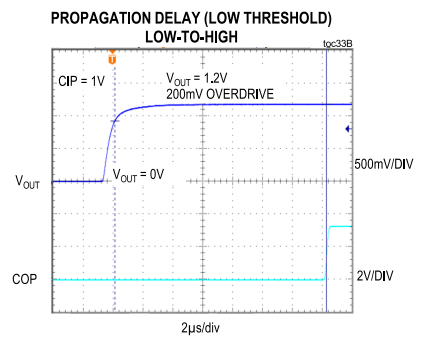
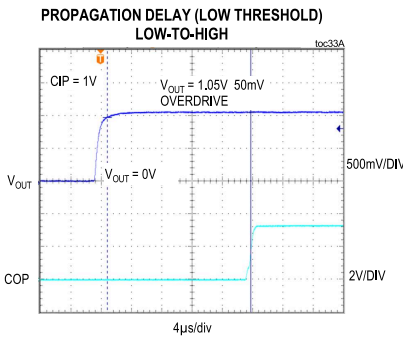
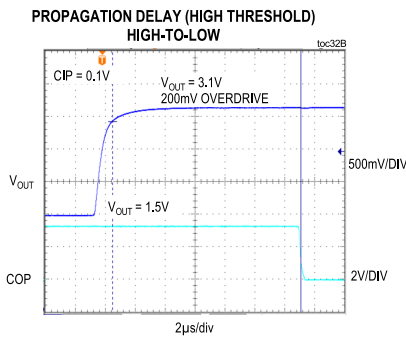
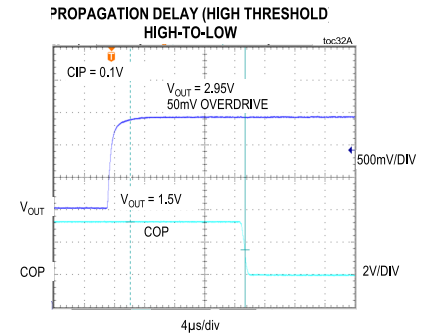
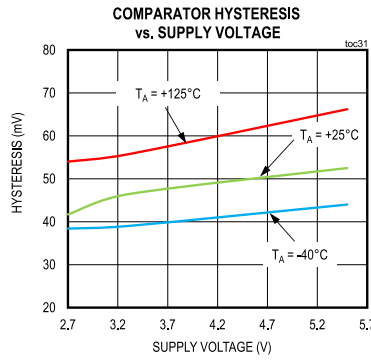
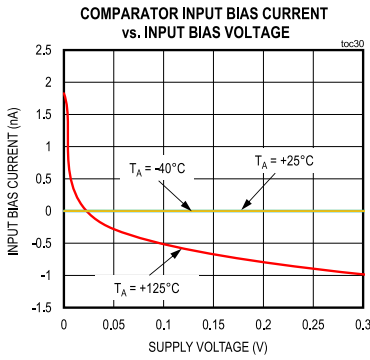
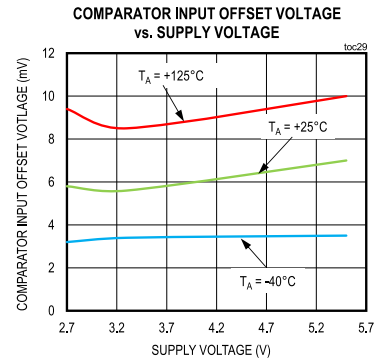
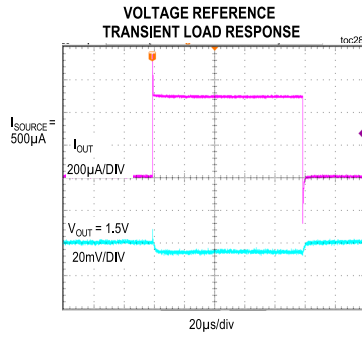
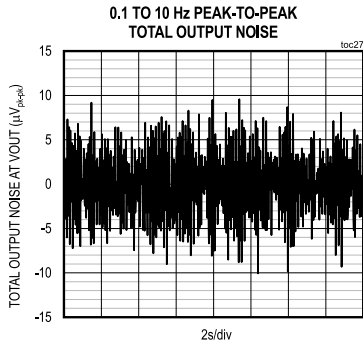
Typical Operating Characteristics (continued)

($V_{DD} = 3.3V$, $V_{SENSE} = 20mV$, $V_{CM} = 48V$, OUT LOAD = $10k\Omega$ and $20pF$ to GND, COP LOAD = $5k\Omega$ and $10pF$ to GND, $T_A = +25^\circ C$, unless otherwise noted.)



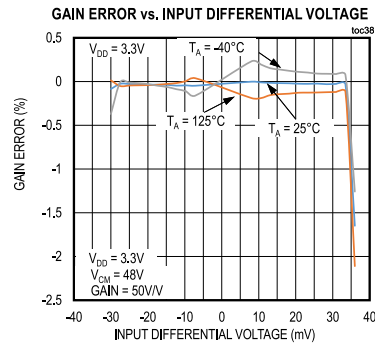
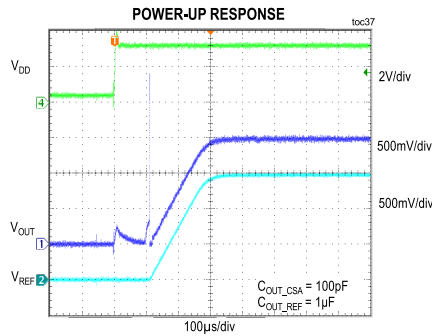
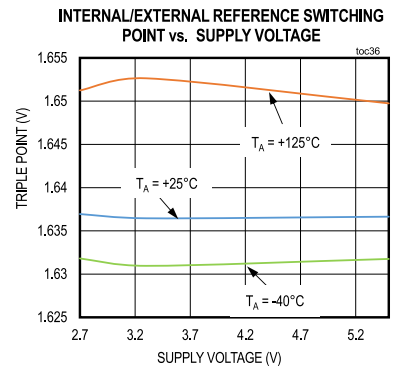
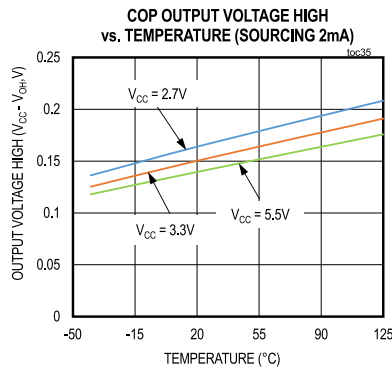
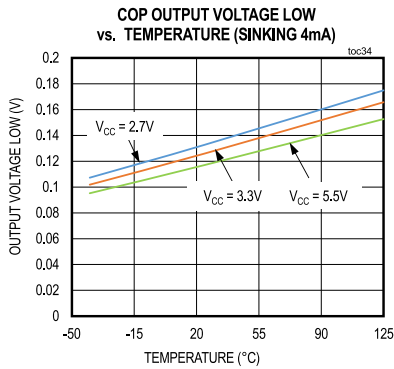
Typical Operating Characteristics (continued)

($V_{DD} = 3.3V$, $V_{SENSE} = 20mV$, $V_{CM} = 48V$, OUT LOAD = $10k\Omega$ and $20pF$ to GND, COP LOAD = $5k\Omega$ and $10pF$ to GND, $T_A = +25^\circ C$, unless otherwise noted.)

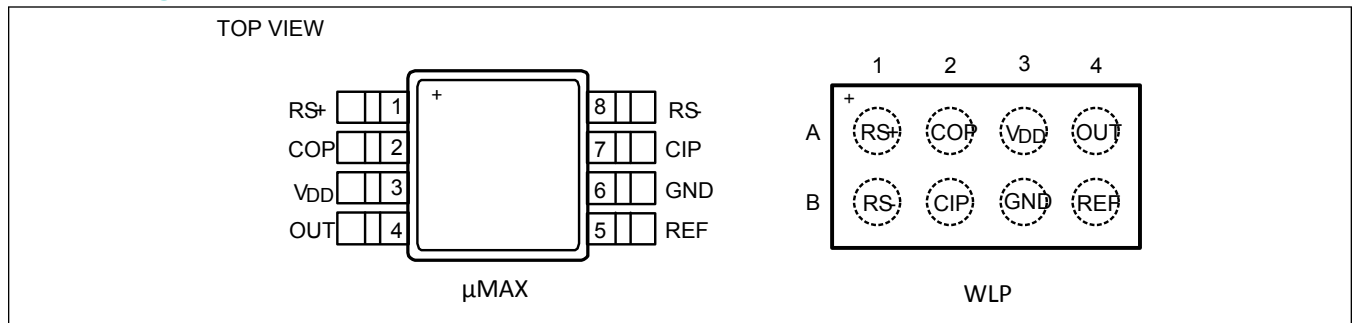


Typical Operating Characteristics (continued)

($V_{DD} = 3.3V$, $V_{SENSE} = 20mV$, $V_{CM} = 48V$, OUT LOAD = $10k\Omega$ and $20pF$ to GND, COP LOAD = $5k\Omega$ and $10pF$ to GND, $T_A = +25^\circ C$, unless otherwise noted.)



Pin Configuration



Pin Description

PIN	NAME	FUNCTION
1	RS+	External Resistor Power-Side Connection Input
2	COP	Active-Low Comparator Push-Pull Output. Output low indicates fault condition.
3	V _{DD}	Supply Voltage Input. +2.7V to +5.5V. Bypass to ground with a 10nF COG\NPO and 1μF X5R.
4	OUT	Current-Sense Output. Output has its common mode point at V _{REF} .
8	RS-	External Resistor Load-Side Connection Input
7	CIP	Comparator Input/Overcurrent Threshold Input
6	GND	Ground. Signal and power return.
5	REF	Internal 1.5V Reference Output. Intended to be used with OUT to indicate the current's direction. Bypass to GND with a 10nF and a 1μF capacitors. Connect external reference greater than 1.5V to override internal reference and change output common mode voltage.

Detailed Description

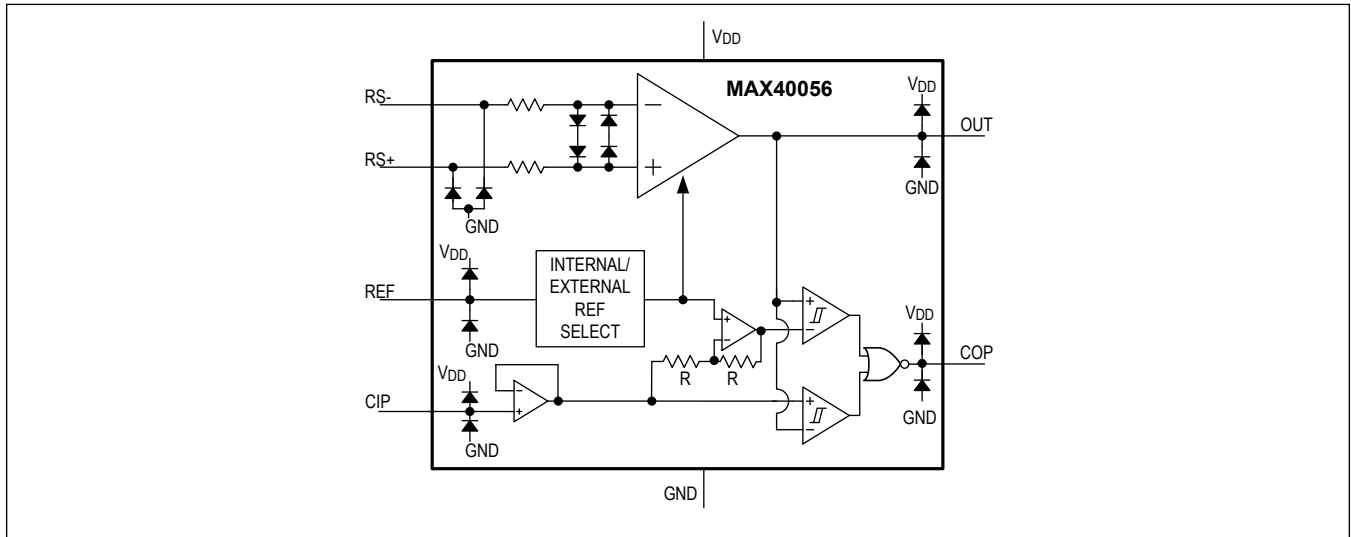


Figure 1. Internal ESD Clamping Structure

Overview

The MAX40056 is a single-supply, high-accuracy, bidirectional current sense amplifier with a high common-mode input range extending from -0.1V to +65V. The input stage provides protection against voltage spikes and inductive kickbacks from -5V up to +70V. The $\pm 5\mu\text{V}$ (typ) input offset voltage and 0.05% (typ) gain error help to ensure low system errors.

The input stage is specifically designed to suppress the disturbance of fast PWM signals, which are common in motor control applications. The MAX40056 is, therefore, well-suited for in-phase current monitoring of inductive loads, such as motor windings and solenoids that are driven by PWM signals. The MAX40056 operates over the full -40°C to $+125^\circ\text{C}$ temperature range and from a supply voltage of +2.7V to +5.5V.

[Figure 1](#) shows the internal clamping/protection structure.

PWM Rejection Input Stage

The proprietary input architecture is immune to the large PWM disturbances present in a typical motor control application. The input stage is designed to withstand -5V to +70V common-mode input voltage without damage. The MAX40056 output recovers within 500ns from PWM edges with slew rates up to and beyond $\pm 500\text{V}/\mu\text{s}$.

Low Input Offset Voltage and Low Gain Error

The MAX40056 utilizes chopper-stabilized architecture to achieve a low input offset voltage less than $\pm 20\mu\text{V}$. This technique also enables extremely low input offset voltage drift over time and temperature to $500\text{nV}/^\circ\text{C}$. The precision input V_{OS} specification allows accurate current measurements with low value current-sense resistors, thus reducing voltage drop and power dissipation on sense resistors. The optimized gain architecture achieves a gain error of less than 0.5% over the entire temperature range of -40°C to $+125^\circ\text{C}$.

CSA Output

From the functional block diagram shown, the MAX40056 CSA output is given by the following equation

$$V_{OUT} = \{I_{SENSE} \times R_{SENSE}\} \times GAIN + V_{REF} \dots (1)$$

Where, I_{SENSE} is the current to be measured, R_{SENSE} is the sense resistor value, $GAIN$ is the voltage gain of the CSA. The gain is 50V/V for the MAX40056F, 20V/V for the MAX40056T, and 10V/V for the MAX40056U respectively. V_{REF} is the reference voltage. This is either the internal integrated reference voltage (1.5V) or an external voltage reference connected to the REF input. When the sense current is positive (the current flows from the RS+ input to the RS- input through the sense resistor), the output voltage is greater than V_{REF} (V), when the sense current is negative, the output voltage is less than V_{REF} (V) indicating negative currents flowing with respect to RS+ and RS- inputs.

Voltage Reference

The voltage reference offsets the amplifier output to V_{REF} when the sensed current is 0A. From Equation (1), the direction of the sensed current can be easily determined by comparing V_{OUT} with V_{REF} .

The MAX40056 has an internal 1.5V voltage reference for use with a nominal 3.3V supply. The internal V_{REF} output can source a small amount current for external loads. The load regulation of the internal reference is 30 μ V/ μ A, so care must be taken to ensure that the accuracy of the reference is maintained when the reference is sourcing current.

When operating from higher supply voltages, a higher full-scale output swing is often desired. In this case, the internal reference can be overridden by a higher-voltage external reference. The integrated comparator constantly compares the internal reference voltage and the voltage on the REF input/output so that the higher reference voltage is always selected.

Window Comparator and Hysteresis

The MAX40056 features an integrated internal window comparator to detect both positive and negative over current conditions. The window comparator (shown in [Figure 2](#)) compares the current sense amplifier output V_{OUT} with a low threshold (V_{CIP}) and a high threshold (V_A). V_{CIP} is generated by an external resistor divider connected to the REF output, and the V_{CIP} input range should be within 80mV to MIN (($V_{REF} - 80mV$), ($V_{DD} - 1.25V$)) for proper operation. V_A is internally generated from V_{REF} and V_{CIP} : $V_A = (2 \times V_{REF}) - V_{CIP}$, with a range from ($V_{REF} + 80mV$) to ($2 \times V_{REF} - 80mV$). Either the internal or an external reference can be used to define the thresholds for the integrated window comparators.

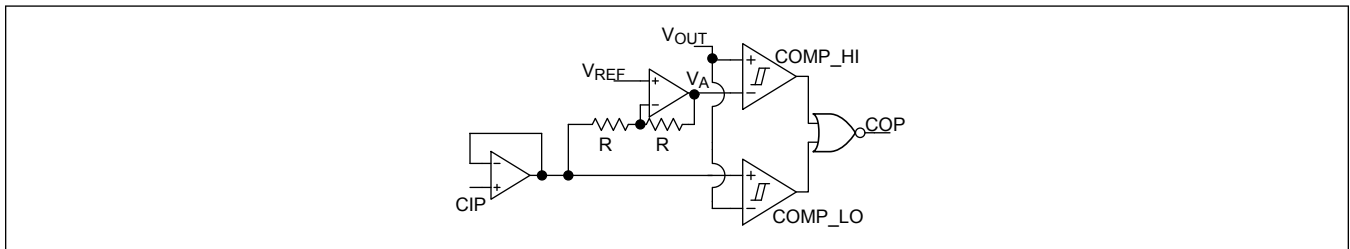


Figure 2. Internal Window Comparator

When V_{OUT} is greater than V_A or when V_{OUT} is less than V_{CIP} , the comparator output is low, indicating a fault condition. The hysteresis direction is shown in [Figure 3](#). COMP_HI and COMP_LO have the same hysteresis direction. When $V+$ rises across $V-$, both comparators have no hysteresis voltage; when $V+$ falls across $V-$, both comparators have a similar hysteresis voltage, thereby providing equivalent noise immunity.

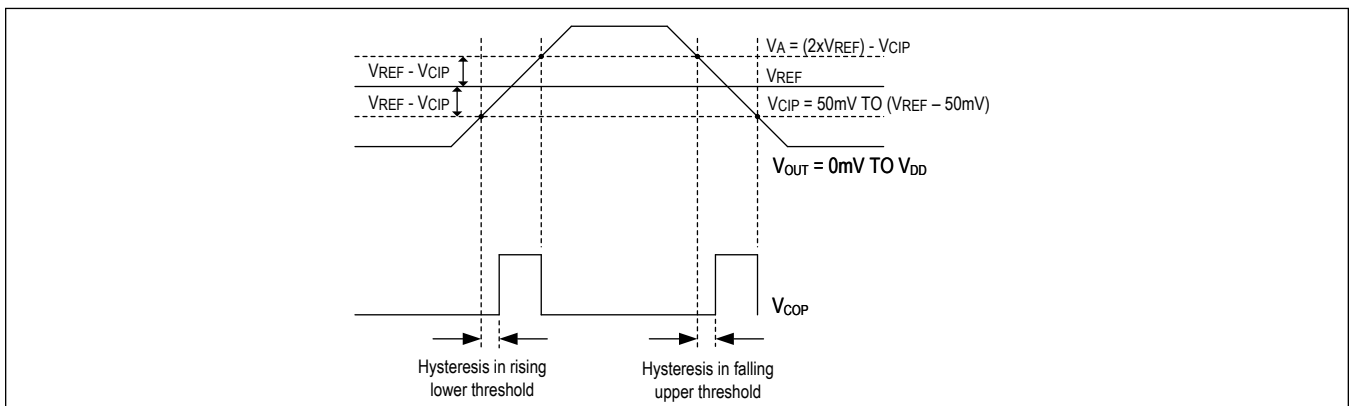


Figure 3. Window Comparator Hysteresis Waveform

Applications Information

Input Sense Voltage Range

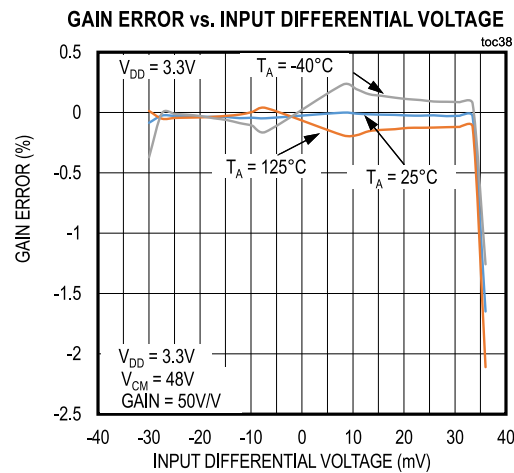
The maximum input differential voltage range is given by the following relation:

$$V_{\text{SENSE}} = \left\{ \frac{\{ \text{GND} - V_{\text{REF}} \}}{\text{GAIN}} \text{ TO } \frac{\{ V_{\text{DD}} - V_{\text{REF}} \}}{\text{GAIN}} \right\}$$

If $V_{\text{DD}} = +3.3\text{V}$ and the MAX40056T (Gain = 20V/V) is used with the 1.5V internal reference, the above equation would provide

$$V_{\text{SENSE}} = \left\{ \frac{\{ 0\text{V} - 1.5\text{V} \}}{20\text{V/V}}, \frac{\{ 3.3\text{V} - 1.5\text{V} \}}{20\text{V/V}} \right\} = -75\text{mV TO } +90\text{mV}$$

For further information on input differential voltage range for different V_{DD} and choice of reference, please refer to [Table 1](#). Refer to the [Electrical Characteristics](#) for the Gain Error specifications. The typical gain error performance for input differential sense range beyond the specified conditions, as shown below.



Choice of Reference Voltage

As the input full scale range is proportional to the V_{REF} and V_{DD} , the input differential sense range can be extended by using an external voltage reference and a higher supply voltage. To achieve the maximum possible input and output range, it is recommended to choose a reference voltage that is half of the supply voltage (V_{DD}). As an example, when $V_{DD} = 5.0V$, select $V_{REF} = 2.5V$. Note that the internal reference may be used with higher supply voltage. The low-side output swing will be the same as for low supply voltages, and the high side swing it is recommended to have the reference voltage to the MAX40056 to be half of the supply voltage. For example, when $V_{DD} = 5.0V$, select $V_{REF} = 2.5V$. [Table 1](#) lists the examples of V_{DD} , V_{REF} , GAIN, and sense voltage combinations.

Table 1. Examples of V_{DD} , V_{REF} , and Sense Voltage Ranges

DEVICE	GAIN (V/V)	SUPPLY VOLTAGE (V)	INTERNAL REFERENCE (V)	EXTERNAL REFERENCE (V)	INPUT DIFFERENTIAL SENSE RANGE V_{SENSE_FS} (mV)
MAX40056F	50	3.3	1.5	–	-30 to +36
		5.0	–	2.5	-50 to +50
MAX40056T	20	3.3	1.5	–	-75 to +90
		5.0	–	2.5	-125 to +125
MAX40056U	10	3.3	1.5	–	-150 to +180
		5.0	–	2.5	-250 to +250

The internal 1.5V integrated reference can be used as a reference for higher supply voltages (V_{DD}). The range of input range is extended only on the positive direction.

Important Considerations

Kelvin Connections

Due to the high currents that may flow through R_{SENSE} , take care to eliminate solder and parasitic trace resistance from causing errors in the sense voltage. Either use a four-terminal current sense resistor or use Kelvin (force and sense) PCB layout techniques.

Figure 4 shows a typical routing of Kelvin-sensed traces to the inputs of the MAX40056. The Kelvin-sense traces should be as close as possible to the current-sense resistor's solder contact pads. If the Kelvin-sensing contact pads are spaced wider relative to the sense resistor, error is introduced from the additional trace resistance.

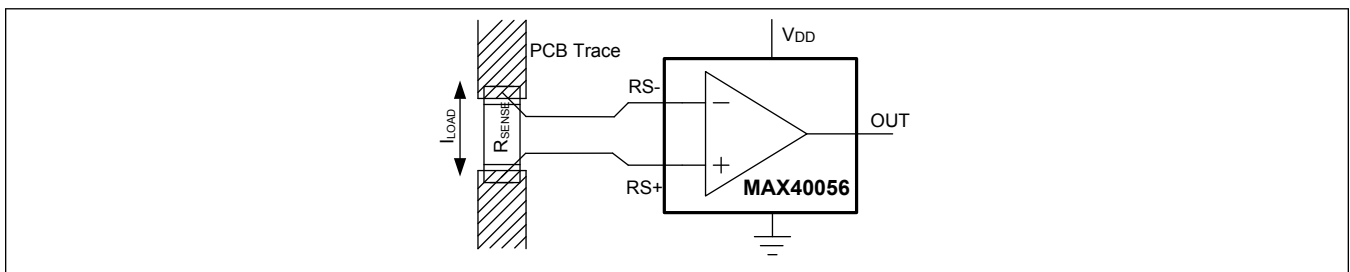


Figure 4. Kelvin Sensing

Stray Inductance

The stray inductance due to package parasitics in the current sense resistor should be kept minimum. The unwanted voltage error produced of the stray inductance is proportional to the magnitude of the load current. Wire-wound resistors have the highest inductance, while metal film is comparably better.

Low-inductance, metal-film resistors are also available. Instead of being spiral wrapped around a core, as in metal-film or wire wound resistors, they are straight bands of metal and are available in values under 100m Ω .

Typical Application Circuits

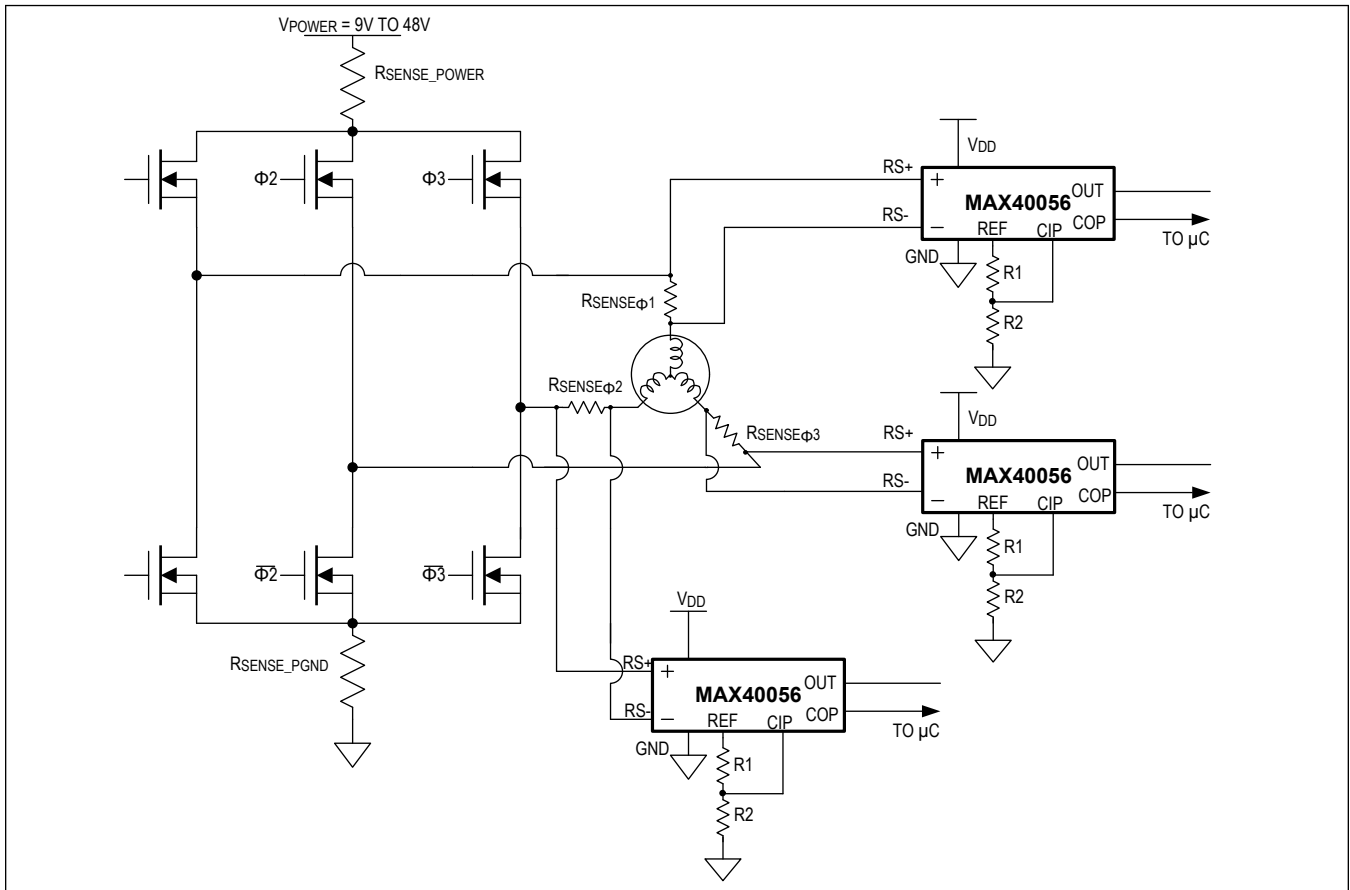


Figure 5. In-Line Current Sensing in Motor Control

Figure 5 shows a typical 3-Phase motor control application. The MAX40056s are connected across the R_{SENSE} resistors to determine the instantaneous in-line phase currents going into the motor.

Typical Application Circuits (continued)

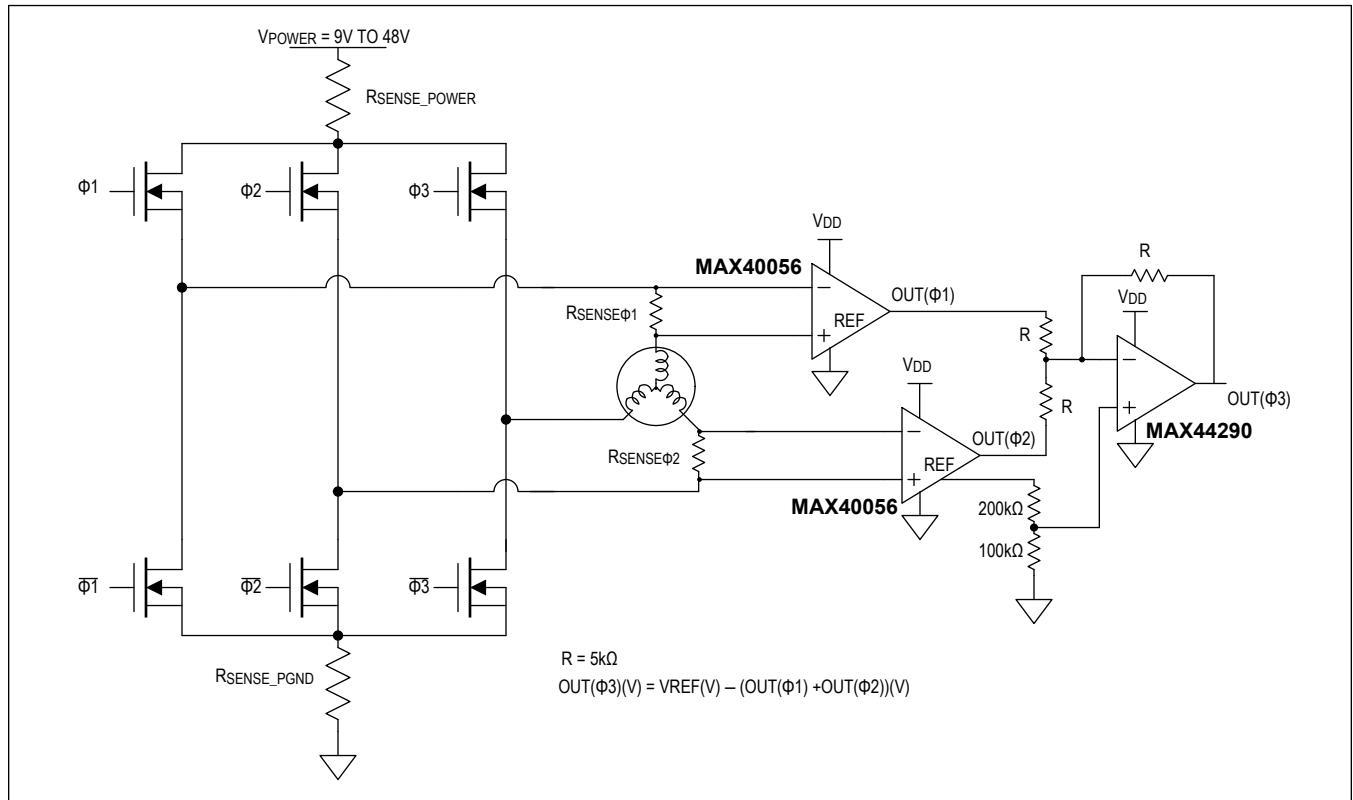


Figure 6. Current Sensing in a 3-Phase Servo Motor

Current Sensing in a 3-Phase Servo Motor

The outputs of two current sense amplifiers can be summed, as shown in [Figure 6](#), to generate a voltage representing the third winding's current.

By Kirchhoff's Law, the third winding current equals the sum of the other two windings, so a simple op-amp summing circuit with three equal-valued resistors is sufficient to produce a voltage proportional to third winding current. Select a large enough resistor value to avoid excessively loading the op-Amp or the CSA outputs. All three amplifiers share the system reference voltage, allowing ratio-metric measurements. If the three amplifiers drive ADC inputs, they will typically share the ADC's supply voltage.

This circuit provides instantaneous winding currents of all three phases without any further computation or knowledge of the PWM pulse phases or duty cycles. Note that the supply bypass capacitors, transient suppressors and catch diodes were omitted for clarity.

Ordering Information

PART NUMBER	TEMP RANGE	PIN-PACKAGE	TOP MARK	GAIN
MAX40056FAUA+	-40°C to +125°C	8 μ MAX	+FAUA	50V/V
MAX40056FAUA/V+	-40°C to +125°C	8 μ MAX	+FA/V	50V/V
MAX40056FAWA+*	-40°C to +125°C	8 WLP	—	50V/V
MAX40056TAUA+	-40°C to +125°C	8 μ MAX	—	20V/V
MAX40056TAUA/V+*	-40°C to +125°C	8 μ MAX	+TA/V	20V/V
MAX40056TAWA+*	-40°C to +125°C	8 WLP	+AAP	20V/V
MAX40056UAUA+*	-40°C to +125°C	8 μ MAX	—	10V/V
MAX40056UAUA/V+	-40°C to +125°C	8 μ MAX	+UA/V	10V/V
MAX40056UAWA+*	-40°C to +125°C	8 WLP	+AAQ	10V/V

+Denotes a lead(Pb)-free/RoHS-compliant package.

*Future product—contact factory for availability.

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	8/18	Initial release	—
1	1/19	Updated <i>Ordering Information</i> and <i>Applications</i>	1, 21
2	5/19	Updated <i>Benefits and Features</i> , <i>Electrical Characteristics</i> , and <i>Detailed Description</i>	1, 4, 12
3	6/19	Updated <i>Ordering Information</i>	20
4	8/19	Updated <i>Input Common Mode</i> specification in <i>Electrical Characteristics</i> table	3
5	11/19	Updated <i>Ordering Information</i>	20

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