SC28L92

3.3 V/5.0 V Dual Universal Asynchronous Receiver/Transmitter (DUART)

Rev. 07 — 19 December 2007 Product data sheet

1. General description

The SC28L92 is a pin and function replacement for the SCC2692 and SC26C92 operating at 3.3 V or 5 V supply with added features and deeper FIFOs. Its configuration on power-up is that of the SC26C92. Its differences from the SCC2692 and SC26C92 are: 16 character receiver, 16 character transmit FIFOs, watchdog timer for each receiver, mode register 0 is added, extended baud rate and overall faster speeds, programmable receiver and transmitter interrupts. (Neither the SC26C92 nor the SCC2692 is being discontinued.)

Pin programming will allow the device to operate with either the Motorola or Intel bus interface. The bit 3 of the MR0A register allows the device to operate in an 8 byte FIFO mode if strict compliance with the SC26C92 FIFO structure is required.

The NXP Semiconductors SC28L92 Dual Universal Asynchronous Receiver/Transmitter (DUART) is a single-chip CMOS-LSI communications device that provides two full-duplex asynchronous receiver/transmitter channels in a single package. It interfaces directly with microprocessors and may be used in a polled or interrupt driven system with modem and DMA interface.

The operating mode and data format of each channel can be programmed independently. Additionally, each receiver and transmitter can select its operating speed as one of 28 fixed baud rates; a 16× clock derived from a programmable counter/timer, or an external 1× or 16× clock. The baud rate generator and counter/timer can operate directly from a crystal or from external clock inputs. The ability to independently program the operating speed of the receiver and transmitter make the DUART particularly attractive for dual-speed channel applications such as clustered terminal systems.

Each receiver and transmitter is buffered by 8 or 16 character FIFOs to minimize the potential of receiver overrun, transmitter underrun and to reduce interrupt overhead in interrupt driven systems. In addition, a flow control capability is provided via RTS/CTS signaling to disable a remote transmitter when the receiver buffer is full.

Also provided on the SC28L92 are a multipurpose 7-bit input port and a multipurpose 8-bit output port. These can be used as general purpose I/O ports or can be assigned specific functions (such as clock inputs or status/interrupt outputs) under program control.

The SC28L92 is available in three package versions: PLCC44, QFP44, and HVQFN48.

2. Features

- Member of IMPACT family: 3.3 V to 5.0 V, –40 °C to +85 °C and 68xxx or 80xxx bus interface for all devices
- Dual full-duplex independent asynchronous receiver/transmitters
- 16 character FIFOs for each receiver and transmitter
- Pin programming selects 68xxx or 80xxx bus interface
- Programmable data format
  - 5 data to 8 data bits plus parity
  - Odd, even, no parity or force parity
  - 1 stop, 1.5 stop or 2 stop bits programmable in $^{1}/_{16}$-bit increments
- 16-bit programmable counter/timer
- Programmable baud rate for each receiver and transmitter selectable from:
  - 28 fixed rates: 50 kBd to 230.4 kBd
  - Other baud rates to 1 MHz at 16×
  - Programmable user-defined rates derived from a programmable counter/timer
  - External 1× or 16× clock
- Parity, framing, and overrun error detection
- False start bit detection
- Line break detection and generation
- Programmable channel mode
  - Normal (full-duplex)
  - Automatic echo
  - Local loopback
  - Remote loopback
  - Multi-drop mode (also called wake-up or 9-bit)
- Multi-function 7-bit input port (includes IACKN)
  - Can serve as clock or control inputs
  - Change of state detection on four inputs
  - Inputs have typically > 100 kΩ pull-up resistors
  - Change of state detectors for modem control
- Multi-function 8-bit output port
  - Individual bit set/reset capability
  - Outputs can be programmed to be status/interrupt signals
  - FIFO status for DMA interface
- Versatile interrupt system
  - Single interrupt output with eight maskable interrupting conditions
  - Output port can be configured to provide a total of up to six separate interrupt outputs that may be wire ORed
  - Each FIFO can be programmed for four different interrupt levels
  - Watchdog timer for each receiver
- Maximum data transfer rates: 1× - 1 Mbit/s, 16× - 1 Mbit/s
- Automatic wake-up mode for multi-drop applications
- Start-end break interrupt/status
- Detects break which originates in the middle of a character

- On-chip crystal oscillator
- Power-down mode
- Receiver time-out mode
- Single 3.3 V or 5 V power supply
- Powers up to emulate SC26C92

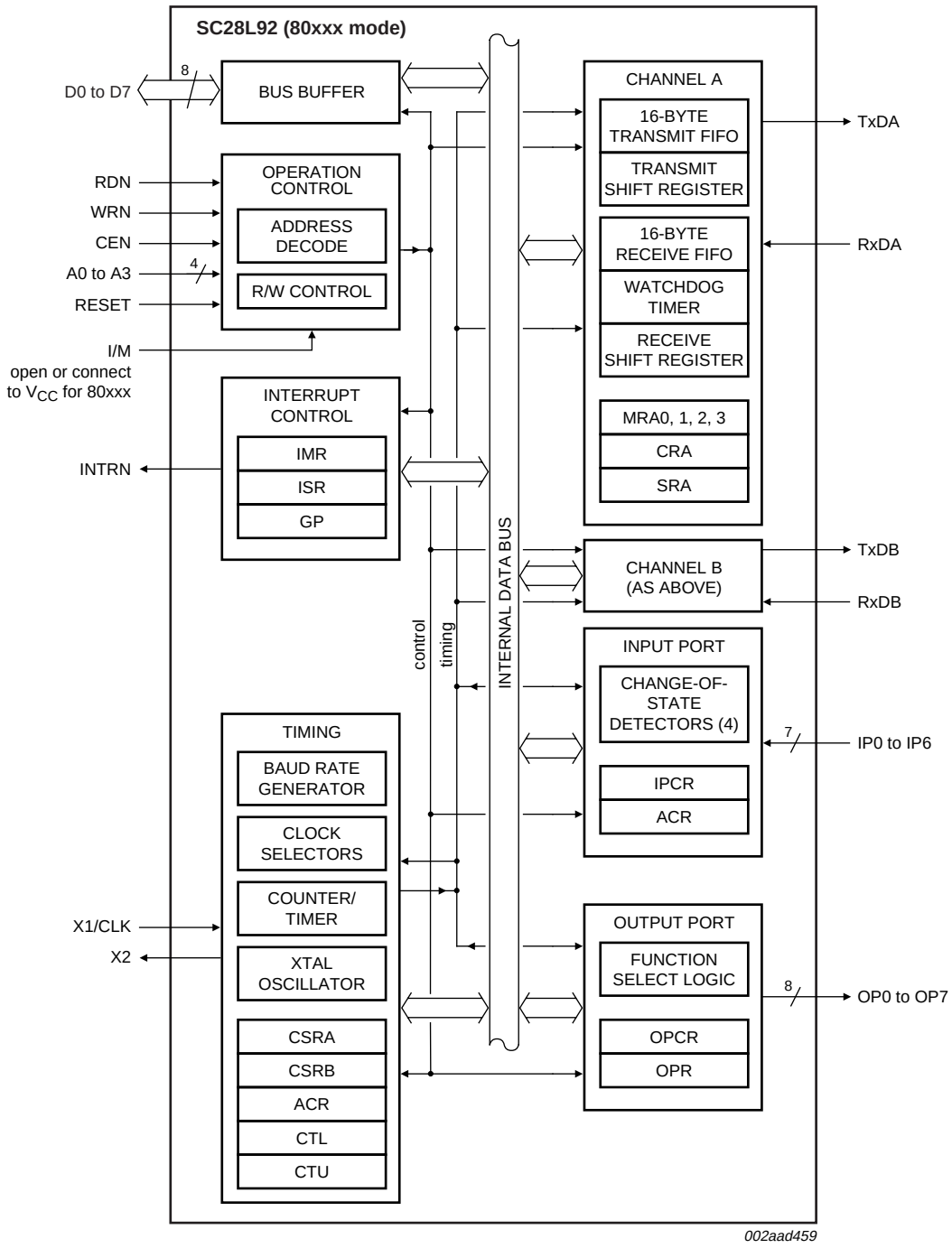
3. Ordering information

Table 1. Ordering information

V_{CC} = 3.3 V ± 10 % or V_{CC} = 5.0 V ± 10 %; T_{amb} = −40 °C to +85 °C

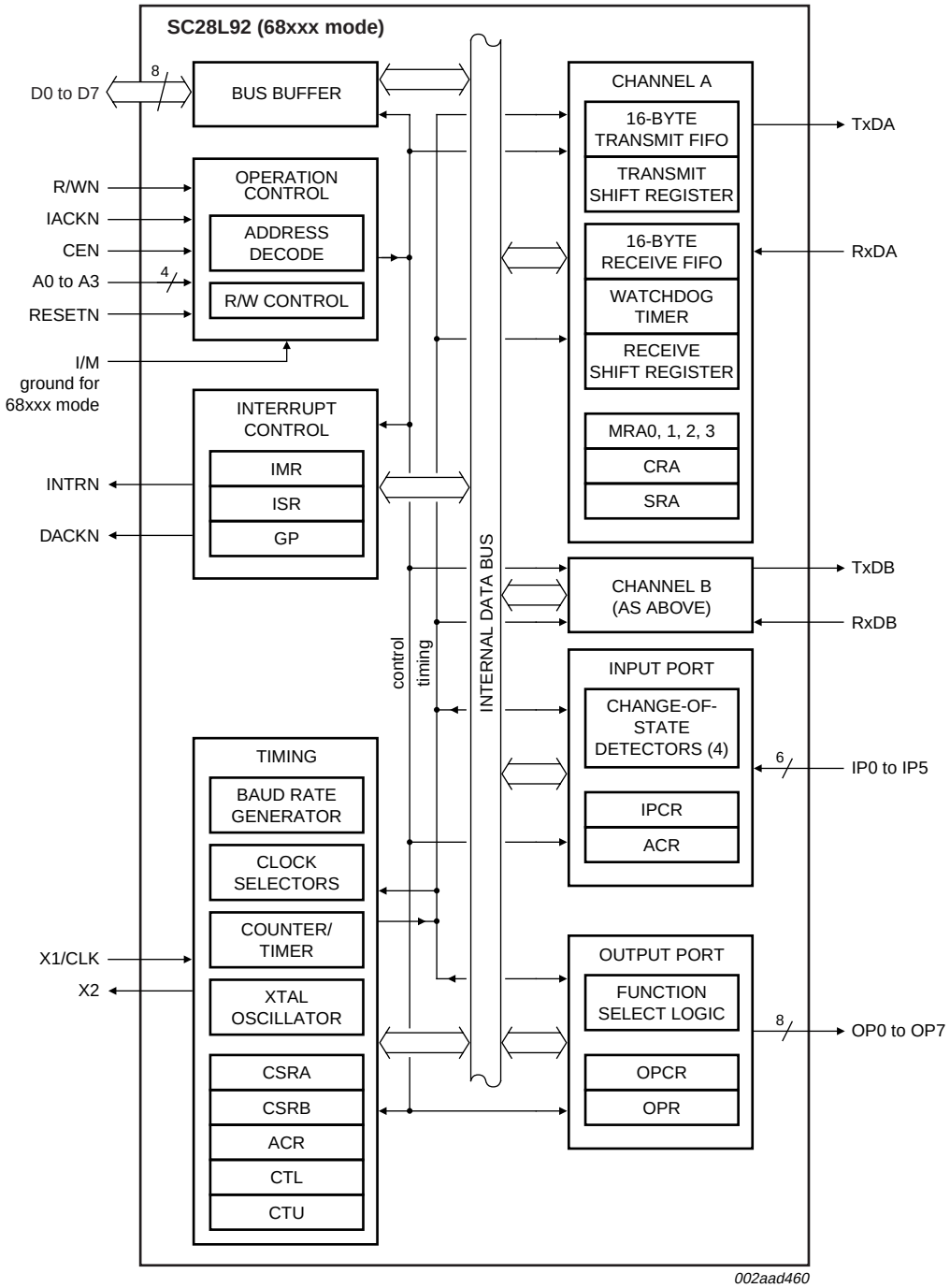
Type number	Package		
	Name	Description	Version
SC28L92A1A	PLCC44	plastic leaded chip carrier; 44 leads	SOT187-2
SC28L92A1B	QFP44	plastic quad flat package; 44 leads (lead length 1.3 mm); body 10 × 10 × 1.75 mm	SOT307-2
SC28L92A1BS	HVQFN48	plastic thermal enhanced very thin quad flat package; no leads; 48 terminals; body 6 × 6 × 0.85 mm	SOT778-4

4. Block diagram



The data pins TxD and RxD are considered idle at the logic 1 (HIGH) level when inactive, or active when at the logic 0 (LOW) level. Comments about these levels when RS232 is referenced often refer to Mark and Space levels. Mark usually means inactive and Space means active. The voltage levels represented by the terms Mark and Space are often reversed from those above: Mark is low voltage, and Space is high voltage.

Fig 1. Block diagram (80xxx mode)



The data pins TxD and RxD are considered idle at the logic 1 (HIGH) level when inactive, or active when at the logic 0 (LOW) level. Comments about these levels when RS232 is referenced often refer to Mark and Space levels. Mark usually means inactive and Space means active. The voltage levels represented by the terms Mark and Space are often reversed from those above: Mark is low voltage, and Space is high voltage.

Fig 2. Block diagram (68xxx mode)

5. Pinning information

5.1 Pinning

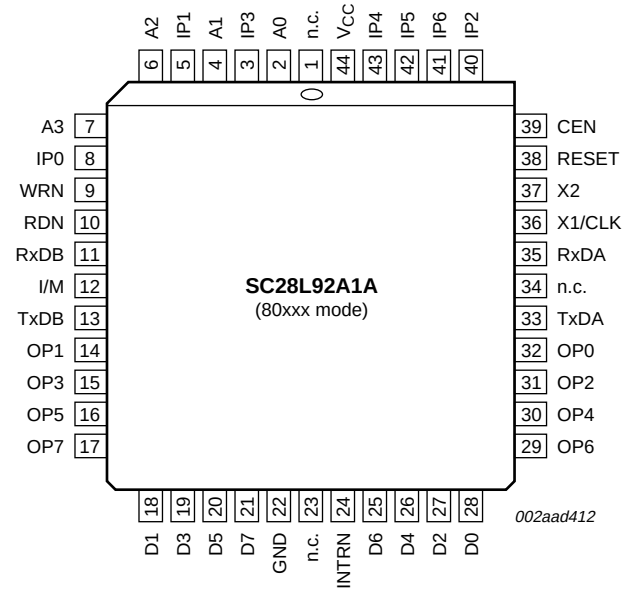


Fig 3. Pin configuration for PLCC44; 80xxx mode

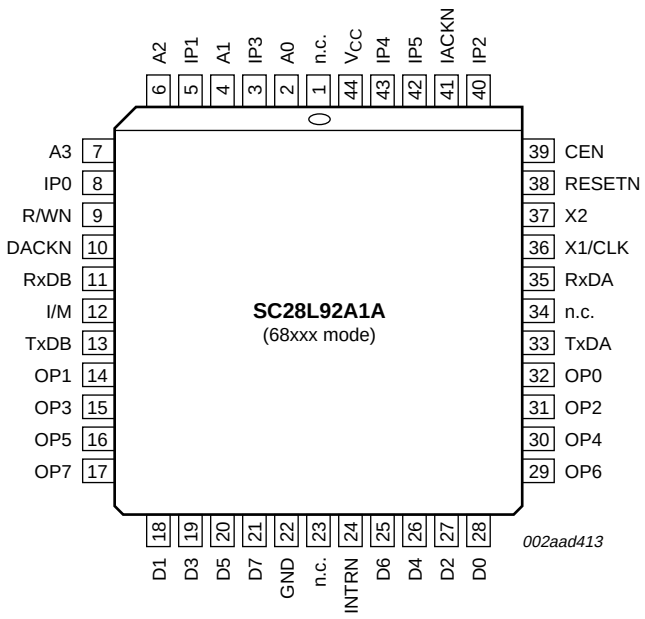


Fig 4. Pin configuration for PLCC44; 68xxx mode

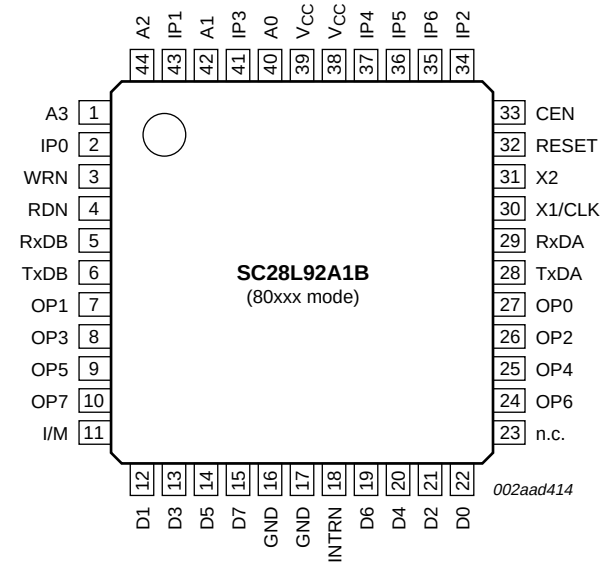


Fig 5. Pin configuration for QFP44; 80xxx mode

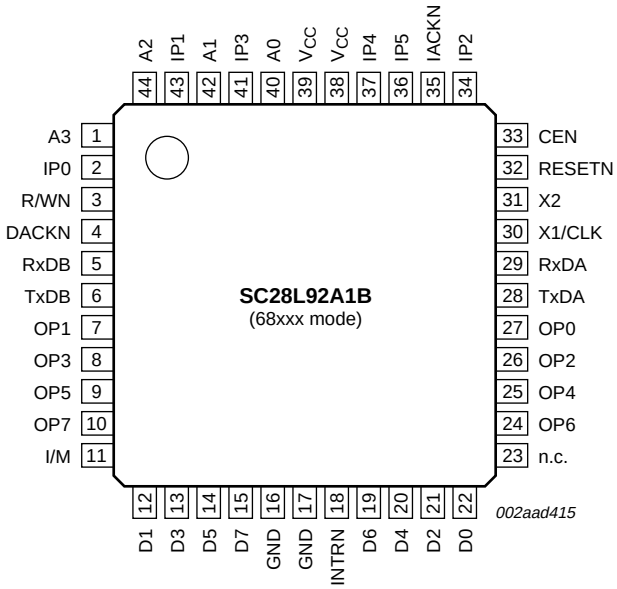
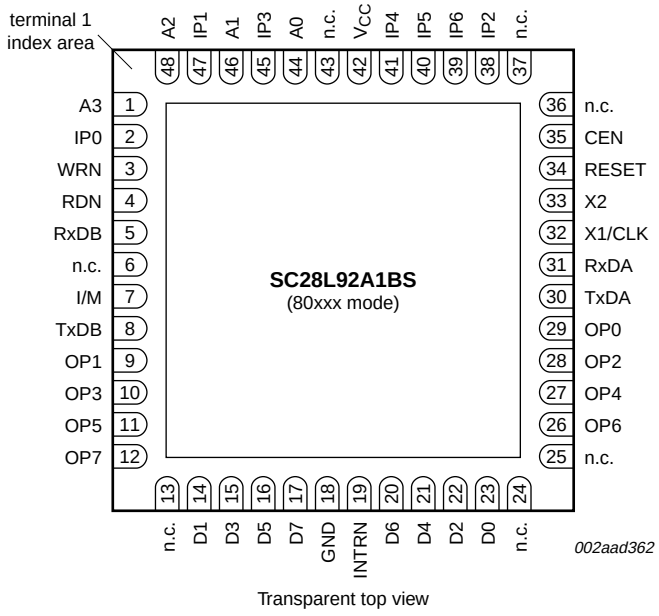
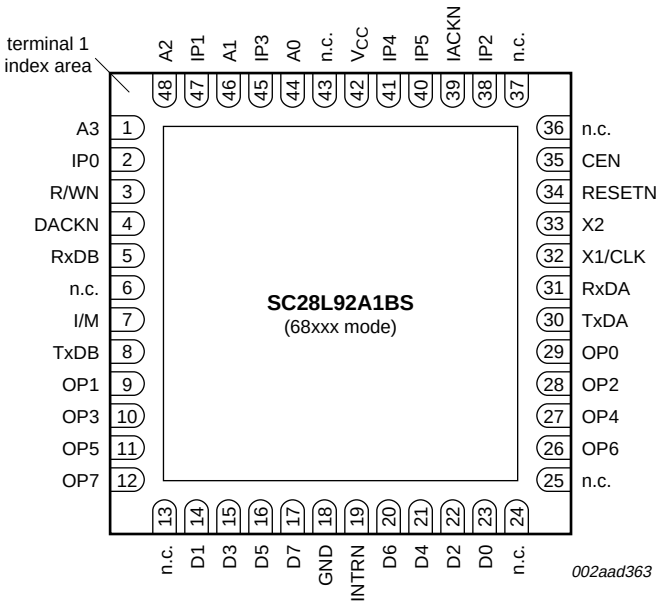


Fig 6. Pin configuration for QFP44; 68xxx mode



Transparent top view

Fig 7. Pin configuration for HVQFN48; 80xxx mode



Transparent top view

Fig 8. Pin configuration for HVQFN48; 68xxx mode

5.2 Pin description

Table 2. Pin description for 80xxx bus interface (Intel)

Symbol	Pin			Type	Description
	PLCC44	QFP44	HVQFN48		
I/M	12	11	7	I	**Bus configuration**: When HIGH or not connected configures the bus interface to the conditions shown in this table.
D0	28	22	23	I/O	**Data bus**: Bidirectional 3-state data bus used to transfer commands, data and status between the DUART and the CPU. D0 is the least significant bit.
D1	18	12	14	I/O	
D2	27	21	22	I/O	
D3	19	13	15	I/O	
D4	26	20	21	I/O	
D5	20	14	16	I/O	
D6	25	19	20	I/O	
D7	21	15	17	I/O	
CEN	39	33	35	I	**Chip enable**: Active LOW input signal. When LOW, data transfers between the CPU and the DUART are enabled on D0 to D7 as controlled by the WRN, RDN and A0 to A3 inputs. When HIGH, places the D0 to D7 lines in the 3-state condition.
WRN	9	3	3	I	**Write strobe**: When LOW and CEN is also LOW, the contents of the data bus is loaded into the addressed register. The transfer occurs on the rising edge of the signal.
RDN	10	4	4	I	**Read strobe**: When LOW and CEN is also LOW, causes the contents of the addressed register to be presented on the data bus. The read cycle begins on the falling edge of RDN.
A0	2	40	44	I	**Address inputs**: Select the DUART internal registers and ports for read/write operations.
A1	4	42	46	I	
A2	6	44	48	I	
A3	7	1	1	I	
RESET	38	32	34	I	**Reset**: A HIGH level clears internal registers (SRA, SRB, IMR, ISR, OPR and OPCR), puts OP0 to OP7 in the HIGH state, stops the counter/timer, and puts channels A and B in the inactive state, with the TxDA and TxDB outputs in the mark (HIGH) state. Sets MR pointer to MR1. See Figure 10.
INTRN	24	18	19	O	**Interrupt request**: Active LOW, open-drain, output which signals the CPU that one or more of the eight maskable interrupting conditions are true. This pin requires a pull-up device.
X1/CLK	36	30	32	I	**Crystal 1**: Crystal or external clock input. A crystal or clock of the specified limits must be supplied at all times. When a crystal is used, a capacitor must be connected from this pin to ground (see Figure 17).
X2	37	31	33	O	**Crystal 2**: Connection for other side of the crystal. When a crystal is used, a capacitor must be connected from this pin to ground (see Figure 17). If X1/CLK is driven from an external source, this pin must be left open.
RxDA	35	29	31	I	**Channel A receiver serial data input**: The least significant bit is received first. See note on drive levels at block diagram (Figure 1).
RxDB	11	5	5	I	**Channel B receiver serial data input**: The least significant bit is received first. See note on drive levels at block diagram (Figure 1).

Table 2. Pin description for 80xxx bus interface (Intel) *…continued*

Symbol	Pin			Type	Description
	PLCC44	QFP44	HVQFN48		
TxDA	33	28	30	O	**Channel A transmitter serial data output**: The least significant bit is transmitted first. This output is held in the Mark condition when the transmitter is disabled, Idle or when operating in local loopback mode. See note on drive levels at block diagram (Figure 1).
TxDB	13	6	8	O	**Channel B transmitter serial data output**: The least significant bit is transmitted first. This output is held in the Mark condition when the transmitter is disabled, Idle, or when operating in local loopback mode. See note on drive levels at block diagram (Figure 1).
OP0	32	27	29	O	**Output 0**: General purpose output or **channel** A request to send (RTSAN, active LOW). Can be deactivated automatically on receive or transmit.
OP1	14	7	9	O	**Output 1**: General-purpose output or channel B request to send (RTSBN, active LOW). Can be deactivated automatically on receive or transmit.
OP2	31	26	28	O	**Output 2**: General purpose output, or channel A transmitter 1× or 16× clock output, or channel A receiver 1× clock output.
OP3	15	8	10	O	**Output 3**: General purpose output or open-drain, active LOW counter/timer output or channel B transmitter 1× clock output, or channel B receiver 1× clock output.
OP4	30	25	27	O	**Output 4**: General purpose output or channel A open-drain, active LOW, RxA interrupt ISR[1] output.
OP5	16	9	11	O	**Output 5**: General-purpose output or channel B open-drain, active LOW, RxB interrupt ISR[5] output.
OP6	29	24	26	O	**Output 6**: General purpose output or channel A open-drain, active LOW, TxA interrupt ISR[0] output.
OP7	17	10	12	O	**Output 7**: General-purpose output, or channel B open-drain, active LOW, TxB interrupt ISR[4] output.
IP0	8	2	2	I	**Input 0**: General purpose input or channel A clear to send active LOW input (CTSAN).
IP1	5	43	47	I	**Input 1**: General purpose input or channel B clear to send active LOW input (CTSBN).
IP2	40	34	38	I	**Input 2**: General-purpose input or counter/timer external clock input.
IP3	3	41	45	I	**Input 3**: General purpose input or channel A transmitter external clock input (TxCA). When the external clock is used by the transmitter, the transmitted data is clocked on the falling edge of the clock.
IP4	43	37	41	I	**Input 4**: General purpose input or channel A receiver external clock input (RxCA). When the external clock is used by the receiver, the received data is sampled on the rising edge of the clock.
IP5	42	36	40	I	**Input 5**: General purpose input or channel B transmitter external clock input (TxCB). When the external clock is used by the transmitter, the transmitted data is clocked on the falling edge of the clock.
IP6	41	35	39	I	**Input 6**: General purpose input or channel B receiver external clock input (RxCB). When the external clock is used by the receiver, the received data is sampled on the rising edge of the clock.
V_{CC}	44	38, 39	42	Pwr	**Power Supply**: 3.3 V ± 10 % or 5 V ± 10 % supply input.

Table 2. Pin description for 80xxx bus interface (Intel) *…continued*

Symbol	Pin			Type	Description
	PLCC44	QFP44	HVQFN48		
GND	22	16, 17	18[1]	Pwr	**Ground**
n.c.	1, 23, 34	23	6, 13, 24, 25, 36, 37, 43	Pwr	Not connected

[1] HVQFN48 package die supply ground is connected to both GND pin and exposed center pad. GND pin must be connected to supply ground for proper device operation. For enhanced thermal, electrical, and board level performance, the exposed pad needs to be soldered to the board using a corresponding thermal pad on the board and for proper heat conduction through the board, thermal vias need to be incorporated in the PCB in the thermal pad region.

Table 3. Pin description for 68xxx bus interface (Motorola)

Symbol	Pin			Type	Description
	PLCC44	QFP44	HVQFN48		
I/M	12	11	7	I	**Bus configuration**: When LOW configures the bus interface to the conditions shown in this table.
D0	28	22	23	I/O	**Data bus**: Bidirectional 3-state data bus used to transfer commands, data and status between the DUART and the CPU. D0 is the least significant bit.
D1	18	12	14	I/O	
D2	27	21	22	I/O	
D3	19	13	15	I/O	
D4	26	20	21	I/O	
D5	20	14	16	I/O	
D6	25	19	20	I/O	
D7	21	15	17	I/O	
CEN	39	33	35	I	**Chip enable**: Active LOW input signal. When LOW, data transfers between the CPU and the DUART are enabled on D0 to D7 as controlled by the R/WN and A0 to A3 inputs. When HIGH, places the D0 to D7 lines in the 3-state condition.
R/WN	9	3	3	I	**Read/Write**: Input signal. When CEN is LOW, R/WN HIGH input indicates a read cycle; when LOW indicates a write cycle.
IACKN	41	35	39	I	**Interrupt acknowledge**: Active LOW input indicating an interrupt acknowledge cycle. Usually asserted by the CPU in response to an interrupt request. When asserted places the interrupt vector on the bus and asserts DACKN.
DACKN	10	4	4	O	**Data transfer acknowledge**: A3-state active LOW output asserted in a write, read, or interrupt acknowledge cycle to indicate proper transfer of data between the CPU and the DUART.
A0	2	40	44	I	**Address inputs**: Select the DUART internal registers and ports for read/write operations.
A1	4	42	46	I	
A2	6	44	48	I	
A3	7	1	1	I	
RESETN	38	32	34	I	**Reset**: A LOW level clears internal registers (SRA, SRB, IMR, ISR, OPR, OPCR), puts OP0 to OP7 in the HIGH state, stops the counter/timer, and puts channels A and B in the inactive state, with the TxDA and TxDB outputs in the mark (HIGH) state. Sets MR pointer to MR1. See Figure 10.

Table 3. Pin description for 68xxx bus interface (Motorola) *…continued*

Symbol	Pin			Type	Description
	PLCC44	QFP44	HVQFN48		
INTRN	24	18	19	O	**Interrupt request**: Active LOW, open-drain, output which signals the CPU that one or more of the eight maskable interrupting conditions are true. This pin requires a pull-up.
X1/CLK	36	30	32	I	**Crystal 1**: Crystal or external clock input. A crystal or clock of the specified limits must be supplied at all times. When a crystal is used, a capacitor must be connected from this pin to ground (see Figure 17).
X2	37	31	33	O	**Crystal 2**: Connection for other side of the crystal. When a crystal is used, a capacitor must be connected from this pin to ground (see Figure 17). If X1/CLK is driven from an external source, this pin must be left open.
RxDA	35	29	31	I	**Channel A receiver serial data input**: The least significant bit is received first. See note on drive levels at block diagram (Figure 2).
RxDB	11	5	5	I	**Channel B receiver serial data input**: The least significant bit is received first. See note on drive levels at block diagram (Figure 2).
TxDA	33	28	30	O	**Channel A transmitter serial data output**: The least significant bit is transmitted first. This output is held in the ‘mark condition when the transmitter is disabled, idle or when operating in local loopback mode. See note on drive levels at block diagram (Figure 2).
TxDB	13	6	8	O	**Channel B transmitter serial data output**: The least significant bit is transmitted first. This output is held in the Mark condition when the transmitter is disabled, idle, or when operating in local loopback mode. See note on drive levels at block diagram (Figure 2).
OP0	32	27	29	O	**Output 0**: General purpose output or channel A request to send (RTSAN, active LOW). Can be deactivated automatically on receive or transmit.
OP1	14	7	9	O	**Output 1**: General purpose output or channel B request to send (RTSBN, active LOW). Can be deactivated automatically on receive or transmit.
OP2	31	26	28	O	**Output 2**: General purpose output, or channel A transmitter 1× or 16× clock output, or channel A receiver 1× clock output.
OP3	15	8	10	O	**Output 3**: General purpose output or open-drain, active LOW counter/timer output or channel B transmitter 1× clock output, or channel B receiver 1× clock output.
OP4	30	25	27	O	**Output 4**: General purpose output or channel A open-drain, active LOW, RxA interrupt ISR [1] output.
OP5	16	9	11	O	**Output 5**: General purpose output or channel B open-drain, active LOW, RxB interrupt ISR[5] output.
OP6	29	24	26	O	**Output 6**: General purpose output or channel A open-drain, active LOW, TxA interrupt ISR[0] output.
OP7	17	10	12	O	**Output 7**: General purpose output, or channel B open-drain, active LOW, TxB interrupt ISR[4] output.
IP0	8	2	2	I	**Input 0**: General purpose input or channel A clear to send active LOW input (CTSAN).
IP1	5	43	47	I	**Input 1**: General purpose input or channel B clear to send active LOW input (CTSBN).
IP2	40	34	38	I	**Input 2**: General purpose input or counter/timer external clock input.

Table 3. Pin description for 68xxx bus interface (Motorola) *…continued*

Symbol	Pin			Type	Description
	PLCC44	QFP44	HVQFN48		
IP3	3	41	45	I	**Input 3**: General purpose input or channel A transmitter external clock input (TxCA). When the external clock is used by the transmitter, the transmitted data is clocked on the falling edge of the clock.
IP4	43	37	41	I	**Input 4**: General purpose input or channel A receiver external clock input (RxCA). When the external clock is used by the receiver, the received data is sampled on the rising edge of the clock.
IP5	42	36	40	I	**Input 5**: General purpose input or channel B transmitter external clock input (TxCB). When the external clock is used by the transmitter, the transmitted data is clocked on the falling edge of the clock.
V_{CC}	44	38, 39	42	Pwr	**Power Supply**: 3.3 V ± 10 % or 5 V ± 10 % supply input.
GND	22	16, 17	18[1]	Pwr	**Ground**
n.c.	1, 23, 34	23	6, 13, 24, 25, 36, 37, 43	-	Not connected

[1] HVQFN48 package die supply ground is connected to both GND pin and exposed center pad. GND pin must be connected to supply ground for proper device operation. For enhanced thermal, electrical, and board level performance, the exposed pad needs to be soldered to the board using a corresponding thermal pad on the board and for proper heat conduction through the board, thermal vias need to be incorporated in the PCB in the thermal pad region.

6. Functional description

6.1 Block diagram

The SC28L92 DUART consists of the following eight major sections: data bus buffer, operation control, interrupt control, timing, communications channels A and B, input port and output port. Refer to Section 4 “Block diagram”.

6.1.1 Data bus buffer

The data bus buffer provides the interface between the external and internal data buses. It is controlled by the operation control block to allow read and write operations to take place between the controlling CPU and the DUART.

6.1.2 Operation control

The operation control logic receives operation commands from the CPU and generates appropriate signals to internal sections to control device operation. It contains address decoding and read and write circuits to permit communications with the microprocessor via the data bus.

6.1.3 Interrupt control

A single active LOW interrupt output (INTRN) is provided which is activated upon the occurrence of any of eight internal events. Associated with the interrupt system are the Interrupt Mask Register (IMR) and the Interrupt Status Register (ISR). The IMR can be programmed to select only certain conditions to cause INTRN to be asserted. The ISR can be read by the CPU to determine all currently active interrupting conditions. Outputs OP3 to OP7 can be programmed to provide discrete interrupt outputs for the transmitter,

receivers, and counter/timer. When OP3 to OP7 are programmed as interrupts, their output buffers are changed to the open-drain active LOW configuration. The OP pins may be used for DMA and modem control as well (see Section 7.4).

6.1.4 FIFO configuration

Each receiver and transmitter has a 16 byte FIFO. These FIFOs may be configured to operate at a fill capacity of either 8 bytes or 16 bytes. This feature may be used if it is desired to operate the SC28L92 in strict compliance with the SC26C92. The 8 byte or 16 byte mode is controlled by the MR0A[3] bit. A logic 0 value for this bit sets the 8-bit mode (the default); a logic 1 sets the 16 byte mode. MR0A bit 3 sets the FIFO size for both channels.

The FIFO fill interrupt level automatically follow the programming of the MR0A[3] bit. See Table 25 and Table 26.

6.1.5 68xxx mode

When the I/M pin is connected to GND (ground), the operation of the SC28L92 switches to the bus interface compatible with the Motorola bus interfaces. Several of the pins change their function as follows:

IP6 becomes IACKN input

RDN becomes DACKN

WRN becomes R/WN

The interrupt vector is enabled and the interrupt vector will be placed on the data bus when IACKN is asserted LOW. The interrupt vector register is located at address 0xC. The contents of this register are set to 0x0F on the application of RESETN.

The generation of DACKN uses two positive edges of the X1 clock as the DACKN delay from the falling edge of CEN. **If the CEN is withdrawn before two edges of the X1 clock occur, the generation of DACKN is terminated**. Systems not strictly requiring DACKN may use the 68xxx mode with the bus timing of the 80xxx mode greatly decreasing the bus cycle time.

6.2 Timing circuits

6.2.1 Crystal clock

The timing block consists of a crystal oscillator, a baud rate generator, a programmable 16-bit counter/timer, and four clock selectors. The crystal oscillator operates directly from a crystal connected across the X1/CLK and X2 inputs. If an external clock of the appropriate frequency is available, it may be connected to X1/CLK. The clock serves as the basic timing reference for the Baud Rate Generator (BRG), the counter/timer, and other internal circuits. A clock signal within the limits specified in Section 10 “Dynamic characteristics” must always be supplied to the DUART. If an external clock is used instead of a crystal, X1 should be driven using a configuration similar to the one in Figure 17. Nominal crystal rate is 3.6864 MHz. Rates up to 8 MHz may be used.

6.2.2 Baud rate generator

The baud rate generator operates from the oscillator or external clock input at the X1 input and is capable of generating 28 commonly used data communications baud rates ranging from 50 kBd to 38.4 kBd. Programming bit 0 of MR0 to a logic 1 gives additional baud rates of 57.6 kBd, 115.2 kBd and 230.4 kBd (500 kHz with X1 at 8.0 MHz). Note that the MR0A[2:0] control this change and that the change applies to both channels. MR0B[2:0] are reserved.

The baud rates are based on an input frequency of 3.6864 MHz. Changing the X1 frequency will change all baud rates by ratio of 3.6864 MHz to the new frequency. All rates generated by the BRG will be in the 16× mode. The clock outputs from the BRG are at 16× the actual baud rate.

The counter/timer can be used as a timer to produce a 16× clock for any other baud rate by counting down the crystal clock or an external clock. The four clock selectors allow the independent selection, for each receiver and transmitter, of any of these baud rates or external timing signal. The use of the counter/timer also requires the generation of a frequency 16× of the baud rate. See Section 6.2.3.

6.2.3 Counter/timer

The Counter/timer is a 16-bit programmable divider that operates in one of three modes: counter, timer and time-out. In the timer mode it generates a square wave. In the counter mode it generates a time delay. In the time-out mode it monitors the time between received characters. The C/T uses the numbers loaded into the Counter/Timer Lower Register (CTLR) and the Counter/Timer Upper Register (CTUR) as its divisor.

The counter/timer clock source and mode of operation (counter or timer) is selected by the Auxiliary Control Register bits 6 to 4 (ACR[6:4]). The output of the counter/timer may be used for a baud rate and/or may be output to the OP pins for some external function that may be totally unrelated to data transmission. The counter/timer also sets the counter/timer ready bit in the Interrupt Status Register (ISR) when its output transitions from logic 1 to logic 0. A register read address (see Table 4) is reserved to issue a start counter/timer command and a second register read address is reserved to issue a stop command. The value of D[7:0] is ignored. The START command always loads the contents of CTUR, CTLR to the counting registers. The STOP command always resets the ISR[3] bit in the interrupt status register.

6.2.4 Timer mode

In the timer mode a symmetrical square wave is generated whose half period is equal in time to division of the selected counter/timer clock frequency by the 16-bit number loaded in the CTLR CTUR. Thus, the frequency of the counter/timer output will be equal to the counter/timer clock frequency divided by twice the value of the CTUR CTLR. While in the timer mode the ISR bit 3 (ISR[3]) will be set each time the counter/timer transitions from logic 1 to logic 0 (HIGH-to-LOW). This continues regardless of issuance of the stop counter command. ISR[3] is reset by the stop counter command.

Note: Reading of the CTU and CTL registers in the timer mode is not meaningful. When the C/T is used to generate a baud rate and the C/T is selected through the CSR then the receivers and/or transmitter will be operating in the 16× mode. Calculation for the number n to program the counter/timer upper and lower registers is shown in Equation 1. The value of the divisor n is

$$n = \frac{counter/timer\ input\ clock}{2 \times 16 \times (desired\ baud\ rate)} \quad (1)$$

Often this division will result in a non-integer number; 26.3 for example. One may only program integer numbers to a digital divider. Therefore 26 (0x1A) would be chosen. If 26.7 were the result of the division, then 27 (0x1B) would be chosen. This gives a baud rate error of 0.3/26.3 or 0.3/26.7 that yields a percentage error of 1.14 % or 1.12 % respectively, well within the ability of the asynchronous mode of operation. Higher input frequency to the counter reduces the error effect of the fractional division.

6.2.5 Counter mode

In the counter mode the counter/timer counts the value of the CTLR CTUR down to zero and then sets the ISR[3] bit and sets the counter/timer output from 1 to 0. It then rolls over to 65,365 and continues counting with no further observable effect. Reading the C/T in the counter mode outputs the present state of the C/T. If the C/T is not stopped, a read of the C/T may result in changing data on the data bus.

6.2.6 Time-out mode

The time-out mode uses the received data stream to control the counter. The time-out mode forces the C/T into the timer mode. Each time a received character is transferred from the shift register to the Rx FIFO, the counter is restarted. If a new character is not received before the counter reaches zero count, the counter ready bit is set, and an interrupt can be generated. This mode can be used to indicate when data has been left in the Rx FIFO for more than the programmed time limit. If the receiver has been programmed to interrupt the CPU when the receive FIFO is full, and the message ends before the FIFO is full, the CPU will not be interrupted for the remaining characters in the Rx FIFO.

By programming the C/T such that it would time-out in just over one character time, the above situation could be avoided. The processor would be interrupted any time the data stream had stopped for more than one character time. **Note**: This is very similar to the watchdog time of MR0. The difference is in the programmability of the delay time and that the watchdog timer is restarted by either a receiver load to the Rx FIFO or a system read from it.

This mode is enabled by writing the appropriate command to the command register. Writing 0xA to CRA or CRB will invoke the time-out mode for that channel. Writing 0xC to CRA or CRB will disable the time-out mode. Only one receiver should use this mode at a time. However, if both are on, the time-out occurs after both receivers have been inactive for the time-out period. The start of the C/T will be on the logic OR of the two receivers.

The time-out mode disables the regular start counter or stop counter commands and puts the C/T into counter mode under the control of the received data stream. Each time a received character is transferred from the shift register to the Rx FIFO, the C/T is stopped after one C/T clock, reloaded with the value in CTUR and CTLR and then restarted on the next C/T clock. If the C/T is allowed to end the count before a new character has been received, the counter ready bit, ISR[3], will be set. If IMR[3] is set, this will generate an interrupt. Since receiving a character restarts the C/T, the receipt of a character after the C/T has timed out will clear the counter ready bit, ISR[3], and the interrupt. Invoking the Set Time-out Mode On command, CRx = 0xA, will also clear the counter ready bit and stop the counter until the next character is received. The counter/timer is controlled with six commands: Start/Stop C/T, Read/Write Counter/Timer lower register and Read/Write

Counter/Timer upper register. These commands have slight differences depending on the mode of operation. Please see the detail of the commands in Section 7.3.3 “Command registers”.

6.2.7 Time-out mode caution

When operating in the special time-out mode, it is possible to generate what appears to be a false interrupt, i.e., an interrupt without a cause. This may result when a time-out interrupt occurs and then, **before** the interrupt is serviced, another character is received, i.e., the data stream has started again. (The interrupt latency is longer than the pause in the data stream.) In this case, when a new character has been received, the counter/timer will be restarted by the receiver, thereby withdrawing its interrupt. If, at this time, the interrupt service begins for the previously seen interrupt, a read of the ISR will show the Counter Ready bit not set. If nothing else is interrupting, this read of the ISR will return a 0x00 character. This action may present the appearance of a spurious interrupt.

6.2.8 Communications channels A and B

Each communications channel of the SC28L92 comprises a full-duplex asynchronous receiver/transmitter (UART). The operating frequency for each receiver and transmitter can be selected independently from the baud rate generator, the counter/timer, or from an external input. The transmitter accepts parallel data from the CPU, converts it to a serial bit stream, inserts the appropriate start, stop, and optional parity bits and outputs a composite serial stream of data on the TxD output pin. The receiver accepts serial data on the RxD pin, converts this serial input to parallel format, checks for start bit, stop bit, parity bit (if any), or break condition and sends an assembled character to the CPU via the receive FIFO. Three status bits (break received, framing and parity errors) are also FIFOed with each data character.

6.2.9 Input port

The inputs to this unlatched 7-bit (6-bit for 68xxx mode) port can be read by the CPU by performing a read operation at address 0xD. A HIGH input results in a logic 1 while a LOW input results in a logic 0. D7 will always read as a logic 1. The pins of this port can also serve as auxiliary inputs to certain portions of the DUART logic, modem and DMA.

Four change-of-state detectors are provided which are associated with inputs IP3, IP2, IP1 and IP0. A HIGH-to-LOW or LOW-to-HIGH transition of these inputs, lasting longer than 25 μs to 50 μs, will set the corresponding bit in the input port change register. The bits are cleared when the register is read by the CPU. Any change of state can also be programmed to generate an interrupt to the CPU.

The input port change of state detection circuitry uses a 38.4 kHz sampling clock derived from one of the baud rate generator taps. This results in a sampling period of slightly more than 25 μs (this assumes that the clock input is 3.6864 MHz). The detection circuitry, in order to guarantee that a true change in level has occurred, requires two successive samples at the new logic level be observed. As a consequence, the minimum duration of the signal change is 25 μs if the transition occurs coincident with the first sample pulse. The 50 μs time refers to the situation in which the change of state is just missed and the first change of state is not detected until 25 μs later.

6.2.10 Output port

The output ports are controlled from six places: the OPCR, OPR, MR, Command, SOPR and ROPR registers. The OPCR register controls the source of the data for the output ports OP2 through OP7. The data source for output ports OP0 and OP1 is controlled by the MR and CR registers. When the OPR is the source of the data for the output ports, the data at the ports is inverted from that in the OPR register. The content of the OPR register is controlled by the set output port bits command and the reset output bits command. These commands are at 0xE and 0xF, respectively. When these commands are used, action takes place only at the bit locations where ones exist. For example, a one in bit location 5 of the data word used with the set output port bits command will result in OPR5 being set to one. The OP5 would then be set to zero (V_{SS}). Similarly, a one in bit position 5 of the data word associated with the reset output ports bits command would set OPR5 to zero and, hence, the pin OP5 to a one (V_{DD}).

These pins along with the IP pins and their change-of-state detectors are often used for modem and DMA control.

6.3 Operation

6.3.1 Transmitter

The SC28L92 is conditioned to transmit data when the transmitter is enabled through the command register. The SC28L92 indicates to the CPU that it is ready to accept a character by setting the TxRDY bit in the status register. This condition can be programmed to generate an interrupt request at OP6 or OP7 and INTRN. When the transmitter is initially enabled the TxRDY and TxEMPT bits will be set in the status register. When a character is loaded to the transmit FIFO the TxEMPT bit will be reset. The TxEMPT will not set until: 1) the transmit FIFO is empty and the transmit shift register has finished transmitting the stop bit of the last character written to the transmit FIFO, or 2) the transmitter is disabled and then re-enabled. The TxRDY bit is set whenever the transmitter is enabled and the Tx FIFO is not full. Data is transferred from the holding register to transmit shift register when it is idle or has completed transmission of the previous character. Characters cannot be loaded into the Tx FIFO while the transmitter is disabled.

The transmitter converts the parallel data from the CPU to a serial bit stream on the TxD output pin. It automatically sends a start bit followed by the programmed number of data bits, an optional parity bit, and the programmed number of stop bits. The least significant bit is sent first. Following the transmission of the stop bits, if a new character is not available in the Tx FIFO, the TxD output remains HIGH and the TxEMT bit in the Status Register (SR) will be set to 1. Transmission resumes and the TxEMT bit is cleared when the CPU loads a new character into the Tx FIFO.

If the transmitter is disabled it continues operating until the character currently being transmitted and any characters in the Tx FIFO, including parity and stop bits, have been transmitted. New data cannot be loaded to the Tx FIFO when the transmitter is disabled.

When the transmitter is reset it stops sending data immediately.

The transmitter can be forced to send a break (a continuous LOW condition) by issuing a START BREAK command via the CR register. The break is terminated by a STOP BREAK command or a transmitter reset.

If CTS option is enabled (MR2[4] = 1), the CTS input at IP0 or IP1 must be LOW in order for the character to be transmitted. The transmitter will check the state of the CTS input at the beginning of each character transmitted. If it is found to be HIGH, the transmitter will delay the transmission of any following characters until the CTS has returned to the LOW state. CTS going HIGH during the serialization of a character will not affect that character.

The transmitter can also control the RTSN outputs, OP0 or OP1 via MR2[5]. When this mode of operation is set, the meaning of the OP0 or OP1 signals will usually be end of message. See description of bit MR2[5] in Table 30 “MR2A - Mode Register 2 channel A (address 0x0) bit description” for more detail. This feature may be used to automatically turn around a transceiver in simplex systems.

6.3.2 Receiver

The SC28L92 is conditioned to receive data when enabled through the command register. The receiver looks for a HIGH-to-LOW (mark-to-space) transition of the start bit on the RxD input pin. If a transition is detected, the state of the RxD pin is sampled each 16× clock for 7 clocks to ½ clocks (16× clock mode) or at the next rising edge of the bit time clock (1× clock mode). If RxD is sampled HIGH, the start bit is invalid and the search for a valid start bit begins again. If RxD is still LOW, a valid start bit is assumed and the receiver continues to sample the input at one bit time intervals at the theoretical center of the bit, until the proper number of data bits and parity bit (if any) have been assembled, and one stop bit has been detected. The least significant bit is received first. The data is then transferred to the receive FIFO and the RxRDY bit in the SR is set to a 1. This condition can be programmed to generate an interrupt at OP4 or OP5 and INTRN. If the character length is less than 8 bits, the most significant unused bits in the Rx FIFO are set to zero.

After the stop bit is detected, the receiver will immediately look for the next start bit. However, if a non-zero character was received without a stop bit (framing error) and RxD remains LOW for one half of the bit period after the stop bit was sampled, then the receiver operates as if a new start bit transition had been detected at that point (one-half bit time after the stop bit was sampled).

The parity error, framing error and overrun error (if any) are strobed into the SR from the next byte to be read from the Rx FIFO. If a break condition is detected (RxD is LOW for the entire character including the stop bit), a character consisting of all zeros will be loaded into the Rx FIFO and the received break bit in the SR is set to 1. The RxD input must return to HIGH for two (2) clock edges of the X1 crystal clock for the receiver to recognize the end of the break condition and begin the search for a start bit.

This will usually require a HIGH time of one X1 clock period or 3 X1 edges since the clock of the controller is not synchronous to the X1 clock.

6.3.3 Transmitter reset and disable

Note the difference between transmitter disable and reset. A transmitter reset stops transmitter action immediately, clears the transmitter FIFO and returns the idle state. A transmitter disable withdraws the transmitter interrupts but allows the transmitter to continue operation until all bytes in its FIFO and shift register have been transmitted including the final stop bits. It then returns to its idle state.

6.3.4 Receiver FIFO

The Rx FIFO consists of a First-In-First-Out (FIFO) stack with a capacity of 8 or 16 characters. Data is loaded from the receive shift register into the topmost empty position of the FIFO. The RxRDY bit in the status register is set whenever one or more characters are available to be read, and a FFULL status bit is set if all 8 or 16 stack positions are filled with data. Either of these bits can be selected to cause an interrupt. A read of the Rx FIFO outputs the data at the top of the FIFO. After the read cycle, the data FIFO and its associated status bits (see Section 6.3.5) are popped thus emptying a FIFO position for new data.

A disabled receiver with data in its FIFO may generate an interrupt (see Section 6.3.5). Its status bits remain active and its watchdog, if enabled, will continue to operate.

6.3.5 Receiver status bits

In addition to the data word, three status bits (parity error, framing error and received break) are also appended to each data character in the FIFO. The overrun error, MR1[5], is not FIFOed.

Status can be provided in two ways, as programmed by the error mode control bit in the mode register. In the character mode, status is provided on a character-by-character basis; the status applies only to the character at the top of the FIFO. In the block mode, the status provided in the SR for these three bits is the logic OR of the status for all characters coming to the top of the FIFO since the last reset error from the command register was issued. In either mode reading the SR does not affect the FIFO. The FIFO is popped only when the Rx FIFO is read. Therefore the status register should be read prior to reading the FIFO.

If the FIFO is full when a new character is received, that character is held in the receive shift register until a FIFO position is available. If an additional character is received while this state exits, the contents of the FIFO are not affected; the character previously in the shift register is lost and the overrun error status bit (SR[4]) will be set upon receipt of the start bit of the new (overrunning) character.

The receiver can control the deactivation of RTS. If programmed to operate in this mode, the RTSN output will be negated when a valid start bit was received and the FIFO is full. When a FIFO position becomes available, the RTSN output will be reasserted (set LOW) automatically. This feature can be used to prevent an overrun, in the receiver, by connecting the RTSN output to the CTSN input of the transmitting device.

If the receiver is disabled, the FIFO characters can be read. However, no additional characters can be received until the receiver is enabled again. If the receiver is reset, the FIFO and all of the receiver status, and the corresponding output ports and interrupt are reset. No additional characters can be received until the receiver is enabled again.

6.3.6 Receiver reset and disable

Receiver disable stops the receiver immediately. Data being assembled in the receiver shift register is lost. Data and status in the FIFO is preserved and may be read. A re-enable of the receiver after a disable will cause the receiver to begin assembling characters at the next start bit detected.

A receiver reset will discard the present shift register date, reset the receiver ready bit (RxRDY), clear the status of the byte at the top of the FIFO and realign the FIFO read/write pointers.

6.3.7 Watchdog

A watchdog timer is associated with each receiver. Its interrupt is enabled by MR0[7]. The purpose of this timer is to alert the control processor that characters are in the Rx FIFO which have not been read. This situation may occur at the end of a transmission when the last few characters received are not sufficient to cause an interrupt.

This counter times out after 64 bit times. It is reset each time a character is transferred from the receiver shift register to the Rx FIFO or a read of the Rx FIFO is executed.

6.3.8 Receiver time-out mode

In addition to the watchdog timer described in Section 6.3.7, the counter/timer may be used for a similar function. Its programmability, of course, allows much greater precision of time-out intervals.

The time-out mode uses the received data stream to control the counter. Each time a received character is transferred from the shift register to the Rx FIFO, the counter is restarted. If a new character is not received before the counter reaches zero count, the counter ready bit is set, and an interrupt can be generated. This mode can be used to indicate when data has been left in the Rx FIFO for more than the programmed time limit. Otherwise, if the receiver has been programmed to interrupt the CPU when the receive FIFO is full, and the message ends before the FIFO is full, the CPU may not know there is data left in the FIFO. The CTU and CTL value would be programmed for just over one character time, so that the CPU would be interrupted as soon as it has stopped receiving continuous data. This mode can also be used to indicate when the serial line has been marking for longer than the programmed time limit. In this case, the CPU has read all of the characters from the FIFO, but the last character received has started the count. If there is no new data during the programmed time interval, the counter ready bit will get set, and an interrupt can be generated.

The time-out mode is enabled by writing the appropriate command to the command register. Writing 0xA to CRA or CRB will invoke the time-out mode for that channel. Writing 0xC to CRA or CRB will disable the time-out mode. The time-out mode should only be used by one channel at once, since it uses the C/T. If, however, the time-out mode is enabled from both receivers, the time-out will occur only when **both** receivers have stopped receiving data for the time-out period. CTU and CTL must be loaded with a value greater than the normal receive character period. The time-out mode disables the regular start counter or stop counter commands and puts the C/T into counter mode under the control of the received data stream. Each time a received character is transferred from the shift register to the Rx FIFO, the C/T is stopped after one C/T clock, reloaded with the value in CTU and CTL and then restarted on the next C/T clock. If the C/T is allowed to end the count before a new character has been received, the counter ready bit, ISR[3], will be set. If IMR[3] is set, this will generate an interrupt. Receiving a character after the C/T has timed out will clear the counter ready bit, ISR[3], and the interrupt. Invoking the set time-out mode on command, CRx = 0xA, will also clear the counter ready bit and stop the counter until the next character is received.

6.3.9 Time-out mode caution

When operating in the special time-out mode, it is possible to generate what appears to be a false interrupt, i.e., an interrupt without a cause. This may result when a time-out interrupt occurs and then, **before** the interrupt is serviced, another character is received, i.e., the data stream has started again. (The interrupt latency is longer than the pause in the data stream.) In this case, when a new character has been receiver, the counter/timer will be restarted by the receiver, thereby withdrawing its interrupt. If, at this time, the interrupt service begins for the previously seen interrupt, a read of the ISR will show the counter ready bit not set. If nothing else is interrupting, this read of the ISR will return a 0x00 character.

6.3.10 Multi-drop mode (9-bit or wake-up)

The DUART is equipped with a wake-up mode for multi-drop applications. This mode is selected by programming bits MR1A[4:3] or MR1B[4:3] to 11 for channels A and B, respectively. In this mode of operation, a master station transmits an address character followed by data characters for the addressed slave station. The slave stations, with receivers that are normally disabled, examine the received data stream and wake-up the CPU (by setting RxRDY) only upon receipt of an address character. The CPU compares the received address to its station address and enables the receiver if it wishes to receive the subsequent data characters. Upon receipt of another address character, the CPU may disable the receiver to initiate the process again.

A transmitted character consists of a start bit, the programmed number of data bits, and Address/Data (A/D) bit, and the programmed number of stop bits. The polarity of the transmitted A/D bit is selected by the CPU by programming bit MR1A[2]/MR1B[2]. MR1A[2]/MR1B[2] = 0 transmits a zero in the A/D bit position, which identifies the corresponding data bits as data while MR1A[2]/MR1B[2] = 1 transmits a one in the A/D bit position, which identifies the corresponding data bits as an address. The CPU should program the mode register prior to loading the corresponding data bits into the Tx FIFO.

In this mode, the receiver continuously looks at the received data stream, whether it is enabled or disabled. If disabled, it sets the RxRDY status bit and loads the character into the Rx FIFO if the received A/D bit is a one (address tag), but discards the received character if the received A/D bit is a zero (data tag). If enabled, all received characters are transferred to the CPU via the Rx FIFO. In either case, the data bits are loaded into the data FIFO while the A/D bit is loaded into the status FIFO position normally used for parity error (SRA[5] or SRB[5]). Framing error, overrun error, and break detect operate normally whether or not the receive is enabled.

7. Programming

7.1 Register overview

The operation of the DUART is programmed by writing control words into the appropriate registers. Operational feedback is provided via status registers which can be read by the CPU. The addressing of the registers is described in Table 4.

The contents of certain control registers are initialized to zero on RESET. Care should be exercised if the contents of a register are changed during operation, since certain changes may cause operational problems.

For example, changing the number of bits per character while the transmitter is active may cause the transmission of an incorrect character. In general, the contents of the MR, the CSR, and the OPCR should only be changed while the receiver(s) and transmitter(s) are not enabled, and certain changes to the ACR should only be made while the C/T is stopped.

Each channel has three mode registers (MR0, MR1 and MR2) which control the basic configuration of the channel. Access to these registers is controlled by independent MR address pointers. These pointers are set to 0x0 or 0x1 by MR control commands in the command register Miscellaneous Commands. Each time the MR registers are accessed the MR pointer increments, stopping at MR2. It remains pointing to MR2 until set to 0x0 or 0x1 via the miscellaneous commands of the command register. The pointer is set to 0x1 on reset for compatibility with previous Philips Semiconductors UART software.

Mode, command, clock select, and status registers are duplicated for each channel to provide total independent operation and control. Refer to Section 7.2 for register bit overview. The reserved registers at addresses 0x2 and 0xA should never be read during normal operation since they are reserved for internal diagnostics.

Table 4. SC28L92 register addressing READ (RDN = 0), WRITE (WRN = 0)[1]

Binary address				Read operation (RDN = 0 and CEN = 0)	Write operation (WRN = 0 and CEN = 0)
0	0	0	0	Mode Register A (MR0A, MR1A, MR2A)	Mode Register A (MR0A, MR1A, MR2A)
0	0	0	1	Status Register A (SRA)	Clock Select Register A (CSRA)
0	0	1	0	reserved	Command Register A (CRA)
0	0	1	1	Rx Holding Register A (RxFIFOA)	Tx Holding Register A (TxFIFOA)
0	1	0	0	Input Port Change Register (IPCR)	Auxiliary Control Register (ACR)
0	1	0	1	Interrupt Status Register (ISR)	Interrupt Mask Register (IMR)
0	1	1	0	Counter/Timer Upper (CTU)	C/T Upper Preset Register (CTPU)
0	1	1	1	Counter/Timer Lower (CTL)	C/T Lower Preset Register (CTPL)
1	0	0	0	Mode Register B (MR0B, MR1B, MR2B)	Mode Register B (MR0B, MR1B, MR2B)
1	0	0	1	Status Register B (SRB)	Clock Select Register B (CSRB)
1	0	1	0	reserved	Command Register B (CRB)
1	0	1	1	Rx Holding Register B (RxFIFOB)	Tx Holding Register B (TxFIFOB)
1	1	0	0	Interrupt vector (68xxx mode)	Interrupt vector (68xxx mode)
1	1	0	0	Miscellaneous register (Intel mode), IVR Motorola mode	Miscellaneous register (Intel mode), IVR Motorola mode
1	1	0	1	Input Port Register (IPR)	Output Port Configuration Register (OPCR)
1	1	1	0	start counter command	Set Output Port Bits Command (SOPR)
1	1	1	1	stop counter command	Reset output Port Bits Command (ROPR)

[1] The three MR registers are accessed via the MR Pointer and Commands 0x1n and 0xBn (where n = represents receiver and transmitter enable bits).

Table 5. Registers for channels A and B

Register name	Channel A register	Channel B register	Access
Mode Register	MRnA	MRnB	R/W
Status Register	SRA	SRB	R only
Clock Select	CSRA	CSRB	W only

Table 5. Registers for channels A and B *…continued*

Register name	Channel A register	Channel B register	Access
Command Register	CRA	CRB	W only
Receiver FIFO	RxFIFOA	RxFIFOB	R only
Transmitter FIFO	TxFIFOA	TxFIFOB	W only

Table 6. Registers supporting both channels

Register name	Mnemonic	Access
Input Port Change Register	IPCR	R
Auxiliary Control Register	ACR	W
Interrupt Status Register	ISR	R
Interrupt Mask Register	IMR	W
Counter/Timer Upper value	CTU	R
Counter/Timer Lower value	CTL	R
Counter/Timer Preset Upper	CTPU	W
Counter/Timer Preset Lower	CTPL	W
Input Port Register	IPR	R
Output Configuration Register	OPCR	W
Set Output Port	SOPR	W
Reset Output Port	ROPR	W
Interrupt vector or GP register	IVR/GP	R/W

7.2 Condensed register bit formats

Table 7. MR0 - Mode Register 0

7	6	5	4	3	2	1	0
RxWATCHDOG	RxINT[2]	TxINT[1:0]		FIFOSIZE	BAUDRATE EXTENDED II	TEST2	BAUDRATE EXTENDED I

Table 8. MR1 - Mode Register 1

7	6	5	4	3	2	1	0
RxRTS control	RxINT[1]	ERRORMODE	PARITYMODE		PARITYTYPE	bits per character	

Table 9. MR2 - Mode Register 2

7	6	5	4	3	2	1	0
channel mode		RTSN Control Tx	CTSN Enable Tx	stop bit length			

Table 10. CSR - Clock Select Register

7	6	5	4	3	2	1	0
receiver clock select code				transmitter clock select code			

Table 11. CR - Command Register

7	6	5	4	3	2	1	0
channel command code				disable Tx	enable Tx	disable Rx	enable Rx

Table 12. SR - channel Status Register

7	6	5	4	3	2	1	0
received break	framing error	parity error	overrun error	TxEMT	TxRDY	RxFULL	RxRDY

Table 13. IMR - Interrupt Mask Register (enables interrupts)

7	6	5	4	3	2	1	0
change input port	change break B	RxRDYB	TxRDTYB	counter ready	change break A	RxRDYA	TxRDYA

Table 14. ISR - Interrupt Status Register

7	6	5	4	3	2	1	0
input port change	change break B	RxRDYB FFULLB	TxRDTYB	counter ready	change break A	RxRDYA FFULLA	TxRDYA

Table 15. CTPU - Counter/Timer Preset Register, Upper

7	6	5	4	3	2	1	0
8 MSB of the BRG timer divisor							

Table 16. CTPL - Counter/Timer Preset Register, Lower

7	6	5	4	3	2	1	0
8 LSB of the BRG timer divisor							

Table 17. ACR - Auxiliary Control Register and change of state control

7	6	5	4	3	2	1	0
BRG set select	counter/timer mode and clock source select (see Table 54 on page 44)			enable IP3 COS interrupt	enable IP2 COS interrupt	enable IP1 COS interrupt	enable IP0 COS interrupt

Table 18. IPCR - Input Port Change Register

7	6	5	4	3	2	1	0
delta IP3	delta IP2	delta IP1	delta IP0	state of IP3	state of IP2	state of IP1	state of IP0

Table 19. IPR - Input Port Register

7	6	5	4	3	2	1	0
state of IP7	state of IP6	state of IP5	state of IP4	state of IP3	state of IP2	state of IP1	state of IP0

Table 20. SOPR - Set Output Port bits Register (SOPR)

7	6	5	4	3	2	1	0
set OP7	set OP6	set OP5	set OP4	set OP3	set OP2	set OP1	set OP0

Table 21. ROPR - Reset Output Port bits Register (ROPR)

7	6	5	4	3	2	1	0
reset OP7	reset OP6	reset OP5	reset OP4	reset OP3	reset OP2	reset OP1	reset OP0

Table 22. OPCR - Output Port Configuration Register

OP1 and OP0 are the RTSN output and are controlled by the MR register

7	6	5	4	3	2	1	0
configure OP7	configure OP6	configure OP5	configure OP4	configure OP3	configure OP3	configure OP2	configure OP2

7.3 Register descriptions

7.3.1 Mode registers

7.3.1.1 Mode Register 0 channel A (MR0A)

Table 23. MR0A - Mode Register 0 channel A (address 0x0) bit allocation

MR0 is accessed by setting the MR pointer to logic 0 via the command register command B.

7	6	5	4	3	2	1	0
RxWATCHDOG	RxINT[2]	TxINT[1:0]		FIFOSIZE	BAUDRATE EXTENDED II	TEST2	BAUDRATE EXTENDED I

Table 24. MR0A - Mode Register 0 channel A (address 0x0) bit description

Bit	Symbol	Description
7	RxWATCHDOG	This bit controls the receiver watchdog timer. 0 = disable 1 = enable When enabled, the watchdog timer will generate a receiver interrupt if the receiver FIFO has not been accessed within 64 bit times of the receiver 1× clock. The watchdog timer is used to alert the control processor that data is in the Rx FIFO that has not been read. This situation will occur when the byte count of the last part of a message is not large enough to generate an interrupt. The watchdog timer presents itself as a receiver interrupt with the RxRDY bit set in SR and ISR.
6	RxINT[2]	Bit 2 of receiver FIFO interrupt level. This bit along with bit 6 of MR1 sets the fill level of the FIFO that generates the receiver interrupt. Note that this control is split between MR0 and MR1. This is for backward compatibility to the SC26C92 and SCC2681. For the receiver these bits control the number of FIFO positions filled when the receiver will attempt to interrupt. After the reset the receiver FIFO is empty. The default setting of these bits cause the receiver to attempt to interrupt when it has one or more bytes in it; see Table 25.
5 and 4	TxINT[1:0]	Transmitter interrupt fill level. For the transmitter these bits control the number of FIFO positions empty when the receiver will attempt to interrupt; see Table 26. After the reset the transmit FIFO has 8 bytes empty. It will then attempt to interrupt as soon as the transmitter is enabled. The default setting (TxINT[1:0] = 00) condition the transmitter to attempt to interrupt only when it is completely empty. As soon as one byte is loaded, it is no longer empty and hence will withdraw its interrupt request.

Table 24. MR0A - Mode Register 0 channel A (address 0x0) bit description *...continued*

Bit	Symbol	Description
3	FIFOSIZE	FIFO size for channel A and channel B. Selects the FIFO depth at 8-byte or 16-byte. 0 = 8 bytes 1 = 16 bytes
2	BAUDRATE EXTENDED I	Bits MR0[2:0] are used to select one of the six baud rate groups. See Table 35 for the group organization. 000 = Normal mode 001 = Extended mode I 100 = Extended mode II Other combinations of MR0[2:0] should not be used.
1	TEST2	
0	BAUDRATE EXTENDED II	

Table 25. Receiver FIFO interrupt fill level[1]

RxINT[2:1] (bits MR0[6] and MR1[6])	Interrupt condition
FIFOSIZE = 0 (8 bytes)	
00	1 or more bytes in FIFO (RxRDY)
01	3 or more bytes in FIFO
10	6 or more bytes in FIFO
11	8 bytes in FIFO (RxFULL)
FIFOSIZE = 1 (16 bytes)	
00	1 or more bytes in FIFO (RxRDY)
01	8 or more bytes in FIFO
10	12 or more bytes in FIFO
11	16 bytes in FIFO (RxFULL)

[1] Interrupt fill level must be set when the transmit and receive FIFOs are empty, otherwise the new level takes effect only after a read or a write to the FIFO.

Table 26. Transmitter FIFO interrupt fill level[1]

TxINT[1:0] (bits MR0[5:4])	Interrupt condition
FIFOSIZE = 0 (8 bytes)	
00	8 bytes empty (TxEMPTY)
01	4 or more bytes empty
10	6 or more bytes empty
11	1 or more bytes empty (TxRDY)
FIFOSIZE = 1 (16 bytes)	
00	16 bytes empty (TxEMPTY)
01	8 or more bytes empty
10	12 or more bytes empty
11	1 or more bytes empty (TxRDY)

[1] Interrupt fill level must be set when the transmit and receive FIFOs are empty, otherwise the new level takes effect only after a read or a write to the FIFO.

7.3.1.2 Mode Register 1 channel A (MR1A)

Table 27. MR1A - Mode Register 1 channel A (address 0x0) bit allocation

MR1A is accessed when the channel A MR pointer points to MR1. The pointer is set to MR1 by RESET or by a set pointer command applied via CR command 1. After reading or writing MR1A, the pointer will point to MR2A[1].

7	6	5	4	3	2	1	0
RxRTS control	RxINT[1]	ERRORMODE	PARITYMODE		PARITYTYPE	bits per character	

[1] In block error mode, block error conditions must be cleared by using the error reset command (command 0x4) or a receiver reset.

Table 28. MR1A - Mode Register 1 channel A (address 0x0) bit description

Bit	Symbol	Description
7	RxRTS	Channel A receiver request to send control (flow control). This bit controls the deactivation of the RTSAN output (OP0) by the receiver. This output is normally asserted by setting OPR[0] and negated by resetting OPR[0]. Proper automatic operation of flow control requires OPR[0] (channel A) or OPR[1] (channel B) to be set to logic 1. 0 = No RTS control 1 = RTS control RxRTS = 1 causes RTSAN to be negated (OP0 is driven to a logic 1 [V_{CC}]) upon receipt of a valid start bit if the channel A FIFO is full. This is the beginning of the reception of the 9th byte. If the FIFO is not read before the start of the 10th or 17th byte, an overrun condition will occur and the 10th or 17th or 17th byte will be lost. However, the bit in OPR[0] is not reset and RTSAN will be asserted again when an empty FIFO position is available. This feature can be used for flow control to prevent overrun in the receiver by using the RTSAN output signal to control the CTSN input of the transmitting device.
6	RxINT[1]	Bit 1 of the receiver interrupt control. See description of RxINT[2] in Table 25 and Table 26.
5	ERRORMODE	Channel A error mode select. 0 = character 1 = block This bit selects the operating mode of the three FIFOed status bits (FE, PE, received break) for channel A. In the character mode, status is provided on a character-by-character basis; the status applies only to the character at the top of the FIFO. In the block mode, the status provided in the SR for these bits is the accumulation (logic OR) of the status for all characters coming to the top of the FIFO since the last reset error command for channel A was issued.
4 and 3	PARITYMODE	Channel A parity mode select 00 = with parity 01 = force parity 10 = no parity 11 = multi-drop special mode If with parity or force parity is selected a parity bit is added to the transmitted character and the receiver performs a parity check on incoming data MR1A[4:3] = 11 selects channel A to operate in the special multi-drop mode described in Section 6.3.10 “Multi-drop mode (9-bit or wake-up)”.

Table 28. MR1A - Mode Register 1 channel A (address 0x0) bit description *...continued*

Bit	Symbol	Description
2	PARITYTYPE	Channel A parity type select 0 = even 1 = odd This bit selects the parity type (odd or even) if the with parity mode is programmed by MR1A[4:3], and the polarity of the forced parity bit if the force parity mode is programmed. It has no effect if the no parity mode is programmed. In the special multi-drop mode it selects the polarity of the A/D bit.
1:0	-	Channel A bits per character select. 00 = 5 bits 01 = 6 bits 10 = 7 bits 11 = 8 bits This field selects the number of data bits per character to be transmitted and received. The character length does not include the start, parity, and stop bits.

7.3.1.3 Mode Register 2 channel A (MR2A)

Table 29. MR2A - Mode Register 2 channel A (address 0x0) bit allocation

MR2A is accessed when the channel A MR pointer points to MR2, which occurs after any access to MR1A. Accesses to MR2A do not change the pointer.

7	6	5	4	3	2	1	0
channel mode		RTSN Control Tx	CTSN Enable Tx	stop bit length			

Table 30. MR2A - Mode Register 2 channel A (address 0x0) bit description

Bit	Symbol	Description
7 and 6	-	Channel A mode select. Each channel of the DUART can operate in one of the following four modes: 00 = Normal mode (default) 01 = Automatic echo mode 10 = Local loopback mode 11 = Remote loopback mode Table 31 gives a description of the channel modes The user must exercise care when switching into and out of the various modes. The selected mode will be activated immediately upon mode selection, even if this occurs in the middle of a received or transmitted character. Likewise, if a mode is deselected the device will switch out of the mode immediately. An exception to this is switching out of auto echo or remote loopback modes: if the deselection occurs just after the receiver has sampled the stop bit (indicated in auto echo by assertion of RxRDY), and the transmitter is enabled, the transmitter will remain in auto echo mode until the entire stop has been retransmitted.

Table 30. MR2A - Mode Register 2 channel A (address 0x0) bit description *...continued*

Bit	Symbol	Description
5	-	Channel A transmitter Request To Send (RTS) control. 0 = No RTS control 1 = RTS control This bit controls the deactivation of the RTSAN output (OP0) by the transmitter. This output is normally asserted by setting OPR[0] and negated by resetting OPR[0]. MR2A[5] = 1 caused OPR[0] to be reset automatically one bit time after the characters in the channel A transmit shift register and in the Tx FIFO, if any, are completely transmitted including the programmed number of stop bits, if the transmitter is not enabled This feature can be used to automatically terminate the transmission of a message as follows (line turnaround): 1. Program auto-reset mode: MR2A[5] = 1 2. Enable transmitter 3. Assert RTSAN: OPR[0] = 1 4. Send message 5. Disable transmitter after the last character is loaded into the channel A Tx FIFO 6. The last character will be transmitted and OPR[0] will be reset one bit time after the last stop bit, causing RTSAN to be negated
4	-	Channel A transmitter Clear To Send (CTS) control. 0 = Input CTSAN(IP0) has no effect on the transmitter 1 = CTS control enabled If this bit is a 1, the transmitter checks the state of CTSAN (IP0) each time it is ready to send a character. If IP0 is asserted (LOW), the character is transmitted. If it is negated (HIGH), the TxDA output remains in the marking state and the transmission is delayed until CTSAN goes LOW. Changes in CTSAN while a character is being transmitted do not affect the transmission of that character.
3 to 0	-	Stop bit length select. This field programs the length of the stop bit appended to the transmitted character. Stop bit lengths of $^{9}/_{16}$ to 1 and $1 - {}^{9}/_{16}$ to 2 bits, in increments of $^{1}/_{16}$ bit, can be programmed for character lengths of 6, 7, and 8 bits. For a character lengths of 5 bits, $1 - {}^{1}/_{16}$ to 2 stop bits can be programmed in increments of $^{1}/_{16}$ bit. In all cases, the receiver only checks for a mark condition at the center of the stop bit position (one half-bit time after the last data bit, or after the parity bit if enabled is sampled). Refer to Table 32 for the values. If an external 1× clock is used for the transmitter: MR2A[3] = 0 selects one stop bit MR2A[3] = 1 selects two stop bits

Table 31. DUART mode description

Mode	Description
Normal	The transmitter and receiver operating independently.
Automatic echo	Places the channel in the automatic echo mode, which automatically retransmits the received data. The following conditions are true while in automatic echo mode: 1. Received data is reclocked and retransmitted on the TxDA output 2. The receive clock is used for the transmitter 3. The receiver must be enabled, but the transmitter need not be enabled 4. The channel A TxRDY and TxEMT status bits are inactive 5. The received parity is checked, but is not regenerated for transmission, i.e. transmitted parity bit is as received 6. Character framing is checked, but the stop bits are retransmitted as received 7. A received break is echoed as received until the next valid start bit is detected 8. CPU to receiver communication continues normally, but the CPU to transmitter link is disabled
Local loopback	Selects local loopback diagnostic mode. In this mode: 1. The transmitter output is internally connected to the receiver input 2. The transmit clock is used for the receiver 3. The TxDA output is held HIGH 4. The RxDA input is ignored 5. The transmitter must be enabled, but the receiver need not be enabled 6. CPU to transmitter and receiver communications continue normally
Remote loopback	Selects remote loopback diagnostic mode. In this mode: 1. Received data is reclocked and retransmitted on the TxDA output 2. The receive clock is used for the transmitter 3. Received data is not sent to the local CPU, and the error status conditions are inactive 4. The received parity is not checked and is not regenerated for transmission, i.e., transmitted parity is as received 5. The receiver must be enabled 6. Character framing is not checked, and the stop bits are retransmitted as received 7. A received break is echoed as received until the next valid start bit is detected

Table 32. Stop bit length

MR2A[3:0] (hexadecimal)	Stop bit length[1]
0	0.563
1	0.625
2	0.688
3	0.750
4	0.813
5	0.875
6	0.938
7	1.000
8	1.563
9	1.653
A	1.688

Table 32. Stop bit length *…continued*

MR2A[3:0] (hexadecimal)	Stop bit length[1]
B	1.750
C	1.813
D	1.875
E	1.938
F	2.000

[1] Add 0.5 to values shown for 0 to 7 if channel is programmed for 5 bit per character

7.3.1.4 Mode Register 0 channel B (MR0B)

MR0B (address 0x8) is accessed when the channel B MR pointer points to MR1. The pointer is set to MR0 by RESET or by a set pointer command applied via CRB. After reading or writing MR0B, the pointer will point to MR1B.

The bit definitions for this register are identical to MR0A, except the FIFO size bit and that all control actions apply to the channel B receiver, transmitter, the corresponding inputs and outputs. MR0B[2:0] are reserved.

7.3.1.5 Mode Register 1 channel B (MR1B)

MR1B (address 0x8) is accessed when the channel B MR pointer points to MR1. The pointer is set to MR1 by RESET or by a set pointer command applied via CRB. After reading or writing MR1B, the pointer will point to MR2B.

The bit definitions for this register are identical to MR1A, except that all control actions apply to the channel B receiver and transmitter and the corresponding inputs and outputs.

7.3.1.6 Mode Register 2 channel B (MR2B)

MR2B (address 0x8) is accessed when the channel B MR pointer points to MR2, which occurs after any access to MR1B. Accesses to MR2B do not change the pointer.

The bit definitions for mode register are identical to the bit definitions for MR2A, except that all control actions apply to the channel B receiver and transmitter and the corresponding inputs and outputs.

7.3.2 Clock select registers

Table 33. CSRA - Clock select register channel A (address 0x1) and CSRB - Clock select register channel B (address 0x9) bit allocation

7	6	5	4	3	2	1	0
receiver clock select code				transmitter clock select code			

7.3.2.1 Clock Select Register channel A (CSRA)

Table 34. CSRA - Clock select register channel A (address 0x1) bit description

Bit	Symbol	Description
7 to 4	-	Receiver clock select. The baud rate clock for the channel A receiver is as shown in Table 35, except as follows: 1110 = IP4 - 16× 1111 = IP4 - 1× The receiver clock is always a 16× clock except for CSRA[7:4] = 1111
3 to 0	-	Transmitter clock select. The baud rate clock for the channel A transmitter is as shown in Table 35, except as follows: 1110 = IP3 - 16× 1111 = IP3 - 1× The transmitter clock is always a 16× clock except for CSRA[3:0] = 1111

Table 35. Baud rate (based on a 3.6864 MHz crystal clock)

See Table 36 for bit rate characteristics.

CSR[7:4] CSR[3:0]	MR0[0] = 0 (Normal mode)		MR0[0] = 1 (Extended mode I)		MR0[2] = 1 (Extended mode II)	
	ACR[7] = 0	ACR[7] = 1	ACR[7] = 0	ACR[7] = 1	ACR[7] = 0	ACR[7] = 1
0000	50	75	300	450	4,800	7,200
0001	110	110	110	110	880	880
0010	134.5	134.5	134.5	134.5	1,076	1,076
0011	200	150	1200	900	19.200	14.400
0100	300	300	1800	1800	28.800	28.800
0101	600	600	3600	3600	57.600	57.600
0110	1,200	1,200	7200	7,200	115,200	115,200
0111	1,050	2,000	1,050	2,000	1,050	2,000
1000	2,400	2,400	14,400	14,400	57,600	57,600
1001	4,800	4,800	28,800	28,800	4,800	4,800
1010	7,200	1,800	7,200	1,800	57,600	14,400
1011	9,600	9,600	57,600	57,600	9,600	9,600
1100	38,400	19,200	230,400	115,200	38,400	19,200
1101	Timer	Timer	Timer	Timer	Timer	Timer

Table 36. Bit rate generator characteristics[1]

Crystal or clock = 3.6864 MHz.

Normal rate (baud)	Actual 16× clock (kHz)	Error (%)
50	0.8	0
75	1.2	0
110	1.759	–0.069
134.5	2.153	0.059
150	2.4	0
200	3.2	0
300	4.8	0
600	9.6	0
1050	16.756	–0.260
1200	19.2	0
1800	28.8	0
2000	32.056	0.175
2400	38.4	0
4800	76.8	0
7200	115.2	0
9600	153.6	0
19200	307.2	0
38400	614.4	0

[1] Duty cycle of 16× clock is 50 % ± 1 %.

7.3.2.2 Clock Select Register channel B (CSRB)

Table 37. CSRB - Clock select register channel B (address 0x9) bit description

Bit	Symbol	Description
7 to 4	-	Receiver clock select. The baud rate clock for the channel B receiver is as shown in Table 35, except as follows: 1110 = IP6 - 16× 1111 = IP6 - 1× The receiver clock is always a 16× clock except for CSRB[7:4] = 1111
3 to 0	-	Transmitter clock select. The baud rate clock for the channel A transmitter is as shown in Table 35, except as follows: 1110 = IP5 - 16× 1111 = IP5 - 1× The transmitter clock is always a 16× clock except for CSRB[3:0] = 1111

7.3.3 Command registers

Table 38. CRA - Command register channel A (address 0x2) and CRB - Command register channel B (address 0xA) bit allocation

7	6	5	4	3	2	1	0
channel command code				disable Tx	enable Tx	disable Rx	enable Rx

7.3.3.1 Command Register channel A (CRA)

CRA is a register used to supply commands to channel A. Multiple commands can be specified in a single write to CRA as long as the commands are non-conflicting, e.g., the enable transmitter and reset transmitter commands cannot be specified in a single command word.

Table 39. CRA - Command register channel A (address 0x2) bit description

Bit	Symbol	Description
7 to 4	-	Miscellaneous commands. Execution of the commands in the upper four bits of this register must be separated by 3 X1 clock edges. Other reads or writes (including writes to the lower four bits) may be inserted to achieve this separation. A description of miscellaneous commands is given in Table 40.
3	-	Disable channel A transmitter. This command terminates transmitter operation and reset the TxDRY and TxEMT status bits. However, if a character is being transmitted or if a character is in the Tx FIFO when the transmitter is disabled, the transmission of the character(s) is completed before assuming the inactive state.
2	-	Enable channel A transmitter. Enables operation of the channel A transmitter. The TxRDY and TxEMT status bits will be asserted if the transmitter is idle.
1	-	Disable channel A receiver. This command terminates operation of the receiver immediately-a character being received will be lost. The command has no effect on the receiver status bits or any other control registers. If the special multi-drop mode is programmed, the receiver operates even if it is disabled. See Section 6.3.10.
0	-	Enable channel A receiver. Enables operation of the channel A receiver. If not in the special wake-up mode, this also forces the receiver into the search for start-bit state.

Table 40. Miscellaneous commands

Command	Description
0000	No command.
0001	Reset MR pointer. Causes the channel A MR pointer to point to MR1.
0010	Reset receiver. Resets the channel A receiver as if a hardware reset had been applied. The receiver is disabled and the FIFO is flushed.
0011	Reset transmitter. Resets the channel A transmitter as if a hardware reset had been applied.
0100	Reset error status. Clears the channel A received break, parity error, and overrun error bits in the status register (SRA[7:4]). Used in character mode to clear OE status (although RB, PE and FE bits will also be cleared) and in block mode to clear all error status after a block of data has been received.
0101	Reset channel A break change interrupt. Causes the channel A break detect change bit in the interrupt status register (ISR[2]) to be cleared to zero.

Table 40. Miscellaneous commands *…continued*

Command	Description
0110	Start break. Forces the TxDA output LOW (spacing). If the transmitter is empty the start of the break condition will be delayed up to two bit times. If the transmitter is active the break begins when transmission of the character is completed. If a character is in the Tx FIFO, the start of the break will be delayed until that character, or any other loaded subsequently are transmitted. The transmitter must be enabled for this command to be accepted.
0111	Stop break. The TxDA line will go HIGH (marking) within two bit times. TxDA will remain HIGH for one bit time before the next character, if any, is transmitted.
1000	Assert RTSN. Causes the RTSN output to be asserted (LOW).
1001	Negate RTSN. Causes the RTSN output to be negated (HIGH).
1010	Set time-out mode on. The receiver in this channel will restart the C/T as each receive character is transferred from the shift register to the Rx FIFO. The C/T is placed in the counter mode, the start counter or stop counter commands are disabled, the counter is stopped, and the counter ready bit, ISR[3], is reset. (see also watchdog timer description in the receiver Section 6.3.7.)
1011	Set MR pointer to 0x0.
1100	Disable time-out mode. This command returns control of the C/T to the regular start counter or stop counter commands. It does not stop the counter, or clear any pending interrupts. After disabling the time-out mode, a stop counter command should be issued to force a reset of the ISR[3] bit.
1101	Not used.
1110	Power-down mode on. In this mode, the DUART oscillator is stopped and all functions requiring this clock are suspended. The execution of commands other than disable Power-down mode (1111) requires a X1/CLK. While in the Power-down mode, do not issue any commands to the CR except the disable Power-down mode command. The contents of all registers will be saved while in this mode. It is recommended that the transmitter and receiver be disabled prior to placing the DUART into Power-down mode. This command is in CRA only.
1111	Disable Power-down mode. This command restarts the oscillator. After invoking this command, wait for the oscillator to start up before writing further commands to the CR. This command is in CRA only. For maximum power reduction input pins should be at V_{SS} or V_{DD}.

7.3.3.2 Command Register channel B (CRB)

CRB is a register used to supply commands to channel B. Multiple commands can be specified in a single write to CRB as long as the commands are non-conflicting, e.g., the enable transmitter and reset transmitter commands cannot be specified in a single command word.

The bit definitions for this register are identical to the bit definitions for CRA, with the exception of miscellaneous commands 0xE and 0xF which are used for Power-down mode. These two commands are not used in CRB. All other control actions that apply to CRA also apply to CRB.

7.3.4 Status registers

7.3.4.1 Status Register channel A (SRA)

Table 41. SRA - Status register channel A (address 0x1) bit allocation

7	6	5	4	3	2	1	0
received break[1]	framing error[1]	parity error[1]	overrun error	TxEMTA	TxRDYA	RxFULLA	RxRDYA

[1] These status bits are appended to the corresponding data character in the receive FIFO. A read of the status provides these bits [7:5] from the top of the FIFO together with bits [4:0]. These bits are cleared by a reset error status command. In character mode they are discarded when the corresponding data character is read from the FIFO. In block error mode, the error-reset command (command 0x4 or receiver reset) must used to clear block error conditions.

Table 42. SRA - Status register channel A (address 0x1) bit description

Bit	Symbol	Description
7	-	Channel A received break. 0 = no 1 = yes This bit indicates that an all zero character of the programmed length has been received without a stop bit. Only a single FIFO position is occupied when a break is received: further entries to the FIFO are inhibited until the RxDA line returns to the marking state for at least one-half a bit time two successive edges of the internal or external 1× clock. **This will usually require a HIGH time of one X1 clock period or 3 X1 edges since the clock of the controller is not synchronous to the X1 clock**. When this bit is set, the channel A change in break bit in the ISR (ISR[2]) is set. ISR[2] is also set when the end of the break condition, as defined above, is detected. The break detect circuitry can detect breaks that originate in the middle of a received character. However, if a break begins in the middle of a character, it must persist until at least the end of the next character time in order for it to be detected. This bit is reset by command 0x4 (0100) written to the command register or by receiver reset.
6	-	Channel A framing error. 0 = no 1 = yes This bit, when set, indicates that a stop bit was not detected (not a logic 1) when the corresponding data character in the FIFO was received. The stop bit check is made in the middle of the first stop bit position.
5	-	Channel A parity error. 0 = no 1 = yes This bit is set when the with parity or force parity mode is programmed and the corresponding character in the FIFO was received with incorrect parity. In the special multi-drop mode the parity error bit stores the receive A/D (Address/Data) bit.

Table 42. SRA - Status register channel A (address 0x1) bit description *...continued*

Bit	Symbol	Description
4	-	Channel A overrun error. 0 = no 1 = yes This bit, when set, indicates that one or more characters in the received data stream have been lost. It is set upon receipt of a new character when the FIFO is full and a character is already in the receive shift register waiting for an empty FIFO position. When this occurs, the character in the receive shift register (and its break detect, parity error and framing error status, if any) is lost. This bit is cleared by a reset error status command.
3	TxEMTA	Channel A transmitter empty. 0 = no 1 = yes This bit will be set when the transmitter under runs, i.e., both the TxEMT and TxRDY bits are set. This bit and TxRDY are set when the transmitter is first enabled and at any time it is re-enabled after either (a) reset, or (b) the transmitter has assumed the disabled state. It is always set after transmission of the last stop bit of a character if no character is in the Tx Holding Register (TxFIFOA) awaiting transmission. It is reset when the Tx Holding Register (TxFIFOA) is loaded by the CPU, a pending transmitter disable is executed, the transmitter is reset, or the transmitter is disabled while in the under run condition.
2	TxRDYA	Channel A transmitter ready. 0 = no 1 = yes This bit, when set, indicates that the transmit FIFO is not full and ready to be loaded with another character. This bit is cleared when the transmit FIFO is loaded by the CPU and there are (after this load) no more empty locations in the FIFO. It is set when a character is transferred to the transmit shift register. TxRDYA is reset when the transmitter is disabled and is set when the transmitter is first enabled. Characters loaded to the Tx FIFO while this bit is logic 0 will be lost. This bit has different meaning from ISR[0].
1	FFULLA	Channel A FIFO full. 0 = no 1 = yes This bit is set when a character is transferred from the receive shift register to the receive FIFO and the transfer causes the FIFO to become full, i.e., all eight (or 16) FIFO positions are occupied. It is reset when the CPU reads the receive FIFO. If a character is waiting in the receive shift register because the FIFO is full, FFULLA will not be reset when the CPU reads the receive FIFO. This bit has different meaning from ISR1 when MR1[6] is programmed to a logic 1
0	RxRDYA	Channel A receiver ready. 0 = no 1 = yes This bit indicates that a character has been received and is waiting in the FIFO to be read by the CPU. It is set when the character is transferred from the receive shift register to the FIFO and reset when the CPU reads the receive FIFO, only if (after this read) there are no more characters in the FIFO - the Rx FIFO becomes empty.

7.3.4.2 Status Register channel B (SRB)

Table 43. SRB - Status register channel B (address 0x9) bit allocation

7	6	5	4	3	2	1	0
received break[1]	framing error[1]	parity error[1]	overrun error	TxEMTB	TxRDYB	RxFULLB	RxRDYB

[1] These status bits are appended to the corresponding data character in the receive FIFO. A read of the status provides these bits [7:5] from the top of the FIFO together with bits [4:0]. These bits are cleared by a reset error status command. In character mode they are discarded when the corresponding data character is read from the FIFO. In block error mode, the error-reset command (command 0x4 or receiver reset) must used to clear block error conditions.

The bit definitions for this register are identical to the bit definitions for SRA, except that all status applies to the channel B receiver and transmitter and the corresponding inputs and outputs.

7.3.5 Output Configuration Control Register (OPCR)

This register controls the signal presented by the OP[7:2] pins. The signal presented by the OP[1:0] pins is controlled by the Rx, Tx, and the command register. The default condition of the OP pins is to drive the complement of the data in the OPR[7:0] register.

When OP[7:2] pins drive DMA or interrupt type signals, they switch to open-drain configuration. Otherwise, they drive strong logic 0 or logic 1 levels.

Table 44. OPCR - Output configuration control register (address 0xD) bit allocation

7	6	5	4	3	2	1	0
configure OP7	configure OP6	configure OP5	configure OP4	configure OP3		configure OP2	

Table 45. OPCR - Output configuration control register (address 0xD) bit description

Bit	Symbol	Description
7	-	OP7 output select 0 = The complement of OPR[7] 1 = The channel B transmitter interrupt output which is the complement of ISR[4]. When in this mode OP7 acts as an open-drain output. Note that this output is not masked by the contents of the IMR.
6	-	OP6 output select 0 = The complement of OPR[6] 1 = The channel A transmitter interrupt output which is the complement of ISR[0]. When in this mode OP6 acts as an open-drain output. Note that this output is not masked by the contents of the IMR.
5	-	OP5 output select 0 = The complement of OPR[5] 1 = The channel B receiver interrupt output which is the complement of ISR[5]. When in this mode OP5 acts as an open-drain output. Note that this output is not masked by the contents of the IMR.
4	-	OP4 output select 0 = The complement of OPR[4] 1 = The channel A receiver interrupt output which is the complement of ISR[1]. When in this mode OP4 acts as an open-drain output. Note that this output is not masked by the contents of the IMR.

Table 45. OPCR - Output configuration control register (address 0xD) bit description

Bit	Symbol	Description
3 and 2	-	OP3 output select 00 = The complement of OPR[3] 01 = The counter/timer output, in which case OP3 acts as an open-drain output. In the timer mode, this output is a square wave at the programmed frequency. In the counter mode, the output remains HIGH until terminal count is reached, at which time it goes LOW. The output returns to the HIGH state when the counter is stopped by a stop counter command. Note that this output is not masked by the contents of the IMR. 10 = The 1× clock for the channel B transmitter, which is the clock that shifts the transmitted data. If data is not being transmitted, a free running 1× clock is output. 11 = The 1× clock for the channel B receiver, which is the clock that samples the received data. If data is not being received, a free running 1× clock is output.
1 and 0	-	OP2 output select 00 = The complement of OPR[2] 01 = The 16× clock for the channel A transmitter. This is the clock selected by CSRA[3:0], and will be a 1× clock if CSRA[3:0] = 1111. 10 = The 1× clock for the channel A transmitter, which is the clock that shifts the transmitted data. If data is not being transmitted, a free running 1× clock is output. 11 = The 1× clock for the channel A receiver, which is the clock that samples the received data. If data is not being received, a free running 1× clock is output.

7.3.6 Set Output Port bits Register (SOPR)

Ones in the byte written to this register will cause the corresponding bit positions in the OPR to set to 1. Zeros have no effect. This allows software to set individual bits without keeping a copy of the OPR bit configuration.

Table 46. SOPR - Set output port bits register (address 0xE) bit allocation

7	6	5	4	3	2	1	0
set OP7	set OP6	set OP5	set OP4	set OP3	set OP2	set OP1	set OP0

Table 47. SOPR - Set output port bits register (address 0xE) bit description

Bit	Symbol	Description
7	-	OPR 7 1 = set bit 0 = no change
6	-	OPR 6 1 = set bit 0 = no change
5	-	OPR 5 1 = set bit 0 = no change
4	-	OPR 4 1 = set bit 0 = no change
3	-	OPR 3 1 = set bit 0 = no change
2	-	OPR 2 1 = set bit 0 = no change
1	-	OPR 1 1 = set bit 0 = no change
0	-	OPR 0 1 = set bit 0 = no change

7.3.7 Reset Output Port bits Register (ROPR)

Ones in the byte written to the ROPR will cause the corresponding bit positions in the OPR to set to 0. Zeros have no effect. This allows software to reset individual bits without keeping a copy of the OPR bit configuration.

Table 48. ROPR - Reset output port bits register (address 0xF) bit allocation

7	6	5	4	3	2	1	0
reset OP7	reset OP6	reset OP5	reset OP4	reset OP3	reset OP2	reset OP1	reset OP0

Table 49. ROPR - Reset output port bits register (address 0xF) bit description

Bit	Symbol	Description
7	-	OPR 7 1 = reset bit 0 = no change
6	-	OPR 6 1 = reset bit 0 = no change
5	-	OPR 5 1 = reset bit 0 = no change
4	-	OPR 4 1 = reset bit 0 = no change
3	-	OPR 3 1 = set bit 0 = no change
2	-	OPR 2 1 = reset bit 0 = no change
1	-	OPR 1 1 = reset bit 0 = no change
0	-	OPR 0 1 = reset bit 0 = no change

7.3.8 Output Port Register (OPR)

Table 50. OPR - Output port register (no address) bit allocation

The output pins (OP pins) drive the complement of the data in this register as controlled by SOPR and ROPR.

7	6	5	4	3	2	1	0
OP7	OP6	OP5	OP4	OP3	OP2	OP1	OP0

Table 51. OPR - Output port register (no address) bit description

Bit	Symbol	Description
7	-	pin OP7 0 = pin HIGH 1 = pin LOW
6	-	pin OP6 0 = pin HIGH 1 = pin LOW
5	-	pin OP5 0 = pin HIGH 1 = pin LOW
4	-	pin OP4 0 = pin HIGH 1 = pin LOW
3	-	pin OP3 0 = pin HIGH 1 = pin LOW
2	-	pin OP2 0 = pin HIGH 1 = pin LOW
1	-	pin OP1 0 = pin HIGH 1 = pin LOW
0	-	pin OP0 0 = pin HIGH 1 = pin LOW

7.3.9 Auxiliary Control Register (ACR)

Table 52. ACR - Auxiliary control register (address 0x4) bit allocation

7	6	5	4	3	2	1	0
BRG set select	counter/timer mode and clock source select			enable IP3 COS interrupt	enable IP2 COS interrupt	enable IP1 COS interrupt	enable IP0 COS interrupt

Table 53. ACR - Auxiliary control register (address 0x4) bit description

Bit	Symbol	Description
7	-	Baud rate generator set select. This bit selects one of two sets of baud rates to be generated by the BRG (see Table 35). The selected set of rates is available for use by the channel A and B receivers and transmitters as described for CSRA in Table 34 and for CSRB in Table 37. Baud rate generator characteristics are given in Table 36.
6 to 4	-	Counter/timer mode and clock source select. This field selects the operating mode of the counter/timer and its clock source as shown in Table 54.
3 to 0	-	IP3, IP2, IP1 and IP0 change-of-state interrupt enable. 0 = off 1 = enabled This field selects which bits of the input port change register (IPCR) cause the input change bit in the interrupt status register (ISR [7]) to be set. If a bit is in the enabled state the setting of the corresponding bit in the IPCR will also result in the setting of ISR [7], which results in the generation of an interrupt output if IMR [7] = 1. If a bit is in the off state, the setting of that bit in the IPCR has no effect on ISR [7].

Table 54. ACR[6:4] field definition[1]

ACR[6:4]	Mode	Clock source
000	counter	external (IP2)
001	counter	TxCA - 1× clock of channel A transmitter
010	counter	TxCB - 1× clock of channel B transmitter
011	counter	crystal or external clock (X1/CLK) divided by 16
100	timer	external (IP2)
101	timer	external (IP2) divided by 16
110	timer	crystal or external clock (X1/CLK)
111	timer	crystal or external clock (X1/CLK) divided by 16

[1] The timer mode generates a square wave.

7.3.10 Input Port Change Register (IPCR)

Table 55. IPCR - Input port change register (address 0x4) bit allocation

7	6	5	4	3	2	1	0
delta IP3	delta IP2	delta IP1	delta IP0	state of IP3	state of IP2	state of IP1	state of IP0

Table 56. IPCR - Input port change register (address 0x4) bit description

Bit	Symbol	Description
7 to 4	-	IP3, IP2, IP1 and IP0 change of state. 0 = no change 1 = change These bits are set when a change of state, as defined in Section 6.2.9 “Input port”, occurs at the respective input pins. They are cleared when the IPCR is read by the CPU. A read of the IPCR also clears ISR[7], the input change bit in the interrupt status register. The setting of these bits can be programmed to generate an interrupt to the CPU.
3 to 0	-	IP3, IP2, IP1 and IP0 state. 0 = LOW 1 = HIGH These bits provide the current state of the respective inputs. The information is unlatched and reflects the state of the input pins at the time the IPCR is read.

7.3.11 Interrupt Status Register (ISR)

This register provides the status of all potential interrupt sources. The contents of this register are masked by the Interrupt Mask Register (IMR). If a bit in the ISR is a logic 1 and the corresponding bit in the IMR is also a logic 1, the INTRN output will be asserted (LOW). If the corresponding bit in the IMR is a zero, the state of the bit in the ISR has no effect on the INTRN output. Note that the IMR does not mask the reading of the ISR. The true status will be provided regardless of the contents of the IMR. The contents of this register are initialized to 0x0 when the DUART is reset.

Table 57. ISR - Interrupt status register (address 0x5) bit allocation

7	6	5	4	3	2	1	0
change input port	change break B	RxRDYB	TxRDYB	counter ready	change break A	RxRDYA	TxRDYA

Table 58. ISR - Interrupt status register (address 0x5) bit description

Bit	Symbol	Description
7	-	Input port change status. 0 = not active 1 = active This bit is a logic 1 when a change of state has occurred at the IP0, IP1, IP2, or IP3 inputs and that event has been selected to cause an interrupt by the programming of ACR[3:0]. The bit is cleared when the CPU reads the IPCR.

Table 58. ISR - Interrupt status register (address 0x5) bit description *...continued*

Bit	Symbol	Description
6	-	Channel B change in break. 0 = not active 1 = active This bit, when set, indicates that the channel B receiver has detected the beginning or the end of a received break. It is reset when the CPU issues a channel B reset break change interrupt command.
5	RxRDYB	RxB interrupt. 0 = not active 1 = active This bit indicates that the channel B receiver is interrupting according to the fill level programmed by the MR0 and MR1 registers or the watchdog timer has timed-out. This bit has a different meaning than the receiver ready/full bit in the status register.
4	TxRDYB	TxB interrupt. 0 = not active 1 = active This bit indicates that the channel B transmitter is interrupting according to the interrupt level programmed in the MR0[5:4] bits. This bit has a different meaning than the TxRDY bit in the status register.
3	-	Counter ready. 0 = not active 1 = active In the counter mode, this bit is set when the counter reaches terminal count and is reset when the counter is stopped by a stop counter command. In the timer mode, this bit is set once each cycle of the generated square wave (every other time that the counter/timer reaches zero count). The bit is reset by a stop counter command. The command, however, does not stop the counter/timer.
2	-	Channel A change in break. 0 = not active 1 = active This bit, when set, indicates that the channel A receiver has detected the beginning or the end of a received break. It is reset when the CPU issues a channel A reset break change interrupt command.
1	RxRDYA	RxA interrupt. 0 = not active 1 = active This bit indicates that the channel A receiver is interrupting according to the fill level programmed by the MR0 and MR1 registers or the watchdog timer has timed-out. This bit has a different meaning than the receiver ready/full bit in the status register.
0	TxRDYA	TxA interrupt. 0 = not active 1 = active This bit indicates that the channel A transmitter is interrupting according to the interrupt level programmed in the MR0[5:4] bits. This bit has a different meaning than the TxRDY bit in the status register.

7.3.12 Interrupt Mask Register (IMR)

The programming of this register selects which bits in the ISR causes an interrupt output. If a bit in the ISR is a logic 1 and the corresponding bit in the IMR is also a logic 1 the INTRN output will be asserted. If the corresponding bit in the IMR is a zero, the state of the bit in the ISR has no effect on the INTRN output. Note that the IMR does not mask the programmable interrupt outputs OP3 to OP7 or the reading of the ISR.

Table 59. IMR - Interrupt mask register (address 0x5) bit allocation

7	6	5	4	3	2	1	0
input port change	change break B	RxRDYB FFULLB	TxRDYB	counter ready	change break A	RxRDYA FFULLA	TxRDYA

Table 60. IMR - Interrupt mask register (address 0x5) bit description

Bit	Symbol	Description
7	-	Input port change. 0 = not enabled 1 = enabled
6	-	Channel B change in break. 0 = not enabled 1 = enabled
5	RxRDYB FFULLB	RxB interrupt. 0 = not enabled 1 = enabled
4	TxRDYB	TxB interrupt. 0 = not enabled 1 = enabled
3	-	Counter ready. 0 = not enabled 1 = enabled
2	-	Channel A change in break. 0 = not enabled 1 = enabled
1	RxRDYA FFULLA	RxA interrupt. 0 = not enabled 1 = enabled
0	TxRDYA	TxA interrupt. 0 = not enabled 1 = enabled

7.3.13 Interrupt Vector Register (IVR; 68xxx mode) or General Purpose register (GP; 80xxx mode)

This register stores the Interrupt Vector. It is initialized to 0x0F on hardware reset and is usually changed from this value during initialization of the SC28L92. The contents of this register will be placed on the data bus when IACKN is asserted LOW or a read of address 0xC is performed.

When not operating in the 68xxx mode, this register may be used as a general purpose one byte storage register. A convenient use could be to store a shadow of the contents of another SC28L92 register (IMR, for example).

Table 61. IVR/GP - Interrupt vector register or general purpose register (address 0xC) bit allocation

7	6	5	4	3	2	1	0
interrupt vector (68xxx mode) or one byte storage (80xxx mode)							

7.3.14 Counter/timer registers

Table 62. CTPU - Counter/Timer Preset Upper register (address 0x6) bit description

Bit	Symbol	Description
7:0	-	The upper eight (8) bits for the 16-bit counter/timer preset register

Table 63. CTPL - Counter/Timer preset Lower register (address 0x7) bit description

Bit	Symbol	Description
7:0	-	The lower eight (8) bits for the 16-bit counter/timer preset register

The CTPU and CTPL hold the eight MSBs and eight LSBs, respectively, of the value to be used by the counter/timer in either the counter or timer modes of operation. The minimum value which may be loaded into the CTPU/CTPL registers is 0x0002. Note that these registers are write only and cannot be read by the CPU.

In the timer mode, the C/T generates a square wave whose period is twice the value (in C/T clock periods) of the CTPU and CTPL. The waveform so generated is often used for a data clock. The formula for calculating the divisor n to load to the CTPU and CTPL for a particular 1× data clock is shown in Equation 2.

$$n = \frac{counter/timer\ clock\ frequency}{2 \times 16 \times (desired\ baud\ rate)} \quad (2)$$

Often this division will result in a non-integer number; 26.3, for example. One can only program integer numbers in a digital divider. Therefore, 26 would be chosen. This gives a baud rate error of 0.3/26.3 which is 1.14 %; well within the ability asynchronous mode of operation.

The C/T will not be running until it receives an initial start counter command (read at address A3 to A0 = 1110). After this, while in timer mode, the C/T will run continuously. Receipt of a start counter command (read with A3 to A0 = 1110) causes the counter to terminate the current timing cycle and to begin a new cycle using the values in CTPU and CTPL. If the value in CTPU and CTPL is changed, the current half-period will not be affected, but subsequent half periods will be affected.

The counter ready status bit (ISR[3]) is set once each cycle of the square wave. The bit is reset by a stop counter command (read with A3 to A0 = 1111). The command however, does not stop the C/T. The generated square wave is output on OP3 if it is programmed to be the C/T output. In the counter mode, the value C/T loaded into CTPU and CTPL by the CPU is counted down to 0. Counting begins upon receipt of a start counter command. Upon reaching terminal count 0x0000, the counter ready interrupt bit (ISR[3]) is set. The counter continues counting past the terminal count until stopped by the CPU. If OP3 is programmed to be the output of the C/T, the output remains HIGH until terminal count is reached, at which time it goes LOW. The output returns to the HIGH state and ISR[3] is cleared when the counter is stopped by a stop counter command. The CPU may change the values of CTPU and CTPL at any time, but the new count becomes effective only on the next start counter commands. If new values have not been loaded, the previous count values are preserved and used for the next count cycle.

In the counter mode, the current value of the upper and lower 8 bits of the counter (CTU, CTL) may be read by the CPU. It is recommended that the counter be stopped when reading to prevent potential problems which may occur if a carry from the lower 8 bits to the upper 8 bits occurs between the times that both halves of the counter are read. However, note that a subsequent start counter command will cause the counter to begin a new count cycle using the values in CTPU and CTPL.

When the C/T clock divided by 16 is selected, the maximum divisor becomes 1,048,575.

7.4 Output port notes

The output ports are controlled from four places: the OPCR register, the OPR register, the MR registers and the command register (except the SCC2681 and SCC68681). The OPCR register controls the source of the data for the output ports OP2 to OP7. The data source for output ports OP0 and OP1 is controlled by the MR and CR registers. When the OPR is the source of the data for the output ports, the data at the ports is inverted from that in the OPR register.

The content of the OPR register is controlled by the Set Output Port bits command and the Reset Output Port bits command. These commands are at 0xE and 0xF, respectively. When these commands are used, action takes place only at the bit locations where ones exist. For example, a logic 1 in bit location 5 of the data word used with the Set Output Port bits command will result in OPR5 being set to one. The OP5 would then be set to logic 0 (V_{SS}). Similarly, a logic 1 in bit position 5 of the data word associated with the Reset Output Ports bits command would set OPR5 to logic 0 and, hence, the pin OP5 to a logic 1 (V_{DD}).

7.5 The CTS, RTS, CTS enable Tx signals

Clear To Send (CTS) is usually meant to be a signal to the transmitter meaning that it may transmit data to the receiver. The CTS input is on pin IP0 for TxA and on IP1 for TxB. The CTS signal is active LOW; thus, it is called CTSAN for TxA and CTSBN for TxB. RTS is usually meant to be a signal from the receiver indicating that the receiver is ready to receive data. It is also active LOW and is, thus, called RTSAN for RxA and RTSBN for RxB. RTSAN is on pin OP0 and RTSBN is on OP1. A receiver's RTS output will usually be connected to the CTS input of the associated transmitter. Therefore, one could say that RTS and CTS are different ends of the same wire.

MR2[4] is the bit that allows the transmitter to be controlled by the CTS pin (IP0 or IP1). When this bit is set to one AND the CTS input is driven HIGH, the transmitter will stop sending data at the end of the present character being serialized. It is usually the RTS output of the receiver that will be connected to the transmitter's CTS input. The receiver will set RTS HIGH when the receiver FIFO is full AND the start bit of the 9th or 17th character is sensed. Transmission then stops with 9 or 17 valid characters in the receiver. When MR2[4] is set to one, CTSN must be at zero for the transmitter to operate. If MR2[4] is set to zero, the IP pin will have no effect on the operation of the transmitter. MR1[7] is the bit that allows the receiver to control OP0. When OP0 (or OP1) is controlled by the receiver, the meaning of that pin will be.

8. Limiting values

Table 64. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
T_{amb}	ambient temperature		[1][2]	–40	+85	°C
T_{stg}	storage temperature			–65	+150	°C
V_{CC}	voltage from V_{CC} to GND		[3]	–0.5	+7.0	V
V_S	voltage from any pin to GND		[3]	–0.5	V_{CC} + 0.5	V
P_D	package power dissipation					
	PLCC44			-	2.4	W
	QFP44			-	1.78	W
	HVQFN48			-	0.5	W
P_{der}	dissipation derating factor	above 25 °C				
	PLCC44			-	19	mW/°C
	QFP44			-	14	mW/°C
	HVQFN48			-	28	mW/°C

[1] For operation at elevated temperatures, the device must be derated based on 150 °C maximum junction temperature.

[2] Parameters are valid over specified temperature range.

[3] This product includes circuitry specifically designed for the protection of its internal devices from damaging effects of excessive static charge. Nonetheless, it is suggested that conventional precautions be taken to avoid applying any voltages larger than the rated maxima.

9. Static characteristics

Table 65. Static characteristics, 5 V operation[1]

V_{CC} = 5 V ± 10 %; T_{amb} = −40 °C to +85 °C; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{IL}	input LOW voltage			-	-	0.8	V
V_{IH}	input HIGH voltage	except pin X1/CLK		2.4	1.5	-	V
		pin X1/CLK		$0.8V_{CC}$	2.4	-	V
V_{OL}	output LOW voltage	I_{OL} = 2.4 mA		-	0.2	0.4	V
V_{OH}	output HIGH voltage	except open-drain outputs; I_{OH} = −400 µA	[2]	V_{CC} − 0.5	-	-	V
$I_{I(1XPD)}$	Power-down mode input current on pin X1/CLK	V_I = 0 V to V_{CC}		0.5	0.05	0.5	µA
$I_{IL(X1)}$	operating input LOW current on pin X1/CLK	V_I = 0 V		−130	-	0	µA
$I_{IH(X1)}$	operating input HIGH current on pin X1/CLK	V_I = V_{CC}		0	-	130	µA
I_I	input leakage current	V_I = 0 V to V_{CC}					
		all except input port pins		−0.5	+0.05	+0.5	µA
		input port pins	[3]	−8	+0.05	+0.5	µA
I_{OZH}	output off current HIGH, 3-state data bus	V_I = V_{CC}		-	-	0.5	µA
I_{OZL}	output off current LOW, 3-state data bus	V_I = 0 V		−0.5	-	-	µA
I_{ODL}	open-drain output LOW current in off state	V_I = 0 V		−0.5	-	-	µA
I_{ODH}	open-drain output HIGH current in off state	V_I = V_{CC}		-	-	0.5	µA
I_{CC}	power supply current	CMOS input levels	[4]				
		operating mode		-	7	25	mA
		Power-down mode		-	≤1	5	µA

[1] The following conditions apply:

a) Parameters are valid over specified temperature and voltage range.

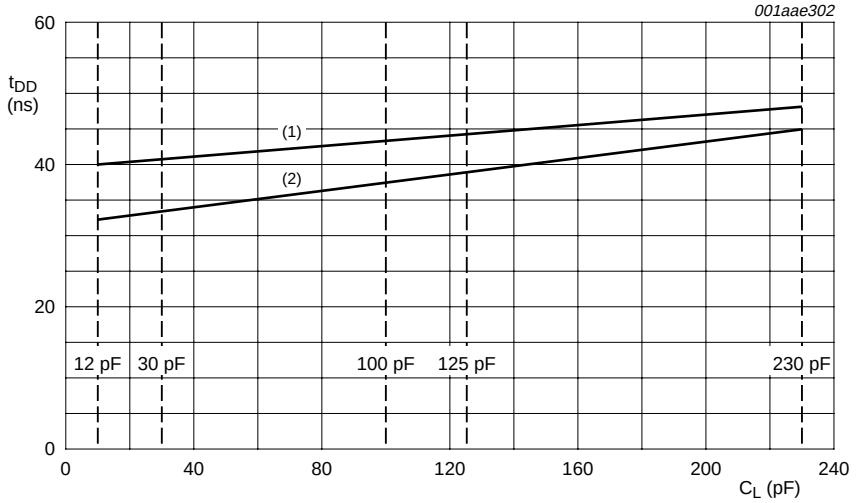
b) All voltage measurements are referenced to ground. For testing, all inputs swing between 0.4 V and 3.0 V with a transition time of 5 ns maximum. For X1/CLK this swing is between 0.4 V and $0.8V_{CC}$. All time measurements are referenced at input voltages of 0.8 V and 2.0 V, and output voltages of 0.8 V and 2.0 V, as appropriate.

c) Typical values are at 25 °C, typical supply voltages, and typical processing parameters.

[2] Test conditions for outputs: C_L = 125 pF, except open-drain outputs. Test conditions for open-drain outputs: C_L = 125 pF, constant current source = 2.6 mA.

[3] Input port pins have active pull-up transistors that will source a typical 2 µA from V_{CC} when the input pins are at V_{SS}. Input port pins at V_{CC} source 0.0 µA.

[4] All outputs are disconnected. Inputs are switching between CMOS levels of V_{CC} − 0.2 V and V_{SS} + 0.2 V.



(1) V_{CC} = 3.3 V; T_{amb} = 25 °C

(2) V_{CC} = 5.0 V; T_{amb} = 25 °C

Bus cycle times:

80xxx mode: $t_{DD} + t_{RWD}$ = 70 ns for V_{CC} = 5 V or 40 ns for V_{CC} = 3.3 V + rise and fall time of control signals.

68xxx mode: $t_{CSC} + t_{DAT}$ + 1 cycle of the X1 clock for = 70 ns for V_{CC} = 5 V + rise and fall time of control signals.

Fig 9. Port timing as a function of capacitive loading at typical conditions

Table 66. Static characteristics, 3.3 V operation[1]

V_{CC} = 3.3 V ± 10 %; T_{amb} = −40 °C to +85 °C; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{IL}	input LOW voltage			-	0.65	$0.2V_{CC}$	V
V_{IH}	input HIGH voltage			$0.8V_{CC}$	1.7	-	V
V_{OL}	output LOW voltage	I_{OL} = 2.4 mA		-	0.2	0.4	V
V_{OH}	output HIGH voltage	except open-drain outputs; I_{OH} = −400 µA	[2]	V_{CC} − 0.5	V_{CC} − 0.2	-	V
$I_{I(1XPD)}$	Power-down mode input current on pin X1/CLK	V_I = 0 V to V_{CC}		−0.5	+0.05	+0.5	µA
$I_{IL(X1)}$	operating input LOW current on pin X1/CLK	V_I = 0 V		−80	-	0	µA
$I_{IH(X1)}$	operating input HIGH current on pin X1/CLK	V_I = V_{CC}		0	-	80	µA
I_I	input leakage current	V_I = 0 V to V_{CC}					
		all except input port pins	[3]	−0.5	+0.05	+0.5	µA
		input port pins	[3]	−8	+0.5	+0.5	µA
I_{OZH}	output off current HIGH, 3-state data bus	V_I = V_{CC}		-	-	0.5	µA
I_{OZL}	output off current LOW, 3-state data bus	V_I = 0 V		−0.5	-	-	µA
I_{ODL}	open-drain output LOW current in off state	V_I = 0 V		−0.5	-	-	µA
I_{ODH}	open-drain output HIGH current in off state	V_I = V_{CC}		-	-	0.5	µA
I_{CC}	power supply current	CMOS input levels	[4]				
		operating mode		-	-	5	mA
		Power-down mode		-	≤1	5.0	µA

[1] The following conditions apply:

a) Parameters are valid over specified temperature and voltage range.

b) All voltage measurements are referenced to ground. For testing, all inputs swing between 0.4 V and 3.0 V with a transition time of 5 ns maximum. For X1/CLK this swing is between 0.4 V and $0.8V_{CC}$. All time measurements are referenced at input voltages of 0.8 V and 2.0 V, and output voltages of 0.8 V and 2.0 V, as appropriate.

c) Typical values are at 25 °C, typical supply voltages, and typical processing parameters.

[2] Test conditions for outputs: C_L = 125 pF, except interrupt outputs. Test conditions for interrupt outputs: C_L = 125 pF, constant current source = 2.6 mA.

[3] Input port pins have active pull-up transistors that will source a typical 2 µA from V_{CC} when they are at V_{SS}. Input port pins at V_{CC} source 0.0 µA.

[4] All outputs are disconnected. Inputs are switching between CMOS levels of V_{CC} − 0.2 V and V_{SS} + 0.2 V.

10. Dynamic characteristics

Table 67. Dynamic characteristics, 5 V operation[1]

V_{CC} = 5.0 V ± 10 %, T_{amb} = −40 °C to +85 °C, unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Reset timing (see Figure 10)						
t_{RES}	reset pulse width		100	18	-	ns
Bus timing[2] (see Figure 11)						
t_{AS}	A0 to A3 set-up time to RDN, WRN LOW		10	6	-	ns
t_{AH}	A0 to A3 hold time from RDN, WRN LOW		20	12	-	ns
t_{CS}	CEN set-up time to RDN, WRN LOW		0	-	-	ns
t_{CH}	CEN hold time from RDN, WRN LOW		0	-	-	ns
t_{RW}	WRN, RDN pulse width (LOW time)		15	8	-	ns
t_{DD}	data valid after RDN LOW	125 pF load; see Figure 9 for smaller loads	-	40	55	ns
t_{DA}	RDN LOW to data bus active	[3]	0	-	-	ns
t_{DF}	data bus floating after RDN or CEN HIGH		-	-	20	ns
t_{DI}	RDN or CEN HIGH to data bus invalid	[4]	0	-	-	ns
t_{DS}	data bus set-up time before WRN or CEN HIGH (write cycle)		25	17	-	ns
t_{DH}	data hold time after WRN HIGH		0	−12	-	ns
t_{RWD}	HIGH time between read and/or write cycles	[2][4]	17	10	-	ns
Port timing[2] (see Figure 15)						
t_{PS}	port in set-up time before RDN LOW (Read IP ports cycle)		0	−20	-	ns
t_{PH}	port in hold time after RDN HIGH		0	−20	-	ns
t_{PD}	OP port valid after WRN or CEN HIGH (OPR write cycle)		-	40	60	ns
Interrupt timing (see Figure 16)						
t_{IR}	INTRN (or OP3 to OP7 when used as interrupts)	read Rx FIFO (RxRDY/FFULL interrupt)	-	40	60	ns
		write Tx FIFO (TxRDY interrupt)	-	40	60	ns
		reset command (delta break change interrupt)	-	40	60	ns
		stop C/T command (counter/timer interrupt	-	40	60	ns
		read IPCR (delta input port change interrupt)	-	40	60	ns
		write IMR (clear of change interrupt mask bit(s))	-	40	60	ns

Table 67. Dynamic characteristics, 5 V operation[1] *…continued*

V_{CC} = 5.0 V ± 10 %, T_{amb} = −40 °C to +85 °C, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
Clock timing (see Figure 17)							
t_{CLK}	X1/CLK HIGH or LOW time			30	20	-	ns
f_{CLK}	X1/CLK frequency		[5]	0.1	3.686	8	MHz
t_{CTC}	C/T clock (IP2) HIGH or LOW time (C/T external clock input)			30	10	-	ns
f_{CTC}	C/T clock (IP2) frequency		[5]	0	-	8	MHz
t_{RX}	RxC HIGH or LOW time	16×		30	10	-	ns
f_{RX}	RxC frequency	16×		0	-	16	MHz
		1×	[5][6]	0	-	1	MHz
t_{TX}	TxC HIGH or LOW time	16×		30	10	-	ns
f_{TX}	TxC frequency	16×		-	-	16	MHz
		1×	[5][6]	0	-	1	MHz
Transmitter timing, external clock (see Figure 18)							
t_{TXD}	TxD output delay from TxC LOW (TxC input pin)			-	40	60	ns
t_{TCS}	output delay from TxC output pin LOW to TxD data output			-	6	30	ns
Receiver timing, external clock (see Figure 19)							
t_{RXS}	RxD data set-up time to RxC HIGH			50	40	-	ns
t_{RXH}	RxD data hold time from RxC HIGH			50	40	-	ns
68xxx or Motorola bus timing (see Figure 12, 13 and 14)[7]							
t_{DCR}	DACKN LOW (read cycle) from X1 HIGH		[7]	-	15	35	ns
t_{DCW}	DACKN LOW (write cycle) from X1 HIGH			-	15	35	ns
t_{DAT}	DACKN high-impedance from CEN or IACKN HIGH			-	8	10	ns
t_{CSC}	CEN or IACKN set-up time to X1 HIGH for minimum DACKN cycle			16	8	-	ns

[1] The following conditions apply:

a) Parameters are valid over specified temperature and voltage range.

b) All voltage measurements are referenced to ground. For testing, all inputs swing between 0.4 V and 3.0 V with a transition time of 5 ns maximum. For X1/CLK this swing is between 0.4 V and 0.8V_{CC}. All time measurements are referenced at input voltages of 0.8 V and 2.0 V, and output voltages of 0.8 V and 2.0 V, as appropriate.

c) Test conditions for outputs: C_L = 125 pF, except open-drain outputs. Test conditions for open-drain outputs: C_L = 125 pF, constant current source = 2.6 mA.

d) Typical values are the average values at +25 °C and 5 V.

[2] Timing is illustrated and referenced to the WRN and RDN Inputs. Also, CEN may be the strobing input. CEN and RDN (also CEN and WRN) are ORed internally. The signal asserted last initiates the cycle and the signal negated first terminates the cycle.

[3] Guaranteed by characterization of sample units.

[4] If CEN is used as the strobing input, the parameter defines the minimum HIGH times between one CEN and the next. The RDN signal must be negated for t_{RWD} to guarantee that any status register changes are valid.

[5] Minimum frequencies are not tested but are guaranteed by design.

[6] Clocks for 1× mode should maintain a 60/40 duty cycle or better.

[7] Minimum DACKN time is ((t_{DCR} or t_{DCW}) t_{CSC} + 2 X1 edges + rise time over 5 ns). Two X1 edges is 273 ns at 3.6864 MHz. For faster bus cycles, the 80xxx bus timing may be used while in the 68xxx mode. It is not necessary to wait for DACKN to insure the proper operation of the SC26C92. In all cases the data will be written to the SC28L92 on the falling edge of DACKN or the rise of CEN. The fall of CEN initializes the bus cycle. The rise of CEN ends the bus cycle. DACKN LOW or CEN HIGH completes the write cycle.

Table 68. Dynamic characteristics, 3.3 V operation[1]

V_{CC} = 3.3 V ± 10 %, T_{amb} = −40 °C to +85 °C, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
Reset timing (see Figure 10)							
t_{RES}	reset pulse width			100	20	-	ns
Bus timing[2] (see Figure 11)							
t_{AS}	A0 to A3 set-up time to RDN, WRN LOW			10	6	-	ns
t_{AH}	A0 to A3 hold time from RDN, WRN LOW			33	16	-	ns
t_{CS}	CEN set-up time to RDN, WRN LOW			0	-	-	ns
t_{CH}	CEN hold time from RDN, WRN LOW			0	-	-	ns
t_{RW}	WRN, RDN pulse width (LOW time)			20	10	-	ns
t_{DD}	data valid after RDN LOW	125 pF load; see Figure 9 for smaller loads		-	46	75	ns
t_{DA}	RDN LOW to data bus active		[3]	0	-	-	ns
t_{DF}	data bus floating after RDN or CEN HIGH			-	15	20	ns
t_{DI}	RDN or CEN HIGH to data bus invalid		[4]	0	-	-	ns
t_{DS}	data bus set-up time before WRN or CEN HIGH (write cycle)			43	20	-	ns
t_{DH}	data hold time after WRN HIGH			0	−15	-	ns
t_{RWD}	HIGH time between read and/or write cycles		[2][4]	27	10	-	ns
Port timing[2] (see Figure 15)							
t_{PS}	port in set-up time before RDN LOW (Read IP ports cycle)			0	−20	-	ns
t_{PH}	port in hold time after RDN HIGH			0	−20	-	ns
t_{PD}	OP port valid after WRN or CEN HIGH (OPR write cycle)			-	50	75	ns
Interrupt timing (see Figure 16)							
t_{IR}	INTRN (or OP3 to OP7 when used as interrupts)	read Rx FIFO (RxRDY/FFULL interrupt)		-	40	79	ns
		write Tx FIFO (TxRDY interrupt)		-	40	79	ns
		reset command (delta break change interrupt)		-	40	79	ns
		stop C/T command (counter/timer interrupt		-	40	79	ns
		read IPCR (delta input port change interrupt)		-	40	79	ns
		write IMR (clear of change interrupt mask bit(s))		-	40	79	ns

Table 68. Dynamic characteristics, 3.3 V operation[1] *...continued*

V_{CC} = 3.3 V ± 10 %, T_{amb} = −40 °C to +85 °C, unless otherwise specified.

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
Clock timing (see Figure 17)							
t_{CLK}	X1/CLK HIGH or LOW time			35	25	-	ns
f_{CLK}	X1/CLK frequency		[5]	0.1	3.686	8	MHz
t_{CTC}	C/T clock (IP2) HIGH or LOW time (C/T external clock input)			30	15	-	ns
f_{CTC}	C/T clock (IP2) frequency		[5]	0	-	8	MHz
t_{RX}	RxC HIGH or LOW time	16×		30	10	-	ns
f_{RX}	RxC frequency	16×		0	-	16	MHz
		1×	[5][6]	0	-	1	MHz
t_{TX}	TxC HIGH or LOW time	16×		30	15	-	ns
f_{TX}	TxC frequency	16×		-	-	16	MHz
		1×	[5][6]	0	-	1	MHz
Transmitter timing, external clock (see Figure 18)							
t_{TXD}	TxD output delay from TxC LOW (TxC input pin)			-	40	78	ns
t_{TCS}	output delay from TxC output pin LOW to TxD data output			-	8	30	ns
Receiver timing, external clock (see Figure 19)							
t_{RXS}	RxD data set-up time to RxC HIGH			50	10	-	ns
t_{RXH}	RxD data hold time from RxC HIGH			50	10	-	ns
68xxx or Motorola bus timing (see Figure 12, 13 and 14)[7]							
t_{DCR}	DACKN LOW (read cycle) from X1 HIGH		[7]	-	18	57	ns
t_{DCW}	DACKN LOW (write cycle) from X1 HIGH			-	18	57	ns
t_{DAT}	DACKN high-impedance from CEN or IACKN HIGH			-	10	15	ns
t_{CSC}	CEN or IACKN set-up time to X1 HIGH for minimum DACKN cycle			30	10	-	ns

[1] The following conditions apply:

a) Parameters are valid over specified temperature and voltage range.

b) All voltage measurements are referenced to ground. For testing, all inputs swing between 0.4 V and 3.0 V with a transition time of 5 ns maximum. For X1/CLK this swing is between 0.4 V and 0.8V_{CC}. All time measurements are referenced at input voltages of 0.8 V and 2.0 V, and output voltages of 0.8 V and 2.0 V, as appropriate.

c) Test conditions for outputs: C_L = 125 pF, except open-drain outputs. Test conditions for open-drain outputs: C_L = 125 pF, constant current source = 2.6 mA.

d) Typical values are the average values at +25 °C and 3.3 V.

[2] Timing is illustrated and referenced to the WRN and RDN Inputs. Also, CEN may be the strobing input. CEN and RDN (also CEN and WRN) are ORed internally. The signal asserted last initiates the cycle and the signal negated first terminates the cycle.

[3] Guaranteed by characterization of sample units.

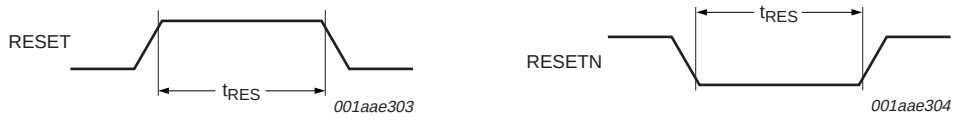
[4] If CEN is used as the strobing input, the parameter defines the minimum HIGH times between one CEN and the next. The RDN signal must be negated for t_{RWD} to guarantee that any status register changes are valid.

[5] Minimum frequencies are not tested but are guaranteed by design.

[6] Clocks for 1× mode should maintain a 60/40 duty cycle or better.

[7] Minimum DACKN time is ((t_{DCR} or t_{DCW}) t_{CSC} + 2 X1 edges + rise time over 5 ns). Two X1 edges is 273 ns at 3.6864 MHz. For faster bus cycles, the 80xxx bus timing may be used while in the 68xxx mode. It is not necessary to wait for DACKN to insure the proper operation of the SC26C92. In all cases the data will be written to the SC28L92 on the falling edge of DACKN or the rise of CEN. The fall of CEN initializes the bus cycle. The rise of CEN ends the bus cycle. DACKN LOW or CEN HIGH completes the write cycle.

11. Timing diagrams



a. 80xxx mode

b. 68xxx mode

Fig 10. Reset timing

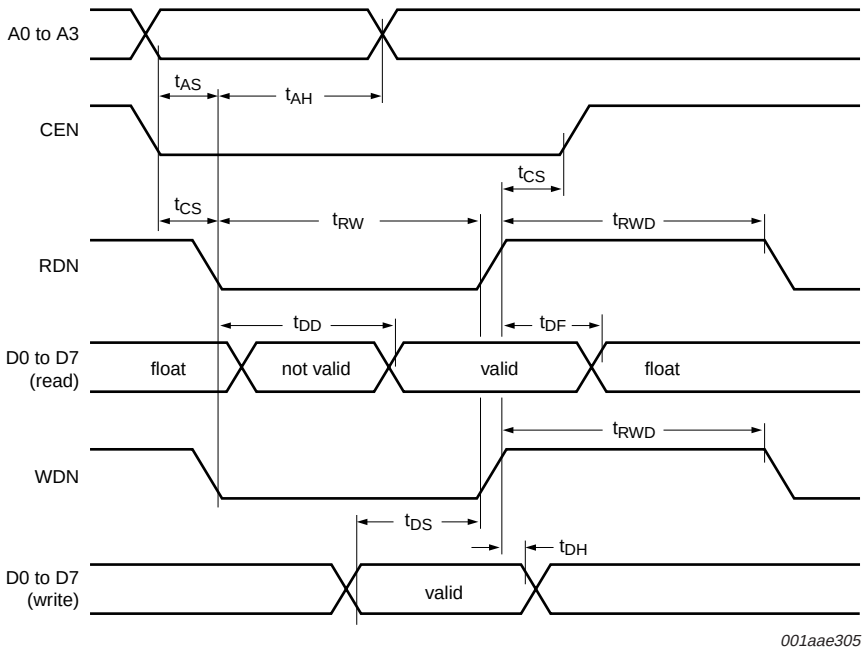
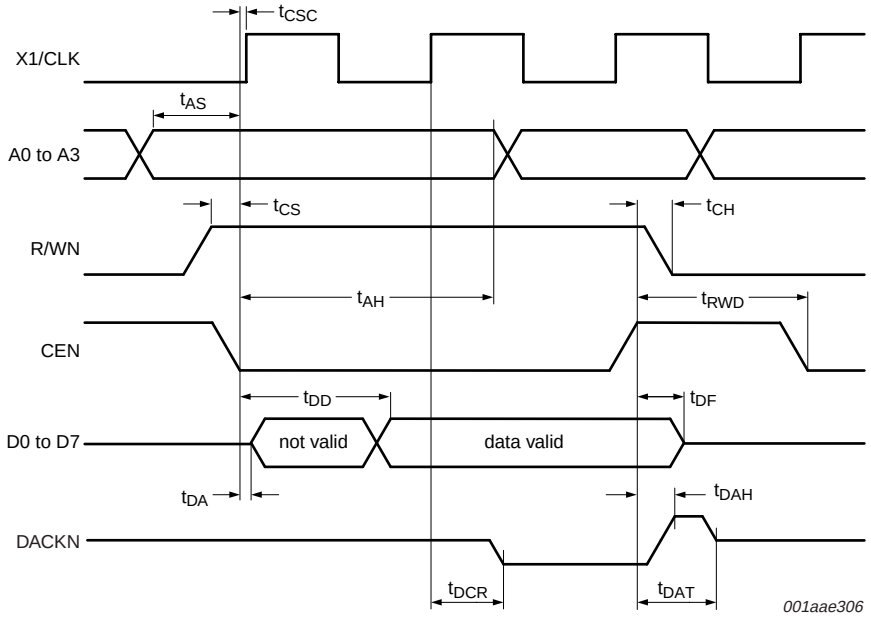
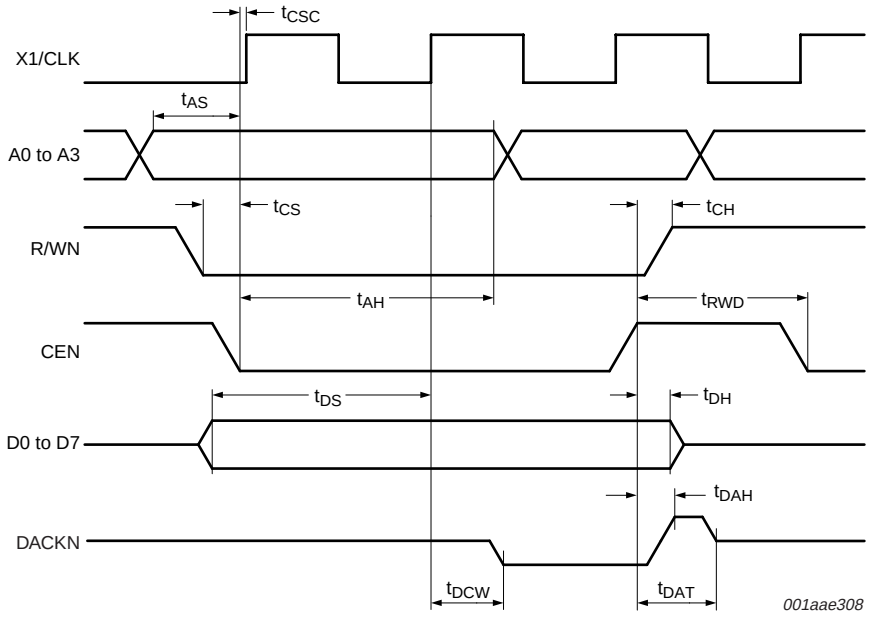


Fig 11. Bus timing (80xxx mode)



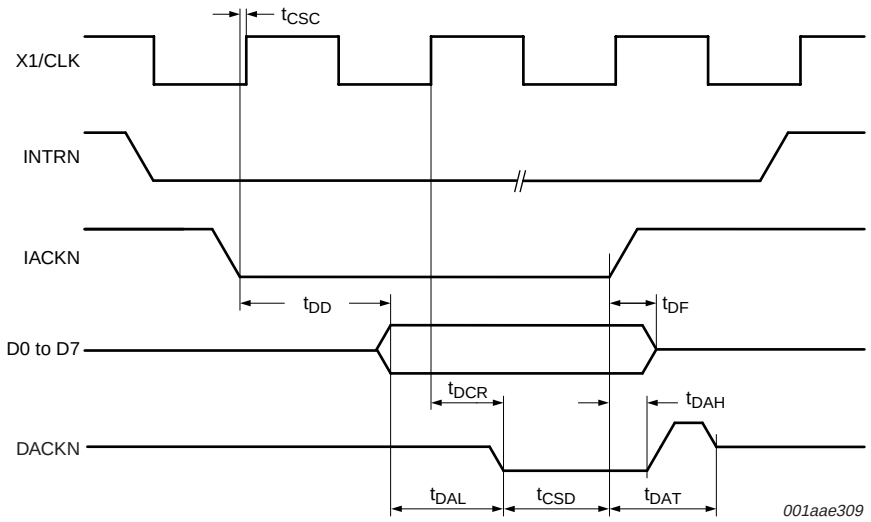
DACKN LOW requires two rising edges of X1 clock after CEN is LOW.

Fig 12. Bus timing, read cycle (68xxx mode)



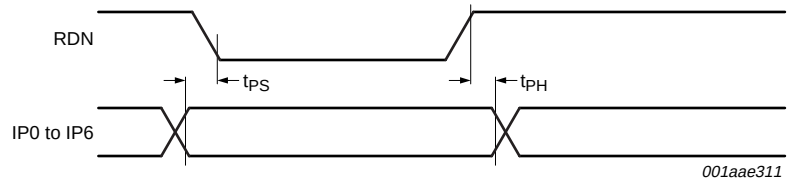
DACKN LOW requires two rising edges of X1 clock after CEN is LOW.

Fig 13. Bus timing, write cycle (68xxx mode)

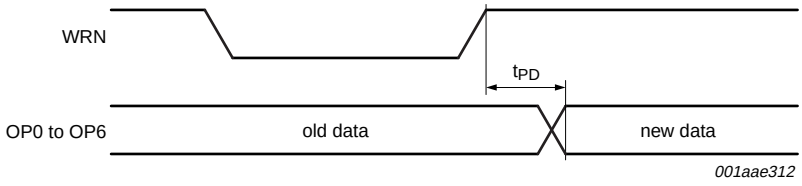


DACKN LOW requires two rising edges of X1 clock after CEN is LOW.

Fig 14. Interrupt cycle timing (68xxx mode)

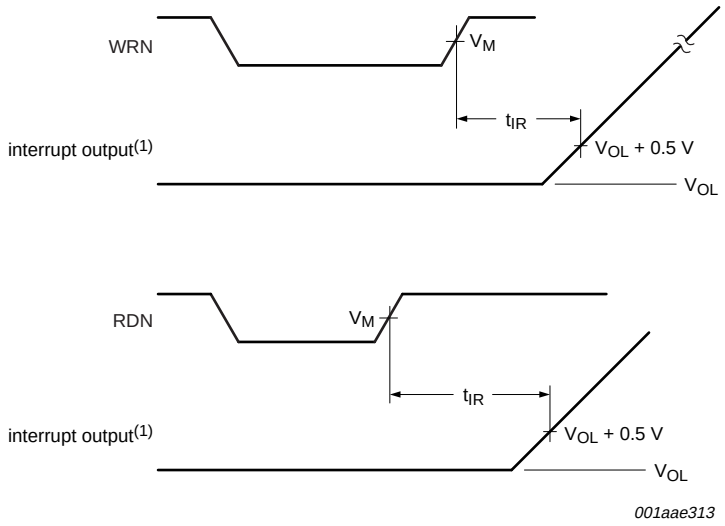


a. Input pins.



b. Output pins.

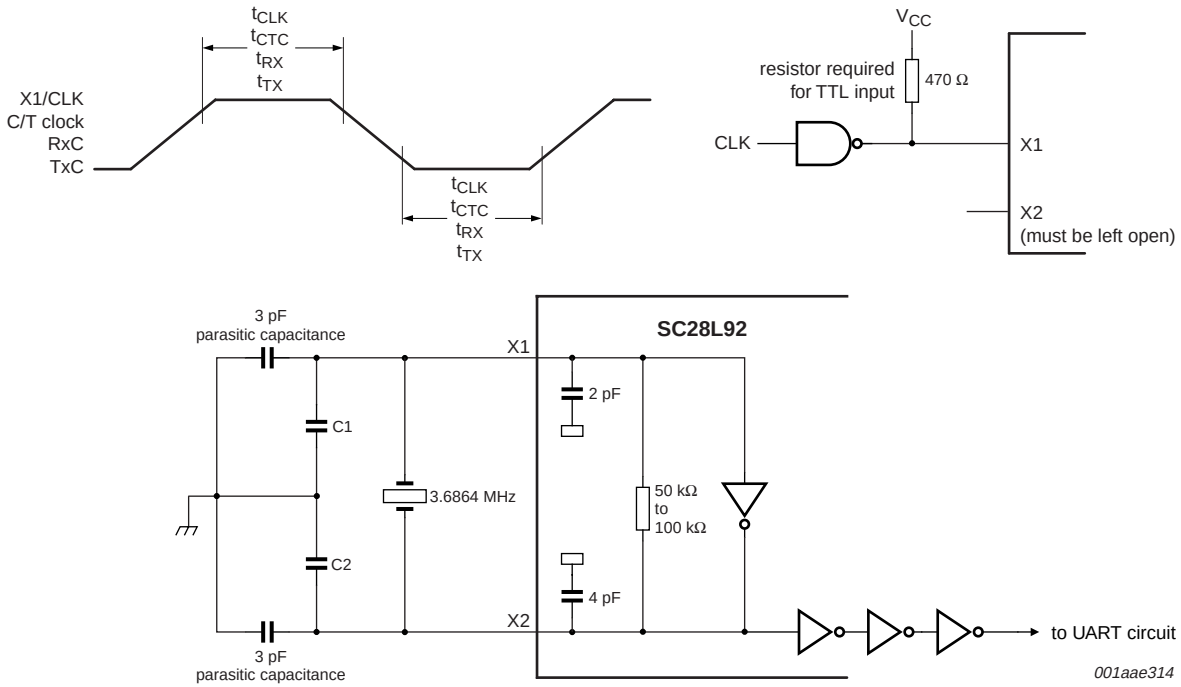
Fig 15. Port timing



The test for open-drain outputs is intended to guarantee switching of the output transistor. Measurement of this response is referenced from the midpoint of the switching signal, V_M, to a point 0.2 V above V_{OL}. This point represents noise margin that assures true switching has occurred. Beyond this level, the effects of external circuitry and test environment are pronounced and can greatly affect the resultant measurement.

(1) IRQN or OP3 to OP7 when used as interrupt outputs.

Fig 16. Interrupt timing (80xxx mode)



C1 = C2 ~ 24 pF for C_L = 13.5 pF. For the oscillator feedback loop, the capacitors C1 and C2 are in series.

C1 and C2 should be chosen according to the crystal manufacturer's specification.

C1 and C2 values will include any parasitic capacitance of the wiring and X1, X2 pins.

Package capacitance approximately 4 pF.

Fig 17. Clock timing

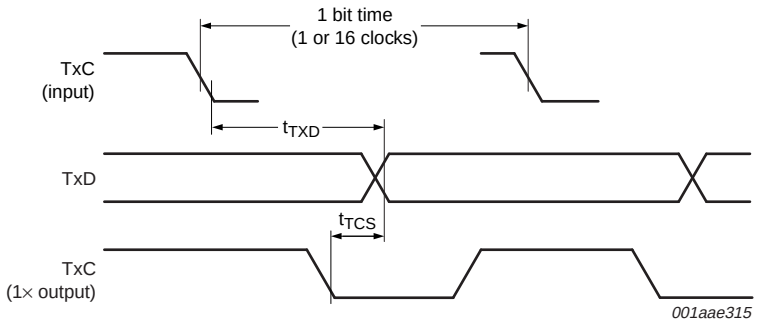


Fig 18. Transmitter external clocks

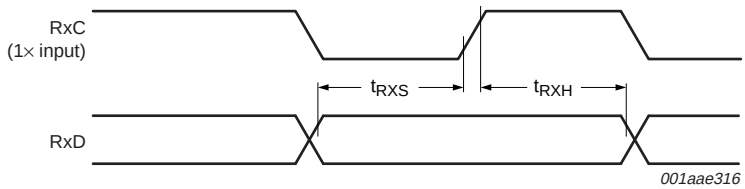
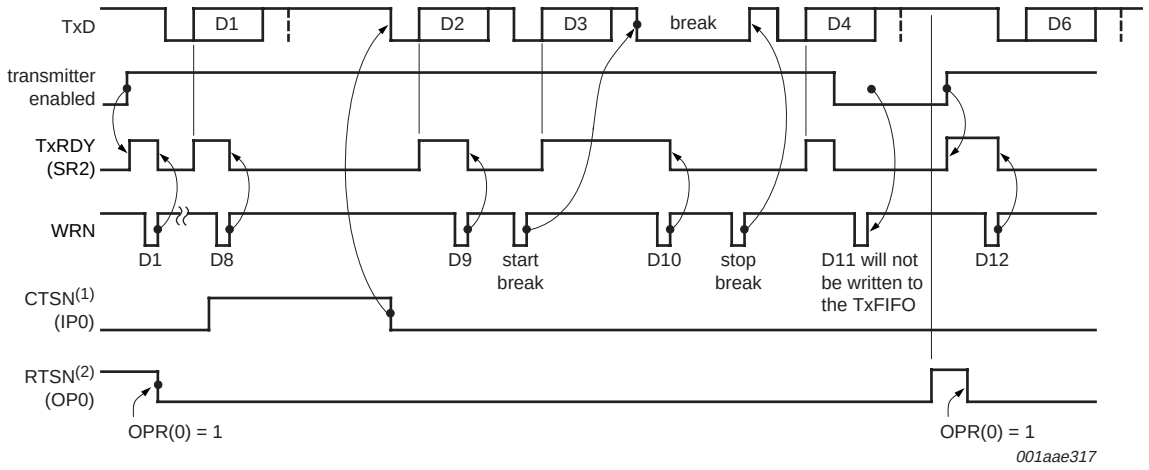


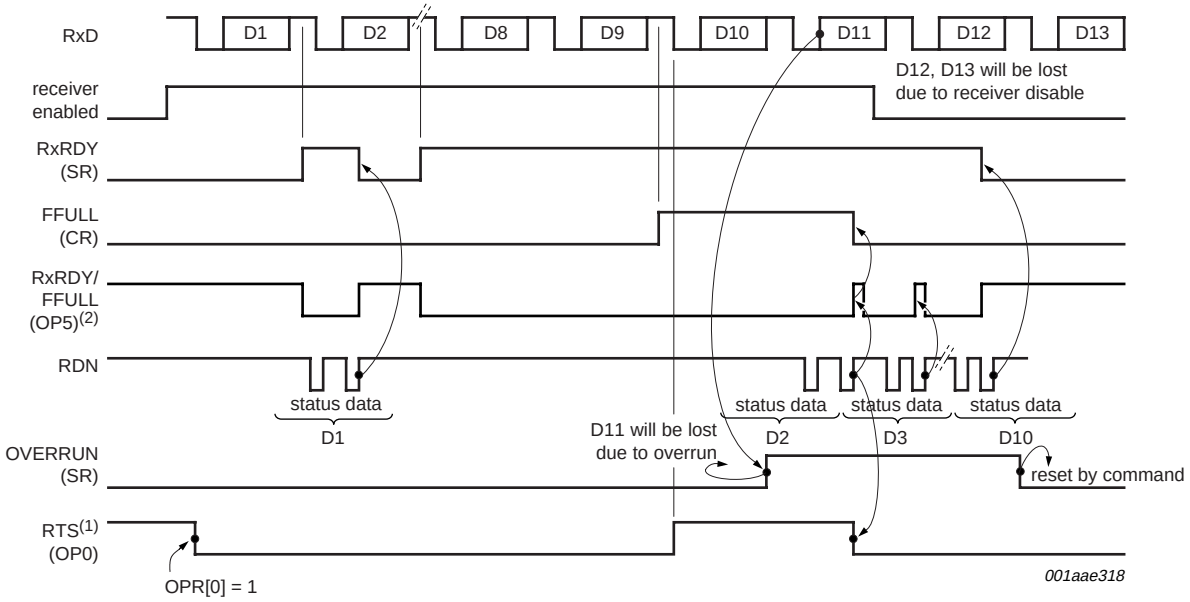
Fig 19. Receiver external clock



(1) Timing shown for MR2[4] = 1.

(2) Timing shown for MR2[5] = 1.

Fig 20. Transmitter timing



(1) Timing shown for MR1[7] = 1.

(2) Shown for OPCR[4] = 1 and MR[6] = 0.

Fig 21. Receiver timing

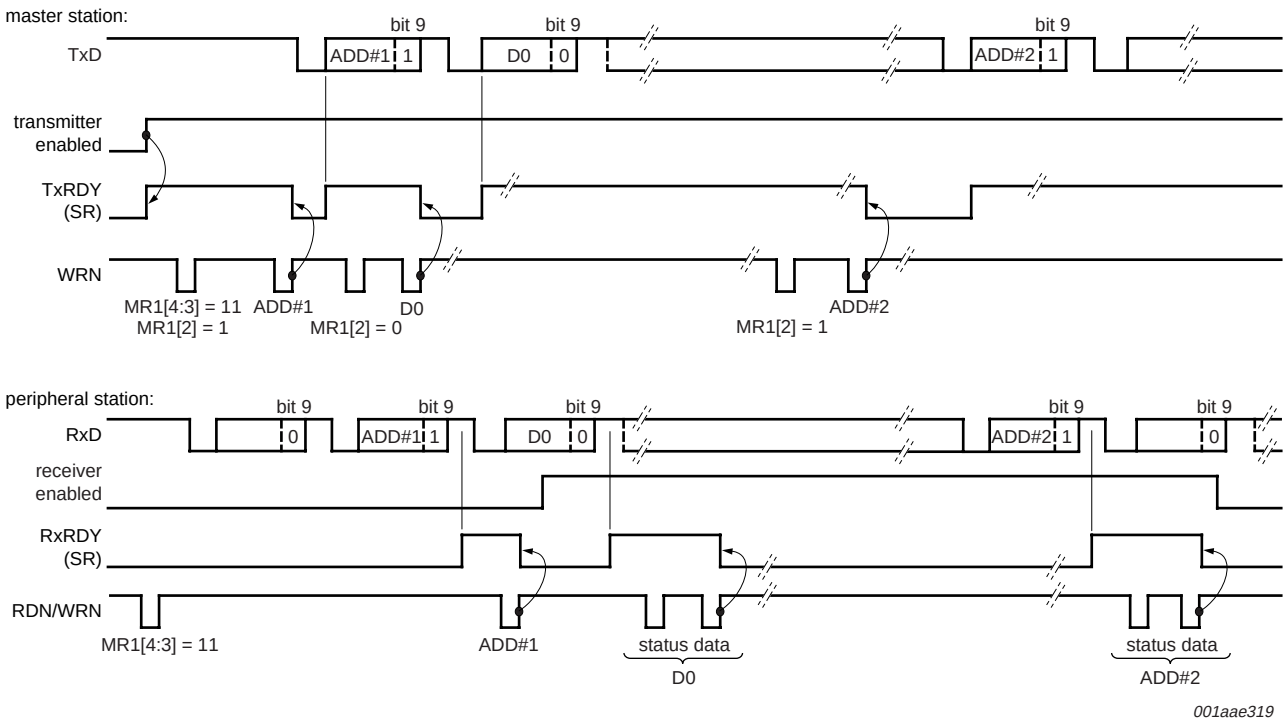


Fig 22. Wake-up mode timing

12. Test information

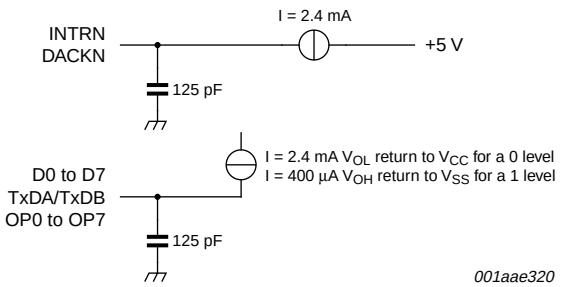
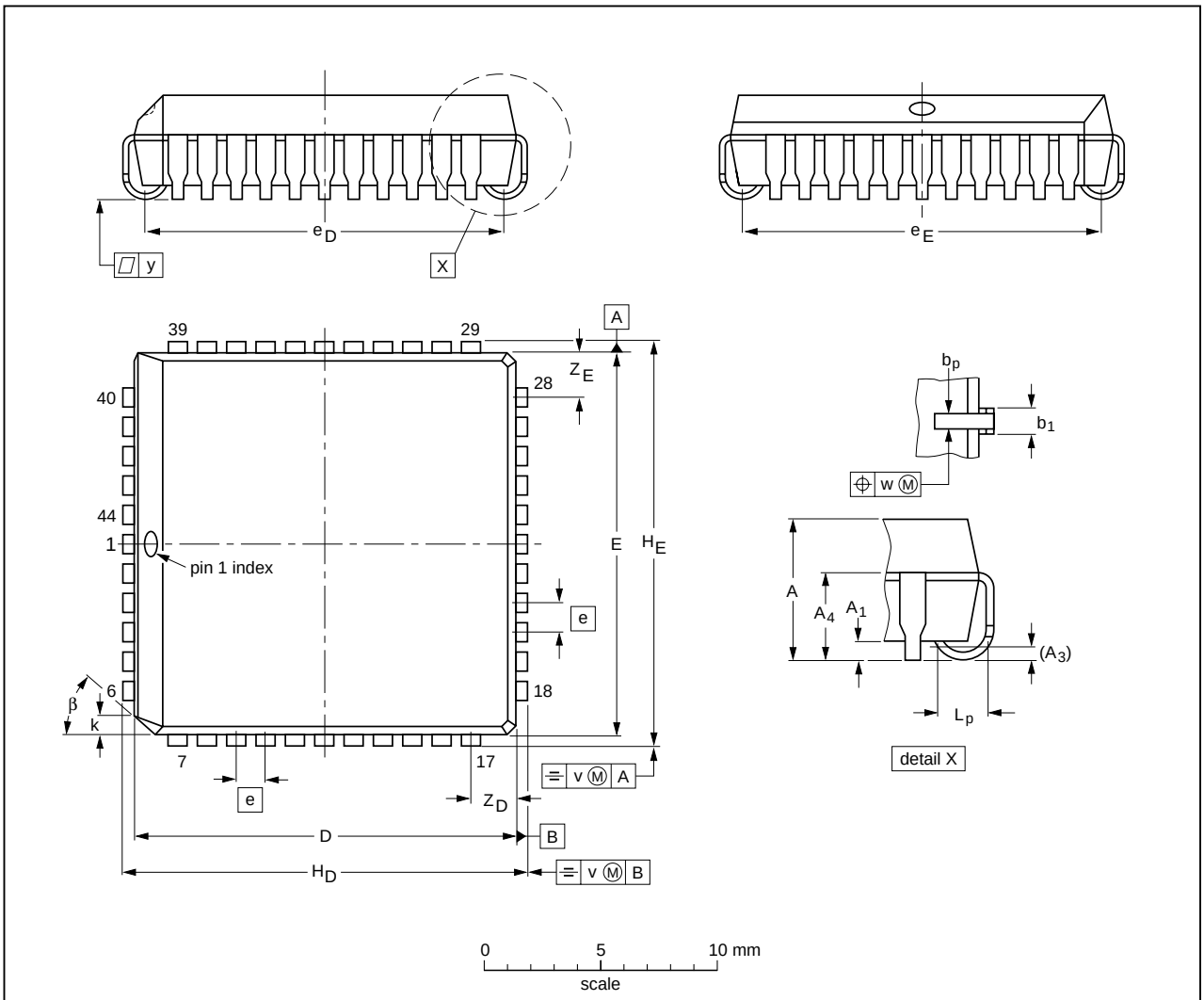


Fig 23. Test conditions on outputs

13. Package outline

PLCC44: plastic leaded chip carrier; 44 leads **SOT187-2**



DIMENSIONS (mm dimensions are derived from the original inch dimensions)

UNIT	A	A_1 min.	A_3	A_4 max.	b_p	b_1	$D^{(1)}$	$E^{(1)}$	e	e_D	e_E	H_D	H_E	k	L_p	v	w	y	$Z_D^{(1)}$ max.	$Z_E^{(1)}$ max.	β
mm	4.57 4.19	0.51	0.25	3.05	0.53 0.33	0.81 0.66	16.66 16.51	16.66 16.51	1.27	16.00 14.99	16.00 14.99	17.65 17.40	17.65 17.40	1.22 1.07	1.44 1.02	0.18	0.18	0.1	2.16	2.16	45°
inches	0.180 0.165	0.02	0.01	0.12	0.021 0.013	0.032 0.026	0.656 0.650	0.656 0.650	0.05	0.63 0.59	0.63 0.59	0.695 0.685	0.695 0.685	0.048 0.042	0.057 0.040	0.007	0.007	0.004	0.085	0.085	

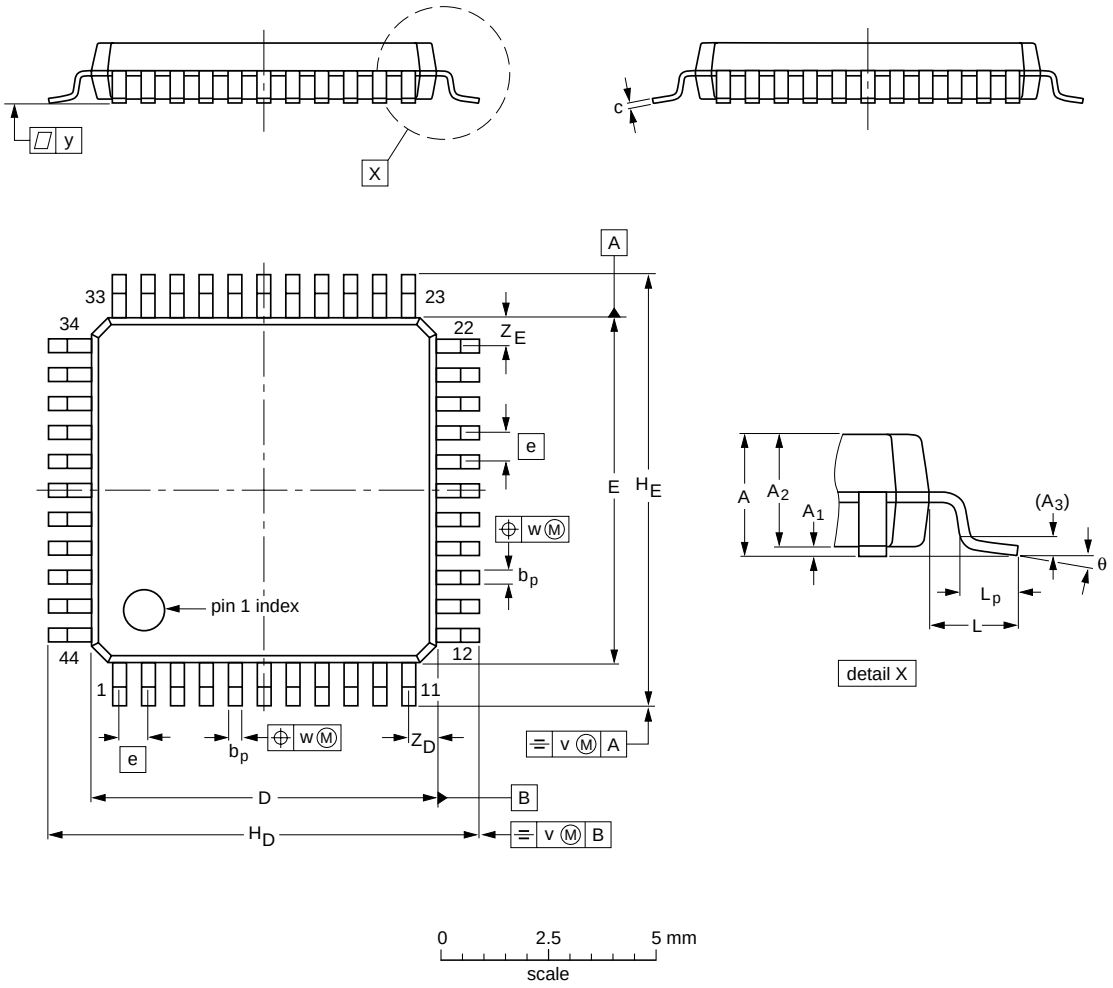
Note

1. Plastic or metal protrusions of 0.25 mm (0.01 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT187-2	112E10	MS-018	EDR-7319			~~99-12-27~~ 01-11-14

Fig 24. Package outline SOT187-2 (PLCC44)

QFP44: plastic quad flat package; 44 leads (lead length 1.3 mm); body 10 x 10 x 1.75 mm **SOT307-2**



DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A_1	A_2	A_3	b_p	c	$D^{(1)}$	$E^{(1)}$	e	H_D	H_E	L	L_p	v	w	y	$Z_D^{(1)}$	$Z_E^{(1)}$	θ
mm	2.1	0.25 0.05	1.85 1.65	0.25	0.4 0.2	0.25 0.14	10.1 9.9	10.1 9.9	0.8	12.9 12.3	12.9 12.3	1.3	0.95 0.55	0.15	0.15	0.1	1.2 0.8	1.2 0.8	10^o 0^o

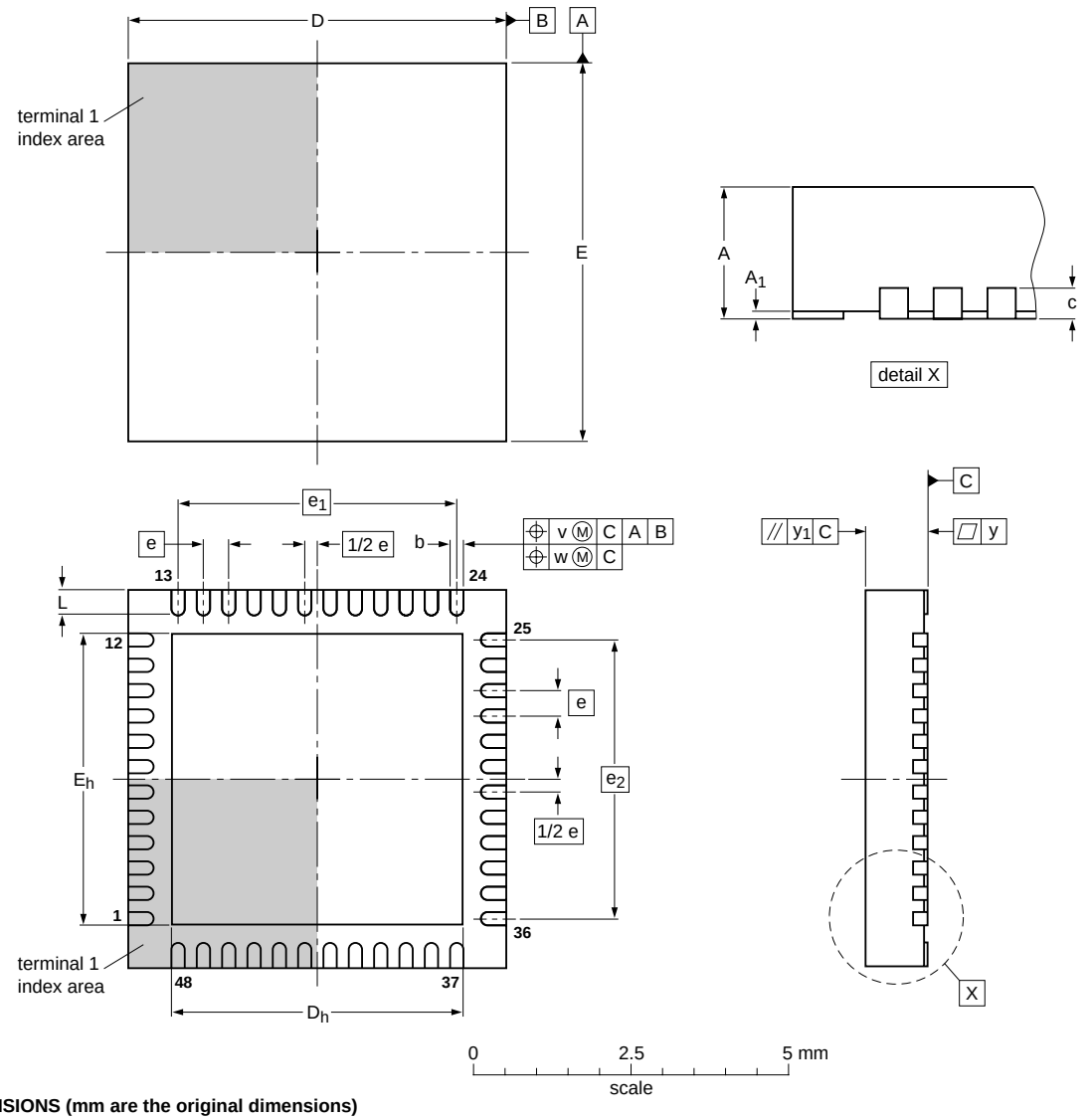
Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT307-2						~~97-08-01~~ 03-02-25

Fig 25. Package outline SOT307-2 (QFP44)

HVQFN48: plastic thermal enhanced very thin quad flat package; no leads; 48 terminals; body 6 x 6 x 0.85 mm **SOT778-4**



DIMENSIONS (mm are the original dimensions)

UNIT	A(1) max	A_1	b	c	D(1)	D_h	E(1)	E_h	e	e_1	e_2	L	v	w	y	y_1
mm	1	0.05 0.00	0.25 0.15	0.2	6.1 5.9	4.75 4.45	6.1 5.9	4.75 4.45	0.4	4.4	4.4	0.5 0.3	0.1	0.05	0.05	0.1

Note

1. Plastic or metal protrusions of 0.075 mm maximum per side are not included

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT778-4	- - -	- - -	- - -			~~04-07-30~~ 04-10-07

Fig 26. Package outline SOT778-4 (HVQFN48)

14. Soldering

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

14.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

14.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus PbSn soldering

14.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

14.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see Figure 27) than a PbSn process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 69 and 70

Table 69. SnPb eutectic process (from J-STD-020C)

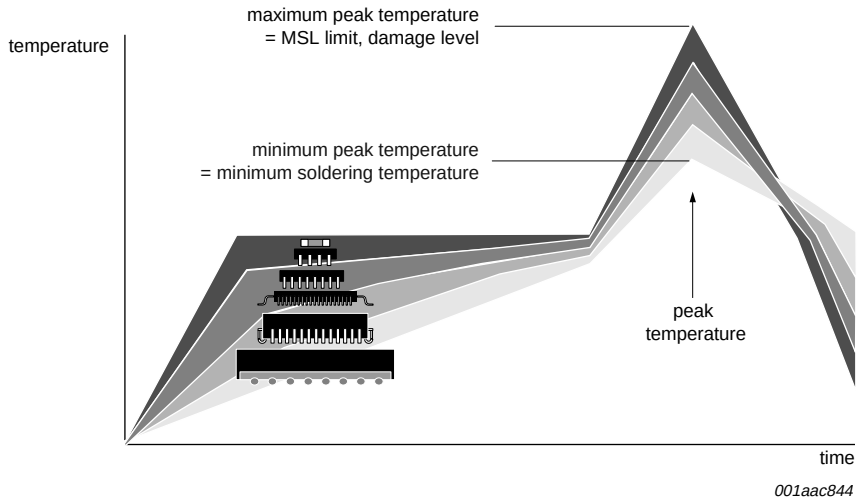
Package thickness (mm)	Package reflow temperature (°C)	
	Volume (mm^3)	
	< 350	≥ 350
< 2.5	235	220
≥ 2.5	220	220

Table 70. Lead-free process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C)		
	Volume (mm^3)		
	< 350	350 to 2000	> 2000
< 1.6	260	260	260
1.6 to 2.5	260	250	245
> 2.5	250	245	245

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see Figure 27.



MSL: Moisture Sensitivity Level

Fig 27. Temperature profiles for large and small components

For further information on temperature profiles, refer to Application Note *AN10365 "Surface mount reflow soldering description"*.

15. Abbreviations

Table 71. Abbreviations

Acronym	Description
DMA	Direct Memory Access
UART	Universal Asynchronous Receiver/Transmitter
FIFO	First In/First Out
CPU	Central Processing Unit
COS	Change Of State
BRG	Baud Rate Generator
MIDI	Musical Instrument Digital Interface
C/T	Counter/Timer

16. Revision history

Table 72. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
SC28L92_7	20071219	Product data sheet	-	SC28L92_6
Modifications:	• The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors. • Legal texts have been adapted to the new company name where appropriate. • added HVQFN48 package option • Figure 1 “Block diagram (80xxx mode)” modified: – reversed position of “control” and “timing” notations – reversed direction of signals IP0 to IP6 • Figure 2 “Block diagram (68xxx mode)” modified: – corrected pin name from “RDN” to “R/WN” – corrected pin name from “WRN” to “IACKN” – corrected pin name from “RESET” to “RESETN” – added signal DACKN – reversed position of “control” and “timing” notations – reversed direction of signals IP0 to IP5 • Section 6.1.4 “FIFO configuration”: – 1st paragraph, 4th sentence: changed “MR0[3] bit” to “MR0A[3] bit” – 1st paragraph, added new 6th sentence – 2nd paragraph: changed “MR0[3] bit” to “MR0A[3] bit” • Table 24 “MR0A - Mode Register 0 channel A (address 0x0) bit description”: – description for bit 3: added “for channel A and channel B” – description for bits [2:0]: in last line of description, changed “MR2[2:0]” to “MR0[2:0]” • Table 25: – added Table note 1 – removed “(default)” (2 places) • Table 26: – added Table note 1 – removed “(default)” (2 places) • Section 7.3.1.4 “Mode Register 0 channel B (MR0B)”, 2nd paragraph re-written. • Table 64 “Limiting values”: added specifications for HVQFN48 package			
SC28L92_6	20060426	Product data sheet	-	SC28L92_5 (9397 750 13125)
SC28L92_5 (9397 750 13125)	20040907	Product specification	-	SC28L92_4 (9397 750 06796)
SC28L92_4 (9397 750 06796)	20000121	Product specification	-	SC28L92_3 (9397 750 05979)
SC28L92_3 (9397 750 05979)	19990507	Product specification	-	SC28L92_2 (9397 750 04465)
SC28L92_2 (9397 750 04465)	19981005	Preliminary specification	-	SC28L92_1
SC28L92_1	-	-	-	-

17. Legal information

17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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