

General Description

The MAX5380/MAX5381/MAX5382 are low-cost, 8-bit digital-to-analog converters (DACs) in miniature 5-pin SOT23 packages, with a simple 2-wire serial interface that allows communication with multiple devices. The MAX5380 has an internal +2V reference and operates from a +2.7V to +3.6V supply. The MAX5381 has an internal +4V reference and operates from a +4.5V to +5.5V supply. The MAX5382 operates over the full +2.7V to +5.5V supply range and has an internal reference equal to 0.9 x V_{DD}.

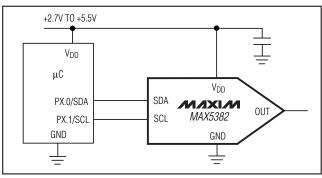
The fast-mode I²C*-compatible serial interface allows communication at data rates up to 400kbps, minimizing board space and reducing interconnect complexity in many applications. Each device is available with one of four factory-preset addresses (see Selector Guide).

These DACs also include an output buffer, a low-power shutdown mode, and a power-on reset that ensures the DAC outputs are at zero when power is initially applied. In shutdown mode, supply current is reduced to less than 1µA and the output is pulled down to GND with a $10k\Omega$ resistor.

Applications

Automatic Tuning (VCO) Power-Amplifier Bias Control Programmable Threshold Levels Automatic Gain Control Automatic Offset Adjustment

Typical Operating Circuit



Features

- ♦ 8-Bit Accuracy in a Miniature 5-Pin SOT23
- ♦ Wide +2.7V to +5.5V Supply Range (MAX5382)
- ♦ Low 230µA max Supply Current
- ♦ 1µA Shutdown Mode
- **♦** Buffered Output Drives Resistive Loads
- ♦ Low-Glitch Power-On Reset to Zero DAC Output
- ♦ Fast I²C-Compatible Serial Interface
- ♦ <±5% Full-Scale Error (MAX5382)
 </p>
- ♦ <±1LSB max INL/DNL</p>

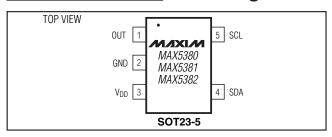
Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	
MAX5380_EUK-T	-40°C to +85°C	5 SOT23	
MAX5381_EUK-T	-40°C to +85°C	5 SOT23	
MAX5382_EUK-T	-40°C to +85°C	5 SOT23	

Selector Guide

PART	ADDRESS	REFERENCE (V)	TOP MARK
MAX5380LEU	JK 0x60	+2.0	ADMN
MAX5380MEU	JK 0x62	+2.0	ADMZ
MAX5380NEU	JK 0x64	+2.0	ADNF
MAX5380PEU	JK 0x66	+2.0	ADMP
MAX5381LEU	JK 0x60	+4.0	ADMV
MAX5381MEU	JK 0x62	+4.0	ADNB
MAX5381NEU	JK 0x64	+4.0	ADNH
MAX5381PEU	JK 0x66	+4.0	ADMR
MAX5382LEU	JK 0x60	0.9 x V _{DD}	ADMX
MAX5382MEU	JK 0x62	0.9 x V _{DD}	ADND
MAX5382NEU	JK 0x64	0.9 x V _{DD}	ADNJ
MAX5382PEU	JK 0x66	0.9 x V _{DD}	ADMT

Pin Configuration



MIXIM

Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

V _{DD} to GND	0.3V to +6V
OUT, SCL, SDA to GND	
Maximum Current into Any Pin	50mA
Continuous Power Dissipation ($T_A = +70^{\circ}C$)	
5-Pin SOT23 (derate 7.1mW/°C above +70°C	C)571mW

Operating Temperature Ranges	
MAX538EUK-T	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Maximum Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = +2.7 \text{V to } +3.6 \text{V (MAX5380)}, V_{DD} = +4.5 \text{V to } +5.5 \text{V (MAX5381)}, V_{DD} = +2.7 \text{V to } +5.5 \text{V (MAX5382)}; R_L = 10 \text{k}\Omega; C_L = 50 \text{pF}, T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are $T_A = +25 ^{\circ}\text{C}$.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
STATIC ACCURACY				1			•
Resolution				8			Bits
Integral Linearity Error	INL	(Note 1)				±1	LSB
Differential Linearity Error	DNL	Guaranteed monot	onic			±1	LSB
Offset Error		(Note 2)			±1	±25	mV
Offset Error Supply Rejection		MAX5382 (Notes 2	, 3)	60			dB
Offset Error Temperature		(Note 2)	MAX5380/MAX5381		3		ppm/°C
Coefficient		(Note 2)	MAX5382		1		Тррпі, С
Full-Scale Error		Code = 255	MAX5380/MAX5381			10	% of
Full-Scale Error		Code = 255	MAX5382			5	ideal FS
Full-Scale Error Supply Rejection		Code = 255, MAX5	5380/MAX5281 (Note 4)			50	dB
Full-Scale Error Temperature		Code = 255	MAX5380/MAX5381		±40		nnm/°C
Coefficient			MAX5382		±10		ppm/°C
DAC OUTPUT			-	1			
		MAX5380		1.8	2	2.2	
Internal Reference (Note 5)	REF	MAX5381 MAX5382		3.6	4	4.4	V
internal helefence (Note 5)	NEF			0.85 x	0.9 x	0.95 x	
				V_{DD}	V_{DD}	V_{DD}	
Output Load Regulation		Code = 255, 0 to 1	00μΑ		0.5		LSB
Output Load Regulation		Code = 0, 0 to 100	μΑ		0.5		LSB
Output Resistance		$V_{OUT} = 0$ to V_{DD} , p	ower-down mode		10		kΩ
DYNAMIC PERFORMANCE	l						
Voltage Output Slew Rate		Positive and negative			0.4		V/µs
Output Settling Time		To 1/2 LSB, 50kΩ and 50pF load (Note 6)			20		μs
Digital Feedthrough		Code = 0, all digital inputs from 0 to V _{DD}			2		nVs
Digital-Analog Glitch Impulse		Code 127 to 128			40		nVs
Wake-Up Time		From software shut	tdown		50		μs

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ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD}=+2.7V\ to\ +3.6V\ (MAX5380),\ V_{DD}=+4.5V\ to\ +5.5V\ (MAX5381),\ V_{DD}=+2.7V\ to\ +5.5V\ (MAX5382);\ R_L=10k\Omega;\ C_L=50pF,\ T_A=T_{MIN}\ to\ T_{MAX},\ unless\ otherwise\ noted.$ Typical values are $T_A=+25^{\circ}C.)$

PARAMETER	SYMBOL	COND	ITIONS	MIN	TYP	MAX	UNITS	
POWER REQUIREMENTS								
		MAX5380		2.7		3.6		
Supply Voltage	V _{DD}	MAX5381		4.5		5.5	V	
		MAX5382		2.7		5.5		
Supply Current	loo	No load, all digital input	s at 0 or V _{DD} , code = 255		150	230	^	
Supply Current	IDD	Shutdown mode				1	μA	
DIGITAL INPUTS (SCL, SDA)								
Input Low Voltage	V _{IL}					0.3 x V _{DD}	V	
Input High Voltage	V _{IH}			0.7 x V _{DD}			V	
Input Hysteresis	V _{HYS}			0.	05 x V _C)D	V	
Input Capacitance	CIN	(Note 7)			10		pF	
Input Leakage Current	I _{IN}					±10	μΑ	
Pulse Width of Spike Suppressed	tsp			0		50	ns	
DIGITAL OUTPUT (SDA, open d	rain)							
Output Low Voltage	Voi	I _{SINK} = 3mA				0.4	V	
	VoL	I _{SINK} = 6mA				0.6	V	
Output Fall Time	tor	VIH(MIN) to VIL(MAX), bus capacitance =	I _{SINK} = 3mA			250	ns	
output I all Tillio	iOF	10pF to 400pF	I _{SINK} = 6mA			250		

TIMING CHARACTERISTICS

(Figure 3; V_{DD} = +2.7V to +3.6V (MAX5380), V_{DD} = +4.5V to +5.5V (MAX5381), V_{DD} = +2.7V to +5.5V (MAX5382); R_L = 10k Ω ; C_L = 50pF, T_A = T_{MIN} to T_{MAX} , unless otherwise noted. Typical values are T_A = +25°C.) (Note 7)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCL Clock Frequency	fscL		0		400	kHz
Bus Free Time Between a STOP and a START Condition	tBUF		1.3			μs
Hold Time Repeated for a START Condition	thd:STA		0.6			μs
Low Period of the SCL Clock	tLOW		1.3			μs
High Period of the SCL Clock	thigh		0.6			μs
Setup Time for a Repeated START Condition	tsu:sta		0.6			μs
Data Hold Time	thd:dat		0		0.9	μs
Data Setup Time	tsu:dat		100			ns

TIMING CHARACTERISTICS (continued)

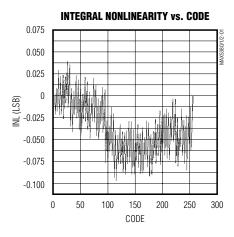
(Figure 3; V_{DD} = +2.7V to +3.6V (MAX5380), V_{DD} = +4.5V to +5.5V (MAX5381), V_{DD} = +2.7V to +5.5V (MAX5382); R_L = 10k Ω ; C_L = 50pF, T_A = T_{MIN} to T_{MAX} , unless otherwise noted. Typical values are T_A = +25°C.) (Note 7)

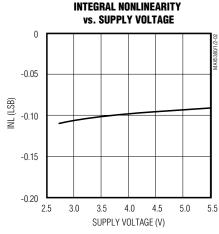
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Rise Time of Both SDA and SCL Signals	t _r				300	ns
Fall Time of Both SDA and SCL Signals	t _f				300	ns
Setup Time for STOP Condition	tsu:sto		0.6			μs
Capacitive Load for Each Bus Line	C _b				400	pF

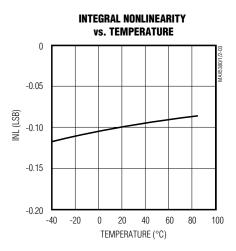
- Note 1: Guaranteed from code 5 to code 255.
- Note 2: The offset value extrapolated from the range over which the INL is guaranteed.
- **Note 3:** MAX5382 tested at $V_{DD} = +5V \pm 10\%$.
- Note 4: MAX5380 tested at V_{DD} = +3V ±10%, MAX5381 tested at V_{DD} = 5V ±10%.
- Note 5: Actual output voltages at full scale are 255/256 x V_{REF}.
- Note 6: Output settling time is measured by taking the code from code 5 to 255, and from code 255 to 5.
- Note 7: Guaranteed by design.

_Typical Operating Characteristics

 $(V_{DD} = +3.0 \text{V (MAX5380)}, V_{DD} = +5.0 \text{V (MAX5381/MAX5382)}; R_L = 10 \text{k}\Omega, T_A = +25 ^{\circ}\text{C}, unless otherwise noted.)$

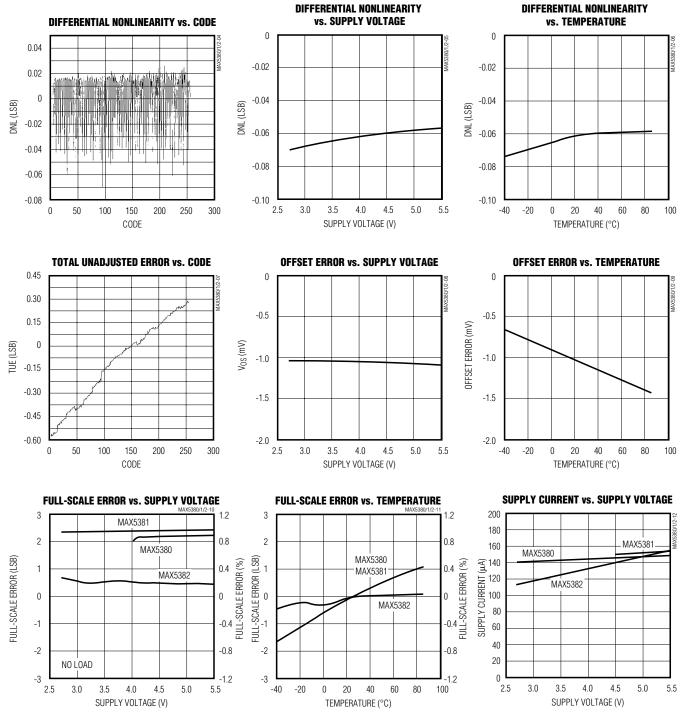






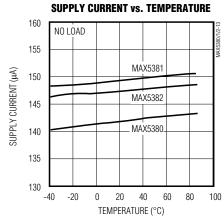
Typical Operating Characteristics (continued)

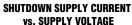
 $(V_{DD} = +3.0V \text{ (MAX5380)}, V_{DD} = +5.0V \text{ (MAX5381/MAX5382)}; R_L = 10k\Omega, T_A = +25^{\circ}C, \text{ unless otherwise noted.})$

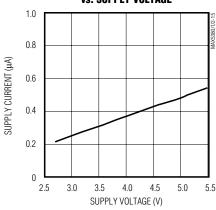


Typical Operating Characteristics (continued)

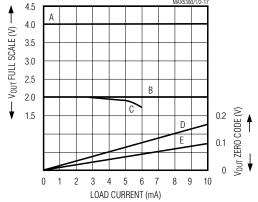
 $(V_{DD} = +3.0V \text{ (MAX5380)}, V_{DD} = +5.0V \text{ (MAX5381/MAX5382)}; R_{L} = 10k\Omega, T_{A} = +25^{\circ}C, unless otherwise noted.)$



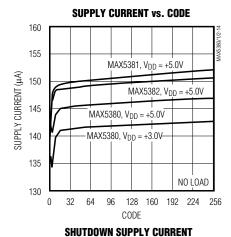




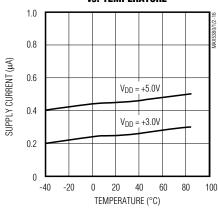
OUTPUT LOAD REGULATION



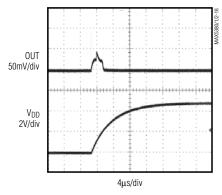
- A: MAX5361/MAX5362, V_{DD} = 4.5V FULL-SCALE OR SOURCING
- B: MAX5360, FULL-SCALE, V_{DD} = 2.7V SINKING, V_{DD} = 5.0V SOURCING
- C: MAX5360, FULL-SCALE, V_{DD} = 2.7V SOURCING
- D: ZERO CODE, V_{DD} = 2.7V SINKING
- E: ZERO CODE, V_{DD} = 5.5V SINKING



VS. TEMPERATURE

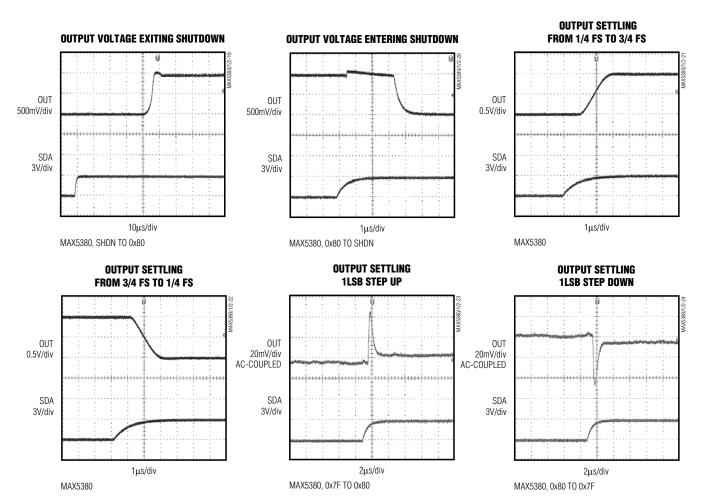


OUTPUT VOLTAGE ON POWER-UP



Typical Operating Characteristics (continued)

 $(V_{DD} = +3.0V \text{ (MAX5380)}, V_{DD} = +5.0V \text{ (MAX5381/MAX5382)}; R_L = 10k\Omega, T_A = +25^{\circ}C, unless otherwise noted.)$



Pin Description

PIN	NAME	FUNCTION
1	OUT	DAC Voltage Output
2	GND	Ground
3	V _{DD}	Power-Supply Input
4	SDA	Serial Data Input
5	SCL	Serial Clock Input

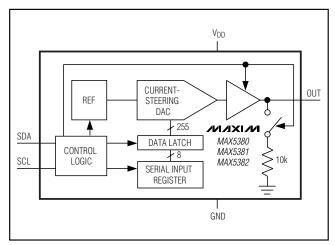


Figure 1. Functional Diagram

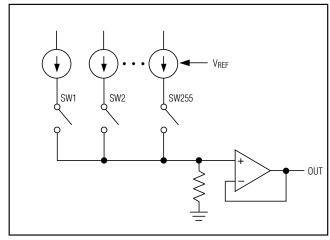


Figure 2. Current-Steering Topology

Table 1. Unipolar Code Output Voltage

DAC CODE	OUTPUT VOLTAGE					
	MAX5380	MAX5381	MAX5382			
1111 1111	2V x (255 / 256)	4V x (255 / 256)	0.9 x V _{DD} x (255 / 256)			
1000 0000	+1V	+2V	0.9 x V _{DD} / 2			
0000 0001	7.8mV	15.6mV	0.9 x V _{DD} / 256			
0000 0000	0	0	0			

Detailed Description

The MAX5380/MAX5381/MAX5382 voltage-output, 8-bit digital-to-analog converters (DACs) offer full 8-bit performance with less than 1LSB integral nonlinearity error and less than 1LSB differential nonlinearity error, ensuring monotonic performance. The devices use a simple 2-wire, fast-mode I²C-compatible serial interface that operates at up to 400kHz. The MAX5380/MAX5381/MAX5382 include an internal reference, an output buffer, and a low-current shutdown mode, which make these devices ideal for low-power, highly integrated applications (See Figure 1. *Functional Diagram*).

Analog Section

The MAX5380/MAX5381/MAX5382 employ a current-steering DAC topology as shown in Figure 2. At the core of the DAC is a reference voltage-to-current converter (V/I) that generates a reference current. This current is mirrored to 255 equally weighted current sources. DAC switches control the outputs of these current mirrors so that only the desired fraction of the total current-mirror

currents is steered to the DAC output. The current is then converted to a voltage across a resistor, and this voltage is buffered by the output buffer amplifier.

Output Voltage

Table 1 shows the relationship between the DAC code and the analog output voltage. The 8-bit DAC code is binary unipolar with 1LSB = V_{REF} / 256. The MAX5380/ MAX5381 have a full-scale output voltage of (+2V - 1LSB) and (+4V - 1LSB), respectively, set by the internal references. The MAX5382 has a full-scale output voltage of (0.9 x V_{DD} - 1LSB).

Output Buffer

The DAC voltage output is an internally buffered unitygain follower that typically slews at $\pm 0.4 \text{V/}\mu\text{s}$. The output can swing from 0 to full scale. With a 1/4 FS to 3/4 FS output transition, the amplifier outputs typically settle to 1/2LSB in less than 5 μ s when loaded with 10k Ω in parallel with 50pF. The buffer amplifiers are stable with any combination of resistive loads >10k Ω and capacitive loads <50pF.

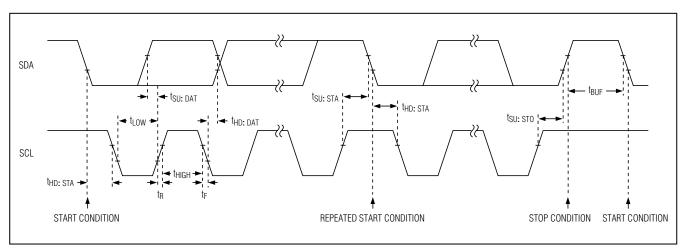


Figure 3. 2-Wire Serial Interface Timing Diagram

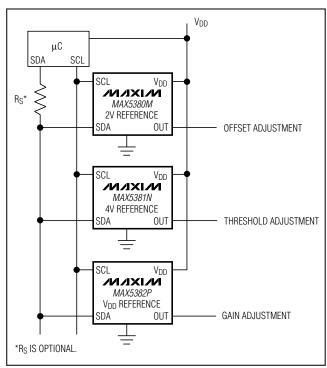


Figure 4. Typical Application Circuit

Power-On Reset

The MAX5380/MAX5381/MAX5382 have a power-on reset circuit to set the DAC's output to 0 when V_{DD} is first applied or when V_{DD} dips below 1.7V (typ). This ensures that unwanted DAC output voltages will not occur immediately following a system startup, such as

after a loss of power. The output glitch at startup is typically less than 50mV.

Shutdown Mode

The MAX5380/MAX5381/MAX5382 include a software-controlled shutdown mode that reduces the supply current to <1 μ A. All internal circuitry is disabled, and an internal 10 $k\Omega$ resistor is placed from OUT to GND to ensure 0V at OUT while in shutdown. The device enters shutdown in less than 5 μ s and exits shutdown in less than 50 μ s.

Digital Section Serial Interface

The MAX5380/MAX5381/MAX5382 use a simple 2-wire serial interface requiring only two I/O lines (2-wire bus) of a standard microprocessor (μP) port. Figure 3 shows the timing diagram for signals on the 2-wire bus.

The two bus lines (SDA and SCL) must be high when the bus is not in use. The MAX5380/MAX5381/ MAX5382 are receive-only devices (slaves) and must be controlled by a bus master device. Figure 4 shows a typical application where up to four devices can be connected to the bus, provided they have different address settings. External pull-up resistors are not necessary on these lines (when driven by push-pull drivers), though these DACs can be used in applications where pull-up resistors are required (such as in I²C systems) to maintain compatibility with existing circuitry. The serial interface operates at SCL rates up to 400kHz. The SDA state is allowed to change only while SCL is low, with the exception of START and STOP conditions as shown in Figure 5. Each transmission consists of a START condition sent by the bus master

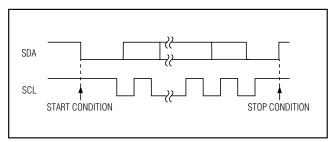


Figure 5. START and STOP Conditions

device, followed by the MAX5380/MAX5381/MAX5382s' preset slave address, a power-mode bit, the DAC data, and finally, a STOP condition (Figure 6). The bus is then free for another transmission.

SDA's state is sampled and therefore must remain stable while SCL is high. Data is transmitted in 8-bit bytes. Nine clock cycles are required to transfer each byte to the MAX5380/MAX5381/MAX5382. Release SDA during the 9th clock cycle since the selected device acknowledges receipt of the byte by pulling SDA low during this time. A series resistor on the SDA line may be needed if the master's output is forced high while the selected device acknowledges (Figure 4).

Slave Address

The MAX5380/MAX5381/MAX5382 are available with one of four preset slave addresses. Each address option is identified by the suffix L, M, N, or P added to the part number. The address is defined as the 7MSBs sent by the master after a START condition. The address options are 0x60, 0x62, 0x64, 0x66 (left justified with LSB set to 0). The 8th bit, typically used to

define a write or read protocol, sets the device's power mode (SHDN). The device is powered-down when SHDN is set to one. During a device search routine, the MAX5380/MAX5381/MAX5382 acknowledge both options (SHDN = 0 or SHDN = 1), but do not change their power state if a stop condition (or restart) is issued immediately. The second byte (DAC data) must be sent/received for the device to update both power mode and DAC output.

DAC Data

The 8-bit DAC data is decoded as straight binary MSB first with 1LSB = V_{REF} / 256 and converted into the corresponding analog voltage as shown in Table 1. After receiving the data byte, the devices acknowledge its receipt and expect a STOP condition, at which point the DAC output is updated.

The MAX5380/MAX5381/MAX5382 update the output and the power mode only if the second byte is clocked in (SHDN = 0) or out (SHDN = 1) of the device. When SHDN = 1, the master will read all ones when clocking out a data byte. The MAX5380/MAX5381/MAX5382 do not drive SDA except for the acknowledge bit.

I²C Compatibility

The MAX5380/MAX5381/MAX5382 are compatible with existing I²C systems. SCL and SDA are high-impedance inputs; SDA has an open drain that pulls the data line low during the 9th clock pulse. Figure 7 shows a typical I²C application. The communication protocol supports standard I²C 8-bit communications. The general call address is ignored, and CBUS formats are not supported. The devices' address is compatible with the 7-bit I²C addressing protocol only. No 10-bit formats

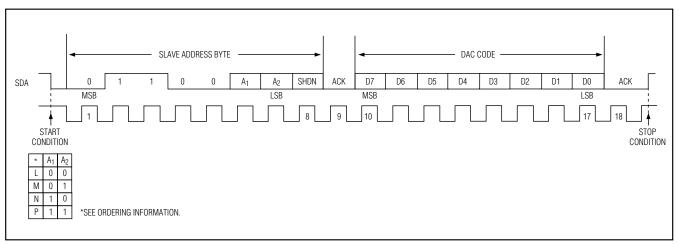


Figure 6. A Complete Serial Transmission

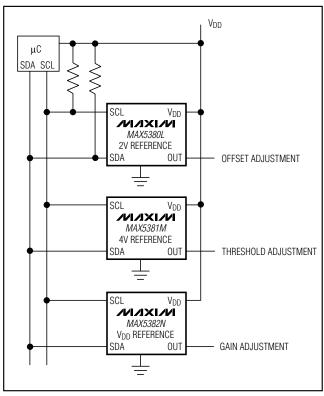


Figure 7. Typical I²C Application

are supported. RESTART protocol is supported, but an immediate STOP condition is necessary to update the DAC. The 8th bit of the address byte, typically used to indicate a read or write protocol, is used in the MAX5380/ MAX5381/MAX5382 to enter or exit shutdown mode. When MAX5380/MAX5381/MAX5382 are addressed in $\rm I^2C$ read mode, they enter shutdown mode.

_Applications Information

Digital Inputs and Interface Logic

The serial 2-wire interface has logic levels defined as $V_{IL} = 0.3 \times V_{DD}$ and $V_{IH} = 0.7 \times V_{DD}$. All inputs include Schmitt trigger buffers to accept slow-transition interfaces. This means that optocouplers can interface directly to the MAX5380/MAX5381/MAX5382 without additional external logic. The digital inputs are compatible with CMOS logic levels and must not be driven with voltages higher than V_{DD} .

Power-Supply Bypassing and Layout

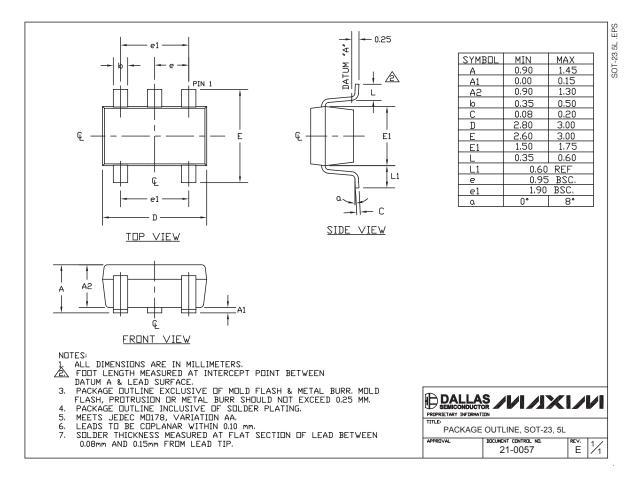
Careful printed circuit board layout is important for best system performance. To reduce crosstalk and noise injection, keep analog and digital signals separate. Ensure that the ground return from GND to the supply ground is short and low impedance; a ground plane is recommended. Bypass VDD with a 0.1 μ F capacitor to ground as close as possible to the device. If the supply is excessively noisy, connect a 10Ω resistor in series with the supply and VDD and add additional capacitance.

_Chip Information

TRANSISTOR COUNT: 2910

Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)



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- Комплексную поставку.
- Работу по проектам и поставку образцов.
- Формирование склада под заказчика.
- Сертификаты соответствия на поставляемую продукцию (по желанию клиента).
- Тестирование поставляемой продукции.
- Поставку компонентов, требующих военную и космическую приемку.
- Входной контроль качества.
- Наличие сертификата ISO.

В составе нашей компании организован Конструкторский отдел, призванный помогать разработчикам, и инженерам.

Конструкторский отдел помогает осуществить:

- Регистрацию проекта у производителя компонентов.
- Техническую поддержку проекта.
- Защиту от снятия компонента с производства.
- Оценку стоимости проекта по компонентам.
- Изготовление тестовой платы монтаж и пусконаладочные работы.



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