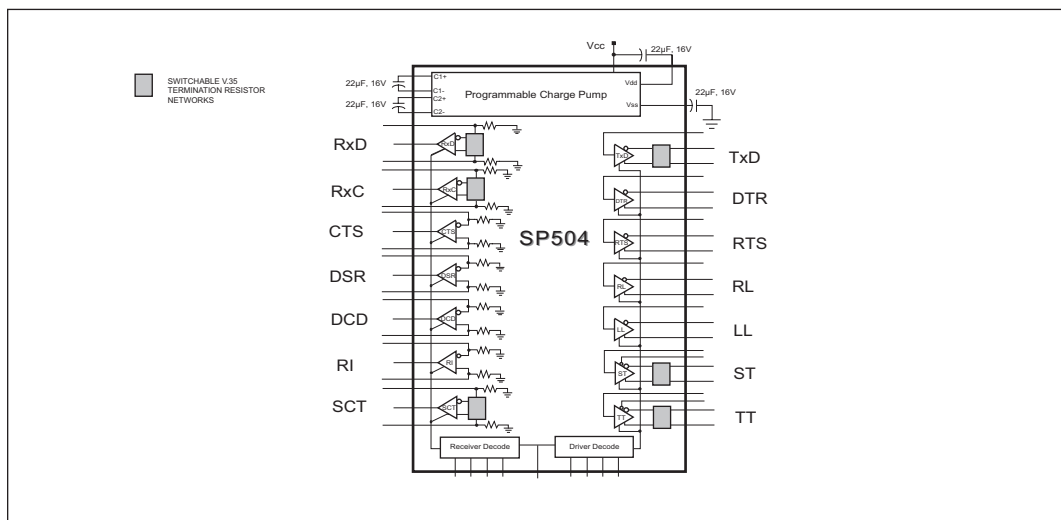




WAN Multi-Mode Serial Transceiver

-
- Pinout diagram of the SP504 module. The module is a square component with pins on all four sides. The top edge has 16 pins, the bottom edge has 16 pins, the left edge has 16 pins, and the right edge has 16 pins. The pins are numbered 1 to 64. The top edge pins are: 36 CTS, 79 SCL, 78 DSR, 77 SCL(B), 76 SCL(A), 75 GND, 74 V_{cc}, 73 V_{cc}, 72 GND, 71 RD(B), 70 RD(A), 69 DM(B), 68 DM(A), 67 CS(B), 66 CS(A), 65 TTB, 64 GND, 63 TTB, 62 V_{cc}, 61 SD(B). The bottom edge pins are: RI 21, ST 22, RTN 23, LL 24, V_{cc} 25, V_{cc} 26, V_{cc} 27, V_{cc} 28, GND 29, C₊ 30, C₊ 31, C₊ 32, C₊ 33, GND 34, GND 35, GND 36, GND 37, GND 38, GND 39, GND 40. The left edge pins are: RxD 1, RDEC 2, RDEC 3, RDEC 4, RDEC 5, TTB 6, SCTN 7, N/C 8, TDEC 9, TDEC 10, TDEC 11, TDEC 12, DTR 13, TXD 14, TXC 15, RTS 16, RL 17, V35_STAT 18, DCD 19, RxC 20. The right edge pins are: 60 GND, 59 SD(B), 58 TR(A), 57 GND, 56 TR(B), 55 V_{cc}, 54 RS(A), 53 GND, 52 RS(B), 51 LL(A), 50 GND, 49 LL(B), 48 V_{cc}, 47 RL(A), 46 GND, 45 RL(B), 44 ST(B), 43 GND, 42 ST(A), 41 V_{cc}.

The **SP504** is a single chip device that supports eight (8) physical serial interface standards for Wide Area Network connectivity. The **SP504** is fabricated using a low power BiCMOS process technology, and incorporates an **Exar** patented (5,306,954) charge pump allowing +5V only operation. Seven (7) drivers and seven (7) receivers can be configured via software for any of the above interface modes at any time. The **SP504** is suitable for DTE-DCE applications. The **SP504** requires only one external resistor per V.35 driver for compliant V.35 Operation.



ABSOLUTE MAXIMUM RATINGS

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V_{CC}+7V

Input Voltages:

Logic.....-0.3V to ($V_{CC}+0.5V$)

Drivers.....-0.3V to ($V_{CC}+0.5V$)

Receivers.....±15V

Output Voltages:

Logic.....-0.3V to ($V_{CC}+0.5V$)

Drivers.....±14V

Receivers.....-0.3V to ($V_{CC}+0.5V$)

Storage Temperature.....-65°C to +150°C

Power Dissipation.....2000mW

Package Derating:

θ_{JA}46 °C/W

θ_{JC}16 °C/W

STORAGE CONSIDERATIONS

Due to the relatively large package size of the 80-pin quad flat-pack, storage in a low humidity environment is preferred. Large high density plastic packages are moisture sensitive and should be stored in Dry Vapor Barrier Bags. Prior to usage, the parts should remain bagged and stored below 40°C and 60%RH. If the parts are removed from the bag, they should be used within 48 hours or stored in an environment at or below 20%RH. If the above conditions cannot be followed, the parts should be baked for four hours at 125°C in order remove moisture prior to soldering. Exar ships the 80-pin QFP in Dry Vapor Barrier Bags with a humidity indicator card and desiccant pack. The humidity indicator should be below 30%RH.

SPECIFICATIONS

T_A = +25°C and V_{CC} = +5.0V unless otherwise noted.

| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|-----------------------------|--------|--------|--------|-------|---|
| Logic Inputs | | | | | |
| V_{IL} | | | 0.8 | Volts | |
| V_{IH} | 2.0 | | | Volts | |
| LOGIC OUTPUTS | | | | | |
| V_{OL} | | | 0.4 | Volts | $I_{OUT} = +3.2mA$ |
| V_{OH} | 2.4 | | | Volts | $I_{OUT} = -1.0mA$ |
| RS-485 DRIVER | | | | | |
| TTL Input Levels | | | | | |
| V_{IL} | | | 0.8 | Volts | |
| V_{IH} | 2.0 | | | Volts | |
| Outputs | | | | | |
| HIGH Level Output | | | +6.0 | Volts | |
| LOW Level Output | -0.3 | | | Volts | |
| Differential Output | +/-1.5 | | +/-5.0 | Volts | $R_L = 54\Omega$, $C_L = 50pF$ |
| Balance | | +/-0.2 | | Volts | $ V_{T1} - \overline{V}_{T1} $ |
| Offset | | +2.5 | | Volts | |
| Open Circuit Voltage | | | +/-6.0 | Volts | |
| Output Current | 28.0 | | | mA | $R_L = 54\Omega$ |
| Short-Circuit Current | | +/-250 | | mA | Terminated in -7V to +10V |
| Transition Time | | 20 | 40 | ns | Rise/Fall time, 10% to 90% |
| Max. Transmission Rate | 10 | | | Mbps | $R_L = 54\Omega$; Figure 3a |
| Propagation Delay t_{PHL} | 50 | 80 | 100 | ns | T_A @ 25°C and $V_{CC} = +5V$ only Fig-ures 3a and 5; $R_L = 54\Omega$, $C_L = 50pF$ |

SPECIFICATIONS

T_A = +25°C and V_{CC} = +5.0V unless otherwise noted.

| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|------------------------------------|---|------|---------|-------|--|
| RS-485 DRIVER (continued) | | | | | |
| Propagation Delay t _{PLH} | 50 | 80 | 100 | ns | T _A @ 25°C and V _{CC} = +5V only Figures 3a and 5; R _L = 54Ω, C _L = 50pF |
| Differential Driver Skew | | 20 | 40 | ns | t _{PHL} - t _{PLH} ; T _A @ 25°C |
| RS-485 RECEIVER | | | | | |
| TTL Output Levels | | | | | |
| V _{OL} | | | 0.4 | Volts | |
| V _{OH} | 2.4 | | | Volts | |
| Input | | | | | |
| HIGH Threshold | +0.2 | | +12 | Volts | (a)-(b) |
| LOW Threshold | -7.0 | | -0.2 | Volts | (a)-(b) |
| Common Mode Range | -7.0 | | +12 | Volts | |
| HIGH Input Current | | | | | Refer to Receiver input graph |
| LOW Input Current | | | | | Refer to Receiver input graph |
| Receiver Sensitivity | | | +/-0.2 | Volts | Over -7V to +12V common mode Range |
| Input Impedance | 12 | | | kΩ | |
| Max. Transmission Rate | 10 | | | Mbps | Figure 3a |
| Propagation Delay t _{PHL} | 80 | 110 | 180 | ns | T _A @ 25°C and V _{CC} = +5V only. Figures 3a and 7; A is inverting and B is non-inverting. |
| Propagation Delay t _{PLH} | 80 | 110 | 180 | ns | |
| Differential Receiver Skew | | 30 | | ns | t _{PHL} - t _{PLH} ; T _A @ +25°C |
| V.35 DRIVER | | | | | |
| TTL Input Levels | | | | | |
| V _{IL} | | | 0.8 | Volts | |
| V _{IH} | 2.0 | | | Volts | |
| Outputs | All Outputs measured with 150Ω termination resistor connected to the non-inverting outputs as shown in Figure 19. | | | | |
| Differential Output | +/-0.44 | | +/-0.66 | Volts | R _L = 100Ω |
| Source Impedance | 50 | 100 | 150 | Ω | |
| Short-Circuit Impedance | 135 | 150 | 165 | Ω | V _{OUT} = -2V to +2V; A = B |
| Voltage Output Offset | -0.6 | | +0.6 | Volts | |
| Transition Time | | 35 | 60 | ns | 48kbps data rate; T _A @ 25°C |
| Max. Transmission Rate | 10 | | | Mbps | R _L = 100Ω |
| Propagation Delay t _{PHL} | 50 | 80 | 100 | ns | T _A @ 25°C and V _{CC} = +5V only Figures 3b and 5 |
| Propagation Delay t _{PLH} | 50 | 80 | 100 | ns | |
| Differential Driver Skew | | 30 | 40 | ns | t _{PHL} - t _{PLH} ; T _A @ +25°C |
| V.35 RECEIVER | | | | | |
| TTL Output Levels | | | | | |
| V _{OL} | | | 0.4 | Volts | |
| V _{OH} | 2.4 | | | Volts | |

SPECIFICATIONS

T_A = +25°C and V_{CC} = +5.0V unless otherwise noted.

| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|--------------------------------------|-------------------|-------|--------------------|-------|--|
| V.35 RECEIVER (continued) | | | | | |
| Input | | | | | |
| Differential Threshold | | +/-80 | | mV | |
| Input Impedance | 90 | 100 | 110 | Ω | |
| Short-Circuit Impedance | 135 | 150 | 165 | Ω | V _{IN} = +2V to -2V |
| Max. Transmission Rate | 10 | | | Mbps | |
| Propagation Delay t _{PHL} | 100 | 130 | 200 | ns | T _A @ 25°C and V _{CC} = +5V only Figures 3b and 7; A is inverting and B is non-inverting. |
| Propagation Delay t _{PLH} | 100 | 130 | 200 | ns | |
| Differential Receiver Skew | | 30 | | ns | t _{PHL} - t _{PLH} ; T _A @ 25°C |
| RS-422 DRIVER (V.11) | | | | | |
| TTL Input Levels | | | | | |
| V _{IL} | | | 0.8 | Volts | |
| V _{IH} | 2.0 | | | Volts | |
| Outputs | | | | | |
| Open circuit Voltage, V _O | | | +/-6.0 | Volts | R _L = 3.9kΩ |
| Differential Output, V _T | +/-2.0 | | +/-5.0 | Volts | R _L = 100Ω |
| | 0.5V _O | | 0.67V _O | Volts | T _A @ 25°C |
| Balance | | | +/-0.4 | Volts | V _T - V _T |
| Offset | | | +3.0 | Volts | |
| Short Circuit Current | | | +/-150 | mA | V _{OUT} = 0V |
| Power Off Current | | | +/-100 | μA | V _{CC} = 0V, V _{OUT} = +/-0.25V |
| Transition Time | | 20 | 40 | ns | Rise/Fall time, 10% - 90% |
| Max. Transmission Rate | 10 | | | Mbps | R _L = 100Ω; Figure 3a |
| Propagation Delay t _{PHL} | 50 | 80 | 100 | ns | T _A @ 25°C and V _{CC} = +5V only Figures 3a and 5; R _{DIFF} = 100Ω |
| Propagation Delay t _{PLH} | 50 | 80 | 100 | ns | |
| Differential Skew | | 20 | 40 | ns | t _{PHL} - t _{PLH} ; T _A @ 25°C |
| RS-422 RECEIVER (V.11) | | | | | |
| TTL Output Levels | | | | | |
| V _{OL} | | | 0.4 | Volts | |
| V _{OH} | 2.4 | | | Volts | |
| Input | | | | | |
| HIGH Threshold | +0.2 | | +6.0 | Volts | (a)-(b) |
| LOW Threshold | -6.0 | | -0.2 | Volts | (a)-(b) |
| Common Mode Range | -7.0 | | +7 | Volts | |
| HIGH Input Current | | | | | Refer to Receiver input graph |
| LOW Input Current | | | | | Refer to Receiver input graph |
| Receiver Sensitivity | | | +/-0.3 | Volts | V _{CM} = +7V to -7V |
| Input Impedance | 4 | | | kΩ | V _{IN} = +10V to -10V |
| Max. Transmission Rate | 10 | | | Mbps | |

SPECIFICATIONS

T_A = +25°C and V_{CC} = +5.0V unless otherwise noted.

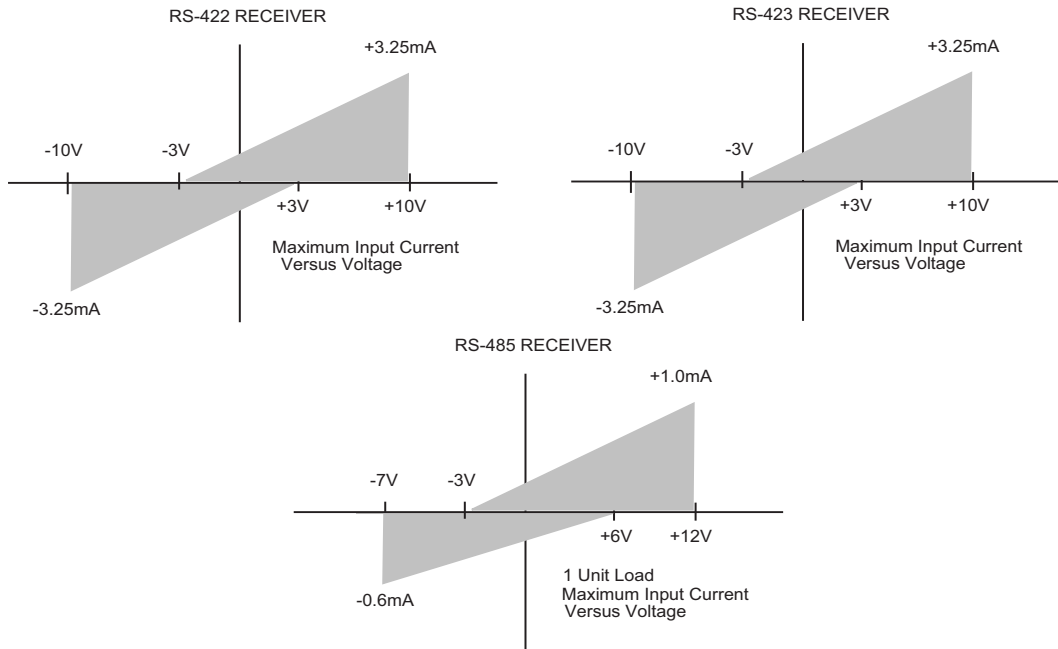
| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|------------------------------------|--------|-------|--------|------------|---|
| RS-422 RECEIVER (V.11) (continued) | | | | | |
| Propagation Delay t_{PHL} | 80 | 110 | 180 | ns | T_A @ 25°C and V_{CC} = +5V only. Figures 3b and 7; A is inverting and B is non-inverting. |
| Propagation Delay t_{PLH} | 80 | 110 | 180 | ns | |
| Differential Receiver Skew | | 30 | | ns | $ t_{PHL} - t_{PLH} $; T_A @ 25°C |
| RS-232 DRIVER (V.28) | | | | | |
| TTL Input Levels | | | | | |
| V_{IL} | | | 0.8 | Volts | |
| V_{IH} | 2.0 | | | Volts | |
| Outputs | | | | | |
| HIGH Level Output | +5.0 | | +15.0 | Volts | $R_L = 3k\Omega$, $V_{IN} = 0.8V$ |
| LOW Level Output | -15.0 | | -5.0 | Volts | $R_L = 3k\Omega$, $V_{IN} = 2.0V$ |
| Open Circuit Voltage | -15 | | +15 | Volts | |
| Short Circuit Current | | | +/-100 | mA | $V_{OUT} = 0V$ |
| Power Off Impedance | 300 | | | Ω | $V_{CC} = 0V$, $V_{OUT} = +/-2.0V$ |
| Slew Rate | | | 30 | V/ μ s | $R_L = 3k\Omega$, $C_L = 50pF$; $V_{CC} = +5.0V$, T_A @ 25°C |
| Transistion Time | | | 1.56 | μ s | $R_L = 3K\Omega$, $C_L = 2500pF$; between +/-3V, T_A @ +25°C |
| Max. Transmission Rate | 120 | 230.4 | | kbps | $R_L = 3k\Omega$, $C_L = 2500pF$ |
| Propagation Delay t_{PHL} | 0.5 | 1 | 4 | μ s | T_A @ 25°C and V_{CC} = +5V only. Measured from 1.5V of V_{IN} to 50% of V_{OUT} ; $R_L = 3k\Omega$ |
| Propagation Delay t_{PLH} | 0.5 | 1 | 4 | μ s | |
| RS-232 RECEIVER (V.28) | | | | | |
| TTL Output Levels | | | | | |
| V_{OL} | | | 0.4 | Volts | |
| V_{OH} | 2.4 | | | Volts | |
| Input | | | | | |
| HIGH Threshold | | 1.7 | 3.0 | Volts | |
| LOW Threshold | 0.8 | 1.2 | | Volts | |
| Reciever Open Circuit Bias | | | +2.0 | Volts | |
| Input Impedance | 3 | 5 | 7 | k Ω | $V_{IN} = +15V$ to -15V |
| Max. Transmission Rate | 120 | 230.4 | | kbps | |
| Propagation Delay t_{PHL} | 0.05 | 0.25 | 1 | μ s | T_A @ 25°C and V_{CC} = +5V only. Measured from 50% of V_{IN} to 1.5V of V_{OUT} |
| Propagation Delay t_{PLH} | 0.05 | 0.25 | 1 | μ s | |
| RS-423 DRIVER (V.10) | | | | | |
| TTL Input Levels | | | | | |
| V_{IL} | | | 0.8 | Volts | |
| V_{IH} | 2.0 | | | Volts | |
| Outputs | | | | | |
| Open Circuit Voltage, V_o | +/-4.0 | | +/-6.0 | Volts | $R_L = 3.9k\Omega$ |

SPECIFICATIONS

$T_A = +25^{\circ}\text{C}$ and $V_{CC} = +5.0\text{V}$ unless otherwise noted.

| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|----------------------------------|-------------|------|--------|--------------------|--|
| RS-423 DRIVER (V.10) (continued) | | | | | |
| HIGH Level Output, V_T | +3.6 | | +6.0 | Volts | $R_L = 450\Omega$; $V_{OUT} \geq 0.9V_{OC}$ |
| LOW Level Output, V_T | -6.0 | | -3.6 | Volts | $R_L = 450\Omega$; $V_{OUT} \geq 0.9V_{OC}$ |
| | $0.9V_{OC}$ | | | Volts | $T_A = +25^{\circ}\text{C}$, $V_{CC} = +5.0\text{V}$ |
| Short Circuit Current | | | +/-150 | mA | $V_{OUT} = 0\text{V}$, $V_{CC} = +5.0\text{V}$ |
| Power Off Current | | | +/-100 | μA | $V_{CC} = 0\text{V}$, $V_{OUT} = +/-0.25\text{V}$ |
| Transition Time | | | 100 | ns | Rise/Fall time, between +/-3V |
| Max. Transmission Rate | 120 | | | kbps | $R_L = 450\Omega$ |
| Propagation Delay t_{PHL} | 0.05 | 0.5 | 2 | μs | $T_A @ 25^{\circ}\text{C}$ and $V_{CC} = +5\text{V}$ only. Measured from 1.5V of V_{IN} to 50% of V_{OUT} ; $R_L = 450\Omega$ |
| Propagation Delay t_{PLH} | 0.05 | 0.5 | 2 | μs | |
| RS-423 RECEIVER (V.10) | | | | | |
| TTL Output Levels | | | | | |
| V_{OL} | | | 0.4 | Volts | |
| V_{OH} | 2.4 | | | Volts | |
| Input | | | | | |
| HIGH Threshold | +0.3 | | +7.0 | Volts | |
| LOW Threshold | -7.0 | | -0.3 | Volts | |
| HIGH Input Current | | | | | Refer to Receiver input graph |
| LOW Input Current | | | | | Refer to Receiver input graph |
| Receiver Sensitivity | | | +/-0.3 | Volts | $V_{CM} = +7\text{V}$ to -7V |
| Input Impedance | 4 | | | k Ω | $V_{IN} = +10\text{V}$ to -10V |
| Max. Transmission Rate | 120 | | | kbps | |
| Propagation Delay t_{PHL} | 0.05 | 0.2 | 1 | μs | $T_A @ 25^{\circ}\text{C}$ and $V_{CC} = +5\text{V}$ only Measured from 50% of V_{IN} to 1.5V of V_{OUT} |
| Propagation Delay t_{PLH} | 0.05 | 0.2 | 1 | μs | |
| POWER REQUIREMENTS | | | | | |
| V_{CC} | 4.75 | 5.00 | 5.25 | Volts | |
| I_{CC} (No Mode Selected) | | 30 | | mA | All I_{CC} values are with $V_{CC} = +5\text{V}$ |
| I_{CC} (RS-232 Mode) | | 140 | | mA | $f_{IN} = 120\text{kbps}$; Drivers loaded |
| I_{CC} (RS-422 Mode) | | 320 | | mA | $f_{IN} = 2\text{Mbps}$; Drivers loaded |
| I_{CC} (RS-449 Mode) | | 320 | | mA | $f_{IN} = 2\text{Mbps}$; Drivers loaded |
| I_{CC} (EIA-530 Mode) | | 320 | | mA | $f_{IN} = 2\text{Mbps}$ Drivers loaded |
| I_{CC} (EIA-530A Mode) | | 320 | | mA | $f_{IN} = 2\text{Mbps}$ Drivers loaded |
| I_{CC} (RS-485 Mode) | | 370 | | mA | $f_{IN} = 2\text{Mbps}$ Drivers loaded |
| I_{CC} (V.35 Mode) | | 210 | | mA | $f_{IN} = 2\text{Mbps}$ Drivers loaded |
| I_{CC} (V.36 Mode) | | 310 | | mA | $f_{IN} = 2\text{Mbps}$ Drivers loaded |
| ENVIRONMENTAL AND MECHANICAL | | | | | |
| Operating Temperature Range | 0 | | +70 | $^{\circ}\text{C}$ | |
| Storage Temperature Range | -65 | | +150 | $^{\circ}\text{C}$ | |
| ESD | | 500 | | V | HBM |

RECEIVER INPUT GRAPHS



OTHER AC CHARACTERISTICS

$T_A = +70^{\circ}\text{C}$ to 0°C and $V_{CC} = +4.75\text{V}$ to $+5.25\text{V}$ unless otherwise noted.

| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|---|------|------|------|---------------|---|
| DRIVER DELAY TIME BETWEEN ACTIVE MODE AND TRI-STATE MODE | | | | | |
| RS-232 Mode | | | | | |
| t_{PZL} : Tri-state to Output LOW | | 0.70 | 5.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_1 closed |
| t_{PZH} : Tri-state to Output HIGH | | 0.40 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_2 closed |
| t_{PLZ} : Output LOW to Tri-state | | 0.20 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_1 closed |
| t_{PHZ} : Output HIGH to Tri-state | | 0.40 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_2 closed |
| RS-423 MODE | | | | | |
| t_{PZL} : Tri-state to Output LOW | | 0.15 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_1 closed |
| t_{PZH} : Tri-state to Output HIGH | | 0.20 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_2 closed |
| t_{PLZ} : Output LOW to Tri-state | | 0.20 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_1 closed |
| t_{PHZ} : Output HIGH to Tri-state | | 0.15 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 ; S_2 closed |
| RS-422, RS-485 MODES | | | | | |
| t_{PZL} : Tri-state to Output LOW | | 2.80 | 10.0 | μs | $C_L = 100\text{pF}$, Fig. 4 & 6; S_1 closed |
| t_{PZH} : Tri-state to Output HIGH | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 & 6; S_2 closed |
| t_{PLZ} : Output LOW to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 4 & 6; S_1 closed |
| t_{PHZ} : Output HIGH to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 4 & 6; S_2 closed |
| V.35 MODE | | | | | |
| t_{PZL} : Tri-state to Output LOW | | 2.60 | 10.0 | μs | $C_L = 100\text{pF}$, Fig. 4 & 6; S_1 closed |
| t_{PZH} : Tri-state to Output HIGH | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 4 & 6; S_2 closed |
| t_{PLZ} : Output LOW to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 4 & 6; S_1 closed |
| t_{PHZ} : Output HIGH to Tri-state | | 0.15 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 4 & 6; S_2 closed |

OTHER AC CHARACTERISTICS

$T_A = +70^{\circ}\text{C}$ to 0°C and $V_{CC} = +4.75\text{V}$ to $+5.25\text{V}$ unless otherwise noted.

| PARAMETER | MIN. | TYP. | MAX. | UNITS | CONDITIONS |
|---|------|------|------|---------------|--|
| RECEIVER DELAY TIME BETWEEN ACTIVE MODE AND TRI-STATE MODE | | | | | |
| RS-232 Mode | | | | | |
| t_{PZL} ; Tri-state to Output LOW | | 0.12 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_1 closed |
| t_{PZH} ; Tri-state to Output HIGH | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_2 closed |
| t_{PLZ} ; Output LOW to Tri-state | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_1 closed |
| t_{PHZ} ; Output HIGH to Tri-state | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_2 closed |
| RS-423 MODE | | | | | |
| t_{PZL} ; Tri-state to Output LOW | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_1 closed |
| t_{PZH} ; Tri-state to Output HIGH | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_2 closed |
| t_{PLZ} ; Output LOW to Tri-state | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_1 closed |
| t_{PHZ} ; Output HIGH to Tri-state | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 ; S_2 closed |
| RS-422, RS-485 MODES | | | | | |
| t_{PZL} ; Tri-state to Output LOW | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 & 8; S_1 closed |
| t_{PZH} ; Tri-state to Output HIGH | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 & 8; S_2 closed |
| t_{PLZ} ; Output LOW to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 2 & 8; S_1 closed |
| t_{PHZ} ; Output HIGH to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 2 & 8; S_2 closed |
| V.35 MODE | | | | | |
| t_{PZL} ; Tri-state to Output LOW | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 & 8; S_1 closed |
| t_{PZH} ; Tri-state to Output HIGH | | 0.10 | 2.0 | μs | $C_L = 100\text{pF}$, Fig. 2 & 8; S_2 closed |
| t_{PLZ} ; Output LOW to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 2 & 8; S_1 closed |
| t_{PHZ} ; Output HIGH to Tri-state | | 0.10 | 2.0 | μs | $C_L = 15\text{pF}$, Fig. 2 & 8; S_2 closed |
| TRANSCEIVER TO TRANSCEIVER SKEW $[(t_{PHL} - t_{PLH})_{TRCV1} - (t_{PHL} - t_{PLH})_{TRCVRX}]$ | | | | | |
| RS-232 Driver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| RS-232 Receiver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| RS-422 Driver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| RS-422 Receiver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| RS-423 Driver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| RS-423 Receiver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| V.35 Driver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |
| V.35 Receiver | | 20 | 50 | ns | $V_{CC} = +5.0\text{V}$, $T_A @ 25^{\circ}\text{C}$ |

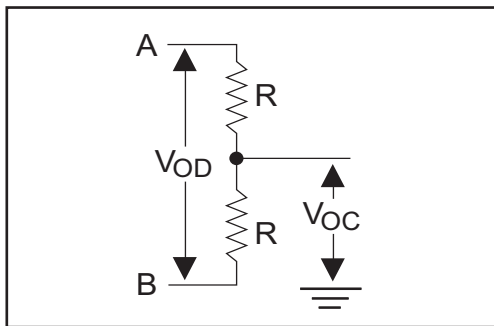


Figure 1. Driver DC Test Load Circuit

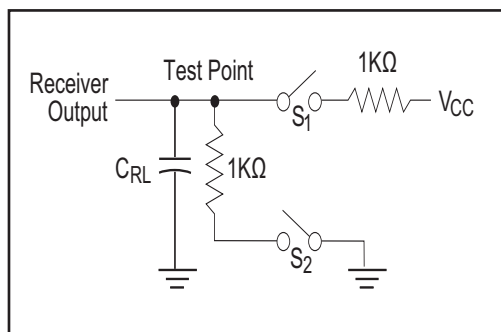


Figure 2. Receiver Timing Test Load Circuit

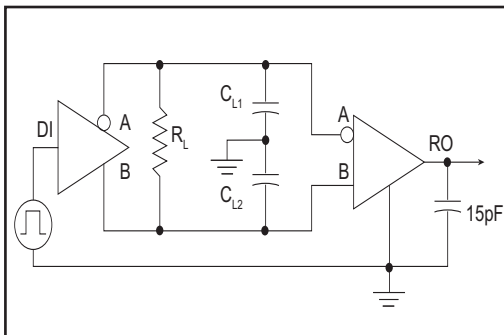


Figure 3a. Driver / Receiver Timing Test Circuit

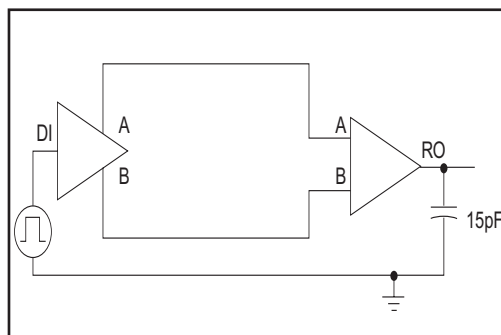


Figure 3b. Timing Test Circuit (V.35 Mode only)

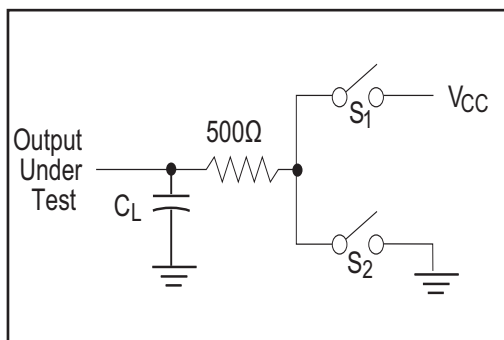


Figure 4. Driver Timing Test Load #2 Circuit

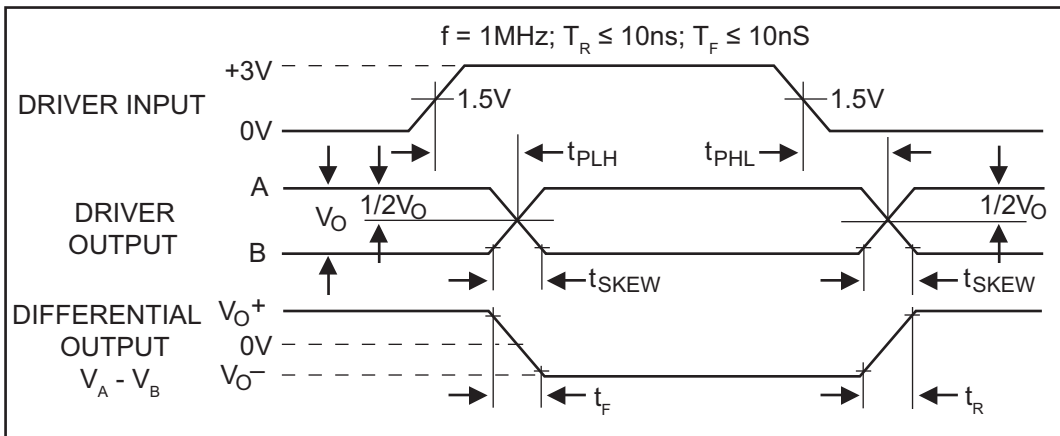


Figure 5. Driver Propagation Delays

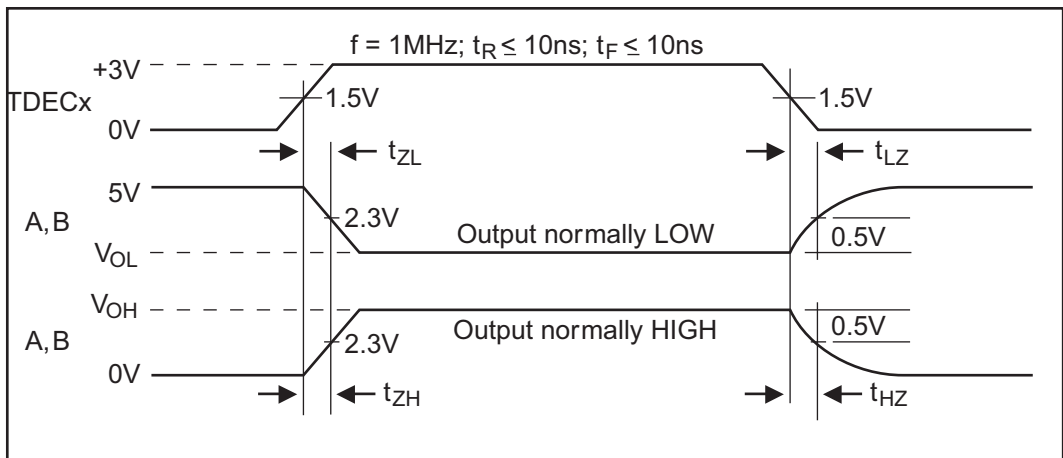


Figure 6. Driver Enable and Disable Times

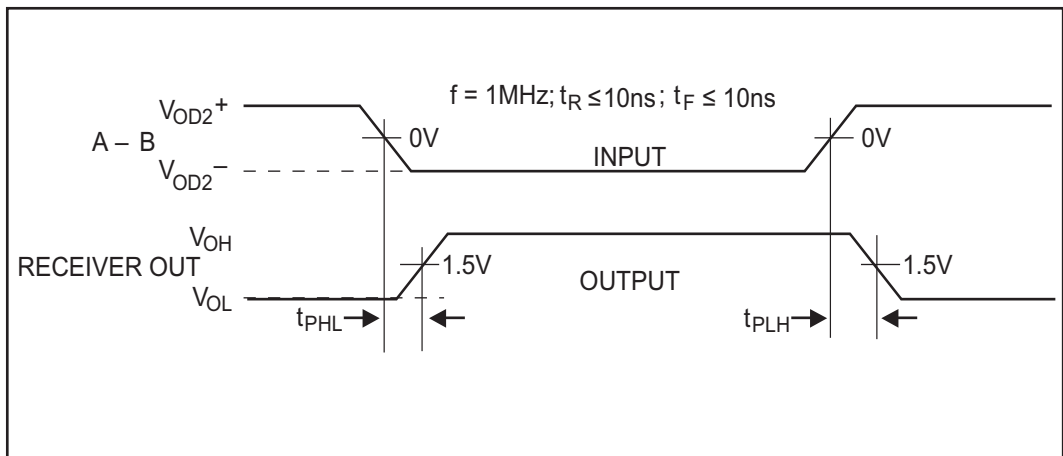


Figure 7. Receiver Propagation Delays

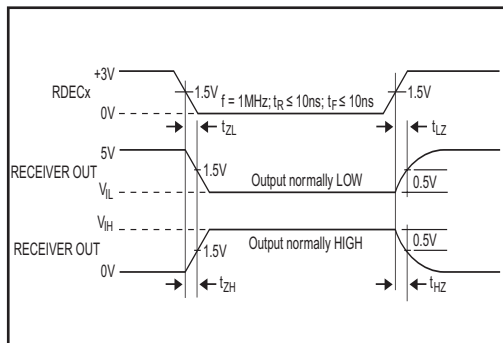


Figure 8. Receiver Enable and Disable Times

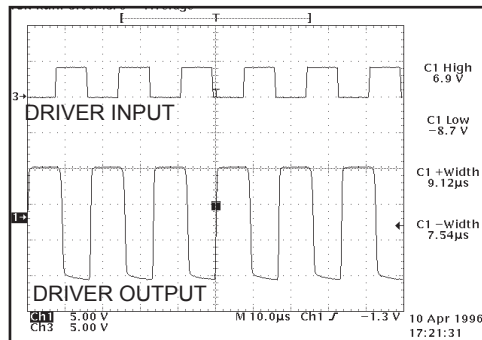


Figure 9. Typical RS-232 Driver Output Waveform

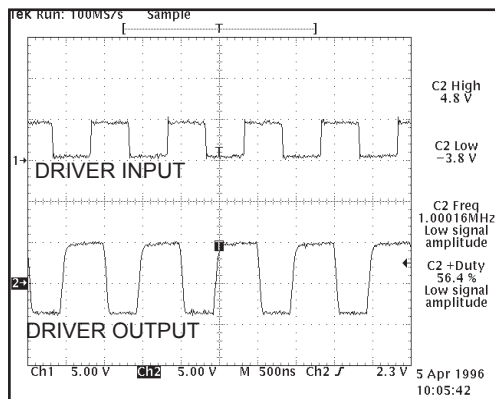


Figure 10. Typical RS-423 Driver Output Waveform

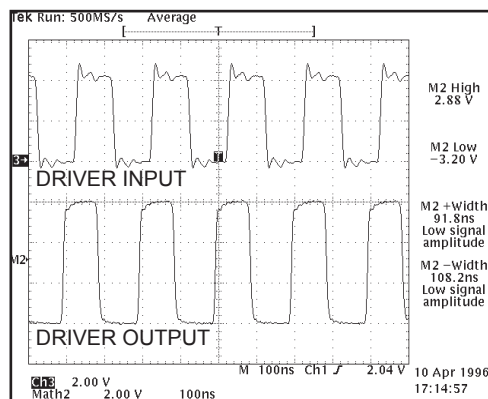


Figure 11. Typical RS-422/RS-485 Driver Output Waveform

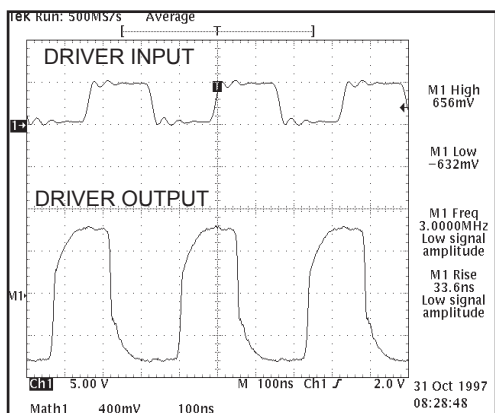


Figure 12. Typical V.35 Driver Output Waveform

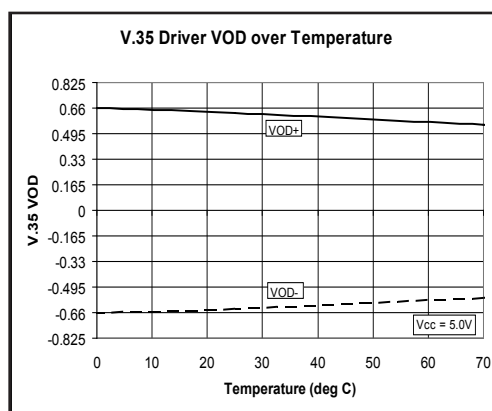
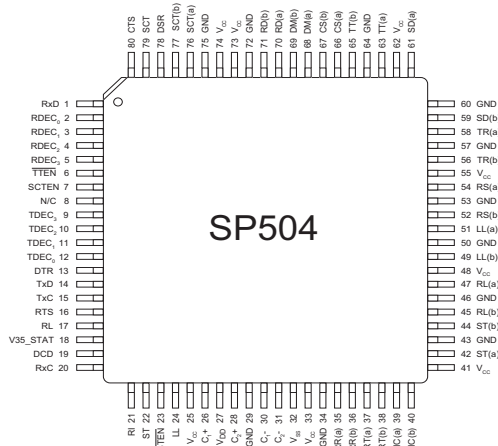


Figure 13. V.35 Driver Output VOD VS. Temperature

PINOUT...



PIN ASSIGNMENTS...

CLOCK AND DATA GROUP

Pin 1 — RxD — Receive Data; TTL output, sourced from RD(a) and RD(b) inputs.

Pin 14 — TxD — TTL input ; transmit data source for SD(a) and SD(b) outputs.

Pin 15 — TxC — Transmit Clock; TTL input for TT driver outputs.

Pin 20 — RxC — Receive Clock; TTL output sourced from RT(a) and RT(b) inputs.

Pin 22 — ST — Send Timing; TTL input; source for ST(a) and ST(b) outputs.

Pin 37 — RT(a) — Receive Timing; analog input, inverted; source for RxC.

Pin 38 — RT(b) — Receive Timing; analog input, non-inverted; source for RxC.

Pin 42 — ST(a) — Send Timing; analog output, inverted; sourced from ST.

Pin 44 — ST(b) — Send Timing; analog output, non-inverted; sourced from ST.

Pin 59 — SD(b) — Analog Out — Send data, non-inverted; sourced from TxD.

Pin 61 — SD(a) — Analog Out — Send data, inverted; sourced from TxD.

Pin 63 — TT(a) — Analog Out — Terminal Timing, inverted; sourced from TxC

Pin 65 — TT(b) — Analog Out — Terminal Timing, non-inverted; sourced from TxC.

Pin 70 — RD(a) — Receive Data, analog input; inverted; source for RxD.

Pin 71 — RD(b) — Receive Data; analog input; non-inverted; source for RxD.

Pin 76 — SCT(a) — Serial Clock Transmit; analog input, inverted; source for SCT.

Pin 77 — SCT(b) — Serial Clock Transmit; analog input, non-inverted; source for SCT

Pin 79 — SCT — Serial Clock Transmit; TTL output; sources from SCT(a) and SCT(b) inputs.

CONTROL LINE GROUP

Pin 13 — DTR — Data Terminal Ready; TTL input; source for TR(a) and TR(b) outputs.

Pin 16 — RTS — Ready To Send; TTL input; source for RS(a) and RS(b) outputs.

Pin 17 — RL — Remote Loopback; TTL input; source for RL(a) and RL(b) outputs.

Pin 18 — V35_STAT — V.35 Status; TTL output; outputs logic high when in V.35 mode.

Pin 19 — DCD — Data Carrier Detect; TTL output; sourced from RR(a) and RR(b) inputs.

Pin 21 — RI — Ring Indicate; TTL output; sourced from IC(a) and IC(b) inputs.

Pin 24 — LL — Local Loopback; TTL input; source for LL(a) and LL(b) outputs.

Pin 35 — RR(a) — Receiver Ready; analog input, inverted; source for DCD.

Pin 36 — RR(b) — Receiver Ready; analog input, non-inverted; source for DCD.

Pin 39 — IC(a) — Incoming Call; analog input, inverted; source for RI.

Pin 40 — IC(b)— Incoming Call; analog input, non-inverted; source for RI.

Pin 45 — RL(b) — Remote Loopback; analog output, non-inverted; sourced from RL.

Pin 47 — RL(a) — Remote Loopback; analog output inverted; sourced from RL.

Pin 49 — LL(b) — Local Loopback; analog output, non-inverted; sourced from LL.

Pin 51 — LL(a) — Local Loopback; analog output, inverted; sourced from LL.

Pin 52 — RS(b) — Ready To Send; analog output, non-inverted; sourced from RTS.

Pin 54 — RS(a) — Ready To Send; analog output, inverted; sourced from RTS.

Pin 56 — TR(b) — Terminal Ready; analog output, non-inverted; sourced from DTR.

Pin 58 — TR(a) — Terminal Ready; analog output, inverted; sourced from DTR.

Pin 66 — CS(a)— Clear To Send; analog input, inverted; source for CTS.

Pin 67 — CS(b)— Clear To Send; analog input, non-inverted; source for CTS.

Pin 68 — DM(a)— Data Mode; analog input, inverted; source for DSR.

Pin 69 — DM(b)— Data Mode; analog input, non-inverted; source for DSR

Pin 78 — DSR — Data Set Ready; TTL output; sourced from DM(a), DM(b) inputs.

Pin 80 — CTS — Clear To Send; TTL output; sourced from CS(a) and CS(b) inputs.

CONTROL REGISTERS

Pins 2–5 — RDEC₀ – RDEC₃ — Receiver decode register; configures receiver modes; TTL inputs.

Pin 6 — $\overline{\text{TTEN}}$ — Enables TT driver, active low; TTL input.

Pin 7 — SCTEN — Enables SCT receiver; active high; TTL input.

Pins 12–9 — TDEC₀ – TDEC₃ — Transmitter decode register; configures transmitter modes; TTL inputs.

Pin 23 — $\overline{\text{STEN}}$ — Enables ST driver; active low; TTL input.

POWER SUPPLIES

Pins 25, 33, 41, 48, 55, 62, 73, 74 — V_{CC} — +5V input.

Pins 29, 34, 43, 46, 50, 53, 57, 60, 64, 72, 75 — GND — Ground.

Pin 27 — V_{DD} +10V Charge Pump Capacitor — Connects from V_{DD} to V_{CC}. Suggested capacitor size is 22μF, 16V.

Pin 32 — V_{SS} –10V Charge Pump Capacitor — Connects from ground to V_{SS}. Suggested capacitor size is 22μF, 16V.

Pins 26 and 30 — C₁⁺ and C₁[–] — Charge Pump Capacitor — Connects from C₁⁺ to C₁[–]. Suggested capacitor size is 22μF, 16V.

Pins 28 and 31 — C₂⁺ and C₂[–] — Charge Pump Capacitor — Connects from C₂⁺ to C₂[–]. Suggested capacitor size is 22μF, 16V.

NOTE: NC pins should be left floating; internal signals may be present.

FEATURES...

The **SP504** is a highly integrated serial transceiver that allows software control of its interface modes. Similar to the SP503, the **SP504** offers the same hardware interface modes for RS-232 (V.28), RS-422A (V.11), RS-449, RS-485, V.35, EIA-530 and includes V.36 and EIA-530A. The interface mode selection is done via an 8-bit switch; four (4) bits control the drivers and four (4) bits control the receivers. The **SP504** is fabricated using low power BiCMOS process technology, and incorporates a **Exar** patented (5,306,954) charge pump allowing +5V only operation. Each device is packaged in an 80-pin JEDEC Quad FlatPack package.

The **SP504** is ideally suited for wide area network connectivity based on the interface modes offered and the driver and receiver configurations. The **SP504** has seven (7) independent drivers and seven (7) independent receivers. In V.35 mode, the **SP504** includes the necessary components and termination resistors internal within the device for compliant V.35 operation.

THEORY OF OPERATION

The **SP504** is made up of five separate circuit blocks — the charge pump, drivers, receivers, decoder and switching array. Each of these circuit blocks is described in more detail below.

Charge-Pump

The **SP504**'s charge pump design is based on the SP503 where **Exar**'s patented charge pump design (5,306,954) uses a four-phase voltage shifting technique to attain symmetrical $\pm 10V$ power supplies. In addition, the **SP504** charge pump incorporates a "programmable" feature that produces an output of $\pm 10V$ or $\pm 5V$ for V_{SS} and V_{DD} depending on the mode of operation. The charge pump still requires external capacitors to store the charge. Figure 18a shows the waveform found on the positive side of capacitor C2, and Figure 18b shows the negative side of capacitor C2. There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

The **SP504** charge pump is used for RS-232 where the output voltage swing is typically $\pm 10V$ and also used for RS-423. However, RS-423 requires the voltage swing on the driver output be between $\pm 4V$ to $\pm 6V$ during an open circuit (no load). The charge pump would need to be regulated down from $\pm 10V$ to $\pm 5V$. A typical $\pm 10V$ charge pump would require external clamping such as 5V zener diodes on V_{DD} and V_{SS} to ground. The $\pm 5V$ output has symmetrical levels as in the $\pm 10V$ output. The $\pm 5V$ is used in the following modes where RS-423 levels are used: RS-449, EIA-530, EIA-530A and V.36.

Phase 1 ($\pm 10V$)

— V_{SS} charge storage — During this phase of the clock cycle, the positive side of capacitors C_1 and C_2 are initially charged to +5V. The C_1^+ is then switched to ground and the charge on C_1^- is transferred to C_2^- . Since C_2^+ is connected to +5V, the voltage potential across capacitor C_2 is now 10V.

Phase 1 ($\pm 5V$)

— V_{SS} & V_{DD} charge storage and transfer — With the C_1 and C_2 capacitors initially charged to +5V, C_1^+ is then switched to ground and the charge on C_1^- is transferred to the V_{SS} storage capacitor. Simultaneously the C_2^- is switched to ground and the 5V charge on C_2^+ is transferred to the V_{DD} storage capacitor.

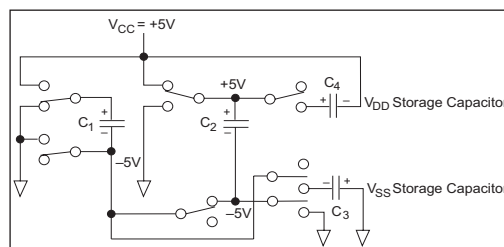


Figure 14a. Charge Pump Phase 1 for $\pm 10V$.

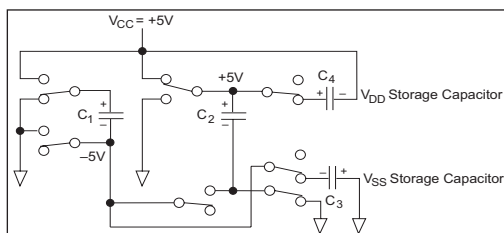


Figure 14b. Charge Pump Phase 1 for $\pm 5V$.

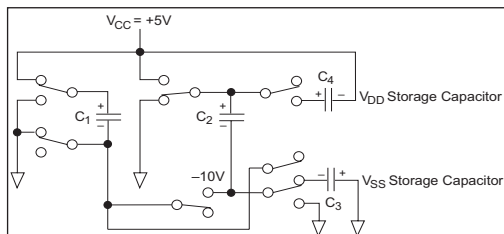


Figure 15a. Charge Pump Phase 2 for $\pm 10V$.

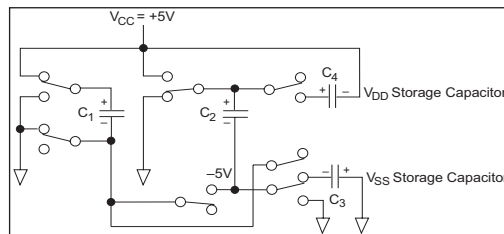


Figure 15b. Charge Pump Phase 2 for $\pm 5V$.

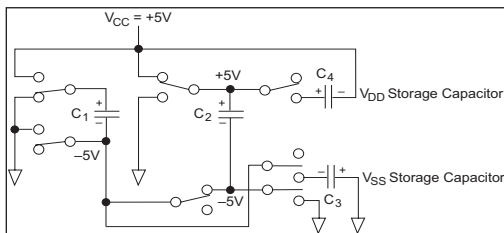


Figure 16. Charge Pump Phase 3.

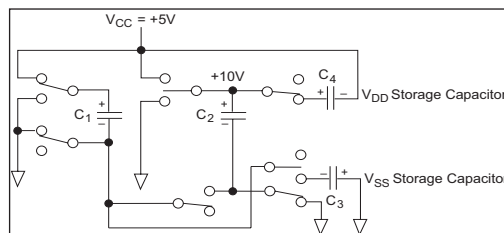


Figure 17. Charge Pump Phase 4.

Phase 2 ($\pm 10V$)

— V_{SS} transfer — Phase two of the clock connects the negative terminal of C_2 to the V_{SS} storage capacitor and the positive terminal of C_2 to ground, and transfers the generated $-10V$ or the generated $-5V$ to C_3 . Simultaneously, the positive side of capacitor C_1 is switched to $+5V$ and the negative side is connected to ground.

Phase 2 ($\pm 5V$)

— V_{SS} & V_{DD} charge storage — C_1^+ is reconnected to V_{CC} to recharge the C_1 capacitor. C_2^+ is switched to ground and C_2^- is connected to C_3 . The $5V$ charge from Phase 1 is now

Phase 3

transferred to the V_{SS} storage capacitor. V_{SS} receives a continuous charge from either C_1 or C_2 . With the C_1 capacitor charged to $5V$, the cycle begins again.

Phase 4

— V_{DD} charge storage — The third phase of the clock is identical to the first phase — the charge transferred in C_1 produces $-5V$ in the negative terminal of C_1 , which is applied to the negative side of capacitor C_2 . Since C_2^+ is at $+5V$, the voltage potential across C_2 is $10V$. For the $5V$ output, C_2^+ is connected to ground so that the potential on C_2 is only $+5V$.

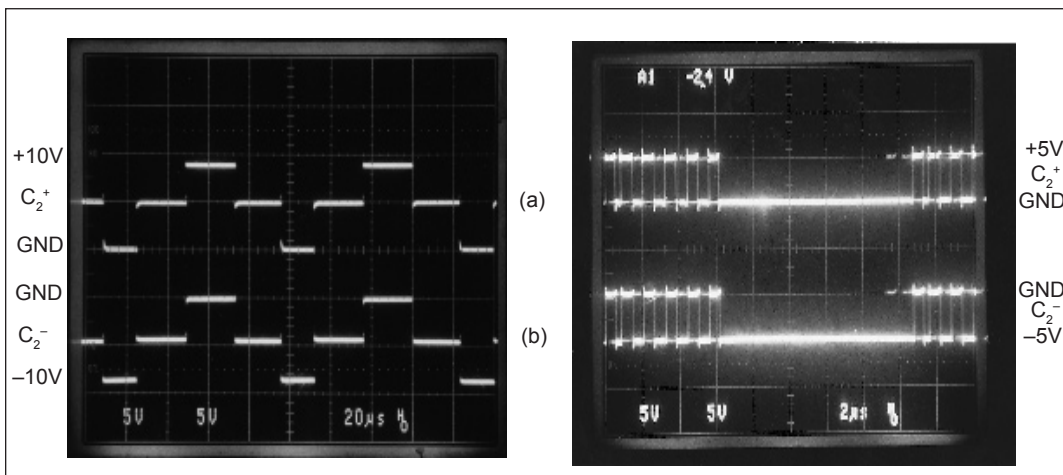


Figure 18a and 18b. Charge Pump Waveforms

Since both V_{DD} and V_{SS} are separately generated from V_{CC} in a no-load condition, V_{DD} and V_{SS} will be symmetrical. Older charge pump approaches that generate V^- from V^+ will show a decrease in the magnitude of V^- compared to V^+ due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors must be a minimum of 22 μ F with a 16V breakdown rating.

External Power Supplies

For applications that do not require +5V only, external supplies can be applied at the V^+ and V^- pins. The value of the external supply voltages must be no greater than $\pm 10.5V$. The tolerance should be $\pm 5\%$ from $\pm 10V$. The current drain for the supplies is used for RS-232 and RS-423 drivers. For the RS-232 driver, the current requirement will be 3.5mA per driver. The RS-423 driver worst case current drain will be 11mA per driver. Power sequencing is required for the **SP504**. The supplies must be sequenced accordingly: +10V, +5V and -10V. An external circuit would be needed for proper power supply sequencing. Consult factory for application circuitry.

Drivers

The **SP504** has seven (7) enhanced independent drivers. Control for the mode selection is done via a four-bit control word. The drivers are pre-arranged such that for each mode of operation, the relative position and functionality of the drivers are set up to accommodate the selected interface mode. As the mode of the drivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line signal levels. Table 1 shows the mode of each driver in the different interface modes that can be selected.

There are four basic types of driver circuits — RS-232, RS-423, RS-485 and V.35.

The RS-232 drivers output single-ended signals with a minimum of $\pm 5V$ (with 3k Ω and 2500pF loading), and can operate up to 120kbps.

The RS-232 drivers are used in RS-232 mode for all signals, and also in V.35 mode where they are used as the control line signals such as DTR and RTS.

The RS-423 drivers are also single-ended signals with a minimum voltage output of $\pm 3.6V$ (with 450 Ω loading) and can operate up to 120kbps. Open circuit V_{OL} and V_{OH} measurements are $\pm 4.0V$ to $\pm 6.0V$. The RS-423 drivers are used in RS-449, EIA-530, EIA-530A and V.36 modes as Category II signals from each of their corresponding specifications.

The third type of driver produces a differential signal that can maintain RS-485, $\pm 1.5V$ differential output levels with a worst case load of 54 Ω . The signal levels and drive capability of the RS-485 drivers allow the drivers to also support RS-422 (V.11) requirements of $\pm 2V$ differential output levels with 100 Ω loads. The RS-422 drivers are used in RS-449, EIA-530, EIA-530A and V.36 modes as Category I signals which are used for clock and data.

The fourth type of driver is the V.35 driver. V.35 levels require $\pm 0.55V$ driver output signals with a load of 100 Ω . The **SP504** drivers simplify existing V.35 implementations that use external termination schemes. The drivers were specifically designed to comply with the requirements of V.35 as well as the driver output impedance values of V.35. The drivers achieve the 50 Ω to 150 Ω source impedance. However, an external 150 Ω resistor to ground must be connected to the non-inverting outputs; SD(b), ST(b), and TT(b), in order to comply with the 135 Ω to 165 Ω short-circuit impedance for V.35. The V.35 driver itself is disabled and transparent when the decoder is in all other modes. All of the differential drivers; RS-485, RS-422, and V.35, can operate up to 10Mbps.

The driver inputs are both TTL or CMOS compatible. Since there are no pull-up or pull-down resistors on the driver inputs, they should be tied to a known logic state in order to define the driver output.

Receivers

The **SP504** has seven (7) independent receivers which can be programmed for the different interface modes. Control for the mode selection is done via a 4-bit control word that is independent from the driver control word. The coding for the drivers and receivers is identical. Therefore, if the modes for the drivers and receivers are supposed to be identical in the application, the control lines can be tied together.

Like the drivers, the receivers are pre-arranged for the specific requirements of the interface. As the operating mode of the receivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line receivers. Table 2 shows the mode of each receiver in the different interface modes that can be selected.

There are three basic types of receiver circuits — RS-232, RS-423, and RS-485.

The RS-232 receiver is a single-ended input with a threshold of 0.8V to 2.4V. The RS-232 receiver has an operating voltage range of $\pm 15\text{V}$ and can receive signals up to 120kbps. The input sensitivity complies with EIA-RS-232 and V.28 at +3V to -3V. The input impedance is $3\text{k}\Omega$ to $7\text{k}\Omega$. RS-232 receivers are used in RS-232 mode for all data, clock and control signals. They are also used in V.35 mode for control line signals such as CTS and DSR.

The RS-423 receivers are also single-ended but have an input threshold as low as $\pm 200\text{mV}$. The input impedance is guaranteed to be greater than $4\text{k}\Omega$, with an operating voltage range of $\pm 7\text{V}$. The RS-423 receivers can operate up to 120kbps. RS-423 receivers are used in RS-449, EIA-530, EIA-530A and V.36 modes as Category II signals as indicated by their corresponding specifications.

The third type of receiver is a differential which supports RS-485. The RS-485 receiver has an input impedance of $15\text{k}\Omega$ and a differential threshold of $\pm 200\text{mV}$. Since the characteristics of an RS-422 (V.11) receiver are actually subsets of RS-485, the receivers for RS-422 requirements are covered by the RS-485

receivers.

RS-422 receivers are used in RS-449, EIA-530, EIA-530A and V.36 as Category I signals for receiving clock, data, and some control line signals. The differential receivers can receive data up to 10Mbps.

The RS-485 receivers are also used for the V.35 mode. Unlike the older implementations of differential or V.35 receivers, the **SP504** contains an internal resistor termination network that ensures a V.35 input impedance of $100\Omega (\pm 10\Omega)$ and a short-circuit impedance of $150\Omega (\pm 15\Omega)$. The traditional V.35 implementations required external termination resistors to achieve the proper V.35 impedances. The internal network is connected via low on-resistance FET switches when the decoder is changed to V.35 mode. The termination network is transparent when all other modes are selected. The V.35 receivers can operate up to 10Mbps.

All receivers include a fail-safe feature that outputs a logic HIGH when the receiver inputs are open. For single-ended RS-232 receivers, there are internal $5\text{k}\Omega$ pull-down resistors on the inputs which produces a logic HIGH ("1") at the receiver outputs. The single-ended RS-423 receivers produce a logic LOW ("0") on the output when the inputs are open. This is due to a pull-up device connected to the input. The differential receivers have the same internal pull-up device on the non-inverting input which produces a logic HIGH ("1") at the receiver output. The three differential receivers when configured in V.35 mode (RxD, RxC & SCT) do not have fail-safe because the internal termination resistor network is connected.

Decoder

The **SP504** has the ability to change the interface mode of the drivers or receivers via an 8-bit switch. The decoder for the drivers and receivers is not latched; it is merely a combinational logic switch.

The control word can be externally latched either HIGH or LOW to write the appropriate code into the **SP504**. The codes shown in Tables 1 and 2 are the only specified, valid modes for the **SP504**. Undefined codes

may represent other interface modes not specified (consult the factory for more information). The drivers are controlled with the data bits labeled $TDEC_3$ – $TDEC_0$. All of the drivers can be put into tri-state mode by writing 0000 to the driver decode switch. The three drivers TxD, ST and TxC, have a 150 Ω pull-down resistor to ground connected at the (b) output. This resistor is part of the V.35 driver circuitry and should be connected when in V.35 mode. Tri-state is possible for all drivers in RS-232 mode. The receivers are controlled with data bits $RDEC_3$ – $RDEC_0$; the code 0000 written to the receivers will place the outputs into tri-state mode. The 0000 decoder word will override the enable control line for the one receiver (SCT).

Using the V.35_STAT Pin

The **SP504** includes a V.35 status pin where the V35_STAT pin (pin 18) is a logic HIGH ("1") when the decoder is set to V.35 mode. The pin is a logic LOW ("0") when in all other modes including tri-state (decoder set at "0000"). Pin 18 allows the user to easily add FET switches or solid state relays to connect the external 150 Ω resistor for V.35 operation. V35_STAT can be connected to the gate of the FET switches or the control of the relays so that the 150 Ω resistors are connected to the non-inverting output of the three V.35 drivers. The output current of the V35_STAT pin is that of a typical TTL load of –3.2mA. The electrical specifications are similar to the **SP504** receiver outputs. This feature would reduce additional logic required by older traditional methods.

NET1/NET2 Testing and Compliance

Many system designers are required to certify their system for use in the European public network. Electrical testing is performed in adherence to the NET (Norme Européenne de Télécommunication) which specifies the ITU Series V specifications. The **SP504** adheres to all the required physical layer testing for NET1 and NET2. Consult factory for details.

SP504 Driver Mode Selection

| Pin Label | Mode: | RS232 | V.35 | RS422 | RS485 | RS449 | EIA530 | EIA-530A | V.36 |
|---------------------------------------|-----------|-----------|-----------|-------|--------|-----------|-----------|-----------|-----------|
| TDEC ₃ - TDEC ₀ | 0000 | 0010 | 1110 | 0100 | 0101 | 1100 | 1101 | 1111 | 0110 |
| SD(a) | tri-state | V.28 | V.35- | V.11- | RS485- | V.11- | V.11- | V.11- | V.11- |
| SD(b) | tri-state | tri-state | V.35+ | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | V.11+ |
| TR(a) | tri-state | V.28 | V.28 | V.11- | RS485- | V.11- | V.11- | V.10 | V.10 |
| TR(b) | tri-state | tri-state | tri-state | V.11+ | RS485+ | V.11+ | V.11+ | tri-state | tri-state |
| RS(a) | tri-state | V.28 | V.28 | V.11- | RS485- | V.11- | V.11- | V.11- | V.10 |
| RS(b) | tri-state | tri-state | tri-state | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | tri-state |
| RL(a) | tri-state | V.28 | V.28 | V.11- | RS485- | V.10 | V.10 | V.11- | V.10 |
| RL(b) | tri-state | tri-state | tri-state | V.11+ | RS485+ | tri-state | tri-state | V.11+ | tri-state |
| LL(a) | tri-state | V.28 | V.28 | V.11- | RS485- | V.10 | V.10 | V.10 | V.10 |
| LL(b) | tri-state | tri-state | tri-state | V.11+ | RS485+ | tri-state | tri-state | tri-state | tri-state |
| ST(a) | tri-state | V.28 | V.35- | V.11- | RS485- | V.11- | V.11- | V.11- | V.11- |
| ST(b) | tri-state | tri-state | V.35+ | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | V.11+ |
| TT(a) | tri-state | V.28 | V.35- | V.11- | RS485- | V.11- | V.11- | V.11- | V.11- |
| TT(b) | tri-state | tri-state | V.35+ | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | V.11+ |

Table 1. Driver Mode Selection

SP504 Receiver Mode Selection

| Pin Label | Mode: | RS232 | V.35 | RS422 | RS485 | RS449 | EIA530 | EIA-530A | V.36 |
|---------------------------------------|--------------|--------------|--------------|-------|--------|--------------|--------------|--------------|--------------|
| RDEC ₃ - RDEC ₀ | 0000 | 0010 | 1110 | 0100 | 0101 | 1100 | 1101 | 1111 | 0110 |
| RD(a) | >12kΩ to GND | V.28 | V.35- | V.11- | RS485- | V.11- | V.11- | V.11- | V.11- |
| RD(b) | >12kΩ to GND | >12kΩ to GND | V.35+ | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | V.11+ |
| RT(a) | >12kΩ to GND | V.28 | V.35- | V.11- | RS485- | V.11- | V.11- | V.11- | V.11- |
| RT(b) | >12kΩ to GND | >12kΩ to GND | V.35+ | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | V.11+ |
| CS(a) | >12kΩ to GND | V.28 | V.28 | V.11- | RS485- | V.11- | V.11- | V.11- | V.10 |
| CS(b) | >12kΩ to GND | >12kΩ to GND | >12kΩ to GND | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | >12kΩ to GND |
| DM(a) | >12kΩ to GND | V.28 | V.28 | V.11- | RS485- | V.11- | V.11- | V.10 | V.10 |
| DM(b) | >12kΩ to GND | >12kΩ to GND | >12kΩ to GND | V.11+ | RS485+ | V.11+ | V.11+ | >12kΩ to GND | >12kΩ to GND |
| RR(a) | >12kΩ to GND | V.28 | V.28 | V.11- | RS485- | V.11- | V.11- | V.11- | V.10 |
| RR(b) | >12kΩ to GND | >12kΩ to GND | >12kΩ to GND | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | >12kΩ to GND |
| IC(a) | >12kΩ to GND | V.28 | V.28 | V.11- | RS485- | V.10 | V.10 | V.10 | V.10 |
| IC(b) | >12kΩ to GND | >12kΩ to GND | >12kΩ to GND | V.11+ | RS485+ | >12kΩ to GND | >12kΩ to GND | >12kΩ to GND | >12kΩ to GND |
| SCT(a) | >12kΩ to GND | V.28 | V.35- | V.11- | RS485- | V.11- | V.11- | V.11- | V.11- |
| SCT(b) | >12kΩ to GND | >12kΩ to GND | V.35+ | V.11+ | RS485+ | V.11+ | V.11+ | V.11+ | V.11+ |

Table 2. Receiver Mode Selection

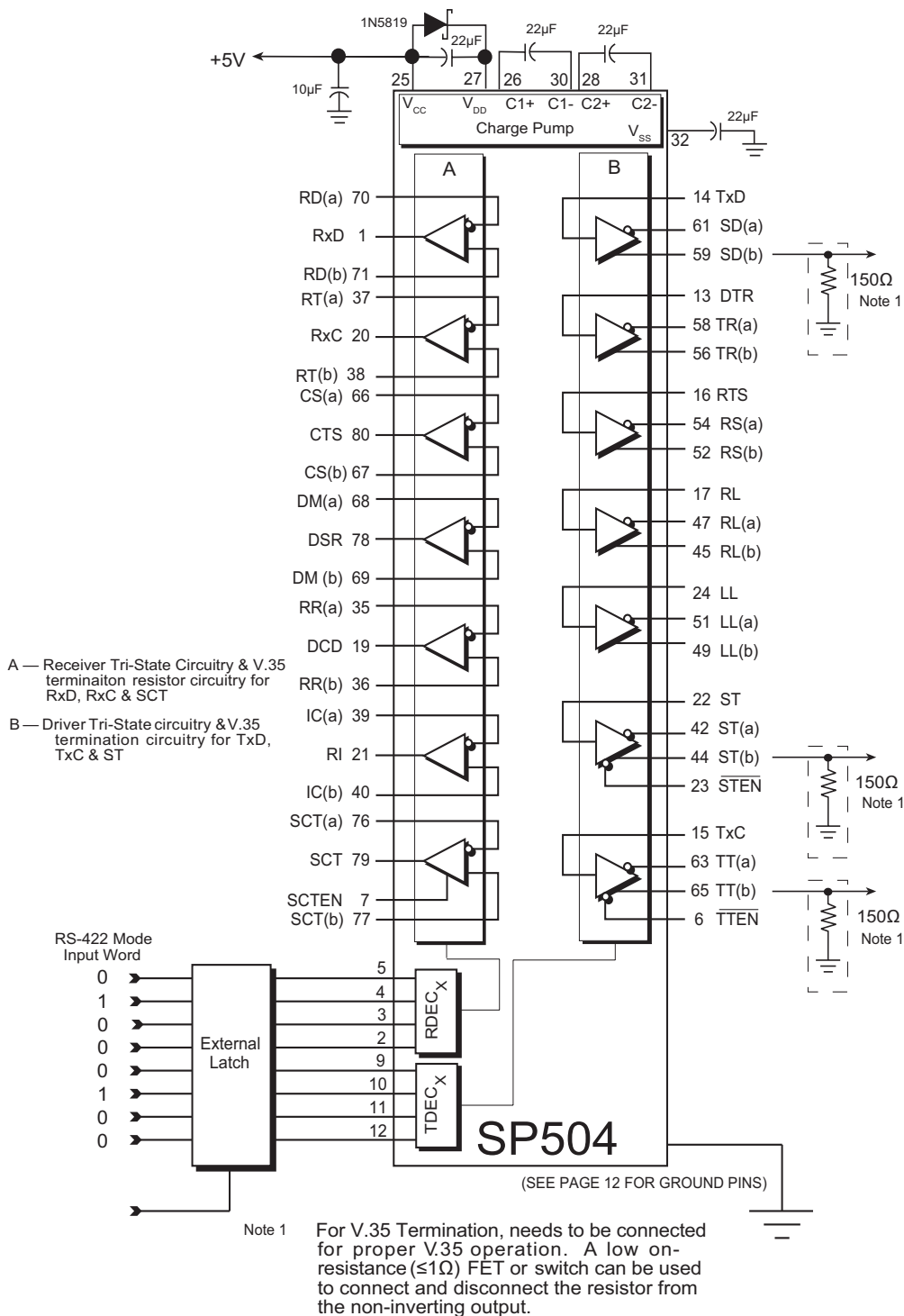


Figure 19. SP504 Typical Operating Circuit

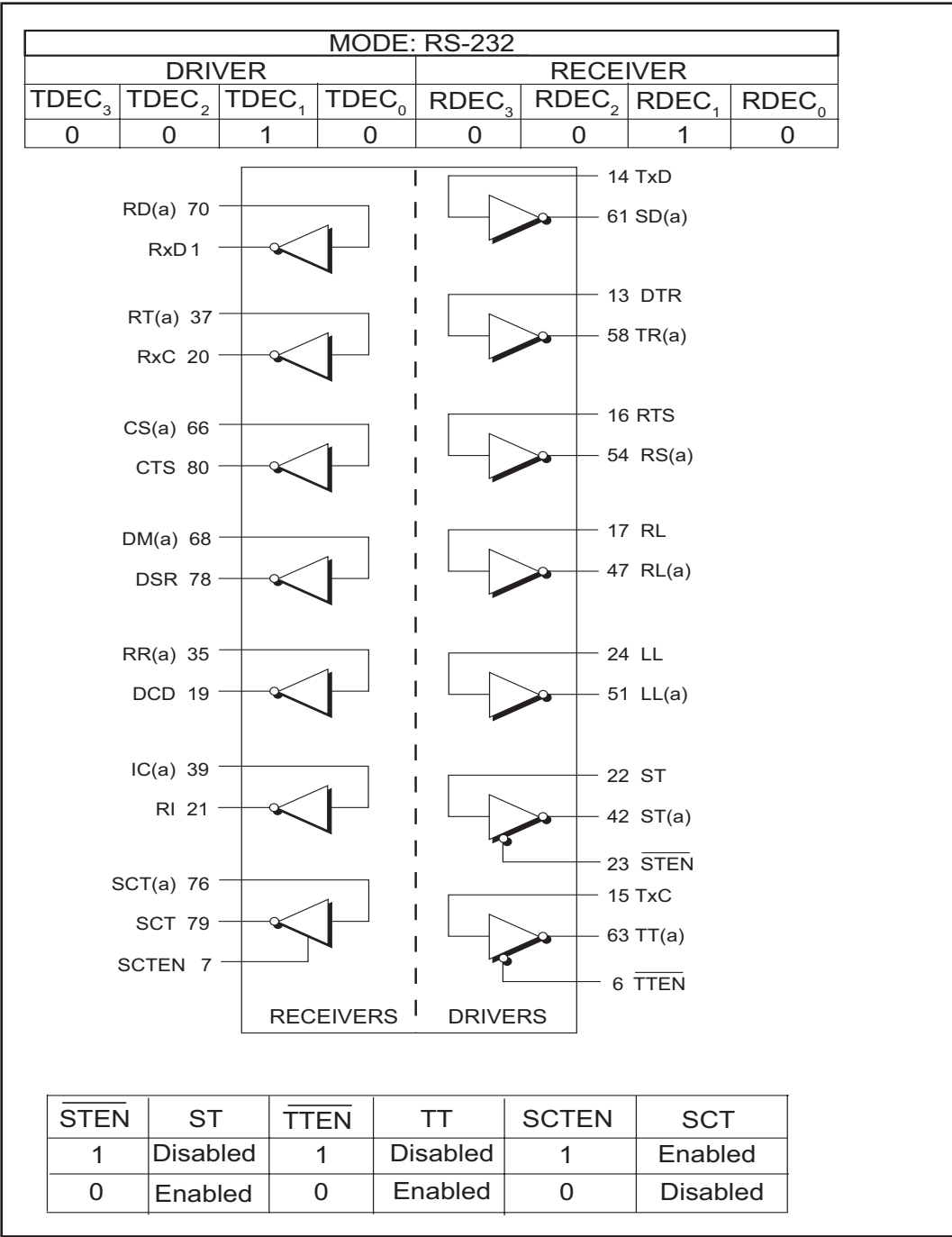
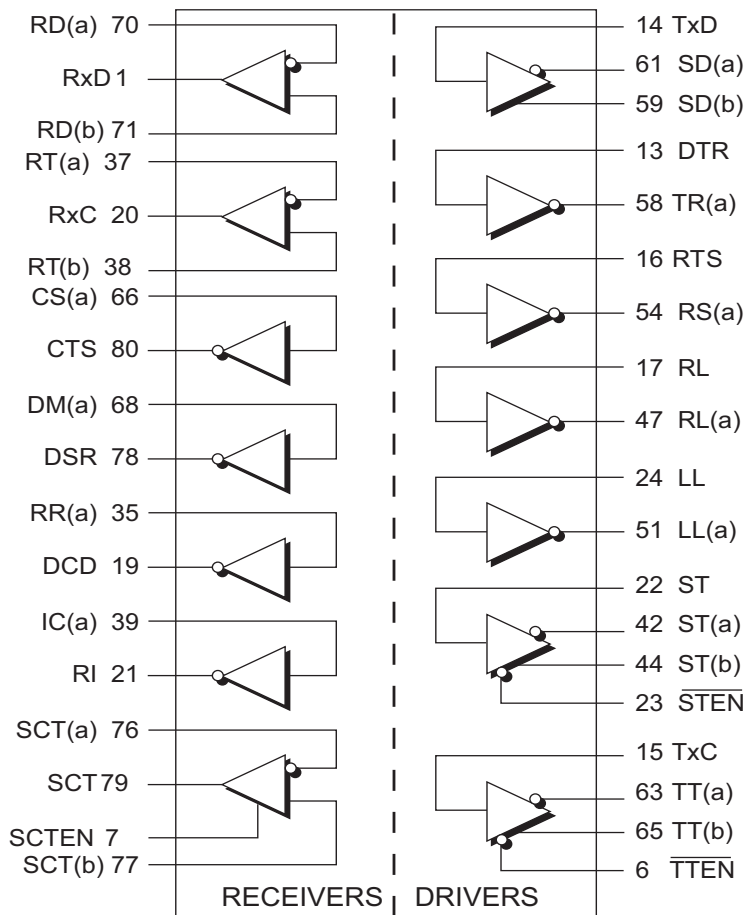


Figure 20. Mode Diagram — RS-232

| MODE: V.35 | | | | | | | |
|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|
| DRIVER | | | | RECEIVER | | | |
| TDEC ₃ | TDEC ₂ | TDEC ₁ | TDEC ₀ | RDEC ₃ | RDEC ₂ | RDEC ₁ | RDEC ₀ |
| 1 | 1 | 1 | 0 | 1 | 1 | 1 | 0 |



| $\overline{\text{STEN}}$ | ST | $\overline{\text{TTEN}}$ | TT | SCTEN | SCT |
|--------------------------|----------|--------------------------|----------|-------|----------|
| 1 | Disabled | 1 | Disabled | 1 | Enabled |
| 0 | Enabled | 0 | Enabled | 0 | Disabled |

Figure 21. Mode Diagram — V.35

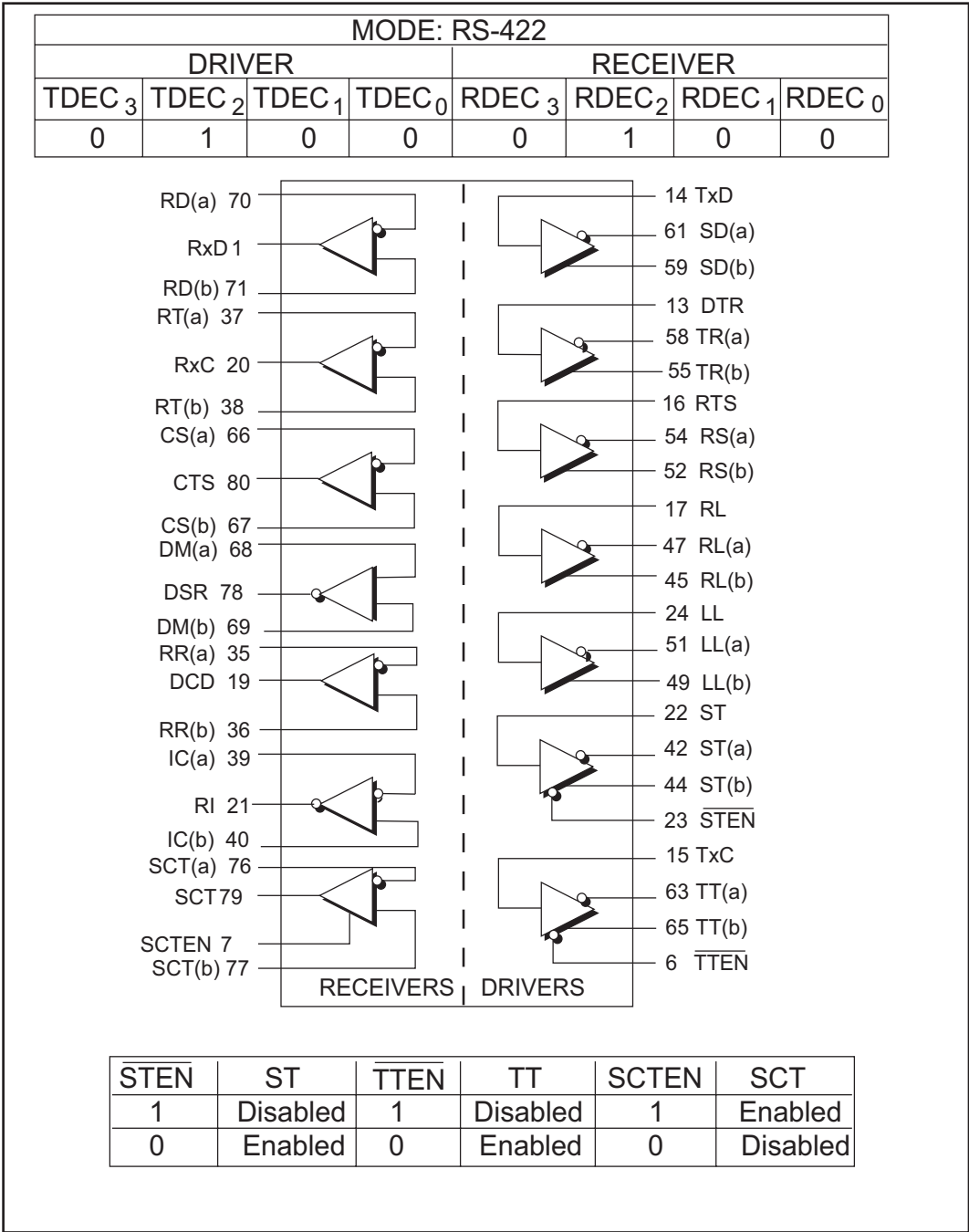


Figure 22. Mode Diagram — RS-422

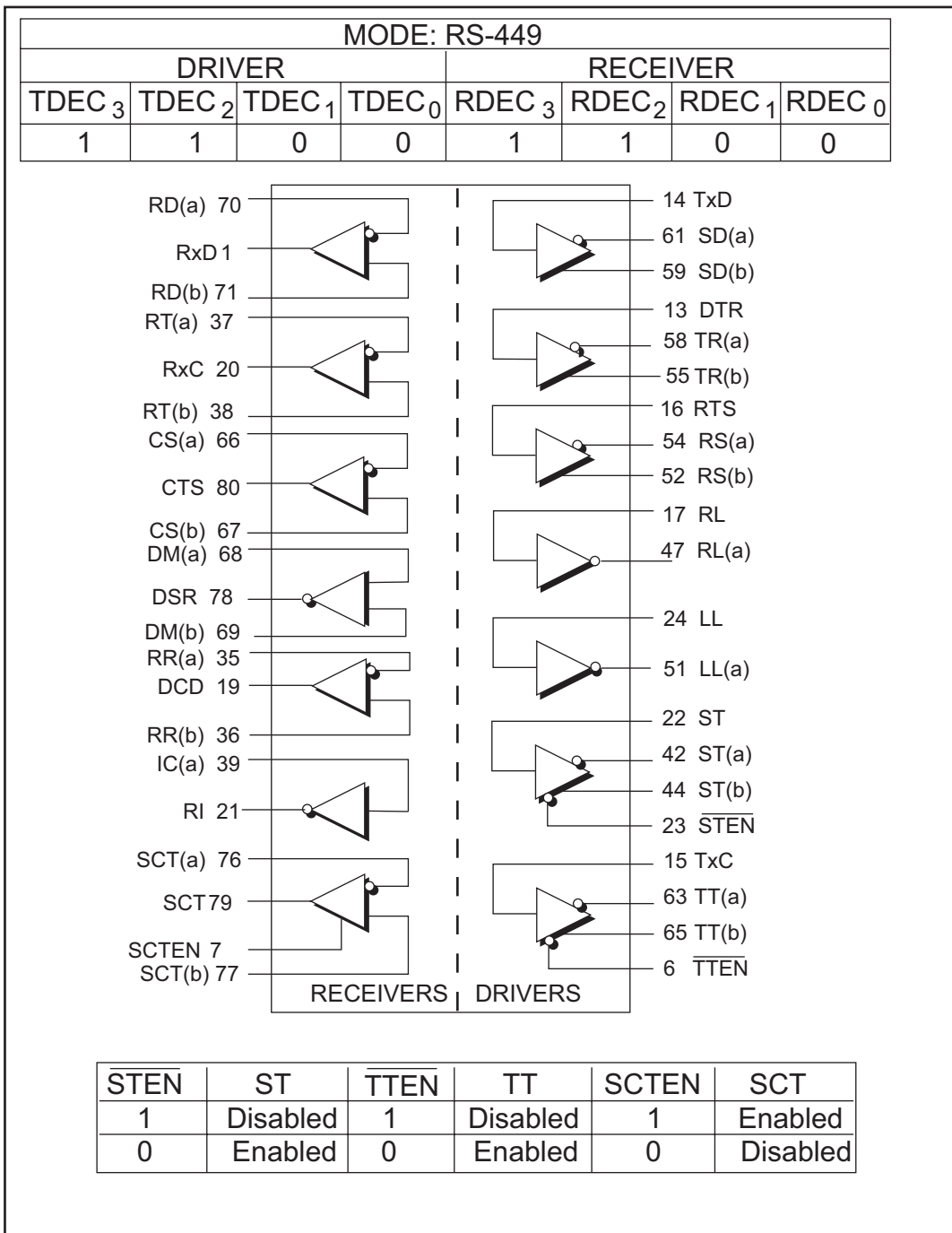


Figure 23. Mode Diagram — RS-449

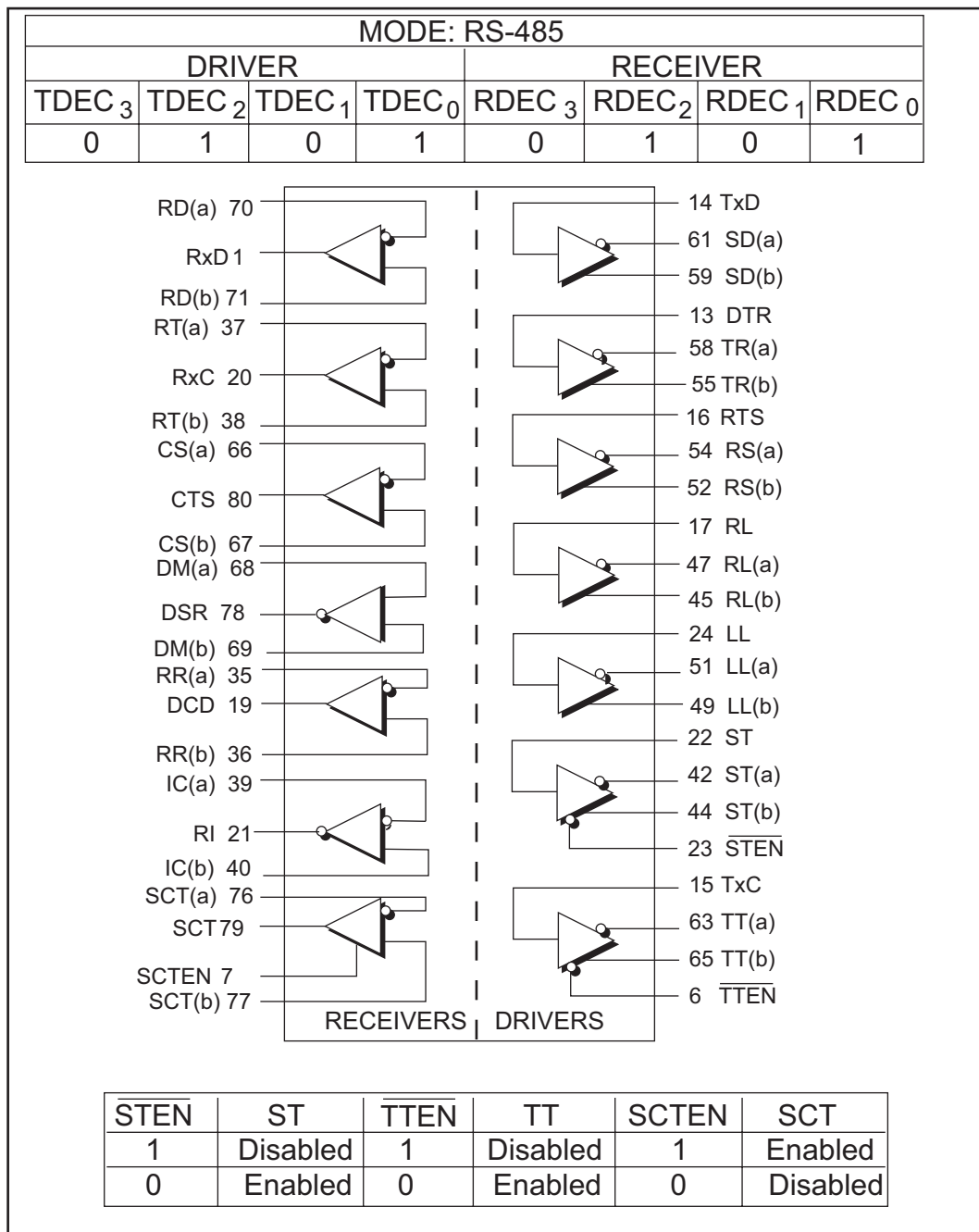


Figure 24. Mode Diagram — RS-485

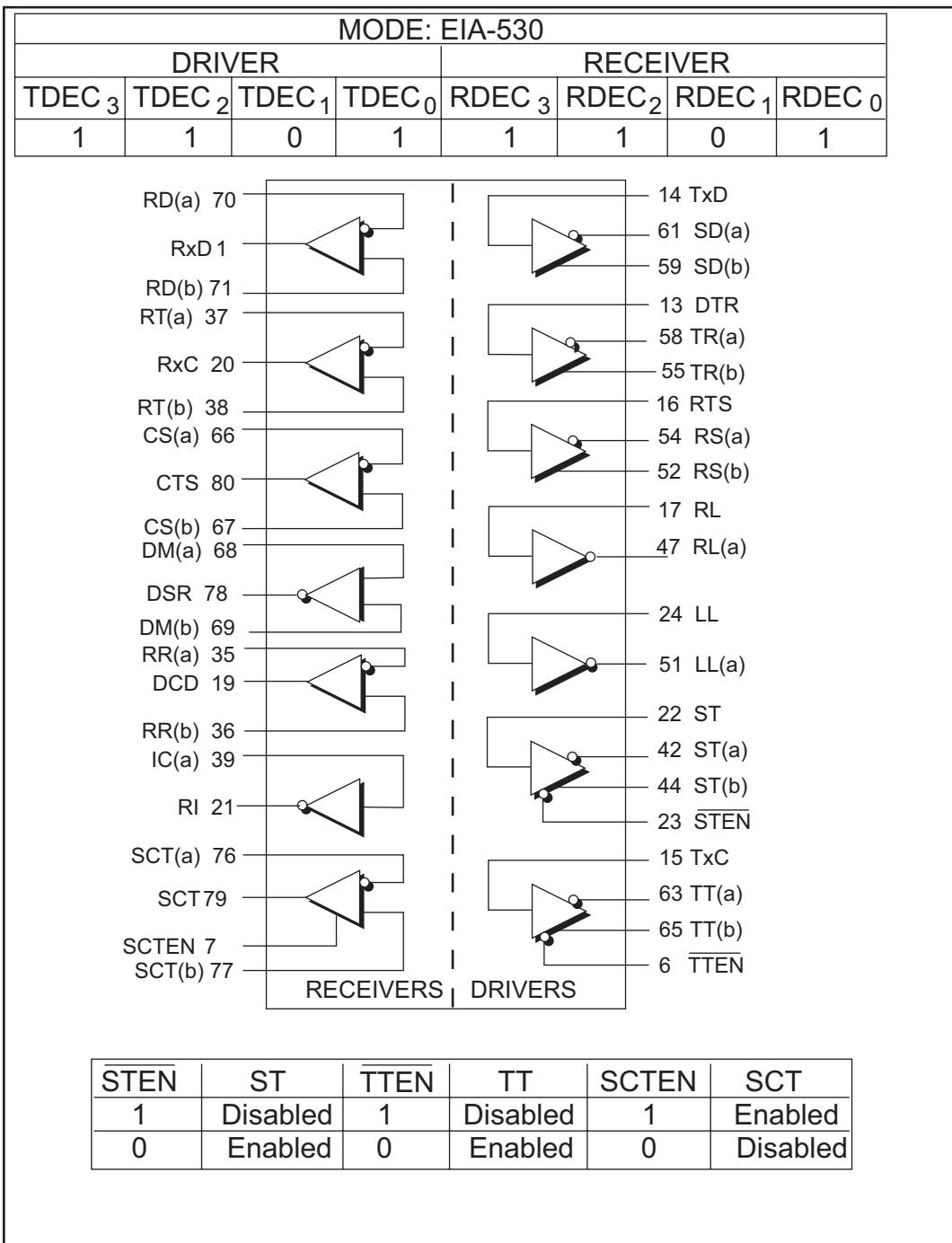


Figure 25. Mode Diagram — EIA-530

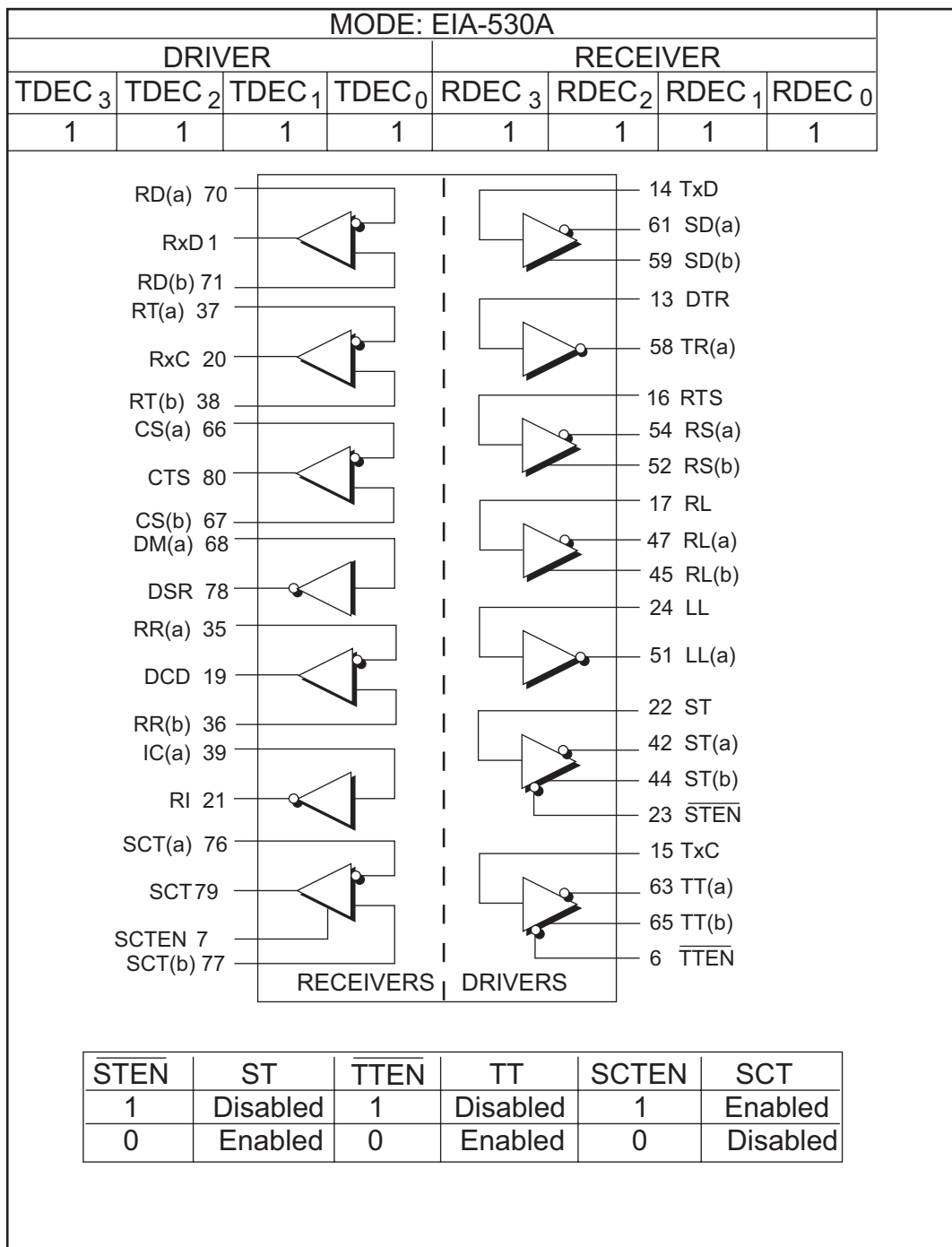


Figure 26. Mode Diagram — EIA-530A

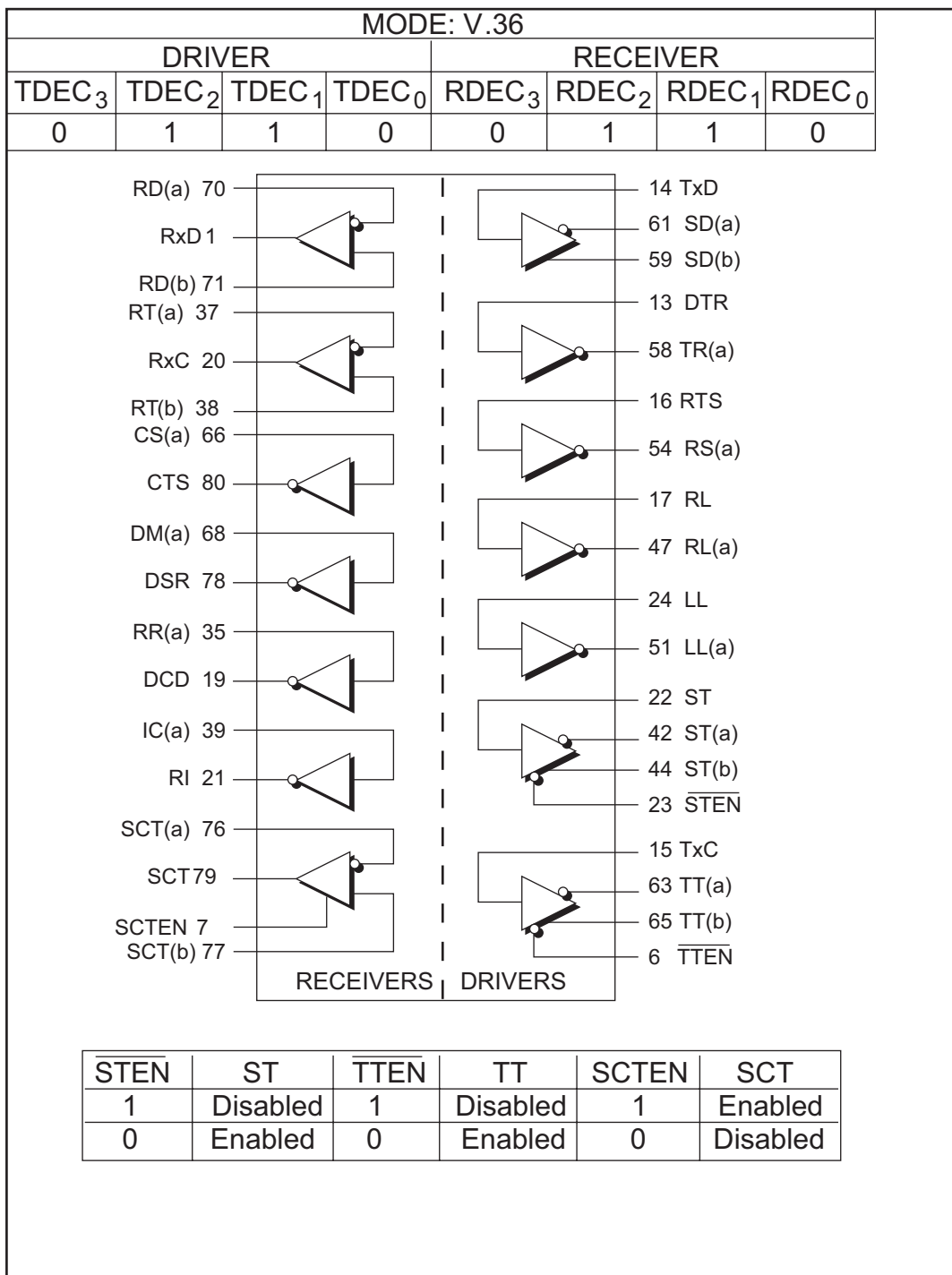


Figure 27. Mode Diagram — V.36

ADDITIONAL TRANSCEIVERS

WITH THE SP504

Serial ports usually can have two data signals (SD, RD), three clock signals (TT, ST, RT), and at least eight control signals (CS, RS, etc.). EIA-RS-449 contains twenty six signal types for a DB-37 connector. A DB-37 serial port design may require thirteen drivers and fourteen receivers¹. Although many applications do not use all these signals, some applications may need to support extra functions such as diagnostics. The **SP504** supports enough transceivers for the primary channels of data, clock and control signals. Configuring LL, RL and TM would require two additional drivers and one receiver if designing for a DTE (one driver and two receivers for a DCE).

A programmable transceiver such as the SP332 is a convenient solution in a design that requires extra single ended or differential drivers/receivers. As shown in Figure 28, the SP332 can be configured to four different variations.

The SP332 in Figure 29 is configured for two single-ended drivers and one differential receiver. For a DTE design, the two drivers are used for LL and RL signals and

the receiver is used for the TM signal. This configuration was selected because the two RS-232 drivers can be used for RS-423 by connecting a zener clamping diode to ground on the two driver outputs. The diodes will limit the voltage swing on the outputs so that the $V_{OC} = \pm 4V$ to $\pm 6V$ adheres to the RS-423 specification. The differential receiver can be easily configured to RS-423 by grounding the non-inverting input. The receiver will adhere to the RS-423 specifications.

| CIRCUIT MNEMONIC | CIRCUIT NAME | CIRCUIT DIRECTION | CIRCUIT TYPE |
|--|--|--|-----------------|
| SG SC RC | SIGNAL GROUND SEND COMMON RECEIVE COMMON | ----- TO DCE FROM DCE | COMMON |
| IS IC TR DM | TERMINAL IN SERVICE INCOMING CALL TERMINAL READY DATA MODE | TO DCE FROM DCE TO DCE FROM DCE | CONTROL |
| SD RD | SEND DATA RECEIVE DATA | TO DCE FROM DCE | DATA |
| TT ST RT | TERMINAL TIMING SEND TIMING RECEIVE TIMING | TO DCE FROM DCE FROM DCE | TIMING |
| RS CS RR SQ NS SF SR | REQUEST TO SEND CLEAR TO SEND RECEIVER READY SIGNAL QUALITY NEW SIGNAL SELECT FREQUENCY SIGNAL RATE SELECTOR | TO DCE FROM DCE FROM DCE FROM DCE TO DCE TO DCE TO DCE | CONTROL |
| SI SSD SRD SRS SCS SRR | SIGNAL RATE INDICATOR SECONDARY SEND DATA SECONDARY RD SECONDARY RS SECONDARY CS SECONDARY RR | FROM DCE TO DCE FROM DCE TO DCE FROM DCE FROM DCE | DATA |
| LL RL TM | LOCAL LOOPBACK REMOTE LOOPBACK TEST MODE | TO DCE TO DCE FROM DCE | CONTROL |
| SS SB | SELECT STANDBY STANDBY INDICATOR | TO DCE FROM DCE | CONTROL |

¹ RS-449 Interchange Circuits Table

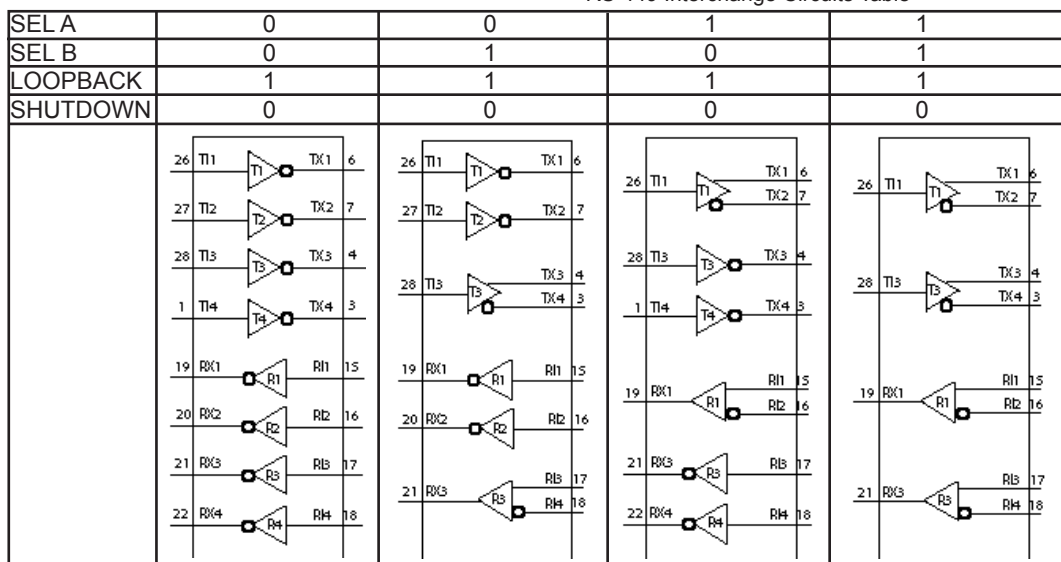


Figure 28. Mode selection for the SP332

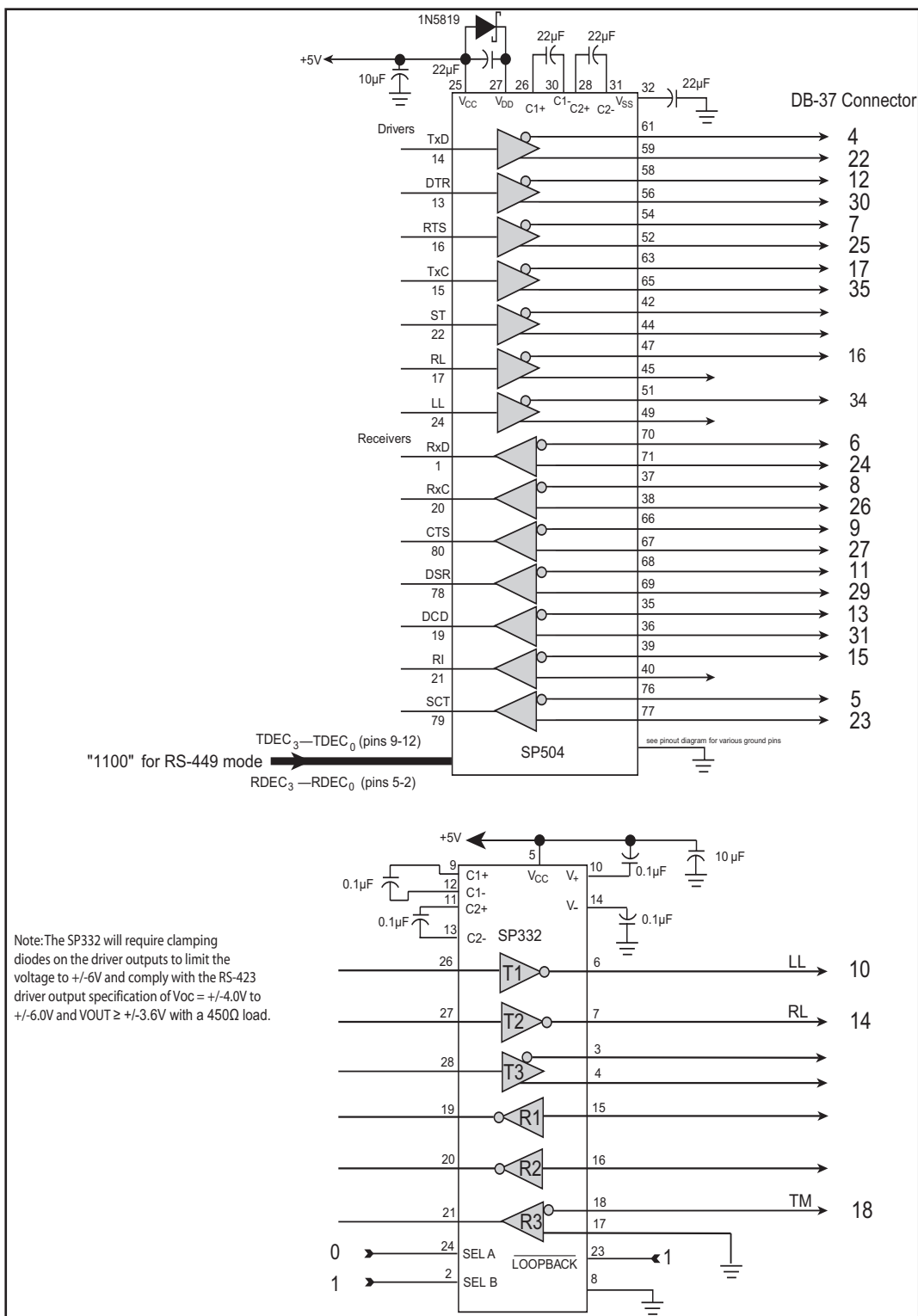
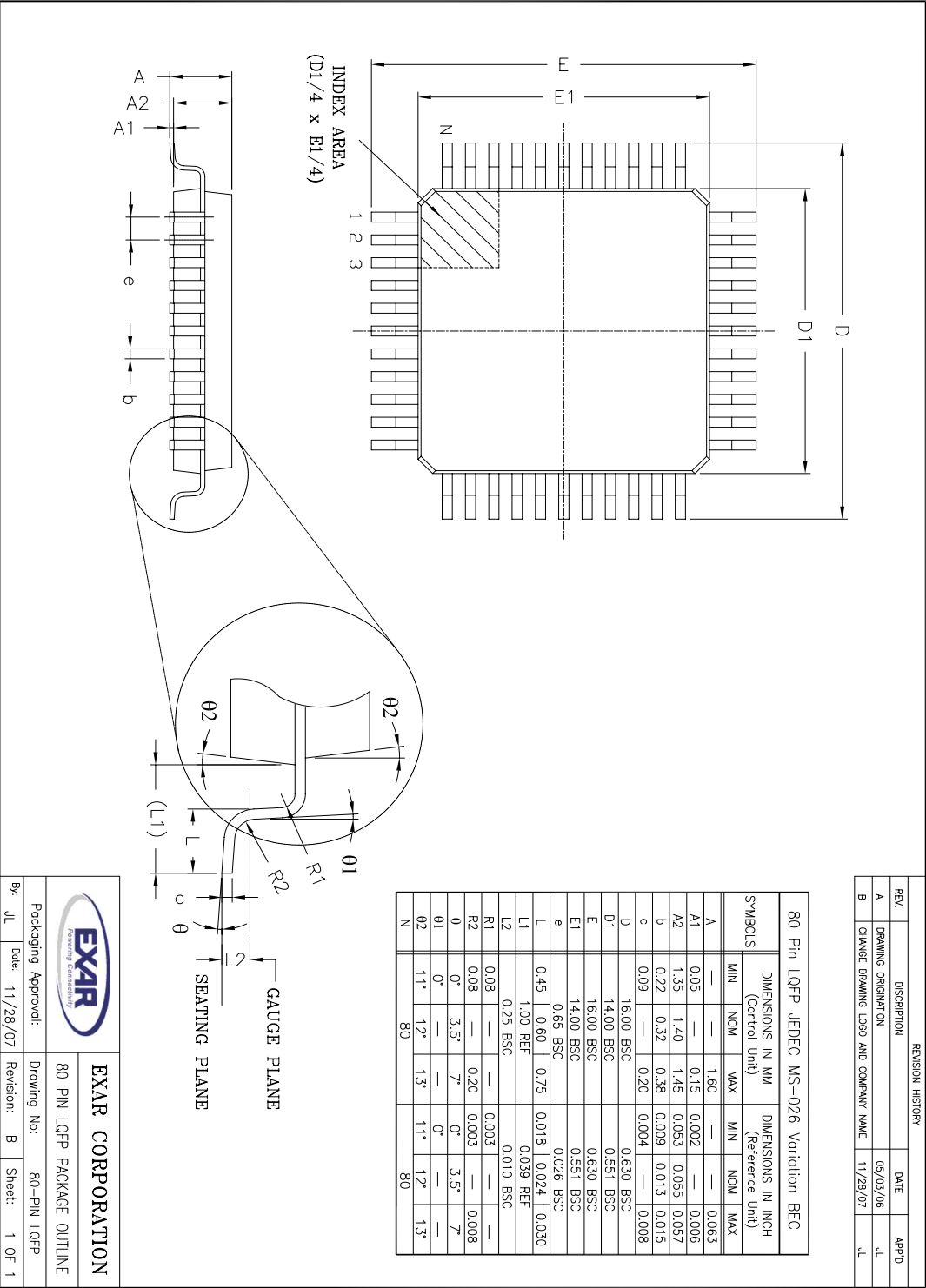


Figure 29. Adding extra differential and single-ended transceivers using the SP332



ORDERING INFORMATION

| | | |
|-----------------|-------------------|---------------|
| Model | Temperature Range | Package Types |
| SP504MCM-L..... | 0°C to +70°C..... | 80-pin LQFP |

REVISION HISTORY

| DATE | REVISION | DESCRIPTION |
|----------|----------|---|
| 01-27-04 | A | Implemented tracking revision. |
| 7-7-08 | 1.0.0 | SP504 is no longer available in MQFP package per PCN 07-1102-06a. SP514 is now only available in LQFP package compliant to RoHS. Changed to Exar data-sheet format and revision to 1.0.0. |
| 10/28/08 | 1.0.1 | Added ESD rating of 500V HBM to electrical characteristics. |
| 12/17/08 | 1.0.2 | Add new V.35 Driver output VOD vs. Temperature graph and update figure numbers. |

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