

# **Intel<sup>®</sup> C600 Series Chipset and Intel<sup>®</sup> X79 Express Chipset**

**Datasheet**

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## Revision History

Revision Number	Description	Date
001	<ul style="list-style-type: none"> <li>• Initial Release</li> </ul>	March 2012
002	<ul style="list-style-type: none"> <li>• Added Intel® X79 Express Chipset</li> <li>• Minor Edits throughout for clarity</li> <li>• Replaced SKU letter designators A/J/B/D/T with product numbers. References all of the lettered SKUs were replaced with SRV/WS.</li> <li>• Chapter 1               <ul style="list-style-type: none"> <li>— Updated Table 1-2, Intel® C600 Series Chipset and Intel® X79 Express Chipset SKUs</li> <li>— Added note to Section 1.2.1, Access Control Services Clarification</li> <li>— Updated Section 1.2.1 SPI Overview</li> </ul> </li> <li>• Chapter 2               <ul style="list-style-type: none"> <li>— Updated PWRBTN# and SLP_SUS# descriptions in Table 2-10.</li> <li>— Updated RTCRST# description in Table 2-16.</li> <li>— Added Note 13 to Table 2-22, General Purpose I/O Signals</li> <li>— Updated Table 2-25, SAS Power Signal Connections</li> <li>— Updated Section 2.28, Device and Revision ID Table</li> </ul> </li> <li>• Chapter 5               <ul style="list-style-type: none"> <li>— Added Note 5 to Table 5-27, State Transition Rules for the PCH</li> <li>— Updated Section 5.18.1.2, SCU Architectural Features, first bullet</li> <li>— Added Note to Section 5.3.1 Valid PCI Express* uplink configuration</li> <li>— Updated Table 5-29, Causes of Intel® Scalable Memory Interconnect (Intel® SMI) and SCI</li> <li>— Updated Table 5-44, Event Transitions that Cause Messages</li> <li>— Updated Section 5.14.7.1, PWRBTN# (Power Button)</li> <li>— Added Note to Section 5.15.4, GPIO Registers Lockdown</li> <li>— Updated Section 5.19, High Precision Event Timers Functional Description</li> <li>— Updated Section 5.23.1, Thermal Sensor</li> <li>— Updated Section 5.26.1.2.1, SPI Flash Regions</li> <li>— Updated Section 5.27, Fan Control/Thermal Management</li> </ul> </li> <li>• Chapter 8               <ul style="list-style-type: none"> <li>— Updated Table 8-4 and 8-5, Icc Value for RTC Well</li> <li>— Updated Table 8-13, Clock Timings</li> <li>— Updated Table 8-26, Power Sequencing and Reset Signal Timings</li> <li>— Added notes to Figures 8-2 and 8-20</li> </ul> </li> <li>• Chapter 9               <ul style="list-style-type: none"> <li>— Updated Table 9-7, Memory Decode Ranges from Processor Perspective</li> </ul> </li> <li>• Chapter 10               <ul style="list-style-type: none"> <li>— Updated Table 10-1, Chipset Configuration Register Memory Map</li> <li>— Updated 10.1.4, Function Level Reset Pending Status Register</li> <li>— Updated 10.1.47, FDSW-Function Disable SUS Well</li> </ul> </li> <li>• Chapter 12               <ul style="list-style-type: none"> <li>— Updated Table 12-1, Gigabit LAN Configuration Registers Address Map</li> </ul> </li> <li>• Chapter 13               <ul style="list-style-type: none"> <li>— Updated Table 13-1, LPC Interface PCI Register Address Map</li> <li>— Updated Section 13.8.3.7, SMI_EN—SMI Control and Enable Register</li> <li>— Updated Section 13.8.3.11, UPRWC—USB Per-Port Registers Write Control Register</li> <li>— Updated Table 13-13 Registers to Control GPIO Address Map</li> </ul> </li> <li>• Chapter 14               <ul style="list-style-type: none"> <li>— Updated Table 14-1, SATA Controller PCI Register Address Map</li> <li>— Updated Section 14.1.37, SGC-SATA General Configuration Register</li> </ul> </li> <li>• Chapter 15               <ul style="list-style-type: none"> <li>— Updated Table 15-1, SATA Controller PCI Register Address Map</li> </ul> </li> <li>• Chapter 17               <ul style="list-style-type: none"> <li>— Updated Section 17.1.20, PWR_CNTL_SIS Register</li> </ul> </li> <li>• Chapter 20               <ul style="list-style-type: none"> <li>— Updated Table 20-1, PCI Express* Configuration Registers Address Map</li> <li>— PE2R2 — PCI Express* Configuration Register 2 (PCI Express—D28:F0/F1/F2/F3/F4/F5/F6/F7) and PE1 — PCI Express* Configuration Register 1 have been removed as no BIOS programming is necessary.</li> </ul> </li> </ul>	March 2013



Revision Number	Description	Date
002 (cont)	<ul style="list-style-type: none"> <li>• Chapter 22               <ul style="list-style-type: none"> <li>— Updated Table 22-1, Serial Peripheral Interface (SPI) Register Address Map</li> <li>— Updated Table 22-1, Gigabit LAN SPI Flash Program Register Address Map</li> </ul> </li> <li>• Chapter 23               <ul style="list-style-type: none"> <li>— Updated Section 23.2.4, TSTR—Thermal Sensor Thermometer Read Register</li> </ul> </li> <li>• Chapter 24               <ul style="list-style-type: none"> <li>— Updated Table 24-1, Intel MEI 1 Configuration Registers Address Map</li> </ul> </li> <li>• Chapter 25               <ul style="list-style-type: none"> <li>— Updated Section 25.1.31, LCAP—Link Capabilities Register (PCI Express—D0:F0)</li> <li>— Updated Section 25.1.33, LSTS—Link Status Register (PCI Express—D0:F0)</li> <li>— Removed LINKCAP2 Register</li> <li>— Updated Section 25.1.38, L2—Link Control 2 Register (PCI Express—D0:F0)</li> </ul> </li> <li>• Chapter 26               <ul style="list-style-type: none"> <li>— Updated Section 26.2.30, LCAP—Link Capabilities Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)</li> <li>— Updated Section 26.2.321, LSTS—Link Status Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)</li> <li>— Removed LINKCAP2 Register</li> <li>— Updated Section 26.2.39, L2—Link Control 2 Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)</li> </ul> </li> </ul>	March 2013

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## Intel® C600 Series Chipset and Intel® X79 Express Chipset Features

- **Direct Media Interface**
  - NEW: Up to 20 Gb/s each direction, full duplex
  - Lane reversal supported
  - Transparent to software
- **PCI Express\* Root Ports**
  - 8 PCI Express\* root ports
  - NEW: Supports PCI Express\* 2.0 running at up to 5.0 GT/s
  - Ports 1-4 and ports 5-8 can independently be configured to support eight x1s, two x4s, two x2s, and four x1s, or one x4 and four x1 port widths.
  - Module based hot-plug supported (that is, ExpressCard\*)
  - Lane reversal supported on x4 configuration
- **NEW: PCI Express\* Uplink Port (SRV/WS SKUs Only)**
  - SKU specific x4 PCI Express\* upstream port dedicated for SAS I/O
- **NEW: Serial Attached SCSI (SAS) Ports (SRV/WS SKUs Only)**
  - SKU specific up to eight 3 Gb/s SAS ports
  - Up to x4 SAS wide port configuration
  - Independently configurable
  - Compliant to SATA 3 Gb/s
  - Automated Out of Band (OOB) Signaling & Speed Negotiation
- **SGPIO Ports**
  - New: 1 Serial GPIO controller for each 4 SAS ports (SRV/WS SKUs Only)
  - Serial GPIO controller for SATA only ports
- **Integrated Serial ATA Host Controller**
  - Up to six SATA ports
  - NEW: Data transfer rates up to 6.0 Gb/s (600 MB/s) on up to 2 ports.
  - Data transfer rates up to 3.0 Gb/s (300 MB/s) on up to 1.5 Gb/s (150 MB/s) all ports.
  - Integrated AHCI controller
- **External SATA support**
  - 3.0 Gb/s / 1.5 Gb/s support
  - Port Disable Capability
- **Intel® Rapid Storage Technology enterprise**
  - Supports SAS as well as SATA ports
  - Configures the Intel® C600 Series chipset SAS ports as a RAID Controller supporting RAID 0/1/5/10
  - Configures the Intel® C600 Series chipset SATA ports as a RAID controller supporting RAID 0/1/5/10
- **USB**
  - Two EHCI Host Controllers, supporting up to fourteen external USB 2.0 ports
  - New: Two USB 2.0 Rate Matching Hubs (RMH) to replace functionality of UHCI controllers
  - Per-Port-Disable Capability
  - Includes up to two USB 2.0 High-speed Debug Ports
  - Supports wake-up from sleeping states S1-S4
  - Supports legacy Keyboard/Mouse software
- **Integrated Gigabit LAN Controller**
  - NEW: Connection utilizes PCI Express\* pins
  - Integrated ASF Management Controller
  - Network security with System Defense
  - Supports IEEE 802.3
  - 10/100/1000 Mbps Ethernet Support
  - Jumbo Frame Support
- **Power Management Logic**
  - Supports ACPI 4.0a
  - ACPI-defined power states (processor driven C states)
  - ACPI Power Management Timer
  - SMI# generation
  - All registers readable/restorable for proper resume from 0 V core well suspend states
  - Support for APM-based legacy power management for non-ACPI implementations
- **External Glue Integration**
  - Integrated Pull-up, Pull-down and Series Termination resistors on processor I/F
  - Integrated Pull-down and Series resistors on USB
- **Enhanced DMA Controller**
  - Two cascaded 8237 DMA controllers
  - Supports LPC DMA



- **Intel® High Definition Audio Interface**
  - PCI Express\* endpoint
  - Independent Bus Master logic for eight general purpose streams: four input and four output
  - Support four external Codexes
  - Supports variable length stream slots
  - Supports multichannel, 32-bit sample depth, 192 kHz sample rate output
  - Provides mic array support
  - Allows for non-48 kHz sampling output
- Support for ACPI Device States
  - Four PWM signals and Eight TACH signals
- **Simple Serial Transport (SST) 1.0 Bus and Platform Environmental Control Interface (PECI)**
- **PCI Bus Interface**
  - Supports PCI Rev 2.3 specification at 33 MHz
  - Four available PCI REQ/GNT pairs (shared with GPIO serial expander signals)
  - Support for 64-bit addressing on PCI using DAC protocol
- **SMBus**
  - Interface speeds greater than 100 kbps
  - SMBus/SMLink architecture provides flexibility and optimizes the interface performance
  - Provides independent manageability bus through SMLink interface
  - Supports SMBus 2.0 Specification
  - Host interface allows processor to communicate using SMBus
  - Slave interface allows an external Microcontroller to communicate with PCH
  - Compatible with most two-wire components that are also I<sup>2</sup>C\* compatible
  - Up to 3 additional SMBus master controllers
- **High Precision Event Timers**
  - Advanced operating system interrupt scheduling
- **Timers Based on 8254**
  - System timer, Refresh request, Speaker tone output
- **Real-Time Clock**
  - 256-byte battery-backed CMOS RAM
  - Integrated oscillator components
  - Lower Power DC/DC Converter implementation
- **System TCO Reduction Circuits**
  - Timers to generate SMI# and Reset upon detection of system hang
  - Timers to detect improper processor reset
  - Integrated processor frequency strap logic
  - Supports ability to disable external devices
- **Interrupt Controller**
  - Supports up to eight PCI interrupt pins
  - Supports PCI 2.3 Message Signaled Interrupts
  - Two cascaded 8259 with 15 interrupts
  - Integrated I/O APIC capability with 24 interrupts
  - Supports Processor System Bus interrupt delivery
- **Serial Peripheral Interface (SPI)**
  - Supports up to two SPI devices
  - Supports 20 MHz, 33 MHz SPI devices
  - Support up to two different erase granularities
- **Low Pin Count (LPC) I/F**
  - Supports two Master/DMA devices.
  - Support for Security Device (Trusted Platform Module) connected to LPC.
- **GPIO**
  - Inversion, Open-Drain (not available on all GPIOs),
  - GPIO lock down
  - NEW: Additional GPIOs using GPIO Serial Expander
- **JTAG**
  - Boundary Scan for testing during board manufacturing
- **Technologies supported**
  - Intel® I/O Virtualization (VT-d) Support (SRV/WS SKUs Only)
  - Intel® Trusted Execution Technology Support
  - Intel® Anti-Theft Technology
  - Intel® Active Management Technology with System Defense (SRV/WS SKUs Only)
  - NEW: Network Outbreak Containment Heuristics
- **Miscellaneous**
  - Thermal sensor for die temp tracking
  - 27x27 mm FCBGA package
  - 901 pins (498 signals, 387 power and ground)
  - 1.1 V operation with 1.5 and 3.3 V I/O
  - Five Integrated Voltage Regulators for different power rails
  - Firmware Hub I/F supports BIOS Memory size up to 8 MBytes

**Note:** Not all features are available on all PCH SKUs. See [Section 1.3](#) for more details.





# 1 Introduction

## 1.1 About This Manual

This manual is intended for Original Equipment Manufacturers and BIOS vendors creating Intel® C600 Series Chipset and Intel® X79 Express Chipset based products (See Section 1.3 for currently defined SKUs).

**Note:** Throughout this document, the terms “Server/Workstation” and “Server/Workstation Only” refer to information that is applicable only to the Intel® C602 Chipset, Intel® C602J Chipset, Intel® C604 Chipset, Intel® C606 Chipset, and Intel® C608 Chipset, unless specifically noted otherwise. Server/Workstation is abbreviated SRV/WS

**Note:** Throughout this document, the terms “High End Desktop” and “High End Desktop Only” refer to information that is applicable only to the Intel® X79 Chipset, unless specifically noted otherwise. High End Desktop is abbreviated HEDT.

**Note:** Throughout this manual, Platform Controller Hub (PCH) is used as a general term and refers to all Intel® C600 Series Chipset and Intel® X79 Express Chipset SKUs, unless specifically noted otherwise.

This manual assumes a working knowledge of the vocabulary and principles of interfaces and architectures such as PCI Express\*, USB, AHCI, SATA, Intel® High Definition Audio (Intel® HD Audio), SMBus, PCI, ACPI and LPC. Although some details of these features are described within this manual, refer to the individual industry specifications listed in Table 1-1 for the complete details.

**Table 1-1. Industry Specifications (Sheet 1 of 2)**

Specification	Location
PCI Express* Base Specification, Revision 1.1	<a href="http://www.pcisig.com/specifications">http://www.pcisig.com/specifications</a>
PCI Express* Base Specification, Revision 2.0	<a href="http://www.pcisig.com/specifications">http://www.pcisig.com/specifications</a>
PCI Express* Base Specification, Revision 3.0 (draft)	<a href="http://www.pcisig.com/specifications">http://www.pcisig.com/specifications</a>
Low Pin Count Interface Specification, Revision 1.1 (LPC)	<a href="http://developer.intel.com/design/chipsets/industry/lpc.htm">http://developer.intel.com/design/chipsets/industry/lpc.htm</a>
System Management Bus Specification, Version 2.0 (SMBus)	<a href="http://www.smbus.org/specs/">http://www.smbus.org/specs/</a>
PCI Local Bus Specification, Revision 2.3 (PCI)	<a href="http://www.pcisig.com/specifications">http://www.pcisig.com/specifications</a>
PCI Power Management Specification, Revision 1.2	<a href="http://www.pcisig.com/specifications">http://www.pcisig.com/specifications</a>
Universal Serial Bus Specification (USB), Revision 2.0	<a href="http://www.usb.org/developers/docs">http://www.usb.org/developers/docs</a>
Advanced Configuration and Power Interface, Version 4.0a (ACPI)	<a href="http://www.acpi.info/spec.htm">http://www.acpi.info/spec.htm</a>
Enhanced Host Controller Interface Specification for Universal Serial Bus, Revision 1.0 (EHCI)	<a href="http://developer.intel.com/technology/usb/ehcispec.htm">http://developer.intel.com/technology/usb/ehcispec.htm</a>
Serial ATA Specification, Revision 3.0	<a href="http://www.serialata.org/specifications.asp">http://www.serialata.org/specifications.asp</a>
Serial ATA II: Extensions to Serial ATA 1.0, Revision 1.0	<a href="http://www.serialata.org/specifications.asp">http://www.serialata.org/specifications.asp</a>
Serial ATA II Cables and Connectors Volume 2 Gold	<a href="http://www.serialata.org/specifications.asp">http://www.serialata.org/specifications.asp</a>
Serial Attached SCSI (SAS) revision 2.0r5	<a href="http://T10.org">http://T10.org</a> (T10 1760-D)
Alert Standard Format Specification, Version 2.0	<a href="http://www.dmtf.org/standards/documents/ASF/DSP0136.pdf">http://www.dmtf.org/standards/documents/ASF/DSP0136.pdf</a>
Desktop and mobile Architecture for System Hardware (DASH) Specification 1.1	<a href="http://www.dmtf.org/standards/published_documents/DSP2014_1.1.0.pdf">http://www.dmtf.org/standards/published_documents/DSP2014_1.1.0.pdf</a>

**Table 1-1. Industry Specifications (Sheet 2 of 2)**

Specification	Location
IEEE 802.3 Fast Ethernet	<a href="http://standards.ieee.org/getieee802/">http://standards.ieee.org/getieee802/</a>
AT Attachment - 6 with Packet Interface (ATA/ATAPI - 6)	<a href="http://T13.org">http://T13.org</a> (T13 1410D)
IA-PC HPET (High Precision Event Timers) Specification, Revision 1.0a	<a href="http://www.intel.com/content/www/us/en/software-developers/software-developers-hpet-spec-1-0a.html">http://www.intel.com/content/www/us/en/software-developers/software-developers-hpet-spec-1-0a.html</a>
TPM Specification 1.02, Level 2 Revision 103	<a href="http://www.trustedcomputinggroup.org/specs/TPM">http://www.trustedcomputinggroup.org/specs/TPM</a>
Intel® Virtualization Technology	<a href="http://www.intel.com/technology/platform-technology/virtualization/index.htm">http://www.intel.com/technology/platform-technology/virtualization/index.htm</a>
SFF-8485 Specification for Serial GPIO (SGPIO) Bus, Revision 0.7	<a href="ftp://ftp.seagate.com/sff/SFF-8485.PDF">ftp://ftp.seagate.com/sff/SFF-8485.PDF</a>
Advanced Host Controller Interface specification for Serial ATA, Revision 1.3	<a href="http://www.intel.com/content/www/us/en/io/serial-ata/serial-ata-ahci-spec-rev1_3.html">http://www.intel.com/content/www/us/en/io/serial-ata/serial-ata-ahci-spec-rev1_3.html</a>
Intel® High Definition Audio Specification, Revision 1.0a	<a href="http://www.intel.com/content/www/us/en/standards/standards-high-def-audio-specs-general-technology.html">http://www.intel.com/content/www/us/en/standards/standards-high-def-audio-specs-general-technology.html</a>
MultiProcessor Specification	<a href="http://www.intel.com/design/pentium/datashts/242016.HTM">http://www.intel.com/design/pentium/datashts/242016.HTM</a>

**Chapter 1. Introduction**

Chapter 1 introduces the PCH and provides information on manual organization and gives a general overview of the PCH.

**Chapter 2. Signal Description**

Chapter 2 provides a block diagram of the PCH and a detailed description of each signal. Signals are arranged according to interface and details are provided as to the drive characteristics (Input/Output, Open Drain, and so forth) of all signals.

**Chapter 3. PCH Pin States**

Chapter 3 provides a complete list of signals, their associated power well, their logic level in each suspend state, and their logic level before and after reset.

**Chapter 4. PCH and System Clock Domains**

Chapter 4 provides a list of each clock domain associated with the PCH.

**Chapter 5. Functional Description**

Chapter 5 provides a detailed description of the functions in the PCH. All PCI buses, devices and functions in this manual are abbreviated using the following nomenclature; Bus:Device:Function. This manual abbreviates buses as *B<sub>n</sub>*, devices as *D<sub>n</sub>*, and functions as *F<sub>n</sub>*. For example Device 31 Function 0 is abbreviated as D31:F0, Bus 1 Device 8 Function 0 is abbreviated as B1:D8:F0. Generally, the bus number will not be used, and can be considered to be Bus 0. Note that the PCH's external PCI bus is typically Bus 1, but may be assigned a different number depending upon system configuration.

**Chapter 6. Ballout Definition**

Chapter 6 provides a table of each signal and its ball assignment in the PCH package.

**Chapter 7. Package Information**

Chapter 7 provides drawings of the physical dimensions and characteristics of the 676-mBGA package.

**Chapter 8. Electrical Characteristics**

Chapter 8 provides all AC and DC characteristics including detailed timing diagrams.

**Chapter 9. Register and Memory Mappings**

Chapter 9 provides an overview of the registers, fixed I/O ranges, variable I/O ranges and memory ranges decoded by the PCH.



### **Chapter 10. Chipset Configuration Registers**

[Chapter 10](#) provides a detailed description of all registers and base functionality that is related to chipset configuration and not a specific interface (such as LPC, PCI, or PCI Express). It contains the root complex register block, which describes the behavior of the upstream internal link.

### **Chapter 11. PCI-to-PCI Bridge Registers**

[Chapter 11](#) provides a detailed description of all registers that reside in the PCI-to-PCI bridge. This bridge resides at Device 30, Function 0 (D30:F0).

### **Chapter 12. Integrated LAN Controller Registers**

[Chapter 12](#) provides a detailed description of all registers that reside in the PCH's integrated LAN controller. The integrated LAN Controller resides at Device 25, Function 0 (D25:F0).

### **Chapter 13. LPC Bridge Registers**

[Chapter 13](#) provides a detailed description of all registers that reside in the LPC bridge. This bridge resides at Device 31, Function 0 (D31:F0). This function contains registers for many different units within the PCH including DMA, Timers, Interrupts, Processor Interface, GPIO, Power Management, System Management and RTC.

### **Chapter 14. SATA Controller Registers**

[Chapter 14](#) provides a detailed description of all registers that reside in the SATA controller #1. This controller resides at Device 31, Function 2 (D31:F2).

### **Chapter 15. SATA Controller Registers**

[Chapter 15](#) provides a detailed description of all registers that reside in the SATA controller #2. This controller resides at Device 31, Function 5 (D31:F5).

### **Chapter 16. SAS Controller Registers (SRV/WS SKUs Only)**

[Chapter 16](#) provides a detailed description of all registers that reside in the SAS controller. The controllers resides at Bus X, Device 0, Functions 0 (BX:D0:F0).

### **Chapter 17. EHCI Controller Registers**

[Chapter 17](#) provides a detailed description of all registers that reside in the two EHCI host controllers. These controllers reside at Device 29, Function 7 (D29:F7) and Device 26, Function 7 (D26:F7).

### **Chapter 18. Intel® High Definition Audio Controller Registers**

[Chapter 18](#) provides a detailed description of all registers that reside in the Intel® High Definition Audio (Intel® HD Audio) controller. This controller resides at Device 27, Function 0 (D27:F0).

### **Chapter 19. SMBus Controller Registers**

[Chapter 19](#) provides a detailed description of all registers that reside in the SMBus controller. This controller resides at Device 31, Function 3 (D31:F3).

### **Chapter 20. PCI Express\* Port Controller Registers**

[Chapter 20](#) provides a detailed description of all registers that reside in the PCI Express\* controller. This controller resides at Device 28, Functions 0 to 5 (D30:F0-F5).

### **Chapter 21. High Precision Event Timers Registers**

[Chapter 21](#) provides a detailed description of all registers that reside in the multimedia timer memory mapped register space.

### **Chapter 22. Serial Peripheral Interface Registers**

[Chapter 22](#) provides a detailed description of all registers that reside in the SPI memory mapped register space.

### **Chapter 23. Thermal Sensors**

[Chapter 23](#) provides a detailed description of all registers that reside in the thermal sensors PCI configuration space. The registers reside at Device 31, Function 6 (D31:F6).

**Chapter 24. Intel® Management Engine (Intel® ME)**

Chapter 24 provides a detailed description of all registers that reside in the thermal sensors PCI configuration space. The registers reside at Device 31, Function 6 (D31:F6).

**Chapter 25. Upstream PCIe\* Interface Registers (Intel® C606, C608 Chipset SKUs Only)**

Chapter 25 provides a detailed description of all registers that reside in the upstream PCI Express\* controller. This controller resides at Bus N, Device 0, Function 0 (BN:DO:F0).

**Chapter 26. PCIe Virtual Root/Switch Port Interface Registers (SRV/WS SKUs Only)**

Chapter 26 provides a detailed description of all registers that reside in the virtual Root port (for Intel C602, C602J, C604 Chipset SKUs) or virtual switch port (for Intel C606, C608 Chipset SKUs) of PCI Express\* controller. For virtual root port, this controller resides at Device 17, Function 0 (D17:F0). For virtual switch port, this controller resides at Bus N+1, Device 8, Function 0 (BN+1:D8:F0).

**Chapter 27. IDF SMBus Controller Registers (SRV/WS SKUs Only)**

Chapter 27 provides a detailed description of all registers that reside in the SMBus controllers that associated with SAS controller. These controllers reside at Bus X, Device 0, Function 3, 4, 5 (BX:DO:F3/F4/F5).

## 1.2 Overview

The PCH provides extensive I/O support. Functions and capabilities include:

- *PCI Express\* Base Specification*, Revision 2.0 support for up to eight ports with transfers up to 5 GT/s.
- PCI Express\* Uplink. (Available on specific SKUs Only)
- *PCI Local Bus Specification*, Revision 2.3 support for 33 MHz PCI operations (supports up to four Req/Gnt pairs).
- ACPI Power Management Logic Support, Revision 4.0a
- Enhanced DMA controller, interrupt controller, and timer functions
- Integrated Serial Attached SCSI host controllers at transfer rate up to 3 Gb/s on up to eight ports. (Available on specific SKUs Only)
- Integrated Serial ATA host controllers with independent DMA operation on up to six ports.
- USB host interface with two EHCI high-speed USB 2.0 Host controllers and 2 rate matching hubs provide support for support for up to fourteen USB 2.0 ports
- Integrated 10/100/1000 Gigabit Ethernet MAC with System Defense
- *System Management Bus (SMBus) Specification*, Version 2.0 with additional support for I<sup>2</sup>C\* devices
- Supports Intel® High Definition Audio
- Supports Intel® Rapid Storage Technology enterprise (Intel® RSTe)
- Supports Intel® Active Management Technology (Intel® AMT). (Available on specific SKUs Only)
- Supports Intel® Virtualization Technology for Directed I/O (Intel® VT-d). (Available on specific SKUs Only)
- Supports Intel® Trusted Execution Technology (Intel® TXT)
- Low Pin Count (LPC) interface
- Firmware Hub (FWH) interface support
- Serial Peripheral Interface (SPI) support
- Intel® Anti-Theft Technology (Intel® AT)
- JTAG Boundary Scan support



The PCH incorporates a variety of PCI devices and functions. Refer to [Table 9-1](#) for details.

## 1.2.1 Capability Overview

The following sub-sections provide an overview of the PCH capabilities.

### Digital Media Interface (DMI)

Digital Media Interface (DMI) is the chip-to-chip connection between the processor and PCH. This high-speed interface integrates advanced priority-based servicing allowing for concurrent traffic and true isochronous transfer capabilities. Base functionality is completely software-transparent, permitting current and legacy software to operate normally.

### PCI Express\* Root Port

The PCH provides up to 8 PCI Express\* Root Ports, supporting the *PCI Express Base Specification*, Revision 2.0. Each Root Port x1 lane supports up to 5 Gb/s bandwidth in each direction (10 Gb/s concurrent). PCI Express\* Root Ports 1-4 or Ports 5-8 can independently be configured to support four x1s, two x2s, one x2 and two x1s, or one x4 port widths.

**Note:** Access Control Services (ACS)/Alternative Routing ID (ARI) are not supported on the PCI Express\* Root Port of the Intel® C600 series chipset, devices connected to these ports may not support direct assignment or Single Root I/O Virtualization (SR-IOV).

### PCI Express\* Uplink (Available on specific SKUs Only)

The PCI Express\* Uplink here is an amalgam of two functions, and Uplink port connecting to a PCI Express\* bus, and a virtual switch connecting the Uplink port to the MFD below. The MFD contains the SAS controllers, and SMBus controllers. The uplink can run at 5.0 Gt/s and 2.5 Gt/s, at x4, x2 and x1 configurations. However, because the PCI Express\* uplink will be connected to Intel(R) components, no 3rd party devices, the expected/supported configuration is simply x4 as 1.0.

**Note:** PCI Express\* Uplink is only available on specific PCH SKUs. See [Section 1.3](#) for details on SKU feature availability.

### Serial Attached SCSI (SAS)/SATA Controller (SAS Available on specific SKUs Only)

The PCH supports upto 8 SAS ports that are compliant with *SAS 2.0 Specification* and all ports support rates up to 3.0 Gb/s. All 8 ports are also independently configurable and compliant with SATA Gen2 and support data transfer rates of up to 3.0 Gb/s.

**Note:** SAS/SATA controller is only available on specific PCH SKUs. Certain SKUs are also limited to support 4 of 8 SAS/SATA ports only. See [Section 1.3](#) for details on SKU feature availability.

### Serial ATA (SATA) Controller

The PCH has two integrated SATA host controllers that support independent DMA operation on up to six ports and supports data transfer rates of up to 6.0 Gb/s (600 MB/s) on up to two ports (Port 0 and 1 Only) while all ports support rates up to 3.0 Gb/s (300 MB/s) and up to 1.5 Gb/s (150 MB/s). The SATA controller contains two modes of operation – a legacy mode using I/O space, and an AHCI mode using memory space. Software that uses legacy mode will not have AHCI capabilities.



The PCH supports the *Serial ATA Specification*, Revision 3.0. The PCH also supports several optional sections of the Serial ATA II: Extensions to *Serial ATA 1.0 Specification*, Revision 1.0 (AHCI support is required for some elements).

## AHCI

The PCH provides hardware support for Advanced Host Controller Interface (AHCI), a standardized programming interface for SATA host controllers. Platforms supporting AHCI may take advantage of performance features such as no master/slave designation for SATA devices—each device is treated as a master—and hardware-assisted native command queuing. AHCI also provides usability enhancements such as Hot-Plug. AHCI requires appropriate software support (for example, an AHCI driver) and for some features, hardware support in the SATA device or additional platform hardware.

## Intel® Rapid Storage Technology enterprise (Intel® RSTe)

The PCH provides support for Intel® Rapid Storage Technology enterprise, providing both AHCI (see above for details on AHCI) and integrated RAID functionality. The industry-leading RAID capability provides high-performance RAID 0, 1, 5, and 10 functionality on up to 6 SATA ports of the PCH. Matrix RAID support is provided to allow multiple RAID levels to be combined on a single set of hard drives, such as RAID 0 and RAID 1 on two disks. Other RAID features include hot-spare support, SMART alerting, and RAID 0 auto replace. Software components include an Option ROM for pre-boot configuration and boot functionality, a Microsoft Windows\* compatible driver, and a user interface for configuration and management of the RAID capability of the PCH. Please see [Section 1.3](#) for details on SKU feature availability.

## PCI Interface

The PCH PCI interface provides a 33 MHz, Revision 2.3 implementation. The PCH integrates a PCI arbiter that supports up to four external PCI bus masters in addition to the internal PCH requests. This allows for combinations of up to four PCI down devices and PCI slots.

## Low Pin Count (LPC) Interface

The PCH implements an LPC Interface as described in the *LPC 1.1 Specification*. The Low Pin Count (LPC) bridge function of the PCH resides in PCI Device 31:Function 0. In addition to the LPC bridge interface function, D31:F0 contains other functional units including DMA, interrupt controllers, timers, power management, system management, GPIO, and RTC.

## Serial Peripheral Interface (SPI)

The PCH provides an SPI Interface and is required to be used on the platform in order to provide chipset configuration settings and Intel® Management Engine (Intel® ME) firmware. If integrated Gigabit Ethernet MAC/PHY is implemented on the platform, the interface is used for this device configuration settings. The interface may also be used as the interface for the BIOS flash device or alternatively a FWH on LPC may be used. The PCH supports up to two SPI flash devices using two chip select pins with speeds up to 50 MHz.

## Compatibility Modules (DMA Controller, Timer/Counters, Interrupt Controller)

The DMA controller incorporates the logic of two 8237 DMA controllers, with seven independently programmable channels. Channels 0–3 are hardwired to 8-bit, count-by-byte transfers, and channels 5–7 are hardwired to 16-bit, count-by-word transfers. Any two of the seven DMA channels can be programmed to support fast Type-F transfers. Channel 4 is reserved as a generic bus master request.



The PCH supports LPC DMA, which is similar to ISA DMA, through the PCH's DMA controller. LPC DMA is handled through the use of the LDRQ# lines from peripherals and special encoding on LAD[3:0] from the host. Single, Demand, Verify, and Increment modes are supported on the LPC interface.

The timer/counter block contains three counters that are equivalent in function to those found in one 8254 programmable interval timer. These three counters are combined to provide the system timer function, and speaker tone. The 14.31818 MHz oscillator input provides the clock source for these three counters.

The PCHPCH provides an ISA-Compatible Programmable Interrupt Controller (PIC) that incorporates the functionality of two, 8259 interrupt controllers. The two interrupt controllers are cascaded so that 14 external and two internal interrupts are possible. In addition, the PCH supports a serial interrupt scheme.

All of the registers in these modules can be read and restored. This is required to save and restore system state after power has been removed and restored to the platform.

### **Advanced Programmable Interrupt Controller (APIC)**

In addition to the standard ISA compatible Programmable Interrupt controller (PIC) described in the previous section, the PCH incorporates the Advanced Programmable Interrupt Controller (APIC).

### **Universal Serial Bus (USB) Controllers**

The PCH has up to two Enhanced Host Controller Interface (EHCI) host controllers that support USB high-speed signaling. High-speed USB 2.0 allows data transfers up to 480 Mb/s which is 40 times faster than full-speed USB. The PCH supports up to fourteen USB 2.0 ports. All fourteen ports are high-speed, full-speed, and low-speed capable.

### **Gigabit Ethernet Controller**

The Gigabit Ethernet Controller provides a system interface using a PCI function. The controller provides a full memory-mapped or IO mapped interface along with a 64-bit address master support for systems using more than 4 GB of physical memory and DMA (Direct Memory Addressing) mechanisms for high performance data transfers. Its bus master capabilities enable the component to process high-level commands and perform multiple operations; this lowers processor utilization by off-loading communication tasks from the processor. Two large configurable transmit and receive FIFOs (up to 20 KB each) help prevent data underruns and overruns while waiting for bus accesses. This enables the integrated LAN controller to transmit data with minimum interframe spacing (IFS).

The LAN controller can operate at multiple speeds (10/100/1000 MB/s) and in either full duplex or half duplex mode. In full duplex mode the LAN controller adheres with the *IEEE 802.3x Flow Control* Specification. Half duplex performance is enhanced by a proprietary collision reduction mechanism. See [Section 5.4](#) for details.

### **RTC**

The PCH contains a Motorola MC146818B-compatible real-time clock with 256 bytes of battery-backed RAM. The real-time clock performs two key functions: keeping track of the time of day and storing system data, even when the system is powered down. The RTC operates on a 32.768 KHz crystal and a 3 V battery.

The RTC also supports two lockable memory ranges. By setting bits in the configuration space, two 8-byte ranges can be locked to read and write accesses. This prevents unauthorized reading of passwords or other system security information.



The RTC also supports a date alarm that allows for scheduling a wake up event up to 30 days in advance, rather than just 24 hours in advance.

## GPIO

Various general purpose inputs and outputs are provided for custom system design. The number of inputs and outputs varies depending on the PCH configuration.

## Enhanced Power Management

The PCH's power management functions include enhanced clock control and various low-power (suspend) states (for example, Suspend-to-RAM and Suspend-to-Disk). A hardware-based thermal management circuit permits software-independent entrance to low-power states. The PCH contains full support for the *Advanced Configuration and Power Interface (ACPI) Specification*, Revision 4.0a.

## Intel® Active Management Technology (Intel® AMT) (Available on specific SKUs Only)

Intel® AMT is a fundamental component of Intel® vPro™ technology. Intel® AMT is a set of advanced manageability features developed as a direct result of IT customer feedback gained through Intel market research. With the advent of powerful tools like the Intel® System Defense Utility, the extensive feature set of Intel® AMT easily integrates into any network environment. See [Section 1.3](#) for details on SKU feature availability.

## Manageability

In addition to Intel® AMT the PCH integrates several functions designed to manage the system and lower the total cost of ownership (TCO) of the system. These system management functions are designed to report errors, diagnose the system, and recover from system lockups without the aid of an external microcontroller.

- **TCO Timer.** The PCH's integrated programmable TCO timer is used to detect system locks. The first expiration of the timer generates an SMI# that the system can use to recover from a software lock. The second expiration of the timer causes a system reset to recover from a hardware lock.
- **Processor Present Indicator.** The PCH looks for the processor to fetch the first instruction after reset. If the processor does not fetch the first instruction, the PCH will reboot the system.
- **ECC Error Reporting.** When detecting an ECC error, the host controller has the ability to send one of several messages to the PCH. The host controller can instruct the PCH to generate either an SMI#, NMI, SERR#, or TCO interrupt.
- **Function Disable.** Function Disable. The PCH provides the ability to disable most integrated functions, including integrated LAN, USB, LPC, Intel HD Audio, SATA, PCI Express, and SMBus. Once disabled, functions no longer decode I/O, memory, or PCI configuration space. Also, no interrupts or power management events are generated from the disabled functions.
- **Intruder Detect.** The PCH provides an input signal (INTRUDER#) that can be attached to a switch that is activated by the system case being opened. The PCH can be programmed to generate an SMI# or TCO interrupt due to an active INTRUDER# signal.



## System Management Bus (SMBus 2.0)

The PCH contains an SMBus Host interface that allows the processor to communicate with SMBus slaves. This interface is compatible with most I<sup>2</sup>C devices. Special I<sup>2</sup>C commands are implemented.

The PCH's SMBus host controller provides a mechanism for the processor to initiate communications with SMBus peripherals (slaves). Also, the PCH supports slave functionality, including the Host Notify protocol. Hence, the host controller supports eight command protocols of the SMBus interface (see *System Management Bus (SMBus) Specification, Version 2.0*): Quick Command, Send Byte, Receive Byte, Write Byte/Word, Read Byte/Word, Process Call, Block Read/Write, and Host Notify.

The PCH's SMBus also implements hardware-based Packet Error Checking for data robustness and the Address Resolution Protocol (ARP) to dynamically provide address to all SMBus devices.

## Intel® HD Audio Controller

The *Intel® High Definition Audio Specification* defines a digital interface that can be used to attach different types of codecs, such as audio and modem codecs. The PCH Intel® HD Audio controller supports up to 4 codecs. The link can operate at either 3.3 V or 1.5 V.

With the support of multi-channel audio stream, 32-bit sample depth, and sample rate up to 192 kHz, the Intel® HD Audio controller provides audio quality that can deliver CE levels of audio experience. On the input side, the PCH adds support for an array of microphones.

## Fan Speed Control

The PCH integrates four fan speed sensors (four TACH signals) and four fan speed controllers (three Pulse Width Modulator signals), which enables monitoring and controlling up to four fans on the system. With the new implementation of the single-wire Simple Serial Transport (SST) 1.0 bus and Platform Environmental Control Interface (PECI), the PCH provides an easy way to connect to SST-based thermal sensors and access the processor thermal data.

## Intel® Virtualization Technology for Directed I/O (Intel® VT-d) (Not available on HEDT SKU)

The PCH provides hardware support for implementation of Intel® Virtualization Technology with Directed I/O (Intel® VT-d). Intel® VT-d consists of technology components that support the virtualization of platforms based on Intel® Architecture Processors. Intel® VT-d 5 technology enables multiple operating systems and applications to run in independent partitions. A partition behaves like a virtual machine (VM) and provides isolation and protection across partitions. Each partition is allocated its own subset of host physical memory.

## JTAG Boundary-Scan

The PCH adds the industry standard JTAG interface and enables Boundary-Scan in place of the XOR chains used in previous generations of chipsets. Boundary-Scan can be used to ensure device connectivity during the board manufacturing process. The JTAG interface allows system manufacturers to improve efficiency by using industry available tools to test the PCH on an assembled board. Since JTAG is a serial interface, it eliminates the need to create probe points for every pin in an XOR chain. This eases pin breakout and trace routing and simplifies the interface between the system and a bed-of-nails tester.

**Note:** Contact your local Intel Field Sales Representative for additional information about JTAG usage on the PCH.



**Serial Over Lan (SOL) Function (Not available on HEDTSKU)**

This function supports redirection of keyboard and text screens to a terminal window on a remote console. The keyboard and text redirection enables the control of the client machine through the network without the need to be physically near that machine. Text and keyboard redirection allows the remote machine to control and configure a client system. The SOL function emulates a standard PCI device and redirects the data from the serial port to the management console using the integrated LAN.

**IDE-R Function (Not available on HEDT SKU)**

The IDE-R function is an IDE Redirection interface that provides client connection to management device attached through IDE-R is only visible to software during a management boot session. During normal boot session, the IDE-R controller does not appear as a PCI present device.

### 1.3 Intel® C600 Series Chipset and Intel® X79 Express Chipset SKU Definition

**Table 1-2. Intel® C600 Series Chipset and Intel® X79 Express Chipset SKUs**

Product Number	SATA 6G Ports (#)	SCU Ports (#)	PCIe* Uplink	SM Bus	Intel® AMT	Intel® VT-D
<b>Intel® C600 Series Chipset (Server/Workstation)</b>						
C602	2	4 (SATA only)	No	4	Yes	Yes
C602J	2	0	No	4	Yes	Yes
C604	2	4	No	4	Yes	Yes
C606	2	8	Yes	5	Yes	Yes
C608	2	8	Yes	6	Yes	Yes
<b>Intel® X79 Express Chipset (High End Desktop)</b>						
X79	2	No	No	3	No	No

**Notes:**

1. Contact your local Intel Field Sales Representative for currently available Intel C600 Series Chipset and Intel X79 Express Chipset SKUs.
2. Table above shows feature difference between Intel C600 Series Chipset and Intel X79 Express Chipset SKUs. If a feature is not listed in the table it is considered a Base feature that is included in all SKUs.





## 2 Signal Description

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This chapter provides a detailed description of each signal. The signals are arranged in functional groups according to their associated interface.

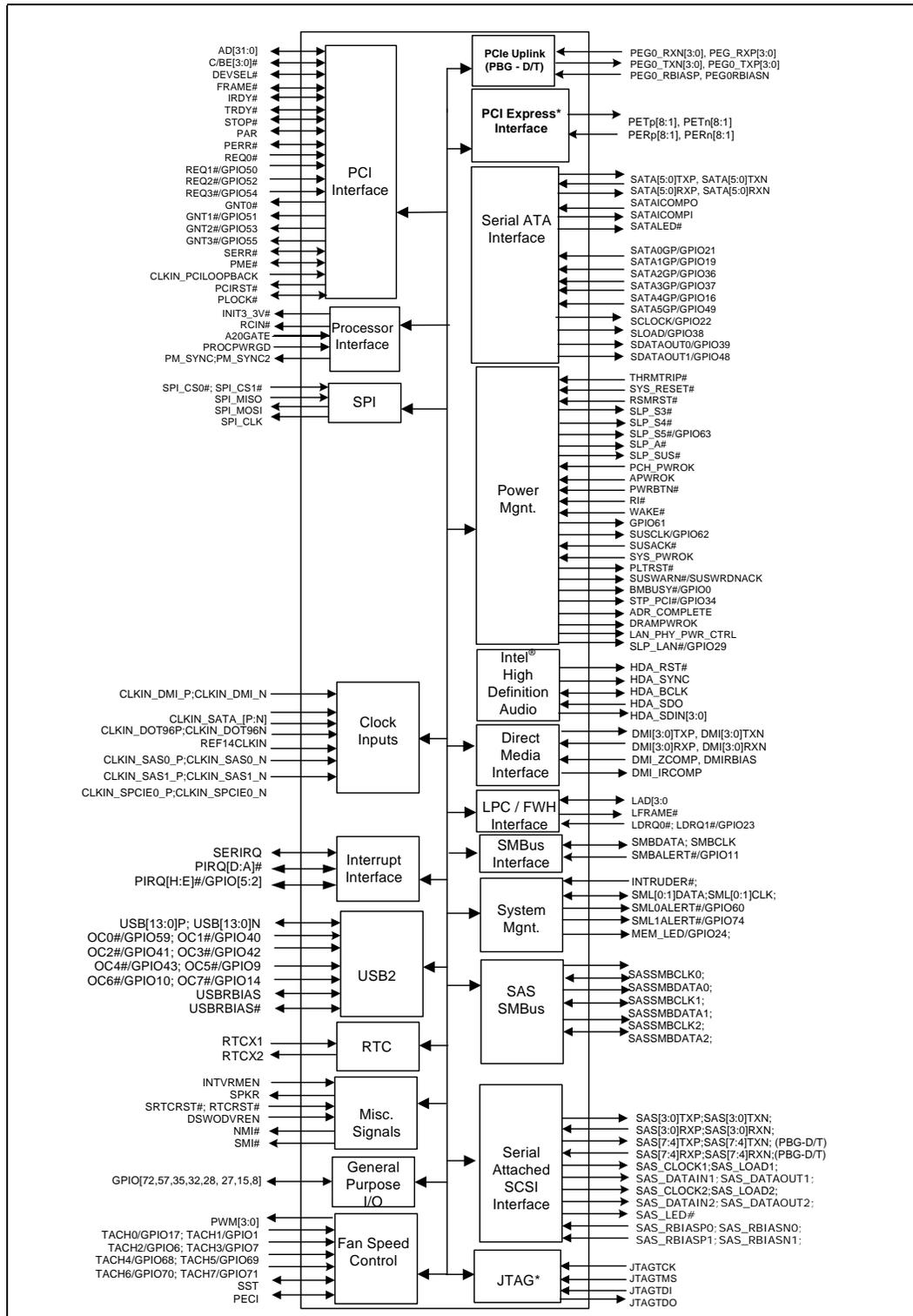
The “#” symbol at the end of the signal name indicates that the active, or asserted state occurs when the signal is at a low voltage level. When “#” is not present, the signal is asserted when at the high voltage level.

The following notations are used to describe the signal type:

<b>I</b>	Input Pin
<b>O</b>	Output Pin
<b>OD O</b>	Open Drain Output Pin.
<b>I/OD</b>	Bi-directional Input/Open Drain Output Pin.
<b>I/O</b>	Bi-directional Input / Output Pin.
<b>CMOS</b>	CMOS buffers. 1.5 V tolerant.
<b>COD</b>	CMOS Open Drain buffers. 3.3 V tolerant.
<b>HVCMOS</b>	High Voltage CMOS buffers. 3.3 V tolerant.
<b>A</b>	Analog reference or output.

The “Type” for each signal is indicative of the functional operating mode of the signal. Unless otherwise noted [Section 3.2](#) or [Section 3.3](#), a signal is considered to be in the functional operating mode after RTCRST# deasserts for signals in the RTC well, after RSMRST# deasserts for signals in the suspend well, and after PCH\_PWROK asserts for signals in the core well, after DPWROK asserts for Signals in the Deep Sleep well, after APWROK asserts for Signals in the Active Sleep well.

Figure 2-1. PCH Interface Signals Block Diagram





## 2.1 Direct Media Interface (DMI) to Host Controller

Table 2-1. Direct Media Interface Signals

Name	Type	Description
DMI_TXP_0, DMI_TXN_0	O	Direct Media Interface Differential Transmit Pair 0
DMI_RXP_0, DMI_RXN_0	I	Direct Media Interface Differential Receive Pair 0
DMI_TXP_1, DMI_TXN_1	O	Direct Media Interface Differential Transmit Pair 1
DMI_RXP_1, DMI_RXN_1	I	Direct Media Interface Differential Receive Pair 1
DMI_TXP_2, DMI_TXN_2	O	Direct Media Interface Differential Transmit Pair 2
DMI_RXP_2, DMI_RXN_2	I	Direct Media Interface Differential Receive Pair 2
DMI_TXP_3, DMI_TXN_3	O	Direct Media Interface Differential Transmit Pair 3
DMI_RXP_3, DMI_RXN_3	I	Direct Media Interface Differential Receive Pair 3
DMI_ZCOMP	I	<b>Impedance Compensation Input:</b> Determines DMI input impedance.
DMI_IRCOMP	O	<b>Impedance/Current Compensation Output:</b> Determines DMI output impedance and bias current.
DMIRBIAS	I/O	<b>DMIRBIAS:</b> Analog connection point for 750 $\Omega$ $\pm$ 1% external precision resistor

## 2.2 PCI Express\*

Table 2-2. PCI Express\* Signals

Name	Type	Description
PETp1, PETn1	O	PCI Express* Differential Transmit Pair 1
PERp1, PERn1	I	PCI Express Differential Receive Pair 1
PETp2, PETn2	O	PCI Express Differential Transmit Pair 2
PERp2, PERn2	I	PCI Express Differential Receive Pair 2
PETp3, PETn3	O	PCI Express Differential Transmit Pair 3
PERp3, PERn3	I	PCI Express Differential Receive Pair 3
PETp4, PETn4	O	PCI Express Differential Transmit Pair 4
PERp4, PERn4	I	PCI Express Differential Receive Pair 4
PETp5, PETn5	O	PCI Express Differential Transmit Pair 5
PERp5, PERn5	I	PCI Express Differential Receive Pair 5
PETp6, PETn6	O	PCI Express Differential Transmit Pair 6
PERp6, PERn6	I	PCI Express Differential Receive Pair 6
PETp7, PETn7	O	PCI Express Differential Transmit Pair 7
PERp7, PERn7	I	PCI Express Differential Receive Pair 7
PETp8, PETn8	O	PCI Express Differential Transmit Pair 8
PERp8, PERn8	I	PCI Express Differential Receive Pair 8



## 2.3 PCI Express\* Uplink (Intel® C606, C608 Chipset SKUs Only)

**Note:** These signals are not used on the HEDT SKU PCH and should be no connects.

**Table 2-3. PCI Express\* Uplink Signals**

Name	Type	Description
PEGO_Tp[3:0], PEGO_Tn[3:0]	O	PCI Express* Uplink Differential Transmit Pairs
PEGO_Rp[3:0], PEGO_Rn[3:0]	I	PCI Express* Uplink Differential Receive Pairs
PEGO_RBIASP, PEGO_RBIASN	I	Analog connection points for an external resistor. Used to set transmit currents and internal load resistors

## 2.4 PCI Interface

**Table 2-4. PCI Interface Signals (Sheet 1 of 3)**

Name	Type	Description																								
AD[31:0]	I/O	<b>PCI Address/Data:</b> AD[31:0] is a multiplexed address and data bus. During the first clock of a transaction, AD[31:0] contain a physical address (32 bits). During subsequent clocks, AD[31:0] contain data. The PCH will drive all 0s on AD[31:0] during the address phase of all PCI Special Cycles.																								
C/BE[3:0]#	I/O	<p><b>Bus Command and Byte Enables:</b> The command and byte enable signals are multiplexed on the same PCI pins. During the address phase of a transaction, C/BE[3:0]# define the bus command. During the data phase C/BE[3:0]# define the Byte Enables.</p> <table border="1"> <thead> <tr> <th>C/BE[3:0]#</th> <th>Command Type</th> </tr> </thead> <tbody> <tr> <td>0000b</td> <td>Interrupt Acknowledge</td> </tr> <tr> <td>0001b</td> <td>Special Cycle</td> </tr> <tr> <td>0010b</td> <td>I/O Read</td> </tr> <tr> <td>0011b</td> <td>I/O Write</td> </tr> <tr> <td>0110b</td> <td>Memory Read</td> </tr> <tr> <td>0111b</td> <td>Memory Write</td> </tr> <tr> <td>1010b</td> <td>Configuration Read</td> </tr> <tr> <td>1011b</td> <td>Configuration Write</td> </tr> <tr> <td>1100b</td> <td>Memory Read Multiple</td> </tr> <tr> <td>1110b</td> <td>Memory Read Line</td> </tr> <tr> <td>1111b</td> <td>Memory Write and Invalidate</td> </tr> </tbody> </table> <p>All command encodings not shown are reserved. The PCH does not decode reserved values, and therefore will not respond if a PCI master generates a cycle using one of the reserved values.</p>	C/BE[3:0]#	Command Type	0000b	Interrupt Acknowledge	0001b	Special Cycle	0010b	I/O Read	0011b	I/O Write	0110b	Memory Read	0111b	Memory Write	1010b	Configuration Read	1011b	Configuration Write	1100b	Memory Read Multiple	1110b	Memory Read Line	1111b	Memory Write and Invalidate
C/BE[3:0]#	Command Type																									
0000b	Interrupt Acknowledge																									
0001b	Special Cycle																									
0010b	I/O Read																									
0011b	I/O Write																									
0110b	Memory Read																									
0111b	Memory Write																									
1010b	Configuration Read																									
1011b	Configuration Write																									
1100b	Memory Read Multiple																									
1110b	Memory Read Line																									
1111b	Memory Write and Invalidate																									
DEVSEL#	I/O	<b>Device Select:</b> The PCH asserts DEVSEL# to claim a PCI transaction. As an output, the PCH asserts DEVSEL# when a PCI master peripheral attempts an access to an internal PCH address or an address destined for DMI (main memory or graphics). As an input, DEVSEL# indicates the response to a PCH-initiated transaction on the PCI bus. DEVSEL# is tri-stated from the leading edge of PLTRST#. DEVSEL# remains tri-stated by the PCH until driven by a target device.																								
FRAME#	I/O	<b>Cycle Frame:</b> The current initiator drives FRAME# to indicate the beginning and duration of a PCI transaction. While the initiator asserts FRAME#, data transfers continue. When the initiator negates FRAME#, the transaction is in the final data phase. FRAME# is an input to the PCH when the PCH is the target, and FRAME# is an output from the PCH when the PCH is the initiator. FRAME# remains tri-stated by the PCH until driven by an initiator.																								



Table 2-4. PCI Interface Signals (Sheet 2 of 3)

Name	Type	Description
<b>IRDY#</b>	I/O	<b>Initiator Ready:</b> IRDY# indicates the PCH's ability, as an initiator, to complete the current data phase of the transaction. It is used in conjunction with TRDY#. A data phase is completed on any clock both IRDY# and TRDY# are sampled asserted. During a write, IRDY# indicates the PCH has valid data present on AD[31:0]. During a read, it indicates the PCH is prepared to latch data. IRDY# is an input to the PCH when the PCH is the target and an output from the PCH when the PCH is an initiator. IRDY# remains tri-stated by the PCH until driven by an initiator.
<b>TRDY#</b>	I/O	<b>Target Ready:</b> TRDY# indicates the PCH's ability as a target to complete the current data phase of the transaction. TRDY# is used in conjunction with IRDY#. A data phase is completed when both TRDY# and IRDY# are sampled asserted. During a read, TRDY# indicates that the PCH, as a target, has placed valid data on AD[31:0]. During a write, TRDY# indicates the PCH, as a target is prepared to latch data. TRDY# is an input to the PCH when the PCH is the initiator and an output from the PCH when the PCH is a target. TRDY# is tri-stated from the leading edge of PLTRST#. TRDY# remains tri-stated by the PCH until driven by a target.
<b>STOP#</b>	I/O	<b>Stop:</b> STOP# indicates that the PCH, as a target, is requesting the initiator to stop the current transaction. STOP# causes the PCH, as an initiator, to stop the current transaction. STOP# is an output when the PCH is a target and an input when the PCH is an initiator.
<b>PAR</b>	I/O	<b>Calculated/Checked Parity:</b> PAR uses "even" parity calculated on 36 bits, AD[31:0] plus C/BE[3:0]#. "Even" parity means that the PCH counts the number of ones within the 36 bits plus PAR and the sum is always even. The PCH always calculates PAR on 36 bits regardless of the valid byte enables. The PCH generates PAR for address and data phases and only ensures PAR to be valid one PCI clock after the corresponding address or data phase. The PCH drives and tri-states PAR identically to the AD[31:0] lines except that the PCH delays PAR by exactly one PCI clock. PAR is an output during the address phase (delayed one clock) for all PCH initiated transactions. PAR is an output during the data phase (delayed one clock) when the PCH is the initiator of a PCI write transaction, and when it is the target of a read transaction. PCH checks parity when it is the target of a PCI write transaction. If a parity error is detected, the PCH will set the appropriate internal status bits, and has the option to generate an NMI# or SMI#.
<b>PERR#</b>	I/O	<b>Parity Error:</b> An external PCI device drives PERR# when it receives data that has a parity error. The PCH drives PERR# when it detects a parity error. The PCH can either generate an NMI# or SMI# upon detecting a parity error (either detected internally or reported using the PERR# signal).
<b>REQ0#</b> <b>REQ1#</b> / GPIO50 / GSXCLK <b>REQ2#</b> / GPIO52 / GSXSLOAD <b>REQ3#</b> /GPIO54 / GSXRESET#	I	<b>PCI Requests:</b> The PCH supports up to 4 masters on the PCI bus. REQ[3:1]# pins can instead be used as GPIO. REQ[3:1]# pins can also be use as GSX signals. (See <a href="#">Section 2.23</a> for details.) <b>Notes:</b> External pull-up resistor is required. When used as native functionality, the pull-up resistor may be to either 3.3 V or 5.0 V per PCI specification. When used as GPIO or not used at all, the pull-up resistor should be to the Vcc3_3 rail
<b>GNT0#</b> <b>GNT1#</b> / GPIO51 / GSXDOUT <b>GNT2#</b> / GPIO53 / GSXDIN <b>GNT3#</b> /GPIO55	O	<b>PCI Grants:</b> The PCH supports up to 4 masters on the PCI bus. GNT[3:1]# pins can instead be used as GPIO. GNT[2:1]# pins can also be use as GSX signals. (See <a href="#">Section 2.23</a> for details.) Pull-up resistors are not required on these signals. If pull-ups are used, they should be tied to the Vcc3_3 power rail. <b>Note:</b> GNT[3:1]#/GPIO[55,53,51] are sampled as a functional strap. See <a href="#">Section 2.26.1</a> for details.
<b>PCIRST#</b>	O	<b>PCI Reset:</b> This is the Secondary PCI Bus reset signal. It is a logical OR of the primary interface PLTRST# signal and the state of the Secondary Bus Reset bit of the Bridge Control register (D30:F0:3Eh, bit 6).
<b>PLOCK#</b>	I/O	<b>PCI Lock:</b> This signal indicates an exclusive bus operation and may require multiple transactions to complete. PCH asserts PLOCK# when it performs non-exclusive transactions on the PCI bus. PLOCK# is ignored when PCI masters are granted the bus.
<b>SERR#</b>	I/OD	<b>System Error:</b> SERR# can be pulsed active by any PCI device that detects a system error condition. Upon sampling SERR# active, the PCH has the ability to generate an NMI, SMI#, or interrupt.



Table 2-4. PCI Interface Signals (Sheet 3 of 3)

Name	Type	Description
PME#	I/OD	<b>PCI Power Management Event:</b> PCI peripherals drive PME# to wake the system from low-power states S1–S5. PME# assertion can also be enabled to generate an SCI from the S0 state. In some cases the PCH may drive PME# active due to an internal wake event. The PCH will not drive PME# high, but it will be pulled up to VccSus3_3 by an internal pull-up resistor.

## 2.5 Serial ATA Interface

Table 2-5. Serial ATA Interface Signals (Sheet 1 of 2)

Name	Type	Description
SATA0TXP SATA0TXN	O	<b>Serial ATA 0 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 0. In compatible mode, SATA Port 0 is the primary master of SATA Controller 1. Supports up to 6 Gb/s, 3 Gb/s, and 1.5 Gb/s.
SATA0RXP SATA0RXN	I	<b>Serial ATA 0 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 0. In compatible mode, SATA Port 0 is the primary master of SATA Controller 1. Supports up to 6 Gb/s, 3 Gb/s, and 1.5 Gb/s.
SATA1TXP SATA1TXN	O	<b>Serial ATA 1 Differential Transmit Pair:</b> These are outbound high-speed differential signals to Port 1. In compatible mode, SATA Port 1 is the secondary master of SATA Controller 1. Supports up to 6 Gb/s, 3 Gb/s, and 1.5 Gb/s.
SATA1RXP SATA1RXN	I	<b>Serial ATA 1 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 1. In compatible mode, SATA Port 1 is the secondary master of SATA Controller 1. Supports up to 6 Gb/s, 3 Gb/s, and 1.5 Gb/s.
SATA2TXP SATA2TXN	O	<b>Serial ATA 2 Differential Transmit Pair:</b> These are outbound high-speed differential signals to Port 2. In compatible mode, SATA Port 2 is the primary slave of SATA Controller 1. Supports up to 3 Gb/s and 1.5 Gb/s.
SATA2RXP SATA2RXN	I	<b>Serial ATA 2 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 2. In compatible mode, SATA Port 2 is the primary slave of SATA Controller 1. Supports up to 3 Gb/s and 1.5 Gb/s.
SATA3TXP SATA3TXN	O	<b>Serial ATA 3 Differential Transmit Pair:</b> These are outbound high-speed differential signals to Port 3. In compatible mode, SATA Port 3 is the secondary slave of SATA Controller 1. Supports up to 3 Gb/s and 1.5 Gb/s.
SATA3RXP SATA3RXN	I	<b>Serial ATA 3 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 3. In compatible mode, SATA Port 3 is the secondary slave of SATA Controller 1. Supports up to 3 Gb/s and 1.5 Gb/s.
SATA4TXP SATA4TXN	O	<b>Serial ATA 4 Differential Transmit Pair:</b> These are outbound high-speed differential signals to Port 4. In compatible mode, SATA Port 4 is the primary master of SATA Controller 2. Supports up to 3 Gb/s and 1.5 Gb/s.
SATA4RXP SATA4RXN	I	<b>Serial ATA 4 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 4. In compatible mode, SATA Port 4 is the primary master of SATA Controller 2. Supports up to 3 Gb/s and 1.5 Gb/s.
SATA5TXP SATA5TXN	O	<b>Serial ATA 5 Differential Transmit Pair:</b> These are outbound high-speed differential signals to Port 5. In compatible mode, SATA Port 5 is the secondary master of SATA Controller 2. Supports up to 3 Gb/s and 1.5 Gb/s.



Table 2-5. Serial ATA Interface Signals (Sheet 2 of 2)

Name	Type	Description
<b>SATA5RXP</b> <b>SATA5RXN</b>	I	<b>Serial ATA 5 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 5. In compatible mode, SATA Port 5 is the secondary master of SATA Controller 2. Supports up to 3 Gb/s and 1.5 Gb/s.
<b>SATAICOMPO</b>	O	<b>Serial ATA Compensation Output:</b> Connected to an external precision resistor to VccCore. Must be connected to <b>SATAICOMPI</b> on the board.
<b>SATAICOMPI</b>	I	<b>Serial ATA Compensation Input:</b> Connected to <b>SATAICOMPO</b> on the board.
<b>SATA0GP</b> / GPIO21	I	<b>Serial ATA 0 General Purpose:</b> This is an input pin which can be configured as an interlock switch corresponding to SATA Port 0. When used as an interlock switch status indication, this signal should be drive to '0' to indicate that the switch is closed and to '1' to indicate that the switch is open. If interlock switches are not required, this pin can be configured as GPIO21.
<b>SATA1GP</b> / GPIO19	I	<b>Serial ATA 1 General Purpose:</b> Same function as SATA0GP, except for SATA Port 1. If interlock switches are not required, this pin can be configured as GPIO19.
<b>SATA2GP</b> / GPIO36	I	<b>Serial ATA 2 General Purpose:</b> Same function as SATA0GP, except for SATA Port 2. If interlock switches are not required, this pin can be configured as GPIO36.
<b>SATA3GP</b> / GPIO37	I	<b>Serial ATA 3 General Purpose:</b> Same function as SATA0GP, except for SATA Port 3. If interlock switches are not required, this pin can be configured as GPIO37.
<b>SATA4GP</b> / GPIO16	I	<b>Serial ATA 4 General Purpose:</b> Same function as SATA0GP, except for SATA Port 4. If interlock switches are not required, this pin can be configured as GPIO16.
<b>SATA5GP</b> / GPIO49 / TEMP_ALERT#	I	<b>Serial ATA 5 General Purpose:</b> Same function as SATA0GP, except for SATA Port 5. If interlock switches are not required, this pin can be configured as GPIO49 or TEMP_ALERT#.
<b>SATALED#</b>	OD O	<b>Serial ATA LED:</b> This signal is an open-drain output pin driven during SATA command activity. It is to be connected to external circuitry that can provide the current to drive a platform LED. When active, the LED is on. When tri-stated, the LED is off. An external pull-up resistor to Vcc_3 is required.
<b>SCLOCK</b> /GPIO22	OD O	<b>SGPIO Reference Clock:</b> The SATA controller uses rising edges of this clock to transmit serial data, and the target uses the falling edge of this clock to latch data. The SCLOCK frequency supported is 32 kHz. If SGPIO interface is not used, this signal can be used as a GPIO22.
<b>SLOAD</b> /GPIO38	OD O	<b>SGPIO Load:</b> The controller drives a '1' at the rising edge of SCLOCK to indicate either the start or end of a bit stream. A 4-bit vendor specific pattern will be transmitted right after the signal assertion. If SGPIO interface is not used, this signal can be used as a GPIO.
<b>SDATAOUT0</b> / GPIO39 <b>SDATAOUT1</b> / GPIO48	OD O	<b>SGPIO Dataout:</b> Driven by the controller to indicate the drive status in the following sequence: drive 0, 1, 2, 3, 4, 5, 0, 1, 2... If SGPIO interface is not used, the signals can be used as GPIO.
<b>SATA3RBIAS</b>	I/O	<b>DMI RBIAS:</b> Analog connection point for an external precision resistor.
<b>SATA3COMPI</b>	I	<b>Impedance Compensation Input:</b> Connected to a 50 ohm (1%) precision external pull-up resistor to vccsata3.
<b>SATA3COMPO</b>	O	<b>Impedance/Current Compensation Output:</b> Connected to a 50 ohm (1%) precision external pull-up resistor.to vccsata3.



## 2.6 SAS Interface (SRV/WS SKUs Only)

**Note:** These signals are not used on the HEDT SKU.

**Table 2-6. SAS Interface Signals (Sheet 1 of 2)**

Name	Type	Description
<b>SAS0TXP</b> <b>SAS0TXN</b>	O	<b>SAS/SATA 0 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 0. <b>Note:</b> On Intel C602 Chipset SKU, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS0RXP</b> <b>SAS0RXN</b>	I	<b>SAS/SATA 0 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 0. <b>Note:</b> On Intel C602 Chipset, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS1TXP</b> <b>SAS1TXN</b>	O	<b>SAS/SATA 1 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 1. <b>Note:</b> On Intel C602 Chipset, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS1RXP</b> <b>SAS1RXN</b>	I	<b>SAS/SATA 1 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 1. <b>Note:</b> On Intel C602 Chipset, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS2TXP</b> <b>SAS2TXN</b>	O	<b>SAS/SATA 2 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 2. <b>Note:</b> On Intel C602 Chipset, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS2RXP</b> <b>SAS2RXN</b>	I	<b>SAS/SATA 2 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 2. <b>Note:</b> On Intel C602 Chipset, work as SATA only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS3TXP</b> <b>SAS3TXN</b>	O	<b>SAS/SATA 3 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 3. <b>Note:</b> On Intel C602 Chipset, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS3RXP</b> <b>SAS3RXN</b>	I	<b>SAS/SATA 3 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 3. <b>Note:</b> On Intel C602 Chipset, work as SATA port only. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS4TXP</b> <b>SAS4TXN</b> (Intel® C606, C608 Chipset SKUs Only)	O	<b>SAS 4 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 4. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS4RXP</b> <b>SAS4RXN</b> (Intel® C606, C608 Chipset SKUs Only)	I	<b>SAS 4 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 4. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS5TXP</b> <b>SAS5TXN</b> (Intel® C606, C608 Chipset SKUs Only)	O	<b>SAS 5 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 5. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS5RXP</b> <b>SAS5RXN</b> (Intel® C606, C608 Chipset SKUs Only)	I	<b>SAS 5 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 5. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS6TXP</b> <b>SAS6TXN</b> (Intel® C606, C608 Chipset SKUs Only)	O	<b>SAS 6 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 6. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS6RXP</b> <b>SAS6RXN</b> (Intel® C606, C608 Chipset SKUs Only)	I	<b>SAS 6 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 6. <b>Note:</b> On HEDT SKU, these signals should be no connects.



Table 2-6. SAS Interface Signals (Sheet 2 of 2)

Name	Type	Description
<b>SAS7TXP</b> <b>SAS7TXN</b> (Intel® C606, C608 Chipset SKUs Only)	O	<b>SAS 7 Differential Transmit Pairs:</b> These are outbound high-speed differential signals to Port 7. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS7RXP</b> <b>SAS7RXN</b> (Intel® C606, C608 Chipset SKUs Only)	I	<b>SAS 7 Differential Receive Pair:</b> These are inbound high-speed differential signals from Port 7. <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS_CLOCK1</b>	O	<b>SCU SGPIO reference clock</b> <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_LOAD1</b>	O	<b>SCU SGPIO load</b> <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_DATAIN1</b>	O	<b>SCU SGPIO data in</b> <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_DATAOUT1</b>	O	<b>SCU SGPIO data out</b> <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_CLOCK2</b> (Intel® C606, C608 Chipset SKUs Only)	O	Used in Intel® C606, C608 Chipset SKUs Only <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_LOAD2</b> (Intel® C606, C608 Chipset SKUs Only)	O	Used in Intel® C606, C608 Chipset SKUs Only <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_DATAIN2</b> (Intel® C606, C608 Chipset SKUs Only)	O	Used in Intel® C606, C608 Chipset SKUs Only <b>Note:</b> On HEDT SKU, these signals should be no connects.
<b>SAS_DATAOUT2</b> (Intel® C606, C608 Chipset SKUs Only)	O	Used in Intel® C606, C608 Chipset SKUs Only <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_LED#</b>	O	Open drain pin used to control the Front Panel LED. <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_RBIASPO</b>	I	Analog connection points for an external resistor. Used to set transmit internal loads and currents. <b>Notes:</b> On HEDT SKU, this signal tied to SAS_RBIASNO through a 6.0 K $\Omega$ $\pm$ 1% resistor. SAS_RBIASNO should be connected to V <sub>SS</sub> at the resistor.
<b>SAS_RBIASNO</b>	I	Analog connection points for an external resistor. Used to set transmit internal loads and currents. <b>Note:</b> On HEDT SKU, this signal tied to SAS_RBIASNO through a 6.0 K $\Omega$ $\pm$ 1% resistor. SAS_RBIASNO should be connected to V <sub>SS</sub> at the resistor.
<b>SAS_RBIASP1</b> (Intel® C606, C608 Chipset SKUs Only)	I	Analog connection points for an external resistor. Used to set transmit internal loads and currents. <b>Note:</b> On HEDT SKU, this signal should be no connect.
<b>SAS_RBIASN1</b> (Intel® C606, C608 Chipset SKUs Only)	I	Analog connection points for an external resistor. Used to set transmit internal loads and currents. <b>Note:</b> On HEDT SKU, this signal should be no connect.



## 2.7 LPC Interface

Table 2-7. LPC Interface Signals

Name	Type	Description
<b>LAD[3:0]</b>	I/O	<b>LPC Multiplexed Command, Address, Data:</b> For LAD[3:0], internal pull-ups are provided.
<b>LFRAME#</b>	O	<b>LPC Frame:</b> LFRAME# indicates the start of an LPC cycle, or an abort.
<b>LDRQ0#</b> , LDRQ1# / GPIO23	I	<b>LPC Serial DMA/Master Request Inputs:</b> LDRQ[1:0]# are used to request DMA or bus master access. These signals are typically connected to an external Super I/O device. An internal pull-up resistor is provided on these signals. LDRQ1# may optionally be used as GPIO.

## 2.8 Interrupt Interface

Table 2-8. Interrupt Signals

Name	Type	Description
<b>SERIRQ</b>	I/OD	<b>Serial Interrupt Request:</b> This pin implements the serial interrupt protocol.
<b>PIRQ[D:A]#</b>	I/OD	<b>PCI Interrupt Requests:</b> In non-APIC mode the PIRQx# signals can be routed to interrupts 3, 4, 5, 6, 7, 9, 10, 11, 12, 14 or 15 as described in <a href="#">Section 5.9.6</a> . Each PIRQx# line has a separate Route Control register. In APIC mode, these signals are connected to the internal I/O APIC in the following fashion: PIRQA# is connected to IRQ16, PIRQB# to IRQ17, PIRQC# to IRQ18, and PIRQD# to IRQ19. This frees the legacy interrupts. These signals are 5 V tolerant.
<b>PIRQ[H:E]# / GPIO[5:2]</b>	I/OD	<b>PCI Interrupt Requests:</b> In non-APIC mode the PIRQx# signals can be routed to interrupts 3, 4, 5, 6, 7, 9, 10, 11, 12, 14 or 15 as described in <a href="#">Section 5.9.6</a> . Each PIRQx# line has a separate Route Control register. In APIC mode, these signals are connected to the internal I/O APIC in the following fashion: PIRQE# is connected to IRQ20, PIRQF# to IRQ21, PIRQG# to IRQ22, and PIRQH# to IRQ23. This frees the legacy interrupts. If not needed for interrupts, these signals can be used as GPIO. These signals are 5 V tolerant.

**Note:** PIRQ Interrupts can only be shared if it is configured as level sensitive. They cannot be shared if configured as edge triggered.



## 2.9 USB 2.0 Interface

Table 2-9. USB 2.0 Interface Signals (Sheet 1 of 2)

Name	Type	Description
<b>USBP0P, USBP0N, USBP1P, USBP1N</b>	I/O	<b>Universal Serial Bus Port [1:0] Differential:</b> These differential pairs are used to transmit Data/Address/Command signals for ports 0 and 1. These ports can be routed to EHCI controller #1.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.
<b>USBP2P, USBP2N, USBP3P, USBP3N</b>	I/O	<b>Universal Serial Bus Port [3:2] Differential:</b> These differential pairs are used to transmit data/address/command signals for ports 2 and 3. These ports can be routed to EHCI controller #1.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.
<b>USBP4P, USBP4N, USBP5P, USBP5N</b>	I/O	<b>Universal Serial Bus Port [5:4] Differential:</b> These differential pairs are used to transmit Data/Address/Command signals for ports 4 and 5. These ports can be routed to EHCI controller #1.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.
<b>USBP6P, USBP6N, USBP7P, USBP7N</b>	I/O	<b>Universal Serial Bus Port [7:6] Differential:</b> These differential pairs are used to transmit Data/Address/Command signals for ports 6 and 7. These ports can be routed to EHCI controller #1.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.
<b>USBP8P, USBP8N, USBP9P, USBP9N</b>	I/O	<b>Universal Serial Bus Port [9:8] Differential:</b> These differential pairs are used to transmit Data/Address/Command signals for ports 8 and 9. These ports can be routed to EHCI controller #2.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.
<b>USBP10P, USBP10N, USBP11P, USBP11N</b>	I/O	<b>Universal Serial Bus Port [11:10] Differential:</b> These differential pairs are used to transmit Data/Address/Command signals for ports 10 and 11. These ports can be routed to EHCI controller #2.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.
<b>USBP12P, USBP12N, USBP13P, USBP13N</b>	I/O	<b>Universal Serial Bus Port [13:12] Differential:</b> These differential pairs are used to transmit Data/Address/Command signals for ports 13 and 12. These ports can be routed to EHCI controller #2.  <b>Note:</b> No external resistors are required on these signals. The PCH integrates 15 k $\Omega$ pull-downs and provides an output driver impedance of 45 $\Omega$ which requires no external series resistor.

**Table 2-9. USB 2.0 Interface Signals (Sheet 2 of 2)**

Name	Type	Description
<b>OC0#</b> / GPIO59 <b>OC1#</b> / GPIO40 <b>OC2#</b> / GPIO41 <b>OC3#</b> / GPIO42 <b>OC4#</b> / GPIO43 <b>OC5#</b> / GPIO9 <b>OC6#</b> / GPIO10 <b>OC7#</b> / GPIO14	I	<b>Overcurrent Indicators:</b> These signals set corresponding bits in the USB controllers to indicate that an overcurrent condition has occurred. OC[7:0]# may optionally be used as GPIOs.  <b>Notes:</b> <ol style="list-style-type: none"> <li>OC# pins are not 5 V tolerant.</li> <li>OC# pins must be shared between ports</li> <li>OC#[3:0] can only be used for EHCI controller #1</li> <li>OC#[4:7] can only be used for EHCI controller #2</li> </ol>
<b>USBRBIAS</b>	O	<b>USB Resistor Bias:</b> Analog connection point for an external resistor. Used to set transmit currents and internal load resistors.
<b>USBRBIAS#</b>	I	<b>USB Resistor Bias Complement:</b> Analog connection point for an external resistor. Used to set transmit currents and internal load resistors.

## 2.10 Power Management Interface

**Note:** Upon entry to S5 due to a power button override, if Deep S4/S5 is enabled and conditions are met per [Section 5.14.6.6](#), the system will transition to Deep S4/S5.

**Table 2-10. Power Management Interface Signals (Sheet 1 of 3)**

Name	Type	Description
<b>APWROK</b>	I	<b>Active Sleep Well (ASW) Power OK:</b> When asserted, indicates that power to the ASW sub-system is stable.
<b>BMBUSY#</b> / GPIO0	I	<b>Bus Master Busy:</b> Generic bus master activity indication driven into the PCH. Can be configured to set the PM1_STS.BM_STS bit. Can also be configured to assert indications transmitted from the PCH to the Processor using the PM_SYNC pin.
<b>DPWROK</b>	I	<b>DPWROK:</b> Power OK Indication for the VccDSW3_3 voltage rail. This input is tied together with RSMRST# on platforms that do not support Deep S4/S5. This signal is in the RTC well.
<b>DRAMPWROK</b>	OD O	<b>DRAM Power OK:</b> This signal should connect to the Processor's SM_DRAMPWROK pin. The PCH asserts this pin to indicate when DRAM power is stable. This pin requires an external pull-up.
<b>LAN_PHY_PWR_CTRL</b> / GPIO12	O	<b>LAN PHY Power Control:</b> LAN_PHY_PWR_CTRL should be connected to LAN_DISABLE_N on the PHY. The PCH will drive LAN_PHY_PWR_CTRL low to put the PHY into a low power state when functionality is not needed.  <b>Note:</b> LAN_PHY_PWR_CTRL can only be driven low if SLP_LAN# is deasserted. Signal can instead be used as GPIO12.
<b>PLTRST#</b>	O	<b>Platform Reset:</b> The PCH asserts PLTRST# to reset devices on the platform (for example, SIO, FWH, LAN, Processor, etc.). The PCH asserts PLTRST# during power-up and when S/W initiates a hard reset sequence through the Reset Control register (I/O Register CF9h). The PCH drives PLTRST# active a minimum of 1 ms when initiated through the Reset Control register (I/O Register CF9h). <b>Note:</b> PLTRST# is in the VccSus3_3 well.
<b>PWRBTN#</b>	I	<b>Power Button:</b> The Power Button will cause SMI# or SCI to indicate a system request to go to a sleep state. If the system is already in a sleep state, this signal will cause a wake event. If PWRBTN# is pressed for more than 4 seconds, this will cause an unconditional transition (power button override) to the S5 state. Override will occur even if the system is in the S1–S4 states. This signal has an internal pull-up resistor and has an internal 16 ms de-bounce on the input. This signal is in the DSW well.  <b>Note:</b> Upon entry to S5 due to a power button override, if Deep S4/S5 is enabled and conditions are met per <a href="#">Section 5.14.6.6</a> , the system will transition to Deep S4/S5.



Table 2-10. Power Management Interface Signals (Sheet 2 of 3)

Name	Type	Description
PCH_PWROK	I	<p><b>Power OK:</b> When asserted, PCH_PWROK is an indication to PCH that all of its core power rails has been stable for at least 10 ms. PCH_PWROK can be driven asynchronously. When PCH_PWROK is negated, the PCH asserts PLTRST#.</p> <p><b>Note:</b> It is required that the power rails associated with PCI/PCIe* (typically the 3.3 V, 5 V, and 12 V core well rails) have been valid for 99 ms prior to PCH_PWROK assertion in order to comply with the 100 ms PCI 2.3/PCIe 1.1 specification on PLTRST# deassertion. PCH_PWROK must not glitch, even if RSMRST# is low.</p>
RI#	I	<p><b>Ring Indicate:</b> This signal is an input from a modem. It can be enabled as a wake event, and this is preserved across power failures.</p>
RSMRST#	I	<p><b>Resume Well Reset:</b> This signal is used for resetting the resume power plane logic. This signal must remain asserted for at least 10 ms after the suspend power wells are valid. When deasserted, this signal is an indication that the suspend power wells are stable.</p>
SLP_A#	O	<p><b>SLP_A#:</b> Used to control power to the active sleep well (ASW) of the PCH.</p>
SLP_LAN# / GPIO29	O	<p><b>LAN Sub-System Sleep Control:</b> When SLP_LAN# is deasserted it indicates that the PHY device must be powered. When SLP_LAN# is asserted, power can be shut off to the PHY device. SLP_LAN# will always be deasserted in S0 and anytime SLP_A# is deasserted.</p> <p>A SLP_LAN#/GPIO Select Soft-Strap can be used for systems NOT using SLP_LAN# functionality to revert to GPIO29 usage. When soft-strap is 0 (default), pin function will be SLP_LAN#. When soft-strap is set to 1, the pin returns to its regular GPIO mode.</p> <p>The pin behavior is summarized in <a href="#">Section 5.14.9.4</a></p>
SLP_S3#	O	<p><b>S3 Sleep Control:</b> SLP_S3# is for power plane control. This signal shuts off power to all non-critical systems when in S3 (Suspend To RAM), S4 (Suspend to Disk), or S5 (Soft Off) states.</p>
SLP_S4#	O	<p><b>S4 Sleep Control:</b> Power plane control. Shuts power to non-critical systems when in the S4 (Suspend to Disk) or S5 (Soft Off) state. This pin must be used to control the DRAM power in order to use the PCH's DRAM power-cycling feature.</p> <p><b>Note:</b> This pin must be used to control the DRAM power in order to use the PCH's DRAM power-cycling feature. Refer to <a href="#">Section 5.14.9.2</a> for details</p>
SLP_S5# / GPIO63	O	<p><b>S5 Sleep Control:</b> SLP_S5# is for power plane control. This signal is used to shut power off to all non-critical systems when in the S5 (Soft Off) states. Pin may also be used as GPIO63.</p>
SLP_SUS#	O	<p><b>Deep S4/S5 Indication:</b> When asserted (low), this signal indicates PCH is in Deep S4/S5 state where internal Sus power is shut off for enhanced power saving. When deasserted (high), this signal indicates exit from Deep S4/S5 state and Sus power can be applied to PCH.</p> <p>If Deep S4/S5 is not supported, then this pin can be left unconnected. This pin is in the DSW power well.</p>
SUSACK#	I	<p><b>SUSACK#:</b> If Deep S4/S5 is supported, the EC must change SUSACK# to match SUSWARN# once the EC has completed the preparations discussed in the description for the SUSWARN# pin.</p> <p><b>Note:</b> SUSWARN# must only change in response to SUSACK# if Deep S4/S5 is supported by the platform.</p> <p>This pin is in the Sus power well.</p>
SUSCLK /GPIO62	O	<p><b>Suspend Clock:</b> This clock is an output of the RTC generator circuit to use by other chips for refresh clock.</p> <p>Pin may also be used as GPIO62.</p>



Table 2-10. Power Management Interface Signals (Sheet 3 of 3)

Name	Type	Description
<b>SUSWARN#</b> GPIO30 /	O	<b>SUSWARN#:</b> This pin asserts low when the PCH is planning to enter the Deep S4/S5 power state and remove Suspend power (using SLP_SUS#). The EC must observe edges on this pin, preparing for SUS well power loss on a falling edge and preparing for SUS well related activity (host/Intel ME wakes and runtime events) on a rising edge. SUSACK# should be asserted within a minimal amount of time from SUSWARN# assertion, as no wake events are supported if SUSWARN# is asserted, but SUSACK# is not asserted. Platforms supporting Deep S4/S5, but not wishing to participate in the handshake during wake and Deep S4/S5 entry may tie SUSACK# to SUSWARN#. This pin may be muxed with a GPIO for use in systems that do not support Deep S4/S5. Reset type: RSMRST# This signal is muxed with GPIO30
<b>SYS_PWROK</b>	I	<b>System Power OK:</b> This generic power good input to the PCH is driven and utilized in a platform-specific manner. While PCH_PWROK always indicates that the CORE well of the PCH is stable, SYS_PWROK is used to inform the PCH that power is stable to some other system component(s) and the system is ready to start the exit from reset.
<b>SYS_RESET#</b>	I	<b>System Reset:</b> This pin forces an internal reset after being debounced. The PCH will reset immediately if the SMBus is idle; otherwise, it will wait up to 25 ms ± 2 ms for the SMBus to idle before forcing a reset on the system.
<b>WAKE#</b>	I	<b>PCI Express* Wake Event:</b> Sideband wake signal on PCI Express asserted by components requesting wake up.
<b>ADR_COMPLETE</b>	O	This pin is not used for server designs.

## 2.11 Processor Interface

Table 2-11. Processor Interface Signals

Name	Type	Description
<b>RCIN#</b>	I	<b>Keyboard Controller Reset CPU:</b> The keyboard controller can generate INIT# to the processor. This saves the external OR gate with the PCH's other sources of INIT#. When the PCH detects the assertion of this signal, INIT# is generated for 16 PCI clocks. <b>Note:</b> The PCH will ignore RCIN# assertion during transitions to the S3, S4, and S5 states.
<b>A20GATE</b>	I	<b>A20 Gate:</b> Functionality reserved. A20M# functionality is not supported.
<b>PROCPWRGD</b>	O	<b>Processor Power Good:</b> This signal should be connected to the processor's PWRGOOD input to indicate when the processor power is valid.
<b>PM_SYNC</b>	O	<b>Power Management Sync:</b> Provides state information from the PCH to the Processor relevant to C-state transitions.
<b>PM_SYNC2</b>	O	<b>Power Management Sync 2:</b> Provides state information from the PCH to the Processor relevant to C-state transitions. Used only in a 4-socket system.
<b>THRMTRIP#</b>	I	<b>Thermal Trip:</b> When low, this signal indicates that a thermal trip from the processor occurred, and the PCH will immediately transition to a S5 state. The PCH will not wait for the processor stop grant cycle since the processor has overheated.



## 2.12 SMBus Interface

Table 2-12. SM Bus Interface Signals

Name	Type	Description
<b>SMBDATA</b>	I/OD	<b>SMBus Data:</b> External pull-up resistor is required.
<b>SMBCLK</b>	I/OD	<b>SMBus Clock:</b> External pull-up resistor is required.
<b>SMBALERT#</b> / GPIO11	I	<b>SMBus Alert:</b> This signal is used to wake the system or generate SMI#. This signal may be used as GPIO11.

## 2.13 System Management Interface

Table 2-13. System Management Interface Signals

Name	Type	Description
<b>INTRUDER#</b>	I	<b>Intruder Detect:</b> This signal can be set to disable system if box detected open. This signal's status is readable; thus, it can be used like a GPI if the Intruder Detection is not needed.
<b>SML0DATA</b>	I/OD	<b>System Management Link 0 Data:</b> SMBus link to external PHY. External pull-up is required.
<b>SML0CLK</b>	I/OD	<b>System Management Link 0 Clock:</b> SMBus link to external PHY. External pull-up is required.
<b>SML0ALERT#</b> / GPIO60 /	O OD	<b>SMLink Alert 0:</b> Output of the integrated LAN controller to external PHY. External pull-up resistor is required. This signal can instead be used as a GPIO60.
<b>SML1ALERT#</b> / PCHHOT#/GPIO74	O OD	PCHHOT#: This signal is used to indicate a PCH temperature out of bounds condition to an external EC, when PCH temperature is greater than value programmed by BIOS. An external pull-up resistor is required on this signal.  <b>Note:</b> A soft-strap determines the native function SML1ALERT# or PCHHOT# usage. When soft-strap is 0, function is SML1ALERT#, when soft-strap is 1, function is PCHHOT#.
<b>SML1CLK</b> / GPIO58	I/OD	<b>System Management Link 1 Clock:</b> SMBus link to optional Embedded Controller or BMC. External pull-up resistor is required.
<b>SML1DATA</b> / GPIO75	I/OD	<b>System Management Link 1 Data:</b> SMBus link to optional Embedded Controller or BMC. External pull-up resistor is required.

## 2.14 SAS System Management Interface (SRV/WS SKUs Only)

**Note:** These signals are not used on the HEDT SKU. These signals should be no connects on HEDT platform designs.

Table 2-14. SAS System Management Interface Signals (Sheet 1 of 2)

Name	Type	Description
<b>SASSMBDATA0</b>	I/O	SAS dedicated SMBus Master data
<b>SASSMBCLK0</b>	O	SAS dedicated SMBus Master Clock
<b>SASSMBDATA1</b> (Intel® C606, C608 Chipset SKUs Only)	I/O	SAS dedicated SMBus Master data



**Table 2-14. SAS System Management Interface Signals (Sheet 2 of 2)**

Name	Type	Description
<b>SASSMBCLK1</b> (Intel® C606, C608 Chipset SKUs Only)	O	SAS dedicated SMBus Master Clock
<b>SASSMBDATA2</b> (Intel® C608 Chipset SKUs Only)	I/O	SAS dedicated SMBus Master data
<b>SASSMBCLK2</b> (Intel® C608 Chipset SKUs Only)	O	SAS dedicated SMBus Master Clock

## 2.15 Real Time Clock Interface

**Table 2-15. Real Time Clock Interface**

Name	Type	Description
<b>RTCX1</b>	Special	<b>Crystal Input 1:</b> This signal is connected to the 32.768 kHz crystal. If no external crystal is used, then RTCX1 can be driven with the desired clock rate.
<b>RTCX2</b>	Special	<b>Crystal Input 2:</b> This signal is connected to the 32.768 kHz crystal. If no external crystal is used, then RTCX2 should be left floating.

## 2.16 Miscellaneous Signals

**Table 2-16. Miscellaneous Signals (Sheet 1 of 2)**

Name	Type	Description
<b>INTVRMEN</b>	I	<b>Internal Voltage Regulator Enable:</b> This signal enables the internal 1.5 V regulators. This signal must be always pulled-up to VccRTC. <b>Note:</b> See VccCore signal description for behavior when INTVRMEN is sampled low (external VR mode).
<b>DSWODVREN</b>	I	<b>Deep Sleep Well Internal Voltage Regulator Enable:</b> This signal enables the internal Deep Sleep 1.1 V regulators. This signal must be always pulled up to VccRTC.
<b>SPKR</b>	O	<b>Speaker:</b> The SPKR signal is the output of counter 2 and is internally “ANDed” with Port 61h bit 1 to provide Speaker Data Enable. This signal drives an external speaker driver device, which in turn drives the system speaker. Upon PLTRST#, its output state is 0. <b>Note:</b> SPKR is sampled as a functional strap. See Section 2.26.1 for more details. There is a weak integrated pull-down resistor on SPKR pin.
<b>RTCRST#</b>	I	<b>RTC Reset:</b> When asserted, this signal resets register bits in the RTC well. <b>Notes:</b> 1. Unless CMOS is being cleared (only to be done in the G3 power state), the RTCRST# input must always be high when all other RTC power planes are on. 2. In the case where the RTC battery is dead or missing on the platform, the RTCRST# pin must rise before the DPWROK pin.
<b>SRTCRST#</b>	I	<b>Secondary RTC Reset:</b> This signal resets the manageability register bits in the RTC well when the RTC battery is removed. <b>Notes:</b> 1. The SRTCRST# input must always be high when all other RTC power planes are on. 2. In the case where the RTC battery is dead or missing on the platform, the SRTCRST# pin must rise before the DPWROK pin.



Table 2-16. Miscellaneous Signals (Sheet 2 of 2)

Name	Type	Description
<b>SML1ALERT# / PCHHOT# / GPIO74</b>	OD	PCHHOT#: This signal is used to indicate a PCH temperature out of bounds condition to an external EC, when PCH temperature is greater than value programmed by BIOS. An external pull-up resistor is required on this signal.  <b>Note:</b> A soft-strap determines the native function SML1ALERT# or PCHHOT# usage. When soft-strap is 0, function is SML1ALERT#, when soft-strap is 1, function is PCHHOT#.
<b>INIT3_3V#</b>	O	<b>Initialization 3.3 V:</b> INIT3_3V# is asserted by the PCH for 16 PCI clocks to reset the processor. This signal is intended for Firmware Hub.
<b>NMI# / GPIO35</b>	O	<b>Non-Maskable Interrupt:</b> NMI# is used to force a non-Maskable interrupt to the processor. <b>Note:</b> The NMI # function is enabled using softstrap
<b>SMI# / GPIO20</b>	O	<b>System Management Interrupt:</b> SMI# is an active low output synchronous to PCICLK. It is asserted by the PCH in response to one of many enabled hardware or software events. <b>Note:</b> The SMI# function is enabled using softstrap

## 2.17 Intel® High Definition Audio (Intel® HD Audio) Link

Table 2-17. Intel® High Definition Audio (Intel® HD Audio) Link Signals

Name	Type	Description
<b>HDA_RST#</b>	O	<b>Intel HD Audio Reset:</b> Master hardware reset to external codec(s).
<b>HDA_SYNC</b>	O	<b>Intel HD Audio Sync:</b> 48 kHz fixed rate sample sync to the codec(s). Also used to encode the stream number.  <b>Note:</b> This signal is sampled as a functional strap. See <a href="#">Section 2.26.1</a> for more details. There is a weak integrated pull-down resistor on this pin.
<b>HDA_BCLK</b>	O	<b>Intel HD Audio Bit Clock Output:</b> 24.000 MHz serial data clock generated by the Intel High Definition Audio controller (the PCH). This signal has a weak internal pull-down resistor.
<b>HDA_SDO</b>	O	<b>Intel HD Audio Serial Data Out:</b> Serial TDM data output to the codec(s). This serial output is double-pumped for a bit rate of 48 Mb/s for Intel High Definition Audio.  <b>Note:</b> This signal is sampled as a functional strap. See <a href="#">Section 2.26.1</a> for more details. There is a weak integrated pull-down resistor on this pin.
<b>HDA_SDIN[3:0]</b>	I	<b>Intel HD Audio Serial Data In [3:0]:</b> Serial TDM data inputs from the codecs. The serial input is single-pumped for a bit rate of 24 Mb/s for Intel High Definition Audio. These signals have integrated pull-down resistors, which are always enabled.  <b>Note:</b> During enumeration, the PCH will drive this signal. During normal operation, the CODEC will drive it.



## 2.18 Serial Peripheral Interface (SPI)

Table 2-18. Serial Peripheral Interface (SPI) Signals

Name	Type	Description
SPI_CS0#	O	<b>SPI Chip Select 0:</b> Used as the SPI bus request signal.
SPI_CS1#	O	<b>SPI Chip Select 1:</b> Used as the SPI bus request signal.
SPI_MISO	I	<b>SPI Master IN Slave OUT:</b> Data input pin for PCH.
SPI_MOSI	I/O	<b>SPI Master OUT Slave IN:</b> Data output pin for PCH.
SPI_CLK	O	<b>SPI Clock:</b> SPI clock signal, during idle the bus owner will drive the clock signal low. 17.86 MHz and 31.25.

## 2.19 Thermal Signals

Table 2-19. Thermal Signals

Signal Name	Type	Description
PWM[3:0]	OD O	<b>Fan Pulse Width Modulation Outputs:</b> Pulse Width Modulated duty cycle output signal that is used for Intel® Quiet System Technology (Intel® QST). When controlling a 3-wire fan, this signal controls a power transistor that, in turn, controls power to the fan. When controlling a 4-wire fan, this signal is connected to the "Control" signal on the fan. The polarity of this signal is programmable. The output default is low. These signals are 5 V tolerant.
TACH0 / GPIO17 TACH1 / GPIO1 TACH2 / GPIO6 TACH3 / GPIO7 TACH4 / GPIO68 TACH5 / GPIO69 TACH6 / GPIO70 TACH7 / GPIO71	I	<b>Fan Tachometer Inputs:</b> Tachometer pulse input signal that is used to measure fan speed. This signal is connected to the "Sense" signal on the fan. Can instead be used as a GPIO.
SST	I/O	<b>Simple Serial Transport:</b> Single-wire, serial bus. Connect to SST compliant devices such as SST thermal sensors or voltage sensors.
PECI	I/O	<b>Platform Environment Control Interface:</b> Single-wire, serial bus. Connect to corresponding pin of the processor for accessing processor digital thermometer.

## 2.20 JTAG Signals

Table 2-20. JTAG Signals

Name	Type	Description
JTAG_TCK	I	<b>Test Clock Input (TCK):</b> The test clock input provides the clock for the JTAG test logic.
JTAG_TMS	I	<b>Test Mode Select (TMS):</b> The signal is decoded by the Test Access Port (TAP) controller to control test operations.
JTAG_TDI	I	<b>Test Data Input (TDI):</b> Serial test instructions and data are received by the test logic at TDI.
JTAG_TDO	OD	<b>Test Data Output (TDO):</b> TDO is the serial output for test instructions and data from the test logic defined in this standard.

**Note:** JTAG Pin definitions are from IEEE Standard Test Access Port and Boundary-Scan Architecture (IEEE Std. 1149.1-2001)



## 2.21 Clock Signals

**Table 2-21. Clock Interface Signals**

Name	Type	Description
<b>CLKIN_DMI_P, CLKIN_DMI_N</b>	I	100 MHz differential reference clock from CK420BQ (or CK505 on HEDT platforms) and used by DMI.
<b>CLKIN_SATA_P, CLKIN_SATA_N</b>	I	100 MHz differential reference clock from CK420BQ (or CK505 on HEDT platforms), provided separately from CLKIN_DMI, for use only as a 100 MHz source for SATA.
<b>CLKIN_DOT96P, CLKIN_DOT96N</b>	I	96 MHz differential reference clock from CK420BQ (or CK505 on HEDT platforms).
<b>REFCLK14IN</b>	I	Single-ended 14.31818 MHz reference clock driven by CK420BQ (or CK505 on HEDT platforms). Used for 8254 Timer, ACPI Timer and HPET.
<b>CLKIN_SAS0_P, CLKIN_SAS0_N</b>	I	100 MHz differential reference clock from CK420BQ. Used for SAS differential clock. <b>Note:</b> For HEDT SKU, these signals must be tied to the 100 MHz reference clock
<b>CLKIN_SAS1_P, CLKIN_SAS1_N</b> (Intel® C606, C608 Chipset SKUs Only)	I	100 MHz differential reference clock from CK420BQ. Used for SAS differential clock.
<b>CLKIN_SPCIE0_P, CLKIN_SPCIE0_N</b> (Intel® C606, C608 Chipset SKUs Only)	I	Upstream PCIe* Switch Port differential reference clock.
<b>CLKIN_PCI</b>	I	<b>PCI Clock:</b> This is a 33 MHz clock feedback input to reduce skew between PCH PCI clock and clock observed by connected PCI devices.



## 2.22 General Purpose I/O Signals

1. GPIO Configuration registers within the Core Well are reset whenever PCH\_PWROK is deasserted.
2. GPIO Configuration registers within the Suspend Well are reset when RSMRST# is asserted, CF9h reset (06h or 0Eh) event occurs, or SYS\_RESET# is asserted. However, CF9h reset and SYS\_RESET# events can be masked from resetting the Suspend well GPIO by programming appropriate GPIO Reset Select (GPIO\_RST\_SEL) registers.
3. GPIO24 is an exception to the other GPIO Signals in the Suspend Well and is not reset by CF9h reset (06h or 0Eh).

**Table 2-22. General Purpose I/O Signals (Sheet 1 of 3)**

Name	Type	Tolerance	Power Well	Default	Blink Capability	Glitch Protection during Power-On Sequence	GPI Event Support	Description
GPIO75	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with SML1DATA (Note 10)
GPIO74	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with SML1ALERT#/ PCHHOT# (Note 10)
GPIO73	I/O	3.3 V	Suspend	GPI	No	No	No	Unmultiplexed
GPIO72	I/O	3.3 V	Suspend	Native	No	No	No	Unmultiplexed (note 4) This signal must not be low prior to ASW well being valid; Requires pull-up resistor.
GPIO71	I/O	3.3 V	Core	Native	No	No	No	Multiplexed with Tach7
GPIO70	I/O	3.3 V	Core	Native	No	No	No	Multiplexed with Tach6
GPIO69	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with Tach5
GPIO68	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with Tach4
GPIO67	I/O	3.3 V	Core	GPO	No	No	No	Unmultiplexed
GPIO66	I/O	3.3 V	Core	GPO	No	No	No	Unmultiplexed
GPIO65	I/O	3.3 V	Core	GPO	No	No	No	Unmultiplexed
GPIO64	I/O	3.3 V	Core	GPO	No	No	No	Unmultiplexed
GPIO63	I/O	3.3 V	Suspend	Native	No	Yes	No	Multiplexed with SLP_S5#
GPIO62	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with SUSCLK
GPIO61	I/O	3.3 V	Suspend	GPO	No	Yes	No	Unmultiplexed (note 4)
GPIO60	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with SML0ALERT#
GPIO59	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with OCO# (Note 10)
GPIO58	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with SML1CLK
GPIO57	I/O	3.3 V	Suspend	GPI	No	Yes	No	Unmultiplexed
GPIO56	I/O	3.3 V	Suspend	GPI	No	No	No	Unmultiplexed
GPIO55	I/O	3.3 V	Core	Native	No	No	No	Multiplexed with GNT3#
GPIO54	I/O	5.0 V	Core	Native	No	No	No	Multiplexed with REQ3#/ GSXRESET#.(Note 10)
GPIO53	I/O	3.3 V	Core	Native	No	No	No	Multiplexed with GNT2#/ GSXDIN
GPIO52	I/O	5.0 V	Core	Native	No	No	No	Multiplexed with REQ2#/ GSXSLOAD. (Note 10)
GPIO51	I/O	3.3 V	Core	Native	No	No	No	Multiplexed with GNT1#/ GSXDOUT
GPIO50	I/O	5.0 V	Core	Native	No	No	No	Multiplexed with REQ1#/ GSXCLK. (Note 10)



Table 2-22. General Purpose I/O Signals (Sheet 2 of 3)

Name	Type	Tolerance	Power Well	Default	Blink Capability	Glitch Protection during Power-On Sequence	GPI Event Support	Description
GPIO49	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with SATA5GP and TEMP_ALERT#
GPIO48	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with SDATAOUT1.
GPIO47	I/O	3.3 V	Suspend	GPI	No	No	No	Unmultiplexed
GPIO46	I/O	3.3 V	Suspend	GPI	No	No	No	Unmultiplexed
GPIO45	I/O	3.3 V	Suspend	GPI	No	No	No	Unmultiplexed
GPIO44	I/O	3.3 V	Suspend	GPI	No	No	No	Unmultiplexed
GPIO[43:40]	I/O	3.3 V	Suspend	Native	No	No	No	Multiplexed with OC[4:1]#. (Note 10)
GPIO39	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with SDATAOUT0.
GPIO38	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with SLOAD.
GPIO37	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with SATA3GP.
GPIO36	I/O	3.3 V	Core	GPI	No	No	No	Multiplexed with SATA2GP.
GPIO35	I/O	3.3 V	Core	GPO	No	No	No	Multiplexed with NMI#.
GPIO34	I/O	3.3 V	Core	GPI	No	No	No	Unmultiplexed (Note 4)
GPIO33	I/O	3.3 V	Core	GPO	No	No	No	Unmultiplexed (Note 4)
GPIO32	I/O	3.3 V	Core	GPO	No	No	No	Unmultiplexed (Note 4)
GPIO31	I/O	3.3 V	DSW	GPI	Yes	Yes	No	Unmultiplexed (Note 4)
GPIO30	I/O	3.3 V	Suspend	Native	Yes	Yes	No	Multiplexed with SUSWARN#. Can be used as SUSWARN# and GPIO30 only.
GPIO29	I/O	3.3 V	Suspend	Native	Yes	Yes	No	Multiplexed with SLP_LAN# Pin usage as GPIO is determined by SLP_LAN#/GPIO Select Soft-strap.(Note 9) Soft-strap value is not preserved for this signal in the Sx/Moff state and the pin will return to its native functionality (SLP_LAN#)
GPIO28	I/O	3.3 V	Suspend	GPO	Yes	No	No	Unmultiplexed
GPIO27	I/O	3.3 V	DSW <sup>11</sup>	GPI	Yes	No	No	Unmultiplexed Can be configured as wake input to allow wakes from Deep S4/S5. This GPIO has no GPIO functionality in the Deep S4/S5 states other than wake from Deep S4/S5 if this option has been configured.
GPIO26	I/O	3.3 V	Suspend	GPO	Yes	No	No	Unmultiplexed
GPIO25	I/O	3.3 V	Suspend	GPO	Yes	No	No	Unmultiplexed
GPIO24	I/O	3.3 V	Suspend	GPO	Yes	Yes	No	Unmultiplexed <b>Note:</b> GPIO24 configuration register bits are cleared by RSMRST# and are not cleared by CF9h reset event.
GPIO23	I/O	3.3 V	Core	Native	Yes	No	No	Multiplexed with LDRQ1#.
GPIO22	I/O	3.3 V	Core	GPI	Yes	No	No	Multiplexed with SCLOCK
GPIO21	I/O	3.3 V	Core	GPI	Yes	No	No	Multiplexed with SATA0GP
GPIO20	I/O	3.3 V	Core	GPO	Yes	No	No	Multiplexed with SMI#
GPIO19	I/O	3.3 V	Core	GPI	Yes	No	No	Multiplexed with SATA1GP



Table 2-22. General Purpose I/O Signals (Sheet 3 of 3)

Name	Type	Tolerance	Power Well	Default	Blink Capability	Glitch Protection during Power-On Sequence	GPI Event Support	Description
GPIO18	I/O	3.3 V	Core	GPO	Yes (Note 6)	No	No	Unmultiplexed
GPIO17	I/O	3.3 V	Core	GPI	Yes	No	No	Multiplexed with TACH0.
GPIO16	I/O	3.3 V	Core	GPI	Yes	No	No	Multiplexed with SATA4GP.
GPIO15	I/O	3.3 V	Suspend	GPO	Yes	No	Yes2	Unmultiplexed
GPIO14	I/O	3.3 V	Suspend	Native	Yes	No	Yes2	Multiplexed with OC7#
GPIO13	I/O	3.3 V or 1.5 V	Suspend	GPI	Yes	No	Yes2	Unmultiplexed (Note 4, 13) <b>Note:</b> GPIO13 is powered by VccSusHDA (either 3.3 V or 1.5 V). Voltage tolerance on the signal is the same as VccSusHDA.
GPIO12	I/O	3.3 V	Suspend	Native	Yes	No	Yes2	Multiplexed with LAN_PHY_PWR_CTRL. GPIO / Native functionality controlled using soft strap (Note 7, 12)
GPIO11	I/O	3.3 V	Suspend	Native	Yes	No	Yes2	Multiplexed with SMBALERT#. (Note 10)
GPIO10	I/O	3.3 V	Suspend	Native	Yes	No	Yes2	Multiplexed with OC6# (Note 10)
GPIO9	I/O	3.3 V	Suspend	Native	Yes	No	Yes2	Multiplexed with OC5# (Note 10)
GPIO8	I/O	3.3 V	Suspend	GPO	Yes	No	Yes2	Unmultiplexed
GPIO[7:6]	I/O	3.3 V	Core	GPI	Yes	No	Yes2	Multiplexed with TACH[3:2].
GPIO[5:2]	I/OD	5 V	Core	GPI	Yes	No	Yes2	Multiplexed with PIRQ[H:E]# (Note 5).
GPIO1	I/O	3.3 V	Core	GPI	Yes	No	Yes2	Multiplexed with TACH1.
GPIO0	I/O	3.3 V	Core	GPI	Yes	No	Yes2	Multiplexed with BMBUSY#

**Notes:**

- All GPIOs can be configured as either input or output.
- GPIO[15:0] can be configured to cause a SMI# or SCI. A GPI can be routed to either an SMI# or an SCI, but not both.
- Some GPIOs exist in the VccSus3\_3 power plane. Care must be taken to make sure GPIO signals are not driven high into powered-down planes. Also, external devices should not be driving powered down GPIOs high. Some GPIOs may be connected to pins on devices that exist in the core well. If these GPIOs are outputs, there is a danger that a loss of core power (PCH\_PWROK low) or a Power Button Override event will result in the PCH driving a pin to a logic 1 to another device that is powered down.
- The functionality that is multiplexed with the GPIO is not used in the PCH.
- When this signal is configured as GPO the output stage is an open drain.
- GPIO18 will toggle at a frequency of approximately 1 Hz when the signal is programmed as a GPIO (when configured as an output) by BIOS.
- For GPIOs where GPIO vs. Native Mode is configured using SPI Soft Strap, the corresponding GPIO\_USE\_SEL bits for these GPIOs have no effect. The GPIO\_USE\_SEL bits for these GPIOs may change to reflect the Soft-Strap configuration even though GPIO Lockdown Enable (GLE) bit is set.
- These pins are used as Functional straps. See Section 2.26.1 for more details.
- Once Soft-strap is set to GPIO mode, this pin will default to GP Input. When Soft-strap is SLP\_LAN# usage and if Host BIOS does not configure as GP Output for SLP\_LAN# control, SLP\_LAN# behavior will be based on the setting of the RTC backed SLP\_LAN# Default Bit(D31:F0:A4h:Bit 8).
- When the multiplexed GPIO is used as GPIO functionality, care should be taken to ensure the signal is stable in its inactive state of the native functionality, immediately after reset until it is initialized to GPIO functionality.
- GPIO functionality is only available when the Suspend well is powered although pin is in DSW.
- GPIO will assume its native functionality until the soft strap is loaded after which time the functionality will be determined by the soft strap setting.
- GPIO13 is powered by VccSusHDA (either 3.3 V or 1.5 V). Voltage tolerance on the signal is the same as VccSusHDA.



## 2.23 GPIO Serial Expander Signals

**Table 2-23. GPIO Serial Expander Interface**

Name	Type	Description
<b>GSXCLK</b>	O	GPIO Serial Expansion clock input. GSXCLK may optionally be used as REQ1# or GPIO50
<b>GSXSLOAD</b>	O	GPIO Serial Expansion data load select. GSXSLOAD may optionally be used as REQ2# or GPIO52
<b>GSXSRESET#</b>	O	GPIO Serial Expansion reset. GSXSRESET# may optionally be used as REQ3# or GPIO54
<b>GSXDOUT</b>	O	GPIO Serial Expansion serial data out. GSXDOUT may optionally be used as GNT1# or GPIO51
<b>GSXDIN</b>	I	GPIO Serial Expansion serial data in. GSXDIN may optionally be used as GNT2# or GPIO53

**Note:** GSX (GPIO Serial Expander) signal functions are enabled using softstrap.

## 2.24 Manageability Signals

The following signals can be optionally utilized by PCH Intel ME supported applications and appropriately configured by Intel ME firmware. When configured and utilized as a Manageability function, the associated host GPIO functionality is no longer available. If the Manageability function is not utilized in a platform, the signal can be used as a host General Purpose I/O or a native function.

**Table 2-24. Manageability Signals (Sheet 1 of 2)**

Name	Type	Description
<b>MGPIO0/ PROC_MISSING/ GPIO24</b>	I/O	MGPIO0 can be used to connect to upgrade ROM. It is also used to indicate Processor Missing to the Intel® Management Engine (Intel® ME). <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO1/GPIO30</b>	I/O	MGPIO1 can be used as an alternative for MGPIO2 or MGPIO5 when neither pins are available for Intel ME. <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO2 / GPIO31</b>	I/O	MGPIO2 can be used as a SMBALERT# signal from PSU to PCH <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO3 / SLP_LAN# / GPIO29</b>	I/O	Intel ME General Purpose I/O 3. <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO4 / SML0ALERT# / GPIO60</b>	I/O	MGPIO4 can be used as an alternative for MGPIO2 or MGPIO5 when neither pins are available for Intel ME. <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO5 / GPIO57</b>	I/O	MGPIO5 can be used as Intel ME firmware recovery mode strap. MGPIO5 can be used as an alternative for MGPIO2 when it is not available for Intel ME. <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO6 / GPIO27</b>	I/O	MGPIO6 can be used as an alternative for MGPIO2 or MGPIO5 when neither pins are available for Intel ME. <b>Note:</b> This signal is in the Deep S4/S5(DSW) power well.
<b>MGPIO7 / GPIO28</b>	I/O	MGPIO7 can be used as an alternative for MGPIO2 or MGPIO5 when neither pins are available for Intel ME. <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO8 / SML1ALERT# / GPIO74</b>	I/O	MGPIO8 can be used as an alternative for MGPIO2 or MGPIO5 when neither pins are available for Intel ME. <b>Note:</b> This signal is in the Suspend power well.



Table 2-24. Manageability Signals (Sheet 2 of 2)

Name	Type	Description
<b>MGPIO9</b> / SATA4GP / GPIO16	I/O	Intel ME General Purpose I/O 9. <b>Note:</b> This signal is in the Core power well.
<b>MGPIO10/ TEMP_ALERT/ SATA5GP</b> / GPIO49	I/O	Used as an alert (active low) to indicate to the external controller (for example, EC or SIO) that temperatures are out of range for the PCH or Graphics/Memory Controller or the processor core. <b>Note:</b> This signal is in the Core power well.
<b>MGPIO11</b> / SML1CLK / GPIO58	I/O	ME General Purpose I/O 11. <b>Note:</b> This signal is in the Suspend power well.
<b>MGPIO12</b> / SML1DATA / GPIO75	I/O	ME General Purpose I/O 12. <b>Note:</b> This signal is in the Suspend power well.

**Note:** SLP\_LAN#/GPIO29 may also be configured by Intel ME FW in Sx/Moff. Please refer to SLP\_LAN#/GPIO29 signal description for details.

## 2.25 Power and Ground Signals

Table 2-25. Power and Ground Signals (Sheet 1 of 2)

Name	Description
<b>DcpRTC</b>	<b>Decoupling:</b> This signal is for RTC decoupling only. This signal requires decoupling.
<b>DcpSST</b>	<b>Decoupling:</b> Internally generated 1.5 V powered off of Suspend Well. This signal requires decoupling. Decoupling is required even if this feature is not used.
<b>DcpSus</b>	1.1 V Suspend well supply that is supplied internally by Internal VRs.
<b>DcpSusByp</b>	Internally generated 1.1 V Deep S4/S5 well power. This rail should not be supplied externally. <b>Note:</b> No decoupling capacitors should be used on this rail.
<b>V5REF</b>	Reference for 5 V tolerance on core well inputs. This power may be shut off in S3, S4, S5 or G3 states.
<b>V5REF_Sus</b>	Reference for 5 V tolerance on suspend well inputs. This power is not expected to be shut off unless the system is unplugged.
<b>VccCore</b>	1.1 V supply for core well logic. This power may be shut off in S3, S4, S5 or G3 states. <b>Note:</b> In external VR mode (INTVRMEN sampled low), the voltage level of VccCore may be indeterminate while DcpSus (1.1 V Suspend Well Power) supply ramps and prior to PWROK assertion.
<b>VccIO</b>	1.1 V supply for core well I/O buffers. This power may be shut off in S3, S4, S5 or G3 states.
<b>Vcc3_3</b>	3.3 V supply for core well I/O buffers. This power may be shut off in S3, S4, S5 or G3 states.
<b>VccASW</b>	1.1 V supply for Active Sleep Well. This plane must be on in S0 and other times the Intel ME is used or integrated LAN is used.
<b>VccDMI</b>	Power supply for DMI. 1.0 to 1.1 V based on the processor VTT voltage. Please refer to the respective processor documentation to find the appropriate voltage level.
<b>VccRTC</b>	3.3 V (can drop to 2.0 V min. in G3 state) supply for the RTC well. This power is not expected to be shut off unless the RTC battery is removed or completely drained. <b>Note:</b> Implementations should not attempt to clear CMOS by using a jumper to pull VccRTC low. Clearing CMOS in a PCH based platform can be done by using a jumper on RTCRST# or GPI.
<b>VccSus3_3</b>	3.3 V supply for suspend well I/O buffers. This power may be shut off in the Deep S4/S5 or G3 states.
<b>VccAUBG</b>	3.3 V supply for suspend well USB reference. <b>Note:</b> This pin may require external filtering.
<b>VccAUPLL</b>	1.1 V supply for core well USB PLL. <b>Note:</b> This pin may require external filtering.



Table 2-25. Power and Ground Signals (Sheet 2 of 2)

Name	Description
<b>VccSusHDA</b>	Suspend supply for Intel HD Audio. This pin can be either 1.5 or 3.3 V.
<b>VccVRM</b>	1.5 V / 1.8 V supply for internal PLL and VRMs
<b>VccDFTERM</b>	1.8 V or 3.3 V supply for DF_TVVS. Can be pulled up to 1.8 V or 3.3 V core.
<b>VccAPLLSATA</b>	1.1 V Analog power supply for SATA. This signal is used for the analog power for SATA. This requires an LC filter and is supplied by the core well. Must be powered even if SATA is not used. <b>Note:</b> This pin can be left as no connect in On-Die VR enabled mode (default).
<b>VccAPLLEXP</b>	1.1 V Analog Power for DMI. This power is supplied by the core well. This requires an LC filter. <b>Note:</b> This pin can be left as no connect in On-Die VR enabled mode (default).
<b>VccAPLLDMI2</b>	1.1 V Analog Power for internal PLL. This power is supplied by the core well. This requires an LC filter. <b>Note:</b> This pin can be left as no connect in On-Die VR enabled mode (default).
<b>V_PROC_IO</b>	Powered by the same supply as the processor I/O voltage. This supply is used to drive the processor interface signals. Please refer to the respective processor documentation to find the appropriate voltage level.
<b>VccDSW3_3</b>	3.3 V supply for Deep Sleep wells. If platform does not support Deep S4/S5, then tie to VccSus3_3.
<b>VccSPI</b>	3.3 V supply for SPI controller logic. This must be powered when VccASW is powered. <b>Note:</b> This rail can be optionally powered on 3.3-V Suspend power (VccSus3_3) based on platform needs.
<b>VccXUS</b>	1.1 V supply for PCI Express Uplink switch wells. Can be tied to Vss for Intel® C602, C604 Chipset SKUs. <b>Note:</b> This signal is not used on HEDT SKU and can be tied to V <sub>SS</sub> or V <sub>CC</sub> , but must be tied to the same power plane as VccSCUS.
<b>VccSCUS</b>	1.1 V supply for SAS switch wells. Can be tied to Vss for Intel® C602, C602J, C604 Chipset SKUs. <b>Note:</b> This signal is not used on HEDT SKU and can be tied to V <sub>SS</sub> or V <sub>CC</sub> , but must be tied to the same power plane as VccXUS.
<b>VccPLLSAS0</b>	1.1 V supply for x4 SAS port. This requires an LC filter and is supplied by the core well. <b>Note:</b> This signal must be connected on all SKUs.
<b>VccPLLSAS1</b>	1.1 V supply for x4 SAS port. This requires an LC filter and is supplied by the core well. <b>Note:</b> This signal is not used on Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs.
<b>VccPILLEXPU</b> (Intel® C606, C608 Chipset SKUs Only)	1.1 V supply for PCI Express Uplink. This requires an LC filter and is supplied by the core well. <b>Note:</b> Must be tied to Vss if VccXUS is tied to Vss on Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs.
<b>VccRBIAS_SAS0</b>	1.1 V supply for x4 SAS port RBIAS. This is supplied by the core well. <b>Note:</b> This signal must be connected on all SKUs.
<b>VccRBIAS_SAS1</b>	1.1 V supply for x4 SAS port RBIAS. This is supplied by the core well. <b>Note:</b> This signal is not used on Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs.
<b>VccRBIAS_PU</b> (Intel® C606, C608 Chipset SKUs Only)	1.1 V supply for PCI Express Uplink RBIAS. This is supplied by the core well. <b>Note:</b> Must be tied to Vss if VccXUS is tied to Vss on Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs.
<b>VccSAS1_5</b>	1.5 V supply for x4 SAS port. This is supplied by the core well. <b>Note:</b> This signal must be connected on all SKUs.
<b>Vss</b>	Grounds.



## 2.26 Pin Straps

### 2.26.1 Functional Straps

The following signals are used for static configuration. They are sampled at the rising edge of PCH\_PWROK to select configurations (except as noted), and then revert later to their normal usage. To invoke the associated mode, the signal should be driven at least four PCI clocks prior to the time it is sampled.

PCH has implemented Soft Straps. Soft Straps are used to configure specific functions within the PCH and processor very early in the boot process before BIOS or SW intervention. When Descriptor Mode is enabled, the PCH will read Soft Strap data out of the SPI device prior to the de-assertion of reset to both the Intel ME and the Host system.

**Table 2-26. Functional Strap Definitions (Sheet 1 of 3)**

Signal	Usage	When Sampled	Comment
SPKR	No Reboot	Rising edge of PCH_PWROK	The signal has a weak internal pull-down. <b>Note:</b> The internal pull-down is disabled after PLTRST# de-asserts. If the signal is sampled high, this indicates that the system is strapped to the “No Reboot” mode (PCH will disable the TCO Timer system reboot feature). The status of this strap is readable using the NO REBOOT bit (Chipset Config Registers: Offset 3410h: bit 5).
INIT3_3V#	Reserved	Rising edge of PCH_PWROK	This signal has a weak internal pull-up. <b>Note:</b> The internal pull-up is disabled after PLTRST# de-asserts. <b>Note:</b> This signal should not be pulled low
GNT3#/GPIO55	Top-Block Swap Override	Rising edge of PCH_PWROK	The signal has a weak internal pull-up. If the signal is sampled low, this indicates that the system is strapped to the “Top-Block Swap” mode. The status of this strap is readable using the Top Swap bit (Chipset Config Registers: Offset 3414h: bit 0). <b>Notes:</b> 1. The internal pull-up is disabled after PLTRST# deasserts. 2. Software will not be able to clear the Top Swap bit until the system is rebooted without GNT3#/GPIO55 being pulled down.
INTVRMEN	Integrated 1.1 V VRM Enable / Disable	Always	Integrated 1.1 V VRMs is enabled when high <b>Note:</b> This signal should always be pulled high.



Table 2-26. Functional Strap Definitions (Sheet 2 of 3)

Signal	Usage	When Sampled	Comment															
GNT1#/GPIO51	Boot BIOS Strap bit [1] BBS[1]	Rising edge of PCH_PWROK	<p>This Signal has a weak internal pull-up. <b>Note:</b> The internal pull-up is disabled after PCIRST# de-asserts.</p> <p>This field determines the destination of accesses to the BIOS memory range. Also controllable using Boot BIOS Destination bit (Chipset Config Registers: Offset 3410h:bit 11). This strap is used in conjunction with Boot BIOS Destination Selection 0 strap.</p> <table border="1"> <thead> <tr> <th>Bit11</th> <th>Bit 10</th> <th>Boot BIOS Destination</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>1</td> <td>0</td> <td>PCI</td> </tr> <tr> <td>1</td> <td>1</td> <td>SPI</td> </tr> <tr> <td>0</td> <td>0</td> <td>LPC</td> </tr> </tbody> </table> <p><b>Note:</b> If option 00 LPC is selected BIOS may still be placed on LPC, but all platforms with PCH require SPI flash connected directly to the PCH's SPI bus with a valid descriptor in order to boot.</p> <p><b>Note:</b> Booting to PCI is intended for debut/testing only. Boot BIOS Destination Select to LPC/PCI by functional strap or using Boot BIOS Destination Bit will not affect SPI accesses initiated by Intel ME or Integrated GbE LAN.</p>	Bit11	Bit 10	Boot BIOS Destination	0	1	Reserved	1	0	PCI	1	1	SPI	0	0	LPC
Bit11	Bit 10	Boot BIOS Destination																
0	1	Reserved																
1	0	PCI																
1	1	SPI																
0	0	LPC																
SATA1GP/ GPIO19	Boot BIOS Strap bit[0] BBS[0]	Rising edge of PCH_PWROK	<p>This Signal has a weak internal pull-up. <b>Note:</b> The internal pull-up is disabled after PCIRST# de-asserts. This field determines the destination of accesses to the BIOS memory range. Also controllable using Boot BIOS Destination bit (Chipset Config Registers: Offset 3410h:bit 10). This strap is used in conjunction with Boot BIOS Destination Selection 1 strap.</p> <table border="1"> <thead> <tr> <th>Bit11</th> <th>Bit 10</th> <th>Boot BIOS Destination</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>1</td> <td>0</td> <td>PCI</td> </tr> <tr> <td>1</td> <td>1</td> <td>SPI</td> </tr> <tr> <td>0</td> <td>0</td> <td>LPC</td> </tr> </tbody> </table> <p><b>Note:</b> If option 00 LPC is selected BIOS may still be placed on LPC, but all platforms with PCH require SPI flash connected directly to the PCH's SPI bus with a valid descriptor in order to boot.</p> <p><b>Note:</b> Booting to PCI is intended for debut/testing only. Boot BIOS Destination Select to LPC/PCI by functional strap or using Boot BIOS Destination Bit will not affect SPI accesses initiated by Intel ME or Integrated GbE LAN.</p>	Bit11	Bit 10	Boot BIOS Destination	0	1	Reserved	1	0	PCI	1	1	SPI	0	0	LPC
Bit11	Bit 10	Boot BIOS Destination																
0	1	Reserved																
1	0	PCI																
1	1	SPI																
0	0	LPC																
GNT2#/ GPIO53	DMI AC Coupling	Rising edge of PCH_PWROK	<p>This Signal has a weak internal pull-up. <b>Note:</b> The internal pull-up is disabled after PLTRST# de-asserts.</p> <p>Tying this strap low enables DMI full voltage AC coupling.</p>															



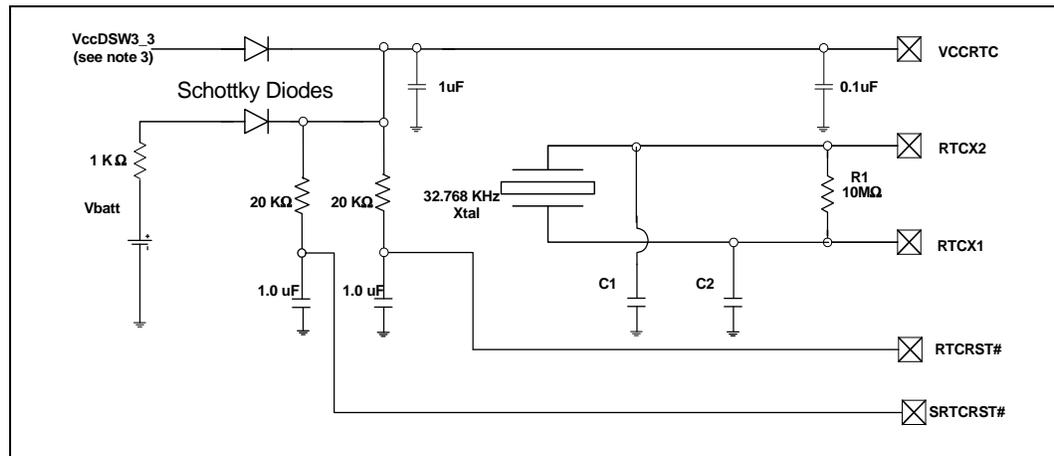
Table 2-26. Functional Strap Definitions (Sheet 3 of 3)

Signal	Usage	When Sampled	Comment
HDA_SDO	Flash Descriptor Security Override/ Intel ME Debug Mode	Rising edge of PCH_PWROK	Signal has a weak internal pull-down. If strap is sampled low, the security measures defined in the Flash Descriptor will be in effect (default). If sampled high, the Flash Descriptor Security will be overridden. This strap should only be asserted high using external pull-up in manufacturing/debug environments ONLY. <b>Note:</b> The weak internal pull-down is disabled after PLTRST# de-asserts. <b>Note:</b> Asserting the HDA_SDO high on the rising edge of PCH_PWROK will also halt Intel ME after chipset bring up and disable runtime Intel ME features. This is a debug mode and must not be asserted after manufacturing/debug.
DF_TVS	DMI Tx /Rx Termination Voltage	Rising edge of PCH_PWROK	This signal has a weak internal pull-down. <b>Note:</b> The internal pull-down is disabled after PLTRST# de-asserts.
GPIO28	On-Die PLL Voltage Regulator	Rising edge of RSMRST# pin	This signal has a weak internal pull-up. The On-Die PLL voltage regulator is enabled when sampled high. When sampled low the On-Die PLL Voltage Regulator is disabled. <b>Note:</b> The internal pull-up is disabled after RSMRST# deasserts.
HDA_SYNC	On-Die PLL Voltage Regulator Voltage Select	Rising edge of RSMRST# pin	This signal has a weak internal pull-down. On Die PLL VR is supplied by 1.5 V from VccVRM when sampled high, 1.8 V from VccVRM when sampled low.
GPIO15	TLS Confidentiality	Rising edge of RSMRST# pin	Low = Intel ME Crypto Transport Layer Security (TLS) cipher suite with no confidentiality High = Intel ME Crypto TLS cipher suite with confidentiality This signal has a weak internal pull down. <b>Notes:</b> 1. A strong pull up may be needed for GPIO functionality. 2. This signal must be pulled up to support Intel RPAT and Intel AMT with TLS. Intel ME configuration parameters also need to be set correctly to enable TLS.
DSWODVREN	Deep S4/S5 Well On-Die Voltage Regulator Enable	Always	If strap is sampled high, the integrated Deep S4/S5 Well (DSW) On-Die VR mode is enabled.
SATA2GP/GPIO36	Reserved	Rising edge of PWROK	This signal has a weak internal pull-down. <b>Note:</b> The internal pull-down is disabled after PLTRST# de-asserts. <b>Note:</b> This signal should not be pulled high when strap is sampled.

## 2.27 External RTC Circuitry

The PCH implements an internal oscillator circuit that is sensitive to step voltage changes in VccRTC. Figure 2-2 shows an example schematic recommended to ensure correct operation of the PCH RTC.

**Figure 2-2. Example External RTC Circuit**



**Notes:**

1. The exact capacitor values for C1 and C2 must be based on the crystal maker recommendations.
2. Reference designators are arbitrarily assigned.
3. For platforms not supporting Deep S4/S5, the VccDSW3\_3 pins will be connected to the VccSus3\_3 pins.
4. Vbatt is voltage provided by the RTC battery (for example, coin cell).
5. VccRTC, RTCX1, RTCX2, RTCRST#, and SRTCST# are PCH pins.
6. VccRTC powers PCH RTC well.
7. RTCX1 is the input to the internal oscillator.
8. RTCX2 is the amplified feedback for the external crystal.

§





## 3 PCH Pin States

### 3.1 Integrated Pull-Ups and Pull-Downs

**Table 3-1. Integrated Pull-Up and Pull-Down Resistors**

Signal	Resistor	Nominal	Notes
GPIO[67:64]	Pull-down	20K	1, 10
GPIO15	Pull-down	20K	3
HDA_SDIN[3:0]	Pull-down	20K	2
HDA_SYNC, HDA_SDO	Pull-down	20K	2, 5
GNT[3:1]#/GPIO[55,53,51],	Pull-up	20K	3, 6, 7
GPIO8	Pull-up	20K	3, 12
LAD[3:0]#	Pull-up	20K	3
LDRQ0#, LDRQ1# / GPIO23	Pull-up	20K	3
DF_TVS	Pull-down	20k	8
PME#	Pull-up	20K	3
INIT3_3V#	Pull-up	20K	3
PWRBTN#	Pull-up	20K	3
SPI_MOSI	Pull-down	20K	3, 5
SPI_MISO	Pull-up	20K	3
SPKR	Pull-down	20K	3, 9
TACH[7:0]/GPIO[71:68,7,6,1,17]	Pull-up	20K	3 (only on TACH[7:0])
USB[13:0] [P,N]	Pull-down	20K	4
GPIO72	Pull-up	20K	3
GPIO27	Pull-up	20K	3, 14
JTAG_TDI, JTAG_TMS	Pull-up	20K	1, 11
JTAG_TCK	Pull-down	20K	1, 11
GPIO28	Pull-up	20K	3, 12
SATA[3:2]GP/GPIO[37:36]	Pull-down	20K	3, 9
GPIO31/MGPIO2	Pull-down	20K	3, 15
GPIO44	Pull-up	20K	1, 12
SST	Pull-down	10K	16
GPIO46	Pull-up	20K	1, 12
SATA1GP/GPIO19	Pull-up	20K	3, 9
SUSACK#	Pull-up	20K	3
PECI	Pull-down	350	17
SASSMBCLK0, SASSMBDATA0	Pull-up	20K	3
SASSMBCLK1, SASSMBDATA1	Pull-up	20K	3
SASSMBCLK2, SASSMBDATA2	Pull-up	20K	3

**Notes:**

1. Simulation data shows that these resistor values can range from 10 kΩ to 40 kΩ.
2. Simulation data shows that these resistor values can range from 9 kΩ to 50 kΩ.
3. Simulation data shows that these resistor values can range from 15 kΩ to 40 kΩ.



4. Simulation data shows that these resistor values can range from 14.25 kΩ to 24.8 kΩ
5. The pull-up or pull-down on this signal is only enabled at boot/reset for strapping function.
6. The pull-up on this signal is not enabled when PCIRST# is high.
7. The pull-up on this signal is not enabled when PCH\_PWROK is low.
8. Simulation data shows that these resistor values can range from 15 kΩ to 31 kΩ.
9. The Pull-up or pull down is not active when PLTRST# is NOT asserted.
10. The pull-down is enabled when PCH\_PWROK is low.
11. External termination is also required on these signals for JTAG enabling.
12. Pull-up is disabled after RSMRST# is deasserted.
13. Not applicable for PCH.
14. Pull-up is enabled only in Deep-S4/5 state.
15. Pull-down is enabled only in Deep-S4/5 state.
16. When the interface is in BUS IDLE, the Internal Pull-down of 10K is enabled. In normal transmission, a 400 ohm pull down takes effect, the signal will be override to logic 1 with pull-up resistor (37 ohms) to VCC 1.5 V.
17. This is a 350-Ω normal pull-down, signal will be overridden to logic 1 with pull-up resistor (31 Ω) to VCC 1.1 V.

## 3.2 Output and I/O Signals Planes and States

Table 3.2 shows the power plane associated with the output and I/O signals, as well as the state at various times. Within the table, the following terms are used:

“High-Z”	Tri-state. PCH not driving the signal high or low.
“High”	PCH is driving the signal to a logic 1.
“Low”	PCH is driving the signal to a logic 0.
“Defined”	Driven to a level that is defined by the function or external pull-up/pull-down resistor (will be high or low).
“Undefined”	PCH is driving the signal, but the value is indeterminate.
“Running”	Clock is toggling or signal is transitioning because function not stopping.
“Off”	The power plane is off; PCH is not driving when configured as an output or sampling when configured as an input.
“Input”	PCH is sampling and signal state determined by external driver.

**Note:** Signal levels are the same in S4 and S5, except as noted.

PCH suspend well signal states are indeterminate and undefined and may glitch prior to RSMRST# deassertion. This does not apply to SLP\_S3#, SLP\_S4# and SLP\_S5#. These signals are determinate and defined prior to RSMRST# deassertion.

PCH core well signal states are indeterminate and undefined and may glitch prior to PCH\_PWROK assertion. This does not apply to THRMTRIP#. This signal is determinate and defined prior to PCH\_PWROK assertion.

DSW indicates PCH Deep Sleep Well. This state provides a few wake events and critical context context to allow system to draw minimal power in S4 or S5 states.

ASW indicates PCH Active Sleep Well. This power well contains functionality associated with active usage models while the host system is in Sx.



Table 3-2. Power Plane and States for Output and I/O Signals (Sheet 1 of 4)

Signal Name	Power Plane	During Reset <sup>2</sup>	Immediately after Reset <sup>2</sup>	S0/S1	S3	S4/S5
<b>PCI Express</b>						
PET[8:1]p, PET[8:1]n	Core	Low	Low <sup>4</sup>	Defined	OFF	OFF
<b>DMI</b>						
DMI_TXP[3:0], DMI_TXN[3:0]	Core	Low	Low	Defined	Off	Off
<b>PCI Bus</b>						
AD[31:0]	Core	Low	Low	Low	Off	Off
C/BE[3:0]#	Core	Low	Low	Low	Off	Off
DEVSEL#	Core	High-Z	High-Z	High-Z	Off	Off
FRAME#	Core	High-Z	High-Z	High-Z	Off	Off
GNT0# <sup>7</sup> , GNT[3:1]# <sup>7</sup> / GPIO[55, 53, 51]	Core	High	High	High	Off	Off
IRDY#, TRDY#	Core	High-Z	High-Z	High-Z	Off	Off
PAR	Core	Low	Low	Low	Off	Off
PCIRST#	Suspend	Low	High	High	Low	Low
PERR#	Core	High-Z	High-Z	High-Z	Off	Off
PLOCK#	Core	High-Z	High-Z	High-Z	Off	Off
STOP#	Core	High-Z	High-Z	High-Z	Off	Off
<b>LPC/FWH Interface</b>						
LAD[3:0]	Core	High	High	High	Off	Off
LFRAME#	Core	High	High	High	Off	Off
INIT3_3V# <sup>7</sup>	Core	High	High	High	Off	Off
<b>SATA Interface</b>						
SATA[5:0]TXP, SATA[5:0]TXN	Core	High-Z	High-Z	Defined	Off	Off
SATALED#	Core	High-Z	High-Z	Defined	Off	Off
SATAICOMPO	Core	High	High	Defined	Off	Off
SCLOCK/GPIO22	Core	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SLOAD/GPIO38	Core	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SDATAOUT[1:0]/GPIO[48,39]	Core	High-Z	High-Z	High-Z	Off	Off
SATA3RBIAS	Core	Terminated to Vss	Terminated to Vss	Terminated to Vss	Off	Off
SATA3ICOMPO	Core	High-Z	High-Z	High-Z	Off	Off
SATA3RCOMPO	Core	High-Z	High-Z	High-Z	Off	Off
<b>Interrupts</b>						
PIRQ[A:D]#,	Core	High-Z	High-Z	High-Z	Off	Off
PIRQ[H:E]# / GPIO[5:2]	Core	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SERIRQ	Core	High-Z	High-Z	High-Z	Off	Off
<b>USB Interface</b>						
USB[13:0][P,N]	Suspend	Low	Low	Defined	Defined	Defined



**Table 3-2. Power Plane and States for Output and I/O Signals (Sheet 2 of 4)**

Signal Name	Power Plane	During Reset <sup>2</sup>	Immediately after Reset <sup>2</sup>	S0/S1	S3	S4/S5
USBRBIAS	Suspend	High-Z	High-Z	High	High	High
<b>Power Management</b>						
LAN_PHY_PWR_CTRL <sup>10</sup> / GPIO12	Suspend	Low	Low	Defined	Defined	Defined
PLTRST#	Suspend	Low	High	High	Low	Low
SLP_A# <sup>5</sup>	Suspend	Low	High	High	Defined	Defined
SLP_S3#	Suspend	Low	High	High	Low	Low
SLP_S4#	Suspend	Low	High	High	High	Defined
SLP_S5#/GPIO63	Suspend	Low	High	High	High	Defined <sup>2</sup>
SLP_SUS#	DSW	Low	High	High	High	High
SUSCLK	Suspend	Low	Running			
DRAMPWROK	Suspend	Low	High-Z	High-Z	High-Z	Low
PM_SYNC	Core	Low	Low	Defined	Off	Off
PM_SYNC2	Core	Low	Low	Defined	Off	Off
SLP_LAN#/GPIO29 <sup>8</sup> SLP_LAN# (using soft-strap) GPIO29 (using soft-strap)	Suspend	Low High-z	Low <sup>8</sup> High-z	High High-z	Defined High-z	Defined High-z
<b>Processor Interface</b>						
PROCPWRGD	Processor	Low	High	High	Off	Off
<b>SMBus Interface</b>						
SMBCLK, SMBDATA	Suspend	High-Z	High-Z	Defined	Defined	Defined
<b>SAS SMBus Interface</b>						
SASSMBCLK0, SASSMBDATA0	CORE	High-Z	High-Z	Defined	Off	Off
<b>SAS SMBus Interface (Intel® C606, C608 Chipset SKUs Only)</b>						
SASSMBCLK1, SASSMBDATA1	CORE	High-Z	High-Z	Defined	Off	Off
<b>SAS SMBus Interface (Intel® C608 Chipset SKU Only)</b>						
SASSMBCLK2, SASSMBDATA2	CORE	High-Z	High-Z	Defined	Off	Off
<b>System Management Interface</b>						
SML0ALERT# / GPIO60	Suspend	High-Z	High-Z <sup>12</sup>	Defined	Defined	Defined
SML0DATA	Suspend	High-Z	High-Z	Defined	Defined	Defined
SML0CLK	Suspend	High-Z	High-Z	Defined	Defined	Defined
GPIO58/SML1CLK	Suspend	High-Z	High-Z	Defined	Defined	Defined
SML1ALERT#/PCH_HOT#/ GPIO74	Suspend	High-Z	High-Z	Defined	Defined	Defined
SML1DATA/GPIO75	Suspend	High-Z	High-Z	Defined	Defined	Defined
<b>Miscellaneous Signals</b>						
SPKR <sup>7</sup>	Core	Low	Low	Defined	Off	Off
JTAG_TDO	Suspend	High-Z	High-Z	High-Z	High-Z	High-Z
<b>Intel® HD Audio Interface</b>						
HDA_RST#	Suspend	Low	Low <sup>3</sup>	Defined	Low	Low



Table 3-2. Power Plane and States for Output and I/O Signals (Sheet 3 of 4)

Signal Name	Power Plane	During Reset <sup>2</sup>	Immediately after Reset <sup>2</sup>	S0/S1	S3	S4/S5
HDA_SDO <sup>7</sup>	Suspend	Low	Low	Defined	Low	Low
HDA_SYNC <sup>7</sup>	Suspend	Low	Low	Defined	Low	Low
HDA_BCLK <sup>13</sup>	Suspend	Low	Low	Low	Low	Low
<b>UnMultiplexed GPIO Signals</b>						
GPIO8	Suspend	High	High	Defined	Defined	Defined
GPIO15 <sup>7</sup>	Suspend	Low	Low	Defined	Defined	Defined
GPIO24	Suspend	Low	Low	Defined	Defined	Defined
GPIO27(Non-Deep S4/S5 mode)	DSW	High-Z	High-Z	High-Z	High-Z	High-Z
GPIO27(Deep S4/S5 mode)	DSW	High-Z	High-Z	High-Z	High-Z	High-Z
GPIO28 <sup>12</sup>	Suspend	High	Low	Low	Low	Low
GPIO32	Core	High	High	Defined	Off	Off
GPIO57	Suspend	High-Z (Input)	High-Z (Input)	Defined	Defined	Defined
GPIO72 <sup>9</sup>	Suspend	High	High	Defined	Defined	Defined
<b>Multiplexed GPIO Signals used as GPIO only</b>						
GPIO0	Core	High-Z (Input)	High-Z (Input)	Defined	Off	Off
GPIO13 <sup>9, 14</sup>	Suspend	High-Z	High-Z	High-Z	High-Z	High-Z
GPIO20	Core	High-Z (Input)	High-Z (Input)	Defined	Off	Off
GPIO30 <sup>9</sup>	Suspend	High-Z (Input)	High-Z (Input)	Defined	Defined	Defined
GPIO31 <sup>9</sup> (Non Deep-S4/S5 mode)	DSW	High-Z (Input)	High-Z (Input)	Defined	Defined	Defined
GPIO31 <sup>9</sup> (Deep-S4/S5 mode)	DSW	High-Z (Input)	High-Z (Input)	Defined	Defined	Defined
GPIO33 <sup>9</sup>	Core	High	High	High	Off	Off
GPIO34	Core	High-Z (Input)	High-Z (Input)	Defined	Off	Off
GPIO35/NMI#	Core	Low	Low	Defined	Off	Off
GPIO[46: 44]	Suspend	High-Z (Input)	High-Z (Input)	Defined	Defined	Defined
GPIO61	Suspend	Low	High	High	Low	Low
<b>SPI Interface</b>						
SPI_CS0#	ASW	High <sup>12</sup>	High	Defined	Defined	Defined
SPI_CS1#	ASW	High <sup>12</sup>	High	Defined	Defined	Defined
SPI_MOSI	ASW	Low <sup>12</sup>	Low	Defined	Defined	Defined
SPI_CLK	ASW	Low <sup>12</sup>	Low	Running	Defined	Defined
<b>Thermal Reporting</b>						
PWM[3:0]	Core	Low	Low	Defined	Off	Off
SST	Suspend	Low	Low	Defined	Off	Off
PECI	Processor	Low	Low	Defined	Off	Off
<b>SAS Interface (SRV/WS SKUs Only)</b>						
SAS[3:0]TXN, SAS[3:0]TXP	CORE	High-Z	High-Z	Defined	Off	Off
SAS_CLOCK1	CORE	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SAS_LOAD1	CORE	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SAS_DATAIN1	CORE	High-Z (Input)	High-Z (Input)	Defined	Off	Off



**Table 3-2. Power Plane and States for Output and I/O Signals (Sheet 4 of 4)**

Signal Name	Power Plane	During Reset <sup>2</sup>	Immediately after Reset <sup>2</sup>	S0/S1	S3	S4/S5
SAS_DATAOUT1	CORE	High-Z	High-Z	High-Z	Off	Off
SAS_RBIASN0, SAS_RBIASP0	Core	Terminated to Vss	Terminated to Vss	Terminated to Vss	Off	Off
<b>SAS Interface (Intel® C606, C608 Chipset SKUs Only)</b>						
SAS[7:4]TXN, SAS[7:4]TXP	CORE	High-Z	High-Z	Defined	Off	Off
SAS_CLOCK2	CORE	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SAS_LOAD2	CORE	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SAS_DATAIN2	CORE	High-Z (Input)	High-Z (Input)	Defined	Off	Off
SAS_DATAOUT2	CORE	High-Z	High-Z	High-Z	Off	Off
SAS_RBIASN1, SAS_RBIASP1	Core	Terminated to Vss	Terminated to Vss	Terminated to Vss	Off	Off
<b>PCIe* Uplink (Intel® C606, C608 Chipset SKUs Only)</b>						
PEGO_TXN_[3:0], PEGO_TXP_[3:0]	CORE	High-Z	Defined	Defined	Off	Off
PEGO_RBIASN, PEG_RBIASP	Core	Terminated to Vss	Terminated to Vss	Terminated to Vss	Off	Off

**Notes:**

- The states of Core and processor signals are evaluated at the times During PLTRST# and Immediately after PLTRST#. The states of the Suspend signals are evaluated at the times During RSMRST# and Immediately after RSMRST#, with an exception to GPIO signals; refer to Section 2.23 for more details on GPIO state after reset. The states of the HDA signals are evaluated at the times During HDA\_RST# and Immediately after HDA\_RST#
- SLP\_S5# signals will be high in the S4 state and low in the S5 state.
- Low until Intel HD Audio Controller Reset bit set (D27:F0:Offset HDBAR+08h:bit 0), at which time HDA\_RST# will be High and HDA\_BIT\_CLK will be Running.
- PETp/n[8:1] low until port is enabled by software.
- The SLP\_A# state will be determined by Intel ME Policies.
- The state of signals in S3-5 will be defined by Intel ME Policies.
- This signal is sampled as a functional strap during reset. Refer to Functional straps definition table for usage.
- SLP\_LAN# behavior after reset is dependent on value of SLP\_LAN# default value bit. A soft-strap is used to select between SLP\_LAN# and GPIO usage. When strap is set to 0 (default), pin is used as SLP\_LAN#, when soft-strap is set to 1, pin is used as GPIO29.
- Native functionality multiplexed with these GPIOs are not utilized in PCH.
- Native/GPIO functionality controlled using soft straps. Default to Native functionality until soft straps are loaded.
- State of the pins depend on the source of VccASW power.
- Pin is tri-stated prior to APWROK assertion during Reset.
- When Controller Reset Bit of Global Control Register (D27:F0 Offset HDBAR 08h bit 0) gets set, this pin will start toggling.
- GPIO13 is powered by VccSusHDA (either 3.3 V or 1.5 V). Voltage tolerance on the signal is the same as VccSusHDA.



### 3.3 Power Planes for Input Signals

Table 3-3 shows the power plane associated with each input signal, as well as what device drives the signal at various times. Valid states include:

High

Low

Static: Will be high or low, but will not change

Driven: Will be high or low, and is allowed to change

Running: For input clocks

PCH suspend well signal states are indeterminate and undefined and may glitch prior to RSMRST# deassertion. This does not apply to SLP\_S3#, SLP\_S4# and SLP\_S5#. These signals are determinate and defined prior to RSMRST# deassertion.

PCH core well signal states are indeterminate and undefined and may glitch prior to PCH\_PWROK assertion. This does not apply to FERR# and THRMTRIP#. These signals are determinate and defined prior to PCH\_PWROK assertion.

**Table 3-3. Power Plane for Input Signals (Sheet 1 of 3)**

Signal Name	Power Well	Driver During Reset	S0/S1	S3	S4/S5
<b>DMI</b>					
DMI_RXP[3:0], DMI_RXN[3:0]	Core	Processor	Driven	Off	Off
<b>PCI Express</b>					
PER[8:1]p, PER[8:1]n	Core	PCI Express* Device	Driven	Off	Off
<b>PCI Bus</b>					
REQ0#, REQ1# / GPIO50 <sup>1</sup> REQ2# / GPIO52 <sup>1</sup> REQ3# / GPIO54 <sup>1</sup>	Core	External Pull-up	Driven	Off	Off
PME#	Suspend	Internal Pull-up	Driven	Driven	Driven
SERR#	Core	PCI Bus Peripherals	Driven	Off	Off
<b>LPC Interface</b>					
LDRQ0#	Core	LPC Devices	Driven	Off	Off
LDRQ1# / GPIO23 <sup>1</sup>	Core	LPC Devices	Driven	Off	Off
<b>SATA Interface</b>					
SATA[5:0]RXP, SATA[5:0]RXN	Core	SATA Drive	Driven	Off	Off
SATAICOMPI	Core	High-Z	Driven	Off	Off
SATA[5:4]GP/ GPIO[49,16] <sup>1</sup>	Core	External Device or External Pull-up/Pull-down	Driven	Off	Off
SATA0GP / GPIO[ 21] <sup>1</sup>	Core	External Device or External Pull-up/Pull-down	Driven	Off	Off
SATA1GP/GPIO19	Core	Internal Pull-up	Driven	Off	Off
SATA[3:2]GP/ GPIO[37:36]	Core	Internal Pull-down	Driven	Off	Off
SATA3COMPI	Core	External Pull-up	Driven	Off	Off



**Table 3-3. Power Plane for Input Signals (Sheet 2 of 3)**

Signal Name	Power Well	Driver During Reset	S0/S1	S3	S4/S5
<b>USB Interface</b>					
OC[7:0]#/GPIO[14,10,9,43:40,59] <sup>1</sup>	Suspend	External Pull-ups	Driven	Driven	Driven
USBRBIAS#	Suspend	External Pull-down	Driven	Driven	Driven
<b>Power Management</b>					
APWROK	Suspend	External Circuit	High	Driven	Driven
PWRBTN#	DSW	Internal Pull-up	Driven	Driven	Driven
PCH_PWROK	RTC	External Circuit	Driven	Driven	Driven
DPWROK	RTC	External Circuit	Driven	Driven	Driven
RI#	Suspend	Serial Port Buffer	Driven	Driven	Driven
RSMRST#	RTC	External RC Circuit	High	High	High
SYS_RESET#	Core	External Circuit	Driven	Off	Off
SYS_PWROK	Suspend	External Circuit	High	Driven	Driven
THRMTRIP#	Core (Processor)	External Thermal Sensor	Driven	Off	Off
WAKE#	Suspend	External Pull-up	Driven	Driven	Driven
<b>Processor Interface</b>					
A2OGATE	Core	External Micro controller or Pull-up	Static	Off	Off
RCIN#	Core	External Micro controller	High	Off	Off
<b>System Management Interface</b>					
SMBALERT# / GPIO11	Suspend	External Pull-up	Driven	Driven	Driven
INTRUDER#	RTC	External Switch	Driven	Driven	Driven
<b>JTAG Interface</b>					
JTAG_TDI <sup>3</sup>	Suspend	Internal Pull-up	High	High	High
JTAG_TMS <sup>3</sup>	Suspend	Internal Pull-up	High	High	High
JTAG_TCK <sup>3</sup>	Suspend	Internal Pull down	Low	Low	Low
<b>Miscellaneous Signals</b>					
INTVRMEN <sup>2</sup>	RTC	External Pull-up	High	High	High
RTCST#	RTC	External RC Circuit	High	High	High
SRTCST#	RTC	External RC Circuit	High	High	High
<b>Clock Interface</b>					
CLKIN_SATA_N, CLKIN_SATA_P	Core	Clock Generator	Running	Off	Off
CLKIN_DOT_96P, CLKIN_DOT_96N	Core	Clock Generator	Running	Off	Off
CLKIN_PCI	Core	Clock Generator	Running	Off	Off
CLKIN_SAS0_N, CLKIN_SAS0_P	Core	Clock Generator	Running	Off	Off
REFCLK14IN	Core	Clock Generator	Running	Off	Off



Table 3-3. Power Plane for Input Signals (Sheet 3 of 3)

Signal Name	Power Well	Driver During Reset	S0/S1	S3	S4/S5
<b>Clock Interface (Intel® C606, C608 Chipset SKUs Only)</b>					
CLKIN_SPCIE0_N, CLKIN_SPCIE0_P	Core	Clock Generator	Running	Off	Off
CLKIN_SAS1_N, CLKIN_SAS1_P	Core	Clock Generator	Running	Off	Off
<b>Intel® HD Audio Interface</b>					
HDA_SDIN[3:0]	Suspend	Internal Pull-down	Driven	Low	Low
<b>SPI Interface</b>					
SPI_MISO	ASW	Internal Pull-up	Driven	Driven	Driven
<b>Thermal Control</b>					
TACH[7:0]/ GPIO[71:68,7,6,1,17] <sup>1</sup>	Core	Internal Pull-up	Driven	Off	Off
<b>SAS Interface</b>					
SAS[3:0]RXP, SAS[3:0]RXN	Core	Internal Pull-down	Driven	Off	Off
<b>SAS Interface (Intel® C606, C608 Chipset SKUs Only)</b>					
SAS[7:4]RXP, SAS[7:4]RXN	Core	Internal Pull-down	Driven	Off	Off
<b>PCIe3 Uplink (Intel® C606, C608 Chipset SKUs Only)</b>					
PEGO_RXN_[3:0], PEGO_RXP_[3:0]	CORE	High-Z	Defined	Defined	Off

**Notes:**

1. These signals can be configured as outputs in GPIO mode.
2. This signal is sampled as a functional strap during Reset. Refer to Functional straps definition table for usage.
3. External termination is also required for JTAG enabling.







## 4 System Clock Domains

The PCH uses clock source inputs provided by CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only), external clock chips. The inputs to PCH include:

- 100 MHz differential, PCI Express 2.0 spec compliant, SSC capable
- 100 MHz differential isolated for SATA, SSC capable
- 100 MHz differential isolated for SAS, non SSC (SRV/WS SKUs Only)
- 100 MHz differential for PCIe Uplink ports, SSC capable
- 96 MHz differential, non SSC
- 14.318 MHz single-ended non SSC

### 4.1 System Clock Domains

Table 4-1 shows the system clock input to the PCH. Table 4-1 shows system clock domains generated by the PCH.

**Table 4-1. PCH Clock Inputs**

Signal	Frequency	Usage
CLKIN_DMI_P, CLKIN_DMI_N	100 MHz	100 MHz differential reference clock from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). Used for DMI and PCIe 2.0 when clock isolation is disabled. Used for DMI only when clock isolation is enabled
CLKIN_SATA_P, CLKIN_SATA_N	100 MHz	100 MHz differential reference clock from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). Used for SATA.
CLKIN_DOT96_P, CLKIN_DOT96_N	96 MHz	96 MHz differential reference clock from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only).
CLKIN_PCI	33.3 MHz	33.3 MHz PCI reference clock
REFCLK14IN	14.31818 MHz	Single-ended 14.31818 MHz reference clock from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). Used for 8254 Timer, ACPI Timer and HPET.
RTCX1	32.768 KHz	Reference input for RTC Oscillator
RTCX2	32.768 KHz	See above
CLKIN_SAS0_P, CLKIN_SAS0_N	100 MHz	100 MHz differential reference clock from CK420BQ (SRV/WS SKUs Only). Used as SAS clock for SCU0 (SAS Controller Unit) and SCU1.
CLKIN_SAS1_P, CLKIN_SAS1_N	100 MHz	100 MHz differential reference clock from CK420BQ (SRV/WS SKUs Only). Used as supplemental clock source for SCU1 in Intel® C606, C608 Chipset SKUs.
CLKIN_SPCIE0_P, CLKIN_SPCIE0_N	100 MHz	100 MHz differential reference clock from CK420BQ (SRV/WS SKUs Only). Used as upstream PCIe Uplink switch port clock reference

**Table 4-2. PCH Clock Outputs**

Signal	Frequency	Usage
GP22_SCLOCK	32.768 KHz	SCLOCK is SATA SGPIO Reference Clock. Can also be used as GPIO22
SUSCLK_GP62	32.768 KHz	SUSCLK is a suspend clock output from RTC generator circuit. Can also be used as GPIO62
SPI_CLK	17.86 MHz/ 20.83 MHz/ 31.25 MHz	SPI Flash clock output

Figure 4-1 and Figure 4-2 show the high level block diagram of PCH clocking.

**Figure 4-1. PCH High-Level Clock Diagram (SRV/WS SKUs Only)**

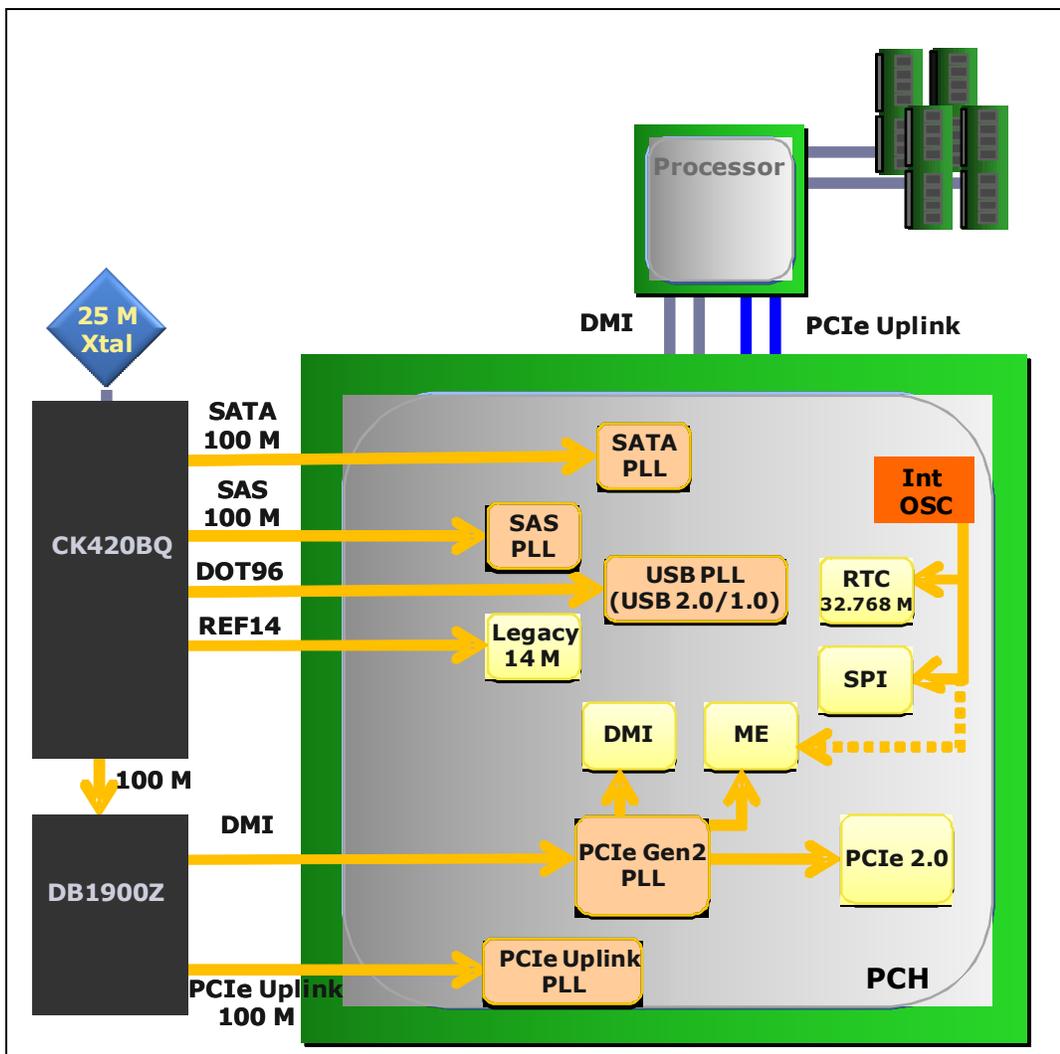
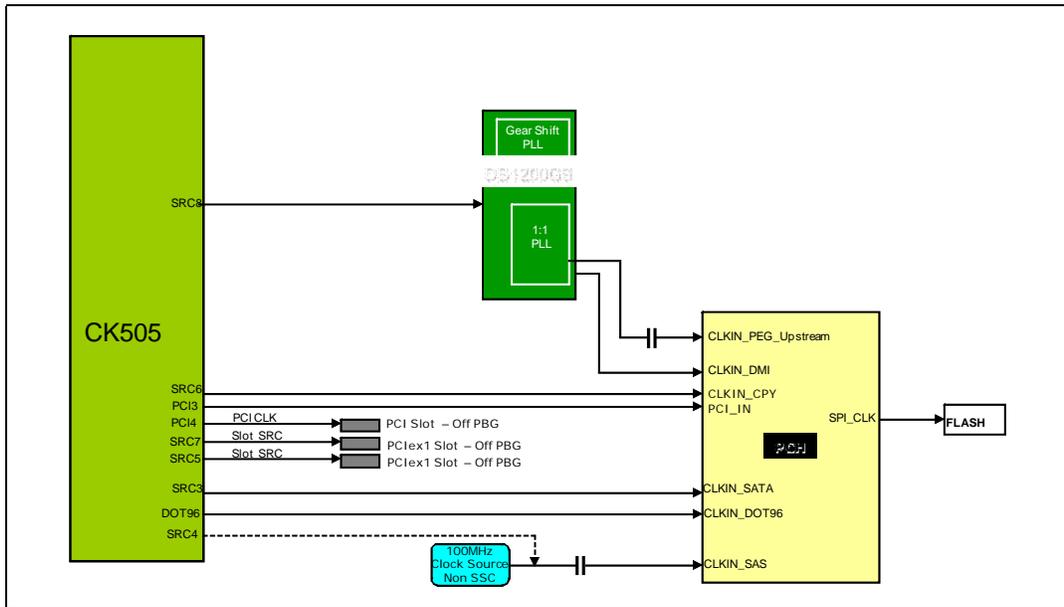




Figure 4-2. PCH High-Level Clock Diagram (HEDT SKU Only)



## 4.2 Functional Blocks

Table 4-3 describes the PLLs on the PCH and the clock domains that are driven from the PLLs.

Table 4-3. PCH PLLs (Sheet 1 of 2)

PLL	Outputs Frequency	Description/Usage
DMI PLL	2.5 GHz/625 MHz/250 MHz	Source clock is 100 MHz from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). The PLL resource to generate the DMI port clocks when clock isolation is enabled. Uses CLKIN_DMI input. This PLL is shut down when clock isolation is disabled. Resides in core power well and is not powered in S3 and below states.
PCIe2 PLL	2.5 GHz/625 MHz/250 MHz	Source clock is 100 MHz from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). PCIe2 PLL drives clocks to PCIe 2.0 ports, Intel ME/VE engines <sup>2</sup> (in S0 state) and the NAND interface logic <sup>2</sup> (in S0 state). It is also used to supply DMI clocks when clock isolation is disabled. Can be configured to use CLKIN_DMI (when clock isolation is disabled) or optional CLKIN_CPY input (when clock isolation is enabled). Resides in core power well and is not powered in S3 and below states.
SATA PLL	3.0 GHz/1.5 GHz/300 MHz/150 MHz	Source clock is 100 MHz from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). This PLL generates clocks for SATA Gen2 and SATA Gen3 ports. Uses CLKIN_SATA input. Resides in core power well and is not powered in S3 and below states.



Table 4-3. PCH PLLs (Sheet 2 of 2)

PLL	Outputs Frequency	Description/Usage
USB PLL	24 MHz/48 MHz/240 MHz/ 480 MHz	Source clock is 96 MHz from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). Uses CLKIN_DOT96 input. Used for USB 2.0/1.0 logic. Resides in core power well and is not powered in S3 and below states.
PCIe Uplink PLL (SRV/WS SKUs Only)	4.0 GHz/500 MHz/250 MHz	Source clock is 100 MHz from CK420BQ (SRV/WS SKUs Only) or CK505 (HEDT SKU Only). There are two PCIe Uplink PLLs in PCH. They generate clocks for PCIe Uplink ports. Uses CLKIN_SPCIE0 input. Resides in core power well and is not powered in S3 and below states.
SAS PLL (SRV/WS SKUs Only)	3.0 GHz/1.5 GHz	Source clock is 100 MHz from CK420BQ (SRV/WS SKUs Only). For Intel® C602, C602J, C604 Chipset SKUs, the SAS PLL generates all the required SAS clocks. It uses CLKIN_SAS0 input. For Intel® C606, C608 Chipset SKUs, there are two SAS PLLs and each SCU (SAS Controller Unit) has one SAS PLL to provide SAS clocks for it. They use CLKIN_SAS[1:0] as inputs, where CLKIN_SAS0 is used for the first SCU and CLKIN_SAS1 for the second SCU. Resides in core power well and is not powered in S3 and below states.

§



## 5 Functional Description

This chapter describes the functions and interfaces of the PCH.

### 5.1 PCI-to-PCI Bridge (D30:F0)

The PCI-to-PCI bridge resides in PCI Device 30, Function 0 on bus #0. This portion of the PCH implements the buffering and control logic between PCI and Direct Media Interface (DMI). The arbitration for the PCI bus is handled by this PCI device. The PCI decoder in this device must decode the ranges for the DMI. All register contents are lost when core well power is removed.

DMI is the chip-to-chip connection between the Processor and PCH. This high-speed interface integrates advanced priority-based servicing allowing for concurrent traffic and true isochronous transfer capabilities. Base functionality is completely software transparent permitting current and legacy software to operate normally. New for PCH the DMI interface operates at 5.0 GT/s.

To provide for true isochronous transfers and configurable Quality of Service (QoS) transactions, the PCH supports two virtual channels on DMI — VC0 and VC1. These two channels provide a fixed arbitration scheme where VC1 is always the highest priority. VC0 is the default conduit of traffic for DMI and is always enabled. VC1 must be specifically enabled and configured at both ends of the DMI link (that is, the PCH and processor).

Configuration registers for DMI, virtual channel support, and DMI active state power management (ASPM) are in the RCRB space in the Chipset Config Registers ([Chapter 10.1](#)).

DMI is also capable of operating in the AC terminated mode for servers. A hardware strap is used to configure DMI in AC terminated mode, see [Section 2.26](#) for details.

#### 5.1.1 PCI Bus Interface

The PCH PCI interface supports *PCI Local Bus Specification*, Revision 2.3, at 33 MHz. The PCH integrates a PCI arbiter that supports up to four external PCI bus masters in addition to the internal PCH requests.

See [Section 5.2](#) for alternative methods for supporting PCI devices.

#### 5.1.2 PCI Bridge As an Initiator

The bridge initiates cycles on the PCI bus when granted by the PCI arbiter. The bridge generates the cycle types shown in [Table 5-1](#).

**Table 5-1. PCI Bridge Initiator Cycle Types**

Command	C/BE#	Notes
I/O Read/Write	2h/3h	Non-posted
Memory Read/Write	6h/7h	Writes are posted
Configuration Read/Write	Ah/Bh	Non-posted
Special Cycles	1h	Posted



### 5.1.2.1 Memory Reads and Writes

The bridge bursts memory writes on PCI that are received as a single packet from DMI.

### 5.1.2.2 I/O Reads and Writes

The bridge generates single DW I/O read and write cycles. When the cycle completes on the PCI bus, the bridge generates a corresponding completion on DMI. If the cycle is retried, the cycle is kept in the down bound queue and may be passed by a postable cycle.

### 5.1.2.3 Configuration Reads and Writes

The bridge generates single DW configuration read and write cycles. When the cycle completes on the PCI bus, the bridge generates a corresponding completion. If the cycle is retried, the cycle is kept in the down bound queue and may be passed by a postable cycle.

### 5.1.2.4 Locked Cycles

The bridge propagates locks from DMI per the *PCI Local Bus Specification*. The PCI bridge implements bus lock, which means the arbiter will not grant to any agent except DMI while locked.

If a locked read results in a target or master abort, the lock is not established (as per the *PCI Local Bus Specification*). Agents north of the PCH must not forward a subsequent locked read to the bridge if they see the first one finish with a failed completion.

### 5.1.2.5 Target / Master Aborts

When a cycle initiated by the bridge is master/target aborted, the bridge will not re-attempt the same cycle. For multiple DW cycles, the bridge increments the address and attempts the next DW of the transaction. For all non-postable cycles, a target abort response packet is returned for each DW that was master or target aborted on PCI. The bridge drops posted writes that abort.

### 5.1.2.6 Secondary Master Latency Timer

The bridge implements a Master Latency Timer using the SMLT register which, upon expiration, causes the deassertion of FRAME# at the next legal clock edge when there is another active request to use the PCI bus.

### 5.1.2.7 Dual Address Cycle (DAC)

The bridge will issue full 64-bit dual address cycles for device memory-mapped registers above 4 GB.



### 5.1.2.8 Memory and I/O Decode to PCI

The PCI bridge in the PCH is a **subtractive decode agent**, which follows the following rules when forwarding a cycle from DMI to the PCI interface:

- The PCI bridge will **positively** decode any memory/I/O address within its window registers, assuming PCICMD.MSE (D30:F0:Offset 04h:bit 1) is set for memory windows and PCICMD.IOSE (D30:F0:Offset 04h:bit 0) is set for I/O windows.
- The PCI bridge will **subtractively** decode any 64-bit memory address not claimed by another agent, assuming PCICMD.MSE (D30:F0:Offset 04h:bit 1) is set.
- The PCI bridge will **subtractively** decode any 16-bit I/O address not claimed by another agent assuming PCICMD.IOSE (D30:F0:Offset 04h:bit 0) is set.
- If BCTRL.IE (D30:F0:Offset 3Eh:bit 2) is set, the PCI bridge will **not positively** forward from primary to secondary called out ranges in the I/O window per *PCI Local Bus Specification* (I/O transactions addressing the last 768 bytes in each, 1 KB block: offsets 100h to 3FFh). The PCI bridge will still take them subtractively assuming the above rules.
- If BCTRL.VGAE (D30:F0:Offset 3Eh:bit 3) is set, the PCI bridge will **positively** forward from primary to secondary I/O and memory ranges as called out in the *PCI Bridge Specification*, assuming the above rules are met.

### 5.1.3 Parity Error Detection and Generation

PCI parity errors can be detected and reported. The following behavioral rules apply:

- When a parity error is detected on PCI, the bridge sets the SECSTS.DPE (D30:F0:Offset 1Eh:Bit 15).
- If the bridge is a master and BCTRL.PERE (D30:F0:Offset 3Eh:Bit 0) is set and one of the parity errors defined below is detected on PCI, then the bridge will set SECSTS.DPD (D30:F0:Offset 1Eh:Bit 8) and will also generate an internal SERR#.
  - During a write cycle, the PERR# signal is active, or
  - A data parity error is detected while performing a read cycle
- If an address or command parity error is detected on PCI and PCICMD.SEE (D30:F0:Offset 04h:bit 8), BCTRL.PERE, and BCTRL.SEE (D30:F0:Offset 3Eh:Bit 1) are all set, the bridge will set PSTS.SSE (D30:F0:Offset 06h:Bit 14) and generate an internal SERR#.
- If the PSTS.SSE is set because of an address parity error and the PCICMD.SEE is set, the bridge will generate an internal SERR#.
- When bad parity is detected from DMI, bad parity will be driven on all data from the bridge.
- When an address parity error is detected on PCI, the PCI bridge will never claim the cycle. This is a slight deviation from the PCI bridge spec, which says that a cycle should be claimed if BCTRL.PERE is not set. However, DMI does not have a concept of address parity error, so claiming the cycle could result in the rest of the system seeing a bad transaction as a good transaction.

### 5.1.4 PCIRST#

The PCIRST# pin is generated under two conditions:

- PLTRST# active
- BCTRL.SBR (D30:F0:Offset 3Eh:Bit 6) set to 1

The PCIRST# pin is in the suspend well. PCIRST# should be tied to PCI bus agents, but not other agents in the system.

### 5.1.5 Peer Cycles

The PCI bridge may be the initiator of peer cycles. Peer cycles include memory, I/O, and configuration cycle types. Peer cycles are only allowed through VC0, and are enabled with the following bits:

- BPC.PDE (D30:F0:Offset 4Ch:Bit 2) – Memory and I/O cycles
- BPC.CDE (D30:F0:Offset 4Ch:Bit 1) – Configuration cycles

When enabled for peer for one of the above cycle types, the PCI bridge will perform a peer decode to see if a peer agent can receive the cycle. When not enabled, memory cycles (posted and/or non-posted) are sent to DMI, and I/O and/or configuration cycles are not claimed.

Configuration cycles have special considerations. Under the *PCI Local Bus Specification*, these cycles are not allowed to be forwarded upstream through a bridge. However, to enable things such as manageability, BPC.CDE can be set. When set, type 1 cycles are allowed into the part. The address format of the type 1 cycle is slightly different from a standard PCI configuration cycle to allow addressing of extended PCI space. The format is shown as in [Table 5-2](#):

**Table 5-2. Type 1 Address Format**

Bits	Definition
31:27	Reserved (same as the <i>PCI Local Bus Specification</i> )
26:24	Extended Configuration Address – allows addressing of up to 4K. These bits are combined with Bits 7:2 to get the full register.
23:16	Bus Number (same as the <i>PCI Local Bus Specification</i> )
15:11	Device Number (same as the <i>PCI Local Bus Specification</i> )
10:8	Function Number (same as the <i>PCI Local Bus Specification</i> )
7:2	Register (same as the <i>PCI Local Bus Specification</i> )
1	0
0	Must be 1 to indicate a type 1 cycle. Type 0 cycles are not decoded.

**Note:** The PCH’s USB controllers cannot perform peer-to-peer traffic.

### 5.1.6 PCI-to-PCI Bridge Model

From a software perspective, the PCH contains a PCI-to-PCI bridge. This bridge connects DMI to the PCI bus. By using the PCI-to-PCI bridge software model, the PCH can have its decode ranges programmed by existing plug-and-play software such that PCI ranges do not conflict with graphics aperture ranges in the Host controller.



### 5.1.7 IDSEL to Device Number Mapping

When addressing devices on the external PCI bus (with the PCI slots), the PCH asserts one address signal as an IDSEL. When accessing Device 0, the PCH asserts AD16. When accessing Device 1, the PCH asserts AD17. This mapping continues all the way up to Device 15 where the PCH asserts AD31. Note that the PCH internal functions (Intel High Definition Audio, USB, SATA and PCI Bridge) are enumerated like they are off of a separate PCI bus (DMI) from the external PCI bus.

### 5.1.8 Standard PCI Bus Configuration Mechanism

The PCI Bus defines a slot based “configuration space” that allows each device to contain up to eight functions with each function containing up to 256, 8-bit configuration registers. The *PCI Local Bus Specification*, Revision 2.3 defines two bus cycles to access the PCI configuration space: Configuration Read and Configuration Write. Memory and I/O spaces are supported directly by the processor. Configuration space is supported by a mapping mechanism implemented within the PCH. The *PCI Local Bus Specification*, Revision 2.3 defines two mechanisms to access configuration space, Mechanism 1 and Mechanism 2. The PCH only supports Mechanism 1.

**Warning:** Configuration writes to internal devices, when the devices are disabled, are illegal and may cause undefined results.

## 5.2 PCI Legacy Mode

PCH may optionally use PCIe-to-PCI bridges to enable external PCI I/O devices. To be able to use PCIe-to-PCI bridges and attached legacy PCI devices, the PCH provides PCI Legacy Mode. PCI Legacy Mode allows both the PCI Express\* root port and PCIe-to-PCI bridge look like subtractive PCI-to-PCI bridges. This allows the PCI Express\* root port to subtractively decode and forward legacy cycles to the bridge, and the PCIe-to-PCI bridge continues forwarding legacy cycles to downstream PCI devices. For designs that would like to utilize PCI Legacy Mode, BIOS must program registers in the PCI-to-PCI bridge (Device 30:Function 0) and in the desired PCI Express\* Root Port (Device 28:Functions 0-7) to enable subtractive decode.

**Note:** Software must ensure that only one PCH device is enabled for Subtractive decode at a time.



## 5.3 PCI Express\*

The PCH contains up to 8 PCI Express\* root ports and one uplink port. All versions of the PCH contain the 8 root ports. The Intel® C606, C608 Chipset SKUs contain a x4 uplink port while the Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs do not. The purpose of the uplink port is to provide a direct path for the SAS controllers, SGPIO used by the SAS controllers, and SMBus ports to the processor/memory without having to be multiplexed onto the DMI bus and sharing bandwidth with the rest of the component. The uplink port is not connected to the downstream root ports (Section 5.3.2).

In all configurations, the SMBus, SGPIO and SAS (SRV/WS SKUs Only) controllers are part of a multifunction device. In the Intel® C602, C602J, C604 Chipset SKUs, the SCU, SGPIO and SMBus controllers are connected to a virtual root port that is connected to the PCH's backbone. This is Device 31 off of Bus0. For the Intel® C606, C608 Chipset, the SCU, SGPIO, and SMBus devices are connected through a virtual switch to the uplink port.

### 5.3.1 PCI Express\* UpLink Port (Bn:D0:F0) (SRV/WS SKUs Only)

The PCI Express\* Uplink here is an amalgam of two functions, an uplink port connecting to a PCI Express\* bus, and a virtual switch connecting the uplink port to the MFD (Multi-Function Device) below. The MFD contains the SAS controllers, and SMBus controllers. This uplink has the following capabilities:

- X4 link width at Gen1 speed
- MSI Interrupt Messaging
- ASPM support for L1 states
- No ISOC support

Because the PCI Express\* uplink will be connected to Intel components, not 3rd party devices, the expected/supported configuration is simply x4 as Gen1.

**Note:**

The only valid configuration for the PCI Express\* uplink is a x4 operating at Gen1 speeds. Any other configurations or speeds are out of spec and not supported.

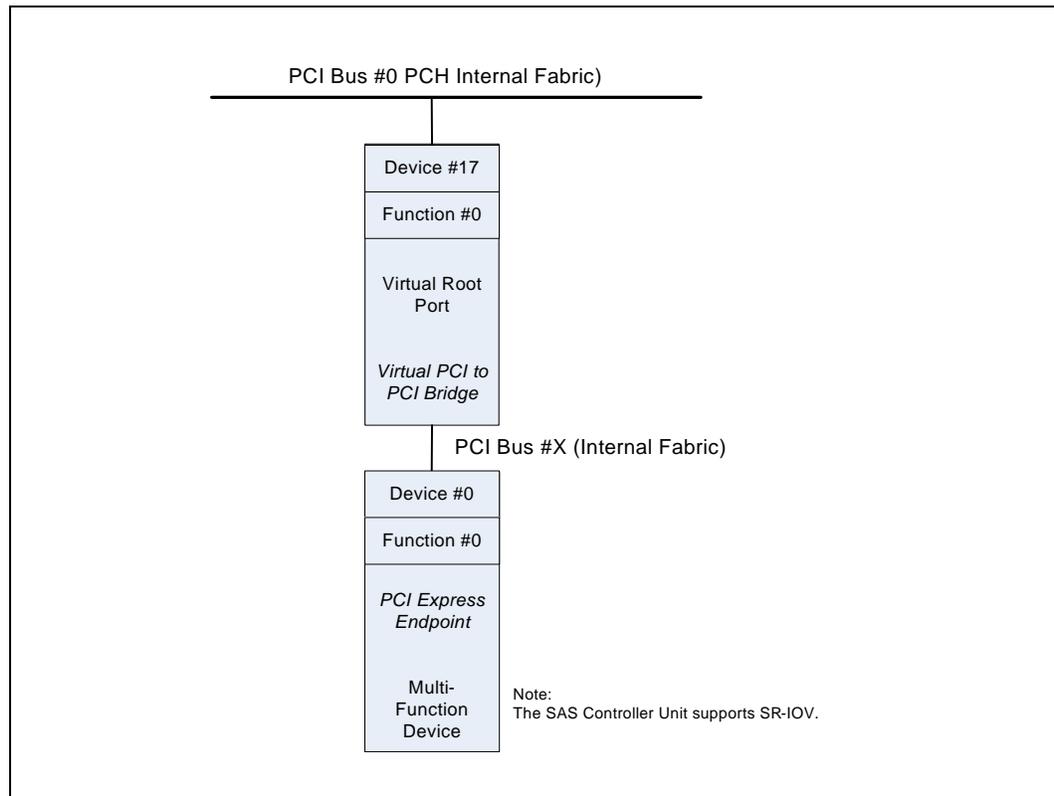


### 5.3.1.1 Programming Model and Addressing for the Intel® C602, C602J, C604 Chipset SKUs

#### 5.3.1.1.1 Programming Model for Intel® C602, C602J, C604 Chipset SKUs

The functions of the integrated MFD are exposed to software through a Root Port connected off the PCH internal fabric since there is no PCI Express\* uplink in the Intel® C602, C602J, C604 Chipset SKUs. There is no physical PCI Express\* link between the root port and the MFD so the link is “virtual”. Software will discover a virtual root port with an attached multi-function end point device. [Figure 5-1](#) shows how the virtual Root Port and the Multi-Function Device as seen by software.

**Figure 5-1. Programming Model for Intel® C602, C602J, C604 Chipset SKUs**



[Table 5-3](#) displays the functions visible to software for the Intel® C602, C602J, C604 Chipset SKUs.

**Table 5-3. Configuration Spaces Visible to Software in Intel® C602, C602J, C604 Chipset SKUs**

Function	PCI Bus Number	PCI Device Number	PCIe Function Number
<b>Note:</b> Virtual Root Port <sup>1</sup>	0	17	0
SAS Controller Unit 0	X <sup>2</sup>	0	0
Multi-function Glue unit	X	0	1
SMBus Controller 0 Unit	X	0	3

1. The current Bus/Device/Function of virtual root port is TBD.  
 2. X is a Bus number greater than Bus 0 assigned by Software.

### 5.3.1.1.2 Address Space for Intel® C602, C602J, C604 Chipset SKUs

Table 5-4 provides a summary of all the addressable spaces within Root Port and the MFD as seen from PCI Bus 0. A detailed description of these spaces follows in later sections.

**Table 5-4. Root Port and SCU Addressable Internal Spaces**

Addressable Space
Virtual Root Port Config Space
SCU Config Space(s), SCU Memory Space, SCU I/O Space
SMBus 0 Config Space, SMBus 0 Memory Space, SMBus 0 I/O Space
SMBus 1 Config Space, SMBus 1 Memory Space, SMBus 1 I/O Space

### 5.3.1.2 Programming Model and Addressing for the Intel® C606, C608 Chipset SKUs

The functions of the integrated MFD are exposed similarly to software through a downstream switch port. Again there is no physical PCI Express\* link so the link is “virtual” between the downstream switch port and the MFD.

### 5.3.1.3 Programming Model for the Intel® C606, C608 Chipset SKUs

The Intel® C606, C608 Chipset SKUs contain a PCI Express\* switch. The Intel® C606, C608 Chipset SKUs contains a x4 uplink and a “virtual” switch port that serves as the connection for the integrated MFD shown in Figure 5-2. Software will discover a virtual switch port with an attached multi-function end point device. The PCI Express\* switch is compliant to the PCI Express Base specification 2.0.

**Figure 5-2. Programming Model for the Intel® C606, C608 Chipset SKUs**

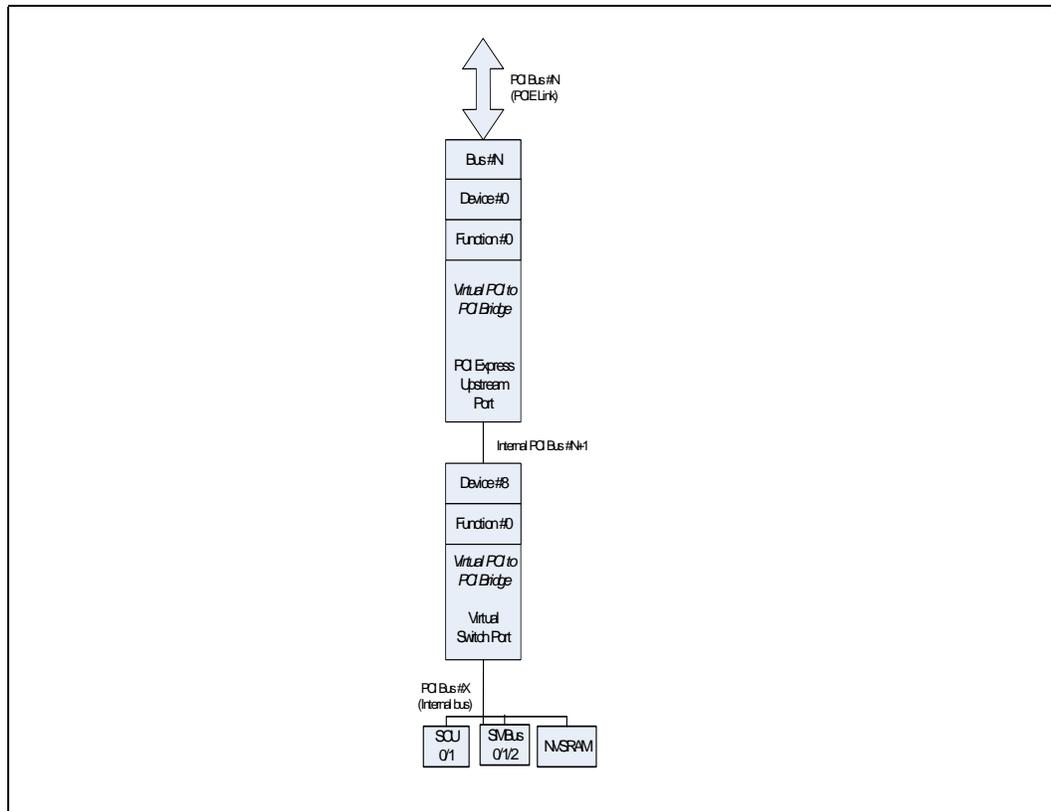




Table 5-5 shows that configuration spaces visible to software for the Intel® C606, C608 Chipset SKUs.

**Table 5-5. Configuration Spaces Visible to Software in the Intel® C606, C608 Chipset SKUs**

Function	PCI Bus Number	PCI Device Number	PCIe Function Number
PCIe Upstream	N	0	0
Virtual Switch Port	N+1	8	0
SAS Controller Unit 0/1	X <sup>1</sup>	0	0
Multi-Function Glue	X	0	1
SMBus Controller 0	X	0	3
SMBus Controller 1	X	0	4
SMBus Controller 2 (Intel® C608 Chipset SKU Only)	X	0	5

1. X is a value greater than N+1 assigned by the BIOS.

### 5.3.1.4 Address Space for Intel® C606, C608 Chipset SKUs

Table 5-6 provides a summary of all addressable spaces within the Intel® C606, C608 Chipset SKUs.

**Table 5-6. Intel® C606, C608 Chipset SKUs Addressable Internal Spaces**

Addressable Space
PCIe Upstream Port Config Space
PCIe Upstream Port Memory Space
Point-to-Point Fabric Config Space
Multi-Function Glue Config Space
SAS Controller Config Space
SAS Controller Memory Space
SAS Controller I/O Space
SMBus Controller 0-2 Config Space (only 2 for Intel® C606 Chipset SKU)
SMBus Controller 0-2 Memory Space (only 2 for Intel® C606 Chipset SKU)
SMBus Controller 0-2 IO Space (only 2 for Intel® C606 Chipset SKU)

### 5.3.1.5 Power Management

The uplink PCI Express\* port will support Active State Power Management (ASPM). The states supported are L0s and L1. ASPM is a hardware only form of power management. Software does not cause/force the link to go into L1. HW will enter these states based upon the state of the devices downstream. If the MFD devices are all in D3 hot, then the link can go into L3 depending on the capability programmed for both the Uplink and to what the Uplink is connected.

### 5.3.1.6 Error Handling

The PCIe uplink supports the full AER (Advanced Error Reporting) error handling. It's use, however, is somewhat more controlled or restricted here. A lot of the error handling is there to handle communication/interface errors between the root port and an unknown device downstream. In this case, both ends of the PCI Express\* link are known (Intel® Xeon® processor E5-1600/E5-2600 product families and the PCH). The endpoints for this link are the devices within PCH.



#### 5.3.1.6.1 Poisoned TLP

If the upstream port receives a TLP with the EP bit set from the processor, it will set the Detected Data Parity Error bit of the Primary Status register and the Poisoned TLP Status bit of the Uncorrectable Error Status register. The Upstream port will send the appropriate error message to the root. If the chip detects a data parity error from data coming from the MFD, it will set the same bits for the downstream port and send the same error messages.

#### 5.3.1.6.2 Unsupported Request

When the upstream port receives a non-posted transaction (IO/Mem/Cfg) that did not match the address/ID range programmed in the upstream port, the upstream port will set the Unsupported Request Error Status of its Uncorrectable Error Status Register and send an ERR\_NONFATAL message or ERR\_COR message as an Advisory Non-Fatal error.

#### 5.3.1.6.3 Completion Timeout

While the upstream port will not create completion timeouts (it only passes through packets), the SCU at the end could generate a completion timeout if it doesn't get an response back from the CPU in the necessary time.

#### 5.3.1.6.4 Completer Abort

If the downstream port receives an inbound (to the memory) non-posted request from the MFD with an ACS violation, it will return a CA status to the MFD. In addition it will log the ACS violation in its Uncorrectable Error Status Register and send an ERR\_NONFATAL or ERR\_COR message as an Advisory Non-Fatal error to the root port.

#### 5.3.1.6.5 Unexpected completion

The upstream port will generate this error if it receives a completion with a routing ID that does not contain a bus number within the programmed valid range. The upstream port will set the Unexpected Completion bit of its Uncorrectable Error Status Register and send an ERR\_COR messages as an Advisory Non-Fatal Error to the root port.

#### 5.3.1.6.6 Receiver overflow

When a port detects a receiver overflow error, the port will set bit the Receiver Overflow bit in the Uncorrectable Error Status Register and send an ERR\_FATAL message to the root complex.

#### 5.3.1.6.7 Flow Control Protocol Error

When a port detects a flow control protocol error, the port will set the Flow Control Protocol Error bit in the Uncorrectable Error Status Register and send an ERR\_FATAL message to the root complex.

#### 5.3.1.6.8 Malformed Packet

When a port receives a malformed TLP, the port will set the Malformed TLP Status bit in its Uncorrectable Error Status Register and send an ERR\_FATAL message to the root complex.

#### 5.3.1.6.9 Error Message Forwarding

Error messages (ERR\_COR, ERR\_NONFATAL, ERR\_FATAL) that are received from the MFD are forwarded from the secondary to the primary side only if the SERR# Enable bit in the Bridge Control Register is set. The error messages are forwarded by the primary side when either the SERR# Enable bit is set in the Command Register or the appropriate bit(s) are set in the Device Control Register. Note that the error messages do not have any effect on the Advanced Error Reporting bits.



#### 5.3.1.6.10 Poisoned Data Forwarding

When a transaction (request and completion) with bad data (poisoned TLP) enters an ingress port, the transaction will be forwarded to an egress port as a poisoned TLP. Similarly, a transaction whose data is corrupted while flowing through the switch fabric will be poisoned by the egress port. The switch internal fabric supports parity on the data bus.

#### 5.3.1.6.11 PWROK Reset Mechanism

All the voltage sources in the system are tracked by a system component that asserts the PWROK signal only after all the voltages have been stable for some predetermined time. The switch receives the PWROK signal as an asynchronous input, meaning that there is no assumed relationship between the assertion or the de-assertion of PWROK and the reference clock. While the PWROK is de-asserted, the switch holds all logic in reset.

The PWROK reset clears all internal state machines and logic, and initializes all registers to their default states, including “sticky” error bits that are persistent through all other reset classes. To eliminate potential system-reliability problems, all devices are also required to either tri-state their outputs or to drive them to safe levels during such a power-on reset.

Refer to the *PCI Express Specification*, Revision 2.0 for details of the relationship between PWROK assertion and the stability of the clocks and power at the inputs of the switch.

#### 5.3.1.6.12 Fundamental Reset Mechanism

As soon as the system is up and running, a full system reset may be required to recover from system-error conditions related to various device or subsystem failures. Fundamental reset mechanism is a warm-reset mechanism that accomplishes this recovery without clearing the “sticky” error-status bits which track the cause of the error conditions of the device or subsystem. It is equivalent to receiving a PERST# which results in a return to initial conditions.

#### 5.3.1.6.13 PCI Express Reset Mechanism

There is no reset signal on the PCI Express, and all reset communication is in-band. The upstream PCI Express device communicates the fact that it is entering and coming out of a reset using messages. The switch responds by also going through a reset. In accordance with the PCI Express protocol, this incoming message is asynchronous to the reference clock. When the uPCIe bridge is put in reset, it communicates that fact to the dPCIe bridges. Each dPCIe then sends Hot Reset indication on its link and reset their non-PRST and non-sticky registers. As long as the uPCIe is in reset, the dPCIe links are kept in reset. For example, if the dPCIe link comes out of reset and sees that the uPCIe bridge is in reset, it immediately sends a Hot Reset in-band indication and resets itself.

#### 5.3.1.6.14 Software PCI Reset (SBR—Secondary Bus Reset)

This reset is initiated by a write to the bridge control registers and resets only the particular dPCIe segment or hierarchy south of the function receiving the SBR. This reset can be used for various reasons including recovering from error conditions on the secondary bus, to redo enumeration, and so forth. This reset is synchronous to the clock domain in which it is used. The SBR is strictly restricted to the particular segment and affects neither the other segments nor the rest of the switch logic. For the dPCIe ports, SBR is strictly restricted to the particular segment and affects neither the other segments nor the rest of the switch logic. For uPCIe, SBR affects all the downstream PCI Express\* segments and resets all the dPCIe register except for sticky bits.



Note that the dPCIe segment resets on the SBR bit being set and comes out of reset when the SBR bit is cleared.

### 5.3.2 PCI Express\* Root Ports (D28:F0,F1,F2,F3,F4,F5, F6, F7)

There are eight root ports available in the PCH. The root ports are compliant to the PCI Express 2.0 specification running at 5 GT/s. The ports all reside in Device 28, and take Function 0 – 7. Port 1 is Function 0, Port 2 is Function 1, Port 3 is Function 2, Port 4 is Function 3, Port 5 is Function 4, Port 6 is Function 5, Port 7 is function 6, and Port 8 is Function 7.

PCI Express\* Root Ports 1-4 or Ports 5-8 can independently be configured as four x1s, two x2s, one x2 and two x1s, or one x4 port widths. The port configuration is set by soft straps in the Flash Descriptor.

**Note:** This section assumes the default PCI Express\* Function Number-to-Root Port mapping is used. Function numbers for a given root port are assignable through the “Root Port Function Number and Hide for PCI Express\* Root Ports” registers (RCBA+0404h).

#### 5.3.2.1 Interrupt Generation

The root port generates interrupts on behalf of Hot-Plug and power management events, when enabled. These interrupts can either be pin based, or can be MSIs, when enabled.

When an interrupt is generated using the legacy pin, the pin is internally routed to the PCH interrupt controllers. The pin that is driven is based upon the setting of the chipset configuration registers. Specifically, the chipset configuration registers used are the D28IP (Base address + 310Ch) and D28IR (Base address + 3146h) registers.

Table 5-7 summarizes interrupt behavior for MSI and wire-modes. In the table “bits” refers to the Hot-Plug and PME interrupt bits.

Table 5-7. MSI versus PCI IRQ Actions

Interrupt Register	Wire-Mode Action	MSI Action
All bits 0	Wire inactive	No action
One or more bits set to 1	Wire active	Send message
One or more bits set to 1, new bit gets set to 1	Wire active	Send message
One or more bits set to 1, software clears some (but not all) bits	Wire active	Send message
One or more bits set to 1, software clears all bits	Wire inactive	No action
Software clears one or more bits, and one or more bits are set on the same clock	Wire active	Send message



## 5.3.2.2 Power Management

### 5.3.2.2.1 S3/S4/S5 Support

Software initiates the transition to S3/S4/S5 by performing an IO write to the Power Management Control register in the PCH. After the IO write completion has been returned to the processor, each root port will send a PME\_Turn\_Off TLP (Transaction Layer Packet) message on its downstream link. The device attached to the link will eventually respond with a PME\_TO\_Ack TLP message followed by sending a PM\_Enter\_L23 DLLP (Data Link Layer Packet) request to enter the L2/L3 Ready state. When all of the PCH root ports links are in the L2/L3 Ready state, the PCH power management control logic will proceed with the entry into S3/S4/S5.

Prior to entering S3, software is required to put each device into D3<sub>HOT</sub>. When a device is put into D3<sub>HOT</sub> it will initiate entry into a L1 link state by sending a PM\_Enter\_L1 DLLP. Thus under normal operating conditions when the root ports sends the PME\_Turn\_Off message the link will be in state L1. However, when the root port is instructed to send the PME\_Turn\_Off message, it will send it whether or not the link was in L1. Endpoints attached to the PCH can make no assumptions about the state of the link prior to receiving a PME\_Turn\_Off message.

**Note:** The PME\_Turn\_Off TLP messaging flow is also issued during a host reset with and without power cycle. Refer to [Table 5-43](#) for a list of host reset resources.

### 5.3.2.2.2 Resuming from Suspended State

The root port contains enough circuitry in the suspend well to detect a wake event through the WAKE# signal and to wake the system. When WAKE# is detected asserted, an internal signal is sent to the power management controller of the PCH to cause the system to wake up. This internal message is not logged in any register, nor is an interrupt/GPE generated due to it.

### 5.3.2.2.3 Device Initiated PM\_PME Message

When the system has returned to a working state from a previous low power state, a device requesting service will send a PM\_PME message continuously, until acknowledge by the root port. The root port will take different actions depending upon whether this is the first PM\_PME has been received, or whether a previous message has been received but not yet serviced by the operating system.

If this is the first message received (RSTS.PS - D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 60h: Bit 16 is cleared), the root port will set RSTS.PS, and log the PME Requester ID into RSTS.RID (D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 60h: Bits 15:0). If an interrupt is enabled using RCTL.PIE (D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 5Ch: Bit 3), an interrupt will be generated. This interrupt can be either a pin or an MSI if MSI is enabled using MC.MSIE (D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 82h: bit 0). See [Section 5.3.2.2.4](#) for Intel® Scalable Memory Interconnect (Intel® SMI)/SCI generation.

If this is a subsequent message received (RSTS.PS is already set), the root port will set RSTS.PP (D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 60h: Bit 17) and log the PME Requester ID from the message in a hidden register. No other action will be taken.

When the first PME event is cleared by software clearing RSTS.PS, the root port will set RSTS.PS, clear RSTS.PP, and move the requester ID from the hidden register into RSTS.RID.

If RCTL.PIE is set, an interrupt will be generated. If RCTL.PIE is not set, a message will be sent to the power management controller so that a GPE can be set. If messages have been logged (RSTS.PS is set), and RCTL.PIE is later written from a 0 to a 1, and

interrupt will be generated. This last condition handles the case where the message was received prior to the operating system re-enabling interrupts after resuming from a low power state.

### 5.3.2.2.4 Intel® Scalable Memory Interconnect (Intel® SMI)/SCI Generation

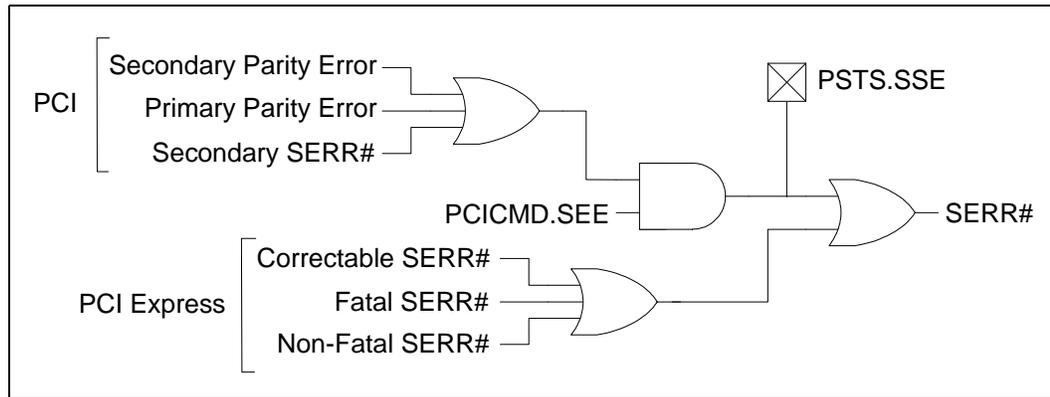
Interrupts for power management events are not supported on legacy operating systems. To support power management on non-PCI Express\* aware operating systems, PM events can be routed to generate SCI. To generate SCI, MPC.PMCE must be set. When set, a power management event will cause SMSCS.PMCS (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 31) to be set.

Additionally, BIOS workarounds for power management can be supported by setting MPC.PMME (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset D8h:Bit 0). When this bit is set, power management events will set SMSCS.PMMS (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 0), and SMI# will be generated. This bit will be set regardless of whether interrupts or SCI is enabled. The SMI# may occur concurrently with an interrupt or SCI.

### 5.3.2.3 SERR# Generation

SERR# may be generated using two paths – through PCI mechanisms involving bits in the PCI header, or through PCI Express\* mechanisms involving bits in the PCI Express\* capability structure.

Figure 5-3. Generation of SERR# to Platform



### 5.3.2.4 Hot-Plug

Each root port implements a Hot-Plug controller which performs the following:

- Messages to turn on/off/blink LEDs
- Presence and attention button detection
- Interrupt generation

The root port only allows Hot-Plug with modules (for example, ExpressCard\*). Edge-connector based Hot-Plug is not supported.

#### 5.3.2.4.1 Presence Detection

When a module is plugged in and power is supplied, the physical layer will detect the presence of the device, and the root port sets SLSTS.PDS (D28:F0/F1/F2/F3/F4/F5:Offset 5Ah:Bit 6) and SLSTS.PDC (D28:F0/F1/F2/F3:Offset 6h:Bit 3). If SLCTL.PDE (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bit 3) and SLCTL.HPE (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bit 5) are both set, the root port will also generate an interrupt.



When a module is removed (using the physical layer detection), the root port clears SLSTS.PDS and sets SLSTS.PDC. If SLCTL.PDE and SLCTL.HPE are both set, the root port will also generate an interrupt.

#### 5.3.2.4.2 Message Generation

When system software writes to SLCTL.AIC (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bits 7:6) or SLCTL.PIC (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bits 9:8), the root port will send a message down the link to change the state of LEDs on the module.

Writes to these fields are non-postable cycles, and the resulting message is a postable cycle. When receiving one of these writes, the root port performs the following:

- Changes the state in the register.
- Generates a completion into the upstream queue.
- Formulates a message for the downstream port if the field is written to regardless of if the field changed.
- Generates the message on the downstream port.
- When the last message of a command is transmitted, sets SLSTS.CCE (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bit 4) to indicate the command has completed. If SLCTL.CCE and SLCTL.HPE (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bit 5) are set, the root port generates an interrupt.

The command completed register (SLSTS.CC) applies only to commands issued by software to control the Attention Indicator (SLCTL.AIC), Power Indicator (SLCTL.PIC), or Power Controller (SLCTL.PCC). However, writes to other parts of the Slot Control Register would invariably end up writing to the indicators, power controller fields; Hence, any write to the Slot Control Register is considered a command and if enabled, will result in a command complete interrupt. The only exception to this rule is a write to disable the command complete interrupt which will not result in a command complete interrupt.

A single write to the Slot Control register is considered to be a single command, and hence receives a single command complete, even if the write affects more than one field in the Slot Control Register.

#### 5.3.2.4.3 Attention Button Detection

When an attached device is ejected, an attention button could be pressed by the user. This attention button press will result in a the PCI Express\* message "Attention\_Button\_Pressed" from the device. Upon receiving this message, the root port will set SLSTS.ABP (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 5Ah:Bit 0).

If SLCTL.ABE (D28:F0/F1/F2/F3/F4/F5:Offset 58h:bit 0) and SLCTL.HPE (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset 58h:Bit 5) are set, the Hot-Plug controller will also generate an interrupt. The interrupt is generated on an edge-event. For example, if SLSTS.ABP is already set, a new interrupt will not be generated.



#### 5.3.2.4.4 Intel® SMI/SCI Generation

Interrupts for Hot-Plug events are not supported on legacy operating systems. To support Hot-Plug on non-PCI Express\* aware operating systems, Hot-Plug events can be routed to generate SCI. To generate SCI, MPC.HPCE (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset D8h:Bit 30) must be set. When set, enabled Hot-Plug events will cause SMSCS.HPCS (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 30) to be set.

Additionally, BIOS workarounds for Hot-Plug can be supported by setting MPC.HPME (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset D8h:Bit 1). When this bit is set, Hot-Plug events can cause Intel SMI status bits in SMSCS to be set. Supported Hot-Plug events and their corresponding SMSCS bit are:

- Command Completed - SCSCS.HPCCM (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 3)
- Presence Detect Changed - SMSCS.HPPDM (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 1)
- Attention Button Pressed - SMSCS.HPABM (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 2)
- Link Active State Changed - SMSCS.HPLAS (D28:F0/F1/F2/F3/F4/F5/F6/F7:Offset DCh:Bit 4)

When any of these bits are set, SMI# will be generated. These bits are set regardless of whether interrupts or SCI is enabled for Hot-Plug events. The SMI# may occur concurrently with an interrupt or SCI.

## 5.4 Gigabit Ethernet Controller (B0:D25:F0)

The PCH integrates a Gigabit Ethernet (GbE) controller. The integrated GbE controller is compatible with the Intel® 82579 Platform LAN Connect device. The integrated GbE controller provides two interfaces for 10/100/1000 Mb/s and manageability operation:

- Based on PCI Express\* - A high-speed SerDes interface using PCI Express\* electrical signaling at half speed while keeping the logical protocol for active state operation mode.
- System Management Bus (SMBus) – A very low speed connection for low power state mode for manageability communication only. At this low power state mode the Ethernet link speed is reduced to 10 Mb/s.

The Intel 82579 can be connected to any available downstream PCI Express\* port in the PCH. The Intel 82579 Phy only runs at a speed of 1250 Mb/s, which is 1/2 of the gen1 2.5 Gb/s PCI Express\* frequency. Each of the PCI Express\* root ports in the PCH chipset have the ability to run at the 1250 Mb/s rate. There is no need to implement a mechanism to detect that the Intel 82579 LAN device is connected. The port configuration (if any), attached to the Intel 82579 LAN device, is pre-loaded from the SPI flash. The selected port adjusts the transmitter to run at the 1250 Mb/s rate and does not need to be PCI Express\* compliant.

**Note:** For more detailed information about Intel 82579 LAN Connect device, refer to *Intel® 82579 Gigabit Ethernet PHY Datasheet*.

**Note:** PCIe validation tools cannot be used for electrical validation of this interface; however, PCIe layout rules apply for on-board routing.

The integrated GbE controller operates at full-duplex at all supported speeds or half-duplex at 10/100 Mb/s. It also adheres to the *IEEE 802.3x Flow Control Specification*.

**Note:** GbE operation (1000 Mb/s) is only supported in S0 mode. In Sx modes, SMBus is the only active bus and is used to support manageability/remote wake-up functionality.



The integrated GbE controller provides a system interface using a PCI Express\* function. A full memory-mapped or I/O-mapped interface is provided to the software, along with DMA mechanisms for high performance data transfer.

The integrated GbE controller features are:

- Network Features
  - Compliant with the 1 Gb/s Ethernet 802.3 802.3u 802.3ab specifications
  - Multi-speed operation: 10/100/1000 Mb/s
  - Full-duplex operation at 10/100/1000 Mb/s: Half-duplex at 10/100 Mb/s
  - Flow control support compliant with the 802.3X specification
  - VLAN support compliant with the 802.3q specification
  - MAC address filters: perfect match unicast filters; multicast hash filtering, broadcast filter and promiscuous mode
  - PCI Express/SMBus interface to GbE PHYs
- Host Interface Features
  - 64-bit address master support for systems using more than 4 GB of physical memory
  - Programmable host memory receive buffers (256 Bytes to 16 KB)
  - Intelligent interrupt generation features to enhance driver performance
  - Descriptor ring management hardware for transmit and receive
  - Software controlled reset (resets everything except the configuration space)
  - Message Signaled Interrupts
- Performance Features
  - Configurable receive and transmit data FIFO, programmable in 1 KB increments
  - TCP segmentation capability compatible with Windows NT\* 5.x off loading features
  - Fragmented UDP checksum offload for packet reassembly
  - IPv4 and IPv6 checksum offload support (receive, transmit, and TCP segmentation offload)
  - Split header support to eliminate payload copy from user space to host space
  - Receive Side Scaling (RSS) with two hardware receive queues
  - Supports 9018 bytes of jumbo packets
  - Packet buffer size 32k bytes
  - LinkSec offload compliant with 802.3ae specification
  - TimeSync offload compliant with 802.1as specification
- Intel Virtualization Technology Features (SRV/WS SKUs Only)
  - Warm function reset – function level reset (FLR)
  - VMDq1
- Power Management Features
  - Magic Packet wake-up enable with unique MAC address
  - ACPI register set and power down functionality supporting D0 and D3 states
  - Full wake up support (APM, ACPI)
  - MAC power down at Sx, DMoff with and without WoL



## 5.4.1 GbE PCI Express Bus Interface

The GbE controller has a PCI Express\* interface to the host processor and host memory. The following sections detail the bus transactions.

### 5.4.1.1 Transaction Layer

The upper layer of the host architecture is the transaction layer. The transaction layer connects to the device core using an implementation specific protocol. Through this core-to-transaction-layer protocol, the application-specific parts of the device interact with the subsystem and transmit and receive requests to or from the remote agent, respectively.

### 5.4.1.2 Data Alignment

#### 5.4.1.2.1 4-KB Boundary

PCI requests must never specify an address/length combination that causes a memory space access to cross a 4 KB boundary. It is hardware's responsibility to break requests into 4 KB-aligned requests (if needed). This does not pose any requirement on software. However, if software allocates a buffer across a 4-KB boundary, hardware issues multiple requests for the buffer. Software should consider aligning buffers to 4 KB boundary in cases where it improves performance.

The alignment to the 4-KB boundaries is done in the core. The transaction layer does not do any alignment according to these boundaries.

#### 5.4.1.2.2 64 Bytes

PCI requests are multiples of 64 bytes and aligned to make better use of memory controller resources. Writes, however, can be on any boundary and can cross a 64-byte alignment boundary.

### 5.4.1.3 Configuration Request Retry Status

The integrated GbE controller might have a delay in initialization due to an NVM read. If the NVM configuration read operation is not completed and the device receives a configuration request, the device responds with a configuration request retry completion status to terminate the request, and thus effectively stalls the configuration request until such time that the sub-system has completed local initialization and is ready to communicate with the host.



## 5.4.2 Error Events and Error Reporting

### 5.4.2.1 Data Parity Error

The PCI host bus does not provide parity protection, but it does forward parity errors from bridges. The integrated GbE controller recognizes parity errors through the internal bus interface and sets the *Parity Error* bit in PCI configuration space. If parity errors are enabled in configuration space, a system error is indicated on the PCI host bus. The offending cycle with a parity error is dropped and not processed by the integrated GbE controller.

### 5.4.2.2 Completion with Unsuccessful Completion Status

A completion with unsuccessful completion status (any status other than 000) is dropped and not processed by the integrated GbE controller. Furthermore, the request that corresponds to the unsuccessful completion is not retried. When this unsuccessful completion status is received, the *System Error* bit in the PCI configuration space is set. If the system errors are enabled in configuration space, a system error is indicated on the PCI host bus.

## 5.4.3 Ethernet Interface

The integrated GbE controller provides a complete CSMA/CD function supporting IEEE 802.3 (10 Mb/s), 802.3u (100 Mb/s) implementations. It also supports the IEEE 802.3z and 802.3ab (1000 Mb/s) implementations. The device performs all of the functions required for transmission, reception, and collision handling called out in the standards.

The mode used to communicate between the PCH and the Intel 82579 PHY supports 10/100/1000 Mb/s operation, with both half- and full-duplex operation at 10/100 Mb/s, and full-duplex operation at 1000 Mb/s.

### 5.4.3.1 Intel® 82579 LAN PHY Interface

The integrated GbE controller and the Intel 82579 PHY communicate through the PCIe and SMBus interfaces. All integrated GbE controller configuration is performed using device control registers mapped into system memory or I/O space. The Intel 82579 device is configured using the PCI Express\* or SMBus interface.

The integrated GbE controller supports various modes as listed in [Table 5-8](#).

**Table 5-8. LAN Mode Support**

Mode	System State	Interface Active	Connections
Normal 10/100/1000 Mb/s	S0	PCI Express* or SMBus <sup>1</sup>	Intel 82579
Manageability and Remote Wake-up	Sx	SMBus	Intel 82579

1. GbE operation is not supported in Sx states.

## 5.4.4 PCI Power Management

The integrated GbE controller supports the Advanced Configuration and Power Interface (ACPI) specification as well as Advanced Power Management (APM). This enables the network-related activity (using an internal host wake signal) to wake up the host. For example, from Sx (S3-S5) to S0.

The integrated GbE controller contains power management registers for PCI and supports D0 and D3 states. PCIe transactions are only allowed in the D0 state, except for host accesses to the integrated GbE controller's PCI configuration registers.



#### 5.4.4.1 Wake Up

The integrated GbE controller supports two types of wake-up mechanisms:

1. Advanced Power Management (APM) Wake Up
2. ACPI Power Management Wake Up

Both mechanisms use an internal logic signal to wake the system up. The wake-up steps are as follows:

1. Host wake event occurs (note that packet is not delivered to host).
2. The Intel 82579 receives a WoL packet/link status change.
3. The Intel 82579 wakes up the integrated GbE controller using an SMBus message.
4. The integrated GbE controller sets the *PME\_STATUS* bit.
5. System wakes from Sx state to S0 state.
6. The host LAN function is transitioned to D0.
7. The host clears the *PME\_STATUS* bit.

##### 5.4.4.1.1 Advanced Power Management Wake Up

Advanced Power Management Wake Up or APM Wake Up was previously known as Wake on LAN (WoL). It is a feature that has existed in the 10/100 Mb/s NICs for several generations. The basic premise is to receive a broadcast or unicast packet with an explicit data pattern and then to assert a signal to wake up the system. In earlier generations, this was accomplished by using a special signal that ran across a cable to a defined connector on the motherboard. The NIC would assert the signal for approximately 50 ms to signal a wake up. The integrated GbE controller uses (if configured to) an in-band PM\_PME message for this.

At power up, the integrated GbE controller reads the *APM Enable* bits from the NVM PCI Init Control Word into the APM Enable (APME) bits of the Wake Up Control (WUC) register. These bits control enabling of APM wake up.

When APM wake up is enabled, the integrated GbE controller checks all incoming packets for Magic Packets.

Once the integrated GbE controller receives a matching Magic Packet, it:

- Sets the Magic Packet *Received* bit in the Wake Up Status (WUS) register.
- Sets the *PME\_Status* bit in the Power Management Control/Status Register (PMCSR).

APM wake up is supported in all power states and only disabled if a subsequent NVM read results in the *APM Wake Up* bit being cleared or the software explicitly writes a 0b to the *APM Wake Up* (APM) bit of the WUC register.

**Note:**

APM wake up settings will be restored to NVM default by the PCH when LAN connected Device (PHY) power is turned off and subsequently restored. Some example host WOL flows are:

- When system transitions to G3 after WOL is disabled from the BIOS, APM host WOL would get enabled.
- Anytime power to the LAN Connected Device (PHY) is cycled while in S4/S5 after WOL is disabled from the BIOS, APM host WOL would get enabled. Anytime power to the LAN Connected Device (PHY) is cycled while in S3, APM host WOL configuration is lost.



#### 5.4.4.1.2 ACPI Power Management Wake Up

The integrated GbE controller supports ACPI Power Management based Wake ups. It can generate system wake-up events from three sources:

- Receiving a Magic Packet.
- Receiving a Network Wake Up Packet.
- Detecting a link change of state.

Activating ACPI Power Management Wakeup requires the following steps:

- The software device driver programs the Wake Up Filter Control (WUFC) register to indicate the packets it needs to wake up from and supplies the necessary data to the IPv4 Address Table (IP4AT) and the Flexible Filter Mask Table (FFMT), Flexible Filter Length Table (FFLT), and the Flexible Filter Value Table (FFVT). It can also set the *Link Status Change Wake Up Enable* (LNKC) bit in the Wake Up Filter Control (WUFC) register to cause wake up when the link changes state.
- The operating system (at configuration time) writes a 1b to the *PME\_EN* bit of the Power Management Control/Status Register (PMCSR.8).

Normally, after enabling wake up, the operating system writes a 11b to the lower two bits of the PMCSR to put the integrated GbE controller into low-power mode.

Once wake up is enabled, the integrated GbE controller monitors incoming packets, first filtering them according to its standard address filtering method, then filtering them with all of the enabled wake-up filters. If a packet passes both the standard address filtering and at least one of the enabled wake-up filters, the integrated GbE controller:

- Sets the *PME\_Status* bit in the PMCSR
- Sets one or more of the *Received* bits in the Wake Up Status (WUS) register. (More than one bit is set if a packet matches more than one filter.)

If enabled, a link state change wake up causes similar results, setting the *Link Status Changed* (LNKC) bit in the Wake Up Status (WUS) register when the link goes up or down.

After receiving a wake-up packet, the integrated GbE controller ignores any subsequent wake-up packets until the software device driver clears all of the *Received* bits in the Wake Up Status (WUS) register. It also ignores link change events until the software device driver clears the *Link Status Changed* (LNKC) bit in the Wake Up Status (WUS) register.

**Note:**

ACPI wake up settings are not preserved when the LAN Connected Device (PHY) power is turned off and subsequently restored. Some example host WOL flows are:

- Anytime power to the LAN Connected Device (PHY) is cycled while in S3 or S4, ACPI host WOL configuration is lost.

### 5.4.5 Configurable LEDs

The integrated GbE controller supports three controllable and configurable LEDs that are driven from the Intel 82579 LAN device. Each of the three LED outputs can be individually configured to select the particular event, state, or activity, which is indicated on that output. In addition, each LED can be individually configured for output polarity as well as for blinking versus non-blinking (steady-state) indication.

The configuration for LED outputs is specified using the LEDCTL register. Furthermore, the hardware-default configuration for all the LED outputs, can be specified using NVM fields, thereby supporting LED displays configurable to a particular OEM preference.



Each of the three LEDs might be configured to use one of a variety of sources for output indication. The MODE bits control the LED source:

- LINK\_100/1000 is asserted when link is established at either 100 or 1000 Mb/s.
- LINK\_10/1000 is asserted when link is established at either 10 or 1000 Mb/s.
- LINK\_UP is asserted when any speed link is established and maintained.
- ACTIVITY is asserted when link is established and packets are being transmitted or received.
- LINK/ACTIVITY is asserted when link is established AND there is NO transmit or receive activity.
- LINK\_10 is asserted when a 10 Mb/ps link is established and maintained.
- LINK\_100 is asserted when a 100 Mb/s link is established and maintained.
- LINK\_1000 is asserted when a 1000 Mb/s link is established and maintained.
- FULL\_DUPLEX is asserted when the link is configured for full duplex operation.
- COLLISION is asserted when a collision is observed.
- PAUSED is asserted when the device's transmitter is flow controlled.
- LED\_ON is always asserted; LED\_OFF is always deasserted.

The *IVRT* bits enable the LED source to be inverted before being output or observed by the blink-control logic. LED outputs are assumed to normally be connected to the negative side (cathode) of an external LED.

The *BLINK* bits control whether the LED should be blinked while the LED source is asserted, and the blinking frequency (either 200 ms on and 200 ms off or 83 ms on and 83 ms off). The blink control can be especially useful for ensuring that certain events, such as ACTIVITY indication, cause LED transitions, which are sufficiently visible to a human eye. The same blinking rate is shared by all LEDs.

## 5.4.6 Function Level Reset Support (FLR) (SRV/WS SKUs Only)

The integrated GbE controller supports FLR capability. FLR capability can be used in conjunction with Intel Virtualization Technology. FLR allows an operating system in a Virtual Machine to have complete control over a device, including its initialization, without interfering with the rest of the platform. The device provides a software interface that enables the operating system to reset the entire device as if a PCI reset was asserted.

### 5.4.6.1 FLR Steps

#### 5.4.6.1.1 FLR Initialization

1. FLR is initiated by software by writing a 1b to the *Initiate FLR* bit.
2. All subsequent requests targeting the function is not claimed and will be master abort immediate on the bus. This includes any configuration, I/O or memory cycles, however, the function must continue to accept completions targeting the function.

#### 5.4.6.1.2 FLR Operation

Function resets all configuration, I/O and memory registers of the function except those indicated otherwise and resets all internal states of the function to the default or initial condition.

#### 5.4.6.1.3 FLR Completion

The *Initiate FLR* bit is reset (cleared) when the FLR reset completes. This bit can be used to indicate to the software that the FLR reset completed.

**Note:** From the time the *Initiate FLR* bit is written to 1b, software must wait at least 100 ms before accessing the function.



## 5.5 LPC Bridge (with System and Management Functions) (D31:F0)

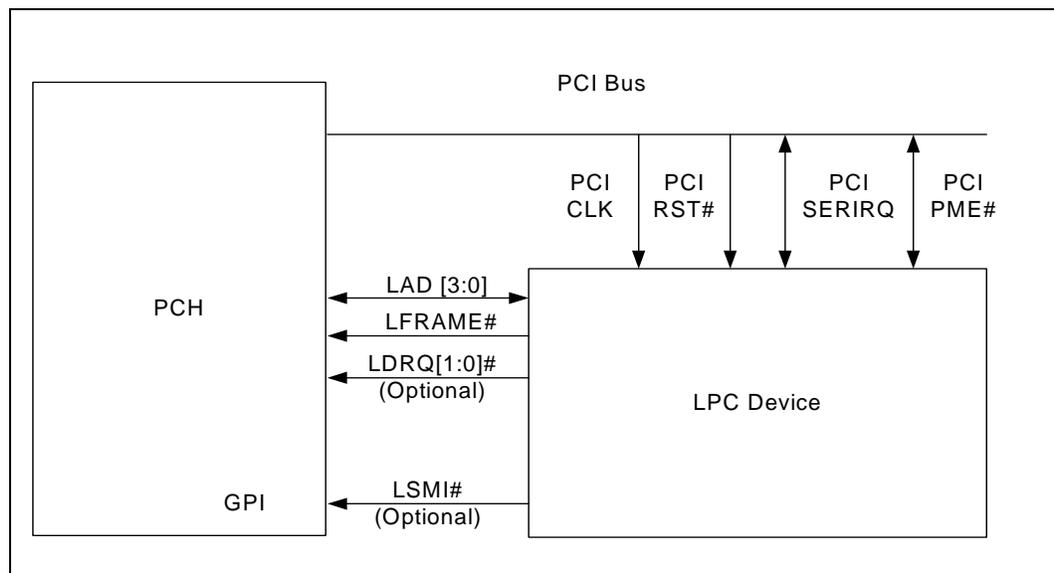
The LPC bridge function of the PCH resides in PCI Device 31:Function 0. In addition to the LPC bridge function, D31:F0 contains other functional units including DMA, Interrupt controllers, Timers, Power Management, System Management, GPIO, and RTC. In this chapter, registers and functions associated with other functional units (power management, GPIO, USB, and so forth) are described in their respective sections.

**Note:** The LPC bridge cannot be configured as a subtractive decode agent.

### 5.5.1 LPC Interface

The PCH implements an LPC interface as described in the *Low Pin Count Interface Specification*, Revision 1.1. The LPC interface to the PCH is shown in Figure 5-4. Note that the PCH implements all of the signals that are shown as optional, but peripherals are not required to do so.

Figure 5-4. LPC Interface Diagram





### 5.5.1.1 LPC Cycle Types

The PCH implements all of the cycle types described in the *Low Pin Count Interface Specification*, Revision 1.1. Table 5-9 shows the cycle types supported by the PCH.

Table 5-9. LPC Cycle Types Supported

Cycle Type	Comment
Memory Read	1 byte only. (See Note 1 below)
Memory Write	1 byte only. (See Note 1 below)
I/O Read	1 byte only. The PCH breaks up 16- and 32-bit processor cycles into multiple 8-bit transfers.
I/O Write	1 byte only. The PCH breaks up 16- and 32-bit processor cycles into multiple 8-bit transfers.
DMA Read	Can be 1, or 2 bytes
DMA Write	Can be 1, or 2 bytes
Bus Master Read	Can be 1, 2, or 4 bytes. (See Note 2 below)
Bus Master Write	Can be 1, 2, or 4 bytes. (See Note 2 below)

**Notes:**

- The PCH provides a single generic memory range (LGMR) for decoding memory cycles and forwarding them as LPC Memory cycles on the LPC bus. The LGMR memory decode range is 64 KB in size and can be defined as being anywhere in the 4 GB memory space. This range needs to be configured by BIOS during POST to provide the necessary memory resources. BIOS should advertise the LPC Generic Memory Range as Reserved to the OS in order to avoid resource conflict. For larger transfers, the PCH performs multiple 8-bit transfers. If the cycle is not claimed by any peripheral, it is subsequently aborted, and the PCH returns a value of all 1s to the processor. This is done to maintain compatibility with ISA memory cycles where pull-up resistors would keep the bus high if no device responds.
- Bus Master Read or Write cycles must be naturally aligned. For example, a 1-byte transfer can be to any address. However, the 2-byte transfer must be word-aligned (that is, with an address where A0=0). A DWord transfer must be DWord-aligned (that is, with an address where A1 and A0 are both 0).

### 5.5.1.2 Start Field Definition

Table 5-10. Start Field Bit Definitions

Bits[3:0] Encoding	Definition
0000	Start of cycle for a generic target
0010	Grant for bus master 0
0011	Grant for bus master 1
1111	Stop/Abort: End of a cycle for a target.

**Note:** All other encodings are RESERVED.



### 5.5.1.3 Cycle Type / Direction (CYCTYPE + DIR)

The PCH always drives Bit 0 of this field to 0. Peripherals running bus master cycles must also drive Bit 0 to 0. Table 5-11 shows the valid bit encodings.

**Table 5-11. Cycle Type Bit Definitions**

Bits[3:2]	Bit1	Definition
00	0	I/O Read
00	1	I/O Write
01	0	Memory Read
01	1	Memory Read
10	0	DMA Read
10	1	DMA Write
11	x	Reserved. If a peripheral performing a bus master cycle generates this value, the PCH aborts the cycle.

### 5.5.1.4 Size

Bits[3:2] are reserved. The PCH always drives them to 00. Peripherals running bus master cycles are also supposed to drive 00 for Bits 3:2; however, the PCH ignores those bits. Bits[1:0] are encoded as listed in Table 5-12.

**Table 5-12. Transfer Size Bit Definition**

Bits[1:0]	Size
00	8-bit transfer (1 byte)
01	16-bit transfer (2 bytes)
10	Reserved. The PCH never drives this combination. If a peripheral running a bus master cycle drives this combination, the PCH may abort the transfer.
11	32-bit transfer (4 bytes)

### 5.5.1.5 SYNC

Valid values for the SYNC field are shown in Table 5-13.

**Table 5-13. SYNC Bit Definition**

Bits[3:0]	Indication
0000	<b>Ready:</b> SYNC achieved with no error. For DMA transfers, this also indicates DMA request deassertion and no more transfers desired for that channel.
0101	<b>Short Wait:</b> Part indicating wait-states. For bus master cycles, the PCH does not use this encoding. Instead, the PCH uses the Long Wait encoding (see next encoding below).
0110	<b>Long Wait:</b> Part indicating wait-states, and many wait-states will be added. This encoding driven by the PCH for bus master cycles, rather than the Short Wait (0101).
1001	<b>Ready More (Used only by peripheral for DMA cycle):</b> SYNC achieved with no error and more DMA transfers desired to continue after this transfer. This value is valid only on DMA transfers and is not allowed for any other type of cycle.
1010	<b>Error:</b> Sync achieved with error. This is generally used to replace the SERR# or IOCHK# signal on the PCI/ISA bus. It indicates that the data is to be transferred, but there is a serious error in this transfer. For DMA transfers, this not only indicates an error, but also indicates DMA request deassertion and no more transfers desired for that channel.

**Notes:**

1. All other combinations are RESERVED.
2. If the LPC controller receives any SYNC returned from the device other than short (0101), long wait (0110), or ready (0000) when running a FWH cycle, indeterminate results may occur. A FWH device is not allowed to assert an Error SYNC.



### 5.5.1.6 SYNC Time-Out

There are several error cases that can occur on the LPC interface. The PCH responds as defined in section 4.2.1.9 of the *Low Pin Count Interface Specification*, Revision 1.1 to the stimuli described therein. There may be other peripheral failure conditions; however, these are not handled by the PCH.

### 5.5.1.7 SYNC Error Indication

The PCH responds as defined in section 4.2.1.10 of the *Low Pin Count Interface Specification*, Revision 1.1.

Upon recognizing the SYNC field indicating an error, the PCH treats this as a SERR by reporting this into the Device 31 Error Reporting Logic.

### 5.5.1.8 LFRAME# Usage

The PCH follows the usage of LFRAME# as defined in the *Low Pin Count Interface Specification*, Revision 1.1.

The PCH performs an abort for the following cases (possible failure cases):

- The PCH starts a Memory, I/O, or DMA cycle, but no device drives a valid SYNC after four consecutive clocks.
- The PCH starts a Memory, I/O, or DMA cycle, and the peripheral drives an invalid SYNC pattern.
- A peripheral drives an illegal address when performing bus master cycles.
- A peripheral drives an invalid value.

### 5.5.1.9 I/O Cycles

For I/O cycles targeting registers specified in the PCH's decode ranges, the PCH performs I/O cycles as defined in the *Low Pin Count Interface Specification*, Revision 1.1. These are 8-bit transfers. If the processor attempts a 16-bit or 32-bit transfer, the PCH breaks the cycle up into multiple 8-bit transfers to consecutive I/O addresses.

**Note:** If the cycle is not claimed by any peripheral (and subsequently aborted), the PCH returns a value of all 1s (FFh) to the processor. This is to maintain compatibility with ISA I/O cycles where pull-up resistors would keep the bus high if no device responds.

### 5.5.1.10 Bus Master Cycles

The PCH supports Bus Master cycles and requests (using LDRO#) as defined in the *Low Pin Count Interface Specification*, Revision 1.1. The PCH has two LDRO# inputs, and thus supports two separate bus master devices. It uses the associated START fields for Bus Master 0 (0010b) or Bus Master 1 (0011b).

**Note:** The PCH does not support LPC Bus Masters performing I/O cycles. LPC Bus Masters should only perform memory read or memory write cycles.



### 5.5.1.11 Configuration and PCH Implications

#### LPC I/F Decoders

To allow the I/O cycles and memory mapped cycles to go to the LPC interface, the PCH includes several decoders. During configuration, the PCH must be programmed with the same decode ranges as the peripheral. The decoders are programmed using the Device 31:Function 0 configuration space.

**Note:** The PCH cannot accept PCI write cycles from PCI-to-PCI bridges or devices with similar characteristics (specifically those with a “Retry Read” feature which is enabled) to an LPC device if there is an outstanding LPC read cycle towards the same PCI device or bridge. These cycles are not part of normal system operation, but may be encountered as part of platform validation testing using custom test fixtures.

#### Bus Master Device Mapping and START Fields

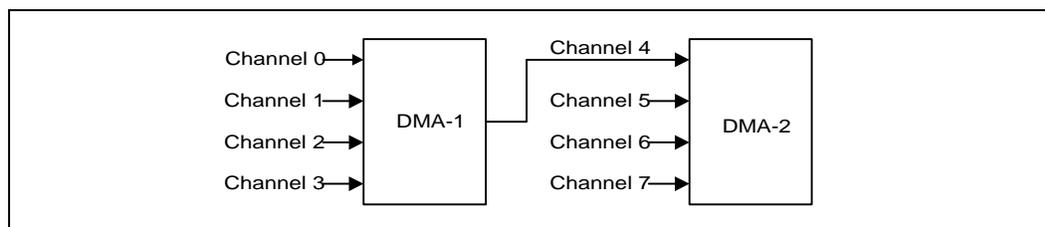
Bus Masters must have a unique START field. In the case of the PCH that supports two LPC bus masters, it drives 0010 for the START field for grants to Bus Master 0 (requested using LDRQ0#) and 0011 for grants to Bus Master 1 (requested using LDRQ1#.). Thus, no registers are needed to configure the START fields for a particular bus master.

## 5.6 DMA Operation (D31:F0)

The PCH supports LPC DMA using the PCH’s DMA controller. The DMA controller has registers that are fixed in the lower 64 KB of I/O space. The DMA controller is configured using registers in the PCI configuration space. These registers allow configuration of the channels for use by LPC DMA.

The DMA circuitry incorporates the functionality of two 8237 DMA controllers with seven independently programmable channels (Figure 5-5). DMA Controller 1 (DMA-1) corresponds to DMA Channels 0–3 and DMA Controller 2 (DMA-2) corresponds to Channels 5–7. DMA Channel 4 is used to cascade the two controllers and defaults to cascade mode in the DMA Channel Mode (DCM) Register. Channel 4 is not available for any other purpose. In addition to accepting requests from DMA slaves, the DMA controller also responds to requests that software initiates. Software may initiate a DMA service request by setting any bit in the DMA Channel Request Register to a 1.

**Figure 5-5. PCH DMA Controller**



Each DMA channel is hardwired to the compatible settings for DMA device size: Channels [3:0] are hardwired to 8-bit, count-by-bytes transfers, and Channels [7:5] are hardwired to 16-bit, count-by-words (address shifted) transfers.

The PCH provides 24-bit addressing in compliance with the ISA-Compatible specification. Each channel includes a 16-bit ISA-Compatible Current Register which holds the 16 least-significant bits of the 24-bit address, an ISA-Compatible Page Register which contains the eight next most significant bits of address.

The DMA controller also features refresh address generation, and auto-initialization following a DMA termination.



## 5.6.1 Channel Priority

For priority resolution, the DMA consists of two logical channel groups: Channels 0–3 and Channels 4–7. Each group may be in either fixed or rotate mode, as determined by the DMA Command Register.

DMA I/O slaves normally assert their DREQ line to arbitrate for DMA service. However, a software request for DMA service can be presented through each channel's DMA Request Register. A software request is subject to the same prioritization as any hardware request. See the detailed register description for Request Register programming information in [Section 13.2](#).

### 5.6.1.1 Fixed Priority

The initial fixed priority structure is as follows:

High priority	Low priority
0, 1, 2, 3	5, 6, 7

The fixed priority ordering is 0, 1, 2, 3, 5, 6, and 7. In this scheme, channel 0 has the highest priority, and Channel 7 has the lowest priority. Channels [3:0] of DMA-1 assume the priority position of Channel 4 in DMA-2, thus taking priority over Channels 5, 6, and 7.

### 5.6.1.2 Rotating Priority

Rotation allows for “fairness” in priority resolution. The priority chain rotates so that the last channel serviced is assigned the lowest priority in the channel group (0–3, 5–7).

Channels 0–3 rotate as a group of 4. They are always placed between Channel 5 and Channel 7 in the priority list.

Channel 5–7 rotate as part of a group of 4. That is, Channels (5–7) form the first three positions in the rotation, while Channel Group (0–3) comprises the fourth position in the arbitration.

## 5.6.2 Address Compatibility Mode

When the DMA is operating, the addresses do not increment or decrement through the High and Low Page Registers. Therefore, if a 24-bit address is 01FFFFh and increments, the next address is 010000h, not 020000h. Similarly, if a 24-bit address is 020000h and decrements, the next address is 02FFFFh, not 01FFFFh. However, when the DMA is operating in 16-bit mode, the addresses still do not increment or decrement through the High and Low Page Registers but the page boundary is now 128 K. Therefore, if a 24-bit address is 01FFFEh and increments, the next address is 000000h, not 010000h. Similarly, if a 24-bit address is 020000h and decrements, the next address is 03FFFEh, not 02FFFEh. This is compatible with the 8237 and Page Register implementation used in the PC-AT. This mode is set after CPURST is valid.

## 5.6.3 Summary of DMA Transfer Sizes

[Table 5-14](#) lists each of the DMA device transfer sizes. The column labeled “Current Byte/Word Count Register” indicates that the register contents represents either the number of bytes to transfer or the number of 16-bit words to transfer. The column labeled “Current Address Increment/Decrement” indicates the number added to or taken from the Current Address register after each DMA transfer cycle. The DMA Channel Mode Register determines if the Current Address Register will be incremented or decremented.



### 5.6.3.1 Address Shifting When Programmed for 16-Bit I/O Count by Words

**Table 5-14. DMA Transfer Size**

DMA Device Data Size And Word Count	Current Byte/Word Count Register	Current Address Increment/Decrement
8-Bit I/O, Count By Bytes	Bytes	1
16-Bit I/O, Count By Words (Address Shifted)	Words	1

The PCH maintains compatibility with the implementation of the DMA in the PC AT that used the 8237. The DMA shifts the addresses for transfers to/from a 16-bit device count-by-words.

**Note:** The least significant bit of the Low Page Register is dropped in 16-bit shifted mode. When programming the Current Address Register (when the DMA channel is in this mode), the Current Address must be programmed to an even address with the address value shifted right by one bit.

The address shifting is shown in Table 5-15.

**Table 5-15. Address Shifting in 16-Bit I/O DMA Transfers**

Output Address	8-Bit I/O Programmed Address (Ch 0-3)	16-Bit I/O Programmed Address (Ch 5-7) (Shifted)
A0 A[16:1] A[23:17]	A0 A[16:1] A[23:17]	0 A[15:0] A[23:17]

**Note:** The least significant bit of the Page Register is dropped in 16-bit shifted mode.

### 5.6.4 Autoinitialize

By programming a bit in the DMA Channel Mode Register, a channel may be set up as an autoinitialize channel. When a channel undergoes autoinitialization, the original values of the Current Page, Current Address and Current Byte/Word Count Registers are automatically restored from the Base Page, Address, and Byte/Word Count Registers of that channel following TC. The Base Registers are loaded simultaneously with the Current Registers by the microprocessor when the DMA channel is programmed and remain unchanged throughout the DMA service. The mask bit is not set when the channel is in autoinitialize. Following autoinitialize, the channel is ready to perform another DMA service, without processor intervention, as soon as a valid DREQ is detected.

### 5.6.5 Software Commands

There are three additional special software commands that the DMA controller can execute. The three software commands are:

- Clear Byte Pointer Flip-Flop
- Master Clear
- Clear Mask Register

They do not depend on any specific bit pattern on the data bus.

## 5.7 LPC DMA

DMA on LPC is handled through the use of the LDRQ# lines from peripherals and special encodings on LAD[3:0] from the host. Single, Demand, Verify, and Increment modes are supported on the LPC interface. Channels 0–3 are 8-bit channels. Channels 5–7 are 16-bit channels. Channel 4 is reserved as a generic bus master request.

### 5.7.1 Asserting DMA Requests

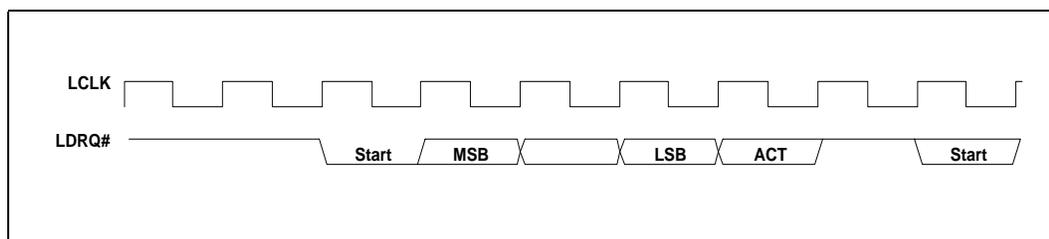
Peripherals that need DMA service encode their requested channel number on the LDRQ# signal. To simplify the protocol, each peripheral on the LPC I/F has its own dedicated LDRQ# signal (they may not be shared between two separate peripherals). The PCH has two LDRQ# inputs, allowing at least two devices to support DMA or bus mastering.

LDRQ# is synchronous with LCLK (PCI clock). As shown in Figure 5-6, the peripheral uses the following serial encoding sequence:

- Peripheral starts the sequence by asserting LDRQ# low (start bit). LDRQ# is high during idle conditions.
- The next three bits contain the encoded DMA channel number (MSB first).
- The next bit (ACT) indicates whether the request for the indicated DMA channel is active or inactive. The ACT bit is 1 (high) to indicate if it is active and 0 (low) if it is inactive. The case where ACT is low is rare, and is only used to indicate that a previous request for that channel is being abandoned.
- After the active/inactive indication, the LDRQ# signal must go high for at least 1 clock. After that one clock, LDRQ# signal can be brought low to the next encoding sequence.

If another DMA channel also needs to request a transfer, another sequence can be sent on LDRQ#. For example, if an encoded request is sent for Channel 2, and then Channel 3 needs a transfer before the cycle for Channel 2 is run on the interface, the peripheral can send the encoded request for Channel 3. This allows multiple DMA agents behind an I/O device to request use of the LPC interface, and the I/O device does not need to self-arbitrate before sending the message.

Figure 5-6. DMA Request Assertion through LDRQ#



### 5.7.2 Abandoning DMA Requests

DMA Requests can be deasserted in two fashions: on error conditions by sending an LDRQ# message with the 'ACT' bit set to 0, or normally through a SYNC field during the DMA transfer. This section describes boundary conditions where the DMA request needs to be removed prior to a data transfer.

There may be some special cases where the peripheral desires to abandon a DMA transfer. The most likely case of this occurring is due to a floppy disk controller which has overrun or underrun its FIFO, or software stopping a device prematurely.



In these cases, the peripheral wishes to stop further DMA activity. It may do so by sending an LDRQ# message with the ACT bit as 0. However, since the DMA request was seen by the PCH, there is no assurance that the cycle has not been granted and will shortly run on LPC. Therefore, peripherals must take into account that a DMA cycle may still occur. The peripheral can choose not to respond to this cycle, in which case the host will abort it, or it can choose to complete the cycle normally with any random data.

This method of DMA deassertion should be prevented whenever possible, to limit boundary conditions both on the PCH and the peripheral.

### 5.7.3 General Flow of DMA Transfers

Arbitration for DMA channels is performed through the 8237 within the host. Once the host has won arbitration on behalf of a DMA channel assigned to LPC, it asserts LFRAME# on the LPC I/F and begins the DMA transfer. The general flow for a basic DMA transfer is as follows:

1. The PCH starts transfer by asserting 0000b on LAD[3:0] with LFRAME# asserted.
2. The PCH asserts 'cycle type' of DMA, direction based on DMA transfer direction.
3. The PCH asserts channel number and, if applicable, terminal count.
4. The PCH indicates the size of the transfer: 8 or 16 bits.
5. If a DMA read...
  - The PCH drives the first 8 bits of data and turns the bus around.
  - The peripheral acknowledges the data with a valid SYNC.
  - If a 16-bit transfer, the process is repeated for the next 8 bits.
6. If a DMA write:
  - The PCH turns the bus around and waits for data.
  - The peripheral indicates data ready through SYNC and transfers the first byte.
  - If a 16-bit transfer, the peripheral indicates data ready and transfers the next byte.
7. The peripheral turns around the bus.

### 5.7.4 Terminal Count

Terminal count is communicated through LAD[3] on the same clock that DMA channel is communicated on LAD[2:0]. This field is the CHANNEL field. Terminal count indicates the last byte of transfer, based upon the size of the transfer.

For example, on an 8-bit transfer size (SIZE field is 00b), if the TC bit is set, then this is the last byte. On a 16-bit transfer (SIZE field is 01b), if the TC bit is set, then the second byte is the last byte. The peripheral, therefore, must internalize the TC bit when the CHANNEL field is communicated, and only signal TC when the last byte of that transfer size has been transferred.

### 5.7.5 Verify Mode

Verify mode is supported on the LPC interface. A verify transfer to the peripheral is similar to a DMA write, where the peripheral is transferring data to main memory. The indication from the host is the same as a DMA write, so the peripheral will be driving data onto the LPC interface. However, the host will not transfer this data into main memory.

### 5.7.6 DMA Request Deassertion

An end of transfer is communicated to the PCH through a special SYNC field transmitted by the peripheral. An LPC device must not attempt to signal the end of a transfer by deasserting LDREQ#. If a DMA transfer is several bytes (for example, a transfer from a demand mode device) the PCH needs to know when to deassert the DMA request based on the data currently being transferred.

The DMA agent uses a SYNC encoding on each byte of data being transferred, which indicates to the PCH whether this is the last byte of transfer or if more bytes are requested. To indicate the last byte of transfer, the peripheral uses a SYNC value of 0000b (ready with no error), or 1010b (ready with error). These encodings tell the PCH that this is the last piece of data transferred on a DMA read (PCH to peripheral), or the byte that follows is the last piece of data transferred on a DMA write (peripheral to the PCH).

When the PCH sees one of these two encodings, it ends the DMA transfer after this byte and deasserts the DMA request to the 8237. Therefore, if the PCH indicated a 16-bit transfer, the peripheral can end the transfer after one byte by indicating a SYNC value of 0000b or 1010b. The PCH does not attempt to transfer the second byte, and deasserts the DMA request internally.

If the peripheral indicates a 0000b or 1010b SYNC pattern on the last byte of the indicated size, then the PCH only deasserts the DMA request to the 8237 since it does not need to end the transfer.

If the peripheral wishes to keep the DMA request active, then it uses a SYNC value of 1001b (ready plus more data). This tells the 8237 that more data bytes are requested after the current byte has been transferred, so the PCH keeps the DMA request active to the 8237. Therefore, on an 8-bit transfer size, if the peripheral indicates a SYNC value of 1001b to the PCH, the data will be transferred and the DMA request will remain active to the 8237. At a later time, the PCH will then come back with another START-CHANNEL-SIZE, and so forth, combination to initiate another transfer to the peripheral.

The peripheral must not assume that the next START indication from the PCH is another grant to the peripheral if it had indicated a SYNC value of 1001b. On a single mode DMA device, the 8237 will re-arbitrate after every transfer. Only demand mode DMA devices can be assured that they will receive the next START indication from the PCH.

**Note:** Indicating a 0000b or 1010b encoding on the SYNC field of an odd byte of a 16-bit channel (first byte of a 16-bit transfer) is an error condition.

**Note:** The host stops the transfer on the LPC bus as indicated, fills the upper byte with random data on DMA writes (peripheral to memory), and indicates to the 8237 that the DMA transfer occurred, incrementing the 8237's address and decrementing its byte count.

### 5.7.7 SYNC Field / LDRQ# Rules

Since DMA transfers on LPC are requested through an LDRQ# assertion message, and are ended through a SYNC field during the DMA transfer, the peripheral must obey the following rule when initiating back-to-back transfers from a DMA channel.

The peripheral must not assert another message for eight LCLKs after a deassertion is indicated through the SYNC field. This is needed to allow the 8237, that typically runs off a much slower internal clock, to see a message deasserted before it is re-asserted so that it can arbitrate to the next agent.

Under default operation, the host only performs 8-bit transfers on 8-bit channels and 16-bit transfers on 16-bit channels.



The method by which this communication between host and peripheral through system BIOS is performed is beyond the scope of this specification. Since the LPC host and LPC peripheral are motherboard devices, no “plug-n-play” registry is required.

The peripheral must not assume that the host is able to perform transfer sizes that are larger than the size allowed for the DMA channel, and be willing to accept a SIZE field that is smaller than what it may currently have buffered.

To that end, it is recommended that future devices that may appear on the LPC bus, that require higher bandwidth than 8-bit or 16-bit DMA allow, do so with a bus mastering interface and not rely on the 8237.

## 5.8 8254 Timers (D31:F0)

The PCH contains three counters that have fixed uses. All registers and functions associated with the 8254 timers are in the core well. The 8254 unit is clocked by a 14.31818 MHz clock.

### Counter 0, System Timer

This counter functions as the system timer by controlling the state of IRQ0 and is typically programmed for Mode 3 operation. The counter produces a square wave with a period equal to the product of the counter period (838 ns) and the initial count value. The counter loads the initial count value 1 counter period after software writes the count value to the counter I/O address. The counter initially asserts IRQ0 and decrements the count value by two each counter period. The counter negates IRQ0 when the count value reaches 0. It then reloads the initial count value and again decrements the initial count value by two each counter period. The counter then asserts IRQ0 when the count value reaches 0, reloads the initial count value, and repeats the cycle, alternately asserting and negating IRQ0.

### Counter 1, Refresh Request Signal

This counter provides the refresh request signal and is typically programmed for Mode 2 operation and only impacts the period of the REF\_TOGGLE bit in Port 61. The initial count value is loaded one counter period after being written to the counter I/O address. The REF\_TOGGLE bit will have a square wave behavior (alternate between 0 and 1) and will toggle at a rate based on the value in the counter. Programming the counter to anything other than Mode 2 will result in undefined behavior for the REF\_TOGGLE bit.

### Counter 2, Speaker Tone

This counter provides the speaker tone and is typically programmed for Mode 3 operation. The counter provides a speaker frequency equal to the counter clock frequency (1.193 MHz) divided by the initial count value. The speaker must be enabled by a write to port 061h (see NMI Status and Control ports).

### 5.8.1 Timer Programming

The counter/timers are programmed in the following fashion:

1. Write a control word to select a counter.
2. Write an initial count for that counter.
3. Load the least and/or most significant bytes (as required by Control Word Bits 5, 4) of the 16-bit counter.
4. Repeat with other counters.



Only two conventions need to be observed when programming the counters. First, for each counter, the control word must be written before the initial count is written. Second, the initial count must follow the count format specified in the control word (least significant byte only, most significant byte only, or least significant byte and then most significant byte).

A new initial count may be written to a counter at any time without affecting the counter's programmed mode. Counting is affected as described in the mode definitions. The new count must follow the programmed count format.

If a counter is programmed to read/write two-byte counts, the following precaution applies: A program must not transfer control between writing the first and second byte to another routine which also writes into that same counter. Otherwise, the counter will be loaded with an incorrect count.

The Control Word Register at port 43h controls the operation of all three counters. Several commands are available:

- **Control Word Command.** Specifies which counter to read or write, the operating mode, and the count format (binary or BCD).
- **Counter Latch Command.** Latches the current count so that it can be read by the system. The countdown process continues.
- **Read Back Command.** Reads the count value, programmed mode, the current state of the OUT pins, and the state of the Null Count Flag of the selected counter.

Table 5-16 lists the six operating modes for the interval counters.

Table 5-16. Counter Operating Modes

Mode	Function	Description
0	Out signal on end of count (=0)	Output is 0. When count goes to 0, output goes to 1 and stays at 1 until counter is reprogrammed.
1	Hardware retriggerable one-shot	Output is 0. When count goes to 0, output goes to 1 for one clock time.
2	Rate generator (divide by n counter)	Output is 1. Output goes to 0 for one clock time, then back to 1 and counter is reloaded.
3	Square wave output	Output is 1. Output goes to 0 when counter rolls over, and counter is reloaded. Output goes to 1 when counter rolls over, and counter is reloaded, and so forth.
4	Software triggered strobe	Output is 1. Output goes to 0 when count expires for one clock time.
5	Hardware triggered strobe	Output is 1. Output goes to 0 when count expires for one clock time.

### 5.8.2 Reading from the Interval Timer

It is often desirable to read the value of a counter without disturbing the count in progress. There are three methods for reading the counters: a simple read operation, counter Latch command, and the Read-Back command. Each is explained below.

With the simple read and counter latch command methods, the count must be read according to the programmed format; specifically, if the counter is programmed for two byte counts, two bytes must be read. The two bytes do not have to be read one right after the other. Read, write, or programming operations for other counters may be inserted between them.



### 5.8.2.1 Simple Read

The first method is to perform a simple read operation. The counter is selected through port 40h (Counter 0), 41h (Counter 1), or 42h (Counter 2).

**Note:** Performing a direct read from the counter does not return a determinate value, because the counting process is asynchronous to read operations. However, in the case of Counter 2, the count can be stopped by writing to the GATE bit in Port 61h.

### 5.8.2.2 Counter Latch Command

The Counter Latch command, written to Port 43h, latches the count of a specific counter at the time the command is received. This command is used to ensure that the count read from the counter is accurate, particularly when reading a two-byte count. The count value is then read from each counter's Count register as was programmed by the Control register.

The count is held in the latch until it is read or the counter is reprogrammed. The count is then unlatched. This allows reading the contents of the counters on the fly without affecting counting in progress. Multiple Counter Latch Commands may be used to latch more than one counter. Counter Latch commands do not affect the programmed mode of the counter in any way.

If a Counter is latched and then, some time later, latched again before the count is read, the second Counter Latch command is ignored. The count read is the count at the time the first Counter Latch command was issued.

### 5.8.2.3 Read Back Command

The Read Back command, written to Port 43h, latches the count value, programmed mode, and current states of the OUT pin and Null Count flag of the selected counter or counters. The value of the counter and its status may then be read by I/O access to the counter address.

The Read Back command may be used to latch multiple counter outputs at one time. This single command is functionally equivalent to several counter latch commands, one for each counter latched. Each counter's latched count is held until it is read or reprogrammed. Once read, a counter is unlatched. The other counters remain latched until they are read. If multiple count Read Back commands are issued to the same counter without reading the count, all but the first are ignored.

The Read Back command may additionally be used to latch status information of selected counters. The status of a counter is accessed by a read from that counter's I/O port address. If multiple counter status latch operations are performed without reading the status, all but the first are ignored.

Both count and status of the selected counters may be latched simultaneously. This is functionally the same as issuing two consecutive, separate Read Back commands. If multiple count and/or status Read Back commands are issued to the same counters without any intervening reads, all but the first are ignored.

If both count and status of a counter are latched, the first read operation from that counter returns the latched status, regardless of which was latched first. The next one or two reads, depending on whether the counter is programmed for one or two type counts, returns the latched count. Subsequent reads return unlatched count.

## 5.9 8259 Interrupt Controllers (PIC) (D31:F0)

The PCH incorporates the functionality of two 8259 interrupt controllers that provide system interrupts for the ISA compatible interrupts. These interrupts are: system timer, keyboard controller, serial ports, parallel ports, floppy disk, mouse, and DMA channels. In addition, this interrupt controller can support the PCI based interrupts, by mapping the PCI interrupt onto the compatible ISA interrupt line. Each 8259 core supports eight interrupts, numbered 0–7. Table 5-17 shows how the cores are connected.

**Table 5-17. Interrupt Controller Core Connections**

8259	8259 Input	Typical Interrupt Source	Connected Pin / Function
Master	0	Internal	Internal Timer / Counter 0 output / HPET #0
	1	Keyboard	IRQ1 using SERIRQ
	2	Internal	Slave controller INTR output
	3	Serial Port A	IRQ3 using SERIRQ, PIRQ#
	4	Serial Port B	IRQ4 using SERIRQ, PIRQ#
	5	Parallel Port / Generic	IRQ5 using SERIRQ, PIRQ#
	6	Floppy Disk	IRQ6 using SERIRQ, PIRQ#
	7	Parallel Port / Generic	IRQ7 using SERIRQ, PIRQ#
Slave	0	Internal Real Time Clock	Internal RTC / HPET #1
	1	Generic	IRQ9 using SERIRQ, SCI, TCO, or PIRQ#
	2	Generic	IRQ10 using SERIRQ, SCI, TCO, or PIRQ#
	3	Generic	IRQ11 using SERIRQ, SCI, TCO, or PIRQ#, or HPET #2
	4	PS/2 Mouse	IRQ12 using SERIRQ, SCI, TCO, or PIRQ#, or HPET #3
	5	Internal	State Machine output based on processor FERR# assertion. May optionally be used for SCI or TCO interrupt if FERR# not needed.
	6	SATA	SATA Primary (legacy mode), or using SERIRQ or PIRQ#
	7	SATA	SATA Secondary (legacy mode) or using SERIRQ or PIRQ#

The PCH cascades the slave controller onto the master controller through master controller interrupt input 2. This means there are only 15 possible interrupts for the PCH's PIC.

Interrupts can individually be programmed to be edge or level, except for IRQ0, IRQ2, IRQ8, and IRQ13.

**Note:**

Active-low interrupt sources (for example, the PIRQ#s) are inverted inside the PCH. In the following descriptions of the 8259s, the interrupt levels are in reference to the signals at the internal interface of the 8259s, after the required inversions have occurred. Therefore, the term "high" indicates "active," which means "low" on an originating PIRQ#.



## 5.9.1 Interrupt Handling

### 5.9.1.1 Generating Interrupts

The PIC interrupt sequence involves three bits, from the IRR, ISR, and IMR, for each interrupt level. These bits are used to determine the interrupt vector returned, and status of any other pending interrupts. Table 5-18 defines the IRR, ISR, and IMR.

**Table 5-18. Interrupt Status Registers**

Bit	Description
IRR	<b>Interrupt Request Register.</b> This bit is set on a low to high transition of the interrupt line in edge mode, and by an active high level in level mode. This bit is set whether or not the interrupt is masked. However, a masked interrupt will not generate INTR.
ISR	<b>Interrupt Service Register.</b> This bit is set, and the corresponding IRR bit cleared, when an interrupt acknowledge cycle is seen, and the vector returned is for that interrupt.
IMR	<b>Interrupt Mask Register.</b> This bit determines whether an interrupt is masked. Masked interrupts will not generate INTR.

### 5.9.1.2 Acknowledging Interrupts

The processor generates an interrupt acknowledge cycle that is translated by the host bridge into a PCI Interrupt Acknowledge Cycle to the PCH. The PIC translates this command into two internal INTA# pulses expected by the 8259 cores. The PIC uses the first internal INTA# pulse to freeze the state of the interrupts for priority resolution. On the second INTA# pulse, the master or slave sends the interrupt vector to the processor with the acknowledged interrupt code. This code is based upon bits [7:3] of the corresponding ICW2 register, combined with three bits representing the interrupt within that controller.

**Table 5-19. Content of Interrupt Vector Byte**

Master, Slave Interrupt	Bits [7:3]	Bits [2:0]
IRQ7,15	ICW2[7:3]	111
IRQ6,14		110
IRQ5,13		101
IRQ4,12		100
IRQ3,11		011
IRQ2,10		010
IRQ1,9		001
IRQ0,8		000

### 5.9.1.3 Hardware/Software Interrupt Sequence

1. One or more of the Interrupt Request lines (IRQ) are raised high in edge mode, or seen high in level mode, setting the corresponding IRR bit.
2. The PIC sends INTR active to the processor if an asserted interrupt is not masked.
3. The processor acknowledges the INTR and responds with an interrupt acknowledge cycle. The cycle is translated into a PCI interrupt acknowledge cycle by the host bridge. This command is broadcast over PCI by the PCH.
4. Upon observing its own interrupt acknowledge cycle on PCI, the PCH converts it into the two cycles that the internal 8259 pair can respond to. Each cycle appears as an interrupt acknowledge pulse on the internal INTA# pin of the cascaded interrupt controllers.



5. Upon receiving the first internally generated INTA# pulse, the highest priority ISR bit is set and the corresponding IRR bit is reset. On the trailing edge of the first pulse, a slave identification code is broadcast by the master to the slave on a private, internal three bit wide bus. The slave controller uses these bits to determine if it must respond with an interrupt vector during the second INTA# pulse.
6. Upon receiving the second internally generated INTA# pulse, the PIC returns the interrupt vector. If no interrupt request is present because the request was too short in duration, the PIC returns vector 7 from the master controller.
7. This completes the interrupt cycle. In Automatic End of Interrupt (AEOI) mode the ISR bit is reset at the end of the second INTA# pulse. Otherwise, the ISR bit remains set until an appropriate EOI command is issued at the end of the interrupt subroutine.

## 5.9.2 Initialization Command Words (ICWx)

Before operation can begin, each 8259 must be initialized. In the PCH, this is a four byte sequence. The four initialization command words are referred to by their acronyms: ICW1, ICW2, ICW3, and ICW4.

The base address for each 8259 initialization command word is a fixed location in the I/O memory space: 20h for the master controller, and A0h for the slave controller.

### 5.9.2.1 ICW1

An I/O write to the master or slave controller base address with data bit 4 equal to 1 is interpreted as a write to ICW1. Upon sensing this write, the PCH PIC expects three more byte writes to 21h for the master controller, or A1h for the slave controller, to complete the ICW sequence.

A write to ICW1 starts the initialization sequence during which the following automatically occur:

1. Following initialization, an interrupt request (IRQ) input must make a low-to-high transition to generate an interrupt.
2. The Interrupt Mask Register is cleared.
3. IRQ7 input is assigned priority 7.
4. The slave mode address is set to 7.
5. Special mask mode is cleared and Status Read is set to IRR.

### 5.9.2.2 ICW2

The second write in the sequence (ICW2) is programmed to provide bits [7:3] of the interrupt vector that will be released during an interrupt acknowledge. A different base is selected for each interrupt controller.

### 5.9.2.3 ICW3

The third write in the sequence (ICW3) has a different meaning for each controller.

- For the master controller, ICW3 is used to indicate which IRQ input line is used to cascade the slave controller. Within the PCH, IRQ2 is used. Therefore, bit 2 of ICW3 on the master controller is set to a 1, and the other bits are set to 0s.
- For the slave controller, ICW3 is the slave identification code used during an interrupt acknowledge cycle. On interrupt acknowledge cycles, the master controller broadcasts a code to the slave controller if the cascaded interrupt won arbitration on the master controller. The slave controller compares this identification code to the value stored in its ICW3, and if it matches, the slave controller assumes responsibility for broadcasting the interrupt vector.



#### 5.9.2.4 ICW4

The final write in the sequence (ICW4) must be programmed for both controllers. At the very least, bit 0 must be set to a 1 to indicate that the controllers are operating in an Intel Architecture-based system.

### 5.9.3 Operation Command Words (OCW)

These command words reprogram the Interrupt controller to operate in various interrupt modes.

- OCW1 masks and unmasks interrupt lines.
- OCW2 controls the rotation of interrupt priorities when in rotating priority mode, and controls the EOI function.
- OCW3 sets up ISR/IRR reads, enables/disables the special mask mode (SMM), and enables/disables polled interrupt mode.

### 5.9.4 Modes of Operation

#### 5.9.4.1 Fully Nested Mode

In this mode, interrupt requests are ordered in priority from 0 through 7, with 0 being the highest. When an interrupt is acknowledged, the highest priority request is determined and its vector placed on the bus. Additionally, the ISR for the interrupt is set. This ISR bit remains set until: the processor issues an EOI command immediately before returning from the service routine; or if in AEOI mode, on the trailing edge of the second INTA#. While the ISR bit is set, all further interrupts of the same or lower priority are inhibited, while higher levels generate another interrupt. Interrupt priorities can be changed in the rotating priority mode.

#### 5.9.4.2 Special Fully-Nested Mode

This mode is used in the case of a system where cascading is used, and the priority has to be conserved within each slave. In this case, the special fully-nested mode is programmed to the master controller. This mode is similar to the fully-nested mode with the following exceptions:

- When an interrupt request from a certain slave is in service, this slave is not locked out from the master's priority logic and further interrupt requests from higher priority interrupts within the slave are recognized by the master and initiate interrupts to the processor. In the normal-nested mode, a slave is masked out when its request is in service.
- When exiting the Interrupt Service routine, software has to check whether the interrupt serviced was the only one from that slave. This is done by sending a Non-Specific EOI command to the slave and then reading its ISR. If it is 0, a non-specific EOI can also be sent to the master.

#### 5.9.4.3 Automatic Rotation Mode (Equal Priority Devices)

In some applications, there are a number of interrupting devices of equal priority. Automatic rotation mode provides for a sequential 8-way rotation. In this mode, a device receives the lowest priority after being serviced. In the worst case, a device requesting an interrupt has to wait until each of seven other devices are serviced at most once.

There are two ways to accomplish automatic rotation using OCW2; the Rotation on Non-Specific EOI Command (R=1, SL=0, EOI=1) and the rotate in automatic EOI mode which is set by (R=1, SL=0, EOI=0).

#### 5.9.4.4 Specific Rotation Mode (Specific Priority)

Software can change interrupt priorities by programming the bottom priority. For example, if IRQ5 is programmed as the bottom priority device, then IRQ6 is the highest priority device. The Set Priority Command is issued in OCW2 to accomplish this, where: R=1, SL=1, and LO–L2 is the binary priority level code of the bottom priority device.

In this mode, internal status is updated by software control during OCW2. However, it is independent of the EOI command. Priority changes can be executed during an EOI command by using the Rotate on Specific EOI Command in OCW2 (R=1, SL=1, EOI=1 and LO–L2=IRQ level to receive bottom priority).

#### 5.9.4.5 Poll Mode

Poll mode can be used to conserve space in the interrupt vector table. Multiple interrupts that can be serviced by one interrupt service routine do not need separate vectors if the service routine uses the poll command. Poll mode can also be used to expand the number of interrupts. The polling interrupt service routine can call the appropriate service routine, instead of providing the interrupt vectors in the vector table. In this mode, the INTR output is not used and the microprocessor internal Interrupt Enable flip-flop is reset, disabling its interrupt input. Service to devices is achieved by software using a Poll command.

The Poll command is issued by setting P=1 in OCW3. The PIC treats its next I/O read as an interrupt acknowledge, sets the appropriate ISR bit if there is a request, and reads the priority level. Interrupts are frozen from the OCW3 write to the I/O read. The byte returned during the I/O read contains a 1 in bit 7 if there is an interrupt, and the binary code of the highest priority level in bits 2:0.

#### 5.9.4.6 Edge and Level Triggered Mode

In ISA systems this mode is programmed using bit 3 in ICW1, which sets level or edge for the entire controller. In the PCH, this bit is disabled and a new register for edge and level triggered mode selection, per interrupt input, is included. This is the Edge/Level control Registers ELCR1 and ELCR2.

If an ELCR bit is 0, an interrupt request will be recognized by a low-to-high transition on the corresponding IRQ input. The IRQ input can remain high without generating another interrupt. If an ELCR bit is 1, an interrupt request will be recognized by a high level on the corresponding IRQ input and there is no need for an edge detection. The interrupt request must be removed before the EOI command is issued to prevent a second interrupt from occurring.

In both the edge and level triggered modes, the IRQ inputs must remain active until after the falling edge of the first internal INTA#. If the IRQ input goes inactive before this time, a default IRQ7 vector is returned.

#### 5.9.4.7 End of Interrupt (EOI) Operations

An EOI can occur in one of two fashions: by a command word write issued to the PIC before returning from a service routine, the EOI command; or automatically when AEOI bit in ICW4 is set to 1.

#### 5.9.4.8 Normal End of Interrupt

In normal EOI, software writes an EOI command before leaving the interrupt service routine to mark the interrupt as completed. There are two forms of EOI commands: Specific and Non-Specific. When a Non-Specific EOI command is issued, the PIC clears the highest ISR bit of those that are set to 1. Non-Specific EOI is the normal mode of operation of the PIC within the PCH, as the interrupt being serviced currently is the interrupt entered with the interrupt acknowledge. When the PIC is operated in modes



that preserve the fully nested structure, software can determine which ISR bit to clear by issuing a Specific EOI. An ISR bit that is masked is not cleared by a Non-Specific EOI if the PIC is in the special mask mode. An EOI command must be issued for both the master and slave controller.

#### 5.9.4.9 Automatic End of Interrupt Mode

In this mode, the PIC automatically performs a Non-Specific EOI operation at the trailing edge of the last interrupt acknowledge pulse. From a system standpoint, this mode should be used only when a nested multi-level interrupt structure is not required within a single PIC. The AEOI mode can only be used in the master controller and not the slave controller.

### 5.9.5 Masking Interrupts

#### 5.9.5.1 Masking on an Individual Interrupt Request

Each interrupt request can be masked individually by the Interrupt Mask Register (IMR). This register is programmed through OCW1. Each bit in the IMR masks one interrupt channel. Masking IRQ2 on the master controller masks all requests for service from the slave controller.

#### 5.9.5.2 Special Mask Mode

Some applications may require an interrupt service routine to dynamically alter the system priority structure during its execution under software control. For example, the routine may wish to inhibit lower priority requests for a portion of its execution but enable some of them for another portion.

The special mask mode enables all interrupts not masked by a bit set in the Mask register. Normally, when an interrupt service routine acknowledges an interrupt without issuing an EOI to clear the ISR bit, the interrupt controller inhibits all lower priority requests. In the special mask mode, any interrupts may be selectively enabled by loading the Mask Register with the appropriate pattern. The special mask mode is set by OCW3 where: SSMM=1, SMM=1, and cleared where SSMM=1, SMM=0.

### 5.9.6 Steering PCI Interrupts

The PCH can be programmed to allow PIRQA#-PIRQH# to be routed internally to interrupts 3-7, 9-12, 14 or 15. The assignment is programmable through the PIRQx Route Control registers, located at 60-63h and 68-6Bh in Device 31:Function 0. One or more PIRQx# lines can be routed to the same IRQx input. If interrupt steering is not required, the Route registers can be programmed to disable steering.

The PIRQx# lines are defined as active low, level sensitive to allow multiple interrupts on a PCI board to share a single line across the connector. When a PIRQx# is routed to specified IRQ line, software must change the IRQ's corresponding ELCR bit to level sensitive mode. The PCH internally inverts the PIRQx# line to send an active high level to the PIC. When a PCI interrupt is routed onto the PIC, the selected IRQ can no longer be used by an active high device (through SERIRQ). However, active low interrupts can share their interrupt with PCI interrupts.

Internal sources of the PIRQs, including SCI and TCO interrupts, cause the external PIRQ to be asserted. The PCH receives the PIRQ input, like all of the other external sources, and routes it accordingly.



## 5.10 Advanced Programmable Interrupt Controller (APIC) (D31:F0)

In addition to the standard ISA-compatible PIC described in the previous chapter, the PCH incorporates the APIC. While the standard interrupt controller is intended for use in a uni-processor system, APIC can be used in either a uni-processor or multi-processor system.

### 5.10.1 Interrupt Handling

The I/O APIC handles interrupts very differently than the 8259. Briefly, these differences are:

- **Method of Interrupt Transmission.** The I/O APIC transmits interrupts through memory writes on the normal datapath to the processor, and interrupts are handled without the need for the processor to run an interrupt acknowledge cycle.
- **Interrupt Priority.** The priority of interrupts in the I/O APIC is independent of the interrupt number. For example, interrupt 10 can be given a higher priority than interrupt 3.
- **More Interrupts.** The I/O APIC in the PCH supports a total of 24 interrupts.
- **Multiple Interrupt Controllers.** The I/O APIC architecture allows for multiple I/O APIC devices in the system with their own interrupt vectors.

### 5.10.2 Interrupt Mapping

The I/O APIC within the PCH supports 24 APIC interrupts. Each interrupt has its own unique vector assigned by software. The interrupt vectors are mapped as follows, and match “Config 6” of the *Multi-Processor Specification*.

Table 5-20. APIC Interrupt Mapping<sup>1</sup> (Sheet 1 of 2)

IRQ #	Using SERIRQ	Direct from Pin	Using PCI Message	Internal Modules
0	No	No	No	Cascade from 8259 #1
1	Yes	No	Yes	
2	No	No	No	8254 Counter 0, HPET #0 (legacy mode)
3	Yes	No	Yes	
4	Yes	No	Yes	
5	Yes	No	Yes	
6	Yes	No	Yes	
7	Yes	No	Yes	
8	No	No	No	RTC, HPET #1 (legacy mode)
9	Yes	No	Yes	Option for SCI, TCO
10	Yes	No	Yes	Option for SCI, TCO
11	Yes	No	Yes	HPET #2, Option for SCI, TCO (Note2)
12	Yes	No	Yes	HPET #3 (Note 3)
13	No	No	No	FERR# logic
14	Yes	No	Yes	SATA Primary (legacy mode)
15	Yes	No	Yes	SATA Secondary (legacy mode)
16	PIRQA#	PIRQA#	Yes	Internal devices are routable; see <a href="#">Section 10.1.20</a> though <a href="#">Section 10.1.29</a> .
17	PIRQB#	PIRQB#		
18	PIRQC#	PIRQC#		
19	PIRQD#	PIRQD#		



**Table 5-20. APIC Interrupt Mapping<sup>1</sup> (Sheet 2 of 2)**

IRQ #	Using SERIRQ	Direct from Pin	Using PCI Message	Internal Modules
20	N/A	PIRQE# <sup>4</sup>	Yes	Option for SCI, TCO, HPET #0,1,2, 3. Other internal devices are routable; see <a href="#">Section 10.1.20</a> though <a href="#">Section 10.1.29</a> .
21	N/A	PIRQF# <sup>4</sup>		
22	N/A	PIRQG# <sup>4</sup>		
23	N/A	PIRQH# <sup>4</sup>		

**Notes:**

1. When programming the polarity of internal interrupt sources on the APIC, interrupts 0 through 15 receive active-high internal interrupt sources, while interrupts 16 through 23 receive active-low internal interrupt sources.
2. If IRQ 11 is used for HPET #2, software should ensure IRQ 11 is not shared with any other devices to ensure the proper operation of HPET #2. PCH hardware does not prevent sharing of IRQ 11.
3. If IRQ 12 is used for HPET #3, software should ensure IRQ 12 is not shared with any other devices to ensure the proper operation of HPET #3. PCH hardware does not prevent sharing of IRQ 12.
4. PIRQ[E:H]# are Multiplexed with GPIO pins. Interrupts PIRQ[E:H]# will not be exposed if they are configured as GPIOs.

### 5.10.3 PCI / PCI Express\* Message-Based Interrupts

When external devices through PCI / PCI Express\* wish to generate an interrupt, they will send the message defined in the *PCI Express\* Base Specification*, Revision 1.0a for generating INTA# - INTD#. These will be translated internal assertions/deassertions of INTA# - INTD#.

### 5.10.4 IOxAPIC Address Remapping (SRV/WS SKUs Only)

To support Intel Virtualization Technology, interrupt messages are required to go through similar address remapping as any other memory request. Address remapping allows for domain isolation for interrupts, so a device assigned in one domain is not allowed to generate an interrupt to another domain.

The address remapping is based on the Bus: Device: Function field associated with the requests. The internal APIC is required to initiate the interrupt message using a unique Bus: Device: function.

The PCH allows BIOS to program the unique Bus: Device: Function address for the internal APIC. This address field does not change the APIC functionality and the APIC is not promoted as a stand-alone PCI device. See Device 31: Function 0 Offset 6Ch for additional information.

### 5.10.5 External Interrupt Controller Support

The PCH supports external APICs off of PCI Express\* ports, and does not support APICs on the PCI bus. The EOI special cycle is only forwarded to PCI Express\* ports.



## 5.11 Serial Interrupt (D31:F0)

The PCH supports a serial IRQ scheme. This allows a single signal to be used to report interrupt requests. The signal used to transmit this information is shared between the host, the PCH, and all peripherals that support serial interrupts. The signal line, SERIRQ, is synchronous to PCI clock, and follows the sustained tri-state protocol that is used by all PCI signals. This means that if a device has driven SERIRQ low, it will first drive it high synchronous to PCI clock and release it the following PCI clock. The serial IRQ protocol defines this sustained tri-state signaling in the following fashion:

- **S – Sample Phase.** Signal driven low
- **R – Recovery Phase.** Signal driven high
- **T – Turn-around Phase.** Signal released

The PCH supports a message for 21 serial interrupts. These represent the 15 ISA interrupts (IRQ0–1, 3–15), the four PCI interrupts, and the control signals SMI# and IOCHK#. The serial IRQ protocol does not support the additional APIC interrupts (20–23).

**Note:** When the SATA controller is configured for legacy IDE mode, IRQ14 and IRQ15 are expected to behave as ISA legacy interrupts, which cannot be shared (that is, through the Serial Interrupt pin). If IRQ14 and IRQ15 are shared with Serial Interrupt pin then abnormal system behavior may occur. For example, IRQ14/15 may not be detected by PCH's interrupt controller. When the SATA controller is not running in Native IDE mode, IRQ14 and IRQ15 are used as special interrupts. If the SATA controller is in native modes, these interrupts can be mapped to other devices accordingly.

### 5.11.1 Start Frame

The serial IRQ protocol has two modes of operation which affect the start frame. These two modes are: Continuous, where the PCH is solely responsible for generating the start frame; and Quiet, where a serial IRQ peripheral is responsible for beginning the start frame.

The mode that must first be entered when enabling the serial IRQ protocol is continuous mode. In this mode, the PCH asserts the start frame. This start frame is 4, 6, or 8 PCI clocks wide based upon the Serial IRQ Control Register, bits 1:0 at 64h in Device 31:Function 0 configuration space. This is a polling mode.

When the serial IRQ stream enters quiet mode (signaled in the Stop Frame), the SERIRQ line remains inactive and pulled up between the Stop and Start Frame until a peripheral drives the SERIRQ signal low. The PCH senses the line low and continues to drive it low for the remainder of the Start Frame. Since the first PCI clock of the start frame was driven by the peripheral in this mode, the PCH drives the SERIRQ line low for 1 PCI clock less than in continuous mode. This mode of operation allows for a quiet, and therefore lower power, operation.



### 5.11.2 Data Frames

Once the Start frame has been initiated, all of the SERIRQ peripherals must start counting frames based on the rising edge of SERIRQ. Each of the IRQ/DATA frames has exactly 3 phases of 1 clock each:

- **Sample Phase.** During this phase, the SERIRQ device drives SERIRQ low if the corresponding interrupt signal is low. If the corresponding interrupt is high, then the SERIRQ devices tri-state the SERIRQ signal. The SERIRQ line remains high due to pull-up resistors (there is no internal pull-up resistor on this signal, an external pull-up resistor is required). A low level during the IRQ0–1 and IRQ2–15 frames indicates that an active-high ISA interrupt is not being requested, but a low level during the PCI INT[A:D], SMI#, and IOCHK# frame indicates that an active-low interrupt is being requested.
- **Recovery Phase.** During this phase, the device drives the SERIRQ line high if in the Sample Phase it was driven low. If it was not driven in the sample phase, it is tri-stated in this phase.
- **Turn-around Phase.** The device tri-states the SERIRQ line.

### 5.11.3 Stop Frame

After all data frames, a Stop Frame is driven by the PCH. The SERIRQ signal is driven low by the PCH for 2 or 3 PCI clocks. The number of clocks is determined by the SERIRQ configuration register. The number of clocks determines the next mode:

**Table 5-21. Stop Frame Explanation**

Stop Frame Width	Next Mode
2 PCI clocks	<b>Quiet Mode.</b> Any SERIRQ device may initiate a Start Frame
3 PCI clocks	<b>Continuous Mode.</b> Only the host () may initiate a Start Frame

### 5.11.4 Specific Interrupts Not Supported using SERIRQ

There are three interrupts seen through the serial stream that are not supported by the PCH. These interrupts are generated internally, and are not sharable with other devices within the system. These interrupts are:

- IRQ0. Heartbeat interrupt generated off of the internal 8254 counter 0.
- IRQ8#. RTC interrupt can only be generated internally.
- IRQ13. Floating point error interrupt generated off of the processor assertion of FERR#.

The PCH ignores the state of these interrupts in the serial stream, and does not adjust their level based on the level seen in the serial stream.

### 5.11.5 Data Frame Format

Table 5-22 shows the format of the data frames. For the PCI interrupts (A–D), the output from the PCH is AND'd with the PCI input signal. This way, the interrupt can be signaled using both the PCI interrupt input signal and using the SERIRQ signal (they are shared).

**Table 5-22. Data Frame Format**

Data Frame #	Interrupt	Clocks Past Start Frame	Comment
1	IRQ0	2	Ignored. IRQ0 can only be generated using the internal 8524
2	IRQ1	5	
3	SMI#	8	Causes SMI# if low. Will set the SERIRQ_SMI_STS bit.
4	IRQ3	11	
5	IRQ4	14	
6	IRQ5	17	
7	IRQ6	20	
8	IRQ7	23	
9	IRQ8	26	Ignored. IRQ8# can only be generated internally.
10	IRQ9	29	
11	IRQ10	32	
12	IRQ11	35	
13	IRQ12	38	
14	IRQ13	41	Ignored. IRQ13 can only be generated from FERR#
15	IRQ14	44	Not attached to SATA logic
16	IRQ15	47	Not attached to SATA logic
17	IOCHCK#	50	Same as ISA IOCHCK# going active.
18	PCI INTA#	53	Drive PIRQA#
19	PCI INTB#	56	Drive PIRQB#
20	PCI INTC#	59	Drive PIRQC#
21	PCI INTD#	62	Drive PIRQD#

## 5.12 Real Time Clock (D31:F0)

The Real Time Clock (RTC) module provides a battery backed-up date and time keeping device with two banks of static RAM with 128 bytes each, although the first bank has 114 bytes for general purpose usage. Three interrupt features are available: time of day alarm with once a second to once a month range, periodic rates of 122  $\mu$ s to 500 ms, and end of update cycle notification. Seconds, minutes, hours, days, day of week, month, and year are counted. Daylight savings compensation is no longer supported. The hour is represented in twelve or twenty-four hour format, and data can be represented in BCD or binary format. The design is functionally compatible with the Motorola MS146818B. The time keeping comes from a 32.768 kHz oscillating source, which is divided to achieve an update every second. The lower 14 bytes on the lower RAM block has very specific functions. The first ten are for time and date information. The next four (0Ah to 0Dh) are registers, which configure and report RTC functions.

The time and calendar data should match the data mode (BCD or binary) and hour mode (12 or 24 hour) as selected in register B. It is up to the programmer to make sure that data stored in these locations is within the reasonable values ranges and represents a possible date and time. The exception to these ranges is to store a value



of C0–FFh in the Alarm bytes to indicate a don't care situation. All Alarm conditions must match to trigger an Alarm Flag, which could trigger an Alarm Interrupt if enabled. The SET bit must be 1 while programming these locations to avoid clashes with an update cycle. Access to time and date information is done through the RAM locations. If a RAM read from the ten time and date bytes is attempted during an update cycle, the value read do not necessarily represent the true contents of those locations. Any RAM writes under the same conditions are ignored.

**Note:** The leap year determination for adding a 29th day to February does not take into account the end-of-the-century exceptions. The logic simply assumes that all years divisible by 4 are leap years. According to the Royal Observatory Greenwich, years that are divisible by 100 are typically not leap years. In every fourth century (years divisible by 400, like 2000), the 100-year-exception is over-ridden and a leap-year occurs. Note that the year 2100 will be the first time in which the current RTC implementation would incorrectly calculate the leap-year.

The PCH does not implement month/year alarms.

### 5.12.1 Update Cycles

An update cycle occurs once a second, if the SET bit of register B is not asserted and the divide chain is properly configured. During this procedure, the stored time and date are incremented, overflow is checked, a matching alarm condition is checked, and the time and date are rewritten to the RAM locations. The update cycle will start at least 488  $\mu$ s after the UIP bit of register A is asserted, and the entire cycle does not take more than 1984  $\mu$ s to complete. The time and date RAM locations (0–9) are disconnected from the external bus during this time.

To avoid update and data corruption conditions, external RAM access to these locations can safely occur at two times. When a updated-ended interrupt is detected, almost 999 ms is available to read and write the valid time and date data. If the UIP bit of Register A is detected to be low, there is at least 488  $\mu$ s before the update cycle begins.

**Warning:** The overflow conditions for leap years adjustments are based on more than one date or time item. To ensure proper operation when adjusting the time, the new time and data values should be set at least two seconds before leap year occurs.

### 5.12.2 Interrupts

The real-time clock interrupt is internally routed within the PCH both to the I/O APIC and the 8259. It is mapped to interrupt vector 8. This interrupt does not leave the PCH, nor is it shared with any other interrupt. IRQ8# from the SERIRQ stream is ignored. However, the High Performance Event Timers can also be mapped to IRQ8#; in this case, the RTC interrupt is blocked.

### 5.12.3 Lockable RAM Ranges

The RTC battery-backed RAM supports two 8-byte ranges that can be locked using the configuration space. If the locking bits are set, the corresponding range in the RAM will not be readable or writable. A write cycle to those locations will have no effect. A read cycle to those locations will not return the location's actual value (resultant value is undefined).

Once a range is locked, the range can be unlocked only by a hard reset, which will invoke the BIOS and allow it to relock the RAM range.

## 5.12.4 Century Rollover

The PCH detects a rollover when the Year byte (RTC I/O space, index Cffset 09h) transitions form 99 to 00. Upon detecting the rollover, the PCH sets the NEWCENTURY\_STS bit (TCOBASE + 04h, bit 7). If the system is in an S0 state, this causes an SMI#. The SMI# handler can update registers in the RTC RAM that are associated with century value. If the system is in a sleep state (S1–S5) when the century rollover occurs, the PCH also sets the NEWCENTURY\_STS bit, but no SMI# is generated. When the system resumes from the sleep state, BIOS should check the NEWCENTURY\_STS bit and update the century value in the RTC RAM.

## 5.12.5 Clearing Battery-Backed RTC RAM

Clearing CMOS RAM in an PCH-based platform can be done by using a jumper on RTCRST# or GPI. Implementations should not attempt to clear CMOS by using a jumper to pull VccRTC low.

### Using RTCRST# to Clear CMOS

A jumper on RTCRST# can be used to clear CMOS values, as well as reset to default, the state of those configuration bits that reside in the RTC power well. When the RTCRST# is strapped to ground, the RTC\_PWR\_STS bit (D31:F0:A4h bit 2) will be set and those configuration bits in the RTC power well will be set to their default state. BIOS can monitor the state of this bit, and manually clear the RTC CMOS array once the system is booted. The normal position would cause RTCRST# to be pulled up through a weak pull-up resistor. [Table 5-23](#) shows which bits are set to their default state when RTCRST# is asserted. This RTCRST# jumper technique allows the jumper to be moved and then replaced—all while the system is powered off. Then, once booted, the RTC\_PWR\_STS can be detected in the set state.

**Table 5-23. Configuration Bits Reset by RTCRST# Assertion (Sheet 1 of 2)**

Bit Name	Register	Location	Bit(s)	Default State
Alarm Interrupt Enable (AIE)	Register B (General Configuration) (RTC_REGB)	I/O space (RTC Index + 0Bh)	5	X
Alarm Flag (AF)	Register C (Flag Register) (RTC_REGC)	I/O space (RTC Index + 0Ch)	5	X
SWSMI_RATE_SEL	General PM Configuration 3 Register GEN_PMCON_3	D31:F0:A4h	7:6	0
SLP_S4# Minimum Assertion Width	General PM Configuration 3 Register GEN_PMCON_3	D31:F0:A4h	5:4	0
SLP_S4# Assertion Stretch Enable	General PM Configuration 3 Register GEN_PMCON_3	D31:F0:A4h	3	0
RTC Power Status (RTC_PWR_STS)	General PM Configuration 3 Register GEN_PMCON_3	D31:F0:A4h	2	0
Power Failure (PWR_FLR)	General PM Configuration 3 Register (GEN_PMCON_3)	D31:F0:A4h	1	0
AFTERG3_EN	General PM Configuration 3 Register GEN_PMCON_3	D31:F0:A4h	0	0
Power Button Override Status (PRBTNOR_STS)	Power Management 1 Status Register (PM1_STS)	PMBase + 00h	11	0



Table 5-23. Configuration Bits Reset by RTCRST# Assertion (Sheet 2 of 2)

Bit Name	Register	Location	Bit(s)	Default State
RTC Event Enable (RTC_EN)	Power Management 1 Enable Register (PM1_EN)	PMBase + 02h	10	0
Sleep Type (SLP_TYP)	Power Management 1 Control (PM1_CNT)	PMBase + 04h	12:10	0
PME_EN	General Purpose Event 0 Enables Register (GPE0_EN)	PMBase + 2Ch	11	0
BATLOW_EN	General Purpose Event 0 Enables Register (GPE0_EN)	PMBase + 2Ch	10	0
RI_EN	General Purpose Event 0 Enables Register (GPE0_EN)	PMBase + 2Ch	8	0
NEWCENTURY_STS	TCO1 Status Register (TCO1_STS)	TCOBase + 04h	7	0
Intruder Detect (INTRD_DET)	TCO2 Status Register (TCO2_STS)	TCOBase + 06h	0	0
Top Swap (TS)	Backed Up Control Register (BUC)	Chipset Config Registers:Offset 3414h	0	X

### Using a GPI to Clear CMOS

A jumper on a GPI can also be used to clear CMOS values. BIOS would detect the setting of this GPI on system boot-up, and manually clear the CMOS array.

**Note:** The GPI strap technique to clear CMOS requires multiple steps to implement. The system is booted with the jumper in new position, then powered back down. The jumper is replaced back to the normal position, then the system is rebooted again.

**Warning:** Do not implement a jumper on VccRTC to clear CMOS.

## 5.13 Processor Interface (D31:F0)

The PCH interfaces to the processor with following pin-based signals other than DMI:

- Standard Outputs to processor: PROCPWRGD, PM\_SYNC, PM\_SYNC2, PECCI
- Standard Input from processor: THRMTRIP#

Most PCH outputs to the processor use standard buffers. The PCH has separate V\_PROC\_IO signals that are pulled up at the system level to the processor voltage, and thus determines VOH for the outputs to the processor.

The following Processor interface legacy pins were removed from the PCH:

- IGNNE#, STPCLK#, DPSP#, DPRSLPVR are no longer required on PCH based systems.
- SMI#, NMI, INIT#, INTR, FERR#: Functionality has been replaced by in-band Virtual Legacy Wire (VLW) messages. See [Section 5.13.3](#).



### 5.13.1 Processor Interface Signals and VLW Messages

This section describes each of the signals that interface between the PCH and the processor(s). Note that the behavior of some signals may vary during processor reset, as the signals are used for frequency strapping.

#### 5.13.1.1 INIT (Initialization)

The INIT# VLW Message is asserted based on any one of several events described in Table 5-24. When any of these events occur, INIT# is asserted for 16 PCI clocks, then driven high.

**Note:** INIT3\_3V# is functionally identical to INIT# VLW but it is a physical signal at 3.3 V.

**Table 5-24. INIT# Going Active**

Cause of INIT3_3V# Going Active	Comment
Shutdown special cycle from processor observed on PCH-Processor interconnect.	INIT assertion based on value of Shutdown Policy Select register (SPS)
PORT92 write, where INIT_NOW (bit 0) transitions from a 0 to a 1.	
PORTCF9 write, where SYS_RST (bit 1) was a 0 and RST_CPU (bit 2) transitions from 0 to 1.	
RCIN# input signal goes low. RCIN# is expected to be driven by the external microcontroller (KBC).	0 to 1 transition on RCIN# must occur before the PCH will arm INIT3_3V# to be generated again. <b>Note:</b> RCIN# signal is expected to be low during S3, S4, and S5 states. Transition on the RCIN# signal in those states (or the transition to those states) may not necessarily cause the INIT3_3V# signal to be generated to the processor.
Processor BIST	To enter BIST, software sets CPU_BIST_EN bit and then does a full processor reset using the CF9 register.

#### 5.13.1.2 FERR# (Numeric Coprocessor Error)

The PCH supports the coprocessor error function with the FERR# message. The function is enabled using the CEN bit. If FERR# is driven active by the processor, IRQ13 goes active (internally). When it detects a write to the COPROC\_ERR register (I/O Register F0h), the PCH negates the internal IRQ13 and IGNNE# will be active. IGNNE# remains active until FERR# is driven inactive. IGNNE# is never driven active unless FERR# is active.

**Note:** IGNNE# – Ignore Numeric Error is now internally generated by the processor.



### 5.13.1.3 NMI (Non-Maskable Interrupt)

Non-Maskable Interrupts (NMIs) can be generated by several sources, as described in Table 5-25.

**Table 5-25. NMI Sources**

Cause of NMI	Comment
SERR# goes active (either internally, externally using SERR# signal, or using message from Processor)	Can instead be routed to generate an SCI, through the NMI2SCI_EN bit (Device 31:Function 0, TCO Base + 08h, bit 11).
IOCHK# goes active using SERIRQ# stream (ISA system Error)	Can instead be routed to generate an SCI, through the NMI2SCI_EN bit (Device 31:Function 0, TCO Base + 08h, bit 11).
SECSTS Register Device 31: Function F0 Offset 1Eh, bit 8.	This is enabled by the Parity Error Response Bit (PER) at Device 30: Function 0 Offset 04, bit 6.
DEV_STS Register Device 31:Function F0 Offset 06h, bit 8	This is enabled by the Parity Error Response Bit (PER) at Device 30: Function 0 Offset 04, bit 6.
GPIO[15:0] when configured as a General Purpose input and routed as NMI (by GPIO_ROUT at Device 31: Function 0 Offset B8)	This is enabled by GPI NMI Enable (GPI_NMI_EN) bits at Device 31: Function 0 Offset: GPIOBASE + 28h bits 15:0

### 5.13.1.4 Processor Power Good (PROCPWRGD)

This signal is connected to the processor’s PRWGOOD input to indicate when the processor power is valid.

## 5.13.2 Dual-Processor Issues

### 5.13.2.1 Usage Differences

In dual-processor designs, some of the processor signals are unused or used differently than for uniprocessor designs.

- FERR# is generally not used, but still supported.
- I/O APIC and SMI# are assumed to be used.

## 5.13.3 Virtual Legacy Wire (VLW) Messages

The PCH supports VLW messages as alternative method of conveying the status of the following legacy sideband interface signals to the Processor:

- INTR, SMI#, INIT#, NMI

**Note:** IGNNE# VLW message is not required to be generated by the PCH as it is internally emulated by the Processor.

VLW are inbound messages to the Processor. They are communicated using Vendor Defined Message over the DMI link.

Legacy processor signals can only be delivered using VLW in PCH. Delivery of legacy processor signals (INTR, SMI#, INIT# or NMI) using I/O APIC controller is not supported.



## 5.14 Power Management

### 5.14.1 Features

- Support for *Advanced Configuration and Power Interface, Version 3.0b (ACPI)* providing power and thermal management
  - ACPI 24-Bit Timer SCI and SMI# Generation
- PCI PME# signal for Wake Up from Low-Power states
- System Sleep State Control
  - ACPI S3 state — Suspend to RAM (STR)
  - ACPI S4 state — Suspend-to-Disk (STD)
  - ACPI G2/S5 state — Soft Off (SOFF)
  - Power Failure Detection and Recovery
  - Deep S4/S5
- Intel ME Power Management Support
  - Wake events from the Intel ME (enabled from all S-States including Catastrophic S5 conditions)

### 5.14.2 PCH and System Power States

Table 5-26 shows the power states defined for PCH-based platforms. The state names generally match the corresponding ACPI states.

**Table 5-26. General Power States for Systems Using the PCH**

State/ Substates	Legacy Name / Description
G0/S0/C0	<b>Full On:</b> Processor operating. Individual devices may be shut down or be placed into lower power states to save power.
G0/S0/Cx	<b>Cx State:</b> Cx states are processor power states within the S0 system state that provide for various levels of power savings. The Processor initiates C-state entry and exit while interacting with the PCH through DMI messaging. The PCH will base its behavior on the Processor state.
G1/S1	<b>S1:</b> PCH provides the S1 messages and the S0 messages on a wake event. It is much preferred for systems to use C-states than S1.
G1/S3	<b>Suspend-To-RAM (STR):</b> The system context is maintained in system DRAM, but power is shut off to non-critical circuits. Memory is retained and refreshes continue. All external clocks stop except RTC.
G1/S4	<b>Suspend-To-Disk (STD):</b> The context of the system is maintained on the disk. All power is then shut off to the system except for the logic required to resume.
G2/S5	<b>Soft Off (SOFF):</b> System context is not maintained. All power is shut off except for the logic required to restart. A full boot is required when waking.
Deep S4/S5	<b>Deep S4/S5:</b> An optional low power state where system context may or may not be maintained depending upon entry condition. All power is shut off except for minimal logic that allows exiting Deep S4/S5. If Deep S4/S5 state was entered from S4 state, then the resume path will place system back into S4. If Deep S4/S5 state was entered from S5 state, then the resume path will place system back into S5.
G3	<b>Mechanical OFF (MOFF):</b> System context not maintained. All power is shut off except for the RTC. No "Wake" events are possible. This state occurs if the user turns off a mechanical switch or if the system power supply is at a level that is insufficient to power the "waking" logic. When system power returns, transition will depend on the state just prior to the entry to G3 and the AFTERG3 bit in the GEN_PMCON_3 register (D31:F0, offset A4). Refer to Table 5-33 for more details.



Table 5-27 shows the transitions rules among the various states. Note that transitions among the various states may appear to temporarily transition through intermediate states. For example, in going from S0 to S3, it may appear to pass through the G1/S1 states. These intermediate transitions and states are not listed in the table.

**Table 5-27. State Transition Rules for the PCH**

Present State	Transition Trigger	Next State
G0/S0/C0	<ul style="list-style-type: none"> <li>• DMI Msg</li> <li>• SLP_EN bit set</li> <li>• Power Button Override<sup>2</sup></li> <li>• Mechanical Off/Power Failure</li> </ul>	<ul style="list-style-type: none"> <li>• G0/S0/Cx</li> <li>• G1/Sx or G2/S5 state</li> <li>• G2/S5</li> <li>• G3</li> </ul>
G0/S0/Cx	<ul style="list-style-type: none"> <li>• DMI Msg</li> <li>• Power Button Override<sup>2</sup></li> <li>• Mechanical Off/Power Failure</li> </ul>	<ul style="list-style-type: none"> <li>• G0/S0/C0</li> <li>• G2/S5</li> <li>• G3</li> </ul>
G1/S1 or G1/S3	<ul style="list-style-type: none"> <li>• Any Enabled Wake Event</li> <li>• Power Button Override<sup>2</sup></li> <li>• Mechanical Off/Power Failure</li> </ul>	<ul style="list-style-type: none"> <li>• G0/S0/C0</li> <li>• G2/S5</li> <li>• G3</li> </ul>
G1/S4	<ul style="list-style-type: none"> <li>• Any Enabled Wake Event</li> <li>• Power Button Override<sup>2</sup></li> <li>• Conditions met as described in <a href="#">Section 5.14.6.6.1</a> and <a href="#">Section 5.14.6.6.2</a></li> <li>• Mechanical Off/Power Failure</li> </ul>	<ul style="list-style-type: none"> <li>• G0/S0/C0</li> <li>• G2/S5</li> <li>• Deep S4/S5</li> <li>• G3</li> </ul>
G2/S5	<ul style="list-style-type: none"> <li>• Any Enabled Wake Event</li> <li>• Conditions met as described in <a href="#">Section 5.14.6.6.1</a> and <a href="#">Section 5.14.6.6.2</a></li> <li>• Mechanical Off/Power Failure</li> </ul>	<ul style="list-style-type: none"> <li>• G0/S0/C0<sup>2</sup></li> <li>• Deep S4/S5</li> <li>• G3</li> </ul>
G2/Deep S4/S5	<ul style="list-style-type: none"> <li>• Any Enabled Wake Event</li> <li>• Mechanical Off/Power Failure</li> </ul>	<ul style="list-style-type: none"> <li>• G0/S0/C0</li> <li>• G1/S4 or G2/S5 (see <a href="#">Section 5.14.6.6.2</a>)</li> <li>• G3</li> </ul>
G3	<ul style="list-style-type: none"> <li>• Power Returns</li> </ul>	<ul style="list-style-type: none"> <li>• Optional to go to S0/C0 (reboot) or G2/S5 (stay off until power button pressed or other wake event). (See Note 1)</li> </ul>

**Notes:**

1. Some wake events can be preserved through power failure.
2. Includes all other applicable types of events that force the host into and stay in G2/S5.
3. If the system was in G1/S4 before G3 entry, then the system will go to S0/C0 or G1/S4.
4. Upon entry to S5 due to a power button override, if Deep S4/S5 is enabled and conditions are met per [Section 5.14.6.6](#) the system will transition to Deep S4/S5.
5. Upon entry to S5 due to a power button override, if Deep S4/S5 is enabled and conditions are met per section 5.13.7.6, the system will transition to Deep S4/S5.

### 5.14.3 System Power Planes

The system has several independent power planes, as described in [Table 5-28](#). Note that when a particular power plane is shut off, it should go to a 0 V level.

**Table 5-28. System Power Plane**

Plane	Controlled By	Description
Processor	SLP_S3# signal	The SLP_S3# signal can be used to cut the power to the processor completely.
Main	SLP_S3# signal	When SLP_S3# goes active, power can be shut off to any circuit not required to wake the system from the S3 state. Since the S3 state requires that the memory context be preserved, power must be retained to the main memory. The processor, devices on the PCI bus, LPC I/F, and graphics will typically be shut off when the Main power plane is off, although there may be small subsections powered.
Memory	SLP_S4# signal SLP_S5# signal	When SLP_S4# goes active, power can be shut off to any circuit not required to wake the system from the S4. Since the memory context does not need to be preserved in the S4 state, the power to the memory can also be shut down. When SLP_S5# goes active, power can be shut off to any circuit not required to wake the system from the S5 state. Since the memory context does not need to be preserved in the S5 state, the power to the memory can also be shut.
Intel ME	SLP_A#	This signal is asserted when the manageability platform goes to MOff. Depending on the platform, this pin may be used to control the Intel ME power planes, LAN subsystem power, and the SPI flash power.
LAN	SLP_LAN#	This signal is asserted in Sx/Moff when both host and Intel ME WOL are not supported. This signal can be use to control power to the Intel GbE PHY.
Suspend	SLP_SUS#	This signal that the Sus rails externally can be shut off for enhanced power saving.
DEVICE[n]	GPIO	Individual subsystems may have their own power plane. For example, GPIO signals may be used to control the power to disk drives, audio amplifiers, or the display screen.

### 5.14.4 SMI#/SCI Generation

Upon any enabled Intel SMI event taking place while the End of Intel SMI (EOS) bit is set, the PCH will clear the EOS bit and assert Intel SMI to the processor, which will cause it to enter SMM space. Intel SMI assertion is performed using a Virtual Legacy Wire (VLW) message. Prior system generations (those based upon legacy processors) used an actual SMI# pin.

Once the Intel SMI VLW has been delivered, the PCH takes no action on behalf of active Intel SMI events until Host software sets the End of Intel SMI (EOS) bit. At that point, if any Intel SMI events are still active, the PCH will send another Intel SMI VLW.

The SCI is a level-mode interrupt that is typically handled by an ACPI-aware operating system. In non-APIC systems (which is the default), the SCI IRQ is routed to one of the 8259 interrupts (IRQ 9, 10, or 11). The 8259 interrupt controller must be programmed to level mode for that interrupt.

In systems using the APIC, the SCI can be routed to interrupts 9, 10, 11, 20, 21, 22, or 23. The interrupt polarity changes depending on whether it is on an interrupt shareable with a PIRQ or not (see [Section 13.1.14](#)). The interrupt remains asserted until all SCI sources are removed.

[Table 5-29](#) shows which events can cause an Intel SMI and SCI. Note that some events can be programmed to cause either an Intel SMI or SCI. The usage of the event for SCI (instead of Intel SMI) is typically associated with an ACPI-based system. Each Intel SMI or SCI source has a corresponding enable and status bit.



**Table 5-29. Causes of Intel® Scalable Memory Interconnect (Intel® SMI) and SCI (Sheet 1 of 2)**

Cause	SCI	SMI	Additional Enables	Where Reported
PME#	Yes	Yes	PME_EN=1	PME_STS
PME_B0 (Internal, Bus 0, PME-Capable Agents)	Yes	Yes	PME_B0_EN=1	PME_B0_STS
PCI Express* PME Messages	Yes	Yes	PCI_EXP_EN=1 (Not enabled for SMI)	PCI_EXP_STS
PCI Express* Hot-Plug Message	Yes	Yes	HOT_PLUG_EN=1 (Not enabled for SMI)	HOT_PLUG_STS
Power Button Press	Yes	Yes	PWRBTN_EN=1	PWRBTN_STS
Power Button Override (Note 7)	Yes	No	None	PRBTNOR_STS
RTC Alarm	Yes	Yes	RTC_EN=1	RTC_STS
Ring Indicate	Yes	Yes	RI_EN=1	RI_STS
USB#1 wakes	Yes	Yes	USB1_EN=1	USB1_STS
USB#2 wakes	Yes	Yes	INTEL_USB2_EN=1	INTEL_USB2_STS
USB#3 wakes	Yes	Yes	USB3_EN=1	USB3_STS
USB#4 wakes	Yes	Yes	USB4_EN=1	USB4_STS
USB#5 wakes	Yes	Yes	USB5_EN=1	USB5_STS
USB#6 wakes	Yes	Yes	USB6_EN=1	USB6_STS
USB#9wakes	Yes	Yes	USB9_EN=1	USB9_STS
ACPI Timer overflow (2.34 sec.)	Yes	Yes	TMROF_EN=1	TMROF_STS
Any GPI[15:0]	Yes	Yes	GPI[x]_Route=10; GPI[x]_EN=1 (SCI) GPI[x]_Route=01; ALT_GPI_SMI[x]_EN=1 (SMI)	GPI[x]_STS ALT_GPI_SMI[x]_STS
GPIO[27]	Yes	Yes	GP27_EN=1	GP27_STS
TCO SCI Logic	Yes	No	TCOSCI_EN=1	TCOSCI_STS
TCO SCI message from MCH	Yes	Yes	none	MCHSCI_STS MCHSMI_STS
TCO SMI Logic	No	Yes	TCO_EN=1	TCO_STS
TCO SMI — Year 2000 Rollover	No	Yes	none	NEWCENTURY_STS
TCO SMI — TCO TIMEROUT	No	Yes	none	TIMEOUT
TCO SMI — OS writes to TCO_DAT_IN register	No	Yes	none	SW_TCO_SMI
TCO SMI — Message from processor	No	Yes	none	DMISMI_STS
TCO SMI — NMI occurred (and NMIs mapped to SMI)	No	Yes	NMI2SMI_EN=1	NMI2SMI_STS
TCO SMI — INTRUDER# signal goes active	No	Yes	INTRD_SEL=10	INTRD_DET
TCO SMI — Change of the BIOSWE (D31:F0:DCh, bit 0) bit from 0 to 1	No	Yes	BCLE=1	BIOSWR_STS
TCO SMI — Write attempted to BIOS	No	Yes	BC.WPD = 0 (Write Protect Disable)	BIOSWR_STS
NMI (and NMI's mapped to SMI) See NMI section for causes of NMI	No	Yes	NMI2SMI_EN=1	TCO_STS_NMI2SMI_STS
BIOS_RLS written to	Yes	No	GBL_EN=1	GBL_STS
GBL_RLS written to	No	Yes	BIOS_EN=1	BIOS_STS
Write to B2h register	No	Yes	APMC_EN = 1	APM_STS



**Table 5-29. Causes of Intel® Scalable Memory Interconnect (Intel® SMI) and SCI (Sheet 2 of 2)**

Cause	SCI	SMI	Additional Enables	Where Reported
Periodic timer expires	No	Yes	PERIODIC_EN=1	PERIODIC_STS
64 ms timer expires	No	Yes	SWSMI_TMR_EN=1	SWSMI_TMR_STS
Enhanced USB Legacy Support Event	No	Yes	LEGACY_USB2_EN = 1	LEGACY_USB2_STS
Enhanced USB Intel Specific Event	No	Yes	INTEL_USB2_EN = 1	INTEL_USB2_STS
Serial IRQ Intel SMI reported	No	Yes	none	SERIRQ_SMI_STS
Device monitors match address in its range	No	Yes	See DEVTRAP_STS register description	DEVTRAP_STS
SMBus Host Controller	No	Yes	SMB_SMI_EN Host Controller Enabled	SMBus host status reg.
SMBus Slave Intel SMI message	No	Yes	none	SMBUS_SMI_STS
SMBus SMBALERT# signal active	No	Yes	none	SMBUS_SMI_STS
SMBus Host Notify message received	No	Yes	HOST_NOTIFY_INTREN	SMBUS_SMI_STS HOST_NOTIFY_STS
Access microcontroller 62h/66h	No	Yes	MCSMI_EN	MCSMI_STS
SLP_EN bit written to 1	No	Yes	SLP_SMI_EN=1	SLP_SMI_STS
SPI Command Completed	No	Yes	See SPI section	SPI_STS
Software Generated GPE	Yes	Yes	SWGPE_EN=1	SWGPE_STS
USB Per-Port Registers Write Enable bit changes to 1	No	Yes	INTEL_USB2_EN=1, Write_Enable_SMI_Enable=1	INTEL_USB2_STS, Write Enable Status
GPIO Lockdown Enable bit changes from '1' to '0'	No	Yes	GPIO_UNLOCK_SMI_EN=1	GPIO_UNLOCK_SMI_STS
VE Host Interface	Yes	Yes	VEHCI_SCI_EN = 1 VEHCI_SMI_EN = 1	VEHCI_SCI_STS VEHCI_SMI_STS
VE Intel ME Interface	Yes	Yes	VEMCI_SCI_EN = 1 VEMCI_SMI_EN = 1	VEMCI_SCI_STS VEMCI_SMI_STS
Intel ME Interface	Yes	Yes	ME_SCI_EN = 1 ME_SMI_EN = 1	ME_SCI_STS ME_SMI_STS
Classic USB Legacy logic (Port 64/60 rd/wr, End of pass-through)	No	Yes	LEGACY_USB_EN = 1	LEGACY_USB_STS
RTC Update-in-progress	No	Yes	see I/O Trap Register section	RTC_UIP_SMI_STS

**Notes:**

1. SCI\_EN must be 1 to enable SCI, except for BIOS\_RLS. SCI\_EN must be 0 to enable SMI.
2. SCI can be routed to cause interrupt 9:11 or 20:23 (20:23 only available in APIC mode).
3. GBL\_SMI\_EN must be 1 to enable SMI.
4. EOS must be written to 1 to re-enable Intel SMI for the next 1.
5. PCH must have Intel SMI fully enabled when PCH is also enabled to trap cycles. If Intel SMI is not enabled in conjunction with the trap enabling, then hardware behavior is undefined.
6. Only GPI[15:0] may generate an Intel SMI or SCI.
7. When a power button override first occurs, the system will transition immediately to S5. The SCI will only occur after the next wake to S0 if the residual status bit (PRBTNOR\_STS) is not cleared prior to setting SCI\_EN.
8. GBL\_STS being set will cause an SCI, even if the SCI\_EN bit is not set. Software must take great care not to set the BIOS\_RLS bit (which causes GBL\_STS to be set) if the SCI handler is not in place.



#### 5.14.4.1 PCI Express\* SCI

PCI Express\* ports and the Processor (using DMI) have the ability to cause PME using messages. When a PME message is received, PCH will set the PCI\_EXP\_STS bit. If the PCI\_EXP\_EN bit is also set, the PCH can cause an SCI using the GPE1\_STS register.

#### 5.14.4.2 PCI Express\* Hot-Plug

PCI Express\* has a Hot-Plug mechanism and is capable of generating a SCI using the GPE1 register. It is also capable of generating an Intel SMI. However, it is not capable of generating a wake event.

### 5.14.5 C-States

PCH-based systems implement C-states by having the Processor control the states. The chipset exchanges messages with the Processor as part of the C-state flow, but the chipset does not directly control any of the Processor impacts of C-states, such as voltage levels or Processor clocking. In addition to the new messages, the PCH also provides additional information to the Processor using a sideband pin (PM\_SYNC). All of the legacy C-state related pins (STPCLK#, STP\_CPU#, DPRSLP#, DPRSLPVR#, and so forth) do not exist on PCH.

### 5.14.6 Sleep States

#### 5.14.6.1 Sleep State Overview

The PCH directly supports different sleep states (S1–S5), which are entered by methods such as setting the SLP\_EN bit, or due to a Power Button press. The entry to the Sleep states is based on several assumptions:

- The G3 state cannot be entered using any software mechanism. The G3 state indicates a complete loss of power.

#### 5.14.6.2 Initiating Sleep State

Sleep states (S1–S5) are initiated by:

- Masking interrupts, turning off all bus master enable bits, setting the desired type in the SLP\_TYP field, and then setting the SLP\_EN bit. The hardware then attempts to gracefully put the system into the corresponding Sleep state.
- Pressing the PWRBTN# Signal for more than 4 seconds to cause a Power Button Override event. In this case the transition to the S5 state is less graceful, since there are no dependencies on DMI messages from the processor or on clocks other than the RTC clock.
- Assertion of the THRMTRIP# signal will cause a transition to the S5 state. This can occur when system is in S0 or S1 state.
- Shutdown by integrated manageability functions (ASF/Intel AMT)
- Internal watchdog timer timeout events



**Table 5-30. Sleep Types**

Sleep Type	Comment
S1	System lowers the processor's power consumption. No snooping is possible in this state.
S3	Asserts SLP_S3#. The SLP_S3# signal controls the power to non-critical circuits. Power is only retained to devices needed to wake from this sleeping state, as well as to the memory.
S4	Asserts SLP_S3# and SLP_S4#. The SLP_S4# signal shuts off the power to the memory subsystem. Only devices needed to wake from this state should be powered.
S5	Same power state as S4. asserts SLP_S3#, SLP_S4# and SLP_S5#.

**5.14.6.3 Exiting Sleep States**

Sleep states (S1–S5) are exited based on Wake events. The Wake events forces the system to a full on state (S0), although some non-critical subsystems might still be shut off and have to be brought back manually. For example, the hard disk may be shut off during a sleep state, and have to be enabled using a GPIO pin before it can be used.

Upon exit from software entered sleep states (that is, those initiated using the SLP\_EN bit) the WAK\_STS bit is set. The possible causes of Wake Events (and their restrictions) are shown in Table 5-31.

**Table 5-31. Causes of Wake Events (Sheet 1 of 2)**

Cause	How Enabled	Wake from S1, Sx	Wake from Deep S4/S5	Wake from S1, Sx After Power Loss (Note 1)	Wake from "Reset" Types (Note 2)
RTC Alarm	Set RTC_EN bit in PM1_EN register.	Y	Y	Y	
Power Button	Always enabled as Wake event.	Y	Y	Y	Y
GPI[15:0]	GPE0_EN register <b>Note:</b> GPI's that are in the core well are not capable of waking the system from sleep states when the core well is not powered.	Y			
GPIO27	Set GP27_EN in GPE0_EN Register.	Y	Y	Y	Y
LAN	Will use PME#. Wake enable set with LAN logic.	Y		Y	
RI#	Set RI_EN bit in GPE0_EN register.	Y		Y	
Intel® High Definition Audio	Event sets PME_B0_STS bit; PM_B0_EN must be enabled. Can not wake from S5 state if it was entered due to power failure or power button override.	Y		Y	
Primary PME#	PME_B0_EN bit in GPE0_EN register.	Y		Y	
Secondary PME#	Set PME_EN bit in GPE0_EN register.	Y		Y	
PCI_EXP_WAKE#	PCI_EXP_WAKE bit. (Note 3)	Y		Y	
SATA	Set PME_EN bit in GPE0_EN register. (Note 4)	S1		S1	
PCI_EXP PME Message	Must use the PCI Express* WAKE# pin rather than messages for wake from S3, S4, or S5.	S1		S1	



**Table 5-31. Causes of Wake Events (Sheet 2 of 2)**

Cause	How Enabled	Wake from S1, Sx	Wake from Deep S4/S5	Wake from S1, Sx After Power Loss (Note 1)	Wake from "Reset" Types (Note 2)
SMBALERT#	Always enabled as Wake event.	Y		Y	Y
SMBus Slave Wake Message (01h)	Wake/SMI# command always enabled as a Wake event. <b>Note:</b> SMBus Slave Message can wake the system from S1–S5, as well as from S5 due to Power Button Override.	Y		Y	Y
SMBus Host Notify message received	HOST_NOTIFY_WKEN bit SMBus Slave Command register. Reported in the SMB_WAK_STS bit in the GPEO_STS register.	Y		Y	Y
Intel® ME Non-Maskable Wake	Always enabled as a wake event.	Y		Y	Y
Integrated WOL Enable Override	WOL Enable Override bit (in Configuration Space).	Y		Y	Y

**Notes:**

1. This column represents what the PCH would honor as wake events but there may be enabling dependencies on the device side which are not enabled after a power loss.
2. Reset Types include: Power Button override, Intel ME initiated power button override, Intel ME initiated host partition reset with power down, Intel ME Watchdog Timer, SMBus unconditional power down, Processor thermal trip, PCH catastrophic temperature event.
3. When the WAKE# pin is active and the PCI Express\* device is enabled to wake the system, the PCH will wake the platform.
4. SATA can only trigger a wake event in S1, but if PME is asserted prior to S3/S4/S5 entry and software does not clear the PME\_B0\_STS, a wake event would still result.

It is important to understand that the various GPIs have different levels of functionality when used as wake events. The GPIs that reside in the core power well can only generate wake events from sleep states where the core well is powered. Also, only certain GPIs are "ACPI Compliant," meaning that their Status and Enable bits reside in ACPI I/O space. Table 5-32 summarizes the use of GPIs as wake events.

**Table 5-32. GPI Wake Events**

GPI	Power Well	Wake From	Notes
GPI[7:0]	Core	S1	ACPI Compliant
GPI[15:8]	Suspend	S1–S5	ACPI Compliant

The latency to exit the various Sleep states varies greatly and is heavily dependent on power supply design, so much so that the exit latencies due to the PCH are insignificant.

**5.14.6.4 PCI Express\* WAKE# Signal and PME Event Message**

PCI Express\* ports can wake the platform from any sleep state (S1, S3, S4, or S5) using the WAKE# pin. WAKE# is treated as a wake event, but does not cause any bits to go active in the GPE\_STS register.

PCI Express\* ports and the processor (using DMI) have the ability to cause PME using messages. When a PME message is received, PCH will set the PCI\_EXP\_STS bit.



### 5.14.6.5 Sx-G3-Sx, Handling Power Failures

Depending on when the power failure occurs and how the system is designed, different transitions could occur due to a power failure.

The AFTERG3\_EN bit provides the ability to program whether or not the system should boot once power returns after a power loss event. If the policy is to not boot, the system remains in an S5 state (unless previously in S4). There are only three possible events that will wake the system after a power failure.

1. **PWRBTN#:** PWRBTN# is always enabled as a wake event. When RSMRST# is low (G3 state), the PWRBTN\_STS bit is reset. When the PCH exits G3 after power returns (RSMRST# goes high), the PWRBTN# signal is already high (because V<sub>CC</sub>-standby goes high before RSMRST# goes high) and the PWRBTN\_STS bit is 0.
2. **RI#:** RI# does not have an internal pull-up. Therefore, if this signal is enabled as a wake event, it is important to keep this signal powered during the power loss event. If this signal goes low (active), when power returns the RI\_STS bit is set and the system interprets that as a wake event.
3. **RTC Alarm:** The RTC\_EN bit is in the RTC well and is preserved after a power loss. Like PWRBTN\_STS the RTC\_STS bit is cleared when RSMRST# goes low.

The PCH monitors both PCH\_PWROK and RSMRST# to detect for power failures. If PCH\_PWROK goes low, the PWROK\_FLR bit is set. If RSMRST# goes low, PWR\_FLR is set.

**Note:** Although PME\_EN is in the RTC well, this signal cannot wake the system after a power loss. PME\_EN is cleared by RTCRST#, and PME\_STS is cleared by RSMRST#.

Table 5-33. Transitions Due to Power Failure

State at Power Failure	AFTERG3_EN bit	Transition When Power Returns
S0, S1, S3	1 0	S5 S0
S4	1 0	S4 S0
S5	1 0	S5 S0
Deep S4/S5	1 0	Deep S4/S51 S0

- Notes:**
1. Entry state to Deep S4/S5 is preserved through G3 allowing resume from Deep S4/S5 to take appropriate path (that is, return to S4 or S5).

### 5.14.6.6 Deep S4/S5

To minimize power consumption while in S4/S5, the PCH supports a lower power, lower featured version of these power states known as Deep S4/S5. In these Deep S4/S5 states, the Suspend wells are powered off, while the new Deep S4/S5 Well (DSW) remains powered. A limited set of wake events are supported by the logic located in the DSW.



### 5.14.6.6.1 Entry Into Deep S4/S5

A combination of conditions is required for entry into Deep S4/S5.

All of the following must be met:

- Intel ME in Mof
- AND ((DPS4\_EN\_AC AND S4) OR (DPS5\_EN\_AC AND S5))

**Table 5-34. Supported Deep S4/S5 Policy Configurations**

Configuration	DPS4_EN_DC	DPS4_EN_AC	DPS5_EN_DC	DPS5_EN_AC
1: Enabled in S5	0	0	1	1
2: Enabled in S4 and S5	1	1	1	1
3: Deep S4 / S5 disabled	0	0	0	0

The PCH also performs a SUSWARN#/SUSACK# handshake to ensure the platform is ready to enter Deep S4/S5. The PCH asserts SUSWARN# as notification that it is about to enter Deep S4/S5. Before the PCH proceeds and asserts SLP\_SUS#, the PCH waits for SUSACK# to assert.

### 5.14.6.6.2 Exit from Deep S4/S5

While in Deep S4/S5, the PCH monitors and responds to a limited set of wake events (RTC Alarm, Power Button, and GPIO27). Upon sensing an enabled Deep S4/S5 wake event, the PCH brings up the Suspend well by deasserting SLP\_SUS#.

**Table 5-35. Deep S4/S5 Wake Events**

Event	Enable
RTC Alarm	RTC_DS_WAKE_DIS (RCBA+3318h:Bit 21)
Power Button	Always enabled
GPIO27	GPIO27_EN (PMBASE+28h:Bit 35)

## 5.14.7 Event Input Signals and Their Usage

The PCH has various input signals that trigger specific events. This section describes those signals and how they should be used.

### 5.14.7.1 PWRBTN# (Power Button)

The PCH PWRBTN# signal operates as a “Fixed Power Button” as described in the *Advanced Configuration and Power Interface, Version 2.0b*. PWRBTN# signal has a 16 ms de-bounce on the input. The state transition descriptions are included in [Table 5-36](#). Note that the transitions start as soon as the PWRBTN# is pressed (but after the debounce logic), and does not depend on when the Power Button is released.

**Note:** During the time that the SLP\_S4# signal is stretched for the minimum assertion width (if enabled), the Power Button is not a wake event. Refer to the following Power Button Override Function section for further detail.



**Table 5-36. Transitions Due to Power Button**

Present State	Event	Transition/Action	Comment
S0/Cx	PWRBTN# goes low	Intel SMI or SCI generated (depending on SCI_EN, PWRBTN_EN and GLB_SMI_EN)	Software typically initiates a Sleep state
S1–S5	PWRBTN# goes low	Wake Event. Transitions to S0 state	Standard wakeup
G3	PWRBTN# pressed	None	No effect since no power Not latched nor detected
S0–S4	PWRBTN# held low for at least 4 consecutive seconds	Unconditional transition to S5 state and if Deep S4/S5 is enabled and conditions are met per Section 5.14.6.6, the system will then transition to Deep S4/S5.	No dependence on processor (DMI Messages) or any other subsystem

**Power Button Override Function**

If PWRBTN# is observed active for at least four consecutive seconds, the state machine unconditionally transitions to the G2/S5 state or Deep S4/S5, regardless of present state (S0–S4), even if the PCH PWROK is not active. In this case, the transition to the G2/S5 state or Deep S4/S5 does not depend on any particular response from the processor (such as, a DMI Messages), nor any similar dependency from any other subsystem.

The PWRBTN# status is readable to check if the button is currently being pressed or has been released. The status is taken after the de-bounce, and is readable using the PWRBTN\_LVL bit.

**Note:** The 4-second PWRBTN# assertion should only be used if a system lock-up has occurred. The 4-second timer starts counting when the PCH is in a S0 state. If the PWRBTN# signal is asserted and held active when the system is in a suspend state (S1–S5), the assertion causes a wake event. Once the system has resumed to the S0 state, the 4-second timer starts.

**Note:** During the time that the SLP\_S4# signal is stretched for the minimum assertion width (if enabled by D31:F0:A4h Bit 3), the Power Button is not a wake event. As a result, it is conceivable that the user will press and continue to hold the Power Button waiting for the system to awake. Since a 4-second press of the Power Button is already defined as an Unconditional Power down, the power button timer will be forced to inactive while the power-cycle timer is in progress. Once the power-cycle timer has expired, the Power Button awakes the system. Once the minimum SLP\_S4# power cycle expires, the Power Button must be pressed for another 4 to 5 seconds to create the Override condition.

**Sleep Button**

The *Advanced Configuration and Power Interface, Version 2.0b* defines an optional Sleep button. It differs from the power button in that it only is a request to go from S0 to S1–S4 (not S5). Also, in an S5 state, the Power Button can wake the system, but the Sleep Button cannot.

Although the PCH does not include a specific signal designated as a Sleep Button, one of the GPIO signals can be used to create a “Control Method” Sleep Button. See the *Advanced Configuration and Power Interface, Version 2.0b* for implementation details.



### 5.14.7.2 RI# (Ring Indicator)

The Ring Indicator can cause a wake event (if enabled) from the S1–S5 states. Table 5-37 shows when the wake event is generated or ignored in different states. If in the G0/S0/Cx states, the PCH generates an interrupt based on RI# active, and the interrupt will be set up as a Break event.

**Table 5-37. Transitions Due to RI# Signal**

Present State	Event	RI_EN	Event
S0	RI# Active	X	Ignored
S1–S5	RI# Active	0	Ignored
		1	Wake Event

**Note:** Filtering/Debounce on RI# will not be done in PCH. Can be in modem or external.

### 5.14.7.3 PME# (PCI Power Management Event)

The PME# signal comes from a PCI device to request that the system be restarted. The PME# signal can generate an SMI#, SCI, or optionally a Wake event. The event occurs when the PME# signal goes from high to low. No event is caused when it goes from low to high.

There is also an internal PME\_B0 bit. This is separate from the external PME# signal and can cause the same effect.

### 5.14.7.4 SYS\_RESET# Signal

When the SYS\_RESET# pin is detected as active after the 16 ms debounce logic, the PCH attempts to perform a “graceful” reset, by waiting up to 25 ms for the SMBus to go idle. If the SMBus is idle when the pin is detected active, the reset occurs immediately; otherwise, the counter starts. If at any point during the count the SMBus goes idle the reset occurs. If, however, the counter expires and the SMBus is still active, a reset is forced upon the system even though activity is still occurring.

Once the reset is asserted, it remains asserted for 5 to 6 ms regardless of whether the SYS\_RESET# input remains asserted or not. It cannot occur again until SYS\_RESET# has been detected inactive after the debounce logic, and the system is back to a full S0 state with PLTRST# inactive. Note that if bit 3 of the CF9h I/O register is set then SYS\_RESET# will result in a full power cycle reset.

### 5.14.7.5 THRMTRIP# Signal

If THRMTRIP# goes active, the processor is indicating an overheat condition, and the PCH immediately transitions to an S5 state, driving SLP\_S3#, SLP\_S4#, SLP\_S5# low, and setting the CTS bit. The transition looks like a power button override.

When a THRMTRIP# event occurs, the PCH will power down immediately without following the normal S0 -> S5 path. The PCH will immediately drive SLP\_S3#, SLP\_S4#, and SLP\_S5# low after sampling THRMTRIP# active.

If the processor is running extremely hot and is heating up, it is possible (although very unlikely) that components around it, such as the PCH, are no longer executing cycles properly. Therefore, if THRMTRIP# goes active, and the PCH is relying on state machine logic to perform the power down, the state machine may not be working, and the system will not power down.

The PCH provides filtering for short low glitches on the THRMTRIP# signal in order to prevent erroneous system shut downs from noise. Glitches shorter than 25 nsec are ignored.



During boot, THRMTRIP# is ignored until SLP\_S3#, PCH\_PWROK, and PLTRST# are all '1'. During entry into a powered-down state (due to S3, S4, S5 entry, power cycle reset, etc.) THRMTRIP# is ignored until either SLP\_S3# = 0, or PCH\_PWROK = 0, or SYS\_PWROK = 0.

**Note:**

A thermal trip event will:

- Clear the PWRBTN\_STS bit
- Clear all the GPE0\_EN register bits
- Clear the SMB\_WAK\_STS bit only if SMB\_SAK\_STS was set due to SMBus slave receiving message and not set due to SMBAlert

### 5.14.8 ALT Access Mode

Before entering a low power state, several registers from powered down parts may need to be saved. In the majority of cases, this is not an issue, as registers have read and write paths. However, several of the ISA compatible registers are either read only or write only. To get data out of write-only registers, and to restore data into read-only registers, the PCH implements an ALT access mode.

If the ALT access mode is entered and exited after reading the registers of the PCH timer (8254), the timer starts counting faster (13.5 ms). The following steps listed below can cause problems:

1. BIOS enters ALT access mode for reading the PCH timer related registers.
2. BIOS exits ALT access mode.
3. BIOS continues through the execution of other needed steps and passes control to the operating system.

After getting control in step #3, if the operating system does not reprogram the system timer again, the timer ticks may be happening faster than expected. For example Microsoft MS-DOS\* and its associated software assume that the system timer is running at 54.6 ms and as a result the time-outs in the software may be happening faster than expected.

Operating systems (for example, Microsoft Windows\* 98 and Windows\* 2000) reprogram the system timer and therefore do not encounter this problem.

For other operating systems (for example, Microsoft MS-DOS\*) the BIOS should restore the timer back to 54.6 ms before passing control to the operating system. If the BIOS is entering ALT access mode before entering the suspend state it is not necessary to restore the timer contents after the exit from ALT access mode.



### 5.14.8.1 Write Only Registers with Read Paths in ALT Access Mode

The registers described in Table 5-38 have read paths in ALT access mode. The access number field in the table indicates which register will be returned per access to that port.

**Table 5-38. Write Only Registers with Read Paths in ALT Access Mode (Sheet 1 of 2)**

Restore Data				Restore Data			
I/O Addr	# of Rds	Access	Data	I/O Addr	# of Rds	Access	Data
00h	2	1	DMA Chan 0 base address low byte	40h	7	1	Timer Counter 0 status, bits [5:0]
		2	DMA Chan 0 base address high byte			2	Timer Counter 0 base count low byte
01h	2	1	DMA Chan 0 base count low byte			3	Timer Counter 0 base count high byte
		2	DMA Chan 0 base count high byte			4	Timer Counter 1 base count low byte
02h	2	1	DMA Chan 1 base address low byte			5	Timer Counter 1 base count high byte
		2	DMA Chan 1 base address high byte			6	Timer Counter 2 base count low byte
03h	2	1	DMA Chan 1 base count low byte			7	Timer Counter 2 base count high byte
		2	DMA Chan 1 base count high byte	41h	1	Timer Counter 1 status, bits [5:0]	
04h	2	1	DMA Chan 2 base address low byte	42h	1	Timer Counter 2 status, bits [5:0]	
		2	DMA Chan 2 base address high byte	70h	1	Bit 7 = NMI Enable, Bits [6:0] = RTC Address	
05h	2	1	DMA Chan 2 base count low byte	C4h	2	1	DMA Chan 5 base address low byte
		2	DMA Chan 2 base count high byte			2	DMA Chan 5 base address high byte
06h	2	1	DMA Chan 3 base address low byte	C6h	2	1	DMA Chan 5 base count low byte
		2	DMA Chan 3 base address high byte			2	DMA Chan 5 base count high byte
07h	2	1	DMA Chan 3 base count low byte	C8h	2	1	DMA Chan 6 base address low byte
		2	DMA Chan 3 base count high byte			2	DMA Chan 6 base address high byte
08h	6	1	DMA Chan 0–3 Command <sup>2</sup>	CAh	2	1	DMA Chan 6 base count low byte
		2	DMA Chan 0–3 Request			2	DMA Chan 6 base count high byte
		3	DMA Chan 0 Mode: Bits(1:0) = 00	CCh	2	1	DMA Chan 7 base address low byte
		4	DMA Chan 1 Mode: Bits(1:0) = 01			2	DMA Chan 7 base address high byte
		5	DMA Chan 2 Mode: Bits(1:0) = 10	CEh	2	1	DMA Chan 7 base count low byte
		6	DMA Chan 3 Mode: Bits(1:0) = 11.			2	DMA Chan 7 base count high byte



**Table 5-38. Write Only Registers with Read Paths in ALT Access Mode (Sheet 2 of 2)**

Restore Data				Restore Data				
I/O Addr	# of Rds	Access	Data	I/O Addr	# of Rds	Access	Data	
20h	12	1	PIC ICW2 of Master controller	D0h	6	1	DMA Chan 4–7 Command <sup>2</sup>	
		2	PIC ICW3 of Master controller			2	DMA Chan 4–7 Request	
		3	PIC ICW4 of Master controller			3	DMA Chan 4 Mode: Bits(1:0) = 00	
		4	PIC OCW1 of Master controller <sup>1</sup>			4	DMA Chan 5 Mode: Bits(1:0) = 01	
		5	PIC OCW2 of Master controller			5	DMA Chan 6 Mode: Bits(1:0) = 10	
		6	PIC OCW3 of Master controller			6	DMA Chan 7 Mode: Bits(1:0) = 11.	
		7	PIC ICW2 of Slave controller					
		8	PIC ICW3 of Slave controller					
		9	PIC ICW4 of Slave controller					
		10	PIC OCW1 of Slave controller <sup>1</sup>					
		11	PIC OCW2 of Slave controller					
		12	PIC OCW3 of Slave controller					

**Notes:**

1. The OCW1 register must be read before entering ALT access mode.
2. Bits 5, 3, 1, and 0 return 0.

**5.14.8.2 PIC Reserved Bits**

Many bits within the PIC are reserved, and must have certain values written in order for the PIC to operate properly. Therefore, there is no need to return these values in ALT access mode. When reading PIC registers from 20h and A0h, the reserved bits shall return the values listed in [Table 5-39](#).

**Table 5-39. PIC Reserved Bits Return Values**

PIC Reserved Bits	Value Returned
ICW2(2:0)	000
ICW4(7:5)	000
ICW4(3:2)	00
ICW4(0)	0
OCW2(4:3)	00
OCW3(7)	0
OCW3(5)	Reflects bit 6
OCW3(4:3)	01



### 5.14.8.3 Read Only Registers with Write Paths in ALT Access Mode

The registers described in Table 5-40 have write paths to them in ALT access mode. Software restores these values after returning from a powered down state. These registers must be handled special by software. When in normal mode, writing to the base address/count register also writes to the current address/count register. Therefore, the base address/count must be written first, then the part is put into ALT access mode and the current address/count register is written.

**Table 5-40. Register Write Accesses in ALT Access Mode**

I/O Address	Register Write Value
08h	DMA Status Register for channels 0–3.
D0h	DMA Status Register for channels 4–7.

## 5.14.9 System Power Supplies, Planes, and Signals

### 5.14.9.1 Power Plane Control with SLP\_S3#, SLP\_S4#, SLP\_S5#, SLP\_A# and SLP\_LAN#

The SLP\_S3# output signal can be used to cut power to the system core supply, since it only goes active for the Suspend-to-RAM state (typically mapped to ACPI S3). Power must be maintained to the PCH suspend well, and to any other circuits that need to generate Wake signals from the Suspend-to-RAM state. During S3 (Suspend-to-RAM) all signals attached to powered down plans will be tri-stated or driven low, unless they are pulled using a pull-up resistor.

Cutting power to the core may be done using the power supply, or by external FETs on the motherboard.

The SLP\_S4# or SLP\_S5# output signal can be used to cut power to the system core supply, as well as power to the system memory, since the context of the system is saved on the disk. Cutting power to the memory may be done using the power supply, or by external FETs on the motherboard.

The SLP\_S4# output signal is used to remove power to additional subsystems that are powered during SLP\_S3#.

SLP\_S5# output signal can be used to cut power to the system core supply, as well as power to the system memory, since the context of the system is saved on the disk. Cutting power to the memory may be done using the power supply, or by external FETs on the motherboard.

SLP\_A# output signal can be used to cut power to the Intel ME, Clock chip and SPI flash on a platform that supports the M3 state (for example, certain power policies in Intel AMT).

SLP\_LAN# output signal can be used to cut power to the external Intel 82579 Gbe PHY device.

### 5.14.9.2 SLP\_S4# and Suspend-To-RAM Sequencing

The system memory suspend voltage regulator is controlled by the Glue logic. The SLP\_S4# signal should be used to remove power to system memory rather than the SLP\_S5# signal. The SLP\_S4# logic in the PCH provides a mechanism to fully cycle the power to the DRAM and/or detect if the power is not cycled for a minimum time.

**Note:** To utilize the minimum DRAM power-down feature that is enabled by the SLP\_S4# Assertion Stretch Enable bit (D31:F0:A4h bit 3), the DRAM power must be controlled by the SLP\_S4# signal.



### 5.14.9.3 PCH\_PWROK Signal

When asserted, PCH\_PWROK is an indication to the PCH that its core well power rails have been powered and stable. PCH\_PWROK can be driven asynchronously. When PCH\_PWROK is low, the PCH asynchronously asserts PLTRST#. PCH\_PWROK must not glitch, even if RSMRST# is low.

It is required that the power associated with PCI/PCIe have been valid for 99 ms prior to PCH\_PWROK assertion in order to comply with the 100 ms PCI 2.3 / PCIe 1.1 specification on PLTRST# deassertion.

**Note:** SYS\_RESET# is recommended for implementing the system reset button. This saves external logic that is needed if the PCH\_PWROK input is used. Additionally, it allows for better handling of the SMBus and processor resets and avoids improperly reporting power failures.

### 5.14.9.4 SLP\_LAN# Pin Behavior

The following table summarizes SLP\_LAN# pin behavior.

**Table 5-41. SLP\_LAN# Pin Behavior**

Pin Functionality (Determined by soft strap)	SLP_LAN Default Value Bit	GPIO29 Input / Output (Determined by GP_IO_SEL bit)	Pin Value In S0 or M3	Value in S3-S5/Moff
SLP_LAN#	0 (Default)	In (Default)	1	0
		Out	1	Depends on GPIO29 output data value
	1	In (Default)	1	1
		Out	1	Depends on GPIO29 output data value
GPIO29	0 (Default)	In	Z (tri-state)	0
	1	In	Z (tri-state)	1
	N/A	Out	Depends on GPIO29 output data value	Depends on GPIO29 output data value

### 5.14.9.5 RTCRST# and SRPCRST#

RTCRST# is used to reset PCH registers in the RTC Well to their default value. If a jumper is used on this pin, it should only be pulled low when system is in the G3 state and then replaced to the default jumper position. Upon booting, BIOS should recognize that RTCRST# was asserted and clear internal PCH registers accordingly. It is imperative that this signal not be pulled low in the S0 to S5 states.

SRPCRST# is used to reset portions of the Intel Management Engine and should not be connected to a jumper or button on the platform. The only time this signal gets asserted (driven low in combination with RTCRST#) should be when the coin cell battery is removed or not installed and the platform is in the G3 state. Pulling this signal low independently (without RTCRST# also being driven low) may cause the platform to enter an indeterminate state. Similar to RTCRST#, it is imperative that SRPCRST# not be pulled low in the S0 to S5 states.

See [Figure 2-2](#) which demonstrates the proper circuit connection of these pins.



### 5.14.9.6 SUSWARN#/GPIO30 Pin Behavior

Table 5-42 summarize SUSWARN#/GPIO30 pin behavior.

**Table 5-42. SUSWARN#/GPIO30 Steady State Pin Behavior**

	Deep S4/S5 (Supported/Not-Supported)	GPIO30 Input/ Output (Determine by GP_IO_SEL bit)	Pin Value in S0	Pin Value in Sx/Moff	Pin Value in Sx/M3	Pin Value in Deep S4/ S5
SUSWARN#	Supported	Native	1	1 (Note 1)	1	Off
GPIO30	Don't Care	IN	High-Z	High-Z	High-Z	Off
	Don't Care	OUT	Depends on GPIO30 output data value	Depends on GPIO30 output data value	Depends on GPIO30 output data value	Off

**Notes:**

1. If entering Deep S4/S5, pin will assert and become undriven ("Off") when suspend well drops upon Deep S4/S5 entry.

### 5.14.10 Legacy Power Management Theory of Operation

Instead of relying on ACPI software, legacy power management uses BIOS and various hardware mechanisms. The scheme relies on the concept of detecting when individual subsystems are idle, detecting when the whole system is idle, and detecting when accesses are attempted to idle subsystems.

However, the operating system is assumed to be at least APM enabled. Without APM calls, there is no quick way to know when the system is idle between keystrokes. The PCH does not support burst modes.

#### 5.14.10.1 APM Power Management

The PCH has a timer that, when enabled by the 1MIN\_EN bit in the Intel SMI Control and Enable register, generates an Intel SMI once per minute. The Intel SMI handler can check for system activity by reading the DEVTRAP\_STS register. If none of the system bits are set, the Intel SMI handler can increment a software counter. When the counter reaches a sufficient number of consecutive minutes with no activity, the Intel SMI handler can then put the system into a lower power state.

If there is activity, various bits in the DEVTRAP\_STS register will be set. Software clears the bits by writing a 1 to the bit position.

The DEVTRAP\_STS register allows for monitoring various internal devices, or Super I/O devices (SP, PP, FDC) on LPC or PCI, keyboard controller accesses, or audio functions on LPC or PCI. Other PCI activity can be monitored by checking the PCI interrupts.

#### 5.14.11 Reset Behavior

When a reset is triggered, the PCH will send a warning message to the Processor to allow the Processor to attempt to complete any outstanding memory cycles and put memory into a safe state before the platform is reset. When the Processor is ready, it will send an acknowledge message to the PCH. Once the message is received the PCH asserts PLTRST#.

The PCH does not require an acknowledge message from the processor to trigger PLTRST#. A global reset will occur after 4 seconds if an acknowledge from the processor is not received.

When the PCH causes a reset by asserting PLTRST# its output signals will go to their reset states as defined in [Chapter 3](#).



A reset in which the host platform is reset and PLTRST# is asserted is called a Host Reset or Host Partition Reset. Depending on the trigger a host reset may also result in power cycling see Table 5-43 for details. If a host reset is triggered and the PCH times out before receiving an acknowledge message from the Processor a Global Reset with power cycle will occur.

A reset in which the host and Intel ME partitions of the platform are reset is called a Global Reset. During a Global Reset, all PCH functionality is reset except RTC Power Well backed information and Suspend well status, configuration, and functional logic for controlling and reporting the reset. Intel ME and Host power back up after the power cycle period.

Straight to S5 is another reset type where all power wells that are controlled by the SLP\_S3#, SLP\_S4#, and SLP\_A# pins, as well as SLP\_S5# and SLP\_LAN# (if pins are not configured as GPIOs), are turned off. All PCH functionality is reset except RTC Power Well backed information and Suspend well status, configuration, and functional logic for controlling and reporting the reset. The host stays there until a valid wake event occurs.

Table 5-43 shows the various reset triggers:

**Table 5-43. Causes of Host and Global Resets (Sheet 1 of 2)**

Trigger	Host Reset without Power Cycle <sup>1</sup>	Host Reset with Power Cycle <sup>2</sup>	Global Reset with Power Cycle <sup>3</sup>	Straight to S5 <sup>6</sup> (Host Stays there)
Write of 0Eh to CF9h (RST_CNT Register)	No	Yes	No (Note 4)	
Write of 06h to CF9h (RST_CNT Register)	Yes	No	No (Note 4)	
SYS_RESET# Asserted and CF9h (RST_CNT Register) Bit 3 = 0	Yes	No	No (Note 4)	
SYS_RESET# Asserted and CF9h (RST_CNT Register) Bit 3 = 1	No	Yes	No (Note 4)	
SMBus Slave Message received for Reset with Power Cycle	No	Yes	No (Note 4)	
SMBus Slave Message received for Reset without Power Cycle	Yes	No	No (Note 4)	
SMBus Slave Message received for unconditional Power Down	No	No	No	Yes
TCO Watchdog Timer reaches zero two times	Yes	No	No (Note 4)	
Power Failure: PWROK signal goes inactive in S0/S1 or DPWROK drops	No	No	Yes	
SYS_PWROK Failure: SYS_PWROK signal goes inactive in S0/S1	No	No	Yes	
Processor Thermal Trip (THRMTRIP#) causes transition to S5 and reset asserts	No	No	No	Yes
PCH internal thermal sensors signals a catastrophic temperature condition	No	No	No	Yes
Power Button 4 second override causes transition to S5 and reset asserts	No	No	No	Yes
Special shutdown cycle from processor causes CF9h-like PLTRST# and CF9h (RST_CNT Register) Bit 3 = 1	No	Yes	No (Note 4)	
Special shutdown cycle from processor causes CF9h-like PLTRST# and CF9h (RST_CNT Register) Bit 3 = 0	Yes	No	No (Note 4)	
Intel ME Triggered Host Reset without power cycle	Yes	No	No (Note 4)	
Intel ME Triggered Host Reset with power cycle	No	Yes	No (Note 4)	



Table 5-43. Causes of Host and Global Resets (Sheet 2 of 2)

Trigger	Host Reset without Power Cycle <sup>1</sup>	Host Reset with Power Cycle <sup>2</sup>	Global Reset with Power Cycle <sup>3</sup>	Straight to S5 <sup>6</sup> (Host Stays there)
Intel ME Triggered Power Button Override	No	No	No	Yes
Intel ME Watchdog Timer Timeout	No	No	No	Yes
Intel ME Triggered Global Reset	No	No	Yes	
Intel ME Triggered Host Reset with power down (host stays there)	No	Yes (Note 5)	No (Note 4)	
PLTRST# Entry Time-out	No	No	Yes	
S3/4/5 Entry Timeout	No	No	No	Yes
PROCPWRGD Stuck Low	No	No	Yes	
Power Management Watchdog Timer	No	No	No	Yes
Intel ME Hardware Uncorrectable Error	No	No	No	Yes

**Notes:**

1. The PCH drops this type of reset request if received while the system is in S3/S4/S5.
2. PCH does not drop this type of reset request if received while system is in a software-entered S3/S4/S5 state. However, the PCH is allowed to perform the reset without executing the RESET\_WARN protocol in these states.
3. The PCH does not send warning message to processor, reset occurs without delay.
4. Trigger will result in Global Reset with power cycle if the acknowledge message is not received by the PCH.
5. The PCH waits for enabled wake event to complete reset.
6. Upon entry to S5, if Deep S4/S5 is enabled and conditions are met per [Section 5.14.6.6](#), the system will transition to Deep S4/S5.

## 5.15 System Management (D31:F0)

The PCH provides various functions to make a system easier to manage and to lower the Total Cost of Ownership (TCO) of the system. Features and functions can be augmented using external A/D converters and GPIO, as well as an external microcontroller.

The following features and functions are supported by the PCH:

- Processor present detection
  - Detects if processor fails to fetch the first instruction after reset
- Various Error detection (such as ECC Errors) indicated by host controller
  - Can generate SMI#, SCI, SERR, NMI, or TCO interrupt
- Intruder Detect input
  - Can generate TCO interrupt or SMI# when the system cover is removed
  - INTRUDER# allowed to go active in any power state, including G3
- Detection of bad BIOS Flash (FWH or Flash on SPI) programming
  - Detects if data on first read is FFh (indicates that BIOS flash is not programmed)
- Ability to hide a PCI device
  - Allows software to hide a PCI device in terms of configuration space through the use of a device hide register. (See [Section 10.1.45](#))

**Note:** Voltage ID from the processor can be read using GPI signals.

### 5.15.1 Theory of Operation

The System Management functions are designed to allow the system to diagnose failing subsystems. The intent of this logic is that some of the system management functionality can be provided without the aid of an external microcontroller.

#### 5.15.1.1 Detecting a System Lockup

When the processor is reset, it is expected to fetch its first instruction. If the processor fails to fetch the first instruction after reset, the TCO timer times out twice and the PCH asserts PLTRST#.

#### 5.15.1.2 Handling an Intruder

The PCH has an input signal, INTRUDER#, that can be attached to a switch that is activated by the system's case being open. This input has a two RTC clock debounce. If INTRUDER# goes active (after the debouncer), this will set the INTRD\_DET bit in the TCO2\_STS register. The INTRD\_SEL bits in the TCO\_CNT register can enable the PCH to cause an SMI# or interrupt. The BIOS or interrupt handler can then cause a transition to the S5 state by writing to the SLP\_EN bit.

The software can also directly read the status of the INTRUDER# signal (high or low) by clearing and then reading the INTRD\_DET bit. This allows the signal to be used as a GPI if the intruder function is not required.

If the INTRUDER# signal goes inactive some point after the INTRD\_DET bit is written as a 1, then the INTRD\_DET signal will go to a 0 when INTRUDER# input signal goes inactive. Note that this is slightly different than a classic sticky bit, since most sticky bits would remain active indefinitely when the signal goes active and would immediately go inactive when a 1 is written to the bit.

**Note:** The INTRD\_DET bit resides in the PCH's RTC well, and is set and cleared synchronously with the RTC clock. Thus, when software attempts to clear INTRD\_DET (by writing a 1 to the bit location) there may be as much as two RTC clocks (about 65  $\mu$ s) delay before the bit is actually cleared. Also, the INTRUDER# signal should be asserted for a minimum of 1 ms to ensure that the INTRD\_DET bit will be set.

**Note:** If the INTRUDER# signal is still active when software attempts to clear the INTRD\_DET bit, the bit remains set and the Intel SMI is generated again immediately. The Intel SMI handler can clear the INTRD\_SEL bits to avoid further Intel SMIs. However, if the INTRUDER# signal goes inactive and then active again, there will not be further Intel SMIs, since the INTRD\_SEL bits would select that no SMI# be generated.

#### 5.15.1.3 Detecting Improper Flash Programming

The PCH can detect the case where the BIOS flash is not programmed. This results in the first instruction fetched to have a value of FFh. If this occurs, the PCH sets the BAD\_BIOS bit. The BIOS flash may reside in FWH or flash on the SPI bus.

#### 5.15.1.4 Heartbeat and Event Reporting using SMLink/SMBus (SRV/WS SKUs Only)

Heartbeat and event reporting using SMLink/SMBus is no longer supported. The Intel AMT logic in PCH can be programmed to generate an interrupt to the Intel ME when an event occurs. The Intel ME will poll the TCO registers to gather appropriate bits to send the event message to the Gigabit Ethernet controller, if Intel ME is programmed to do so.

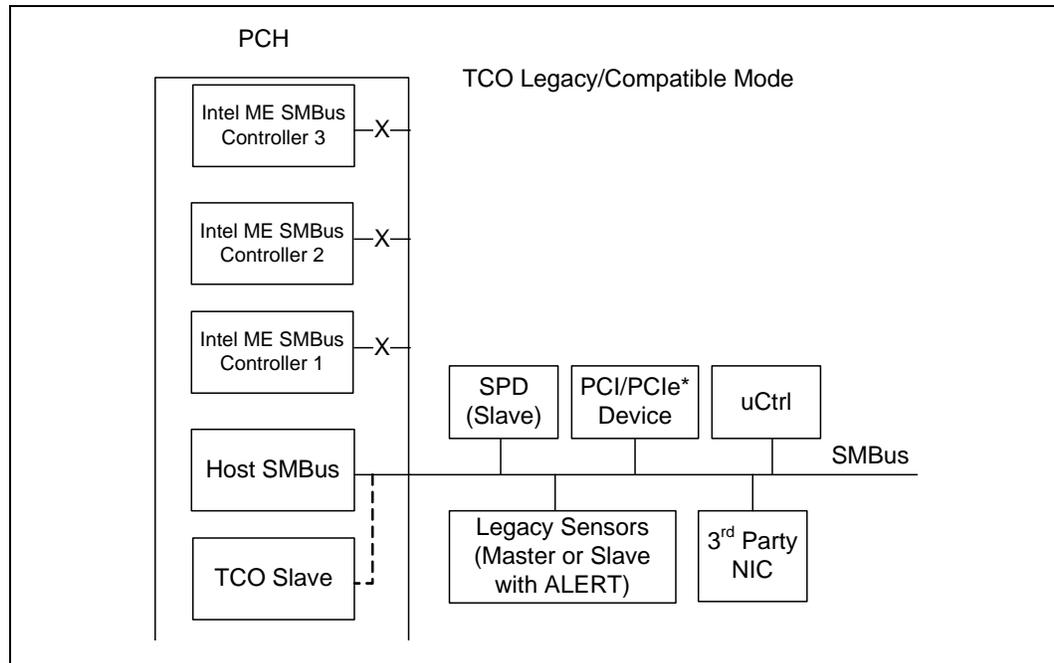


## 5.15.2 TCO Modes

### 5.15.2.1 TCO Legacy/Compatible Mode

In TCO Legacy/Compatible mode, only the host SMBus is utilized. The TCO Slave is connected to the host SMBus internally by default. In this mode, the Intel ME SMBus controllers are not used and should be disabled by soft strap.

**Figure 5-7. TCO Legacy/Compatible Mode SMBus Configuration**



In TCO Legacy/Compatible mode the PCH can function directly with an external LAN controller or equivalent external LAN controller to report messages to a network management console without the aid of the system processor. This is crucial in cases where the processor is malfunctioning or cannot function due to being in a low-power state. Table 5-44 includes a list of events that will report messages to the network management console.

**Table 5-44. Event Transitions that Cause Messages**

Event	Assertion?	Deassertion?	Comments
INTRUDER# pin	yes	no	Must be in "S1 or hung S0" state
THRM# pin	yes	yes	Must be in "S1 or hung S0" state. Note that the THRM# pin is isolated when the core power is off, thus preventing this event in S3-S5.
Watchdog Timer Expired	yes	no (NA)	"S1 or hung S0" state entered
GPIO[11]/SMBALERT# pin	yes	yes	Must be in "S1 or hung S0" state
BATLOW#	yes	yes	Must be in "S1 or hung S0" state

**Note:** The GPIO11/SMBALERT# pin will trigger an event message (when enabled by the GPIO11\_ALERT\_DISABLE bit) regardless of whether it is configured as a GPI or not.

### 5.15.2.2 Advanced TCO Mode

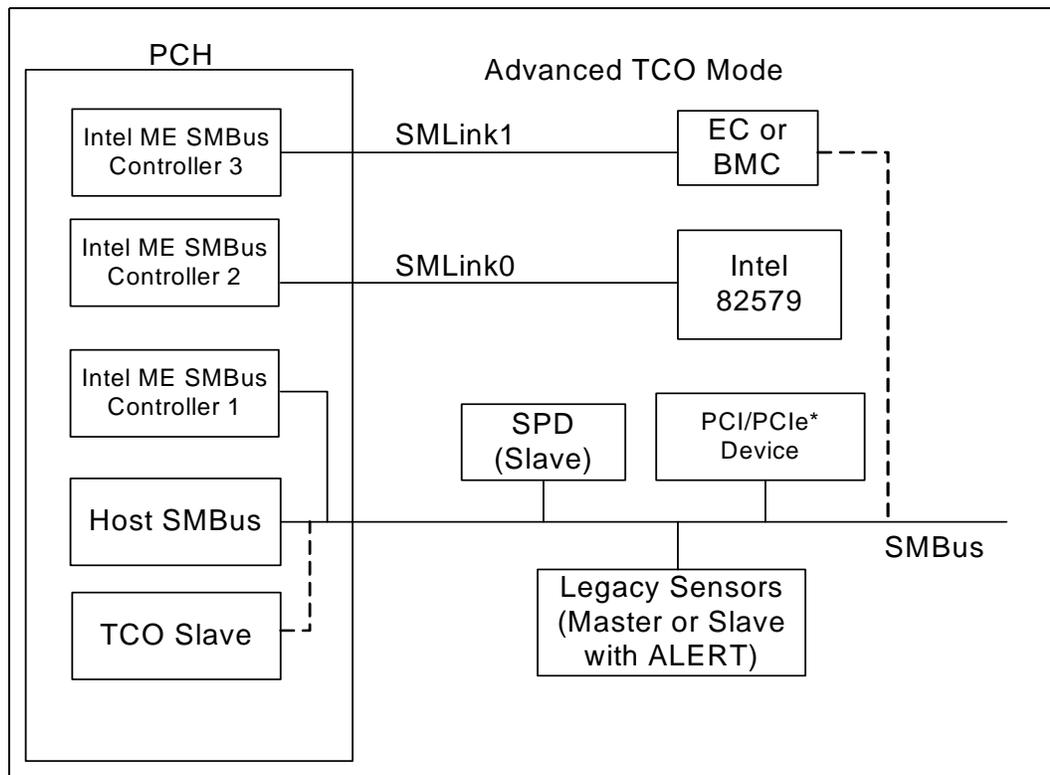
PCH supports the Advanced TCO mode in which SMLink0 and SMLink1 are used in addition to the host SMBus. See Figure 5-8 for more details. In this mode, the Intel ME SMBus controllers must be enabled by soft strap (\*TCO Slave Select) in the flash descriptor.

The SMLink0 is dedicated to integrated LAN use and when an Intel PHY 82579 is connected to SMLink0, a soft strap must be set to indicate that the PHY is connected to SMLink0. The interface will be running at the frequency of 300 KHz - 400 KHz depending on different factors such as board routing or bus loading when the Fast Mode is enabled using a soft strap.

**Note:** With Intel SPS FW, the SMLink0 can also be used with BMC. However, this precludes use of the Intel PHY 82579.

SMLink1 is dedicated to Embedded Controller (EC) or Baseboard Management Controller (BMC) use. In the case where a BMC is connected to SMLink1, the BMC communicates with Intel ME through Intel ME SMBus connected to SMLink1. The host and TCO slave communicated with BMC through SMBus.

Figure 5-8. Advanced TCO Mode





## 5.16 General Purpose I/O (D31:F0)

The PCH contains up to 70 General Purpose Input/Output (GPIO) signals. Each GPIO can be configured as an input or output signal. The number of inputs and outputs varies depending on the configuration. Below is a brief summary of new GPIO features.

- Capability to mask Suspend well GPIOs from CF9h events configured using GP\_RST\_SEL registers)
- Added capability to program GPIO prior to switching to output

### 5.16.1 Power Wells

Some GPIOs exist in the suspend power plane. Care must be taken to make sure GPIO signals are not driven high into powered-down planes. Some PCH GPIOs may be connected to pins on devices that exist in the core well. If these GPIOs are outputs, there is a danger that a loss of core power (PCH\_PWROK low) or a Power Button Override event results in PCH driving a pin to a logic 1 to another device that is powered down.

### 5.16.2 SMI# SCI and NMI Routing

The routing bits for GPIO[15:0] allow an input to be routed to SMI#, SCI, NMI or neither. Note that a bit can be routed to either an SMI# or an SCI, but not both.

### 5.16.3 Triggering

GPIO[15:0] have “sticky” bits on the input. Refer to the GPE0\_STS register and the ALT\_GPI\_SMI\_STS register. As long as the signal goes active for at least 2 clock cycles, the PCH keeps the sticky status bit active. The active level can be selected in the GP\_INV register. This does not apply to GPI\_NMI\_STS residing in GPIO IO space.

If the system is in an S0 or an S1 state, the GPI inputs are sampled at 33 MHz, so the signal only needs to be active for about 60 ns to be latched. In the S3–S5 states, the GPI inputs are sampled at 32.768 kHz, and thus must be active for at least 61 microseconds to be latched.

**Note:** GPIs that are in the core well are not capable of waking the system from sleep states where the core well is not powered.

If the input signal is still active when the latch is cleared, it will again be set. Another edge trigger is not required. This makes these signals “level” triggered inputs.

### 5.16.4 GPIO Registers Lockdown

The following GPIO registers are locked down when the GPIO Lockdown Enable (GLE) bit is set. The GLE bit resides in D31:F0:GPIO Control (GC) register.

- Offset 00h: GPIO\_USE\_SEL[31:0]
- Offset 04h: GP\_IO\_SEL[31:0]
- Offset 0Ch: GP\_LVL[31:0]
- Offset 28h: GPI\_NMI\_EN[15:0]
- Offset 2Ch: GPI\_INV[31:0]
- Offset 30h: GPIO\_USE\_SEL2[63:32]
- Offset 34h: GPI\_IO\_SEL2[63:32]
- Offset 38h: GP\_LVL2[63:32]
- Offset 40h: GPIO\_USE\_SEL3[95:64]

- Offset 44h: GPI\_IO\_SEL3[95:64]
- Offset 48h: GP\_LVL3[95:64]
- Offset 60h: GP\_RST\_SEL[31:0]
- Offset 64h: GP\_RST\_SEL2[63:32]
- Offset 68h: GP\_RST\_SEL3[95:64]

Once these registers are locked down, they become Read-Only registers and any software writes to these registers will have no effect. To unlock the registers, the GPIO Lockdown Enable (GLE) bit is required to be cleared to '0'. When the GLE bit changes from a '1' to a '0' a System Management Interrupt (SMI#) is generated if enabled. Once the GPIO\_UNLOCK\_SMI bit is set, it can not be changed until a PLTRST# occurs. This ensures that only BIOS can change the GPIO configuration. If the GLE bit is cleared by unauthorized software, BIOS will set the GLE bit again when the SMI# is triggered and these registers will continue to be locked down.

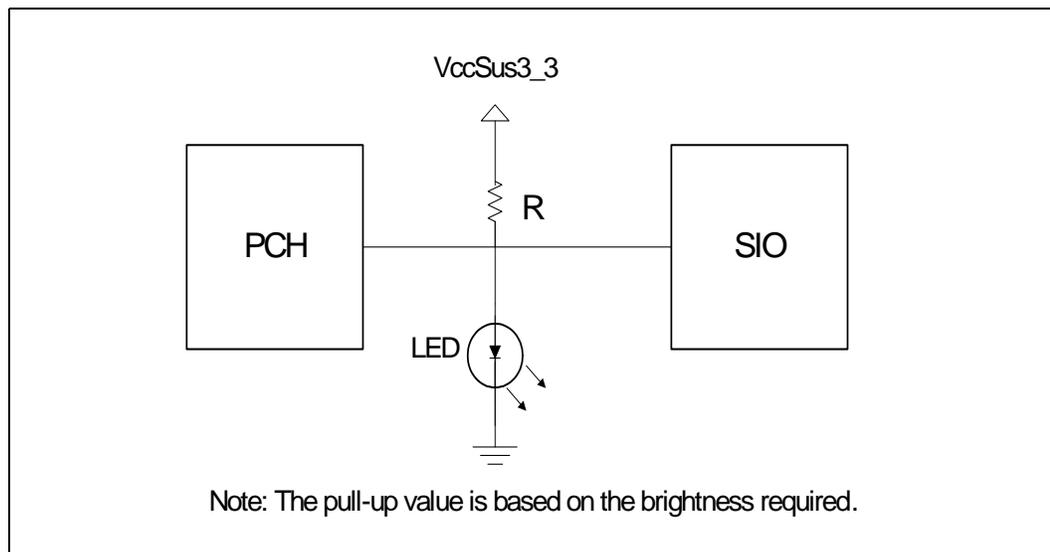
### 5.16.5 Serial POST Codes over GPIO

PCH adds the extended capability allowing system software to serialize POST or other messages on GPIO. This capability negates the requirement for dedicated diagnostic LEDs on the platform. Additionally, based on the newer BTX form factors, the PCI bus as a target for POST codes is increasingly difficult to support as the total number of PCI devices supported are decreasing.

#### 5.16.5.1 Theory of Operation

For the PCH generation POST code serialization logic will be shared with GPIO. These GPIOs will likely be shared with LED control offered by the Super I/O (SIO) component. Figure 5-9 shows a likely configuration.

Figure 5-9. Serial Post over GPIO Reference Circuit



The anticipated usage model is that either the PCH or the SIO can drive a pin low to turn off an LED. In the case of the power LED, the SIO would normally leave its corresponding pin in a high-Z state to allow the LED to turn on. In this state, the PCH can blink the LED by driving its corresponding pin low and subsequently tri-stating the buffer. The I/O buffer should not drive a '1' when configured for this functionality and should be capable of sinking 24 mA of current.



An external optical sensing device can detect the on/off state of the LED. By externally post-processing the information from the optical device, the serial bit stream can be recovered. The hardware will supply a 'sync' byte before the actual data transmission to allow external detection of the transmit frequency. The frequency of transmission should be limited to 1 transition every 1  $\mu$ s to ensure the detector can reliably sample the on/off state of the LED. To allow flexibility in pull-up resistor values for power optimization, the frequency of the transmission is programmable using the DRS field in the GP\_GB\_CMDSTS register.

The serial bit stream is Manchester encoded. This choice of transmission ensures that a transition will be seen on every clock. The 1 or 0 data is based on the transmission happening during the high or low phase of the clock.

As the clock will be encoded within the data stream, hardware must ensure that the Z-0 and 0-Z transitions are glitch-free. Driving the pin directly from a flop or through glitch-free logic are possible methods to meet the glitch-free requirement.

A simplified hardware/software register interface provides control and status information to track the activity of this block. Software enabling the serial blink capability should implement an algorithm referenced below to send the serialized message on the enabled GPIO.

1. Read the Go/Busy status bit in the GP\_GB\_CMDSTS register and verify it is cleared. This will ensure that the GPIO is idled and a previously requested message is still not in progress.
2. Write the data to serialize into the GP\_GB\_DATA register.
3. Write the DLS and DRS values into the GP\_GB\_CMDSTS register and set the Go bit. This may be accomplished using a single write.

The reference diagram shows the LEDs being powered from the suspend supply. By providing a generic capability that can be used both in the main and the suspend power planes maximum flexibility can be achieved. A key point to make is that the PCH will not unintentionally drive the LED control pin low unless a serialization is in progress. System board connections utilizing this serialization capability are required to use the same power plane controlling the LED as the GPIO pin. Otherwise, the PCH GPIO may float low during the message and prevent the LED from being controlled from the SIO. The hardware will only be serializing messages when the core power well is powered and the processor is operational.

Care should be taken to prevent the PCH from driving an active '1' on a pin sharing the serial LED capability. Since the SIO could be driving the line to 0, having the PCH drive a 1 would create a high current path. A recommendation to avoid this condition involves choosing a GPIO defaulting to an input. The GP\_SER\_BLINK register should be set first before changing the direction of the pin to an output. This sequence ensures the open-drain capability of the buffer is properly configured before enabling the pin as an output.

### 5.16.5.2 Serial Message Format

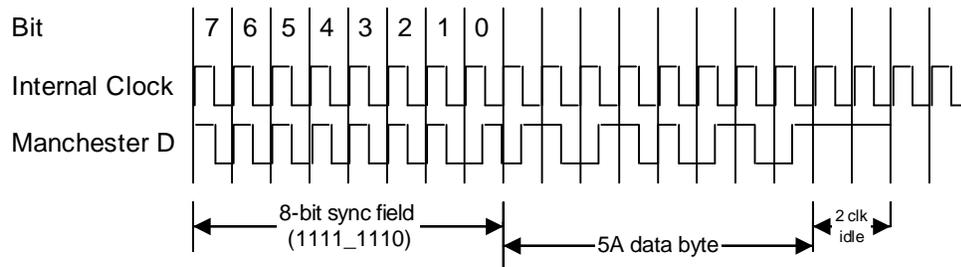
In order to serialize the data onto the GPIO, an initial state of high-Z is assumed. The SIO is required to have its LED control pin in a high-Z state as well to allow PCH to blink the LED (refer to the reference diagram).

The three components of the serial message include the sync, data, and idle fields. The sync field is 7 bits of '1' data followed by 1 bit of '0' data. Starting from the high-Z state (LED on) provides external hardware a known initial condition and a known pattern. In case one or more of the leading 1 sync bits are lost, the 1s followed by 0 provide a clear indication of 'end of sync'. This pattern will be used to 'lock' external sampling logic to the encoded clock.

The data field is shifted out with the highest byte first (MSB). Within each byte, the most significant bit is shifted first (MSb).

The idle field is enforced by the hardware and is at least 2 bit times long. The hardware will not clear the Busy and Go bits until this idle time is met. Supporting the idle time in hardware prevents time-based counting in BIOS as the hardware is immediately ready for the next serial code when the Go bit is cleared. Note that the idle state is represented as a high-Z condition on the pin. If the last transmitted bit is a 1, returning to the idle state will result in a final 0-1 transition on the output Manchester data. Two full bit times of idle correspond to a count of 4 time intervals (the width of the time interval is controlled by the DRS field).

The following waveform shows a 1-byte serial write with a data byte of 5Ah. The internal clock and bit position are for reference purposes only. The Manchester D is the resultant data generated and serialized onto the GPIO. Since the buffer is operating in open-drain mode the transitions are from high-Z to 0 and back.



## 5.16.6 GPIO Serial Expander (GSX)

### 5.16.6.1 Overview

There are a finite number of GPIOs available to be used in the PCH and servers frequently runs out of GPIOs. To help alleviate this issue, a new capability has been added to the PCH, the GPIO Serial Expander. This is a new interface that uses external serial-to-parallel and parallel-to-serial expander chips to provide up to 64 additional general purpose I/O signals in steps of 8 while only consuming 5 PCH's I/O pins.

### 5.16.6.2 Configuration

GSX uses 5 signals, Clock (GSXCLK), Dataout (GSXSDOUT), Datain (GSXSDIN), Reset (GSXSRESET#) and Load (GSXSLOAD). These signals are multiplexed onto PCI Grant and PCI Request signals. A soft strap is used to configure whether GSX is enabled or not. There is no hardstrap configuration or post-boot BIOS setting to change this.

**Note:**

All GSX native functions are determined by GPIO Serial Expander Enable soft strap. Software MUST NOT program the GPIO53/GSXSDIN pin to GPIO mode by setting GPIO\_USE\_SEL[53] bit when GSX is enabled through soft strap. GPIO mode will override GSX operational mode and possible cause board contention on GPIO53 if the platform had planned to use this pin as GSXDIN. It is also recommend that GPIO\_IO\_SEL[53] be set to 1 when operating in GSX mode as added protection against board contention.

### 5.16.6.3 Operation

When the soft straps for the PCH are read, the multiplexed signals become GSX only signals and can not be used as PCI signals or general purpose I/O signals. Coming out of reset, the GSXSRESET# signal automatically gets asserted to clear the outputs. This signal stays active until the first cycle to program/upload data.

Software is required to set up the appropriate registers. It defines how many output registers and input registers there are. The max number of combined registers is 8 as the maximum GPIOs are 64. The registers can be any mix and match of input and



output. For example, you could have 64 outputs and no inputs, 64 inputs and no outputs, 8 inputs and 56 outputs, and so forth. Also, it's not required to add up to a maximum of 64 I/O. The GSX bus could also support only 8 inputs and 8 outputs, for example.

After resetting the GSX bus with a write to IOERST, software will load up the CxGPOLVL and CxGPOLVL\_DW1 registers with data to be written out to the serial to parallel output expanders (how many bits are programmed, is dependent upon how many outputs are defined in the capabilities register). A write to the START (ST) bit will cause the serialization process to begin. First all the output bits are shifted out to the serial to parallel buffers. Then GSXSLOAD goes high to latch in and enable the output of the buffers. At the same time, GSXSLOAD latches in the data into the parallel-to-serial buffers and that data is read into the input buffers (CxGPILVL and CxGPILVL\_DW1).

Once the START bit is set, the serialization process starts running continuously... writing out the contents of the CxGPOLVL registers and programming the contents of the CxGPILVL registers. Clearing this bit (writing a "0" to it) will stop the process but only on an atomic boundary. That is HW will finish serializing the output and finishing reading in the serial data if it began the cycle.

There are two read only bits to help software with the programming of the CxGPOLVL registers and the reading of the CxGPILVL registers. RUNNING (RUN) is set to a "1" as long as the HW is in the process of writing out and reading in data. BUSY (BSY) is a "1" as long as the CxGPOLVL data has not been completely written out at least once. For software to make sure that data is not in the middle of being updated, it needs to wait until RUNNING is a "0". SW will program START to a "0" and wait for RUNNING to be a "0" before it knows it's safe to load in new data to the output buffers, or read data from the input buffers without fear of data being updated in the middle of the cycle.



## 5.17 SATA Host Controller (D31:F2, F5)

The SATA function in the PCH has three modes of operation to support different operating system conditions. In the case of Native IDE enabled operating systems, the PCH uses two controllers to enable all six ports of the bus. The first controller (Device 31: Function 2) supports ports 0 -3 and the second controller (Device 31: Function 5) supports ports 4 and 5. When using a legacy operating system, only one controller (Device 31: Function 2) is available that supports ports 0 - 3. In AHCI or RAID mode, only one controller (Device 31: Function 2) is utilized enabling all six ports and the second controller (Device 31: Function 5) shall be disabled.

The MAP register [Section 15.1.28](#) provides the ability to share PCI functions. When sharing is enabled, all decode of I/O is done through the SATA registers. Device 31, Function 1 (IDE controller) is hidden by software writing to the Function Disable Register (D31, F0, offset F2h, bit 1), and its configuration registers are not used.

The PCH SATA controllers feature six sets of interface signals (ports) that can be independently enabled or disabled (they cannot be tri-stated or driven low). Each interface is supported by an independent DMA controller.

The PCH SATA controllers interact with an attached mass storage device through a register interface that is equivalent to that presented by a traditional IDE host adapter (when AHCI/RAID disabled). The host software follows existing standards and conventions when accessing the register interface and follows standard command protocol conventions.

**Note:** SATA interface transfer rates are independent of UDMA mode settings. SATA interface transfer rates will operate at the bus’s maximum speed, regardless of the UDMA mode reported by the SATA device or the system BIOS.

### 5.17.1 SATA 6 Gb/s Support

The PCH supports SATA 6 Gb/s transfers with all capable SATA devices. SATA 6 Gb/s supports s available on PCH Ports 0 and 1 only.

**Note:** PCH ports 0 and 1 also supports SATA 1.5 Gb/s and 3.0 Gb/s device transfers, while ports 2-5 only support SATA 1.5 Gb/s and 3.0 Gb/s device transfers.

### 5.17.2 SATA Feature Support

Feature	PCH (AHCI/RAID Disabled)	PCH (AHCI/RAID Enabled)
Native Command Queuing (NCQ)	N/A	Supported
Auto Activate for DMA	N/A	Supported
Hot-Plug Support	N/A	Supported
Asynchronous Signal Recovery	N/A	Supported
3 Gb/s Transfer Rate	Supported	Supported
ATAPI Asynchronous Notification	N/A	Supported
Host & Link Initiated Power Management	N/A	Supported
Staggered Spin-Up	Supported	Supported
Command Completion Coalescing	N/A	N/A
External SATA	N/A	Supported



Feature	Description
Native Command Queuing (NCQ)	Allows the device to reorder commands for more efficient data transfers
Auto Activate for DMA	Collapses a DMA Setup then DMA Activate sequence into a DMA Setup only
Hot Plug Support	Allows for device detection without power being applied and ability to connect and disconnect devices without prior notification to the system
Asynchronous Signal Recovery	Provides a recovery from a loss of signal or establishing communication after hot plug
6 Gb/s Transfer Rate	Capable of data transfers up to 6Gb/s
ATAPI Asynchronous Notification	A mechanism for a device to send a notification to the host that the device requires attention
Host & Link Initiated Power Management	Capability for the host controller or device to request Partial and Slumber interface power states
Staggered Spin-Up	Enables the host the ability to spin up hard drives sequentially to prevent power load problems on boot
Command Completion Coalescing	Reduces interrupt and completion overhead by allowing a specified number of commands to complete and then generating an interrupt to process the commands
External SATA	Technology that allows for an outside the box connection of up to 2 meters (when using the cable defined in SATA-IO)

### 5.17.3 Theory of Operation

#### 5.17.3.1 Standard ATA Emulation

The PCH contains a set of registers that shadow the contents of the legacy IDE registers. The behavior of the Command and Control Block registers, PIO, and DMA data transfers, resets, and interrupts are all emulated.

**Note:** The PCH will assert INTR when the master device completes the EDD command regardless of the command completion status of the slave device. If the master completes EDD first, an INTR is generated and BSY will remain '1' until the slave completes the command. If the slave completes EDD first, BSY will be '0' when the master completes the EDD command and asserts INTR. Software must wait for busy to clear (0) before completing an EDD command, as required by the ATA5 through ATA7 (T13) industry standards.

#### 5.17.3.2 48-Bit LBA Operation

The SATA host controller supports 48-bit LBA through the host-to-device register FIS when accesses are performed using writes to the task file. The SATA host controller will ensure that the correct data is put into the correct byte of the host-to-device FIS.

There are special considerations when reading from the task file to support 48-bit LBA operation. Software may need to read all 16-bits. Since the registers are only 8-bits wide and act as a FIFO, a bit must be set in the device/control register, which is at offset 3F6h for primary and 376h for secondary (or their native counterparts).

If software clears bit 7 of the control register before performing a read, the last item written will be returned from the FIFO. If software sets bit 7 of the control register before performing a read, the first item written will be returned from the FIFO.



### 5.17.4 SATA Swap Bay Support

The PCH provides for basic SATA swap bay support using the PSC register configuration bits and power management flows. A device can be powered down by software and the port can then be disabled, allowing removal and insertion of a new device.

**Note:** This SATA swap bay operation requires board hardware (implementation specific), BIOS, and operating system support.

### 5.17.5 Hot-Plug Operation

PCH supports Hot-Plug Surprise removal and Insertion Notification. An internal SATA port with a Mechanical Presence Switch can support PARTIAL and SLUMBER with Hot Plug Enabled. Software can take advantage of power savings in the low power states while enabling hot-plug operation. Refer to chapter 7 of the AHCI specification for details.

### 5.17.6 Function Level Reset Support (FLR) (SRV/WS SKUs Only)

The SATA Host Controller supports the Function Level Reset (FLR) capability. The FLR capability can be used in conjunction with Intel Virtualization Technology. FLR allows an Operating System in a Virtual Machine to have complete control over a device, including its initialization, without interfering with the rest of the platform. The device provides a software interface that enables the Operating System to reset the whole device as if a PCI reset was asserted.

#### 5.17.6.1 FLR Steps

##### 5.17.6.1.1 FLR Initialization

1. A FLR is initiated by software writing a '1' to the Initiate FLR bit.
2. All subsequent requests targeting the Function will not be claimed and will be Master Abort Immediate on the bus. This includes any configuration, I/O or Memory cycles, however, the Function shall continue to accept completions targeting the Function.

##### 5.17.6.1.2 FLR Operation

The Function will Reset all configuration, I/O and memory registers of the Function except those indicated otherwise and reset all internal states of the Function to the default or initial condition.

##### 5.17.6.1.3 FLR Completion

The Initiate FLR bit is reset (cleared) when the FLR reset is completed. This bit can be used to indicate to the software that the FLR reset is completed.

**Note:** From the time Initiate FLR bit is written to '1' software must wait at least 100 ms before accessing the function.



## 5.17.7 Intel® Rapid Storage Technology Enterprise Configuration

The Intel® Rapid Storage Technology enterprise (Intel® RSTe) offers several diverse options for RAID (redundant array of independent disks) to meet the needs of the end user. AHCI support provides higher performance and alleviates disk bottlenecks by taking advantage of the independent DMA engines that each SATA port offers in PCH.

- RAID Level 0 performance scaling up to 4 drives, enabling higher throughput for data intensive applications such as video editing.
- Data redundancy is offered through RAID Level 1, which performs mirroring.
- RAID Level 10 provides high levels of storage performance with increased data protection, combining the fault-tolerance of RAID Level 1 with the performance of RAID Level 0. By striping RAID Level 1 segments, high I/O rates can be achieved on systems that require both performance and fault-tolerance. RAID Level 10 requires 4 hard drives, and provides the capacity of two drives.
- RAID Level 5 provides highly efficient storage while maintaining fault-tolerance on 3 or more drives. By striping parity, and rotating it across all disks, fault tolerance of any single drive is achieved while only consuming 1 drive worth of capacity. That is, a 3 drive RAID 5 has the capacity of 2 drives, or a 4 drive RAID 5 has the capacity of 3 drives. RAID 5 has high read transaction rates, with a medium write rate. RAID 5 is well suited for applications that require high amounts of storage while maintaining fault tolerance.

By using the PCH's built-in Intel Rapid Storage Technology, there is no loss of additional PCIe/system resources or add-in card slot/motherboard space footprint used compared to when a discrete RAID controller is implemented.

Intel Rapid Storage Technology enterprise functionality requires the following items:

1. PCH SKU enabled for Intel Rapid Storage Technology enterprise (see [Section 1.3](#))
2. Intel Rapid Storage Manager RAID Option ROM must be on the platform
3. Intel Rapid Storage Manager drivers, most recent revision.
4. At least two SATA hard disk drives (minimum depends on RAID configuration).

Intel Rapid Storage Technology enterprise is not available in the following configurations:

1. The SATA controller is in compatible mode.
2. The SATA controller is programmed in RAID mode, but the AIE bit (D31:F2:Offset 9Ch bit 7) is set to 1.

### 5.17.7.1 Intel Rapid Storage Technology Manager RAID Option ROM

The Intel Rapid Storage Technology Manager RAID Option ROM is a standard PnP Option ROM that is easily integrated into any System BIOS. When in place, it provides the following three primary functions:

- Provides a text mode user interface that allows the user to manage the RAID configuration on the system in a pre-operating system environment. Its feature set is kept simple to keep size to a minimum, but allows the user to create and delete RAID volumes and select recovery options when problems occur.
- Provides boot support when using a RAID volume as a boot disk. It does this by providing Int13 services when a RAID volume needs to be accessed by MS-DOS applications (such as NTLDR) and by exporting the RAID volumes to the System BIOS for selection in the boot order.
- At each boot up, provides the user with a status of the RAID volumes and the option to enter the user interface by pressing CTRL-I.



## 5.17.8 Power Management Operation

Power management of the PCH SATA controller and ports will cover operations of the host controller and the SATA wire.

### 5.17.8.1 Power State Mappings

The D0 PCI power management state for device is supported by the PCH SATA controller.

SATA devices may also have multiple power states. From parallel ATA, three device states are supported through ACPI. They are:

- **D0** – device is working and instantly available.
- **D1** – device enters when it receives a STANDBY IMMEDIATE command. Exit latency from this state is in seconds
- **D3** – from the SATA device's perspective, no different than a D1 state, in that it is entered using the STANDBY IMMEDIATE command. However, an ACPI method is also called which will reset the device and then cut its power.

Each of these device states are subsets of the host controller's D0 state.

Finally, SATA defines three PHY layer power states, which have no equivalent mappings to parallel ATA. They are:

- **PHY READY** – PHY logic and PLL are both on and active
- **Partial** – PHY logic is powered, but in a reduced state. Exit latency is no longer than 10 ns
- **Slumber** – PHY logic is powered, but in a reduced state. Exit latency can be up to 10 ms.

Since these states have much lower exit latency than the ACPI D1 and D3 states, the SATA controller defines these states as sub-states of the device D0 state.

### 5.17.8.2 Power State Transitions

#### 5.17.8.2.1 Partial and Slumber State Entry/Exit

The partial and slumber states save interface power when the interface is idle. The SATA controller defines PHY layer power management (as performed using primitives) as a driver operation from the host side, and a device proprietary mechanism on the device side. The SATA controller accepts device transition types, but does not issue any transitions as a host. All received requests from a SATA device will be ACKed.

When an operation is performed to the SATA controller such that it needs to use the SATA cable, the controller must check whether the link is in the Partial or Slumber states, and if so, must issue a COM\_WAKE to bring the link back online. Similarly, the SATA device must perform the same action.

#### 5.17.8.2.2 Device D1, D3 States

These states are entered after some period of time when software has determined that no commands will be sent to this device for some time. The mechanism for putting a device in these states does not involve any work on the host controller, other than sending commands over the interface to the device. The command most likely to be used in ATA/ATAPI is the "STANDBY IMMEDIATE" command.



### 5.17.8.2.3 Host Controller D3<sub>HOT</sub> State

After the interface and device have been put into a low power state, the SATA host controller may be put into a low power state. This is performed using the PCI power management registers in configuration space. There are two very important aspects to note when using PCI power management.

1. When the power state is D3, only accesses to configuration space are allowed. Any attempt to access the memory or I/O spaces will result in master abort.
2. When the power state is D3, no interrupts may be generated, even if they are enabled. If an interrupt status bit is pending when the controller transitions to D0, an interrupt may be generated.

When the controller is put into D3, it is assumed that software has properly shut down the device and disabled the ports. Therefore, there is no need to sustain any values on the port wires. The interface will be treated as if no device is present on the cable, and power will be minimized.

When returning from a D3 state, an internal reset will not be performed.

### 5.17.8.2.4 Non-AHCI Mode PME# Generation

When in non-AHCI mode (legacy mode) of operation, the SATA controller does not generate PME#. This includes attach events (since the port must be disabled), or interlock switch events (using the SATAGP pins).

### 5.17.8.3 Intel® Scalable Memory Interconnect (Intel® SMI) Trapping (APM)

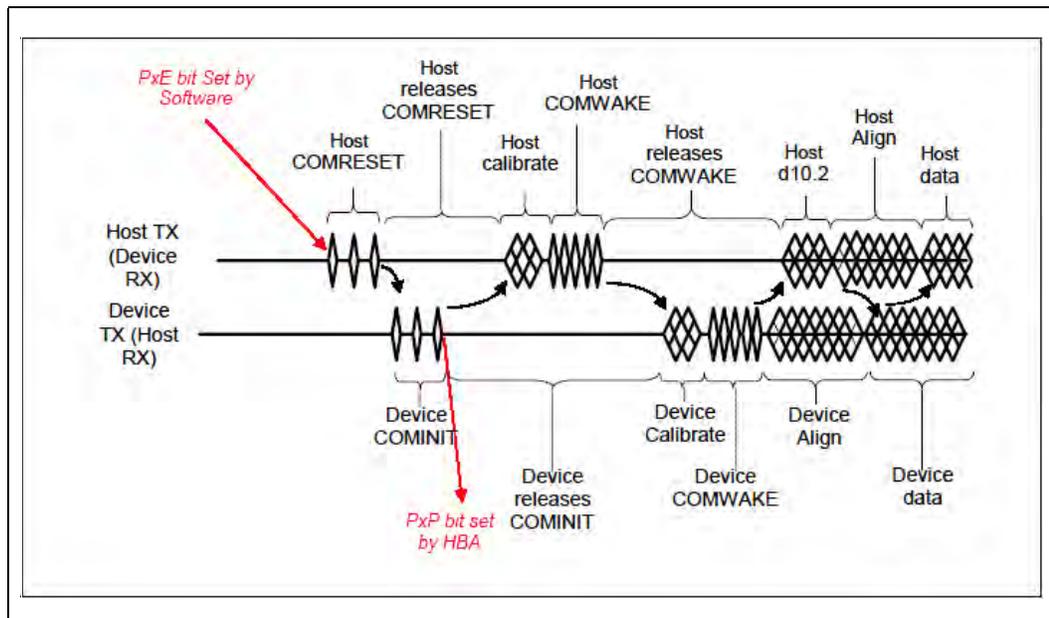
Device 31:Function2:Offset C0h (see [Section 14.1.41](#)) control for generating SMI# on accesses to the IDE I/O spaces. These bits map to the legacy ranges (1F0–1F7h, 3F6h, 170–177h, and 376h) and native IDE ranges defined by PCMDBA, PCTLBA, SCMDBA and SCTLBA. If the SATA controller is in legacy mode and is using these addresses, accesses to one of these ranges with the appropriate bit set causes the cycle to not be forwarded to the SATA controller, and for an SMI# to be generated. If an access to the Bus-Master IDE registers occurs while trapping is enabled for the device being accessed, then the register is updated, an SMI# is generated, and the device activity status bits ([Section 14.1.42](#)) are updated indicating that a trap occurred.

## 5.17.9 SATA Device Presence

In legacy mode, the SATA controller does not generate interrupts based on hot plug/unplug events. However, the SATA PHY does know when a device is connected (if not in a partial or slumber state), and it is beneficial to communicate this information to host software as this will greatly reduce boot times and resume times.

The flow used to indicate SATA device presence is shown in [Figure 5-10](#). The 'PxE' bit refers to PCS.P[3:0]E bits, depending on the port being checked and the 'PxP' bits refer to the PCS.P[3:0]P bits, depending on the port being checked. If the PCS/PxP bit is set a device is present, if the bit is cleared a device is not present. If a port is disabled, software can check to see if a new device is connected by periodically re-enabling the port and observing if a device is present, if a device is not present it can disable the port and check again later. If a port remains enabled, software can periodically poll PCS.PxP to see if a new device is connected.

Figure 5-10. Flow for Port Enable / Device Present Bits



### 5.17.10 SATA LED

The SATALED# output is driven whenever the BSY bit is set in any SATA port. The SATALED# is an active-low open-drain output. When SATALED# is low, the LED should be active. When SATALED# is high, the LED should be inactive.

### 5.17.11 AHCI Operation

The PCH provides hardware support for Advanced Host Controller Interface (AHCI), a programming interface for SATA host controllers developed through a joint industry effort. AHCI defines transactions between the SATA controller and software and enables advanced performance and usability with SATA. Platforms supporting AHCI may take advantage of performance features such as no master/slave designation for SATA devices—each device is treated as a master—and hardware assisted native command queuing. AHCI also provides usability enhancements such as Hot-Plug. AHCI requires appropriate software support (such as, an AHCI driver) and for some features, hardware support in the SATA device or additional platform hardware.

The PCH supports all of the mandatory features of the *Serial ATA Advanced Host Controller Interface Specification*, Revision 1.2 and many optional features, such as hardware assisted native command queuing, aggressive power management, LED indicator support, and Hot-Plug through the use of interlock switch support (additional platform hardware and software may be required depending upon the implementation).

**Note:** For reliable device removal notification while in AHCI operation without the use of interlock switches (surprise removal), interface power management should be disabled for the associated port. See Section 7.3.1 of the *AHCI Specification* for more information.



## 5.17.12 SGPIO Signals

The SGPIO signals, in accordance to the SFF-8485 specification, support per-port LED signaling. These signals are not related to SATALED#, which allows for simplified indication of SATA command activity. The SGPIO group interfaces with an external controller chip that fetches and serializes the data for driving across the SGPIO bus. The output signals then control the LEDs. This feature is only valid in AHCI/RAID mode.

Intel does not validate all possible usage cases of this feature. Customers should validate their specific design implementation on their own platforms.

### 5.17.12.1 Mechanism

The enclosure management for SATA Controller 1 (Device 31: Function 2) involves sending messages that control LEDs in the enclosure. The messages for this function are stored after the normal registers in the AHCI BAR, at Offset 580h bytes for PCH from the beginning of the AHCI BAR as specified by the EM\_LOC global register (Section 14.4.1.6).

Software creates messages for transmission in the enclosure management message buffer. The data in the message buffer should not be changed if CTL.TM bit is set by software to transmit an update message. Software should only update the message buffer when CTL.TM bit is cleared by hardware otherwise the message transmitted will be indeterminate. Software then writes a register to cause hardware to transmit the message or take appropriate action based on the message content. The software should only create message types supported by the controller, which is LED messages for PCH. If the software creates other non LED message types (such as SAF-TE, SES-2), the SGPIO interface may hang and the result is indeterminate.

During reset all SGPIO pins will be in tri-state state. The interface will continue to be in tri-state state after reset until the first transmission occurs when software programs the message buffer and sets the transmit bit CTL.TM. The SATA Host controller will initiate the transmission by driving SCLOCK and at the same time drive the SLOAD to '0' prior to the actual bit stream transmission. The Host will drive SLOAD low for at least 5 SCLOCK then only start the bit stream by driving the SLOAD to high. SLOAD will be driven high for 1 SCLOCK follow by vendor specific pattern that is default to "0000" if software has yet to program the value. A total of 21-bit stream from 7 ports (Port0, Port1, Port2, Port3, Port4 Port5 and Port6) of 3-bit per port LED message will be transmitted on SDATAOUT0 pin after the SLOAD is driven high for 1 SCLOCK. Only 3 ports (Port4, Port5 and Port6) of 9 bit total LED message follow by 12 bits of tri-state value will be transmitted out on SDATAOUT1 pin.

All the default LED message values will be high prior to software setting them, except the Activity LED message that is configured to be hardware driven that will be generated based on the activity from the respective port. All the LED message values will be driven to '1' for the port that is unimplemented as indicated in the Port Implemented register regardless of the software programmed value through the message buffer.

There are 2 different ways of resetting PCH SGPIO interface, asynchronous reset and synchronous reset. Asynchronous reset is caused by platform reset to cause the SGPIO interface to be tri-state asynchronously. Synchronous reset is caused by setting the CTL.RESET bit, clearing the GHC.AE bit or HBA reset, where Host Controller will complete the existing full bit stream transmission then only tri-state all the SGPIO pins. After the reset, both synchronous and asynchronous, the SGPIO pins will stay tri-stated.

**Note:** PCH Host Controller does not ensure that it will cause the target SGPIO device or controller to be reset. Software is responsible to keep PCH SGPIO interface in tri-state for 2 second in order to cause a reset on the target of the SGPIO interface.



### 5.17.12.2 Message Format

Messages shall be constructed with a one DWord header that describes the message to be sent followed by the actual message contents. The first DWord shall be constructed as follows:

Bit	Description
31:28	Reserved
27:24	<b>Message Type (MTYPE):</b> Specifies the type of the message. The message types are: 0h = LED 1h = SAF-TE 2h = SES-2 3h = SGPIO (register based interface) All other values reserved
23:16	<b>Data Size (DSIZE):</b> Specifies the data size in bytes. If the message (enclosure services command) has a data buffer that is associated with it that is transferred, the size of that data buffer is specified in this field. If there is no separate data buffer, this field shall have a value of '0'. The data directly follows the message in the message buffer. For PCH, this value should always be '0'.
15:8	<b>Message Size (MSIZE):</b> Specifies the size of the message in bytes. The message size does not include the one DWord header. A value of '0' is invalid. For PCH, the message size is always 4 bytes.
7:0	Reserved

The SAF-TE, SES-2, and SGPIO message formats are defined in the corresponding specifications, respectively. The LED message type is defined in [Section 5.17.12.3](#). It is the responsibility of software to ensure the content of the message format is correct. If the message type is not programmed as 'LED' for this controller, the controller shall not take any action to update its LEDs. Note that for LED message type, the message size is always consisted of 4 bytes.



### 5.17.12.3 LED Message Type

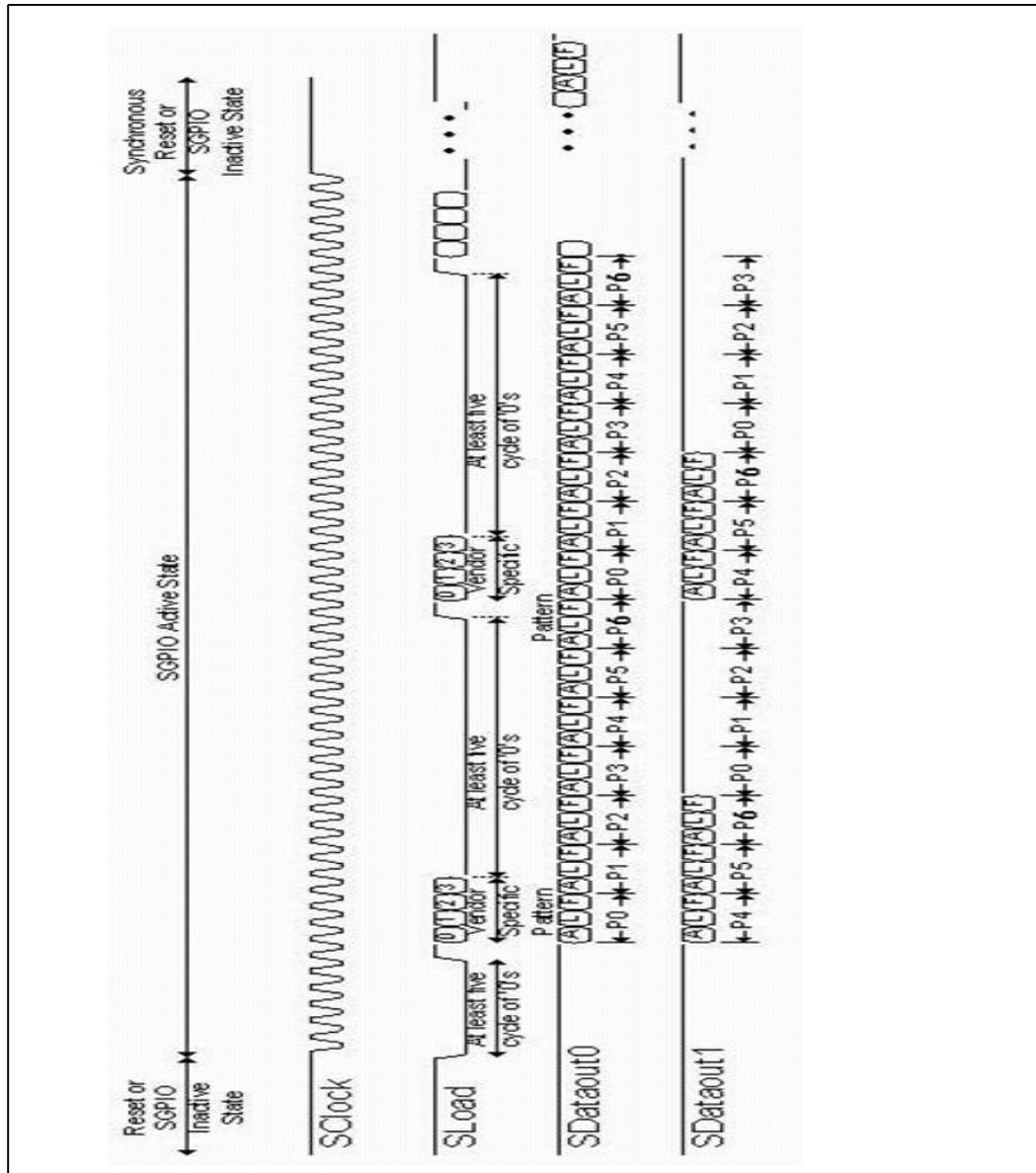
The LED message type specifies the status of up to three LEDs. Typically, the usage for these LEDs is activity, fault, and locate. Not all implementations necessarily contain all LEDs (for example, some implementations may not have a locate LED). The message identifies the HBA port number and the Port Multiplier port number that the slot status applies to. If a Port Multiplier is not in use with a particular device, the Port Multiplier port number shall be '0'. The format of the LED message type is defined in [Table 5-45](#). The LEDs shall retain their values until there is a following update for that particular slot.

**Table 5-45. Multi-Activity LED Message Type**

Byte	Description
3-2	<p><b>Value (VAL):</b> This field describes the state of each LED for a particular location. There are three LEDs that may be supported by the HBA. Each LED has 3 bits of control.</p> <p><b>LED values are:</b>                      000b - LED shall be off                      001b - LED shall be solid on as perceived by human eye                      All other values reserved</p> <p><b>The LED bit locations are:</b>                      Bits 2:0 - Activity LED (may be driven by hardware)                      Bits 5:3 - Vendor Specific LED (such as, locate)                      Bits 8:6 - Vendor Specific LED (such as, fault)                      Bits 15:9 - Reserved</p> <p><b>Vendor specific message is:</b>                      Bit 3:0 - Vendor Specific Pattern                      Bit 15:4 - Reserved</p> <p><b>Note:</b> If Activity LED Hardware Driven (ATTR.ALHD) bit is set, host will output the hardware LED value sampled internally and will ignore software written activity value on bit [2:0]. Since PCH Enclosure Management does not support port multiplier based LED message, the LED message will be generated independently based on respective port's operation activity. Vendor specific LED values Locate (Bits 5:3) and Fault (Bits 8:6) always are driven by software.</p>
1	<p><b>Port Multiplier Information:</b> Specifies slot specific information related to Port Multiplier.                      Bits 3:0 specify the Port Multiplier port number for the slot that requires the status update. If a Port Multiplier is not attached to the device in the affected slot, the Port Multiplier port number shall be '0'. Bits 7:4 are reserved. PCH does not support LED messages for devices behind a Port Multiplier. This byte should be 0.</p>
0	<p><b>HBA Information:</b> Specifies slot specific information related to the HBA.                      Bits 4:0 - HBA port number for the slot that requires the status update.                      Bit 5 - If set to '1', Value is a vendor specific message that applies to the entire enclosure. If cleared to '0', Value applies to the port specified in bits 4:0.                      Bits 7:6 - Reserved</p>

### 5.17.12.4 SGPIO Waveform

Figure 5-11. Serial Data Transmitted over the SGPIO Interface



### 5.17.13 External SATA

PCH supports external SATA. External SATA utilizes the SATA interface outside of the system box. The usage model for this feature must comply with the Serial ATA II Cables and Connectors Volume 2 Gold specification at [www.sata-io.org](http://www.sata-io.org). Intel validates two configurations:

1. The cable-up solution involves an internal SATA cable that connects to the SATA motherboard connector and spans to a back panel PCI bracket with an eSATA connector. A separate eSATA cable is required to connect an eSATA device.
2. The back-panel solution involves running a trace to the I/O back panel and connecting a device using an external SATA connector on the board.



## 5.18 SAS/SATA Controller Overview (SAS is for SRV/WS SKUs Only)

**Note:** SAS is not available on HEDT.

### 5.18.1 SCU Features

#### 5.18.1.1 Other Relevant Documents

- ISO/IEC 14776-372, *SCSI Enclosure Services-2 (SES-2)* (INCITS T10/1559-D)
- ISO/IEC 14776-453, *SCSI Primary Commands-4 (SPC-4)*
- ISO/IEC 14776-322, *SCSI Block Commands-3 (SBC-3)*
- ISO/IEC 14776-413, *SCSI Architecture Model-4 (SAM-4)*
- ISO/IEC 14776-971, *AT Attachment with Packet Interface-7 Volume 1 (ATA/ATAPI-7 V1)* (ANSI INCITS 397-2005)
- ISO/IEC 14776-971, *AT Attachment with Packet Interface-7 Volume 3 (ATA/ATAPI-7 V3)(Serial ATA)* (ANSI INCITS 397-2005)
- Serial Attached SCSI (SAS) [ANSI INCITS 376-2003]
- Serial Attached SCSI (SAS) revision 2.0r5
- Serial ATA: Data Link Interface revision 2.5

#### 5.18.1.2 SCU Architectural Features

The Storage Controller Unit is a stand alone I/O controller that supports Serial Attached SCSI (SAS) and Serial ATA (SATA) by incorporating dedicated messaging unit, DMA engines, frame buffering and protocol controllers to execute I/O requests. The Storage Controller Unit (SCU) supports execution of I/O requests for multiple modes of operations such as SSP, STP and SMP initiator and SATA host operations. Each of four SCU protocol engines can operate independently in any of the modes and can also execute SAS wide port operations. The SCU incorporates the following features:

- Protocol Engine Group
  - SSP, SMP, STP Initiator mode
  - SATA Host mode
  - SATA Port Selector (PS), Native Command Queuing (NCQ) supported
  - Automated Out Of Band (OOB) signaling
  - Automated Speed Negotiation (SN)
  - Automated Transport Layer
  - Automated Link Layer
  - 1.5 Gbps and 3.0 Gbps Link operations for SAS and SATA
  - Link Level Power Management
  - Automated task scheduling
  - Wide Ports up to x4
- Storage DMA Engine
  - Automated Scatter Gather List processing
  - Intel® Block Protection Technology Context management
- End to End data path protection
  - \* using Parity, ECC and BPT

### 5.18.1.3 Features Excluded in Current SCU Architecture

- STP Host/SATA Target functions
- SSP Target Mode
- SMP Target Mode
- Bi-Directional SCSI commands support.
- Multiple Task Priority Level - only support Normal and High.
- Full Staggered spin-up in SATA devices (only support partial power on staggered spinup for SATA devices)
- SAS Connection Multiplexing

## 5.18.2 SCU Configurations

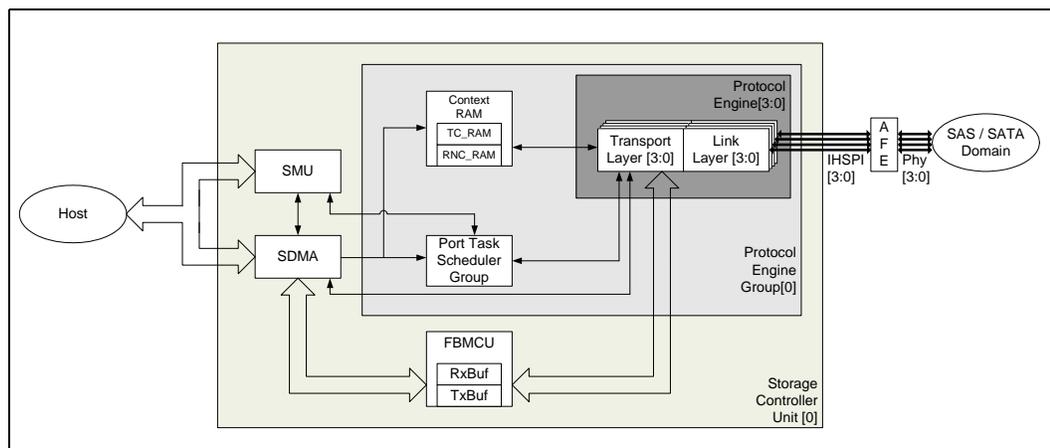
### 5.18.2.1 SCU Configurations and Numbering Conventions

There are two distinct configurations of the SCU:

- Single SCU-4
- Double SCU-4

The Single SCU-4 is shown in [Figure 5-12](#).

**Figure 5-12. Single SCU-4 Configuration**

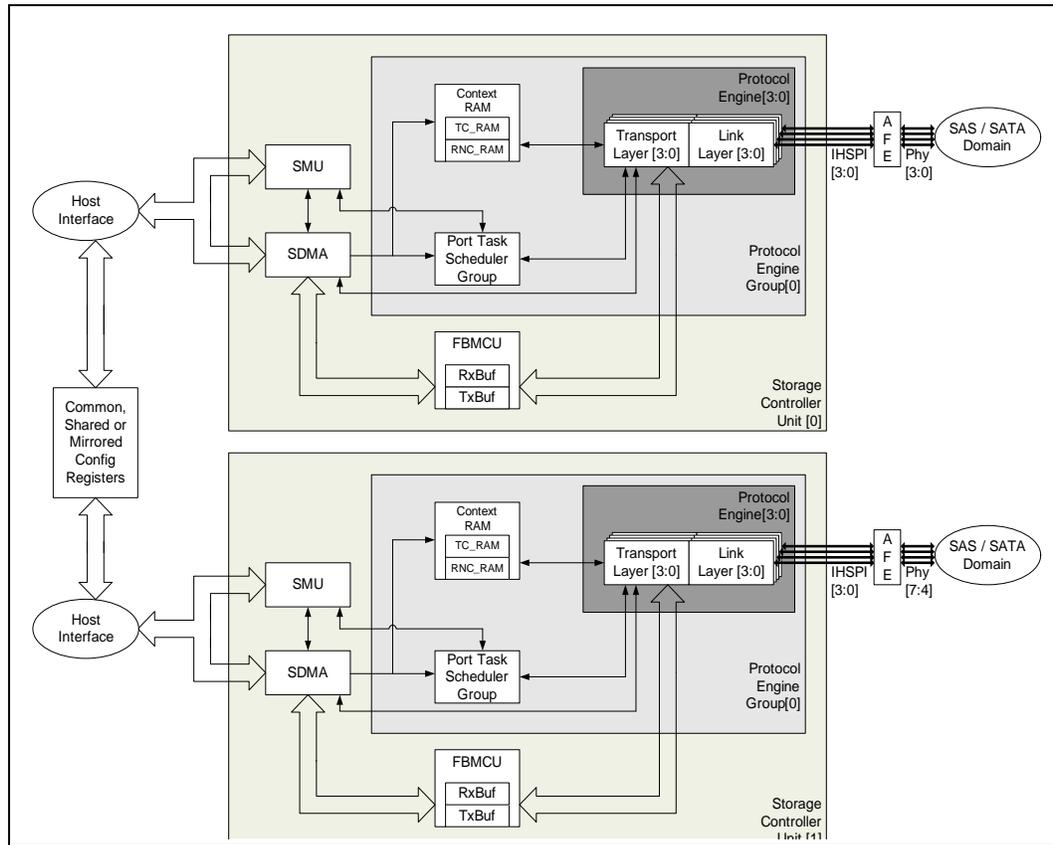


The single SCU-4 appears to the Driver as SCU[0]. There is a single Protocol Engine Group, PEG[0]. Within this Protocol Engine Group there are four Protocol Engines, PE[3:0], which connect to Phy[3:0]. There are four Port Task Schedulers (PTS), some of which are disabled depending on how the Driver configures it for Wide Port. Note that although the figure shows the SCU connecting to a SAS/SATA Domain, this could be direct-attached SAS or SATA disks.

The next configuration is a Dual SCU-4, as shown in [Figure 5-13](#).



Figure 5-13. Double SCU-4 Configuration



The Dual SCU-4 appears to the Driver as SCU[0] + SCU[1] behind a common PCIe function. Both SCUs are mapped behind a common set of PCIe BARs. Each SCU contains a single PEG. Note that on SCU[1] the Phys are numbered 4 thru 7 and the PEG is numbered as PEG[0].

The Intel C602 Chipset SKU includes a single SCU-4 to provide 4 ports of SATA.

The Intel C604 Chipset SKU includes a single SCU-4 to provide 4 ports of SATA/SAS.

The Intel C606, C608 Chipset SKUs includes a Dual SCU-4 that provides 8 ports of SATA/SAS.

**5.18.2.1.1 Run-Time Configurations**

In addition to the other types of configurations, the Driver will be able to change the run-time configuration of the SCU. These allow the driver to configure a subset of features.

At a high level these are:

Protocol Support: Each link can be configured to support SSP, SMP, STP, or SATA.

Wide Port Configuration: The PTS is configured to support Wide Ports.

Transport Layer Retry: Support of TLR can be disabled for the part as a whole.



### 5.18.3 Storage Controller Unit (SCU) Architecture

The SCU Architecture can be divided into 4 major layers:

- Host Queue/Memory Communication Interface which includes the Storage Messaging Unit (SMU) and the Storage DMA (SDMA) functional blocks
- Port Task Scheduler Group which includes 4 Port Task Schedulers, Port Configuration Switch, Task Schedule RAM and Remote Node Schedule RAM
- 4 Transport Layer functional blocks which are part of the Protocol Engine Group
- 4 Link Layer functional blocks which are part of the Protocol Engine Group

The Protocol Engine Group also includes the Context RAM Memory Controller (CRAMC) with Task Context (TC RAM) and Remote Node Context RAM (RNC RAM).

The Frame Buffer Memory Controller Unit (FBMCU) with SRAM are used by the Transport Layer functional blocks for Tx and Rx frames buffers storage.

The term "Task" is used throughout this document. Following description clarifies the kinds of Tasks the SCU supports. A Task can be one of the following types

(TaskType):

IORead:	A request to perform an I/O Read as an initiator.
IOWrite:	A request to perform an I/O Write as an initiator.
TaskMgmt:	A request to perform a task management function, that is, a non-I/O task (initiator).
RawFrame:	A raw frame where the entire header is provided by the Driver.
Primitive:	A request to send a primitive outside of a connection.

In addition to the TaskType, each Task will define the Protocol to use. Four different Protocol types are supported for a task:

SMP:	SMP supported for initiator.
SSP:	SSP supported for initiator
STP/SATA:	STP and SATA use the same protocol type, only initiator/host mode is supported.
None:	Used for sending primitives.

The TaskType 'Primitive' will support sending the following:

- NOTIFY(POWER FAIL)
- BROADCAST(SES)



### 5.18.3.1 SCU Theory of Operation

The SCU Architectural terms and Definitions referenced in this document are defined below:

- Task - a job issued by the driver to SCU to request SCU to perform some amount of work described with the associated task context information.
- Local Port - a communication entity that contains one or more Transport Layer (TL)/Link Layer (LL) pairs that are associated with a single PTS.
- Remote Node - a SAS or SATA device which can be communicated to using an SCU local port including SSP Initiator, Expander, SMP Initiator and SATA Device.
- Index - a SCU internal addressing mechanism used to refer to data structure, memory, PTS or TL.
  - Remote Node Index (RNI) - an index used by SCU to reference to data structure RNC associated to a remote device which can be communicated through the SCU port.
  - Task Context Index (TCi) - an index used by the TL/SDMA to reference to data structure TC that contains all the information associated with the task execution.
- Context - it is a data structure that usually resides in memory that contains all the necessary information for the functional block that is using the context to perform it's function..
  - Task Context (TC) - a data structure that contains all the necessary information for SCU to execute a task.
  - Remote Node Context (RNC) - a data structure that contains all the necessary information about the characteristic of the remote node for SCU to manage connection and task execution.

When the SCU is initialized and configured by the driver after power up and topology discovery, the driver assigns a task to the SCU in the form of a Task Context in a host work queue in host memory. The Task Context contains all the necessary information for the SCU to execute the entire task until completion or until terminated with an error posted in the host completion queue in host memory.

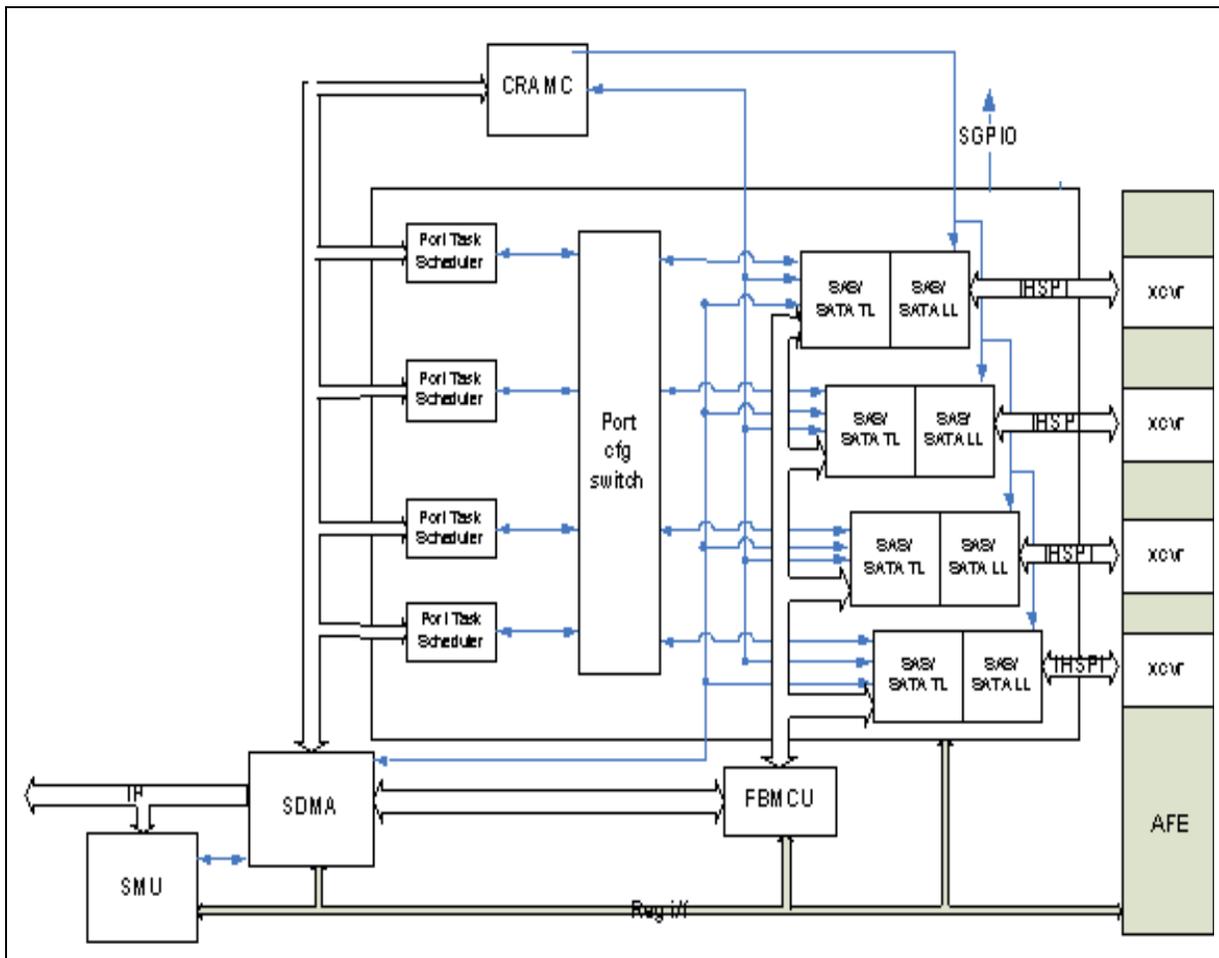
The host driver will notify the Storage Messaging Unit (SMU) when a task is ready. The SMU will inform the Storage DMA Engine (SDMA) to fetch the Task Context (TC) from the host memory. The SDMA will load the TC into TC RAM as indexed by the TCi and at the same time transfer the Task Schedule portion of the context within the TC to the Port Task Scheduler (PTS). The Port Task Scheduler will link the task to the task list that is associated with the task under the corresponding Remote Node.

The Port Task Scheduler will schedule the tasks based on a round robin algorithm. When a task is assigned to a Transport Layer function block, the TL will fetch the Task Context associated with the assigned task from the TC RAM using the CRAMC after the Link Layer Connection Manager establishes a connection to the remote node.

The Link Layer is responsible for Link Initialization, Connection Management, Data Encoding/Decoding, Basic Frame Validation, elasticity-FIFO, Link Level Flow Control, Frame CRC-Generation/Verification, Data Scrambling/De-Scrambling, Primitive Sequence Management, Frame Building and Remote Node Context Management.

The SAS Port Layer functions (such as wide port mapping) are managed by the Port Task Scheduler.

Figure 5-14. Storage Controller Block Diagram



### 5.18.3.2 SCU Functional Block Overview

The functional blocks of the SCU are detailed in the following sub-sections.

#### 5.18.3.2.1 SMU Overview

The SMU (Storage Messaging Unit) provides the interface of the SCU to the Driver. The major functions of the SMU are as follows:

- Allow the Driver to initiate new TCs to the SCU, the SMU then requests that the SDMA perform the actual DMA of the TCs
- Manage the completion queue (which contains Task Completions, Unsolicited Frame Notifications, and Event Notifications)
- Provide the locations in Host Memory to the TL where to put Unsolicited Frame payload and headers
- Provide a means for all units to pass Event Notifications to the Driver
- Allow the Driver to post new RNCs to the SCU
- Coalesce interrupts to allow more efficient Driver use



In general the SMU is responsible for determining where in Host Memory a particular data element is stored and passes requests so that the SDMA can transfer between Host Memory and the appropriate internal data structure. Note that Host Memory is either system memory or RAID cache memory, depending on the usage model.

**5.18.3.2.1.1 Memory Mapped Register (MMR) Interface**

The Memory Mapped Registers provide a way for the Driver to configure parameters throughout the SCU. The entire memory mapped register space is claimed by the SMU.

Each PCI Function within the SMU consumes memory space for SMU control/status and the MSI-X Table and Pending Bit Array. These registers are mapped into PCI Memory Space through the Base Address Registers (SCUPBAR0, SRIOVBAR0).

**5.18.3.2.1.2 Post Context Queue**

The “Post Context Queue” is used to pass new Tasks and Remote Node Contexts (TCs and RNCs) from the Driver to the SDMA. The value written includes the Context command Type, Protocol Engine Group Index (PEGi), Local Port Index (LPi) and Context Index (TCi/RNi).

The valid Context commands are specified in [Table 5-46](#).

**Table 5-46. Context Command Type**

Context Command Type
Task Context Commands
Post_TC
Post_TC_Abort
Dump_TC
Remote Node Context Commands <sup>1</sup>
Post_RNC_32
Post_RNC_96
Post_RNC_Invalidate
Dump_RNC_32
Dump_RNC_96
Post_RNC_Suspend
Post_RNC_Resume
Post_I_T_Nexus_Loss_Timer_Enable
Post_I_T_Nexus_Loss_Timer_Disable

1. The RNC commands can only be posted through function 0.

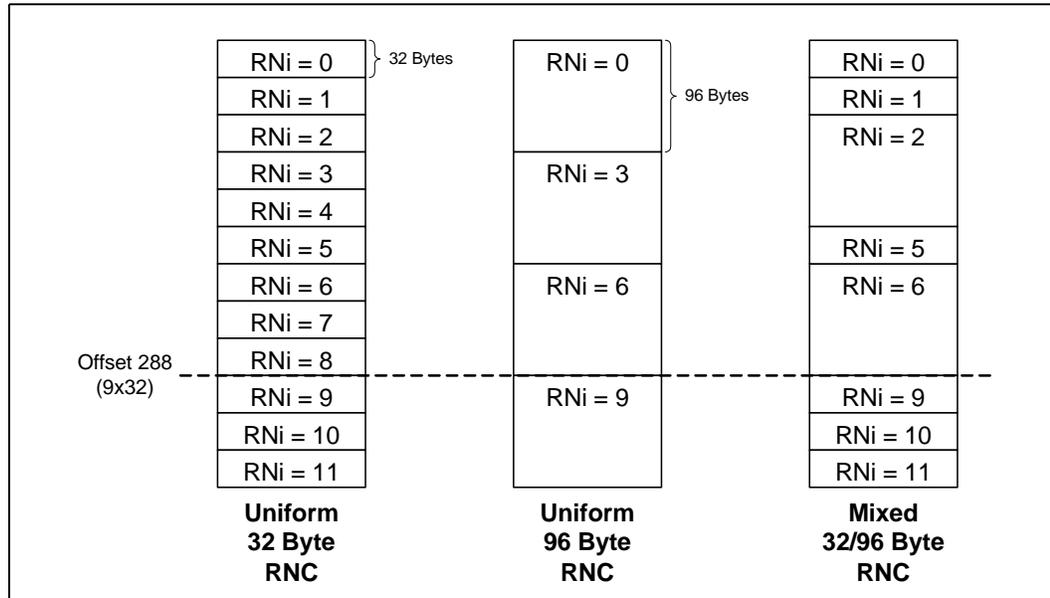
The Post\_TC, Abort\_TC, and Dump\_TC commands all reference a Task Context index (TCi) and are referred to collectively as TC Commands. When posting a TC Command, the Driver will identify the Protocol Engine Group, Local Port, and provide a Task Context index (TCi).

The Post\_RNC, Dump\_RNC, and Post\_I\_T\_Nexus commands all reference a Remote Node index (RNi) and are referred to collectively as RNC Commands. When posting a RNC Command, the Driver will identify the Protocol Engine Group, Local Port, and provide a Remote Node Index (RNi). The Post\_RNC\_32/96 commands will result in an RNC data transfer from host memory to the RNC\_RAM. The Dump\_RNC\_32/96 commands will result in an RNC data transfer from the RNC\_RAM to host memory. The other commands operate on RNCs in the RNC\_RAM but do not result in a data transfer to/from host memory.

Each Task Context is 256 bytes in size and is laid out in contiguous memory space

A Remote Node Context is either 32 or 96 Bytes in size and will be laid out on 32 Byte aligned address offsets. The RNi indicates the starting address of the RNC in multiples of 32-bytes regardless of whether it is a 32-byte or 96-byte context. See Figure 5-15 as an example.

**Figure 5-15. RNC Sizes and Indexing Example**



**5.18.3.2.1.3 Completion Queue**

The Completion Queue is located in host memory and is used as a circular queue for posting completions back to the Driver. After receiving notification from the other SCU units, the SMU puts a Completion Entry into the Completion Queue by directly issuing a 32-bit write. The Completion Entry can be one of the types shown in Table 5-47.

**Table 5-47. Completion Entry Format**

	3	3	2	2	2	1	1	1	1	1	1	0	Type
	1	0	8	7	4	3	8	7	6	5	2	1	
C	T = 0	Status					PEGi	LPi		TCi			Task Completion
C	T = 1	Status	Command			PEGi	LPi		TCi/RNi			SDMA (CDMA) Completion	
C	T = 2	Ufi						PEi		RNi			Unsolicited Frame Notification
C	T = 3	Notification Code				PEGi	LPi/PEi <sup>1</sup>		TCi			Critical Notification (such as, I_T_Nexus Time Out)	
C	T = 4 <sup>2</sup>	Event Code				PEGi	LPi/PEi		TCi/RNi			Event Notification (can get dropped)	
C	T = 5	Status	Command			PEGi	LPi		TCi/RNi			SMU (PCQ) Events	
C	T = 6	Status				RegisterOffset/AM						SMU Generated Events	
C	T = 7	Reserved											Reserved

1. Events from the Transport and Link Layers will use PEi, events from the PTSG will use LPi  
 2. Type 4-7 are considered Events and will be discarded if there is no room in the Completion Queue for Events.

Every completion entry contains a Cycle bit “C”, a Type field “T” and a Protocol Engine Group index (PEGi).



### 5.18.3.2.2 SDMA Overview

The SDMA (Storage DMA Unit) consists of two DMA channels: the Context DMA (CDMA) and the Payload DMA (PDMA). The CDMA consists of a CDMA Descriptor Manager (CDMA DM) and a CDMA Engine, and the PDMA consists of a PDMA Descriptor Manager (PDMA DM) and a PDMA Engine. Each DMA Engine consists of a Receive DMA Engine (writing to host memory) and a Transmit DMA Engine (reading from host memory). Note that in this document the term host memory is used to imply a memory subsystem outside of the SCU.

The CDMA and PDMA Engines operate on descriptors. A descriptor describes a single DMA Engine operation between a host memory buffer and an SCU unit. The maximum DMA length that a descriptor can describe is up to 256 bytes and 1024 bytes for the CDMA and PDMA respectively. The CDMA or PDMA Descriptor Manager determines the DMA request type and generates a single descriptor or multiple descriptors with the proper source address, destination address and transfer length to define the DMA transfer operation either for receiving data (writing to host memory) or transmitting data (reading from host memory). Note that based on how the host memory buffers are described by the Scatter-Gather List (SGL), a single DMA request issued to the PDMA Descriptor Manager may yield multiple descriptors.

When the CDMA or PDMA Engine operation is completed, the result of the operation is written to the Completion RAM of the CDMA or PDMA Engine for inspection and processing of the completion DWord by the CDMA or PDMA Descriptor Manager.

#### 5.18.3.2.2.1 Intel® Block Protection Technology Unit

An Intel Block Protection Technology Unit (BGU) is integrated on the Host output data path of the PDMA Engine to perform block guard operations on data from the Frame Buffer Memory Controller Unit (FBMCU)-to-Host. Similarly, a BGU is integrated on the FBMCU output data path of the PDMA Engine to perform block guard operations on data from Host-to-FBMCU. Each BGU is capable of the Generation, Stripping, Updating, and Verification of the Data Integrity fields (DIF) that can be embedded into the data streams.

### 5.18.3.2.3 SMCU Overview

The Storage Controller Unit integrates two identical high performance, multi-ported SRAM Memory Controller units (SMCU). The first SMCU, called Frame Buffer Memory Controller Unit (FBMCU), is used to provide access to the on-chip frame buffer SRAM Memory. The second SMCU, called Context RAM Controller (CRAMC), is used to provide access to the on-chip context SRAM memory.

The SRAM Memory Controller supports:

- Error Correction Code (ECC)
  - Single-bit error correction, multi-bit error detection
  - 7-bit ECC across every DW data
- Read-modify-write when the byte enables for DW data to write are not all asserted.
- 256-bit wide SRAM Memory Interface with ECC protection
- 10 Read and 10 Write, Memory Port Interfaces (MPI)
  - Each MPI is 128-bit wide with data parity protection
- Two request arbiters
  - One for Read and one for Write requests
- One MMR interface
  - Decodes and accepts any MMR requests targeting the SMCU's MMR space
- Interleave read and write requests in every other SRAM memory clock to minimize SRAM read latency



The SRAM interface provides a direct connection to a high bandwidth and reliable memory subsystem. An 7-bit Error Correction Code (ECC) across every 32-bit word improves system reliability.

#### 5.18.3.2.4 Port Task Scheduler Overview

The key functions of the PTSG are to schedule outbound tasks to the appropriate protocol engine to be executed by transport layer and post status to the driver through SMU when the task is completed; manage SAS Port Layer functions, such as wide port management and I\_T Nexus Loss timeout management; handle other functions like task timeout, task abortion, local port suspension, remote node suspension, etc.

Each PTSG includes the following major functional blocks:

- 4 Port Task Schedulers (PTS) - PTS schedules tasks to be executed by the TMs of the configured port.
- 1 Port Configuration Switch (PCS) - This switch is configured by the Driver by programming the MMRs through SMU after link initialization to map the PEs to a particular PTS based on the information that was exchanged by the Identify Address Frames.
- 1 Event Timeout Manager (ETM) - The Event Timeout Manager is responsible for checking any active task that has timed out and also monitoring the I\_T Nexus timeout situation for the active remote node.
- 1 Task Schedule Context RAM (TSC RAM) - this memory is used by all the PTSs within the PTSG to store TSCs for task scheduling.
- 1 Remote Node Schedule Context RAM (RNSC RAM) - this memory is used by all the PTSs within the PTSG to store RNSCs for remote node scheduling.

The PTSG also manages the SAS port layer function that handles the SAS Wide Port functionality. The PTS will ensure that the order of IO command frames sent to the target port (as an initiator) will be the same order as the tasks issued by the driver unless it is a high priority new command task.

#### 5.18.3.2.5 Transport Layer Overview

The transport layer consists of five major sub-modules in the SCU. They are:

- Transport Layer Back End (TLBE)  
The Transport Layer Back End provides a shared interface between the SDMA and core TL blocks, and acts as a central arbiter for all Event Notifications within the Protocol Engine Group (PEG).
- SSP Transport Layer Group (SSP TL)
- SMP Transport Layer Group (SMP TL)
- STP/SATA Transport Layer Group (STP TL)
- Transport Layer Front End (TLFE)  
The Transport Layer Front End (TLFE) is located between the transport layers and link layers. Its main function is to provide Context RAM access arbitration between Transport and Link layer logic.

#### 5.18.3.2.6 Link Layer Overview

The SCU Protocol engine (PE) supports SSP, SMP, STP and SATA Link Layer protocol operations through a combination of protocol specific functions and common protocol functions. The link layer manages frame transmission, frame reception, encoding/decoding of characters, connection management, primitive sequence detection and processing, and the protocol link flow control. The PE implements a common link layer architecture that enables each link to operate with any of the supported protocols based on OOB and connection assignments. The PE also implements a common Connection manager used to manage SSP, SMP and STP connections automatically. The



link layer for each protocol engine also has common Out of Band sequence and Speed Negotiation controls to perform SAS or SATA operations. The PE link layers interfaces to a common Frame Transmit and Frame Receive DMA controller that manages the movement of frame data to FBMCU and from the AFE.

#### 5.18.3.2.6.1 PE Link Layer Features

The following list of link layer functions are executed by the PE Link Layer.

- Out of Band sequence handling
- Speed Negotiation
- Frame Transmission
- Frame Reception
- Primitive Generation/Detection
  - SAS Primitive sequences
  - SATA Primitive sequences
- 8b10b ENDEC
  - SAS characters
  - SATA characters
- Scrambling/de-scrambling
  - SSP, SMP
  - STP, SATA
- SSP Link Layer functionality
  - Initiator
- SMP Link Layer functionality
  - Initiator
- STP/SATA Host Link Layer state machine
- SAS Link Connection Control
- Rate Matching
- Flow Control
  - SSP
  - SATA
- Frame Buffer data storage/retrieval
- 1.5/3.0 Link rate support

#### 5.18.3.2.6.2 PE Link Layer Theory of Operation

After the SCU has been brought out of reset and the protocol transceivers have been initialized the PE link layer is prepared to start operations. The device driver will enable each protocol engine individually, this enable will start the automated link layer operations for Out of Band (OOB) sequences and Speed Negotiation (SN) to perform the Phy Reset Sequence. The OOB/SN manager will perform SAS OOB functions to detect if a SAS device or a SATA device is present. The OOB/SN manager also provides the mechanism for the device driver to initiate the transmission of the protocol based Port Selector switching sequence. The OOB/SN manager will further conduct SAS or SATA speed negotiation dependent upon the detection of a SAS PHY or SATA PHY.

Link initialization can be initiated independently for each protocol engine by the device driver through a dedicated link initialization control register.



### 5.18.3.2.7 Staggered Spin-Up Control

The SCU needs supports Staggered Spin-Up as a feature, under the control of the Driver. This allows the Driver to stagger when drives are spun-up, thus avoiding any power surges that might overload a power supply.

The process for handling Staggered Spin-Up for a nominal start-up procedure is as follows:

1. The Driver starts all links
2. On SATA links (detected by OOB), the LL will default to the SATA SPINUP HOLD state.
3. On SAS links, the LL completes the entire start-up sequence. By default, the LL will not send NOTIFY(ENABLE SPINUP) primitives.
4. The Driver walks through each link every X seconds (an OEM configured parameter), and sets LL registers to either start sending NOTIFY(ENABLE SPINUP) or release the link from the SPINUP HOLD state, depending on whether the link is SAS or SATA.

### 5.18.3.2.8 Discovery

The discovery process begins after Link Initialization is complete. The Driver is responsible for discovering all SAS devices in the domain (determining the device type, SAS address, and supported protocols), and configuring the devices if necessary (that is, expander routing tables).

### 5.18.3.2.9 Port Configuration /SAS Address

After power up, the driver will assign the SAS address - usually the same local SAS address (unless SCU is programmed to be SATA direct attached only) to all the links in the Local SAS Address register in the Connection Manager.

## 5.18.4 SCU Physical Layer/PHY Overview

### 5.18.4.1 Introduction

The physical layer (Phy) integrated with the SCU is a four-port SAS/SATA transceiver (called the Storage Phy- SPhy) supporting 1.5 Gbps and 3.0 Gbps with an Analog front-end (AFE) and a Digital interface block (DIF). The PCH supports either a single instantiation of the Sphy or a dual instantiation of the SPhy. The DIF block contains the registers that control several aspects of the AFE.

### 5.18.4.2 SPhy Functionality & Features

SPhy Features

- Link rates of 1.5 Gbps and 3.0 Gbps.
- Meets SAS and SATA industry electrical requirements at all of the supported rates.
- BER of less than  $1 \times 10^{-15}$
- 40-to-1 bit serializer and 1-to-40 bit de-serializer with embedded clock extraction.
- Independent transceiver operation with respect to protocol and data rate.
- Independent transmit and receive data rates on a per-transceiver basis; this mode is not part of normal SAS/SATA signaling, but it is utilized during speed negotiation.
- On-chip termination.
- Independent reset and power-down/enable controls for each receiver and each transmitter.



- OOB envelope detection with programmable threshold of OOB burst envelope amplitude on a per-transceiver basis.
- Control for putting the transmitter into a DC idle state on a per-transceiver basis.
- Several loop-back modes: far-end retimed (in protocol engine), far-end digital (in DIF), near-end analog (in AFE), and external analog (outside the package on the PC board)
- 40-bit data path for each receiver and transmitter
- Comma sequence detection and notification for the protocol engine to manage the link
- Disabling and enabling of comma sequence detection
- Spread-Spectrum Clocking (SSC) transmission is available on a per-transceiver basis for SATA. SSC is not available for SAS
- Controls for entering and exiting SAS and SATA Partial and Slumber power management states on a per-transceiver basis

#### **5.18.4.2.1 OOB Burst Detection and Control**

In order to support the SAS and SATA protocol signaling requirements, the protocol engine has ability to select OOB burst amplitude detection levels.

#### **5.18.4.2.2 Transmit Amplitude Control**

The transmitter control block supports the SAS and SATA protocol signaling requirements by providing the protocol engine the ability to select transmitter amplitude transmission levels on a per-transmitter basis using the register interface and the table-based look-up structure of the transmitter.

#### **5.18.4.2.3 Common Mode Voltage Control**

The transmitter control block supports a function that allows the protocol engine to individually place each transmitter into a DC idle state. The transmitter will place the transmitter output driver into DC idle condition until the protocol engine dictates a transition into a new state.

#### **5.18.4.2.4 Tx/Rx Bit Rate Selection**

The transceivers support 1.5, and 3.0 Gbps by providing independent transmitter and receiver rate selection control in each transceiver. This control also provides the ability to transmit at one bit rate and receive data at a different bit rate.

#### **5.18.4.2.5 Comma Detection Enable/Disable**

The AFE receiver control block provides control to enable/disable notification to the protocol engine that it has detected a comma sequence in the de-serialized bit stream. This control also enables/disables the DWord alignment functions in the receiver control block allowing data to be transferred without interruption.

#### **5.18.4.2.6 Reset and Power-Down**

The SPhy supports the ability to reset and power-down each transceiver unit independently.

#### **5.18.4.2.7 Power Management States**

The SATA power management states of Partial and Slumber are supported.



#### 5.18.4.2.8 Tx/Rx Data Loop Back Modes

The DIF block supports several modes and controls to loop-back data within the transceiver, thereby enabling the data stream between the transmitter and receiver to be connected to each other. The digital wrap back, near end analog loop-back, far end retimed loop-back, and far end digital loop-back capabilities are contained locally to each transceiver; the external analog loop-back may occur between transceivers depending upon HVM testing requirements. The DIF block supports controls to enable implementation of a far-end retimed loop back mode within the SAS/SATA protocol engine.

#### 5.18.4.2.9 Reference Clocking Requirements

The AFE common block develops the PLL output clocks for each of the transceiver blocks from a differential off-chip oscillator. The crystal oscillator shall be 100 MHz and shall not have spread-spectrum clocking (SSC). The SPhy could share this reference clock with any other interfaces on the same product as long as they do not require SSC.

### 5.18.5 Interrupts and Interrupt Coalescing

There are two types of interrupts:

Completion Queue Interrupt:

This interrupt can occur whenever the completion queue is not empty. This interrupt is coalesced as explained below.

Error Interrupt:

This interrupt indicates one or more error conditions have occurred which will impact the Driver and SCU operation. This causes an immediate interrupt.

#### 5.18.5.1 Interrupts

The SMU implements support for both Legacy INTx interrupts and MSI-X interrupts. For a multi-function device, including an IOV aware device, the interrupt logic is replicated per function.

##### 5.18.5.1.1 Legacy Interrupts

PCI Express implements a legacy INTx virtual wire interrupt signaling mechanism that uses the Assert\_INTx / Deassert\_INTx semantics to convey the level sensitive nature of traditional INTx# interrupt pins.

The “SCU PF Interrupt Pin Register (SCUPIPR)”, (see [Section 16.2.1.22](#)) specifies which interrupt line is used for the normal runtime interrupt.

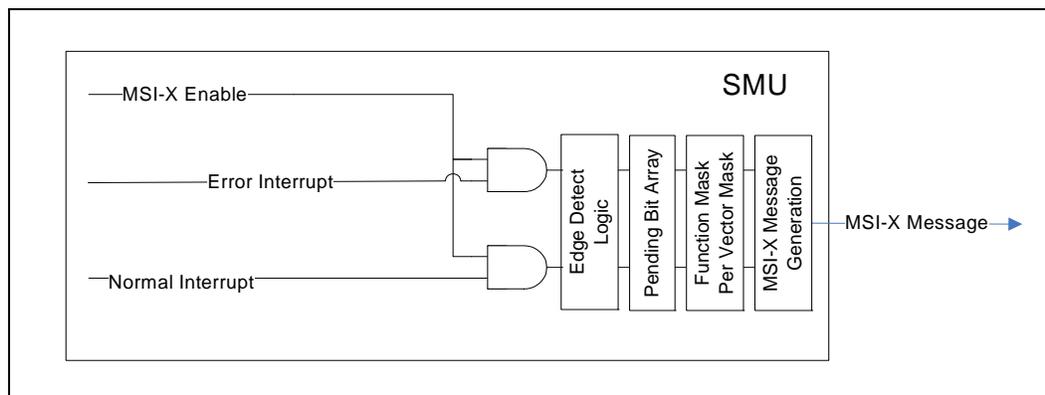
##### 5.18.5.1.2 MSI-X Capability

If a host processor enables Message-Signaled Interrupts (MSI-X), the SMU is responsible to signal interrupt to the host using a PCI write instead of generating an Assert\_INTx PCI Express\* message.

The Interrupt Disable bit in the PCI Command Register does not affect the generation of MSI-X interrupts.



Figure 5-16. MSI-X Generation



To signal an Interrupt with MSI-X enabled, a memory write transaction will be created using the Message Address and the Message Data of the associated entry.

## 5.18.6 SMU Error and Event Generation

The SMU is the only unit that will generate the Error interrupt. All other SCU units will signal detected 'errors' using an 'Event Notification'.

### 5.18.6.1 Event Generation

For most errors, the SMU will generate an Event Notification using the affected Address Modifier to direct the event to the appropriate Completion Queue. Some events are directed to the physical function (PF) and are indicated in the description.

The SMU generates the following errors:

- **Uncorrectable Error on read of PCQ (Uncorr\_PCQ\_Rd)**  
This Event is generated by the Post Context Queue(PCQ) processing logic
- **Invalid Context Command Error (Invalid\_Context\_Cmd)**  
This Event is generated by the Post Context Queue processing logic and is the result of an Invalid Context Command, an index out of range, or an RNC command by a Virtual Function.
- **Parity Error Detected on write to SMU (Uncorr\_Reg\_Wr)**  
This error is detected by the MMR interface logic and is the result of receiving a PCIe poisoned TLP, or the result of internal parity corruption.
- **Uncorrectable error on read of HTTLBAR, HTTUBAR, and TCR or MSI-X MT\_MLAR, MT\_MUAR, and MT\_MDR (Uncorr\_Reg\_Rd)**  
Above registers are implemented in a RAM and a double-bit ECC error during a read of the Host Task Table or MSI-X registers will result in an event notification.

The SMU also receives status information from the PCIe Interface and converts it to an event notification:

- **Function Level Reset (Function\_Level\_Reset)**  
This is an indication that the Initiate FLR bit has been set in the PCIe Configuration Space of a VF. When a rising edge is detected on the FLR signal from the PCIe Configuration Space, the SMU will:
  - Generate a Critical Notification to the physical function (PF). Note that an FLR to the PF will not generate an Event Notification.  
This event will also trigger the Function Level reset mechanism defined in [Section 5.18.9](#).



### 5.18.6.2 Error Interrupt

- **Uncorrectable Error on read of CQLBAR, or CQUBAR.**  
Above registers are implemented in a RAM and a double-bit ECC error during a read of the Completion Queue BAR can not be signalled as an event.
- **Completion Queue Suspended**  
This condition should not occur under normal operations and is likely the result of a programming error.

## 5.18.7 Host Interface Error Conditions

The SCU adheres to the error conditions defined within the PCI Express\* specification for both requester and completer operation.

IOSF (PCH's On-Chip System Fabric) and PCI Express\* error conditions cause the SCU to log header information and to set status bits to inform error handling code of the exact cause of the error condition. PCI Express\* classifies errors as Correctable or Uncorrectable. Since all PCI Express\* Correctable errors are link related (and the SCU does not contain a link) the SCU does not detect any PCI Express\* Correctable errors (all errors are detected as Uncorrectable).

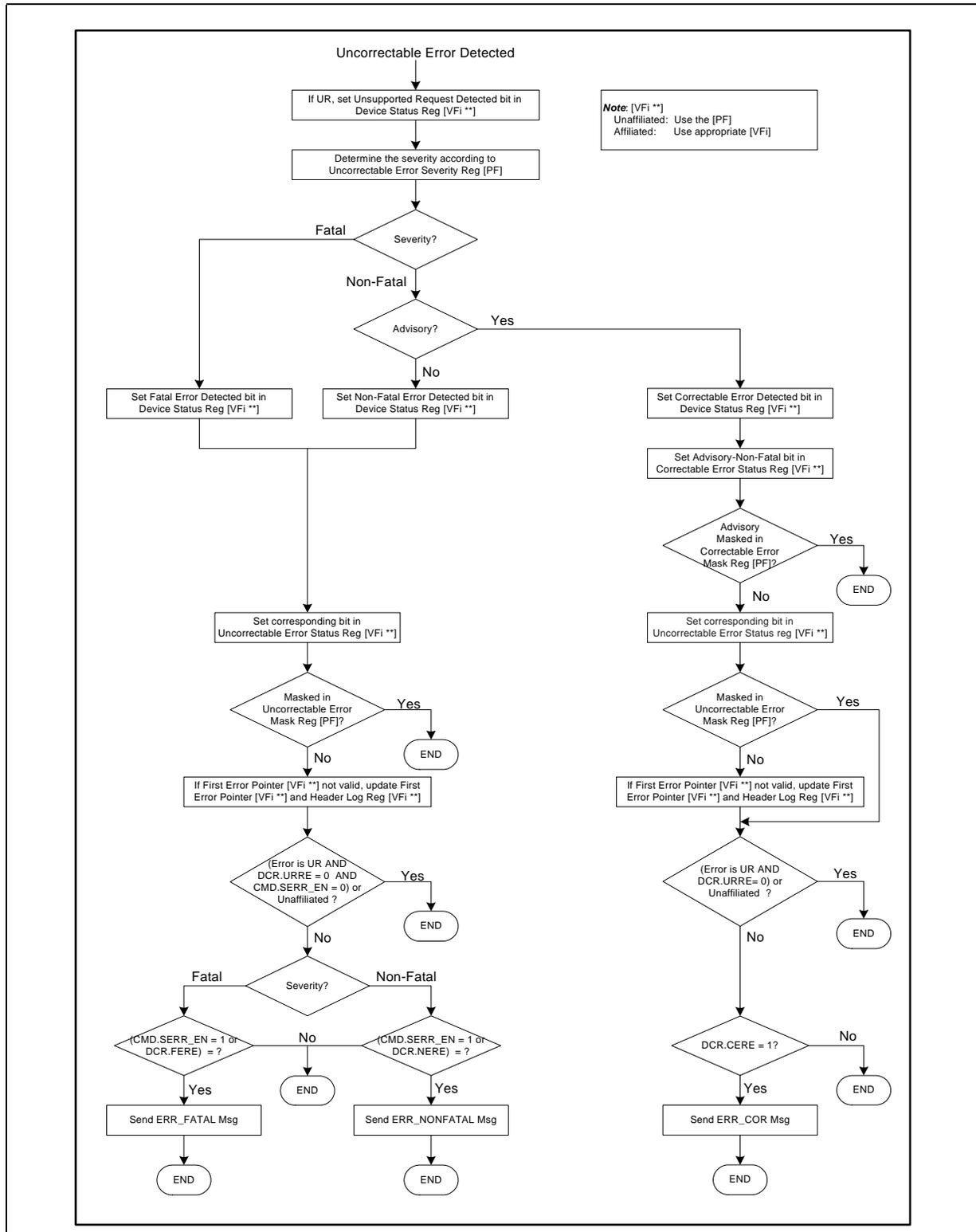
The following is a simplified summary of the flow. The entire flow is outlined in detail in [Figure 5-17](#).

First determine the Severity of the Uncorrectable error (Fatal or Non-Fatal). The Severity of each error type is defined by the programming of bits in the "SCU PF PCI Express\* Uncorrectable Error Severity (SCU P I ERRUNC SEV)" register. (see [Section 16.2.5.4](#))

- **Fatal:**
  - Log (if enabled).
  - Send ERR\_FATAL message (if enabled).
- **Non-Fatal:** Determine whether the error can be considered Advisory or not. This is done in an SCU implementation-specific manner. Errors are generally considered Advisory if the other party in the transaction is better suited to handling/reporting the error (such as, Unsupported Request) in a non-posted transaction (in this case the original requester will receive UR in the completion status and can decide what the appropriate error recovery/reporting mechanism should be).
  - **Advisory:**
    - Log (if enabled).
    - Send ERR\_COR message (if enabled).
  - **Non-Advisory:**
    - Log (if enabled).
    - Send ERR\_NONFATAL message (if enabled).



Figure 5-17. Uncorrectable Error Signalling and Logging Flowchart





The following sections detail all error conditions on the PCI Express/IOSF.

### 5.18.7.1 Unaffiliated Errors (Non-Function-Specific Errors)

Unaffiliated errors are those which cannot be unambiguously associated with a single function. For example, a Memory transaction which misses all of the Memory BARs of all of the functions (PFs and VFs) in the endpoint.

#### 5.18.7.1.1 Malformed

Note that per the PCI Express\* specification all malformed TLPs are treated as unaffiliated errors. The following checks are made to detect malformed TLPs.

- Data Payload exceeds the length specified by the value in the Max\_Payload\_Size field of the Device Control Register.
  - This error will be detected by the Integrated Device Fabric (IDF).
- Transactions having reserved combinations of Fmt and Type Field, that is, all commands not in the following set:
  - MRd32, MRd64, LTMRd32, LTMRd64, MRdLk32, MRdLk64, MWr32, MWr64, LTMWr32, LTMWr64, IORd, IOWr, CfgRd0, CfgWr0, CfgRd1, CfgWr1, Msg, MsgD, Cpl, CplD, CplLk, CpDLk
  - The SCU instead handles this as an Unexpected Completion.

#### 5.18.7.1.2 Unaffiliated Unsupported Requests (UR)

The following checks are made to detect unaffiliated Unsupported Requests:

- Memory or IO transactions which fail to match any of the active Memory or I/O BARs.
- Configuration requests which fail to target a valid function.
- Certain types of Messages which go unclaimed as stated in the rules in [Section 5.18.8](#).

#### 5.18.7.1.3 Unaffiliated Unexpected Completions

The following checks are made to detect unaffiliated Unexpected Completions:

- Completions in which the Requester ID (Bus#, Dev# Fn#) does not target any valid function (PF or VF).

### 5.18.7.2 Affiliated Errors (Function-Specific Errors)

Affiliated errors are those which can be unambiguously associated with a single function. For example, a Memory transaction which hits a Memory BAR of a function (PF or VF) in the endpoint but violates the programming model of that function. Affiliated cases are handled entirely by the endpoint.



#### 5.18.7.2.1 Affiliated Unsupported Requests (UR)

The following checks are made to detect affiliated Unsupported Requests:

- Certain types of Messages which are claimed but treated as UR as stated in the rules in [Section 5.18.8](#).
- Poisoned I/O or Configuration write request (EP bit set).
- Configuration write with an IOSF data parity error.
- Memory or I/O transaction while in a non-D0 power state.
- MRdLk32/64, LTMrd32/64, LTMwr32/64 transactions.

#### 5.18.7.2.2 Completer Abort (CA)

Completer Aborts are transactions which violate the programming model of the SCU. The following checks are made to detect Completer Aborts:

- Memory transactions which target the Memory Controllers and which cross a 16B aligned boundary.
- Memory transactions which target the MSI-X table and which cross a 16B aligned boundary.
- Memory transactions which target registers and which cross a 4B aligned boundary.

These requests must first have passed the Malformed TLP checks as well as the Unsupported Request checks.

#### 5.18.7.2.3 Affiliated Unexpected Completions

Completions are considered affiliated when the Requester ID (Bus#, Dev# Fn#) targets a valid function (PF or VF). The following checks are made to detect affiliated Unexpected Completions. In all the following error cases the completion data is discarded (not sent to the SDMA).

- The Tag does not match that of any outstanding non-posted request performed by the SCU as the Initiator.
- TC  $\neq$  0.
- The Status of a completion without data is other than Successful, CA or UR.
- Locked Completions (CpILk, CpIDLk).
- Completion with data for which the length exceeds the remaining length expected for the outstanding non-posted request.

#### 5.18.7.2.4 Poisoned Completion or Poisoned Posted Memory Write

A completion or posted memory transaction is considered poisoned if the EP bit is set.

- Poisoned Completions are passed through to the SDMA with bad parity.
- Poisoned Memory Writes are passed through to the SMU with bad parity.

Poisoned TLPs received for I/O or Configuration Writes are treated as URs.

#### 5.18.7.2.5 Completion Timeout

A completion timeout occurs when an outstanding non-posted request initiated by the SCU fails to receive all of its completion data within the completion timeout period (16 ms to 32 ms).



### 5.18.7.3 Data Parity Error on the Integrated Device Fabric (IDF)

Data parity will be forwarded to the internal units (SMU or SDMA). The SCU will indicate the error to the SCU driver.

## 5.18.8 Host Interface Messages Received

The following sections describe how the SCU handles PCI-Express messages as a target. Any message which goes unclaimed by all enabled functions on the Integrated Device Fabric (IDF) will be logged in all enabled physical functions as an unaffiliated Unexpected Request (UR) with the exception of PME\_TO.

### 5.18.8.1 Messages Routed by ID

- If the Routing ID (RID) fails to match any enabled SCU function (PF or VF) then the SCU will not claim the transaction.
- If the RID matches one of the enabled SCU functions, then the transaction will be claimed and:
  - Type-1 Vendor Defined Messages (VDMs) are silently dropped.
  - Others are dropped and are logged as UR.

### 5.18.8.2 Messages Routed by Broadcast

- Type-1 VDMs are claimed and silently dropped.
- UNLOCK is claimed and silently dropped.
- PME\_TO is not claimed.
- Others are claimed, dropped and are logged as UR.

### 5.18.8.3 All other Messages

All other message formats are not claimed by the SCU.

## 5.18.9 Reset

### 5.18.9.1 Fundamental Reset

Fundamental Reset is a hardware mechanism for setting or returning the PCI Express\* Port states and all MMR registers to their default condition. The fundamental reset can be generated through:

- Primary Reset, or
- Secondary Bus Reset

### 5.18.9.2 Function Level Reset (FLR)

Function level reset is initiated by a configuration write which sets the Initiate FLR bit in "SCU VF PCI Express\* Device Control Register x (SCU V I EXP DCTL x)" (VF, see Section 16.3.3.5) or "SCU PF PCI Express\* Device Control Register (SCU P I EXP DCTL)" (PF, see Section 16.2.4.5). An FLR to a VF resets only that VF. Other VFs and the PF are unaffected (SR-IOV continues to operate).



### 5.18.9.2.1 Function Level Reset (Virtual Function)

When the Initiate FLR bit is set, in the “SCU VF PCI Express\* Device Control Register x (SCU V I EXP DCTL x)” (VF, see Section 16.3.3.5) the SMU will reset a subset of the VF MMR registers and generate an Event Notification to the master Driver in the physical function (PF) indicating that it should abort all outstanding tasks and re-initialize the VF.

### 5.18.9.2.2 Function Level Reset (Physical Function)

When the Initiate FLR bit is set, in the “SCU PF PCI Express\* Device Control Register (SCU P I EXP DCTL)” (PF, see Section 16.2.4.5) a hardware reset is asserted to all of the SCU (except for the IOSF interface). Therefore, the SMU, SDMA, and PEG are all reset.

## 5.18.10 SGPIO

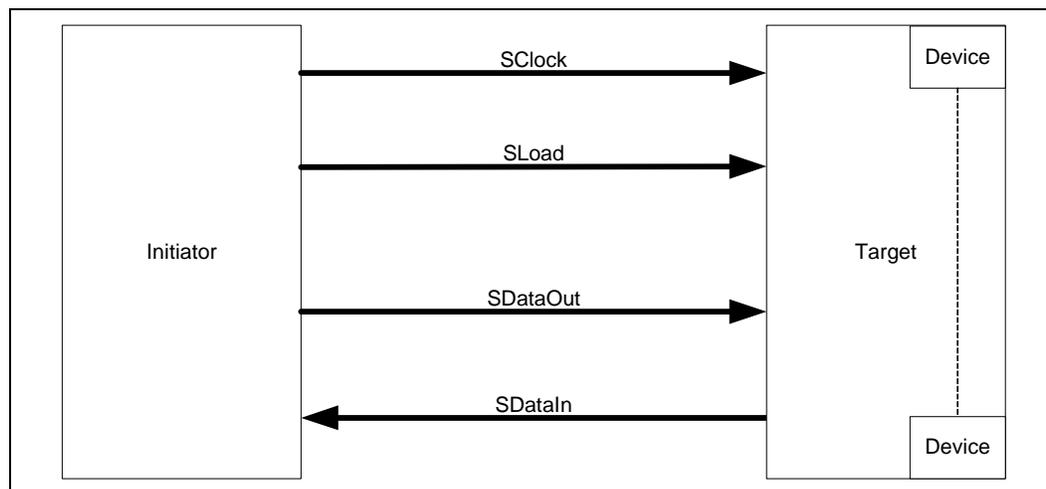
### 5.18.10.1 Overview

This chapter describes the Serial General Purpose Input Output (SGPIO) Unit that is used in the Storage Controller Unit (SCU). The SCU is organized into Protocol Engine Groups (PEGs). Each Protocol Engine Group (PEG) can support up to four Protocol Engines (PEs). Each PEG supports one SGPIO unit. The SGPIO unit also provides a feature that allows two PEGs to use a single SGPIO unit. However, this feature is only valid in SGPIO (serial) mode of operation. Therefore, the SGPIO unit can support up to eight devices.

The SGPIO is a serial bus consisting of four signals: SClock, SLoad, SDataOut, and SDataIn. The SGPIO is used to serialize general purpose I/O signals. The SGPIO defines communication between an initiator and a target. The target typically converts output signals into multiple parallel LED signals and provides inputs from general purpose inputs. Figure 5-1 shows the SGPIO bus. A target typically consists of multiple devices, and SGPIO protocol allows each device on the target to support up to three output and three input signals.

The SGPIO interface on the SCU can support up to eight devices (drives) on the target end. Each device can control up to three output bits and three input bits. Therefore, the SGPIO interface on the SCU can support up to twenty-four input signals and twenty-four output signals.

Figure 5-18. SGPIO Bus Overview

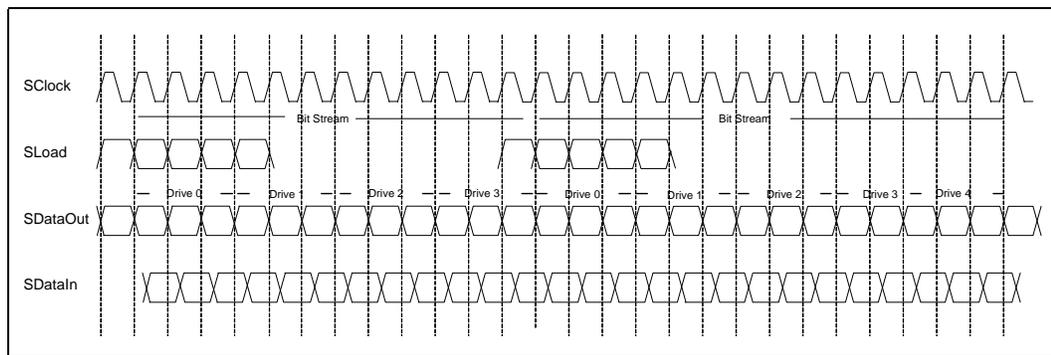


### 5.18.10.2 Theory of Operation

The SGPIO is used to serialize general purpose I/O signals. For example, the initiator may want to drive multiple LEDs on the target, and thus do so by sampling and serializing the parallel initiator LED signals at a fixed sampling rate dictated by the low-to-high transition of the SLoad signal. Note that SClock is a free-running clock. The receiver (initiator or target) would then take the bit samples from the bit stream and converts them into parallel LED signals.

Figure 5-19 shows the input and output bit streams relative to SClock and SLoad signals. Note that the SGPIO interface sends a repeating bit stream on SDataOut and receives a repeating bit stream SDataIn. The bit stream is restarted each time the SLoad signal is set high. Note that the example in Figure 5-19 shows four drives and five drives. The bit stream need not be the same length every time.

Figure 5-19. SGPIO Repeating Bit Stream



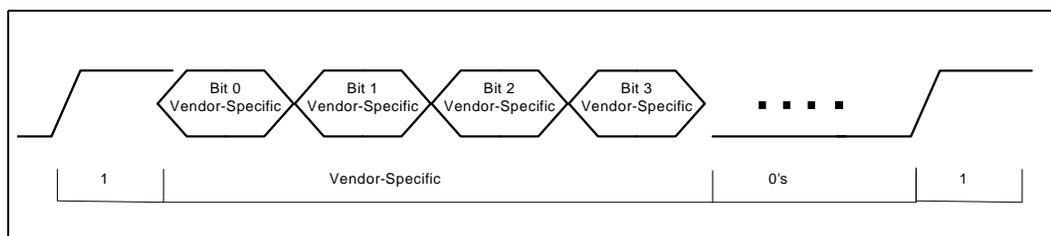
#### 5.18.10.2.1 SGPIO SClock Output Signal

SClock is a free-running clock running at a fixed frequency of up to 100 KHz. The rising edge of SClock is used to transmit SLoad, SDataOut, and SDataIn. The falling edge of SClock is used to latch SLoad, SDataOut, and SDataIn.

#### 5.18.10.2.2 SGPIO SLoad Output Signal

The initiator shall repeatedly send SDataOut bits and receives SDataIn bits. The SLoad signal indicates when the bit stream is ending or being restarted. After SLoad is asserted (set to 1), the next four bits positions on SLoad contain a vendor-specific pattern. Following the vendor-specific pattern, the initiator shall set the SLoad to 0 until it wants to restart the bits stream.

Figure 5-20. SLoad Signal

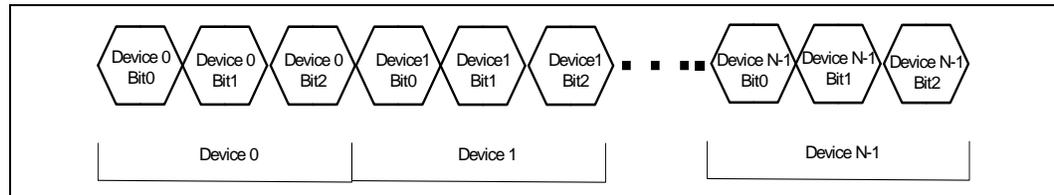




### 5.18.10.2.3 SDataOut

The SDataOut signal carries output bits associated with devices on the target. For example, on the SCU the SGPIO can drive up to three bits per device and up to eight devices on the target, thus is able to control twenty-four outputs on the target. The SDataOut signal carries the 3-bit outputs for each device in the same order in each repeated bit stream.

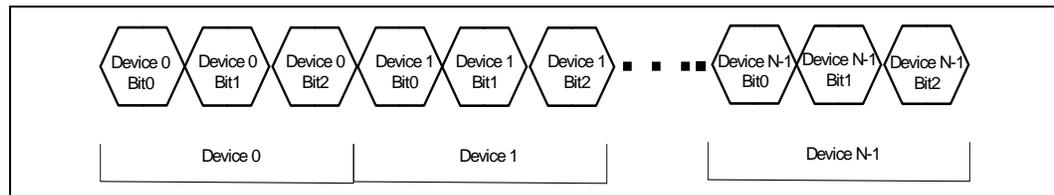
Figure 5-21. SDataOut Signal



### 5.18.10.2.4 SGPIO SDataIn Signal

The SDataIn signal carries input bits associated with devices on the target. For example, on the SCU the SGPIO can receive up to three bits per device and up to eight devices on the target, thus is able to receive twenty-four inputs from the target. The SDataIn signal carries the 3-bit inputs for each device in the same order in each repeated bit stream.

Figure 5-22. SDataIn Signal



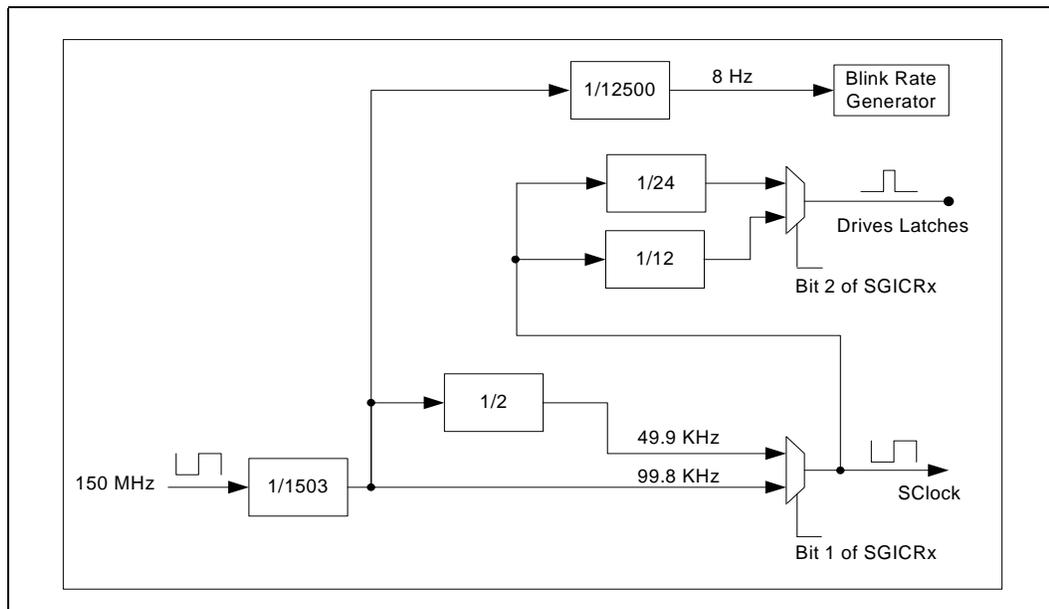
### 5.18.10.3 Clock Requirements

The SCU generates and drives three clock signals that are used to run the various blocks of the SGPIO units.

- SCLock - is the output clock of the SGPIO interface and runs at a either 49.9 KHz or 99.8 KHz.
- Load Clock - this clock is used internally to load the internal latches. This clock runs at 1/12 or 1/24 the SCLock rate.
- Blink Generator Clock - this clock is used to drive the blink generator. This clock runs at 1/12500 of the SCLock rate.

Figure 5-23 shows the clock structure.

Figure 5-23. Clock Structure



#### 5.18.10.4 Output Signals

The SGPIO unit can support up to eight drives, and each drive can support up to three output signals. This allows the SGPIO unit to be able to drive up to twenty-four output signals.

The SGPIO supports the following output signals:

- Fixed High
- PE Activity, PE Status, or Reserved
- Two programmable Blinks (A and B)

In addition the outputs can be optionally inverted.

Each output bit can be independently selected using the “SGPIO Output Data Select Register[0: 7]”. The selected output can in turn be inverted by software driver using the “SGPIO Output Data Select Register[0: 7]”.

Figure 5-24, Figure 5-25, and Figure 5-26 respectively show the three output signals supported per drive (OD0, OD1, and OD2) and the supported output signal selections.



Figure 5-24. SGPIO Output OD0 Signal

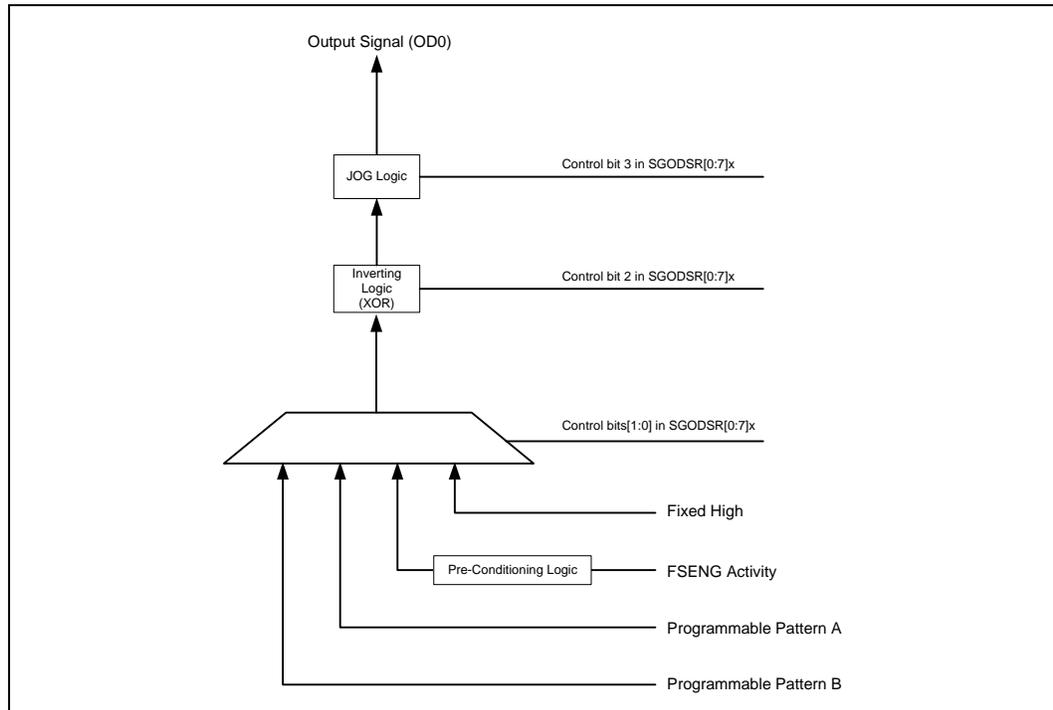


Figure 5-25. SGPIO Output OD1 Signal

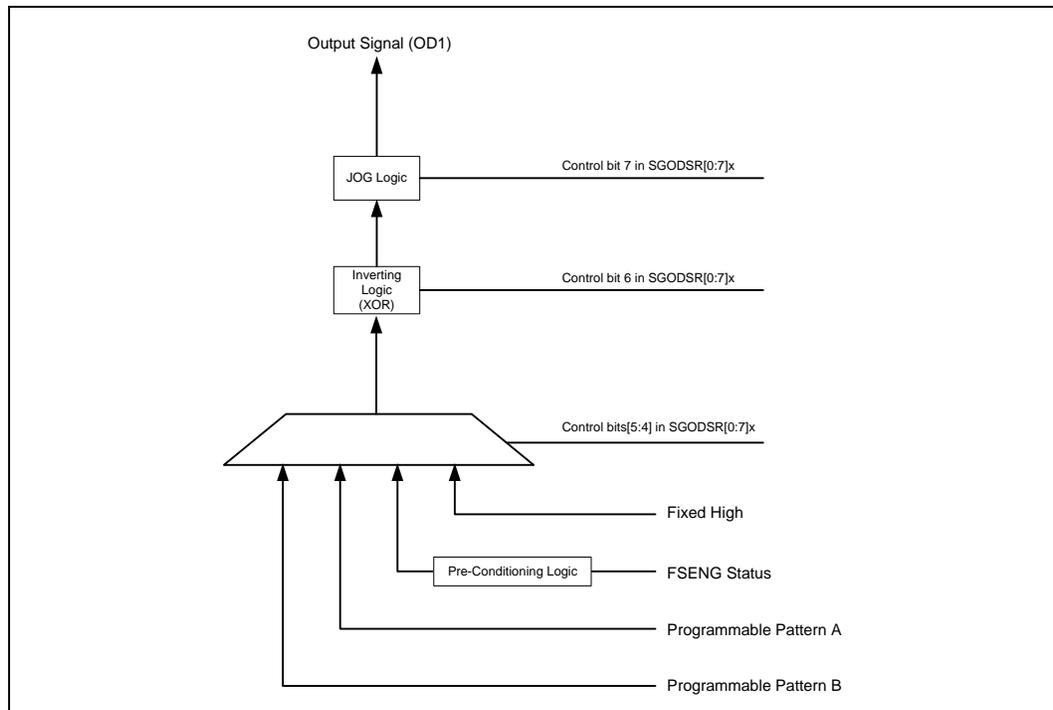
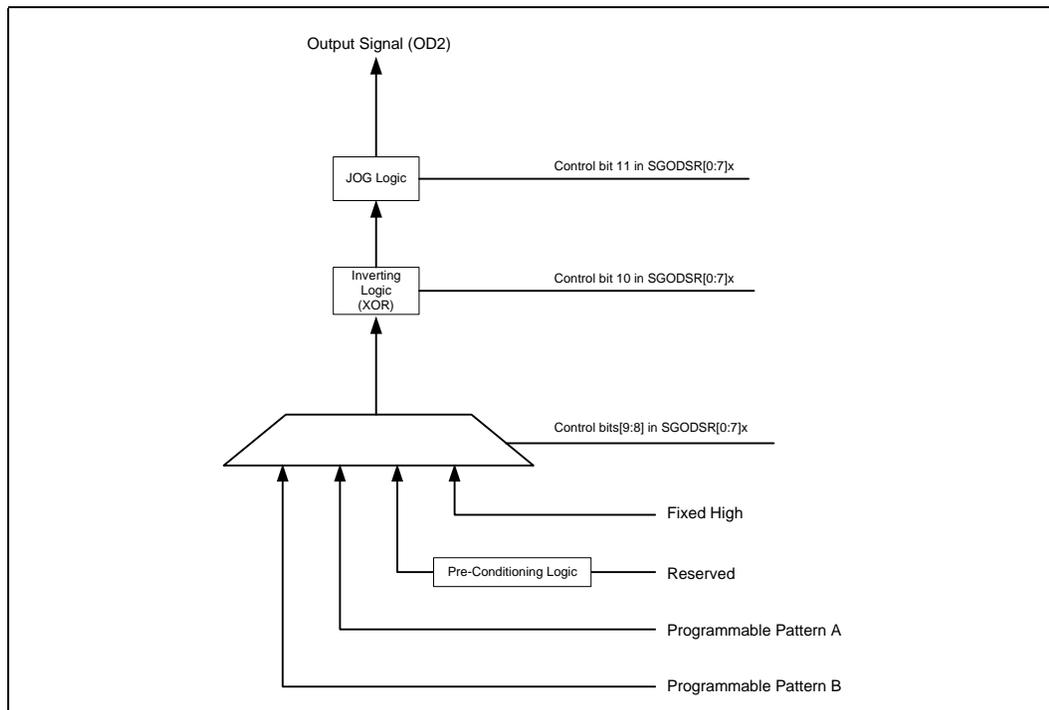


Figure 5-26. SGPIO Output OD2 Signal



### 5.18.10.5 SCU Input Signals

Each SCU PEG (Protocol Engine Group) supports one SGPIO unit. And each PEG can support up to four PEs (Protocol Engines). The SGPIO unit is designed to accommodate up to two PEGs (eight PEs). For example, the SGPIO unit can support eight sets of drive inputs. Note that each drive input set supports three inputs OD[2:0]. The lower four sets of drive inputs are driven by the local PEG, whereas the upper four sets of drive inputs are driven by the other PEG (or other SCU). Each PE drives two signals: activity (PE\_ACT) and status (PE\_STAT). Each PE\_ACT/PE\_STAT pair is driven to one of the SGPIO unit drive inputs. These PE activity and status signals can be selected as optional output signals of the SGPIO unit that can be driven serially on the SDataOut pin or on the direct LED signals. Refer to Figure 5-24 and Figure 5-25 for the output selections. Table 5-48 shows how the input signals are mapped to the ODx inputs of the SGPIO unit.

Table 5-48. SGPIO Input Mapping (Sheet 1 of 2)

Input Signals	SGPIOx Inputs	Input Signals	SGPIOx Inputs
Fixed High	Drive0.OD0	Fixed High	Drive4.OD0
PE Activity [0]		Other PEG, PE Activity [0]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive0.OD1	Fixed High	Drive4.OD1
PE Status [0]		Other PEG, PE Status [0]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	



**Table 5-48. SGPIO Input Mapping (Sheet 2 of 2)**

Input Signals	SGPIOx Inputs	Input Signals	SGPIOx Inputs
Fixed High	Drive0.OD2	Fixed High	Drive4.OD2
Reserved		Reserved	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive1.OD0	Fixed High	Drive5.OD0
PE Activity [1]		Other PEG, PE Activity [1]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive1.OD1	Fixed High	Drive5.OD1
PE Status [1]		Other PEG, PE Status [1]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive1.OD2	Fixed High	Drive5.OD2
Reserved		Reserved	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive2.OD0	Fixed High	Drive6.OD0
PE Activity [2]		Other PEG, PE Activity [2]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive2.OD1	Fixed High	Drive6.OD1
PE Status [2]		Other PEG, PE Status [2]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive2.OD2	Fixed High	Drive6.OD2
Reserved		Reserved	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive3.OD0	Fixed High	Drive7.OD0
PE Activity [3]		Other PEG, PE Activity [3]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive3.OD1	Fixed High	Drive7.OD1
PE Status [3]		Other PEG, PE Status [3]	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	
Fixed High	Drive3.OD2	Fixed High	Drive7.OD2
Reserved		Reserved	
Programmable Pattern A		Programmable Pattern A	
Programmable Pattern B		Programmable Pattern B	



### 5.18.10.5.1 JOG Requirements

The jog feature is optional and is controlled by the “SGPIO Output Data Select Register[0:7]”. When enabled, this feature monitors the input signal and if the input signal is detected low for about 4 seconds it will be forced high for a 250 ms duration.

### 5.18.10.5.2 SCU Drive Pre-Conditioning Requirements

All the SCU activity and status signals are pre-conditioned when entering the SGPIO units. The pre-conditioning logic monitors for any short pulse or any high frequency input signal and ensures that the input signal is stretched and held high for at least 125 ms.

### 5.18.10.5.3 Programmable Blink Patterns

Each of the SGPIO output signal supports two programmable blink patterns that can be selected using the “SGPIO Output Data Select Register[0:7]”. The blink rate generator is clocked using an 8 Hz clock and allows the user to program a low and a high duration time using two 4-bit fields located in the “SGPIO Programmable Blink Register”. The shortest low/high duration time that can be program is 125 milliseconds and the longest low/high duration time that can be programmed is 2 seconds. The shortest blink rate period is 250 milliseconds and the longest blink rate period is 4 seconds.

### 5.18.10.6 SGPIO Serializer Modes of Operations

The SGPIO serializer supports the following modes simultaneously:

- Direct (parallel) LED mode (up to 8 LEDs; Drives[3:0], OD[1:0])
- SGPIO (serial) mode (up to 24 LEDs; Drives[7:0], OD[2:0])

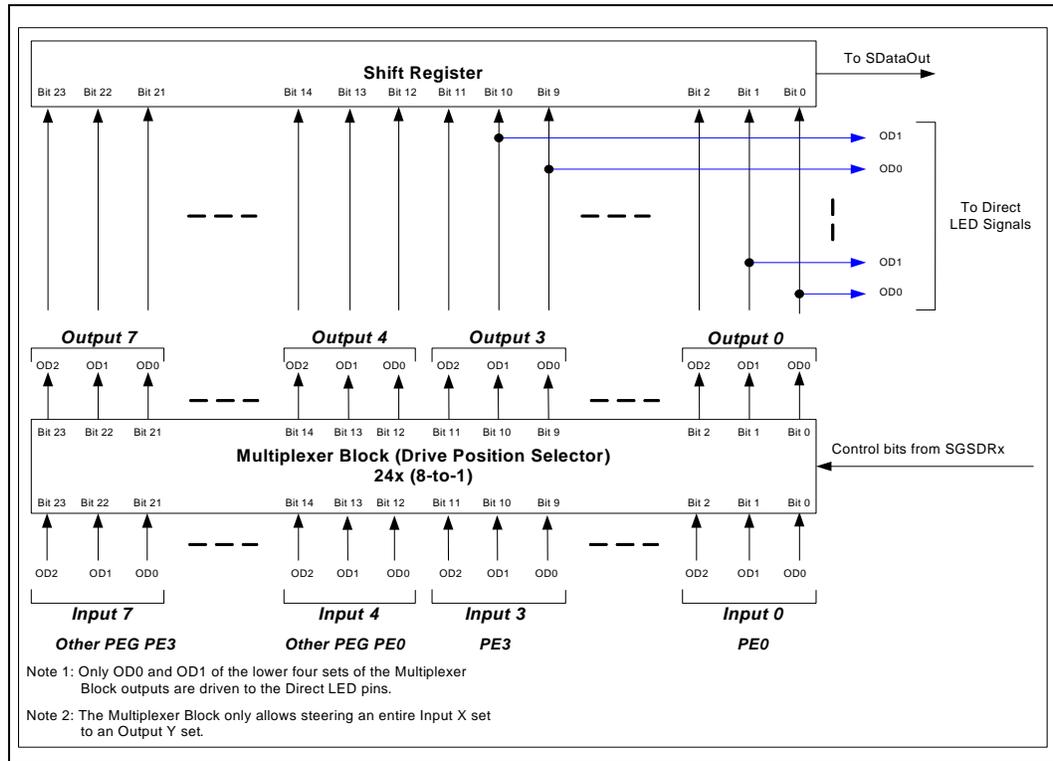
The SGPIO serializer requires up to 8 pins to support the direct drive mode and 4 pins to support the serial mode of operation.

A Drive-Position multiplexer block provides the ability to route any input Drive number to any output Drive number before being driven to the shift register and to the direct LED signals (refer to [Figure 5-27](#)). Note, all three signals of a Drive are routed simultaneously.

Note that the SGPIO unit can support up to 3 LEDs per PE and up to eight PEs in SGPIO (serial) mode. However, the Direct parallel LED mode can only support 2 LEDs per PE and four PEs.



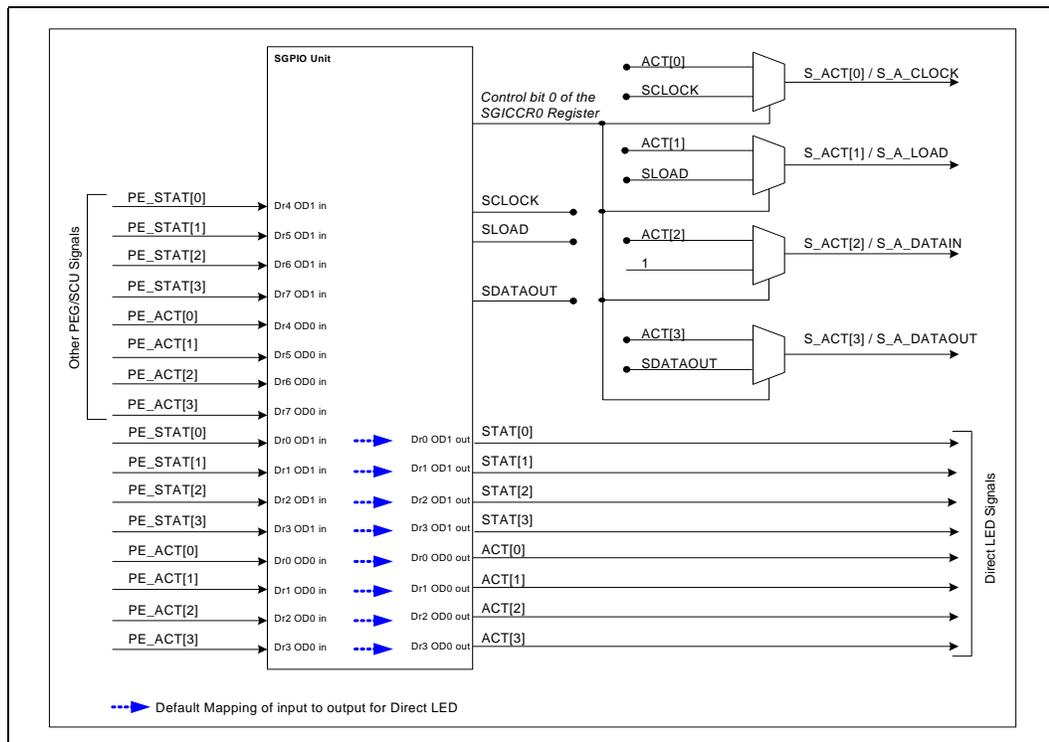
Figure 5-27. Output Signal Routing



### 5.18.10.7 Serial Pin Multiplexing

The SGPIO unit's serial pins also support a Direct (parallel) Activity LED mode. Figure 5-28 shows how the SGPIO unit signals are used and multiplexed. Bit 0 of the "SGPIO Interface Control Register" is used to select between the SGPIO (serial) mode and the direct Activity LED (parallel) mode, and by default bit 0 selects the parallel mode.

Figure 5-28. SCU SGPIO Unit Pin Mapping



## 5.19 High Precision Event Timers (HPET)

This function provides a set of timers that can be used by the operating system. The timers are defined such that in the future, the operating system may be able to assign specific timers to be used directly by specific applications. Each timer can be configured to cause a separate interrupt.

PCH provides eight timers. The timers are implemented as a single counter, and each timer has its own comparator and value register. The counter increases monotonically. Each individual timer can generate an interrupt when the value in its value register matches the value in the main counter.

The registers associated with these timers are mapped to a memory space (much like the I/O APIC). However, it is not implemented as a standard PCI function. The BIOS reports to the operating system the location of the register space. The hardware can support an assignable decode space; however, the BIOS sets this space prior to handing it over to the operating system. It is not expected that the operating system will move the location of these timers once it is set by the BIOS.

### 5.19.1 Timer Accuracy

1. The timers are accurate over any 1 ms period to within 0.05% of the time specified in the timer resolution fields.
2. Within any 100 microsecond period, the timer reports a time that is up to two ticks too early or too late. Each tick is less than or equal to 100 ns, so this represents an error of less than 0.2%.
3. The timer is monotonic. It does not return the same value on two consecutive reads (unless the counter has rolled over and reached the same value).



The main counter is clocked by the 14.31818 MHz clock, synchronized into the 66.666 MHz domain. This results in a non-uniform duty cycle on the synchronized clock, but does have the correct average period. The accuracy of the main counter is as accurate as the 14.31818 MHz clock.

## 5.19.2 Interrupt Mapping

The interrupts associated with the various timers have several interrupt mapping options. When reprogramming the HPET interrupt routing scheme (LEG\_RT\_CNF bit in the General Configuration Register), a spurious interrupt may occur. This is because the other source of the interrupt (8254 timer) may be asserted. Software should mask interrupts prior to clearing the LEG\_RT\_CNF bit.

### Mapping Option #1 (Legacy Replacement Option)

In this case, the Legacy Replacement Rout bit (LEG\_RT\_CNF) is set. This forces the mapping found in Table 5-49.

**Table 5-49. Legacy Replacement Routing**

Timer	8259 Mapping	APIC Mapping	Comment
0	IRQ0	IRQ2	In this case, the 8254 timer will not cause any interrupts
1	IRQ8	IRQ8	In this case, the RTC will not cause any interrupts.
2 & 3	Per IRQ Routing Field.	Per IRQ Routing Field	
4, 5, 6, 7	not available	not available	

**Note:** The Legacy Option does not preclude delivery of IRQ0/IRQ8 using processor message interrupts.

### Mapping Option #2 (Standard Option)

In this case, the Legacy Replacement Rout bit (LEG\_RT\_CNF) is 0. Each timer has its own routing control. The interrupts can be routed to various interrupts in the 8259 or I/O APIC. A capabilities field indicates which interrupts are valid options for routing. If a timer is set for edge-triggered mode, the timers should not be share with any PCI interrupts.

For the PCH, the only supported interrupt values are as follows:

Timer 0 and 1: IRQ20, 21, 22 & 23 (I/O APIC only).

Timer 2: IRQ11 (8259 or I/O APIC) and IRQ20, 21, 22 & 23 (I/O APIC only).

Timer 3: IRQ12 (8259 or I/O APIC) and IRQ 20, 21, 22 & 23 (I/O APIC only).

Interrupts from Timer 4, 5, 6, 7 can only be delivered using processor message interrupts.

### Mapping Option #3 (Processor Message Option)

In this case, the interrupts are mapped directly to processor messages without going to the 8259 or I/O (x) APIC. To use this mode, the interrupt must be configured to edge-triggered mode. The Tn\_PROCMSG\_EN\_CNF bit must be set to enable this mode.

When the interrupt is delivered to the processor, the message is delivered to the address indicated in the Tn\_PROCMSG\_INT\_ADDR field. The data value for the write cycle is specified in the Tn\_PROCMSG\_INT\_VAL field.

Notes:

1. The processor message interrupt delivery option has HIGHER priority and is mutually exclusive to the standard interrupt delivery option. Thus, if the Tn\_PROCMMSG\_EN\_CNF bit is set, the interrupts will be delivered directly to the processor rather than via the APIC or 8259.
2. The processor message interrupt delivery can be used even when the legacy mapping is used.
3. The *IA-PC HPET Specification* uses the term “FSB Interrupt” to describe these type of interrupts.

### 5.19.3 Periodic versus Non-Periodic Modes

#### Non-Periodic Mode

Timer 0 is configurable to 32 (default) or 64-bit mode, whereas Timers 1:7 only support 32-bit mode (See Section 21.1.5).

#### **Warning:**

Software must be careful when programming the comparator registers. If the value written to the register is not sufficiently far in the future, then the counter may pass the value before it reaches the register and the interrupt will be missed. The BIOS should pass a data structure to the OS to indicate that the OS should not attempt to program the periodic timer to a rate faster than 5 microseconds.

All of the timers support non-periodic mode.

Refer to Section 2.3.9.2.1 of the *IA-PC HPET Specification* for more details of this mode.

#### Periodic Mode

Timer 0 is the only timer that supports periodic mode. Refer to Section 2.3.9.2.2 of the *IA-PC HPET Specification* for more details of this mode.

If the software resets the main counter, the value in the comparator’s value register needs to reset as well. This can be done by setting the TIMERN\_VAL\_SET\_CNF bit. Again, to avoid race conditions, this should be done with the main counter halted. The following usage model is expected:

1. Software clears the ENABLE\_CNF bit to prevent any interrupts
2. Software Clears the main counter by writing a value of 00h to it.
3. Software sets the TIMER0\_VAL\_SET\_CNF bit.
4. Software writes the new value in the TIMER0\_COMPARATOR\_VAL register
5. Software sets the ENABLE\_CNF bit to enable interrupts.

The Timer 0 Comparator Value register cannot be programmed reliably by a single 64-bit write in a 32-bit environment except if only the periodic rate is being changed during run-time. If the actual Timer 0 Comparator Value needs to be reinitialized, then the following software solution will always work regardless of the environment:

1. Set TIMER0\_VAL\_SET\_CNF bit
2. Set the lower 32 bits of the Timer0 Comparator Value register
3. Set TIMER0\_VAL\_SET\_CNF bit
4. Set the upper 32 bits of the Timer0 Comparator Value register



## 5.19.4 Enabling the Timers

The BIOS or operating system PnP code should route the interrupts. This includes the Legacy Rout bit, Interrupt Rout bit (for each timer), and interrupt type (to select the edge or level type for each timer)

The Device Driver code should do the following for an available timer:

1. Set the Overall Enable bit (Offset 10h, bit 0).
2. Set the timer type field (selects one-shot or periodic).
3. Set the interrupt enable
4. Set the comparator value

## 5.19.5 Interrupt Levels

Interrupts directed to the internal 8259s are active high. See [Section 5.10](#) for information regarding the polarity programming of the I/O APIC for detecting internal interrupts.

If the interrupts are mapped to the 8259 or I/O APIC and set for level-triggered mode, they can be shared with PCI interrupts. They may be shared although it's unlikely for the operating system to attempt to do this.

If more than one timer is configured to share the same IRQ (using the `TIMERn_INT_ROUT_CNF` fields), then the software must configure the timers to level-triggered mode. Edge-triggered interrupts cannot be shared.

## 5.19.6 Handling Interrupts

Section 2.4.6 of the *IA-PC HPET Specification* describes Handling Interrupts.

## 5.19.7 Issues Related to 64-Bit Timers with 32-Bit Processors

Section 2.4.7 of the *IA-PC HPET Specification* describes Issues Related to 64-Bit Timers with 32-Bit Processors.

## 5.20 USB EHCI Host Controllers (D29:F0 and D26:F0)

The PCH contains two Enhanced Host Controller Interface (EHCI) host controllers which support up to fourteen USB 2.0 high-speed root ports. USB 2.0 allows data transfers up to 480 Mb/s. USB 2.0 based Debug Port is also implemented in the PCH.

### 5.20.1 EHC Initialization

The following descriptions step through the expected PCH Enhanced Host Controller (EHC) initialization sequence in chronological order, beginning with a complete power cycle in which the suspend well and core well have been off.

#### 5.20.1.1 BIOS Initialization

BIOS performs a number of platform customization steps after the core well has powered up. Contact your Intel Field Representative for additional PCH BIOS information.



### 5.20.1.2 Driver Initialization

See Chapter 4 of the *Enhanced Host Controller Interface Specification for Universal Serial Bus*, Revision 1.0.

### 5.20.1.3 EHC Resets

In addition to the standard PCH hardware resets, portions of the EHC are reset by the HCRESET bit and the transition from the D3<sub>HOT</sub> device power management state to the D0 state. The effects of each of these resets are:

Reset	Does Reset	Does not Reset	Comments
HCRESET bit set.	Memory space registers except Structural Parameters (which is written by BIOS).	Configuration registers.	The HCRESET must only affect registers that the EHCI driver controls. PCI Configuration space and BIOS-programmed parameters can not be reset.
Software writes the Device Power State from D3 <sub>HOT</sub> (11b) to D0 (00b).	Core well registers (except BIOS-programmed registers).	Suspend well registers; BIOS-programmed core well registers.	The D3-to-D0 transition must not cause wake information (suspend well) to be lost. It also must not clear BIOS-programmed registers because BIOS may not be invoked following the D3-to-D0 transition.

If the detailed register descriptions give exceptions to these rules, those exceptions override these rules. This summary is provided to help explain the reasons for the reset policies.

## 5.20.2 Data Structures in Main Memory

See Section 3 and Appendix B of the *Enhanced Host Controller Interface Specification for Universal Serial Bus*, Revision 1.0 for details.

## 5.20.3 USB 2.0 Enhanced Host Controller DMA

The PCH USB 2.0 EHC implements three sources of USB packets. They are, in order of priority on USB during each microframe:

1. The USB 2.0 Debug Port (see Section USB 2.0 Based Debug Port),
2. The Periodic DMA engine, and
3. The Asynchronous DMA engine.

The PCH always performs any currently-pending debug port transaction at the beginning of a microframe, followed by any pending periodic traffic for the current microframe. If there is time left in the microframe, then the EHC performs any pending asynchronous traffic until the end of the microframe (EOF1). Note that the debug port traffic is only presented on Port 1 and Port 9, while the other ports are idle during this time.

## 5.20.4 Data Encoding and Bit Stuffing

See Chapter 8 of the *Universal Serial Bus Specification, Revision 2.0*.

## 5.20.5 Packet Formats

See Chapter 8 of the *Universal Serial Bus Specification, Revision 2.0*.



The PCH EHCI allows entrance to USB test modes, as defined in the USB 2.0 specification, including Test J, Test Packet, etc. However note that the PCH Test Packet test mode interpacket gap timing may not meet the USB 2.0 specification.

## 5.20.6 USB 2.0 Interrupts and Error Conditions

Section 4 of the *Enhanced Host Controller Interface Specification for Universal Serial Bus*, Revision 1.0 goes into detail on the EHC interrupts and the error conditions that cause them. All error conditions that the EHC detects can be reported through the EHCI Interrupt status bits. Only PCH-specific interrupt and error-reporting behavior is documented in this section. The EHCI Interrupts Section must be read first, followed by this section of the datasheet to fully comprehend the EHC interrupt and error-reporting functionality.

- Based on the EHC Buffer sizes and buffer management policies, the Data Buffer Error can never occur on the PCH.
- Master Abort and Target Abort responses from hub interface on EHC-initiated read packets will be treated as Fatal Host Errors. The EHC halts when these conditions are encountered.
- The PCH may assert the interrupts which are based on the interrupt threshold as soon as the status for the last complete transaction in the interrupt interval has been posted in the internal write buffers. The requirement in the *Enhanced Host Controller Interface Specification for Universal Serial Bus*, Revision 1.0 (that the status is written to memory) is met internally, even though the write may not be seen on DMI before the interrupt is asserted.
- Since the PCH supports the 1024-element Frame List size, the Frame List Rollover interrupt occurs every 1024 milliseconds.
- The PCH delivers interrupts using PIRQH#.
- The PCH does not modify the CERR count on an Interrupt IN when the "Do Complete-Split" execution criteria are not met.
- For complete-split transactions in the Periodic list, the "Missed Microframe" bit does not get set on a control-structure-fetch that fails the late-start test. If subsequent accesses to that control structure do not fail the late-start test, then the "Missed Microframe" bit will get set and written back.

### 5.20.6.1 Aborts on USB 2.0-Initiated Memory Reads

If a read initiated by the EHC is aborted, the EHC treats it as a fatal host error. The following actions are taken when this occurs:

- The Host System Error status bit is set
- The DMA engines are halted after completing up to one more transaction on the USB interface
- If enabled (by the Host System Error Enable), then an interrupt is generated
- If the status is Master Abort, then the Received Master Abort bit in configuration space is set
- If the status is Target Abort, then the Received Target Abort bit in configuration space is set
- If enabled (by the SERR Enable bit in the function's configuration space), then the Signaled System Error bit in configuration bit is set.



## 5.20.7 USB 2.0 Power Management

### 5.20.7.1 Pause Feature

This feature allows platforms to dynamically enter low-power states during brief periods when the system is idle (that is, between keystrokes). This is useful for enabling power management features in the PCH. The policies for entering these states typically are based on the recent history of system bus activity to incrementally enter deeper power management states. Normally, when the EHC is enabled, it regularly accesses main memory while traversing the DMA schedules looking for work to do; this activity is viewed by the power management software as a non-idle system, thus preventing the power managed states to be entered. Suspending all of the enabled ports can prevent the memory accesses from occurring, but there is an inherent latency overhead with entering and exiting the suspended state on the USB ports that makes this unacceptable for the purpose of dynamic power management. As a result, the EHCI software drivers are allowed to pause the EHC DMA engines when it knows that the traffic patterns of the attached devices can afford the delay. The pause only prevents the EHC from generating memory accesses; the SOF packets continue to be generated on the USB ports (unlike the suspended state).

### 5.20.7.2 Suspend Feature

The *Enhanced Host Controller Interface (EHCI) For Universal Serial Bus Specification*, Section 4.3 describes the details of Port Suspend and Resume.

### 5.20.7.3 ACPI Device States

The USB 2.0 function only supports the D0 and D3 PCI Power Management states. Notes regarding the PCH implementation of the Device States:

1. The EHC hardware does not inherently consume any more power when it is in the D0 state than it does in the D3 state. However, software is required to suspend or disable all ports prior to entering the D3 state such that the maximum power consumption is reduced.
2. In the D0 state, all implemented EHC features are enabled.
3. In the D3 state, accesses to the EHC memory-mapped I/O range will master abort. Note that, since the Debug Port uses the same memory range, the Debug Port is only operational when the EHC is in the D0 state.
4. In the D3 state, the EHC interrupt must never assert for any reason. The internal PME# signal is used to signal wake events, and so forth.
5. When the Device Power State field is written to D0 from D3, an internal reset is generated. See section EHC Resets for general rules on the effects of this reset.
6. Attempts to write any other value into the Device Power State field other than 00b (D0 state) and 11b (D3 state) will complete normally without changing the current value in this field.

### 5.20.7.4 ACPI System States

The EHC behavior as it relates to other power management states in the system is summarized in the following list:

- The System is always in the S0 state when the EHC is in the D0 state. However, when the EHC is in the D3 state, the system may be in any power management state (including S0).
- When in D0, the Pause feature (See [Section 5.20.7.1](#)) enables dynamic processor low-power states to be entered.
- The PLL in the EHC is disabled when entering the S3/S4/S5 states (core power turns off).
- All core well logic is reset in the S3/S4/S5 states.



## 5.20.8 USB 2.0 Legacy Keyboard Operation

The PCH must support the possibility of a keyboard downstream from either a full-speed/low-speed or a high-speed port. The description of the legacy keyboard support is unchanged from USB 1.1.

- The EHC provides the basic ability to generate SMIs on an interrupt event, along with more sophisticated control of the generation of Intel SMIs.

## 5.20.9 USB 2.0 Based Debug Port

The PCH supports the elimination of the legacy COM ports by providing the ability for new debugger software to interact with devices on a USB 2.0 port.

High-level restrictions and features are:

- Operational before USB 2.0 drivers are loaded.
- Functions even when the port is disabled.
- Allows normal system USB 2.0 traffic in a system that may only have one USB port.
- Debug Port device (DPD) must be high-speed capable and connect directly to Port 1 and Port 9 on PCH systems (such as, the DPD cannot be connected to Port 1/Port 9 through a hub. When a DPD is detected the PCH EHCI will bypass the integrated Rate Matching Hub and connect directly to the port and the DPD).
- Debug Port FIFO always makes forward progress (a bad status on USB is simply presented back to software).
- The Debug Port FIFO is only given one USB access per microframe.

The Debug port facilitates operating system and device driver debug. It allows the software to communicate with an external console using a USB 2.0 connection. Because the interface to this link does not go through the normal USB 2.0 stack, it allows communication with the external console during cases where the operating system is not loaded, the USB 2.0 software is broken, or where the USB 2.0 software is being debugged. Specific features of this implementation of a debug port are:

- Only works with an external USB 2.0 debug device (console)
- Implemented for a specific port on the host controller
- Operational anytime the port is not suspended AND the host controller is in D0 power state.
- Capability is interrupted when port is driving USB RESET

### 5.20.9.1 Theory of Operation

There are two operational modes for the USB debug port:

1. Mode 1 is when the USB port is in a disabled state from the viewpoint of a standard host controller driver. In Mode 1, the Debug Port controller is required to generate a “keepalive” packets less than 2 ms apart to keep the attached debug device from suspending. The keepalive packet should be a standalone 32-bit SYNC field.
2. Mode 2 is when the host controller is running (that is, host controller’s *Run/Stop#* bit is 1). In Mode 2, the normal transmission of SOF packets will keep the debug device from suspending.

### Behavioral Rules

1. In both modes 1 and 2, the Debug Port controller must check for software requested debug transactions at least every 125 microseconds.
2. If the debug port is enabled by the debug driver, and the standard host controller driver resets the USB port, USB debug transactions are held off for the duration of the reset and until after the first SOF is sent.
3. If the standard host controller driver suspends the USB port, then USB debug transactions are held off for the duration of the suspend/resume sequence and until after the first SOF is sent.
4. The ENABLED\_CNT bit in the debug register space is independent of the similar port control bit in the associated Port Status and Control register.

Table 5-50 shows the debug port behavior related to the state of bits in the debug registers as well as bits in the associated Port Status and Control register.

**Table 5-50. Debug Port Behavior**

OWNER_CNT	ENABLED_CT	Port Enable	Run / Stop	Suspend	Debug Port Behavior
0	X	X	X	X	Debug port is not being used. Normal operation.
1	0	X	X	X	Debug port is not being used. Normal operation.
1	1	0	0	X	Debug port in Mode 1. SYNC keepalives sent plus debug traffic
1	1	0	1	X	Debug port in Mode 2. SOF (and only SOF) is sent as keepalive. Debug traffic is also sent. Note that no other normal traffic is sent out this port, because the port is not enabled.
1	1	1	0	0	Invalid. Host controller driver should never put controller into this state (enabled, not running and not suspended).
1	1	1	0	1	Port is suspended. No debug traffic sent.
1	1	1	1	0	Debug port in Mode 2. Debug traffic is interspersed with normal traffic.
1	1	1	1	1	Port is suspended. No debug traffic sent.

#### 5.20.9.1.1 OUT Transactions

An Out transaction sends data to the debug device. It can occur only when the following are true:

- The debug port is enabled
- The debug software sets the GO\_CNT bit
- The WRITE\_READ#\_CNT bit is set

The sequence of the transaction is:

1. Software sets the appropriate values in the following bits:
  - USB\_ADDRESS\_CNF
  - USB\_ENDPOINT\_CNF
  - DATA\_BUFFER[63:0]
  - TOKEN\_PID\_CNT[7:0]
  - SEND\_PID\_CNT[15:8]



- DATA\_LEN\_CNT
  - WRITE\_READ#\_CNT: (Note: This will always be 1 for OUT transactions.)
  - GO\_CNT: (note: this will always be 1 to initiate the transaction)
2. The debug port controller sends a token packet consisting of:
    - SYNC
    - TOKEN\_PID\_CNT field
    - USB\_ADDRESS\_CNT field
    - USB\_ENDPOINT\_CNT field
    - 5-bit CRC field
  3. After sending the token packet, the debug port controller sends a data packet consisting of:
    - SYNC
    - SEND\_PID\_CNT field
    - The number of data bytes indicated in DATA\_LEN\_CNT from the DATA\_BUFFER
    - 16-bit CRC

**Note:**

A DATA\_LEN\_CNT value of 0 is valid in which case no data bytes would be included in the packet.

4. After sending the data packet, the controller waits for a handshake response from the debug device.
  - If a handshake is received, the debug port controller:
    - a. Places the received PID in the RECEIVED\_PID\_STS field
    - b. Resets the ERROR\_GOOD#\_STS bit
    - c. Sets the DONE\_STS bit
  - If no handshake PID is received, the debug port controller:
    - a. Sets the EXCEPTION\_STS field to 001b
    - b. Sets the ERROR\_GOOD#\_STS bit
    - c. Sets the DONE\_STS bit

### 5.20.9.1.2 IN Transactions

An IN transaction receives data from the debug device. It can occur only when the following are true:

- The debug port is enabled
- The debug software sets the GO\_CNT bit
- The WRITE\_READ#\_CNT bit is reset

The sequence of the transaction is:

1. Software sets the appropriate values in the following bits:
  - USB\_ADDRESS\_CNF
  - USB\_ENDPOINT\_CNF
  - TOKEN\_PID\_CNT[7:0]
  - DATA\_LEN\_CNT
  - WRITE\_READ#\_CNT: (Note: This will always be 0 for IN transactions.)
  - GO\_CNT: (Note: This will always be 1 to initiate the transaction.)



2. The debug port controller sends a token packet consisting of:
  - SYNC
  - TOKEN\_PID\_CNT field
  - USB\_ADDRESS\_CNT field
  - USB\_ENDPOINT\_CNT field
  - 5-bit CRC field.
3. After sending the token packet, the debug port controller waits for a response from the debug device.  
If a response is received:
  - The received PID is placed into the RECEIVED\_PID\_STS field
  - Any subsequent bytes are placed into the DATA\_BUFFER
  - The DATA\_LEN\_CNT field is updated to show the number of bytes that were received after the PID.
4. If a valid packet was received from the device that was one byte in length (indicating it was a handshake packet), then the debug port controller:
  - Resets the ERROR\_GOOD#\_STS bit
  - Sets the DONE\_STS bit
5. If a valid packet was received from the device that was more than one byte in length (indicating it was a data packet), then the debug port controller:
  - Transmits an ACK handshake packet
  - Resets the ERROR\_GOOD#\_STS bit
  - Sets the DONE\_STS bit
6. If no valid packet is received, then the debug port controller:
  - Sets the EXCEPTION\_STS field to 001b
  - Sets the ERROR\_GOOD#\_STS bit
  - Sets the DONE\_STS bit.

### 5.20.9.1.3 Debug Software

#### Enabling the Debug Port

There are two mutually exclusive conditions that debug software must address as part of its startup processing:

- The EHCI has been initialized by system software
- The EHCI has not been initialized by system software

Debug software can determine the current 'initialized' state of the EHCI by examining the Configure Flag in the EHCI USB 2.0 Command Register. If this flag is set, then system software has initialized the EHCI. Otherwise the EHCI should not be considered initialized. Debug software will initialize the debug port registers depending on the state of the EHCI. However, before this can be accomplished, debug software must determine which root USB port is designated as the debug port.

#### Determining the Debug Port

Debug software can easily determine which USB root port has been designated as the debug port by examining bits 20:23 of the EHCI Host Controller Structural Parameters register. This 4-bit field represents the numeric value assigned to the debug port (that is, 0001=port 1).



### Debug Software Startup with Non-Initialized EHCI

Debug software can attempt to use the debug port if after setting the OWNER\_CNT bit, the Current Connect Status bit in the appropriate (See *Determining the Debug Port Presence*) PORTSC register is set. If the Current Connect Status bit is not set, then debug software may choose to terminate or it may choose to wait until a device is connected.

If a device is connected to the port, then debug software must reset/enable the port. Debug software does this by setting and then clearing the Port Reset bit the PORTSC register. To ensure a successful reset, debug software should wait at least 50 ms before clearing the Port Reset bit. Due to possible delays, this bit may not change to 0 immediately; reset is complete when this bit reads as 0. Software must not continue until this bit reads 0.

If a high-speed device is attached, the EHCI will automatically set the Port Enabled/Disabled bit in the PORTSC register and the debug software can proceed. Debug software should set the ENABLED\_CNT bit in the Debug Port Control/Status register, and then reset (clear) the Port Enabled/Disabled bit in the PORTSC register (so that the system host controller driver does not see an enabled port when it is first loaded).

### Debug Software Startup with Initialized EHCI

Debug software can attempt to use the debug port if the Current Connect Status bit in the appropriate (See *Determining the Debug Port*) PORTSC register is set. If the Current Connect Status bit is not set, then debug software may choose to terminate or it may choose to wait until a device is connected.

If a device is connected, then debug software must set the OWNER\_CNT bit and then the ENABLED\_CNT bit in the Debug Port Control/Status register.

### Determining Debug Peripheral Presence

After enabling the debug port functionality, debug software can determine if a debug peripheral is attached by attempting to send data to the debug peripheral. If all attempts result in an error (Exception bits in the Debug Port Control/Status register indicates a Transaction Error), then the attached device is not a debug peripheral. If the debug port peripheral is not present, then debug software may choose to terminate or it may choose to wait until a debug peripheral is connected.

## 5.20.10 EHCI Caching

EHCI Caching is a power management feature in the USB (EHCI) host controllers which enables the controller to execute the schedules entirely in cache and eliminates the need for the DMA engine to access memory when the schedule is idle. EHCI caching allows the processor to maintain longer C-state residency times and provides substantial system power savings.

## 5.20.11 USB Pre-Fetch Based Pause

The Pre-Fetch Based Pause is a power management feature in USB (EHCI) host controllers to ensure maximum C3/C4 processor power state time with C2 popup. This feature applies to the period schedule, and works by allowing the DMA engine to identify periods of idleness and preventing the DMA engine from accessing memory when the periodic schedule is idle. Typically in the presence of periodic devices with multiple millisecond poll periods, the periodic schedule will be idle for several frames between polls.

The USB Pre-Fetch Based Pause feature is disabled by setting bit 4 of EHCI Configuration Register [Section 17.2.1](#).



## 5.20.12 Function Level Reset Support (FLR) (SRV/WS SKUs Only)

The USB EHCI Controllers support the Function Level Reset (FLR) capability. The FLR capability can be used in conjunction with Intel Virtualization Technology. FLR allows an Operating System in a Virtual Machine to have complete control over a device, including its initialization, without interfering with the rest of the platform. The device provides a software interface that enables the Operating System to reset the whole device as if a PCI reset was asserted.

### 5.20.12.1 FLR Steps

#### 5.20.12.1.1 FLR Initialization

1. A FLR is initiated by software writing a '1' to the Initiate FLR bit.
2. All subsequent requests targeting the Function will not be claimed and will be Master Abort Immediate on the bus. This includes any configuration, I/O or Memory cycles, however, the Function shall continue to accept completions targeting the Function.

#### 5.20.12.1.2 FLR Operation

The Function will Reset all configuration, I/O and memory registers of the Function except those indicated otherwise and reset all internal states of the Function to the default or initial condition.

#### 5.20.12.1.3 FLR Completion

The Initiate FLR bit is reset (cleared) when the FLR reset is completed. This bit can be used to indicate to the software that the FLR reset is completed.

**Note:** From the time Initiate FLR bit is written to 1, software must wait at least 100 ms before accessing the function.

## 5.20.13 USB Overcurrent Protection

The PCH has implemented programmable USB Overcurrent signals. The PCH provides a total of 8 overcurrent pins to be shared across the 14 ports.

Four overcurrent signals have been allocated to the ports in each USB Device:

- OC[3:0]# for Device 29 (Ports 0-7)
- OC[7:4]# for Device 26 (Ports 8-13)

Each pin is mapped to one or more ports by setting bits in the USBOCM1 and USBOCM2 registers. See [Section 10.1.52](#) and [Section 10.1.53](#). It is system BIOS' responsibility to ensure that each port is mapped to only one over current pin. Operation with more than one overcurrent pin mapped to a port is undefined. It is expected that multiple ports are mapped to a single overcurrent pin, however they should be connected at the port and not at the PCH pin. Shorting these pins together may lead to reduced test capabilities. By default, two ports are routed to each of the OC[6:0]# pins. OC7# is not used by default.

#### **Notes:**

1. All USB ports routed out of the package must have Overcurrent protection. It is system BIOS responsibility to ensure all used ports have OC protection
2. USB Ports that are unused on the system (not routed out from the package) should not have OC pins assigned to them.



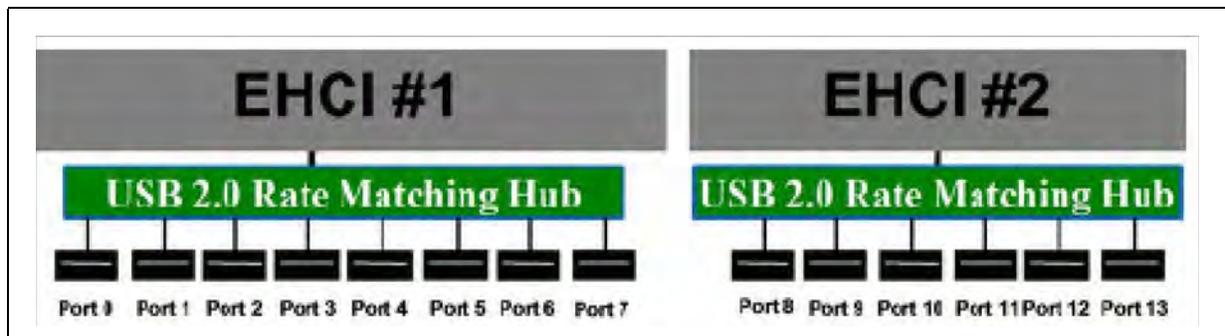
## 5.21 Integrated USB 2.0 Rate Matching Hub

### 5.21.1 Overview

The PCH has integrated two USB 2.0 Rate Matching Hubs (RMH). One hub is connected to each of the EHCI controllers as shown in the figure below. The Hubs convert low and full-speed traffic into high-speed traffic. The RMHs will appear to software like an external hub is connected to Port 0 of each EHCI controller. In addition, port 1 of each of the RMHs is muxed with Port 1 of the EHCI controllers and is able to bypass the RMH for use as the Debug Port.

The hub operates like any USB 2.0 Discrete Hub and will consume one tier of hubs allowed by the USB 2.0 Spec. section 4.1.1. A maximum of four additional non-root hubs can be supported on any of the PCH USB Ports. The RMH will report the following Vendor ID = 8087h and Product ID = 0024h.

**Figure 5-29. EHCI with USB 2.0 with Rate Matching Hub**



### 5.21.2 Architecture

A hub consists of three components: the Hub Repeater, the Hub Controller, and the Transaction Translator.

1. The Hub Repeater is responsible for connectivity setup and tear-down. It also supports exception handling, such as bus fault detection and recovery and connect/disconnect detect.
2. The Hub Controller provides the mechanism for host-to-hub communication. Hub-specific status and control commands permit the host to configure a hub and to monitor and control its individual downstream facing ports.
3. The Transaction Translator (TT) responds to high-speed split transactions and translates them to full-/low-speed transactions with full-/low-speed devices attached on downstream facing ports. There is 1 TT per RMH in PCH.

See chapter 11 of the USB 2.0 Specification for more details on the architecture of the hubs.



## 5.22 SMBus Controller

Depending on the SKU, the PCH contains two kinds of SMBus Controllers – the Host SMBus Controller and the IDF (Integrated Device Fabric) SMBus Controller.

**Note:** The IDF (Integrated Device Fabric) SMBus Controller is not available on the HEDT SKU.

### 5.22.1 Host SMBus Controller(D31:F3)

The PCH provides an System Management Bus (SMBus) 2.0 host controller as well as an SMBus Slave Interface. The host controller provides a mechanism for the processor to initiate communications with SMBus peripherals (slaves). The PCH is also capable of operating in a mode in which it can communicate with I<sup>2</sup>C compatible devices.

The PCH can perform SMBus messages with either packet error checking (PEC) enabled or disabled. The actual PEC calculation and checking is performed in hardware by the PCH.

The Slave Interface allows an external master to read from or write to the PCH. Write cycles can be used to cause certain events or pass messages, and the read cycles can be used to determine the state of various status bits. The PCH's internal host controller cannot access the PCH's internal Slave Interface.

The PCH SMBus logic exists in Device 31:Function 3 configuration space, and consists of a transmit data path, and host controller. The transmit data path provides the data flow logic needed to implement the seven different SMBus command protocols and is controlled by the host controller. The PCH SMBus controller logic is clocked by RTC clock.

The SMBus Address Resolution Protocol (ARP) is supported by using the existing host controller commands through software, except for the new Host Notify command (which is actually a received message).

The programming model of the host controller is combined into two portions: a PCI configuration portion, and a system I/O mapped portion. All static configuration, such as the I/O base address, is done using the PCI configuration space. Real-time programming of the Host interface is done in system I/O space.

The PCH SMBus host controller checks for parity errors as a target. If an error is detected, the detected parity error bit in the PCI Status Register (Device 31:Function 3:Offset 06h:bit 15) is set. If bit 6 and bit 8 of the PCI Command Register (Device 31:Function 3:Offset 04h) are set, an SERR# is generated and the signaled SERR# bit in the PCI Status Register (bit 14) is set.

### 5.22.2 IDF SMBus Controllers (Bus x:Device 0:Function 3,4,5) (SRV/WS SKUs Only)

There are three additional host SMBus functions in the Integrated Device Function (function 3, 4, and 5) for a total of potentially 4 host accessible controllers on the PCH. Host software will have the ability to use a number of the host SMBus controllers depending on the PCH SKUs.

The IDF SMBus controllers are similar to the host SMBus in their operations and programming interface. The primary difference is that the IDF SMBus controllers are PCI Express\* function that support message signalled interrupts.

The IDF SMBus controllers are SMBus 2.0 compliant devices supporting all protocols defined in the SMBus specification: Quick, Byte, Word, Block, and process call. The controllers also support an I<sup>2</sup>C mode to communicate with I<sup>2</sup>C compatible devices. SMBus messages can be sent either with PEC enabled or disabled though the actual PEC calculation and checking is performed by software.



### 5.22.3 Host Controller

The SMBus host controller is used to send commands to other SMBus slave devices. Software sets up the host controller with an address, command, and, for writes, data and optional PEC; and then tells the controller to start. When the controller has finished transmitting data on writes, or receiving data on reads, it generates an SMI# or interrupt, if enabled.

The host controller supports 8 command protocols of the SMBus interface (see *System Management Bus (SMBus) Specification, Version 2.0*): Quick Command, Send Byte, Receive Byte, Write Byte/Word, Read Byte/Word, Process Call, Block Read/Write, Block Write-Block Read Process Call, and Host Notify.

The SMBus host controller requires that the various data and command fields be setup for the type of command to be sent. When software sets the START bit, the SMBus Host controller performs the requested transaction, and interrupts the processor (or generates an SMI#) when the transaction is completed. Once a START command has been issued, the values of the “active registers” (Host Control, Host Command, Transmit Slave Address, Data 0, Data 1) should not be changed or read until the interrupt status message (INTR) has been set (indicating the completion of the command). Any register values needed for computation purposes should be saved prior to issuing of a new command, as the SMBus host controller updates all registers while completing the new command.

The PCH supports the *System Management Bus (SMBus) Specification, Version 2.0*. Slave functionality, including the Host Notify protocol, is available on the SMBus pins. The SMLink and SMBus signals can be tied together externally depending on TCO mode used. Refer to section 5.14.2 for more details.

Using the SMB host controller to send commands to the PCH's SMB slave port is not supported.

#### 5.22.3.1 Command Protocols

In all of the following commands, the Host Status Register (offset 00h) is used to determine the progress of the command. While the command is in operation, the HOST\_BUSY bit is set. If the command completes successfully, the INTR bit will be set in the Host Status Register. If the device does not respond with an acknowledge, and the transaction times out, the DEV\_ERR bit is set. If software sets the KILL bit in the Host Control Register while the command is running, the transaction will stop and the FAILED bit will be set.

##### Quick Command

When programmed for a Quick Command, the Transmit Slave Address Register is sent. The PEC byte is never appended to the Quick Protocol. Software should force the PEC\_EN bit to 0 when performing the Quick Command. Software must force the I2C\_EN bit to 0 when running this command. See section 5.5.1 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.

##### Send Byte / Receive Byte

For the Send Byte command, the Transmit Slave Address and Device Command Registers are sent

For the Receive Byte command, the Transmit Slave Address Register is sent. The data received is stored in the DATA0 register. Software must force the I2C\_EN bit to 0 when running this command.

The Receive Byte is similar to a Send Byte, the only difference is the direction of data transfer. See sections 5.5.2 and 5.5.3 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.



### Write Byte/Word

The first byte of a Write Byte/Word access is the command code. The next 1 or 2 bytes are the data to be written. When programmed for a Write Byte/Word command, the Transmit Slave Address, Device Command, and Data0 Registers are sent. In addition, the Data1 Register is sent on a Write Word command. Software must force the I2C\_EN bit to 0 when running this command. See section 5.5.4 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.

### Read Byte/Word

Reading data is slightly more complicated than writing data. First the PCH must write a command to the slave device. Then it must follow that command with a repeated start condition to denote a read from that device's address. The slave then returns 1 or 2 bytes of data. Software must force the I2C\_EN bit to 0 when running this command.

When programmed for the read byte/word command, the Transmit Slave Address and Device Command Registers are sent. Data is received into the DATA0 on the read byte, and the DATA0 and DATA1 registers on the read word. See section 5.5.5 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.

### Process Call

The process call is so named because a command sends data and waits for the slave to return a value dependent on that data. The protocol is simply a Write Word followed by a Read Word, but without a second command or stop condition.

When programmed for the Process Call command, the PCH transmits the Transmit Slave Address, Host Command, DATA0 and DATA1 registers. Data received from the device is stored in the DATA0 and DATA1 registers. The Process Call command with I2C\_EN set and the PEC\_EN bit set produces undefined results. Software must force either I2C\_EN or PEC\_EN to 0 when running this command. See section 5.5.6 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.

**Note:** For process call command, the value written into bit 0 of the Transmit Slave Address Register (SMB I/O register, offset 04h) needs to be 0.

**Note:** If the I2C\_EN bit is set, the protocol sequence changes slightly: the Command Code (bits 18:11 in the bit sequence) are not sent - as a result, the slave will not acknowledge (bit 19 in the sequence).



## Block Read/Write

The PCH contains a 32-byte buffer for read and write data which can be enabled by setting bit 1 of the Auxiliary Control register at offset 0Dh in I/O space, as opposed to a single byte of buffering. This 32-byte buffer is filled with write data before transmission, and filled with read data on reception. In the PCH, the interrupt is generated only after a transmission or reception of 32 bytes, or when the entire byte count has been transmitted/received.

**Note:** When operating in I<sup>2</sup>C mode (I2C\_EN bit is set), the PCH will never use the 32-byte buffer for any block commands.

The byte count field is transmitted but ignored by the PCH as software will end the transfer after all bytes it cares about have been sent or received.

For a Block Write, software must either force the I2C\_EN bit or both the PEC\_EN and AAC bits to 0 when running this command.

The block write begins with a slave address and a write condition. After the command code the PCH issues a byte count describing how many more bytes will follow in the message. If a slave had 20 bytes to send, the first byte would be the number 20 (14h), followed by 20 bytes of data. The byte count may not be 0. A Block Read or Write is allowed to transfer a maximum of 32 data bytes.

When programmed for a block write command, the Transmit Slave Address, Device Command, and Data0 (count) registers are sent. Data is then sent from the Block Data Byte register; the total data sent being the value stored in the Data0 Register. On block read commands, the first byte received is stored in the Data0 register, and the remaining bytes are stored in the Block Data Byte register. See section 5.5.7 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.

**Note:** For Block Write, if the I2C\_EN bit is set, the format of the command changes slightly. The PCH will still send the number of bytes (on writes) or receive the number of bytes (on reads) indicated in the DATA0 register. However, it will not send the contents of the DATA0 register as part of the message. Also, the Block Write protocol sequence changes slightly: the Byte Count (bits 27:20 in the bit sequence) are not sent - as a result, the slave will not acknowledge (bit 28 in the sequence).



## I<sup>2</sup>C Read

This command allows the PCH to perform block reads to certain I<sup>2</sup>C devices, such as serial E<sup>2</sup>PROMs. The SMBus Block Read supports the 7-bit addressing mode only.

However, this does not allow access to devices using the I<sup>2</sup>C “Combined Format” that has data bytes after the address. Typically these data bytes correspond to an offset (address) within the serial memory chips.

**Note:** This command is supported independent of the setting of the I2C\_EN bit. The I<sup>2</sup>C Read command with the PEC\_EN bit set produces undefined results. Software must force both the PEC\_EN and AAC bit to 0 when running this command.

For I<sup>2</sup>C Read command, the value written into bit 0 of the Transmit Slave Address Register (SMB I/O register, offset 04h) needs to be 0.

The format that is used for the command is shown in [Table 5-51](#).

**Table 5-51. I<sup>2</sup>C Block Read**

Bit	Description
1	Start
8:2	Slave Address — 7 bits
9	Write
10	Acknowledge from slave
18:11	Send DATA1 register
19	Acknowledge from slave
20	Repeated Start
27:21	Slave Address — 7 bits
28	Read
29	Acknowledge from slave
37:30	Data byte 1 from slave — 8 bits
38	Acknowledge
46:39	Data byte 2 from slave — 8 bits
47	Acknowledge
–	Data bytes from slave / Acknowledge
–	Data byte N from slave — 8 bits
–	NOT Acknowledge
–	Stop

The PCH will continue reading data from the peripheral until the NAK is received.



## Block Write–Block Read Process Call

The block write-block read process call is a two-part message. The call begins with a slave address and a write condition. After the command code the host issues a write byte count ( $M$ ) that describes how many more bytes will be written in the first part of the message. If a master has 6 bytes to send, the byte count field will have the value 6 (0000 0110b), followed by the 6 bytes of data. The write byte count ( $M$ ) cannot be 0.

The second part of the message is a block of read data beginning with a repeated start condition followed by the slave address and a Read bit. The next byte is the read byte count ( $N$ ), which may differ from the write byte count ( $M$ ). The read byte count ( $N$ ) cannot be 0.

The combined data payload must not exceed 32 bytes. The byte length restrictions of this process call are summarized as follows:

- $M \geq 1$  byte
- $N \geq 1$  byte
- $M + N \leq 32$  bytes

The read byte count does not include the PEC byte. The PEC is computed on the total message beginning with the first slave address and using the normal PEC computational rules. It is highly recommended that a PEC byte be used with the Block Write-Block Read Process Call. Software must do a read to the command register (offset 2h) to reset the 32 byte buffer pointer prior to reading the block data register.

Note that there is no STOP condition before the repeated START condition, and that a NACK signifies the end of the read transfer.

**Note:** E32B bit in the Auxiliary Control register must be set when using this protocol.

See section 5.5.8 of the *System Management Bus (SMBus) Specification, Version 2.0* for the format of the protocol.

### 5.22.4 Bus Arbitration

Several masters may attempt to get on the bus at the same time by driving the SMBDATA line low to signal a start condition. The PCH continuously monitors the SMBDATA line. When the PCH is attempting to drive the bus to a 1 by letting go of the SMBDATA line, and it samples SMBDATA low, then some other master is driving the bus and the PCH will stop transferring data.

If the PCH sees that it has lost arbitration, the condition is called a collision. The PCH will set the BUS\_ERR bit in the Host Status Register, and if enabled, generate an interrupt or SMI#. The processor is responsible for restarting the transaction.

When the PCH is a SMBus master, it drives the clock. When the PCH is sending address or command as an SMBus master, or data bytes as a master on writes, it drives data relative to the clock it is also driving. It will not start toggling the clock until the start or stop condition meets proper setup and hold time. The PCH will also ensure minimum time between SMBus transactions as a master.

**Note:** The PCH supports the same arbitration protocol for both the SMBus and the System Management (SMLink) interfaces.



## 5.22.5 Bus Timing

### 5.22.5.1 Clock Stretching

Some devices may not be able to handle their clock toggling at the rate that the PCH as an SMBus master would like. They have the capability of stretching the low time of the clock. When the PCH attempts to release the clock (allowing the clock to go high), the clock will remain low for an extended period of time.

The PCH monitors the SMBus clock line after it releases the bus to determine whether to enable the counter for the high time of the clock. While the bus is still low, the high time counter must not be enabled. Similarly, the low period of the clock can be stretched by an SMBus master if it is not ready to send or receive data.

### 5.22.5.2 Bus Time Out (PCH as SMBus Master)

If there is an error in the transaction, such that an SMBus device does not signal an acknowledge, or holds the clock lower than the allowed time-out time, the transaction will time out. The PCH will discard the cycle and set the DEV\_ERR bit. The time out minimum is 25 ms (800 RTC clocks). The time-out counter inside the PCH will start after the last bit of data is transferred by the PCH and it is waiting for a response.

The 25 ms timeout counter will not count under the following conditions:

1. BYTE\_DONE\_STATUS bit (SMBus I/O Offset 00h, bit 7) is set
2. The SECOND\_TO\_STS bit (TCO I/O Offset 06h, bit 1) is not set (this indicates that the system has not locked up).

## 5.22.6 Interrupts / SMI#

The PCH SMBus controller uses PIRQB# as its interrupt pin. However, the system can alternatively be set up to generate SMI# instead of an interrupt, by setting the SMBUS\_SMI\_EN bit (Device 31:Function 0: Offset 40h: bit 1).

Table 5-53 and Table 5-54 specify how the various enable bits in the SMBus function control the generation of the interrupt, Host and Slave SMI, and Wake internal signals. The rows in the tables are additive, which means that if more than one row is true for a particular scenario then the Results for all of the activated rows will occur.

**Table 5-52. Enable for SMBALERT#**

Event	INTREN (Host Control I/O Register, Offset 02h, Bit 0)	SMB_SMI_EN (Host Configuration Register, D31:F3:Offset 40h, Bit 1)	SMBALERT_DIS (Slave Command I/O Register, Offset 11h, Bit 2)	Result
SMBALERT# asserted low (always reported in Host Status Register, Bit 5)	X	X	X	Wake generated
	X	1	0	Slave SMI# generated (SMBUS_SMI_STS)
	1	0	0	Interrupt generated



**Table 5-53. Enables for SMBus Slave Write and SMBus Host Events**

Event	INTREN (Host Control I/O Register, Offset 02h, Bit 0)	SMB_SMI_EN (Host Configuration Register, D31:F3:Offset 40h, Bit1)	Event
Slave Write to Wake/ SMI# Command	X	X	Wake generated when asleep. Slave SMI# generated when awake (SMBUS_SMI_STS).
Slave Write to SMLINK_SLAVE_SMI Command	X	X	Slave SMI# generated when in the S0 state (SMBUS_SMI_STS)
Any combination of Host Status Register [4: 1] asserted	0	X	None
	1	0	Interrupt generated
	1	1	Host SMI# generated

**Table 5-54. Enables for the Host Notify Command**

HOST_NOTIFY_INTREN (Slave Control I/O Register, Offset 11h, Bit 0)	SMB_SMI_EN (Host Config Register, D31:F3:Off40h, Bit 1)	HOST_NOTIFY_WKEN (Slave Control I/O Register, Offset 11h, Bit 1)	Result
0	X	0	None
X	X	1	Wake generated
1	0	X	Interrupt generated
1	1	X	Slave SMI# generated (SMBUS_SMI_STS)

### 5.22.7 SMBALERT#

SMBALERT# is multiplexed with GPIO[11]. When enable and the signal is asserted, The PCH can generate an interrupt, an SMI#, or a wake event from S1–S5.

### 5.22.8 SMBus CRC Generation and Checking

If the AAC bit is set in the Auxiliary Control register, the PCH automatically calculates and drives CRC at the end of the transmitted packet for write cycles, and will check the CRC for read cycles. It will not transmit the contents of the PEC register for CRC. The PEC bit must not be set in the Host Control register if this bit is set, or unspecified behavior will result.

If the read cycle results in a CRC error, the DEV\_ERR bit and the CRCE bit in the Auxiliary Status register at offset 0Ch will be set.



### 5.22.9 SMBus Slave Interface

The PCH's SMBus Slave interface is accessed using the SMBus. The SMBus slave logic will not generate or handle receiving the PEC byte and will only act as a Legacy Alerting Protocol device. The slave interface allows the PCH to decode cycles, and allows an external microcontroller to perform specific actions. Key features and capabilities include:

- Supports decode of three types of messages: Byte Write, Byte Read, and Host Notify.
- Receive Slave Address register: This is the address that the PCH decodes. A default value is provided so that the slave interface can be used without the processor having to program this register.
- Receive Slave Data register in the SMBus I/O space that includes the data written by the external microcontroller.
- Registers that the external microcontroller can read to get the state of the PCH.
- Status bits to indicate that the SMBus slave logic caused an interrupt or SMI# due to the reception of a message that matched the slave address.
  - Bit 0 of the Slave Status Register for the Host Notify command
  - Bit 16 of the Intel SMI Status Register [Section 13.8.3.8](#) for all others

**Note:** The external microcontroller should not attempt to access the PCH's SMBus slave logic until either:

- 800 milliseconds after both: RTCRST# is high and RSMRST# is high, OR
- The PLTRST# de-asserts

If a master leaves the clock and data bits of the SMBus interface at 1 for 50  $\mu$ s or more in the middle of a cycle, the PCH slave logic's behavior is undefined. This is interpreted as an unexpected idle and should be avoided when performing management activities to the slave logic.

**Note:** When an external microcontroller accesses the SMBus Slave Interface over the SMBus a translation in the address is needed to accommodate the least significant bit used for read/write control. For example, if the PCH slave address (RCV\_SLVA) is left at 44h (default), the external micro controller would use an address of 88h/89h (write/read).



### 5.22.9.1 Format of Slave Write Cycle

The external master performs Byte Write commands to the PCH SMBus Slave I/F. The “Command” field (bits 11:18) indicate which register is being accessed. The Data field (bits 20:27) indicate the value that should be written to that register.

Table 5-55 has the values associated with the registers.

**Table 5-55. Slave Write Registers**

Register	Function
0	Command Register. See Table 5-56 below for legal values written to this register.
1–3	Reserved
4	Data Message Byte 0
5	Data Message Byte 1
6–7	Reserved
8	Reserved
9–FFh	Reserved

**Note:** The external microcontroller is responsible to make sure that it does not update the contents of the data byte registers until they have been read by the system processor. The PCH overwrites the old value with any new value received. A race condition is possible where the new value is being written to the register just at the time it is being read. PCH will not attempt to cover this race condition (that is, unpredictable results in this case).

**Table 5-56. Command Types**

Command Type	Description
0	Reserved
1	<b>WAKE/SMI#.</b> This command wakes the system if it is not already awake. If system is already awake, an SMI# is generated. <b>Note:</b> The SMB_WAK_STS bit will be set by this command, even if the system is already awake. The Intel SMI handler should then clear this bit.
2	<b>Unconditional Powerdown.</b> This command sets the PWRBTNOR_STS bit, and has the same effect as the Powerbutton Override occurring.
3	<b>HARD RESET WITHOUT CYCLING:</b> This command causes a hard reset of the system (does not include cycling of the power supply). This is equivalent to a write to the CF9h register with bits 2:1 set to 1, but bit 3 set to 0.
4	<b>HARD RESET SYSTEM.</b> This command causes a hard reset of the system (including cycling of the power supply). This is equivalent to a write to the CF9h register with bits 3:1 set to 1.
5	<b>Disable the TCO Messages.</b> This command will disable the PCH from sending Heartbeat and Event messages (as described in Section 5.15). Once this command has been executed, Heartbeat and Event message reporting can only be re-enabled by assertion and deassertion of the RSMRST# signal.
6	<b>WD RELOAD:</b> Reload watchdog timer.
7	Reserved
8	<b>SMLINK_SLV_SMI.</b> When PCH detects this command type while in the S0 state, it sets the SMLINK_SLV_SMI_STS bit. This command should only be used if the system is in an S0 state. If the message is received during S1–S5 states, the PCH acknowledges it, but the SMLINK_SLV_SMI_STS bit does not get set. <b>Note:</b> It is possible that the system transitions out of the S0 state at the same time that the SMLINK_SLV_SMI command is received. In this case, the SMLINK_SLV_SMI_STS bit may get set but not serviced before the system goes to sleep. Once the system returns to S0, the Intel SMI associated with this bit would then be generated. Software must be able to handle this scenario.
9-FFh	Reserved.



### 5.22.9.2 Format of Read Command

The external master performs Byte Read commands to the PCH SMBus Slave interface. The “Command” field (bits 18:11) indicate which register is being accessed. The Data field (bits 30:37) contain the value that should be read from that register.

**Table 5-57. Slave Read Cycle Format**

Bit	Description	Driven by	Comment
1	Start	External Microcontroller	
2-8	Slave Address - 7 bits	External Microcontroller	Must match value in Receive Slave Address register
9	Write	External Microcontroller	Always 0
10	ACK	PCH	
11-18	Command code – 8 bits	External Microcontroller	Indicates which register is being accessed. See <a href="#">Table 5-58</a> below for list of implemented registers.
19	ACK	PCH	
20	Repeated Start	External Microcontroller	
21-27	Slave Address - 7 bits	External Microcontroller	Must match value in Receive Slave Address register
28	Read	External Microcontroller	Always 1
29	ACK	PCH	
30-37	Data Byte	PCH	Value depends on register being accessed. <a href="#">Table 5-58</a> below for list of implemented registers.
38	NOT ACK	External Microcontroller	
39	Stop	External Microcontroller	

**Table 5-58. Data Values for Slave Read Registers (Sheet 1 of 2)**

Register	Bits	Description
0	7:0	Reserved for capabilities indication. Should always return 00h. Future chips may return another value to indicate different capabilities.
1	2:0	System Power State 000 = S0 001 = S1 010 = Reserved 011 = S3 100 = S4 101 = S5 110 = Reserved 111 = Reserved
	7:3	Reserved
2	3:0	Reserved
	7:4	Reserved
3	5:0	<b>Watchdog Timer current value</b> Note that Watchdog Timer has 10 bits, but this field is only 6 bits. If the current value is greater than 3Fh, PCH will always report 3Fh in this field.
	7:6	Reserved



**Table 5-58. Data Values for Slave Read Registers (Sheet 2 of 2)**

Register	Bits	Description
4	0	1 = The <b>Intruder Detect</b> (INTRD_DET) bit is set. This indicates that the system cover has probably been opened.
	1	1 = <b>BTI Temperature Event</b> occurred. This bit will be set if the PCH's THRM# input signal is active. Else this bit will read "0."
	2	<b>DOA Processor Status</b> . This bit will be 1 to indicate that the processor is dead
	3	1 = <b>SECOND_TO_STS</b> bit set. This bit will be set after the second time-out (SECOND_TO_STS bit) of the Watchdog Timer occurs.
	6:4	Reserved. Will always be 0, but software should ignore.
	7	Reflects the value of the GPIO[11]/SMBALERT# pin (and is dependent upon the value of the GPI_INV[11] bit. If the GPI_INV[11] bit is 1, then the value in this bit equals the level of the GPI[11]/SMBALERT# pin (high = 1, low = 0). If the GPI_INV[11] bit is 0, then the value of this bit will equal the inverse of the level of the GPIO[11]/SMBALERT# pin (high = 0, low = 1).
5	0	<b>FWH bad bit</b> . This bit will be 1 to indicate that the FWH read returned FFh, which indicates that it is probably blank.
	1	Reserved
	2	<b>SYS_PWROK Power Failure Status</b> : This bit will be 1 if the SYSPWR_FLR bit in the GEN_PMCON_2 register is set.
	3	<b>INIT3_3V# due to receiving Shutdown message</b> : This event is visible from the reception of the shutdown message until a platform reset is done if the Shutdown Policy Select bit (SPS) is configured to drive INIT3_3V#. When the SPS bit is configured to generate PLTRST# based on shutdown, this register bit will always return 0. Events on signal will not create a event message
	4	Reserved
	5	<b>POWER_OK_BAD</b> : Indicates the failure core power well ramp during boot/resume. This bit will be active if the SLP_S3# pin is de-asserted and PCH_PWROK pin is not asserted.
	6	<b>Thermal Trip</b> : This bit will shadow the state of processor Thermal Trip status bit (CTS) (16.2.1.2, GEN_PMCON_2, bit 3). Events on signal will not create a event message
	7	Reserved: Default value is "X" <b>Note:</b> Software should not expect a consistent value when this bit is read through SMBUS/SMLink.
6	7:0	Contents of the Message 1 register. Refer to <a href="#">Section 13.9.8</a> for the description of this register.
7	7:0	Contents of the Message 2 register. Refer to <a href="#">Section 13.9.8</a> for the description of this register.
8	7:0	Contents of the TCO_WDCNT register. Refer to <a href="#">Section 13.9.9</a> for the description of this register.
9	7:0	Seconds of the RTC
A	7:0	Minutes of the RTC
B	7:0	Hours of the RTC
C	7:0	"Day of Week" of the RTC
D	7:0	"Day of Month" of the RTC
E	7:0	Month of the RTC
F	7:0	Year of the RTC
10h–FFh	7:0	Reserved



## Behavioral Notes

According to SMBus protocol, Read and Write messages always begin with a Start bit – Address– Write bit sequence. When the PCH detects that the address matches the value in the Receive Slave Address register, it will assume that the protocol is always followed and ignore the Write bit (bit 9) and signal an Acknowledge during bit 10. In other words, if a Start –Address–Read occurs (which is illegal for SMBus Read or Write protocol), and the address matches the PCH's Slave Address, the PCH will still grab the cycle.

Also according to SMBus protocol, a Read cycle contains a Repeated Start–Address–Read sequence beginning at bit 20. Once again, if the Address matches the PCH's Receive Slave Address, it will assume that the protocol is followed, ignore bit 28, and proceed with the Slave Read cycle.

**Note:** An external microcontroller must not attempt to access the PCH's SMBus Slave logic until at least 1 second after both RTCRST# and RSMRST# are de-asserted (high).

### 5.22.9.3 Slave Read of RTC Time Bytes

The PCH SMBus slave interface allows external SMBus master to read the internal RTC's time byte registers.

The RTC time bytes are internally latched by the PCH's hardware whenever RTC time is not changing and SMBus is idle. This ensures that the time byte delivered to the slave read is always valid and it does not change when the read is still in progress on the bus. The RTC time will change whenever hardware update is in progress, or there is a software write to the RTC time bytes.

The PCH SMBus slave interface only supports Byte Read operation. The external SMBus master will read the RTC time bytes one after another. It is software's responsibility to check and manage the possible time rollover when subsequent time bytes are read.

For example, assuming the RTC time is 11 hours: 59 minutes: 59 seconds. When the external SMBus master reads the hour as 11, then proceeds to read the minute, it is possible that the rollover happens between the reads and the minute is read as 0. This results in 11 hours: 0 minute instead of the correct time of 12 hours: 0 minutes. Unless it is certain that rollover will not occur, software is required to detect the possible time rollover by reading multiple times such that the read time bytes can be adjusted accordingly if needed.

### 5.22.9.4 Format of Host Notify Command

The PCH tracks and responds to the standard Host Notify command as specified in the *System Management Bus (SMBus) Specification, Version 2.0*. The host address for this command is fixed to 0001000b. If the PCH already has data for a previously-received host notify command which has not been serviced yet by the host software (as indicated by the HOST\_NOTIFY\_STS bit), then it will NACK following the host address byte of the protocol. This allows the host to communicate non-acceptance to the master and retain the host notify address and data values for the previous cycle until host software completely services the interrupt.

**Note:** Host software must always clear the HOST\_NOTIFY\_STS bit after completing any necessary reads of the address and data registers.

Table 5-59 shows the Host Notify format.



Table 5-59. Host Notify Format

Bit	Description	Driven By	Comment
1	Start	External Master	
8:2	SMB Host Address — 7 bits	External Master	Always 0001_000
9	Write	External Master	Always 0
10	ACK (or NACK)	PCH	PCH NACKs if HOST_NOTIFY_STS is 1
17:11	Device Address — 7 bits	External Master	Indicates the address of the master; loaded into the Notify Device Address Register
18	Unused — Always 0	External Master	7-bit-only address; this bit is inserted to complete the byte
19	ACK	PCH	
27:20	Data Byte Low — 8 bits	External Master	Loaded into the Notify Data Low Byte Register
28	ACK	PCH	
36:29	Data Byte High — 8 bits	External Master	Loaded into the Notify Data High Byte Register
37	ACK	PCH	
38	Stop	External Master	

## 5.23 Thermal Management

### 5.23.1 Thermal Sensor

The PCH incorporates one on-die Digital thermal sensor (DTS) for thermal management. The thermal sensor can provide PCH temperature information to an EC or SIO device that can be used to determine how to control the fans.

This thermal sensor is located near the DMI interface. The on-die thermal sensor is placed as close as possible to the hottest on-die location to reduce thermal gradients and to reduce the error on the sensor trip thresholds. The thermal Sensor trip points may be programmed to generate various interrupts including SCI, Intel SMI, PCI and other General Purpose events.

#### 5.23.1.1 Internal Thermal Sensor Operation

The internal thermal sensor reports four trip points: Aux2, Aux, Hot and Catastrophic trip points in the order of increasing temperature.

##### Aux, Aux2 Temperature Trip Points

These trip points may be set dynamically if desired and provides an interrupt to ACPI (or other software) when it is crossed in either direction. These auxiliary temperature trip points do not automatically cause any hardware throttling but may be used by software to trigger interrupts. This trip point is set below the Hot temperature trip point and responses are separately programmable from the hot temperature settings, in order to provide incrementally more aggressive actions. Aux and Aux2 trip points are fully Software programmable during system run-time. Aux2 trip point is set below the Aux temperature trip point.



### Hot Temperature Trip Point

This trip point may be set dynamically if desired and provides an interrupt to ACPI (or other software) when it is crossed in either direction. Software could optionally set this as an Interrupt when the temperature exceeds this level setting. Hot trip does not provide any default hardware based thermal throttling, and is available only as a customer configurable interrupt when  $T_{j,max}$  has been reached.

### Catastrophic Trip Point

This trip point is set at the temperature at which the PCH must be shut down immediately without any software support. The catastrophic trip point must correspond to a temperature ensured to be functional in order for the interrupt generation and Hardware response. Hardware response using THERMTRIP# would be an unconditional transition to S5. The catastrophic transition to the S5 state does not enforce a minimum time in the S5 state. It is assumed that the S5 residence and the reboot sequence cools down the system. If the catastrophic condition remains when the catastrophic power down enable bit is set by BIOS, then the system will re-enter S5.

### Thermometer Mode

The thermometer is implemented using a counter that starts at 0 and increments during each sample point until the comparator indicates the temperature is above the current value. The value of the counter is loaded into a read-only register (Thermal Sensor Thermometer Read) when the comparator first trips.

#### 5.23.1.1.1 Recommended Programming for Available Trip Points

There may be a  $\pm 2^{\circ}\text{C}$  offset due to thermal gradient between the hot-spot and the location of the thermal sensor. Trip points should be programmed to account for this temperature offset between the hot-spot  $T_{j,max}$  and the thermal sensor.

**Aux Trip Points** should be programmed for software and firmware control using interrupts.

**Hot Trip Point** should be set to throttle at  $108^{\circ}\text{C}$  ( $T_{j,max}$ ) due to DTS trim accuracy adjustments. Hot trip points should also be programmed for a software response.

**Catastrophic Trip Point** should be set to halt operation to avoid maximum  $T_j$  of about  $120^{\circ}\text{C}$ .

**Note:** Crossing a trip point in either direction may generate several types of interrupts. Each trip point has a register that can be programmed to select the type of interrupt to be generated. Crossing a trip point is implemented as edge detection on each trip point to generate the interrupts.

#### 5.23.1.1.2 Thermal Sensor Accuracy ( $T_{accuracy}$ )

$T_{accuracy}$  for PCH is  $\pm 5^{\circ}\text{C}$  in the temperature range  $90^{\circ}\text{C}$  to  $120^{\circ}\text{C}$ .  $T_{accuracy}$  is  $\pm 10^{\circ}\text{C}$  for temperatures from  $45^{\circ}\text{C}$  -  $90^{\circ}\text{C}$ . PCH may not operate above  $+108^{\circ}\text{C}$ . This value is based on product characterization and is not ensured by manufacturing test.

Software has the ability to program the  $T_{cat}$ ,  $T_{hot}$ , and  $T_{aux}$  trip points, but these trip points should be selected with consideration for the thermal sensor accuracy and the quality of the platform thermal solution. Overly conservative (unnecessarily low) temperature settings may unnecessarily degrade performance due to frequent throttling, while overly aggressive (dangerously high) temperature settings may fail to protect the part against permanent thermal damage.



## 5.23.2 Thermal Reporting Over System Management Link 1 Interface (SMLink1)

SMLink1 interface in the PCH is the SMBus link to an optional external controller. A SMBus protocol is defined on the PCH to allow compatible devices such as Embedded Controller (EC) or SIO to obtain system thermal data from sensors integrated into components on the system using the SMLink1 interface. The sensors that can be monitored using the SMLink1 include those in the processor, PCH, and DIMMs with sensors implemented. This solution allows an external device or controller to use the system thermal data for system thermal management.

**Note:** To enable Thermal Reporting, the Thermal Data Reporting enable and processor/PCH/DIMM temperature read enables have to be set in the Thermal Reporting Control (TRC) Register (See [Section 23.2](#) for details on Register)

There are 2 uses for the PCH's thermal reporting capability:

1. To provide system thermal data to an external controller. The controller can manage the fans and other cooling elements based on this data. In addition, the PCH can be programmed by setting appropriate bits in the Alert Enable (AE) Register (See [Section 23.2](#) for details on this register) to alert the controller when a device has gone outside of its temperature limits. The alert causes the assertion of the PCH's TEMP\_ALERT# (SATA5GP/GPIO49/TEMP\_ALERT#) signal. See [Section 5.23.2.6](#) for more details.
2. To provide an interface between the external controller and host software. This software interface has no direct affect on the PCH's thermal collection. It is strictly a software interface to pass information or data.

The PCH responds to thermal requests only when the system is in S0 or S1. Once the PCH has been programmed, it will start responding to a request while the system is in S0 or S1.

To implement this thermal reporting capability, the platform is required to have appropriate Intel ME firmware, BIOS support, and compatible devices that support the SMBus protocol.

### 5.23.2.1 Supported Addresses

The PCH supports 2 addresses: I<sup>2</sup>C Address for writes and Block Read Address for reads. These addresses need to be distinct.

#### 5.23.2.1.1 I<sup>2</sup>C\* Address

This address is used for writes to the PCH.

- The address is set by soft straps which are values stored in SPI flash and are defined by the OEM. The address can be set to any value the platform requires.
- This address supports all the writes listed in [Table 5-60](#) below.
- SMBus reads by the external controller to this address are not allowed and result in indeterminate behavior.



### 5.23.2.1.2 Block Read Address

This address is used for reads from the PCH.

- The address is set by soft straps or BIOS. It can be set to any value the platform requires.
- This address only supports SMBus Block Read command and not Byte or Word Read.
- The Block Read command is supported as defined in the SMBus 2.0 specification, with the command being 40h, and the byte count being provided by the PCH following the block read format in the SMBus spec.
- Writes are not allowed to this address, and result in indeterminate behavior.
- Packet Error Code (PEC) may be enabled or not, which is set up by BIOS.

### 5.23.2.2 I<sup>2</sup>C Write Commands to the Intel<sup>®</sup> Management Engine

Table 5-60 lists the write commands supported by the Intel ME.

All bits in the write commands must be written to the PCH or the operation will be aborted. For example, for 6-bytes write commands, all 48 bits must be written or the operation will be aborted.

The command format follows the Block Write format of the SMBus specification.

**Table 5-60. I<sup>2</sup>C Write Commands to the Intel<sup>®</sup> Management Engine**

Transaction	Slave Addr	Data Byte0 (Commnd)	Data Byte 1 (Byte Count)	Data Byte 2	Data Byte 3	Data Byte 4	Data Byte 5	Data Byte 6	Data Byte 7
Write Processor Temp Limits	I <sup>2</sup> C	42h	4h	Lower Limit [15:8]	Lower Limit [7:0]	Upper Limit [15:8]	Upper Limit [7:0]		
Write PCH Temp Limits	I <sup>2</sup> C	44h	2h	Lower Limit [7:0]	Upper Limit [7:0]				
Write DIMM Temp Limits	I <sup>2</sup> C	45h	2h	Lower Limit [7:0]	Upper Limit [7:0]				



### 5.23.2.3 Block Read Command

The external controller may read thermal information from the PCH using the SMBus Block Read Command. Byte-read and Word-read SMBus commands are not supported. Note that the reads use a different address than the writes.

The command format follows the Block Read format of the SMBus spec.

The PCH and external controller are set up by BIOS with the length of the read that is supported by the platform. The device must always do reads of the lengths set up by BIOS.

The PCH supports any one of the following lengths: 2, 4, 5, 9, 10, 14 or 20 bytes. The data always comes in the order described in [Table 5-61](#), where 0 is the first byte received in time on the SMBus.

**Table 5-61. Block Read Command - Byte Definition**

Byte	Description
Byte 0	Processor Package temperature, in absolute degrees Celsius (C) It is a single byte for the highest temperature between the 2 components. This is not relative to some max or limit, but is the maximum in absolute degrees. If the processor temperature collection has errors, this field will be FFh. Read value represents bits [7:0] of PTV (Processor Temperature Value)
Byte 1	The PCH temp in degrees C. FFh indicates error condition. Read value represents bits [7:0] of ITV (Internal Temperature Values) Register described in <a href="#">Section 23.2</a> . <b>Note:</b> Requires TRC (Thermal Reporting Control) Register bit [5] to be enabled. Please see <a href="#">Section 23.2</a> .
Byte 4:2	Reserved
Byte 5	Thermal Sensor (TS) on DIMM 0 If DIMM not populated, or if there is no TS on DIMM, value will be 0h Read value represents bits[7:0] of DTV (DIMM Temperature Values) Register described in <a href="#">Section 23.2</a> . <b>Note:</b> Requires TRC (Thermal Reporting Control) Register bit [0] to be enabled. Please see <a href="#">Section 23.2</a> .
Byte 6	Thermal Sensor (TS) on DIMM 1 If DIMM not populated, or if there is no TS on DIMM, value will be 0h Read value represents bits[15:8] of DTV (DIMM Temperature Values) Register described in <a href="#">Section 23.2</a> . <b>Note:</b> Requires TRC (Thermal Reporting Control) Register bit [1] to be enabled. Please see <a href="#">Section 23.2</a> .
Byte 7	Thermal Sensor (TS) on DIMM 2 If DIMM not populated, or if there is no TS on DIMM, value will be 0h Read value represents bits[23:16] of DTV (DIMM Temperature Values) Register described in <a href="#">Section 23.2</a> . <b>Note:</b> Requires TRC (Thermal Reporting Control) Register bit [2] to be enabled. Please see <a href="#">Section 23.2</a> .
Byte 8	Thermal Sensor (TS) on DIMM 3 If DIMM not populated, or if there is no TS on DIMM, value will be 0h Read value represents bits[31:24] of DTV (DIMM Temperature Values) Register described in <a href="#">Section 23.2</a> . Note: Requires TRC (Thermal Reporting Control) Register bit [3] to be enabled.
Byte 9	Sequence number. Can be used to check if PCH's FW or HW is hung. See <a href="#">Section 5.23.2.9</a> for usage. This byte is updated every time the collected data is updated <b>Note:</b> Read value represents bits[23:16] of ITV (Internal Temperature Values) Register described in <a href="#">Section 23.2</a> .
Byte 19:10	Reserved



A 2-byte read would provide both the PCH and processor temperature. A device that wants DIMM information would read 9 bytes.

#### 5.23.2.4 Read Data Format

For each of the data fields an ERROR Code is listed below. This code indicates that the PCH failed in its access to the device. This would be for the case where the read returned no data, or some illegal value. In general that would mean the device is broken. The EC can treat the device that failed the read as broken or with some fail-safe mechanism.

##### 5.23.2.4.1 PCH and DIMM Temperature

The temperature readings for the PCH, DIMM are 8-bit unsigned values from 0–255. The minimum granularity supported by the internal thermal sensor is 1°C. Thus, there are no fractional values for the PCH or DIMM temperatures.

Note the sensors used within the components do not support values below 0 degrees, so this field is treated as 8 bits (0-255) absolute and not 2's complement (-128 to 127).

Devices that are not present or that are disabled will be set to 0h. Devices that have a failed reading (that is, the read from the device did not return any legal value) will be set to FFh. A failed reading means that the attempt to read that device returned a failure. The failure could have been from a bus failure or that the device itself had an internal failure. For instance, a system may only have one DIMM and it would report only that one value, and the values for the other DIMM's would all be 00h.

#### 5.23.2.5 Thermal Data Update Rate

The temperature values are updated every 200 ms in the PCH, so reading more often than that simply returns the same data multiple times. Also, the data may be up to 200 ms old if the external controller reads the data right before the next update window.

#### 5.23.2.6 Temperature Comparator and Alert

The PCH has the ability to alert the external controller when temperatures are out of range. This is done using the PCH's TEMP\_ALERT# signal. The alert is a simple comparator. If any device's temperature is outside the limit range for that device, then the signal is asserted (electrical low). Note that this alert does not use the SML1ALERT#.

The PCH supports 3 ranges:

1. Processor Package range - upper and lower limit (8 bits each, in degrees C).
2. PCH range - upper and lower limit (8 bits each, in degrees C) for PCH temperature.
3. DIMM range - upper and lower limit (8 bits each, in degrees C), applies to all DIMM's (up to 4 supported) that are enabled. Disabled (unpopulated) DIMMs do not participate in the thermal compares.

The comparator checks if the device is within the specified range, including the limits. For example, a device that is at 100 degrees when the upper limit is 100 will not trigger the alert. Likewise, a device that is at 70 degrees when the lower limit is 70 will not trigger the alert.

The compares are done only on devices that have been enabled by BIOS for checking. Since BIOS knows how many DIMM's and processors are in the system, it enables the checking only for those devices that are physically present.



The compares are done in firmware, so all the compares are executed in one software loop and at the end, if there is any out of bound temperature, the PCH's TEMP\_ALERT# signal is asserted.

When the external controller sees the TEMP\_ALERT# signal low, it knows some device is out of range. It can read the temperatures and then change the limits for the devices. Note that it may take up to 250 ms before the actual writes cause the signal to change state. For instance if the PCH is at 105 degrees and the limit is 100, the alert is triggered. If the controller changes the limits to 110, the TEMP\_ALERT# signal may remain low until the next thermal sampling window (every 200 ms) occurs and only then go high, assuming the PCH was still within its limits.

At boot, the controller can monitor the TEMP\_ALERT# signal state. When BIOS has finished all the initialization and enabled the temperature comparators, the TEMP\_ALERT# signal will be asserted since the default state of the limit registers is 0h; hence, when the PCH first reads temperatures, they will be out of range. This is the positive indication that the external controller may now read thermal information and get valid data. If the TEMP\_ALERT# signal is enabled and not asserted within 30 seconds after PLTRST#, the external controller should assume there is a fatal error and handle accordingly. In general the TEMP\_ALERT# signal will assert within 1-4 seconds, depending on the actual BIOS implementation and flow.

**Note:** The TEMP\_ALERT# assertion is only valid when PLTRST# is deasserted. The controller should mask the state of this signal when PLTRST# is asserted. Since the controller may be powered even when the PCH and the rest of the platform are not, the signal may glitch as power is being asserted, thus the controller should wait until PLTRST# has deasserted before monitoring the signal.

#### 5.23.2.6.1 Special Conditions

The external controller should have a graceful means of handling the following:

1. TEMP\_ALERT# asserts, and the controller reads PCH, but all temperature values are within limits.  
In this case, the controller should assume that by the time the controller could read the data, it had changed and moved back within the limits.
2. External controller writes new values to temperature limits, but TEMP\_ALERT# is still asserted after several hundred msecs. When read, the values are back within limits.  
In this case, the controller should treat this as case where the temperature changed and caused TEMP\_ALERT# assertion, and then changed again to be back within limits.
3. There is the case where the external controller writes an update to the limit register, while the PCH is collecting the thermal information and updating the thermal registers. The limit change will only take affect when the write completes and the Intel ME can process this change. If the Intel ME is already in the process of collecting data and doing the compares, then it will continue to use the old limits during this round of compares, and then use the new limits in the next compare window.
4. Each SMBus write to change the limits is an atomic operation, but is distinct in itself. Therefore the external controller could write PCH limit, and then write DIMM limit. In the middle of those 2 writes, the thermal collecting procedure could be called by the Intel ME, so that the comparisons for the limits are done with the new PCH limits but the old DIMM limits.

**Note:** The limit writes are done when the SMBus write is complete; therefore, the limits are updated atomically with respect to the thermal updates and compares. There is never a case where the compares and the thermal update are interrupted in the middle by the write of new limits. The thermal updates and compares are done as one non-interruptible routine, and then the limit writes would change the limit value outside of that routine.



### 5.23.2.7 BIOS Set Up

In order for the PCH to properly report temperature and enable alerts, the BIOS must configure the PCH at boot or from suspend/resume state by writing the following information to the PCH MMIO space. This information is NOT configurable using the external controller.

- Enables for each of the possible thermal alerts (PCH and DIMM). Note that each DIMM is enabled individually.
- Enables for reading DIMM and PCH temperatures. Note that each can be enabled individually.
- SMBus address to use for each DIMM.

Setting up the temperature calculation equations.

### 5.23.2.8 SMBus Rules

The PCH may NACK an incoming SMBus transaction. In certain cases the PCH will NACK the address, and in other cases it will NACK the command depending on internal conditions (for example, errors, busy conditions). Given that most of the cases are due to internal conditions, the external controller must alias a NACK of the command and a NACK of the address to the same behavior. The controller must not try to make any determination of the reason for the NACK, based on the type of NACK (command vs. address).

The PCH will NACK when it is enabled but busy. The external controller is required to retry up to 3 times when they are NACK'ed to determine if the FW is busy with a data update. When the data values are being updated by the Intel ME, it will force this NACK to occur so that the data is atomically updated to the external controller. In reality if there is a NACK because of the PCH being busy, in almost all cases the next read will succeed since the update internally takes very little time.

The only long delay where there can be a NACK is if the internal Intel ME engine is reset. This is due to some extreme error condition and is therefore rare. In this case the NACK may occur for up to 30 seconds. After that, the external controller must assume that the PCH will never return good data. Even in the best of cases, when this internal reset occurs, it will always be a second or 2 to re-enable responding.

#### 5.23.2.8.1 During Block Read

On the Block Read, the PCH will respect the NACK and Stop indications from the external controller, but will consider this an error case. It will recover from this case and correctly handle the next SMBus request.

The PCH will honor STOP during the block read command and cease providing data. On the next Block Read, the data will start with byte 0 again. However, this is not a recommended usage except for 'emergency cases'. In general the external controller should read the entire length of data that was originally programmed.

#### 5.23.2.8.2 Block Read Special Handling

On the Block Read, the PCH will respect the NACK and Stop indications from the external controller, but will consider this an error case. It will recover from this case and correctly handle the next SMBus request.

The PCH will honor STOP during the block read command and cease providing data. On the next Block Read, the data will start with byte 0 again. However, this is not a recommended usage except for 'emergency cases'. In general the external controller should read the entire length of data that was originally programmed.



### 5.23.2.9 Case for Considerations

Below are some corner cases and some possible actions that the external controller could take.

Note that a 1-byte sequence number is available to the data read by the external controller. Each time the PCH updates the thermal information it will increment the sequence number. The external controller can use this value as an indication that the thermal FW is actually operating. Note that the sequence number will roll over to 00h when it reaches FFh.

1. Power on:

The PCH will not respond to any SMBus activity (on SMLink1 interface) until it has loaded the thermal Firmware (FW), which in general would take 1-4 seconds. During this period the PCH will NACK any SMBus transaction from the external controller.

The load should take 1-4 seconds, but the external controller should design for 30 seconds based on long delays for S4 resume which takes longer than normal power up. This would be an extreme case, but for larger memory footprints and non-optimized recovery times, 30 seconds is a safe number to use for the timeout.

Recover/Failsafe: if PCH has not responded within 30 seconds, the external controller can assume that the system has had a major error and the external controller should ramp the fans to some reasonably high value.

The only recover from this is an internal reset on the PCH, which is not visible to the external controller. Therefore the external controller might choose to poll every 10-60 seconds (some fairly long period) hereafter to see if the PCH's thermal reporting has come alive.

2. PCH's Thermal FW hangs and requires an internal reset which is not visible to the external controller.

The PCH will NACK any SMBus transaction from the external controller. The PCH may not be able to respond for up to 30 seconds while the FW is being reset and reconfigured.

The external controller could choose to poll every 1-10 seconds to see if the thermal FW has been successfully reset and is now providing data.

General recovery for this case is about 1 second, but 30 seconds should be used by the external controller at the timeout.

Recovery/Failsafe: same as in case #1.

3. Fatal PCH error, causes a global reset of all components.

When there is a fatal PCH error, a global reset may occur, and then case #1 applies.

The external controller can observe, if desired, PLTRST# assertion as an indication of this event.

4. PCH thermal FW fails or is hung, but no reset occurs

The sequence number will not be updated, so the external controller knows to go to failsafe after some number of reads (8 or so) return the same sequence number.

The external controller could choose to poll every 1-10 seconds to see if the thermal FW has been successfully reset and working again.

In the absence of other errors, the updates for the sequence number should never be longer than 400 ms, so the number of reads needed to indicate that there is a hang should be at around 2 seconds. But when there is an error, the sequence number may not get updated for seconds. In the case that the external controller sees a NACK from the PCH, then it should restart its sequence counter, or otherwise be aware that the NACK condition needs to be factored into the sequence number usage.

The use of sequence numbers is not required, but is provided as a means to ensure correct PCH FW operation.

5. When PCH updates the Block Read data structure, the external controller gets a NACK during this period.



To ensure atomicity of the SMBus data read with respect to the data itself, when the data buffer is being updated, the PCH will NACK the Block Read transaction.

The update is only a few micro-seconds, so very short in terms of SMBus polling time; therefore, the next read should be successful. The external controller should attempt 3 reads to handle this condition before moving on.

If the Block read has started (that is, the address is ACK'ed) then the entire read will complete successfully, and the PCH will update the data only after the SMBus read has completed.

6. System is going from S0 to S3/4/5. Note that the thermal monitoring FW is fully operational if the system is in S0/S1, so the following only applies to S3/4/5. When the PCH detects the OS request to go to S3/4/5, it will take the SMLink1 controller offline as part of the system preparation. The external controller will see a period where its transactions are getting NACK'ed, and then see SLP\_S3# assert. This period is relatively short (a couple of seconds depending on how long all the devices take to place themselves into the D3 state), and would be far less than the 30 second limit mentioned above.
7. TEMP\_ALERT# - Since there can be an internal reset, the TEMP\_ALERT# may get asserted after the reset. The external controller must accept this assertion and handle it.

#### 5.23.2.9.1 Example Algorithm for Handling Transaction

One algorithm for the transaction handling could be summarized as follows. This is just an example to illustrate the above rules. There could be other algorithms that can achieve the same results.

1. Perform SMBus transaction.
2. If ACK, then continue
3. If NACK
  - a. Try again for 2 more times, in case the PCH is busy updating data.
  - b. If 3 successive transactions receive NACK, then
    - Ramp fans, assuming some general long reset or failure
    - Try every 1-10 seconds to see if SMBus transactions are now working
    - If they start then return to step 1
    - If they continue to fail, then stay in this step and poll, but keep the fans ramped up or implement some other failure recovery mechanism.



## 5.24 Intel® High Definition Audio (Intel® HD Audio) Overview (D27:F0)

The PCH's Intel® High Definition Audio (Intel® HD Audio) controller communicates with the external codec(s) over the Intel High Definition Audio serial link. The controller consists of a set of DMA engines that are used to move samples of digitally encoded data between system memory and an external codec(s). The PCH implements four output DMA engines and 4 input DMA engines. The output DMA engines move digital data from system memory to a D-A converter in a codec. PCH implements a single Serial Data Output signal (HDA\_SDOOUT) that is connected to all external codecs. The input DMA engines move digital data from the A-D converter in the codec to system memory. The PCH implements four Serial Digital Input signals (HDA\_SDI[3:0]) supporting up to four codecs.

Audio software renders outbound and processes inbound data to/from buffers in system memory. The location of individual buffers is described by a Buffer Descriptor List (BDL) that is fetched and processed by the controller. The data in the buffers is arranged in a predefined format. The output DMA engines fetch the digital data from memory and reformat it based on the programmed sample rate, bit/sample and number of channels. The data from the output DMA engines is then combined and serially sent to the external codecs over the Intel High Definition Audio link. The input DMA engines receive data from the codecs over the Intel High Definition Audio link and format the data based on the programmable attributes for that stream. The data is then written to memory in the predefined format for software to process. Each DMA engine moves one stream of data. A single codec can accept or generate multiple streams of data, one for each A-D or D-A converter in the codec. Multiple codecs can accept the same output stream processed by a single DMA engine.

Codec commands and responses are also transported to and from the codecs using DMA engines.

The PCH HD audio controller supports the Function Level Reset (FLR).

## 5.25 PCH Intel® Management Engine Firmware

The PCH offers different firmware options depending on the design (server or workstation) and platform usage models. In all cases, SPI Flash is required to connect to PCH to load the Intel ME FW. Please also see platform specific PDG for detailed HW requirements.

### 5.25.1 Intel® Server Platform Services Firmware

Intel® Server Platform Services FW is for server platforms. It comes in four flavors.

#### 5.25.1.1 Silicon Enabling

This option provides the fundamental Intel ME FW functions required to boot a server design. In addition it provides following functions:

- Power management controller (PMC) patching to provide a way of applying future enhancements or fixes to PMC



### 5.25.1.2 Intel® Intelligent Power Node Manager 2.0

Intel® Intelligent Power Node Manager 2.0 is a platform power reporting and capping technology, which provides an enhanced set of features, as compared to its previous version.

- Intel Intelligent Power Node Manager 2.0 supports multiple power policies for multiple power domains, including thermal policies.
- The enhanced algorithms provide shorter response times, enhanced dynamic range of power control, and reliable and uninterrupted power capping even during OS or BMC failure.
- By using an intelligent algorithm system, system performance is improved for a given power limit.
- Power supply optimization technology reduces cost or improve efficiency of power supplies.
- Server platform services is an accompanying function that provides access to PECI information by the BMC - critical selected information is available for efficient aggregated access by the BMC without losing the access to any other information available in a raw format.

### 5.25.1.3 Manageability Controller (MC) Compliant with Data Center Management Interface (DCMI) Specification

This option provides a building block infrastructure for OEMs to configure and adopt the manageability controller according to their platform design needs without spending development or engineering time for server manageability. MC also provides an ability to interface with external Service Processors for advanced manageability requirements. Hardware features supported:

- Four PWM and Eight TACHS providing maximum of four Thermal zones with two TACHS per zone
- 12 GPIO dedicated for the Manageability Controller for LED and other controls
- Three SMBus Transports, two dedicated and one shared with Host
- SST, PECI and MEI transports
- Either Side-band SMBus Intel LOMs or Integrated MAC to external PHY
- LM75/TMP75 Thermal Sensors
- PMBus for Power Instrumentation and Control

Manageability Features supported:

- 128 Sensors capable to be configurable as I<sup>2</sup>C, PECI, SST, GPIO, PMBus and Virtual Sensors.
- Up to 32 individually configurable actions based on the Sensors such as Fan Speed Control, LED Controls and any other custom build control mechanisms derived from the sensors.
- Piece-wise, Clamped algorithms for Fan Speed Control configurable through PIA.
- All commands of DCMI 1.5 including all DCMI 1.0 features.
- Additional IPMI commands for Chassis, Sensor, Storage, and Transport for Provisioning and Configuration for OEMs.
- IPMB communication to external Server Processors for Platform Events and Alerts.
- Well documented BIOS to MC interaction.
- Both the simple DCMI-compliant power management interface as well as the full Intel Intelligent Power Node Manager 2.0 interface for provisioning and data security.



Security Features:

- Security is provided for manufacturing data, user configuration and provisioning data through encryption using CBC-128 and xRC4.
- RMCP+ authentication and integrity algorithms support includes MD5, SHA1, and SHA-256.
- Capable of providing PSK and RSA certificate verification

#### 5.25.1.4 Combined Intel® Intelligent Power Node Manager 2.0 and Management Controller Compliant with DCMI

A fourth SPS FW option combines both Intel Intelligent Power Node Manager 2.0 and DCMI features.

### 5.25.2 Intel® AMT 7.0 (SRV/WS SKUs Only)

**Intel Active Management Technology** is a set of advanced manageability features developed to meet the evolving demands placed on IT to manage a network infrastructure. Intel AMT reduces the Total Cost of Ownership (TCO) for IT management through features such as asset tracking, remote manageability, and robust policy-based security, resulting in fewer desk-side visits and reduced incident support durations. Intel AMT extends the manageability capability for IT through Out Of Band (OOB), allowing asset information, remote diagnostics, recovery, and contain capabilities to be available on client systems even when they are in a low power, or “off” state, or in situations when the operating system is hung.

In 2005, Intel developed a set of manageability services called Intel Active Management Technology (Intel AMT). To increase features and reduce cost in 2006 Intel integrated the operating environment for AMT to run on all Intel chipsets:

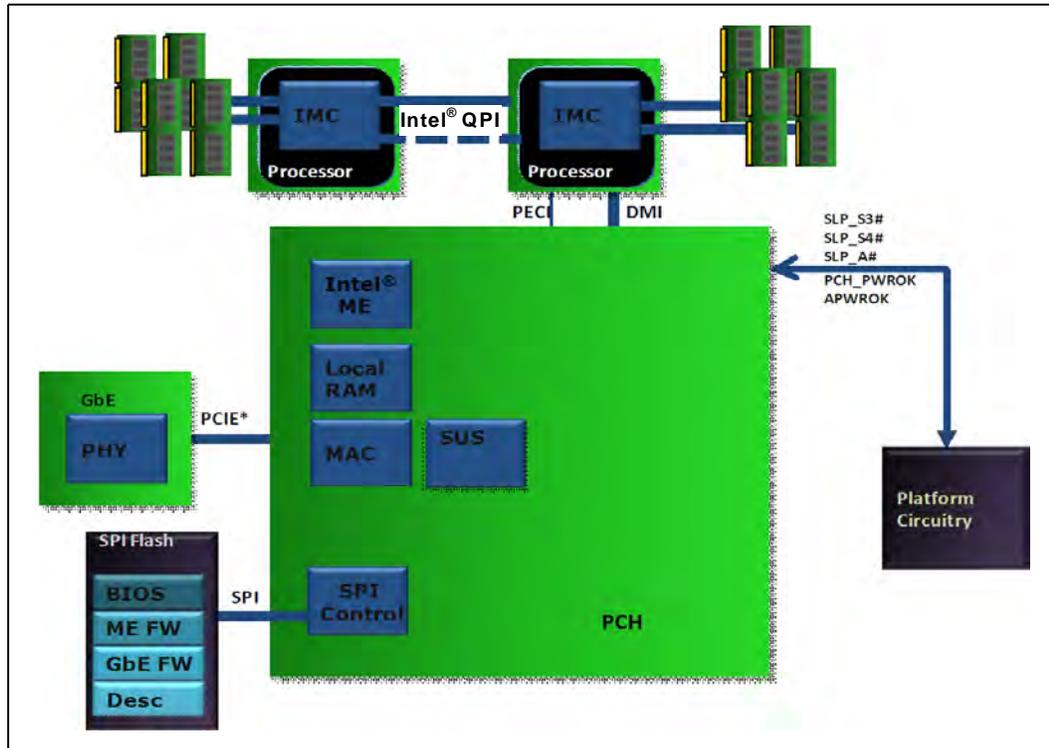
- A microcontroller and support HW was integrated in the MCH (North Bridge)
- Additional support HW resided in ICH (South Bridge)

This embedded operating environment is called the Intel Management Engine (Intel ME). In 2008 Intel integrated an additional microcontroller called the Virtualization Engine (VE). In 2009 with platform repartitioning, Intel ME and VE HW was designed to reside in PCH. Key properties of Intel ME:

- Connectivity
  - Integration into I/O subsystem of PCH
  - Delivers advanced I/O functions
- Security
  - More secure (Intel root of trust) and isolated execution
  - Increased security of flash file system
- Modularity and Partitioning
  - OSV, VMM and SW Independence
  - Respond rapidly to competitive changes
- Power
  - Always On Always Connected
  - Advanced functions in low power S3-S4-S5 operation
  - OS independent PM & thermal heuristics

Intel ME FW provides a variety of services that range from low-level hardware initialization and provisioning to high-level end-user software based IT manageability services. One of Intel ME FW's most established and recognizable features is Intel Active Management Technology.

**Figure 5-30. PCH Intel® Management Engine (Intel® ME) High-Level Block Diagram**



### 5.25.3 Intel® Management Engine Requirements

Intel ME is a platform-level solution that utilizes multiple system components including:

- The Intel ME is the general purpose controller that resides in PCH. It operates in parallel to and is resource-isolated from the host processor.
- The flash device stores Intel ME firmware (FW) code that is executed by the Intel ME for its operations. In M0, the highest power state for Intel ME, this code is loaded from flash into DRAM and cached in secure and isolated SRAM. Code that resides in DRAM is stored in 16 MB of unified memory architecture (UMA) memory taken off the highest order rank in channel 0. PCH controls the flash device through the SPI interface and internal logic.
- In order to interface with DRAM, the Intel ME utilizes the integrated memory controller (IMC) present in the processor. DMI serves as the interface for communication between the IMC and Intel ME. This interfacing occurs in only M0 power state. In the lower Intel ME power state, M3, code is executed exclusively from secure and isolated Intel ME local RAM.
- The LAN controller embedded in PCH as well as Intel Gigabit Platform LAN Connect device are required for Intel AMT network connectivity. (SRV/WS SKUs Only)
- BIOS to provide asset detection and POST diagnostics (BIOS and Intel ME FW can optionally share same flash memory device).
- An ISV software package - such as LANDesk\*, Altiris, or Microsoft SMS\* can be used to take advantage of Intel AMT's platform manageability capabilities. (SRV/WS SKUs Only)



## 5.26 Serial Peripheral Interface (SPI)

The Serial Peripheral Interface (SPI) is a 4-pin interface that provides a lower-cost alternative for system flash versus the Firmware Hub on the LPC bus.

The 4-pin SPI interface consists of clock (CLK), master data out (Master Out Slave In (MOSI)), master data in (Master In Slave Out (MISO)) and an active low chip select (SPI\_CS[1:0]#).

The PCH supports up to two SPI flash devices using two separate Chip Select pins. Each SPI flash device can be up to 16 MB. The PCH SPI interface supports 20 MHz, 33 MHz and 50 MHz SPI devices. A SPI Flash device on with Chip Select 0 with a valid descriptor MUST be attached directly to the PCH.

Communication on the SPI bus is done with a Master – Slave protocol. The Slave is connected to the PCH and is implemented as a tri-state bus.

**Note:** If Boot BIOS Strap = "00" LPC is selected as the location for BIOS. BIOS may still be placed on LPC, but all platforms with PCH requires SPI flash connected directly to the PCH's SPI bus with a valid descriptor connected to Chip Select 0 in order to boot. Refer to [Section 2.26](#) for details of Boot BIOS strap settings.

**Note:** When SPI is selected by the Boot BIOS Destination Strap and a SPI device is detected by the PCH, LPC based BIOS flash is disabled.

### 5.26.1 SPI Supported Feature Overview

SPI Flash on the PCH has two operational modes, descriptor and non-descriptor.

#### 5.26.1.1 Non-Descriptor Mode

Non-Descriptor Mode is not supported as a valid flash descriptor is required for all PCH Platforms.

#### 5.26.1.2 Descriptor Mode

Descriptor Mode is required for all SKUs of PCH. It enables many new features of the chipset:

- Integrated Gigabit Ethernet and Host processor for Gigabit Ethernet Software
- Intel Active Management Technology (SRV/WS SKUs Only)
- Intel ME Firmware
- PCI Express\* root port configuration
- Supports up to two SPI components using two separate chip select pins
  - 1 SPI Flash and 1 user authentication device.
- Hardware enforced security restricting master accesses to different regions
- Chipset Soft Strap regions provides the ability to use Flash NVM as an alternative to hardware pull-up/pull-down resistors for PCH and Processor
- Supports the SPI Fast Read instruction and frequencies of up to 50 MHz
- Support Single Input, Dual Output Fast read
- Uses standardized Flash Instruction Set



### 5.26.1.2.1 SPI Flash Regions

In Descriptor Mode the Flash is divided into five separate regions:

Region	Content
0	Flash Descriptor
1	BIOS
2	Intel ME
3	Gigabit Ethernet
4	Platform Data

Only three masters can access the four regions: Host processor running BIOS code, Integrated Gigabit Ethernet and Host processor running Gigabit Ethernet Software, and Intel Management Engine. The Flash Descriptor and Intel ME region are the only required regions. The Flash Descriptor has to be in Region 0 and Region 0 must be located in the first sector of Device 0 (offset 10).

### Flash Region Sizes

SPI flash space requirements differ by platform and configuration. The Flash Descriptor requires one 4 KB or larger block. GbE requires two 4 KB or larger blocks. The amount of flash space consumed is dependent on the erase granularity of the flash part and the platform requirements for the Intel ME and BIOS regions. The Intel ME region contains firmware to support Intel Active Management Technology, and other Intel ME capabilities.

**Table 5-62. Region Size versus Erase Granularity of Flash Components**

Region	Size with 4 KB Blocks	Size with 8 KB Blocks	Size with 64 KB Blocks
Descriptor	4 KB	8 KB	64 KB
GbE	8 KB	16 KB	128 KB
BIOS	Varies by Platform	Varies by Platform	Varies by Platform
ME	Varies by Platform	Varies by Platform	Varies by Platform

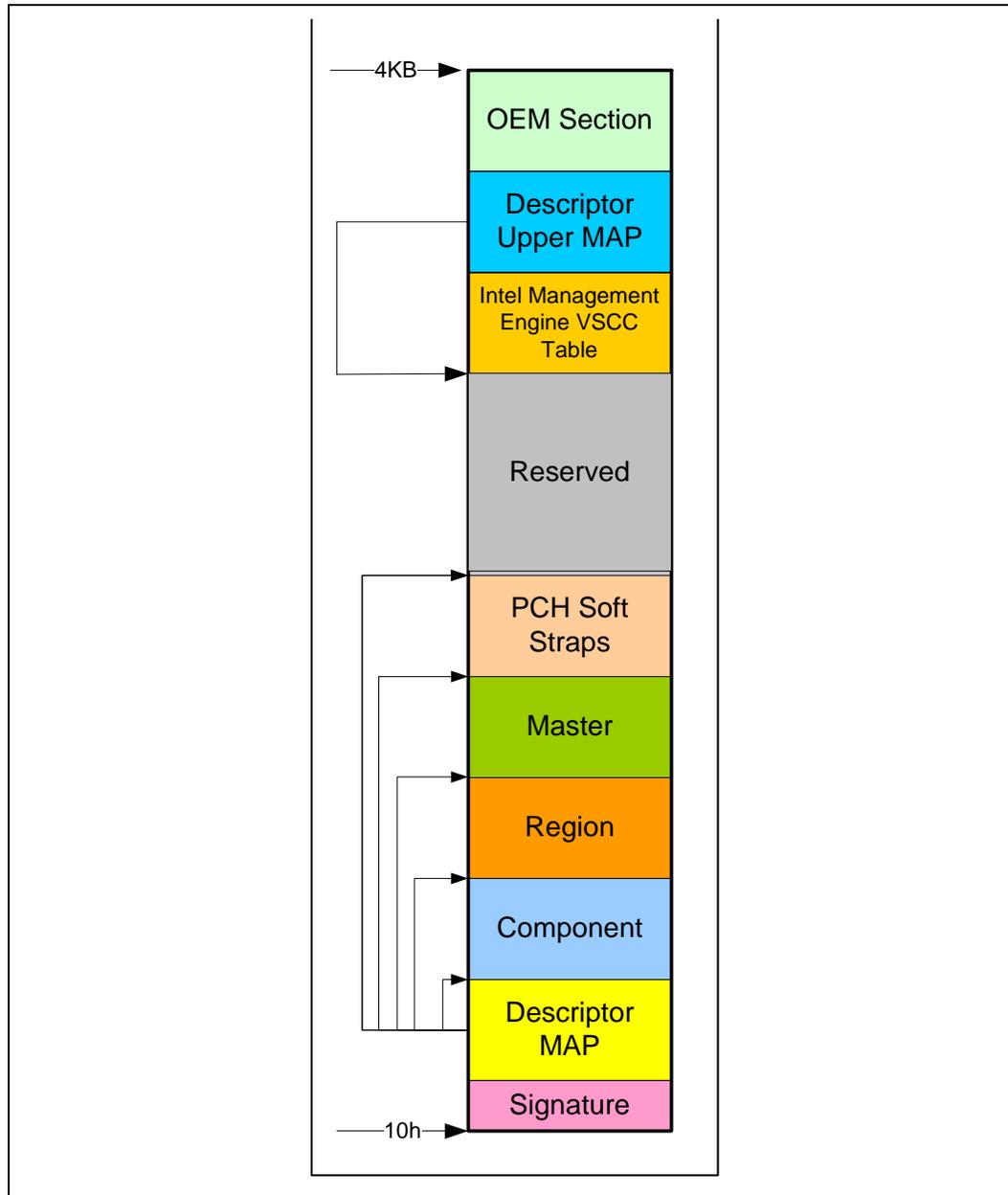
## 5.26.2 Flash Descriptor

The maximum size of the Flash Descriptor is 4 KB. If the block/sector size of the SPI flash device is greater than 4 KB, the flash descriptor will only use the first 4 KB of the first block. The flash descriptor requires its own block at the bottom of memory (00h). The information stored in the Flash Descriptor can only be written during the manufacturing process as its read/write permissions must be set to Read only when the computer leaves the manufacturing floor.

The Flash Descriptor is made up of eleven sections (see [Figure 5-31](#)).



Figure 5-31. Flash Descriptor Sections



1. The Flash signature selects Descriptor Mode as well as verifies if the flash is programmed and functioning. The data at the bottom of the flash (offset 10h) must be 0FF0A55Ah in order to be in Descriptor mode.
2. The Descriptor map has pointers to the other five descriptor sections as well as the size of each.
3. The component section has information about the SPI flash in the system including: the number of components, density of each, illegal instructions (such as chip erase), and frequencies for read, fast read and write/erase instructions.
4. The Region section points to the three other regions as well as the size of each region.



5. The master region contains the security settings for the flash, granting read/write permissions for each region and identifying each master by a requestor ID. See [Section 5.26.2.1](#) for more information.
- 6 & 7. The Processor and PCH chipset soft strap sections contain Processor and PCH configurable parameters.
8. The Reserved region between the top of the Processor strap section and the bottom of the OEM Section is reserved for future chipset usages.
9. The Descriptor Upper MAP determines the length and base address of the Intel ME VSCC Table.
10. The Intel ME VSCC Table holds the JEDEC ID and the VSCC information of the entire SPI Flash supported by the NVM image.
11. OEM Section is 256 Bytes reserved at the top of the Flash Descriptor for use by OEM.

### 5.26.2.1 Descriptor Master Region

The master region defines read and write access setting for each region of the SPI device. The master region recognizes three masters: BIOS, Gigabit Ethernet, and Intel ME. Each master is only allowed to do direct reads of its primary regions.

**Table 5-63. Region Access Control Table**

Master Read/Write Access			
Region	Processor and BIOS	Intel® ME	GbE Controller
<b>Descriptor</b>	N/A	N/A	N/A
<b>BIOS</b>	Processor and BIOS can always read from and write to BIOS Region	Read / Write	Read / Write
<b>Intel ME</b>	Read / Write	Intel ME can always read from and write to Intel ME Region	Read / Write
<b>Gigabit Ethernet</b>	Read / Write	Read / Write	GbE software can always read from and write to GbE region
<b>Platform Data Region</b>	N/A	N/A	N/A

### 5.26.3 Flash Access

There are two types of flash accesses:

Direct Access:

- Masters are allowed to do direct read only of their primary region.
  - Gigabit Ethernet region can only be directly accessed by the Gigabit Ethernet controller. Gigabit Ethernet software must use Program Registers to access the Gigabit Ethernet region.
- Master's Host or Intel ME virtual read address is converted into the SPI Flash Linear Address (FLA) using the Flash Descriptor Region Base/Limit registers.

Program Register Access:

- Program Register Accesses are not allowed to cross a 4 KB boundary and can not issue a command that might extend across two components.
- Software programs the FLA corresponding to the region desired.
  - Software must read the devices Primary Region Base/Limit address to create a FLA.



### 5.26.3.1 Direct Access Security

- Requester ID of the device must match that of the primary Requester ID in the Master Section
- Calculated Flash Linear Address must fall between primary region base/limit
- Direct Write not allowed
- Direct Read Cache contents are reset to 0's on a read from a different master
  - Supports the same cache flush mechanism in ICH7 which includes Program Register Writes

### 5.26.3.2 Register Access Security

- Only primary region masters can access the registers.

**Note:** Processor running Gigabit Ethernet software can access Gigabit Ethernet registers.

- Masters are only allowed to read or write those regions they have read/write permission.
- Using the Flash Region Access Permissions, one master can give another master read/write permissions to their area.
- Using the five Protected Range registers, each master can add separate read/write protection above that granted in the Flash Descriptor for their own accesses.
  - Example: BIOS may want to protect different regions of BIOS from being erased.
  - Ranges can extend across region boundaries.

## 5.26.4 Serial Flash Device Compatibility Requirements

A variety of serial flash devices exist in the market. For a serial flash device to be compatible with the PCH SPI bus, it must meet the minimum requirements detailed in the following sections.

**Note:** Depending on the SKU, PCH platforms require Intel ME firmware.

**Note:** The HEDT SKU only supports the fundamental Intel ME function.

### 5.26.4.1 PCH SPI Based BIOS Requirements

A serial flash device must meet the following minimum requirements when used explicitly for system BIOS storage.

- Erase size capability of at least one of the following: 64 Kbytes, 8 Kbytes, 4 Kbytes, or 256 bytes.
- Device must support multiple writes to a page without requiring a preceding erase cycle (Refer to [Section 5.26.5](#))
- Serial flash device must ignore the upper address bits such that an address of FFFFFFFh aliases to the top of the flash memory.
- SPI Compatible Mode 0 support (clock phase is 0 and data is latched on the rising edge of the clock).
- If the device receives a command that is not supported or incomplete (less than 8 bits), the device must complete the cycle gracefully without any impact on the flash content.
- An erase command (page, sector, block, chip, etc.) must set all bits inside the designated area (page, sector, block, chip, and so forth) to 1 (Fh).



- Status Register bit 0 must be set to 1 when a write, erase or write to status register is in progress and cleared to 0 when a write or erase is NOT in progress.
- Devices requiring the Write Enable command must automatically clear the Write Enable Latch at the end of Data Program instructions.
- Byte write must be supported. The flexibility to perform a write between 1 byte to 64 bytes is recommended.
- Hardware Sequencing requirements are optional in BIOS only platforms.
- SPI flash parts that do not meet Hardware sequencing command set requirements may work in BIOS only platforms using software sequencing.

#### 5.26.4.2 Integrated LAN Firmware SPI Flash Requirements

A serial flash device that will be used for system BIOS and Integrated LAN or Integrated LAN only must meet all the SPI Based BIOS Requirements plus:

- Hardware sequencing.
- 4, 8, or 64 KB erase capability must be supported.

##### 5.26.4.2.1 SPI Flash Unlocking Requirements for Integrated LAN

BIOS must ensure there is no SPI flash based read/write/erase protection on the GbE region. GbE firmware and drivers for the integrated LAN need to be able to read, write and erase the GbE region at all times.

#### 5.26.4.3 Intel® Management Engine (Intel® ME) Firmware SPI Flash Requirements

Intel ME Firmware must meet the SPI flash based BIOS Requirements plus:

- Hardware sequencing.
- Flash part must be uniform 4 KB erasable block throughout the entire device or have 64 KB blocks with the first block (lowest address) divided into 4 KB or 8 KB blocks.
- Write protection scheme must meet SPI flash unlocking requirements for Intel ME.

##### 5.26.4.3.1 SPI Flash Unlocking Requirements for Intel® ME

Flash devices must be globally unlocked (read, write and erase access on the Intel ME region) from power on by writing 00h to the flash's status register to disable write protection.

If the status register must be unprotected, it must use the enable write status register command 50h or write enable 06h.

Opcode 01h (write to status register) must then be used to write a single byte of 00h into the status register. This must unlock the entire part. If the SPI flash's status register has non-volatile bits that must be written to, bits [5:2] of the flash's status register must be all 0h to indicate that the flash is unlocked.

If bits [5:2] return a non zero values, the Intel ME firmware will send a write of 00h to the status register. This must keep the flash part unlocked.

If there is no need to execute a write enable on the status register, then opcodes 06h and 50h must be ignored.

After global unlock, BIOS has the ability to lock down small sections of the flash as long as they do not involve the Intel ME or GbE region.



#### 5.26.4.4 Hardware Sequencing Requirements

Table 5-64 contains a list of commands and the associated opcodes that a SPI-based serial flash device must support in order to be compatible with hardware sequencing.

**Table 5-64. Hardware Sequencing Commands and Opcode Requirements**

Commands	Opcode	Notes
Write to Status Register	01h	Writes a byte to SPI flash's status register. Enable Write to Status Register command must be run prior to this command.
Program Data	02h	Single byte or 64 byte write as determined by flash part capabilities and software.
Read Data	03h	
Write Disable	04h	
Read Status	05h	Outputs contents of SPI flash's status register
Write Enable	06h	
Fast Read	0Bh	
Enable Write to Status Register	06h or 50h	Enables a bit in the status register to allow an update to the status register
Erase	Program-mable	256B, 4 Kbyte, 8 Kbyte or 64 Kbyte
Full Chip Erase	C7h	
JEDEC ID	9Fh	See Section 5.26.4.4.1.

##### 5.26.4.4.1 Single Input, Dual Output Fast Read

The PCH now supports the functionality of a single input, dual output fast read. Opcode and address phase are shifted in serially to the serial flash SI (Serial In) pin. Data is read out after 8 clocks (dummy bits or wait states) from the both the SI and SO pin effectively doubling the through put of each fast read output. In order to enable this functionality, both Single Input Dual Output Fast Read Supported and Fast Read supported must be enabled.

##### 5.26.4.4.2 JEDEC ID

Since each serial flash device may have unique capabilities and commands, the JEDEC ID is the necessary mechanism for identifying the device so the uniqueness of the device can be comprehended by the controller (master). The JEDEC ID uses the opcode 9Fh and a specified implementation and usage model. This JEDEC Standard Manufacturer and Device ID read method is defined in Standard JESD21-C, PRN03-NV.

#### 5.26.5 Multiple Page Write Usage Model

The system BIOS and Intel ME firmware usage models require that the serial flash device support multiple writes to a page (minimum of 512 writes) without requiring a preceding erase command. BIOS commonly uses capabilities such as counters that are used for error logging and system boot progress logging. These counters are typically implemented by using byte-writes to 'increment' the bits within a page that have been designated as the counter. The Intel ME firmware usage model requires the capability for multiple data updates within any given page. These data updates occur using byte-writes without executing a preceding erase to the given page. Both the BIOS and Intel ME firmware multiple page write usage models apply to sequential and non-sequential data writes.

**Note:** This usage model requirement is based on any given bit only being written once from a '1' to a '0' without requiring the preceding erase. An erase would be required to change bits back to the 1 state.



### 5.26.5.1 Soft Flash Protection

There are two types of flash protection that are not defined in the flash descriptor supported by PCH:

1. BIOS Range Write Protection
2. SMI#-Based Global Write Protection

Both mechanisms are logically OR'd together such that if any of the mechanisms indicate that the access should be blocked, then it is blocked. Table 5-65 provides a summary of the mechanisms.

**Table 5-65. Flash Protection Mechanism Summary**

Mechanism	Accesses Blocked	Range Specific?	Reset-Override or SMI#-Override?	Equivalent Function on FWH
BIOS Range Write Protection	Writes	Yes	Reset Override	FWH Sector Protection
Write Protect	Writes	No	SMI# Override	Same as Write Protect in Intel ICHs for FWH

A blocked command will appear to software to finish, except that the Blocked Access status bit is set in this case.

### 5.26.5.2 BIOS Range Write Protection

The PCH provides a method for blocking writes to specific ranges in the SPI flash when the Protected BIOS Ranges are enabled. This is achieved by checking the Opcode type information (which can be locked down by the initial Boot BIOS) and the address of the requested command against the base and limit fields of a Write Protected BIOS range.

**Note:** Once BIOS has locked down the Protected BIOS Range registers, this mechanism remains in place until the next system reset.

### 5.26.5.3 SMI# Based Global Write Protection

The PCH provides a method for blocking writes to the SPI flash when the Write Protected bit is cleared (that is, protected). This is achieved by checking the Opcode type information (which can be locked down by the initial Boot BIOS) of the requested command.

The Write Protect and Lock Enable bits interact in the same manner for SPI BIOS as they do for the FWH BIOS.

## 5.26.6 Flash Device Configurations

The PCH-based platform must have a SPI flash connected directly to the PCH with a valid descriptor and Intel ME Firmware. BIOS may be stored in other locations such as Firmware Hub. Note this will not avoid the direct SPI flash connected to PCH requirement.



## 5.26.7 SPI Flash Device Recommended Pinout

The table below contains the recommended serial flash device pin-out for an 8-pin device. Use of the recommended pin-out on an 8-pin device reduces complexities involved with designing the serial flash device onto a motherboard and allows for support of a common footprint usage model (refer to [Section 5.26.8.1](#)).

**Table 5-66. Recommended Pinout for 8-Pin Serial Flash Device**

Pin #	Signal
1	Chips Select
2	Data Output
3	Write Protect
4	Ground
5	Data Input
6	Serial Clock
7	Hold / Reset
8	Supply Voltage

Although an 8-pin device is preferred over a 16-pin device due to footprint compatibility, the following table contains the recommended serial flash device pin-out for a 16-pin SOIC.

## 5.26.8 Serial Flash Device Package

**Table 5-67. Recommended Pinout for 16-Pin Serial Flash Device**

Pin #	Signal	Pin #	Signal
1	Hold / Reset	9	Write Protect
2	Supply Voltage	10	Ground
3	No Connect	11	No Connect
4	No Connect	12	No Connect
5	No Connect	13	No Connect
6	No Connect	14	No Connect
7	Chip Select	15	Serial Data In
8	Serial Data Out	16	Serial Clock

### 5.26.8.1 Common Footprint Usage Model

In order to minimize platform motherboard redesign and to enable platform Bill of Material (BOM) selectability, many PC System OEM's design their motherboard with a single common footprint. This common footprint allows population of a soldered down device or a socket that accepts a leadless device. This enables the board manufacturer to support, using selection of the appropriate BOM, either of these solutions on the same system without requiring any board redesign.

The common footprint usage model is desirable during system debug and by flash content developers since the leadless device can be easily removed and reprogrammed without damage to device leads. When the board and flash content is mature for high-volume production, both the socketed leadless solution and the soldered down leaded solution are available through BOM selection.

### 5.26.8.2 Serial Flash Device Package Recommendations

It is highly recommended that the common footprint usage model be supported. An example of how this can be accomplished is as follows:

- The recommended pinout for 8-pin serial flash devices is used (refer to [Section 5.26.7](#)).
- The 8-pin device is supported in either an 8-contact VDFPN (6x5 mm MLP) package or an 8-contact WSON (5x6 mm) package. These packages can fit into a socket that is land pattern compatible with the wide body SO8 package.
- The 8-pin device is supported in the SO8 (150 mil) and in the wide-body SO8 (200 mil) packages.

The 16-pin device is supported in the SO16 (300 mil) package.

## 5.27 Fan Control/Thermal Management

The PCH implements 4 PWM and 8 TACH signals for integrated fan speed control.

**Note:** Integrated fan speed control functionality requires a correctly configured system, including an appropriate processor, PCH with Intel® ME, Intel® ME Firmware, and system BIOS support. (SRV/WS SKUs only)

### 5.27.1 PWM Outputs

This signal is driven as open-drain. An external pull-up resistor is integrated into the fan to provide the rising edge of the PWM output signal. The PWM output is driven low during reset, which represents 0% duty cycle to the fans. After reset de-assertion, the PWM output will continue to be driven low until one of the following occurs:

- The internal PWM control register is programmed to a non-zero value by the appropriate firmware.
- The watchdog timer expires (enabled and set at 4 seconds by default).
- The polarity of the signal is inverted by firmware.

Note that if a PWM output will be programmed to inverted polarity for a particular fan, then the low voltage driven during reset represents 100% duty cycle to the fan.

### 5.27.2 TACH Inputs

This signal is driven as an open-collector or open-drain output from the fan. An external pull-up is expected to be implemented on the motherboard to provide the rising edge of the TACH input. This signal has analog hysteresis and digital filtering due to the potentially slow rise and fall times. This signal has a weak internal pull-up resistor to keep the input buffer from floating if the TACH input is not connected to a fan.



## 5.28 Feature Capability Mechanism

A set of registers is included in the PCH LPC Interface (Device 31, Function 0, offset E0h - EBh) that allows the system software or BIOS to easily determine the features supported by PCH. These registers can be accessed through LPC PCI configuration space, thus allowing for convenient single point access mechanism for chipset feature detection.

This set of registers consists of:

- Capability ID (FDCAP)
- Capability Length (FDLEN)
- Capability Version and Vendor-Specific Capability ID (FDVER)
- Feature Vector (FVECT)

## 5.29 Intel® Virtualization Technology (SRV/WS SKUs Only)

Intel® Virtualization Technology (Intel® VT) makes a single system appear as multiple independent systems to software. This allows for multiple, independent operating systems to be running simultaneously on a single system. Intel VT comprises technology components to support virtualization of platforms based on Intel architecture microprocessors and chipsets. The first revision of this technology (Intel VT for IA-32 Intel® Architecture [Intel VT-x]) added hardware support in the processor to improve the virtualization performance and robustness. The second revision of this specification (Intel VT for Directed I/O [Intel VT-d]) adds chipset hardware implementation to improve I/O performance and robustness.

The Intel VT-d spec and other Intel VT documents can be referenced here: <http://www.intel.com/technology/platform-technology/virtualization/index.htm>

### 5.29.1 Intel® Virtualization Technology (Intel® VT) for Directed I/O (Intel® VT-d) Objectives

The key Intel VT-d objectives are domain based isolation and hardware based virtualization. A domain can be abstractly defined as an isolated environment in a platform to which a subset of host physical memory is allocated. Virtualization allows for the creation of one or more partitions on a single system. This could be multiple partitions in the same OS or there can be multiple operating system instances running on the same system offering benefits such as system consolidation, legacy migration, activity partitioning or security.

### 5.29.2 Intel® VT-d features supported on PCH

- The following devices and functions support FLR in PCH:
  - High Definition Audio (Device 27: Function 0)
  - SATA Host Controller #1 (Device 31: Function 2)
  - SATA Host Controller #2 (Device 31: Function 5)
  - USB2 (EHCI) Host Controller #1 (Device 29: Function 0)
  - USB2 (EHCI) Host Controller #2 (Device 26: Function 0)
  - GbE Lan Host Controller (Device 25: Function 0)
- Interrupt virtualization support for IOxAPIC
- Virtualization Support for HPETs



### 5.29.3 Support for Function Level Reset (FLR) in PCH

Intel VT-d allows system software (VMM/OS) to assign I/O devices to multiple domains. The system software, then, requires ways to reset I/O devices or their functions within, as it assigns/re-assigns I/O devices from one domain to another. The reset capability is required to ensure the devices have undergone proper re-initialization and are not keeping the stale state. A standard ability to reset I/O devices is also useful for the VMM in case where a guest domain with assigned devices has become unresponsive or has crashed.

PCI Express\* defines a form of device hot reset which can be initiated through the Bridge Control register of the root/switch port to which the device is attached. However, the hot reset cannot be applied selectively to specific device functions. Also, no similar standard functionality exists for resetting root-complex integrated devices.

Current reset limitations can be addressed through a *function level reset* (FLR) mechanism that allows software to independently reset specific device functions.

### 5.29.4 Virtualization Support for PCH's IOxAPIC

The Intel VT-d architecture extension requires Interrupt Messages to go through the similar Address Remapping as any other memory requests. This is to allow domain isolation for interrupts such that a device assigned in one domain is not allowed to generate interrupts to another domain.

The Address Remapping for Intel VT-d is based on the Bus:Device:Function field associated with the requests. Hence, it is required for the internal IOxAPIC to initiate the Interrupt Messages using a unique Bus:Device:Function.

PCH supports BIOS programmable unique Bus:Device:Function for the internal IOxAPIC. The Bus:Device:Function field does not change the IOxAPIC functionality in anyway, nor promoting IOxAPIC as a stand-alone PCI device. The field is only used by the IOxAPIC in the following:

- As the Requestor ID when initiating Interrupt Messages to the CPU
- As the Completer ID when responding to the reads targeting the IOxAPIC's Memory-Mapped I/O registers

### 5.29.5 Virtualization Support for High Precision Event Timer (HPET)

The Intel VT-d architecture extension requires Interrupt Messages to go through the similar Address Remapping as any other memory requests. This is to allow domain isolation for interrupts such that a device assigned in one domain is not allowed to generate interrupts to another domain.

The Address Remapping for Intel VT-d is based on the Bus:Device:Function field associated with the requests. Hence, it is required for the HPET to initiate processor message interrupts using unique Bus:Device:Function.

PCH supports BIOS programmable unique Bus:Device:Function for each of the HPET timers. The Bus:Device:Function field does not change the HPET functionality in anyway, nor promoting it as a stand-alone PCI device. The field is only used by the HPET timer in the following:

- As the Requestor ID when initiating processor message interrupts to the Processor
- As the Completer ID when responding to the reads targeting its Memory-Mapped registers

The registers for the programmable Bus:Device:Function for HPET timer 7:0 reside under the Device 31:Function 0 LPC Bridge's configuration space.

## §



# 6 PCH Ballout Definition

This chapter contains the PCH ballout information.

**Note:** Not all listed signals are used on all PCH SKUs. See Chapter 2, “Signal Description” for details.

Figure 6-1 shows the ballout from a top of the package view. Figure 6-2, Figure 6-3, Figure 6-4, Figure 6-5 show the ballout zoomed in from a top of package quadrant view.

**Figure 6-1. PCH Ballout (Top View)**

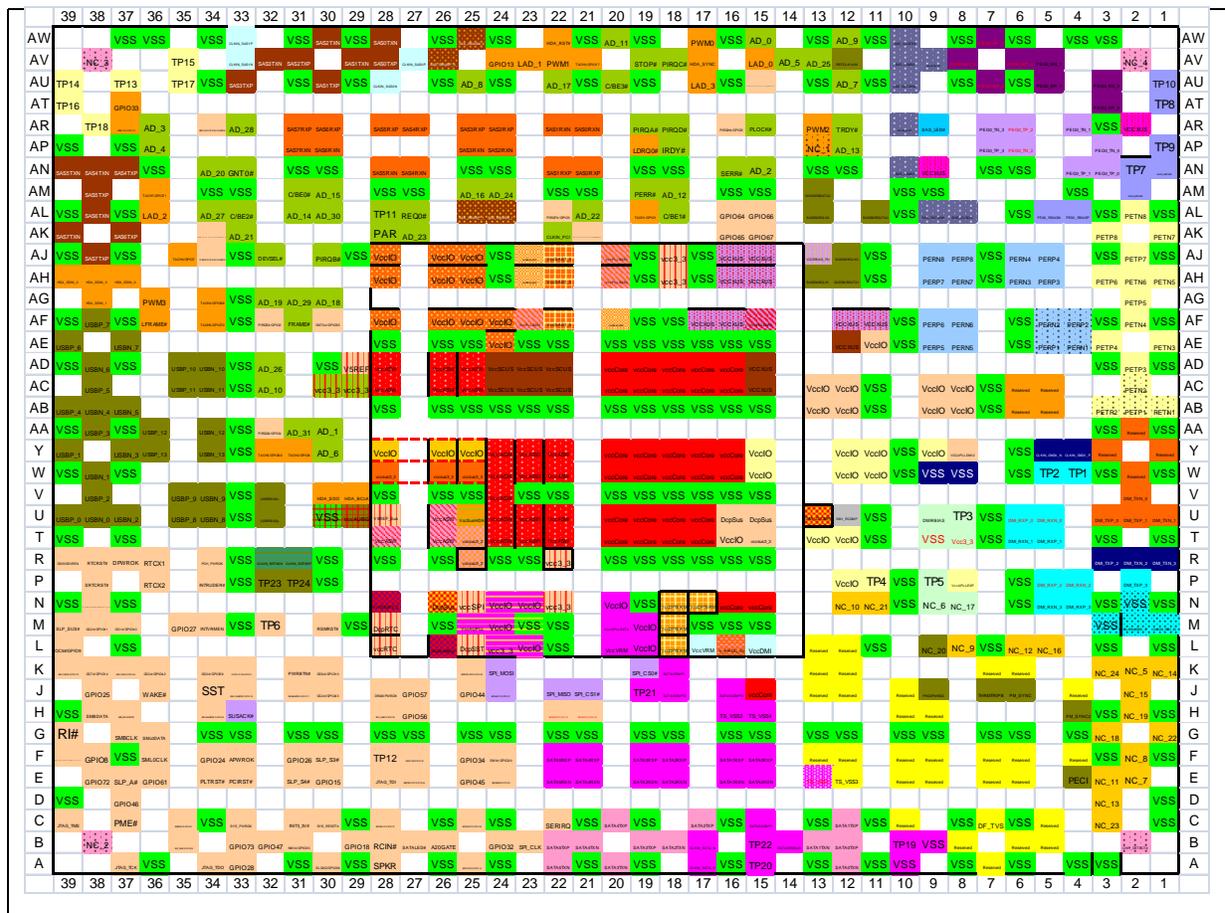




Figure 6-2. PCH Ballout (Top View - Upper Left)

	39	38	37	36	35	34	33	32	31	30	29	28	27	26	25	24	23	22	21
AW			VSS VSS		VSS	CLKIN_SAS1P		VSS	SAS2TXN	VSS	SAS0TXN		VSS	SAS7SEREN_0	VSS		HDA_RST#	VSS	
AV		NC_3		TP15		CLKIN_SAS1N	SAS3TXN	SAS2TXP	SAS1TXN	SAS0TXP	CLKIN_SAS0P	SAS7BIASP_6			GPIO13	LAD_1	PWM1	TACH0/GPIO7	
AU	TP14		TP13	TP17	VSS	SAS3TXP		VSS	SAS1TXP	VSS	CLKIN_SAS0N		VSS	AD_8	VSS		AD_17	VSS	
AT	TP16		GPIO33																
AR		TP18		AD_3		AD_28		SAS7RXP	SAS6RXP		SAS5RXP	SAS4RXP		SAS3RXP	SAS2RXP		SAS1RXP	SAS0RXP	
AP	VSS		VSS	AD_4				SAS7RXN	SAS6RXN					SAS3RXN	SAS2RXN				
AN	SAS5TXN	SAS4TXN	SAS4TXP	VSS		AD_20	GNT0#	VSS	VSS		SAS5RXN	SAS4RXN		VSS	VSS		SAS1RXP	SAS0RXP	
AM		SAS5TXP		TACH7/GPIO1		VSS	VSS	C/BE0#	AD_15		VSS	VSS		AD_16	AD_24		VSS	VSS	
AL	VSS	SAS6TXN	VSS	LAD_2		AD_27	C/BE2#		AD_14	AD_30		TP11	REQ0#				PIRQ#/GPIO3	AD_22	
AK	SAS7TXN		SAS6TXP				AD_21					PAR	AD_23					CLKIN_PCI	
AJ	VSS	SAS7TXP	VSS		TACH0/GPIO2		VSS	DEVSEL#		PIRQB#	VSS	VccIO		VccIO	VccIO	VSS		VccIO	VccIO
AH	HDA_SDN_2	HDA_SDN_3	HDA_SDN_0									VccIO		VccIO	VccIO	VSS		VccIO	VccIO
AG		HDA_SDN_1		PWM3		TACH4/GPIO8	VSS	AD_19	AD_29	AD_18								VccIO	VccIO
AF	VSS	USBP_7	VSS	LFRAME#		TACH6/GPIO7	VSS	PIRQE#/GPIO2	FRAME#	GNT3#/GPIO5		VccIO		VccIO	VccIO	VccIO	VccIO	VccIO	VccIO
AE	USBP_6		USBN_7									VSS		VSS	VSS	VccIO	VSS	VSS	
AD	VSS	USBN_6	VSS		USBP_10	USBN_10	VSS	AD_26		VSS	V5REF	VccASW		VccASW	VccASW	VccSCUS	VccSCUS	VccSCUS	VccSCUS
AC		USBP_5			USBP_11	USBN_11	VSS	AD_10		Vcc3_3	Vcc3_3	VccASW		VccASW	VccASW	VccSCUS	VccSCUS	VccSCUS	VccSCUS
AB	USBP_4	USBN_4	USBN_5									VSS		VSS	VSS	VSS	VSS	VSS	VSS
AA	VSS	USBP_3	VSS	USBP_12		USBN_12	VSS	PIRQ#/GPIO4	AD_31	AD_1									
Y	USBP_1		USBN_3	USBP_13		USBN_13	VSS	TACH6/GPIO9	TACH0/GPIO4	AD_6		VccIO		VccIO	VccIO	VccASW	VccASW	VccASW	VccASW
W	VSS	USBN_1	VSS									VccIO3_3		VccIO3_3	VccIO3_3	VccASW	VccASW	VccASW	VccASW
V		USBP_2			USBP_9	USBN_9	VSS	USBBIAS+	HDA_SDO	HDA_BCLK		VSS		VSS	VSS	VccASW	VSS	VSS	VSS
U	USBP_0	USBN_0	USBN_2		USBP_8	USBN_8	VSS	USBBIAS-	VSS	VccAUBG	V5REF_SUP			VccASW	VccASW	VccASW	VccASW	VccASW	VccASW



Figure 6-3. PCH Ballout (Top View - Upper Right)

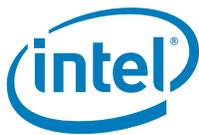
	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	
AW	AD_11	VSS		PWM0	VSS	AD_0		VSS	AD_9	VSS	SAS_L0Q0		VSS	PEGO_RN_3	VSS		VSS	VSS			
AV		STOP#	PIRQC#	HDA_SYNC		LAD_0	AD_5	AD_25	REFOLK14N		SAS_L0Q0		VSS	PEGO_RN_2		PEGO_RN_1			NC_4		
AU	C/BE3#	VSS		LAD_3	VSS			VSS	AD_7	VSS	SAS_L0Q0		VSS	PEGO_RN_1	VSS	PEGO_RP_1					TP10
AT																		PEGO_RP_0			TP8
AR		PIRQA#	PIRQD#		PIRQH_QP0C	PLOCK#		PWM2	TRDY#		SAS_LED#			PEGO_TN_3	PEGO_TP_2		PEGO_TN_1	VSS	VCCXUS		
AP		LDRQ0#	IRDY#					NC_1	AD_13					PEGO_TP_3	PEGO_TN_2			PEGO_TN_0			TP9
AN		VSS	VSS		SERR#	AD_2		VSS	VSS		SAS_LED#	VCCXUS		VSS	VSS		PEGO_TP_1	PEGO_TP_0			TP7
AM		PERR#	AD_12		VSS	VSS					VSS	VSS					VSS				
AL		TACH_QP0C	C/BE1#		GPIO64	GPIO66		SASMB0TA2			VSS				VSS	PEGO_R0A5N	PEGO_R0A6P			PETN8	VSS
AK					GPIO65	GPIO67														PETP8	PETN7
AJ	VCCFL0A0	VSS	vcc3_3	VSS	VCCXUS	VCCXUS		VCCMAE_PU	SASMB0C0U	VSS		PERN8	PERP8	VSS	PERN4	PERP4		VSS	PETP7	VSS	
AH	VCCFL0A0	VSS	vcc3_3	VSS	VCCXUS	VCCXUS		SASMB0C1U	SASMB0TA1	VSS		PERP7	PERN7	VSS	PERN3	PERP3			PETP6	PETN6	PETN5
AG																				PETP5	
AF	vcc3_0	VSS	VSS	VCCXUS	VCCXUS	VCCFL0A0			VCCXUS	VCCXUS	VSS	PERP6	PERN6		VSS	PERN2	PERP2		VSS	PETN4	VSS
AE	VSS	VSS	VSS	VSS	VSS	VSS		VCCXUS	VccIO	VSS		PERP5	PERN5		VSS	PERP1	PERN1		PETP4		PETN3
AD	vccCore	vccCore	vccCore	vccCore	vccCore	vccCore	VCCXUS												VSS	PETP3	VSS
AC	vccCore	vccCore	vccCore	vccCore	vccCore	vccCore	VCCXUS	VccIO	VccIO	VSS		VccIO	VccIO	VSS	Reserved	Reserved				PETN2	
AB	VSS	VSS	VSS	VSS	VSS	VSS		VccIO	VccIO	VSS		VccIO	VccIO	VSS	Reserved	Reserved			PETP2	PETP1	PETN1
AA																			VSS	Reserved	VSS
Y	vccCore	vccCore	vccCore	vccCore	vccCore	vccCore	VccIO		VccIO	VccIO	VSS	VccIO	VCCAPLDM12		VSS	CLKIN_QND0_N	CLKIN_QND0_P	Reserved		Reserved	Reserved
W	vccCore	vccCore	vccCore	vccCore	vccCore	vccCore	VccIO		VccIO	VccIO	VSS	VSS	VSS		VSS	TP2	TP1	VSS	Reserved		VSS
V	VSS	VSS	VSS	VSS	VSS	VSS														DM_LTXN_0	
U	vccCore	vccCore	vccCore	vccCore	DcpSus	DcpSus		DM_Z0M0	DM1_RC0MP	VSS		DM1RBIAS	TP3	VSS		DM1_RXP_0	DM1_RXN_0		DM1_TXP_0	DM1_TXP_1	DM1_TXN_1



Figure 6-4. PCH Ballout (Top View - Lower Left)

U	USBP_0	USBN_0	USBN_2	USBP_8	USBN_8	VSS	USBRN_6	VSS	VccAUBG	VREF_S1#	VccASW	VccSubHDA	VccASW	VccASW	VccASW	Vc			
T	VSS	VSS								VccASW	VccASW	VccASW	VccASW	VccASW	VccASW	Vc			
R	OSWDRREN	RTCRST#	DPWROK	RTCX1	PCH_PWRCK	VSS	CLKIN_D07#EN	CLKIN_D07#P	VSS	VSS	VSS	VccASW	VccASW	VccASW	VccASW	Vc			
P		SRTCST#	RTCX2		INTRUDER#	VSS	TP23	TP24	VSS			VccASW	VccASW	VccASW	VccASW	Vc			
N	VSS	VSS								VccDSW3_3	DcpSus	VccSPI	VccIO	VccIO	Vcc3_3	Vc			
M	SLP_SUS#	OC2#(GPIO4)	OC1#(GPIO4)		GPIO27	INTVRMEN	VSS	TP6	RSMRST#	VSS	DcpRTC	VSS	VccAUPLL	VccIO	VSS	VSS/VccA			
L	OC5#(GPIO9)	VSS								VccRTC	DcpSusByp	DcpSST	Vcc3_3	VccIO	VSS	Vc			
K	OC0#(GPIO3)	OC7#(GPIO4)	OC0#(GPIO4)	OC3#(GPIO4)	OC2#(GPIO5)	OC0#(GPIO5)	PWRBTN#	OC5#(GPIO10)				SPI_MOSI							
J		GPIO25	WAKE#		SST				DRAMPWRCK	GPIO57	GPIO44		SPI_MISO	SPI_CS1#					
H	VSS	SMBDATA	ASD#WAKE		SUSACK#				GPIO56										
G	R#	SMBCLK	SML0DATA		VSS	VSS	VSS	VSS	VSS	VSS	VSS	VSS	VSS	VSS	VSS	VSS			
F		GPIO8	VSS	SML0CLK	GPIO24	APWROK	GPIO26	SLP_S3#	TP12	GPIO34	SMB#(GPIO20)		SATA5RXP	SATA4RXP					
E		GPIO72	SLP_A#	GPIO61	PLTRST#	PCIRST#	SLP_S4#	GPIO15	JTAG_TDI	GPIO45			SATA5RXN	SATA4RXN					
D	VSS		GPIO46																
C	JTAG_TMS		PME#		VSS	SYS_PWRCK	INIT3_3V#	SYS_RESET#	VSS		VSS	VSS	SERIRQ	VSS					
B		NC_2			GPIO73	GPIO47	MMIO#(GPIO5)		GPIO18	RCIN#	SATALED#	A20GATE	GPIO32	SPL_CLK	SATA5TXP	SATA4TXN			
A		JTAG_TCK	VSS		JTAG_TDO	GPIO28	VSS	SLOD#(GPIO8)	VSS	SPKR	VSS	VSS	SATA5TXN	VSS					
	39	38	37	36	35	34	33	32	31	30	29	28	27	26	25	24	23	22	21





**Table 6-1. PCH Ballout by Signal Name (Sheet 1 of 25)**

PCH Ball Name	Ball #
A20GATE	B26
AD0	AW15
AD1	AA30
AD10	AC32
AD11	AW20
AD12	AM18
AD13	AP12
AD14	AL31
AD15	AM30
AD16	AM25
AD17	AU22
AD18	AG30
AD19	AG32
AD2	AN15
AD20	AN34
AD21	AK33
AD22	AL21
AD23	AK27
AD24	AM24
AD25	AV13
AD26	AD32
AD27	AL34
AD28	AR33
AD29	AG31
AD3	AR36
AD30	AL30
AD31	AA31
AD4	AP36
AD5	AV14
AD6	Y30
AD7	AU12
AD8	AU25
AD9	AW12
ADR_COMPLETE	H37
APWROK	F33
BMBUSY#/ GPIO0	E24

**Table 6-1. PCH Ballout by Signal Name (Sheet 2 of 25)**

PCH Ball Name	Ball #
C/BE0#	AM31
C/BE1#	AL18
C/BE2#	AL33
C/BE3#	AU20
CHIP_DETECT#	B2
CLKIN_DMI_N	M1
CLKIN_DMI_P	M2
CLKIN_DOT_96N	R32
CLKIN_DOT_96P	R31
CLKIN_GND0_N	Y5
CLKIN_GND0_P	Y4
CLKIN_PCI	AK22
CLKIN_SAS0_N	AU28
CLKIN_SAS0_P	AV27
CLKIN_SAS1_N	AV33
CLKIN_SAS1_P	AW33
CLKIN_SATA_N	B17
CLKIN_SATA_P	A17
CLKIN_SPCIE0_N	AN1
CLKIN_SPCIE0_P	AM2
DcpRTC	M28
DcpSST	L25
DcpSus	U15
DcpSus	U16
DcpSus	N26
DcpSusByp	L26
DEVSEL#	AJ32
DF_TV5	C7
DMI_IRCOMP	U12
DMI_RXN_0	U5
DMI_RXN_1	T6
DMI_RXN_2	P4
DMI_RXN_3	N5
DMI_RXP_0	U6
DMI_RXP_1	T5
DMI_RXP_2	P5
DMI_RXP_3	N4

**Table 6-1. PCH Ballout by Signal Name (Sheet 3 of 25)**

PCH Ball Name	Ball #
DMI_TXN_0	V2
DMI_TXN_1	U1
DMI_TXN_2	R2
DMI_TXN_3	R1
DMI_TXP_0	U3
DMI_TXP_1	U2
DMI_TXP_2	R3
DMI_TXP_3	P2
DMI_ZCOMP	U13
DMIRBIAS	U9
DPWROK	R37
DRAMPWROK	J28
DSWODVREN	R39
FRAME#	AF31
GNT0#	AN33
GNT1# / GPIO51 / GSXDOUT	AU15
GNT2# / GPIO53 / GSXDIN	AJ34
GNT3# / GPIO55	AF30
GPIO13	AV24
GPIO15	E30
GPIO18	B29
GPIO24	F34
GPIO25	J38
GPIO26	F31
GPIO27	M35
GPIO28	A33
GPIO31/MGPIO2	K33
GPIO32	B24
GPIO33	AT37
GPIO34	F25
GPIO44	J25
GPIO45	E25
GPIO46	D37
GPIO47	B32
GPIO56	H27



**Table 6-1. PCH Ballout by Signal Name (Sheet 4 of 25)**

PCH Ball Name	Ball #
GPIO57	J27
GPIO64	AL16
GPIO65	AK16
GPIO66	AL15
GPIO67	AK15
GPIO72	E38
GPIO73	B33
GPIO8	F38
HDA_BCLK	V29
HDA_RST#	AW22
HDA_SDIN0	AH37
HDA_SDIN1	AG38
HDA_SDIN2	AH39
HDA_SDIN3	AH38
HDA_SDO	V30
HDA_SYNC	AV17
INIT3_3V#	C31
INTRUDER#	P34
INTVRMEN	M34
IRDY#	AP18
JTAG_TCK	A37
JTAG_TDI	E28
JTAG_TDO	A34
JTAG_TMS	C39
LAD0	AV15
LAD1	AV23
LAD2	AL36
LAD3	AU17
LAN_PHY_PWR_CTL / GPIO12	F39
LDRQ0#	AP19
LDRQ1# / GPIO23	AR37
LFRAME#	AF36
NC_1	AP13
NC_2	B38
NC_3	AV38
NC_4	AV2

**Table 6-1. PCH Ballout by Signal Name (Sheet 5 of 25)**

PCH Ball Name	Ball #
NMI#/GPIO35	B31
NC_5	K2
NC_6	N9
NC_7	E2
NC_8	F2
NC_9	L8
NC_10	N12
NC_11	E3
NC_12	L6
NC_13	D3
NC_14	K1
NC_15	J2
NC_16	L5
NC_17	N8
NC_18	G3
NC_19	H2
NC_20	L9
NC_21	N11
NC_22	G1
NC_23	C3
NC_24	K3
OC0# / GPIO59	K34
OC1# / GPIO40	M37
OC2# / GPIO41	M38
OC3# / GPIO42	K36
OC4# / GPIO43	J30
OC5# / GPIO9	L39
OC6# / GPIO10	K30
OC7# / GPIO14	K38
PAR	AK28
PCH_PWROK	R34
PCIRST#	E33
PECI	E4
PEGO_RBIAASN	AL5
PEGO_RBIAASP	AL4
PEGO_RN0	AU3

**Table 6-1. PCH Ballout by Signal Name (Sheet 6 of 25)**

PCH Ball Name	Ball #
PEGO_RN1	AV5
PEGO_RN2	AU7
PEGO_RN3	AV8
PEGO_RP0	AT3
PEGO_RP1	AU5
PEGO_RP2	AV6
PEGO_RP3	AW7
PEGO_TN0	AP3
PEGO_TN1	AR4
PEGO_TN2	AP6
PEGO_TN3	AR7
PEGO_TP0	AN3
PEGO_TP1	AN4
PEGO_TP2	AR6
PEGO_TP3	AP7
PERn1	AE4
PERn2	AF5
PERn3	AH6
PERn4	AJ6
PERn5	AE8
PERn6	AF8
PERn7	AH8
PERn8	AJ9
PERp1	AE5
PERp2	AF4
PERp3	AH5
PERp4	AJ5
PERp5	AE9
PERp6	AF9
PERp7	AH9
PERp8	AJ8
PERR#	AM19
PETn1	AB1
PETn2	AC2
PETn3	AE1
PETn4	AF2



**Table 6-1. PCH Ballout by Signal Name (Sheet 7 of 25)**

PCH Ball Name	Ball #
PETn5	AH1
PETn6	AH2
PETn7	AK1
PETn8	AL2
PETp1	AB2
PETp2	AB3
PETp3	AD2
PETp4	AE3
PETp5	AG2
PETp6	AH3
PETp7	AJ2
PETp8	AK3
PIROA#	AR19
PIROB#	AJ30
PIROC#	AV18
PIROD#	AR18
PIROE# / GPIO2	AF32
PIROF# / GPIO3	AL22
PIROG# / GPIO4	AA32
PIROH# / GPIO5	AR16
PLOCK#	AR15
PLTRST#	E34
PM_SYNC	J6
PM_SYNC2	H4
PME#	C37
PROCPWRGD	J9
PWM0	AW17
PWM1	AV22
PWM2	AR13
PWM3	AG36
PWRBTN#	K31
RCIN#	B28
REFCLK14IN	AV12
REQ0#	AL27
REQ1# / GPIO50 / GSXCLK	AR34

**Table 6-1. PCH Ballout by Signal Name (Sheet 8 of 25)**

PCH Ball Name	Ball #
REQ2# / GPIO52 / GSXSLOAD	AK34
REQ3# / GPIO54 / GSXSRESET#	AK21
Reserved	A7
Reserved	AA2
Reserved	AB5
Reserved	AB6
Reserved	AC5
Reserved	AC6
Reserved	B5
Reserved	B6
Reserved	B8
Reserved	C10
Reserved	C5
Reserved	E10
Reserved	E6
Reserved	E7
Reserved	E9
Reserved	F10
Reserved	F12
Reserved	F13
Reserved	F4
Reserved	F6
Reserved	F7
Reserved	F9
Reserved	H10
Reserved	H9
Reserved	J10
Reserved	J12
Reserved	J13
Reserved	J4
Reserved	K12
Reserved	K13
Reserved	K6
Reserved	K7
Reserved	L12

**Table 6-1. PCH Ballout by Signal Name (Sheet 9 of 25)**

PCH Ball Name	Ball #
Reserved	L13
Reserved	W2
Reserved	Y1
Reserved	Y3
RI#	G39
RSMRST#	M30
RTCST#	R38
RTCX1	R36
RTCX2	P36
SAS0RXN	AR21
SAS1RXN	AR22
SAS2RXN	AP24
SAS3RXN	AP25
SAS4RXN	AN27
SAS5RXN	AN28
SAS6RXN	AP30
SAS7RXN	AP31
SAS0RXP	AN21
SAS1RXP	AN22
SAS2RXP	AR24
SAS3RXP	AR25
SAS4RXP	AR27
SAS5RXP	AR28
SAS6RXP	AR30
SAS7RXP	AR31
SAS0TXN	AW28
SAS1TXN	AV29
SAS2TXN	AW30
SAS3TXN	AV32
SAS4TXN	AN38
SAS5TXN	AN39
SAS6TXN	AL38
SAS7TXN	AK39
SAS0TXP	AV28
SAS1TXP	AU30
SAS2TXP	AV31
SAS3TXP	AU33



**Table 6-1. PCH Ballout by Signal Name (Sheet 10 of 25)**

PCH Ball Name	Ball #
SAS4TXP	AN37
SAS5TXP	AM38
SAS6TXP	AK37
SAS7TXP	AJ38
SAS_CLOCK1	AL8
SAS_LOAD1	AN10
SAS_DATAIN1	AL9
SAS_DATAOUT1	AV9
SAS_CLOCK2	AW10
SAS_LOAD2	AV10
SAS_DATAIN2	AU10
SAS_DATAOUT2	AR10
SAS_LED#	AR9
SAS_RBIBASNO	AW25
SAS_RBIBASN1	AL24
SAS_RBIBASPO	AV26
SAS_RBIBASP1	AL25
SASSMBCLK0	AJ12
SASSMBCLK1	AH13
SASSMBCLK2	AL13
SASSMBDATA0	AL11
SASSMBDATA1	AH12
SASSMBDATA2	AM13
SATA0RXN	E15
SATA1RXN	E16
SATA2RXN	E18
SATA3RXN	E19
SATA4RXN	E21
SATA5RXN	E22
SATA0RXP	F15
SATA1RXP	F16
SATA2RXP	F18
SATA3RXP	F19
SATA4RXP	F21
SATA5RXP	F22
SATA0TXN	A12

**Table 6-1. PCH Ballout by Signal Name (Sheet 11 of 25)**

PCH Ball Name	Ball #
SATA1TXN	B13
SATA2TXN	B18
SATA3TXN	A20
SATA4TXN	B21
SATA5TXN	A22
SATA0TXP	B12
SATA1TXP	C12
SATA2TXP	C17
SATA3TXP	B19
SATA4TXP	C20
SATA5TXP	B22
SATA0GP / GPIO21	J24
SATA1GP / GPIO19	A25
SATA2GP / GPIO36	C25
SATA3GP / GPIO37	C28
SATA4GP / GPIO16	H22
SATA5GP / GPIO49 / TEMP_ALERT#	H21
SATAICOMPI	K18
SATAICOMPO	J18
SATALED#	B27
SCLOCK / GPIO22	F27
SDATAOUT0 / GPIO39	K25
SDATAOUT1 / GPIO48	E27
SATA3RBIAS	B14
SATA3COMPI	C15
SATA3COMPO	J16
SERIRQ	C22
SERR#	AN16
SLOAD / GPIO38	A30
SLP_A#	E37
SLP_LAN# / GPIO29	H28
SLP_S3#	F30
SLP_S4#	E31
SLP_S5# / GPIO63	B35

**Table 6-1. PCH Ballout by Signal Name (Sheet 12 of 25)**

PCH Ball Name	Ball #
SLP_SUS#	M39
SMBALERT# / GPIO11	J31
SMBCLK	G37
SMBDATA	H38
SMI# / GPIO20	F24
SMLOALERT# / GPIO60	H34
SML0CLK	F36
SML0DATA	G36
SML1ALERT# / GPIO74	J33
SML1CLK / GPIO58	K37
SML1DATA / GPIO75	K39
SPI_CLK	B23
SPI_CS0#	K19
SPI_CS1#	J21
SPI_MISO	J22
SPI_MOSI	K24
SPKR	A28
SRTCST#	P38
SST	J34
STOP#	AV19
SUSACK#	H33
SUSWARN# / GPIO30	N38
GPIO61	E36
SUSCLK / GPIO62	C35
SYS_PWROK	C33
SYS_RESET#	C30
TACH0 / GPIO17	AV21
TACH1 / GPIO1	AL19
TACH2 / GPIO6	Y31
TACH3 / GPIO7	AJ35
TACH4 / GPIO68	AG34
TACH5 / GPIO69	Y32
TACH6 / GPIO70	AF34



**Table 6-1. PCH Ballout by Signal Name (Sheet 13 of 25)**

PCH Ball Name	Ball #
TACH7 / GPIO71	AM36
THRMTRIP#	J7
TP1	W4
TP10	AU1
TP11	AL28
TP12	F28
TP13	AU37
TP14	AU39
TP15	AV35
TP16	AT39
TP17	AU35
TP18	AR38
TP19	B10
TP2	W5
TP20	A15
TP21	J19
TP22	B15
TP23	P32
TP24	P31
TP3	U8
TP4	P11
TP5	P9
TP6	M32
TP7	AN2
TP8	AT1
TP9	AP1
TRDY#	AR12
TS_VSS1	E13
TS_VSS2	H16
TS_VSS3	E12
TS_VSS4	H15
USBP0N	U38
USBP0P	U39
USBP10N	AD34
USBP10P	AD35
USBP11N	AC34
USBP11P	AC35

**Table 6-1. PCH Ballout by Signal Name (Sheet 14 of 25)**

PCH Ball Name	Ball #
USBP12N	AA34
USBP12P	AA36
USBP13N	Y34
USBP13P	Y36
USBP1N	W38
USBP1P	Y39
USBP2N	U37
USBP2P	V38
USBP3N	Y37
USBP3P	AA38
USBP4N	AB38
USBP4P	AB39
USBP5N	AB37
USBP5P	AC38
USBP6N	AD38
USBP6P	AE39
USBP7N	AE37
USBP7P	AF38
USBP8N	U34
USBP8P	U35
USBP9N	V34
USBP9P	V35
USBRBIAS	U32
USBRBIAS#	V32
V_PROC_IO	L16
V5REF	AD29
V5REF_Sus	U28
Vcc3_3	R22
Vcc3_3	N22
Vcc3_3	AJ18
Vcc3_3	AH18
Vcc3_3	AC30
Vcc3_3	AC29
Vcc3_3	T8
Vcc3_3	L24
VccCore	AD20
VccCore	AD19

**Table 6-1. PCH Ballout by Signal Name (Sheet 15 of 25)**

PCH Ball Name	Ball #
VccCore	AD18
VccCore	AD17
VccCore	AD16
VccCore	AC20
VccCore	AC19
VccCore	AC18
VccCore	AC17
VccCore	AC16
VccCore	Y20
VccCore	Y19
VccCore	Y18
VccCore	Y17
VccCore	Y16
VccCore	W20
VccCore	W19
VccCore	W18
VccCore	W17
VccCore	W16
VccCore	U20
VccCore	U19
VccCore	U18
VccCore	U17
VccCore	T20
VccCore	T19
VccCore	T18
VccCore	T17
VccCore	N16
VccCore	N15
VccCore	J15
VccDFTERM	N18
VccDFTERM	N17
VccDFTERM	M18
VccDFTERM	L18
VccDMI	L15
VccDSW3_3	N28
VccIO	AE11
VccIO	AC13



**Table 6-1. PCH Ballout by Signal Name (Sheet 16 of 25)**

PCH Ball Name	Ball #
VccIO	AC12
VccIO	AC9
VccIO	AC8
VccIO	AB13
VccIO	AB12
VccIO	AB9
VccIO	AB8
VccIO	Y15
VccIO	Y12
VccIO	Y11
VccIO	Y9
VccIO	W15
VccIO	W12
VccIO	W11
VccIO	T13
VccIO	T12
VccIO	T16
VccIO	P12
VccIO	N24
VccIO	N23
VccIO	M24
VccIO	L23
VccIO	Y28
VccIO	Y26
VccIO	Y25
VccIO	N20
VccIO	M19
VccIO	L19
VccAUPLL	M25
VccRBIAS_SAS0	AF20
VccRBIAS_SAS1	AJ23
VccRBIAS_SAS1	AH23
VccIO	AJ28
VccIO	AJ26
VccIO	AJ25
VccIO	AH28

**Table 6-1. PCH Ballout by Signal Name (Sheet 17 of 25)**

PCH Ball Name	Ball #
VccIO	AH26
VccIO	AH25
VccIO	AF28
VccIO	AF26
VccIO	AF25
VccIO	AF24
VccIO	AE24
VccSCUS	AC22
VccSCUS	AC23
VccSCUS	AC24
VccSCUS	AD22
VccSCUS	AD23
VccSCUS	AD24
VccXUS	AR2
VccXUS	AN9
VccRBIAS_PU	AJ13
VccXUS	AJ16
VccXUS	AJ15
VccXUS	AH16
VccXUS	AH15
VccXUS	AF17
VccXUS	AF16
VccXUS	AF12
VccXUS	AF11
VccXUS	AC15
VccXUS	AD15
VccXUS	AE12
VccASW	AD28
VccASW	AD26
VccASW	AD25
VccASW	AC28
VccASW	AC26
VccASW	AC25
VccASW	Y24
VccASW	Y23
VccASW	Y22

**Table 6-1. PCH Ballout by Signal Name (Sheet 18 of 25)**

PCH Ball Name	Ball #
VccASW	W24
VccASW	W23
VccASW	W22
VccASW	V24
VccASW	U24
VccASW	U23
VccASW	U22
VccASW	T24
VccASW	T23
VccASW	T22
VccASW	U26
VccASW	T28
VccASW	T26
VccAPLLDMI2	Y8
VccAPLLEXP	P8
VccAPLLSATA	M20
VccPLLSAS0	AJ20
VccPLLSAS0	AH20
VccPLLSAS1	AF23
VccPLLEXP	AF15
VccRTC	L28
VccSAS1_5	AJ22
VccSAS1_5	AH22
VccSAS1_5	AF22
VccSPI	N25
VccSus3_3	T25
VccSus3_3	R25
VccSus3_3	W28
VccSus3_3	W26
VccSus3_3	W25
VccAUBG	U29
VccSus3_3	T15
VccSusHDA	U25
VccVRM	L17
VccVRM	L20
Vss (0)	AW37



**Table 6-1. PCH Ballout by Signal Name (Sheet 19 of 25)**

PCH Ball Name	Ball #
Vss	AW36
Vss	AW34
Vss	AW31
Vss	AW29
Vss	AW26
Vss	AW24
Vss	AW21
Vss	AW19
Vss	AW16
Vss (10)	AW13
Vss	AW11
Vss	AW8
Vss	AW6
Vss	AW4
Vss	AW3
Vss	AU34
Vss	AU31
Vss	AU29
Vss	AU26
Vss (20)	AU24
Vss	AU21
Vss	AU19
Vss	AU16
Vss	AU13
Vss	AU11
Vss	AU8
Vss	AU6
Vss	AR3
Vss	AP39
Vss (30)	AP37
Vss	AN36
Vss	AN31
Vss	AN30
Vss	AN25
Vss	AN24
Vss	AN19
Vss	AN18

**Table 6-1. PCH Ballout by Signal Name (Sheet 20 of 25)**

PCH Ball Name	Ball #
Vss	AN13
Vss	AN12
Vss (40)	AN7
Vss	AN6
Vss	AM34
Vss	AM33
Vss	AM28
Vss	AM27
Vss	AM22
Vss	AM21
Vss	AM16
Vss	AM15
Vss (50)	AM10
Vss	AM9
Vss	AM4
Vss	AL39
Vss	AL37
Vss	AL10
Vss	AL6
Vss	AL3
Vss	AL1
Vss	AJ39
Vss (60)	AJ37
Vss	AJ33
Vss	AJ29
Vss	AJ24
Vss	AJ19
Vss	AJ17
Vss	AJ11
Vss	AJ7
Vss	AJ3
Vss	AJ1
Vss (70)	AH24
Vss	AH19
Vss	AH17
Vss	AH11
Vss	AH7

**Table 6-1. PCH Ballout by Signal Name (Sheet 21 of 25)**

PCH Ball Name	Ball #
Vss	AG33
Vss	AF39
Vss	AF37
Vss	AF33
Vss	AF19
Vss (80)	AF18
Vss	AF10
Vss	AF6
Vss	AF3
Vss	AF1
Vss	AE28
Vss	AE26
Vss	AE25
Vss	AE23
Vss	AE22
Vss (90)	AE20
Vss	AE19
Vss	AE18
Vss	AE17
Vss	AE16
Vss	AE15
Vss	AE10
Vss	AE6
Vss	AD39
Vss	AD37
Vss (100)	AD33
Vss	AD30
Vss	AD3
Vss	AD1
Vss	AC33
Vss	AC11
Vss	AC7
Vss	AB28
Vss	AB26
Vss	AB25
Vss (110)	AB24
Vss	AB23



**Table 6-1. PCH Ballout by Signal Name (Sheet 22 of 25)**

PCH Ball Name	Ball #
Vss	AB22
Vss	AB20
Vss	AB19
Vss	AB18
Vss	AB17
Vss	AB16
Vss	AB15
Vss	AB11
Vss (120)	AB7
Vss	AA39
Vss	AA37
Vss	AA33
Vss	AA3
Vss	AA1
Vss	Y33
Vss	Y10
Vss	Y6
Vss	W39
Vss (130)	W37
Vss	W10
Vss	W6
Vss	W3
Vss	W1
Vss	V33
Vss	V28
Vss	V26
Vss	V25
Vss	V23
Vss (140)	V22
Vss	V20
Vss	V19
Vss	V18
Vss	V17
Vss	V16
Vss	V15
Vss	U33

**Table 6-1. PCH Ballout by Signal Name (Sheet 23 of 25)**

PCH Ball Name	Ball #
Vss	U11
Vss	U7
Vss (150)	T39
Vss	T37
Vss	T11
Vss	T7
Vss	T3
Vss	T1
Vss	R33
Vss	R30
Vss	R28
Vss	R26
Vss (160)	R24
Vss	R23
Vss	R20
Vss	R19
Vss	R18
Vss	R17
Vss	R16
Vss	R15
Vss	P33
Vss	P30
Vss (170)	P10
Vss	P6
Vss	N39
Vss	N37
Vss	N19
Vss	N10
Vss	N6
Vss	N3
Vss	N1
Vss	M33
Vss (180)	M29
Vss	M26
Vss	M22
Vss	M17

**Table 6-1. PCH Ballout by Signal Name (Sheet 24 of 25)**

PCH Ball Name	Ball #
Vss	M16
Vss	M15
Vss	L37
Vss	L22
Vss	L11
Vss	L7
Vss (190)	L3
Vss	L1
Vss	H39
Vss	H3
Vss	H1
Vss	G34
Vss	G33
Vss	G31
Vss	G30
Vss	G28
Vss (200)	G27
Vss	G25
Vss	G24
Vss	G22
Vss	G21
Vss	G19
Vss	G18
Vss	G16
Vss	G15
Vss	G13
Vss (210)	G12
Vss	G10
Vss	G9
Vss	G7
Vss	G6
Vss	G4
Vss	F37
Vss	F3
Vss	F1
Vss	D39



**Table 6-1. PCH Ballout by Signal Name (Sheet 25 of 25)**

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PCH Ball Name	Ball #
Vss (220)	D1
Vss	C34
Vss	C29
Vss	C26
Vss	C24
Vss	C21
Vss	C19
Vss	C16
Vss	C13
Vss	C11
Vss (230)	C8
Vss	C1
Vss	A36
Vss	A31
Vss	A29
Vss	A26
Vss	A24
Vss	A21
Vss	A19
Vss (240)	A16
Vss	A13
Vss	A11
Vss	A8
Vss	A6
Vss	A4
Vss	A3
Vss	T9
Vss	U30
Vss	M23
Vss (250)	W9
Vss	W8
Vss	N2
Vss	M3
Vss	B9
Vss	A10
WAKE#	J36



## 7 Package Information

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Refer to the *Intel® C600 Series Chipset Thermal and Mechanical Design Guidelines* or *Intel® X79 Express Chipset Thermal and Mechanical Design Guidelines* document for PCH package information.

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## 8 Electrical Characteristics

This chapter contains the DC and AC characteristics for the PCH. AC timing diagrams are included.

### 8.1 Thermal Specifications

Refer to the *Intel® C600 Series Chipset Thermal and Mechanical Design Guidelines* or *Intel® X79 Express Chipset Thermal and Mechanical Design Guidelines* document for PCH package information.

### 8.2 Absolute Maximum Ratings

**Table 8-1. PCH Absolute Maximum Ratings**

Parameter	Maximum Limits
Voltage on any 5 V Tolerant Pin with respect to Ground (V5REF = 5 V)	-0.5 to V5REF + 0.5 V
Voltage on any 3.3 V Pin with respect to Ground	-0.5 to Vcc3_3 + 0.4 V
Voltage on any 1.8 V Tolerant Pin with respect to Ground	-0.5 to VccVRM + 0.5 V
Voltage on any 1.5 V Pin with respect to Ground	-0.5 to VccVRM + 0.5 V
Voltage on any 1.1 V Tolerant Pin with respect to Ground	-0.5 to VccIO + 0.5 V
1.1 V Supply Voltage with respect to VSS	-0.5 to 1.3 V
1.8 V Supply Voltage with respect to VSS	-0.5 to 1.98 V
3.3 V Supply Voltage with respect to VSS	-0.5 to 3.7 V
5.0 V Supply Voltage with respect to VSS	-0.5 to 5.5 V
V_PROC_IO Supply Voltage with respect to VSS	-0.5 to 1.3 V
1.1 V Supply Voltage for the analog PLL with respect to VSS	-0.5 to 1.3 V
1.5 V Supply Voltage for the analog PLL with respect to VSS	-0.5 to 1.65 V
1.8 V Supply Voltage for the analog PLL with respect to VSS	-0.5 to 1.98 V

Table 8-1 specifies absolute maximum and minimum ratings. At conditions outside functional operation condition limits, but within absolute maximum and minimum ratings, neither functionality nor long-term reliability can be expected. If a device is returned to conditions within functional operation limits after having been subjected to conditions outside these limits (but within the absolute maximum and minimum ratings) the device may be functional, but with its lifetime degraded depending on exposure to conditions exceeding the functional operation condition limits.

At conditions exceeding absolute maximum and minimum ratings, neither functionality nor long-term reliability can be expected. Moreover, if a device is subjected to these conditions for any length of time, it will either not function or its reliability will be severely degraded when returned to conditions within the functional operating condition limits.

Although the PCH contains protective circuitry to resist damage from Electrostatic Discharge (ESD), precautions should always be taken to avoid high static voltages or electric fields.



### 8.3 PCH Power Supply Range

Table 8-2. PCH Power Supply Range

Power Supply	Minimum	Nominal	Maximum
1.0 V	0.95 V	1.00 V	1.05 V
1.05 V	0.998 V	1.05 V	1.10 V
1.1 V	1.05 V	1.10 V	1.16 V
1.5 V	1.43 V	1.50 V	1.58 V
1.8 V	1.71 V	1.80 V	1.89 V
3.3 V	3.14 V	3.30 V	3.47 V
5 V	4.75 V	5.00 V	5.25 V

### 8.4 General DC Characteristics

I<sub>CC</sub> values in Table 8-3 and Table 8-4 specifications have been validated using post-silicon measurements. These values are provided primarily for sizing platform VR solutions.

Table 8-3. Power Supply ICC Specifications by Domain (Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs)

Voltage Rail	Voltage (V)	S0 Iccmax Current <sup>3</sup> (A)	TDC MAX <sup>4</sup> (A)	TDC Typical <sup>5</sup> (A)	Sx Iccmax Current <sup>3</sup> (A)	Sx Idle Current <sup>6</sup> (A)	G3
V5REF	5	1 (mA)	1 (mA)	1 (mA)	-	-	-
V5REF_Sus	5	1 (mA)	1 (mA)	1 (mA)	< 1 (mA)	< 1 (mA)	-
Vcc3_3	3.3	0.17	0.02	0.02	-	-	-
VccSus3_3	3.3	0.08	0.04	0.03	0.15	0.05	-
Vcc <sup>1</sup>	1.1	7.95	5.55	4.05	-	-	-
VccASW	1.1	1.5	1.0	0.5	0.8	0.4	-
VccDSW	3.3	0.002	< 1 (mA)	< 1 (mA)	< 1 (mA)	< 1 (mA)	-
VccSAS	1.5	0.15	0.13	0.13	-	-	-
VccVRM <sup>2</sup>	1.5	0.2	0.12	0.11	-	-	-
V_PROC_IO	1.0 - 1.1	1(mA)	1(mA)	1(mA)	-	-	-
VccDMI	1.0 - 1.1	0.057	0.057	0.045	-	-	-
VccRTC	-	-	-	-	-	-	6 uA <sup>7,8</sup>

**Notes:**

- Vcc includes VccIO, VccCORE, and so forth, that are in the 1.1 V core well and typically supplied by a common VR source.
- VccVRM can optionally be used in 1.8 V mode.
- Iccmax currents define the operational maximums which must be provided by platform power delivery VR and traces (activity on worst-case 3-sigma manufacturing units).
- TDC currents represent steady-state consumption, by supply rail, for Full Feature TDP specifications. (Max) defines platform thermal solution necessary to support 3-sigma manufacturing variance,
- TDC (Typ) is representative consumption of volume units at Full-Feature TDP configuration.
- Sx Idle current is representative consumption of volume units at full idle (including Intel ME)
- G3 state shown to provide an estimate of battery life
- Icc (RTC) data is taken with VccRTC at 3.0 V while the system in a mechanical off (G3) state at room temperature.



**Table 8-4. Power Supply I<sub>CC</sub> Specifications by Domain (Intel® C606, C608 Chipset SKUs)**

Voltage Rail	Voltage	S0 Iccmax Current <sup>3</sup> (A)	TDC MAX <sup>4</sup> (A)	TDC Typical <sup>5</sup> (A)	Sx Iccmax Current <sup>3</sup> (A)	Sx Idle Current <sup>6</sup> (A)	G3
V5REF	5	1 (mA)	1 (mA)	1 (mA)	-	-	-
V5REF_Sus	5	1 (mA)	1 (mA)	1 (mA)	< 1 (mA)	< 1 (mA)	-
Vcc3_3	3.3	0.17	0.02	0.02	-	-	-
VccSus3_3	3.3	0.08	0.04	0.03	0.15	0.05	-
Vcc <sup>1</sup>	1.1	11.55	8.7	6.7	-	-	-
VccASW	1.1	1.5	1.0	0.46	0.8	0.4	-
VccDSW	3.3	0.002	< 1 (mA)	< 1 (mA)	< 1 (mA)	< 1 (mA)	-
VccSAS	1.5	0.28	0.26	0.26	-	-	-
VccVRM <sup>2</sup>	1.5	0.16	0.12	0.11	-	-	-
V_PROC_IO	1.0 - 1.1	1(mA)	1(mA)	1(mA)	-	-	-
VccDMI	1.0 - 1.1	0.057	0.057	0.045			-
VccRTC	-	-	-	-	-	-	6 uA <sup>7,8</sup>

**Notes:**

- Vcc includes VccIO, VccCORE, and so forth, that are in the 1.1 V core well & typically supplied by a common VR source.
- VccVRM can optionally be used in 1.8 V mode.
- Iccmax currents define the operational maximums which must be provided by platform power delivery VR and traces (peak activity on worst-case 3-sigma manufacturing units).
- TDC currents represent steady-state consumption, by supply rail, for Full Feature TDP specifications. (Max) defines platform thermal solution necessary to support 3-sigma manufacturing variance,
- TDC (Typ) is representative consumption of volume units at Full-Feature TDP configuration.
- Sx Idle current is representative consumption of volume units at full idle (includes Intel Management Engine)
- G3 state shown to provide an estimate of battery life
- Icc (RTC) data is taken with VccRTC at 3.0 V while the system in a mechanical off (G3) state at room temperature.

**Table 8-5. DC Characteristic Input Signal Association (Sheet 1 of 3)**

Symbol	Associated Signals
VIH1/VIL1 (5 V Tolerant)	<b>PCI Signals:</b> AD[31:0], C/BE[3:0]#, DEVSEL#, FRAME#, IRDY#, PAR, PERR#, PLOCK#, REQ[3:0]#, SERR#, STOP#, TRDY# <b>Interrupt Signals:</b> PIRQ[D:A]#, PIRQ[H:E]# <b>GPIO Signals:</b> GPIO[54, 52, 50, 5:2] <b>GSX Signals:</b> GSXDIN
VIMIN2-Gen3i/ VIMAX2-Gen3i	<b>SATA Signals:</b> SATA[1:0]RX[P,N] (6.0 Gb/s internal SATA)
VIH3/VIL3	<b>Clock Signals:</b> REFCLK14IN <b>Power Management Signals:</b> PWRBTN#, RI#, SYS_RESET#, WAKE#, SUSACK#. <b>GPIO Signals:</b> GPIO[71:68, 63:61, 57, 48, 39, 38, 34, 32, 31, 30, 29, 24, 22, 17, 7, 6, 1] <b>Thermal/Fan Control Signals:</b> TACH[7:0]
VIH4/VIL4	<b>Clock Signals:</b> CLKIN_PCI <b>Processor Signals:</b> A20GATE <b>PCI Signals:</b> PME# <b>Interrupt Signals:</b> SERIRQ <b>SATA Signals:</b> SATA[5:0]GP <b>SPI Signals:</b> SPI_MISO <b>Strap Signals:</b> SPKR, GNT[3:1]#, (Strap purposes only) <b>LPC Signals:</b> LAD[3:0], LDRQ0#, LDRQ1#, <b>GPIO Signals:</b> GPIO[73, 72, 67:64, 59, 56, 55, 53, 51, 49, 47:40, 37, 36, 35, 33, 28, 27, 26, 25, 23, 21, 20, 19, 18, 16, 15, 14, 12, 10, 9, 8, 0] <b>USB Signals:</b> OC[7:0]#



Table 8-5. DC Characteristic Input Signal Association (Sheet 2 of 3)

Symbol	Associated Signals
VIH5/VIL5	<b>SMBus Signals:</b> SMBCLK, SMBDATA, SMBALERT# <b>SAS SMBus Signals (SRV/WS SKUs Only):</b> SASSMBCLK0, SASSMBDATA0, SASSMBCLK1, SASSMBDATA1, SASSMBCLK2, SASSMBDATA2, <b>System Management Signals:</b> SML[1:0]CLK, SML[1:0]DATA <b>GPIO Signals:</b> GPIO[75, 74, 60, 58, 11]
VIH6/VIL6	<b>JTAG Signals:</b> JTAG_TDI, JTAG_TMS, JTAG_TCK
VIH7/VIL7	<b>Processor Signals:</b> THRMTRIP#
VIMIN8Gen1/ VIMAX8Gen1, VIMIN8Gen2/ VIMAX8Gen2,	<b>PCI Express* Data RX Signals:</b> PER[p,n][8:1] (2.5 GT/s and 5.0 GT/s)
VIH9/VIL9	<b>Real Time Clock Signals:</b> RTCX1
VIMIN10 -Gen1i/ VIMAX10-Gen1i	<b>SATA Signals:</b> SATA[5:0]RX[P,N] (1.5 Gb/s internal SATA)
VIMIN10 -Gen1m/ VIMAX10-Gen1m	<b>SATA Signals:</b> SATA[5:0]RX[P,N] (1.5 Gb/s external SATA)
VIMIN10 -Gen2i/ VIMAX10-Gen2i	<b>SATA Signals:</b> SATA[5:0]RX[P,N] (3.0 Gb/s internal SATA)
VIMIN10 -Gen2m/ VIMAX10-Gen2m	<b>SATA Signals:</b> SATA[5:0]RX[P,N] (3.0 Gb/s external SATA)
VIH11/VIL11	<b>Intel® High Definition Audio Signals:</b> HDA_SDIN[3:0] (3.3V Mode) <b>Strap Signals:</b> HDA_SDOOUT, HDA_SYNC (Strap purposes only) <b>GPIO Signals:</b> GPIO13  <b>Note:</b> See VIL_HDA/VIH_HDA for High Definition Audio Low Voltage Mode
VIH12 (Absolute Maximum) / VIL12 (Absolute Minimum) / Vclk_in_cross(abs)	<b>Clock Signals:</b> CLKIN_DMI_[P,N], CLKIN_DOT96[P,N], CLKIN_SATA_[P,N]
VIH13/VIL13	<b>Miscellaneous Signals:</b> RTCRST#
VIH14/VIL14	<b>Power Management Signals:</b> PCH_PWROK, RSMRST#, DPWROK <b>System Management Signals:</b> INTRUDER# <b>Miscellaneous Signals:</b> INTVRMEN, SRTCST#
VIH15/VIL15	<b>Processor Interface:</b> RCIN# <b>Power management Signals:</b> SYS_PWROK, APWROK
VIMIN16/VIMAX16 (SRV/WS SKUs Only)	<b>SAS Signals:</b> SAS[7:0]RX[P,N] (1.5 Gb/s)
VIMIN17/VIMAX17 (SRV/WS SKUs Only)	<b>SAS Signals:</b> SAS[7:0]RX[P,N] (3.0 Gb/s)
VIMIN18/VIMAX18 (Intel® C606, C608 Chipset SKUs Only)	<b>PCI Express* Uplink RX Signals:</b> PEGO_R[p,n][3:0]
VDI / VCM / VSE (5V Tolerant)	<b>USB Signals:</b> USBP[13:0][P,N] (Low-speed and Full-speed)
VHSSQ / VHSDSC / VHSCM (5 V Tolerant)	<b>USB Signals:</b> USBP[13:0][P,N] (in High-speed Mode)



**Table 8-5. DC Characteristic Input Signal Association (Sheet 3 of 3)**

Symbol	Associated Signals
VIH_HDA / VIL_HDA	<b>Intel High Definition Audio Signals:</b> HDA_SDIN[3:0] <b>Strap Signals:</b> HDA_SDOUT, HDA_SYNC (Strap purposes only) <b>Note:</b> Only applies when running in Low Voltage Mode (1.5 V)
VIH_SST/VIL_SST	<b>Thermal Reporting Signals:</b> SST
VIH_PECI/VIL_PECI	<b>Thermal Reporting Signals:</b> Peci
VIH_SASCLK/ VIL_SASCLK Vcm_sas (SRV/WS SKUs Only)	<b>SAS Clocks:</b> CLKIN_SAS0[P,N], CLKIN_SAS1[P,N]
VIH_UPCLK/ VIL_UPCLK Vcm_up (SRV/WS SKUs Only)	<b>PCIe* Uplink Clock:</b> CLKIN_SPCIE0[P,N]

**Table 8-6. DC Input Characteristics (Sheet 1 of 3)**

Symbol	Parameter	Min	Max	Unit	Notes
VIL1	Input Low Voltage	-0.5	0.3 x 3.3 V	V	9
VIH1	Input High Voltage	0.5 x 3.3 V	V5REF + 0.5	V	9
VIMIN2-Gen3i	Minimum Input Voltage - 6.0 Gb/s SATA	240	—	mVdiffp-p	5
VIMAX2-Gen3i	Maximum Input Voltage - 6.0 Gb/s SATA	—	1000	mVdiffp-p	5
VIL3	Input Low Voltage	-0.5	0.8	V	
VIH3	Input High Voltage	2.0	3.3 V + 0.5	V	9
VIL4	Input Low Voltage	-0.5	0.3 x 3.3 V	V	9
VIH4	Input High Voltage	0.5 x 3.3 V)	3.3 V + 0.5	V	9
VIL5	Input Low Voltage	-0.5	0.8	V	
VIH5	Input High Voltage	2.1	3.3 V + 0.5	V	9
VIL6	Input Low Voltage	-0.5	0.35	V	10
VIH6	Input High Voltage	0.75	1.1 V + 0.5	V	10
VIL7	Input Low Voltage	0	0.51 x V_PROC_IO	V	
VIH7	Input High Voltage	0.81 x V_PROC_IO	V_PROC_IO	V	
VIMIN8Gen1	Minimum Input Voltage	175	—	mVdiffp-p	4
VIMAX8Gen1	Maximum Input Voltage	—	1200	mVdiffp-p	4
VIMIN8Gen2	Minimum Input Voltage	100	—	mVdiffp-p	4
VIMAX8Gen2	Maximum Input Voltage	—	1200	mVdiffp-p	4
VIL9	Input Low Voltage	-0.5	0.10	V	
VIH9	Input High Voltage	0.50	1.2	V	
VIMIN10- Gen1i	Minimum Input Voltage - 1.5 Gb/s internal SATA	325	—	mVdiffp-p	5
VIMAX10-Gen1i	Maximum Input Voltage - 1.5 Gb/s internal SATA	—	600	mVdiffp-p	5



**Table 8-6. DC Input Characteristics (Sheet 2 of 3)**

Symbol	Parameter	Min	Max	Unit	Notes
VIMIN10-Gen1m	Minimum Input Voltage - 1.5 Gb/s eSATA	240	—	mVdiffp-p	5
VIMAX10-Gen1m	Maximum Input Voltage - 1.5 Gb/s eSATA	—	600	mVdiffp-p	5
VIMIN10-Gen2i	Minimum Input Voltage - 3.0 Gb/s internal SATA	275	—	mVdiffp-p	5
VIMAX10-Gen2i	Maximum Input Voltage - 3.0 Gb/s internal SATA	—	750	mVdiffp-p	5
VIMIN10-Gen2m	Minimum Input Voltage - 3.0 Gb/s eSATA	240	—	mVdiffp-p	5
VIMAX10-Gen2m	Maximum Input Voltage - 3.0 Gb/s eSATA	—	750	mVdiffp-p	5
VIL11	Input Low Voltage	-0.5	0.35 x 3.3 V	V	9
VIH11	Input High Voltage	0.65 x 3.3 V	3.3 + 0.5 V	V	9
VIL12 (Absolute Minimum)	Input Low Voltage	-0.3		V	
VIH12 (Absolute Maximum)	Input High Voltage		1.150	V	
VIL13	Input Low Voltage	-0.5	0.78	V	
VIH13	Input High Voltage	2.3	VccRTC + 0.5	V	6
VIL14	Input Low Voltage	-0.5	0.78	V	
VIH14	Input High Voltage	2.0	VccRTC + 0.5	V	6
VIL15	Input Low Voltage	-0.5	0.8	V	9
VIH15	Input High Voltage	2.1	3.3 V + 0.5	V	9
VIMIN16 (SRV/WS SKUs Only)	Minimum Input Voltage - 1.5 Gb/s SAS	325	—	mVdiffp-p	
VIMAX16 (SRV/WS SKUs Only)	Maximum Input Voltage - 1.5 Gb/s SAS	—	1600	mVdiffp-p	
VIMIN17 (SRV/WS SKUs Only)	Minimum Input Voltage - 3.0 Gb/s SAS	275	—	mVdiffp-p	
VIMAX17 (SRV/WS SKUs Only)	Maximum Input Voltage - 3.0 Gb/s SAS	—	1600	mVdiffp-p	
VIMIN18 (SRV/WS SKUs Only)	Minimum Input Voltage - PCIe Uplink	15	—	mVdiffp-p	
VIMAX18 (SRV/WS SKUs Only)	Maximum Input Voltage - PCIe Uplink	—	1200	mVdiffp-p	
Vclk_in_cross(a bs)	Absolute Crossing Point	0.250	0.550	V	11
Vcross-delta	Vcross variation		140	mV	11
VDI	Differential Input Sensitivity	0.2	—	V	1,3
VCM	Differential Common Mode Range	0.8	2.5	V	2,3
VSE	Single-Ended Receiver Threshold	0.8	2.0	V	3
VHSSQ	HS Squelch Detection Threshold	100	150	mV	
VHSDSC	HS Disconnect Detection Threshold	525	625	mV	



**Table 8-6. DC Input Characteristics (Sheet 3 of 3)**

Symbol	Parameter	Min	Max	Unit	Notes
VHSCM	HS Data Signaling Common Mode Voltage Range	-50	500	mV	
VIL_HDA	Input Low Voltage	0	0.4 x V <sub>cc_HDA</sub>	V	
VIH_HDA	Input High Voltage	0.6 x V <sub>cc_HDA</sub>	1.5	V	
VIL_SST	Input Low Voltage	-0.3	0.4	V	
VIH_SST	Input High Voltage	1.1	1.5	V	
VIL_PECI	Input Low Voltage	-0.15	0.275 x V <sub>PROC_IO</sub>	V	
VIH_PECI	Input High Voltage	0.725 x V <sub>PROC_IO</sub>	V <sub>PROC_IO</sub> + 0.15	V	
VIH_SASCLK (SRV/WS SKUs Only)	Differential Input High Voltage - SAS Clocks	150	—	mV	
VIH_SASCLK (SRV/WS SKUs Only)	Differential Input Low Voltage - SAS Clocks	—	-150	mV	
ERRefclk-diffRise, ERRefclk-diff-Fall	Differential Rising and falling edge rates	1	4	V/ns	12,13
VRB-diff	Differential ringback voltage	-100	100	mV	
VIL_UPCLK (SRV/WS SKUs Only)	Differential Input High Voltage - SAS Clocks	150	—	mV	
VIL_UPCLK (SRV/WS SKUs Only)	Differential Input Low Voltage - SAS Clocks	—	-150	mV	
ERRefclk-diffRise, ERRefclk-diff-Fall	Differential Rising and falling edge rates	1	4	V/ns	12,13
VRB-diff	Differential ringback voltage	-100	100	mV	

**Notes:**

1.  $V_{DI} = |USBPx[P] - USBPx[N]|$
2. Includes VDI range
3. Applies to Low-Speed/Full-Speed USB
4. PCI Express\* mVdiff p-p =  $2 * |PETp[x] - PETn[x]|$
5. SATA Vdiff, RX (VIMAX10/MIN10) is measured at the SATA connector on the receiver side (generally, the motherboard connector), where SATA mVdiff p-p =  $2 * |SATA[x]RXP - SATA[x]RXN|$
6. VccRTC is the voltage applied to the VccRTC well of the PCH. When the system is in a G3 state, this is generally supplied by the coin cell battery, but for S5 and greater, this is generally VccSus3\_3.
7. This is an AC Characteristic that represents transient values for these signals
8. Applies to High-Speed USB 2.0.
9. 3.3 V refers to VccSus3\_3 for signals in the suspend well and to Vcc3\_3 for signals in the core well. See Table 3-2, or Table 3-3 for signal and power well association.
10. 1.1 V refers to VccIO or VccCore for signals in the core well and to VccASW for signals in the Active Sleep well. See Table 3-2 or Table 3-3 for signal and power well association.
11. The Vcross and Vcross delta spec are not applicable to SAS and PCIe Uplink due to the presence of AC coupling capacitor. OEM's are encouraged to use vendor parts that meet Vcross and Vcross delta spec specified in the vendor datasheet on their respective test boards.
12. The SAS and Uplink receivers are more sensitive to the low end edge rate value 1 V/ns. Failures of edge rate spec on the higher side i.e failures of edge rate reported more than 4V/ns are acceptable up to 6V/ns and these high side failures up to 6V/ns are not required to be reported.
13. The rising edge of CLKIN\_SAS[0/1]\_DN is equal to the falling edge of CLKIN\_SAS[0/1]\_DP.



Table 8-7. DC Characteristic Output Signal Association (Sheet 1 of 2)

Symbol	Associated Signals
VOH1/VOL1	<b>Processor Signal:</b> PM_SYNC, PM_SYNC2, PROCPWRGD
VOH2/VOL2	<b>LPC Signals:</b> LAD[3:0], LFRAME#, INIT3_3V# <b>Power Management Signal:</b> LAN_PHY_PWR_CTRL <b>PCI Signals:</b> AD[31:0], C/BE[3:0], DEVSEL#, FRAME#, IRDY#, PAR, PCIRST#, GNT[3:0]#, PME#(1) <b>Interrupt Signals:</b> PIRQ[D:A], PIRQ[H:E]#(1) <b>GPIO Signals:</b> GPIO[73, 72, 59, 56, 55:50, 49, 47:44 43:40, 37, 36, 35, 33, 28, 27, 26, 25, 23, 21, 20, 19, 18, 16, 15, 14, 13, 12, 10, 9, 8, 5:2, 0] <b>SPI Signals:</b> SPI_CS0#, SPI_CS1#, SPI_MOSI, SPI_CLK <b>GSX Signals:</b> GSCLK, GSXSLOAD, GSXSRESET#, GSXDOUT <b>Miscellaneous Signals:</b> SPKR
VOH3/VOL3	<b>SMBus Signals:</b> SMBCLK(1), SMBDATA(1) <b>System Management Signals:</b> SML[1:0]CLK(1), SML[1:0]DATA(1), SML0ALERT#, SML1ALERT# <b>GPIO Signals:</b> GPIO[75, 74, 60, 58, 11]
VOH4/VOL4	<b>Power Management Signals:</b> SLP_S3#, SLP_S4#, SLP_S5#, SLP_A#, SLP_LAN#, SUSCLK, DRAMPWROK, SLP_SUS# <b>SATA Signals:</b> SATALED#, SCLOCK, SLOAD, SDATAOUT0, SDATAOUT1 <b>SAS SGPIO Signals (SRV/WS SKUs Only):</b> SAS_LED#, SAS_CLOCK1, SAS_LOAD1, SAS_DATAIN1, SAS_DATAOUT1, SAS_CLOCK2, SAS_LOAD2, SAS_DATAIN2, SAS_DATAOUT2 <b>GPIO Signals:</b> GPIO[71:68, 63:61, 57, 48, 39, 38, 34, 32, 31, 30, 29, 24, 22, 17, 7, 6, 1] <b>Interrupt Signals:</b> SERIRQ <b>ADR Signal:</b> ADR_COMPLETE
VOH5/VOL5	<b>USB Signals:</b> USBP[13:0][P,N] in Low-speed and Full-speed Modes
VOMIN6 -Gen3i/ VOMAX6-Gen3i	<b>SATA Signals:</b> SATA[1:0]TX[P,N] (6.0 Gb/s Internal SATA)
VOMIN7 -Gen1i,m/ VOMAX7-Gen1i,m	<b>SATA Signals:</b> SATA[5:0]TX[P,N] (1.5 Gb/s Internal and External SATA)
VOMIN7 -Gen2i,m/ VOMAX7-Gen2i,m	<b>SATA Signals:</b> SATA[5:0]TX[P,N] (3.0 Gb/s Internal and External SATA)
VOMIN8-PCIeGen12/ VOMAX8-PCIeGen12	<b>PCI Express* Data TX Signals:</b> PET[p,n][8:1] (Gen 1 and Gen 2)
VOH9/VOL9	<b>Power Management Signal:</b> PLTRST#
VOMIN10/VOMAX10 (SRV/WS SKUs Only)	<b>SAS Signals:</b> SAS[7:0]TX[P,N] (SAS-1.1)
VOMIN11/VOMAX11 (SRV/WS SKUs Only)	<b>SAS Signals:</b> SAS[7:0]TX[P,N] (SAS-2.0)
VOMIN12/VOMAX12 (Intel® C606, C608 Chipset SKUs Only)	<b>PCI Express* Uplink TX Signals:</b> PEG0_T[p,n][3:0]
VHSOI VHSOH VHSOL VCHIRPJ VCHIRPK	<b>USB Signals:</b> USBP[13:0][P: N] in High-speed Mode
VOH_HDA/VOL_HDA	<b>Intel High Definition Audio Signals:</b> HDA_RST#, HDA_SDOOUT, HDA_SYNC, HDA_BCLK
VOL_JTAG	<b>JTAG Signals:</b> JTAG_TDO
VOH_PCICLK/ VOL_PCICLK	<b>GPIO Signals:</b> [67:64]
VOL_SGPIO	<b>SGPIO Signals:</b> SCLOCK, SLOAD, SDATAOUT0, SDATAOUT1



**Table 8-7. DC Characteristic Output Signal Association (Sheet 2 of 2)**

Symbol	Associated Signals
VOH_PWM/ VOL_PWM	<b>Thermal Control Signals:</b> PWM[3:0] <sup>1</sup>
VOH_SST/VOL_SST	<b>SST signal:</b> SST
VOH_PECI/VOL_PECI	<b>PECI signal:</b> PECI

**Note:**

1. These signals are open-drain.

**Table 8-8. DC Output Characteristics (Sheet 1 of 2)**

Symbol	Parameter	Min	Max	Unit	I <sub>OL</sub> / I <sub>OH</sub>	Notes
VOL1	Output Low Voltage	—	0.255	V	3 mA	
VOH1	Output High Voltage	V_PROC_IO - 0.3	V_PROC_IO	V	-3 mA	
VOL2	Output Low Voltage	—	0.1 x 3.3 V	V	1.5 mA	7
VOH2	Output High Voltage	0.9 x 3.3 V	3.3	V	-0.5 mA	7
VOL3	Output Low Voltage	0	0.4	V		
VOH3	Output High Voltage	3.3 V - 0.5	—	V	4 mA	1, 7
VOL4	Output Low Voltage	—	0.4	V	6 mA	
VOH4	Output High Voltage	3.3 V - 0.5	3.3 V	V	-2 mA	7
VOL5	Output Low Voltage	—	0.4	V	5 mA	
VOH5	Output High Voltage	3.3 V - 0.5	—	V	-2 mA	7
VOMIN6-Gen3i	Minimum Output Voltage	200	—	mVdiff p-p		3
VOMAX6-Gen3i	Maximum Output Voltage	—	900	mVdiff p-p		3
VOMIN7-Gen1i,m	Minimum Output Voltage	400	—	mVdiff p-p		3
VOMAX7-Gen1i,m	Maximum Output Voltage	—	600	mVdiff p-p		3
VOMIN7-Gen2i,m	Minimum Output Voltage	400	—	mVdiff p-p		3
VOMAX7-Gen2i,m	Maximum Output Voltage	—	700	mVdiff p-p		3
VOMIN8-PCIeGen12	Output Low Voltage	800	—	mVdiff p-p		2
VOMAX8-PCIeGen12	Output High Voltage	—	1200	mVdiff p-p		2
VOL9	Output Low Voltage	—	0.1 x 3.3 V	V	1.5 mA	7
VOH9	Output High Voltage	0.9 x 3.3 V	3.3	V	-2.0 mA	7
VOMIN10	Minimum Output Voltage	800	—	mVdiff p-p		
VOMAX10	Maximum Output Voltage	—	1600	mVdiff p-p		
VOMIN11	Minimum Output Voltage	850	—	mVdiff p-p		
VOMAX11	Maximum Output Voltage	—	1200	mVdiff p-p		
VOMIN12	Minimum Output Voltage	250	—	mVdiff p-p		



**Table 8-8. DC Output Characteristics (Sheet 2 of 2)**

Symbol	Parameter	Min	Max	Unit	I <sub>OL</sub> / I <sub>OH</sub>	Notes
VOMAX12	Maximum Output Voltage	—	1200	mVdiff p-p		
VHSOI	HS Idle Level	-10.0	10.0	mV		
VHSOH	HS Data Signaling High	360	440	mV		
VHSOL	HS Data Signaling Low	-10.0	10.0	mV		
VCHIRPJ	Chirp J Level	700	1100	mV		
VCHIRPK	Chirp K Level	-900	-500	mV		
VOL_HDA	Output Low Voltage	—	0.1 x VccSusHDA	V	1.5 mA	
VOH_HDA	Output High Voltage	0.9 x VccSusHDA	—	V	-0.5 mA	
VOL_PWM	Output Low Voltage	—	0.4	V	8 mA	
VOH_PWM	Output High Voltage	—	—			1
VOL_SGPIIO	Output Low Voltage	—	0.4	V		
VOL_PCICLK	Output Low Voltage		0.4	V	-1 mA	
VOH_PCICLK	Output High Voltage	2.4		V	1 mA	
VOL_SST	Output Low Voltage	0	0.3	V	0.5 mA	
VOH_SST	Output High Voltage	1.1	1.5	V	-6 mA	
VOL_PECI	Output Low Voltage	—	0.25 x V_PROC_IO	V	0.5 mA	
VOH_PECI	Output High Voltage	0.75 x V_PROC_IO	V_PROC_IO		-6 mA	
VOL_HDA	Output Low Voltage	—	0.1 x VccHDA	V	1.5 mA	
VOL_JTAG	Output Low Voltage	0	0.1 x 1.05 V	V	1.5 mA	

**Notes:**

1. The SERR#, PIRQ[H:A], SMBDATA, SMBCLK, SML[1:0]CLK, SML[1:0]DATA, SML[1:0]ALERT# and PWM[3:0] signal has an open-drain driver and SATALED# has an open-collector driver, and the VOH spec does not apply. This signal must have external pull up resistor.
2. PCI Express\* mVdiff p-p = 2\*|PETp[x] - PETn[x]|
3. SATA Vdiff, tx (V<sub>OMIN7</sub>/V<sub>OMAX7</sub>) is measured at the SATA connector on the transmit side (generally, the motherboard connector), where SATA mVdiff p-p = 2\*|SATA[x]TXP - SATA[x]TXN|
4. Maximum I<sub>ol</sub> for PROCPWRGD is 12mA for short durations (<500 mS per 1.5 s) and 9 mA for long durations.
5. For INIT3\_3V only, for low current devices, the following applies: V<sub>OL5</sub> Max is 0.15 V at an I<sub>OL5</sub> of 2 mA.
6. 3.3 V refers to VccSus3\_3 for signals in the suspend well, to Vcc3\_3 for signals in the core well and to VccDSW3\_3 for those signals in the Deep Sleep well. See Table 3-2 or Table 3-3 for signal and power well association.
7. 3.3 V refers to VccSus3\_3 for signals in the suspend well and to Vcc3\_3 for signals in the core well and to VccDSW3\_3 for signals in the ME well. See Table 3-2, or Table 3-3 for signal and power well association.

**Table 8-9. Other DC Characteristics (Sheet 1 of 2)**

Symbol	Parameter	Min	Nom	Max	Unit	Notes
V_PROC_IO	Processor I/F	.95	1.0 - 1.1	1.16	V	1
V5REF	PCH Core Well Reference Voltage	4.75	5	5.25	V	1
Vcc3_3	I/O Buffer Voltage	3.14	3.3	3.47	V	1
VccVRM	1.5 V Internal PLL and VRMs	1.455	1.5	1.545	V	1, 3
VccVRM	1.8 V Internal PLL and VRMs	1.746	1.8	1.854	V	1, 3
V5REF_Sus	Suspend Well Reference Voltage	4.75	5	5.25	V	1
VccSus3_3	Suspend Well I/O Buffer Voltage	3.14	3.3	3.47	V	1
VccCore	Internal Logic Voltage	1.05	1.1	1.16	V	1
VccIO	Core Well I/O buffers	1.05	1.1	1.16	V	1
VccDMI	DMI Buffer Voltage	.95	1.0 - 1.1	1.16	V	1
VccSPI	3.3 V Supply for SPI Controller Logic	3.14	3.3	3.47	V	1



Table 8-9. Other DC Characteristics (Sheet 2 of 2)

Symbol	Parameter	Min	Nom	Max	Unit	Notes
VccASW	1.1 V Supply for Intel ME and Interated LAN	1.05	1.1	1.16	V	1
VccRTC (G3-S0)	Battery Voltage	2	—	3.47	V	1
VccSusHDA	High Definition Audio Controller Suspend Voltage	3.14	3.3	3.47	V	1
VccSusHDA (low voltage)	High Definition Audio Controller Low Voltage Mode Suspend Voltage	1.43	1.5	1.58	V	1
VccDFTERM	1.8V supply power supply for DF_TV5	1.71	1.8	1.89	V	1
VccDSW3_3	3.3v supply for Deep S4/S5 wells	3.14	3.3	3.47	V	1
VccRBIAS_PU (Intel® C606, C608 Chipset SKUs Only)	PCIe Uplink RBIAS Voltage	1.05	1.1	1.15	V	4
VccRBIAS_SAS0 (SRV/WS SKUs Only)	SAS0 RBIAS Voltage	1.05	1.1	1.15	V	4
VccRBIAS_SAS1 (SRV/WS SKUs Only)	SAS1 RBIAS Voltage	1.05	1.1	1.15	V	4
VccPLLEXPU (Intel® C606, C608 Chipset SKUs Only)	PCIe Uplink PLL Voltage	1.05	1.1	1.15	V	4
VccPLLSAS0 (SRV/WS SKUs Only)	SAS0 PLL Voltage	1.05	1.1	1.15	V	4
VccPLLSAS1 (SRV/WS SKUs Only)	SAS1 PLL Voltage	1.05	1.1	1.15	V	4
I <sub>LI1</sub>	PCI_3V Hi-Z State Data Line Leakage	-10	—	10	μA	(0 V < V <sub>IN</sub> < V <sub>cc3_3</sub> )
I <sub>LI2</sub>	PCI_5V Hi-Z State Data Line Leakage	-70	—	70	μA	Max V <sub>IN</sub> = 2.7 V Min V <sub>IN</sub> = 0.5 V
I <sub>LI3</sub>	Input Leakage Current – All Other	-10	—	10	μA	2
C <sub>IN</sub>	Input Capacitance – All Other	—	—	TBD	pF	F <sub>C</sub> = 1 MHz
C <sub>OUT</sub>	Output Capacitance	—	—	TBD	pF	F <sub>C</sub> = 1 MHz
C <sub>I/O</sub>	I/O Capacitance	—	—	10	pF	F <sub>C</sub> = 1 MHz
		<b>Typical Value</b>				
CL	XTAL25_IN	3			pF	
CL	RTCX1	6			pF	
CL	RTCX2	6			pF	

**Notes:**

- The I/O buffer supply voltage is measured at the PCH package pins. The tolerances shown in Table 8-9 are inclusive of all noise from DC up to 20 MHz. In testing, the voltage rails should be measured with a bandwidth limited oscilloscope that has a rolloff of 3 dB/decade above 20 MHz.
- Includes Single Ended clocks REFCLK14IN, and CLKIN\_PCI.
- Includes only DC tolerance. AC tolerance will be 2% in addition to this range.
- Includes both DC and AC tolerance. For optimal effect, Min/Max value should be within 3% of the nominal value.



## 8.5 AC Characteristics

**Table 8-10. PCI Express\* and DMI Interface Timings**

Symbol	Parameter	Min	Max	Unit	Figures	Notes
<b>Transmitter and Receiver Timings</b>						
UI	Unit Interval – PCI Express* Gen 1 (2.5 GT/s)	399.88	400.12	ps		5
UI	Unit Interval – PCI Express Gen 2 (5.0 GT/s)	199.9	200.1	ps		5
UI	Unit Interval – DMI	399.88	400.12	ps		5
T <sub>TX-EYE</sub>	Minimum Transmission Eye Width	0.7	—	UI	8-25	1,2
T <sub>TX-RISE/Fall (Gen1)</sub>	D+/D- TX Out put Rise/Fall time	-0.125		UI		1,2
T <sub>TX-RISE/Fall (Gen2)</sub>	D+/D- TX Out put Rise/Fall time	-0.15		UI		1,2
T <sub>RX-EYE</sub>	Minimum Receiver Eye Width	0.40	—	UI	8-26	3,4

**Notes:**

- Specified at the measurement point into a timing and voltage compliance test load and measured over any 250 consecutive TX UIs. (Also refer to the Transmitter compliance eye diagram)
- A T<sub>TX-EYE</sub> = 0.70 UI provides for a total sum of deterministic and random jitter budget of T<sub>TXJITTER-MAX</sub> = 0.30 UI for the Transmitter collected over any 250 consecutive TX UIs. The T<sub>TXEYE-MEDIAN-to-MAX-JITTER</sub> specification ensures a jitter distribution in which the median and the maximum deviation from the median is less than half of the total TX jitter budget collected over any 250 consecutive TX UIs. It should be noted that the median is not the same as the mean. The jitter median describes the point in time where the number of jitter points on either side is approximately equal as opposed to the averaged time value.
- Specified at the measurement point and measured over any 250 consecutive UIs. The test load documented in the PCI Express\* specification 2.0 should be used as the RX device when taking measurements (also refer to the Receiver compliance eye diagram). If the clocks to the RX and TX are not derived from the same reference clock, the TX UI recovered from 3500 consecutive UI must be used as a reference for the eye diagram.
- A T<sub>RX-EYE</sub> = 0.40 UI provides for a total sum of 0.60 UI deterministic and random jitter budget for the Transmitter and interconnect collected any 250 consecutive UIs. The T<sub>RX-EYE-MEDIAN-to-MAX-JITTER</sub> specification ensures a jitter distribution in which the median and the maximum deviation from the median is less than half of the total 0.6 UI jitter budget collected over any 250 consecutive TX UIs. It should be noted that the median is not the same as the mean. The jitter median describes the point in time where the number of jitter points on either side is approximately equal as opposed to the averaged time value. If the clocks to the RX and TX are not derived from the same reference clock, the TX UI recovered from 3500 consecutive UI must be used as the reference for the eye diagram.
- Nominal Unit Interval is 400 ps for 2.5 GT/s and 200 ps for 5 GT/s.

**Table 8-11. PCI Express\* Uplink Interface Timings (Intel® C606, C608 Chipset SKUs Only)**

Symbol	Parameter	Min	Max	Unit	Figures	Notes
<b>Transmitter and Receiver Timings</b>						
UI	Unit Interval	124.96	125.04	ps		1
T <sub>RX-EYE</sub>	Minimum Receiver Eye Width	0.3		UI		

**Note:**

- The specified UI is equivalent to a tolerance of ±300 ppm for each reference clock source.



Table 8-12. SAS Interface Timings (SRV/WS SKUs Only)

Sym	Parameter	Min	Max	Units	Notes	Figure
UI	Gen I Operating Data Period	666.43	670.23	ps		
UI-2	Gen II Operating Data Period (3Gb/s)	333.21	335.11	ps		
UI-OOB	OOB Operating Data period	665.07	668.27	ns		
t120	Rise Time	0.15	0.41	UI		
t121	Fall Time	0.15	0.41	UI		
t122	TX differential skew	—	20	ps		
t123	COMRESET	310.4	329.6	ns		
t124	COMWAKE transmit spacing	103.5	109.9	ns		
t125	COMSAS transmit spacing	931.2	988.8	ns		

Table 8-13. Clock Timings (Sheet 1 of 2)

Sym	Parameter	Min	Max	Unit	Notes	Figure
<b>REFCLK14IN</b>						
t6	Period	69.820	69.862	ns		
t7	High time	29.975	38.467	ns		
t8	Low time	29.975	38.467	ns		
	Duty Cycle	40	60	%		
	Rising Edge Rate	1.0	4	V/ns		
	Falling Edge Rate	1.0	4	V/ns		
	Jitter	—	800	ps		
<b>SMBus/SMLink Clock (SMBCLK, SML[1:0]CLK)</b>						
f <sub>smb</sub>	Operating Frequency	10	100	KHz	5	
t22	High time	4.0	50	μs	1	8-20
t23	Low time	4.7	—	μs		8-20
t24	Rise time	—	1000	ns		8-20
t25	Fall time	—	300	ns		8-20
<b>SMLink0 Clock (SML0CLK) (See note 7)</b>						
f <sub>smb</sub>	Operating Frequency	0	400	KHz		
t22_SML	High time	0.6	50	ms	2	8-20
t23_SML	Low time	1.3	—	ms		8-20
t24_SML	Rise time	—	300	ns		8-20
t25_SML	Fall time	—	300	ns		8-20
<b>HDA_BCLK (Intel High Definition Audio)</b>						
f <sub>HDA</sub>	Operating Frequency	24.0		MHz		
	Frequency Tolerance	—	100	ppm		
t26a	C2C Jitter (refer to Clock Chip Specification)	—	300	ppm		
t27a	High Time (Measured at 0.75 Vcc)	18.75	22.91	ns		8-11
t28a	Low Time (Measured at 0.35 Vcc)	18.75	22.91	ns		8-11



Table 8-13. Clock Timings (Sheet 2 of 2)

Sym	Parameter	Min	Max	Unit	Notes	Figure
<b>SATA Clock (CLKIN_SATA_[P:N]) from a Clock Chip</b>						
t36(ssc-on)	Period	9.999	10.05	ns		
t36(ssc-off)	Period	9.999	10.001	ns		
	Slew rate	1	8	V/ns		
	C2C Jitter (refer to Clock Chip Specification)		50	ps	3	
<b>DMI Clock (CLKIN_DMI_[P:N]) from a Clock Chip</b>						
tDMI(ssc-on)	Period	9.999	10.05	ns		
tDMI(ssc-off)	Period	9.999	10.001	ns		
	Slew rate	1	4	V/ns		
	clock duty cycle	45	55	%		
	VRB-Diff	-100	100	mV		
Tstable		500		ps		
<b>PCIe* Uplink and SAS Clock (CLKIN_SPCIE0_[P:N], CLKIN_SAS[1:0]_[P:N]) from a Clock Chip (PCIe* Uplink is Intel® C606, C608 Chipset SKUs Only and SAS Clock is SRV/WS Only)</b>						
tUplink(ssc-on)	Period	9.999	10.05	ns		
tUplink(ssc-off)	Period	9.999	10.001	ns		
tSAS(ssc-off only)	Period	9.999	10.001	ns		
	slew rate	1	4	V/ns	7	
	clock duty cycle	45	55	%		
Tstable		500		ps		
<b>DOT 96 MHz (CLKIN_DOT96[P,N]) from a clock chip</b>						
t36	Period	10.066	10.768	ns		
	Slew rate	1	8	V/ns		
	C2C Jitter (refer to Clock Chip Specification)		250	ps	3	
<b>Suspend Clock (SUSCLK)</b>						
f <sub>susclk</sub>	Operating Frequency	32		kHz	2	
t39	High Time	10	—	μs	2	
t39a	Low Time	10	—	μs	2	
<b>SPI_CLK</b>						
Slew_Rise	Output Rise Slew Rate (0.2Vcc - 0.6Vcc)	1	4	V/ns	4	8-22
Slew_Fall	Output Fall Slew Rate (0.6Vcc - 0.2Vcc)	1	4	V/ns	4	8-22

**Notes:**

- The maximum high time (t18 Max) provide a simple ensured method for devices to detect bus idle conditions.
- SUSCLK duty cycle can range from 30% minimum to 70% maximum.
- Jitter is specified as cycle to cycle measured in pico seconds. Period min and max includes cycle to cycle jitter
- Testing condition: 1 kohm pull up to Vcc, 1 kohm pull down and 10 pF pull down and 1/2 inch trace See [Figure 8-28](#) for more detail.
- When the PCH communicates to BMC using SMLINK signal, up to 400 kHz clock frequency can be supported.
- When SMLink0 is configured to run in Fast Mode using a soft strap, the operating frequency is in the range of 300 KHz-400 KHz.



- The SAS and Uplink receivers are more sensitive to the low end edge rate value 1 V/ns. Failures of edge rate spec on the higher side i.e failures of edge rate reported more than 4 V/ns are acceptable up to 6 V/ns and these high side failures up to 6V/ns are not required to be reported.

**Table 8-14. PCI Interface Timing**

Sym	Parameter	Min	Max	Units	Notes	Figure
t40	AD[31:0] Valid Delay	2	11	ns	1	8-12
t41	AD[31:0] Setup Time to PCICLK Rising	7	—	ns		8-13
t42	AD[31:0] Hold Time from PCICLK Rising	0	—	ns		8-13
t43	C/BE[3:0]#, FRAME#, TRDY#, IRDY#, STOP#, PAR, PERR#, PLOCK#, DEVSEL# Valid Delay from PCICLK Rising	2	11	ns	1	8-12
t44	C/BE[3:0]#, FRAME#, TRDY#, IRDY#, STOP#, PAR, PERR#, PLOCK#, IDSEL, DEVSEL# Output Enable Delay from PCICLK Rising	2		ns		8-16
t45	C/BE[3:0]#, FRAME#, TRDY#, IRDY#, STOP#, PERR#, PLOCK#, DEVSEL#, GNT[A:B]# Float Delay from PCICLK Rising	2	28	ns		8-14
t46	C/BE[3:0]#, FRAME#, TRDY#, IRDY#, STOP#, SERR#, PERR#, DEVSEL#, Setup Time to PCICLK Rising	7		ns		8-13
t47	C/BE[3:0]#, FRAME#, TRDY#, IRDY#, STOP#, SERR#, PERR#, DEVSEL#, REQ[A:B]# Hold Time from PCLKIN Rising	0	—	ns		8-13
t48	PCIRST# Low Pulse Width	1		ms		8-15
t49	GNT[3:0]# Valid Delay from PCICLK Rising	2	12	ns		
t50	REQ[3:0]# Setup Time to PCICLK Rising	12	—	ns		

**Note:**

- Refer to note 3 of table 4-4 in Section 4.2.2.2 and note 2 of table 4-6 in Section 4.2.3.2 of the *PCI Local Bus Specification*, Revision 2.3, for measurement details.

**Table 8-15. Universal Serial Bus Timing (Sheet 1 of 2)**

Sym	Parameter	Min	Max	Units	Notes	Fig
<b>Full-speed Source (Note 7)</b>						
t100	USBPx+, USBPx- Driver Rise Time	4	20	ns	1, 6 C <sub>L</sub> = 50 pF	8-17
t101	USBPx+, USBPx- Driver Fall Time	4	20	ns	1, 6 C <sub>L</sub> = 50 pF	8-17
t102	Source Differential Driver Jitter - To Next Transition - For Paired Transitions	-3.5 -4	3.5 4	ns ns	2, 3	8-18
t103	Source SEO interval of EOP	160	175	ns	4	8-19
t104	Source Jitter for Differential Transition to SEO Transition	-2	5	ns	5	
t105	Receiver Data Jitter Tolerance - T o Next Transition - For Paired Transitions	-18.5 -9	18.5 9	ns ns	3	8-18
t106	EOP Width: Must accept as EOP	82	—	ns	4	8-19
t107	Width of SEO interval during differential transition	—	14	ns		
<b>Low-speed Source (Note 8)</b>						

**Table 8-15. Universal Serial Bus Timing (Sheet 2 of 2)**

Sym	Parameter	Min	Max	Units	Notes	Fig
<b>Full-speed Source (Note 7)</b>						
t108	USBPx+, USBPx – Driver Rise Time	75	300	ns	<sup>6</sup> C <sub>L</sub> = 200pF C <sub>L</sub> = 600pF	8-17
t109	USBPx+, USBPx – Driver Fall Time	75	300	ns	<sup>6</sup> C <sub>L</sub> = 200pF C <sub>L</sub> = 600pF	8-17
t110	Source Differential Driver Jitter To Next Transition For Paired Transitions	-25 -14	25 14	ns ns	2, 3	8-18
t111	Source SEO interval of EOP	1.25	1.50	µs	4	8-19
t112	Source Jitter for Differential Transition to SEO Transition	-40	100	ns	5	
t113	Receiver Data Jitter Tolerance - To Next Transition- For Paired Transitions	-152 -200	152 200	ns ns	3	8-18
t114	EOP Width: Must accept as EOP	670	—	ns	4	8-19
t115	Width of SEO interval during differential transition	—	210	ns		

**Notes:**

1. Driver output resistance under steady state drive is specified at 28 Ω at minimum and 43 Ω at maximum.
2. Timing difference between the differential data signals.
3. Measured at crossover point of differential data signals.
4. Measured at 50% swing point of data signals.
5. Measured from last crossover point to 50% swing point of data line at leading edge of EOP.
6. Measured from 10% to 90% of the data signal.
7. Full-speed Data Rate has minimum of 11.97 Mb/s and maximum of 12.03 Mb/s.
8. Low-speed Data Rate has a minimum of 1.48 Mb/s and a maximum of 1.52 Mb/s.

**Table 8-16. SATA Interface Timings**

Sym	Parameter	Min	Max	Units	Notes	Figure
UI	Gen I Operating Data Period	666.43	670.23	ps		
UI-2	Gen II Operating Data Period (3Gb/s)	333.21	335.11	ps		
UI-3	Gen III Operating Data Period (6Gb/s)	166.6667	166.6083	ps		
t120gen1	Rise Time	0.15	0.41	UI	1	
t120gen2	Rise Time	0.2	0.41	UI	1	
t120gen3	Rise Time	0.2	0.41	UI	1	
t121gen1	Fall Time	0.15	0.41	UI	2	
t121gen2	Fall Time	0.2	0.41	UI	2	
t121gen3	Fall Time	0.2	0.48	UI	2	
t122	TX differential skew	—	20	ps		
t123	COMRESET	310.4	329.6	ns	3	
t124	COMWAKE transmit spacing	103.5	109.9	ns	3	
t125	OOB Operating Data period	646.67	686.67	ns	4	

**Notes:**

1. 20% – 80% at transmitter
2. 80% – 20% at transmitter
3. As measured from 100 mV differential crosspoints of last and first edges of burst.
4. Operating data period during Out-Of-Band burst transmissions.



Table 8-17. SMBus and SMLink Timing

Sym	Parameter	Min	Max	Units	Notes	Fig
t130	Bus Free Time Between Stop and Start Condition	4.7	—	µs		8-20
t130 <sub>SMLFM</sub>	Bus Free Time Between Stop and Start Condition	1.3	—	µs	5	8-20
t131	Hold Time after (repeated) Start Condition. After this period, the first clock is generated.	4.0	—	µs		8-20
t131 <sub>SMLFM</sub>	Hold Time after (repeated) Start Condition. After this period, the first clock is generated.	0.6	—	µs	5	8-20
t132	Repeated Start Condition Setup Time	4.7	—	µs		8-20
t132 <sub>SMLFM</sub>	Repeated Start Condition Setup Time	0.6	—	µs	5	8-20
t133	Stop Condition Setup Time	4.0	—	µs		8-20
t133 <sub>SMLFM</sub>	Stop Condition Setup Time	0.6	—	µs	5	8-20
t134	Data Hold Time	0	—	ns	4	8-20
t134 <sub>SMLFM</sub>	Data Hold Time	0	—	ns	4, 5	8-20
t135	Data Setup Time	250	—	ns		8-20
t135 <sub>SMLFM</sub>	Data Setup Time	100	—	ns	5	8-20
t136	Device Time Out	25	35	ms	1	
t137	Cumulative Clock Low Extend Time (slave device)	—	25	ms	2	8-21
t138	Cumulative Clock Low Extend Time (master device)	—	10	ms	3	8-21

**Notes:**

1. A device will timeout when any clock low exceeds this value.
2. t137 is the cumulative time a slave device is allowed to extend the clock cycles in one message from the initial start to stop. If a slave device exceeds this time, it is expected to release both its clock and data lines and reset itself.
3. t138 is the cumulative time a master device is allowed to extend its clock cycles within each byte of a message as defined from start-to-ack, ack-to-ack or ack-to-stop.
4. t134 has a minimum timing for I<sup>2</sup>C of 0 ns, while the minimum timing for SMBus is 300 ns.
5. Timings with the SMLFM designator apply only to SMLink0 and only when SMLink0 is operating in Fast Mode.

Table 8-18. Intel® High Definition Audio Timing

Sym	Parameter	Min	Max	Units	Notes	Fig
t143	Time duration for which HDA_SDO is valid before HDA_BCLK edge.	7	—	ns		8-23
t144	Time duration for which HDA_SDO is valid after HDA_BCLK edge.	7	—	ns		8-23
t145	Setup time for HDA_SDIN[3:0] at rising edge of HDA_BCLK	15	—	ns		8-23
t146	Hold time for HDA_SDIN[3:0] at rising edge of HDA_BCLK	0	—	ns		8-23

Table 8-19. LPC Timing (Sheet 1 of 2)

Sym	Parameter	Min	Max	Units	Notes	Fig
t150	LAD[3:0] Valid Delay from PCICLK Rising	2	11	ns		8-12
t151	LAD[3:0] Output Enable Delay from PCICLK Rising	2		ns		8-16
t152	LAD[3:0] Float Delay from PCICLK Rising	—	28	ns		8-14
t153	LAD[3:0] Setup Time to PCICLK Rising	7	—	ns		8-13
t154	LAD[3:0] Hold Time from PCICLK Rising	0	—	ns		8-13



**Table 8-19. LPC Timing (Sheet 2 of 2)**

Sym	Parameter	Min	Max	Units	Notes	Fig
t155	LDRQ[1:0]# Setup Time to PCICLK Rising	12	—	ns		8-13
t156	LDRQ[1:0]# Hold Time from PCICLK Rising	0	—	ns		8-13
t157	eE# Valid Delay from PCICLK Rising	2	12	ns		8-12

**Table 8-20. Miscellaneous Timings**

Sym	Parameter	Min	Max	Units	Notes	Fig
t160	SERIRQ Setup Time to PCICLK Rising	7	—	ns		8-13
t161	SERIRQ Hold Time from PCICLK Rising	0	—	ns		8-13
t162	RI#, GPIO, USB Resume Pulse Width	2	—	RTCCLK		8-15
t163	SPKR Valid Delay from OSC Rising	—	200	ns		8-12
t164	SERR# Active to NMI Active	—	200	ns		

**Table 8-21. SPI Timings (20 MHz)**

Sym	Parameter	Min	Max	Units	Notes	Fig
t180a	Serial Clock Frequency - 20M Hz Operation	17.06	18.73	MHz	1	
t183a	Tco of SPI_MOSI with respect to serial clock falling edge at the host	-5	13	ns		8-22
t184a	Setup of SPI_MISO with respect to serial clock falling edge at the host	16	—	ns		8-22
t185a	Hold of SPI_MISO with respect to serial clock falling edge at the host	0	—	ns		8-22
t186a	Setup of SPI_CS[1:0]# assertion with respect to serial clock rising at the host	30	—	ns		8-22
t187a	Hold of SPI_CS[1:0]# deassertion with respect to serial clock falling at the host	30	—	ns		8-22
t188a	SPI_CLK high time	26.37	—	ns		8-22
t189a	SPI_CLK low time	26.82	—	ns		8-22

**Notes:**

1. The typical clock frequency driven by the PCH is 17.86 MHz.
2. Measurement point for low time and high time is taken at 0.5 (VccSUS3\_3).

**Table 8-22. SPI Timings (33 MHz) (Sheet 1 of 2)**

Sym	Parameter	Min	Max	Units	Notes	Fig
t180b	Serial Clock Frequency - 33 MHz Operation	29.83	32.81	MHz	1	
t183b	Tco of SPI_MOSI with respect to serial clock falling edge at the host	-5	5	ns		8-22
t184b	Setup of SPI_MISO with respect to serial clock falling edge at the host	8	—	ns		8-22
t185b	Hold of SPI_MISO with respect to serial clock falling edge at the host	0	—	ns		8-22
t186b	Setup of SPI_CS[1:0]# assertion with respect to serial clock rising at the host	30	—	ns		8-22



Table 8-22. SPI Timings (33 MHz) (Sheet 2 of 2)

Sym	Parameter	Min	Max	Units	Notes	Fig
t187b	Hold of SPI_CS[1:0]# deassertion with respect to serial clock falling at the host	30	—	ns		8-22
t188b	SPI_CLK High time	14.88	-	ns		8-22
t189b	SPI_CLK Low time	15.18	-	ns		8-22

**Notes:**

1. The typical clock frequency driven by the PCH is 31.25 MHz.
2. Measurement point for low time and high time is taken at 0.5 (VccSUS3\_3).

Table 8-23. SPI Timings (50 MHz)

Sym	Parameter	Min	Max	Units	Notes	Fig
t180c	Serial Clock Frequency - 50 MHz Operation	46.99	53.40	MHz	1	8-22
t183c	Tco of SPI_MOSI with respect to serial clock falling edge at the host	-3	3	ns		8-22
t184c	Setup of SPI_MISO with respect to serial clock falling edge at the host	8	-	ns		8-22
t185c	Hold of SPI_MISO with respect to serial clock falling edge at the host	0	-	ns		8-22
t186c	Setup of SPI_CS[1:0]# assertion with respect to serial clock rising edge at the host	30	-	ns		8-22
t187c	Hold of SPI_CS[1:0]# assertion with respect to serial clock rising edge at the host	30	-	ns		8-22
t188c	SPI_CLK High time	7.1	-	ns	2, 3	8-22
t189c	SPI_CLK Low time	11.17	-	ns	2, 3	8-22

**Notes:**

1. Typical clock frequency driven by the PCH is 50 MHz. This frequency is not available for ES1 samples.
2. When using 50 MHz mode ensure target flash component can meet t188c and t189c specifications.
3. Measurement point for low time and high time is taken at 0.5 (VccSUS3\_3).

Table 8-24. SST Timings

Sym	Parameter	Min	Max	Units	Notes	Fig
t <sub>BIT</sub>	Bit time (overall time evident on SST) Bit time driven by an originator	0.495 0.495	500 250	μs μs	1	-
t <sub>BIT,jitter</sub>	Bit time jitter between adjacent bits in an SST message header or data bytes after timing has been negotiated	—	—	%		
t <sub>BIT,drift</sub>	Change in bit time across a SST address or SST message bits as driven by the originator. This limit only applies across t <sub>BIT-A</sub> bit drift and t <sub>BIT-M</sub> drift.	—	—	%		
t <sub>H1</sub>	High level time for logic '1'	0.6	0.8	x t <sub>BIT</sub>	2	
t <sub>H0</sub>	High level time for logic '0'	0.2	0.4	x t <sub>BIT</sub>		
t <sub>SSTR</sub>	Rise time (measured from V <sub>OL</sub> = 0.3V to V <sub>IH,min</sub> )	—	25 + 5	ns/ node		
t <sub>SSTF</sub>	Fall time (measured from V <sub>OH</sub> = 1.1V to V <sub>IL,max</sub> )	—	33	ns/ node		

**Notes:**

1. The originator must drive a more restrictive time to allow for quantized sampling errors by a client yet still attain the minimum time less than 500 μs. t<sub>BIT</sub> limits apply equally to t<sub>BIT-A</sub> and t<sub>BIT-M</sub>. PCH is targeted on 1 Mbps which is 1 μs bit time.
2. The minimum and maximum bit times are relative to t<sub>BIT</sub> defined in the Timing Negotiation pulse.
3. t<sub>BIT-A</sub> is the negotiated address bit time and t<sub>BIT-M</sub> is the negotiated message bit time.

**Table 8-25. PECl Timings**

Sym	Parameter	Min	Max	Units	Notes	Fig
t <sub>BIT</sub>	Bit time (overall time evident on PECl)	0.495	500	μs	1	
	Bit time driven by an originator	0.495	250	μs		
t <sub>BIT,jitter</sub>	Bit time jitter between adjacent bits in an PECl message header or data bytes after timing has been negotiated	—	—	%		
t <sub>BIT,drift</sub>	Change in bit time across a PECl address or PECl message bits as driven by the originator. This limit only applies across t <sub>BIT-A</sub> bit drift and t <sub>BIT-M</sub> drift.	—	—	%		
t <sub>H1</sub>	High level time for logic '1'	0.6	0.8	x t <sub>BIT</sub>	2	
t <sub>H0</sub>	High level time for logic '0'	0.2	0.4	x t <sub>BIT</sub>		
t <sub>PECIR</sub>	Rise time (measured from VOL to VIH,min, Vtt(nom) -5%)	—	30 + (5 x NNODES)	ns	3	
t <sub>PECIF</sub>	Fall time (measured from VOH to VIL,max, Vtt(nom) +5%)	—	30 x NNODES	ns	3	

**Notes:**

1. The originator must drive a more restrictive time to allow for quantized sampling errors by a client yet still attain the minimum time less than 500 μs. t<sub>BIT</sub> limits apply equally to t<sub>BIT-A</sub> and t<sub>BIT-M</sub>. PCH is targeted on 2 MHz which is 500 ns bit time.
2. The minimum and maximum bit times are relative to t<sub>BIT</sub> defined in the Timing Negotiation pulse.
3. Extended trace lengths may appear as additional nodes.
4. t<sub>BIT-A</sub> is the negotiated address bit time and t<sub>BIT-M</sub> is the negotiated message bit time.

## 8.6 Power Sequencing and Reset Signal Timings

**Table 8-26. Power Sequencing and Reset Signal Timings (Sheet 1 of 3)**

Sym	Parameter	Min	Max	Units	Notes	Fig
t200	VccRTC active to RTCRST# deassertion	9	—	ms	23	8-1, 8-2
t200a	RTCRST# deassertion to DPWROK high	1	—	ms		8-1, 8-2
t200b	VccDSW3_3 active to DPWROK high	10	—	ms		8-1, 8-2
t200c	VccDSW3_3 active to VccSus3_3 active	0	—	ms		8-1, 8-2
t201	VccSUS active to RSMRST# deassertion	10	—	ms	1	8-1, 8-2
t202	DPWROK high to SLP_SUS# deassertion	95	—	ms	2, 3	8-1, 8-2
t202a	RSMRST# and SLP_SUS# deassertion to SUSCLK toggling	5	—	ms	3, 4	8-1, 8-2
t203	SLP_S5# high to SLP_S4# high	30	—	us	5, 24	8-3
t204	SLP_S4# high to SLP_S3# high	30	—	us	6	8-3
t205	Vcc active to PCH_PWROK active	10	—	ms	7, 14	8-3, 8-4
t206	PCH_PWROK deglitch time	1	—	ms	8	8-3, 8-4
t207	VccASW active to APWROK high	1	—	ms		8-3
t208	Clock chip clock outputs to PCH_PWROK high	1	—	ms		8-3, 8-4



**Table 8-26. Power Sequencing and Reset Signal Timings (Sheet 2 of 3)**

Sym	Parameter	Min	Max	Units	Notes	Fig	
t209	PCH_PWROK active to PROCPWRGD active	1		ms		8-3, 8-4	
t210	PROCPWRGD and SYS_PWROK high to PLTRST# deassertion	1.06		ms		8-3, 8-4	
t212	APWROK high to SPI Soft-Strap Reads	500	—	µs	22	8-5	
t214	DMI message and all PCI Express* ports and DMI in L2/L3 state to PLTRST# active	270		us		8-6	
t217	PLTRST# active to PROCPWRGD inactive	30		us		8-6	
t218	PROCPWRGD inactive to SLP_S3# assertion	11		us		8-6	
t220	SLP_S3# low to SLP_S4# low	30		us		8-6	
t221	SLP_S4# low to SLP_S5# low	30		us		8-6	
t222	SLP_S3# active to PCH_PWROK deasserted	0				8-6	
t223	PCH_PWROK rising to DRAMPWRGD rising	0		us		8-8	
t224	DRAMPWRGD falling to SLP_S4# falling	-100		ns	12	8-8	
t225	VccRTC active to VccDSW3_3 active	0	—	ms	1, 13	8-2	
t227	VccSUS active to VccASW active	0		ms	1		
t229	VccASW active to Vcc active	0		ms			
t230	APWROK high to PCH_PWROK high	0		ms			
t231	PCH_PWROK low to Vcc falling	40		ns	14, 15, 16		
t232	APWROK falling to VccASW falling	40		ns	16		
t233	SLP_S3# assertion to VccCore rail falling	5		us	14, 15		
t234	DPWROK falling to VccDSW rail falling	40		ns		8-7	
t235	RSMRST# assertion to VccSUS falling	40		ns	1, 15, 16	8-7	
t236	RTCST# assertion to VccRTC falling	0		ms		8-7	
t237	SLP_LAN# (or LANPHYPC) rising to Intel LAN Phy power high and stable		20	ms			
t238	DPWROK falling to any of VccDSW, VccSUS, VccASW, or Vcc falling	40		ns	1, 14, 15, 16		
t239	V5REF_Sus active to VccSus3_3 active	0	—	ms	17		
t240	V5REF active to Vcc3_3 active	See Note 15	—	ms	17		
t241	VccSus supplies active to Vcc supplies active	0	—	ms	1, 14		
t242	HDA_RST# active low pulse width	1	—	µs			
t244	VccSus active to SLP_S5#, SLP_S4#, SLP_S3#, PLTRST# and PCIRST# valid	—	50	ns	21		
t246	S4 Wake Event to SLP_S4# inactive (S4 Wake)	See Note Below				5	
t247	S3 Wake Event to SLP_S3# inactive (S3 Wake)	See Note Below				6	
t251	RSMRST# deassertion to APWROK assertion	0		ms			



Table 8-26. Power Sequencing and Reset Signal Timings (Sheet 3 of 3)

Sym	Parameter	Min	Max	Units	Notes	Fig
t252	THRMTrip# active to SLP_S3#, SLP_S4#, SLP_S5# active		175	ns		
t253	RSMRST# rising edge transition from 20% to 80%		50	µs		
t254	RSMRST# falling edge transition		50	µs	19, 20	

**Notes:**

1. VccSus supplies include VccSus3\_3, V5REF\_Sus, VccSusHDA.
2. This timing is a nominal value counted using RTC clock. If RTC clock isn't already stable at the rising edge of RSMRST#, this timing could be longer than the specified value.
3. Platforms not supporting Deep S4/S5 will typically have SLP\_SUS# left as no connect. Hence DPWROK high and RSMRST# deassertion to SUSCLK toggling would be t202+t202a=100ms minimum
4. Platforms supporting Deep S4/S5 will have SLP\_SUS# deassert prior to RSMRST#. Platforms not supporting Deep S4/S5 will have RSMRST# deassert prior to SLP\_SUS#.
5. Dependency on SLP\_S4# and SLP\_A# stretching
6. Dependency on SLP\_S3# and SLP\_A# stretching
7. It is required that the power rails associated with PCI/PCIe (typically the 3.3 V, 5 V, and 12 V core well rails) have been valid for 99 ms prior to PCH\_PWROK assertion in order to comply with the 100 ms PCI/PCIe 2.0 specification on PLTRST# deassertion. System designers must ensure the requirement is met on the platforms.
8. Ensure PCH\_PWROK is a solid logic '1' before proceeding with the boot sequence. Note: If PCH\_PWROK drops after t206 it will be considered a power failure.
9. Not Applicable for PCH.
10. Not Applicable for PCH.
11. Requires SPI messaging to be completed.
12. The negative min timing implies that DRAMPWRGD must either fall before SLP\_S4# or within 100 ns after it.
13. The VccDSW3\_3 supplies must never be active while the VccRTC supply is inactive.
14. Vcc includes VccIO, VccCORE, Vcc3\_3, Vcc1\_1, V5REF, V\_PROC\_IO, VccDMI and VccASW (if Intel® ME only powered in S0).
15. A Power rail is considered to be inactive when the rail is at its nominal voltage minus 5% or less.
16. Board design may meet (t231 AND t232 AND t235) OR (t238).
17. V5REF must be powered up before Vcc3\_3, or after Vcc3\_3 within 0.7 V. Also, V5REF must power down after Vcc3\_3, or before Vcc3\_3 within 0.7 V. V5REF\_Sus must be powered up before VccSus3\_3, or after VccSus3\_3 within 0.7 V. Also, V5REF\_Sus must power down after VccSus3\_3, or before VccSus3\_3 within 0.7 V.
18. If RTC clock is not already stable at RSMRST# rising edge, this time may be longer.
19. RSMRST# falling edge must transition to 0.8 V or less before VccSus3\_3 drops to 2.9 V
20. The 50 µs should be measured from Vih to Vil (2 V to 0.78 V).
21. This is an internal timing showing when the signals (SLP\_S5#, SLP\_S4#, SLP\_S3#, PLTRST# and PCIRST#) are valid after VccSus rail is Active.
22. APWROK high to SPI Soft-Start Read is an internal PCH timing. The timing cannot be measured externally and included here for general power sequencing reference.
23. Measured from VccRTC-10% to RTCRST# reaching 55%\*VccRTC. VccRTC is defined as the final settling voltage that the rail ramps.
24. Timing does not apply after Deep S3/S4 exit when Intel ME has configured SLP\_S5# and/or SLP\_S4# to rise with SLP\_A#.



## 8.7 Power Management Timing Diagrams

Figure 8-1. G3 w/RTC Loss to S4/S5 (With Deep S4/S5 Support) Timing Diagram

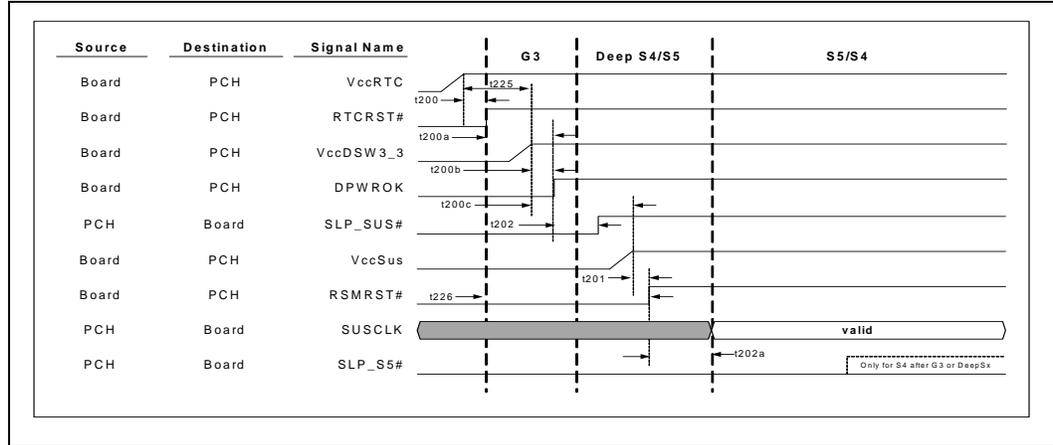
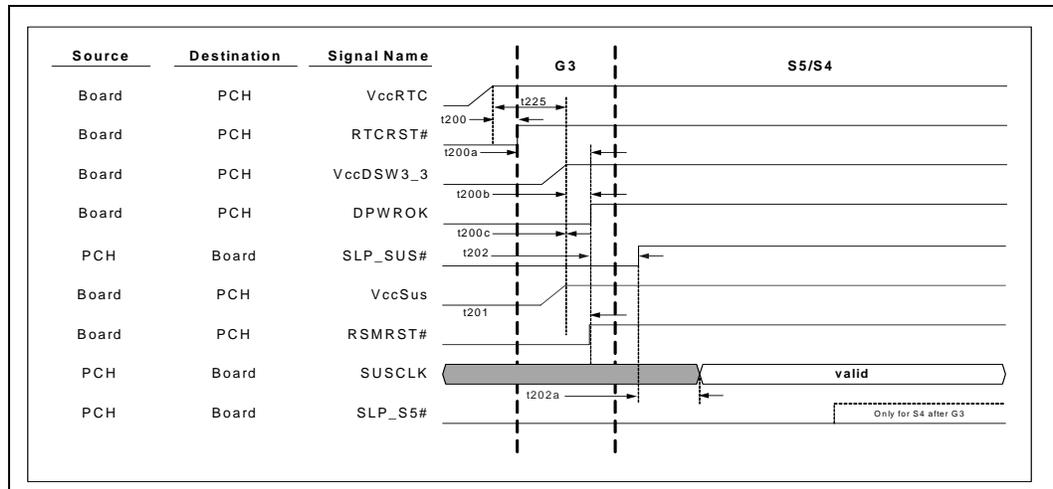


Figure 8-2. G3 w/RTC Loss to S4/S5 (Without Deep S4/S5 Support) Timing Diagram



**Note:** VccSus rail ramps up later in comparison to VccDSW due to assumption that SLP\_SUS# is used to control power to VccSus.

Figure 8-3. S5 to S0 Timing Diagram

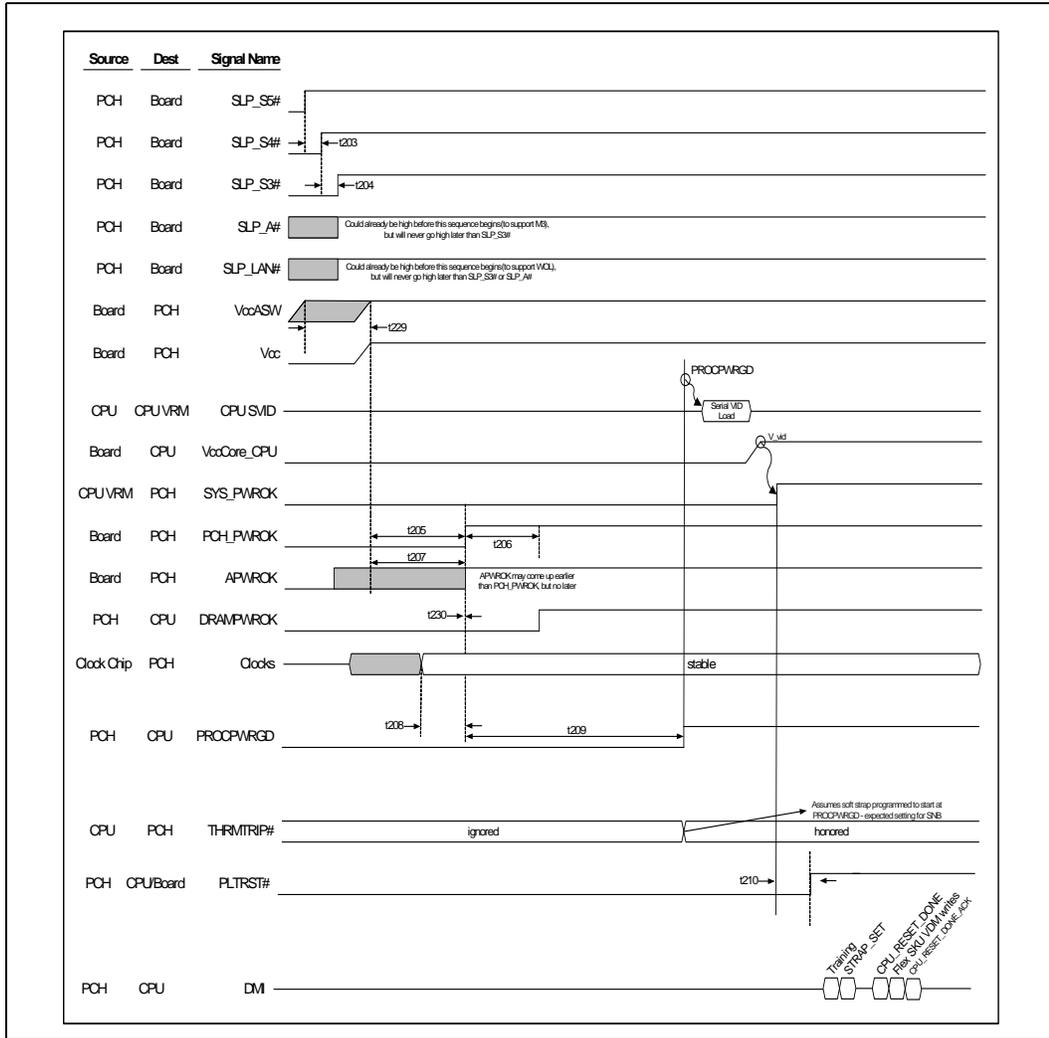




Figure 8-4. S3/M3 to S0 Timing Diagram

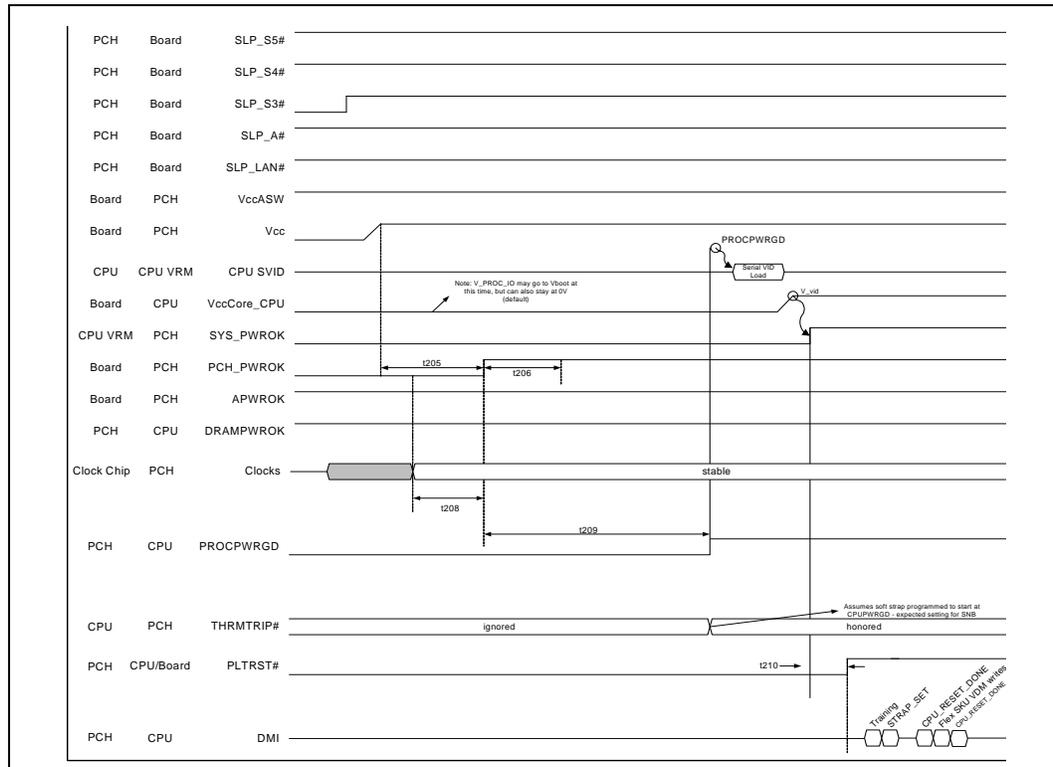


Figure 8-5. S5/Moff - S5/M3 Timing Diagram

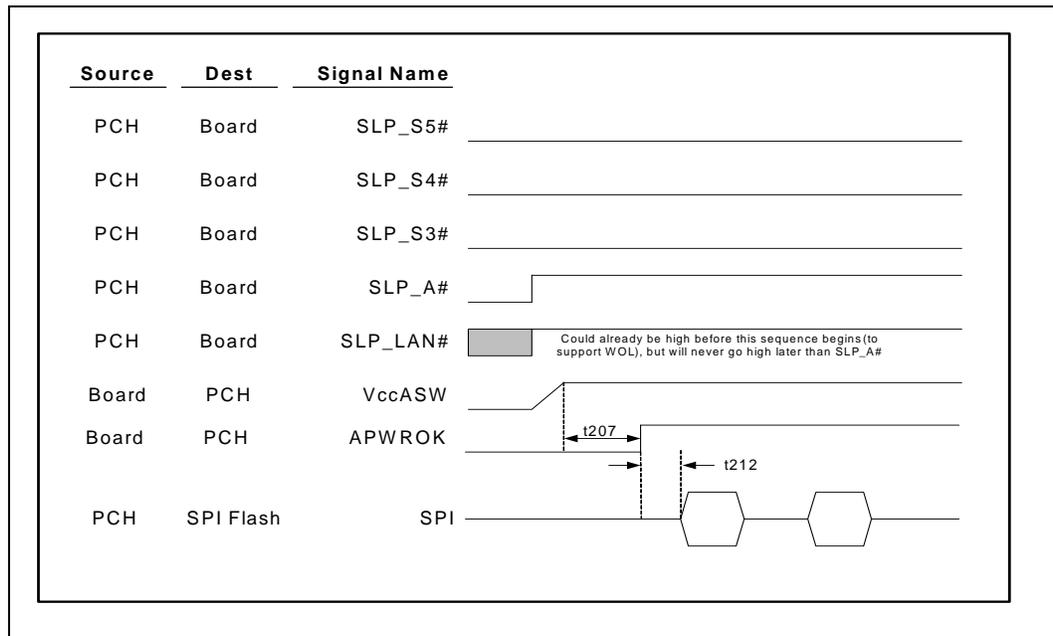
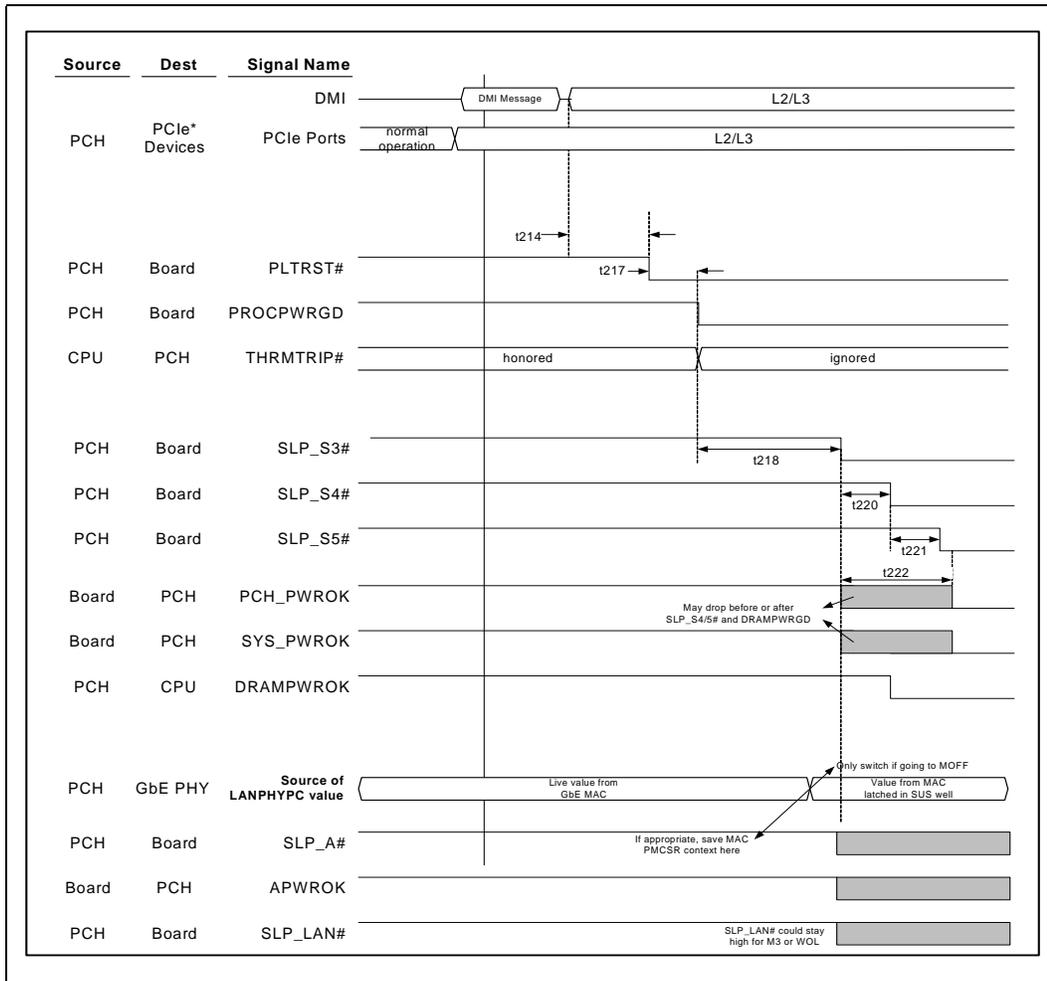
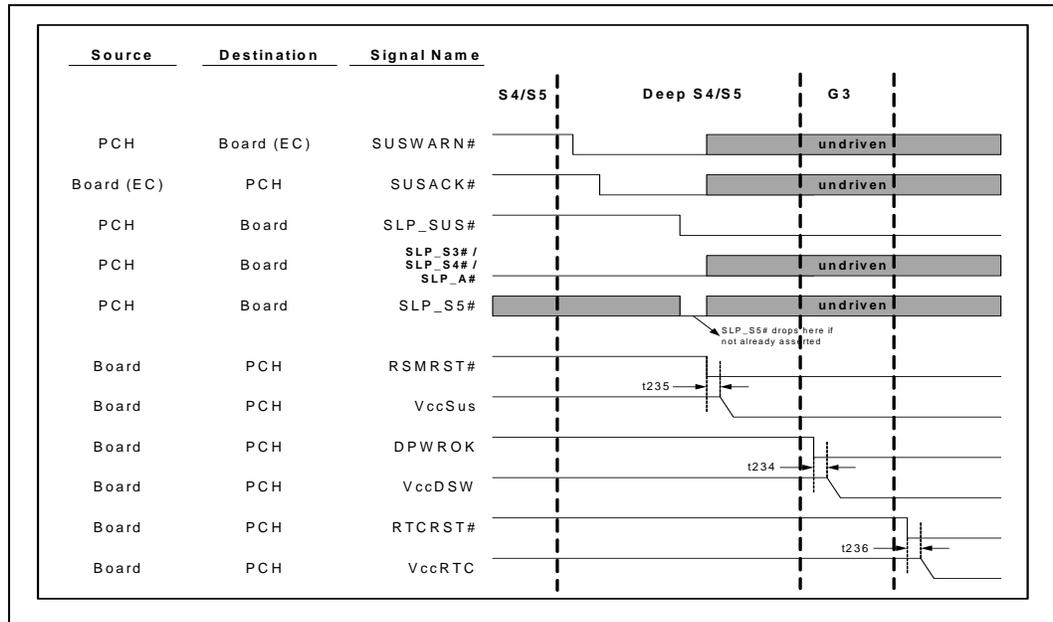


Figure 8-6. S0 to S5 Timing Diagram

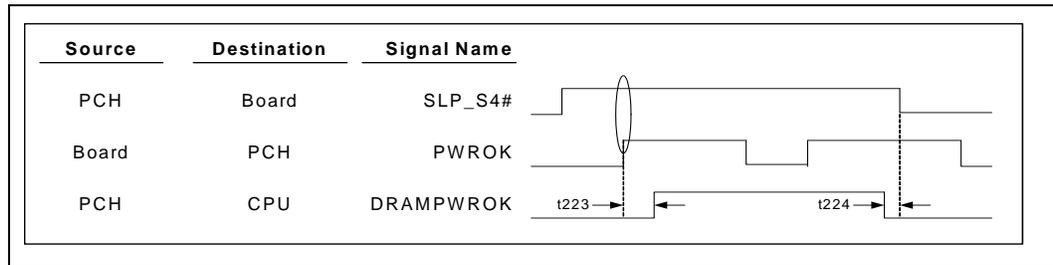




**Figure 8-7. S4/S5 to Deep S4/S5 to G3 w/ RTC Loss Timing Diagram**

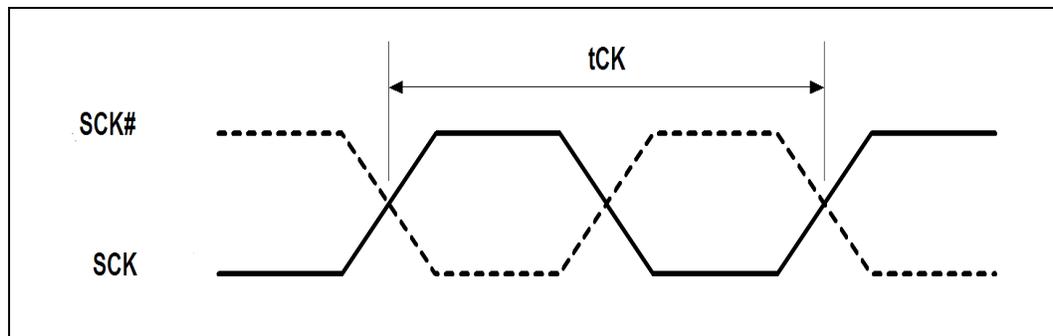


**Figure 8-8. DRAMPWROK Timing Diagram**

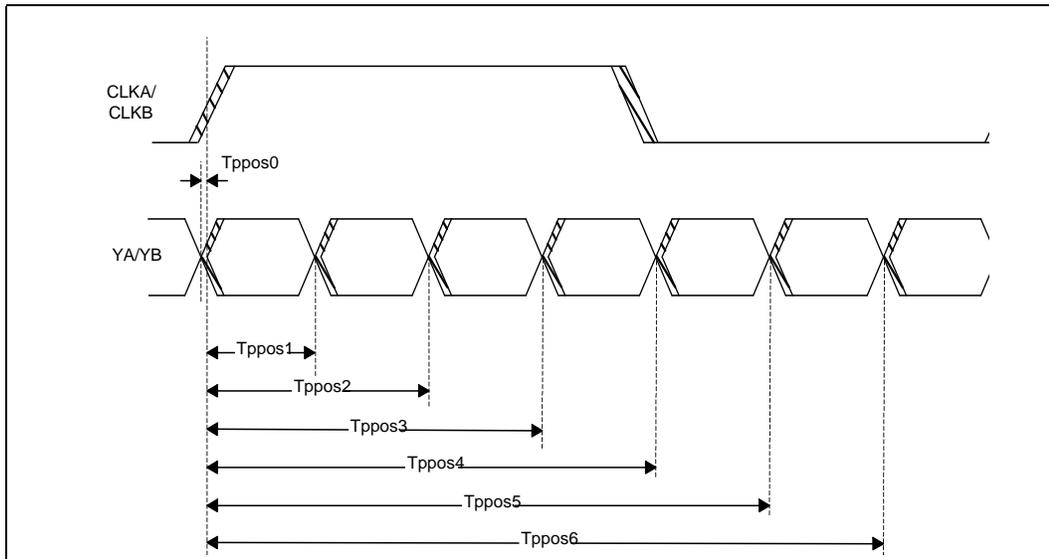


## 8.8 AC Timing Diagrams

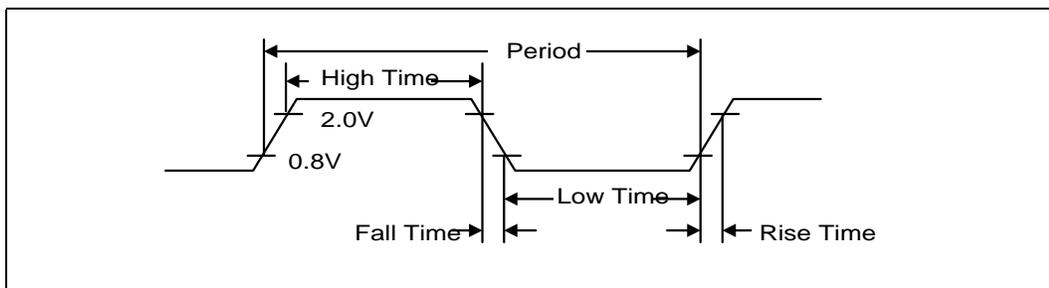
**Figure 8-9. Clock Cycle Time**



**Figure 8-10. Transmitting Position (Data to Strobe)**



**Figure 8-11. Clock Timing**



**Figure 8-12. Valid Delay from Rising Clock Edge**

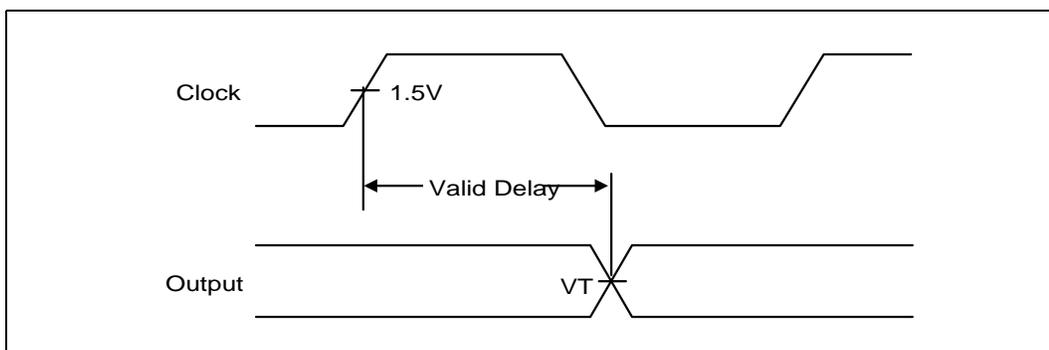




Figure 8-13. Setup and Hold Times

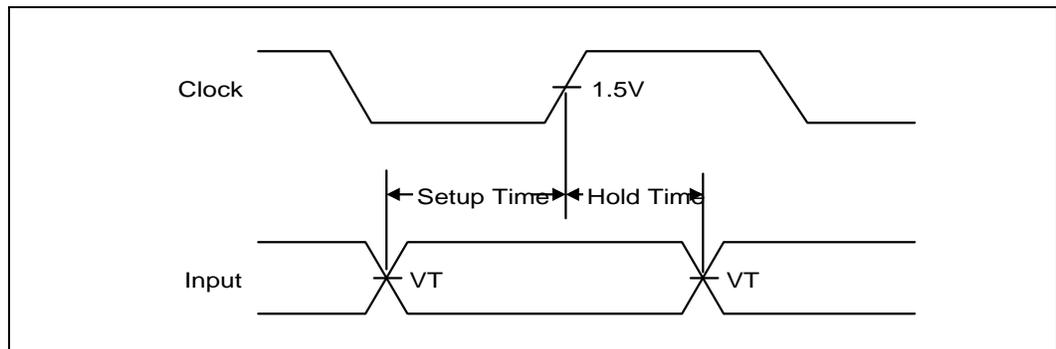


Figure 8-14. Float Delay

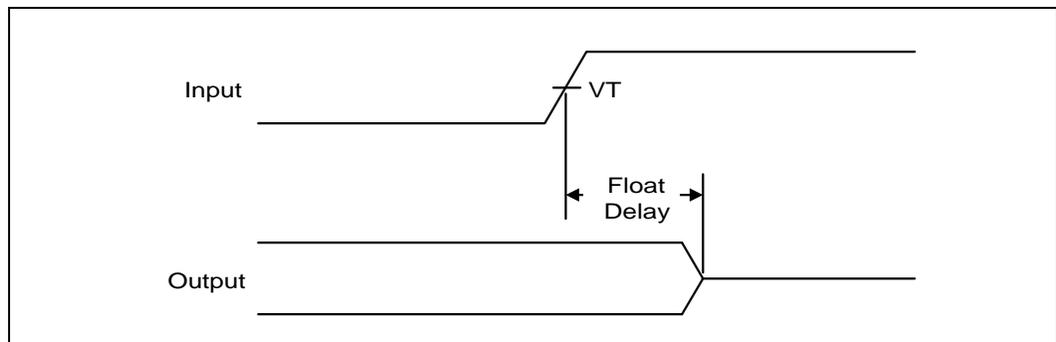


Figure 8-15. Pulse Width

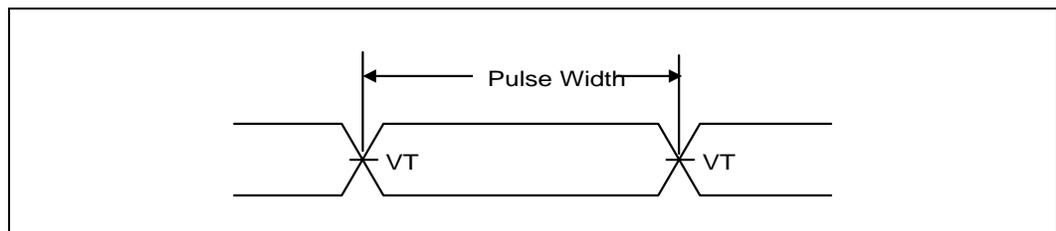


Figure 8-16. Output Enable Delay

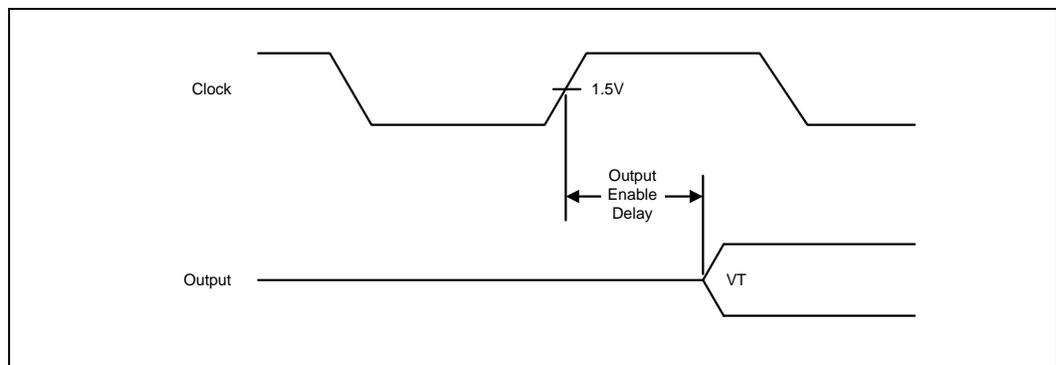


Figure 8-17. USB Rise and Fall Times

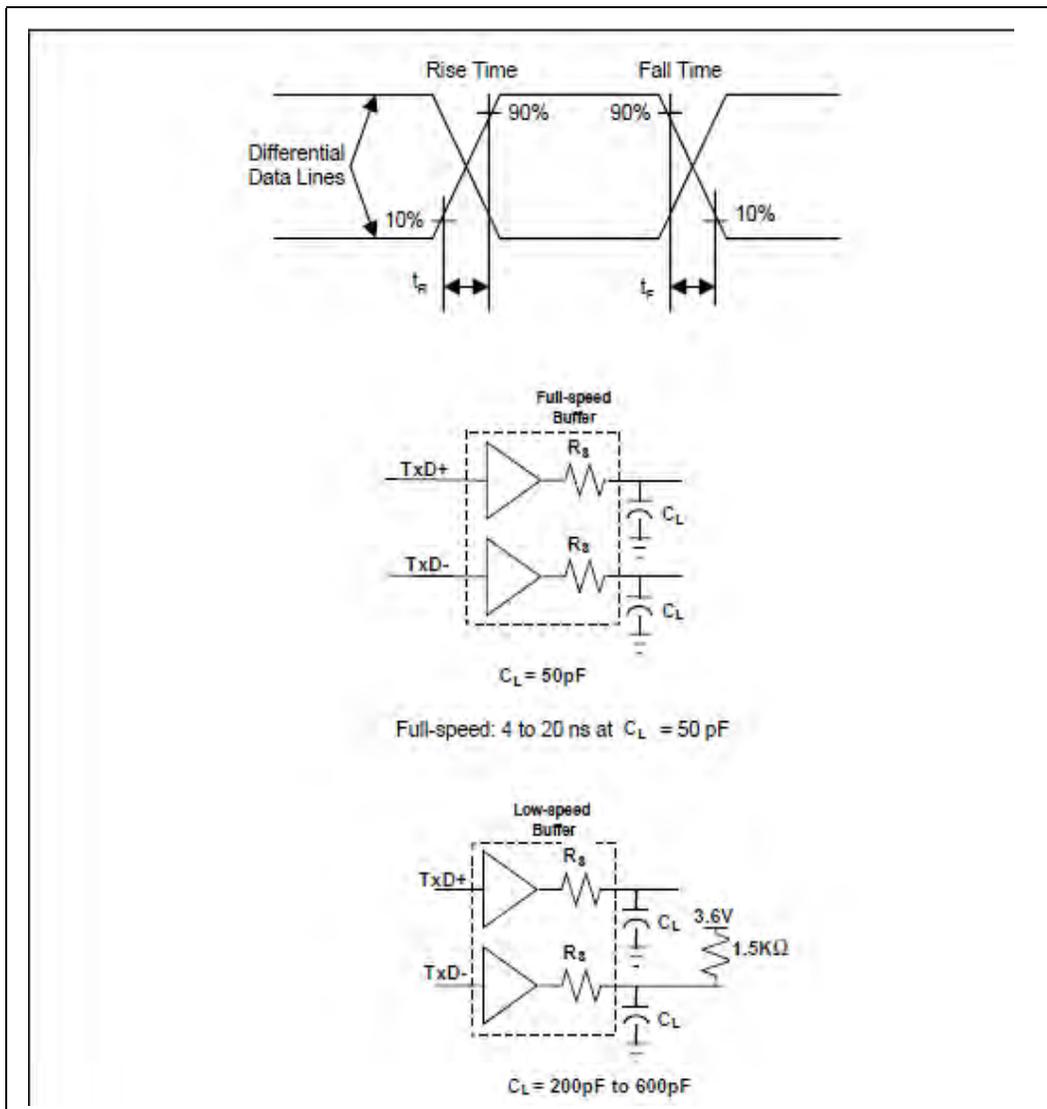




Figure 8-18. USB Jitter

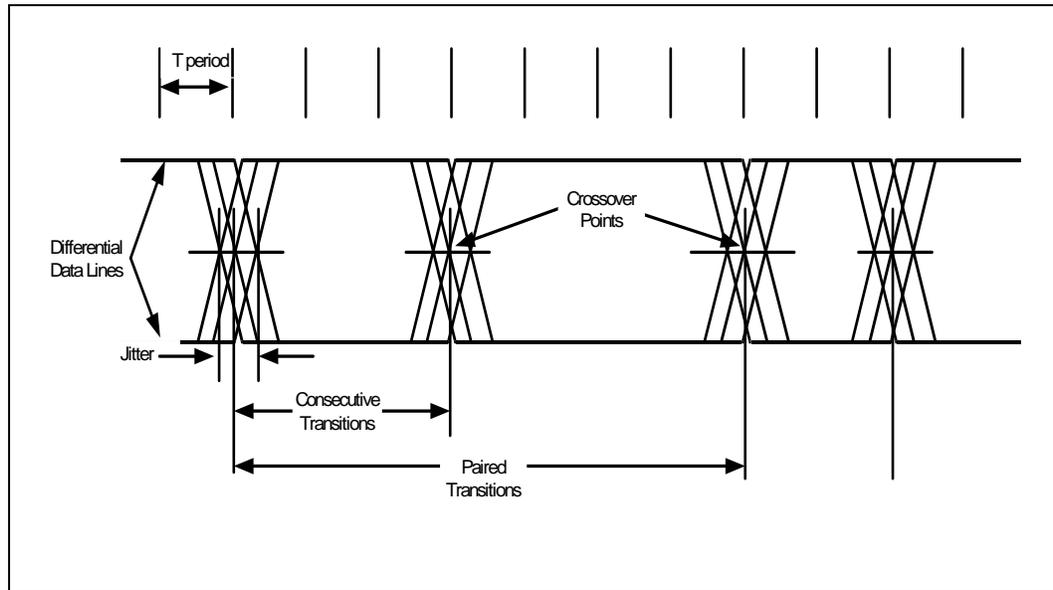


Figure 8-19. USB EOP Width

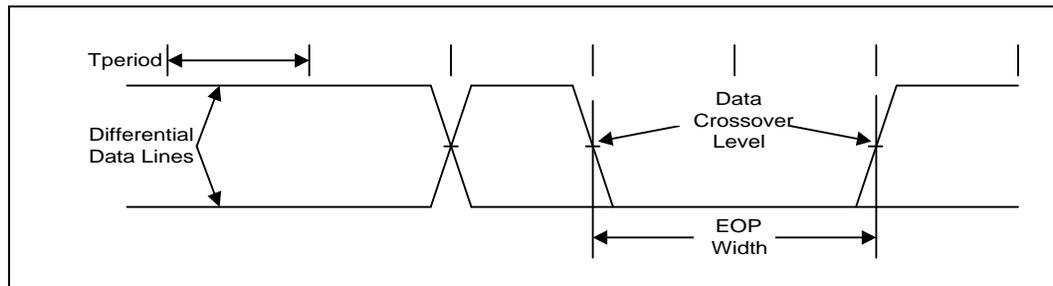
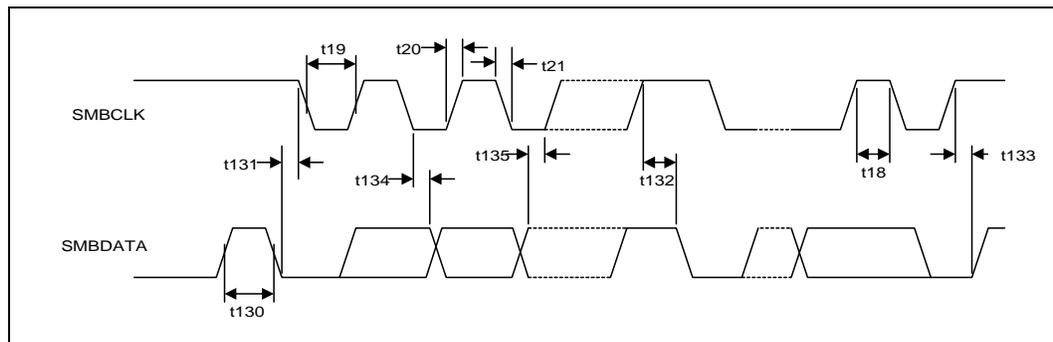
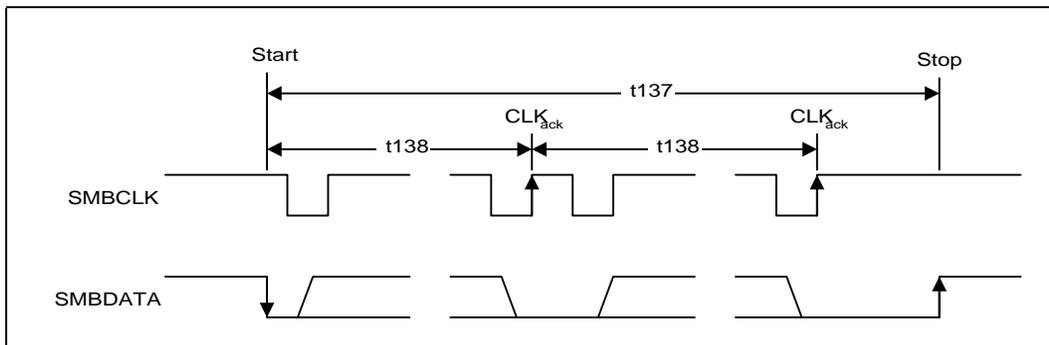


Figure 8-20. SMBus/SMLink Transaction



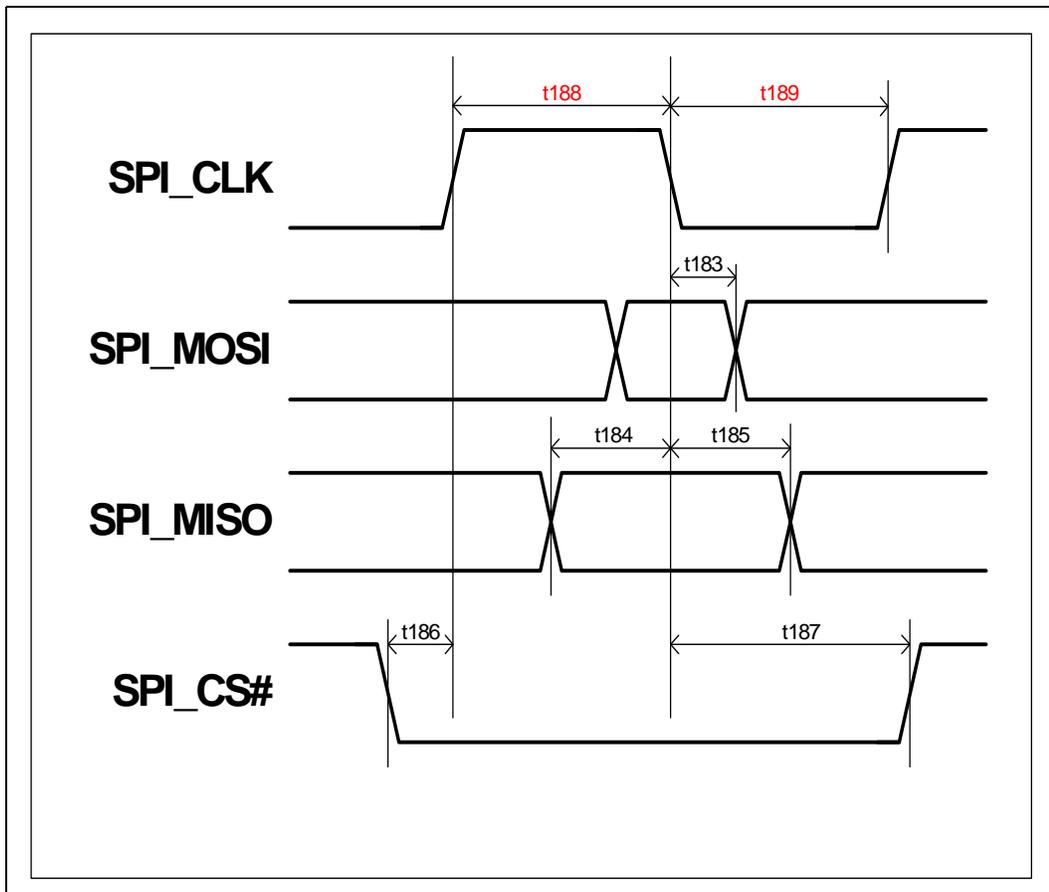
**Note:** txx also refers to txx\_SM, txxx also refers to txxxSMLFM, SMBCLK also refers to SML[1:0]CLK, and SMBDATA also refers to SML[1:0]DATA in Figure 8-20.

**Figure 8-21. SMBus/SMLink Timeout**



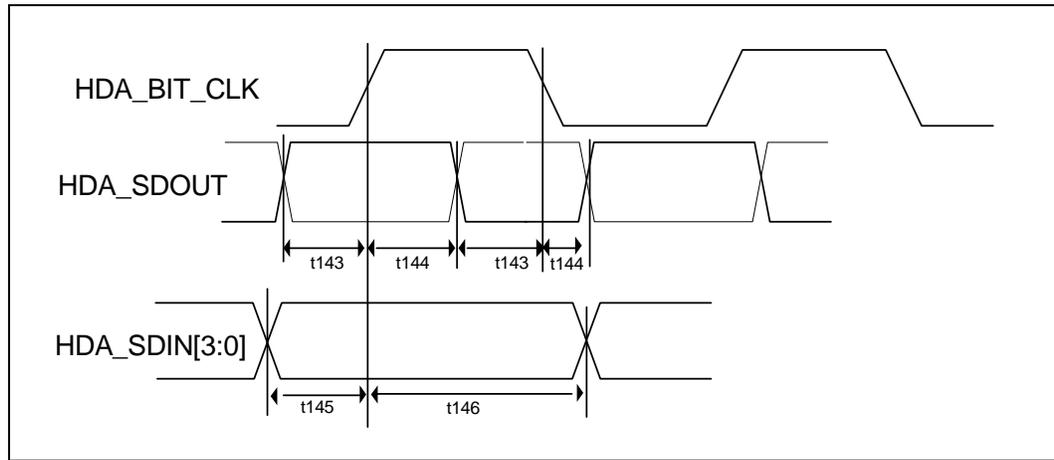
**Note:** SMBCLK also refers to SML[1:0]CLK and SMBDATA also refers to SML[1:0]DATA in Figure 8-21.

**Figure 8-22. SPI Timings**





**Figure 8-23. Intel® High Definition Audio Input and Output Timings**



**Figure 8-24. Transmitting Position (Data to Strobe)**

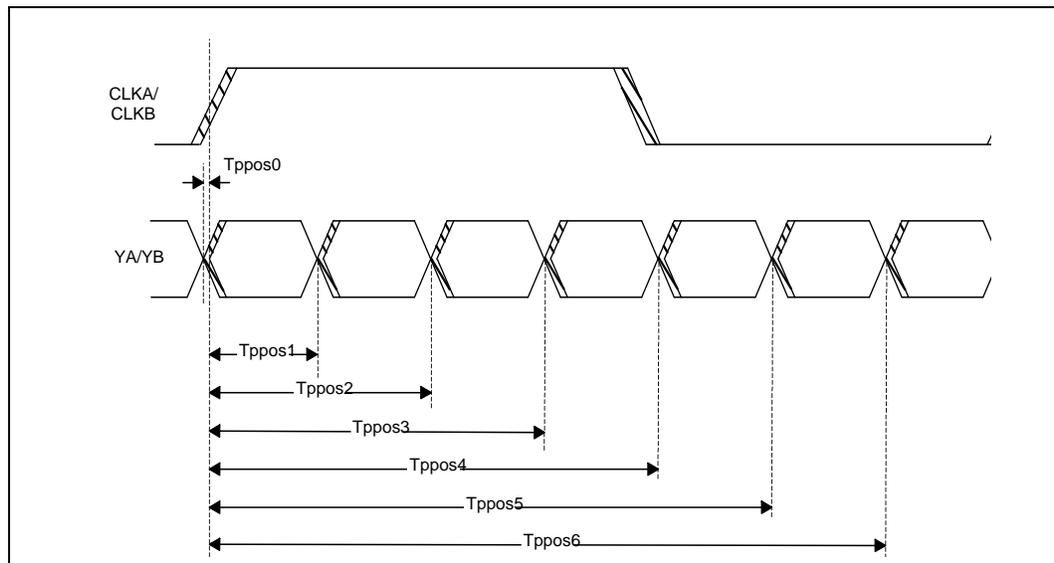


Figure 8-25. PCI Express\* Transmitter Eye

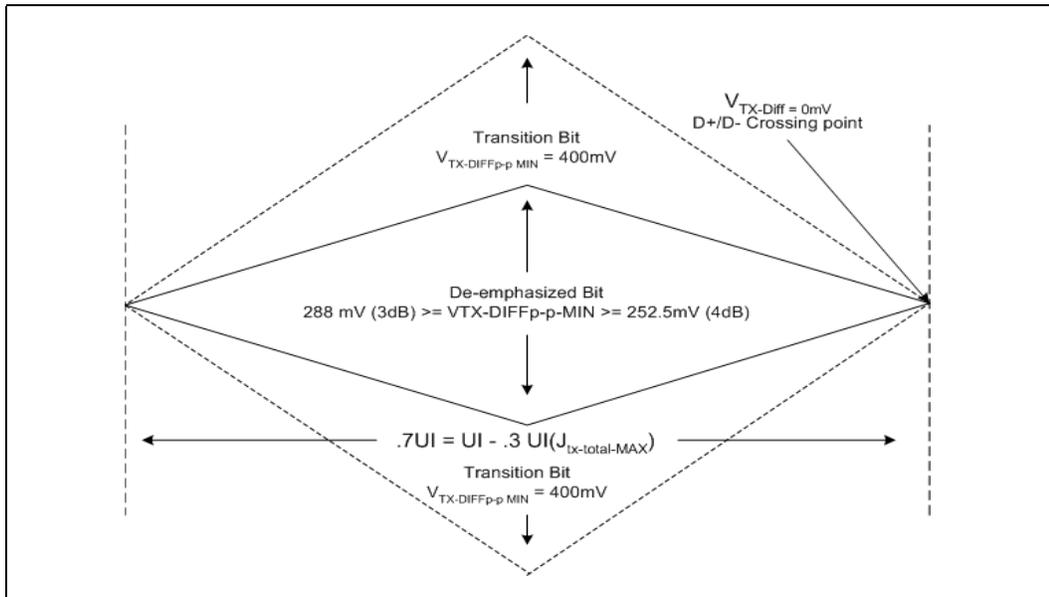


Figure 8-26. PCI Express\* Receiver Eye

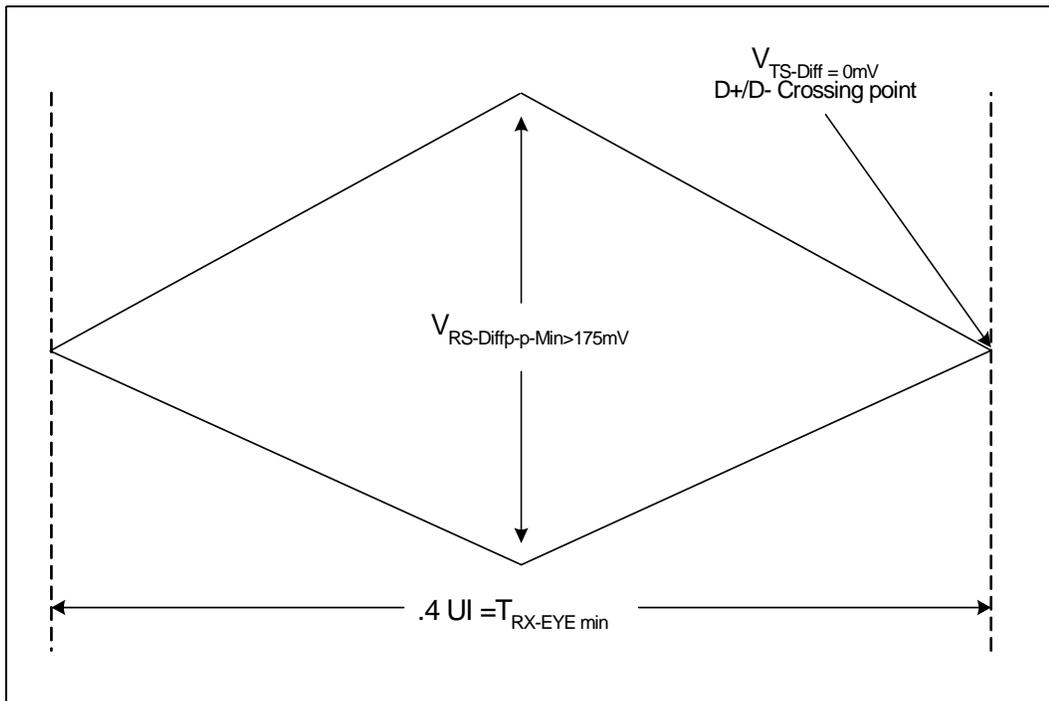




Figure 8-27. Measurement Points for Differential Waveforms.

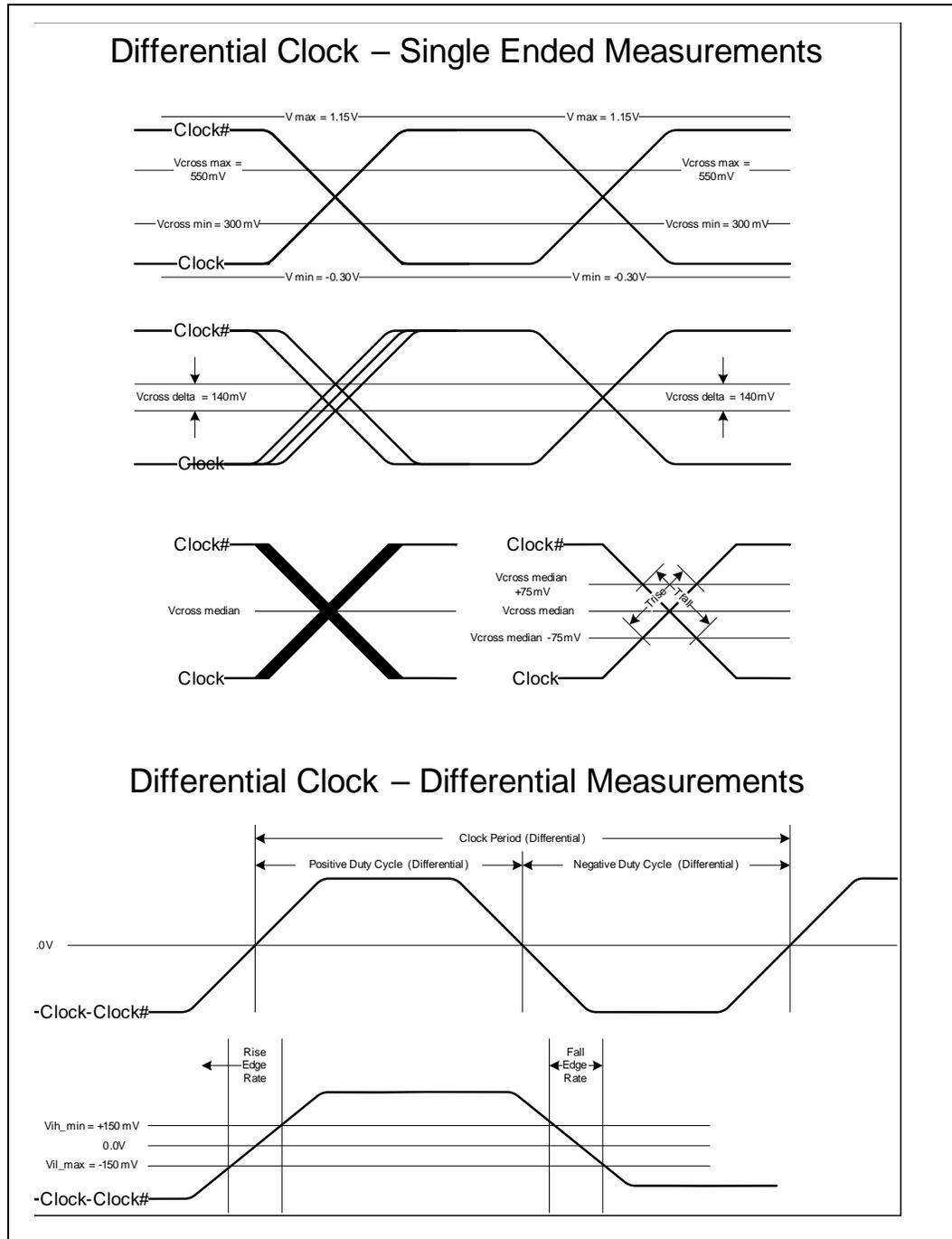
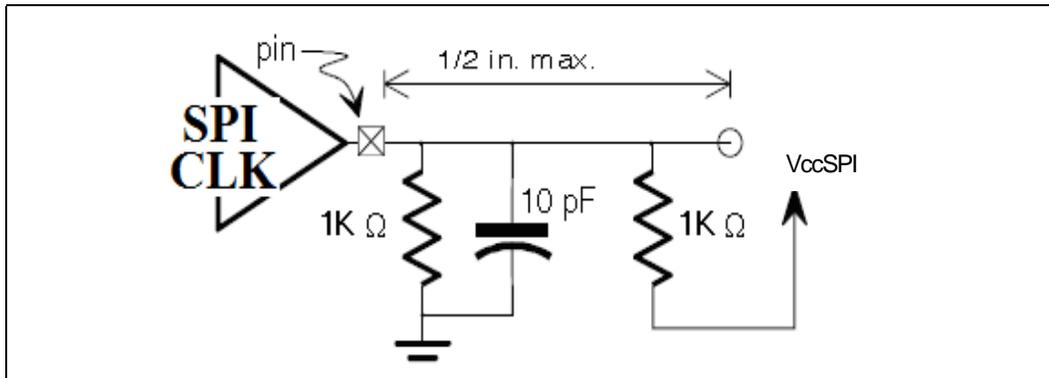


Figure 8-28. PCH Test Load



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## 9 Register and Memory Mapping

The PCH contains registers that are located in the processor's I/O space and memory space and sets of PCI configuration registers that are located in PCI configuration space. This chapter describes the PCH I/O and memory maps at the register-set level. Register access is also described. Register-level address maps and Individual register bit descriptions are provided in the following chapters. The following notations and definitions are used in the register/instruction description chapters.

<b>RO</b>	Read Only. In some cases, if a register is read only, writes to this register location have no effect. However, in other cases, two separate registers are located at the same location where a read accesses one of the registers and a write accesses the other register. See the I/O and memory map tables for details.
<b>WO</b>	Write Only. In some cases, if a register is write only, reads to this register location have no effect. However, in other cases, two separate registers are located at the same location where a read accesses one of the registers and a write accesses the other register. See the I/O and memory map tables for details.
<b>R/W</b>	Read/Write. A register with this attribute can be read and written.
<b>R/WC</b>	Read/Write Clear. A register bit with this attribute can be read and written. However, a write of 1 clears (sets to 0) the corresponding bit and a write of 0 has no effect.
<b>R/WL</b>	Read/Write Lockable. A register bit with the attribute can be read at any time but writes may only occur if the associated lock bit is set to unlock. If the associated lock bit is set to lock, this register bit becomes RO unless otherwise indicated.
<b>R/WO</b>	Read/Write-Once. A register bit with this attribute can be written only once after power up. After the first write, the bit becomes read only.
<b>R/WLO</b>	Read/Write, Lock-Once. A register bit with this attribute can be written to the non-locked value multiple times, but to the locked value only once. After the locked value has been written, the bit becomes read only.
<b>R/W/SN</b>	Read/Write register initial value loaded from NVM
<b>Reserved</b>	The value of reserved bits must never be changed. For details see <a href="#">Section 9.2</a> .
<b>Default</b>	When the PCH is reset, it sets its registers to predetermined default states. It is the responsibility of the system initialization software to determine configuration, operating parameters, and optional system features that are applicable, and to program the PCH registers accordingly.
<b>Bold</b>	Register bits that are highlighted in bold text indicate that the bit is implemented in the PCH. Register bits that are not implemented or are hardwired will remain in plain text.



## 9.1 PCI Devices and Functions

The PCH incorporates a variety of PCI devices and functions, as shown in [Table 9-1](#). The first is the PCI-To-PCI bridge (Device 30). The second device (Device 31) contains most of the standard PCI functions that always existed in the PCI-to-ISA bridges (South Bridges), such as the Intel® 82371AB PIIX4. The third and fourth (Device 29 and Device 26) are the USB and USB2 host controller devices. The fifth (Device 28) is PCI Express\* device. The sixth (Device 27) is HD Audio controller device. The seventh (Device 25) is the Gigabit Ethernet controller device. The eighth device i(Device 22) is the Intel® Management Engine Interface (Intel® MEI). The ninth device (Device 17) is the Virtual Root Port.

If for some reason, the particular system platform does not want to support any one of the Device Functions, with the exception of D30:F0 can individually be disabled. The integrated Gigabit Ethernet controller will be disabled if no Platform LAN Connect component is detected (See [Chapter 5.4](#)). When a function is disabled, it does not appear at all to the software. A disabled function will not respond to any register reads or writes, insuring that these devices appear hidden to software.

**Note:** In the normal platform, M will equal 0. For some server platforms, it may be desirable to have multiple PCH's in the system which means some PCH's may reside on a bus greater than 0.

**Table 9-1. PCI Devices and Functions for all PCH SKUs**

Bus:Device:Function	Function Description
Bus M: Device 30: Function 0	PCI-to-PCI Bridge
Bus M: Device 31: Function 0	LPC Controller <sup>1</sup>
Bus M: Device 31: Function 2	SATA Controller #1
Bus M: Device 31: Function 3	SMBus Controller
Bus M: Device 31: Function 5	SATA Controller #2 <sup>2</sup>
Bus M: Device 31: Function 6	Thermal Subsystem
Bus M: Device 29: Function 0	USB EHCI Controller #1 <sup>3</sup>
Bus M: Device 26: Function 0	USB EHCI Controller #2 <sup>3</sup>
Bus M: Device 28: Function 0	PCI Express* Port 1 <sup>4</sup>
Bus M: Device 28: Function 1	PCI Express* Port 2 <sup>4</sup>
Bus M: Device 28: Function 2	PCI Express* Port 3 <sup>4</sup>
Bus M: Device 28: Function 3	PCI Express* Port 4 <sup>4</sup>
Bus M: Device 28: Function 4	PCI Express* Port 5 <sup>4</sup>
Bus M: Device 28: Function 5	PCI Express* Port 6 <sup>4</sup>
Bus M: Device 28: Function 6	PCI Express* Port 7 <sup>4</sup>
Bus M: Device 28: Function 7	PCI Express* Port 8 <sup>4</sup>
Bus M: Device 27: Function 0	Intel HD Audio Controller
Bus M: Device 25: Function 0	Gigabit Ethernet Controller
Bus M: Device 22: Function 0	Host Embedded Controller Interface #1
Bus M: Device 22: Function 1	Host Embedded Controller Interface #2
Bus M: Device 22: Function 2	IDE-R
Bus M: Device 22: Function 3	KT
Bus X: Device 0: Function 0	SCU 0
Bus X: Device 0: Function 1	IDF
Bus X: Device 0: Function 3	SMB 0 (Associate with SCU0)



**Notes:**

1. The PCI-to-LPC bridge contains registers that control LPC, Power Management, System Management, GPIO, Processor Interface, RTC, Interrupts, Timers, and DMA.
2. SATA controller 2 (D31:F5) is only visible when D31:F2 CC.SCC=01h.
3. Prior to BIOS initialization of the PCH USB subsystem, the EHCI controllers will appear as Function 7. After BIOS initialization, the EHCI controllers will be Function 0.
4. This section assumes the default PCI Express\* Function Number-to-Root Port mapping is used. Function numbers for a given root port are assignable through the "Root Port Function Number and Hide for PCI Express\* Root Ports" registers (RCBA+0404h).

**Table 9-2. PCI Devices and Functions for PCH Intel® C602, C602J, C604 Chipset and Intel® X79 Express Chipset SKUs**

Bus:Device:Function	Function Description
Bus M: Device 17: Function 0	PCIe Virtual Root Port

**Table 9-3. Additional PCI Devices and Functions for Intel® C606, C608 Chipset SKUs**

Bus:Device:Function	Function Description
Bus N: Device 0: Function 0	PCIe Upstream Port
Bus N+1: Device 8: Function 0	PCIe Virtual Switch Port
Bus X: Device 0: Function 4	SMB 1 (Associate with SCU1)

**Notes:**

1. X is a value greater than N+1 assigned by the BIOS.
2. Intel® C606, C608 Chipset SKU can be configured using soft strap to route SCU traffic to DMI link. In such case, virtual root port (D17:F0) will be used in place of PCIe Upstream port and virtual switch port.

**Table 9-4. Additional PCI Devices and Functions for Intel® C608 Chipset SKU**

Bus:Device:Function	Function Description
Bus X: Device 0: Function 5	SMB 2

## 9.2 PCI Configuration Map

Each PCI function on the PCH has a set of PCI configuration registers. The register address map tables for these register sets are included at the beginning of the chapter for the particular function.

Configuration Space registers are accessed through configuration cycles on the PCI bus by the Host bridge using configuration mechanism #1 detailed in the *PCI Local Bus Specification*.

Some of the PCI registers contain reserved bits. Software must deal correctly with fields that are reserved. On reads, software must use appropriate masks to extract the defined bits and not rely on reserved bits being any particular value. On writes, software must ensure that the values of reserved bit positions are preserved. That is, the values of reserved bit positions must first be read, merged with the new values for other bit positions and then written back. Note the software does not need to perform read, merge, write operation for the configuration address register.

In addition to reserved bits within a register, the configuration space contains reserved locations. Software should not write to reserved PCI configuration locations in the device-specific region (above address offset 3Fh).



## 9.3 I/O Map

The I/O map is divided into Fixed and Variable address ranges. Fixed ranges cannot be moved, but in some cases can be disabled. Variable ranges can be moved and can also be disabled.

### 9.3.1 Fixed I/O Address Ranges

Table 9-5 shows the Fixed I/O decode ranges from the processor perspective. Note that for each I/O range, there may be separate behavior for reads and writes. DMI (Direct Media Interface) cycles that go to target ranges that are marked as “Reserved” will not be decoded by the PCH, and will be passed to PCI unless the Subtractive Decode Policy bit is set (D31:F0:Offset 42h, bit 0). If a PCI master targets one of the fixed I/O target ranges, it will be positively decoded by the PCH in medium speed.

Address ranges that are not listed or marked “Reserved” are **not** decoded by the PCH (unless assigned to one of the variable ranges).

**Table 9-5. Fixed I/O Ranges Decoded by PCH (Sheet 1 of 2)**

I/O Address	Read Target	Write Target	Internal Unit
00h–08h	DMA Controller	DMA Controller	DMA
09h–0Eh	RESERVED	DMA Controller	DMA
0Fh	DMA Controller	DMA Controller	DMA
10h–18h	DMA Controller	DMA Controller	DMA
19h–1Eh	RESERVED	DMA Controller	DMA
1Fh	DMA Controller	DMA Controller	DMA
20h–21h	Interrupt Controller	Interrupt Controller	Interrupt
24h–25h	Interrupt Controller	Interrupt Controller	Interrupt
28h–29h	Interrupt Controller	Interrupt Controller	Interrupt
2Ch–2Dh	Interrupt Controller	Interrupt Controller	Interrupt
2E–2F	LPC SIO	LPC SIO	Forwarded to LPC
30h–31h	Interrupt Controller	Interrupt Controller	Interrupt
34h–35h	Interrupt Controller	Interrupt Controller	Interrupt
38h–39h	Interrupt Controller	Interrupt Controller	Interrupt
3Ch–3Dh	Interrupt Controller	Interrupt Controller	Interrupt
40h–42h	Timer/Counter	Timer/Counter	PIT (8254)
43h	RESERVED	Timer/Counter	PIT
4E–4F	LPC SIO	LPC SIO	Forwarded to LPC
50h–52h	Timer/Counter	Timer/Counter	PIT
53h	RESERVED	Timer/Counter	PIT
60h	Microcontroller	Microcontroller	Forwarded to LPC
61h	NMI Controller	NMI Controller	Processor I/F
62h	Microcontroller	Microcontroller	Forwarded to LPC
64h	Microcontroller	Microcontroller	Forwarded to LPC
66h	Microcontroller	Microcontroller	Forwarded to LPC
70h	RESERVED <sup>1</sup>	NMI and RTC Controller	RTC
71h	RTC Controller	RTC Controller	RTC
72h	RTC Controller	NMI and RTC Controller	RTC



Table 9-5. Fixed I/O Ranges Decoded by PCH (Sheet 2 of 2)

I/O Address	Read Target	Write Target	Internal Unit
73h	RTC Controller	RTC Controller	RTC
74h	RTC Controller	NMI and RTC Controller	RTC
75h	RTC Controller	RTC Controller	RTC
76h	RTC Controller	NMI and RTC Controller	RTC
77h	RTC Controller	RTC Controller	RTC
80h	DMA Controller, LPC, PCI, or PCIe	DMA Controller and LPC, PCI, or PCIe	DMA
81h–83h	DMA Controller	DMA Controller	DMA
84h–86h	DMA Controller	DMA Controller and LPC, PCI, or PCIe	DMA
87h	DMA Controller	DMA Controller	DMA
88h	DMA Controller	DMA Controller and LPC or PCI, or PCIe	DMA
89h–8Bh	DMA Controller	DMA Controller	DMA
8Ch–8Eh	DMA Controller	DMA Controller and LPC or PCI, or PCIe	DMA
08Fh	DMA Controller	DMA Controller	DMA
90h–91h	DMA Controller	DMA Controller	DMA
92h	Reset Generator	Reset Generator	Processor I/F
93h–9Fh	DMA Controller	DMA Controller	DMA
A0h–A1h	Interrupt Controller	Interrupt Controller	Interrupt
A4h–A5h	Interrupt Controller	Interrupt Controller	Interrupt
A8h–A9h	Interrupt Controller	Interrupt Controller	Interrupt
ACh–ADh	Interrupt Controller	Interrupt Controller	Interrupt
B0h–B1h	Interrupt Controller	Interrupt Controller	Interrupt
B2h–B3h	Power Management	Power Management	Power Management
B4h–B5h	Interrupt Controller	Interrupt Controller	Interrupt
B8h–B9h	Interrupt Controller	Interrupt Controller	Interrupt
BCh–BDh	Interrupt Controller	Interrupt Controller	Interrupt
C0h–D1h	DMA Controller	DMA Controller	DMA
D2h–DDh	RESERVED	DMA Controller	DMA
DEh–DFh	DMA Controller	DMA Controller	DMA
F0h	FERR# / Interrupt Controller	FERR# / Interrupt Controller	Processor I/F
170h–177h	SATA Controller, PCI, or PCIe	SATA Controller, PCI, or PCIe	Forwarded to SATA
1F0h–1F7h	SATA Controller, PCI, or PCIe	SATA Controller, PCI, or PCIe	Forwarded to SATA
200h–207h	Gameport Low	Gameport Low	Forwarded to LPC
208h–20Fh	Gameport High	Gameport High	Forwarded to LPC
376h	SATA Controller, PCI, or PCIe	SATA Controller, PCI, or PCIe	Forwarded to SATA
3F6h	SATA Controller, PCI, or PCIe	SATA Controller, PCI, or PCIe	Forwarded to SATA
4D0h–4D1h	Interrupt Controller	Interrupt Controller	Interrupt
CF9h	Reset Generator	Reset Generator	Processor I/F

**Note:**

1. See Section 13.7.2.



### 9.3.2 Variable I/O Decode Ranges

Table 9-6 shows the Variable I/O Decode Ranges. They are set using Base Address Registers (BARs) or other configuration bits in the various PCI configuration spaces. The PNP software (PCI or ACPI) can use their configuration mechanisms to set and adjust these values.

**Warning:** The Variable I/O Ranges should not be set to conflict with the Fixed I/O Ranges. Unpredictable results if the configuration software allows conflicts to occur. The PCH does not perform any checks for conflicts.

**Table 9-6. Variable I/O Decode Ranges**

Range Name	Mappable	Size (Bytes)	Target
ACPI	Anywhere in 64 KB I/O Space	64	Power Management
IDE Bus Master	Anywhere in 64 KB I/O Space	1. 16 or 32 2. 16	1. SATA Host Controller #1, #2 2. IDE-R (SRV/WS SKUs Only)
Native IDE Command	Anywhere in 64 KB I/O Space <sup>1</sup>	8	1. SATA Host Controller #1, #2 2. IDE-R (SRV/WS SKUs Only)
Native IDE Control	Anywhere in 64 KB I/O Space <sup>1</sup>	4	1. SATA Host Controller #1, #2 2. IDE-R (SRV/WS SKUs Only)
SMBus	Anywhere in 64 KB I/O Space	32	SMB Unit
TCO	96 Bytes above ACPI Base	32	TCO Unit
SATA Index/Data Pair	Anywhere in 64 KB I/O Space	16	SATA Host Controller #1, #2
GPIO	Anywhere in 64 KB I/O Space	128	GPIO Unit
Parallel Port	3 Ranges in 64 KB I/O Space	83	LPC Peripheral
Serial Port 1	8 Ranges in 64 KB I/O Space	8	LPC Peripheral
Serial Port 2	8 Ranges in 64 KB I/O Space	8	LPC Peripheral
Floppy Disk Controller	2 Ranges in 64 KB I/O Space	8	LPC Peripheral
LAN	Anywhere in 64 KB I/O Space	322	LAN Unit
LPC Generic 1	Anywhere in 64 KB I/O Space	4 to 256	LPC Peripheral
LPC Generic 2	Anywhere in 64 KB I/O Space	4 to 256	LPC Peripheral
LPC Generic 3	Anywhere in 64 KB I/O Space	4 to 256	LPC Peripheral
LPC Generic 4	Anywhere in 64 KB I/O Space	4 to 256	LPC Peripheral
I/O Trapping Ranges	Anywhere in 64 KB I/O Space	1 to 256	Trap on Backbone
PCI Bridge	Anywhere in 64 KB I/O Space	I/O Base/ Limit	PCI Bridge
PCI Express* Root Ports	Anywhere in 64 KB I/O Space	I/O Base/ Limit	PCI Express* Root Ports 1-8
KT	Anywhere in 64 KB I/O Space	8	KT

**Notes:**

1. All ranges are decoded directly from DMI. The I/O cycles will not be seen on PCI, except the range associated with PCI bridge.
2. The LAN range is typically not used, as the registers can also be accessed using a memory space.
3. There is also an alias 400h above the parallel port range that is used for ECP parallel ports.



## 9.4 Memory Map

Table 9-7 shows (from the processor perspective) the memory ranges that the PCH decodes. Cycles that arrive from DMI that are not directed to any of the internal memory targets that decode directly from DMI will be driven out on PCI unless the Subtractive Decode Policy bit is set (D31:F0:Offset 42h, bit 0).

PCI cycles generated by external PCI masters will be positively decoded unless they fall in the PCI-to-PCI bridge memory forwarding ranges (those addresses are reserved for PCI peer-to-peer traffic). If the cycle is not in the internal LAN controller's range, it will be forwarded up to DMI. Software must not attempt locks to the PCH's memory-mapped I/O ranges for EHCI and HPET. If attempted, the lock is not honored which means potential deadlock conditions may occur.

**Table 9-7. Memory Decode Ranges from Processor Perspective (Sheet 1 of 2)**

Memory Range	Target	Dependency/Comments
0000 0000h–000D FFFFh 0010 0000h–TOM (Top of Memory)	Main Memory	TOM registers in Host controller
000E 0000h–000E FFFFh	LPC or SPI	Bit 6 in BIOS Decode Enable register is set
000F 0000h–000F FFFFh	LPC or SPI	Bit 7 in BIOS Decode Enable register is set
FEC_ _000h–FEC_ _040h	IO(x) APIC inside PCH	_ _ is controlled using APIC Range Select (ASEL) field and APIC Enable (AEN) bit
FEC1 0000h–FEC1 7FFF	PCI Express* Port 1	PCI Express* Root Port 1 I/OxAPIC Enable (PAE) set
FEC1 8000h–FEC1 FFFFh	PCI Express* Port 2	PCI Express* Root Port 2 I/OxAPIC Enable (PAE) set
FEC2 0000h–FEC2 7FFFh	PCI Express* Port 3	PCI Express* Root Port 3 I/OxAPIC Enable (PAE) set
FEC2 8000h–FEC2 FFFFh	PCI Express* Port 4	PCI Express* Root Port 4 I/OxAPIC Enable (PAE) set
FEC3 0000h–FEC3 7FFFh	PCI Express* Port 5	PCI Express* Root Port 5 I/OxAPIC Enable (PAE) set
FEC3 8000h–FEC3 FFFFh	PCI Express* Port 6	PCI Express* Root Port 6 I/OxAPIC Enable (PAE) set
FEC4 0000 - FEC4 7FFF	PCI Express* Port 7	PCI Express* Root Port 7 I/OxAPIC Enable (PAE) set
FEC4 8000 - FEC4 FFFF	PCI Express* Port 8	PCI Express* Root Port 8 I/OxAPIC Enable (PAE) set
FED4 0000h–FED4 BFFFh	TPM on LPC	If Intel TPM is enabled, FED4_0000h – FED4_7FFFh goes to Intel TPM. If disabled, the entire range goes to LPC.
FFC0 0000h–FFC7 FFFFh FF80 0000h–FF87 FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 8 in BIOS Decode Enable register is set
FFC8 0000h–FFCF FFFFh FF88 0000h–FF8F FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 9 in BIOS Decode Enable register is set
FFD0 0000h–FFD7 FFFFh FF90 0000h–FF97 FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 10 in BIOS Decode Enable register is set
FFD8 0000h–FFDF FFFFh FF98 0000h–FF9F FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 11 in BIOS Decode Enable register is set
FFE0 000h–FFE7 FFFFh FFA0 0000h–FFA7 FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 12 in BIOS Decode Enable register is set
FFE8 0000h–FFE7 FFFFh FFA8 0000h–FFAF FFFFh	LPC or SPI (or PCI) <sup>3</sup>	Bit 13 in BIOS Decode Enable register is set
FFF0 0000h–FFF7 FFFFh FFB0 0000h–FFB7 FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 14 in BIOS Decode Enable register is set
FFF8 0000h–FFFF FFFFh FFB8 0000h–FFBF FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Always enabled. The top two, 64 KB blocks of this range can be swapped, as described in <a href="#">Section 9.4.1</a> .
FF70 0000h–FF7F FFFFh FF30 0000h–FF3F FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 3 in BIOS Decode Enable register is set
FF60 0000h–FF6F FFFFh FF20 0000h–FF2F FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 2 in BIOS Decode Enable register is set



**Table 9-7. Memory Decode Ranges from Processor Perspective (Sheet 2 of 2)**

Memory Range	Target	Dependency/Comments
FF50 0000h–FF5F FFFFh FF10 0000h–FF1F FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 1 in BIOS Decode Enable register is set
FF40 0000h–FF4F FFFFh FF00 0000h–FF0F FFFFh	LPC or SPI (or PCI) <sup>2</sup>	Bit 0 in BIOS Decode Enable register is set
128 KB anywhere in 4-GB range	Integrated LAN Controller	Enable using BAR in Device 25:Function 0 (Integrated LAN Controller MBARA)
4 KB anywhere in 4 GB range	Integrated LAN Controller	Enable using BAR in Device 25:Function 0 (Integrated LAN Controller MBARB)
1 KB anywhere in 4-GB range	USB EHCI Controller #1 <sup>1</sup>	Enable using standard PCI mechanism (Device 29, Function 0)
1 KB anywhere in 4-GB range	USB EHCI Controller #2 <sup>1</sup>	Enable using standard PCI mechanism (Device 26, Function 0)
FED4 0000h–FED4 FFFFh	TPM on LPC	None
Memory Base/Limit anywhere in 4 GB range	PCI Bridge	Enable using standard PCI mechanism (Device 30: Function 0)
Prefetchable Memory Base/Limit anywhere in 64-bit address range	PCI Bridge	Enable using standard PCI mechanism (Device 30: Function 0)
64 KB anywhere in 4 GB range	LPC	LPC Generic Memory Range. Enable using setting bit[0] of the LPC Generic Memory Range register (D31:F0:offset 98h).
32 Bytes anywhere in 64-bit address range	SMBus	Enable using standard PCI mechanism (Device 31: Function 3)
2 KB anywhere above 64 KB to 4 GB range	SATA Host Controller #1	AHCI memory-mapped registers. Enable using standard PCI mechanism (Device 31: Function 2)
Memory Base/Limit anywhere in 4 GB range	PCI Express* Root Ports 1-8	Enable using standard PCI mechanism (Device 28: Function 0-7)
Prefetchable Memory Base/Limit anywhere in 64-bit address range	PCI Express* Root Ports 1-8	Enable using standard PCI mechanism (Device 28: Function 0-7)
4 KB anywhere in 64-bit address range	Thermal Reporting	Enable using standard PCI mechanism (Device 31: Function 6 TBAR/TBARH)
4 KB anywhere in 64-bit address range	Thermal Reporting	Enable using standard PCI mechanism (Device 31: Function 6 TBARB/TBARBH)
16 Bytes anywhere in 64-bit address range	Intel® Management Engine Interface (Intel® MEI) #1, #2	Enable using standard PCI mechanism (Device 22: Function 1:0)
4 KB anywhere in 4 GB range	KT	Enable using standard PCI mechanism (Device 22: Function 3)
16 KB anywhere in 4 GB range	Root Complex Register Block (RCRB)	Enable using setting bit[0] of the Root Complex Base Address register (D31:F0:offset F0h).
512 B anywhere in 64-bit addressing space	Intel HD Audio Host Controller	Enable using standard PCI mechanism (Device 27, Function 0)
FED0 X000h–FED0 X3FFh	High Precision Event Timers <sup>1</sup>	BIOS determines the “fixed” location which is one of four, 1-KB ranges where X (in the first column) is 0h, 1h, 2h, or 3h.
All other	PCI	None

**Notes:**

- Software must not attempt locks to memory mapped I/O ranges for USB EHCI or High Precision Event Timers. If attempted, the lock is not honored, which means potential deadlock conditions may occur.
- PCI is the target when the Boot BIOS Destination selection bits are set to 10b (Chipset Config Registers: Offset 3401 bits 11:10). When PCI selected, the Firmware Hub Decode Enable bits have no effect.



### 9.4.1 Boot-Block Update Scheme

The PCH supports a “top-block swap” mode that has the PCH swap the top block in the FWH or SPI flash (the boot block) with another location. This allows for safe update of the Boot Block (even if a power failure occurs). When the “TOP\_SWAP” Enable bit is set, the PCH will invert A16 for cycles going to the upper two 64 KB blocks in the FWH or appropriate address lines as selected in Boot Block Size (BIOS Boot-Block size) soft strap for SPI.

Specifically for FHW, in this mode accesses to FFFF\_0000h-FFFF\_FFFFh are directed to FFFE\_0000h-FFFE\_FFFFh and vice versa. When the Top Swap Enable bit is 0, the PCH will not invert A16.

Specifically for SPI, in this mode the “Top-Block Swap” behavior is as described below. When the Top Swap Enable bit is 0, the PCH will not invert any address bit.

**Table 9-8. SPI Mode Address Swapping**

BIOS Boot-Block Size Value	Accesses to	Being Directed to
000 (64 KB)	FFFF_0000h - FFFF_FFFFh	FFFE_0000h - FFFE_FFFFh and vice versa
001 (128 KB)	FFFE_0000h - FFFF_FFFFh	FFFC_0000h - FFFD_FFFFh and vice versa
010 (256 KB)	FFFC_0000h - FFFF_FFFFh	FFF8_0000h - FFFB_FFFFh and vice versa
011 (512 KB)	FFF8_0000h - FFFF_FFFFh	FFF0_0000h - FFF7_FFFFh and vice versa
100 (1 MB)	FFF0_0000h - FFFF_FFFFh	FFE0_0000h - FFEF_FFFFh and vice versa
101 - 111	Reserved	Reserved

This bit is automatically set to 0 by RTCRST#, but not by PLTRST#.

The scheme is based on the concept that the top block is reserved as the “boot” block, and the block immediately below the top block is reserved for doing boot-block updates.

The algorithm is:

1. Software copies the top block to the block immediately below the top.
2. Software checks that the copied block is correct. This could be done by performing a checksum calculation.
3. Software sets the TOP\_SWAP bit. This will invert the appropriate address bits for the cycles going to the FWH or SPI.
4. Software erases the top block.
5. Software writes the new top block.
6. Software checks the new top block.
7. Software clears the TOP\_SWAP bit.
8. Software sets the Top\_Swap Lock-Down bit.

If a power failure occurs at any point after step 3, the system will be able to boot from the copy of the boot block that is stored in the block below the top. This is because the TOP\_SWAP bit is backed in the RTC well.

**Note:** The top-block swap mode may be forced by an external strapping option. When top-block swap mode is forced in this manner, the TOP\_SWAP bit cannot be cleared by software. A re-boot with the strap removed will be required to exit a forced top-block swap mode.



**Note:** Top-block swap mode only affects accesses to the Firmware Hub space, not feature space for FWH.

**Note:** The top-block swap mode has no effect on accesses below FFFE\_0000h for FWH.

§



# 10 Chipset Configuration Registers

This section describes all registers and base functionality that is related to chipset configuration and not a specific interface (such as LPC, PCI, or PCI Express). It contains the root complex register block, which describes the behavior of the upstream internal link.

This block is mapped into memory space, using the Root Complex Base Address (RCBA) register of the PCI-to-LPC bridge. Accesses in this space must be limited to 32-(DW) bit quantities. Burst accesses are not allowed.

All chipset configuration registers are located in the core well unless otherwise indicated.

## 10.1 Chipset Configuration Registers (Memory Space)

**Note:** Address locations that are not shown should be treated as Reserved (see [Section 9.2](#) for details).

**Table 10-1. Chipset Configuration Register Memory Map (Memory Space) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Type
0050–0053h	CIR0	Chipset Initialization Register 0	00000000h	R/WL
0400–0403h	RPC	Root Port Configuration	0000000yh	R/W, RO
0404–0407h	RPFN	Root Port Function Number for PCI Express* Root Ports	76543210h	R/WO, RO
0408–040Bh	FLRSTAT	Function Level Reset Pending Status Summary	00000000h	RO
1E00–1E03h	TRSR	Trap Status Register	00000000h	R/WC, RO
1E10–1E17h	TRCR	Trapped Cycle Register	0000000000000000h	RO
1E18–1E1Fh	TWDR	Trapped Write Data Register	0000000000000000h	RO
1E80–1E87h	IOTR0	I/O Trap Register 0	0000000000000000h	R/W
1E88–1E8Fh	IOTR1	I/O Trap Register 1	0000000000000000h	R/W
1E90–1E97h	IOTR2	I/O Trap Register 2	0000000000000000h	R/W
1E98–1E9Fh	IOTR3	I/O Trap Register 3	0000000000000000h	R/W
2014–2017h	VOCTL	VC 0 Resource Control	800000FFh	R/WL, RO
201A–201Bh	VOSTS	VC 0 Resource Status	0000h	RO
2020–2023h	V1CTL	VC 1 Resource Control	00000000h	R/W, RO, R/WL
2026–2027h	V1STS	VC 1 Resource Status	0000h	RO
20AC–20AFh	REC	Root Error Command	0000h	R/W
21A4–21A7h	LCAP	Link Capabilities	00012C42h	RO, R/WO
21A8–21A9h	LCTL	Link Control	0000h	R/W
21AA–21ABh	LSTS	Link Status	0042h	RO
21B0–21B1h	DLCTL2	DMI Link Control 2	0000h	R/W, RO
2234–2237h	DMIC	DMI Control	00000000h	R/W, RO
3000–3000h	TCTL	TCO Control	00h	R/W
3100–3103h	D31IP	Device 31 Interrupt Pin	03243200h	R/W, RO



**Table 10-1. Chipset Configuration Register Memory Map (Memory Space) (Sheet 2 of 2)**

Offset	Mnemonic	Register Name	Default	Type
3104–3107h	D30IP	Device 30 Interrupt Pin	00000000h	RO
3108–310Bh	D29IP	Device 29 Interrupt Pin	10004321h	R/W
310C–310Fh	D28IP	Device 28 Interrupt Pin	00214321h	R/W
3110–3113h	D27IP	Device 27 Interrupt Pin	00000001h	R/W
3114–3117h	D26IP	Device 26 Interrupt Pin	30000321h	R/W
3118–311Bh	D25IP	Device 25 Interrupt Pin	00000001h	R/W
311C–311Fh	D24IP	Device 24 Interrupt Pin	00000001h	R/W
3124–3127h	D22IP	Device 22 Interrupt Pin	00004321h	R/W
3140–3141h	D31IR	Device 31 Interrupt Route	3210h	R/W
3144–3145h	D29IR	Device 29 Interrupt Route	3210h	R/W
3146–3147h	D28IR	Device 28 Interrupt Route	3210h	R/W
3148–3149h	D27IR	Device 27 Interrupt Route	3210h	R/W
314C–314Fh	D26IR	Device 26 Interrupt Route	3210h	R/W
3150–3153h	D25IR	Device 25 Interrupt Route	3210h	R/W
3154–3157h	D24IR	Device 24 Interrupt Route	3210h	R/W
315C–316Fh	D22IR	Device 22 Interrupt Route	3210h	R/W
31FE–31FFh	OIC	Other Interrupt Control	0000h	R/W
3310–3313h	PRSTS	Power and Reset Status	03000000h	RO, R/WC
3318–331Bh	PM_CFG	Power Management Configuration	00000000h	R/W
332C–332Fh	DEEP_S4_POL	Deep S4 Power Policies	00000000h	R/W
3330–3333h	DEEP_S5_POL	Deep S5 Power Policies	00000000h	R/W
3400–3403h	RC	RTC Configuration	00000000h	R/W, R/WLO
3404–3407h	HPTC	High Precision Timer Configuration	00000000h	R/W
3410–3413h	GCS	General Control and Status	000000yy0h	R/W, R/WLO
3414–3414h	BUC	Backed Up Control	00h	R/W
3418–341Bh	FD	Function Disable	00000000h	R/W
341C–341Fh	CG	Clock Gating	00000000h	R/W
3420–3420h	FDSW	Function Disable SUS Well	00h	R/W
3428–342Bh	FD2	Function Disable 2	00000000h	R/W
3450–3453h	GSXBAR	GPIO Serial Expander Base Address	00000000h	R/W, RO
3454–3457h	GSXCTRL	GPIO Serial Expander Control Register	00000000h	R/W, RO
3590–3593h	MISCCTL	Miscellaneous Control Register	00000000h	R/W
3598–3599h	USBIRE	USB Initialization Register E	0000h	R/W
35A4–35A7h	USBOCM2	USB Overcurrent MAP Register 2	00000000h	R/WO
35B0–35B3h	RMHWKCTL	USB Remap Control	00000000h	R/WO





### 10.1.3 RPFN—Root Port Function Number and Hide for PCI Express\* Root Ports

Offset Address: 0404-0407h Attribute: R/WO, RO  
 Default Value: 76543210h Size: 32-bit

For the PCI Express\* root ports, the assignment of a function number to a root port is not fixed. BIOS may re-assign the function numbers on a port by port basis. This capability will allow BIOS to disable/hide any root port and still have functions 0 through N-1 where N is the total number of enabled root ports.

Port numbers will remain fixed to a physical root port.

The existing root port Function Disable registers operate on physical ports (not functions).

Port Configuration (1x4, 4x1, and so forth) is not affected by the logical function number assignment and is associated with physical ports.

Bit	Description
31	<b>Root Port 8 Config Hide (RP8CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.
30:28	<b>Root Port 8 Function Number (RP8FN)</b> — R/WO. These bits set the function number for PCI Express* Root Port 8. This root port function number must be a unique value from the other root port function numbers
27	<b>Root Port 7 Config Hide (RP7CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.
26:24	<b>Root Port 7 Function Number (RP7FN)</b> — R/WO. These bits set the function number for PCI Express* Root Port 7. This root port function number must be a unique value from the other root port function numbers
23	<b>Root Port 6 Config Hide (RP6CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.
22:20	<b>Root Port 6 Function Number (RP6FN)</b> — R/WO. These bits set the function number for PCI Express* Root Port 6. This root port function number must be a unique value from the other root port function numbers
19	<b>Root Port 5 Config Hide (RP5CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.
18:16	<b>Root Port 5 Function Number (RP5FN)</b> — R/WO. These bits set the function number for PCI Express* Root Port 5. This root port function number must be a unique value from the other root port function numbers
15	<b>Root Port 4 Config Hide (RP4CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.
14:12	<b>Root Port 4 Function Number (RP4FN)</b> — R/WO. These bits set the function number for PCI Express* Root Port 4. This root port function number must be a unique value from the other root port function numbers
11	<b>Root Port 3 Config Hide (RP3CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.
10:8	<b>Root Port 3 Function Number (RP3FN)</b> — R/WO. These bits set the function number for PCI Express* Root Port 3. This root port function number must be a unique value from the other root port function numbers
7	<b>Root Port 2 Config Hide (RP2CH)</b> — R/W. This bit is used to hide the root port and any devices behind it from being discovered by the OS. When set to '1' the root port will not claim any downstream configuration transactions.





### 10.1.5 TRSR—Trap Status Register

Offset Address: 1E00–1E03h      Attribute: R/WC, RO  
 Default Value: 00000000h      Size: 32-bit

Bit	Description
31:4	Reserved
3:0	<p><b>Cycle Trap SMI# Status (CTSS)</b> — R/WC. These bits are set by hardware when the corresponding Cycle Trap register is enabled and a matching cycle is received (and trapped). These bits are OR'ed together to create a single status bit in the Power Management register space.</p> <p>Note that the SMI# and trapping must be enabled in order to set these bits. These bits are set before the completion is generated for the trapped cycle, thereby ensuring that the processor can enter the SMI# handler when the instruction completes. Each status bit is cleared by writing a 1 to the corresponding bit location in this register.</p>

### 10.1.6 TRCR—Trapped Cycle Register

Offset Address: 1E10–1E17h      Attribute: RO  
 Default Value: 0000000000000000h      Size: 64-bit

This register saves information about the I/O Cycle that was trapped and generated the SMI# for software to read.

Bit	Description
63:25	Reserved
24	<p><b>Read/Write# (RWI)</b> — RO. Trapped cycle was a write cycle. Trapped cycle was a read cycle.</p>
23:20	Reserved
19:16	<p><b>Active-high Byte Enables (AHBE)</b> — RO. This is the DWord-aligned byte enables associated with the trapped cycle. A 1 in any bit location indicates that the corresponding byte is enabled in the cycle.</p>
15:2	<p><b>Trapped I/O Address (TIOA)</b> — RO. This is the DWord-aligned address of the trapped cycle.</p>
1:0	Reserved

### 10.1.7 TWDR—Trapped Write Data Register

Offset Address: 1E18–1E1Fh      Attribute: RO  
 Default Value: 0000000000000000h      Size: 64-bit

This register saves the data from I/O write cycles that are trapped for software to read.

Bit	Description
63:32	Reserved
31:0	<p><b>Trapped I/O Data (TIOD)</b> — RO. DWord of I/O write data. This field is undefined after trapping a read cycle.</p>



### 10.1.8 IOTRn—I/O Trap Register (0-3)

Offset Address: 1E80–1E87h Register 0      Attribute:      R/W  
 1E88–1E8Fh Register 1  
 1E90–1E97h Register 2  
 1E98–1E9Fh Register 3  
 Default Value: 0000000000000000h      Size:      64-bit

These registers are used to specify the set of I/O cycles to be trapped and to enable this functionality.

Bit	Description
63:50	Reserved
49	<b>Read/Write Mask (RWM)</b> — R/W. The cycle must match the type specified in bit 48. Trapping logic will operate on both read and write cycles.
48	<b>Read/Write# (RWIO)</b> — R/W. 0 = Write 1 = Read <b>Note:</b> The value in this field does not matter if bit 49 is set.
47:40	Reserved
39:36	<b>Byte Enable Mask (BEM)</b> — R/W. A 1 in any bit position indicates that any value in the corresponding byte enable bit in a received cycle will be treated as a match. The corresponding bit in the Byte Enables field, below, is ignored.
35:32	<b>Byte Enables (TBE)</b> — R/W. Active-high DWord-aligned byte enables.
31:24	Reserved
23:18	<b>Address[7:2] Mask (ADMA)</b> — R/W. A 1 in any bit position indicates that any value in the corresponding address bit in a received cycle will be treated as a match. The corresponding bit in the Address field, below, is ignored. The mask is only provided for the lower 6 bits of the DWord address, allowing for traps on address ranges up to 256 bytes in size.
17:16	Reserved
15:2	<b>I/O Address[15:2] (IOAD)</b> — R/W. DWord-aligned address
1	Reserved
0	<b>Trap and SMI# Enable (TRSE)</b> — R/W. 0 = Trapping and SMI# logic disabled. 1 = The trapping logic specified in this register is enabled.



### 10.1.9 VOCTL—Virtual Channel 0 Resource Control Register

Offset Address: 2014–2017h      Attribute: R/WL, RO  
 Default Value: 80000011h      Size: 32-bit

Bit	Description
31	<b>Virtual Channel Enable (EN)</b> — RO. Always set to 1. VCO is always enabled and cannot be disabled.
30:27	Reserved
26:24	<b>Virtual Channel Identifier (ID)</b> — RO. Indicates the ID to use for this virtual channel.
23:16	Reserved
15:10	<b>Extended TC/VC Map (ETVM)</b> : R/WL. Defines the upper 8-bits of the VCO 16-bit TC/VC mapping registers. These registers use the PCI Express* reserved TC[3] traffic class bit. These bits are locked if the TCLOCKDN bit (RCBA+0050h:bit 31) is set.
9:7	<b>Reserved</b>
6:1	<b>Transaction Class / Virtual Channel Map (TVM)</b> — R/WL. Indicates which transaction classes are mapped to this virtual channel. When a bit is set, this transaction class is mapped to the virtual channel. These bits are locked if the TCLOCKDN bit (RCBA+0050h:bit 31) is set.
0	Reserved

### 10.1.10 VOSTS—Virtual Channel 0 Resource Status Register

Offset Address: 201A–201Bh      Attribute: RO  
 Default Value: 0000h      Size: 16-bit

Bit	Description
15:2	Reserved
1	<b>VC Negotiation Pending (NP)</b> — RO. When set, indicates the virtual channel is still being negotiated with ingress ports.
0	Reserved

### 10.1.11 V1CTL—Virtual Channel 1 Resource Control Register

Offset Address: 2020–2023h      Attribute: R/W, RO, R/WL  
 Default Value: 00000000h      Size: 32-bit

Bit	Description
31	<b>Virtual Channel Enable (EN)</b> — R/W. Enables the VC when set. Disables the VC when cleared.
30:28	Reserved
27:24	<b>Virtual Channel Identifier (ID)</b> — R/W. Indicates the ID to use for this virtual channel.
23:16	Reserved
15:10	<b>Extended TC/VC Map (ETVM)</b> : R/WL. Defines the upper 8-bits of the VCO 16-bit TC/VC mapping registers. These registers use the PCI Express* reserved TC[3] traffic class bit. These bits are locked if the TCLOCKDN bit (RCBA+0050h:bit 31) is set.
9:8	<b>Reserved</b>
7:1	<b>Transaction Class / Virtual Channel Map (TVM)</b> — R/WL. Indicates which transaction classes are mapped to this virtual channel. When a bit is set, this transaction class is mapped to the virtual channel. These bits are locked if the TCLOCKDN bit (RCBA+0050h:bit 31) is set.
0	Reserved



### 10.1.12 V1STS—Virtual Channel 1 Resource Status Register

Offset Address: 2026–2027h      Attribute: RO  
 Default Value: 0000h      Size: 16-bit

Bit	Description
15:2	Reserved
1	<b>VC Negotiation Pending (NP)</b> — RO. When set, indicates the virtual channel is still being negotiated with ingress ports.
0	Reserved

### 10.1.13 REC—Root Error Command Register

Offset Address: 20AC–20AFh      Attribute: R/W  
 Default Value: 0000h      Size: 32-bit

Bit	Description
31	<b>Drop Poisoned Downstream Packets (DPDP)</b> — R/W. Determines how downstream packets on DMI are handled that are received with the EP field set, indicating poisoned data: 0 = Packets are forwarded downstream without forcing the UT field set. 1 = This packet and all subsequent packets with data received on DMI for any VC will have their Unsupported Transaction (UT) field set causing them to master Abort downstream. Packets without data such as memory, IO and config read requests are allowed to proceed.
30:0	Reserved

### 10.1.14 LCAP—Link Capabilities Register

Offset Address: 21A4–21A7h      Attribute: R/WO, RO  
 Default Value: 00012C42h      Size: 32-bit

Bit	Description
31:18	Reserved
17:15	<b>L1 Exit Latency (EL1)</b> — R/WO. 000b – Less than 1 $\mu$ s 001b – 1 $\mu$ s to less than 2 $\mu$ s 010b – 2 $\mu$ s to less than 4 $\mu$ s 011b – 4 $\mu$ s to less than 8 $\mu$ s 100b – 8 $\mu$ s to less than 16 $\mu$ s 101b – 16 $\mu$ s to less than 32 $\mu$ s 110b – 32 $\mu$ s to 64 $\mu$ s 111b – More than 64 $\mu$ s
14:12	<b>L0s Exit Latency (ELO)</b> — R/W. This field indicates that exit latency is 128 ns to less than 256 ns.
11:10	<b>Active State Link PM Support (APMS)</b> — R/W. Indicates the level of ASPM support on DMI. 00 = Disabled 01 = L0s entry supported 10 = Reserved 11 = L0s and L1 entry supported
9:4	<b>Maximum Link Width (MLW)</b> — RO. Indicates the maximum link width is 4 ports.
3:0	<b>Supported Link Speed (MLS)</b> — RO. Indicates the supported links speeds is 5.0 GT/s.



### 10.1.15 LCTL—Link Control Register

Offset Address: 21A8–21A9h  
 Default Value: 0000h

Attribute: R/W  
 Size: 16-bit

Bit	Description
15:8	Reserved
7	<b>Extended Synch (ES)</b> — R/W. When set, forces extended transmission of FTS ordered sets when exiting L0s prior to entering L0 and extra TS1 sequences at exit from L1 prior to entering L0.
6:2	Reserved
1:0	<b>Active State Link PM Control (ASPM)</b> — R/W. Indicates whether DMI should enter L0s, L1, or both. 00 = Disabled 01 = L0s entry enabled 10 = L1 entry enabled 11 = L0s and L1 entry enabled

### 10.1.16 LLSTS—Link Status Register

Offset Address: 21AA–21ABh  
 Default Value: 0042h

Attribute: RO  
 Size: 16-bit

Bit	Description
15:10	Reserved
9:4	<b>Negotiated Link Width (NLW)</b> — RO. Negotiated link width is x4 (000100b).
3:0	<b>Current Link Speed (LS)</b> — RO. 0001b = 2.5 Gb/s 0010b = 5.0 Gb/s

### 10.1.17 DLCTL2—DMI Link Control 2 Register

Offset Address: 21B0–21B1h  
 Default Value: 0001h

Attribute: R/W, RO  
 Size: 16-bit

Bit	Description
31:4	Reserved
3:0	<b>DLCTL2 Field 1</b> — R/W. BIOS must set these bits.

### 10.1.18 DMIC—DMI Control Register

Offset Address: 2234–2237h  
 Default Value: 00000000h

Attribute: R/W  
 Size: 32-bit

Bit	Description
31:2	Reserved
1:0	<b>DMI Clock Gate Enable (DMICGEN)</b> — R/W. BIOS must program this field to 11b.





Bit	Description
11:8	<b>SATA Pin (SIP)</b> — R/W. Indicates which pin the SATA controller drives as its interrupt. 0h = No interrupt 1h = INTA# 2h = INTB# (Default) 3h = INTC# 4h = INTD# 5h–Fh = Reserved
7:4	Reserved
3:0	LPC Bridge Pin (LIP) — RO. Currently, the LPC bridge does not generate an interrupt, so this field is read-only and 0.

### 10.1.21 D30IP—Device 30 Interrupt Pin Register

Offset Address: 3104–3107h                      Attribute: RO  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:4	Reserved
3:0	PCI Bridge Pin (PIP) — RO. Currently, the PCI bridge does not generate an interrupt, so this field is read-only and 0.

### 10.1.22 D29IP—Device 29 Interrupt Pin Register

Offset Address: 3108–310Bh                      Attribute: R/W  
 Default Value: 10004321h                      Size: 32-bit

Bit	Description
31:4	Reserved
3:0	<b>EHCI #1 Pin (E1P)</b> — R/W. Indicates which pin the EHCI controller #1 drives as its interrupt, if controller exists. 0h = No interrupt 1h = INTA# (Default) 2h = INTB# 3h = INTC# 4h = INTD# 5h–7h = Reserved <b>Note:</b> EHCI Controller #1 is mapped to Device 29 Function 0.

### 10.1.23 D28IP—Device 28 Interrupt Pin Register

Offset Address: 310C–310Fh                      Attribute: R/W  
 Default Value: 00214321h                      Size: 32-bit

Bit	Description
31:28	<b>PCI Express* #8 Pin (P8IP)</b> — R/W. Indicates which pin the PCI Express* port #8 drives as its interrupt. 0h = No interrupt 1h = INTA# 2h = INTB# (Default) 3h = INTC# 4h = INTD# 5h–7h = Reserved



Bit	Description
27:24	<p><b>PCI Express* #7 Pin (P7IP)</b> — R/W. Indicates which pin the PCI Express* port #7 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA# (Default)                      2h = INTB#                      3h = INTC#                      4h = INTD#                      5h-7h = Reserved</p>
23:20	<p><b>PCI Express* #6 Pin (P6IP)</b> — R/W. Indicates which pin the PCI Express* port #6 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA#                      2h = INTB# (Default)                      3h = INTC#                      4h = INTD#                      5h-7h = Reserved</p>
19:16	<p><b>PCI Express* #5 Pin (P5IP)</b> — R/W. Indicates which pin the PCI Express* port #5 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA# (Default)                      2h = INTB#                      3h = INTC#                      4h = INTD#                      5h-7h = Reserved</p>
15:12	<p><b>PCI Express* #4 Pin (P4IP)</b> — R/W. Indicates which pin the PCI Express* port #4 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA#                      2h = INTB#                      3h = INTC#                      4h = INTD# (Default)                      5h-7h = Reserved</p>
11:8	<p><b>PCI Express* #3 Pin (P3IP)</b> — R/W. Indicates which pin the PCI Express* port #3 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA#                      2h = INTB#                      3h = INTC# (Default)                      4h = INTD#                      5h-7h = Reserved</p>
7:4	<p><b>PCI Express* #2 Pin (P2IP)</b> — R/W. Indicates which pin the PCI Express* port #2 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA#                      2h = INTB# (Default)                      3h = INTC#                      4h = INTD#                      5h-7h = Reserved</p>
3:0	<p><b>PCI Express* #1 Pin (P1IP)</b> — R/W. Indicates which pin the PCI Express* port #1 drives as its interrupt.</p> <p>0h = No interrupt                      1h = INTA# (Default)                      2h = INTB#                      3h = INTC#                      4h = INTD#                      5h-7h = Reserved</p>



### 10.1.24 D27IP—Device 27 Interrupt Pin Register

Offset Address: 3110–3113h                      Attribute: R/W  
Default Value: 00000001h                      Size: 32-bit

Bit	Description
31:4	Reserved
3:0	<b>Intel HD Audio Pin (ZIP)</b> — R/W. Indicates which pin the Intel HD Audio controller drives as its interrupt. 0h = No interrupt 1h = INTA# (Default) 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved

### 10.1.25 D26IP—Device 26 Interrupt Pin Register

Offset Address: 3114–3117h                      Attribute: R/W  
Default Value: 30000321h                      Size: 32-bit

Bit	Description
31:4	Reserved
3:0	<b>EHCI #2 Pin (E2P)</b> — R/W. Indicates which pin EHCI controller #2 drives as its interrupt, if controller exists. 0h = No Interrupt 1h = INTA# (Default) 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved <b>Note:</b> EHCI Controller #2 is mapped to Device 26 Function 0.

### 10.1.26 D25IP—Device 25 Interrupt Pin Register

Offset Address: 3118–311Bh                      Attribute: R/W  
Default Value: 00000001h                      Size: 32-bit

Bit	Description
31:4	Reserved
3:0	<b>GbE LAN Pin (LIP)</b> — R/W. Indicates which pin the internal GbE LAN controller drives as its interrupt 0h = No Interrupt 1h = INTA# (Default) 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved



### 10.1.27 D22IP—Device 22 Interrupt Pin Register

Offset Address: 3124–3127h                      Attribute: R/W  
 Default Value: 00004321h                      Size: 32-bit

Bit	Description
31:16	Reserved
15:12	<b>KT Pin (KTIP)</b> — R/W. Indicates which pin the Keyboard text PCI functionality drives as its interrupt 0h = No Interrupt 1h = INTA# 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved
11:8 (HEDT SKU Only)	Reserved
11:8 (SRV/WS SKUs Only)	<b>IDE-R Pin (IDERIP)</b> — R/W. Indicates which pin the IDE Redirect PCI functionality drives as its interrupt 0h = No Interrupt 1h = INTA# 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved
7:4	<b>Intel MEI #2 Pin (MEI2IP)</b> — R/W. Indicates which pin the Intel MEI #2 drives as its interrupt 0h = No Interrupt 1h = INTA# 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved
3:0	<b>Intel MEI #1 Pin (MEI1IP)</b> — R/W. Indicates which pin the Intel MEI #1 drives as its interrupt 0h = No Interrupt 1h = INTA# 2h = INTB# 3h = INTC# 4h = INTD# 5h-Fh = Reserved



### 10.1.28 D31IR—Device 31 Interrupt Route Register

Offset Address: 3140–3141h      Attribute: R/W  
 Default Value: 3210h      Size: 16-bit

Bit	Description
15	Reserved
14:12	<b>Interrupt D Pin Route (IDR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTD# pin reported for device 31 functions. 0h = PIRQA# 1h = PIRQB# 2h = PIRQC# 3h = PIRQD# (Default) 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
11	Reserved
10:8	<b>Interrupt C Pin Route (ICR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTC# pin reported for device 31 functions. 0h = PIRQA# 1h = PIRQB# 2h = PIRQC# (Default) 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
7	Reserved
6:4	<b>Interrupt B Pin Route (IBR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTB# pin reported for device 31 functions. 0h = PIRQA# 1h = PIRQB# (Default) 2h = PIRQC# 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
3	Reserved
2:0	<b>Interrupt A Pin Route (IAR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTA# pin reported for device 31 functions. 0h = PIRQA# (Default) 1h = PIRQB# 2h = PIRQC# 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#

### 10.1.29 D30IR—Device 30 Interrupt Route Register

Offset Address: 3142–3143h      Attribute: RO  
 Default Value: 0000h      Size: 16-bit

Bit	Description
15:0	Reserved. No interrupts generated from Device 30.





### 10.1.31 D28IR—Device 28 Interrupt Route Register

Offset Address: 3146–3147h  
 Default Value: 3210h

Attribute: R/W  
 Size: 16-bit

Bit	Description
15	Reserved
14:12	<b>Interrupt D Pin Route (IDR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTD# pin reported for device 28 functions. 0h = PIRQA# 1h = PIRQB# 2h = PIRQC# 3h = PIRQD# (Default) 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
11	Reserved
10:8	<b>Interrupt C Pin Route (ICR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTC# pin reported for device 28 functions. 0h = PIRQA# 1h = PIRQB# 2h = PIRQC# (Default) 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
7	Reserved
6:4	<b>Interrupt B Pin Route (IBR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTB# pin reported for device 28 functions. 0h = PIRQA# 1h = PIRQB# (Default) 2h = PIRQC# 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
3	Reserved
2:0	<b>Interrupt A Pin Route (IAR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTA# pin reported for device 28 functions. 0h = PIRQA# (Default) 1h = PIRQB# 2h = PIRQC# 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#





### 10.1.33 D26IR—Device 26 Interrupt Route Register

Offset Address: 314C–314Dh  
 Default Value: 3210h

Attribute: R/W  
 Size: 16-bit

Bit	Description
15	Reserved
14:12	<b>Interrupt D Pin Route (IDR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTD# pin reported for device 26 functions: 0h = PIRQA# 1h = PIRQB# 2h = PIRQC# 3h = PIRQD# (Default) 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
11	Reserved
10:8	<b>Interrupt C Pin Route (ICR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTC# pin reported for device 26 functions. 0h = PIRQA# 1h = PIRQB# 2h = PIRQC# (Default) 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
7	Reserved
6:4	<b>Interrupt B Pin Route (IBR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTB# pin reported for device 26 functions. 0h = PIRQA# 1h = PIRQB# (Default) 2h = PIRQC# 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#
3	Reserved
2:0	<b>Interrupt A Pin Route (IAR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTA# pin reported for device 26 functions. 0h = PIRQA# (Default) 1h = PIRQB# 2h = PIRQC# 3h = PIRQD# 4h = PIRQE# 5h = PIRQF# 6h = PIRQG# 7h = PIRQH#





### 10.1.35 D22IR—Device 22 Interrupt Route Register

Offset Address: 315C–315Dh  
 Default Value: 3210h

Attribute: R/W  
 Size: 16-bit

Bit	Description
15	Reserved
14:12	<p><b>Interrupt D Pin Route (IDR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTD# pin reported for device 22 functions:</p> <p>0h = PIRQA#            1h = PIRQB#            2h = PIRQC#            3h = PIRQD# (Default)            4h = PIRQE#            5h = PIRQF#            6h = PIRQG#            7h = PIRQH#</p>
11	Reserved
10:8	<p><b>Interrupt C Pin Route (ICR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTC# pin reported for device 22 functions.</p> <p>0h = PIRQA#            1h = PIRQB#            2h = PIRQC# (Default)            3h = PIRQD#            4h = PIRQE#            5h = PIRQF#            6h = PIRQG#            7h = PIRQH#</p>
7	Reserved
6:4	<p><b>Interrupt B Pin Route (IBR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTB# pin reported for device 22 functions.</p> <p>0h = PIRQA#            1h = PIRQB# (Default)            2h = PIRQC#            3h = PIRQD#            4h = PIRQE#            5h = PIRQF#            6h = PIRQG#            7h = PIRQH#</p>
3	Reserved
2:0	<p><b>Interrupt A Pin Route (IAR)</b> — R/W. Indicates which physical pin on the PCH is connected to the INTA# pin reported for device 22 functions.</p> <p>0h = PIRQA# (Default)            1h = PIRQB#            2h = PIRQC#            3h = PIRQD#            4h = PIRQE#            5h = PIRQF#            6h = PIRQG#            7h = PIRQH#</p>



### 10.1.36 OIC—Other Interrupt Control Register

Offset Address: 31FE–31FFh      Attribute: R/W  
 Default Value: 0000h      Size: 16-bit

Bit	Description
15:10	Reserved
9	<b>Coprocessor Error Enable (CEN)</b> — R/W. 0 = FERR# will not generate IRQ13 nor IGNNE#. 1 = If FERR# is low, the PCH generates IRQ13 internally and holds it until an I/O port F0h write. It will also drive IGNNE# active.
8	<b>APIC Enable (AEN)</b> — R/W. 0 = The internal IOxAPIC is disabled. 1 = Enables the internal IOxAPIC and its address decode. <b>Note:</b> Software should read this register after modifying APIC enable bit prior to access to the IOxAPIC address range.
7:0	<b>APIC Range Select (ASEL)</b> — R/W. These bits define address bits 19:12 for the IOxAPIC range. The default value of 00h enables compatibility with prior PCH products as an initial value. This value must not be changed unless the IOxAPIC Enable bit is cleared.

**Note:** FEC1\_0000h–FEC4\_FFFFh is allocated to PCIe when I/OxApic Enable (PAE) bit is set.

### 10.1.37 PRSTS—Power and Reset Status Register

Offset Address: 3310–3313h      Attribute: RO, R/WC  
 Default Value: 03000000h      Size: 32-bit

Bit	Description
31:16	Reserved
15	<b>Power Management Watchdog Timer</b> — R/WC. This bit is set when the Power Management watchdog timer causes a global reset.
14:7	Reserved
6	<b>Intel ME Watchdog Timer Status</b> — R/WC. This bit is set when the Intel ME watchdog timer causes a global reset.
5	<b>Wake On LAN Override Wake Status (WOL_OVR_WK_STS)</b> — R/WC. This bit gets set when all of the following conditions are met: <ul style="list-style-type: none"> <li>• Integrated LAN Signals a Power Management Event</li> <li>• The system is not in S0</li> <li>• The “WOL Enable Override” bit is set in configuration space.</li> </ul> BIOS can read this status bit to determine this wake source. Software clears this bit by writing a 1 to it.
4	<b>PRSTS Field 1</b> — R/W. BIOS may write to this bit field.
3	<b>Intel ME Host Power Down (ME_HOST_PWRDN)</b> — R/WC. This bit is set when the Intel ME generates a host reset with power down.
2	<b>Intel ME Host Reset Warm Status (ME_HRST_WARM_STS)</b> — R/WC. This bit is set when the Intel ME generates a Host reset without power cycling. Software clears this bit by writing a 1 to this bit position.
1	<b>Intel ME Host Reset Cold Status (ME_HRST_COLD_STS)</b> — R/WC. This bit is set when the Intel ME generates a Host reset with power cycling. Software clears this bit by writing a 1 to this bit position.
0	<b>Intel ME WAKE STATUS (ME_WAKE_STS)</b> — R/WC. This bit is set when the Intel ME generates a Non-Maskable wake event, and is not affected by any other enable bit. When this bit is set, the Host Power Management logic wakes to S0.



### 10.1.38 PM\_CFG—Power Management Configuration

Offset Address: 3318–331Bh                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:27	Reserved.
26:24	<b>PM_CFG Field 1</b> — R/W. BIOS must program this field to '101'.
23:22	Reserved.
21	<b>RTC Wake from Deep S4/S5 Disable (RTC_DS_WAKE_DIS)</b> — R/W. When set, this bit disables RTC wakes from waking the system from Deep S4/S5. This bit is reset by RTCRST#.
20	Reserved.
19:18	<p><b>SLP_SUS# Minimum Assertion Width (SLP_SUS_MIN_ASST_WDTH)</b>— R/W. This field indicates the minimum assertion width of the SLP_SUS# signal to ensure that the SUS power supplies have been fully power cycled. This value may be modified per platform depending on power supply capacitance, board capacitance, power circuits, etc.</p> <p>Valid values are:            11 = 4 seconds            10 = 1 second            01 = 500 ms            00 = 0 ms (that is, stretching disabled - default)</p> <p>These bits are cleared by RTCRST# assertion.</p> <p>This field is RO when the SLP Stretching Policy Lock-Down bit is set.</p> <p>This field is ignored when exiting G3 or Deep S4/S5 states if the “Disable SLP Stretching After SUS Well Power Up” bit is set. Note that unlike with all other SLP_* pin stretching, this disable bit only impacts SLP_SUS# stretching during G3 exit rather than both G3 and Deep S4/S5 exit. SLP_SUS# stretching always applies to Deep S4/S5 regardless of the disable bit.</p> <p>For platforms that enable Deep S4/S5, BIOS must program SLP_SUS# stretching to be greater than or equal to the largest stretching value on any other SLP_* pin (SLP_S3#, SLP_S4#, or SLP_A#).</p>
17:16	<p><b>SLP_A# Minimum Assertion Width (SLP_A_MIN_ASST_WDTH)</b> — R/W. This field indicates the minimum assertion width of the SLP_A# signal to ensure that the ASW power supplies have been fully power cycled. This value may be modified per platform depending on power supply capacitance, board capacitance, power circuits, etc.</p> <p>Valid values are:            11 = 2 seconds            10 = 98 ms            01 = 4 seconds            00 = 0 ms (that is, stretching disabled - default)</p> <p>These bits are cleared by RTCRST# assertion.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This field is RO when the SLP Stretching Policy Lock-Down bit is set.</li> <li>This field is ignored when exiting G3 or Deep S4/S5 states if the “Disable SLP Stretching After SUS Well Power Up” bit is set.</li> </ol>
15:0	Reserved.



### 10.1.39 DEEP\_S4\_POL—Deep S4/S5 From S4 Power Policies

Offset Address: 332C–332Fh                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit  
 This register is in the RTC power well and is reset by RTCRST# assertion.

Bit	Description
31:2	Reserved.
1	<b>Deep S4/S5 From S4 Enable in DC Mode (DPS4_EN_DC)</b> — R/W. A '1' in this bit enables the platform to enter Deep S4/S5 while operating in S4 on DC power (based on the AC_PRESENT pin value).
0	<b>Deep S4/S5 From S4 Enable in AC Mode (DPS4_EN_AC)</b> — R/W. A '1' in this bit enables the platform to enter Deep S4 while operating in S4 on AC power (based on the AC_PRESENT pin value).

### 10.1.40 DEEP\_S5\_POL—Deep S4/S5 From S5 Power Policies

Offset Address: 3330–3333h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit  
 This register is in the RTC power well and is reset by RTCRST# assertion.

Bit	Description
31:16	Reserved.
15	<b>Deep S4/S5 From S5 Enable in DC Mode (DPS5_EN_DC)</b> — R/W. A '1' in this bit enables the platform to enter Deep S4/S5 while operating in S5 on DC power.
14	<b>Deep S4/S5 From S5 Enable in AC Mode (DPS5_EN_AC)</b> — R/W. A '1' in this bit enables the platform to enter Deep S4/S5 while operating in S5 on AC power.
13:0	Reserved.

### 10.1.41 RC—RTC Configuration Register

Offset Address: 3400–3403h                      Attribute: R/W, R/WLO  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:5	Reserved
4	<b>Upper 128 Byte Lock (UL)</b> — R/WLO. 0 = Bytes not locked. 1 = Bytes 38h-3Fh in the upper 128-byte bank of RTC RAM are locked and cannot be accessed. Writes will be dropped and reads will not return any ensured data. Bit reset on system reset.
3	<b>Lower 128 Byte Lock (LL)</b> — R/WLO. 0 = Bytes not locked. 1 = Bytes 38h-3Fh in the lower 128-byte bank of RTC RAM are locked and cannot be accessed. Writes will be dropped and reads will not return any ensured data. Bit reset on system reset.
2	<b>Upper 128 Byte Enable (UE)</b> — R/W. 0 = Bytes locked. 1 = The upper 128-byte bank of RTC RAM can be accessed.
1:0	Reserved



### 10.1.42 HPTC—High Precision Timer Configuration Register

Offset Address: 3404–3407h Attribute: R/W  
 Default Value: 00000000h Size: 32-bit

Bit	Description
31:8	Reserved
7	<b>Address Enable (AE)</b> — R/W. 0 = Address disabled. 1 = The PCH will decode the High Precision Timer memory address range selected by bits 1:0 below.
6:2	Reserved
1:0	<b>Address Select (AS)</b> — R/W. This 2-bit field selects 1 of 4 possible memory address ranges for the High Precision Timer functionality. The encodings are: 00 = FED0_0000h – FED0_03FFh 01 = FED0_1000h – FED0_13FFh 10 = FED0_2000h – FED0_23FFh 11 = FED0_3000h – FED0_33FFh

### 10.1.43 GCS—General Control and Status Register

Offset Address: 3410–3413h Attribute: R/W, R/WLO  
 Default Value: 00000yy0h (yy = xx0000x0b) Size: 32-bit

Bit	Description										
31:13	Reserved.										
12	<b>Function Level Reset Capability Structure Select (FLRCSEL)</b> — R/W. 0 = Function Level Reset (FLR) will utilize the standard capability structure with unique capability ID assigned by PCISIG. 1 = Vendor Specific Capability Structure is selected for FLR.										
11:10	<p><b>Boot BIOS Straps (BBS)</b> — R/W. This field determines the destination of accesses to the BIOS memory range. The default values for these bits represent the strap values of GNT1# /GPIO51 (bit 11) at the rising edge of PCH_PWROK and SATA1GP/GPIO19 (bit 10) at the rising edge of PCH_PWROK.</p> <table border="1"> <thead> <tr> <th>Bits 11:10</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>00b</td> <td>LPC</td> </tr> <tr> <td>01b</td> <td>RESERVED</td> </tr> <tr> <td>10b</td> <td>PCI</td> </tr> <tr> <td>11b</td> <td>SPI</td> </tr> </tbody> </table> <p>When PCI is selected, the top 16 MB of memory below 4 GB (FF00_0000h to FFFF_FFFFh) is accepted by the primary side of the PCI P2P bridge and forwarded to the PCI bus. This allows systems with corrupted or unprogrammed flash to boot from a PCI device. The PCI-to-PCI bridge Memory Space Enable bit does not need to be set (nor any other bits) in order for these cycles to go to PCI. Note that BIOS decode range bits and the other BIOS protection bits have no effect when PCI is selected. This functionality is intended for debug/testing only.</p> <p>When SPI or LPC is selected, the range that is decoded is further qualified by other configuration bits described in the respective sections.</p> <p>The value in this field can be overwritten by software as long as the BIOS Interface Lock-Down (bit 0) is not set.</p> <p><b>Note:</b> Booting to PCI is intended for debug/testing only. Boot BIOS Destination Select to LPC/PCI by functional strap or using Boot BIOS Destination Bit will not affect SPI accesses initiated by Intel ME or Integrated GbE LAN.</p>	Bits 11:10	Description	00b	LPC	01b	RESERVED	10b	PCI	11b	SPI
Bits 11:10	Description										
00b	LPC										
01b	RESERVED										
10b	PCI										
11b	SPI										



Bit	Description
9	<p><b>Server Error Reporting Mode (SERM)</b> — R/W.</p> <p>0 = The PCH is the final target of all errors. The Processor sends a messages to the PCH for the purpose of generating NMI.</p> <p>1 = The Processor is the final target of all errors from PCI Express* and DMI. In this mode, if the PCH detects a fatal, non-fatal, or correctable error on DMI or its downstream ports, it sends a message to the Processor. If the PCH receives an ERR_* message from the downstream port, it sends that message to the Processor.</p>
8:6	Reserved
5	<p><b>No Reboot (NR)</b> — R/W. This bit is set when the “No Reboot” strap (SPKR pin on the PCH) is sampled high on PCH_PWROK. This bit may be set or cleared by software if the strap is sampled low but may not override the strap when it indicates “No Reboot”.</p> <p>0 = System will reboot upon the second timeout of the TCO timer.</p> <p>1 = The TCO timer will count down and generate the SMI# on the first timeout, but will not reboot on the second timeout.</p>
4	<p><b>Alternate Access Mode Enable (AME)</b> — R/W.</p> <p>0 = Disabled.</p> <p>1 = Alternate access read only registers can be written, and write only registers can be read. Before entering a low power state, several registers from powered down parts may need to be saved. In the majority of cases, this is not an issue, as registers have read and write paths. However, several of the ISA compatible registers are either read only or write only. To get data out of write-only registers, and to restore data into read-only registers, the PCH implements an alternate access mode. For a list of these registers see <a href="#">Section 5.14.9</a>.</p>
3	<p><b>Shutdown Policy Select (SPS)</b> — R/W.</p> <p>0 = PCH will drive INIT# in response to the shutdown Vendor Defined Message (VDM). (Default)</p> <p>1 = PCH will treat the shutdown VDM similar to receiving a CF9h I/O write with data value 06h, and will drive PLTRST# active.</p>
2	<p><b>Reserved Page Route (RPR)</b> — R/W. Determines where to send the reserved page registers. These addresses are sent to PCI or LPC for the purpose of generating POST codes. The I/O addresses modified by this field are: 80h, 84h, 85h, 86h, 88h, 8Ch, 8Dh, and 8Eh.</p> <p>0 = Writes will be forwarded to LPC, shadowed within the PCH, and reads will be returned from the internal shadow</p> <p>1 = Writes will be forwarded to PCI, shadowed within the PCH, and reads will be returned from the internal shadow.</p> <p><b>Note:</b> If some writes are done to LPC/PCI to these I/O ranges, and then this bit is flipped, such that writes will now go to the other interface, the reads will not return what was last written. Shadowing is performed on each interface.</p> <p>The aliases for these registers, at 90h, 94h, 95h, 96h, 98h, 9Ch, 9Dh, and 9Eh, are always decoded to LPC.</p>
1	Reserved
0	<p><b>BIOS Interface Lock-Down (BILD)</b> — R/WLO.</p> <p>0 = Disabled.</p> <p>1 = Prevents BUC.TS (offset 3414, bit 0) and GCS.BBS (offset 3410h, bits 11:10) from being changed. This bit can only be written from 0 to 1 once.</p>



### 10.1.44 BUC—Backed Up Control Register

Offset Address: 3414–3414h                      Attribute: R/W  
 Default Value: 0000000xb                      Size: 8-bit

All bits in this register are in the RTC well and only cleared by RTCRST#

Bit	Description
7:6	Reserved
5	<p><b>LAN Disable</b> — R/W.            0 = LAN is Enabled            1 = LAN is Disabled.</p> <p>Changing the internal GbE controller from disabled to enabled requires a system reset (write of 0Eh to CF9h (RST_CNT Register)) immediately after clearing the LAN disable bit. A reset is not required if changing the bit from enabled to disabled.</p> <p>This bit is locked by the Function Disable SUS Well Lockdown register. Once locked this bit can not be changed by software.</p>
4	<p><b>Daylight Savings Override (SDO)</b> — R/W.            0 = Daylight Savings is Enabled.            1 = The DSE bit in RTC Register B is set to Read-only with a value of 0 to disable daylight savings.</p>
3:1	Reserved
0	<p><b>Top Swap (TS)</b> — R/W.            0 = PCH will not invert A16.            1 = PCH will invert A16, A17, or A18 for cycles going to the BIOS space in the FWH.</p> <p>If booting from LPC (FWH), then the boot-block size is 64 KB and A16 is inverted if Top Swap is enabled.</p> <p>If booting from SPI, then the BIOS Boot-Block size soft strap determines if A16, A17, or A18 should be inverted if Top Swap is enabled.</p> <p>If PCH is strapped for Top-Swap (GNT3#/GPIO55 is low at rising edge of PCH_PWROK), then this bit cannot be cleared by software. The strap jumper should be removed and the system rebooted.</p>

### 10.1.45 FD—Function Disable Register

Offset Address: 3418–341Bh                      Attribute: R/W  
 Default Value: See bit description                      Size: 32-bit

When disabling a function, only the configuration space is disabled. Software must ensure that all functionality within a controller that is not desired (such as memory spaces, I/O spaces, and DMA engines) is disabled prior to disabling the function.

When a function is disabled, software must not attempt to re-enable it. A disabled function can only be re-enabled by a platform reset.

Bit	Description
31:26	Reserved
25	<p><b>Serial ATA Disable 2 (SAD2)</b> — R/W. Default is 0.            0 = The SATA controller #2 (D31:F5) is enabled.            1 = The SATA controller #2 (D31:F5) is disabled.</p>
24	<p><b>Thermal Sensor Registers Disable (TTD)</b> — R/W. Default is 0.            0 = Thermal Sensor Registers (D31:F6) are is enabled.            1 = Thermal Sensor Registers (D31:F6) are is disabled.</p>
23	<p><b>PCI Express* 8 Disable (PE8D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the “link down” state.            0 = PCI Express* port #8 is enabled.            1 = PCI Express* port #8 is disabled.</p>



Bit	Description
22	<b>PCI Express* 7 Disable (PE7D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #7 is enabled. 1 = PCI Express* port #7 is disabled.
21	<b>PCI Express* 6 Disable (PE6D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the "link down" state. 0 = PCI Express* port #6 is enabled. 1 = PCI Express* port #6 is disabled.
20	<b>PCI Express* 5 Disable (PE5D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #5 is enabled. 1 = PCI Express* port #5 is disabled.
19	<b>PCI Express* 4 Disable (PE4D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the "link down" state. 0 = PCI Express* port #4 is enabled. 1 = PCI Express* port #4 is disabled. <b>Note:</b> This bit must be set when Port 1 is configured as a x4.
18	<b>PCI Express* 3 Disable (PE3D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #3 is enabled. 1 = PCI Express* port #3 is disabled. <b>Note:</b> This bit must be set when Port 1 is configured as a x4.
17	<b>PCI Express* 2 Disable (PE2D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #2 is enabled. 1 = PCI Express* port #2 is disabled. <b>Note:</b> This bit must be set when Port 1 is configured as a x4 or a x2.
16	<b>PCI Express* 1 Disable (PE1D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #1 is enabled. 1 = PCI Express* port #1 is disabled.
15	<b>EHCI #1 Disable (EHCI1D)</b> — R/W. Default is 0. 0 = The EHCI #1 is enabled. 1 = The EHCI #1 is disabled.
14	<b>LPC Bridge Disable (LBD)</b> — R/W. Default is 0. 0 = The LPC bridge is enabled. 1 = The LPC bridge is disabled. Unlike the other disables in this register, the following additional spaces will no longer be decoded by the LPC bridge: <ul style="list-style-type: none"> <li>• Memory cycles below 16 MB (1000000h)</li> <li>• I/O cycles below 64 KB (10000h)</li> <li>• The Internal I/OxAPIC at FEC0_0000 to FECF_FFFF</li> </ul> Memory cycles in the LPC BIOS range below 4 GB will still be decoded when this bit is set, but the aliases at the top of 1 MB (the E and F segment) no longer will be decoded.
13	<b>EHCI #2 Disable (EHCI2D)</b> — R/W. Default is 0. 0 = The EHCI #2 is enabled. 1 = The EHCI #2 is disabled.
12:5	Reserved
4	<b>Intel HD Audio Disable (HDAD)</b> — R/W. Default is 0. 0 = The Intel HD Audio controller is enabled. 1 = The Intel HD Audio controller is disabled and its PCI configuration space is not accessible.
3	<b>SMBus Disable (SD)</b> — R/W. Default is 0. 0 = The SMBus controller is enabled. 1 = The SMBus controller is disabled. In ICH5 and previous, this also disabled the I/O space. In the PCH, it only disables the configuration space.



Bit	Description
22	<b>PCI Express* 7 Disable (PE7D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #7 is enabled. 1 = PCI Express* port #7 is disabled.
21	<b>PCI Express* 6 Disable (PE6D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the “link down” state. 0 = PCI Express* port #6 is enabled. 1 = PCI Express* port #6 is disabled.
20	<b>PCI Express* 5 Disable (PE5D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #5 is enabled. 1 = PCI Express* port #5 is disabled.
19	<b>PCI Express* 4 Disable (PE4D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the “link down” state. 0 = PCI Express* port #4 is enabled. 1 = PCI Express* port #4 is disabled. <b>Note:</b> This bit must be set when Port 1 is configured as a x4.
18	<b>PCI Express* 3 Disable (PE3D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #3 is enabled. 1 = PCI Express* port #3 is disabled. <b>Note:</b> This bit must be set when Port 1 is configured as a x4.
17	<b>PCI Express* 2 Disable (PE2D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #2 is enabled. 1 = PCI Express* port #2 is disabled. <b>Note:</b> This bit must be set when Port 1 is configured as a x4 or a x2.
16	<b>PCI Express* 1 Disable (PE1D)</b> — R/W. Default is 0. When disabled, the link for this port is put into the link down state. 0 = PCI Express* port #1 is enabled. 1 = PCI Express* port #1 is disabled.
15	<b>EHCI #1 Disable (EHCI1D)</b> — R/W. Default is 0. 0 = The EHCI #1 is enabled. 1 = The EHCI #1 is disabled.
14	<b>LPC Bridge Disable (LBD)</b> — R/W. Default is 0. 0 = The LPC bridge is enabled. 1 = The LPC bridge is disabled. Unlike the other disables in this register, the following additional spaces will no longer be decoded by the LPC bridge: <ul style="list-style-type: none"> <li>• Memory cycles below 16 MB (1000000h)</li> <li>• I/O cycles below 64 KB (10000h)</li> <li>• The Internal I/OxAPIC at FEC0_0000 to FECF_FFFF</li> </ul> Memory cycles in the LPC BIOS range below 4 GB will still be decoded when this bit is set, but the aliases at the top of 1 MB (the E and F segment) no longer will be decoded.
13	<b>EHCI #2 Disable (EHCI2D)</b> — R/W. Default is 0. 0 = The EHCI #2 is enabled. 1 = The EHCI #2 is disabled.
12:5	Reserved
4	<b>Intel HD Audio Disable (HDAD)</b> — R/W. Default is 0. 0 = The Intel HD Audio controller is enabled. 1 = The Intel HD Audio controller is disabled and its PCI configuration space is not accessible.
3	<b>SMBus Disable (SD)</b> — R/W. Default is 0. 0 = The SMBus controller is enabled. 1 = The SMBus controller is disabled. In ICH5 and previous, this also disabled the I/O space. In the PCH, it only disables the configuration space.



Bit	Description
2	<b>Serial ATA Disable 1 (SAD1)</b> — R/W. Default is 0. 0 = The SATA controller #1 (D31:F2) is enabled. 1 = The SATA controller #1 (D31:F2) is disabled.
1	<b>PCI Bridge Disable</b> — R/W. Default is 0. 0 = The PCI-to-PCI bridge (D30:F0) is enabled. 1 = The PCI-to-PCI bridge (D30:F0) is disabled.
0	BIOS must set this bit to 1b.

### 10.1.46 CG—Clock Gating

Offset Address: 341C–341Fh                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31	<b>Legacy (LPC) Dynamic Clock Gate Enable</b> — R/W. 0 = Legacy Dynamic Clock Gating is Disabled 1 = Legacy Dynamic Clock Gating is Enabled
30	Reserved
29:28	<b>CG Field 1</b> — R/W. BIOS must program this field to 11b.
27	<b>SATA Port 3 Dynamic Clock Gate Enable</b> — R/W. 0 = SATA Port 3 Dynamic Clock Gating is Disabled 1 = SATA Port 3 Dynamic Clock Gating is Enabled
26	<b>SATA Port 2 Dynamic Clock Gate Enable</b> — R/W. 0 = SATA Port 2 Dynamic Clock Gating is Disabled 1 = SATA Port 2 Dynamic Clock Gating is Enabled
25	<b>SATA Port 1 Dynamic Clock Gate Enable</b> — R/W. 0 = SATA Port 1 Dynamic Clock Gating is Disabled 1 = SATA Port 1 Dynamic Clock Gating is Enabled
24	<b>SATA Port 0 Dynamic Clock Gate Enable</b> — R/W. 0 = SATA Port 0 Dynamic Clock Gating is Disabled 1 = SATA Port 0 Dynamic Clock Gating is Enabled
23	<b>LAN Static Clock Gating Enable (LANSCGE)</b> — R/W. 0 = LAN Static Clock Gating is Disabled 1 = LAN Static Clock Gating is Enabled when the LAN Disable bit is set in the Backed Up Control RTC register.
22	<b>Intel HD Audio Dynamic Clock Gate Enable</b> — R/W. 0 = Intel HD Audio Dynamic Clock Gating is Disabled 1 = Intel HD Audio Dynamic Clock Gating is Enabled
21	<b>Intel HD Audio Static Clock Gate Enable</b> — R/W. 0 = Intel HD Audio Static Clock Gating is Disabled 1 = Intel HD Audio Static Clock Gating is Enabled
20	<b>USB EHCI Static Clock Gate Enable</b> — R/W. 0 = USB EHCI Static Clock Gating is Disabled 1 = USB EHCI Static Clock Gating is Enabled
19	<b>USB EHCI Dynamic Clock Gate Enable</b> — R/W. 0 = USB EHCI Dynamic Clock Gating is Disabled 1 = USB EHCI Dynamic Clock Gating is Enabled
18	<b>SATA Port 5 Dynamic Clock Gate Enable</b> — R/W. 0 = SATA Port 5 Dynamic Clock Gating is Disabled 1 = SATA Port 5 Dynamic Clock Gating is Enabled
17	<b>SATA Port 4 Dynamic Clock Gate Enable</b> — R/W. 0 = SATA Port 4 Dynamic Clock Gating is Disabled 1 = SATA Port 4 Dynamic Clock Gating is Enabled
16	<b>PCI Dynamic Gate Enable</b> — R/W. 0 = PCI Dynamic Gating is Disabled 1 = PCI Dynamic Gating is Enabled





### 10.1.49 GSXBAR—GPIO Serial Expander Base Address

Offset Address: 3450–3453h                      Attribute: R/W, RO  
 Default Value: FED04000h                      Size: 32-bit

Bit	Description
31:10	<b>Base Address (BA)</b> —R/W. Base Address of GPIO Serial Expander logic.
9:4	Reserved
3	<b>Prefetchable Memory (PF)</b> —RO. Default is 0. Indicate the memory space is not prefetchable.
2:1	<b>Memory Type (TP)</b> —RO. Set to 00b indicating a 32-bit BAR.
0	<b>Resource Type (RTE)</b> —RO. Set to 0 indicating a Memory Space BAR.

### 10.1.50 GSXCTRL—GPIO Serial Expander Control Register

Offset Address: 3454–3457h                      Attribute: R/W, RO  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:5	Reserved
4	<b>GSX BAR Enable (GSXBAREN)</b> —R/W. Default is 0. 0 = GSXBAR is disabled. 1 = GSXBAR is enabled. <b>Note:</b> If GSX is disabled using soft strap, this bit will always read 0.
3:0	Reserved

### 10.1.51 MISCCTL—Miscellaneous Control Register

Offset Address: 3590–3593h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit

This register is in the suspend well. This register is not reset on D3-to-D0, HCRESET nor core well reset.

Bit	Description
31:2	Reserved.
1	<b>EHCI 2 USBR Enable</b> — R/W. When set, this bit enables support for the USB-r redirect device on the EHCI controller in Device 26. SW must complete programming the following registers before this bit is set: 1. Enable RMH 2. HCSPARAMS (N_CC, N_Ports)
0	<b>EHCI 1 USBR Enable</b> — R/W. When set, this bit enables support for the USB-r redirect device on the EHCI controller in Device 29. SW must complete programming the following registers before this bit is set: 1. Enable RMH 2. HCSPARAMS (N_CC, N_Ports)



### 10.1.52 USB0CM1—Overcurrent MAP Register 1

Offset Address: 35A0-35A3h                      Attribute: R/W0  
 Default Value: C0300C03h                      Size: 32-bit

All bits in this register are in the Resume Well and is only cleared by RSMRST#.

Bit	Description																		
31:24	<p><b>OC3 Mapping</b> Each bit position maps OC3# to a set of ports as follows: The OC3# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>31</td> <td>30</td> <td>29</td> <td>28</td> <td>27</td> <td>26</td> <td>25</td> <td>24</td> </tr> <tr> <td><b>Port</b></td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table>	<b>Bit</b>	31	30	29	28	27	26	25	24	<b>Port</b>	7	6	5	4	3	2	1	0
<b>Bit</b>	31	30	29	28	27	26	25	24											
<b>Port</b>	7	6	5	4	3	2	1	0											
23:16	<p><b>OC2 Mapping</b> Each bit position maps OC2# to a set of ports as follows: The OC2# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>23</td> <td>22</td> <td>21</td> <td>20</td> <td>19</td> <td>18</td> <td>17</td> <td>16</td> </tr> <tr> <td><b>Port</b></td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table>	<b>Bit</b>	23	22	21	20	19	18	17	16	<b>Port</b>	7	6	5	4	3	2	1	0
<b>Bit</b>	23	22	21	20	19	18	17	16											
<b>Port</b>	7	6	5	4	3	2	1	0											
15:8	<p><b>OC1 Mapping</b> Each bit position maps OC1# to a set of ports as follows: The OC1# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>15</td> <td>14</td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> </tr> <tr> <td><b>Port</b></td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table>	<b>Bit</b>	15	14	13	12	11	10	9	8	<b>Port</b>	7	6	5	4	3	2	1	0
<b>Bit</b>	15	14	13	12	11	10	9	8											
<b>Port</b>	7	6	5	4	3	2	1	0											
7:0	<p><b>OC0 Mapping</b> Each bit position maps OC0# to a set of ports as follows: The OC0# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> <tr> <td><b>Port</b></td> <td>7</td> <td>6</td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> </table>	<b>Bit</b>	7	6	5	4	3	2	1	0	<b>Port</b>	7	6	5	4	3	2	1	0
<b>Bit</b>	7	6	5	4	3	2	1	0											
<b>Port</b>	7	6	5	4	3	2	1	0											



### 10.1.53 USBOCM2—Overcurrent MAP Register 2

Offset Address: 35A4-35A7h                      Attribute: R/WO  
 Default Value: 00h                              Size: 32-bit

All bits in this register are in the Resume Well and is only cleared by RSMRST#.

Bit	Description														
31:30	<b>Reserved</b>														
29:24	<p><b>OC7 Mapping</b> Each bit position maps OC7# to a set of ports as follows: The OC7# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>29</td> <td>28</td> <td>27</td> <td>26</td> <td>25</td> <td>24</td> </tr> <tr> <td><b>Port</b></td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> </tr> </table>	<b>Bit</b>	29	28	27	26	25	24	<b>Port</b>	13	12	11	10	9	8
<b>Bit</b>	29	28	27	26	25	24									
<b>Port</b>	13	12	11	10	9	8									
23:22	<b>Reserved</b>														
21:16	<p><b>OC6 Mapping</b> Each bit position maps OC6# to a set of ports as follows: The OC6# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>21</td> <td>20</td> <td>19</td> <td>18</td> <td>17</td> <td>16</td> </tr> <tr> <td><b>Port</b></td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> </tr> </table>	<b>Bit</b>	21	20	19	18	17	16	<b>Port</b>	13	12	11	10	9	8
<b>Bit</b>	21	20	19	18	17	16									
<b>Port</b>	13	12	11	10	9	8									
15:14	<b>Reserved</b>														
13:8	<p><b>OC5 Mapping</b> Each bit position maps OC5# to a set of ports as follows: The OC5# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> </tr> <tr> <td><b>Port</b></td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> </tr> </table>	<b>Bit</b>	13	12	11	10	9	8	<b>Port</b>	13	12	11	10	9	8
<b>Bit</b>	13	12	11	10	9	8									
<b>Port</b>	13	12	11	10	9	8									
7:6	<b>Reserved</b>														
5:0	<p><b>OC4 Mapping</b> Each bit position maps OC4# to a set of ports as follows: The OC4# pin is ganged to the overcurrent signal of each port that has its corresponding bit set. It is SW's responsibility to ensure that a given port's bit map is set only for one OC pin.</p> <table border="1"> <tr> <td><b>Bit</b></td> <td>5</td> <td>4</td> <td>3</td> <td>2</td> <td>1</td> <td>0</td> </tr> <tr> <td><b>Port</b></td> <td>13</td> <td>12</td> <td>11</td> <td>10</td> <td>9</td> <td>8</td> </tr> </table>	<b>Bit</b>	5	4	3	2	1	0	<b>Port</b>	13	12	11	10	9	8
<b>Bit</b>	5	4	3	2	1	0									
<b>Port</b>	13	12	11	10	9	8									

### 10.1.54 RMHWKCTL- Rate Matching Hub Wake Control Register

Offset Address: 35B0-35B3h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit

All bits in this register are in the Resume Well and is only cleared by RSMRST#

Bit	Description
31:10	<b>Reserved</b>
9	<b>RMH 2 Inherit EHCI2 Wake Control Settings:</b> When this bit is set, the RMH behaves as if bits 6:4 of this register reflect the appropriate bits of EHCI PORTSC0 bits 22:20.
8	<b>RMH 1 Inherit EHCI1 Wake Control Settings:</b> When this bit is set, the RMH behaves as if bits 2:0 of this register reflect the appropriate bits of EHCI PORTSC0 bits 22:20.
7	<p><b>RMH 2 Upstream Wake on Device Resume</b> This bit governs the hub behavior when globally suspended and the system is in Sx.</p> <p>0 = Enables the port to be sensitive to device initiated resume events as system wake-up events. that is, the hub will initiate a resume on its upstream port and cause a wake from Sx when a device resume occurs on an enabled DS port</p> <p>1 = Device resume event is seen on a downstream port, the hub does not initiate a wake upstream and does not cause a wake from Sx</p>



Bit	Description
6	<p><b>RMH 2 Upstream Wake on OC Disable</b> This bit governs the hub behavior when globally suspended and the system is in Sx.</p> <p>0 = Enables the port to be sensitive to over-current conditions as system wake-up events. i.e, the hub will initiate a resume on its upstream port and cause a wake from Sx when an OC condition occurs on an enabled DS port</p> <p>1 = Over-current event does not initiate a wake upstream and does not cause a wake from Sx</p>
5	<p><b>RMH 2 Upstream Wake on Disconnect Disable</b> This bit governs the hub behavior when globally suspended and the system is in Sx</p> <p>0 = Enables disconnect events on downstream port to be treated as resume events to be propagated upstream. In this case, it is allowed to initiate a wake on its upstream port and cause a system wake from Sx in response to a disconnect event on a downstream port</p> <p>1 = Downstream disconnect events do not initiate a resume on its upstream port or cause a resume from Sx.</p>
4	<p><b>RMH 2 Upstream Wake on Connect Enable</b> This bit governs the hub behavior when globally suspended and the system is in Sx.</p> <p>0 = Enables connect events on a downstream port to be treated as resume events to be propagated upstream. As well as waking up the system from Sx.</p> <p>1 = Downstream connect events do not wake the system from Sx nor does it initiate a resume on its upstream port.</p>
3	<p><b>RMH 1 Upstream Wake on Device Resume</b> This bit governs the hub behavior when globally suspended and the system is in Sx.</p> <p>0 = Enables the port to be sensitive to device initiated resume events as system wake-up events. i.e, the hub will initiate a resume on its upstream port and cause a wake from Sx when a device resume occurs on an enabled DS port</p> <p>1 = Device resume event is seen on a downstream port, the hub does not initiate a wake upstream and does not cause a wake from Sx</p>
2	<p><b>RMH 1 Upstream Wake on OC Disable</b> This bit governs the hub behavior when globally suspended and the system is in Sx.</p> <p>0 = Enables the port to be sensitive to over-current conditions as system wake-up events. i.e, the hub will initiate a resume on its upstream port and cause a wake from Sx when an OC condition occurs on an enabled DS port</p> <p>1 = Over-current event does not initiate a wake upstream and does not cause a wake from Sx</p>
1	<p><b>RMH 1 Upstream Wake on Disconnect Disable</b> This bit governs the hub behavior when globally suspended and the system is in Sx</p> <p>0 = Enables disconnect events on downstream port to be treated as resume events to be propagated upstream. In this case, it is allowed to initiate a wake on its upstream port and cause a system wake from Sx in response to a disconnect event on a downstream port</p> <p>1 = Downstream disconnect events do not initiate a resume on its upstream port or cause a resume from Sx.</p>
0	<p><b>RMH 1 Upstream Wake on Connect Enable</b> This bit governs the hub behavior when globally suspended and the system is in Sx.</p> <p>0 = Enables connect events on a downstream port to be treated as resume events to be propagated upstream. As well as waking up the system from Sx.</p> <p>1 = Downstream connect events do not wake the system from Sx nor does it initiate a resume on its upstream port.</p>

§



# 11 PCI-to-PCI Bridge Registers (D30:F0)

The PCH PCI bridge resides in PCI Device 30, Function 0 on bus #0. This implements the buffering and control logic between PCI and the backbone. The arbitration for the PCI bus is handled by this PCI device.

## 11.1 PCI Configuration Registers (D30:F0)

**Note:** Address locations that are not shown should be treated as Reserved (see [Section 9.2](#) for details).

**Table 11-1. PCI Bridge Register Address Map (PCI-PCI—D30:F0)**

Offset	Mnemonic	Register Name	Default	Type
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PSTS	PCI Status	0010h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h–0Bh	CC	Class Code	060401h	RO
0Dh	PMLT	Primary Master Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	01h	RO
18h–1Ah	BNUM	Bus Number	000000h	RO
1Bh	SMLT	Secondary Master Latency Timer	00h	R/W
1Ch–1Dh	IOBASE_LIMIT	I/O Base and Limit	0000h	R/W, RO
1Eh–1Fh	SECSTS	Secondary Status	0280h	R/WC, RO
20h–23h	MEMBASE_LIMIT	Memory Base and Limit	00000000h	R/W
24h–27h	PREF_MEM_BASE_LIMIT	Prefetchable Memory Base and Limit	00010001h	R/W, RO
28h–2Bh	PMBU32	Prefetchable Memory Upper 32 Bits	00000000h	R/W
2Ch–2Fh	PMLU32	Prefetchable Memory Limit Upper 32 Bits	00000000h	R/W
34h	CAPP	Capability List Pointer	50h	RO
3Ch–3Dh	INTR	Interrupt Information	0000h	R/W, RO
3Eh–3Fh	BCTRL	Bridge Control	0000h	R/WC, RO, R/W
40h–41h	SPDH	Secondary PCI Device Hiding	0000h	R/W, RO
44h–47h	DTC	Delayed Transaction Control	00000000h	R/W
48h–4Bh	BPS	Bridge Proprietary Status	00000000h	R/WC, RO
4Ch–4Fh	BPC	Bridge Policy Configuration	00001200h	R/W, RO
50–51h	SVCAP	Subsystem Vendor Capability Pointer	000Dh	RO
54h–57h	SVID	Subsystem Vendor IDs	00000000	R/WO















### 11.1.16 PMLU32—Prefetchable Memory Limit Upper 32 Bits Register (PCI-PCI—D30:F0)

Offset Address: 2C–2Fh                      Attribute: R/W  
 Default Value: 00000000h                  Size: 32 bits

Bit	Description
31:0	<b>Prefetchable Memory Limit Upper Portion (PMLU)</b> — R/W. Upper 32-bits of the prefetchable address limit.

### 11.1.17 CAPP—Capability List Pointer Register (PCI-PCI—D30:F0)

Offset Address: 34h                              Attribute: RO  
 Default Value: 50h                              Size: 8 bits

Bit	Description
7:0	<b>Capabilities Pointer (PTR)</b> — RO. Indicates that the pointer for the first entry in the capabilities list is at 50h in configuration space.

### 11.1.18 INTR—Interrupt Information Register (PCI-PCI—D30:F0)

Offset Address: 3Ch–3Dh                      Attribute: R/W, RO  
 Default Value: 0000h                          Size: 16 bits

Bit	Description
15:8	<b>Interrupt Pin (IPIN)</b> — RO. The PCI bridge does not assert an interrupt.
7:0	<b>Interrupt Line (ILINE)</b> — R/W. Software written value to indicate which interrupt line (vector) the interrupt is connected to. No hardware action is taken on this register. Since the bridge does not generate an interrupt, BIOS should program this value to FFh as per the PCI bridge specification.

### 11.1.19 BCTRL—Bridge Control Register (PCI-PCI—D30:F0)

Offset Address: 3Eh–3Fh                      Attribute: R/WC, RO, R/W  
 Default Value: 0000h                          Size: 16 bits

Bit	Description
15:12	Reserved
11	<b>Discard Timer SERR# Enable (DTE)</b> — R/W. Controls the generation of SERR# on the primary interface in response to the DTS bit being set: 0 = Do not generate SERR# on a secondary timer discard 1 = Generate SERR# in response to a secondary timer discard
10	<b>Discard Timer Status (DTS)</b> — R/WC. This bit is set to 1 when the secondary discard timer (see the SDT bit below) expires for a delayed transaction in the hard state.
9	<b>Secondary Discard Timer (SDT)</b> — R/W. This bit sets the maximum number of PCI clock cycles that the PCH waits for an initiator on PCI to repeat a delayed transaction request. The counter starts once the delayed transaction data is has been returned by the system and is in a buffer in the PCH PCI bridge. If the master has not repeated the transaction at least once before the counter expires, the PCH PCI bridge discards the transaction from its queue. 0 = The PCI master timeout value is between $2^{15}$ and $2^{16}$ PCI clocks 1 = The PCI master timeout value is between $2^{10}$ and $2^{11}$ PCI clocks
8	<b>Primary Discard Timer (PDT)</b> — R/W. This bit is R/W for software compatibility only.
7	<b>Fast Back to Back Enable (FBE)</b> — RO. Hardwired to 0. The PCI logic will not generate fast back-to-back cycles on the PCI bus.



Bit	Description
6	<p><b>Secondary Bus Reset (SBR)</b> — R/W. Controls PCIRST# assertion on PCI.</p> <p>0 = Bridge deasserts PCIRST#                      1 = Bridge asserts PCIRST#. When PCIRST# is asserted, the delayed transaction buffers, posting buffers, and the PCI bus are initialized back to reset conditions. The rest of the part and the configuration registers are not affected.</p>
5	<p><b>Master Abort Mode (MAM)</b> — R/W. Controls the PCH PCI bridge's behavior when a master abort occurs:</p> <p>Master Abort on Processor /PCH Interconnect (DMI):                      0 = Bridge asserts TRDY# on PCI. It drives all 1s for reads, and discards data on writes.                      1 = Bridge returns a target abort on PCI.</p> <p>Master Abort PCI (non-locked cycles):                      0 = Normal completion status will be returned on the Processor/PCH interconnect.                      1 = Target abort completion status will be returned on the Processor/PCH interconnect.</p> <p><b>Note:</b> All locked reads will return a completer abort completion status on the Processor/PCH interconnect.</p>
4	<p><b>VGA 16-Bit Decode (V16D)</b> — R/W. Enables the PCH PCI bridge to provide 16-bits decoding of VGA I/O address precluding the decode of VGA alias addresses every 1 KB. This bit requires the VGAE bit in this register be set.</p>
3	<p><b>VGA Enable (VGAE)</b> — R/W. When set to a 1, the PCH PCI bridge forwards the following transactions to PCI regardless of the value of the I/O base and limit registers. The transactions are qualified by CMD.MSE (D30:F0:04 bit 1) and CMD.IOSE (D30:F0:04 bit 0) being set.</p> <ul style="list-style-type: none"> <li>Memory addresses: 000A0000h-000BFFFFh</li> <li>I/O addresses: 3B0h-3BBh and 3C0h-3DFh. For the I/O addresses, bits [63:16] of the address must be 0, and bits [15:10] of the address are ignored (that is, aliased).</li> </ul> <p>The same holds true from secondary accesses to the primary interface in reverse. That is, when the bit is 0, memory and I/O addresses on the secondary interface between the above ranges will be claimed.</p>
2	<p><b>ISA Enable (IE)</b> — R/W. This bit only applies to I/O addresses that are enabled by the I/O Base and I/O Limit registers and are in the first 64 KB of PCI I/O space. If this bit is set, the PCH PCI bridge will block any forwarding from primary to secondary of I/O transactions addressing the last 768 bytes in each 1-KB block (offsets 100h to 3FFh).</p>
1	<p><b>SERR# Enable (SEE)</b> — R/W. Controls the forwarding of secondary interface SERR# assertions on the primary interface. When set, the PCI bridge will forward SERR# pin.</p> <ul style="list-style-type: none"> <li>SERR# is asserted on the secondary interface.</li> <li>This bit is set.</li> <li>CMD.SEE (D30:F0:04 bit 8) is set.</li> </ul>
0	<p>Parity Error Response Enable (PERE) — R/W.</p> <p>0 = Disable                      1 = The PCH PCI bridge is enabled for parity error reporting based on parity errors on the PCI bus.</p>



### 11.1.20 SPDH—Secondary PCI Device Hiding Register (PCI-PCI—D30:F0)

Offset Address: 40h–41h Attribute: R/W, RO  
 Default Value: 0000h Size: 16 bits

This register allows software to hide the PCI devices, either plugged into slots or on the motherboard.

Bit	Description
15:4	Reserved
3	<b>Hide Device 3 (HD3)</b> — R/W, RO. Same as bit 0 of this register, except for device 3 (AD[19])
2	<b>Hide Device 2 (HD2)</b> — R/W, RO. Same as bit 0 of this register, except for device 2 (AD[18])
1	<b>Hide Device 1 (HD1)</b> — R/W, RO. Same as bit 0 of this register, except for device 1 (AD[17])
0	<b>Hide Device 0 (HD0)</b> — R/W, RO. 0 = The PCI configuration cycles for this slot are not affected. 1 = The PCH hides device 0 on the PCI bus. This is done by masking the IDSEL (keeping it low) for configuration cycles to that device. Since the device will not see its IDSEL go active, it will not respond to PCI configuration cycles and the processor will think the device is not present. AD[16] is used as IDSEL for device 0.

### 11.1.21 DTC—Delayed Transaction Control Register (PCI-PCI—D30:F0)

Offset Address: 44h–47h Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31	<b>Discard Delayed Transactions (DDT)</b> — R/W. 0 = Logged delayed transactions are kept. 1 = The PCH PCI bridge will discard any delayed transactions it has logged. This includes transactions in the pending queue, and any transactions in the active queue, whether in the hard or soft DT state. The prefetchers will be disabled and return to an idle state. <b>Note:</b> If a transaction is running on PCI at the time this bit is set, that transaction will continue until either the PCI master disconnects (by deasserting FRAME#) or the PCI bridge disconnects (by asserting STOP#). This bit is cleared by the PCI bridge when the delayed transaction queues are empty and have returned to an idle state. Software sets this bit and polls for its completion
30	<b>Block Delayed Transactions (BDT)</b> — R/W. 0 = Delayed transactions accepted 1 = The PCH PCI bridge will not accept incoming transactions which will result in delayed transactions. It will blindly retry these cycles by asserting STOP#. All postable cycles (memory writes) will still be accepted.
29:8	Reserved
7:6	<b>Maximum Delayed Transactions (MDT)</b> — R/W. Controls the maximum number of delayed transactions that the PCH PCI bridge will run. Encodings are: 00 =) 2 Active, 5 pending 01 =) 2 active, no pending 10 =) 1 active, no pending 11 =) Reserved
5	Reserved
4	<b>Auto Flush After Disconnect Enable (AFADE)</b> — R/W. 0 = The PCI bridge will retain any fetched data until required to discard by producer/consumer rules. 1 = The PCI bridge will flush any prefetched data after either the PCI master (by deasserting FRAME#) or the PCI bridge (by asserting STOP#) disconnects the PCI transfer.





### 11.1.23 BPC—Bridge Policy Configuration Register (PCI-PCI—D30:F0)

Offset Address: 4Ch–4Fh                      Attribute: R/W  
 Default Value: 00001200h                  Size: 32 bits

Bit	Description																				
31:30	Reserved																				
29	<p><b>Subtractive Decode Compatibility Device ID (SDCID)</b> — R/W: When '0', this function shall report a Device ID of 244Eh. When set to '1', this function shall report the device Device ID value assigned to the PCI-to-PCI Bridge in the <i>Intel® C600 Series Chipset and Intel® X79 Express Chipset Specification Update</i>.</p> <p>If subtractive decode (SDE) is enabled, having this bit as '0' allows the function to present a Device ID that is recognized by the OS.</p>																				
28	<p><b>Subtractive Decode Enable (SDE)</b> — R/W:</p> <p>0 = Subtractive decode is disabled this function and will only claim transactions positively.          1 = The subtractive decode policy as listed in SDP below applies.          Software must ensure that only one PCH device is enabled for Subtractive decode at a time.</p>																				
27:14	Reserved																				
13:8	<p><b>Upstream Read Latency Threshold (URLT)</b> — R/W: This field specifies the number of PCI clocks after internally enqueueing an upstream memory read request at which point the PCI target logic should insert wait states in order to optimize lead-off latency. When the master returns after this threshold has been reached and data has not arrived in the Delayed Transaction completion queue, then the PCI target logic will insert wait states instead of immediately retrying the cycle. The PCI target logic will insert up to 16 clocks of target initial latency (from FRAME# assertion to TRDY# or STOP# assertion) before retrying the PCI read cycle (if the read data has not arrived yet).</p> <p>Note that the starting event for this Read Latency Timer is not explicitly visible externally. A value of 0h disables this policy completely such that wait states will never be inserted on the read lead-off data phase.</p> <p>The default value (12h) specifies 18 PCI clocks (540 ns) and is approximately 4 clocks less than the typical idle lead-off latency expected for desktop PCH systems. This value may need to be changed by BIOS, depending on the platform.</p>																				
7	<p><b>Subtractive Decode Policy (SDP)</b> — R/W.</p> <p>0 = The PCI bridge always forwards memory and I/O cycles that are not claimed by any other device on the backbone (primary interface) to the PCI bus (secondary interface).          1 = The PCI bridge will not claim and forward memory or I/O cycles at all unless the corresponding Space Enable bit is set in the Command register.</p> <p><b>Note:</b> The Boot BIOS Destination Selection strap can force the BIOS accesses to PCI.</p> <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>CMD.MSE</th> <th>BPC.SDP</th> <th>Range</th> <th>Forwarding Policy</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Don't Care</td> <td>Forward unclaimed cycles</td> </tr> <tr> <td>0</td> <td>1</td> <td>Don't Care</td> <td>Forwarding Prohibited</td> </tr> <tr> <td>1</td> <td>X</td> <td>Within range</td> <td>Positive decode and forward</td> </tr> <tr> <td>1</td> <td>X</td> <td>Outside</td> <td>Subtractive decode &amp; forward</td> </tr> </tbody> </table>	CMD.MSE	BPC.SDP	Range	Forwarding Policy	0	0	Don't Care	Forward unclaimed cycles	0	1	Don't Care	Forwarding Prohibited	1	X	Within range	Positive decode and forward	1	X	Outside	Subtractive decode & forward
CMD.MSE	BPC.SDP	Range	Forwarding Policy																		
0	0	Don't Care	Forward unclaimed cycles																		
0	1	Don't Care	Forwarding Prohibited																		
1	X	Within range	Positive decode and forward																		
1	X	Outside	Subtractive decode & forward																		
6	<p><b>PERR#-to-SERR# Enable (PSE)</b> — R/W. When this bit is set, a 1 in the PERR# Assertion status bit (in the Bridge Proprietary Status register) will result in an internal SERR# assertion on the primary side of the bridge (if also enabled by the SERR# Enable bit in the primary Command register). SERR# is a source of NMI.</p>																				
5	<p><b>Secondary Discard Timer Testmode (SDTT)</b> — R/W.</p> <p>0 = The secondary discard timer expiration will be defined in BCTRL.SDT (D30:F0:3E, bit 9)          1 = The secondary discard timer will expire after 128 PCI clocks.</p>																				
4:3	Reserved																				
2	<p><b>Peer Decode Enable (PDE)</b> — R/W.</p> <p>0 = The PCI bridge assumes that all memory cycles target main memory, and all I/O cycles are not claimed.          1 = The PCI bridge will perform peer decode on any memory or I/O cycle from PCI that falls outside of the memory and I/O window registers</p>																				
1	Reserved																				
0	<p><b>Received Target Abort SERR# Enable (RTAE)</b> — R/W. When set, the PCI bridge will report SERR# when PSTS.RTA (D30:F0:06 bit 12) or SSTS.RTA (D30:F0:1E bit 12) are set, and CMD.SEE (D30:F0:04 bit 8) is set.</p>																				







# 12 Gigabit LAN Configuration Registers

## 12.1 Gigabit LAN Configuration Registers (Gigabit LAN – D25:F0)

**Note:** Refer to the Intel 82579 datasheet for additional LAN Configuration Status Register information.

**Note:** Register address locations that are not shown in [Table 12-1](#) should be treated as Reserved.

**Table 12-1. Gigabit LAN Configuration Registers Address Map (Gigabit LAN –D25:F0) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Type
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h–0Bh	CC	Class Code	020000h	RO
0Ch	CLS	Cache Line Size	00h	R/W
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	00h	RO
10h–13h	MBARA	Memory Base Address A	00000000h	R/W, RO
14h–17h	MBARB	Memory Base Address B	00000000h	R/W, RO
18h–1Bh	MBARC	Memory Base Address C	00000001h	R/W, RO
2Ch–2Dh	SVID	Subsystem Vendor ID	See register description	RO
2Eh–2Fh	SID	Subsystem ID	See register description	RO
30h–33h	ERBA	Expansion ROM Base Address	See register description	RO
34h	CAPP	Capabilities List Pointer	C8h	RO
3Ch–3Dh	INTR	Interrupt Information	See register description	R/W, RO
3Eh	MLMG	Maximum Latency/Minimum Grant	00h	RO
C8h–C9h	CLIST1	Capabilities List 1	D001h	RO
CAh–CBh	PMC	PCI Power Management Capability	See register description	RO
CCh–CDh	PMCS	PCI Power Management Control and Status	See register description	R/WC, R/W, RO
CFh	DR	Data Register	See register description	RO
D0h–D1h	CLIST2	Capabilities List 2	E005h	R/WO, RO



**Table 12-1. Gigabit LAN Configuration Registers Address Map (Gigabit LAN –D25:F0) (Sheet 2 of 2)**

Offset	Mnemonic	Register Name	Default	Type
D2h–D3h	MCTL	Message Control	0080h	R/W, RO
D4h–D7h	MADDL	Message Address Low	See register description	R/W
D8h–DBh	MADDH	Message Address High	See register description	R/W
DCh–DDh	MDAT	Message Data	See register description	R/W
E0h–E1h	FLRCAP	Function Level Reset Capability	0009h	RO
E2h–E3h	FLRCLV	Function Level Reset Capability Length and Value	See register description	R/WO, RO
E4h–E5h	DEVCTRL	Device Control	0000h	R/W, RO

### 12.1.1 VID—Vendor Identification Register (Gigabit LAN—D25:F0)

Address Offset: 00h–01h                      Attribute: RO  
 Default Value: 8086h                         Size: 16 bits

Bit	Description
15:0	<b>Vendor ID</b> — RO. This is a 16-bit value assigned to Intel. The field may be auto-loaded from the NVM at address 0Dh during init time depending on the "Load Vendor/Device ID" bit field in NVM word 0Ah with a default value of 8086h.

### 12.1.2 DID—Device Identification Register (Gigabit LAN—D25:F0)

Address Offset: 02h–03h                      Attribute: RO  
 Default Value: See bit description         Size: 16 bits

Bit	Description
15:0	<b>Device ID</b> — RO. This is a 16-bit value assigned to the PCH Gigabit LAN controller. The field may be auto-loaded from the NVM word 0Dh during initialization time depending on the "Load Vendor/Device ID" bit field in NVM word 0Ah.



### 12.1.3 PCICMD—PCI Command Register (Gigabit LAN—D25:F0)

Address Offset: 04h–05h  
Default Value: 0000h

Attribute: R/W, RO  
Size: 16 bits

Bit	Description
15:11	Reserved
10	<p><b>Interrupt Disable</b> — R/W. This disables pin-based INTx# interrupts on enabled Hot-Plug and power management events. This bit has no effect on MSI operation.</p> <p>0 = Internal INTx# messages are generated if there is an interrupt for Hot-Plug or power management and MSI is not enabled. 1 = Internal INTx# messages will not be generated.</p> <p>This bit does not affect interrupt forwarding from devices connected to the root port. Assert_INTx and Deassert_INTx messages will still be forwarded to the internal interrupt controllers if this bit is set.</p>
9	Fast Back to Back Enable (FBE) — RO. Hardwired to 0.
8	<p><b>SERR# Enable (SEE)</b> — R/W.</p> <p>0 = Disable 1 = Enables the Gb LAN controller to generate an SERR# message when PSTS.SSE is set.</p>
7	Wait Cycle Control (WCC) — RO. Hardwired to 0.
6	<p><b>Parity Error Response (PER)</b> — R/W.</p> <p>0 = Disable. 1 = Indicates that the device is capable of reporting parity errors as a master on the backbone.</p>
5	Palette Snoop Enable (PSE) — RO. Hardwired to 0.
4	Postable Memory Write Enable (PMWE) — RO. Hardwired to 0.
3	Special Cycle Enable (SCE) — RO. Hardwired to 0.
2	<p><b>Bus Master Enable (BME)</b> — R/W.</p> <p>0 = Disable. All cycles from the device are master aborted 1 = Enable. Allows the root port to forward cycles onto the backbone from a Gigabit LAN* device.</p>
1	<p><b>Memory Space Enable (MSE)</b> — R/W.</p> <p>0 = Disable. Memory cycles within the range specified by the memory base and limit registers are master aborted on the backbone. 1 = Enable. Allows memory cycles within the range specified by the memory base and limit registers can be forwarded to the Gigabit LAN device.</p>
0	<p><b>I/O Space Enable (IOSE)</b> — R/W. This bit controls access to the I/O space registers.</p> <p>0 = Disable. I/O cycles within the range specified by the I/O base and limit registers are master aborted on the backbone. 1 = Enable. Allows I/O cycles within the range specified by the I/O base and limit registers can be forwarded to the Gigabit LAN device.</p>



### 12.1.4 PCISTS—PCI Status Register (Gigabit LAN—D25:F0)

Address Offset: 06h–07h                      Attribute: R/WC, RO  
 Default Value: 0010h                      Size: 16 bits

Bit	Description
15	<b>Detected Parity Error (DPE)</b> — R/WC. 0 = No parity error detected. 1 = Set when the Gb LAN controller receives a command or data from the backbone with a parity error. This is set even if PCIMD.PER (D25:F0, bit 6) is not set.
14	<b>Signaled System Error (SSE)</b> — R/WC. 0 = No system error signaled. 1 = Set when the Gb LAN controller signals a system error to the internal SERR# logic.
13	<b>Received Master Abort (RMA)</b> — R/WC. 0 = Root port has not received a completion with unsupported request status from the backbone. 1 = Set when the GbE LAN controller receives a completion with unsupported request status from the backbone.
12	<b>Received Target Abort (RTA)</b> — R/WC. 0 = Root port has not received a completion with completer abort from the backbone. 1 = Set when the Gb LAN controller receives a completion with completer abort from the backbone.
11	<b>Signaled Target Abort (STA)</b> — R/WC. 0 = No target abort received. 1 = Set whenever the Gb LAN controller forwards a target abort received from the downstream device onto the backbone.
10:9	DEVSEL# Timing Status (DEV_STS) — RO. Hardwired to '0'.
8	<b>Master Data Parity Error Detected (DPED)</b> — R/WC. 0 = No data parity error received. 1 = Set when the Gb LAN Controller receives a completion with a data parity error on the backbone and PCIMD.PER (D25:F0, bit 6) is set.
7	Fast Back to Back Capable (FB2BC) — RO. Hardwired to '0'.
6	Reserved
5	66 MHz Capable — RO. Hardwired to 0.
4	Capabilities List — RO. Hardwired to 1. Indicates the presence of a capabilities list.
3	<b>Interrupt Status</b> — RO. Indicates status of Hot-Plug and power management interrupts on the root port that result in INTx# message generation. 0 = Interrupt is de-asserted. 1 = Interrupt is asserted. This bit is not set if MSI is enabled. If MSI is not enabled, this bit is set regardless of the state of PCICMD.Interrupt Disable bit (D25:F0:04h:bit 10).
2:0	Reserved

### 12.1.5 RID—Revision Identification Register (Gigabit LAN—D25:F0)

Offset Address: 08h                      Attribute: RO  
 Default Value: See bit description                      Size: 8 bits

Bit	Description
7:0	<b>Revision ID</b> — RO. Refer to the <i>Intel® C600 Series Chipset and Intel® X79 Express Chipset Specification Update</i> for the value of the Revision ID Register





### 12.1.10 MBARA—Memory Base Address Register A (Gigabit LAN—D25:F0)

Address Offset: 10h–13h                      Attribute: R/W, RO  
Default Value: 00000000h                      Size: 32 bits

The internal CSR registers and memories are accessed as direct memory mapped offsets from the base address register. SW may only access whole DWord at a time.

Bit	Description
31:17	<b>Base Address (BA) — R/W.</b> Software programs this field with the base address of this region.
16:4	<b>Memory Size (MSIZE) — R/W.</b> Memory size is 128 KB.
3	<b>Prefetchable Memory (PM) — RO.</b> The GbE LAN controller does not implement prefetchable memory.
2:1	<b>Memory Type (MT) — RO.</b> Set to 00b indicating a 32 bit BAR.
0	<b>Memory / IO Space (MIOS) — RO.</b> Set to 0 indicating a Memory Space BAR.

### 12.1.11 MBARB—Memory Base Address Register B (Gigabit LAN—D25:F0)

Address Offset: 14h–17h                      Attribute: R/W, RO  
Default Value: 00000000h                      Size: 32 bits

The internal registers that are used to access the LAN Space in the External FLASH device. Access to these registers are direct memory mapped offsets from the base address register. Software may only access a DWord at a time.

Bit	Description
31:12	<b>Base Address (BA) — R/W.</b> Software programs this field with the base address of this region.
11:4	<b>Memory Size (MSIZE) — R/W.</b> Memory size is 4 KB.
3	<b>Prefetchable Memory (PM) — RO.</b> The Gb LAN controller does not implement prefetchable memory.
2:1	<b>Memory Type (MT) — RO.</b> Set to 00b indicating a 32 bit BAR.
0	<b>Memory / IO Space (MIOS) — RO.</b> Set to 0 indicating a Memory Space BAR.











### 12.1.23 CLIST 2—Capabilities List Register 2 (Gigabit LAN—D25:F0)

Address Offset: D0h–D1h                      Attribute:                      R/WO, RO  
 Default Value: E005h                      Size:                      16 bits  
 Function Level Reset: No (Bits 15:8 only)

Bit	Description
15:8	<b>Next Capability (NEXT)</b> — R/WO. Value of E0h points to the Function Level Reset capability structure. These bits are not reset by Function Level Reset.
7:0	<b>Capability ID (CID)</b> — RO. Indicates the linked list item is a Message Signaled Interrupt Register.

### 12.1.24 MCTL—Message Control Register (Gigabit LAN—D25:F0)

Address Offset: D2h–D3h                      Attribute:                      R/W, RO  
 Default Value: 0080h                      Size:                      16 bits

Bit	Description
15:8	Reserved
7	<b>64-bit Capable (CID)</b> — RO. Set to 1 to indicate that the GbE LAN Controller is capable of generating 64-bit message addresses.
6:4	<b>Multiple Message Enable (MME)</b> — RO. Returns 000b to indicate that the GbE LAN controller only supports a single message.
3:1	<b>Multiple Message Capable (MMC)</b> — RO. The GbE LAN controller does not support multiple messages.
0	<b>MSI Enable (MSIE)</b> — R/W. 0 = MSI generation is disabled. 1 = The Gb LAN controller will generate MSI for interrupt assertion instead of INTx signaling.

### 12.1.25 MADDL—Message Address Low Register (Gigabit LAN—D25:F0)

Address Offset: D4h–D7h                      Attribute:                      R/W  
 Default Value: See bit description                      Size:                      32 bits

Bit	Description
31:0	<b>Message Address Low (MADDL)</b> — R/W. Written by the system to indicate the lower 32 bits of the address to use for the MSI memory write transaction. The lower two bits will always return 0 regardless of the write operation.

### 12.1.26 MADDH—Message Address High Register (Gigabit LAN—D25:F0)

Address Offset: D8h–DBh                      Attribute:                      R/W  
 Default Value: See bit description                      Size:                      32 bits

Bit	Description
31:0	<b>Message Address High (MADDH)</b> — R/W. Written by the system to indicate the upper 32 bits of the address to use for the MSI memory write transaction.



### 12.1.27 MDAT—Message Data Register (Gigabit LAN—D25:F0)

Address Offset: DCh–DDh                      Attribute: R/W  
 Default Value: See bit description        Size: 16 bits

Bit	Description
31:0	<b>Message Data (MDAT)</b> — R/W. Written by the system to indicate the lower 16 bits of the data written in the MSI memory write DWORD transaction. The upper 16 bits of the transaction are written as 0000h.

### 12.1.28 FLRCAP—Function Level Reset Capability (Gigabit LAN—D25:F0)

Address Offset: E0h–E1h                      Attribute: RO  
 Default Value: 0009h                        Size: 16 bits

Bit	Description
15:8	<b>Next Pointer</b> — RO. This field provides an offset to the next capability item in the capability list. The value of 00h indicates the last item in the list.
7:0	<b>Capability ID</b> — RO. The value of this field depends on the FLRCSSEL bit. 13h = If FLRCSSEL = 0 09h = If FLRCSSEL = 1, indicating vendor specific capability.

### 12.1.29 FLRCLV—Function Level Reset Capability Length and Version (Gigabit LAN—D25:F0)

Address Offset: E2h–E3h                      Attribute: R/WO, RO  
 Default Value: See Description.            Size: 16 bits  
 Function Level Reset: No (Bits 9:8 Only When FLRCSSEL = 0)

When FLRCSSEL = 0, this register is defined as follows:

Bit	Description
15:10	Reserved.
9	<b>Function Level Reset Capability</b> — R/WO. 1 = Support for Function Level Reset. This bit is not reset by Function Level Reset.
8	<b>TXP Capability</b> — R/WO. 1 = Indicates support for the Transactions Pending (TXP) bit. TXP must be supported if FLR is supported.
7:0	<b>Capability Length</b> — RO. The value of this field indicates the number of bytes of the vendor specific capability as require by the PCI spec. It has the value of 06h for the Function Level Reset capability.

When FLRCSSEL = 1, this register is defined as follows:

Bit	Description
15:12	<b>Vendor Specific Capability ID</b> — RO. A value of 2h in this field identifies this capability as Function Level Reset.
11:8	<b>Capability Version</b> — RO. The value of this field indicates the version of the Function Level Reset Capability. Default is 0h.
7:0	<b>Capability Length</b> — RO. The value of this field indicates the number of bytes of the vendor specific capability as require by the PCI spec. It has the value of 06h for the Function Level Reset capability.





Bit	Description
31:25	Reserved
24	<b>PHY Power Down (PHYPDN)</b> — R/W. When cleared (0b), the PHY power down setting is controlled by the internal logic of PCH.
23:0	Reserved

### 12.2.2 GBECRS2—Gigabit Ethernet Capabilities and Status Register 2

Address Offset: MBARA + 18h                      Attribute: R/W/SN  
 Default Value: 01501000h                      Size: 32 bit

Bit	Description
31:21	Reserved
20	<b>PHY Power Down Enable (PHYPDEN)</b> — R/W/SN. When set, this bit enables the PHY to enter a low-power state when the LAN controller is at the DMoff/D3 or with no WOL.
19:0	Reserved

### 12.2.3 GBECRS3—Gigabit Ethernet Capabilities and Status Register 3

Address Offset: MBARA + 20h                      Attribute: R/W/V  
 Default Value: 1000XXXXh                      Size: 32 bit

Bit	Description
31:29	Reserved
28	<b>Ready Bit (RB)</b> — R/W/V. Set to 1 by the Gigabit Ethernet Controller at the end of the MDI transaction. This bit should be reset to 0 by software at the same time the command is written.
27:26	<b>MDI Type</b> — R/W/V. 01 = MDI Write 10 = MDI Read All other values are reserved.
25:21	LAN Connected Device Address (PHYADD) — R/W/V.
20:16	LAN Connected Device Register Address (PHYREGADD) — R/W/V.
15:0	<b>DATA</b> — R/W/V.

### 12.2.4 GBECRS4—Gigabit Ethernet Capabilities and Status Register 4

Address Offset: MBARA + 2Ch                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bit



Bit	Description
31	<b>WOL Indication Valid (WIV)</b> — R/W. Set to 1 by BIOS to indicate that the WOL indication setting in bit 30 of this register is valid.
30	<b>WOL Enable Setting by BIOS (WESB)</b> — R/W. 1 = WOL Enabled in BIOS. 0 = WOL Disabled in BIOS.
29:0	Reserved

### 12.2.5 GBECRS5—Gigabit Ethernet Capabilities and Status Register 5

Address Offset: MBARA + F00h      Attribute: R/W/V  
 Default Value: 00010008h      Size: 32 bit

Bit	Description
31:6	Reserved
5	<b>SW Semaphore FLAG (SWFLAG)</b> — R/W/V. This bit is set by the device driver to gain access permission to shared CSR registers with the firmware and hardware.
4:0	Reserved

### 12.2.6 GBECRS6—Gigabit Ethernet Capabilities and Status Register 6

Address Offset: MBARA + F10h      Attribute: R/W/SN  
 Default Value: 0004000Ch      Size: 32 bit

Bit	Description
31:7	Reserved
6	<b>Global GbE Disable (GGD)</b> — R/W/SN. Prevents the PHY from autonegotiating 1000Mb/s link in all power states.
5:4	Reserved
3	<b>GbE Disable at non D0a</b> — R/W/SN. Prevents the PHY from autonegotiating 1000Mb/s link in all power states except D0a. This bit must be set since GbE is not supported in Sx states.
2	<b>LPLU in non D0a (LPLUND)</b> — R/W/SN. Enables the PHY to negotiate for the slowest possible link in all power states except D0a.
1	<b>LPLU in D0a (LPLUD)</b> — R/W/SN. Enables the PHY to negotiate for the slowest possible link in all power states. This bit overrides bit 2.
0	Reserved

### 12.2.7 GBECRS7—Gigabit Ethernet Capabilities and Status Register 7

Address Offset: MBARA + 5400h      Attribute: R/W  
 Default Value: XXXXXXXXh      Size: 32 bit

Bit	Description
31:0	<b>Receive Address Low (RAL)</b> — R/W. The lower 32 bits of the 48 bit Ethernet Address.



### 12.2.8 GBECRSR8—Gigabit Ethernet Capabilities and Status Register 8

Address Offset: MBARA + 5404h      Attribute: R/W  
Default Value: XXXXXXXXh      Size: 32 bit

Bit	Description
31	<b>Address Valid</b> — R/W.
30:16	Reserved
15:0	<b>Receive Address High (RAH)</b> — R/W. The lower 16 bits of the 48 bit Ethernet Address.

### 12.2.9 GBECRSR9—Gigabit Ethernet Capabilities and Status Register 9

Address Offset: MBARA + 5800h      Attribute: R/W/SN  
Default Value: 00000008h      Size: 32 bit

Bit	Description
31:1	Reserved
0	<b>Advanced Power Management Enable (APME)</b> — R/W/SN. 1 = APM Wakeup is enabled 0 = APM Wakeup is disabled

## §



# 13 LPC Interface Bridge Registers (D31:F0)

The LPC bridge function of the PCH resides in PCI Device 31:Function 0. This function contains many other functional units, such as DMA and Interrupt controllers, Timers, Power Management, System Management, GPIO, RTC, and LPC Configuration Registers.

Registers and functions associated with other functional units are described in their respective sections.

## 13.1 PCI Configuration Registers (LPC I/F—D31:F0)

**Note:** Address locations that are not shown should be treated as Reserved.

**Table 13-1. LPC Interface PCI Register Address Map (LPC I/F—D31:F0) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Type
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0007h	R/W, RO
06h–07h	PCISTS	PCI Status	0210h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	00h	RO
0Ah	SCC	Sub Class Code	01h	RO
0Bh	BCC	Base Class Code	06h	RO
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	80h	RO
2Ch–2Fh	SS	Sub System Identifiers	00000000h	R/WO
34h	CAPP	Capability List Pointer	E0h	RO
40h–43h	PMBASE	ACPI Base Address	00000001h	R/W, RO
44h	ACPI_CNTL	ACPI Control	00h	R/W
48h–4Bh	GPIOBASE	GPIO Base Address	00000001h	R/W, RO
4C	GC	GPIO Control	00h	R/W
60h–63h	PIRQ[n]_ROUT	PIRQ[A–D] Routing Control	80808080h	R/W
64h	SIRQ_CNTL	Serial IRQ Control	10h	R/W, RO
68h–6Bh	PIRQ[n]_ROUT	PIRQ[E–H] Routing Control	80808080h	R/W
6Ch–6Dh	LPC_IBDF	IOxAPIC Bus: Device: Function	00F8h	R/W
70h–7F	LPC_HnBDF	HPET Configuration	00F8h	R/W
80h	LPC_I/O_DEC	I/O Decode Ranges	0000h	R/W
82h–83h	LPC_EN	LPC I/F Enables	0000h	R/W
84h–87h	GEN1_DEC	LPC I/F Generic Decode Range 1	00000000h	R/W
88h–8Bh	GEN2_DEC	LPC I/F Generic Decode Range 2	00000000h	R/W
8Ch–8Eh	GEN3_DEC	LPC I/F Generic Decode Range 3	00000000h	R/W



**Table 13-1. LPC Interface PCI Register Address Map (LPC I/F—D31:F0) (Sheet 2 of 2)**

Offset	Mnemonic	Register Name	Default	Type
90h–93h	GEN4_DEC	LPC I/F Generic Decode Range 4	00000000h	R/W
94h–97h	ULKMC	USB Legacy Keyboard / Mouse Control		
98h–9Bh	LGMR	LPC Generic Memory Range	00000000h	R/W
A0h–CFh		Power Management (See Section 13.8.1)		
D0h–D3h	BIOS_SEL1	BIOS Select 1	00112233h	R/W, RO
D4h–D5h	BIOS_SEL2	BIOS Select 2	4567h	R/W
D8h–D9h	BIOS_DEC_EN1	BIOS Decode Enable 1	FFCFh	R/W, RO
DCh	BIOS_CNTL	BIOS Control	20h	R/WLO, R/W, RO
E0h–E1h	FDCAP	Feature Detection Capability ID	0009h	RO
E2h	FDLEN	Feature Detection Capability Length	0Ch	RO
E3h	FDVER	Feature Detection Version	10h	RO
E4h–EBh	FDVCT	Feature Vector	See Description	RO
F0h–F3h	RCBA	Root Complex Base Address	00000000h	R/W

### 13.1.1 VID—Vendor Identification Register (LPC I/F—D31:F0)

Offset Address: 00h–01h                      Attribute: RO  
 Default Value: 8086h                        Size: 16-bit  
 Lockable: No                                    Power Well: Core

Bit	Description
15:0	<b>Vendor ID</b> — RO. This is a 16-bit value assigned to Intel. Intel VID = 8086h

### 13.1.2 DID—Device Identification Register (LPC I/F—D31:F0)

Offset Address: 02h–03h                      Attribute: RO  
 Default Value: See bit description        Size: 16-bit  
 Lockable: No                                    Power Well: Core

Bit	Description
15:0	<b>Device ID</b> — RO. This is a 16-bit value assigned to the PCH LPC bridge. Refer to the <i>Intel® C600 Series Chipset and Intel® X79 Express Chipset Specification Update</i> for the value of the Device ID Register.









### 13.1.13 PMBASE—ACPI Base Address Register (LPC I/F—D31:F0)

Offset Address:	40h–43h	Attribute:	R/W, RO
Default Value:	00000001h	Size:	32 bit
Lockable:	No	Usage:	ACPI, Legacy
		Power Well:	Core

Sets base address for ACPI I/O registers, GPIO registers and TCO I/O registers. These registers can be mapped anywhere in the 64-K I/O space on 128-byte boundaries.

Bit	Description
31:16	Reserved
15:7	<b>Base Address</b> — R/W. This field provides 128 bytes of I/O space for ACPI, GPIO, and TCO logic. This is placed on a 128-byte boundary.
6:1	Reserved
0	Resource Type Indicator (RTE) — RO. Hardwired to 1 to indicate I/O space.

### 13.1.14 ACPI\_CNTL—ACPI Control Register (LPC I/F — D31:F0)

Offset Address:	44h	Attribute:	R/W
Default Value:	00h	Size:	8 bit
Lockable:	No	Usage:	ACPI, Legacy
		Power Well:	Core

Bit	Description																
7	<b>ACPI Enable (ACPI_EN)</b> — R/W. 0 = Disable. 1 = Decode of the I/O range pointed to by the ACPI base register is enabled, and the ACPI power management function is enabled. Note that the APM power management ranges (B2/B3h) are always enabled and are not affected by this bit.																
6:3	Reserved																
2:0	<b>SCI IRQ Select (SCI_IRQ_SEL)</b> — R/W. Specifies on which IRQ the SCI will internally appear. If not using the APIC, the SCI must be routed to IRQ9–11, and that interrupt is not sharable with the SERIRQ stream, but is shareable with other PCI interrupts. If using the APIC, the SCI can also be mapped to IRQ20–23, and can be shared with other interrupts.  <table border="0" style="margin-left: 40px;"> <thead> <tr> <th style="text-align: left;">Bits</th> <th style="text-align: left;">SCI Map</th> </tr> </thead> <tbody> <tr> <td>000b</td> <td>IRQ9</td> </tr> <tr> <td>001b</td> <td>IRQ10</td> </tr> <tr> <td>010b</td> <td>IRQ11</td> </tr> <tr> <td>011b</td> <td>Reserved</td> </tr> <tr> <td>100b</td> <td>IRQ20 (Only available if APIC enabled)</td> </tr> <tr> <td>101b</td> <td>IRQ21 (Only available if APIC enabled)</td> </tr> <tr> <td>110b</td> <td>IRQ22 (Only available if APIC enabled)</td> </tr> </tbody> </table> When the interrupt is mapped to APIC interrupts 9, 10 or 11, the APIC should be programmed for active-high reception. When the interrupt is mapped to APIC interrupts 20 through 23, the APIC should be programmed for active-low reception.	Bits	SCI Map	000b	IRQ9	001b	IRQ10	010b	IRQ11	011b	Reserved	100b	IRQ20 (Only available if APIC enabled)	101b	IRQ21 (Only available if APIC enabled)	110b	IRQ22 (Only available if APIC enabled)
Bits	SCI Map																
000b	IRQ9																
001b	IRQ10																
010b	IRQ11																
011b	Reserved																
100b	IRQ20 (Only available if APIC enabled)																
101b	IRQ21 (Only available if APIC enabled)																
110b	IRQ22 (Only available if APIC enabled)																



### 13.1.15 GPIOBASE—GPIO Base Address Register (LPC I/F — D31:F0)

Offset Address: 48h–4Bh                      Attribute: R/W, RO  
 Default Value: 00000001h                  Size: 32 bit

Bit	Description
31:16	Reserved. Always 0.
15:7	<b>Base Address (BA)</b> — R/W. Provides the 128 bytes of I/O space for GPIO.
6:1	Reserved. Always 0.
0	RO. Hardwired to 1 to indicate I/O space.

### 13.1.16 GC—GPIO Control Register (LPC I/F — D31:F0)

Offset Address: 4Ch                              Attribute: R/W  
 Default Value: 00h                              Size: 8 bit

Bit	Description
7:5	Reserved.
4	<b>GPIO Enable (EN)</b> — R/W. This bit enables/disables decode of the I/O range pointed to by the GPIO Base Address register (D31:F0:48h) and enables the GPIO function. 0 = Disable. 1 = Enable.
3:1	Reserved.
0	<b>GPIO Lockdown Enable (GLE)</b> — R/W. This bit enables lockdown of the following GPIO registers: <ul style="list-style-type: none"> <li>• Offset 00h: GPIO_USE_SEL</li> <li>• Offset 04h: GP_IO_SEL</li> <li>• Offset 0Ch: GP_LVL</li> <li>• Offset 30h: GPIO_USE_SEL2</li> <li>• Offset 34h: GP_IO_SEL2</li> <li>• Offset 38h: GP_LVL2</li> <li>• Offset 40h: GPIO_USE_SEL3</li> <li>• Offset 44h: GP_IO_SEL3</li> <li>• Offset 48h: GP_LVL3</li> <li>• Offset 60h: GP_RST_SEL</li> </ul> 0 = Disable. 1 = Enable.  When this bit is written from a 1-to-0, an SMI# is generated, if enabled. This ensures that only SMM code can change the above GPIO registers after they are locked down.



### 13.1.17 PIRQ[n]\_ROUT—PIRQ[A,B,C,D] Routing Control Register (LPC I/F—D31:F0)

Offset Address: PIRQA – 60h, PIRQB – 61h, Attribute: R/W  
 PIRQC – 62h, PIRQD – 63h  
 Default Value: 80h Size: 8 bit  
 Lockable: No Power Well: Core

Bit	Description																																				
7	<p><b>Interrupt Routing Enable (IRQEN)</b> — R/W.            0 = The corresponding PIRQ is routed to one of the ISA-compatible interrupts specified in bits[3:0].            1 = The PIRQ is not routed to the 8259.</p> <p><b>Note:</b> BIOS must program this bit to 0 during POST for any of the PIRQs that are being used. The value of this bit may subsequently be changed by the OS when setting up for I/O APIC interrupt delivery mode.</p>																																				
6:4	Reserved																																				
3:0	<p><b>IRQ Routing</b> — R/W. (ISA compatible.)</p> <table border="1"> <thead> <tr> <th>Value</th> <th>IRQ</th> <th>Value</th> <th>IRQ</th> </tr> </thead> <tbody> <tr> <td>0000b</td> <td>Reserved</td> <td>1000b</td> <td>Reserved</td> </tr> <tr> <td>0001b</td> <td>Reserved</td> <td>1001b</td> <td>IRQ9</td> </tr> <tr> <td>0010b</td> <td>Reserved</td> <td>1010b</td> <td>IRQ10</td> </tr> <tr> <td>0011b</td> <td>IRQ3</td> <td>1011b</td> <td>IRQ11</td> </tr> <tr> <td>0100b</td> <td>IRQ4</td> <td>1100b</td> <td>IRQ12</td> </tr> <tr> <td>0101b</td> <td>IRQ5</td> <td>1101b</td> <td>Reserved</td> </tr> <tr> <td>0110b</td> <td>IRQ6</td> <td>1110b</td> <td>IRQ14</td> </tr> <tr> <td>0111b</td> <td>IRQ7</td> <td>1111b</td> <td>IRQ15</td> </tr> </tbody> </table>	Value	IRQ	Value	IRQ	0000b	Reserved	1000b	Reserved	0001b	Reserved	1001b	IRQ9	0010b	Reserved	1010b	IRQ10	0011b	IRQ3	1011b	IRQ11	0100b	IRQ4	1100b	IRQ12	0101b	IRQ5	1101b	Reserved	0110b	IRQ6	1110b	IRQ14	0111b	IRQ7	1111b	IRQ15
Value	IRQ	Value	IRQ																																		
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0010b	Reserved	1010b	IRQ10																																		
0011b	IRQ3	1011b	IRQ11																																		
0100b	IRQ4	1100b	IRQ12																																		
0101b	IRQ5	1101b	Reserved																																		
0110b	IRQ6	1110b	IRQ14																																		
0111b	IRQ7	1111b	IRQ15																																		





### 13.1.19 PIRQ[n]\_ROUT—PIRQ[E,F,G,H] Routing Control Register (LPC I/F—D31:F0)

Offset Address: PIRQE – 68h, PIRQF – 69h, Attribute: R/W  
 PIRQG – 6Ah, PIRQH – 6Bh  
 Default Value: 80h Size: 8 bit  
 Lockable: No Power Well: Core

Bit	Description																																				
7	<p><b>Interrupt Routing Enable (IRQEN)</b> — R/W.            0 = The corresponding PIRQ is routed to one of the ISA-compatible interrupts specified in bits[3:0].            1 = The PIRQ is not routed to the 8259.</p> <p><b>Note:</b> BIOS must program this bit to 0 during POST for any of the PIRQs that are being used. The value of this bit may subsequently be changed by the OS when setting up for I/O APIC interrupt delivery mode.</p>																																				
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Value	IRQ	Value	IRQ																																		
0000b	Reserved	1000b	Reserved																																		
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0101b	IRQ5	1101b	Reserved																																		
0110b	IRQ6	1110b	IRQ14																																		
0111b	IRQ7	1111b	IRQ15																																		

### 13.1.20 LPC\_IBDF—IOxAPIC Bus:Device:Function (LPC I/F—D31:F0)

Offset Address: 6Ch-6Dh Attribute: R/W  
 Default Value: 00F8h Size: 16 bit

Bit	Description								
15:0	<p><b>IOxAPIC Bus:Device:Function (IBDF)</b>— R/W. this field specifies the bus:device:function that PCH's IOxAPIC will be using for the following:</p> <ul style="list-style-type: none"> <li>As the Requester ID when initiating Interrupt Messages to the processor.</li> <li>As the Completer ID when responding to the reads targeting the IOxAPIC's Memory-Mapped I/O registers.</li> </ul> <p>The 16-bit field comprises the following:</p> <table border="1"> <thead> <tr> <th>Bits</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>15:8</td> <td>Bus Number</td> </tr> <tr> <td>7:3</td> <td>Device Number</td> </tr> <tr> <td>2:0</td> <td>Function Number</td> </tr> </tbody> </table> <p>This field defaults to Bus 0: Device 31: Function 0 after reset. BIOS can program this field to provide a unique bus:device:function number for the internal IOxAPIC.</p>	Bits	Description	15:8	Bus Number	7:3	Device Number	2:0	Function Number
Bits	Description								
15:8	Bus Number								
7:3	Device Number								
2:0	Function Number								







### 13.1.23 LPC\_EN—LPC I/F Enables Register (LPC I/F—D31:F0)

Offset Address: 82h – 83h  
 Default Value: 0000h

Attribute: R/W  
 Size: 16 bit  
 Power Well: Core

Bit	Description
15:14	Reserved
13	<b>CNF2_LPC_EN</b> — R/W. Microcontroller Enable # 2. 0 = Disable. 1 = Enables the decoding of the I/O locations 4Eh and 4Fh to the LPC interface. This range is used for a microcontroller.
12	<b>CNF1_LPC_EN</b> — R/W. Super I/O Enable. 0 = Disable. 1 = Enables the decoding of the I/O locations 2Eh and 2Fh to the LPC interface. This range is used for Super I/O devices.
11	<b>MC_LPC_EN</b> — R/W. Microcontroller Enable # 1. 0 = Disable. 1 = Enables the decoding of the I/O locations 62h and 66h to the LPC interface. This range is used for a microcontroller.
10	<b>KBC_LPC_EN</b> — R/W. Keyboard Enable. 0 = Disable. 1 = Enables the decoding of the I/O locations 60h and 64h to the LPC interface. This range is used for a microcontroller.
9	<b>GAMEH_LPC_EN</b> — R/W. High Gameport Enable 0 = Disable. 1 = Enables the decoding of the I/O locations 208h to 20Fh to the LPC interface. This range is used for a gameport.
8	<b>GAMEL_LPC_EN</b> — R/W. Low Gameport Enable 0 = Disable. 1 = Enables the decoding of the I/O locations 200h to 207h to the LPC interface. This range is used for a gameport.
7:4	Reserved
3	<b>FDD_LPC_EN</b> — R/W. Floppy Drive Enable 0 = Disable. 1 = Enables the decoding of the FDD range to the LPC interface. This range is selected in the LPC_FDD/LPT Decode Range Register (D31:F0:80h, bit 12).
2	<b>LPT_LPC_EN</b> — R/W. Parallel Port Enable 0 = Disable. 1 = Enables the decoding of the LPT range to the LPC interface. This range is selected in the LPC_FDD/LPT Decode Range Register (D31:F0:80h, bit 9:8).
1	<b>COMB_LPC_EN</b> — R/W. Com Port B Enable 0 = Disable. 1 = Enables the decoding of the COMB range to the LPC interface. This range is selected in the LPC_COM Decode Range Register (D31:F0:80h, bits 6:4).
0	<b>COMA_LPC_EN</b> — R/W. Com Port A Enable 0 = Disable. 1 = Enables the decoding of the COMA range to the LPC interface. This range is selected in the LPC_COM Decode Range Register (D31:F0:80h, bits 3:2).



### 13.1.24 GEN1\_DEC—LPC I/F Generic Decode Range 1 Register (LPC I/F—D31:F0)

Offset Address: 84h – 87h  
Default Value: 00000000h

Attribute: R/W  
Size: 32 bit  
Power Well: Core

Bit	Description
31:24	Reserved
23:18	<b>Generic I/O Decode Range Address[7:2] Mask</b> — R/W. A 1 in any bit position indicates that any value in the corresponding address bit in a received cycle will be treated as a match. The corresponding bit in the Address field, below, is ignored. The mask is only provided for the lower 6 bits of the DWord address, allowing for decoding blocks up to 256 bytes in size.
17:16	Reserved
15:2	<b>Generic I/O Decode Range 1 Base Address (GEN1_BASE)</b> — R/W. <b>Note:</b> The PCH Does not provide decode down to the word or byte level
1	Reserved
0	<b>Generic Decode Range 1 Enable (GEN1_EN)</b> — R/W. 0 = Disable. 1 = Enable the GEN1 I/O range to be forwarded to the LPC I/F

### 13.1.25 GEN2\_DEC—LPC I/F Generic Decode Range 2 Register (LPC I/F—D31:F0)

Offset Address: 88h – 8Bh  
Default Value: 00000000h

Attribute: R/W  
Size: 32 bit  
Power Well: Core

Bit	Description
31:24	Reserved
23:18	<b>Generic I/O Decode Range Address[7:2] Mask</b> — R/W. A 1 in any bit position indicates that any value in the corresponding address bit in a received cycle will be treated as a match. The corresponding bit in the Address field, below, is ignored. The mask is only provided for the lower 6 bits of the DWord address, allowing for decoding blocks up to 256 bytes in size.
17:16	Reserved
15:2	<b>Generic I/O Decode Range 2 Base Address (GEN1_BASE)</b> — R/W. <b>Note:</b> The PCH does not provide decode down to the word or byte level
1	Reserved
0	<b>Generic Decode Range 2 Enable (GEN2_EN)</b> — R/W. 0 = Disable. 1 = Enable the GEN2 I/O range to be forwarded to the LPC I/F











Bit	Description
15	<b>BIOS_F8_EN</b> — RO. This bit enables decoding two 512-KB BIOS memory ranges, and one 128-KB memory range. 0 = Disable 1 = Enable the following ranges for the BIOS: FFF80000h – FFFFFFFFh FFB80000h – FFBFFFFFFh
14	<b>BIOS_F0_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFF00000h – FFF7FFFFh FFB00000h – FFB7FFFFh
13	<b>BIOS_E8_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFE80000h – FFEFFFFh FFA80000h – FFAFFFFFFh
12	<b>BIOS_E0_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFE00000h – FFE7FFFFh FFA00000h – FFA7FFFFh
11	<b>BIOS_D8_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFD80000h – FFDFFFFFFh FF980000h – FF9FFFFFFh
10	<b>BIOS_D0_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFD00000h – FFD7FFFFh FF900000h – FF97FFFFh
9	<b>BIOS_C8_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFC80000h – FFCFFFFFFh FF880000h – FF8FFFFFFh
8	<b>BIOS_C0_EN</b> — R/W. This bit enables decoding two 512-KB BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FFC00000h – FFC7FFFFh FF800000h – FF87FFFFh
7	<b>BIOS_Legacy_F_EN</b> — R/W. This enables the decoding of the legacy 64 KB range at F0000h – FFFFFh. 0 = Disable. 1 = Enable the following legacy ranges for the BIOS: F0000h – FFFFFh <b>Note:</b> The decode for the BIOS legacy F segment is enabled only by this bit and is not affected by the GEN_PMCON_1.iA64_EN bit.
6	<b>BIOS_Legacy_E_EN</b> — R/W. This enables the decoding of the legacy 64 KB range at E0000h – EFFFFh. 0 = Disable. 1 = Enable the following legacy ranges for the BIOS: E0000h – EFFFFh <b>Note:</b> The decode for the BIOS legacy E segment is enabled only by this bit and is not affected by the GEN_PMCON_1.iA64_EN bit.
5:4	Reserved
3	<b>BIOS_70_EN</b> — R/W. Enables decoding two 1-M BIOS memory ranges. 0 = Disable. 1 = Enable the following ranges for the BIOS: FF700000h – FF7FFFFFFh FF300000h – FF3FFFFFFh







### 13.1.37 FVECIDX—Feature Vector Index (LPC I/F—D31:F0)

Offset Address: E4h-E7h                      Attribute: R/W  
 Default Value: 00000000h                  Size: 32 bit  
    Power Well: Core

Bit	Description
31:6	Reserved
5:2	<b>Index (IDX)</b> — R/W. 4-bit index pointer into the 64-byte Feature Vector space. Data is read from the FVECD register. This points to a DWord register.
1:0	Reserved

### 13.1.38 FVECD—Feature Vector Data (LPC I/F—D31:F0)

Offset Address: E8h-EBh                      Attribute: RO  
 Default Value: See Description              Size: 32 bit  
    Power Well: Core

Bit	Description
31:0	Data (DATA) — RO. 32-bit data value that is read from the Feature Vector offset pointed to by FVECIDX.

### 13.1.39 Feature Vector Space

#### 13.1.39.1 FVECO—Feature Vector Register 0

FVECIDX.IDX: 0000b                              Attribute: RO  
 Default Value: See Description              Size: 32 bit  
    Power Well: Core

Bit	Description
31:12	Reserved
11:10	USB Port Count Capability — RO 00 = 14 ports 01 = 12 ports 10 = 10 ports 11 = Reserved
9:8	Reserved
7	RAID Capability — RO Disabled Capable
6	SATA Ports 2 and 3 — RO Capable Disabled
5:4	Reserved
3	SATA Port 1 6 Gb/s Capability— RO Capable Disabled







**Table 13-2. DMA Registers (Sheet 2 of 2)**

Port	Alias	Register Name	Default	Type
C0h	C1h	Channel 4 DMA Base & Current Address	Undefined	R/W
C2h	C3h	Channel 4 DMA Base & Current Count	Undefined	R/W
C4h	C5h	Channel 5 DMA Base & Current Address	Undefined	R/W
C6h	C7h	Channel 5 DMA Base & Current Count	Undefined	R/W
C8h	C9h	Channel 6 DMA Base & Current Address	Undefined	R/W
CAh	CBh	Channel 6 DMA Base & Current Count	Undefined	R/W
CCh	CDh	Channel 7 DMA Base & Current Address	Undefined	R/W
CEh	CFh	Channel 7 DMA Base & Current Count	Undefined	R/W
D0h	D1h	Channel 4–7 DMA Command	Undefined	WO
		Channel 4–7 DMA Status	Undefined	RO
D4h	D5h	Channel 4–7 DMA Write Single Mask	000001XXb	WO
D6h	D7h	Channel 4–7 DMA Channel Mode	000000XXb	WO
D8h	D9h	Channel 4–7 DMA Clear Byte Pointer	Undefined	WO
DAh	DBh	Channel 4–7 DMA Master Clear	Undefined	WO
DCh	DDh	Channel 4–7 DMA Clear Mask	Undefined	WO
DEh	DFh	Channel 4–7 DMA Write All Mask	0Fh	R/W

### 13.2.1 DMABASE\_CA—DMA Base and Current Address Registers

I/O Address: Ch. #0 = 00h; Ch. #1 = 02h Attribute: R/W  
 Ch. #2 = 04h; Ch. #3 = 06h Size: 16 bit (per channel),  
 Ch. #5 = C4h Ch. #6 = C8h but accessed in two 8-bit  
 Ch. #7 = CCh; quantities  
 Default Value: Undefined  
 Lockable: No Power Well: Core

Bit	Description
15:0	<p><b>Base and Current Address</b> — R/W. This register determines the address for the transfers to be performed. The address specified points to two separate registers. On writes, the value is stored in the <i>Base Address</i> register and copied to the <i>Current Address</i> register. On reads, the value is returned from the <i>Current Address</i> register.</p> <p>The address increments/decrements in the Current Address register after each transfer, depending on the mode of the transfer. If the channel is in auto-initialize mode, the Current Address register will be reloaded from the Base Address register after a terminal count is generated.</p> <p>For transfers to/from a 16-bit slave (channels 5–7), the address is shifted left one bit location. Bit 15 will be shifted into Bit 16.</p> <p>The register is accessed in 8 bit quantities. The byte is pointed to by the current byte pointer flip/flop. Before accessing an address register, the byte pointer flip/flop should be cleared to ensure that the low byte is accessed first</p>



### 13.2.2 DMABASE\_CC—DMA Base and Current Count Registers

I/O Address: Ch. #0 = 01h; Ch. #1 = 03h Attribute: R/W  
 Ch. #2 = 05h; Ch. #3 = 07h Size: 16-bit (per channel),  
 Ch. #5 = C6h; Ch. #6 = CAh but accessed in two 8-bit  
 Ch. #7 = CEh; quantities  
 Default Value: Undefined  
 Lockable: No Power Well: Core

Bit	Description
15:0	<p><b>Base and Current Count</b> — R/W. This register determines the number of transfers to be performed. The address specified points to two separate registers. On writes, the value is stored in the <i>Base Count</i> register and copied to the <i>Current Count</i> register. On reads, the value is returned from the <i>Current Count</i> register.</p> <p>The actual number of transfers is one more than the number programmed in the Base Count Register (that is, programming a count of 4h results in 5 transfers). The count is decrements in the Current Count register after each transfer. When the value in the register rolls from 0 to FFFFh, a terminal count is generated. If the channel is in auto-initialize mode, the Current Count register will be reloaded from the Base Count register after a terminal count is generated.</p> <p>For transfers to/from an 8-bit slave (channels 0–3), the count register indicates the number of bytes to be transferred. For transfers to/from a 16-bit slave (channels 5–7), the count register indicates the number of words to be transferred.</p> <p>The register is accessed in 8 bit quantities. The byte is pointed to by the current byte pointer flip/flop. Before accessing a count register, the byte pointer flip/flop should be cleared to ensure that the low byte is accessed first.</p>

### 13.2.3 DMAMEM\_LP—DMA Memory Low Page Registers

I/O Address: Ch. #0 = 87h; Ch. #1 = 83h  
 Ch. #2 = 81h; Ch. #3 = 82h  
 Ch. #5 = 8Bh; Ch. #6 = 89h  
 Ch. #7 = 8Ah; Attribute: R/W  
 Default Value: Undefined Size: 8-bit  
 Lockable: No Power Well: Core

Bit	Description
7:0	<p><b>DMA Low Page</b> (ISA Address bits [23:16]) — R/W. This register works in conjunction with the DMA controller's Current Address Register to define the complete 24-bit address for the DMA channel. This register remains static throughout the DMA transfer. Bit 16 of this register is ignored when in 16 bit I/O count by words mode as it is replaced by the bit 15 shifted out from the current address register.</p>

### 13.2.4 DMACMD—DMA Command Register

I/O Address: Ch. #0–3 = 08h;  
 Ch. #4–7 = D0h Attribute: WO  
 Default Value: Undefined Size: 8-bit  
 Lockable: No Power Well: Core

Bit	Description
7:5	Reserved. Must be 0.
4	<p><b>DMA Group Arbitration Priority</b> — WO. Each channel group is individually assigned either fixed or rotating arbitration priority. At part reset, each group is initialized in fixed priority.</p> <p>0 = Fixed priority to the channel group            1 = Rotating priority to the group.</p>



Bit	Description
3	Reserved. Must be 0.
2	<b>DMA Channel Group Enable</b> — WO. Both channel groups are enabled following part reset. 0 = Enable the DMA channel group. 1 = Disable. Disabling channel group 4–7 also disables channel group 0–3, which is cascaded through channel 4.
1:0	Reserved. Must be 0.

### 13.2.5 DMASTA—DMA Status Register

I/O Address: Ch. #0–3 = 08h;  
Ch. #4–7 = D0h      Attribute: RO  
Default Value: Undefined      Size: 8-bit  
Lockable: No      Power Well: Core

Bit	Description
7:4	<b>Channel Request Status</b> — RO. When a valid DMA request is pending for a channel, the corresponding bit is set to 1. When a DMA request is not pending for a particular channel, the corresponding bit is set to 0. The source of the DREQ may be hardware or a software request. Note that channel 4 is the cascade channel, so the request status of channel 4 is a logical OR of the request status for channels 0 through 3. 4 = Channel 0 5 = Channel 1 (5) 6 = Channel 2 (6) 7 = Channel 3 (7)
3:0	<b>Channel Terminal Count Status</b> — RO. When a channel reaches terminal count (TC), its status bit is set to 1. If TC has not been reached, the status bit is set to 0. Channel 4 is programmed for cascade, so the TC bit response for channel 4 is irrelevant: 0 = Channel 0 1 = Channel 1 (5) 2 = Channel 2 (6) 3 = Channel 3 (7)

### 13.2.6 DMA\_WRSMSK—DMA Write Single Mask Register

I/O Address: Ch. #0–3 = 0Ah;  
Ch. #4–7 = D4h      Attribute: WO  
Default Value: 0000 01xx      Size: 8-bit  
Lockable: No      Power Well: Core

Bit	Description
7:3	Reserved. Must be 0.
2	<b>Channel Mask Select</b> — WO. 0 = Enable DREQ for the selected channel. The channel is selected through bits [1:0]. Therefore, only one channel can be masked / unmasked at a time. 1 = Disable DREQ for the selected channel.
1:0	<b>DMA Channel Select</b> — WO. These bits select the DMA Channel Mode Register to program. 00 = Channel 0 (4) 01 = Channel 1 (5) 10 = Channel 2 (6) 11 = Channel 3 (7)



### 13.2.7 DMACH\_MODE—DMA Channel Mode Register

I/O Address:	Ch. #0–3 = 0Bh;	Attribute:	WO
	Ch. #4–7 = D6h	Size:	8-bit
Default Value:	0000 00xx	Power Well:	Core
Lockable:	No		

Bit	Description
7:6	<b>DMA Transfer Mode</b> — WO. Each DMA channel can be programmed in one of four different modes: 00 = Demand mode 01 = Single mode 10 = Reserved 11 = Cascade mode
5	<b>Address Increment/Decrement Select</b> — WO. This bit controls address increment/decrement during DMA transfers. 0 = Address increment. (default after part reset or Master Clear) 1 = Address decrement.
4	<b>Autoinitialize Enable</b> — WO. 0 = Autoinitialize feature is disabled and DMA transfers terminate on a terminal count. A part reset or Master Clear disables autoinitialization. 1 = DMA restores the Base Address and Count registers to the current registers following a terminal count (TC).
3:2	<b>DMA Transfer Type</b> — WO. These bits represent the direction of the DMA transfer. When the channel is programmed for cascade mode, (bits[7:6] = 11) the transfer type is irrelevant. 00 = Verify – No I/O or memory strobes generated 01 = Write – Data transferred from the I/O devices to memory 10 = Read – Data transferred from memory to the I/O device 11 = Invalid
1:0	<b>DMA Channel Select</b> — WO. These bits select the DMA Channel Mode Register that will be written by bits [7:2]. 00 = Channel 0 (4) 01 = Channel 1 (5) 10 = Channel 2 (6) 11 = Channel 3 (7)

### 13.2.8 DMA Clear Byte Pointer Register

I/O Address:	Ch. #0–3 = 0Ch;	Attribute:	WO
	Ch. #4–7 = D8h	Size:	8-bit
Default Value:	xxxx xxxx	Power Well:	Core
Lockable:	No		

Bit	Description
7:0	<b>Clear Byte Pointer</b> — WO. No specific pattern. Command enabled with a write to the I/O port address. Writing to this register initializes the byte pointer flip/flop to a known state. It clears the internal latch used to address the upper or lower byte of the 16-bit Address and Word Count Registers. The latch is also cleared by part reset and by the Master Clear command. This command precedes the first access to a 16-bit DMA controller register. The first access to a 16-bit register will then access the significant byte, and the second access automatically accesses the most significant byte.



### 13.2.9 DMA Master Clear Register

I/O Address: Ch. #0–3 = 0Dh;  
 Ch. #4–7 = DAh                      Attribute:                      WO  
 Default Value: xxxx xxxx                      Size:                      8-bit

Bit	Description
7:0	<b>Master Clear</b> — WO. No specific pattern. Enabled with a write to the port. This has the same effect as the hardware Reset. The Command, Status, Request, and Byte Pointer flip/flop registers are cleared and the Mask Register is set.

### 13.2.10 DMA\_CLMSK—DMA Clear Mask Register

I/O Address: Ch. #0–3 = 0Eh;  
 Ch. #4–7 = DCh                      Attribute:                      WO  
 Default Value: xxxx xxxx                      Size:                      8-bit  
 Lockable: No                      Power Well:                      Core

Bit	Description
7:0	<b>Clear Mask Register</b> — WO. No specific pattern. Command enabled with a write to the port.

### 13.2.11 DMA\_WRMSK—DMA Write All Mask Register

I/O Address: Ch. #0–3 = 0Fh;  
 Ch. #4–7 = DEh                      Attribute:                      R/W  
 Default Value: 0000 1111                      Size:                      8-bit  
 Lockable: No                      Power Well:                      Core

Bit	Description
7:4	Reserved. Must be 0.
3:0	<p><b>Channel Mask Bits</b> — R/W. This register permits all four channels to be simultaneously enabled/disabled instead of enabling/disabling each channel individually, as is the case with the Mask Register – Write Single Mask Bit. In addition, this register has a read path to allow the status of the channel mask bits to be read. A channel's mask bit is automatically set to 1 when the Current Byte/Word Count Register reaches terminal count (unless the channel is in auto-initialization mode). Setting the bit(s) to a 1 disables the corresponding DREQ(s). Setting the bit(s) to a 0 enables the corresponding DREQ(s). Bits [3:0] are set to 1 upon part reset or Master Clear. When read, bits [3:0] indicate the DMA channel [3:0] ([7:4]) mask status.</p> <p>Bit 0 = Channel 0 (4) 1 = Masked, 0 = Not Masked                      Bit 1 = Channel 1 (5) 1 = Masked, 0 = Not Masked                      Bit 2 = Channel 2 (6) 1 = Masked, 0 = Not Masked                      Bit 3 = Channel 3 (7) 1 = Masked, 0 = Not Masked</p> <p><b>Note:</b> Disabling channel 4 also disables channels 0–3 due to the cascade of channels 0 – 3 through channel 4.</p>





There are two special commands that can be issued to the counters through this register, the Read Back Command and the Counter Latch Command. When these commands are chosen, several bits within this register are redefined. These register formats are described below:

### RDBK\_CMD—Read Back Command

The Read Back Command is used to determine the count value, programmed mode, and current states of the OUT pin and Null count flag of the selected counter or counters. Status and/or count may be latched in any or all of the counters by selecting the counter during the register write. The count and status remain latched until read, and further latch commands are ignored until the count is read. Both count and status of the selected counters may be latched simultaneously by setting both bit 5 and bit 4 to 0. If both are latched, the first read operation from that counter returns the latched status. The next one or two reads, depending on whether the counter is programmed for one or two byte counts, returns the latched count. Subsequent reads return an unlatched count.

Bit	Description
7:6	<b>Read Back Command.</b> Must be 11 to select the Read Back Command
5	<b>Latch Count of Selected Counters.</b> 0 = Current count value of the selected counters will be latched 1 = Current count will not be latched
4	<b>Latch Status of Selected Counters.</b> 0 = Status of the selected counters will be latched 1 = Status will not be latched
3	<b>Counter 2 Select.</b> 1 = Counter 2 count and/or status will be latched
2	<b>Counter 1 Select.</b> 1 = Counter 1 count and/or status will be latched
1	<b>Counter 0 Select.</b> 1 = Counter 0 count and/or status will be latched.
0	Reserved. Must be 0.

### LTCH\_CMD—Counter Latch Command

The Counter Latch Command latches the current count value. This command is used to insure that the count read from the counter is accurate. The count value is then read from each counter's count register through the Counter Ports Access Ports Register (40h for counter 0, 41h for counter 1, and 42h for counter 2). The count must be read according to the programmed format, that is, if the counter is programmed for two byte counts, two bytes must be read. The two bytes do not have to be read one right after the other (read, write, or programming operations for other counters may be inserted between the reads). If a counter is latched once and then latched again before the count is read, the second Counter Latch Command is ignored.

Bit	Description
7:6	<b>Counter Selection.</b> These bits select the counter for latching. If "11" is written, then the write is interpreted as a read back command. 00 = Counter 0 01 = Counter 1 10 = Counter 2
5:4	<b>Counter Latch Command.</b> 00 = Selects the Counter Latch Command.
3:0	Reserved. Must be 0.



### 13.3.2 SBYTE\_FMT—Interval Timer Status Byte Format Register

I/O Address: Counter 0 = 40h,  
 Counter 1 = 41h, Attribute: RO  
 Counter 2 = 42h Size: 8 bits per counter  
 Default Value: Bits[6:0] undefined, Bit 7=0

Each counter's status byte can be read following a Read Back Command. If latch status is chosen (bit 4=0, Read Back Command) as a read back option for a given counter, the next read from the counter's Counter Access Ports Register (40h for counter 0, 41h for counter 1, and 42h for counter 2) returns the status byte. The status byte returns the following:

Bit	Description
7	<b>Counter OUT Pin State</b> — RO. 0 = OUT pin of the counter is also a 0 1 = OUT pin of the counter is also a 1
6	<b>Count Register Status</b> — RO. This bit indicates when the last count written to the Count Register (CR) has been loaded into the counting element (CE). The exact time this happens depends on the counter mode, but until the count is loaded into the counting element (CE), the count value will be incorrect. 0 = Count has been transferred from CR to CE and is available for reading. 1 = Null Count. Count has not been transferred from CR to CE and is not yet available for reading.
5:4	<b>Read/Write Selection Status</b> — RO. These reflect the read/write selection made through bits[5:4] of the control register. The binary codes returned during the status read match the codes used to program the counter read/write selection. 00 = Counter Latch Command 01 = Read/Write Least Significant Byte (LSB) 10 = Read/Write Most Significant Byte (MSB) 11 = Read/Write LSB then MSB
3:1	<b>Mode Selection Status</b> — RO. These bits return the counter mode programming. The binary code returned matches the code used to program the counter mode, as listed under the bit function above. 000 = Mode 0 — Out signal on end of count (=0) 001 = Mode 1 — Hardware retriggerable one-shot x10 = Mode 2 — Rate generator (divide by n counter) x11 = Mode 3 — Square wave output 100 = Mode 4 — Software triggered strobe 101 = Mode 5 — Hardware triggered strobe
0	<b>Countdown Type Status</b> — RO. This bit reflects the current countdown type. 0 = Binary countdown 1 = Binary Coded Decimal (BCD) countdown.

### 13.3.3 Counter Access Ports Register

I/O Address: Counter 0 – 40h,  
 Counter 1 – 41h, Attribute: R/W  
 Counter 2 – 42h  
 Default Value: All bits undefined Size: 8 bit

Bit	Description
7:0	<b>Counter Port</b> — R/W. Each counter port address is used to program the 16-bit Count Register. The order of programming, either LSB only, MSB only, or LSB then MSB, is defined with the Interval Counter Control Register at port 43h. The counter port is also used to read the current count from the Count Register, and return the status of the counter programming following a Read Back Command.



## 13.4 8259 Interrupt Controller (PIC) Registers

### 13.4.1 Interrupt Controller I/O MAP

The interrupt controller registers are located at 20h and 21h for the master controller (IRQ 0–7), and at A0h and A1h for the slave controller (IRQ 8–13). These registers have multiple functions, depending upon the data written to them. Table 13-3 shows the different register possibilities for each address.

**Table 13-3. PIC Registers**

Port	Aliases	Register Name	Default Value	Type
20h	24h, 28h, 2Ch, 30h, 34h, 38h, 3Ch	Master PIC ICW1 Init. Cmd Word 1	Undefined	WO
		Master PIC OCW2 Op Ctrl Word 2	001XXXXXb	WO
		Master PIC OCW3 Op Ctrl Word 3	X01XXX10b	WO
21h	25h, 29h, 2Dh, 31h, 35h, 39h, 3Dh	Master PIC ICW2 Init. Cmd Word 2	Undefined	WO
		Master PIC ICW3 Init. Cmd Word 3	Undefined	WO
		Master PIC ICW4 Init. Cmd Word 4	01h	WO
		Master PIC OCW1 Op Ctrl Word 1	00h	R/W
A0h	A4h, A8h, ACh, B0h, B4h, B8h, BCh	Slave PIC ICW1 Init. Cmd Word 1	Undefined	WO
		Slave PIC OCW2 Op Ctrl Word 2	001XXXXXb	WO
		Slave PIC OCW3 Op Ctrl Word 3	X01XXX10b	WO
A1h	A5h, A9h, ADh, B1h, B5h, B9h, BDh	Slave PIC ICW2 Init. Cmd Word 2	Undefined	WO
		Slave PIC ICW3 Init. Cmd Word 3	Undefined	WO
		Slave PIC ICW4 Init. Cmd Word 4	01h	WO
		Slave PIC OCW1 Op Ctrl Word 1	00h	R/W
4D0h	–	Master PIC Edge/Level Triggered	00h	R/W
4D1h	–	Slave PIC Edge/Level Triggered	00h	R/W

**Note:** Refer to note addressing active-low interrupt sources in 8259 Interrupt Controllers section (Chapter 5.9).

### 13.4.2 ICW1—Initialization Command Word 1 Register

Offset Address: Master Controller – 20h      Attribute: WO  
 Slave Controller – A0h      Size: 8 bit /controller  
 Default Value: All bits undefined

A write to Initialization Command Word 1 starts the interrupt controller initialization sequence, during which the following occurs:

1. The Interrupt Mask register is cleared.
2. IRQ7 input is assigned priority 7.
3. The slave mode address is set to 7.
4. Special mask mode is cleared and Status Read is set to IRR.

Once this write occurs, the controller expects writes to ICW2, ICW3, and ICW4 to complete the initialization sequence.



Bit	Description
7:5	<b>ICW/OCW Select</b> — WO. These bits are MCS-85 specific, and not needed. 000 = Should be programmed to “000”
4	<b>ICW/OCW Select</b> — WO. 1 = This bit must be a 1 to select ICW1 and enable the ICW2, ICW3, and ICW4 sequence.
3	<b>Edge/Level Bank Select (LTIM)</b> — WO. Disabled. Replaced by the edge/level triggered control registers (ELCR, D31:F0:4D0h, D31:F0:4D1h).
2	ADI — WO. 0 = Ignored for the PCH. Should be programmed to 0.
1	<b>Single or Cascade (SNGL)</b> — WO. 0 = Must be programmed to a 0 to indicate two controllers operating in cascade mode.
0	<b>ICW4 Write Required (IC4)</b> — WO. 1 = This bit must be programmed to a 1 to indicate that ICW4 needs to be programmed.

### 13.4.3 ICW2—Initialization Command Word 2 Register

Offset Address: Master Controller – 21h      Attribute: WO  
 Slave Controller – A1h                      Size: 8 bit /controller  
 Default Value: All bits undefined

ICW2 is used to initialize the interrupt controller with the five most significant bits of the interrupt vector address. The value programmed for bits[7:3] is used by the processor to define the base address in the interrupt vector table for the interrupt routines associated with each IRQ on the controller. Typical ISA ICW2 values are 08h for the master controller and 70h for the slave controller.

Bit	Description
7:3	<b>Interrupt Vector Base Address</b> — WO. Bits [7:3] define the base address in the interrupt vector table for the interrupt routines associated with each interrupt request level input.
2:0	<b>Interrupt Request Level</b> — WO. When writing ICW2, these bits should all be 0. During an interrupt acknowledge cycle, these bits are programmed by the interrupt controller with the interrupt to be serviced. This is combined with bits [7:3] to form the interrupt vector driven onto the data bus during the second INTA# cycle. The code is a three bit binary code:
	<b>Code                      Master Interrupt                      Slave Interrupt</b>
	000b                      IRQ0                      IRQ8
	001b                      IRQ1                      IRQ9
	010b                      IRQ2                      IRQ10
	011b                      IRQ3                      IRQ11
	100b                      IRQ4                      IRQ12
	101b                      IRQ5                      IRQ13
	110b                      IRQ6                      IRQ14
111b                      IRQ7                      IRQ15	



### 13.4.4 ICW3—Master Controller Initialization Command Word 3 Register

Offset Address: 21h Attribute: WO  
 Default Value: All bits undefined Size: 8 bits

Bit	Description
7:3	0 = These bits must be programmed to 0.
2	<b>Cascaded Interrupt Controller IRQ Connection</b> — WO. This bit indicates that the slave controller is cascaded on IRQ2. When IRQ8#–IRQ15 is asserted, it goes through the slave controller's priority resolver. The slave controller's INTR output onto IRQ2. IRQ2 then goes through the master controller's priority solver. If it wins, the INTR signal is asserted to the processor, and the returning interrupt acknowledge returns the interrupt vector for the slave controller. 1 = This bit must always be programmed to a 1.
1:0	0 = These bits must be programmed to 0.

### 13.4.5 ICW3—Slave Controller Initialization Command Word 3 Register

Offset Address: A1h Attribute: WO  
 Default Value: All bits undefined Size: 8 bits

Bit	Description
7:3	0 = These bits must be programmed to 0.
2:0	<b>Slave Identification Code</b> — WO. These bits are compared against the slave identification code broadcast by the master controller from the trailing edge of the first internal INTA# pulse to the trailing edge of the second internal INTA# pulse. These bits must be programmed to 02h to match the code broadcast by the master controller. When 02h is broadcast by the master controller during the INTA# sequence, the slave controller assumes responsibility for broadcasting the interrupt vector.

### 13.4.6 ICW4—Initialization Command Word 4 Register

Offset Address: Master Controller – 021h Attribute: WO  
 Slave Controller – 0A1h Size: 8 bits  
 Default Value: 01h

Bit	Description
7:5	0 = These bits must be programmed to 0.
4	<b>Special Fully Nested Mode (SFNM)</b> — WO. 0 = Should normally be disabled by writing a 0 to this bit. 1 = Special fully nested mode is programmed.
3	<b>Buffered Mode (BUF)</b> — WO. 0 = Must be programmed to 0 for the PCH. This is non-buffered mode.
2	<b>Master/Slave in Buffered Mode</b> — WO. Not used. 0 = Should always be programmed to 0.
1	<b>Automatic End of Interrupt (AEOI)</b> — WO. 0 = This bit should normally be programmed to 0. This is the normal end of interrupt. 1 = Automatic End of Interrupt (AEOI) mode is programmed.
0	<b>Microprocessor Mode</b> — WO. 1 = Must be programmed to 1 to indicate that the controller is operating in an Intel Architecture-based system.



### 13.4.7 OCW1—Operational Control Word 1 (Interrupt Mask) Register

Offset Address: Master Controller – 021h    Attribute: R/W  
 Slave Controller – 0A1h    Size: 8 bits  
 Default Value: 00h

Bit	Description
7:0	<b>Interrupt Request Mask</b> — R/W. When a 1 is written to any bit in this register, the corresponding IRQ line is masked. When a 0 is written to any bit in this register, the corresponding IRQ mask bit is cleared, and interrupt requests will again be accepted by the controller. Masking IRQ2 on the master controller will also mask the interrupt requests from the slave controller.

### 13.4.8 OCW2—Operational Control Word 2 Register

Offset Address: Master Controller – 020h    Attribute: WO  
 Slave Controller – 0A0h    Size: 8 bits  
 Default Value: Bit[4:0]=undefined, Bit[7:5]=001

Following a part reset or ICW initialization, the controller enters the fully nested mode of operation. Non-specific EOI without rotation is the default. Both rotation mode and specific EOI mode are disabled following initialization.

Bit	Description																				
7:5	<b>Rotate and EOI Codes</b> (R, SL, EOI) — WO. These three bits control the Rotate and End of Interrupt modes and combinations of the two. 000 = Rotate in Auto EOI Mode (Clear) 001 = Non-specific EOI command 010 = No Operation 011 = *Specific EOI Command 100 = Rotate in Auto EOI Mode (Set) 101 = Rotate on Non-Specific EOI Command 110 = *Set Priority Command 111 = *Rotate on Specific EOI Command *L0 – L2 Are Used																				
4:3	<b>OCW2 Select</b> — WO. When selecting OCW2, bits 4:3 = 00																				
2:0	<b>Interrupt Level Select</b> (L2, L1, L0) — WO. L2, L1, and L0 determine the interrupt level acted upon when the SL bit is active. A simple binary code, outlined below, selects the channel for the command to act upon. When the SL bit is inactive, these bits do not have a defined function; programming L2, L1 and L0 to 0 is sufficient in this case.																				
	<table border="0"> <thead> <tr> <th>Code</th> <th>Interrupt Level</th> <th>Code</th> <th>Interrupt Level</th> </tr> </thead> <tbody> <tr> <td>000b</td> <td>IRQ0/8</td> <td>000b</td> <td>IRQ4/12</td> </tr> <tr> <td>001b</td> <td>IRQ1/9</td> <td>001b</td> <td>IRQ5/13</td> </tr> <tr> <td>010b</td> <td>IRQ2/10</td> <td>010b</td> <td>IRQ6/14</td> </tr> <tr> <td>011b</td> <td>IRQ3/11</td> <td>011b</td> <td>IRQ7/15</td> </tr> </tbody> </table>	Code	Interrupt Level	Code	Interrupt Level	000b	IRQ0/8	000b	IRQ4/12	001b	IRQ1/9	001b	IRQ5/13	010b	IRQ2/10	010b	IRQ6/14	011b	IRQ3/11	011b	IRQ7/15
Code	Interrupt Level	Code	Interrupt Level																		
000b	IRQ0/8	000b	IRQ4/12																		
001b	IRQ1/9	001b	IRQ5/13																		
010b	IRQ2/10	010b	IRQ6/14																		
011b	IRQ3/11	011b	IRQ7/15																		













Bit	Description
16	<b>Mask</b> — R/W. 0 = Not masked: An edge or level on this interrupt pin results in the delivery of the interrupt to the destination. 1 = Masked: Interrupts are not delivered nor held pending. Setting this bit after the interrupt is accepted by a local APIC has no effect on that interrupt. This behavior is identical to the device withdrawing the interrupt before it is posted to the processor. It is software's responsibility to deal with the case where the mask bit is set after the interrupt message has been accepted by a local APIC unit but before the interrupt is dispensed to the processor.
15	<b>Trigger Mode</b> — R/W. This field indicates the type of signal on the interrupt pin that triggers an interrupt. 0 = Edge triggered. 1 = Level triggered.
14	<b>Remote IRR</b> — R/W. This bit is used for level triggered interrupts; its meaning is undefined for edge triggered interrupts. 0 = Reset when an EOI message is received from a local APIC. 1 = Set when Local APIC/s accept the level interrupt sent by the I/O APIC.
13	<b>Interrupt Input Pin Polarity</b> — R/W. This bit specifies the polarity of each interrupt signal connected to the interrupt pins. 0 = Active high. 1 = Active low.
12	<b>Delivery Status</b> — RO. This field contains the current status of the delivery of this interrupt. Writes to this bit have no effect. 0 = Idle. No activity for this interrupt. 1 = Pending. Interrupt has been injected, but delivery is not complete.
11	<b>Destination Mode</b> — R/W. This field determines the interpretation of the Destination field. 0 = Physical. Destination APIC ID is identified by bits 59:56. 1 = Logical. Destinations are identified by matching bit 63:56 with the Logical Destination in the Destination Format Register and Logical Destination Register in each Local APIC.
10:8	<b>Delivery Mode</b> — R/W. This field specifies how the APICs listed in the destination field should act upon reception of this signal. Certain Delivery Modes will only operate as intended when used in conjunction with a specific trigger mode. These encodings are listed in the note below:
7:0	<b>Vector</b> — R/W. This field contains the interrupt vector for this interrupt. Values range between 10h and FEh.

**Note:** Delivery Mode encoding:

000 = Fixed. Deliver the signal on the INTR signal of all processor cores listed in the destination. Trigger Mode can be edge or level.

001 = Lowest Priority. Deliver the signal on the INTR signal of the processor core that is executing at the lowest priority among all the processors listed in the specified destination. Trigger Mode can be edge or level.

010 = SMI (System Management Interrupt). Requires the interrupt to be programmed as edge triggered. The vector information is ignored but must be programmed to all 0s for future compatibility: **not supported**

011 = Reserved

100 = NMI. Deliver the signal on the NMI signal of all processor cores listed in the destination. Vector information is ignored. NMI is treated as an edge triggered interrupt even if it is programmed as level triggered. For proper operation this redirection table entry must be programmed to edge triggered. The NMI delivery mode does not set the RIRR bit. If the redirection table is incorrectly set to level, the loop count will continue counting through the redirection table addresses. Once the count for the NMI pin is reached again, the interrupt will be sent again: **not supported**

101 = INIT. Deliver the signal to all processor cores listed in the destination by asserting the INIT signal. All addressed local APICs will assume their INIT state. INIT is always treated as an edge triggered interrupt even if programmed as level triggered. For proper operation this redirection table entry must be programmed to edge triggered. The INIT delivery mode does not set the RIRR bit. If the redirection table is incorrectly set to level, the loop count will continue counting through the redirection table addresses. Once the count for the INIT pin is reached again, the interrupt will be sent again: **not supported**

110 = Reserved

111 = ExtINT. Deliver the signal to the INTR signal of all processor cores listed in the destination as an interrupt that originated in an externally connected 8259A compatible interrupt controller. The INTA cycle that corresponds to this ExtINT delivery will be routed to the external controller that is expected to supply the vector. Requires the interrupt to be programmed as edge triggered.



## 13.6 Real Time Clock Registers

### 13.6.1 I/O Register Address Map

The RTC internal registers and RAM are organized as two banks of 128 bytes each, called the standard and extended banks. The first 14 bytes of the standard bank contain the RTC time and date information along with four registers, A–D, that are used for configuration of the RTC. The extended bank contains a full 128 bytes of battery backed SRAM, and will be accessible even when the RTC module is disabled (using the RTC configuration register). Registers A–D do not physically exist in the RAM.

All data movement between the host processor and the real-time clock is done through registers mapped to the standard I/O space. The register map appears in [Table 13-6](#).

**Table 13-6. RTC I/O Registers**

I/O Locations	If U128E bit = 0	Function
70h and 74h	Also alias to 72h and 76h	Real-Time Clock (Standard RAM) Index Register
71h and 75h	Also alias to 73h and 77h	Real-Time Clock (Standard RAM) Target Register
72h and 76h		Extended RAM Index Register (if enabled)
73h and 77h		Extended RAM Target Register (if enabled)

**Notes:**

- I/O locations 70h and 71h are the standard legacy location for the real-time clock. The map for this bank is shown in [Table 13-7](#). Locations 72h and 73h are for accessing the extended RAM. The extended RAM bank is also accessed using an indexed scheme. I/O address 72h is used as the address pointer and I/O address 73h is used as the data register. Index addresses above 127h are not valid. If the extended RAM is not needed, it may be disabled.
- Software must preserve the value of bit 7 at I/O addresses 70h and 74h. When writing to this address, software must first read the value, and then write the same value for bit 7 during the sequential address write. Note that port 70h is not directly readable. The only way to read this register is through Alt Access mode. Although RTC Index bits 6:0 are readable from port 74h, bit 7 will always return 0. If the NMI# enable is not changed during normal operation, software can alternatively read this bit once and then retain the value for all subsequent writes to port 70h.

### 13.6.2 Indexed Registers

The RTC contains two sets of indexed registers that are accessed using the two separate Index and Target registers (70/71h or 72/73h), as shown in [Table 13-7](#).

**Table 13-7. RTC (Standard) RAM Bank**

Index	Name
00h	Seconds
01h	Seconds Alarm
02h	Minutes
03h	Minutes Alarm
04h	Hours
05h	Hours Alarm
06h	Day of Week
07h	Day of Month
08h	Month
09h	Year
0Ah	Register A
0Bh	Register B
0Ch	Register C
0Dh	Register D
0Eh–7Fh	114 Bytes of User RAM



### 13.6.2.1 RTC\_REGA—Register A

RTC Index:	0A	Attribute:	R/W
Default Value:	Undefined	Size:	8-bit
Lockable:	No	Power Well:	RTC

This register is used for general configuration of the RTC functions. None of the bits are affected by RSMRST# or any other PCH reset signal.

Bit	Description
7	<p><b>Update In Progress (UIP)</b> — R/W. This bit may be monitored as a status flag.</p> <p>0 = The update cycle will not start for at least 488 μs. The time, calendar, and alarm information in RAM is always available when the UIP bit is 0.</p> <p>1 = The update is soon to occur or is in progress.</p>
6:4	<p><b>Division Chain Select (DV[2:0])</b> — R/W. These three bits control the divider chain for the oscillator, and are not affected by RSMRST# or any other reset signal.</p> <p>010 = Normal Operation</p> <p>11X = Divider Reset</p> <p>101 = Bypass 15 stages (test mode only)</p> <p>100 = Bypass 10 stages (test mode only)</p> <p>011 = Bypass 5 stages (test mode only)</p> <p>001 = Invalid</p> <p>000 = Invalid</p>
3:0	<p><b>Rate Select (RS[3:0])</b> — R/W. Selects one of 13 taps of the 15 stage divider chain. The selected tap can generate a periodic interrupt if the PIE bit is set in Register B. Otherwise this tap will set the PF flag of Register C. If the periodic interrupt is not to be used, these bits should all be set to 0. RS3 corresponds to bit 3.</p> <p>0000 = Interrupt never toggles</p> <p>0001 = 3.90625 ms</p> <p>0010 = 7.8125 ms</p> <p>0011 = 122.070 μs</p> <p>0100 = 244.141 μs</p> <p>0101 = 488.281 μs</p> <p>0110 = 976.5625 μs</p> <p>0111 = 1.953125 ms</p> <p>1000 = 3.90625 ms</p> <p>1001 = 7.8125 ms</p> <p>1010 = 15.625 ms</p> <p>1011 = 31.25 ms</p> <p>1100 = 62.5 ms</p> <p>1101 = 125 ms</p> <p>1110 = 250 ms</p> <p>1111 = 500 ms</p>



### 13.6.2.2 RTC\_REGB—Register B (General Configuration)

RTC Index: 0Bh Attribute: R/W  
 Default Value: UOU00UUU (U: Undefined) Size: 8-bit  
 Lockable: No Power Well: RTC

Bit	Description
7	<p><b>Update Cycle Inhibit (SET)</b> — R/W. Enables/Inhibits the update cycles. This bit is not affected by RSMRST# nor any other reset signal.</p> <p>0 = Update cycle occurs normally once each second.            1 = A current update cycle will abort and subsequent update cycles will not occur until SET is returned to 0. When set is one, the BIOS may initialize time and calendar bytes safely.</p> <p><b>Note:</b> This bit should be set then cleared early in BIOS POST after each powerup directly after coin-cell battery insertion.</p>
6	<p><b>Periodic Interrupt Enable (PIE)</b> — R/W. This bit is cleared by RSMRST#, but not on any other reset.</p> <p>0 = Disable.            1 = Enable. Allows an interrupt to occur with a time base set with the RS bits of register A.</p>
5	<p><b>Alarm Interrupt Enable (AIE)</b> — R/W. This bit is cleared by RTCRST#, but not on any other reset.</p> <p>0 = Disable.            1 = Enable. Allows an interrupt to occur when the AF is set by an alarm match from the update cycle. An alarm can occur once a second, one an hour, once a day, or one a month.</p>
4	<p><b>Update-Ended Interrupt Enable (UIE)</b> — R/W. This bit is cleared by RSMRST#, but not on any other reset.</p> <p>0 = Disable.            1 = Enable. Allows an interrupt to occur when the update cycle ends.</p>
3	<p><b>Square Wave Enable (SQWE)</b> — R/W. This bit serves no function in the PCH. It is left in this register bank to provide compatibility with the Motorola 146818B. The PCH has no SQW pin. This bit is cleared by RSMRST#, but not on any other reset.</p>
2	<p><b>Data Mode (DM)</b> — R/W. This bit specifies either binary or BCD data representation. This bit is not affected by RSMRST# nor any other reset signal.</p> <p>0 = BCD            1 = Binary</p>
1	<p><b>Hour Format (HOURFORM)</b> — R/W. This bit indicates the hour byte format. This bit is not affected by RSMRST# nor any other reset signal.</p> <p>0 = Twelve-hour mode. In twelve-hour mode, the seventh bit represents AM as 0 and PM as one.            1 = Twenty-four hour mode.</p>
0	<p><b>Daylight Savings Legacy Software Support (DLSWS)</b> — R/W. Daylight savings functionality is no longer supported. This bit is used to maintain legacy software support and has no associated functionality. If BUC.DSO bit is set, the DLSWS bit continues to be R/W.</p>



### 13.6.2.3 RTC\_REGC—Register C (Flag Register)

RTC Index: 0Ch Attribute: RO  
 Default Value: 00U00000 (U: Undefined) Size: 8-bit  
 Lockable: No Power Well: RTC

Writes to Register C have no effect.

Bit	Description
7	<b>Interrupt Request Flag (IRQF)</b> — RO. $IRQF = (PF * PIE) + (AF * AIE) + (UF * UFE)$ . This bit also causes the RTC Interrupt to be asserted. This bit is cleared upon RSMRST# or a read of Register C.
6	<b>Periodic Interrupt Flag (PF)</b> — RO. This bit is cleared upon RSMRST# or a read of Register C. 0 = If no taps are specified using the RS bits in Register A, this flag will not be set. 1 = Periodic interrupt Flag will be 1 when the tap specified by the RS bits of register A is 1.
5	<b>Alarm Flag (AF)</b> — RO. 0 = This bit is cleared upon RTCRST# or a read of Register C. 1 = Alarm Flag will be set after all Alarm values match the current time.
4	<b>Update-Ended Flag (UF)</b> — RO. 0 = The bit is cleared upon RSMRST# or a read of Register C. 1 = Set immediately following an update cycle for each second.
3:0	Reserved. Will always report 0.

### 13.6.2.4 RTC\_REGD—Register D (Flag Register)

RTC Index: 0Dh Attribute: R/W  
 Default Value: 10UUUUUU (U: Undefined) Size: 8-bit  
 Lockable: No Power Well: RTC

Bit	Description
7	<b>Valid RAM and Time Bit (VRT)</b> — R/W. 0 = This bit should always be written as a 0 for write cycle, however it will return a 1 for read cycles. 1 = This bit is hardwired to 1 in the RTC power well.
6	Reserved. This bit always returns a 0 and should be set to 0 for write cycles.
5:0	<b>Date Alarm</b> — R/W. These bits store the date of month alarm value. If set to 000000b, then a don't care state is assumed. The host must configure the date alarm for these bits to do anything, yet they can be written at any time. If the date alarm is not enabled, these bits will return 0s to mimic the functionality of the Motorola 146818B. These bits are not affected by any reset assertion.



## 13.7 Processor Interface Registers

Table 13-8 is the register address map for the processor interface registers.

**Table 13-8. Processor Interface PCI Register Address Map**

Offset	Mnemonic	Register Name	Default	Type
61h	NMI_SC	NMI Status and Control	00h	R/W, RO
70h	NMI_EN	NMI Enable	80h	R/W (special)
92h	PORT92	Fast A20 and Init	00h	R/W
F0h	COPROC_ERR	Coprocessor Error	00h	WO
CF9h	RST_CNT	Reset Control	00h	R/W

### 13.7.1 NMI\_SC—NMI Status and Control Register

I/O Address:	61h	Attribute:	R/W, RO
Default Value:	00h	Size:	8-bit
Lockable:	No	Power Well:	Core

Bit	Description
7	<b>SERR# NMI Source Status (SERR#_NMI_STS)</b> — RO. 1 = Bit is set if a PCI agent detected a system error and pulses the PCI SERR# line and if bit 2 (PCI_SERR_EN) is cleared. This interrupt source is enabled by setting bit 2 to 0. To reset the interrupt, set bit 2 to 1 and then set it to 0. When writing to port 61h, this bit must be 0. <b>Note:</b> This bit is set by any of the PCH internal sources of SERR; this includes SERR assertions forwarded from the secondary PCI bus, errors on a PCI Express* port, or other internal functions that generate SERR#.
6	<b>IOCHK# NMI Source Status (IOCHK#_NMI_STS)</b> — RO. 1 = Bit is set if an LPC agent (using SERIRO) asserted IOCHK# and if bit 3 (IOCHK#_NMI_EN) is cleared. This interrupt source is enabled by setting bit 3 to 0. To reset the interrupt, set bit 3 to 1 and then set it to 0. When writing to port 61h, this bit must be a 0.
5	<b>Timer Counter 2 OUT Status (TMR2_OUT_STS)</b> — RO. This bit reflects the current state of the 8254 counter 2 output. Counter 2 must be programmed following any PCI reset for this bit to have a determinate value. When writing to port 61h, this bit must be a 0.
4	<b>Refresh Cycle Toggle (REF_TOGGLE)</b> — RO. This signal toggles from either 0 to 1 or 1 to 0 at a rate that is equivalent to when refresh cycles would occur. When writing to port 61h, this bit must be a 0.
3	<b>IOCHK# NMI Enable (IOCHK#_NMI_EN)</b> — R/W. 0 = Enabled. 1 = Disabled and cleared.
2	<b>PCI SERR# Enable (PCI_SERR_EN)</b> — R/W. 0 = SERR# NMIs are enabled. 1 = SERR# NMIs are disabled and cleared.
1	<b>Speaker Data Enable (SPKR_DAT_EN)</b> — R/W. 0 = SPKR output is a 0. 1 = SPKR output is equivalent to the Counter 2 OUT signal value.
0	<b>Timer Counter 2 Enable (TIM_CNT2_EN)</b> — R/W. 0 = Disable 1 = Enable





### 13.7.5 RST\_CNT—Reset Control Register

I/O Address:	CF9h	Attribute:	R/W
Default Value:	00h	Size:	8-bit
Lockable:	No	Power Well:	Core

Bit	Description
7:4	Reserved
3	<p><b>Full Reset (FULL_RST)</b> — R/W. This bit is used to determine the states of SLP_S3#, SLP_S4#, and SLP_S5# after a CF9 hard reset (SYS_RST = 1 and RST_CPU is set to 1), after PCH_PWROK going low (with RSMRST# high), or after two TCO timeouts.</p> <p>0 = PCH will keep SLP_S3#, SLP_S4# and SLP_S5# high. 1 = PCH will drive SLP_S3#, SLP_S4# and SLP_S5# low for 3 – 5 seconds.</p> <p><b>Note:</b> When this bit is set, it also causes the full power cycle (SLP_S3/4/5# assertion) in response to SYS_RESET#, PCH_PWROK#, and Watchdog timer reset sources.</p>
2	<p><b>Reset Processor (RST_CPU)</b> — R/W. When this bit transitions from a 0 to a 1, it initiates a hard or soft reset, as determined by the SYS_RST bit (bit 1 of this register).</p>
1	<p><b>System Reset (SYS_RST)</b> — R/W. This bit is used to determine a hard or soft reset to the processor.</p> <p>0 = When RST_CPU bit goes from 0 to 1, the PCH performs a soft reset by activating INIT# for 16 PCI clocks. 1 = When RST_CPU bit goes from 0 to 1, the PCH performs a hard reset by activating PLTRST# Oactive for a minimum of about 1 millisecond. In this case, SLP_S3#, SLP_S4# and SLP_S5# state (assertion or deassertion) depends on FULL_RST bit setting. The PCH main power well is reset when this bit is 1. It also resets the resume well bits (except for those noted throughout the datasheet).</p>
0	Reserved

## 13.8 Power Management Registers

The power management registers are distributed within the PCI Device 31: Function 0 space, as well as a separate I/O range. Each register is described below. Unless otherwise indicated, bits are in the main (core) power well.

Bits not explicitly defined in each register are assumed to be reserved. When writing to a reserved bit, the value should always be 0. Software should not attempt to use the value read from a reserved bit, as it may not be consistently 1 or 0.

### 13.8.1 Power Management PCI Configuration Registers (PM—D31:F0)

Table 13-9 shows a small part of the configuration space for PCI Device 31: Function 0. It includes only those registers dedicated for power management. Some of the registers are only used for Legacy Power management schemes.

**Table 13-9. Power Management PCI Register Address Map (PM—D31:F0) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Type
A0h-A1h	GEN_PMCON_1	General Power Management Configuration 1	0000h	R/W, R/WO, RO
A2h	GEN_PMCON_2	General Power Management Configuration 2	00h	RO, R/WC, R/W
A4h-A5h	GEN_PMCON_3	General Power Management Configuration 3	4206h	R/W, R/WL
A6h	GEN_PMCON_LOCK	General Power Management Configuration Lock	00h	RO, R/WL, R/WS
A9h	CIR4	Chipset Initialization Register 4	03h	R/W





### 13.8.1.2 GEN\_PMCON\_2—General PM Configuration 2 Register (PM—D31:F0)

Offset Address:	A2h	Attribute:	RO, R/WC, R/W
Default Value:	00h	Size:	8-bit
Lockable:	No	Usage:	ACPI, Legacy
		Power Well:	Resume

Bit	Description
7	<p><b>DRAM Initialization Bit</b> — R/W. This bit does not affect hardware functionality in any way. BIOS is expected to set this bit prior to starting the DRAM initialization sequence and to clear this bit after completing the DRAM initialization sequence. BIOS can detect that a DRAM initialization sequence was interrupted by a reset by reading this bit during the boot sequence.</p> <ul style="list-style-type: none"> <li>If the bit is 1, then the DRAM initialization was interrupted.</li> <li>This bit is reset by the assertion of the RSMRST# pin.</li> </ul>
6	Reserved
5	<p><b>Memory Placed in Self-Refresh (MEM_SR)</b> — RO.</p> <ul style="list-style-type: none"> <li>If the bit is 1, DRAM should have remained powered and held in Self-Refresh through the last power state transition (that is, the last time the system left S0).</li> <li>This bit is reset by the assertion of the RSMRST# pin.</li> </ul>
4	<p><b>System Reset Status (SRS)</b> — R/WC. Software clears this bit by writing a 1 to it.  0 = SYS_RESET# button Not pressed.  1 = PCH sets this bit when the SYS_RESET# button is pressed. BIOS is expected to read this bit and clear it, if it is set.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This bit is also reset by RSMRST# and CF9h resets.</li> <li>The SYS_RESET# is implemented in the Main power well. This pin must be properly isolated and masked to prevent incorrectly setting this Suspend well status bit.</li> </ol>
3	<p><b>Processor Thermal Trip Status (CTS)</b> — R/WC.  0 = Software clears this bit by writing a 1 to it.  1 = This bit is set when PLTRST# is inactive and THRMTRIP# goes active while the system is in an S0 or S1 state.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This bit is also reset by RSMRST#, and CF9h resets. It is not reset by the shutdown and reboot associated with the Processor THRMTRIP# event.</li> <li>The CF9h reset in the description refers to CF9h type core well reset which includes SYS_RESET#, PCH_PWROK/SYS_PWROK low, SMBus hard reset, TCO Timeout. This type of reset will clear CTS bit.</li> </ol>
2	<p><b>Minimum SLP_S4# Assertion Width Violation Status</b> — R/WC.  0 = Software clears this bit by writing a 1 to it.  1 = Hardware sets this bit when the SLP_S4# assertion width is less than the time programmed in the SLP_S4# Minimum Assertion Width field (D31:F0: Offset A4h: bits 5: 4). The PCH begins the timer when SLP_S4# is asserted during S4/S5 entry or when the RSMRST# input is deasserted during SUS well power-up. Note that this bit is functional regardless of the values in the SLP_S4# Assertion Stretch Enable (D31:F0: Offset A4h: bit 3) and in the Disable SLP Stretching after SUS Well Power Up (D31:F0: Offset A4h: bit 12).</p> <p><b>Note:</b> This bit is reset by the assertion of the RSMRST# pin, but can be set in some cases before the default value is readable.</p>
1	<p><b>SYS_PWROK Failure (SYSPWR_FLR)</b> — R/WC.  0 = This bit will be cleared only by software writing a 1 back to the bit or by SUS well power loss.  <b>Note:</b> This bit will be set any time SYS_PWROK drops unexpectedly when the system was in S0 or S1 state.</p>
0	<p><b>PCH_PWROK Failure (PWROK_FLR)</b> — R/WC.  0 = This bit will be cleared only by software writing a 1 back to the bit or by SUS well power loss.  1 = This bit will be set any time PCH_PWROK goes low when the system was in S0 or S1 state.  <b>Note:</b> See <a href="#">Chapter 5.14.9.3</a> for more details about the PCH_PWROK pin functionality.</p>



### 13.8.1.3 GEN\_PMCON\_3—General PM Configuration 3 Register (PM—D31:F0)

Offset Address: A4h Attribute: R/W, R/WC  
 Default Value: 4206h Size: 16-bit  
 Lockable: No Usage: ACPI, Legacy  
 Power Well: RTC, SUS

Bit	Description															
15	<p><b>PME B0 S5 Disable (PME_B0_S5_DIS)</b>— R/W. When set to '1', this bit blocks wake events from PME_B0_STS in S5, regardless of the state of PME_B0_EN. When cleared (default), wake events from PME_B0_STS are allowed in S5 if PME_B0_EN = '1'.            Wakes from power states other than S5 are not affected by this policy bit.            The net effect of setting PME_B0_S5_DIS = '1' is described by the truth table below:            Y = Wake; N = Don't wake; B0 = PME_B0_EN; OV = WOL Enable Override</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>B0/OV</th> <th>S1/S3/S4</th> <th>S5</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>N</td> <td>N</td> </tr> <tr> <td>01</td> <td>N</td> <td>Y (LAN only)</td> </tr> <tr> <td>11</td> <td>Y (all PME B0 sources)</td> <td>Y (LAN only)</td> </tr> <tr> <td>01</td> <td>Y (all PME B0 sources)</td> <td>N</td> </tr> </tbody> </table> <p>This bit is cleared by the RTCRST# pin.</p>	B0/OV	S1/S3/S4	S5	00	N	N	01	N	Y (LAN only)	11	Y (all PME B0 sources)	Y (LAN only)	01	Y (all PME B0 sources)	N
B0/OV	S1/S3/S4	S5														
00	N	N														
01	N	Y (LAN only)														
11	Y (all PME B0 sources)	Y (LAN only)														
01	Y (all PME B0 sources)	N														
14	<p><b>SUS Well Power Failure (SUS_PWR_FLR)</b> — R/WC.            0 = Software writes a 1 to this bit to clear it.            1 = This bit is set to '1' whenever SUS well power is lost, as indicated by RSMRST# assertion.  <b>Note:</b> This bit is in the SUS well, and defaults to '1' based on RSMRST# assertion (not cleared by any type of reset).</p>															
13	<p><b>WOL Enable Override (WOL_EN_OVRD)</b> — R/W.            0 = WOL policies are determined by PME_B0 enable bit and appropriate LAN status bits            1 = Enable appropriately configured integrated LAN to wake the system in S5 only regardless of the value in the PME_B0_EN bit in the GPE0_EN register.  <b>Note:</b> This bit is cleared by the RTCRST# pin.</p>															
12	<p><b>Disable SLP Stretching After SUS Well Power Up (DIS_SLP_STRCH_SUS_UP):</b> R/W            0 = Enables stretching on SLP signals after SUS power failure as enabled and configured in other fields.            1 = Disables stretching on SLP signals when powering up after a SUS well power loss, regardless of the state of the SLP_S4# Assertion Stretch Enable (bit 3).            This bit is cleared by the RTCRST# pin.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This field is RO when the SLP Stretching Policy Lock-Down bit is set.</li> <li>If this bit is cleared, SLP stretch timers start on SUS well power up (the PCH has no ability to count stretch time while the SUS well is powered down).</li> <li>This policy bit has a different effect on SLP_SUS# stretching than on the other SLP_* pins since SLP_SUS# is the control signal for one of the scenarios where SUS well power is lost (Deep S4/S5). The effect of setting this bit to '1' on:               <ul style="list-style-type: none"> <li>— SLP_S3# and SLP_S4# stretching: disabled after any SUS power loss.</li> <li>— SLP_SUS# stretching: disabled after G3, but no impact on Deep S4/S5.</li> </ul> </li> </ol>															
11:10	<p><b>SLP_S3# Minimum Assertion Width:</b> R/W This 2-bit value indicates the minimum assertion width of the SLP_S3# signal to ensure that the Main power supplies have been fully power-cycled.            Valid Settings are:            00 = 60 us            01 = 1 ms            10 = 50 ms            11 = 2 s            This bit is cleared by the RSMRST# pin.</p> <p><b>Note:</b> This field is RO when the SLP Stretching Policy Lock-Down bit is set.</p>															



Bit	Description
9	<p><b>General Reset Status (GEN_RST_STS)</b> — R/WC. This bit is set by hardware whenever PLTRST# asserts for any reason other than going into a software-entered sleep state (using PM1CNT.SLP_EN write) or a suspend well power failure (RSMRST# pin assertion). BIOS is expected to consult and then write a 1 to clear this bit during the boot flow before determining what action to take based on PM1_STS.WAK_STS = 1. If GEN_RST_STS = '1', the cold reset boot path should be followed rather than the resume path, regardless of the setting of WAK_STS.</p> <p>This bit is cleared by the RSMRST# pin.</p>
8	<p><b>SLP_LAN# Default Value (SLP_LAN_DEFAULT)</b> — R/W. This bit specifies the value to drive on the SLP_LAN# pin when in Sx/Moff and Intel ME FW nor host BIOS has configured SLP_LAN# as an output. When this bit is set to 1 SLP_LAN# will default to be driven high, when set to 0 SLP_LAN# will default to be driven low.</p> <p>This bit will always determine SLP_LAN# behavior when in S4/S5/Moff after SUS power loss, in S5/Moff after a host partition reset with power down and when in S5/Moff due to an unconditional power down.</p> <p>This bit is cleared by RTCRST#.</p>
7:6	<p><b>SWSMI_RATE_SEL</b> — R/W. This field indicates when the SWSMI timer will time out. Valid values are:</p> <p>00 = 1.5 ms ± 0.6 ms  01 = 16 ms ± 4 ms  10 = 32 ms ± 4 ms  11 = 64 ms ± 4 ms</p> <p>These bits are not cleared by any type of reset except RTCRST#.</p>
5:4	<p><b>SLP_S4# Minimum Assertion Width</b> — R/W. This field indicates the minimum assertion width of the SLP_S4# signal to ensure that the DRAM modules have been safely power-cycled. Valid values are:</p> <p>11 = 1 second  10 = 2 seconds  01 = 3 seconds  00 = 4 seconds</p> <p>This value is used in two ways:</p> <ol style="list-style-type: none"> <li>If the SLP_S4# assertion width is ever shorter than this time, a status bit is set for BIOS to read when S0 is entered.</li> <li>If enabled by bit 3 in this register, the hardware will prevent the SLP_S4# signal from deasserting within this minimum time period after asserting.</li> </ol> <p>RTCRST# forces this field to the conservative default state (00b).</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This field is RO when the SLP Stretching Policy Lock-Down bit is set.</li> <li>Note that the logic that measures this time is in the suspend power well. Therefore, when leaving a G3 or Deep S4/S5 state, the minimum time is measured from the deassertion of the internal suspend well reset (unless the "Disable SLP Stretching After SUS Well Power Up" bit is set).</li> </ol>
3	<p><b>SLP_S4# Assertion Stretch Enable</b> — R/W.</p> <p>0 = The SLP_S4# minimum assertion time is defined in Power Sequencing and Reset Signal Timings table.  1 = The SLP_S4# signal minimally assert for the time specified in bits 5:4 of this register.</p> <p>This bit is cleared by RTCRST#.</p> <p><b>Note:</b> This bit is RO when the SLP Stretching Policy Lock-Down bit is set.</p>







Bit	Description
5:4	<b>GPIO2 Route</b> — R/W. See bits 1:0 for description.
3:2	<b>GPIO1 Route</b> — R/W. See bits 1:0 for description.
1:0	<b>GPIO0 Route</b> — R/W. GPIO can be routed to cause an NMI, SMI# or SCI when the GPIO[n]_STS bit is set. If the GPIO0 is not set to an input, this field has no effect. If the system is in an S1–S5 state and if the GPE0_EN bit is also set, then the GPIO can cause a Wake event, even if the GPIO is NOT routed to cause an NMI, SMI# or SCI. 00 = No effect. 01 = SMI# (if corresponding ALT_GPI_SMI_EN bit is also set) 10 = SCI (if corresponding GPE0_EN bit is also set) 11 = NMI (If corresponding GPI_NMI_EN is also set)

**Note:** GPIOs that are not implemented will not have the corresponding bits implemented in this register.

### 13.8.2 APM I/O Decode

Table 13-10 shows the I/O registers associated with APM support. This register space is enabled in the PCI Device 31: Function 0 space (APMDEC\_EN), and cannot be moved (fixed I/O location).

**Table 13-10. APM Register Map**

Address	Mnemonic	Register Name	Default	Type
B2h	APM_CNT	Advanced Power Management Control Port	00h	R/W
B3h	APM_STS	Advanced Power Management Status Port	00h	R/W

#### 13.8.2.1 APM\_CNT—Advanced Power Management Control Port Register

I/O Address:	B2h	Attribute:	R/W
Default Value:	00h	Size:	8-bit
Lockable:	No	Usage:	Legacy Only
Power Well:	Core		

Bit	Description
7:0	Used to pass an APM command between the OS and the SMI handler. Writes to this port not only store data in the APMC register, but also generates an SMI# when the APMC_EN bit is set.

#### 13.8.2.2 APM\_STS—Advanced Power Management Status Port Register

I/O Address:	B3h	Attribute:	R/W
Default Value:	00h	Size:	8-bit
Lockable:	No	Usage:	Legacy Only
Power Well:	Core		

Bit	Description
7:0	Used to pass data between the OS and the SMI handler. Basically, this is a scratchpad register and is not affected by any other register or function (other than a PCI reset).



### 13.8.3 Power Management I/O Registers

Table 13-11 shows the registers associated with ACPI and Legacy power management support. These registers locations are all offsets from the ACPI base address defined in the PCI Device 31: Function 0 space (PMBASE), and can be moved to any 128-byte aligned I/O location. In order to access these registers, the ACPI Enable bit (ACPI\_EN) must be set. The registers are defined to be compliant with the ACPI 3.0b specification, and generally use the same bit names.

**Note:** All reserved bits and registers will always return 0 when read, and will have no effect when written.

**Table 13-11. ACPI and Legacy I/O Register Map**

PMBASE + Offset	Mnemonic	Register Name	Default	Type
00h–01h	PM1_STS	PM1 Status	0000h	R/WC
02h–03h	PM1_EN	PM1 Enable	0000h	R/W
04h–07h	PM1_CNT	PM1 Control	00000000h	R/W, WO
08h–0Bh	PM1_TMR	PM1 Timer	xx000000h	RO
20–27h	GPE0_STS	General Purpose Event 0 Status	00000000 00000000h	R/WC
28–2Fh	GPE0_EN	General Purpose Event 0a Enables	00000000 00000000h	R/W
30h–33h	SMI_EN	SMI# Control and Enable	00000002h	R/W, WO, R/WO
34h–37h	SMI_STS	SMI Status	00000000h	R/WC, RO
38h–39h	ALT_GP_SMI_EN	Alternate GPI SMI Enable	0000h	R/W
3Ah–3Bh	ALT_GP_SMI_STS	Alternate GPI SMI Status	0000h	R/WC
3Ch–3Dh	UPRWC	USB Per-Port Registers Write Control	0000h	R/WC, R/W, R/WO
42h	GPE_CNTL	General Purpose Event Control	00h	R/W
44h–45h	DEVTRAP_STS	Device Trap Status Status	0000h	R/WC
50h	PM2_CNT	Power Management 2 Control	00h	R/W
60h–7Fh	—	Reserved for TCO	—	—



### 13.8.3.1 PM1\_STS—Power Management 1 Status Register

I/O Address: PMBASE + 00h  
 Attribute: R/WC  
 Default Value: 0000h  
 Size: 16-bit  
 Lockable: No  
 Usage: ACPI or Legacy  
 Power Well: Bits 0–7: Core,  
 Bits 12-15: Resume  
 Bit 11: RTC,  
 Bits 8 and 10: DSW

If bit 10 or 8 in this register is set, and the corresponding \_EN bit is set in the PM1\_EN register, then the PCH will generate a Wake Event. Once back in an S0 state (or if already in an S0 state when the event occurs), the PCH will also generate an SCI if the SCI\_EN bit is set, or an SMI# if the SCI\_EN bit is not set.

**Note:** Bit 5 does not cause an SMI# or a wake event. Bit 0 does not cause a wake event but can cause an SMI# or SCI.

Bit	Description
15	<p><b>Wake Status (WAK_STS)</b> — R/WC. This bit is not affected by hard resets caused by a CF9 write, but is reset by RSMRST#.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = Set by hardware when the system is in one of the sleep states (using the SLP_EN bit) and an enabled wake event occurs. Upon setting this bit, the PCH will transition the system to the ON state.</p> <p>If the AFTERG3_EN bit is not set and a power failure (such as removed batteries) occurs without the SLP_EN bit set, the system will return to an S0 state when power returns, and the WAK_STS bit will not be set.</p> <p>If the AFTERG3_EN bit is set and a power failure occurs without the SLP_EN bit having been set, the system will go into an S5 state when power returns, and a subsequent wake event will cause the WAK_STS bit to be set. Note that any subsequent wake event would have to be caused by either a Power Button press, or an enabled wake event that was preserved through the power failure (enable bit in the RTC well).</p>
14	<p><b>PCI Express* Wake Status (PCIEXPWAK_STS)</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it. If the WAKE# pin is still active during the write or the PME message received indication has not been cleared in the root port, then the bit will remain active (that is, all inputs to this bit are level-sensitive).            1 = This bit is set by hardware to indicate that the system woke due to a PCI Express* wakeup event. This wakeup event can be caused by the PCI Express* WAKE# pin being active or receipt of a PCI Express* PME message at a root port. This bit is set only when one of these events causes the system to transition from a non-S0 system power state to the S0 system power state. This bit is set independent of the state of the PCIEXP_WAKE_DIS bit.</p> <p><b>Note:</b> This bit does not itself cause a wake event or prevent entry to a sleeping state. Thus, if the bit is 1 and the system is put into a sleeping state, the system will not automatically wake.</p>
13:12	Reserved
11	<p><b>Power Button Override Status (PWRBTNOR_STS)</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = This bit is set any time a Power Button Override occurs (that is, the power button is pressed for at least 4 consecutive seconds), due to the corresponding bit in the SMBus slave message, Intel ME Initiated Power Button Override, Intel ME Initiated Host Reset with Power down or due to an internal thermal sensor catastrophic condition. The power button override causes an unconditional transition to the S5 state. The BIOS or SCI handler clears this bit by writing a 1 to it. This bit is not affected by hard resets using CF9h writes, and is not reset by RSMRST#. Thus, this bit is preserved through power failures. Note that if this bit is still asserted when the global SCI_EN is set then an SCI will be generated.</p> <p><b>Note:</b> Upon entry to S5 due to an event described above, if Deep S4/S5 is enabled and conditions are met per Section 5.14.6.6, the system will transition to Deep S4/S5.</p>
10	<p><b>RTC Status (RTC_STS)</b> — R/WC. This bit is not affected by hard resets caused by a CF9 write, but is reset by DPWROK.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = Set by hardware when the RTC generates an alarm (assertion of the IRQ8# signal). Additionally if the RTC_EN bit (PMBASE + 02h, bit 10) is set, the setting of the RTC_STS bit will generate a wake event.</p>
9	Reserved



Bit	Description
8	<p><b>Power Button Status (PWRBTN_STS)</b> — R/WC. This bit is not affected by hard resets caused by a CF9 write but is reset by DPWROK</p> <p>0 = If the PWRBTN# signal is held low for more than 4 seconds, the hardware clears the PWRBTN_STS bit, sets the PWRBTNOR_STS bit, and the system transitions to the S5 state with only PWRBTN# enabled as a wake event.</p> <p>This bit can be cleared by software by writing a one to the bit position.</p> <p>1 = This bit is set by hardware when the PWRBTN# signal is asserted Low, independent of any other enable bit.</p> <p>In the S0 state, while PWRBTN_EN and PWRBTN_STS are both set, an SCI (or SMI# if SCI_EN is not set) will be generated.</p> <p>In any sleeping state S1–S5, while PWRBTN_EN (PMBASE + 02h, bit 8) and PWRBTN_STS are both set, a wake event is generated.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>If the PWRBTN_STS bit is cleared by software while the PWRBTN# signal is still asserted, this will not cause the PWRBTN_STS bit to be set. The PWRBTN# signal must go inactive and active again to set the PWRBTN_STS bit.</li> <li>Upon entry to S5 due to a power button override, if Deep S4/S5 is enabled and conditions are met per <a href="#">Section 5.14.6.6</a>, the system will transition to Deep S4/S5.</li> </ol>
7:6	Reserved
5	<p><b>Global Status (GBL_STS)</b> — R/WC.</p> <p>0 = The SCI handler should then clear this bit by writing a 1 to the bit location.</p> <p>1 = Set when an SCI is generated due to BIOS wanting the attention of the SCI handler. BIOS has a corresponding bit, BIOS_RLS, which will cause an SCI and set this bit.</p>
4	<p><b>Bus Master Status (BM_STS)</b> — R/WC. This bit will not cause a wake event, SCI or SMI#.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by the PCH when a PCH-visible bus master requests access to memory or the BM_BUSY# signal is active.</p>
3:1	Reserved
0	<p><b>Timer Overflow Status (TMROF_STS)</b> — R/WC.</p> <p>0 = The SCI or SMI# handler clears this bit by writing a 1 to the bit location.</p> <p>1 = This bit gets set any time bit 22 of the 24-bit timer goes high (bits are numbered from 0 to 23). This will occur every 2.3435 seconds. When the TMROF_EN bit (PMBASE + 02h, bit 0) is set, then the setting of the TMROF_STS bit will additionally generate an SCI or SMI# (depending on the SCI_EN).</p>



### 13.8.3.2 PM1\_EN—Power Management 1 Enable Register

I/O Address: PMBASE + 02h  
 Attribute: RO; R/W  
 Default Value: 0000h  
 Size: 16-bit  
 Lockable: No  
 Usage: ACPI or Legacy  
 Power Well: Bits 0–7: Core,  
 Bits 8-9, 11–15: Resume,  
 Bit 10: RTC

Bit	Description												
15	Reserved												
14	<b>PCI Express* Wake Disable (PCIEXPWAK_DIS)</b> — R/W. Modification of this bit has no impact on the value of the PCIEXP_WAKE_STS bit. 0 = Inputs to the PCIEXP_WAKE_STS bit in the PM1 Status register enabled to wake the system. 1 = Inputs to the PCIEXP_WAKE_STS bit in the PM1 Status register disabled from waking the system.												
13:11	Reserved												
10	<b>RTC Alarm Enable (RTC_EN)</b> — R/W. This bit is in the RTC well to allow an RTC event to wake after a power failure. In addition to being cleared by RTCRST# assertion, the PCH also clears this bit due to a Power Button Override event, Intel ME Initiated Power Button Override, Intel ME Initiated Host Reset with Power down, SMBus unconditional power down, Processor thermal trip event, or due to an internal thermal sensor catastrophic condition. 0 = No SCI (or SMI#) or wake event is generated then RTC_STS (PMBASE + 00h, bit 10) goes active. 1 = An SCI (or SMI#) or wake event will occur when this bit is set and the RTC_STS bit goes active.												
9	Reserved.												
8	<b>Power Button Enable (PWRBTN_EN)</b> — R/W. This bit is used to enable the setting of the PWRBTN_STS bit to generate a power management event (SMI#, SCI). PWRBTN_EN has no effect on the PWRBTN_STS bit (PMBASE + 00h, bit 8) being set by the assertion of the power button. The Power Button is always enabled as a Wake event. 0 = Disable. 1 = Enable.												
7:6	Reserved.												
5	<b>Global Enable (GBL_EN)</b> — R/W. When both the GBL_EN and the GBL_STS bit (PMBASE + 00h, bit 5) are set, an SCI is raised. 0 = Disable. 1 = Enable SCI on GBL_STS going active.												
4:1	Reserved.												
0	<b>Timer Overflow Interrupt Enable (TMROF_EN)</b> — R/W. Works in conjunction with the SCI_EN bit (PMBASE + 04h, bit 0) as described below: <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>TMROF_EN</th> <th>SCI_EN</th> <th>Effect when TMROF_STS is set</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>X</td> <td>No SMI# or SCI</td> </tr> <tr> <td>1</td> <td>0</td> <td>SMI#</td> </tr> <tr> <td>1</td> <td>1</td> <td>SCI</td> </tr> </tbody> </table>	TMROF_EN	SCI_EN	Effect when TMROF_STS is set	0	X	No SMI# or SCI	1	0	SMI#	1	1	SCI
TMROF_EN	SCI_EN	Effect when TMROF_STS is set											
0	X	No SMI# or SCI											
1	0	SMI#											
1	1	SCI											



### 13.8.3.3 PM1\_CNT—Power Management 1 Control

I/O Address: PMBASE + 04h  
 Attribute: R/W, WO  
 Default Value: 00000000h  
 Size: 32-bit  
 Lockable: No  
 Usage: ACPI or Legacy  
 Power Well: Bits 0–7: Core,  
 Bits 8–12: RTC,  
 Bits 13-15: Resume

Bit	Description																		
31:14	Reserved.																		
13	<b>Sleep Enable (SLP_EN)</b> — WO. Setting this bit causes the system to sequence into the Sleep state defined by the SLP_TYP field.																		
12:10	<p><b>Sleep Type (SLP_TYP)</b> — R/W. This 3-bit field defines the type of Sleep the system should enter when the SLP_EN bit is set to 1. These bits are only reset by RTCRST#.</p> <table border="1"> <thead> <tr> <th>Code</th> <th>Master Interrupt</th> </tr> </thead> <tbody> <tr> <td>000b</td> <td>ON: Typically maps to S0 state.</td> </tr> <tr> <td>001b</td> <td>Puts CPU in S1 state.</td> </tr> <tr> <td>010b</td> <td>Reserved</td> </tr> <tr> <td>011b</td> <td>Reserved</td> </tr> <tr> <td>100b</td> <td>Reserved</td> </tr> <tr> <td>101b</td> <td>Suspend-To-RAM. Assert SLP_S3#: Typically maps to S3 state.</td> </tr> <tr> <td>110b</td> <td>Suspend-To-Disk. Assert SLP_S3#, and SLP_S4#: Typically maps to S4 state.</td> </tr> <tr> <td>111b</td> <td>Soft Off. Assert SLP_S3#, SLP_S4#, and SLP_S5#: Typically maps to S5 state.</td> </tr> </tbody> </table>	Code	Master Interrupt	000b	ON: Typically maps to S0 state.	001b	Puts CPU in S1 state.	010b	Reserved	011b	Reserved	100b	Reserved	101b	Suspend-To-RAM. Assert SLP_S3#: Typically maps to S3 state.	110b	Suspend-To-Disk. Assert SLP_S3#, and SLP_S4#: Typically maps to S4 state.	111b	Soft Off. Assert SLP_S3#, SLP_S4#, and SLP_S5#: Typically maps to S5 state.
Code	Master Interrupt																		
000b	ON: Typically maps to S0 state.																		
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010b	Reserved																		
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101b	Suspend-To-RAM. Assert SLP_S3#: Typically maps to S3 state.																		
110b	Suspend-To-Disk. Assert SLP_S3#, and SLP_S4#: Typically maps to S4 state.																		
111b	Soft Off. Assert SLP_S3#, SLP_S4#, and SLP_S5#: Typically maps to S5 state.																		
9:3	Reserved.																		
2	<p><b>Global Release (GBL_RLS)</b> — WO.</p> <p>0 = This bit always reads as 0.                      1 = ACPI software writes a 1 to this bit to raise an event to the BIOS. BIOS software has a corresponding enable and status bits to control its ability to receive ACPI events.</p>																		
1	<p><b>Bus Master Reload (BM_RLD)</b> — R/W. This bit is treated as a scratchpad bit. This bit is reset to 0 by PLTRST#.</p> <p>0 = Bus master requests will not cause a break from the C3 state.                      1 = Enables Bus Master requests (internal or external) to cause a break from the C3 state.                      If software fails to set this bit before going to C3 state, the PCH will still return to a snooperable state from C3 or C4 states due to bus master activity.</p>																		
0	<p><b>SCI Enable (SCI_EN)</b> — R/W. Selects the SCI interrupt or the SMI# interrupt for various events including the bits in the PM1_STS register (bit 10, 8, 0), and bits in GPE0_STS.</p> <p>0 = These events will generate an SMI#.                      1 = These events will generate an SCI.</p>																		



### 13.8.3.4 PM1\_TMR—Power Management 1 Timer Register

I/O Address: PMBASE + 08h

Default Value:	xx000000h	Attribute:	RO
Lockable:	No	Size:	32-bit
Power Well:	Core	Usage:	ACPI

Bit	Description
31:24	Reserved
23:0	<p><b>Timer Value (TMR_VAL)</b> — RO. Returns the running count of the PM timer. This counter runs off a 3.579545 MHz clock (14.31818 MHz divided by 4). It is reset to 0 during a PCI reset, and then continues counting as long as the system is in the S0 state. After an S1 state, the counter will not be reset (it will continue counting from the last value in S0 state).</p> <p>Anytime bit 22 of the timer goes HIGH to LOW (bits referenced from 0 to 23), the TMROF_STS bit (PMBASE + 00h, bit 0) is set. The High-to-Low transition will occur every 2.3435 seconds. If the TMROF_EN bit (PMBASE + 02h, bit 0) is set, an SCI interrupt is also generated.</p>

### 13.8.3.5 GPE0\_STS—General Purpose Event 0a Status Register

I/O Address: PMBASE + 20h

		Attribute:	R/WC; RO
Default Value:	0000000000000000h	Size:	64-bit
Lockable:	No	Usage:	ACPI
Power Well:	Bits 0-34, 56-63: Resume, Bit 35: DSW		

This register is symmetrical to the General Purpose Event 0a Enable Register. Unless indicated otherwise below, if the corresponding \_EN bit is set, then when the \_STS bit get set, the PCH will generate a Wake Event. Once back in an S0 state (or if already in an S0 state when the event occurs), the PCH will also generate an SCI if the SCI\_EN bit is set, or an SMI# if the SCI\_EN bit (PMBASE + 04h, bit 0) is not set.

Bits 15:0 should not be reset by CF9 write. Bits 31:16 are reset by CF9h full resets.

Bit	Description
63:36	Reserved.
35	<p><b>GPIO27_STS</b>— R/WC. 0 = Disable. 1 = Set by hardware and can be reset by writing a one to this bit position or a resume well reset. This bit is set at the level specified in GP27IO_POL. Note that GPIO27 is always monitored as an input for the purpose of setting this bit, regardless of the actual GPIO configuration.</p>
34:32	Reserved.
31:16	<p><b>GPIOn_STS</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. 1 = These bits are set any time the corresponding GPIO is set up as an input and the corresponding GPIO signal is high (or low if the corresponding GP_INV bit is set). If the corresponding enable bit is set in the GPE0_EN register, then when the GPIO[n]_STS bit is set:</p> <ul style="list-style-type: none"> <li>If the system is in an S1–S5 state, the event will also wake the system.</li> <li>If the system is in an S0 state (or upon waking back to an S0 state), a SCI will be caused depending on the GPIO_ROUT bits (D31:F0:B8h, bits 31:30) for the corresponding GPI.</li> </ul> <p><b>Note:</b> Mapping is as follows: bit 31 corresponds to GPIO[15]... and bit 16 corresponds to GPIO[0].</p>
15:14	Reserved



Bit	Description
13	<p><b>Power Management Event Bus 0 Status (PME_B0_STS)</b> — R/WC</p> <p>This bit will be set to 1 by the Intel PCH when any internal device with PCI Power Management capabilities on bus 0 asserts the equivalent of the PME# signal. Additionally, if the PME_B0_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_B0_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_B0_EN bit is set, and the system is in an S1-S4 state (or S5 state due to SLP_TYP and SLP_EN), then the setting of the PME_B0_STS bit will generate a wake event. If the system is in an S5 state due to power button override, then the PME_B0_STS bit will not cause a wake event or SCI.</p> <p>The default for this bit is 0. This bit is cleared by a software write of '1'.</p> <p>The following are internal devices which can set this bit:</p> <ul style="list-style-type: none"> <li>• Intel HD Audio</li> <li>• Intel ME "maskable" wake events</li> <li>• Integrated LAN</li> <li>• SATA</li> <li>• EHCI</li> </ul>
12	Reserved
11	<p><b>PME_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.  1 = Set by hardware when the PME# signal goes active. Additionally, if the PME_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_EN bit is set, and the system is in an S1-S4 state (or S5 state due to setting SLP_TYP and SLP_EN), then the setting of the PME_STS bit will generate a wake event. If the system is in an S5 state due to power button override or a power failure, then PME_STS will not cause a wake event or SCI.</p>
10	Reserved.
9	<p><b>PCI_EXP_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.  1 = Set by hardware to indicate that:</p> <ul style="list-style-type: none"> <li>• The PME event message was received on one or more of the PCI Express* ports</li> <li>• An Assert PMEGPE message received from the Processor using DMI</li> </ul> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The PCI WAKE# pin has no impact on this bit.</li> <li>2. If the PCI_EXP_STS bit went active due to an Assert PMEGPE message, then a Deassert PMEGPE message must be received prior to the software write in order for the bit to be cleared.</li> <li>3. If the bit is not cleared and the corresponding PCI_EXP_EN bit is set, the level-triggered SCI will remain active.</li> <li>4. A race condition exists where the PCI Express* device sends another PME message because the PCI Express* device was not serviced within the time when it must resend the message. This may result in a spurious interrupt, and this is comprehended and approved by the PCI Express* specification. The window for this race condition is approximately 95-105 milliseconds.</li> </ol>
8	<p><b>RI_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.  1 = Set by hardware when the RI# input signal goes active.</p>
7	<p><b>SMBus Wake Status (SMB_WAK_STS)</b> — R/WC. The SMBus controller can independently cause an SMI#, so this bit does not need to do so (unlike the other bits in this register). Software clears this bit by writing a 1 to it.</p> <p>0 = Wake event Not caused by the PCH's SMBus logic.  1 = Set by hardware to indicate that the wake event was caused by the PCH's SMBus logic. This bit will be set by the WAKE/SMI# command type, even if the system is already awake. The SMI handler should then clear this bit.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The SMBus controller will independently cause an SMI# so this bit does not need to do so (unlike the other bits in this register).</li> <li>2. This bit is set by the SMBus slave command 01h (Wake/SMI#) even when the system is in the S0 state. Therefore, to avoid an instant wake on subsequent transitions to sleep states, software must clear this bit after each reception of the Wake/SMI# command or just prior to entering the sleep state.</li> <li>3. The SMBALERT_STS bit (D31:F3:I/O Offset 00h:Bit 5) should be cleared by software before the SMB_WAK_STS bit is cleared.</li> </ol>



Bit	Description
13	<p><b>Power Management Event Bus 0 Status (PME_B0_STS)</b> — R/WC</p> <p>This bit will be set to 1 by the Intel PCH when any internal device with PCI Power Management capabilities on bus 0 asserts the equivalent of the PME# signal. Additionally, if the PME_BO_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_BO_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_BO_EN bit is set, and the system is in an S1-S4 state (or S5 state due to SLP_TYP and SLP_EN), then the setting of the PME_BO_STS bit will generate a wake event. If the system is in an S5 state due to power button override, then the PME_BO_STS bit will not cause a wake event or SCI.</p> <p>The default for this bit is 0. This bit is cleared by a software write of '1'.</p> <p>The following are internal devices which can set this bit:</p> <ul style="list-style-type: none"> <li>• Intel HD Audio</li> <li>• Intel ME "maskable" wake events</li> <li>• Integrated LAN</li> <li>• SATA</li> <li>• EHCI</li> </ul>
12	Reserved
11	<p><b>PME_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware when the PME# signal goes active. Additionally, if the PME_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_EN bit is set, and the system is in an S1-S4 state (or S5 state due to setting SLP_TYP and SLP_EN), then the setting of the PME_STS bit will generate a wake event. If the system is in an S5 state due to power button override or a power failure, then PME_STS will not cause a wake event or SCI.</p>
10	Reserved.
9	<p><b>PCI_EXP_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware to indicate that:</p> <ul style="list-style-type: none"> <li>• The PME event message was received on one or more of the PCI Express* ports</li> <li>• An Assert PMEGPE message received from the Processor using DMI</li> </ul> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The PCI WAKE# pin has no impact on this bit.</li> <li>2. If the PCI_EXP_STS bit went active due to an Assert PMEGPE message, then a Deassert PMEGPE message must be received prior to the software write in order for the bit to be cleared.</li> <li>3. If the bit is not cleared and the corresponding PCI_EXP_EN bit is set, the level-triggered SCI will remain active.</li> <li>4. A race condition exists where the PCI Express* device sends another PME message because the PCI Express* device was not serviced within the time when it must resend the message. This may result in a spurious interrupt, and this is comprehended and approved by the PCI Express* specification. The window for this race condition is approximately 95-105 milliseconds.</li> </ol>
8	<p><b>RI_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware when the RI# input signal goes active.</p>
7	<p><b>SMBus Wake Status (SMB_WAK_STS)</b> — R/WC. The SMBus controller can independently cause an SMI#, so this bit does not need to do so (unlike the other bits in this register). Software clears this bit by writing a 1 to it.</p> <p>0 = Wake event Not caused by the PCH's SMBus logic.</p> <p>1 = Set by hardware to indicate that the wake event was caused by the PCH's SMBus logic. This bit will be set by the WAKE/SMI# command type, even if the system is already awake. The SMI handler should then clear this bit.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The SMBus controller will independently cause an SMI# so this bit does not need to do so (unlike the other bits in this register).</li> <li>2. This bit is set by the SMBus slave command 01h (Wake/SMI#) even when the system is in the S0 state. Therefore, to avoid an instant wake on subsequent transitions to sleep states, software must clear this bit after each reception of the Wake/SMI# command or just prior to entering the sleep state.</li> <li>3. The SMBALERT_STS bit (D31:F3:I/O Offset 00h:Bit 5) should be cleared by software before the SMB_WAK_STS bit is cleared.</li> </ol>



Bit	Description
13	<p><b>Power Management Event Bus 0 Status (PME_B0_STS)</b> — R/WC</p> <p>This bit will be set to 1 by the Intel PCH when any internal device with PCI Power Management capabilities on bus 0 asserts the equivalent of the PME# signal. Additionally, if the PME_B0_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_B0_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_B0_EN bit is set, and the system is in an S1-S4 state (or S5 state due to SLP_TYP and SLP_EN), then the setting of the PME_B0_STS bit will generate a wake event. If the system is in an S5 state due to power button override, then the PME_B0_STS bit will not cause a wake event or SCI.</p> <p>The default for this bit is 0. This bit is cleared by a software write of '1'.</p> <p>The following are internal devices which can set this bit:</p> <ul style="list-style-type: none"> <li>• Intel HD Audio</li> <li>• Intel ME "maskable" wake events</li> <li>• Integrated LAN</li> <li>• SATA</li> <li>• EHCI</li> </ul>
12	Reserved
11	<p><b>PME_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware when the PME# signal goes active. Additionally, if the PME_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_EN bit is set, and the system is in an S1-S4 state (or S5 state due to setting SLP_TYP and SLP_EN), then the setting of the PME_STS bit will generate a wake event. If the system is in an S5 state due to power button override or a power failure, then PME_STS will not cause a wake event or SCI.</p>
10	Reserved.
9	<p><b>PCI_EXP_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware to indicate that:</p> <ul style="list-style-type: none"> <li>• The PME event message was received on one or more of the PCI Express* ports</li> <li>• An Assert PMEGPE message received from the Processor using DMI</li> </ul> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The PCI WAKE# pin has no impact on this bit.</li> <li>2. If the PCI_EXP_STS bit went active due to an Assert PMEGPE message, then a Deassert PMEGPE message must be received prior to the software write in order for the bit to be cleared.</li> <li>3. If the bit is not cleared and the corresponding PCI_EXP_EN bit is set, the level-triggered SCI will remain active.</li> <li>4. A race condition exists where the PCI Express* device sends another PME message because the PCI Express* device was not serviced within the time when it must resend the message. This may result in a spurious interrupt, and this is comprehended and approved by the PCI Express* specification. The window for this race condition is approximately 95-105 milliseconds.</li> </ol>
8	<p><b>RI_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware when the RI# input signal goes active.</p>
7	<p><b>SMBus Wake Status (SMB_WAK_STS)</b> — R/WC. The SMBus controller can independently cause an SMI#, so this bit does not need to do so (unlike the other bits in this register). Software clears this bit by writing a 1 to it.</p> <p>0 = Wake event Not caused by the PCH's SMBus logic.</p> <p>1 = Set by hardware to indicate that the wake event was caused by the PCH's SMBus logic. This bit will be set by the WAKE/SMI# command type, even if the system is already awake. The SMI handler should then clear this bit.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The SMBus controller will independently cause an SMI# so this bit does not need to do so (unlike the other bits in this register).</li> <li>2. This bit is set by the SMBus slave command 01h (Wake/SMI#) even when the system is in the S0 state. Therefore, to avoid an instant wake on subsequent transitions to sleep states, software must clear this bit after each reception of the Wake/SMI# command or just prior to entering the sleep state.</li> <li>3. The SMBALERT_STS bit (D31:F3:I/O Offset 00h:Bit 5) should be cleared by software before the SMB_WAK_STS bit is cleared.</li> </ol>



Bit	Description
13	<p><b>Power Management Event Bus 0 Status (PME_B0_STS)</b> — R/WC</p> <p>This bit will be set to 1 by the Intel PCH when any internal device with PCI Power Management capabilities on bus 0 asserts the equivalent of the PME# signal. Additionally, if the PME_BO_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_BO_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_BO_EN bit is set, and the system is in an S1-S4 state (or S5 state due to SLP_TYP and SLP_EN), then the setting of the PME_BO_STS bit will generate a wake event, If the system is in an S5 state due to power button override, then the PME_BO_STS bit will not cause a wake event or SCI.</p> <p>The default for this bit is 0. This bit is cleared by a software write of '1'.</p> <p>The following are internal devices which can set this bit:</p> <ul style="list-style-type: none"> <li>• Intel HD Audio</li> <li>• Intel ME "maskable" wake events</li> <li>• Integrated LAN</li> <li>• SATA</li> <li>• EHCI</li> </ul>
12	Reserved
11	<p><b>PME_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware when the PME# signal goes active. Additionally, if the PME_EN and SCI_EN bits are set, and the system is in an S0 state, then the setting of the PME_STS bit will generate an SCI (or SMI# if SCI_EN is not set). If the PME_EN bit is set, and the system is in an S1-S4 state (or S5 state due to setting SLP_TYP and SLP_EN), then the setting of the PME_STS bit will generate a wake event. If the system is in an S5 state due to power button override or a power failure, then PME_STS will not cause a wake event or SCI.</p>
10	Reserved.
9	<p><b>PCI_EXP_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware to indicate that:</p> <ul style="list-style-type: none"> <li>• The PME event message was received on one or more of the PCI Express* ports</li> <li>• An Assert PMEGPE message received from the Processor using DMI</li> </ul> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The PCI WAKE# pin has no impact on this bit.</li> <li>2. If the PCI_EXP_STS bit went active due to an Assert PMEGPE message, then a Deassert PMEGPE message must be received prior to the software write in order for the bit to be cleared.</li> <li>3. If the bit is not cleared and the corresponding PCI_EXP_EN bit is set, the level-triggered SCI will remain active.</li> <li>4. A race condition exists where the PCI Express* device sends another PME message because the PCI Express* device was not serviced within the time when it must resend the message. This may result in a spurious interrupt, and this is comprehended and approved by the PCI Express* specification. The window for this race condition is approximately 95-105 milliseconds.</li> </ol>
8	<p><b>RI_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.</p> <p>1 = Set by hardware when the RI# input signal goes active.</p>
7	<p><b>SMBus Wake Status (SMB_WAK_STS)</b> — R/WC. The SMBus controller can independently cause an SMI#, so this bit does not need to do so (unlike the other bits in this register). Software clears this bit by writing a 1 to it.</p> <p>0 = Wake event Not caused by the PCH's SMBus logic.</p> <p>1 = Set by hardware to indicate that the wake event was caused by the PCH's SMBus logic. This bit will be set by the WAKE/SMI# command type, even if the system is already awake. The SMI handler should then clear this bit.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The SMBus controller will independently cause an SMI# so this bit does not need to do so (unlike the other bits in this register).</li> <li>2. This bit is set by the SMBus slave command 01h (Wake/SMI#) even when the system is in the S0 state. Therefore, to avoid an instant wake on subsequent transitions to sleep states, software must clear this bit after each reception of the Wake/SMI# command or just prior to entering the sleep state.</li> <li>3. The SMBALERT_STS bit (D31:F3:I/O Offset 00h:Bit 5) should be cleared by software before the SMB_WAK_STS bit is cleared.</li> </ol>



Bit	Description
6	<b>TCOSCI_STS</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = TOC logic or thermal sensor logic did Not cause SCI. 1 = Set by hardware when the TCO logic or thermal sensor logic causes an SCI.
5:3	Reserved.
2	<b>SWGPE_STS</b> — R/WC. The SWGPE_CTRL bit (bit 1 of GPE_CTRL reg) acts as a level input to this bit.
1	<b>HOT_PLUG_STS</b> — R/WC. 0 = This bit is cleared by writing a 1 to this bit position. 1 = When a PCI Express* Hot-Plug event occurs. This will cause an SCI if the HOT_PLUG_EN and SCI_EN bits are set.
0	Reserved.

### 13.8.3.6 GPE0\_EN—General Purpose Event 0 Enables Register

I/O Address: PMBASE + 28h      Attribute: R/W  
 Default Value: 0000000000000000h      Size: 64-bit  
 Lockable: No      Usage: ACPI  
 Power Well: Bits 0–7, 9, 12, 14–34, 36–63: Resume,  
 Bits 8, 10–11, 13, 35: RTC

This register is symmetrical to the General Purpose Event 0Status Register.

Bit	Description
63:36	Reserved.
35	<b>GPIO27_EN</b> — R/W. 0 = Disable. 1 = Enable the setting of the GPIO27_STS bit to generate a wake event/SCI/SMI#. GPIO27 is a valid host wake event from Deep S4/S5. The wake enable configuration persists after a G3 state. <b>Note:</b> In the Deep S4/S5 state, GPIO27 has no GPIO functionality other than wake enable capability, which is enabled when this bit is set.
34:32	Reserved.
31:16	<b>GPIIn_EN</b> — R/W. These bits enable the corresponding GPI[n]_STS bits being set to cause a SCI, and/or wake event. These bits are cleared by RSMRST#. <b>Note:</b> Mapping is as follows: bit 31 corresponds to GPIO15... and bit 16 corresponds to GPIO0.
15:14	Reserved
13	<b>PME_B0_EN</b> — R/W. 0 = Disable 1 = Enables the setting of the PME_B0_STS bit to generate a wake event and/or an SCI or SMI#. PME_B0_STS can be a wake event from the S1–S4 states, or from S5 (if entered using SLP_TYP and SLP_EN) or power failure, but not Power Button Override. This bit defaults to 0. It is only cleared by Software or RTCRST#. It is not cleared by CF9h writes.
12	Reserved
11	<b>Power Management Event Enable (PME_EN)</b> — R/W. 0 = Disable. 1 = Enables the setting of the PME_STS to generate a wake event and/or an SCI. PME# can be a wake event from the S1 – S4 state or from S5 (if entered using SLP_EN, but not power button override). In addition to being cleared by RTCRST# assertion, the PCH also clears this bit due to a Power Button Override event, Intel ME Initiated Power Button Override, Intel ME Initiated Host Reset with Power down, SMBus unconditional power down, Processor thermal trip event, or due to an internal thermal sensor catastrophic condition.
10	Reserved



Bit	Description
9	<b>PCI Express* Enable (PCI_EXP_EN)</b> — R/W. 0 = Disable SCI generation upon PCI_EXP_STS bit being set. 1 = Enables PCH to cause an SCI when PCI_EXP_STS bit is set. This is used to allow the PCI Express* ports, including the link to the Processor, to cause an SCI due to wake/PME events.
8	<b>RI_EN</b> — R/W. The value of this bit will be maintained through a G3 state and is not affected by a hard reset caused by a CF9h write. 0 = Disable. 1 = Enables the setting of the RI_STS to generate a wake event. In addition to being cleared by RTCRST# assertion, the PCH also clears this bit due to a Power Button Override event, Intel ME Initiated Power Button Override, Intel ME Initiated Host Reset with Power down, SMBus unconditional power down, Processor thermal trip event, or due to an internal thermal sensor catastrophic condition.
7	Reserved
6	<b>TCOSCI_EN</b> — R/W. 0 = Disable. 1 = Enables the setting of the TCOSCI_STS to generate an SCI. In addition to being cleared by RTCRST# assertion, the PCH also clears this bit due to a Power Button Override event, Intel ME Initiated Power Button Override, Intel ME Initiated Host Reset with Power down, SMBus unconditional power down, Processor thermal trip event, or due to an internal thermal sensor catastrophic condition.
5:3	Reserved
2	<b>Software GPE Enable (SWGPE_EN)</b> — R/W. This bit allows software to control the assertion of SWGPE_STS bit. This bit, when set to 1, enables the SW GPE function. If SWGPE_CTRL is written to a 1, hardware will set SWGPE_STS (acts as a level input) If SWGPE_STS, SWGPE_EN, and SCI_EN are all 1's, an SCI will be generated If SWGPE_STS = 1, SWGPE_EN = 1, SCI_EN = 0, and GBL_SMI_EN = 1 then an SMI# will be generated
1	<b>HOT_PLUG_EN</b> — R/W. 0 = Disables SCI generation upon the HOT_PLUG_STS bit being set. 1 = Enables the PCH to cause an SCI when the HOT_PLUG_STS bit is set. This is used to allow the PCI Express* ports to cause an SCI due to hot-plug events.
0	Reserved.

### 13.8.3.7 SMI\_EN—SMI Control and Enable Register

I/O Address:	PMBASE + 30h	Attribute:	R/W, R/WO, WO
Default Value:	00000002h	Size:	32 bit
Lockable:	No	Usage:	ACPI or Legacy
Power Well:	Core		

**Note:** This register is symmetrical to the SMI status register.

Bit	Description
31:28	<b>Reserved</b>
27	<b>GPIO_UNLOCK_SMI_EN</b> — R/WO. Setting this bit will cause the Intel PCH to generate an SMI# when the GPIO_UNLOCK_SMI_STS bit is set in the SMI_STS register. Once written to '1', this bit can only be cleared by PLTRST#.
26:19	Reserved
18	<b>INTEL_USB2_EN</b> — R/W. 0 = Disable 1 = Enables Intel-Specific USB2 SMI logic to cause SMI#.
17	<b>LEGACY_USB2_EN</b> — R/W. 0 = Disable 1 = Enables legacy USB2 logic to cause SMI#.
16:15	Reserved



Bit	Description
14	<b>PERIODIC_EN</b> — R/W. 0 = Disable. 1 = Enables the PCH to generate an SMI# when the PERIODIC_STS bit is set in the SMI_STS register.
13	<b>TCO_EN</b> — R/WL. 0 = Disables TCO logic generating an SMI#. Note that if the NMI2SMI_EN bit is set, SMIs that are caused by re-routed NMIs will not be gated by the TCO_EN bit. Even if the TCO_EN bit is 0, NMIs will still be routed to cause SMIs. 1 = Enables the TCO logic to generate SMI#. <b>Note:</b> This bit cannot be written once the TCO_LOCK bit is set.
12	Reserved
11	<b>MCSMI_EN</b> Microcontroller SMI Enable ( <b>MCSMI_EN</b> ) — R/W. 0 = Disable. 1 = Enables PCH to trap accesses to the microcontroller range (62h or 66h) and generate an SMI#. Note that “trapped” cycles will be claimed by the PCH on PCI, but not forwarded to LPC.
10:8	Reserved
7	<b>BIOS Release (BIOS_RLS)</b> — WO. 0 = This bit will always return 0 on reads. Writes of 0 to this bit have no effect. 1 = Enables the generation of an SCI interrupt for ACPI software when a one is written to this bit position by BIOS software. <b>Note:</b> GBL_STS being set will cause an SCI, even if the SCI_EN bit is not set. Software must take great care not to set the BIOS_RLS bit (which causes GBL_STS to be set) if the SCI handler is not in place.
6	<b>Software SMI# Timer Enable (SWSMI_TMR_EN)</b> — R/W. 0 = Disable. Clearing the SWSMI_TMR_EN bit before the timer expires will reset the timer and the SMI# will not be generated. 1 = Starts Software SMI# Timer. When the SWSMI timer expires (the timeout period depends upon the SWSMI_RATE_SEL bit setting), SWSMI_TMR_STS is set and an SMI# is generated. SWSMI_TMR_EN stays set until cleared by software.
5	<b>APMC_EN</b> — R/W. 0 = Disable. Writes to the APM_CNT register will not cause an SMI#. 1 = Enables writes to the APM_CNT register to cause an SMI#.
4	<b>SLP_SMI_EN</b> ) — R/W. 0 = Disables the generation of SMI# on SLP_EN. Note that this bit must be 0 before the software attempts to transition the system into a sleep state by writing a 1 to the SLP_EN bit. 1 = A write of 1 to the SLP_EN bit (bit 13 in PM1_CNT register) will generate an SMI#, and the system will not transition to the sleep state based on that write to the SLP_EN bit.
3	<b>LEGACY_USB_EN</b> — R/W. 0 = Disable. 1 = Enables legacy USB circuit to cause SMI#.
2	<b>BIOS_EN</b> — R/W. 0 = Disable. 1 = Enables the generation of SMI# when ACPI software writes a 1 to the GBL_RLS bit. Note that if the BIOS_STS bit, which gets set when software writes 1 to GBL_RLS bit, is already a 1 at the time that BIOS_EN becomes 1, an SMI# will be generated when BIOS_EN gets set.
1	<b>End of SMI (EOS)</b> — R/W (special). This bit controls the arbitration of the SMI signal to the processor. This bit must be set for the PCH to assert SMI# low to the processor after SMI# has been asserted previously. 0 = Once the PCH asserts SMI# low, the EOS bit is automatically cleared. 1 = When this bit is set to 1, SMI# signal will be deasserted for 4 PCI clocks before its assertion. In the SMI handler, the processor should clear all pending SMIs (by servicing them and then clearing their respective status bits), set the EOS bit, and exit SMM. This will allow the SMI arbiter to re-assert SMI upon detection of an SMI event and the setting of a SMI status bit. <b>Note:</b> PCH is able to generate 1st SMI after reset even though EOS bit is not set. Subsequent SMI require EOS bit is set.
0	<b>GBL_SMI_EN</b> — R/WL. 0 = No SMI# will be generated by PCH. This bit is reset by a PCI reset event. 1 = Enables the generation of SMI# in the system upon any enabled SMI event. <b>Note:</b> When the SMI_LOCK bit is set, this bit cannot be changed.



### 13.8.3.8 SMI\_STS—SMI Status Register

I/O Address:	PMBASE + 34h	Attribute:	RO, R/WC
Default Value:	00000000h	Size:	32-bit
Lockable:	No	Usage:	ACPI or Legacy
Power Well:	Core		

**Note:** If the corresponding \_EN bit is set when the \_STS bit is set, the Intel PCH will cause an SMI# (except bits 8-10 and 12, which do not need enable bits since they are logic ORs of other registers that have enable bits). The PCH uses the same GPE0\_EN register (I/O address: PMBase+2Ch) to enable/disable both SMI and ACPI SCI general purpose input events. ACPI OS assumes that it owns the entire GPE0\_EN register per the ACPI specification. Problems arise when some of the general-purpose inputs are enabled as SMI by BIOS, and some of the general purpose inputs are enabled for SCI. In this case ACPI OS turns off the enabled bit for any GPIx input signals that are not indicated as SCI general-purpose events at boot, and exit from sleeping states. BIOS should define a dummy control method which prevents the ACPI OS from clearing the SMI GPE0\_EN bits.

Bit	Description
31:28	Reserved
27	<b>GPIO_UNLOCK_SMI_STS</b> — R/WC. This bit will be set if the GPIO registers lockdown logic is requesting an SMI#. Writing a '1' to this bit position clears this bit to '0'.
26	<b>SPI_STS</b> — RO. This bit will be set if the SPI logic is generating an SMI#. This bit is read only because the sticky status and enable bits associated with this function are located in the SPI registers.
25:22	Reserved
21	<b>MONITOR_STS</b> — RO. This bit will be set if the Trap/SMI logic has caused the SMI. This will occur when the processor or a bus master accesses an assigned register (or a sequence of accesses). See Section 10.1.20 through Section 10.1.35 for details on the specific cause of the SMI.
20	<b>PCI_EXP_SMI_STS</b> — RO. PCI Express* SMI event occurred. This could be due to a PCI Express* PME event or Hot-Plug event.
19	Reserved
18	<b>INTEL_USB2_STS</b> — RO. This non-sticky read-only bit is a logical OR of each of the SMI status bits in the Intel-Specific USB2 SMI Status Register ANDed with the corresponding enable bits. This bit will not be active if the enable bits are not set. Writes to this bit will have no effect. All integrated EHCIs are represented with this bit.
17	<b>LEGACY_USB2_STS</b> — RO. This non-sticky read-only bit is a logical OR of each of the SMI status bits in the USB2 Legacy Support Register ANDed with the corresponding enable bits. This bit will not be active if the enable bits are not set. Writes to this bit will have no effect. All integrated EHCIs are represented with this bit.
16	<b>SMBus SMI Status (SMBUS_SMI_STS)</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = This bit is set from the 64 kHz clock domain used by the SMBus. Software must wait at least 15.63 μs after the initial assertion of this bit before clearing it. 1 = Indicates that the SMI# was caused by: 1. The SMBus Slave receiving a message that an SMI# should be caused, or 2. The SMBALERT# signal goes active and the SMB_SMI_EN bit is set and the SMBALERT_DIS bit is cleared, or 3. The SMBus Slave receiving a Host Notify message and the HOST_NOTIFY_INTREN and the SMB_SMI_EN bits are set, or 4. The PCH detecting the SMLINK_SLAVE_SMI command while in the S0 state.
15	<b>SERIRQ_SMI_STS</b> — RO. 0 = SMI# was not caused by the SERIRQ decoder. 1 = Indicates that the SMI# was caused by the SERIRQ decoder. <b>Note:</b> This is not a sticky bit
14	<b>PERIODIC_STS</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = Software clears this bit by writing a 1 to it. 1 = This bit is set at the rate determined by the PER_SMI_SEL bits. If the PERIODIC_EN bit (PMBASE + 30h, bit 14) is also set, the PCH generates an SMI#.



Bit	Description
13	<b>TCO_STS</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = SMI# not caused by TCO logic. 1 = Indicates the SMI# was caused by the TCO logic. Note that this is not a wake event.
12	<b>Device Monitor Status (DEVMON_STS)</b> — RO. 0 = SMI# not caused by Device Monitor. 1 = Set if bit 0 of the DEVACT_STS register (PMBASE + 44h) is set. The bit is not sticky, so writes to this bit will have no effect.
11	<b>Microcontroller SMI# Status (MCSMI_STS)</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = Indicates that there has been no access to the power management microcontroller range (62h or 66h). 1 = Set if there has been an access to the power management microcontroller range (62h or 66h) and the Microcontroller Decode Enable #1 bit in the LPC Bridge I/O Enables configuration register is 1 (D31:F0:Offset 82h:bit 11). Note that this implementation assumes that the Microcontroller is on LPC. If this bit is set, and the MCSMI_EN bit is also set, the PCH will generate an SMI#.
10	<b>GPE0_STS</b> — RO. This bit is a logical OR of the bits in the ALT_GP_SMI_STS register that are also set up to cause an SMI# (as indicated by the GPI_ROUT registers) and have the corresponding bit set in the ALT_GP_SMI_EN register. Bits that are not routed to cause an SMI# will have no effect on this bit. 0 = SMI# was not generated by a GPI assertion. 1 = SMI# was generated by a GPI assertion.
9	<b>GPE0_STS</b> — RO. This bit is a logical OR of the bits 47:32, 14:10, 8, 6:2, and 0 in the GPE0_STS register (PMBASE + 28h) that also have the corresponding bit set in the GPE0_EN register (PMBASE + 2Ch). 0 = SMI# was not generated by a GPE0 event. 1 = SMI# was generated by a GPE0 event.
8	<b>PM1_STS_REG</b> — RO. This is an ORs of the bits in the ACPI PM1 Status Register (offset PMBASE+00h) that can cause an SMI#. 0 = SMI# was not generated by a PM1_STS event. 1 = SMI# was generated by a PM1_STS event.
7	Reserved
6	<b>SWSMI_TMR_STS</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = Software SMI# Timer has Not expired. 1 = Set by the hardware when the Software SMI# Timer expires.
5	<b>APM_STS</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = No SMI# generated by write access to APM Control register with APMCH_EN bit set. 1 = SMI# was generated by a write access to the APM Control register with the APMC_EN bit set.
4	<b>SLP SMI Status (SLP_SMI_STS)</b> — R/WC This bit will be set by the Intel PCH when a write access attempts to set the SLP_EN bit. This bit is cleared by writing a 1 to this bit position
3	<b>LEGACY_USB_STS</b> — RO. This bit is a logical OR of each of the SMI status bits in the USB Legacy Keyboard/Mouse Control Registers ANDed with the corresponding enable bits. This bit will not be active if the enable bits are not set. 0 = SMI# was not generated by USB Legacy event. 1 = SMI# was generated by USB Legacy event.
2	<b>BIOS_STS</b> — R/WC. 0 = No SMI# generated due to ACPI software requesting attention. 1 = This bit gets set by hardware when a 1 is written by software to the GBL_RLS bit (D31:F0:PMBase + 04h:bit 2). When both the BIOS_EN bit (D31:F0:PMBase + 30h:bit 2) and the BIOS_STS bit are set, an SMI# will be generated. The BIOS_STS bit is cleared when software writes a 1 to its bit position.
1:0	Reserved



### 13.8.3.9 ALT\_GP\_SMI\_EN—Alternate GPI SMI Enable Register

I/O Address:	PMBASE + 38h	Attribute:	R/W
Default Value:	0000h	Size:	16-bit
Lockable:	No	Usage:	ACPI or Legacy
Power Well:	Resume		

Bit	Description
15:0	<p><b>Alternate GPI Intel SMI Enable</b> — R/W. These bits are used to enable the corresponding GPIO to cause an SMI#. For these bits to have any effect, the following must be true.</p> <ul style="list-style-type: none"> <li>The corresponding bit in the ALT_GP_SMI_EN register is set.</li> <li>The corresponding GPI must be routed in the GPI_ROUT register to cause an Intel SMI.</li> <li>The corresponding GPIO must be implemented.</li> </ul> <p><b>Note:</b> Mapping is as follows: bit 15 corresponds to GPIO15... bit 0 corresponds to GPIO0.</p>

### 13.8.3.10 ALT\_GP\_SMI\_STS—Alternate GPI SMI Status Register

I/O Address:	PMBASE + 3Ah	Attribute:	R/WC
Default Value:	0000h	Size:	16-bit
Lockable:	No	Usage:	ACPI or Legacy
Power Well:	Resume		

Bit	Description
15:0	<p><b>Alternate GPI SMI Status</b> — R/WC. These bits report the status of the corresponding GPIOs. 0 = Inactive. Software clears this bit by writing a 1 to it. 1 = Active</p> <p>These bits are sticky. If the following conditions are true, then an SMI# will be generated and the GPE0_STS bit set:</p> <ul style="list-style-type: none"> <li>The corresponding bit in the ALT_GP_SMI_EN register (PMBASE + 38h) is set</li> <li>The corresponding GPIO must be routed in the GPI_ROUT register to cause an SMI.</li> <li>The corresponding GPIO must be implemented.</li> </ul> <p>All bits are in the resume well. Default for these bits is dependent on the state of the GPIO pins.</p>

### 13.8.3.11 UPRWC—USB Per-Port Registers Write Control Register

I/O Address:	PMBASE + 3Ch	Attribute:	R/WC, R/W, R/WO
Default Value:	0000h	Size:	16-bit
Lockable:	No	Usage:	ACPI or Legacy
Power Well:	Resume		

Bit	Description
15:9	Reserved
8	<p><b>Write Enable Status</b> — R/WC</p> <p>0 = This bit gets set by hardware when the “Per-Port Registers Write Enable” bit is written from 0 to 1</p> <p>1 = This bit is cleared by software writing a 1b to this bit location</p> <p>The setting condition takes precedence over the clearing condition in the event that both occur at once.</p> <p>When this bit is 1b and bit 0 is 1b, the INTEL_USB2_STS bit is set in the SMI_STS register.</p>
7:1	Reserved.
1	Reserved
0	<p><b>Write Enable SMI Enable</b>— R/WO</p> <p>0 = Disable</p> <p>1 = enables the generation of SMI when the Per-Port Registers Write Enable (bit 1) is written from 0 to 1. Once written to 1b, this bit can not be cleared by software.</p>



### 13.8.3.12 GPE\_CNTL— General Purpose Control Register

I/O Address:	PMBASE +42h	Attribute:	R/W
Default Value:	00h	Size:	8-bit
Lockable:	No	Usage:	ACPI or Legacy
Power Well:	Bits 0-1, 3-7: Resume Bit 2: RTC		

Bit	Description
7:3	Reserved
2	<p><b>GPIO27_POL</b> — R/W. This bit controls the polarity of the GPIO27 pin needed to set the GPIO27_STS bit.</p> <p>0 = GPIO27 = 0 will set the GPIO27_STS bit. 1 = GPIO27 = 1 will set the GPIO27_STS bit.</p> <p><b>Note:</b> This bit is cleared by RTCRST# assertion.</p>
1	<p><b>SWGPE_CTRL</b>— R/W. This bit allows software to control the assertion of SWGPE_STS bit. This bit is used by hardware as the level input signal for the SWGPE_STS bit in the GPE0_STS register. When SWGPE_CTRL is 1, SWGPE_STS will be set to 1, and writes to SWGPE_STS with a value of 1 to clear SWGPE_STS will result in SWGPE_STS being set back to 1 by hardware. When SWGPE_CTRL is 0, writes to SWGPE_STS with a value of 1 will clear SWGPE_STS to 0.</p> <p>In addition to being cleared by RSMRST# assertion, the PCH also clears this bit due to a Power Button Override event, Intel ME Initiated Power Button Override, Intel ME Initiated Host Reset with Power down, SMBus unconditional power down, Processor thermal trip event, or due to an internal thermal sensor catastrophic condition.</p>
0	Reserved.



### 13.8.3.13 DEVACT\_STS — Device Activity Status Register

I/O Address:	PMBASE + 44h	Attribute:	R/WC
Default Value:	0000h	Size:	16-bit
Lockable:	No	Usage:	Legacy Only
Power Well:	Core		

Each bit indicates if an access has occurred to the corresponding device's trap range, or for bits 6:9 if the corresponding PCI interrupt is active. This register is used in conjunction with the Periodic SMI# timer to detect any system activity for legacy power management. The periodic SMI# timer indicates if it is the right time to read the DEVACT\_STS register (PMBASE + 44h).

**Note:** Software clears bits that are set in this register by writing a 1 to the bit position.

Bit	Description
15:13	Reserved
12	<b>KBC_ACT_STS</b> — R/WC. KBC (60/64h). 0 = Indicates that there has been no access to this device's I/O range. 1 = This device's I/O range has been accessed. Clear this bit by writing a 1 to the bit location.
11:10	Reserved
9	<b>PRIQDH_ACT_STS</b> — R/WC. PIRQ[D or H]. 0 = The corresponding PCI interrupts have not been active. 1 = At least one of the corresponding PCI interrupts has been active. Clear this bit by writing a 1 to the bit location.
8	<b>PIRQCG_ACT_STS</b> — R/WC. PIRQ[C or G]. 0 = The corresponding PCI interrupts have not been active. 1 = At least one of the corresponding PCI interrupts has been active. Clear this bit by writing a 1 to the bit location.
7	<b>PIRQBF_ACT_STS</b> — R/WC. PIRQ[B or F]. 0 = The corresponding PCI interrupts have not been active. 1 = At least one of the corresponding PCI interrupts has been active. Clear this bit by writing a 1 to the bit location.
6	<b>PIRQAE_ACT_STS</b> — R/WC. PIRQ[A or E]. 0 = The corresponding PCI interrupts have not been active. 1 = At least one of the corresponding PCI interrupts has been active. Clear this bit by writing a 1 to the bit location.
5:0	Reserved

### 13.8.3.14 PM2\_CNT—Power Management 2 Control

I/O Address:	PMBASE + 50h	Attribute:	R/W
Default Value:	00h	Size:	8-bit
Lockable:	No	Usage:	ACPI
Power Well:	Core		

Bit	Description
7:1	Reserved
0	<b>Arbiter Disable (ARB_DIS)</b> — R/W This bit is a scratchpad bit for legacy software compatibility.



## 13.9 System Management TCO Registers

The TCO logic is accessed using registers mapped to the PCI configuration space (Device 31:Function 0) and the system I/O space. For TCO PCI Configuration registers, see LPC Device 31:Function 0 PCI Configuration registers.

### TCO Register I/O Map

The TCO I/O registers reside in a 32-byte range pointed to by a TCOBASE value, which is, PMBASE + 60h in the PCI config space. The following table shows the mapping of the registers within that 32-byte range. Each register is described in the following sections.

**Table 13-12. TCO I/O Register Address Map**

TCOBASE + Offset	Mnemonic	Register Name	Default	Type
00h–01h	TCO_RLD	TCO Timer Reload and Current Value	0000h	R/W
02h	TCO_DAT_IN	TCO Data In	00h	R/W
03h	TCO_DAT_OUT	TCO Data Out	00h	R/W
04h–05h	TCO1_STS	TCO1 Status	0000h	R/WC, RO
06h–07h	TCO2_STS	TCO2 Status	0000h	R/WC
08h–09h	TCO1_CNT	TCO1 Control	0000h	R/W, R/WLO, R/WC
0Ah–0Bh	TCO2_CNT	TCO2 Control	0008h	R/W
0Ch–0Dh	TCO_MESSAGE1, TCO_MESSAGE2	TCO Message 1 and 2	00h	R/W
0Eh	TCO_WDCNT	Watchdog Control	00h	R/W
0Fh	—	Reserved	—	—
10h	SW_IRQ_GEN	Software IRQ Generation	03h	R/W
11h	—	Reserved	—	—
12h–13h	TCO_TMR	TCO Timer Initial Value	0004h	R/W
14h–1Fh	—	Reserved	—	—



### 13.9.1 TCO\_RLD—TCO Timer Reload and Current Value Register

I/O Address: TCOBASE +00h      Attribute: R/W  
 Default Value: 0000h      Size: 16-bit  
 Lockable: No      Power Well: Core

Bit	Description
15:10	Reserved
9:0	<b>TCO Timer Value</b> — R/W. Reading this register will return the current count of the TCO timer. Writing any value to this register will reload the timer to prevent the timeout.

### 13.9.2 TCO\_DAT\_IN—TCO Data In Register

I/O Address: TCOBASE +02h      Attribute: R/W  
 Default Value: 00h      Size: 8-bit  
 Lockable: No      Power Well: Core

Bit	Description
7:0	<b>TCO Data In Value</b> — R/W. This data register field is used for passing commands from the OS to the SMI handler. Writes to this register will cause an SMI and set the SW_TCO_SMI bit in the TCO1_STS register (D31:F0:04h).

### 13.9.3 TCO\_DAT\_OUT—TCO Data Out Register

I/O Address: TCOBASE +03h      Attribute: R/W  
 Default Value: 00h      Size: 8-bit  
 Lockable: No      Power Well: Core

Bit	Description
7:0	<b>TCO Data Out Value</b> — R/W. This data register field is used for passing commands from the Intel SMI handler to the OS. Writes to this register will set the TCO_INT_STS bit in the TCO1_STS register. It will also cause an interrupt, as selected by the TCO_INT_SEL bits.

### 13.9.4 TCO1\_STS—TCO1 Status Register

I/O Address: TCOBASE +04h      Attribute: R/WC, RO  
 Default Value: 2000h      Size: 16-bit  
 Lockable: No      Power Well: Core  
 (Except bit 7, in RTC)

Bit	Description
15:14	Reserved
13	<b>TCO_SLVSEL (TCO Slave Select)</b> — RO. This register bit is Read Only by Host and indicates the value of TCO Slave Select Soft Strap. Refer to the PCH Soft Straps section of the SPI Chapter for details.
12	<b>DMISERR_STS</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. 1 = PCH received a DMI special cycle message using DMI indicating that it wants to cause an SERR#. The software must read the Processor to determine the reason for the SERR#.
11	Reserved
10	<b>DMISMI_STS</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. 1 = PCH received a DMI special cycle message using DMI indicating that it wants to cause an SMI. The software must read the Processor to determine the reason for the SMI.



Bit	Description
9	<p><b>DMISCI_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = PCH received a DMI special cycle message using DMI indicating that it wants to cause an SCI. The software must read the Processor to determine the reason for the SCI.</p>
8	<p><b>BIOSWR_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = PCH sets this bit and generates and SMI# to indicate an invalid attempt to write to the BIOS. This occurs when either:            a) The BIOSWP bit is changed from 0 to 1 and the BLD bit is also set, or            b) any write is attempted to the BIOS and the BIOSWP bit is also set.</p> <p><b>Note:</b> On write cycles attempted to the 4 MB lower alias to the BIOS space, the BIOSWR_STS will not be set.</p>
7	<p><b>NEWCENTURY_STS</b> — R/WC. This bit is in the RTC well.</p> <p>0 = Cleared by writing a 1 to the bit position or by RTCRST# going active.            1 = This bit is set when the Year byte (RTC I/O space, index offset 09h) rolls over from 99 to 00. Setting this bit will cause an SMI# (but not a wake event).</p> <p><b>Note:</b> The NEWCENTURY_STS bit is not valid when the RTC battery is first installed (or when RTC power has not been maintained). Software can determine if RTC power has not been maintained by checking the RTC_PWR_STS bit (D31:F0:A4h, bit 2), or by other means (such as a checksum on RTC RAM). If RTC power is determined to have not been maintained, BIOS should set the time to a valid value and then clear the NEWCENTURY_STS bit.</p> <p>The NEWCENTURY_STS bit may take up to 3 RTC clocks for the bit to be cleared after a 1 is written to the bit to clear it. After writing a 1 to this bit, software should not exit the SMI handler until verifying that the bit has actually been cleared. This will ensure that the SMI is not re-entered.</p>
6:4	Reserved
3	<p><b>TIMEOUT</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = Set by PCH to indicate that the SMI was caused by the TCO timer reaching 0.</p>
2	<p><b>TCO_INT_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = SMI handler caused the interrupt by writing to the TCO_DAT_OUT register (TCOBASE + 03h).</p>
1	<p><b>SW_TCO_SMI</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it.            1 = Software caused an SMI# by writing to the TCO_DAT_IN register (TCOBASE + 02h).</p>
0	<p><b>NMI2SMI_STS</b> — RO.</p> <p>0 = Cleared by clearing the associated NMI status bit.            1 = Set by the PCH when an SMI# occurs because an event occurred that would otherwise have caused an NMI (because NMI2SMI_EN is set).</p>



### 13.9.5 TCO2\_STS—TCO2 Status Register

I/O Address:	TCOBASE +06h	Attribute:	R/WC
Default Value:	0000h	Size:	16-bit
Lockable:	No	Power Well:	Resume (Except Bit 0, in RTC)

Bit	Description
15:5	Reserved
4	<p><b>SMLink Slave Intel SMI Status (SMLINK_SLV_SMI_STS)</b> — R/WC. Allow the software to go directly into a pre-determined sleep state. This avoids race conditions. Software clears this bit by writing a 1 to it.</p> <p>0 = The bit is reset by RSMRST#, but not due to the PCI Reset associated with exit from S3–S5 states.</p> <p>1 = PCH sets this bit to 1 when it receives the Intel SMI message on the SMLink Slave Interface.</p>
3	Reserved
2	<p><b>BOOT_STS</b> — R/WC.</p> <p>0 = Cleared by PCH based on RSMRST# or by software writing a 1 to this bit. Note that software should first clear the SECOND_TO_STS bit before writing a 1 to clear the BOOT_STS bit.</p> <p>1 = Set to 1 when the SECOND_TO_STS bit goes from 0 to 1 and the processor has not fetched the first instruction.</p> <p>If rebooting due to a second TCO timer timeout, and if the BOOT_STS bit is set, the PCH will reboot using the 'safe' multiplier (1111). This allows the system to recover from a processor frequency multiplier that is too high, and allows the BIOS to check the BOOT_STS bit at boot. If the bit is set and the frequency multiplier is 1111, then the BIOS knows that the processor has been programmed to an invalid multiplier.</p>
1	<p><b>SECOND_TO_STS</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it, or by a RSMRST#.</p> <p>1 = PCH sets this bit to 1 to indicate that the TIMEOUT bit had been (or is currently) set and a second timeout occurred before the TCO_RLD register was written. If this bit is set and the NO_REBOOT config bit is 0, then the PCH will reboot the system after the second timeout. The reboot is done by asserting PLTRST#.</p>
0	<p><b>Intruder Detect (INTRD_DET)</b> — R/WC.</p> <p>0 = Software clears this bit by writing a 1 to it, or by RTCRST# assertion.</p> <p>1 = Set by PCH to indicate that an intrusion was detected. This bit is set even if the system is in G3 state.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This bit has a recovery time. After writing a 1 to this bit position (to clear it), the bit may be read back as a 1 for up to 65 microseconds before it is read as a 0. Software must be aware of this recovery time when reading this bit after clearing it.</li> <li>If the INTRUDER# signal is active when the software attempts to clear the INTRD_DET bit, the bit will remain as a 1, and the SMI# will be generated again immediately. The SMI handler can clear the INTRD_SEL bits (TCOBASE + 0Ah, bits 2:1), to avoid further SMIs. However, if the INTRUDER# signal goes inactive and then active again, there will not be further SMI's (because the INTRD_SEL bits would select that no SMI# be generated).</li> <li>If the INTRUDER# signal goes inactive some point after the INTRD_DET bit is written as a 1, then the INTRD_DET signal will go to a 0 when INTRUDER# input signal goes inactive. Note that this is slightly different than a classic sticky bit, since most sticky bits would remain active indefinitely when the signal goes active and would immediately go inactive when a 1 is written to the bit.</li> </ol>



### 13.9.6 TCO1\_CNT—TCO1 Control Register

I/O Address: TCOBASE +08h      Attribute: R/W, R/WLO, R/WC  
 Default Value: 0000h      Size: 16-bit  
 Lockable: No      Power Well: Core

Bit	Description															
15:13	Reserved															
12	<b>TCO_LOCK</b> — R/WLO. When set to 1, this bit prevents writes from changing the TCO_EN bit (in offset 30h of Power Management I/O space). Once this bit is set to 1, it can not be cleared by software writing a 0 to this bit location. A core-well reset is required to change this bit from 1 to 0. This bit defaults to 0.															
11	<b>TCO Timer Halt (TCO_TMR_HLT)</b> — R/W. 0 = The TCO Timer is enabled to count. 1 = The TCO Timer will halt. It will not count, and thus cannot reach a value that will cause an SMI# or set the SECOND_TO_STS bit. When set, this bit will prevent rebooting and prevent Alert On LAN event messages from being transmitted on the SMLink (but not Alert On LAN* heartbeat messages).															
10	Reserved															
9	<b>NMI2SMI_EN</b> — R/W. 0 = Normal NMI functionality. 1 = Forces all NMIs to instead cause SMIs. The functionality of this bit is dependent upon the settings of the NMI_EN bit and the GBL_SMI_EN bit as detailed in the following table: <table border="1" style="margin-left: 40px; margin-top: 10px;"> <thead> <tr> <th>NMI_EN</th> <th>GBL_SMI_EN</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0b</td> <td>0b</td> <td>No SMI# at all because GBL_SMI_EN = 0</td> </tr> <tr> <td>0b</td> <td>1b</td> <td>SMI# will be caused due to NMI events</td> </tr> <tr> <td>1b</td> <td>0b</td> <td>No SMI# at all because GBL_SMI_EN = 0</td> </tr> <tr> <td>1b</td> <td>1b</td> <td>No SMI# due to NMI because NMI_EN = 1</td> </tr> </tbody> </table>	NMI_EN	GBL_SMI_EN	Description	0b	0b	No SMI# at all because GBL_SMI_EN = 0	0b	1b	SMI# will be caused due to NMI events	1b	0b	No SMI# at all because GBL_SMI_EN = 0	1b	1b	No SMI# due to NMI because NMI_EN = 1
NMI_EN	GBL_SMI_EN	Description														
0b	0b	No SMI# at all because GBL_SMI_EN = 0														
0b	1b	SMI# will be caused due to NMI events														
1b	0b	No SMI# at all because GBL_SMI_EN = 0														
1b	1b	No SMI# due to NMI because NMI_EN = 1														
8	<b>NMI_NOW</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. The NMI handler is expected to clear this bit. Another NMI will not be generated until the bit is cleared. 1 = Writing a 1 to this bit causes an NMI. This allows the BIOS or SMI handler to force an entry to the NMI handler.															
7:0	Reserved															

### 13.9.7 TCO2\_CNT—TCO2 Control Register

I/O Address: TCOBASE +0Ah      Attribute: R/W  
 Default Value: 0008h      Size: 16-bit  
 Lockable: No      Power Well: Resume

Bit	Description
15:6	Reserved
5:4	<b>OS_POLICY</b> — R/W. OS-based software writes to these bits to select the policy that the BIOS will use after the platform resets due the WDT. The following convention is recommended for the BIOS and OS: 00 = Boot normally 01 = Shut down 10 = Do not load OS. Hold in pre-boot state and use LAN to determine next step 11 = Reserved  <b>Note:</b> These are just scratchpad bits. They should not be reset when the TCO logic resets the platform due to Watchdog Timer.



Bit	Description
3	<b>GPIO11_ALERT_DISABLE</b> — R/W. At reset (using RSMRST# asserted) this bit is set and GPIO[11] alerts are disabled. 0 = Enable. 1 = Disable GPIO11/SMBALERT# as an alert source for the heartbeats and the SMBus slave.
2:1	<b>INTRD_SEL</b> — R/W. This field selects the action to take if the INTRUDER# signal goes active. 00 = No interrupt or SMI# 01 = Interrupt (as selected by TCO_INT_SEL). 10 = Intel SMI 11 = Reserved
0	Reserved

### 13.9.8 TCO\_MESSAGE1 and TCO\_MESSAGE2 Registers

I/O Address: TCOBASE + 0Ch (Message 1) Attribute: R/W  
TCOBASE + 0Dh (Message 2)  
Default Value: 00h Size: 8-bit  
Lockable: No Power Well: Resume

Bit	Description
7:0	<b>TCO_MESSAGE[n]</b> — R/W. BIOS can write into these registers to indicate its boot progress. The external microcontroller can read these registers to monitor the boot progress.

### 13.9.9 TCO\_WDCNT—TCO Watchdog Control Register

Offset Address: TCOBASE + 0Eh Attribute: R/W  
Default Value: 00h Size: 8 bits  
Power Well: Resume

Bit	Description
7:0	The BIOS or system management software can write into this register to indicate more details on the boot progress. The register will reset to 00h based on a RSMRST# (but not PLTRST#). The external microcontroller can read this register to monitor boot progress.

### 13.9.10 SW\_IRQ\_GEN—Software IRQ Generation Register

Offset Address: TCOBASE + 10h Attribute: R/W  
Default Value: 03h Size: 8 bits  
Power Well: Core

Bit	Description
7:2	Reserved
1	<b>IRQ12_CAUSE</b> — R/W. When software sets this bit to 1, IRQ12 will be asserted. When software sets this bit to 0, IRQ12 will be deasserted.
0	<b>IRQ1_CAUSE</b> — R/W. When software sets this bit to 1, IRQ1 will be asserted. When software sets this bit to 0, IRQ1 will be deasserted.



### 13.9.11 TCO\_TMR—TCO Timer Initial Value Register

I/O Address:	TCOBASE + 12h	Attribute:	R/W
Default Value:	0004h	Size:	16-bit
Lockable:	No	Power Well:	Core

Bit	Description
15:10	Reserved
9:0	<p><b>TCO Timer Initial Value</b> — R/W. Value that is loaded into the timer each time the TCO_RLD register is written. Values of 0000h or 0001h will be ignored and should not be attempted. The timer is clocked at approximately 0.6 seconds, and thus allows timeouts ranging from 1.2 second to 613.8 seconds.</p> <p><b>Note:</b> The timer has an error of <math>\pm 1</math> tick (0.6s). The TCO Timer will only count down in the S0 state.</p>

## 13.10 General Purpose I/O Registers (D31:F0)

The control for the general purpose I/O signals is handled through a 128-byte I/O space. The base offset for this space is selected by the GPIOBASE register.

**Table 13-13. Registers to Control GPIO Address Map**

GPIOBASE + Offset	Mnemonic	Register Name	Default	Access
00h–03h	GPIO_USE_SEL	GPIO Use Select	BF7FA1FFh	R/W
04h–07h	GP_IO_SEL	GPIO Input/Output Select	E8EB6EFFh	R/W
08h–0Bh	—	Reserved	0h	—
0Ch–0Fh	GP_LVL	GPIO Level for Input or Output	02FE0100h	R/W
10h–13h	—	Reserved	0h	—
14h–17h	—	Reserved	0h	—
18h–1Bh	GPO_BLINK	GPIO Blink Enable	00040000h	R/W
1Ch–1Fh	GP_SER_BLINK	GP Serial Blink	00000000h	R/W
20–23h	GP_SB_CMDSTS	GP Serial Blink Command Status	00080000h	R/W
24–27h	GP_SB_DATA	GP Serial Blink Data	00000000h	R/W
28–29h	GPI_NMI_EN	GPI NMI Enable	0000	R/W
2A–2Bh	GPI_NMI_STS	GPI NMI Status	0000	R/WC
2C–2Fh	GPI_INV	GPIO Signal Invert	00000000h	R/W
30h–33h	GPIO_USE_SEL2	GPIO Use Select 2	020300FFh	R/W
34h–37h	GP_IO_SEL2	GPIO Input/Output Select 2	1F57FFF4h	R/W
38h–3Bh	GP_LVL2	GPIO Level for Input or Output 2	A4AA0007h	R/W
3Ch–3Fh	—	Reserved	0h	—
40h–43h	GPIO_USE_SEL3	GPIO Use Select 3	0000033Fh	R/W
44h–47h	GP_IO_SEL3	GPIO Input/Output Select 3	00000FF0h	R/W
48h–4Bh	GP_LVL3	GPIO Level for Input or Output 3	000000C0h	R/W
4Ch–5Fh	—	Reserved	0h	—
60h–63h	GP_RST_SEL1	GPIO Reset Select 1	01000000h	R/W
64h–67h	GP_RST_SEL2	GPIO Reset Select 2	0h	R/W
68h–6Bh	GP_RST_SEL3	GPIO Reset Select 3	0h	R/W
6Ch–7Fh	—	Reserved	0h	—



### 13.10.1 GPIO\_USE\_SEL—GPIO Use Select Register

Offset Address:	GPIOBASE + 00h	Attribute:	R/W
Default Value:	BF7FA1FFh	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16:23, Resume for 8: 15, 24:31

Bit	Description
31:0	<p><b>GPIO_USE_SEL[31:0]</b> — R/W. Each bit in this register enables the corresponding GPIO (if it exists) to be used as a GPIO, rather than for the native function. 0 = Signal used as native function. 1 = Signal used as a GPIO.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>The following bits are always 1 because they are always unMultiplexed: 8, 15, 24, 27, and 28.</li> <li>After a full reset (RSMRST#) all multiplexed signals in the resume and core wells are configured as their default function. After only a PLTRST#, the GPIOs in the core well are configured as their default function.</li> <li>When configured to GPIO mode, the muxing logic will present the inactive state to native logic that uses the pin as an input.</li> <li>By default, all GPIOs are reset to the default state by CF9h reset except GPIO24. Other resume well GPIOs' reset behavior can be programmed using GP_RST_SEL registers.</li> <li>Bit 26 may be overridden by bit 8 in the GEN_PMCON_3 Register.</li> <li>Bit 29 can be configured to GPIO when SLP_LAN#/GPIO29 Select Soft-strap is set to 1 (GPIO usage).</li> </ol>

### 13.10.2 GP\_IO\_SEL—GPIO Input/Output Select Register

Offset Address:	GPIOBASE +04h	Attribute:	R/W
Default Value:	E8EB6EFFh	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16:23, Resume for 8: 15, 24:31

Bit	Description
31:0	<p><b>GP_IO_SEL[31:0]</b> — R/W.</p> <p>When configured in native mode (GPIO_USE_SEL[n] is 0), writes to these bits have no effect. The value reported in this register is undefined when programmed as native mode. 0 = Output. The corresponding GPIO signal is an output. 1 = Input. The corresponding GPIO signal is an input.</p>



### 13.10.3 GP\_LVL—GPIO Level for Input or Output Register

Offset Address:	GPIOBASE +0Ch	Attribute:	R/W
Default Value:	02FE0100h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16:23, Resume for 8: 15, 24: 31

Bit	Description
31:0	<p><b>GP_LVL[31:0]</b>— R/W.</p> <p>These registers are implemented as dual read/write with dedicated storage each. Write value will be stored in the write register, while read is coming from the read register which will always reflect the value of the pin.</p> <p>If GPIO[n] is programmed to be an output (using the corresponding bit in the GP_IO_SEL register), then the corresponding GP_LVL[n] write register value will drive a high or low value on the output pin. 1 = high, 0 = low.</p> <p>When configured in native mode (GPIO_USE_SEL[n] is 0), writes to these bits are stored but have no effect to the pin value. The value reported in this register is undefined when programmed as native mode.</p> <p><b>Note:</b> Bit 29 setting will be ignored if Intel ME FW is configuring SLP_LAN# behavior. When GPIO29/SLP_LAN# Select Soft-strap is set to 1 (GPIO usage), bit 29 can be used as regular GP_LVL bit.</p>

### 13.10.4 GPO\_BLINK—GPO Blink Enable Register

Offset Address:	GPIOBASE +18h	Attribute:	R/W
Default Value:	00040000h	Size:	32-bit
Lockable:	No	Power Well:	Core for 0: 7, 16:23, Resume for 8: 15, 24: 31

Bit	Description
31:0	<p><b>GP_BLINK[31:0]</b> — R/W. The setting of this bit has no effect if the corresponding GPIO signal is programmed as an input.</p> <p>0 = The corresponding GPIO will function normally.</p> <p>1 = If the corresponding GPIO is programmed as an output, the output signal will blink at a rate of approximately once per second. The high and low times have approximately 0.5 seconds each. The GP_LVL bit is not altered when this bit is set.</p> <p>The value of the corresponding GP_LVL bit remains unchanged during the blink process, and does not effect the blink in any way. The GP_LVL bit is not altered when programmed to blink. It will remain at its previous value.</p> <p>These bits correspond to GPIO in the Resume well. These bits revert to the default value based on RSMRST# or a write to the CF9h register (but not just on PLTRST#).</p>

**Note:** GPIO18 will blink by default immediately after reset. This signal could be connected to an LED to indicate a failed boot (by programming BIOS to clear GP\_BLINK18 after successful POST).



### 13.10.5 GP\_SER\_BLINK—GP Serial Blink

Offset Address:	GPIOBASE +1Ch	Attribute:	R/W
Default Value:	00000000h	Size:	32-bit
Lockable:	No	Power Well:	Core for 0: 7, 16: 23, Resume for 8: 15, 24: 31

Bit	Description
31:0	<p><b>GP_SER_BLINK[31:0]</b> — R/W. The setting of this bit has no effect if the corresponding GPIO is programmed as an input or if the corresponding GPIO has the GPO_BLINK bit set. When set to a '0', the corresponding GPIO will function normally.</p> <p>When using serial blink, this bit should be set to a 1 while the corresponding GP_IO_SEL bit is set to 1. Setting the GP_IO_SEL bit to 0 after the GP_SER_BLINK bit ensures PCH will not drive a 1 on the pin as an output. When this corresponding bit is set to a 1 and the pin is configured to output mode, the serial blink capability is enabled. The PCH will serialize messages through an open-drain buffer configuration.</p> <p>The value of the corresponding GP_LVL bit remains unchanged and does not impact the serial blink capability in any way.</p> <p>Writes to this register have no effect when the corresponding pin is configured in native mode and the read value returned is undefined.</p>

### 13.10.6 GP\_SB\_CMDSTS—GP Serial Blink Command Status

Offset Address:	GPIOBASE +20h	Attribute:	R/W, RO
Default Value:	00080000h	Size:	32-bit
Lockable:	No	Power Well:	Core

Bit	Description
31:24	Reserved
23:22	<p><b>Data Length Select (DLS)</b> — R/W. This field determines the number of bytes to serialize on GPIO</p> <p>00 = Serialize bits 7:0 of GP_SB_DATA (1 byte)            01 = Serialize bits 15:0 of GP_SB_DATA (2 bytes)            10 = Undefined - Software must not write this value            11 = Serialize bits 31:0 of GP_SB_DATA (4 bytes)</p> <p>Software should not modify the value in this register unless the Busy bit is clear. Writes to this register have no effect when the corresponding pin is configured in native mode and the read value returned is undefined.</p>
21:16	<p><b>Data Rate Select (DRS)</b> — R/W. This field selects the number of 120 ns time intervals to count between Manchester data transitions. The default of 8h results in a 960 ns minimum time between transitions. A value of 0h in this register produces undefined behavior.</p> <p>Software should not modify the value in this register unless the Busy bit is clear.</p>
15:9	Reserved
8	<p><b>Busy</b> — RO. This read-only status bit is the hardware indication that a serialization is in progress. Hardware sets this bit to 1 based on the Go bit being set. Hardware clears this bit when the Go bit is cleared by the hardware.</p>
7:1	Reserved
0	<p><b>Go</b> — R/W. This bit is set to 1 by software to start the serialization process. Hardware clears the bit after the serialized data is sent. Writes of 0 to this register have no effect. Software should not write this bit to 1 unless the Busy status bit is cleared.</p>







### 13.10.13 GP\_LVL2—GPIO Level for Input or Output 2 Register

Offset Address:	GPIOBASE + 38h	Attribute:	R/W
Default Value:	A4AA0007h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16: 23, Resume for 8: 15, 24: 31

Bit	Description
31:0	<p><b>GP_LVL[63:32]</b> — R/W.</p> <p>These registers are implemented as dual read/write with dedicated storage each. Write value will be stored in the write register, while read is coming from the read register which will always reflect the value of the pin. If GPIO[n] is programmed to be an output (using the corresponding bit in the GP_IO_SEL register), then the corresponding GP_LVL[n] write register value will drive a high or low value on the output pin. 1 = high, 0 = low.</p> <p>When configured in native mode (GPIO_USE_SEL[n] is 0), writes to these bits are stored but have no effect to the pin value. The value reported in this register is undefined when programmed as native mode.</p> <p><b>Note:</b> This register corresponds to GPIO[63:32]. Bit 0 corresponds to GPIO32.</p>

### 13.10.14 GPIO\_USE\_SEL3—GPIO Use Select 3 Register

Offset Address:	GPIOBASE + 40h	Attribute:	R/W
Default Value:	0000033Fh	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16: 23, Resume for 8: 15, 24: 31

Bit	Description
31:12	Always 0. No corresponding GPIO.
11:0	<p><b>GPIO_USE_SEL3[75:64]</b>— R/W. Each bit in this register enables the corresponding GPIO (if it exists) to be used as a GPIO, rather than for the native function.</p> <p>0 = Signal used as native function. 1 = Signal used as a GPIO.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>The following bit is always 1 because it is always unMultiplexed: 8</li> <li>If GPIO[n] does not exist, then, the (n-32) bit in this register will always read as 0 and writes will have no effect.</li> <li>After a full reset RSMRST# all multiplexed signals in the resume and core wells are configured as their default function. After only a PLTRST#, the GPIOs in the core well are configured as their default function.</li> <li>When configured to GPIO mode, the muxing logic will present the inactive state to native logic that uses the pin as an input.</li> </ol> <p>This register corresponds to GPIO[95:64]. Bit 0 corresponds to GPIO64 and bit 11 corresponds to GPIO75.</p>

### 13.10.15 GP\_IO\_SEL3—GPIO Input/Output Select 3 Register

Offset Address:	GPIOBASE + 44h	Attribute:	R/W
Default Value:	00000FF0h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16: 23, Resume for 8: 15, 24: 31

Bit	Description
31:12	Always 0. No corresponding GPIO.
11:0	<p><b>GP_IO_SEL3[75:64]</b>— R/W.</p> <p>0 = GPIO signal is programmed as an output. 1 = Corresponding GPIO signal (if enabled in the GPIO_USE_SEL3 register) is programmed as an input.</p> <p>This register corresponds to GPIO[95:64]. Bit 0 corresponds to GPIO64.</p>



### 13.10.16 GP\_LVL3—GPIO Level for Input or Output 3 Register

Offset Address:	GPIOBASE +48h	Attribute:	R/W
Default Value:	000000C0h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16: 23, Resume for 8: 15, 24: 31

Bit	Description
31:12	Always 0. No corresponding GPIO.
11:0	<p><b>GP_LVL[75:64]</b>— R/W.</p> <p>These registers are implemented as dual read/write with dedicated storage each. Write value will be stored in the write register, while read is coming from the read register which will always reflect the value of the pin. If GPIO[n] is programmed to be an output (using the corresponding bit in the GP_IO_SEL register), then the corresponding GP_LVL[n] write register value will drive a high or low value on the output pin. 1 = high, 0 = low.</p> <p>When configured in native mode (GPIO_USE_SEL[n] is 0), writes to these bits are stored but have no effect to the pin value. The value reported in this register is undefined when programmed as native mode.</p> <p>This register corresponds to GPIO[75: 64]. Bit 0 corresponds to GPIO64 and bit 11 corresponds to GPIO75.</p>

### 13.10.17 GP\_RST\_SEL1 — GPIO Reset Select

Offset Address:	GPIOBASE +60h	Attribute:	R/W
Default Value:	01000000h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16: 23, Resume for 8: 15, 24: 31

Bit	Description
31:24	<p><b>GP_RST_SEL[31:24]</b> — R/W.</p> <p>0 = Corresponding GPIO registers will be reset by PCH_PWROK deassertion, CF9h reset (06h or 0Eh), or SYS_RST# assertion.</p> <p>1 = Corresponding GPIO registers will be reset by RSMRST# assertion only.</p> <p><b>Note:</b> GPIO[24] register bits are not cleared by CF9h reset by default.</p>
23:16	Reserved
15:8	<p><b>GP_RST_SEL[15:8]</b> — R/W.</p> <p>0 = Corresponding GPIO registers will be reset by PCH_PWROK deassertion, CF9h reset (06h or 0Eh), or SYS_RST# assertion.</p> <p>1 = Corresponding GPIO registers will be reset by RSMRST# assertion only.</p>
7:0	Reserved



### 13.10.18 GP\_RST\_SEL2 – GPIO Reset Select

Offset Address:	GPIOBASE +64h	Attribute:	R/W
Default Value:	00000000h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16:23, Resume for 8: 15, 24:31

Bit	Description
31:24	<b>GP_RST_SEL[63:56]</b> – R/W. 0 = Corresponding GPIO registers will be reset by PCH_PWROK deassertion, CF9h reset (06h or 0Eh), or SYS_RST# assertion. 1 = Corresponding GPIO registers will be reset by RSMRST# assertion only.
23:16	Reserved
15:8	<b>GP_RST_SEL[47:40]</b> – R/W. 0 = Corresponding GPIO registers will be reset by PCH_PWROK deassertion, CF9h reset (06h or 0Eh), or SYS_RST# assertion. 1 = Corresponding GPIO registers will be reset by RSMRST# assertion only.
7:0	Reserved

### 13.10.19 GP\_RST\_SEL3 – GPIO Reset Select

Offset Address:	GPIOBASE +68h	Attribute:	R/W
Default Value:	00000000h	Size:	32-bit
Lockable:	Yes	Power Well:	Core for 0: 7, 16:23, Resume for 8: 15, 24:31

Bit	Description
31:12	Reserved
11:8	<b>GP_RST_SEL[75:72]</b> – R/W. 0 = Corresponding GPIO registers will be reset by PCH_PWROK deassertion, CF9h reset (06h or 0Eh), or SYS_RST# assertion. 1 = Corresponding GPIO registers will be reset by RSMRST# assertion only.
7:0	Reserved



## 13.11 GPIO Serial Expander MMIO Registers

The control for the GSX signals is handled through MMIO space. The base offset for this space is selected by the GSXBAR register in [Section 10.1.49](#).

**Table 13-14. Registers to Control GSX Address Map**

GSXBAR + offset	Mnemonic	Register Name	Default	Access
000h–00Fh	—	Reserved	0h	—
010h–013h	GSX_CxCAP	GSX Capabilities 1	00000000h	R/W, RO
014h–017h	GSX_CxCAP2	GSX Capabilities 2	00031250h	—
018h–01Fh	—	Reserved	0h	—
020h–023h	GSX_CxGPILVL	GSX Input Level DWord 0	00000000h	RO
024h–027h	GSX_CxGPILVL_DW1	GSX Input Level DWord 1	00000000h	RO
028h–02Fh	—	Reserved	0h	—
030h–033h	GSX_CxGPOLVL	GSX Output Level DWord 0	00000000h	R/W
034h–037h	GSX_CxGPOLVL_DW1	GSX Output Level DWord 1	00000000h	R/W
038h–03Fh	—	Reserved	0h	—
0040h–0043h	GSX_CxCMD	GSX Command Register	00000000h	R/W, RO
044h–3FFh	—	Reserved	0h	—

### 13.11.1 GSX\_CxCAP – GSX Capabilities Register 1

Offset Address: GSXBAR +10h                      Attribute: R/W, RO  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:10	Reserved
9:5	<p><b>Number of Output Expanders (NOUT)</b> — R/W. BIOS programs this field to indicate number of output expander components which corresponds to multiple of CxGPO in byte granularity.</p> <p>00000b = No output expanders            00001b = 1 output expander            00010b = 2 output expanders            ...</p> <p><b>Note:</b> Total number of NOUT + NIN &lt;= 8</p>
4:0	<p><b>Number of Input Expanders (NIN)</b> — R/W. BIOS programs this field to indicate number of output expander components which corresponds to multiple of CxGPI in byte granularity.</p> <p>00000b = No input expanders            00001b = 1 input expander            00010b = 2 input expanders            ...</p> <p><b>Note:</b> Total number of NOUT + NIN &lt;= 8</p>



### 13.11.2 GSX\_CxCAP2 – GSX Capabilities Register 2

Offset Address: GSXBAR +14h                      Attribute:            R/W, RO  
 Default Value: 000015625h                      Size:                    32-bit

Bit	Description
31:26	Reserved
25:12	<p><b>SCLK Rate (SCLKR) – RO.</b>            SCLKR and SCLKRD are BCD (binary-coded decimal) encoded. The SCLKR represent MHz rate as a whole number, and SCLKR_D represent the decimal number.</p> <p><b>Note:</b> The GSXSCLK is running at 15.625MHZ.</p>
11:0	<p><b>SCLK Rate Decimal (SCLKR_D) – RO.</b> Refer to SCLKR.</p> <p><b>Note:</b> The GSXSCLK is running at 15.625 MHz.</p>

### 13.11.3 GSX\_CxGPILVL – GSX Input Level Register DW0

Offset Address: GSXBAR +20h                      Attribute:            RO  
 Default Value: 00000000h                      Size:                    32-bit

Bit	Description
31:0	<p><b>GPI Level (GPILVL) – RO.</b>            BIOS or software read returns the value of the CxGPI received over the GSX channel. GPILVL[y] corresponds to CxGPI[y] where y falls within [31:0] range. CGPILVL[0] contains the first bit being serially shifted in during an atomic input serialization process. Hardware serialization process shifts in each bit of CxGPI value in ascending order from [bit 0] to [((NIN*8)-1)'s MSB bit].</p>

### 13.11.4 GSX\_CxGPILVL\_DW1 – GSX Input Level Register DW1

Offset Address: GSXBAR +24h                      Attribute:            RO  
 Default Value: 00000000h                      Size:                    32-bit

Bit	Description
31:0	<p><b>GPI Level (GPILVL_DW1) – RO.</b>            BIOS or software read returns the value of the CxGPI received over the GSX channel. GPILVL[y] corresponds to CxGPI[y] where y falls within [63:32] range.</p>

### 13.11.5 GSX\_CxGPOLVL – GSX Output Level Register DW0

Offset Address: GSXBAR +30h                      Attribute:            R/W  
 Default Value: 00000000h                      Size:                    32-bit

Bit	Description
31:0	<p><b>GPO Level (GPOLVL) – R/W.</b>            BIOS or software writes to this field to program the value of each output bit that will be sent in the serialization process. GPOLVL[y] corresponds to CxGPO[y] where y within CxGPO[31:0] range. GPOLVL[0] is the last bit in this register to be shifted out serially. Hardware serialization process shifts out each bit of CxGPOLVL_DW1 &amp; CxGPOLVL in descending order from [((NOUT*8)-1)'s MSB bit] to [bit 0].</p>



### 13.11.6 GSX\_CxGPOLVL\_DW1 – GSX Output Level Register DW1

Offset Address: GSXBAR +34h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:0	<b>GPO Level (GPOLVL_DW1) – R/W.</b> BIOS or software writes to this field to program the value of each output bit that will be sent in the serialization process. GPOLVL[y] corresponds to CxGPO[y] where y within CxGPO[63:32] range.

### 13.11.7 GSX\_CxCMD – GSX Command Register

Offset Address: GSXBAR +40h                      Attribute: R/W, RO  
 Default Value: 00000000h                      Size: 32-bit

Bit	Description
31:4	Reserved.
3	<b>Input and Output Expander Reset Sequence (IOERST) – R/W.</b> Software writes '1' to this bit to cause a reset sequence that brings both input and output expander into a default state. Serialization process will be able to begin at default bit position again.  <b>Note:</b> This bit is cleared once the above reset sequence is completed.
2	<b>Serialization Running (RUN) – RO.</b> 0 = Serialization is complete. 1 = Serialization is in progress. <b>Note:</b> When software clears the ST bit, software shall poll on RUN bit to be '0' before software can write '1' to ST bit again.
1	<b>Busy (BSY) – RO.</b> Software reads this field to determine if the serialization of most recently updated GPOLVL_DW1 and/or GPOLVL content has been completely serialized out on the GSX. Hardware will automatically clear the bit to '0' after all of the newly written value of GPOLVL_DW1 and/or GPOLVL bits have been serialized out at least once.
0	<b>Start (ST) – R/W.</b> 0 = Stop serialization process. 1 = Start serialization process. <b>Notes:</b> 1. Software can only write this bit to '1' when Busy (BSY) status bit is cleared and CxCAP register is programmed. 2. If software write this bit to '0', serialization process will stop at an atomic boundary. 3. Clearing Start (ST) bit does not cause GSXSRESET# to be asserted.

## §



# 14 SATA Controller Registers (D31:F2)

## 14.1 PCI Configuration Registers (SATA–D31:F2)

**Note:** Address locations that are not shown should be treated as Reserved.

All of the SATA registers are in the core well. None of the registers can be locked.

**Table 14-1. SATA Controller PCI Register Address Map (SATA–D31:F2) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Type
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	02B0h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	See register description	See register description
0Ah	SCC	Sub Class Code	See register description	See register description
0Bh	BCC	Base Class Code	01h	RO
0Dh	PMLT	Primary Master Latency Timer	00h	RO
0Eh	HTYPE	Header Type	00h	RO
10h–13h	PCMD_BAR	Primary Command Block Base Address	00000001h	R/W, RO
14h–17h	PCNL_BAR	Primary Control Block Base Address	00000001h	R/W, RO
18h–1Bh	SCMD_BAR	Secondary Command Block Base Address	00000001h	R/W, RO
1Ch–1Fh	SCNL_BAR	Secondary Control Block Base Address	00000001h	R/W, RO
20h–23h	BAR	Legacy Bus Master Base Address	00000001h	R/W, RO
24h–27h	ABAR / SIDPBA	AHCI Base Address / SATA Index Data Pair Base Address	See register description	See register description
2Ch–2Dh	SVID	Subsystem Vendor Identification	0000h	R/WO
2Eh–2Fh	SID	Subsystem Identification	0000h	R/WO
34h	CAP	Capabilities Pointer	80h	RO
3Ch	INT_LN	Interrupt Line	00h	R/W
3Dh	INT_PN	Interrupt Pin	See register description	RO
40h–41h	IDE_TIM	Primary IDE Timing Register	0000h	R/W
42h–43h	IDE_TIM	Secondary IDE Timing Register	0000h	R/W
44h	SIDETIM	Slave IDE Timing	00h	R/W
48h	SDMA_CNT	Synchronous DMA Control	00h	R/W
4Ah–4Bh	SDMA_TIM	Synchronous DMA Timing	0000h	R/W
54h–47h	IDE_CONFIG	IDE I/O Configuration	00000000h	R/W
70h–71h	PID	PCI Power Management Capability ID	See register description	RO



Table 14-1. SATA Controller PCI Register Address Map (SATA-D31:F2) (Sheet 2 of 2)

Offset	Mnemonic	Register Name	Default	Type
72h–73h	PC	PCI Power Management Capabilities	See register description	RO
74h–75h	PMCS	PCI Power Management Control and Status	See register description	R/W, RO, R/WC
80h–81h	MSICI	Message Signaled Interrupt Capability ID	7005h	RO
82h–83h	MSIMC	Message Signaled Interrupt Message Control	0000h	RO, R/W
84h–87h	MSIMA	Message Signaled Interrupt Message Address	00000000h	RO, R/W
88h–89h	MSIMD	Message Signaled Interrupt Message Data	0000h	R/W
90h	MAP	Address Map	0000h	R/W
92h–93h	PCS	Port Control and Status	0000h	R/W, RO
94h–97h	SCLKCG	SATA Clock Gating Control	00000000h	R/W
9Ch–9Fh	SGC	SATA General Configuration	00000000h	R/W, R/WO
A8h–ABh	SCAP0	SATA Capability Register 0	0010B012h	RO, R/WO
ACH–AFh	SCAP1	SATA Capability Register 1	00000048h	RO
B0h–B1h	FLRCID	FLR Capability ID	0009h	RO
B2h–B3h	FLRCLV	FLR Capability Length and Version	See register description	R/WO, RO
B4h–B5h	FLRCTRL	FLR Control	0000h	RO, R/W
C0h	ATC	APM Trapping Control	00h	R/W
C4h	ATS	ATM Trapping Status	00h	R/WC
D0h–D3h	SP	Scratch Pad	00000000h	R/W
E0h–E3h	BFCS	BIST FIS Control/Status	00000000h	R/W, R/WC
E4h–E7h	BFTD1	BIST FIS Transmit Data, DW1	00000000h	R/W
E8h–EBh	BFTD2	BIST FIS Transmit Data, DW2	00000000h	R/W

**Note:** The PCH SATA controller is not arbitrated as a PCI device, therefore it does not need a master latency timer.

### 14.1.1 VID—Vendor Identification Register (SATA–D31:F2)

Offset Address: 00h–01h                      Attribute: RO  
 Default Value: 8086h                        Size: 16 bit  
 Lockable: No                                    Power Well: Core

Bit	Description
15:0	<b>Vendor ID</b> — RO. This is a 16-bit value assigned to Intel. Intel VID = 8086h

### 14.1.2 DID—Device Identification Register (SATA–D31:F2)

Offset Address: 02h–03h                      Attribute: RO  
 Default Value: See bit description            Size: 16 bit  
 Lockable: No                                    Power Well: Core

Bit	Description
15:0	<b>Device ID</b> — RO. This is a 16-bit value assigned to the PCH SATA controller. <b>Note:</b> The value of this field will change dependent upon the value of the MAP Register. See Section 14.1.34

















### 14.1.22 IDE\_TIM – IDE Timing Register (SATA–D31:F2)

Address Offset: Primary: 40h–41h      Attribute: R/W  
 Secondary: 42h–43h  
 Default Value: 0000h      Size: 16 bits

Bits 14:12 and 9:0 of this register are R/W to maintain software compatibility. These bits have no effect on hardware.

Bit	Description
15	<b>IDE Decode Enable (IDE)</b> — R/W. Individually enable/disable the Primary or Secondary decode. 0 = Disable. 1 = Enables the PCH to decode the associated Command Blocks (1F0–1F7h for primary, 170–177h for secondary, or their native mode BAR equivalents) and Control Block (3F6h for primary, 376h for secondary, or their native mode BAR equivalents). This bit effects the IDE decode ranges for both legacy and native-Mode decoding.
14:12	<b>IDE_TIM Field 2</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.
11:10	Reserved
9:0	<b>IDE_TIM Field 1</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.

### 14.1.23 SIDETIM—Slave IDE Timing Register (SATA–D31:F2)

Address Offset: 44h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

**Note:** This register is R/W to maintain software compatibility. These bits have no effect on hardware.

Bit	Description
7:0	<b>SIDETIM Field 1</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.

### 14.1.24 SDMA\_CNT—Synchronous DMA Control Register (SATA–D31:F2)

Address Offset: 48h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

**Note:** This register is R/W to maintain software compatibility. These bits have no effect on hardware.

Bit	Description
7:4	Reserved
3:0	<b>SDMA_CNT Field 1</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.





### 14.1.27 PID—PCI Power Management Capability Identification Register (SATA–D31:F2)

Address Offset: 70h–71h Attribute: RO  
Default Value: See Register Description Size: 16 bits

Bits	Description
15:8	Next Capability (NEXT) — RO. B0h — if SCC = 01h (IDE mode) indicating next item is FLR capability pointer. A8h — for all other values of SCC to point to the next capability structure.
7:0	Capability ID (CID) — RO. Hardwired to 01h. Indicates that this pointer is a PCI power management.

### 14.1.28 PC—PCI Power Management Capabilities Register (SATA–D31:F2)

Address Offset: 72h–73h Attribute: RO  
Default Value: See Register Description Size: 16 bits

Bits	Description
15:11	<b>PME Support (PME_SUP)</b> — RO. 00000 = If SCC = 01h, indicates no PME support in IDE mode. 01000 = If SCC is not 01h, in a non-IDE mode, indicates PME# can be generated from the D3 <sub>HOT</sub> state in the SATA host controller.
10	D2 Support (D2_SUP) — RO. Hardwired to 0. The D2 state is not supported
9	D1 Support (D1_SUP) — RO. Hardwired to 0. The D1 state is not supported
8:6	<b>Auxiliary Current (AUX_CUR)</b> — RO. PME# from D3 <sub>COLD</sub> state is not supported, therefore this field is 000b.
5	<b>Device Specific Initialization (DSI)</b> — RO. Hardwired to 0 to indicate that no device-specific initialization is required.
4	Reserved
3	PME Clock (PME_CLK) — RO. Hardwired to 0 to indicate that PCI clock is not required to generate PME#.
2:0	<b>Version (VER)</b> — RO. Hardwired to 011 to indicates support for Revision 1.2 of the PCI Power Management Specification.











### 14.1.35 PCS—Port Control and Status Register (SATA–D31:F2)

Address Offset:	92h–93h	Attribute:	R/W, RO
Default Value:	0000h	Size:	16 bits
Function Level Reset:	No		

By default, the SATA ports are set to the disabled state (bits [5:0] = '0'). When enabled by software, the ports can transition between the on, partial, and slumber states and can detect devices. When disabled, the port is in the "off" state and cannot detect any devices.

If an AHCI-aware or RAID enabled operating system is being booted, then system BIOS shall insure that all supported SATA ports are enabled prior to passing control to the OS. Once the AHCI aware OS is booted it becomes the enabling/disabling policy owner for the individual SATA ports. This is accomplished by manipulating a port's PxSCTL and PxCMD fields. Because an AHCI or RAID aware OS will typically not have knowledge of the PxE bits and because the PxE bits act as master on/off switches for the ports, pre-boot software must insure that these bits are set to '1' prior to booting the OS, regardless as to whether or not a device is currently on the port.

Bits	Description
15	<b>OOB Retry Mode (ORM)</b> — R/W. 0 = The SATA controller will not retry after an OOB failure 1 = The SATA controller will continue to retry after an OOB failure until successful (infinite retry)
14	Reserved.
13	<b>Port 5 Present (P5P)</b> — RO. The status of this bit may change at any time. This bit is cleared when the port is disabled using P5E. This bit is not cleared upon surprise removal of a device. 0 = No device detected. 1 = The presence of a device on Port 5 has been detected.
12	<b>Port 4 Present (P4P)</b> — RO. The status of this bit may change at any time. This bit is cleared when the port is disabled using P4E. This bit is not cleared upon surprise removal of a device. 0 = No device detected. 1 = The presence of a device on Port 4 has been detected.
11	<b>Port 3 Present (P3P)</b> — RO. The status of this bit may change at any time. This bit is cleared when the port is disabled using P3E. This bit is not cleared upon surprise removal of a device. 0 = No device detected. 1 = The presence of a device on Port 3 has been detected.
10	<b>Port 2 Present (P2P)</b> — RO. The status of this bit may change at any time. This bit is cleared when the port is disabled using P2E. This bit is not cleared upon surprise removal of a device. 0 = No device detected. 1 = The presence of a device on Port 2 has been detected.
9	<b>Port 1 Present (P1P)</b> — RO. The status of this bit may change at any time. This bit is cleared when the port is disabled using P1E. This bit is not cleared upon surprise removal of a device. 0 = No device detected. 1 = The presence of a device on Port 1 has been detected.
8	<b>Port 0 Present (P0P)</b> — RO. The status of this bit may change at any time. This bit is cleared when the port is disabled using P0E. This bit is not cleared upon surprise removal of a device. 0 = No device detected. 1 = The presence of a device on Port 0 has been detected.
7:6	Reserved
5	<b>Port 5 Enabled (P5E)</b> — R/W R/O. 0 = Disabled. The port is in the 'off' state and cannot detect any devices. 1 = Enabled. The port can transition between the on, partial, and slumber states and can detect devices. <b>Note:</b> This bit takes precedence over P5CMD.SUD (offset ABAR+398h:bit 1) If MAP.SC is '0'; if SCC is '01h' this bit will be read only '0' or if MAP.SPD[5] is '1'.



Bits	Description
4	<p><b>Port 4 Enabled (P4E)</b> — R/W R/O.            0 = Disabled. The port is in the 'off' state and cannot detect any devices.            1 = Enabled. The port can transition between the on, partial, and slumber states and can detect devices.  <b>Note:</b> This bit takes precedence over P4CMD.SUD (offset ABAR+318h:bit 1)            If MAP.SC is '0', if SCC is '01h' this bit will be read only '0' or if MAP.SPD[4] is '1'.</p>
3	<p><b>Port 3 Enabled (P3E)</b> — R/W R/O.            0 = Disabled. The port is in the 'off' state and cannot detect any devices.            1 = Enabled. The port can transition between the on, partial, and slumber states and can detect devices.  <b>Note:</b> This bit takes precedence over P3CMD.SUD (offset ABAR+298h:bit 1). When MAP.SPD[3] is '1' this is reserved and is read-only 0.</p>
2	<p><b>Port 2 Enabled (P2E)</b> — R/W R/O.            0 = Disabled. The port is in the 'off' state and cannot detect any devices.            1 = Enabled. The port can transition between the on, partial, and slumber states and can detect devices.  <b>Note:</b> This bit takes precedence over P2CMD.SUD (offset ABAR+218h:bit 1). When MAP.SPD[2] is '1' this is reserved and is read-only 0.</p>
1	<p><b>Port 1 Enabled (P1E)</b> — R/W R/O.            0 = Disabled. The port is in the 'off' state and cannot detect any devices.            1 = Enabled. The port can transition between the on, partial, and slumber states and can detect devices.  <b>Note:</b> This bit takes precedence over P1CMD.SUD (offset ABAR+198h:bit 1). When MAP.SPD[1] is '1' this is reserved and is read-only 0.</p>
0	<p><b>Port 0 Enabled (P0E)</b> — R/W R/O.            0 = Disabled. The port is in the 'off' state and cannot detect any devices.            1 = Enabled. The port can transition between the on, partial, and slumber states and can detect devices.  <b>Note:</b> This bit takes precedence over P0CMD.SUD (offset ABAR+118h:bit 1). When MAP.SPD[0] is '1' this is reserved and is read-only 0.</p>

### 14.1.36 SCLKCG—SATA Clock Gating Control Register

Address Offset: 94h-97h                      Attribute: R/W  
 Default Value: 00000000h                    Size: 32 bits

Bit	Description
31:30	Reserved.
29:24	<p><b>Port Clock Disable (PCD)</b> — R/W            0 = All clocks to the associated port logic will operate normally.            1 = The backbone clock driven to the associated port logic is gated and will not toggle.            Bit 29: Port 5            Bit 28: Port 4            Bit 27: Port 3            Bit 26: Port 2            Bit 25: Port 1            Bit 24: Port 0            If a port is not available, software shall set the corresponding bit to 1. Software can also set the corresponding bits to 1 on ports that are disabled.            Software cannot set the PCD [port x]='1' if the corresponding PCS.PxE='1' in either Dev31Func2 or Dev31Func5 (dual controller IDE mode).</p>
23:9	Reserved.
8:0	<b>SCLKCG Field 1</b> — R/W. BIOS must program these bits to 183h.







### 14.1.38 FLRCID—FLR Capability ID (SATA–D31:F2)

Address Offset: B0-B1h Attribute: RO  
 Default Value: 0009h Size: 16 bits

Bit	Description
15:8	<b>Next Capability Pointer</b> — RO. 00h indicates the final item in the capability list.
7:0	<b>Capability ID</b> — RO. The value of this field depends on the FLRCSSEL (RCBA+3410h:bit 12) bit. 13h = If PFLRCSSEL = 0 09h (Vendor Specific) = If PFLRCSSEL = 1

### 14.1.39 FLRCLV—FLR Capability Length and Version (SATA–D31:F2)

Address Offset: B2-B3h Attribute: RO, R/WO  
 Default Value: xx06h Size: 16 bits  
 Function Level Reset: No (Bit 9:8 Only when FLRCSSEL = '0')

When FLRCSSEL (RCBA+3410h:bit 12) = '0', this register is defined as follows:

Bit	Description
15:10	Reserved.
9	<b>FLR Capability</b> — R/WO. 1 = Support for Function Level reset. This bit is not reset by the Function Level Reset.
8	<b>TXP Capability</b> — R/WO. 1 = Support for Transactions Pending (TXP) bit. TXP must be supported if FLR is supported.
7:0	<b>Vendor-Specific Capability ID</b> — RO. This field indicates the # of bytes of this Vendor Specific capability as required by the PCI specification. It has the value of 06h for the FLR capability.

When FLRCSSEL = '1', this register is defined as follows:

Bit	Description
15:12	<b>Vendor-Specific Capability ID</b> — RO. A value of 2h identifies this capability as the Function Level Reset (FLR).
11:8	<b>Capability Version</b> — RO. This field indicates the version of the FLR capability.
7:0	<b>Vendor-Specific Capability ID</b> — RO. This field indicates the # of bytes of this Vendor Specific capability as required by the PCI specification. It has the value of 06h for the FLR capability.

### 14.1.40 FLRC—FLR Control (SATA–D31:F2)

Address Offset: B4-B5h Attribute: RO, R/W  
 Default Value: 0000h Size: 16 bits

Bit	Description
15:9	Reserved.
8	<b>Transactions Pending (TXP)</b> — RO. 0 = Controller has received all non-posted requests. 1 = Controller has issued non-posted requests which has not been completed.
7:1	Reserved.
0	<b>Initiate FLR</b> — R/W. Used to initiate FLR transition. A write of '1' indicates FLR transition. Since hardware must not respond to any cycles till FLR completion the value read by software from this bit is '0'.









## 14.2 Bus Master IDE I/O Registers (D31:F2)

The bus master IDE function uses 16 bytes of I/O space, allocated using the BAR register, located in Device 31:Function 2 Configuration space, offset 20h. All bus master IDE I/O space registers can be accessed as byte, word, or DWord quantities. Reading reserved bits returns an indeterminate, inconsistent value, and writes to reserved bits have no affect (but should not be attempted). These registers are only used for legacy operation. Software must not use these registers when running AHCI. All I/O registers are reset by Function Level Reset. The description of the I/O registers address map is shown in [Table 14-2](#).

**Table 14-2. Bus Master IDE I/O Register Address Map**

BAR+ Offset	Mnemonic	Register	Default	Type
00	BMICP	Command Register Primary	00h	R/W
01	—	Reserved	—	RO
02	BMISP	Bus Master IDE Status Register Primary	00h	R/W, R/WC, RO
03	—	Reserved	—	RO
04–07	BMIDP	Bus Master IDE Descriptor Table Pointer Primary	xxxxxxxh	R/W
08	BMICS	Command Register Secondary	00h	R/W
09	—	Reserved	—	RO
0Ah	BMISS	Bus Master IDE Status Register Secondary	00h	R/W, R/WC, RO
0Bh	—	Reserved	—	RO
0Ch–0Fh	BMIDS	Bus Master IDE Descriptor Table Pointer Secondary	xxxxxxxh	R/W
10h	AIR	AHCI Index Register	00000000h	R/W, RO
14h	AIDR	AHCI Index Data Register	xxxxxxxh	R/W



### 14.2.1 BMIC[P,S]—Bus Master IDE Command Register (D31:F2)

Address Offset: Primary: BAR + 00h      Attribute: R/W  
 Secondary: BAR + 08h  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:4	Reserved. Returns 0.
3	<b>Read / Write Control (R/WC)</b> — R/W. This bit sets the direction of the bus master transfer. This bit must NOT be changed when the bus master function is active. 0 = Memory reads 1 = Memory writes
2:1	Reserved. Returns 0.
0	<b>Start/Stop Bus Master (START)</b> — R/W. 0 = All state information is lost when this bit is cleared. Master mode operation cannot be stopped and then resumed. If this bit is reset while bus master operation is still active (that is, the Bus Master IDE Active bit (D31:F2:BAR + 02h, bit 0) of the Bus Master IDE Status register for that IDE channel is set) and the drive has not yet finished its data transfer (the Interrupt bit in the Bus Master IDE Status register for that IDE channel is not set), the bus master command is said to be aborted and data transferred from the drive may be discarded instead of being written to system memory. 1 = Enables bus master operation of the controller. Bus master operation does not actually start unless the Bus Master Enable bit (D31:F2:04h, bit 2) in PCI configuration space is also set. Bus master operation begins when this bit is detected changing from 0 to 1. The controller will transfer data between the IDE device and memory only when this bit is set. Master operation can be halted by writing a 0 to this bit.  <b>Note:</b> This bit is intended to be cleared by software after the data transfer is completed, as indicated by either the Bus Master IDE Active bit being cleared or the Interrupt bit of the Bus Master IDE Status register for that IDE channel being set, or both. Hardware does not clear this bit automatically. If this bit is cleared to 0 prior to the DMA data transfer being initiated by the drive in a Device to memory data transfer, then the PCH will not send DMAT to terminate the data transfer. SW intervention (such as sending SRST) is required to reset the interface in this condition.



## 14.2.2 BMIS[P,S]—Bus Master IDE Status Register (D31:F2)

Address Offset: Primary: BAR + 02h      Attribute: R/W, R/WC, RO  
 Secondary: BAR + 0Ah  
 Default Value: 00h      Size: 8 bits

Bit	Description
7	<b>Simplex Only</b> — RO. 0 = Both bus master channels (primary and secondary) can be operated independently and can be used at the same time. 1 = Only one channel may be used at the same time.
6	<b>Drive 1 DMA Capable</b> — R/W. 0 = Not Capable. 1 = Capable. Set by device dependent code (BIOS or device driver) to indicate that drive 1 for this channel is capable of DMA transfers, and that the controller has been initialized for optimum performance. The PCH does not use this bit. It is intended for systems that do not attach BMIDE to the PCI bus.
5	<b>Drive 0 DMA Capable</b> — R/W. 0 = Not Capable 1 = Capable. Set by device dependent code (BIOS or device driver) to indicate that drive 0 for this channel is capable of DMA transfers, and that the controller has been initialized for optimum performance. The PCH does not use this bit. It is intended for systems that do not attach BMIDE to the PCI bus.
4:3	Reserved. Returns 0.
2	<b>Interrupt</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. 1 = Set when a device FIS is received with the 'I' bit set, provided that software has not disabled interrupts using the IEN bit of the Device Control Register (see chapter 5 of the <i>Serial ATA Specification</i> , Revision 1.0a).
1	<b>Error</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. 1 = This bit is set when the controller encounters a target abort or master abort when transferring data on PCI.
0	<b>Bus Master IDE Active (ACT)</b> — RO. 0 = This bit is cleared by the PCH when the last transfer for a region is performed, where EOT for that region is set in the region descriptor. It is also cleared by the PCH when the Start Bus Master bit (D31:F2:BAR+ 00h, bit 0) is cleared in the Command register. When this bit is read as a 0, all data transferred from the drive during the previous bus master command is visible in system memory, unless the bus master command was aborted. 1 = Set by the PCH when the Start bit is written to the Command register.

## 14.2.3 BMID[P,S]—Bus Master IDE Descriptor Table Pointer Register (D31:F2)

Address Offset: Primary: BAR + 04h–07h      Attribute: R/W  
 Secondary: BAR + 0Ch–0Fh  
 Default Value: All bits undefined      Size: 32 bits

Bit	Description
31:2	<b>Address of Descriptor Table (ADDR)</b> — R/W. The bits in this field correspond to bits [31:2] of the memory location of the Physical Region Descriptor (PRD). The Descriptor Table must be Dword-aligned. The Descriptor Table must not cross a 64-K boundary in memory.
1:0	Reserved



### 14.2.4 AIR—AHCI Index Register (D31:F2)

Address Offset: Primary: BAR + 10h      Attribute: R/W  
 Default Value: 00000000h      Size: 32 bits

This register is available only when SCC is not 01h.

Bit	Description
31:11	Reserved
10:2	<b>Index (INDEX)</b> — R/W: This Index register is used to select the Dword offset of the Memory Mapped AHCI register to be accessed. A Dword, Word or Byte access is specified by the active byte enables of the I/O access to the Data register.
1:0	Reserved

### 14.2.5 AIDR—AHCI Index Data Register (D31:F2)

Address Offset: Primary: BAR + 14h      Attribute: R/W  
 Default Value: All bits undefined      Size: 32 bits

This register is available only when SCC is not 01h.

Bit	Description
31:0	<b>Data (DATA)</b> — R/W: This Data register is a “window” through which data is read or written to the AHCI memory mapped registers. A read or write to this Data register triggers a corresponding read or write to the memory mapped register pointed to by the Index register. The Index register must be setup prior to the read or write to this Data register. Note that a physical register is not actually implemented as the data is actually stored in the memory mapped registers. Since this is not a physical register, the “default” value is the same as the default value of the register pointed to by Index.

## 14.3 Serial ATA Index/Data Pair Superset Registers

All of these I/O registers are in the core well. They are exposed only when SCC is 01h (that is, IDE programming interface).

These are Index/Data Pair registers that are used to access the SerialATA superset registers (SerialATA Status (PxSSTS), SerialATA Control (PxSCTL) and SerialATA Error (PxSERR)). The I/O space for these registers is allocated through SIDPBA. Locations with offset from 08h to 0Fh are reserved for future expansion. Software-write operations to the reserved locations will have no effect while software-read operations to the reserved locations will return 0.

Offset	Mnemonic	Register
00h–03h	SINDEX	Serial ATA Index
04h–07h	SDATA	Serial ATA Data
08h–0Ch	—	Reserved
0Ch–0Fh	—	Reserved



### 14.3.1 SINDX – Serial ATA Index (D31:F2)

Address Offset: SIDPBA + 00h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:16	Reserved
15:8	<p><b>Port Index (PIDX)</b> – R/W: This Index field is used to specify the port of the SATA controller at which the port-specific SSTS, SCTL, and SERR registers are located.</p> <p>00h = Primary Master (Port 0)            01h = Primary Slave (Port 2)            02h = Secondary Master (Port 1)            03h = Secondary Slave (Port 3)            All other values are Reserved.</p>
7:0	<p><b>Register Index (RIDX)</b> – R/W: This index field is used to specify one out of three registers currently being indexed into. These three registers are the Serial ATA superset SStatus, SControl and SError memory registers and are port specific, hence for this SATA controller, there are four sets of these registers. Refer to <a href="#">Section 14.4.2.10</a>, <a href="#">Section 14.4.2.11</a>, and <a href="#">Section 14.4.2.12</a> for definitions of the SStatus, SControl and SError registers.</p> <p>00h = SSTS            01h = SCTL            02h = SERR            All other values are Reserved.</p>

### 14.3.2 SDATA – Serial ATA Data (D31:F2)

Address Offset: SIDPBA + 04h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:0	<p><b>Data (DATA)</b> – R/W: This Data register is a “window” through which data is read or written to from the register pointed to by the Serial ATA Index (SINDX) register above. Note that a physical register is not actually implemented as the data is actually stored in the memory mapped registers. Since this is not a physical register, the “default” value is the same as the default value of the register pointed to by SINDX.RIDX field.</p>









## 14.4 AHCI Registers (D31:F2)

**Note:** These registers are AHCI-specific and available when the PCH is properly configured. The Serial ATA Status, Control, and Error registers are special exceptions and may be accessed on all PCH components if properly configured; see [Section 14.3](#) for details.

The memory mapped registers within the SATA controller exist in non-cacheable memory space. Additionally, locked accesses are not supported. If software attempts to perform locked transactions to the registers, indeterminate results may occur. Register accesses shall have a maximum size of 64-bits; 64-bit access must not cross an 8-byte alignment boundary. All memory registers are reset by Function Level Reset unless specified otherwise.

The registers are broken into two sections – generic host control and port control. The port control registers are the same for all ports, and there are as many registers banks as there are ports.

**Table 14-3. AHCI Register Address Map**

ABAR + Offset	Mnemonic	Register
00–1Fh	GHC	Generic Host Control
20h–FFh	—	Reserved
100h–17Fh	P0PCR	Port 0 port control registers
180h–1FFh	P1PCR	Port 1 port control registers
200h–27Fh	P2PCR	Port 2 port control registers
280h–2FFh	P3PCR	Port 3 port control registers
300h–37Fh	P4PCR	Port 4 port control registers
380h–3FFh	P5PCR	Port 5 port control registers
400h–47Fh	P6PCR	Port 6 port control registers

### 14.4.1 AHCI Generic Host Control Registers (D31:F2)

**Table 14-4. Generic Host Controller Register Address Map**

ABAR + Offset	Mnemonic	Register	Default	Type
00–03	CAP	Host Capabilities	FF22FFC2h	R/WO, RO
04–07	GHC	Global PCH Control	00000000h	R/W, RO
08–0Bh	IS	Interrupt Status	00000000h	R/WC
0Ch–0Fh	PI	Ports Implemented	00000000h	R/WO, RO
10h–13h	VS	AHCI Version	00010300h	RO
14h–17h	CCC_CTL	Command Completion Coalescing Control	00010121h	R/W, RO
18h–1Bh	CCC_PORTS	Command Completion Coalescing Ports	00000000h	R/W
1Ch–1Fh	EM_LOC	Enclosure Management Location	01600002h	RO
20h–23h	EM_CTRL	Enclosure Management Control	07010000h	R/W, R/WO, RO
70h–73h	VS	AHCI Version	00010000h	RO
A0h–A3h	VSP	Vendor Specific	00000000h	RO, R/WO
C8h–C9h	RSTF	Intel RST Feature Capabilities	003Fh	R/WO



### 14.4.1.1 CAP—Host Capabilities Register (D31:F2)

Address Offset: ABAR + 00h–03h                      Attribute:                      R/WO, RO  
 Default Value: FF22FFC2h                              Size:                              32 bits  
 Function Level Reset: No

All bits in this register that are R/WO are reset only by PLTRST#.

Bit	Description
31	<b>Supports 64-bit Addressing (S64A)</b> — RO. Indicates that the SATA controller can access 64-bit data structures. The 32-bit upper bits of the port DMA Descriptor, the PRD Base, and each PRD entry are read/write.
30	<b>Supports Command Queue Acceleration (SCQA)</b> — R/WO. When set to 1, indicates that the SATA controller supports SATA command queuing using the DMA Setup FIS. The PCH handles DMA Setup FISes natively, and can handle auto-activate optimization through that FIS.
29	Supports SNotification Register (SSNTF): — RO. The PCH SATA Controller does not support the SNotification register.
28	<b>Supports Mechanical Presence Switch (SMPS)</b> — R/WO. When set to 1, indicates whether the SATA controller supports mechanical presence switches on its ports for use in Hot Plug operations. This value is loaded by platform BIOS prior to OS initialization. If this bit is set, BIOS must also map the SATAGP pins to the SATA controller through GPIO space.
27	<b>Supports Staggered Spin-up (SSS)</b> — R/WO. Indicates whether the SATA controller supports staggered spin-up on its ports, for use in balancing power spikes. This value is loaded by platform BIOS prior to OS initialization. 0 = Staggered spin-up not supported. 1 = Staggered spin-up supported.
26	<b>Supports Aggressive Link Power Management (SALP)</b> — R/WO. 0 = Software shall treat the PxCMD.ALPE and PxCMD.ASP bits as reserved. 1 = The SATA controller supports auto-generating link requests to the partial or slumber states when there are no commands to process.
25	<b>Supports Activity LED (SAL)</b> — RO. Indicates that the SATA controller supports a single output pin (SATALED#) which indicates activity.
24	<b>Supports Command List Override (SCLO)</b> — R/WO. When set to '1', indicates that the Controller supports the PxCMD.CLO bit and its associated function. When cleared to '0', the Controller is not capable of clearing the BSY and DRQ bits in the Status register in order to issue a software reset if these bits are still set from a previous operation.
23:20	<b>Interface Speed Support (ISS)</b> — R/WO. Indicates the maximum speed the SATA controller can support on its ports. 1h = 1.5 Gb/s; 2h = 3.0 Gb/s; 3h = 6.0 Gb/s.
19	Supports Non-Zero DMA Offsets (SNZO) — RO. Reserved, as per the AHCI Revision 1.3 specification
18	<b>Supports AHCI Mode Only (SAM)</b> — RO. The SATA controller may optionally support AHCI access mechanism only. 0 = SATA controller supports both IDE and AHCI Modes 1 = SATA controller supports AHCI Mode Only
17	<b>Supports Port Multiplier (PMS)</b> — R/WO. The PCH SATA controller does not support Port Multipliers. BIOS must clear this bit by writing a 0 to this field.
16	Reserved
15	<b>PIO Multiple DRQ Block (PMD)</b> — RO. Hardwired to 1. The SATA controller supports PIO Multiple DRQ Command Block
14	<b>Slumber State Capable (SSC)</b> — R/WO. When set to 1, the SATA controller supports the slumber state.
13	<b>Partial State Capable (PSC)</b> — R/WO. When set to 1, the SATA controller supports the partial state.
12:8	<b>Number of Command Slots (NCS)</b> — RO. Hardwired to 1Fh to indicate support for 32 slots.
7	<b>Command Completion Coalescing Supported (CCCS)</b> — R/WO. 0 = Command Completion Coalescing Not Supported 1 = Command Completion Coalescing Supported



Bit	Description
6	<b>Enclosure Management Supported (EMS)</b> — R/WO. 0 = Enclosure Management Not Supported 1 = Enclosure Management Supported
5	<b>Supports External SATA (SXS)</b> — R/WO. 0 = External SATA is not supported on any ports 1 = External SATA is supported on one or more ports When set, SW can examine each SATA port's Command Register (PxCMD) to determine which port is routed externally.
4:0	<b>Number of Ports (NPS)</b> — RO. Indicates number of supported ports. Note that the number of ports indicated in this field may be more than the number of ports indicated in the PI (ABAR + 0Ch) register.

#### 14.4.1.2 GHC—Global PCH Control Register (D31:F2)

Address Offset: ABAR + 04h–07h      Attribute: R/W, RO  
Default Value: 00000000h      Size: 32 bits

Bit	Description
31	<b>AHCI Enable (AE)</b> — R/W. When set, this bit indicates that an AHCI driver is loaded and the controller will be talked to using AHCI mechanisms. This can be used by an PCH that supports both legacy mechanisms (such as SFF-8038i) and AHCI to know when the controller will not be talked to as legacy. 0 = Software will communicate with the PCH using legacy mechanisms. 1 = Software will communicate with the PCH using AHCI. The PCH will not have to allow command processing using both AHCI and legacy mechanisms. Software shall set this bit to 1 before accessing other AHCI registers.
30:3	Reserved
2	<b>MSI Revert to Single Message (MRSM)</b> — RO: When set to '1' by hardware, this bit indicates that the host controller requested more than one MSI vector but has reverted to using the first vector only. When this bit is cleared to '0', the Controller has not reverted to single MSI mode (that is hardware is already in single MSI mode, software has allocated the number of messages requested, or hardware is sharing interrupt vectors if MC.MME < MC.MMC). "MC.MSIE = '1' (MSI is enabled) "MC.MMC > 0 (multiple messages requested) "MC.MME > 0 (more than one message allocated) "MC.MME! = MC.MMC (messages allocated not equal to number requested) When this bit is set to '1', single MSI mode operation is in use and software is responsible for clearing bits in the IS register to clear interrupts. This bit shall be cleared to '0' by hardware when any of the four conditions stated is false. This bit is also cleared to '0' when MC.MSIE = '1' and MC.MME = 0h. In this case, the hardware has been programmed to use single MSI mode, and is not "reverting" to that mode. For PCH, the Controller shall always revert to single MSI mode when the number of vectors allocated by the host is less than the number requested. This bit is ignored when GHC.HR = 1.
1	<b>Interrupt Enable (IE)</b> — R/W. This global bit enables interrupts from the PCH. 0 = All interrupt sources from all ports are disabled. 1 = Interrupts are allowed from the AHCI controller.
0	<b>Controller Reset (HR)</b> — R/W. Resets PCH AHCI controller. 0 = No effect 1 = When set by software, this bit causes an internal reset of the PCH AHCI controller. All state machines that relate to data transfers and queuing return to an idle condition, and all ports are re-initialized using COMRESET. <b>Note:</b> For further details, consult Section 10.4.3 of the <i>Serial ATA Advanced Host Controller Interface</i> specification revision 1.3.



### 14.4.1.3 IS—Interrupt Status Register (D31:F2)

Address Offset: ABAR + 08h–0Bh                      Attribute: R/WC  
Default Value: 00000000h                      Size: 32 bits

This register indicates which of the ports within the controller have an interrupt pending and require service.

Bit	Description
31:6	Reserved. Returns 0.
5	<b>Interrupt Pending Status Port[5] (IPS[5])</b> — R/WC. 0 = No interrupt pending. 1 = Port 5 has an interrupt pending. Software can use this information to determine which ports require service after an interrupt.
4	<b>Interrupt Pending Status Port[4] (IPS[4])</b> — R/WC. 0 = No interrupt pending. 1 = Port 4 has an interrupt pending. Software can use this information to determine which ports require service after an interrupt.
3	<b>Interrupt Pending Status Port[3] (IPS[3])</b> — R/WC. 0 = No interrupt pending. 1 = Port 3 has an interrupt pending. Software can use this information to determine which ports require service after an interrupt.
2	<b>Interrupt Pending Status Port[2] (IPS[2])</b> — R/WC. 0 = No interrupt pending. 1 = Port 2 has an interrupt pending. Software can use this information to determine which ports require service after an interrupt.
1	<b>Interrupt Pending Status Port[1] (IPS[1])</b> — R/WC. 0 = No interrupt pending. 1 = Port 1 has an interrupt pending. Software can use this information to determine which ports require service after an interrupt.
0	<b>Interrupt Pending Status Port[0] (IPS[0])</b> — R/WC. 0 = No interrupt pending. 1 = Port 0 has an interrupt pending. Software can use this information to determine which ports require service after an interrupt.

### 14.4.1.4 PI—Ports Implemented Register (D31:F2)

Address Offset: ABAR + 0Ch–0Fh                      Attribute: R/WO, RO  
Default Value: 00000000h                      Size: 32 bits  
Function Level Reset: No

This register indicates which ports are exposed to the PCH. It is loaded by platform BIOS. It indicates which ports that the device supports are available for software to use. For ports that are not available, software must not read or write to registers within that port.

Bit	Description
31:6	Reserved. Returns 0.
5	<b>Ports Implemented Port 5 (PI5)</b> — R/WO. 0 = The port is not implemented. 1 = The port is implemented. This bit is read-only '0' if MAP.SC = '0' or SCC = '01h'.
4	<b>Ports Implemented Port 4 (PI4)</b> — R/WO. 0 = The port is not implemented. 1 = The port is implemented. This bit is read-only '0' if MAP.SC = '0' or SCC = '01h'.
3	<b>Ports Implemented Port 3 (PI3)</b> — R/WO. 0 = The port is not implemented. 1 = The port is implemented.



Bit	Description
2	<b>Ports Implemented Port 2 (PI2)</b> — R/WO. 0 = The port is not implemented. 1 = The port is implemented.
1	<b>Ports Implemented Port 1 (PI1)</b> — R/WO. 0 = The port is not implemented. 1 = The port is implemented.
0	<b>Ports Implemented Port 0 (PI0)</b> — R/WO. 0 = The port is not implemented. 1 = The port is implemented.

**14.4.1.5 VS—AHCI Version (D31:F2)**

Address Offset: ABAR + 10h–13h                      Attribute: RO  
 Default Value: 00010300h                      Size: 32 bits

This register indicates the major and minor version of the AHCI specification. It is BCD encoded. The upper two bytes represent the major version number, and the lower two bytes represent the minor version number. Example: Version 3.12 would be represented as 00030102h. The current version of the specification is 1.30 (00010300h).

Bit	Description
31:16	<b>Major Version Number (MJR)</b> — RO. Indicates the major version is 1
15:0	<b>Minor Version Number (MNR)</b> — RO. Indicates the minor version is 30.

**14.4.1.6 EM\_LOC—Enclosure Management Location Register (D31:F2)**

Address Offset: ABAR + 1Ch–1Fh                      Attribute: RO  
 Default Value: 01600002h                      Size: 32 bits

This register identifies the location and size of the enclosure management message buffer. This register is reserved if enclosure management is not supported (that is, CAP.EMS = 0).

Bit	Description
31:16	<b>Offset (OFST)</b> — RO. The offset of the message buffer in Dwords from the beginning of the ABAR.
15:0	<b>Buffer Size (SZ)</b> — RO. Specifies the size of the transmit message buffer area in Dwords. The PCH SATA controller only supports transmit buffer. A value of 0 is invalid.



### 14.4.1.7 EM\_CTRL—Enclosure Management Control Register (D31:F2)

Address Offset: ABAR + 20h–23h                      Attribute: R/W, R/WO, RO  
 Default Value: 07010000h                      Size: 32 bits

This register is used to control and obtain status for the enclosure management interface. This register includes information on the attributes of the implementation, enclosure management messages supported, the status of the interface, whether any message are pending, and is used to initiate sending messages. This register is reserved if enclosure management is not supported (CAP\_EMS = 0).

Bit	Description
31:27	Reserved
26	<b>Activity LED Hardware Driven (ATTR.ALHD)</b> — R/WO. 1 = The SATA controller drives the activity LED for the LED message type in hardware and does not utilize software for this LED. The host controller does not begin transmitting the hardware based activity signal until after software has written CTL.TM=1 after a reset condition.
25	<b>Transmit Only (ATTR.XMT)</b> — RO. 0 = The SATA controller supports transmitting and receiving messages. 1 = The SATA controller only supports transmitting messages and does not support receiving messages.
24	<b>Single Message Buffer (ATTR.SMB)</b> — RO. 0 = There are separate receive and transmit buffers such that unsolicited messages could be supported. 1 = The SATA controller has one message buffer that is shared for messages to transmit and messages received. Unsolicited receive messages are not supported and it is software's responsibility to manage access to this buffer.
23:20	Reserved
19	<b>SGPIO Enclosure Management Messages (SUPP.SGPIO)</b> — RO. 1 = The SATA controller supports the SGPIO register interface message type.
18	<b>SES-2 Enclosure Management Messages (SUPP.SES2)</b> — RO. 1 = The SATA controller supports the SES-2 message type.
17	<b>SAF-TE Enclosure Management Messages (SUPP.SAFTE)</b> — RO. 1 = The SATA controller supports the SAF-TE message type.
16	<b>LED Message Types (SUPP.LED)</b> — RO. 1 = The SATA controller supports the LED message type.
15:10	Reserved
9	<b>Reset (RST):</b> — R/W. 0 = A write of 0 to this bit by software will have no effect. 1 = When set by software, The SATA controller resets all enclosure management message logic and takes all appropriate reset actions to ensure messages can be transmitted / received after the reset. After the SATA controller completes the reset operation, the SATA controller sets the value to 0.
8	<b>Transmit Message (CTL.TM)</b> — R/W. 0 = A write of 0 to this bit by software will have no effect. 1 = When set by software, The SATA controller transmits the message contained in the message buffer. When the message is completely sent, the SATA controller sets the value to 0. Software must not change the contents of the message buffer while CTL.TM is set to 1.
7:1	Reserved
0	<b>Message Received (STS.MR):</b> — RO. Message Received is not supported in the PCH.



#### 14.4.1.8 CAP2—HBA Capabilities Extended

Address Offset: ABAR + 24h-27h      Attribute: RO  
 Default Value: 00000004h      Size: 32 bits  
 Function Level Reset: No

Bit	Description
31:3	Reserved
2	<b>Automatic Partial to Slumber Transitions (APST)</b> 0= Not supported 1= Supported
1	Reserved
0	Reserved

#### 14.4.1.9 VSP—Vendor Specific (D31:F2)

Address Offset: ABAR + A0h-A3h      Attribute: RO, R/WO  
 Default Value: 00000000h      Size: 32 bits

Bit	Description
31:1	Reserved
0	<b>SATA Initialization Field</b> — R/WO BIOS must clear this bit by writing a 0 to this field.

#### 14.4.1.10 Intel® Rapid Storage Technology enterprise (Intel® RSTe) Feature Capabilities

Address Offset: ABAR + C8h-C9h      Attribute: R/WO  
 Default Value: 003Fh      Size: 16 bits  
 Function Level Reset: No

No hardware action is taken on this register. This register is needed for the Intel® Rapid Storage Technology enterprise software. These bits are set by BIOS to request the feature from the appropriate Intel Rapid Storage Technology enterprise software.

Bit	Description
15:12	Reserved
11:10	<b>OROM UI Normal Delay (OUD)</b> — R/WO. The values of these bits specify the delay of the OROM UI Splash Screen in a normal status. 00 = 2 Seconds (Default) 01 = 4 Seconds 10 = 6 Seconds 11 = 8 Seconds  If bit 5 = 0b these values will be disregarded.
9	Reserved
8	<b>Intel® RRT Only on eSATA (ROES)</b> — R/WO Indicates the request that only Intel® Rapid Recovery Technology (RRT) volumes can span internal and external SATA (eSATA). If not set, any RAID volume can span internal and external SATA. 0 = Disabled 1 = Enabled



Bit	Description
7	<b>LED Locate (LEDL) — R/WO</b> Indicates the request that the LED/SGPIO hardware is attached and ping to locate feature is enabled in the OS. 0 = Disabled 1 = Enabled
6	<b>HDD Unlock (HDDLK) — R/WO</b> Indicates the requested status of HDD password unlock in the OS. 0 = Disabled 1 = Enabled
5	<b>Intel RSTe OROM UI (RSTOROMUI) — R/WO.</b> Indicates the requested status of the Intel® RSTe OROM UI display. 0 = The Intel RSTe OROM UI and banner are not displayed if all disks and RAID volumes have a normal status. 1 = The Intel RSTe OROM UI is displayed during each boot.
4	<b>Intel RSTe — R/WO</b> Indicates the requested status of the Intel® Rapid Recovery Technology Support 0 = The Intel RSTe is disabled 1 = The Intel RSTe is enabled
3	<b>RAID 5 Enable (R5E) — R/WO</b> Indicates the requested status of RAID 5 Support 0 = Disabled 1 = Enabled
2	<b>RAID 10 Enable (R10E) — R/WO</b> Indicates the requested status of RAID 10 Support 0 = Disabled 1 = Enabled
1	<b>RAID 1 Enable (R1E) — R/WO</b> Indicates the requested status of RAID 1 Support 0 = Disabled 1 = Enabled
0	<b>RAID 0 Enable (R0E) — R/WO</b> Indicates the requested status of RAID 0 Support 0 = Disabled 1 = Enabled



## 14.4.2 Port Registers (D31:F2)

Ports not available will result in the corresponding Port DMA register space being reserved. The controller shall ignore writes to the reserved space on write cycles and shall return '0' on read cycle accesses to the reserved location.

SSD Functionality of Integrated NAND Module appears as Port 6(7th SATA port)

When the NVMHCI is exposed as a port under AHCI, Port 7 registers will start at ABAR + 480h.

**Table 14-5. Port [5:0] DMA Register Address Map (Sheet 1 of 3)**

ABAR + Offset	Mnemonic	Register
100h–103h	POCLB	Port 0 Command List Base Address
104h–107h	POCLBU	Port 0 Command List Base Address Upper 32-Bits
108h–10Bh	POFB	Port 0 FIS Base Address
10Ch–10Fh	POFBU	Port 0 FIS Base Address Upper 32-Bits
110h–113h	POIS	Port 0 Interrupt Status
114h–117h	POIE	Port 0 Interrupt Enable
118h–11Bh	POCMD	Port 0 Command
11Ch–11Fh	—	Reserved
120h–123h	POTFD	Port 0 Task File Data
124h–127h	POSIG	Port 0 Signature
128h–12Bh	POSSTS	Port 0 Serial ATA Status
12Ch–12Fh	POSCTL	Port 0 Serial ATA Control
130h–133h	POSERR	Port 0 Serial ATA Error
134h–137h	POSACT	Port 0 Serial ATA Active
138h–13Bh	POCI	Port 0 Command Issue
13Ch–17Fh	—	Reserved
180h–183h	P1CLB	Port 1 Command List Base Address
184h–187h	P1CLBU	Port 1 Command List Base Address Upper 32-Bits
188h–18Bh	P1FB	Port 1 FIS Base Address
18Ch–18Fh	P1FBU	Port 1 FIS Base Address Upper 32-Bits
190h–193h	P1IS	Port 1 Interrupt Status
194h–197h	P1IE	Port 1 Interrupt Enable
198h–19Bh	P1CMD	Port 1 Command
19Ch–19Fh	—	Reserved
1A0h–1A3h	P1TFD	Port 1 Task File Data
1A4h–1A7h	P1SIG	Port 1 Signature
1A8h–1ABh	P1SSTS	Port 1 Serial ATA Status
1ACh–1AFh	P1SCTL	Port 1 Serial ATA Control
1B0h–1B3h	P1SERR	Port 1 Serial ATA Error
1B4h–1B7h	P1SACT	Port 1 Serial ATA Active
1B8h–1BBh	P1CI	Port 1 Command Issue
1BCh–1FFh	—	Reserved
200h–203h	P2CLB	Port 2 Command List Base Address
204h–207h	P2CLBU	Port 2 Command List Base Address Upper 32-Bits



**Table 14-5. Port [5:0] DMA Register Address Map (Sheet 2 of 3)**

ABAR + Offset	Mnemonic	Register
208h–20Bh	P2FB	Port 2 FIS Base Address
20Ch–20Fh	P2FBU	Port 2 FIS Base Address Upper 32-Bits
210h–213h	P2IS	Port 2 Interrupt Status
214h–217h	P2IE	Port 2 Interrupt Enable
218h–21Bh	P2CMD	Port 2 Command
21Ch–21Fh	—	Reserved
220h–223h	P2TFD	Port 2 Task File Data
224h–227h	P2SIG	Port 2 Signature
228h–22Bh	P2SSTS	Port 2 Serial ATA Status
22Ch–22Fh	P2SCTL	Port 2 Serial ATA Control
230h–233h	P2SERR	Port 2 Serial ATA Error
234h–237h	P2SACT	Port 2 Serial ATA Active
238h–23Bh	P2CI	Port 2 Command Issue
23Ch–27Fh	—	Reserved
280h–283h	P3CLB	Port 3 Command List Base Address
284h–287h	P3CLBU	Port 3 Command List Base Address Upper 32-Bits
288h–28Bh	P3FB	Port 3 FIS Base Address
28Ch–28Fh	P3FBU	Port 3 FIS Base Address Upper 32-Bits
290h–293h	P3IS	Port 3 Interrupt Status
294h–297h	P3IE	Port 3 Interrupt Enable
298h–29Bh	P3CMD	Port 3 Command
29Ch–29Fh	—	Reserved
2A0h–2A3h	P3TFD	Port 3 Task File Data
2A4h–2A7h	P3SIG	Port 3 Signature
2A8h–2ABh	P3SSTS	Port 3 Serial ATA Status
2ACh–2AFh	P3SCTL	Port 3 Serial ATA Control
2B0h–2B3h	P3SERR	Port 3 Serial ATA Error
2B4h–2B7h	P3SACT	Port 3 Serial ATA Active
2B8h–2BBh	P3CI	Port 3 Command Issue
2BCh–2FFh	—	Reserved
300h–303h	P4CLB	Port 4 Command List Base Address
304h–307h	P4CLBU	Port 4 Command List Base Address Upper 32-Bits
308h–30Bh	P4FB	Port 4 FIS Base Address
30Ch–30Fh	P4FBU	Port 4 FIS Base Address Upper 32-Bits
310h–313h	P4IS	Port 4 Interrupt Status
314h–317h	P4IE	Port 4 Interrupt Enable
318h–31Bh	P4CMD	Port 4 Command
31Ch–31Fh	—	Reserved
320h–323h	P4TFD	Port 4 Task File Data
324h–327h	P4SIG	Port 4 Signature
328h–32Bh	P4SSTS	Port 4 Serial ATA Status
32Ch–32Fh	P4SCTL	Port 4 Serial ATA Control



**Table 14-5. Port [5:0] DMA Register Address Map (Sheet 3 of 3)**

ABAR + Offset	Mnemonic	Register
330h–333h	P4SERR	Port 4 Serial ATA Error
334h–337h	P4SACT	Port 4 Serial ATA Active
338h–33Bh	P4CI	Port 4 Command Issue
33Ch–37Fh	—	Reserved
380h–383h	P5CLB	Port 5 Command List Base Address
384h–387h	P5CLBU	Port 5 Command List Base Address Upper 32-Bits
388h–38Bh	P5FB	Port 5 FIS Base Address
38Ch–38Fh	P5FBU	Port 5 FIS Base Address Upper 32-Bits
390h–393h	P5IS	Port 5 Interrupt Status
394h–397h	P5IE	Port 5 Interrupt Enable
398h–39Bh	P5CMD	Port 5 Command
39Ch–39Fh	—	Reserved
3A0h–3A3h	P5TFD	Port 5 Task File Data
3A4h–3A7h	P5SIG	Port 5 Signature
3A8h–3ABh	P5SSTS	Port 5 Serial ATA Status
3ACh–3AFh	P5SCTL	Port 5 Serial ATA Control
3B0h–3B3h	P5SERR	Port 5 Serial ATA Error
3B4h–3B7h	P5SACT	Port 5 Serial ATA Active
3B8h–3BBh	P5CI	Port 5 Command Issue
3BCh–FFFh	—	Reserved

**14.4.2.1 PxCLB—Port [5:0] Command List Base Address Register (D31:F2)**

Address Offset: Port 0: ABAR + 100h      Attribute: R/W  
 Port 1: ABAR + 180h  
 Port 2: ABAR + 200h  
 Port 3: ABAR + 280h  
 Port 4: ABAR + 300h  
 Port 5: ABAR + 380h

Default Value: Undefined      Size: 32 bits

Bit	Description
31:10	<b>Command List Base Address (CLB)</b> — R/W. Indicates the 32-bit base for the command list for this port. This base is used when fetching commands to execute. The structure pointed to by this address range is 1 KB in length. This address must be 1-KB aligned as indicated by bits 31:10 being read/write. Note that these bits are not reset on a Controller reset.
9:0	Reserved



### 14.4.2.2 PxCLBU—Port [5:0] Command List Base Address Upper 32-Bits Register (D31:F2)

Address Offset: Port 0: ABAR + 104h      Attribute: R/W  
Port 1: ABAR + 184h  
Port 2: ABAR + 204h  
Port 3: ABAR + 284h  
Port 4: ABAR + 304h  
Port 5: ABAR + 384h

Default Value: Undefined      Size: 32 bits

Bit	Description
31:0	<b>Command List Base Address Upper (CLBU)</b> — R/W. Indicates the upper 32-bits for the command list base address for this port. This base is used when fetching commands to execute. Note that these bits are not reset on a Controller reset.

### 14.4.2.3 PxFB—Port [5:0] FIS Base Address Register (D31:F2)

Address Offset: Port 0: ABAR + 108h      Attribute: R/W  
Port 1: ABAR + 188h  
Port 2: ABAR + 208h  
Port 3: ABAR + 288h  
Port 4: ABAR + 308h  
Port 5: ABAR + 388h

Default Value: Undefined      Size: 32 bits

Bit	Description
31:8	<b>FIS Base Address (FB)</b> — R/W. Indicates the 32-bit base for received FISes. The structure pointed to by this address range is 256 bytes in length. This address must be 256-byte aligned, as indicated by bits 31:3 being read/write. Note that these bits are not reset on a Controller reset.
7:0	Reserved

### 14.4.2.4 PxFBU—Port [5:0] FIS Base Address Upper 32-Bits Register (D31:F2)

Address Offset: Port 0: ABAR + 10Ch      Attribute: R/W  
Port 1: ABAR + 18Ch  
Port 2: ABAR + 20Ch  
Port 3: ABAR + 28Ch  
Port 4: ABAR + 30Ch  
Port 5: ABAR + 38Ch

Default Value: Undefined      Size: 32 bits

Bit	Description
31:0	<b>FIS Base Address Upper (FBU)</b> — R/W. Indicates the upper 32-bits for the received FIS base for this port. Note that these bits are not reset on a Controller reset.



### 14.4.2.5 PxIS—Port [5:0] Interrupt Status Register (D31:F2)

Address Offset: Port 0: ABAR + 110h      Attribute: R/WC, RO  
 Port 1: ABAR + 190h  
 Port 2: ABAR + 210h  
 Port 3: ABAR + 290h  
 Port 4: ABAR + 310h  
 Port 5: ABAR + 390h

Default Value: 00000000h      Size: 32 bits

Bit	Description
31	<b>Cold Port Detect Status (CPDS)</b> — RO. Cold presence detect is not supported.
30	<b>Task File Error Status (TFES)</b> — R/WC. This bit is set whenever the status register is updated by the device and the error bit (PxTFD.bit 0) is set.
29	<b>Host Bus Fatal Error Status (HBFS)</b> — R/WC. Indicates that the PCH encountered an error that it cannot recover from due to a bad software pointer. In PCI, such an indication would be a target or master abort.
28	<b>Host Bus Data Error Status (HBDS)</b> — R/WC. Indicates that the PCH encountered a data error (uncorrectable ECC / parity) when reading from or writing to system memory.
27	<b>Interface Fatal Error Status (IFS)</b> — R/WC. Indicates that the PCH encountered an error on the SATA interface which caused the transfer to stop.
26	<b>Interface Non-fatal Error Status (INFS)</b> — R/WC. Indicates that the PCH encountered an error on the SATA interface but was able to continue operation.
25	Reserved
24	<b>Overflow Status (OFS)</b> — R/WC. Indicates that the PCH received more bytes from a device than was specified in the PRD table for the command.
23	<b>Incorrect Port Multiplier Status (IPMS)</b> — R/WC. The PCH SATA controller does not support Port Multipliers.
22	<b>PhyRdy Change Status (PRCS)</b> — RO. When set to '1', this bit indicates the internal PhyRdy signal changed state. This bit reflects the state of PxSERR.DIAG.N. Unlike most of the other bits in the register, this bit is RO and is only cleared when PxSERR.DIAG.N is cleared. Note that the internal PhyRdy signal also transitions when the port interface enters partial or slumber power management states. Partial and slumber must be disabled when Surprise Removal Notification is desired, otherwise the power management state transitions will appear as false insertion and removal events.
21:8	Reserved
7	<b>Device Interlock Status (DIS)</b> — R/WC. When set, this bit indicates that a platform interlock switch has been opened or closed, which may lead to a change in the connection state of the device. This bit is only valid in systems that support an interlock switch (CAP.SIS [ABAR+00:bit 28] set). For systems that do not support an interlock switch, this bit will always be 0.
6	<b>Port Connect Change Status (PCS)</b> — RO. This bit reflects the state of PxSERR.DIAG.X. (ABAR+130h/1D0h/230h/2D0h, bit 26) Unlike other bits in this register, this bit is only cleared when PxSERR.DIAG.X is cleared. 0 = No change in Current Connect Status. 1 = Change in Current Connect Status.
5	<b>Descriptor Processed (DPS)</b> — R/WC. A PRD with the I bit set has transferred all its data.
4	<b>Unknown FIS Interrupt (UFS)</b> — RO. When set to '1', this bit indicates that an unknown FIS was received and has been copied into system memory. This bit is cleared to '0' by software clearing the PxSERR.DIAG.F bit to '0'. Note that this bit does not directly reflect the PxSERR.DIAG.F bit. PxSERR.DIAG.F is set immediately when an unknown FIS is detected, whereas this bit is set when the FIS is posted to memory. Software should wait to act on an unknown FIS until this bit is set to '1' or the two bits may become out of sync.
3	<b>Set Device Bits Interrupt (SDBS)</b> — R/WC. A Set Device Bits FIS has been received with the I bit set and has been copied into system memory.
2	<b>DMA Setup FIS Interrupt (DSS)</b> — R/WC. A DMA Setup FIS has been received with the I bit set and has been copied into system memory.
1	<b>PIO Setup FIS Interrupt (PSS)</b> — R/WC. A PIO Setup FIS has been received with the I bit set, it has been copied into system memory, and the data related to that FIS has been transferred.
0	<b>Device to Host Register FIS Interrupt (DHRS)</b> — R/WC. A D2H Register FIS has been received with the I bit set, and has been copied into system memory.



### 14.4.2.6 PxIE—Port [5:0] Interrupt Enable Register (D31:F2)

Address Offset: Port 0: ABAR + 114h      Attribute: R/W, RO  
 Port 1: ABAR + 194h  
 Port 2: ABAR + 214h  
 Port 3: ABAR + 294h  
 Port 4: ABAR + 314h  
 Port 5: ABAR + 394h

Default Value: 00000000h      Size: 32 bits

This register enables and disables the reporting of the corresponding interrupt to system software. When a bit is set ('1') and the corresponding interrupt condition is active, then an interrupt is generated. Interrupt sources that are disabled ('0') are still reflected in the status registers.

Bit	Description
31	<b>Cold Presence Detect Enable (CPDE)</b> — RO. Cold Presence Detect is not supported.
30	<b>Task File Error Enable (TFEE)</b> — R/W. When set, and GHC.IE and PxTFD.STS.ERR (due to a reception of the error register from a received FIS) are set, the PCH will generate an interrupt.
29	<b>Host Bus Fatal Error Enable (HBFE)</b> — R/W. When set, and GHC.IE and PxS.HBFS are set, the PCH will generate an interrupt.
28	<b>Host Bus Data Error Enable (HBDE)</b> — R/W. When set, and GHC.IE and PxS.HBDS are set, the PCH will generate an interrupt.
27	<b>Host Bus Data Error Enable (HBDE)</b> — R/W. When set, GHC.IE is set, and PxIS.HBDS is set, the PCH will generate an interrupt.
26	<b>Interface Non-fatal Error Enable (INFE)</b> — R/W. When set, GHC.IE is set, and PxIS.INFS is set, the PCH will generate an interrupt.
25	Reserved
24	<b>Overflow Error Enable (OFE)</b> — R/W. When set, and GHC.IE and PxS.OFS are set, the PCH will generate an interrupt.
23	<b>Incorrect Port Multiplier Enable (IPME)</b> — R/W. The PCH SATA controller does not support Port Multipliers. BIOS and storage software should keep this bit cleared to 0.
22	<b>PhyRdy Change Interrupt Enable (PRCE)</b> — R/W. When set, and GHC.IE is set, and PxIS.PRCs is set, the PCH shall generate an interrupt.
21:8	Reserved
7	<b>Device Interlock Enable (DIE)</b> — R/W. When set, and PxIS.DIS is set, the PCH will generate an interrupt. For systems that do not support an interlock switch, this bit shall be a read-only 0.
6	<b>Port Change Interrupt Enable (PCE)</b> — R/W. When set, and GHC.IE and PxS.PCS are set, the PCH will generate an interrupt.
5	<b>Descriptor Processed Interrupt Enable (DPE)</b> — R/W. When set, and GHC.IE and PxS.DPS are set, the PCH will generate an interrupt.
4	<b>Unknown FIS Interrupt Enable (UFIE)</b> — R/W. When set, and GHC.IE is set and an unknown FIS is received, the PCH will generate this interrupt.
3	<b>Set Device Bits FIS Interrupt Enable (SDBE)</b> — R/W. When set, and GHC.IE and PxS.SDBS are set, the PCH will generate an interrupt.
2	<b>DMA Setup FIS Interrupt Enable (DSE)</b> — R/W. When set, and GHC.IE and PxS.DSS are set, the PCH will generate an interrupt.
1	<b>PIO Setup FIS Interrupt Enable (PSE)</b> — R/W. When set, and GHC.IE and PxS.PSS are set, the PCH will generate an interrupt.
0	<b>Device to Host Register FIS Interrupt Enable (DHRE)</b> — R/W. When set, and GHC.IE and PxS.DHRS are set, the PCH will generate an interrupt.



### 14.4.2.7 PxCMD—Port [5:0] Command Register (D31:F2)

Address Offset: Port 0: ABAR + 118h      Attribute: R/W, RO, R/WO  
 Port 1: ABAR + 198h  
 Port 2: ABAR + 218h  
 Port 3: ABAR + 298h  
 Port 4: ABAR + 318h  
 Port 5: ABAR + 398h

Default Value: 0000w00wh      Size: 32 bits  
 where w = 00?0b (for?, see bit description)

Function Level Reset: No (Bit 21, 19 and 18 only)

Bit	Description														
31:28	<p><b>Interface Communication Control (ICC)</b> — R/W. This is a four bit field that can be used to control reset and power states of the interface. Writes to this field will cause actions on the interface, either as primitives or an OOB sequence, and the resulting status of the interface will be reported in the PxSSTS register (Address offset Port 0: ABAR+124h, Port 1: ABAR+1A4h, Port 2: ABAR+224h, Port 3: ABAR+2A4h, Port 4: ABAR+224h, Port 5: ABAR+2A4h).</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Definition</th> </tr> </thead> <tbody> <tr> <td>Fh–7h</td> <td>Reserved</td> </tr> <tr> <td>6h</td> <td>Slumber: This will cause the PCH to request a transition of the interface to the slumber state. The SATA device may reject the request and the interface will remain in its current state</td> </tr> <tr> <td>5h–3h</td> <td>Reserved</td> </tr> <tr> <td>2h</td> <td>Partial: This will cause the PCH to request a transition of the interface to the partial state. The SATA device may reject the request and the interface will remain in its current state.</td> </tr> <tr> <td>1h</td> <td>Active: This will cause the PCH to request a transition of the interface into the active</td> </tr> <tr> <td>0h</td> <td>No-Op / Idle: When software reads this value, it indicates the PCH is not in the process of changing the interface state or sending a device reset, and a new link command may be issued.</td> </tr> </tbody> </table> <p>When system software writes a non-reserved value other than No-Op (0h), the PCH will perform the action and update this field back to Idle (0h).            If software writes to this field to change the state to a state the link is already in (such as interface is in the active state and a request is made to go to the active state), the PCH will take no action and return this field to Idle.  <b>Note:</b> When the ALPE bit (bit 26) is set, then this register should not be set to 02h or 06h.</p>	Value	Definition	Fh–7h	Reserved	6h	Slumber: This will cause the PCH to request a transition of the interface to the slumber state. The SATA device may reject the request and the interface will remain in its current state	5h–3h	Reserved	2h	Partial: This will cause the PCH to request a transition of the interface to the partial state. The SATA device may reject the request and the interface will remain in its current state.	1h	Active: This will cause the PCH to request a transition of the interface into the active	0h	No-Op / Idle: When software reads this value, it indicates the PCH is not in the process of changing the interface state or sending a device reset, and a new link command may be issued.
Value	Definition														
Fh–7h	Reserved														
6h	Slumber: This will cause the PCH to request a transition of the interface to the slumber state. The SATA device may reject the request and the interface will remain in its current state														
5h–3h	Reserved														
2h	Partial: This will cause the PCH to request a transition of the interface to the partial state. The SATA device may reject the request and the interface will remain in its current state.														
1h	Active: This will cause the PCH to request a transition of the interface into the active														
0h	No-Op / Idle: When software reads this value, it indicates the PCH is not in the process of changing the interface state or sending a device reset, and a new link command may be issued.														
27	<p><b>Aggressive Slumber / Partial (ASP)</b> — R/W. When set, and the ALPE bit (bit 26) is set, the PCH shall aggressively enter the slumber state when it clears the PxCI register and the PxSACT register is cleared. When cleared, and the ALPE bit is set, the PCH will aggressively enter the partial state when it clears the PxCI register and the PxSACT register is cleared. If CAP.SALP is cleared to '0', software shall treat this bit as reserved.</p>														
26	<p><b>Aggressive Link Power Management Enable (ALPE)</b> — R/W. When set, the PCH will aggressively enter a lower link power state (partial or slumber) based upon the setting of the ASP bit (bit 27).</p>														
25	<p><b>Drive LED on ATAPI Enable (DLAE)</b> — R/W. When set to 1, the PCH will drive the LED pin active for ATAPI commands (PxCLB[CHz.A] set) in addition to ATA commands. When cleared, the PCH will only drive the LED pin active for ATA commands. See <a href="#">Section 5.17.10</a> for details on the activity LED.</p>														
24	<p><b>Device is ATAPI (ATAPI)</b> — R/W. When set to 1, the connected device is an ATAPI device. This bit is used by the PCH to control whether or not to generate the LED when commands are active. See <a href="#">Section 5.17.10</a> for details on the activity LED.</p>														
23	<p><b>Automatic Partial Slumber Transitions Enabled (APSTE)</b>— R/W.            0 = This port will not perform Automatic Partial to Slumber Transitions.            1 = The HBA may perform Automatic Partial to Slumber Transitions.  <b>Note:</b> Software should only set this bit to '1' if CAP2.APST is set to '1'.</p>														



Bit	Description
22	<p><b>SATA Initialization Field</b> — R/WO            BIOS must write a 0 to this field.            This field is not reset by FLR.</p>
21	<p><b>External SATA Port (ESP)</b> — R/WO.            0 = This port supports internal SATA devices only.            1 = This port will be used with an external SATA device and hot plug is supported. When set, CAP.SXS must also be set.            This bit is not reset by Function Level Reset.</p>
20	Reserved
19	<p><b>Mechanical Switch Attached to Port (MPSP)</b> — R/WO. If set to 1, the PCH supports a mechanical presence switch attached to this port.            The PCH takes no action on the state of this bit – it is for system software only. For example, if this bit is cleared, and an interlock switch toggles, the PCH still treats it as a proper interlock switch event.  <b>Note:</b> This bit is not reset on a Controller reset or by a Function Level Reset.</p>
18	<p><b>Hot-Plug Capable Port (HPCP)</b> — R/WO.            0 = Port is not capable of Hot-Plug.            1 = Port is Hot-Plug capable.            This indicates whether the platform exposes this port to a device which can be Hot-Plugged. SATA by definition is hot-pluggable, but not all platforms are constructed to allow the device to be removed (it may be screwed into the chassis, for example). This bit can be used by system software to indicate a feature such as “eject device” to the end-user. The PCH takes no action on the state of this bit - it is for system software only. For example, if this bit is cleared, and a Hot-Plug event occurs, the PCH still treats it as a proper Hot-Plug event.  <b>Note:</b> This bit is not reset on a Controller reset or by a Function Level Reset.</p>
17:16	Reserved.
15	<p><b>Controller Running (CR)</b> — RO. When this bit is set, the DMA engines for a port are running. See section 5.2.2 of the <i>Serial ATA AHCI Specification</i> for details on when this bit is set and cleared by the PCH.</p>
14	<p><b>FIS Receive Running (FR)</b> — RO. When set, the FIS Receive DMA engine for the port is running. See section 12.2.2 of the <i>Serial ATA AHCI Specification</i> for details on when this bit is set and cleared by the PCH.</p>
13	<p><b>Mechanical Presence Switch State (MPSS)</b> — RO. The MPSS bit reports the state of a mechanical presence switch attached to this port. If CAP.SMPS is set to 1 and the mechanical presence switch is closed then this bit is cleared to 0. If CAP.SMPS is set to 1 and the mechanical presence switch is open then this bit is set to 1. If CAP.SMPS is set to '0' then this bit is cleared to 0. Software should only use this bit if both CAP.SMPS and PxCMD.MPSP are set to 1.</p>
12:8	<p><b>Current Command Slot (CCS)</b> — RO. Indicates the current command slot the PCH is processing. This field is valid when the ST bit is set in this register, and is constantly updated by the PCH. This field can be updated as soon as the PCH recognizes an active command slot, or at some point soon after when it begins processing the command.            This field is used by software to determine the current command issue location of the PCH. In queued mode, software shall not use this field, as its value does not represent the current command being executed. Software shall only use PxCI and PxSACT when running queued commands.</p>
7:5	Reserved
4	<p><b>FIS Receive Enable (FRE)</b> — R/W. When set, the PCH may post received FISes into the FIS receive area pointed to by PxFB (ABAR+108h/188h/208h/288h) and PxFBU (ABAR+10Ch/18Ch/20Ch/28Ch). When cleared, received FISes are not accepted by the PCH, except for the first D2H (device-to-host) register FIS after the initialization sequence.            System software must not set this bit until PxFB (PxFBU) have been programmed with a valid pointer to the FIS receive area, and if software wishes to move the base, this bit must first be cleared, and software must wait for the FR bit (bit 14) in this register to be cleared.</p>



Bit	Description
3	<p><b>Command List Override (CLO)</b> — R/W. Setting this bit to '1' causes PxTFD.STS.BSY and PxTFD.STS.DRQ to be cleared to '0'. This allows a software reset to be transmitted to the device regardless of whether the BSY and DRQ bits are still set in the PxTFD.STS register. The Controller sets this bit to '0' when PxTFD.STS.BSY and PxTFD.STS.DRQ have been cleared to '0'. A write to this register with a value of '0' shall have no effect.</p> <p>This bit shall only be set to '1' immediately prior to setting the PxCMD.ST bit to '1' from a previous value of '0'. Setting this bit to '1' at any other time is not supported and will result in indeterminate behavior. Software must wait for CLO to be cleared to '0' before setting PxCMD.ST to '1'.</p>
2	<p><b>Power On Device (POD)</b> — RO. Cold presence detect not supported. Defaults to 1.</p>
1	<p><b>Spin-Up Device (SUD)</b> — R/W / RO</p> <p>This bit is R/W and defaults to 0 for systems that support staggered spin-up (R/W when CAP.SSS (ABAR+00h:bit 27) is 1). Bit is RO 1 for systems that do not support staggered spin-up (when CAP.SSS is 0).</p> <p>0 = No action. 1 = On an edge detect from 0 to 1, the PCH starts a COMRESET initialization sequence to the device.</p> <p>Clearing this bit to '0' does not cause any OOB signal to be sent on the interface. When this bit is cleared to '0' and PxSCTL.DET=0h, the Controller will enter listen mode.</p>
0	<p><b>Start (ST)</b> — R/W. When set, the PCH may process the command list. When cleared, the PCH may not process the command list. Whenever this bit is changed from a 0 to a 1, the PCH starts processing the command list at entry 0. Whenever this bit is changed from a 1 to a 0, the PxCI register is cleared by the PCH upon the PCH putting the controller into an idle state. Refer to section 10.3 of the Serial ATA AHCI Specification for important restrictions on when ST can be set to 1 and cleared to 0.</p>

#### 14.4.2.8 PxTFD—Port [5:0] Task File Data Register (D31:F2)

Address Offset: Port 0: ABAR + 120h      Attribute: RO  
 Port 1: ABAR + 1A0h  
 Port 2: ABAR + 220h  
 Port 3: ABAR + 2A0h  
 Port 4: ABAR + 320h  
 Port 5: ABAR + 3A0h

Default Value: 0000007Fh      Size: 32 bits

This is a 32-bit register that copies specific fields of the task file when FISes are received. The FISes that contain this information are: D2H Register FIS, PIO Setup FIS and Set Device Bits FIS

Bit	Description																		
31:16	Reserved																		
15:8	<b>Error (ERR)</b> — RO. Contains the latest copy of the task file error register.																		
7:0	<p><b>Status (STS)</b> — RO. Contains the latest copy of the task file status register. Fields of note in this register that affect AHCI.</p> <table border="1"> <thead> <tr> <th>Bit</th> <th>Field</th> <th>Definition</th> </tr> </thead> <tbody> <tr> <td>7</td> <td>BSY</td> <td>Indicates the interface is busy</td> </tr> <tr> <td>6:4</td> <td>N/A</td> <td>Not applicable</td> </tr> <tr> <td>3</td> <td>DRQ</td> <td>Indicates a data transfer is requested</td> </tr> <tr> <td>2:1</td> <td>N/A</td> <td>Not applicable</td> </tr> <tr> <td>0</td> <td>ERR</td> <td>Indicates an error during the transfer</td> </tr> </tbody> </table>	Bit	Field	Definition	7	BSY	Indicates the interface is busy	6:4	N/A	Not applicable	3	DRQ	Indicates a data transfer is requested	2:1	N/A	Not applicable	0	ERR	Indicates an error during the transfer
Bit	Field	Definition																	
7	BSY	Indicates the interface is busy																	
6:4	N/A	Not applicable																	
3	DRQ	Indicates a data transfer is requested																	
2:1	N/A	Not applicable																	
0	ERR	Indicates an error during the transfer																	



### 14.4.2.9 PxSIG—Port [5:0] Signature Register (D31:F2)

Address Offset: Port 0: ABAR + 124h      Attribute: RO  
Port 1: ABAR + 1A4h  
Port 2: ABAR + 224h  
Port 3: ABAR + 2A4h  
Port 4: ABAR + 324h  
Port 5: ABAR + 3A4h

Default Value: FFFFFFFFh      Size: 32 bits

This is a 32-bit register which contains the initial signature of an attached device when the first D2H Register FIS is received from that device. It is updated once after a reset sequence.

Bit	Description
31:0	<b>Signature (SIG)</b> — RO. Contains the signature received from a device on the first D2H register FIS. The bit order is as follows:
	<b>Bit</b> <b>Field</b>
	31:24      LBA High Register
	23:16      LBA Mid Register
	15:8      LBA Low Register
7:0      Sector Count Register	



#### 14.4.2.10 PxSSTS—Port [5:0] Serial ATA Status Register (D31:F2)

Address Offset: Port 0: ABAR + 128h      Attribute: RO  
 Port 1: ABAR + 1A8h  
 Port 2: ABAR + 228h  
 Port 3: ABAR + 2A8h  
 Port 4: ABAR + 328h  
 Port 5: ABAR + 3A8h

Default Value: 00000000h      Size: 32 bits

This is a 32-bit register that conveys the current state of the interface and host. The PCH updates it continuously and asynchronously. When the PCH transmits a COMRESET to the device, this register is updated to its reset values.

Bit	Description										
31:12	Reserved										
11:8	<p><b>Interface Power Management (IPM)</b> — RO. Indicates the current interface state:</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>Device not present or communication not established</td> </tr> <tr> <td>1h</td> <td>Interface in active state</td> </tr> <tr> <td>2h</td> <td>Interface in PARTIAL power management state</td> </tr> <tr> <td>6h</td> <td>Interface in SLUMBER power management state</td> </tr> </tbody> </table> <p>All other values reserved.</p>	Value	Description	0h	Device not present or communication not established	1h	Interface in active state	2h	Interface in PARTIAL power management state	6h	Interface in SLUMBER power management state
Value	Description										
0h	Device not present or communication not established										
1h	Interface in active state										
2h	Interface in PARTIAL power management state										
6h	Interface in SLUMBER power management state										
7:4	<p><b>Current Interface Speed (SPD)</b> — RO. Indicates the negotiated interface communication speed.</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>Device not present or communication not established</td> </tr> <tr> <td>1h</td> <td>Generation 1 communication rate negotiated</td> </tr> <tr> <td>2h</td> <td>Generation 2 communication rate negotiated</td> </tr> <tr> <td>3h</td> <td>Generation 3 communication rate negotiated</td> </tr> </tbody> </table> <p>All other values reserved.            The PCH Supports Gen 1 communication rates (1.5 Gb/s) and Gen 2 rates (3.0 Gb/s) and Gen 3 rates (6.0 Gb/s).</p>	Value	Description	0h	Device not present or communication not established	1h	Generation 1 communication rate negotiated	2h	Generation 2 communication rate negotiated	3h	Generation 3 communication rate negotiated
Value	Description										
0h	Device not present or communication not established										
1h	Generation 1 communication rate negotiated										
2h	Generation 2 communication rate negotiated										
3h	Generation 3 communication rate negotiated										
3:0	<p><b>Device Detection (DET)</b> — RO. Indicates the interface device detection and Phy state:</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No device detected and Phy communication not established</td> </tr> <tr> <td>1h</td> <td>Device presence detected but Phy communication not established</td> </tr> <tr> <td>3h</td> <td>Device presence detected and Phy communication established</td> </tr> <tr> <td>4h</td> <td>Phy in offline mode as a result of the interface being disabled or running in a BIST loopback mode</td> </tr> </tbody> </table> <p>All other values reserved.</p>	Value	Description	0h	No device detected and Phy communication not established	1h	Device presence detected but Phy communication not established	3h	Device presence detected and Phy communication established	4h	Phy in offline mode as a result of the interface being disabled or running in a BIST loopback mode
Value	Description										
0h	No device detected and Phy communication not established										
1h	Device presence detected but Phy communication not established										
3h	Device presence detected and Phy communication established										
4h	Phy in offline mode as a result of the interface being disabled or running in a BIST loopback mode										



### 14.4.2.11 PxSCTL – Port [5:0] Serial ATA Control Register (D31:F2)

Address Offset: Port 0: ABAR + 12Ch      Attribute: R/W, RO  
 Port 1: ABAR + 1ACh  
 Port 2: ABAR + 22Ch  
 Port 3: ABAR + 2ACh  
 Port 4: ABAR + 32Ch  
 Port 5: ABAR + 3ACh

Default Value: 00000004h      Size: 32 bits

This is a 32-bit read-write register by which software controls SATA capabilities. Writes to the SControl register result in an action being taken by the PCH or the interface. Reads from the register return the last value written to it.

Bit	Description										
31:20	Reserved										
19:16	<b>Port Multiplier Port (PMP)</b> — R/W. This field is not used by AHCI										
15:12	Select Power Management (SPM) — R/W. This field is not used by AHCI										
11:8	<p><b>Interface Power Management Transitions Allowed (IPM)</b> — R/W. Indicates which power states the PCH is allowed to transition to:</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No interface restrictions</td> </tr> <tr> <td>1h</td> <td>Transitions to the PARTIAL state disabled</td> </tr> <tr> <td>2h</td> <td>Transitions to the SLUMBER state disabled</td> </tr> <tr> <td>3h</td> <td>Transitions to both PARTIAL and SLUMBER states disabled</td> </tr> </tbody> </table> <p>All other values reserved</p>	Value	Description	0h	No interface restrictions	1h	Transitions to the PARTIAL state disabled	2h	Transitions to the SLUMBER state disabled	3h	Transitions to both PARTIAL and SLUMBER states disabled
Value	Description										
0h	No interface restrictions										
1h	Transitions to the PARTIAL state disabled										
2h	Transitions to the SLUMBER state disabled										
3h	Transitions to both PARTIAL and SLUMBER states disabled										
7:4	<p><b>Speed Allowed (SPD)</b> — R/W. Indicates the highest allowable speed of the interface. This speed is limited by the CAP.ISS (ABAR+00h:bit 23:20) field.</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No speed negotiation restrictions</td> </tr> <tr> <td>1h</td> <td>Limit speed negotiation to Generation 1 communication rate</td> </tr> <tr> <td>2h</td> <td>Limit speed negotiation to Generation 2 communication rate</td> </tr> <tr> <td>3h</td> <td>Limit speed negotiation to Generation 3 communication rate (Port 0 and Port 1 only)</td> </tr> </tbody> </table> <p>The PCH Supports Gen 1 communication rates (1.5 Gb/s) and Gen 2 rates (3.0 Gb/s) and Gen 3 rates (6 Gb/s).</p>	Value	Description	0h	No speed negotiation restrictions	1h	Limit speed negotiation to Generation 1 communication rate	2h	Limit speed negotiation to Generation 2 communication rate	3h	Limit speed negotiation to Generation 3 communication rate (Port 0 and Port 1 only)
Value	Description										
0h	No speed negotiation restrictions										
1h	Limit speed negotiation to Generation 1 communication rate										
2h	Limit speed negotiation to Generation 2 communication rate										
3h	Limit speed negotiation to Generation 3 communication rate (Port 0 and Port 1 only)										
3:0	<p><b>Device Detection Initialization (DET)</b> — R/W. Controls the PCH's device detection and interface initialization.</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No device detection or initialization action requested</td> </tr> <tr> <td>1h</td> <td>Perform interface communication initialization sequence to establish communication. This is functionally equivalent to a hard reset and results in the interface being reset and communications re-initialized</td> </tr> <tr> <td>4h</td> <td>Disable the Serial ATA interface and put Phy in offline mode</td> </tr> </tbody> </table> <p>All other values reserved.</p> <p>When this field is written to a 1h, the PCH initiates COMRESET and starts the initialization process. When the initialization is complete, this field shall remain 1h until set to another value by software. This field may only be changed to 1h or 4h when PxCMD.ST is 0. Changing this field while the PCH is running results in undefined behavior.</p> <p><b>Note:</b> It is permissible to implement any of the Serial ATA defined behaviors for transmission of COMRESET when DET=1h.</p>	Value	Description	0h	No device detection or initialization action requested	1h	Perform interface communication initialization sequence to establish communication. This is functionally equivalent to a hard reset and results in the interface being reset and communications re-initialized	4h	Disable the Serial ATA interface and put Phy in offline mode		
Value	Description										
0h	No device detection or initialization action requested										
1h	Perform interface communication initialization sequence to establish communication. This is functionally equivalent to a hard reset and results in the interface being reset and communications re-initialized										
4h	Disable the Serial ATA interface and put Phy in offline mode										



#### 14.4.2.12 PxSERR—Port [5:0] Serial ATA Error Register (D31:F2)

Address Offset: Port 0: ABAR + 130h      Attribute: R/WC  
 Port 1: ABAR + 1B0h  
 Port 2: ABAR + 230h  
 Port 3: ABAR + 2B0h  
 Port 4: ABAR + 330h  
 Port 5: ABAR + 3B0h

Default Value: 00000000h      Size: 32 bits

Bits 26:16 of this register contain diagnostic error information for use by diagnostic software in validating correct operation or isolating failure modes. Bits 11:0 contain error information used by host software in determining the appropriate response to the error condition. If one or more of bits 11:8 of this register are set, the controller will stop the current transfer.

Bit	Description
31:27	Reserved
26	<b>Exchanged (X)</b> — R/WC. When set to '1' this bit indicates that a change in device presence has been detected since the last time this bit was cleared. This bit shall always be set to 1 anytime a COMINIT signal is received. This bit is reflected in the POIS.PCS bit.
25	<b>Unrecognized FIS Type (F)</b> — R/WC. Indicates that one or more FISs were received by the Transport layer with good CRC, but had a type field that was not recognized.
24	<b>Transport state transition error (T)</b> — R/WC. Indicates that an error has occurred in the transition from one state to another within the Transport layer since the last time this bit was cleared.
23	<b>Link Sequence Error (S)</b> : Indicates that one or more Link state machine error conditions was encountered. The Link Layer state machine defines the conditions under which the link layer detects an erroneous transition.
22	<b>Handshake (H)</b> — R/WC. Indicates that one or more R_ERR handshake response was received in response to frame transmission. Such errors may be the result of a CRC error detected by the recipient, a disparity or 8b/10b decoding error, or other error condition leading to a negative handshake on a transmitted frame.
21	<b>CRC Error (C)</b> — R/WC. Indicates that one or more CRC errors occurred with the Link Layer.
20	<b>Disparity Error (D)</b> — R/WC. This field is not used by AHCI.
19	<b>10b to 8b Decode Error (B)</b> — R/WC. Indicates that one or more 10b to 8b decoding errors occurred.
18	<b>Comm Wake (W)</b> — R/WC. Indicates that a Comm Wake signal was detected by the Phy.
17	<b>Phy Internal Error (I)</b> — R/WC. Indicates that the Phy detected some internal error.
16	<b>PhyRdy Change (N)</b> — R/WC. When set to 1 this bit indicates that the internal PhyRdy signal changed state since the last time this bit was cleared. In the PCH, this bit will be set when PhyRdy changes from a 0 -> 1 or a 1 -> 0. The state of this bit is then reflected in the PxlS.PRCs interrupt status bit and an interrupt will be generated if enabled. Software clears this bit by writing a 1 to it.
15:12	Reserved
11	<b>Internal Error (E)</b> — R/WC. The SATA controller failed due to a master or target abort when attempting to access system memory.
10	<b>Protocol Error (P)</b> — R/WC. A violation of the Serial ATA protocol was detected. Note: The PCH does not set this bit for all protocol violations that may occur on the SATA link.
9	<b>Persistent Communication or Data Integrity Error (C)</b> — R/WC. A communication error that was not recovered occurred that is expected to be persistent. Persistent communications errors may arise from faulty interconnect with the device, from a device that has been removed or has failed, or a number of other causes.
8	<b>Transient Data Integrity Error (T)</b> — R/WC. A data integrity error occurred that was not recovered by the interface.
7:2	Reserved.
1	<b>Recovered Communications Error (M)</b> — R/WC. Communications between the device and host was temporarily lost but was re-established. This can arise from a device temporarily being removed, from a temporary loss of Phy synchronization, or from other causes and may be derived from the PhyNRdy signal between the Phy and Link layers.
0	<b>Recovered Data Integrity Error (I)</b> — R/WC. A data integrity error occurred that was recovered by the interface through a retry operation or other recovery action.



### 14.4.2.13 PxSACT—Port [5:0] Serial ATA Active (D31:F2)

Address Offset: Port 0: ABAR + 134h      Attribute:      R/W  
 Port 1: ABAR + 1B4h  
 Port 2: ABAR + 234h  
 Port 3: ABAR + 2B4h  
 Port 4: ABAR + 334h  
 Port 5: ABAR + 3B4h

Default Value: 00000000h      Size:      32 bits

Bit	Description
31:0	<b>Device Status (DS)</b> — R/W. System software sets this bit for SATA queuing operations prior to setting the PxCI.CI bit in the same command slot entry. This field is cleared using the Set Device Bits FIS. This field is also cleared when PxCMD.ST (ABAR+118h/198h/218h/298h: bit 0) is cleared by software, and as a result of a COMRESET or SRST.

### 14.4.2.14 PxCI—Port [5:0] Command Issue Register (D31:F2)

Address Offset: Port 0: ABAR + 138h      Attribute:      R/W  
 Port 1: ABAR + 1B8h  
 Port 2: ABAR + 238h  
 Port 3: ABAR + 2B8h  
 Port 4: ABAR + 338h  
 Port 5: ABAR + 3B8h

Default Value: 00000000h      Size:      32 bits

Bit	Description
31:0	<b>Commands Issued (CI)</b> — R/W. This field is set by software to indicate to the PCH that a command has been built-in system memory for a command slot and may be sent to the device. When the PCH receives a FIS which clears the BSY and DRQ bits for the command, it clears the corresponding bit in this register for that command slot. Bits in this field shall only be set to '1' by software when PxCMD.ST is set to '1'. This field is also cleared when PxCMD.ST (ABAR+118h/198h/218h/298h: bit 0) is cleared by software.

Bit	Description
31:0	<b>Command List Base Address Upper (CLBU)</b> — R/W. Indicates the upper 32-bits for the command list base address for this port. This base is used when fetching commands to execute. Note that these bits are not reset on a Controller reset.

## §



# 15 SATA Controller Registers (D31:F5)

## 15.1 PCI Configuration Registers (SATA–D31:F5)

**Note:** Address locations that are not shown should be treated as Reserved.

All of the SATA registers are in the core well. None of the registers can be locked.

**Table 15-1. SATA Controller PCI Register Address Map (SATA–D31:F5) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Type
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	02B0h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	See register description	See register description
0Ah	SCC	Sub Class Code	See register description	See register description
0Bh	BCC	Base Class Code	01h	RO
0Dh	PMLT	Primary Master Latency Timer	00h	RO
10h–13h	PCMD_BAR	Primary Command Block Base Address	00000001h	R/W, RO
14h–17h	PCNL_BAR	Primary Control Block Base Address	00000001h	R/W, RO
18h–1Bh	SCMD_BAR	Secondary Command Block Base Address	00000001h	R/W, RO
1Ch–1Fh	SCNL_BAR	Secondary Control Block Base Address	00000001h	R/W, RO
20h–23h	BAR	Legacy Bus Master Base Address	00000001h	R/W, RO
24h–27h	SIDPBA	Serial ATA Index / Data Pair Base Address	00000000h	See register description
2Ch–2Dh	SVID	Subsystem Vendor Identification	0000h	R/WO
2Eh–2Fh	SID	Subsystem Identification	0000h	R/WO
34h	CAP	Capabilities Pointer	70h	RO
3Ch	INT_LN	Interrupt Line	00h	R/W
3Dh	INT_PN	Interrupt Pin	See register description	RO
40h–41h	IDE_TIM	Primary IDE Timing Register	0000h	R/W
42h–43h	IDE_TIM	Secondary IDE Timing Registers	0000h	R/W
48h	SDMA_CNT	Synchronous DMA Control	00h	R/W
4Ah–4Bh	SDMA_TIM	Synchronous DMA Timing	0000h	R/W
54h–57h	IDE_CONFIG	IDE I/O Configuration	00000000h	R/W
70h–71h	PID	PCI Power Management Capability ID	See register description	RO
72h–73h	PC	PCI Power Management Capabilities	4003h	RO







### 15.1.4 PCISTS — PCI Status Register (SATA–D31:F5)

Address Offset: 06h–07h  
Default Value: 02B0h

Attribute: R/WC, RO  
Size: 16 bits

**Note:** For the writable bits, software must write a '1' to clear bits that are set. Writing a '0' to the bit has no effect.

Bit	Description
15	<b>Detected Parity Error (DPE)</b> — R/WC. 0 = No parity error detected by SATA controller. 1 = SATA controller detects a parity error on its interface.
14	<b>Signaled System Error (SSE)</b> — RO. Reserved as '0'.
13	<b>Received Master Abort (RMA)</b> — R/WC. 0 = Master abort Not generated. 1 = SATA controller, as a master, generated a master abort.
12	Reserved
11	<b>Signaled Target Abort (STA)</b> — RO. Reserved as '0'.
10:9	<b>DEVSEL# Timing Status (DEV_STS)</b> — RO. 01 = Hardwired; Controls the device select time for the SATA controller's PCI interface.
8	<b>Data Parity Error Detected (DPED)</b> — R/WC. For PCH, this bit can only be set on read completions received from SiBUS where there is a parity error. 1 = SATA controller, as a master, either detects a parity error or sees the parity error line asserted, and the parity error response bit (bit 6 of the command register) is set.
7	<b>Fast Back to Back Capable (FB2BC)</b> — RO. Reserved as '1'.
6	<b>User Definable Features (UDF)</b> — RO. Reserved as '0'.
5	<b>66 MHz Capable (66 MHZ_CAP)</b> — RO. Reserved as '1'.
4	<b>Capabilities List (CAP_LIST)</b> — RO. This bit indicates the presence of a capabilities list. The minimum requirement for the capabilities list must be PCI power management for the SATA controller.
3	<b>Interrupt Status (INTS)</b> — RO. Reflects the state of INTx# messages, IRQ14 or IRQ15. 0 = Interrupt is cleared (independent of the state of Interrupt Disable bit in the command register [offset 04h]). 1 = Interrupt is to be asserted
2:0	Reserved





### 15.1.8 BCC—Base Class Code Register (SATA-D31:F5SATA-D31:F5)

Address Offset: 0Bh Attribute: RO  
Default Value: 01h Size: 8 bits

Bit	Description
7:0	<b>Base Class Code (BCC)</b> — RO. 01h = Mass storage device

### 15.1.9 PMLT—Primary Master Latency Timer Register (SATA-D31:F5)

Address Offset: 0Dh Attribute: RO  
Default Value: 00h Size: 8 bits

Bit	Description
7:0	<b>Master Latency Timer Count (MLTC)</b> — RO. 00h = Hardwired. The SATA controller is implemented internally, and is not arbitrated as a PCI device, so it does not need a Master Latency Timer.

### 15.1.10 PCMD\_BAR—Primary Command Block Base Address Register (SATA-D31:F5)

Address Offset: 10h–13h Attribute: R/W, RO  
Default Value: 00000001h Size: 32 bits

Bit	Description
31:16	Reserved
15:3	<b>Base Address</b> — R/W. This field provides the base address of the I/O space (8 consecutive I/O locations).
2:1	Reserved
0	<b>Resource Type Indicator (RTE)</b> — RO. Hardwired to '1' to indicate a request for I/O space.

**Note:** This 8-byte I/O space is used in native mode for the Primary Controller's Command Block.

### 15.1.11 PCNL\_BAR—Primary Control Block Base Address Register (SATA-D31:F5)

Address Offset: 14h–17h Attribute: R/W, RO  
Default Value: 00000001h Size: 32 bits

Bit	Description
31:16	Reserved
15:2	<b>Base Address</b> — R/W. This field provides the base address of the I/O space (4 consecutive I/O locations).
1	Reserved
0	<b>Resource Type Indicator (RTE)</b> — RO. Hardwired to '1' to indicate a request for I/O space.

**Note:** This 4-byte I/O space is used in native mode for the Primary Controller's Command Block.





### 15.1.15 SIDPBA — SATA Index/Data Pair Base Address Register (SATA–D31:F5)

Address Offset: 24h–27h                      Attribute: R/W, RO  
 Default Value: 00000000h                      Size: 32 bits

When SCC is 01h

When the programming interface is IDE, the register represents an I/O BAR allocating 16B of I/O space for the I/O mapped registers defined in Section 15.3. Note that although 16B of locations are allocated, some maybe reserved.

Bit	Description
31:16	Reserved
15:4	<b>Base Address (BA)</b> — R/W. Base address of register I/O space
3:1	Reserved
0	<b>Resource Type Indicator (RTE)</b> — RO. Hardwired to 1 to indicate a request for I/O space.

### 15.1.16 SVID—Subsystem Vendor Identification Register (SATA–D31:F5)

Address Offset: 2Ch–2Dh                      Attribute: R/WO  
 Default Value: 0000h                      Size: 16 bits  
 Lockable: No                      Power Well: Core  
 Function Level Reset: No

Bit	Description
15:0	<b>Subsystem Vendor ID (SVID)</b> — R/WO. Value is written by BIOS. No hardware action taken on this value.

### 15.1.17 SID—Subsystem Identification Register (SATA–D31:F5)

Address Offset: 2Eh–2Fh                      Attribute: R/WO  
 Default Value: 0000h                      Size: 16 bits  
 Lockable: No                      Power Well: Core

Bit	Description
15:0	<b>Subsystem ID (SID)</b> — R/WO. Value is written by BIOS. No hardware action taken on this value.

### 15.1.18 CAP—Capabilities Pointer Register (SATA–D31:F5)

Address Offset: 34h                      Attribute: RO  
 Default Value: 70h                      Size: 8 bits

Bit	Description
7:0	<b>Capabilities Pointer (CAP_PTR)</b> — RO. Indicates that the first capability pointer offset is 70h if the Sub Class Code (SCC) (Dev 31:F2:0Ah) is configure as IDE mode (value of 01).







### 15.1.24 IDE\_CONFIG—IDE I/O Configuration Register (SATA-D31:F5)

Address Offset: 54h–57h                      Attribute: R/W  
 Default Value: 00000000h                  Size: 32 bits

**Note:** This register is R/W to maintain software compatibility. These bits have no effect on hardware.

Bit	Description
31:24	Reserved
23:16	<b>IDE_CONFIG Field 6</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.
15	Reserved
14	<b>IDE_CONFIG Field 5</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.
13	Reserved
12	<b>IDE_CONFIG Field 4</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.
11:8	Reserved
7:4	<b>IDE_CONFIG Field 3</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.
3	Reserved
2	<b>IDE_CONFIG Field 2</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.
1	Reserved
0	<b>IDE_CONFIG Field 1</b> — R/W. This field is R/W to maintain software compatibility. This field has no effect on hardware.

### 15.1.25 PID—PCI Power Management Capability Identification Register (SATA-D31:F5)

Address Offset: 70h–71h                      Attribute: RO  
 Default Value: B001h                        Size: 16 bits

Bits	Description
15:8	<b>Next Capability (NEXT)</b> — RO. When SCC is 01h, this field will be B0h indicating the next item is FLR Capability Pointer in the list.
7:0	<b>Capability ID (CID)</b> — RO. Indicates that this pointer is a PCI power management.

### 15.1.26 PC—PCI Power Management Capabilities Register (SATA-D31:F5)

Address Offset: 72h–73h                      Attribute: RO  
 Default Value: 4003h                        Size: 16 bits

Bits	Description
15:11	<b>PME Support (PME_SUP)</b> — RO. By default with SCC = 01h, the default value of '00000' indicates no PME support in IDE mode.
10	D2 Support (D2_SUP) — RO. Hardwired to '0'. The D2 state is not supported
9	D1 Support (D1_SUP) — RO. Hardwired to '0'. The D1 state is not supported



Bits	Description
8:6	Auxiliary Current (AUX_CUR) — RO. PME# from D3 <sub>COLD</sub> state is not supported, therefore this field is 000b.
5	Device Specific Initialization (DSI) — RO. Hardwired to '0' to indicate that no device-specific initialization is required.
4	Reserved
3	PME Clock (PME_CLK) — RO. Hardwired to '0' to indicate that PCI clock is not required to generate PME#.
2:0	<b>Version (VER)</b> — RO. Hardwired to '011' to indicates support for Revision 1.2 of the PCI Power Management Specification.

### 15.1.27 PMCS—PCI Power Management Control and Status Register (SATA–D31:F5)

Address Offset: 74h–75h                      Attribute:                      RO, R/W, R/WC  
 Default Value: 0008h                      Size:                      16 bits  
 Function Level Reset: No (Bits 8 and 15 only)

Bits	Description
15	<b>PME Status (PMES)</b> — R/WC. Bit is set when a PME event is to be requested, and if this bit and PMEE is set, a PME# will be generated from the SATA controller. <b>Note:</b> When SCC=01h this bit will be RO '0'. Software is advised to clear PMEE together with PMES prior to changing SCC through MAP.SMS. This bit is not reset by Function Level Reset.
14:9	Reserved
8	<b>PME Enable (PMEE)</b> — R/W. When SCC is not 01h, this bit R/W. When set, the SATA controller generates PME# form D3 <sub>HOT</sub> on a wake event. <b>Note:</b> When SCC=01h this bit will be RO '0'. Software is advised to clear PMEE together with PMES prior to changing SCC through MAP.SMS. This bit is not reset by Function Level Reset.
7:4	Reserved
3	<b>No Soft Reset (NSFRST)</b> — RO. These bits are used to indicate whether devices transitioning from D3 <sub>HOT</sub> state to D0 state will perform an internal reset. 0 = Device transitioning from D3 <sub>HOT</sub> state to D0 state perform an internal reset. 1 = Device transitioning from D3 <sub>HOT</sub> state to D0 state do not perform an internal reset. Configuration content is preserved. Upon transition from the D3 <sub>HOT</sub> state to D0 state initialized state, no additional operating system intervention is required to preserve configuration context beyond writing to the PowerState bits. Regardless of this bit, the controller transition from D3 <sub>HOT</sub> state to D0 state by a system or bus segment reset will return to the state D0 uninitialized with only PME context preserved if PME is supported and enabled.
2	Reserved
1:0	<b>Power State (PS)</b> — R/W. These bits are used both to determine the current power state of the SATA controller and to set a new power state. 00 = D0 state 11 = D3 <sub>HOT</sub> state When in the D3 <sub>HOT</sub> state, the controller's configuration space is available, but the I/O and memory spaces are not. Additionally, interrupts are blocked.

### 15.1.28 MAP—Address Map Register (SATA–D31:F5)16

Address Offset: 90h    Attribute:                      R/W, R/WO, RO  
 Default Value: 00h    Size:                      bits  
 Function Level Reset: No (Bits 9:8 only)











## 15.2.1 BMIC[P,S]—Bus Master IDE Command Register (D31:F5)

Address Offset: Primary: BAR + 00h      Attribute: R/W  
 Secondary: BAR + 08h  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:4	Reserved.
3	<b>Read / Write Control (R/WC)</b> — R/W. This bit sets the direction of the bus master transfer: This bit must NOT be changed when the bus master function is active. 0 = Memory reads 1 = Memory writes
2:1	Reserved.
0	<b>Start/Stop Bus Master (START)</b> — R/W. 0 = All state information is lost when this bit is cleared. Master mode operation cannot be stopped and then resumed. If this bit is reset while bus master operation is still active (that is, the Bus Master IDE Active bit (D31:F5:BAR + 02h, bit 0) of the Bus Master IDE Status register for that IDE channel is set) and the drive has not yet finished its data transfer (the Interrupt bit in the Bus Master IDE Status register for that IDE channel is not set), the bus master command is said to be aborted and data transferred from the drive may be discarded instead of being written to system memory. 1 = Enables bus master operation of the controller. Bus master operation does not actually start unless the Bus Master Enable bit (D31:F1:04h, bit 2) in PCI configuration space is also set. Bus master operation begins when this bit is detected changing from '0' to '1'. The controller will transfer data between the IDE device and memory only when this bit is set. Master operation can be halted by writing a '0' to this bit.  <b>Note:</b> This bit is intended to be cleared by software after the data transfer is completed, as indicated by either the Bus Master IDE Active bit being cleared or the Interrupt bit of the Bus Master IDE Status register for that IDE channel being set, or both. Hardware does not clear this bit automatically. If this bit is cleared to '0' prior to the DMA data transfer being initiated by the drive in a device to memory data transfer, then the PCH will not send DMAT to terminate the data transfer. SW intervention (for example, sending SRST) is required to reset the interface in this condition.

## 15.2.2 BMIS[P,S]—Bus Master IDE Status Register (D31:F5)

Address Offset: Primary: BAR + 02h      Attribute: R/W, R/WC, RO  
 Secondary: BAR + 0Ah  
 Default Value: 00h      Size: 8 bits

Bit	Description
7	<b>PRD Interrupt Status (PRDIS)</b> — R/WC. 0 = Software clears this bit by writing a '1' to it. 1 = This bit is set when the host controller execution of a PRD that has its PRD_INT bit set.
6	Reserved.
5	<b>Drive 0 DMA Capable</b> — R/W. 0 = Not Capable 1 = Capable. Set by device dependent code (BIOS or device driver) to indicate that drive 0 for this channel is capable of DMA transfers, and that the controller has been initialized for optimum performance. The PCH does not use this bit. It is intended for systems that do not attach BMIDE to the PCI bus.
4:3	Reserved.



Bit	Description
2	<b>Interrupt</b> — R/WC. 0 = Software clears this bit by writing a '1' to it. 1 = Set when a device FIS is received with the 'I' bit set, provided that software has not disabled interrupts using the IEN bit of the Device Control Register (see Chapter 5 of the <i>Serial ATA Specification</i> , Revision 1.0a).
1	<b>Error</b> — R/WC. 0 = Software clears this bit by writing a '1' to it. 1 = This bit is set when the controller encounters a target abort or master abort when transferring data on PCI.
0	<b>Bus Master IDE Active (ACT)</b> — RO. 0 = This bit is cleared by the PCH when the last transfer for a region is performed, where EOT for that region is set in the region descriptor. It is also cleared by the PCH when the Start Bus Master bit (D31:F5:BAR+ 00h, bit 0) is cleared in the Command register. When this bit is read as a 0, all data transferred from the drive during the previous bus master command is visible in system memory, unless the bus master command was aborted. 1 = Set by the PCH when the Start bit is written to the Command register.

### 15.2.3 BMID[P,S]—Bus Master IDE Descriptor Table Pointer Register (D31:F5)

Address Offset: Primary: BAR + 04h–07h Attribute: R/W  
 Secondary: BAR + 0Ch–0Fh  
 Default Value: All bits undefined Size: 32 bits

Bit	Description
31:2	<b>Address of Descriptor Table (ADDR)</b> — R/W. The bits in this field correspond to bits [31:2] of the memory location of the Physical Region Descriptor (PRD). The Descriptor Table must be DWord-aligned. The Descriptor Table must not cross a 64-K boundary in memory.
1:0	Reserved

## 15.3 Serial ATA Index/Data Pair Superset Registers

All of these I/O registers are in the core well. They are exposed only when SCC is 01h (that is, IDE programming interface) and the controller is not in combined mode. These are Index/Data Pair registers that are used to access the SerialATA superset registers (SerialATA Status, SerialATA Control and SerialATA Error). The I/O space for these registers is allocated through SIDPBA. Locations with offset from 08h to 0Fh are reserved for future expansion. Software-write operations to the reserved locations shall have no effect while software-read operations to the reserved locations shall return '0'.

### 15.3.1 SINDX—SATA Index Register (D31:F5)

Address Offset: SIDPBA + 00h Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

**Note:** These are Index/Data Pair Registers that are used to access the SSTS, SCTL, and SERR. The I/O space for these registers is allocated through SIDPBA.



Bit	Description
31:16	Reserved
15:8	<b>Port Index (PIDX)</b> — R/W: This Index field is used to specify the port of the SATA controller at which the port-specific SSTS, SCTL, and SERR registers are located. 00h = Primary Master (Port 4) 02h = Secondary Master (Port 5) All other values are Reserved.
7:0	<b>Register Index (RIDX)</b> — R/W: This Index field is used to specify one out of three registers currently being indexed into. 00h = SSTS 01h = SCTL 02h = SERR All other values are Reserved

### 15.3.2 SDATA—SATA Index Data Register (D31:F5)

Address Offset: SIDPBA + 04h                      Attribute: R/W  
 Default Value: All bits undefined              Size: 32 bits

**Note:** These are Index/Data Pair Registers that are used to access the SSTS, SCTL, and SERR. The I/O space for these registers is allocated through SIDPBA.

Bit	Description
31:0	<b>Data (DATA)</b> — R/W: This Data register is a “window” through which data is read or written to the memory mapped registers. A read or write to this Data register triggers a corresponding read or write to the memory mapped register pointed to by the Index register. The Index register must be setup prior to the read or write to this Data register. Note that a physical register is not actually implemented as the data is actually stored in the memory mapped registers. Since this is not a physical register, the “default” value is the same as the default value of the register pointed to by Index.

#### 15.3.2.1 PxSSTS—Serial ATA Status Register (D31:F5)

Address Offset:    Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

SDATA when SINDX.RIDX is 00h. This is a 32-bit register that conveys the current state of the interface and host. The PCH updates it continuously and asynchronously. When the PCH transmits a COMRESET to the device, this register is updated to its reset values.





Bit	Description										
11:8	<p><b>Interface Power Management Transitions Allowed (IPM)</b> — R/W. Indicates which power states the PCH is allowed to transition to:</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No interface restrictions</td> </tr> <tr> <td>1h</td> <td>Transitions to the PARTIAL state disabled</td> </tr> <tr> <td>2h</td> <td>Transitions to the SLUMBER state disabled</td> </tr> <tr> <td>3h</td> <td>Transitions to both PARTIAL and SLUMBER states disabled</td> </tr> </tbody> </table> <p>All other values reserved</p>	Value	Description	0h	No interface restrictions	1h	Transitions to the PARTIAL state disabled	2h	Transitions to the SLUMBER state disabled	3h	Transitions to both PARTIAL and SLUMBER states disabled
Value	Description										
0h	No interface restrictions										
1h	Transitions to the PARTIAL state disabled										
2h	Transitions to the SLUMBER state disabled										
3h	Transitions to both PARTIAL and SLUMBER states disabled										
7:4	<p><b>Speed Allowed (SPD)</b> — R/W. Indicates the highest allowable speed of the interface. This speed is limited by the CAP.ISS (ABAR+00h:bit 23:20) field.</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No speed negotiation restrictions</td> </tr> <tr> <td>1h</td> <td>Limit speed negotiation to Generation 1 communication rate</td> </tr> <tr> <td>2h</td> <td>Limit speed negotiation to Generation 2 communication rate</td> </tr> </tbody> </table> <p>All other values reserved. The PCH Supports Gen 1 communication rates (1.5 Gb/s) and Gen 2 rates (3.0 Gb/s).</p>	Value	Description	0h	No speed negotiation restrictions	1h	Limit speed negotiation to Generation 1 communication rate	2h	Limit speed negotiation to Generation 2 communication rate		
Value	Description										
0h	No speed negotiation restrictions										
1h	Limit speed negotiation to Generation 1 communication rate										
2h	Limit speed negotiation to Generation 2 communication rate										
3:0	<p><b>Device Detection Initialization (DET)</b> — R/W. Controls the PCH's device detection and interface initialization.</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0h</td> <td>No device detection or initialization action requested</td> </tr> <tr> <td>1h</td> <td>Perform interface communication initialization sequence to establish communication. This is functionally equivalent to a hard reset and results in the interface being reset and communications re-initialized</td> </tr> <tr> <td>4h</td> <td>Disable the Serial ATA interface and put Phy in offline mode</td> </tr> </tbody> </table> <p>All other values reserved.</p>	Value	Description	0h	No device detection or initialization action requested	1h	Perform interface communication initialization sequence to establish communication. This is functionally equivalent to a hard reset and results in the interface being reset and communications re-initialized	4h	Disable the Serial ATA interface and put Phy in offline mode		
Value	Description										
0h	No device detection or initialization action requested										
1h	Perform interface communication initialization sequence to establish communication. This is functionally equivalent to a hard reset and results in the interface being reset and communications re-initialized										
4h	Disable the Serial ATA interface and put Phy in offline mode										

**15.3.2.3 PxSERR—Serial ATA Error Register (D31:F5)**

Address Offset: Attribute: R/WC  
 Default Value: 00000000h Size: 32 bits

SDATA when SINDx.RIDX is 02h.

Bits 26:16 of this register contains diagnostic error information for use by diagnostic software in validating correct operation or isolating failure modes. Bits 11:0 contain error information used by host software in determining the appropriate response to the error condition. If one or more of bits 11:8 of this register are set, the controller will stop the current transfer.

Bit	Description
31:27	Reserved
26	<b>Exchanged (X)</b> — R/WC. When set to '1' this bit indicates that a change in device presence has been detected since the last time this bit was cleared. This bit shall always be set to '1' anytime a COMINIT signal is received. This bit is reflected in the POIS.PCS bit.
25	<b>Unrecognized FIS Type (F)</b> — R/WC. Indicates that one or more FISs were received by the Transport layer with good CRC, but had a type field that was not recognized.
24	<b>Transport state transition error (T)</b> — R/WC. Indicates that an error has occurred in the transition from one state to another within the Transport layer since the last time this bit was cleared.



Bit	Description
23	<b>Link Sequence Error (S)</b> : Indicates that one or more Link state machine error conditions was encountered. The Link Layer state machine defines the conditions under which the link layer detects an erroneous transition.
22	<b>Handshake (H)</b> — R/WC. Indicates that one or more R_ERR handshake response was received in response to frame transmission. Such errors may be the result of a CRC error detected by the recipient, a disparity or 8b/10b decoding error, or other error condition leading to a negative handshake on a transmitted frame.
21	<b>CRC Error (C)</b> — R/WC. Indicates that one or more CRC errors occurred with the Link Layer.
20	<b>Disparity Error (D)</b> — R/WC. This field is not used by AHCI.
19	<b>10b to 8b Decode Error (B)</b> — R/WC. Indicates that one or more 10b to 8b decoding errors occurred.
18	<b>Comm Wake (W)</b> — R/WC. Indicates that a Comm Wake signal was detected by the Phy.
17	<b>Phy Internal Error (I)</b> — R/WC. Indicates that the Phy detected some internal error.
16	<b>PhyRdy Change (N)</b> — R/WC. When set to '1' this bit indicates that the internal PhyRdy signal changed state since the last time this bit was cleared. In the PCH, this bit will be set when PhyRdy changes from a 0 → 1 or a 1 → 0. The state of this bit is then reflected in the PxIS.PRCs interrupt status bit and an interrupt will be generated if enabled. Software clears this bit by writing a '1' to it.
15:12	Reserved
11	<b>Internal Error (E)</b> — R/WC. The SATA controller failed due to a master or target abort when attempting to access system memory.
10	<b>Protocol Error (P)</b> — R/WC. A violation of the Serial ATA protocol was detected. <b>Note:</b> The PCH does not set this bit for all protocol violations that may occur on the SATA link.
9	<b>Persistent Communication or Data Integrity Error (C)</b> — R/WC. A communication error that was not recovered occurred that is expected to be persistent. Persistent communications errors may arise from faulty interconnect with the device, from a device that has been removed or has failed, or a number of other causes.
8	<b>Transient Data Integrity Error (T)</b> — R/WC. A data integrity error occurred that was not recovered by the interface.
7:2	Reserved.
1	<b>Recovered Communications Error (M)</b> — R/WC. Communications between the device and host was temporarily lost but was re-established. This can arise from a device temporarily being removed, from a temporary loss of Phy synchronization, or from other causes and may be derived from the PhyNRdy signal between the Phy and Link layers.
0	<b>Recovered Data Integrity Error (I)</b> — R/WC. A data integrity error occurred that was recovered by the interface through a retry operation or other recovery action.

§



# 16 Storage Controller Unit (SCU) Registers (SRV/WS SKUs Only)

The following sections describe the SCU PCI Configuration registers with support for SR-IOV as defined by the *Single Root I/O Virtualization and Sharing Specification*, Revision 1.1.

The SCU includes a single PF configuration space with an SR-IOV extended capability that references up to 31 VF configuration spaces.

Regardless of the SCU type (Single-SCU or Dual-SCU) the SCU always appears to SW as a **single** Physical function with support for SR-IOV as defined by the Single Root I/O Virtualization and Sharing Specification.

For Physical and Virtual Function Configuration Register definitions, refer to [Section 16.2](#) and [Section 16.3](#) respectively.

## 16.1 Register Attribute Definitions

**Table 16-3. Register Base Attribute Definitions**

Attr	Description
RO	<b>Read Only:</b> These bits can only be read by software, writes have no effect. The value of the bits is determined by the hardware only.
R/W	<b>Read / Write:</b> These bits can be read and written by software.
R/W1C	<b>Read / Write 1 to Clear:</b> These bits can be read and cleared by software. Writing a '1' to a bit clears it, while writing a '0' to a bit has no effect. Hardware sets these bits.
WO	<b>Write Only:</b> These bits can only be written by software, reads return zero. <b>Note:</b> Use of this attribute type is deprecated and can only be used to describe bits without persistent state.
RC	<b>Read Clear:</b> These bits can only be read by software, but a read causes the bits to be cleared. Hardware sets these bits. <b>Note:</b> Use of this attribute type is only allowed on legacy functions, as side-effects on reads are not desirable.
RCW	<b>Read Clear / Write:</b> These bits can be read and written by software, but a read causes the bits to be cleared. <b>Note:</b> Use of this attribute type is only allowed on legacy functions, as side-effects on reads are not desirable.
RV	<b>Reserved:</b> These bits are reserved for future expansion and their value must not be modified by software. When writing these bits, software must preserve the value read. The bits are read-only must return '0' when read.



### 16.1.1 Address Attribute Modifier Definitions

Following are the definitions of Address Attribute Modifiers used in this section

Attribute Modifiers specify additional information about the behavior of register bits when used in conjunction with applicable Base Attributes. Bits without a Sticky attribute modifier are set to their default value by a hard reset.

**Table 16-4. Register Attribute Modifier Definitions**

Attr Modifier	Applicable Attr	Description
S	RO (w/ -V), R/W, R/W1C	<b>Sticky:</b> These bits are only re-initialized to their default value by a PWRGD reset. <b>Note:</b> Does not apply to RO (constant) bits.
-K	R/W, WO	<b>Key:</b> These bits control the ability to write other bits (identified with a 'Lock' modifier).
-L	R/W, WO	<b>Lock:</b> Hardware can make these bits "Read Only" using a separate configuration bit or other logic. <b>Note:</b> Mutually exclusive with 'Once' modifier. <b>Note:</b> BIOS <b>must</b> ensure that all registers having -L attribute are programmed correctly.
-O	R/W, WO	<b>Once:</b> After reset, these bits can only be written by software once, after which the bits becomes "Read Only". <b>Note:</b> Mutually exclusive with 'Lock' modifier and does not make sense with 'Variant' or 'Restricted' modifiers.
-R	R/W	<b>Restricted:</b> On a write, the value of these bits may differ from what is provided by software. <b>Note:</b> The use of this modifier should be limited to only where absolutely necessary.
-V	RO, R/W	<b>Variant:</b> The value of these bits can be updated by hardware. <b>Note:</b> R/W1C and RC bits are variant by definition and therefore do not need to be modified.

Modifiers without a leading dash are appended to the end of the Base Attribute for compatibility with industry specs. Modifiers with a leading dash are appended (in alphabetical order) after a single dash when more than one apply. Some Modifiers may be used together to accurately describe the register bit behavior.

**Table 16-5. Register Domain Definitions**

Attr	Description
S	<b>Sticky:</b> These bits are only re-initialized to their default value by a PWRGD reset.
PRST	<b>Primary Reset:</b> These bits are only re-initialized to their default value by a PWRGD or Primary reset signal. These bits are not reset on Secondary bus reset.
FLR	<b>Function Level Reset:</b> In addition to their "normal" reset behavior, these bits are also re-initialized to their default value by a Function Level Reset (initiated by setting the Initiate Function Level Reset bit in <a href="#">Section 16.2.4.5</a> for the PF or in <a href="#">Section 16.3.3.5</a> for the VF).



## 16.2 SCU Physical Function Configuration Registers

Table 16-6. SCU PF PCI Configuration Registers (Sheet 1 of 2)

Configuration Address Offset	Mnemonic and Register Name	Default	Attribute
+000H	SCUPVID — SCU PF Vendor ID Register	8086h	RO
+002H	SCUPDID — SCU PF Device ID Register	See bit description	RO
+004H	SCUPCMD — SCU PF Command Register	0000h	RV, RO, R/W
+006H	SCUPSR — SCU PF Device Status Register	See bit description	RV, RO, R/W1C
+008H	SCUPRID — SCU PF Revision ID Register	00h	RO
+009H	SCUPCCR — SCU PF Class Code Register	10700h	RO
+00CH	SCUPCLSR — SCU PF Cacheline Size Register	00h	R/W
+00DH	SCUPLT — SCU PF Latency Timer Register	00h	RO
+00EH	SCUPHTR — SCU PF Header Type Register	00h	RO
+00FH	SCUPBISTR — SCU PF BIST Register	00h	RV,RO
+010H	SCUPBAR0 — SCU PF Base Address Register 0	See bit description	RV, RO, R/W
+014H	SCUPUBAR0 — SCU PF Upper Base Address Register 0	0h	R/W
+018H	SCUPBAR1 — SCU PF Base Address Register 1	See bit description	RV, RO, R/W
+01CH	SCUPUBAR1 — SCU PF Upper Base Address Register 1	0h	R/W
+020H	SCUPBAR2 — SCU PF Base Address Register 2	1h	RO, R/W
+02CH	SPSVIR — SCU PF Subsystem Vendor ID Register	0h	R/W
+02EH	SPSIR — SCU PF Subsystem ID Register	0h	R/W
+030H	PERBAR — SCU PF Expansion ROM Base Address Register	0h	RV
+034H	SCU PF Cap Ptr — SCU PF Capabilities Pointer Register	98h	R/W
+03CH	SCUPILR — SCU PF Interrupt Line Register	FFh	R/W
+03DH	SCUPIPR — SCU PF Interrupt Pin Register	01h	R/W
+03EH	SCUPMGNT — SCU PF Minimum Grant Register	00h	RO
+03FH	SCUPMLAT — SCU PF Maximum Latency Register	00h	RO
+040H	SCUDIDOV — SCU DID Override Register	0h	RV, R/W
+098H	PF PM Cap ID — PF PM Capability Identifier Register	01h	RO
+099H	PF PM Next Item Ptr — PF PM Next Item Pointer Register	C4h	R/W
+09AH	PAPMCR — SCU PF Power Management Capabilities Register	See bit description	RV, RO
+09CH	PAPMCSR — SCU PF Power Management Control/Status Register"	0h	RO, RV, R/W
+0A0H	P MSIX CAP — PF MSI-X Capability Register	See bit description	RV, RO, R/W
+0A4H	P MSIX TOR — PF MSI-X Table Offset Register	See bit description	RO
+0A8H	P MSIX PBAOR — PF MSI-X Pending Bit Array Offset Register	See bit description	RO
+0ACH–0COH	Reserved		
+0C4H	SCU P I EXP CAPID — SCU PF PCI Express* Capability Identifier Register	10h	RO
+0C5H	SCU P I EXP NXTP — SCU PF I PCI Express* Next Item Pointer Register	A0h	R/W
+0C6H	SCU P I EXP CAP — SCU PF PCI Express* Capabilities Register	See bit description	RO, RV
+0C8H	SCU P I EXP DCAP — SCU PF PCI Express* Device Capabilities Register	See bit description	RV, RO
+0CCH	SCU P I EXP DCTL — SCU PF PCI Express* Device Control Register	See bit description	R/W, RO
+0CEH	SCU P I EXP DSTS — SCU PF PCI Express* Device Status Register	0h	RV, RO, R/W1C
+0DOH	SCU P I EXP LCAP — SCU PF PCI Express* Link Capabilities Register	See bit description	RV, RO
+0D4H	SCU P I EXP LCTL — SCU PF PCI Express* Link Control Register	0h	RO, RV, R/W
+0D6H	SCU P I EXP LSTS — SCU PF PCI Express* Link Status Register	See bit description	RO, RV
+100H	SCU P I ADVERR CAPID — SCU PF PCI Express* Advanced Error Capability Identifier	See bit description	R/W, RO
+104H	SCU P I ERRUNC STS — SCU PF PCI Express* Uncorrectable Error Status	0h	RV, R/W1C
+108H	SCU P I ERRUNC MSK — SCU PF PCI Express* Uncorrectable Error Mask	0h	RV, R/W



**Table 16-6. SCU PF PCI Configuration Registers (Sheet 2 of 2)**

Configuration Address Offset	Mnemonic and Register Name	Default	Attribute
+10CH	SCU P I ERRUNC SEV — SCU PF PCI Express* Uncorrectable Error Severity	See bit description	RV, R/W, RO
+110H	SCU P I ERRCOR STS — SCU PF PCI Express* Correctable Error Status	0h	RV, R/W1C
+114H	SCU P I ERRCOR MSK — SCU PF PCI Express* Correctable Error Mask	See bit description	RV, R/W
+118H	SCU P I ADVERR CTL — SCU PF Advanced Error Control and Capability Register	0h	RV, R/W, RO
+11CH	PADVERR LOG0 — SCU PF PCI Express* Advanced Error Header Log	0h	RO
+120H	PADVERR LOG1 — SCU PF PCI Express* Advanced Error Header Log	0h	RO
+124H	PADVERR LOG2 — SCU PF PCI Express* Advanced Error Header Log	0h	RO
+128H	PADVERR LOG3 — SCU PF PCI Express* Advanced Error Header Log	0h	RO
+138H	PARIDHDR — PF Alternative Routing ID Capability Header	See bit description	R/W, RO
+13CH	PARIDCAP — PF Alternative Routing ID Capability Register	0h	R/W, RV, RO
+13EH	PARIDCTL — PF Alternative Routing ID Control Register	0h	RV, RO
+140H	SRIOVHDR — SR-IOV Extended Capability Header	See bit description	R/W, RO
+144H	SRIOVCAP — SR-IOV Extended Capabilities	0h	RV, RO
+148H	SRIOVCTL — SR-IOV Control Register	0h	RV, R/W
+14AH	SRIOVSTS — SR-IOV Status Register	0h	RV, RO
+14CH	SRIOVIVF — SR-IOV InitialVFs Register	001Fh	RO
+14EH	SRIOVTVF — SR-IOV TotalVFs Register	001Fh	RO
+150H	SRIOVNVF — SR-IOV NumVFs Register	0h	R/W
+152H	SRIOVFDL — SR-IOV Function Dependency Link	0h	RV, RO
+154H	SRIOVFO — SR-IOV First VF Offset Register	See bit description	RO
+156H	SRIOVSTRIDE — SR-IOV VF Stride Register	0001h	RO
+15AH	SRIOVDID — SR-IOV Device ID	0h	RO
+15CH	SRIOVSUPGSR — SR-IOV Supported Page Size Register	See bit description	RO
+160H	SRIOVSYPGSR — SR-IOV System Page Size Register	See bit description	R/W
+164H	SRIOVBAR0 — SR-IOV Base Address Register 0	See bit description	R/W, RV, RO
+168H	SRIOVUBAR0 — SR-IOV Upper Base Address Register 0	0h	R/W
+17CH	SRIOVMIG — SR-IOV VF Migration State Array Offset	0h	RO
+180H	PTPHRHDR — PF TPH Requester Capability Header	See bit description	R/W, RO
+1184H	PTPHRCAP — PF TPH Requester Capability Register	See bit description	RV, RO
+188H	PTPHRCTL — PF TPH Requester Control Register	0h	RV, RO, R/W



## 16.2.1 PCI Standard Header Registers

### 16.2.1.1 SCUPVID—SCU PF Vendor ID Register (SCU – D0:F0)

Address Offset: 00h-01h Attribute: RO  
 Default Value: 8086h Size: 16 bits

Bit	Attr	Default	Description
15:00	RO	8086h	<b>SCU Vendor ID:</b> This is a 16-bit value assigned to Intel

### 16.2.1.2 SCUPDID—SCU PF Device ID Register (SCU – D0:F0)

Address Offset: 02h-03h Attribute: RO  
 Default Value: See Bit Description Size: 16 bits

The SCU Device ID Register reports a function of “SCU DID Override Register (SCUDIDOV)”, Fuses and Straps.

Bit	Attr	Default	Description
15:04	RO-V	0000h	<b>SCU Device ID 15to4:</b> Device ID[15:4].
3:0	RO-V	0h	<b>SCU Device ID 3to0:</b> Device ID[3:0]

### 16.2.1.3 SCUPCMD—SCU PF Command Register (SCU – D0:F0)

Address Offset: 04h-05h Attribute: RV, RO, R/W  
 Default Value: 0000h Size: 16 bits

<b>SCUPCMD</b> Bus: XDevice: 0Function: 0,2Offset: 04h;			
Bit	Attr	Default	Description
15:11	RV	00000b	Reserved
10	R/W FLR	0b	<b>Interrupt Disable:</b> Controls the ability of the SCU to generate INTx interrupt messages. When set, the SCU is prevented from generating INTx interrupt messages and will generate a Deassert_INTx message for any emulation interrupts already asserted.
9	RO	0b	<b>Fast Back to Back Enable:</b> Does not apply to PCI Express. Hard-wired to 0
8	R/W FLR	0b	<b>SERR# Enable:</b> When set, the SCU is allowed to report non-fatal and fatal errors detected by the SCU to the Root Complex. <b>Note:</b> Errors are reported either through this bit or through the PCI Express* specific bits in the “SCU P I EXP DCTL—SCU PF PCI Express* Device Control Register (SCU – D0:F0)”.
7	RO	0b	<b>Address/Data Stepping Control:</b> Does not apply to PCI Express. Hard-wired to 0.
6	R/W FLR	0b	<b>Parity Error Response:</b> When set, the SCU takes normal action in response to a poisoned TLP received from PCI Express. When cleared, parity checking is disabled. <b>Note:</b> If the bit is cleared but the Poisoned TLP Mask is cleared in the “SCU P I ERRUNC MSK—SCU PF PCI Express* Uncorrectable Error Mask (SCU – D0:F0)” register, the SCU will still log the error in the Advanced Error Reporting registers and generate an Uncorrectable Error message.
5	RO	0b	<b>VGA Palette Snoop Enable:</b> Does not apply to PCI Express. Hard-wired to 0.
4	RO	0b	<b>Memory Write and Invalidate Enable:</b> Does not apply to PCI Express. Hard-wired to 0.
3	RO	0b	<b>Special Cycle Enable:</b> Does not apply to PCI Express. Hard-wired to 0.



SCUPCMD Bus: XDevice: 0Function: 0,2Offset: 04h;			
Bit	Attr	Default	Description
2	R/W FLR	0b	<b>Bus Master Enable:</b> When cleared, the SCU is prevented from issuing any memory or I/O read/write requests. Requests other than memory or I/O requests are not controlled by this bit. The SCU will initiate a completion transaction regardless of the setting.
1	R/W FLR	0b	<b>Memory Enable:</b> Controls the SCU PF BAR response to memory transactions. When cleared, the SCU PF does not claim memory transactions. If no function in the device claims the transaction, it results in an unaffiliated unsupported request.
0	R/W FLR	0b	<b>I/O Space Enable:</b> Controls the SCU PF BAR response to I/O transactions. When cleared, the SCU PF does not claim I/O transactions. If no function in the device claims the transaction, it results in an unaffiliated unsupported request.

### 16.2.1.4 SCUPSR—SCU PF Device Register (SCU – D0:F0)

Address Offset: 06h-07h                      Attribute:                      RV, RO, R/W1C  
 Default Value: see bit description                      Size:                      16 bits

Bit	Attr	Default	Description
15	R/W1C FLR	0b	<b>Detected Parity Error:</b> set when the SCU receives a poisoned TLP regardless of the state of the Parity Error Response in the SCUPCMD register.
14	R/W1C FLR	0b	<b>SERR# Asserted:</b> set when the SCU sends an ERR_FATAL or ERR_NONFATAL message, and the SERR Enable bit in the SCUPCMD register is '1'.
13	R/W1C FLR	0b	<b>Received Master Abort:</b> set when the SCU receives a completion with Unsupported Request Completion Status.
12	R/W1C FLR	0b	<b>Received Target Abort:</b> set when the SCU receives a completion with Completer Abort Completion Status.
11	R/W1C FLR	0b	<b>Signaled Target Abort:</b> set when the SCU completes a Request using Completer Abort Completion Status
10:9	RO	00b	<b>DEVSEL# Timing:</b> Does not apply to PCI Express. Hard-wired to 0.
8	R/W1C FLR	0b	<b>Master Data Parity Error:</b> This bit is set by the SCU if its Parity Error Enable bit is set and either of the following two conditions occurs: This bit is set under the following conditions. <ul style="list-style-type: none"> <li>• SCU receives a Poisoned Completion for an Outbound Read Request</li> <li>• SCU transmits a Poisoned TLP for an Outbound Write Request.</li> </ul> If the Parity Error Response bit is cleared in the <a href="#">Section 16.2.1.3</a> , this bit is never set.
7	RO	0b	<b>Fast Back-to-Back:</b> Does not apply to PCI Express. Hard-wired to 0.
6	RV	0b	Reserved
5	RO	0b	<b>66 MHz Capable (C66):</b> Does not apply to PCI Express. Hard-wired to 0
4	RO	1b	<b>Capabilities List:</b> All PCI Express* devices are required to implement the PCI Express* capability structure. Hard-wired to 1.
3	RO-V FLR	0b	<b>Interrupt Status:</b> Indicates that an INTx interrupt is pending internally to the device. <b>Note:</b> Setting the Interrupt Disable bit to a 1 in (bit 10 of SCUPCMD) has no effect on the state of this bit.
2:0	RV	000b	Reserved















### 16.2.2.3 PAPMCR—SCU PF Power Management Capabilities Register (SCU – D0:F0)

Address Offset: 9A–9Bh Attribute: RO, RV  
 Default Value: See bit description Size: 16 bit

Bit	Attr	Default	Description
15:11	RO	00000b	<b>PME Support:</b> This function is not capable of asserting the <b>PME#</b> signal in any state, since <b>PME#</b> is not supported by the SCU.
10	RO	0b	<b>D2 Support:</b> This bit is set to 0b indicating that the SCU does not support the D2 Power Management State
9	RO	0b	<b>D1 Support:</b> This bit is set to 0b indicating that the SCU does not support the D1 Power Management State
8:6	RO	000b	<b>Aux Current:</b> This field is set to 000b indicating that the SCU has no current requirements for the 3.3Vaux signal as defined in the <i>PCI Bus Power Management Interface Specification</i> , Revision 1.2
5	RO	0b	<b>DSI:</b> This field is set to 0b meaning that this function will not require a device specific initialization sequence following the transition to the D0 un-initialized state.
4	RV	0b	Reserved
3	RO	0b	<b>PME Clock:</b> Since the SCU does not support <b>PME#</b> signal generation this bit is cleared to 0b.
2:0	RO	011b	<b>Version:</b> Setting these bits to 011b means that this function complies with <i>PCI Bus Power Management Interface Specification</i> , Revision 1.2

### 16.2.2.4 PAPMCSR—SCU PF Power Management Control/Status Register

Address Offset: 9Ch–9Dh Attribute: RO, RV, R/W  
 Default Value: 00h Size: 16 bit

Bit	Attr	Default	Description
15	RO	0b	<b>PME Status:</b> This function is not capable of asserting the <b>PME#</b> signal in any state, since <b>PME##</b> is not supported by the SCU.
14:9	RV	00h	Reserved
8	RO	0b	<b>PME En:</b> This bit is hard-wired to read-only 0b since this function does not support <b>PME#</b> generation from any power state.
7:4	RV	000000b	Reserved
3	RV	0b	<b>No Soft Reset:</b> This bit is set to zero, therefore, the SCU will perform an internal reset on the D3hot to D0 transition and all of the configuration state will return to the default values.
2	RV	000000b	Reserved
1:0	R/W-R FLR	00b	<b>Power State:</b> This 2-bit field is used both to determine the current power state of a function and to set the function into a new power state. The definition of the values is: 00b = D0 01b = D1 (Unsupported) 10b = D2 (Unsupported) 11b = D3hot The SCU supports only the D0 and D3hot states. The register is designed to discard writes of 01b or 10b, though the write operation should complete on the bus normally. In other words, no state change should occur.







### 16.2.4.3 SCU P I EXP CAP—SCU PF PCI Express\* Capabilities Register (SCU – D0:F0)

Address Offset: C6–C7h Attribute: RO, RV  
 Default Value: See bit description Size: 16 bit

Bit	Attr	Default	Description
15:14	RV	0b	Preserved
13:9	RO	00000b	<b>Interrupt Message Number:</b> This only applies to Root Complex and Switch devices. This register is hardcoded to 0.
8	RO	0b	<b>Slot Implemented:</b> Indicates that the PCI Express* Link associated with this port is connected to a slot. Only valid for root complex and switch downstream ports. Hard-wired to 0
7:4	RO	0000b	<b>Device/Port Type:</b> Indicates the type of PCI Express* logical device. 0000b = PCI Express* Endpoint device
3:0	RO	2h	<b>Capability Version:</b> Indicates PCI-SIG defined PCI Express* capability structure version number SCU supports version 2.

### 16.2.4.4 SCU P I EXP DCAP—SCU PF PCI Express\* Device Capabilities Register (SCU – D0:F0)

Address Offset: C8–CBh Attribute: RO, RV  
 Default Value: See bit description Size: 32 bit

Bit	Attr	Default	Description
31:29	RV	000b	Preserved
28	RO	1b	<b>Function Level Reset Capability (FLR):</b> is required for all VFs and PFs according to the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9.
27:26	RO	00b	<b>Captured Slot Power Limit Scale:</b> Specifies the scale used for the Slot Power Limit Value. This value is set when the Set Slot Power Limit message is received.
25:18	RO	00h	<b>Captured Slot Power Limit Value:</b> In combination with the Slot Power Limit Scale value, specifies the upper limit on power supplied by slot. This value is set when the Set Slot Power Limit message is received.
17:16	RV	00b	Preserved
15	RO	1b	<b>Role-Based Error Reporting:</b> this bit is set to indicate that this device implements the Role Base Error Reporting defined in <i>PCI Express Base Specification</i> , Revision 2.0.
14	RV	0b	Reserved
13	RV	0b	Reserved
12	RV	0b	Reserved
11:9	RO	000b	<b>Endpoint L1 Acceptable Latency:</b> Total acceptable latency that the SCU can withstand due to a transition from L1 state.
8:6	RO	111b	<b>Endpoint L0 Acceptable Latency:</b> Total acceptable latency that the SCU can withstand due to a transition from L0s to L0 state.
5	RO	0b	<b>Extended Tag Field Supported:</b> The SCU does support generation of 8-bit Tags.
4:3	RO	00b	<b>Phantom Functions Supported</b> The SCU does not use phantom functions to extend the number of outstanding requests.
2:0	RO	011b	<b>Max Payload Size Supported:</b> Indicates that the SCU can support a max payload of 1 KB







### 16.2.4.7 SCU P I EXP LCAP—SCU PF PCI Express\* Link Capabilities Register (SCU – D0:F0)

Address Offset: D0–D3h Attribute: RO, RV  
 Default Value: See bit description Size: 32 bit

Bit	Attr	Default	Description
31:24	RO	00h	<b>Port #:</b> PCI Express* port number.
23:22	RV	0h	Reserved
21	RO	0b	<b>Link Bandwidth Notification Capability (LBNC):</b> Not supported.
20	RO	0b	<b>Data Link Layer Link Active Reporting Capable (DLLARC):</b> Not supported.
19	RO	0b	<b>Surprise Down Error Reporting Capable (SDERC):</b> Not supported.
18	RO	0b	<b>Clock Power Management (CPM): IOSF clock gating.</b>
17:15	RO	000b	<b>L1 Exit Latency (L1EL):</b>
14:12	RO	000b	<b>L0s Exit Latency (L0SEL):</b>
11:10	RO	11b	<b>Active State Link PM Support:</b>
9:4	RO	1h	<b>Maximum Link Width (MLW):</b> This device supports a maximum width of x8.
3:0	RO	1h	<b>Maximum Link Speed (MLS):</b> The PCI Express* Link operates at 2.5 Gb/s.

### 16.2.4.8 SCU P I EXP LCTL—SCU PF PCI Express\* Link Control Register (SCU – D0:F0)

Address Offset: D4–D5h Attribute: RO, RV, R/W  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:8	RV	00h	Reserved
7	R/W	0b	<b>Extended Synch:</b> When set forces extended transmissions of FTS ordered sets in FTS and extra TS2 at exit from L1 prior to entering L0. This mode provides external devices monitoring the link time to achieve bit and symbol lock before the link enters L0 state and resumes communication.
6	R/W	0b	<b>Common Clock Configuration:</b> When set indicates that this component and the component at the opposite end of this Link are operating with a distributed common reference clock. This bit used to report the correct L0s and L1 Exit Latencies in the PCIE LCAP register
5	RO	0b	<b>Retrain Link:</b> Not Applicable to endpoints. Hard-wired to 0
4	RO	0b	<b>Link Disable:</b> Not Applicable to endpoints. Hard-wired to 0
3	R/W	0b	<b>Read Completion Boundary (RCB) Control:</b> Indicates the Root Complex's RCB.
2	RV	0b	Reserved
1:0	R/W	00b	<b>Active State PM Control:</b> This field controls the level of active state PM supported on the given PCI Express* Link.





### 16.2.5.2 SCU P I ERRUNC STS—SCU PF PCI Express\* Uncorrectable Error Status (SCU – D0:F0)

Address Offset: 104–107h  
Default Value: 00000000h

Attribute: RV, R/W1C  
Size: 32 bit

Bit	Attr	Default	Description
31:23	RV	000h	Reserved
22	R/W1CS	0b	<b>Uncorrectable Internal Error Status:</b> As a receiver, set whenever an Internal Bus Command Parity Error is detected. The Header is logged.
21	RV	0b	Reserved
20	R/W1CS	0b	<b>Unsupported Request Error Status:</b> As a receiver, Set whenever an unsupported request is detected. The Header is logged.
19	RV	0b	<b>ECRC Check:</b> As a receiver, set when ECRC check fails. The Header is logged. ECRC checking is not supported.
18	R/W1CS	0b	<b>Malformed TLP:</b> As a receiver, set whenever a malformed TLP is detected. The Header is logged.
17	RV	0b	<b>Receiver Overflow:</b> Set if PCI Express receive buffers overflow.
16	R/W1CS	0b	<b>Unexpected Completion:</b> As a receiver, set whenever a completion is received that does not match the SCU requestor ID or outstanding Tag. The Header is logged.
15	R/W1CS	0b	<b>Completer Abort:</b> As a completer, set whenever an internal agent signals a data abort. The header is logged.
14	R/W1CS	0b	<b>Completion Timeout:</b> As a requester, set whenever an outbound Non Posted Request does not receive a completion within 16-32 ms.
13	RV	0b	<b>Flow Control Protocol Error Status:</b> Set whenever a flow control protocol error is detected.
12	R/W1CS	0b	<b>Poisoned TLP Received:</b> As a receiver, set whenever a poisoned TLP is received from PCI Express. The header is logged. Note that internal queue errors are not covered by this bit, they are logged by the target of the transaction.
11:5	RV	00h	Reserved
4	RV	0b	<b>Data Link Protocol Error:</b> Set whenever a data link protocol error is detected.
3:0	RV	0h	Reserved

### 16.2.5.3 SCU P I ERRUNC MSK—SCU PF PCI Express\* Uncorrectable Error Mask (SCU – D0:F0)

Address Offset: 108–10Bh  
Default Value: 00000000h

Attribute: RV, R/W  
Size: 32 bit

Bit	Attr	Default	Description
31:23	RV	000h	Reserved
22	R/WS	1b	<b>Uncorrectable Internal Error Mask:</b> When '1' error reporting is masked.
21	RV	0b	Reserved
20	R/WS	0b	<b>Unsupported Request Error Mask:</b> When '1' error reporting is masked.
19	RV	0b	<b>ECRC Check Error Mask:</b> When '1' error reporting is masked.
18	R/WS	0b	<b>Malformed TLP Error Mask:</b> When '1' error reporting is masked.
17	RV	0b	<b>Receiver Overflow Error Mask:</b> When '1' error reporting is masked.
16	R/WS	0b	<b>Unexpected Completion Error Mask:</b> When '1' error reporting is masked.
15	R/WS	0b	<b>Completer Abort Error Mask:</b> When '1' error reporting is masked.
14	R/WS	0b	<b>Completion Time Out Error Mask:</b> When '1' error reporting is masked.



Bit	Attr	Default	Description
13	RV	0b	<b>Flow Control Protocol Error Mask:</b> When '1' error reporting is masked.
12	R/WS	0b	<b>Poisoned TLP Received Error Mask:</b> When '1' error reporting is masked.
11:5	RV	00h	Reserved.
4	RV	0b	<b>Data Link Protocol Error Mask:</b> When '1' error reporting is masked.
3:0	RV	0h	Reserved

#### 16.2.5.4 SCU P I ERRUNC SEV—SCU PF PCI Express\* Uncorrectable Error Severity (SCU – D0:F0)

Address Offset: 10C–10Fh      Attribute: RV, R/W, RO  
 Default Value: See bit description      Size: 32 bit

Bit	Attr	Default	Description
31:23	RV	000h	Reserved
22	R/WS	1b	<b>Uncorrectable Internal Error Severity (UIES):</b>
21	RV	0b	Reserved
20	R/WS	0b	<b>Unsupported Request Error Severity:</b>
19	RV	0b	<b>ECRC Check Severity:</b>
18	R/WS	1b	<b>Malformed TLP Severity:</b>
17	RO	1b	<b>Receiver Overflow Severity:</b>
16	R/WS	0b	<b>Unexpected Completion Severity:</b>
15	R/WS	0b	<b>Completer Abort Severity:</b>
14	R/WS	0b	<b>Completion Time Out Severity:</b>
13	RO	1b	<b>Flow Control Protocol Error Severity:</b>
12	R/WS	0b	<b>Poisoned TLP Received Severity:</b>
11:5	RV	00h	Reserved
4	RO	1b	<b>Data Link Protocol Error Severity:</b>
3:0	RV	0h	Reserved

#### 16.2.5.5 SCU P I ERRCOR STS—SCU PF PCI Express\* Correctable Error Status (SCU – D0:F0)

Address Offset: 110–113h      Attribute: RV, R/W1C  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:14	RV	0	Reserved
13	R/W1CS	0b	<b>Advisory Non-Fatal Error Status</b>
12	RV	0b	<b>Replay Timer Timeout Status:</b> Set whenever a replay timer timeout occurs.
11:9	RV	000b	Reserved
8	RV	0b	<b>REPLAY NUM Rollover Status:</b> Set whenever the replay number rolls over from 11 to 00.
7	RV	0b	<b>Bad DLLP Status:</b> Sets this bit on CRC errors on DLLP.
6	RV	0b	<b>Bad TLP Status:</b> Sets this bit on CRC errors or sequence number out of range on TLP.
5:1	RV	00h	Reserved
0	RV	0b	<b>Receiver Error Status:</b> Set whenever the physical layer detects a receiver error.



### 16.2.5.6 SCU P I ERRCOR MSK—SCU PF PCI Express\* Correctable Error Mask (SCU – D0:F0)

Address Offset: 114–117h Attribute: RV, R/W  
 Default Value: See bit description Size: 32 bit

Bit	Attr	Default	Description
31:14	RV	0	Reserved
13	R/WS	1b	<b>Advisory Non-Fatal Error Mask:</b> this bit is set by default to enable compatibility with software that does not comprehend Role-Based Error Reporting.
12	RV	0b	<b>Replay Timer Timeout Mask:</b>
11:9	RV	000b	Reserved
8	RV	0b	<b>REPLAY NUM Rollover Mask:</b>
7	RV	0b	<b>Bad DLLP Mask:</b>
6	RV	0b	<b>Bad TLP Mask:</b>
5:1	RV	00h	Reserved
0	RV	0b	<b>Receiver Error Mask:</b>

### 16.2.5.7 SCU P I ADVERR CTL—SCU PF Advanced Error Control and Capability Register (SCU – D0:F0)

Address Offset: 118–11Bh Attribute: RV, R/W, RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:9	RV	0	Reserved
8	R/WS	0b	<b>ECRC Check Enable:</b> When set enables ECRC checking.
7	RO	0b	<b>ECRC Check Capable:</b> Indicates the SCU is <b>not</b> capable of checking ECRC.
6	R/WS	0b	<b>ECRC Generation Enable:</b> When set enables ECRC generation.
5	RO	0b	<b>ECRC Generation Capable:</b> Indicates the SCU is <b>not</b> capable of generating ECRC.
4:0	ROS-V	00000b	<b>The First Error Pointer:</b> Identifies the bit position of the first error reported in the <a href="#">Section 16.2.5.2</a> register. <b>Note:</b> This register will not update until all bits in the ERRUNC STS register are cleared.

### 16.2.5.8 PADVERR LOGO—SCU PF PCI Express\* Advanced Error Header Log (SCU – D0:F0)

Address Offset: 11C–11Fh Attribute: RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:0	ROS-V	0	<b>1st DWord of the Header for the PCIe packet in error (HDRLOGDW0):</b> Once an error is logged in this register, it remains locked for further error logging until the time the software clears the status bit that cause the header log, that is, the error pointer is rearmed to log again.





### 16.2.6.2 PARIDCAP—PF Alternative Routing ID Capability Register (SCU – D0:F0)

Address Offset: 13C–13Dh                      Attribute: R/W, RV, RO  
 Default Value: 0000h                      Size: 16 bit

Bit	Attr	Default	Description
15:8	R/WL PRST	00h	<b>Next Function Number:</b> The function number of the next highest numbered PF in a multi-function device.
7:2	RV	00h	Reserved
1	RO	0b	<b>ACS Functional Groups Capability:</b> SCU does not support.
0	RO	0b	<b>MFVC Functional Groups Capability:</b> SCU does not support.

### 16.2.6.3 PARIDCTL—PF Alternative Routing ID Control Register (SCU – D0:F0)

Address Offset: 13E–13Fh                      Attribute: RV, RO  
 Default Value: 0000h                      Size: 16 bit

Bit	Attr	Default	Description
15:7	RV	00h	Reserved
6:4	RO	000b	<b>Function Group:</b> Hardwired to Zero as SCU does not support Function Groups.
3:2	RV	00b	Reserved
1	RO	0b	<b>ACS Functional Groups Enable:</b> Hardwired to Zero as SCU does not support.
0	RO	0b	<b>MFVC Functional Groups Enable:</b> Hardwired to Zero as SCU does not support.

## 16.2.7 PF SR-IOV Extended Capability Structure

This section describes the PCI Express\* Extended Configuration Space registers that make up the SR-IOV Extended Capability Structure.

### 16.2.7.1 SRIOVHDR—SR-IOV Extended Capability Header (SCU – D0:F0)

Address Offset: 140–143h                      Attribute: R/W, RO  
 Default Value: See bit description                      Size: 32 bit

Bit	Attr	Default	Description
31:20	R/WL PRST	000h	<b>Next Capability Offset:</b> This field contains 000h as this is the end of the extended capability list for the SCU.
19:16	RO	1h	<b>Capability Version:</b> This is set to 1h for the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9.
15:0	RO	0010h	<b>PCI Express* Extended Capability ID:</b> The PCI SIG has assigned 0010h to the SR-IOV extended capability.



### 16.2.7.2 SRIOVCAP—SR-IOV Extended Capabilities (SCU – D0:F0)

Address Offset: 144–147h Attribute: RV, RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:21	RO	000h	<b>VF Migration Interrupt Message Number (VMIMN):</b> Hardwired to zero as the SCU does not support Multi-Root I/O Virtualization (MR-IOV).
20:1	RV	00000h	Reserved
0	RO	0b	<b>VF Migration Capable:</b> The SCU does not support MR-IOV; therefore, does not support VF Migration.

### 16.2.7.3 SRIOVCTL—SR-IOV Control Register (SCU – D0:F0)

Address Offset: 148–149h Attribute: RV, R/W  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:5	RV	000h	Reserved
4	R/W FLR	0b	<b>ARI Capable Hierarchy:</b> This bit is a hint to the device that it is in an ARI capable hierarchy. It is permitted to use this bit to determine stride and first-VF-offset. This bit is R/W in the lowest numbered physical function, and RV in other functions. This is only a hint, and the SCU does <i>not</i> use this bit.
3	R/W FLR	0b	<b>VF MSE:</b> Controls the SCU VF BAR response to memory transactions. When cleared, the SCU VFs do not claim memory transactions. If no function in the device claims the transaction, it results in an unaffiliated unsupported request.
2	R/W FLR	0b	<b>VF Migration Interrupt Enable:</b> Enables/Disables VF Migration State Change Interrupt. <b>Note:</b> Not supported by the SCU.
1	R/W FLR	0b	<b>VF Migration Enable:</b> Enables/Disables VF Migration Support. <b>Note:</b> Not supported by the SCU.
0	R/W FLR	0b	<b>VF Enable:</b> Enables/Disables VFs. When this bit is clear (0b) all VFs are disabled (VFs shall not master transactions and VFs shall not claim configuration, memory or I/O transactions). If no function in the device claims the transaction, it results in an unaffiliated unsupported request.

### 16.2.7.4 SRIOVSTS—SR-IOV Status Register (SCU – D0:F0)

Address Offset: 14A–14Bh Attribute: RV, RO  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:1	RV	000h	Reserved
0	RO	0	<b>VF Migration Status:</b> <b>Note:</b> Since the SCU does not support VF Migration, this bit will be hardwired to zero.



### 16.2.7.5 SRIOVIVF—SR-IOV InitialVFs Register (SCU – D0:F0)

Address Offset: 14C–14Dh Attribute: RO  
 Default Value: 001Fh Size: 16 bit

Bit	Attr	Default	Description
15:0	RO	001Fh	<b>InitialVFs:</b> Indicates to SR software the number of VFs that are initially associated with the Physical Function (PF). <b>Note:</b> For SR-IOV, this register must always be equal to the Section 16.2.7.6 as VF Migration is not supported.

### 16.2.7.6 SRIOVTVF—SR-IOV TotalVFs Register (SCU – D0:F0)

Address Offset: 14E–14Fh Attribute: RO  
 Default Value: 001Fh Size: 16 bit

Bit	Attr	Default	Description
15:0	RO	001Fh	<b>TotalVFs:</b> Indicates to SR software the maximum number of VFs that could be associated with the Physical Function (PF).

### 16.2.7.7 SRIOVNVF—SR-IOV NumVFs Register (SCU – D0:F0)

Address Offset: 150–151h Attribute: R/W  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:0	R/W FLR	0000h	<b>NumVFs:</b> Controls the number of VFs software assigns to the PF. Software sets NumVFs as part of the process of creating VFs. This number of VFs shall be visible in the PCI Express* fabric after both NumVFs is set to a valid value and VF Enable is set to one. <b>Note:</b> NumVFs may only be written while VF Enable is Clear. If NumVFs is written when VF Enable is Set, the results are undefined. If the SMU or SDMA attempt to master a transaction on PCI using an invalid VFi, a Master-Abort is returned to the requester (SMU or SDMA) and the transaction will <b>not</b> be forwarded to the PCI bus. The VFi is invalid under any of the following conditions: <ol style="list-style-type: none"> <li>VF Enable is Clear, or</li> <li>VFi &gt; TotalVFs, or</li> <li>VFi &gt; NumVFs, or</li> <li>Bus Master Enable for that VFi is Clear.</li> </ol>

### 16.2.7.8 SRIOVFDL—SR-IOV Function Dependency Link (SCU – D0:F0)

Address Offset: 152–153h Attribute: RV, RO  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:8	RV	00h	Reserved
7:0	RO	00h	<b>Function Dependency Link:</b> As the SCU is a single function device, this is set to 00H.





**16.2.7.13 SRIOVSYPGSR—SR-IOV System Page Size Register (SCU – D0:F0)**

Address Offset: 160–163h Attribute: R/W, RV, RO  
 Default Value: See bit description Size: 32 bit

Bit	Attr	Default	Description
31:0	R/W FLR	1h	<p><b>System Page Size:</b> The SCU supports the 4-KB, 8-KB, 64-KB, 256-KB, 1-MB and 4-MB page sizes. By setting one and only one of these bits, the OS can configure the SCU to one of its' supported page sizes. The default page size is 4-KB.</p> <p><b>Note:</b> A given bit n set in this register corresponds to support for a page size of 2<sup>(n+12)</sup> bytes. For example, the setting of bit 0 indicates support for a 4-KB page size. VF Enable of Section 16.2.7.3 must be zero when this register is written.</p>

**16.2.7.14 SRIOVBAR0—SR-IOV Base Address Register 0 (SCU – D0:F0)**

Address Offset: 164–167h Attribute: R/W, RV, RO  
 Default Value: See bit description Size: 32 bit

Bit	Attr	Default	Description																																
31:14	R/W-V FLR	00000h	<p><b>SRIOV Base Address 0:</b> These bits are used to define the actual locations that the VFs of the SCU function are to respond to when addressed from the PCI bus. <i>PCI Local Bus Specification</i>, Revision 3.0 compliant scanning of this register, at a minimum reveals a 16KB memory window. However, if the System Page Size is programmed larger than 16KB, the size of the memory window must adjust to two times the System Page Size as described in Section 16.2.7.13, "SRIOVSYPGSR—SR-IOV System Page Size Register (SCU – D0:F0)" on page 591. This would mean that bits above bit 13 in this register may respond as Reserved (RV) rather than Read/Write (R/W) opening up a window larger than 16KB. In addition, the window size doubles for a Dual-SCU configuration.</p> <p><b>System Page Size Bits responding as RV Window Size (per VF)</b></p> <table border="1"> <thead> <tr> <th colspan="2">Single-SCU</th> <th colspan="2">Dual-SCU</th> </tr> <tr> <th>System Page Size</th> <th>Bit Range</th> <th>System Page Size</th> <th>Bit Range</th> </tr> </thead> <tbody> <tr> <td>4 KB</td> <td>None</td> <td>16 KB</td> <td>14:13</td> </tr> <tr> <td>8 KB</td> <td>None</td> <td>32 KB</td> <td>16:15</td> </tr> <tr> <td>64 KB</td> <td>16:14</td> <td>128 KB</td> <td>17:16</td> </tr> <tr> <td>256 KB</td> <td>18:14</td> <td>512 KB</td> <td>19:16</td> </tr> <tr> <td>1 MB</td> <td>20:14</td> <td>2 MB</td> <td>21:16</td> </tr> <tr> <td>4 MB</td> <td>22:14</td> <td>8 MB</td> <td>23:16</td> </tr> </tbody> </table> <p>The reported window size is the window size per VF and may also be given by the following equations:                      Single-SCU:  <math>Window\_Size\_Per\_VF = \text{Max}(16KB, 2 * System\_Page\_Size)</math>                      Dual-SCU:  <math>Window\_Size\_Per\_VF = 2 * \text{Max}(16KB, 2 * System\_Page\_Size)</math>                      The total size of the SRIOVBAR0 window will be this size multiplied by the number of enabled VFs:  <math>Window\_Size\_Total = VFs * Window\_Size\_Per\_VF</math>                      The base address of any VF having VF index of VFi is:  <math>VF\_Base = SRIOVBAR0 + ((VFi - 1) * Window\_Size\_Per\_VF)</math></p>	Single-SCU		Dual-SCU		System Page Size	Bit Range	System Page Size	Bit Range	4 KB	None	16 KB	14:13	8 KB	None	32 KB	16:15	64 KB	16:14	128 KB	17:16	256 KB	18:14	512 KB	19:16	1 MB	20:14	2 MB	21:16	4 MB	22:14	8 MB	23:16
Single-SCU		Dual-SCU																																	
System Page Size	Bit Range	System Page Size	Bit Range																																
4 KB	None	16 KB	14:13																																
8 KB	None	32 KB	16:15																																
64 KB	16:14	128 KB	17:16																																
256 KB	18:14	512 KB	19:16																																
1 MB	20:14	2 MB	21:16																																
4 MB	22:14	8 MB	23:16																																
13:4	RV	00h	Reserved																																
3	RO	1b	<b>Prefetchable Indicator:</b> If set, defines the memory space as prefetchable.																																
2:1	RO	10b	<b>Type Indicator:</b> Memory Window is locatable anywhere in 64 bit address space																																
0	RO	0b	<b>Memory Space Indicator:</b> This bit field describes memory or I/O space base address. This bit must be hard-wired to zero as SR-IOV does not support I/O space.																																

**16.2.7.15 SRIOVUBAR0—SR-IOV Upper Base Address Register 0 (SCU – D0:F0)**

Address Offset: 168–16Bh                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bit

Bit	Attr	Default	Description
31:0	R/W FLR	00000000h	<b>SR-IOV Upper Base Address 0:</b> Together with the SR-IOV Base Address 0 these bits define the actual location the VMs will respond to when addressed from the PCI bus

**16.2.7.16 SRIOVFMIG—SR-IOV VF Migration State Array Offset (SCU – D0:F0)**

Address Offset: 17C–17Fh                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bit

Bit	Attr	Default	Description
31:0	RO	0h	<b>VF Migration State Array Offset:</b> This value is hardwired to zero as the SCU is not VF Migration Capable.

**16.2.8 PF TPH Requester Extended Capability Structure**

This section describes the PCI Express\* Extended Configuration Space registers that make up the TPH (TLP Processing Hints) Requester Extended Capability Structure.

**16.2.8.1 PTPHRHDR—PF TPH Requester Capability Header (SCU – D0:F0)**

Address Offset: 180–183h                      Attribute: R/W, RO  
 Default Value: See bit description                      Size: 32 bit

Bit	Attr	Default	Description
31:20	R/WL PRST	140h	<b>Next Capability Offset:</b> This field points to the next item in the extended capabilities list, the SR-IOV extended capability.
19:16	RO	1h	<b>Capability Version:</b> This is set to 1h for the most current version of the specification.
15:0	RO	0017h	<b>PCI Express* Extended Capability ID:</b> The PCI SIG has assigned 0017h to the TPH Requester extended capability.



### 16.2.8.2 PTPHRCAP—PF TPH Requester Capability Register (SCU – D0:F0)

Address Offset: 184–187h                      Attribute:                      RV, RO  
 Default Value: See bit description                      Size:                      32 bit

Bit	Attr	Default	Description
31:27	RV	00h	Reserved
26:16	RO	000h	<b>ST Table Size:</b> ST Table is not present.
15:11	RV	00h	Reserved
10:9	RO	0h	<b>ST Table Location:</b> ST Table is not present.
8	RO	0b	<b>Extended TPH Requester Supported:</b> SCU does <i>not</i> generate requests with the TPH TLP Prefix.
7:3	RV	00h	Reserved
2	RO	1b	<b>Device Specific Mode Supported:</b> SCU supports the Device Specific Mode of operation.
1	RO	0b	<b>Interrupt Vector Mode Supported:</b> SCU does <i>not</i> support the Interrupt Vector Mode of operation.
0	RO	1b	<b>No ST Mode Supported:</b> SCU supports the No ST Mode of operation.

### 16.2.8.3 PTPHCTL—PF TPH Requester Control Register (SCU – D0:F0)

Address Offset: 188–18Bh                      Attribute:                      RV, RO, R/W  
 Default Value: 00000000h                      Size:                      32 bit

Bit	Attr	Default	Description
31:10	RV	00h	Reserved
9	RO	0b	<b>Extended TPH Enable:</b> The SCU is never Extended TPH enabled.
8	R/W FLR	0b	<b>TPH Requester Enable:</b> When set, the SCU is permitted to use TPH.
7:3	RV	00h	Reserved
2:0	R/W FLR	0h	<b>ST Mode Select:</b> Sets the ST mode of operation. 000b = No ST Mode 001b = Interrupt Vector Mode (not supported; behaves as No ST Mode) 010b = Device Specific Mode Others = Reserved (behave as No ST Mode)



## 16.3 SCU Virtual Function Configuration Registers

The following sections describe the SCU VF configuration registers.

**Table 16-7. SCU VF PCI Configuration Registers (Sheet 1 of 2)**

Configuration Address Offset	Register Name and Neumonics	Default	Attributes
+000H	SCUVID x—SCU Vendor ID Register x	FFFFh	RO
+002H	SCUVDID x—SCU VF Device ID Register x	FFFFh	RO
+004H	SCUVFCMD x—SCU VF Command Register x	0h	RO, RV, R/W
+006H	SCUVR x—SCU VF Status Register x	See bit description	RO, R/W1C, RV
+008H	SCUVRID x—SCU VF Revision ID Register	0h	RO
+009H	SCUVCCR x—SCU VF Class Code Register x	10700h	RO
+00CH	SCUVCLSR x—SCU VF Cacheline Size Register x	0h	RO
+00DH	SCUULT x—SCU VF Latency Timer Register x	0h	RO
+00EH	SCUVHTR x—SCU VF Header Type Register x	0h	RO
+02CH	SVSVIR x—SCU VF Subsystem Vendor ID Register x	0h	RO
+02EH	SVSIR x—SCU VF Subsystem ID Register x	0h	RO
+034H	SCU VF Cap Ptr x—SCU VF Capabilities Pointer Register x	C4h	R/W
+03CH	SCUVILR x—SCU VF Interrupt Line Register x	0h	RO
+03DH	SCUVIPR x—SCU VF Interrupt Pin Register x	0h	RO
+03EH	SCUVMGNT x—SCU VF Minimum Grant Register x	0h	RO
+03FH	SCUMLAT x—SCU VF Maximum Latency Register x	0h	RO
+0A0H	V MSIX CAP x—VF MSI-X Capability Register x	See bit description	R/W, RV, RO
+0A4H	SV MSIX TOR x—VF MSI-X Table Offset Register x	See bit description	RO
+0A8H	V MSIX PBAOR x—VF MSI-X Pending Bit Array Offset Register x	See bit description	RO
+0ACH	V MSIX CR x—VF MSI-X Control Register x	0h	RV, R/W
+0C4H	SCU V I EXP CAPID x—SCU VF PCI Express* Capability Identifier Register x	10h	RO
+0C5H	SCU V I EXP NXTP x—SCU VF I PCI Express* Next Item Pointer Register x	A0h	R/W
+0C6H	SCU V I EXP CAP x—SCU VF PCI Express* Capabilities Register x	See bit description	RO, RV
+0C8H	SCU V I EXP DCAP x—SCU VF PCI Express* Device Capabilities Register x	See bit description	RV, RO
+0CCH	SCU V I EXP DCTL x—SCU VF PCI Express* Device Control Register x	0h	RO, R/W
+0CEH	SCU V I EXP DSTS x—SCU VF PCI Express* Device Status Register x	0h	RO, R/W1C, RV
+0D0H	SCU V I EXP LCAP x—SCU VF PCI Express* Link Capabilities Register x	See bit description	RO, RV
+0D4H	SCU V I EXP LCTL x—SCU VF PCI Express* Link Control Register x	0h	RO, RV
+0D6H	SCU V I EXP LSTS x—SCU VF PCI Express* Link Status Register x	0h	RV
+100H	SCU V I AERR CAPID x—SCU VF PCI Express* Advanced Error Capability Identifier x	See bit description	RO, R/W
+104H	SCU V I ERRUNC STS x—SCU VF PCI Express* Uncorrectable Error Status x	0h	RV, R/W1C
+108H	SCU V I ERRUNC MSK x—SCU VF PCI Express* Uncorrectable Error Mask x	0h	RV
+10CH	SCU V I ERRUNC SEV x—SCU VF PCI Express* Uncorrectable Error Severity x	0h	RV
+110H	SCU V I ERRCOR STS x—SCU VF PCI Express* Correctable Error Status x	0h	RV, R/W1C
+114H	SCU V I ERRCOR MSK x—SCU VF PCI Express* Correctable Error Mask x	0h	RV
+118H	SCU V I ADVERR CTL x—SCU VF Advanced Error Control and Capability Register x)	0h	RV, RO
+11CH	VADVERR LOG0 x—SCU VF PCI Express* Advanced Error Header Log x	0h	RO
+120H	VADVERR LOG1 x—SCU VF PCI Express* Advanced Error Header Log x	0h	RO





### 16.3.1.3 SCUVCMD x—SCU VF Command Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 04–05h  
 Default Value: 0000h

Attribute: RO, RV, R/W  
 Size: 16 bit

Bit	Attr	Default	Description
15:11	RV	00000b	Reserved
10	RO	0b	<b>Interrupt Disable:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field is hardwired to 0b for all VFs. <b>Note:</b> This bit does not apply to VFs.
9	RO	0b	<b>Fast Back to Back Enable:</b> Does not apply to PCI Express. Hard-wired to 0
8	RO	0b	<b>SERR# Enable:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field is hardwired to 0b for all VFs. In addition the functionality associated with the setting of this bit in the <a href="#">Section 16.2.1.3</a> will apply to all VFs.
7	RO	0b	<b>Address/Data Stepping Control:</b> Does not apply to PCI Express. Hard-wired to 0.
6	RO	0b	<b>Parity Error Response:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field is hardwired to 0b for all VFs. In addition the functionality associated with the setting of this bit in the <a href="#">Section 16.2.1.3</a> will apply to all VFs.
5	RO	0b	<b>VGA Palette Snoop Enable:</b> Does not apply to PCI Express. Hard-wired to 0.
4	RO	0b	<b>Memory Write and Invalidate Enable:</b> Does not apply to PCI Express. Hard-wired to 0.
3	RO	0b	<b>Special Cycle Enable:</b> Does not apply to PCI Express. Hard-wired to 0.
2	R/W FLR	0b	<b>Bus Master Enable:</b> When cleared, the SCU is prevented from issuing any memory or I/O read/write requests. Requests other than memory or I/O requests are not controlled by this bit. The SCU will initiate a completion transaction regardless of the setting. <b>Note:</b> Transactions for a VF that has its Bus Master Enable set must not be blocked by transactions for VFs that have their Bus Master Enable cleared.
1	RO	0b	<b>Memory Enable:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field is hardwired to 0b for all VFs.
0	RO	0b	<b>I/O Space Enable:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field is hardwired to 0b for all VFs.



### 16.3.1.4 SCU\_VSR x—SCU VF Status Register x (D1-3 : F0-7, D4: F0-6)

Address Offset: 06–07h Attribute: RO, R/W1C, RV  
 Default Value: See bit description Size: 16 bit

Bit	Attr	Default	Description
15	R/W1C FLR	0b	<b>Detected Parity Error:</b> set when the SCU receives a poisoned TLP regardless of the state of the Parity Error Response in the SCUPCMD register.
14	R/W1C FLR	0b	<b>SERR# Asserted:</b> set when the SCU sends an ERR FATAL or ERR NONFATAL message, and the SERR Enable bit in the SCUPCMD register is '1'.
13	R/W1C FLR	0b	<b>Received Master Abort:</b> set when the SCU receives a completion with Unsupported Request Completion Status.
12	R/W1C FLR	0b	<b>Received Target Abort:</b> set when the SCU receives a completion with Completer Abort Completion Status.
11	R/W1C FLR	0b	<b>Signaled Target Abort:</b> set when the SCU completes a Request using Completer Abort Completion Status
10:9	RO	00b	<b>DEVSEL# Timing:</b> Does not apply to PCI Express. Hard-wired to 0.
8	R/W1C FLR	0b	<b>Master Data Parity Error:</b> This bit is set by the SCU if its Parity Error Enable bit is set and either of the following two conditions occurs: <ul style="list-style-type: none"> <li>• SCU receives a Poisoned Completion for an Outbound Read Request</li> <li>• SCU transmits a Poisoned TLP for an Outbound Write Request.</li> </ul> If the Parity Error Response bit is cleared in the "SCUPCMD—SCU PF Command Register (SCU – D0:F0)", this bit is never set.
7	RO	0b	<b>Fast Back-to-Back:</b> Does not apply to PCI Express. Hard-wired to 0.
6	RV	0b	Reserved
5	RO	0b	<b>66 MHz Capable (C66):</b> Does not apply to PCI Express. Hard-wired to 0
4	RO	1b	<b>Capabilities List:</b> All PCI Express* devices are required to implement the PCI Express* capability structure. Hard-wired to 1.
3	RO	0b	<b>Interrupt Status:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field is hardwired to 0b for all VFs. <b>Note:</b> This bit does not apply to VFs.
2:0	RV	0b	Reserved.

### 16.3.1.5 SCU\_VRID x—SCU VF Revision ID Register (D1-3 : F0-7, D4 : F0-6)

Address Offset: 08h Attribute: RO  
 Default Value: 00h Size: 8 bit

Bit	Attr	Default	Description
07:00	RO-V	00h	<b>SCU Revision:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 states that this field should be viewed as a Vendor Defined Extension to the Device ID. In the SCU, this is implemented as a read-only copy of the PF register ("SCUPRID—SCU PF Revision ID Register (SCU – D0:F0)").



### 16.3.1.6 SCUVCCR x—SCU VF Class Code Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 09–0Bh Attribute: RO  
 Default Value: 10700h Size: 24 bit

Bit	Attr	Default	Description
23:00	RO	10700h	<b>Class Code:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field return the same value as the <a href="#">Section 16.2.1.6</a> for all VFs.

### 16.3.1.7 SCUVCLSR x—SCU VF Cacheline Size Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 0Ch Attribute: RO  
 Default Value: 00h Size: 8 bit

Bit	Attr	Default	Description
07:00	RO	00h	<b>SCU Cacheline Size:</b> For PCI Express, this field has no impact on device functionality. Furthermore, for all VFs, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to 00h.

### 16.3.1.8 SCUVLT x—SCU VF Latency Timer Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 0Dh Attribute: RO  
 Default Value: 00h Size: 8 bit

Bit	Attr	Default	Description
07:00	RO	00h	<b>Programmable Latency Timer:</b> The latency timer does not apply to PCI Express. Hard-wired 0.

### 16.3.1.9 SCUVHTR x—SCU VF Header Type Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 0Eh Attribute: RO  
 Default Value: 00h Size: 8 bit

Bit	Attr	Default	Description
7	RO	0b	<b>Multi-Function Device (MFD):</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 states that this field must be 00h for VFs.
06:00	RO	00h	<b>Header Type:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 states that this field must be 00h for VFs.

### 16.3.1.10 SVSVIR x—SCU VF Subsystem Vendor ID Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 2C–2Dh Attribute: RO  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:0	RO-V	0h	<b>Subsystem Vendor ID:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that when read, this read only register must return the same value as the <a href="#">Section 16.2.1.16</a> for all VFs.











**16.3.3.2 SCU V I EXP NXTP x—SCU VF I PCI Express\* Next Item Pointer Register x (D1-3 : F0-7, D4 : F0-6)**

Address Offset: C5h Attribute: R/W  
 Default Value: A0h Size: 8 bit

Bit	Attr	Default	Description
7:0	R/WL PRST	A0h	<b>Next Item Pointer:</b> This field provides an offset into the function's configuration space pointing to the next item in the function's capability list which in the SCU is the MSI-X extended capabilities header.

**16.3.3.3 SCU V I EXP CAP x—SCU VF PCI Express\* Capabilities Register x (D1-3 : F0-7, D4 : F0-6)**

Address Offset : C6–C7h Attribute RO, RV  
 Default Value: See bit description Size: 16 bit

Bit	Attr	Default	Description
15:14	RV	00b	Reserved
13:9	RO	00000b	<b>Interrupt Message Number:</b> This only applies to Root Complex and Switch devices. This register is hardcoded to 0.
8	RO	0b	<b>Slot Implemented:</b> Indicates that the PCI Express* Link associated with this port is connected to a slot. Only valid for root complex and switch downstream ports. Hard-wired to 0
7:4	RO	0000b	<b>Device/Port Type:</b> Indicates the type of PCI Express* logical device. 0000b = PCI Express* Endpoint device
3:0	RO	2h	<b>Capability Version:</b> Indicates PCI-SIG defined PCI Express* capability structure version number SCU supports version 2h.









Default Value: See bit description      Size: 32 bit

Bit	Attr	Default	Description
31:20	R/WL PRST	138h	<b>Next Capability Pointer:</b> This field points to the Alternative Routing ID extended capability.
19:16	RO	1h	<b>Capability Version Number:</b> PCI Express Advanced Error Reporting Extended Capability Version Number.
15:0	RO	0001h	<b>Advanced Error Capability ID:</b> PCI Express Extended Capability ID indicating Advanced Error Reporting Capability.

#### 16.3.4.2 SCU V I ERRUNC STS x—SCU VF PCI Express\* Uncorrectable Error Status x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 104–107h      Attribute: RV, R/W1CS  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:21	RV	0	Reserved
20	R/W1CS	0b	<b>Unsupported Request Error Status:</b> As a receiver, Set whenever an unsupported request is detected. The Header is logged.
19	RV	0b	<b>ECRC Check:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
18	RV	0b	<b>Malformed TLP:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
17	RV	0b	<b>Receiver Overflow:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
16	R/W1CS	0b	<b>Unexpected Completion:</b> As a receiver, set whenever a completion is received that does not match the SCU requestor ID or outstanding Tag. The Header is logged.
15	R/W1CS	0b	<b>Completer Abort:</b> As a completer, set whenever an internal agent signals a data abort. The header is logged.
14	R/W1CS	0b	<b>Completion Timeout:</b> As a requester, set whenever an outbound Non Posted Request does not receive a completion within 16-32 ms.
13	RV	0b	<b>Flow Control Protocol Error Status:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
12	R/W1CS	0b	<b>Poisoned TLP Received:</b> As a receiver, set whenever a poisoned TLP is received from PCI Express. The header is logged. Note that internal queue errors are not covered by this bit, they are logged by the Configuration target of the transaction.
11:6	RV	0b	Reserved
5	RV	0b	<b>Surprise Down Error:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
4	RV	0b	<b>Data Link Protocol Error:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
3:0	RV	0h	Reserved





### 16.3.4.4 SCU V I ERRUNC SEV x—SCU VF PCI Express\* Uncorrectable Error Severity x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 10C–10Fh  
Default Value: 00000000h

Attribute: RV  
Size: 32 bit

Bit	Attr	Default	Description
31:22	RV	0	Reserved
21	RV	0b	<b>ACS Violation Error Severity:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.4</a> applies to all of the VFs.
20	RV	0b	<b>Unsupported Request Error Severity:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.4</a> applies to all of the VFs.
19	RV	0b	<b>ECRC Check Error Severity:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
18	RV	0b	<b>Malformed TLP Error Severity:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
17	RV	0b	<b>Receiver Overflow Error Severity:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
16	RV	0b	<b>Unexpected Completion Error Severity:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.4</a> applies to all of the VFs.
15	RV	0b	<b>Completer Abort Error Severity:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.4</a> applies to all of the VFs.
14	RV	0b	<b>Completion Time Out Error Severity:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.4</a> applies to all of the VFs.
13	RV	0b	<b>Flow Control Protocol Error Severity:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
12	RV	0b	<b>Poisoned TLP Received Error Field:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.4</a> applies to all of the VFs.
11:6	RV	00h	Reserved
5	RV	0b	<b>Surprise Down Error Severity:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
4	RV	0b	<b>Data Link Protocol Error Severity:</b> As a non-function specific error, the <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros.
3:0	RV	0h	Reserved





### 16.3.4.7 SCU V I ADVERR CTL x—SCU VF Advanced Error Control and Capability Register x) (D1-3 : F0-7, D4 : F0-6)

Address Offset: 118–11Bh Attribute: RV, RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:9	RV	0	Reserved
8	RV	0b	<b>ECRC Check Enable:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.7</a> applies to all of the VFs.
7	RO	0b	<b>ECRC Check Capable:</b> Indicates the SCU is <b>not</b> capable of checking ECRC.
6	RV	0b	<b>ECRC Generation Enable:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 requires that this field be hardwired to all zeros and that the setting of this field in <a href="#">Section 16.2.5.7</a> applies to all of the VFs.
5	RO	0b	<b>ECRC Generation Capable:</b> Indicates the SCU is <b>not</b> capable of generating ECRC.
4:0	ROS-V	00000b	<b>The First Error Pointer:</b> Identifies the bit position of the first error reported in <a href="#">Section 16.3.4.2</a> register. <b>Note:</b> This register will not update until all bits in the ERRUNC STS register are cleared.

## 16.3.5 Advanced Error Header Log Registers

### 16.3.5.1 VADVERR LOG0 x—SCU VF PCI Express\* Advanced Error Header Log x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 11C–11Fh Attribute: RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:0	ROS-V	0	<b>1st DWord of the Header for the PCIe packet in error (HDRLOGDW0):</b> Once an error is logged in this register, it remains locked for further error logging until the time the software clears the status bit that cause the header log, that is, the error pointer is rearmed to log again.

### 16.3.5.2 VADVERR LOG1 x—SCU VF PCI Express\* Advanced Error Header Log x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 120–123h Attribute: RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:0	ROS-V	0	<b>2nd DWord of the Header for the PCIe packet in error (HDRLOGDW1):</b> Once an error is logged in this register, it remains locked for further error logging until the time the software clears the status bit that cause the header log, that is, the error pointer is rearmed to log again.



### 16.3.5.3 VADVERR LOG2 x—SCU VF PCI Express\* Advanced Error Header Log x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 124–127h Attribute: RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:0	ROS-V	0	<b>3rd DWord of the Header for the PCIe packet in error (HDRLOGDW2):</b> Once an error is logged in this register, it remains locked for further error logging until the time the software clears the status bit that cause the header log, that is, the error pointer is rearmed to log again.

### 16.3.5.4 VADVERR LOG3 x—SCU VF PCI Express\* Advanced Error Header Log x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 128–12Bh Attribute: RO  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:0	ROS-V	0	<b>4th DWord of the Header for the PCIe packet in error (HDRLOGDW3):</b> Once an error is logged in this register, it remains locked for further error logging until the time the software clears the status bit that cause the header log, that is, the error pointer is rearmed to log again.

## 16.3.6 VF Alternative Routing ID Extended Capability Structure

This section describes the PCI Express\* Extended Configuration Space registers that make up the Alternative Routing ID Extended Capability Structure.

### 16.3.6.1 VARIDHDR x—VF Alternative Routing ID Capability Header x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 138–13Bh Attribute: RO, R/W  
 Default Value: see bit description Size: 32 bit

Bit	Attr	Default	Description
31:20	R/WL PRST	180h	<b>Next Capability Offset:</b> This field contains 180h which points to the next item in the extended capabilities list, the TPH requester extended capability.
19:16	RO	1h	<b>Capability Version:</b> This is set to 1h for the most current version of the specification.
15:0	RO	000Eh	<b>PCI Express* Extended Capability ID:</b> The PCI SIG has assigned 000Eh to the ARI extended capability.

### 16.3.6.2 VARIDCAP x—VF Alternative Routing ID Capability Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 13C–13Dh Attribute: RV, RO  
 Default Value: 0000h Size: 16 bit

Bit	Attr	Default	Description
15:8	RV	00h	<b>Next Function Number:</b> The <i>Single Root I/O Virtualization and Sharing Specification</i> , Revision 0.9 states that this field is undefined for VFs.
7:2	RV	00h	Reserved
1	RO	0b	<b>ACS Functional Groups Capability:</b> SCU does not support.
0	RO	0b	<b>MFVC Functional Groups Capability:</b> SCU does not support.



### 16.3.6.3 VARIDCTL x—VF Alternative Routing ID Control Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 13E–13Fh                      Attribute:                      RV, RO  
 Default Value: 0000h                      Size:                      16 bit

Bit	Attr	Default	Description
15:7	RV	000h	Reserved
6:4	RO	0h	<b>Function Group:</b> Hardwired to Zero as SCU does not support Function Groups.
3:2	RV	00b	Reserved
1	RO	0b	<b>ACS Functional Groups Enable:</b> Hardwired to Zero as SCU does not support.
0	RO	0b	<b>MFVC Functional Groups Enable:</b> Hardwired to Zero as SCU does not support.

## 16.3.7 VF TPH Requester Extended Capability Structure

### 16.3.7.1 VTPHRHDR x—VF TPH Requester Capability Header x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 180–183h                      Attribute:                      RO  
 Default Value: See bit description                      Size:                      32 bit

Bit	Attr	Default	Description
31:20	RO	000h	<b>Next Capability Offset:</b> This field contains 000h indicating the end of the SCUs VF Extended capability list.
19:16	RO	1h	<b>Capability Version:</b> This is set to 1h for the most current version of the specification.
15:0	RO	0017h	<b>PCI Express* Extended Capability ID:</b> The PCI SIG has assigned 0017h to the TPH Requester extended capability.

### 16.3.7.2 VTPHRCAP x—VF TPH Requester Capability Register x (D1-3 : F0-7, D4 : F0-6)

Address Offset: 184–187h                      Attribute:                      RV, RO  
 Default Value: See bit description                      Size:                      32 bit

Bit	Attr	Default	Description
31:27	RV	00h	Reserved
26:16	RO	000h	<b>ST Table Size:</b> ST Table is not present.
15:11	RV	00h	Reserved
10:9	RO	0h	<b>ST Table Location:</b> ST Table is not present.
8	RO	0b	<b>Extended TPH Requester Supported:</b> SCU does <i>not</i> generate requests with the TPH TLP Prefix.
7:3	RV	00h	Reserved
2	RO	1b	<b>Device Specific Mode Supported:</b> SCU supports the Device Specific Mode of operation.
1	RO	0b	<b>Interrupt Vector Mode Supported:</b> SCU does <i>not</i> support the Interrupt Vector Mode of operation.
0	RO	1b	<b>No ST Mode Supported:</b> SCU supports the No ST Mode of operation.





Bit	Attr	Default	Description
01	R/W	0b	<b>SGPIO Serial Clock Rate Select (SSCRS):</b> This bit selects the frequency of the SGPIO serial clock. 0 = The SGPIO serial clock runs at 99.8 KHz 1 = The SGPIO serial clock runs at 49.9 KHz.
00	R/W	0b	<b>SGPIO Functionality Enable (SFE):</b> 1 = The SGPIO bus pins (SCLOCK, SLOAD, SDATAIN and SDATAOUT) are used for SGPIO signaling. 0 = The SGPIO pins are used for Direct LED controls. (Default)

## 16.4.2 SGPBR- SGPIO Programmable Blink Register

Address Offset: SCUPBAR1+1404h      Attribute: R/W, RO  
Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:16	RO	0000h	Reserved.
15:12	R/W	0000b	<b>Programmable Pattern B High Duration Time (PPBHDT):</b> This field is used to program the high duration time in millisecond for pattern B. 0000 = 125 ms 0001 = 250 ms 0010 = 375 ms 0011 = 500 ms 0100 = 625 ms 0101 = 750 ms 0110 = 875 ms 0111 = 1000 ms 1000 = 1125 ms 1001 = 1250 ms 1010 = 1375 ms 1011 = 1500 ms 1100 = 1625 ms 1101 = 1750 ms 1110 = 1875 ms 1111 = 2000 ms
11:8	R/W	0000b	<b>Programmable Pattern B Low Duration Time (PPBLDT):</b> This field is used to program the low duration time in millisecond for pattern B. 0000 = 125 ms 0001 = 250 ms 0010 = 375 ms 0011 = 500 ms 0100 = 625 ms 0101 = 750 ms 0110 = 875 ms 0111 = 1000 ms 1000 = 1125 ms 1001 = 1250 ms 1010 = 1375 ms 1011 = 1500 ms 1100 = 1625 ms 1101 = 1750 ms 1110 = 1875 ms 1111 = 2000 ms



Bit	Attr	Default	Description
7:4	R/W	0000b	<p><b>Programmable Pattern A High Duration Time (PPAHDT):</b> This field is used to program the high duration time in millisecond for pattern A.</p> <p>0000 = 125 ms            0001 = 250 ms            0010 = 375 ms            0011 = 500 ms            0100 = 625 ms            0101 = 750 ms            0110 = 875 ms            0111 = 1000 ms            1000 = 1125 ms            1001 = 1250 ms            1010 = 1375 ms            1011 = 1500 ms            1100 = 1625 ms            1101 = 1750 ms            1110 = 1875 ms            1111 = 2000 ms</p>
3:0	R/W	0000b	<p><b>Programmable Pattern A Low Duration Time (PPALDT):</b> This field is used to program the low duration time in millisecond for pattern A.</p> <p>0000 = 125 ms            0001 = 250 ms            0010 = 375 ms            0011 = 500 ms            0100 = 625 ms            0101 = 750 ms            0110 = 875 ms            0111 = 1000 ms            1000 = 1125 ms            1001 = 1250 ms            1010 = 1375 ms            1011 = 1500 ms            1100 = 1625 ms            1101 = 1750 ms            1110 = 1875 ms            1111 = 2000 ms</p>

### 16.4.3 SGSDLR- SGPIO Start Drive Lower Register

Address Offset: SCUPBAR1+1408h      Attribute: R/W, RO  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:15	RO	0000h	Reserved.
14:12	R/W	011b	<p><b>Output 3 Select Bits (O3SB):</b> This bit field selects which <i>Input[7:0]</i> of the Multiplexer Block is selected to drive <b>Output 3</b>.</p> <p>000 = Input[0]            001 = Input[1]            010 = Input[2]            011 = Input[3]            100 = Input[4]            101 = Input[5]            110 = Input[6]            111 = Input[7]</p>
11	RO	0b	Reserved.
10:08	R/W	010b	<p><b>Output 2 Select Bits (O2SB):</b> This bit field selects which <i>Input[7:0]</i> of the Multiplexer Block is selected to drive <b>Output 2</b>.</p> <p>000 = Input[0]            001 = Input[1]            010 = Input[2]            011 = Input[3]            100 = Input[4]            101 = Input[5]            110 = Input[6]            111 = Input[7]</p>



Bit	Attr	Default	Description
07	RO	0b	Reserved.
06:04	R/W	001b	<b>Output 1 Select Bits (O1SB):</b> This bit field selects which <b>Input[7:0]</b> of the Multiplexer Block is selected to drive <b>Output 1</b> . 000 = Input[0] 001 = Input[1] 010 = Input[2] 011 = Input[3] 100 = Input[4] 101 = Input[5] 110 = Input[6] 111 = Input[7]
03	RO	0b	Reserved.
02:00	R/W	000b	<b>Output 0 Select Bits (O0SB):</b> This bit field selects which <b>Input[7:0]</b> of the Multiplexer Block is selected to drive <b>Output 0</b> . 000 = Input[0] 001 = Input[1] 010 = Input[2] 011 = Input[3] 100 = Input[4] 101 = Input[5] 110 = Input[6] 111 = Input[7]

#### 16.4.4 SGSDUR- SGPIO Start Drive Upper Register

Address Offset: SCUPBAR1 + 140Ch      Attribute: R/W, RO  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:15	RO	0000h	Reserved.
14:12	R/W	111b	<b>Output 7 Select Bits (O7SB):</b> This bit field selects which <b>Input[7:0]</b> of the Multiplexer Block is selected to drive <b>Output 7</b> . 000 = Input[0] 001 = Input[1] 010 = Input[2] 011 = Input[3] 100 = Input[4] 101 = Input[5] 110 = Input[6] 111 = Input[7]
11	RO	0b	Reserved.
10:08	R/W	110b	<b>Output 6 Select Bits (O6SB):</b> This bit field selects which <b>Input[7:0]</b> of the Multiplexer Block is selected to drive <b>Output 6</b> . 000 = Input[0] 001 = Input[1] 010 = Input[2] 011 = Input[3] 100 = Input[4] 101 = Input[5] 110 = Input[6] 111 = Input[7]
07	RO	0b	Reserved.
06:04	R/W	101b	<b>Output 5 Select Bits (O5SB):</b> This bit field selects which <b>Input[7:0]</b> of the Multiplexer Block is selected to drive <b>Output 5</b> . 000 = Input[0] 001 = Input[1] 010 = Input[2] 011 = Input[3] 100 = Input[4] 101 = Input[5] 110 = Input[6] 111 = Input[7]



Bit	Attr	Default	Description
03	RO	0b	Reserved.
02:00	R/W	100b	<b>Output 4 Select Bits (O4SB):</b> This bit field selects which <b>Input[7:0]</b> of the Multiplexer Block is selected to drive <b>Output 4</b> . 000 = Input[0] 001 = Input[1] 010 = Input[2] 011 = Input[3] 100 = Input[4] 101 = Input[5] 110 = Input[6] 111 = Input[7]

### 16.4.5 SGSIDLR- SGPIO Input Data Lower Register

Address Offset: SCUPBAR1 + 1410h      Attribute: RO  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:15	RO	0000h	Reserved.
14:12	RO	000b	<b>Drive 3 input data (D3ID):</b>
11	RO	0b	Reserved.
10:08	RO	000b	<b>Drive 2 input data (D2ID):</b>
07	RO	0b	Reserved.
06:04	RO	000b	<b>Drive 1 input data (D1ID):</b>
03	RO	0b	Reserved.
02:00	RO	000b	<b>Drive 0 input data (D0ID):</b>

### 16.4.6 SGSIDUR- SGPIO Input Data Upper Register

Address Offset: SCUPBAR1 + 1414h      Attribute: RO  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:15	RO	0000h	Reserved.
14:12	RO	000b	<b>Drive 7 input data. (D7ID):</b>
11	RO	0b	Reserved.
10:08	RO	000b	<b>Drive 6 input data (D6ID):</b>
07	RO	0b	Reserved.
06:04	RO	000b	<b>Drive 5 input data (D5ID):</b>
03	RO	0b	Reserved.
02:00	RO	000b	<b>Drive 4 input data (D4ID):</b>

### 16.4.7 SGVSCR- SGPIO Vendor Specific Code Register

Address Offset: SCUPBAR1 + 1418h      Attribute: R/W, RO  
 Default Value: 00000000h      Size: 32 bit

Bit	Attr	Default	Description
31:04	RO	0000000h	Reserved.



Bit	Attr	Default	Description
03:00	R/W	0h	<b>Vendor Specific data (VSD):</b> The four bits vendor-specific code is the first four bits shifted on the SLoad pin after SLoad is driven high.



### 16.4.8 SGODSR[0-7]—SGPIO Output Data Select Register[0-7]

Address Offset: SCUPBAR1+1420h Attribute: R/W, RO  
 SCUPBAR1+1424h  
 SCUPBAR1+1428h  
 SCUPBAR1+142Ch  
 SCUPBAR1+1430h  
 SCUPBAR1+1434h  
 SCUPBAR1+1438h  
 SCUPBAR1+143Ch  
 Default Value: 00000000h Size: 32 bit

Bit	Attr	Default	Description
31:12	RO	00000h	Reserved.
11	R/W	0b	<b>OD2 JOG Enable (OD2JE):</b> When set this bit enables the jog mechanism to be applied on the input selected by bits[09:08]. When cleared, the selected input is not altered.
10	R/W	0b	<b>Invert OD2 Selected Input (IOD2SI):</b> When set this bit causes the input selected by bits[09:08] to be inverted. When cleared, the selected input is not altered.
09:08	R/W	00b	<b>OD2 Input Select (OD2IS):</b> This field selects the input that drives output OD2 of Drive N, where N = 0–7. 00 = Fixed - High 01 = Programmable pattern A 10 = Programmable pattern B 11 = Reserved
07	R/W	0b	<b>OD1 JOG Enable (OD1JE):</b> When set this bit enables the jog mechanism to be applied on the input selected by bits[05:04]. When cleared, the selected input is not altered.
06	R/W	0b	<b>Invert OD1 Selected Input (IOD1SI):</b> When set this bit causes the input selected by bits[05:04] to be inverted. When cleared, the selected input is not altered.
05:04	R/W	00b	<b>OD1 Input Select (OD1IS):</b> This field selects the input that drives output OD1 of Drive N, where N = 0–7. 00 = Fixed - High 01 = Programmable pattern A 10 = Programmable pattern B 11 = FSENG Activity
03	R/W	0b	<b>OD0 JOG Enable (OD0JE):</b> When set this bit enables the jog mechanism to be applied on the input selected by bits[01:00]. When cleared, the selected input is not altered.
02	R/W	0b	<b>Invert OD0 Selected Input (IOD0SI):</b> When set this bit causes the input selected by bits[01:00] to be inverted. When cleared, the selected input is not altered.
01:00	R/W	00b	<b>OD0 Input Select (OD0IS):</b> This field selects the input that drives output OD0 of Drive N, where N = 0–7. 00 = Fixed - High 01 = Programmable pattern A 10 = Programmable pattern B 11 = FSENG Activity

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# 17 EHCI Controller Registers (D29:F0, D26:F0)

## 17.1 USB EHCI Configuration Registers (USB EHCI—D29:F0, D26:F0)

**Note:** Register address locations that are not shown in Table 17-1 should be treated as Reserved (see Table 9-3 for details).

**Note:** Prior to BIOS initialization of the PCH USB subsystem, the EHCI controllers will appear as Function 7. After BIOS initialization, the EHCI controllers will be Function 0.

**Table 17-1. USB EHCI PCI Register Address Map (USB EHCI—D29:F0, D26:F0) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default Value	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0290h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	20h	RO
0Ah	SCC	Sub Class Code	03h	RO
0Bh	BCC	Base Class Code	0Ch	RO
0Dh	PMLT	Primary Master Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	80h	RO
10h–13h	MEM_BASE	Memory Base Address	00000000h	R/W, RO
2Ch–2Dh	SVID	USB EHCI Subsystem Vendor Identification	XXXXh	R/W
2Eh–2Fh	SID	USB EHCI Subsystem Identification	XXXXh	R/W
34h	CAP_PTR	Capabilities Pointer	50h	RO
3Ch	INT_LN	Interrupt Line	00h	R/W
3Dh	INT_PN	Interrupt Pin	See register description	RO
50h	PWR_CAPID	PCI Power Management Capability ID	01h	RO
51h	NXT_PTR1	Next Item Pointer	58h	R/W
52h–53h	PWR_CAP	Power Management Capabilities	C9C2h	R/W
54h–55h	PWR_CNTL_STS	Power Management Control/Status	0000h	R/W, R/WC, RO
58h	DEBUG_CAPID	Debug Port Capability ID	0Ah	RO
59h	NXT_PTR2	Next Item Pointer #2	98h	RO
5Ah–5Bh	DEBUG_BASE	Debug Port Base Offset	20A0h	RO
60h	USB_RELNUM	USB Release Number	20h	RO
61h	FL_ADJ	Frame Length Adjustment	20h	R/W
62h–63h	PWAKE_CAP	Port Wake Capabilities	01FFh	R/W







### 17.1.4 PCISTS—PCI Status Register (USB EHCI—D29:F0, D26:F0)

Address Offset: 06h–07h  
 Default Value: 0290h

Attribute: R/WC, RO  
 Size: 16 bits

**Note:** For the writable bits, software must write a 1 to clear bits that are set. Writing a 0 to the bit has no effect.

Bit	Description
15	<b>Detected Parity Error (DPE)</b> — R/WC. 0 = No parity error detected. 1 = This bit is set by the PCH when a parity error is seen by the EHCI controller, regardless of the setting of bit 6 or bit 8 in the Command register or any other conditions.
14	<b>Signaled System Error (SSE)</b> — R/WC. 0 = No SERR# signaled by the PCH. 1 = This bit is set by the PCH when it signals SERR# (internally). The SER_EN bit (bit 8 of the Command Register) must be 1 for this bit to be set.
13	<b>Received Master Abort (RMA)</b> — R/WC. 0 = No master abort received by EHC on a memory access. 1 = This bit is set when EHC, as a master, receives a master abort status on a memory access. This is treated as a Host Error and halts the DMA engines. This event can optionally generate an SERR# by setting the SERR# Enable bit.
12	<b>Received Target Abort (RTA)</b> — R/WC. 0 = No target abort received by EHC on memory access. 1 = This bit is set when EHC, as a master, receives a target abort status on a memory access. This is treated as a Host Error and halts the DMA engines. This event can optionally generate an SERR# by setting the SERR# Enable bit (D29:F0, D26:F0:04h, bit 8).
11	Signaled Target Abort (STA) — RO. This bit is used to indicate when the EHCI function responds to a cycle with a target abort. There is no reason for this to happen, so this bit is hardwired to 0.
10:9	DEVSEL# Timing Status (DEVT_STS) — RO. This 2-bit field defines the timing for DEVSEL# assertion.
8	<b>Master Data Parity Error Detected (DPED)</b> — R/WC. 0 = No data parity error detected on USB2.0 read completion packet. 1 = This bit is set by the PCH when a data parity error is detected on a USB 2.0 read completion packet on the internal interface to the EHCI host controller and bit 6 of the Command register is set to 1.
7	Fast Back to Back Capable (FB2BC) — RO. Hardwired to 1.
6	User Definable Features (UDF) — RO. Hardwired to 0.
5	66 MHz Capable (66 MHz _CAP) — RO. Hardwired to 0.
4	Capabilities List (CAP_LIST) — RO. Hardwired to 1 indicating that offset 34h contains a valid capabilities pointer.
3	<b>Interrupt Status</b> — RO. This bit reflects the state of this function's interrupt at the input of the enable/disable logic. 0 = This bit will be 0 when the interrupt is deasserted. 1 = This bit is a 1 when the interrupt is asserted. The value reported in this bit is independent of the value in the Interrupt Enable bit.
2:0	Reserved





### 17.1.10 HEADTYP—Header Type Register (USB EHCI—D29:F0, D26:F0)

Address Offset: 0Eh                      Attribute: RO  
 Default Value: 80h                      Size: 8 bits

Bit	Description
7	<b>Multi-Function Device</b> — RO. When set to '1' indicates this is a multifunction device: 0 = Single-function device 1 = Multi-function device.
6:0	Configuration Layout. Hardwired to 00h, which indicates the standard PCI configuration layout.

### 17.1.11 MEM\_BASE—Memory Base Address Register (USB EHCI—D29:F0, D26:F0)

Address Offset: 10h–13h                      Attribute: R/W, RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:10	<b>Base Address</b> — R/W. Bits [31:10] correspond to memory address signals [31:10], respectively. This gives 1-KB of locatable memory space aligned to 1-KB boundaries.
9:4	Reserved
3	<b>Prefetchable</b> — RO. Hardwired to 0 indicating that this range should not be prefetched.
2:1	<b>Type</b> — RO. Hardwired to 00b indicating that this range can be mapped anywhere within 32-bit address space.
0	<b>Resource Type Indicator (RTE)</b> — RO. Hardwired to 0 indicating that the base address field in this register maps to memory space.

### 17.1.12 SVID—USB EHCI Subsystem Vendor ID Register (USB EHCI—D29:F0, D26:F0)

Address Offset: 2Ch–2Dh                      Attribute: R/W  
 Default Value: XXXXh                      Size: 16 bits  
 Reset: None

Bit	Description
15:0	<b>Subsystem Vendor ID (SVID)</b> — R/W. This register, in combination with the USB 2.0 Subsystem ID register, enables the operating system to distinguish each subsystem from the others. <b>Note:</b> Writes to this register are enabled when the WRT_RDONLY bit (D29:F0, D26:F0:80h, bit 0) is set to 1.















Bit	Description
19	<p><b>Intel SMI on Frame List Rollover</b> — RO. This bit is a shadow bit of Frame List Rollover bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 3) in the USB2.0_STS register.</p> <p><b>Note:</b> To clear this bit system software must write a 1 to the Frame List Rollover bit in the USB2.0_STS register.</p>
18	<p><b>Intel SMI on Port Change Detect</b> — RO. This bit is a shadow bit of Port Change Detect bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 2) in the USB2.0_STS register.</p> <p><b>Note:</b> To clear this bit system software must write a 1 to the Port Change Detect bit in the USB2.0_STS register.</p>
17	<p><b>Intel SMI on USB Error</b> — RO. This bit is a shadow bit of USB Error Interrupt (USBERRINT) bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 1) in the USB2.0_STS register.</p> <p><b>Note:</b> To clear this bit system software must write a 1 to the USB Error Interrupt bit in the USB2.0_STS register.</p>
16	<p><b>Intel SMI on USB Complete</b> — RO. This bit is a shadow bit of USB Interrupt (USBINT) bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 0) in the USB2.0_STS register.</p> <p><b>Note:</b> To clear this bit system software must write a 1 to the USB Interrupt bit in the USB2.0_STS register.</p>
15	<p><b>Intel SMI on BAR Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is 1 and Intel SMI on BAR (D29:F0, D26:F0:6Ch, bit 31) is 1, then the host controller will issue an Intel SMI.</p>
14	<p><b>Intel SMI on PCI Command Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is 1 and Intel SMI on PCI Command (D29:F0, D26:F0:6Ch, bit 30) is 1, then the host controller will issue an Intel SMI.</p>
13	<p><b>Intel SMI on OS Ownership Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1 AND the OS Ownership Change bit (D29:F0, D26:F0:6Ch, bit 29) is 1, the host controller will issue an Intel SMI.</p>
12:6	Reserved.
5	<p><b>Intel SMI on Async Advance Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1, and the Intel SMI on Async Advance bit (D29:F0, D26:F0:6Ch, bit 21) is a 1, the host controller will issue an Intel SMI immediately.</p>
4	<p><b>Intel SMI on Host System Error Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1, and the Intel SMI on Host System Error (D29:F0, D26:F0:6Ch, bit 20) is a 1, the host controller will issue an Intel SMI.</p>
3	<p><b>Intel SMI on Frame List Rollover Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1, and the Intel SMI on Frame List Rollover bit (D29:F0, D26:F0:6Ch, bit 19) is a 1, the host controller will issue an Intel SMI.</p>
2	<p><b>Intel SMI on Port Change Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1, and the Intel SMI on Port Change Detect bit (D29:F0, D26:F0:6Ch, bit 18) is a 1, the host controller will issue an Intel SMI.</p>
1	<p><b>Intel SMI on USB Error Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1, and the Intel SMI on USB Error bit (D29:F0, D26:F0:6Ch, bit 17) is a 1, the host controller will issue an Intel SMI immediately.</p>
0	<p><b>Intel SMI on USB Complete Enable</b> — R/W.</p> <p>0 = Disable.                      1 = Enable. When this bit is a 1, and the Intel SMI on USB Complete bit (D29:F0, D26:F0:6Ch, bit 16) is a 1, the host controller will issue an Intel SMI immediately.</p>













## 17.2 Memory-Mapped I/O Registers

The EHCI memory-mapped I/O space is composed of two sets of registers: Capability Registers and Operational Registers.

**Note:** The PCH EHCI controller will not accept memory transactions (neither reads nor writes) as a target that are locked transactions. The locked transactions should not be forwarded to PCI as the address space is known to be allocated to USB.

**Note:** When the EHCI function is in the D3 PCI power state, accesses to the USB 2.0 memory range are ignored and result a master abort. Similarly, if the Memory Space Enable (MSE) bit (D29:F0, D26:F0:04h, bit 1) is not set in the Command register in configuration space, the memory range will not be decoded by the PCH enhanced host controller (EHC). If the MSE bit is not set, the PCH must default to allowing any memory accesses for the range specified in the BAR to go to PCI. This is because the range may not be valid and, therefore, the cycle must be made available to any other targets that may be currently using that range.

### 17.2.1 Host Controller Capability Registers

These registers specify the limits, restrictions and capabilities of the host controller implementation. Within the host controller capability registers, only the structural parameters register is writable. These registers are implemented in the suspend well and is only reset by the standard suspend-well hardware reset, not by HCRESET or the D3-to-D0 reset.

**Note:** Note that the EHCI controller does not support as a target memory transactions that are locked transactions. Attempting to access the EHCI controller Memory-Mapped I/O space using locked memory transactions will result in undefined behavior.

**Note:** Note that when the USB2 function is in the D3 PCI power state, accesses to the USB2 memory range are ignored and will result in a master abort. Similarly, if the Memory Space Enable (MSE) bit is not set in the Command register in configuration space, the memory range will not be decoded by the Enhanced Host Controller (EHC). If the MSE bit is not set, the EHC will not claim any memory accesses for the range specified in the BAR.

**Table 17-2. Enhanced Host Controller Capability Registers**

MEM_BASE + Offset	Mnemonic	Register	Default	Type
00h	CAPLENGTH	Capabilities Registers Length	20h	RO
02h-03h	HCVERSION	Host Controller Interface Version Number	0100h	RO
04h-07h	HCSPARAMS	Host Controller Structural Parameters	00204208h (D29:F0) 00203206 (D26:F0)	R/W (special), RO
08h-0Bh	HCCPARAMS	Host Controller Capability Parameters	00006881h	RO

**Note:** "Read/Write Special" means that the register is normally read-only, but may be written when the WRT\_RDONLY bit is set. Because these registers are expected to be programmed by BIOS during initialization, their contents must not get modified by HCRESET or D3-to-D0 internal reset.



### 17.2.1.1 CAPLENGTH—Capability Registers Length Register

Offset: MEM\_BASE + 00h Attribute: RO  
 Default Value: 20h Size: 8 bits

Bit	Description
7:0	<b>Capability Register Length Value</b> — RO. This register is used as an offset to add to the Memory Base Register (D29:F0, D26:F0:10h) to find the beginning of the Operational Register Space. This field is hardwired to 20h indicating that the Operation Registers begin at offset 20h.

### 17.2.1.2 HCIVERSION—Host Controller Interface Version Number Register

Offset: MEM\_BASE + 02h–03h Attribute: RO  
 Default Value: 0100h Size: 16 bits

Bit	Description
15:0	<b>Host Controller Interface Version Number</b> — RO. This is a two-byte register containing a BCD encoding of the version number of interface that this host controller interface conforms.

### 17.2.1.3 HCSPARAMS—Host Controller Structural Parameters

Offset: MEM\_BASE + 04h–07h Attribute: R/W, RO  
 Default Value: 00204208h (D29:F0) Size: 32 bits  
 00203206h (D26:F0)  
 Function Level Reset: No

**Note:** This register is reset by a suspend well reset and not a D3-to-D0 reset or HCRESET.

Bit	Description
31:24	Reserved.
23:20	<b>Debug Port Number (DP_N)</b> — RO. Hardwired to 2h indicating that the Debug Port is on the second lowest numbered port on the EHCI. EHCI#1: Port 1 EHCI#2: Port 9
19:16	Reserved
15:12	<b>Number of Companion Controllers (N_CC)</b> — R/W. This field indicates the number of companion controllers associated with this USB EHCI host controller. BIOS must program this field to 0b to indicate companion host controllers are not supported. Port-ownership hand-off is not supported. Only high-speed devices are supported on the host controller root ports.
11:8	<b>Number of Ports per Companion Controller (N_PCC)</b> — RO. This field indicates the number of ports supported per companion host controller. This field is 0h indication no other companion controller support.
7:4	Reserved. These bits are reserved and default to 0.
3:0	<b>N_PORTS</b> — R/W. This field specifies the number of physical downstream ports implemented on this host controller. The value of this field determines how many port registers are addressable in the Operational Register Space. Valid values are in the range of 1h to Fh. A 0 in this field is undefined. For Integrated USB 2.0 Rate Matching Hub Enabled: Each EHCI reports 2 ports by default. Port 0 assigned to the RMH and port 1 assigned as the debug port. When the KVM/USB-R feature is enabled it will show up as Port2 on the EHCI, and BIOS would need to update this field to 3h.

**Note:** This register is writable when the WRT\_RDONLY bit is set.



### 17.2.1.4 HCCPARAMS—Host Controller Capability Parameters Register

Offset: MEM\_BASE + 08h-0Bh Attribute: RO  
 Default Value: 00006881h Size: 32 bits

Bit	Description
31:18	Reserved
17	<b>Asynchronous Schedule Update Capability (ASUC)</b> — R/W. There is no functionality associated with this bit.
16	<b>Periodic Schedule Update Capability (PSUC)</b> — RO. This field is hardwired to 0b to indicate that the EHC hardware supports the Periodic Schedule Update Event Flag in the USB2.0_CMD register.
15:8	<b>EHCI Extended Capabilities Pointer (EECP)</b> — RO. This field is hardwired to 68h, indicating that the EHCI capabilities list exists and begins at offset 68h in the PCI configuration space.
7:4	<b>Isochronous Scheduling Threshold</b> — RO. This field indicates, relative to the current position of the executing host controller, where software can reliably update the isochronous schedule. When bit 7 is 0, the value of the least significant 3 bits indicates the number of micro-frames a host controller hold a set of isochronous data structures (one or more) before flushing the state. When bit 7 is a 1, then host software assumes the host controller may cache an isochronous data structure for an entire frame. Refer to the EHCI specification for details on how software uses this information for scheduling isochronous transfers. This field is hardwired to 8h.
3	Reserved.
2	<b>Asynchronous Schedule Park Capability</b> — RO. This bit is hardwired to 0 indicating that the host controller does not support this optional feature
1	<b>Programmable Frame List Flag</b> — RO. 0 = System software must use a frame list length of 1024 elements with this host controller. The USB2.0_CMD register (D29:F0, D26:F0:CAPLENGTH + 20h, bits 3:2) <i>Frame List Size</i> field is a read-only register and must be set to 0. 1 = System software can specify and use a smaller frame list and configure the host controller using the USB2.0_CMD register <i>Frame List Size</i> field. The frame list must always be aligned on a 4K page boundary. This requirement ensures that the frame list is always physically contiguous.
0	<b>64-bit Addressing Capability</b> — RO. This field documents the addressing range capability of this implementation. The value of this field determines whether software should use the 32-bit or 64-bit data structures. This bit is hardwired to 1. <b>Note:</b> The PCH supports 64 bit addressing only.



## 17.2.2 Host Controller Operational Registers

This section defines the enhanced host controller operational registers. These registers are located after the capabilities registers. The operational register base must be DWord-aligned and is calculated by adding the value in the first capabilities register (CAPLENGTH) to the base address of the enhanced host controller register address space (MEM\_BASE). Since CAPLENGTH is always 20h, Table 17-3 already accounts for this offset. All registers are 32 bits in length.

**Table 17-3. Enhanced Host Controller Operational Register Address Map**

MEM_BASE + Offset	Mnemonic	Register Name	Default	Special Notes	Attribute
20h–23h	USB2.0_CMD	USB 2.0 Command	00080000h		R/W, RO
24h–27h	USB2.0_STS	USB 2.0 Status	00001000h		R/WC, RO
28h–2Bh	USB2.0_INTR	USB 2.0 Interrupt Enable	00000000h		R/W
2Ch–2Fh	FRINDEX	USB 2.0 Frame Index	00000000h		R/W,
30h–33h	CTRLDSSEGMENT	Control Data Structure Segment	00000000h		R/W, RO
34h–37h	PERODICLISTBASE	Period Frame List Base Address	00000000h		R/W
38h–3Bh	ASYNCLISTADDR	Current Asynchronous List Address	00000000h		R/W
3Ch–5Fh	—	Reserved	0h		RO
60h–63h	CONFIGFLAG	Configure Flag	00000000h	Suspend	R/W
64h–67h	PORT0SC	Port 0 Status and Control	00003000h	Suspend	R/W, R/WC, RO
68h–6Bh	PORT1SC	Port 1 Status and Control	00003000h	Suspend	R/W, R/WC, RO
6Ch–6Fh	PORT2SC	Port 2 Status and Control	00003000h	Suspend	R/W, R/WC, RO
70h–73h	PORT3SC	Port 3 Status and Control	00003000h	Suspend	R/W, R/WC, RO
74h–77h	PORT4SC	Port 4 Status and Control	00003000h	Suspend	R/W, R/WC, RO
78h–7Bh	PORT5SC	Port 5 Status and Control	00003000h	Suspend	R/W, R/WC, RO
74h–77h (D29 Only)	PORT6SC	Port 6 Status and Control	00003000h	Suspend	R/W, R/WC, RO
78h–7Bh (D29 Only)	PORT7SC	Port 7 Status and Control	00003000h	Suspend	R/W, R/WC, RO
7Ch–9Fh	—	Reserved	Undefined		RO
A0h–B3h	—	Debug Port Registers	Undefined		See register description
B4h–3FFh	—	Reserved	Undefined		RO

**Note:** Software must read and write these registers using only DWord accesses. These registers are divided into two sets. The first set at offsets MEM\_BASE + 00:3Bh are implemented in the core power well. Unless otherwise noted, the core well registers are reset by the assertion of any of the following:

- Core well hardware reset
- HCRESET
- D3-to-D0 reset

The second set at offsets MEM\_BASE + 60h to the end of the implemented register space are implemented in the Suspend power well. Unless otherwise noted, the suspend well registers are reset by the assertion of either of the following:

- Suspend well hardware reset
- HCRESET



**17.2.2.1 USB2.0\_CMD—USB 2.0 Command Register**

Offset: MEM\_BASE + 20–23h Attribute: R/W, RO  
 Default Value: 00080000h Size: 32 bits

Bit	Description																		
31:24	Reserved																		
23:16	<p><b>Interrupt Threshold Control</b> — R/W. System software uses this field to select the maximum rate at which the host controller will issue interrupts. The only valid values are defined below. If software writes an invalid value to this register, the results are undefined.</p> <table border="1"> <thead> <tr> <th>Value</th> <th>Maximum Interrupt Interval</th> </tr> </thead> <tbody> <tr> <td>00h</td> <td>Reserved</td> </tr> <tr> <td>01h</td> <td>1 micro-frame</td> </tr> <tr> <td>02h</td> <td>2 micro-frames</td> </tr> <tr> <td>04h</td> <td>4 micro-frames</td> </tr> <tr> <td>08h</td> <td>8 micro-frames (default, equates to 1 ms)</td> </tr> <tr> <td>10h</td> <td>16 micro-frames (2 ms)</td> </tr> <tr> <td>20h</td> <td>32 micro-frames (4 ms)</td> </tr> <tr> <td>40h</td> <td>64 micro-frames (8 ms)</td> </tr> </tbody> </table>	Value	Maximum Interrupt Interval	00h	Reserved	01h	1 micro-frame	02h	2 micro-frames	04h	4 micro-frames	08h	8 micro-frames (default, equates to 1 ms)	10h	16 micro-frames (2 ms)	20h	32 micro-frames (4 ms)	40h	64 micro-frames (8 ms)
Value	Maximum Interrupt Interval																		
00h	Reserved																		
01h	1 micro-frame																		
02h	2 micro-frames																		
04h	4 micro-frames																		
08h	8 micro-frames (default, equates to 1 ms)																		
10h	16 micro-frames (2 ms)																		
20h	32 micro-frames (4 ms)																		
40h	64 micro-frames (8 ms)																		
15:14	Reserved																		
13	<b>Asynch Schedule Update (ASC)</b> — R/W. There is no functionality associated with this bit.																		
12	<p><b>Periodic Schedule Prefetch Enable</b> — R/W. This bit is used by software to enable the host controller to prefetch the periodic schedule even in C0.                      0 = Prefetch based pause enabled only when not in C0.                      1 = Prefetch based pause enable in C0.</p> <p>Once software has written a 1b to this bit to enable periodic schedule prefetching, it must disable prefetching by writing a 0b to this bit whenever periodic schedule updates are about to begin. Software should continue to dynamically disable and re-enable the prefetcher surrounding any updates to the periodic scheduler (that is until the host controller has been reset using a HRESET).</p>																		
11:8	Unimplemented Asynchronous Park Mode Bits — RO. Hardwired to 000b indicating the host controller does not support this optional feature.																		
7	Light Host Controller Reset — RO. Hardwired to 0. The PCH does not implement this optional reset.																		
6	<p><b>Interrupt on Async Advance Doorbell</b> — R/W. This bit is used as a doorbell by software to tell the host controller to issue an interrupt the next time it advances asynchronous schedule.                      0 = The host controller sets this bit to a 0 after it has set the Interrupt on Async Advance status bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 5) in the USB2.0_STS register to a 1.                      1 = Software must write a 1 to this bit to ring the doorbell. When the host controller has evicted all appropriate cached schedule state, it sets the Interrupt on Async Advance status bit in the USB2.0_STS register. If the <i>Interrupt on Async Advance Enable</i> bit in the USB2.0_INTR register (D29:F0, D26:F0:CAPLENGTH + 28h, bit 5) is a 1 then the host controller will assert an interrupt at the next interrupt threshold. See the EHCI specification for operational details.</p> <p><b>Note:</b> Software should not write a 1 to this bit when the asynchronous schedule is inactive. Doing so will yield undefined results.</p>																		
5	<p><b>Asynchronous Schedule Enable</b> — R/W. This bit controls whether the host controller skips processing the Asynchronous Schedule.                      0 = Do not process the Asynchronous Schedule                      1 = Use the ASYNCLISTADDR register to access the Asynchronous Schedule.</p>																		
4	<p><b>Periodic Schedule Enable</b> — R/W. This bit controls whether the host controller skips processing the Periodic Schedule.                      0 = Do not process the Periodic Schedule                      1 = Use the PERIODICLISTBASE register to access the Periodic Schedule.</p>																		



Bit	Description															
3:2	<b>Frame List Size</b> — RO. The PCH hardwires this field to 00b because it only supports the 1024-element frame list size.															
1	<p><b>Host Controller Reset (HCRESET)</b> — R/W. This control bit used by software to reset the host controller. The effects of this on root hub registers are similar to a Chip Hardware Reset (that is, RSMRST# assertion and PCH_PWROK deassertion on the PCH).</p> <p>When software writes a 1 to this bit, the host controller resets its internal pipelines, timers, counters, state machines, etc. to their initial value. Any transaction currently in progress on USB is immediately terminated. A USB reset is not driven on downstream ports.</p> <p><b>Note:</b> PCI configuration registers and Host controller capability registers are not effected by this reset.</p> <p>All operational registers, including port registers and port state machines are set to their initial values. Port ownership reverts to the companion host controller(s), with the side effects described in the EHCI spec. Software must re-initialize the host controller in order to return the host controller to an operational state.</p> <p>This bit is set to 0 by the host controller when the reset process is complete. Software cannot terminate the reset process early by writing a 0 to this register.</p> <p>Software should not set this bit to a 1 when the HCHalted bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 12) in the USB2.0_STS register is a 0. Attempting to reset an actively running host controller will result in undefined behavior. This reset me be used to leave EHCI port test modes.</p>															
0	<p><b>Run/Stop (RS)</b> — R/W.</p> <p>0 = Stop (default)</p> <p>1 = Run. When set to a 1, the Host controller proceeds with execution of the schedule. The Host controller continues execution as long as this bit is set. When this bit is set to 0, the Host controller completes the current transaction on the USB and then halts. The HCHalted bit in the USB2.0_STS register indicates when the Host controller has finished the transaction and has entered the stopped state.</p> <p>Software should not write a 1 to this field unless the host controller is in the Halted state (that is, HCHalted in the USBSTS register is a 1). The Halted bit is cleared immediately when the Run bit is set.</p> <p>The following table explains how the different combinations of Run and Halted should be interpreted:</p> <table border="1"> <thead> <tr> <th>Run/Stop</th> <th>Halted</th> <th>Interpretation</th> </tr> </thead> <tbody> <tr> <td>0b</td> <td>0b</td> <td>In the process of halting</td> </tr> <tr> <td>0b</td> <td>1b</td> <td>Halted</td> </tr> <tr> <td>1b</td> <td>0b</td> <td>Running</td> </tr> <tr> <td>1b</td> <td>1b</td> <td>Invalid - the HCHalted bit clears immediately</td> </tr> </tbody> </table> <p>Memory read cycles initiated by the EHC that receive any status other than Successful will result in this bit being cleared.</p>	Run/Stop	Halted	Interpretation	0b	0b	In the process of halting	0b	1b	Halted	1b	0b	Running	1b	1b	Invalid - the HCHalted bit clears immediately
Run/Stop	Halted	Interpretation														
0b	0b	In the process of halting														
0b	1b	Halted														
1b	0b	Running														
1b	1b	Invalid - the HCHalted bit clears immediately														

**Note:** The Command Register indicates the command to be executed by the serial bus host controller. Writing to the register causes a command to be executed.



### 17.2.2.2 USB2.0\_STS—USB 2.0 Status Register

Offset: MEM\_BASE + 24h–27h Attribute: R/WC, RO  
 Default Value: 00001000h Size: 32 bits

This register indicates pending interrupts and various states of the Host controller. The status resulting from a transaction on the serial bus is not indicated in this register. See the Interrupts description in section 4 of the EHCI specification for additional information concerning USB 2.0 interrupt conditions.

**Note:** For the writable bits, software must write a 1 to clear bits that are set. Writing a 0 has no effect.

Bit	Description
31:16	Reserved.
15	<p><b>Asynchronous Schedule Status</b> —RO. This bit reports the current real status of the Asynchronous Schedule.                      0 = Disabled. (Default)                      1 = Enabled.</p> <p><b>Note:</b> The Host controller is not required to <i>immediately</i> disable or enable the Asynchronous Schedule when software transitions the <i>Asynchronous Schedule Enable</i> bit (D29:F0, D26:F0:CAPLENGTH + 20h, bit 5) in the USB2.0_CMD register. When this bit and the <i>Asynchronous Schedule Enable</i> bit are the same value, the Asynchronous Schedule is either enabled (1) or disabled (0).</p>
14	<p><b>Periodic Schedule Status</b> —RO. This bit reports the current real status of the Periodic Schedule.                      0 = Disabled. (Default)                      1 = Enabled.</p> <p><b>Note:</b> The Host controller is not required to <i>immediately</i> disable or enable the Periodic Schedule when software transitions the <i>Periodic Schedule Enable</i> bit (D29:F0, D26:F0:CAPLENGTH + 20h, bit 4) in the USB2.0_CMD register. When this bit and the <i>Periodic Schedule Enable</i> bit are the same value, the Periodic Schedule is either enabled (1) or disabled (0).</p>
13	<p><b>Reclamation</b> —RO. This read-only status bit is used to detect an empty asynchronous schedule. The operational model and valid transitions for this bit are described in Section 4 of the EHCI Specification.</p>
12	<p><b>HCHalted</b> —RO.                      0 = This bit is a 0 when the Run/Stop bit is a 1.                      1 = The Host controller sets this bit to 1 after it has stopped executing as a result of the Run/Stop bit being set to 0, either by software or by the Host controller hardware (such as, internal error). (Default)</p>
11:6	Reserved
5	<p><b>Interrupt on Async Advance</b> — R/WC. System software can force the host controller to issue an interrupt the next time the host controller advances the asynchronous schedule by writing a 1 to the <i>Interrupt on Async Advance Doorbell</i> bit (D29:F0, D26:F0:CAPLENGTH + 20h, bit 6) in the USB2.0_CMD register. This bit indicates the assertion of that interrupt source.</p>
4	<p><b>Host System Error</b> — R/WC.                      0 = No serious error occurred during a host system access involving the Host controller module                      1 = The Host controller sets this bit to 1 when a serious error occurs during a host system access involving the Host controller module. A hardware interrupt is generated to the system. Memory read cycles initiated by the EHC that receive any status other than Successful will result in this bit being set.</p> <p>When this error occurs, the Host controller clears the Run/Stop bit in the USB2.0_CMD register (D29:F0, D26:F0:CAPLENGTH + 20h, bit 0) to prevent further execution of the scheduled TDs. A hardware interrupt is generated to the system (if enabled in the Interrupt Enable Register).</p>
3	<p><b>Frame List Rollover</b> — R/WC.                      0 = No <i>Frame List Index</i> rollover from its maximum value to 0.                      1 = The Host controller sets this bit to a 1 when the <i>Frame List Index</i> rolls over from its maximum value to 0. Since the PCH only supports the 1024-entry Frame List Size, the <i>Frame List Index</i> rolls over every time FRNUM13 toggles.</p>



Bit	Description
2	<b>Port Change Detect</b> — R/WC. This bit is allowed to be maintained in the Auxiliary power well. Alternatively, it is also acceptable that on a D3 to D0 transition of the EHCI HC device, this bit is loaded with the OR of all of the PORTSC change bits (including: Force port resume, overcurrent change, enable/disable change and connect status change). Regardless of the implementation, when this bit is readable (that is, in the D0 state), it must provide a valid view of the Port Status registers. 0 = No change bit transition from a 0 to 1 or No Force Port Resume bit transition from 0 to 1 as a result of a J-K transition detected on a suspended port. 1 = The Host controller sets this bit to 1 when any port for which the <i>Port Owner</i> bit is set to 0 has a change bit transition from a 0 to 1 or a Force Port Resume bit transition from 0 to 1 as a result of a J-K transition detected on a suspended port.
1	<b>USB Error Interrupt (USBERRINT)</b> — R/WC. 0 = No error condition. 1 = The Host controller sets this bit to 1 when completion of a USB transaction results in an error condition (such as DWord, error counter underflow). If the TD on which the error interrupt occurred also had its IOC bit set, both this bit and Bit 0 are set. See the EHCI specification for a list of the USB errors that will result in this interrupt being asserted.
0	<b>USB Interrupt (USBINT)</b> — R/WC. 0 = No completion of a USB transaction whose Transfer Descriptor had its IOC bit set. No short packet is detected. 1 = The Host controller sets this bit to 1 when the cause of an interrupt is a completion of a USB transaction whose Transfer Descriptor had its IOC bit set. The Host controller also sets this bit to 1 when a short packet is detected (actual number of bytes received was less than the expected number of bytes).

### 17.2.2.3 USB2.0\_INTR—USB 2.0 Interrupt Enable Register

Offset: MEM\_BASE + 28h–2Bh      Attribute: R/W  
 Default Value: 00000000h      Size: 32 bits

This register enables and disables reporting of the corresponding interrupt to the software. When a bit is set and the corresponding interrupt is active, an interrupt is generated to the host. Interrupt sources that are disabled in this register still appear in the USB2.0\_STS Register to allow the software to poll for events. Each interrupt enable bit description indicates whether it is dependent on the interrupt threshold mechanism (see Section 4 of the EHCI specification), or not.

Bit	Description
31:6	Reserved.
5	<b>Interrupt on Async Advance Enable</b> — R/W. 0 = Disable. 1 = Enable. When this bit is a 1, and the Interrupt on Async Advance bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 5) in the USB2.0_STS register is a 1, the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software clearing the Interrupt on Async Advance bit.
4	<b>Host System Error Enable</b> — R/W. 0 = Disable. 1 = Enable. When this bit is a 1, and the Host System Error Status bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 4) in the USB2.0_STS register is a 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Host System Error bit.
3	<b>Frame List Rollover Enable</b> — R/W. 0 = Disable. 1 = Enable. When this bit is a 1, and the Frame List Rollover bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 3) in the USB2.0_STS register is a 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Frame List Rollover bit.



Bit	Description
2	<b>Port Change Interrupt Enable</b> — R/W. 0 = Disable. 1 = Enable. When this bit is a 1, and the Port Change Detect bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 2) in the USB2.0_STS register is a 1, the host controller will issue an interrupt. The interrupt is acknowledged by software clearing the Port Change Detect bit.
1	<b>USB Error Interrupt Enable</b> — R/W. 0 = Disable. 1 = Enable. When this bit is a 1, and the USBERRINT bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 1) in the USB2.0_STS register is a 1, the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software by clearing the USBERRINT bit in the USB2.0_STS register.
0	<b>USB Interrupt Enable</b> — R/W. 0 = Disable. 1 = Enable. When this bit is a 1, and the USBINT bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 0) in the USB2.0_STS register is a 1, the host controller will issue an interrupt at the next interrupt threshold. The interrupt is acknowledged by software by clearing the USBINT bit in the USB2.0_STS register.

### 17.2.2.4 FRINDEX—Frame Index Register

Offset: MEM\_BASE + 2Ch–2Fh      Attribute: R/W  
 Default Value: 00000000h      Size: 32 bits

The SOF frame number value for the bus SOF token is derived or alternatively managed from this register. Refer to Section 4 of the EHCI specification for a detailed explanation of the SOF value management requirements on the host controller. The value of FRINDEX must be within 125 μs (1 micro-frame) ahead of the SOF token value. The SOF value may be implemented as an 11-bit shadow register. For this discussion, this shadow register is 11 bits and is named SOFV. SOFV updates every 8 micro-frames (1 millisecond). An example implementation to achieve this behavior is to increment SOFV each time the FRINDEX[2:0] increments from 0 to 1.

Software must use the value of FRINDEX to derive the current micro-frame number, both for high-speed isochronous scheduling purposes and to provide the **get** micro-frame number function required to client drivers. Therefore, the value of FRINDEX and the value of SOFV must be kept consistent if chip is reset or software writes to FRINDEX. Writes to FRINDEX must also **write-through** FRINDEX[13:3] to SOFV[10:0]. In order to keep the update as simple as possible, software should never write a FRINDEX value where the three least significant bits are 111b or 000b.

**Note:** This register is used by the host controller to index into the periodic frame list. The register updates every 125 microseconds (once each micro-frame). Bits [12:3] are used to select a particular entry in the Periodic Frame List during periodic schedule execution. The number of bits used for the index is fixed at 10 for the PCH since it only supports 1024-entry frame lists. This register must be written as a DWord. Word and byte writes produce undefined results. This register cannot be written unless the Host controller is in the Halted state as indicated by the *HCHalted* bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 12). A write to this register while the Run/Stop bit (D29:F0, D26:F0:CAPLENGTH + 20h, bit 0) is set to a 1 (USB2.0\_CMD register) produces undefined results. Writes to this register also effect the SOF value. See Section 4 of the EHCI specification for details.

Bit	Description
31:14	Reserved
13:0	<b>Frame List Current Index/Frame Number</b> — R/W. The value in this register increments at the end of each time frame (such as, micro-frame). Bits [12:3] are used for the Frame List current index. This means that each location of the frame list is accessed 8 times (frames or micro-frames) before moving to the next index.



### 17.2.2.5 CTRLDSSEGMENT—Control Data Structure Segment Register

Offset: MEM\_BASE + 30h–33h Attribute: R/W, RO  
Default Value: 00000000h Size: 32 bits

This 32-bit register corresponds to the most significant address bits [63:32] for all EHCI data structures. Since the PCH hardwires the 64-bit Addressing Capability field in HCCPARAMS to 1, this register is used with the link pointers to construct 64-bit addresses to EHCI control data structures. This register is concatenated with the link pointer from either the PERIODICLISTBASE, ASYNCLISTADDR, or any control data structure link field to construct a 64-bit address. This register allows the host software to locate all control data structures within the same 4 GB memory segment.

Bit	Description
31:12	<b>Upper Address[63:44]</b> — RO. Hardwired to 0s. The PCH EHC is only capable of generating addresses up to 16 terabytes (44 bits of address).
11:0	<b>Upper Address[43:32]</b> — R/W. This 12-bit field corresponds to address bits 43:32 when forming a control data structure address.

### 17.2.2.6 PERIODICLISTBASE—Periodic Frame List Base Address Register

Offset: MEM\_BASE + 34h–37h Attribute: R/W  
Default Value: 00000000h Size: 32 bits

This 32-bit register contains the beginning address of the Periodic Frame List in the system memory. Since the PCH host controller operates in 64-bit mode (as indicated by the 1 in the 64-bit Addressing Capability field in the HCCSPARAMS register) (offset 08h, bit 0), then the most significant 32 bits of every control data structure address comes from the CTRLDSSEGMENT register. HCD loads this register prior to starting the schedule execution by the host controller. The memory structure referenced by this physical memory pointer is assumed to be 4-Kbyte aligned. The contents of this register are combined with the Frame Index Register (FRINDEX) to enable the Host controller to step through the Periodic Frame List in sequence.

Bit	Description
31:12	<b>Base Address (Low)</b> — R/W. These bits correspond to memory address signals [31:12], respectively.
11:0	Reserved.



### 17.2.2.7 ASYNCLISTADDR—Current Asynchronous List Address Register

Offset: MEM\_BASE + 38h–3Bh Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

This 32-bit register contains the address of the next asynchronous queue head to be executed. Since the PCH host controller operates in 64-bit mode (as indicated by a 1 in 64-bit Addressing Capability field in the HCCPARAMS register) (offset 08h, bit 0), then the most significant 32 bits of every control data structure address comes from the CTRLDSSEGMENT register (offset 08h). Bits [4:0] of this register cannot be modified by system software and will always return 0s when read. The memory structure referenced by this physical memory pointer is assumed to be 32-byte aligned.

Bit	Description
31:5	<b>Link Pointer Low (LPL)</b> — R/W. These bits correspond to memory address signals [31:5], respectively. This field may only reference a Queue Head (QH).
4:0	Reserved.

### 17.2.2.8 CONFIGFLAG—Configure Flag Register

Offset: MEM\_BASE + 60h–63h Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

This register is in the suspend power well. It is only reset by hardware when the suspend power is initially applied or in response to a host controller reset.

Bit	Description
31:1	Reserved.
0	<b>Configure Flag (CF)</b> — R/W. Host software sets this bit as the last action in its process of configuring the Host controller. This bit controls the default port-routing control logic. Bit values and side-effects are listed below. See section 4 of the EHCI spec for operation details. 0 = Compatibility debug only (default). 1 = Port routing control logic default-routes all ports to this host controller.

### 17.2.2.9 PORTSC—Port N Status and Control Register

Offset: Port 0 RMH: MEM\_BASE + 64h–67h  
 Port 1 Debug Port: MEM\_BASE + 68–6Bh  
 Port 2 USB redirect (if enabled): MEM\_BASE + 6C–6Fh

Attribute: R/W, R/WC, RO  
 Default Value: 00003000h Size: 32 bits

**Note:** This register is associated with the upstream ports of the EHCI controller and does not represent downstream hub ports. USB Hub class commands must be used to determine RMH port status and enable test modes. See Chapter 11 of the USB Specification, Revision 2.0 for more details. Rate Matching Hub wake capabilities can be configured by the RMHWKCTL Register (RCBA+35B0h) located in the Chipset Configuration chapter.

A host controller must implement one or more port registers. Software uses the N\_Port information from the Structural Parameters Register to determine how many ports need to be serviced. All ports have the structure defined below. Software must not write to unreported Port Status and Control Registers.

This register is in the suspend power well. It is only reset by hardware when the suspend power is initially applied or in response to a host controller reset. The initial conditions of a port are:

- No device connected
- Port disabled.



When a device is attached, the port state transitions to the attached state and system software will process this as with any status change notification. Refer to Section 4 of the EHCI specification for operational requirements for how change events interact with port suspend mode.

Bit	Description														
31:23	Reserved.														
22	<b>Wake on Overcurrent Enable (WKOC_E)</b> — R/W. 0 = Disable. (Default) 1 = Enable. Writing this bit to a 1 enables the setting of the PME Status bit in the Power Management Control/Status Register (offset 54, bit 15) when the overcurrent Active bit (bit 4 of this register) is set.														
21	<b>Wake on Disconnect Enable (WKDSCNNT_E)</b> — R/W. 0 = Disable. (Default) 1 = Enable. Writing this bit to a 1 enables the setting of the PME Status bit in the Power Management Control/Status Register (offset 54, bit 15) when the Current Connect Status changes from connected to disconnected (that is, bit 0 of this register changes from 1 to 0).														
20	<b>Wake on Connect Enable (WKCNT_E)</b> — R/W. 0 = Disable. (Default) 1 = Enable. Writing this bit to a 1 enables the setting of the PME Status bit in the Power Management Control/Status Register (offset 54, bit 15) when the Current Connect Status changes from disconnected to connected (that is, bit 0 of this register changes from 0 to 1).														
19:16	<b>Port Test Control</b> — R/W. When this field is 0s, the port is NOT operating in a test mode. A non-zero value indicates that it is operating in test mode and the specific test mode is indicated by the specific value. The encoding of the test mode bits are (0110b – 1111b are reserved):  <table border="1"> <thead> <tr> <th>Value</th> <th>Maximum Interrupt Interval</th> </tr> </thead> <tbody> <tr> <td>0000b</td> <td>Test mode not enabled (default)</td> </tr> <tr> <td>0001b</td> <td>Test J_STATE</td> </tr> <tr> <td>0010b</td> <td>Test K_STATE</td> </tr> <tr> <td>0011b</td> <td>Test SE0_NAK</td> </tr> <tr> <td>0100b</td> <td>Test Packet</td> </tr> <tr> <td>0101b</td> <td>FORCE_ENABLE</td> </tr> </tbody> </table> Refer to the USB Specification Revision 2.0, Chapter 7 for details on each test mode.	Value	Maximum Interrupt Interval	0000b	Test mode not enabled (default)	0001b	Test J_STATE	0010b	Test K_STATE	0011b	Test SE0_NAK	0100b	Test Packet	0101b	FORCE_ENABLE
Value	Maximum Interrupt Interval														
0000b	Test mode not enabled (default)														
0001b	Test J_STATE														
0010b	Test K_STATE														
0011b	Test SE0_NAK														
0100b	Test Packet														
0101b	FORCE_ENABLE														
15:14	Reserved.														
13	<b>Port Owner</b> — R/W. This bit unconditionally goes to a 0 when the Configured Flag bit in the USB2.0_CMD register makes a 0 to 1 transition. System software uses this field to release ownership of the port to a selected host controller (in the event that the attached device is not a high-speed device). Software writes a 1 to this bit when the attached device is not a high-speed device. A 1 in this bit means that a companion host controller owns and controls the port. See Section 4 of the EHCI Specification for operational details.														
12	<b>Port Power (PP)</b> — RO. Read-only with a value of 1. This indicates that the port does have power.														
11:10	<b>Line Status</b> — RO. These bits reflect the current logical levels of the D+ (bit 11) and D- (bit 10) signal lines. These bits are used for detection of low-speed USB devices prior to the port reset and enable sequence. This field is valid only when the port enable bit is 0 and the current connect status bit is set to a 1. 00 = SE0 10 = J-state 01 = K-state 11 = Undefined														
9	Reserved.														



Bit	Description												
8	<p><b>Port Reset</b> — R/W. When software writes a 1 to this bit (from a 0), the bus reset sequence as defined in the USB Specification, Revision 2.0 is started. Software writes a 0 to this bit to terminate the bus reset sequence. Software must keep this bit at a 1 long enough to ensure the reset sequence completes as specified in the USB Specification, Revision 2.0.</p> <p>1 = Port is in Reset. 0 = Port is not in Reset.</p> <p><b>Note:</b> When software writes a 0 to this bit, there may be a delay before the bit status changes to a 0. The bit status will not read as a 0 until after the reset has completed. If the port is in high-speed mode after reset is complete, the host controller will automatically enable this port (such as, set the <i>Port Enable</i> bit to a 1). A host controller must terminate the reset and stabilize the state of the port within 2 milliseconds of software transitioning this bit from 0 to 1.</p> <p>For example: if the port detects that the attached device is high-speed during reset, then the host controller must have the port in the enabled state within 2 ms of software writing this bit to a 0. The <i>HCHalted</i> bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 12) in the USB2.0_STS register should be a 0 before software attempts to use this bit. The host controller may hold Port Reset asserted to a 1 when the <i>HCHalted</i> bit is a 1. This bit is 0 if Port Power is 0</p> <p><b>Note:</b> System software should not attempt to reset a port if the <i>HCHalted</i> bit in the USB2.0_STS register is a 1. Doing so will result in undefined behavior.</p>												
7	<p><b>Suspend</b> — R/W.</p> <p>0 = Port not in suspend state. (Default) 1 = Port in suspend state.</p> <p>Port Enabled Bit and Suspend bit of this register define the port states as follows:</p> <table border="1" data-bbox="509 953 967 1094"> <thead> <tr> <th>Port Enabled</th> <th>Suspend</th> <th>Port State</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>X</td> <td>Disabled</td> </tr> <tr> <td>1</td> <td>0</td> <td>Enabled</td> </tr> <tr> <td>1</td> <td>1</td> <td>Suspend</td> </tr> </tbody> </table> <p>When in suspend state, downstream propagation of data is blocked on this port, except for port reset. Note that the bit status does not change until the port is suspended and that there may be a delay in suspending a port depending on the activity on the port.</p> <p>The host controller will unconditionally set this bit to a 0 when software sets the <i>Force Port Resume</i> bit to a 0 (from a 1). A write of 0 to this bit is ignored by the host controller.</p> <p>If host software sets this bit to a 1 when the port is not enabled (that is, Port enabled bit is a 0) the results are undefined.</p>	Port Enabled	Suspend	Port State	0	X	Disabled	1	0	Enabled	1	1	Suspend
Port Enabled	Suspend	Port State											
0	X	Disabled											
1	0	Enabled											
1	1	Suspend											
6	<p><b>Force Port Resume</b> — R/W.</p> <p>0 = No resume (K-state) detected/driven on port. (Default) 1 = Resume detected/driven on port. Software sets this bit to a 1 to drive resume signaling. The Host controller sets this bit to a 1 if a J-to-K transition is detected while the port is in the Suspend state. When this bit transitions to a 1 because a J-to-K transition is detected, the Port Change Detect bit (D29:F0, D26:F0:CAPLENGTH + 24h, bit 2) in the USB2.0_STS register is also set to a 1. If software sets this bit to a 1, the host controller must not set the Port Change Detect bit.</p> <p><b>Note:</b> When the EHCI controller owns the port, the resume sequence follows the defined sequence documented in the USB Specification, Revision 2.0. The resume signaling (Full-speed 'K') is driven on the port as long as this bit remains a 1. Software must appropriately time the Resume and set this bit to a 0 when the appropriate amount of time has elapsed. Writing a 0 (from 1) causes the port to return to high-speed mode (forcing the bus below the port into a high-speed idle). This bit will remain a 1 until the port has switched to the high-speed idle.</p>												
5	<p><b>Overcurrent Change</b> — R/WC. The functionality of this bit is not dependent upon the port owner. Software clears this bit by writing a 1 to it.</p> <p>0 = No change. (Default) 1 = There is a change to Overcurrent Active.</p>												
4	<p><b>Overcurrent Active</b> — RO.</p> <p>0 = This port does not have an overcurrent condition. (Default) 1 = This port currently has an overcurrent condition. This bit will automatically transition from 1 to 0 when the over current condition is removed. The PCH automatically disables the port when the overcurrent active bit is 1.</p>												



Bit	Description
3	<b>Port Enable/Disable Change</b> — R/WC. For the root hub, this bit gets set to a 1 only when a port is disabled due to the appropriate conditions existing at the EOF2 point (See Chapter 11 of the USB Specification for the definition of a port error). This bit is not set due to the Disabled-to-Enabled transition, nor due to a disconnect. Software clears this bit by writing a 1 to it. 0 = No change in status. (Default). 1 = Port enabled/disabled status has changed.
2	<b>Port Enabled/Disabled</b> — R/W. Ports can only be enabled by the host controller as a part of the reset and enable. Software cannot enable a port by writing a 1 to this bit. Ports can be disabled by either a fault condition (disconnect event or other fault condition) or by host software. Note that the bit status does not change until the port state actually changes. There may be a delay in disabling or enabling a port due to other host controller and bus events. 0 = Disable 1 = Enable (Default)
1	<b>Connect Status Change</b> — R/WC. This bit indicates a change has occurred in the port's Current Connect Status. Software sets this bit to 0 by writing a 1 to it. 0 = No change (Default). 1 = Change in Current Connect Status. The host controller sets this bit for all changes to the port device connect status, even if system software has not cleared an existing connect status change. For example, the insertion status changes twice before system software has cleared the changed condition, hub hardware will be "setting" an already-set bit (that is, the bit will remain set).
0	<b>Current Connect Status</b> — RO. This value reflects the current state of the port, and may not correspond directly to the event that caused the Connect Status Change bit (Bit 1) to be set. 0 = No device is present. (Default) 1 = Device is present on port.

### 17.2.3 USB 2.0-Based Debug Port Registers

The Debug port's registers are located in the same memory area, defined by the Base Address Register (MEM\_BASE), as the standard EHCI registers. The base offset for the debug port registers (A0h) is declared in the Debug Port Base Offset Capability Register at Configuration offset 5Ah (D29:F0, D26:F0:offset 5Ah). The specific EHCI port that supports this debug capability (Port 1 for D29:F0 and Port 9 for D26:F0) is indicated by a 4-bit field (bits 20–23) in the HCSPARAMS register of the EHCI controller. The address map of the Debug Port registers is shown in Table 17-4.

Table 17-4. Debug Port Register Address Map

MEM_BASE + Offset	Mnemonic	Register Name	Default	Attribute
A0–A3h	CNTL_STS	Control/Status	00000000h	R/W, R/WC, RO
A4–A7h	USBPID	USB PIDs	00000000h	R/W, RO
A8–AFh	DATABUF[7:0]	Data Buffer (Bytes 7:0)	00000000 00000000h	R/W
B0–B3h	CONFIG	Configuration	00007F01h	R/W

**Notes:**

1. All of these registers are implemented in the core well and reset by PLTRST#, EHC HCRESET, and a EHC D3-to-D0 transition.
2. The hardware associated with this register provides no checks to ensure that software programs the interface correctly. How the hardware behaves when programmed improperly is undefined.



**17.2.3.1 CNTL\_STS—Control/Status Register**

Offset: MEM\_BASE + A0h Attribute: R/W, R/WC, RO  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31	Reserved
30	<b>OWNER_CNT</b> — R/W. 0 = Ownership of the debug port is NOT forced to the EHCI controller (Default) 1 = Ownership of the debug port is forced to the EHCI controller (that is, immediately taken away from the companion Classic USB Host controller) If the port was already owned by the EHCI controller, then setting this bit has no effect. This bit overrides all of the ownership-related bits in the standard EHCI registers.
29	Reserved
28	<b>ENABLED_CNT</b> — R/W. 0 = Software can clear this by writing a 0 to it. The hardware clears this bit for the same conditions where the Port Enable/Disable Change bit (in the PORTSC register) is set. (Default) 1 = Debug port is enabled for operation. Software can directly set this bit if the port is already enabled in the associated PORTSC register (this is enforced by the hardware).
27:17	Reserved
16	<b>DONE_STS</b> — R/WC. Software can clear this by writing a 1 to it. 0 = Request Not complete 1 = Set by hardware to indicate that the request is complete.
15:12	<b>LINK_ID_STS</b> — RO. This field identifies the link interface. 0h = Hardwired. Indicates that it is a USB Debug Port.
11	Reserved.
10	<b>IN_USE_CNT</b> — R/W. Set by software to indicate that the port is in use. Cleared by software to indicate that the port is free and may be used by other software. This bit is cleared after reset. (This bit has no affect on hardware.)
9:7	<b>EXCEPTION_STS</b> — RO. This field indicates the exception when the ERROR_GOOD#_STS bit is set. This field should be ignored if the ERROR_GOOD#_STS bit is 0. 000 = No Error. (Default) <b>Note:</b> This should not be seen since this field should only be checked if there is an error. 001 = Transaction error: Indicates the USB 2.0 transaction had an error (CRC, bad PID, timeout, etc.) 010 = Hardware error. Request was attempted (or in progress) when port was suspended or reset. All Other combinations are reserved
6	<b>ERROR_GOOD#_STS</b> — RO. 0 = Hardware clears this bit to 0 after the proper completion of a read or write. (Default) 1 = Error has occurred. Details on the nature of the error are provided in the Exception field.
5	<b>GO_CNT</b> — R/W. 0 = Hardware clears this bit when hardware sets the DONE_STS bit. (Default) 1 = Causes hardware to perform a read or write request. <b>Note:</b> Writing a 1 to this bit when it is already set may result in undefined behavior.
4	<b>WRITE_READ#_CNT</b> — R/W. Software clears this bit to indicate that the current request is a read. Software sets this bit to indicate that the current request is a write. 0 = Read (Default) 1 = Write
3:0	<b>DATA_LEN_CNT</b> — R/W. This field is used to indicate the size of the data to be transferred. default = 0h. For write operations, this field is set by software to indicate to the hardware how many bytes of data in Data Buffer are to be transferred to the console. A value of 0h indicates that a zero-length packet should be sent. A value of 1–8 indicates 1–8 bytes are to be transferred. Values 9–Fh are invalid and how hardware behaves if used is undefined. For read operations, this field is set by hardware to indicate to software how many bytes in Data Buffer are valid in response to a read operation. A value of 0h indicates that a zero length packet was returned and the state of Data Buffer is not defined. A value of 1–8 indicates 1–8 bytes were received. Hardware is not allowed to return values 9–Fh. The transferring of data always starts with byte 0 in the data area and moves toward byte 7 until the transfer size is reached.



**Notes:**

1. Software should do Read-Modify-Write operations to this register to preserve the contents of bits not being modified. This include RESERVED bits.
2. To preserve the usage of RESERVED bits in the future, software should always write the same value read from the bit until it is defined. Reserved bits will always return 0 when read.

### 17.2.3.2 USBPID—USB PIDs Register

Offset: MEM\_BASE + A4h–A7h Attribute: R/W, RO  
 Default Value: 00000000h Size: 32 bits

This Dword register is used to communicate PID information between the USB debug driver and the USB debug port. The debug port uses some of these fields to generate USB packets, and uses other fields to return PID information to the USB debug driver.

Bit	Description
31:24	Reserved.
23:16	<b>RECEIVED_PID_STS[23:16]</b> — RO. Hardware updates this field with the received PID for transactions in either direction. When the controller is writing data, this field is updated with the handshake PID that is received from the device. When the host controller is reading data, this field is updated with the data packet PID (if the device sent data), or the handshake PID (if the device NAKs the request). This field is valid when the hardware clears the GO_DONE#_CNT bit.
15:8	<b>SEND_PID_CNT[15:8]</b> — R/W. Hardware sends this PID to begin the data packet when sending data to USB (that is, WRITE_READ#_CNT is asserted). Software typically sets this field to either DATA0 or DATA1 PID values.
7:0	<b>TOKEN_PID_CNT[7:0]</b> — R/W. Hardware sends this PID as the Token PID for each USB transaction. Software typically sets this field to either IN, OUT, or SETUP PID values.

### 17.2.3.3 DATABUF[7:0]—Data Buffer Bytes[7:0] Register

Offset: MEM\_BASE + A8h–AFh Attribute: R/W  
 Default Value: 0000000000000000h Size: 64 bits

This register can be accessed as 8 separate 8-bit registers or 2 separate 32-bit register.

Bit	Description
63:0	<b>DATABUFFER[63:0]</b> — R/W. This field is the 8 bytes of the data buffer. Bits 7:0 correspond to least significant byte (byte 0). Bits 63:56 correspond to the most significant byte (byte 7). The bytes in the Data Buffer must be written with data before software initiates a write request. For a read request, the Data Buffer contains valid data when DONE_STS bit (offset A0, bit 16) is cleared by the hardware, ERROR_GOOD#_STS (offset A0, bit 6) is cleared by the hardware, and the DATA_LENGTH_CNT field (offset A0, bits 3:0) indicates the number of bytes that are valid.

### 17.2.3.4 CONFIG—Configuration Register

Offset: MEM\_BASE + B0–B3h Attribute: R/W  
 Default Value: 00007F01h Size: 32 bits

Bit	Description
31:15	Reserved
14:8	<b>USB_ADDRESS_CNF</b> — R/W. This 7-bit field identifies the USB device address used by the controller for all Token PID generation. (Default = 7Fh)
7:4	Reserved
3:0	<b>USB_ENDPOINT_CNF</b> — R/W. This 4-bit field identifies the endpoint used by the controller for all Token PID generation. (Default = 1h)

## §



# 18 Intel® High Definition Audio Controller Registers (D27:F0)

The Intel® High Definition Audio (Intel® HD Audio) controller resides in PCI Device 27, Function 0 on bus 0. This function contains a set of DMA engines that are used to move samples of digitally encoded data between system memory and external codecs.

**Note:** All registers in this function (including memory-mapped registers) must be addressable in byte, word, and DWord quantities. The software must always make register accesses on natural boundaries (that is, DWord accesses must be on DWord boundaries; word accesses on word boundaries, and so forth) Register access crossing the DWord boundary are ignored. In addition, the memory-mapped register space must not be accessed with the LOCK semantic exclusive-access mechanism. If software attempts exclusive-access mechanisms to the Intel HD Audio memory-mapped space, the results are undefined.

**Note:** Users interested in providing feedback on the Intel HD Audio specification or planning to implement the Intel HD Audio specification into a future product will need to execute the *Intel® High Definition Audio Specification Developer's Agreement*. For more information, contact [nextgenaudio@intel.com](mailto:nextgenaudio@intel.com).

## 18.1 Intel® HD Audio PCI Configuration Space (Intel HD Audio—D27:F0)

**Note:** Address locations that are not shown should be treated as Reserved.

**Table 18-5. Intel® High Definition Audio PCI Register Address Map (Intel HD Audio D27:F0) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	00h	RO
0Ah	SCC	Sub Class Code	03h	RO
0Bh	BCC	Base Class Code	04h	RO
0Ch	CLS	Cache Line Size	00h	R/W
0Dh	LT	Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	00h	RO
10h–13h	HDBARL	Intel HD Audio Lower Base Address (Memory)	00000004h	R/W, RO
14h–17h	HDBARU	Intel HD Audio Upper Base Address (Memory)	00000000h	R/W
2Ch–2Dh	SVID	Subsystem Vendor Identification	0000h	R/WO
2Eh–2Fh	SID	Subsystem Identification	0000h	R/WO
34h	CAPPTR	Capability List Pointer	50h	RO
3Ch	INTLN	Interrupt Line	00h	R/W
3Dh	INTPN	Interrupt Pin	See Register Description	RO





### 18.1.2 DID—Device Identification Register (Intel® High Definition Audio Controller—D27:F0)

Offset Address: 02h–03h                      Attribute: RO  
 Default Value: See bit description              Size: 16 bits

Bit	Description
15:0	<b>Device ID</b> — RO. This is a 16-bit value assigned to the PCH's Intel High Definition Audio controller. Refer to the <i>Intel® C600 Series Chipset and Intel® X79 Express Chipset Specification Update</i> for the value of the Device ID Register

### 18.1.3 PCICMD—PCI Command Register (Intel® HD Audio Controller—D27:F0)

Offset Address: 04h–05h                      Attribute: R/W, RO  
 Default Value: 0000h                      Size: 16 bits

Bit	Description
15:11	Reserved
10	<b>Interrupt Disable (ID)</b> — R/W. 0= The INTx# signals may be asserted. 1= The Intel HD Audio controller's INTx# signal will be de-asserted. <b>Note:</b> This bit does not affect the generation of MSIs.
9	Fast Back to Back Enable (FBE) — RO. Not implemented. Hardwired to 0.
8	<b>SERR# Enable (SERR_EN)</b> — R/W. SERR# is not generated by the PCH's Intel HD Audio Controller.
7	Wait Cycle Control (WCC) — RO. Not implemented. Hardwired to 0.
6	Parity Error Response (PER) — R/W. PER functionality not implemented.
5	VGA Palette Snoop (VPS). Not implemented. Hardwired to 0.
4	Memory Write and Invalidate Enable (MWIE) — RO. Not implemented. Hardwired to 0.
3	Special Cycle Enable (SCE). Not implemented. Hardwired to 0.
2	<b>Bus Master Enable (BME)</b> — R/W. Controls standard PCI Express* bus mastering capabilities for Memory and I/O, reads and writes. Note that this bit also controls MSI generation since MSI's are essentially Memory writes. 0 = Disable 1 = Enable
1	<b>Memory Space Enable (MSE)</b> — R/W. Enables memory space addresses to the Intel HD Audio controller. 0 = Disable 1 = Enable
0	I/O Space Enable (IOSE)—RO. Hardwired to 0 since the Intel HD Audio controller does not implement I/O space.



### 18.1.4 PCISTS—PCI Status Register (Intel® HD Audio Controller—D27:F0)

Offset Address: 06h–07h                      Attribute: RO, R/WC  
 Default Value: 0010h                      Size: 16 bits

Bit	Description
15	Detected Parity Error (DPE) — RO. Not implemented. Hardwired to 0.
14	SERR# Status (SERRS) — RO. Not implemented. Hardwired to 0.
13	<b>Received Master Abort (RMA)</b> — R/WC. Software clears this bit by writing a 1 to it. 0 = No master abort received. 1 = The Intel High Definition Audio controller sets this bit when, as a bus master, it receives a master abort. When set, the Intel® High Definition Audio controller clears the run bit for the channel that received the abort.
12	Received Target Abort (RTA) — RO. Not implemented. Hardwired to 0.
11	Signaled Target Abort (STA) — RO. Not implemented. Hardwired to 0.
10:9	DEVSEL# Timing Status (DEV_STS) — RO. Does not apply. Hardwired to 0.
8	Data Parity Error Detected (DPED) — RO. Not implemented. Hardwired to 0.
7	Fast Back to Back Capable (FB2BC) — RO. Does not apply. Hardwired to 0.
6	Reserved.
5	66 MHz Capable (66MHZ_CAP) — RO. Does not apply. Hardwired to 0.
4	<b>Capabilities List (CAP_LIST)</b> — RO. Hardwired to 1. Indicates that the controller contains a capabilities pointer list. The first item is pointed to by looking at configuration offset 34h.
3	<b>Interrupt Status (IS)</b> — RO. 0 = This bit is 0 after the interrupt is cleared. 1 = This bit is 1 when the INTx# is asserted. Note that this bit is not set by an MSI.
2:0	Reserved.

### 18.1.5 RID—Revision Identification Register (Intel® HD Audio Controller—D27:F0)

Offset: 08h                      Attribute: RO  
 Default Value: See bit description                      Size: 8 Bits

Bit	Description
7:0	<b>Revision ID</b> — RO. Refer to the <i>Intel® C600 Series Chipset and Intel® X79 Express Chipset Specification Update</i> for the value of the Revision ID Register

### 18.1.6 PI—Programming Interface Register (Intel® HD Audio Controller—D27:F0)

Offset: 09h                      Attribute: RO  
 Default Value: 00h                      Size: 8 bits

Bit	Description
7:0	<b>Programming Interface</b> — RO.





### 18.1.12 HDBARL—Intel® HD Audio Lower Base Address Register (Intel® HD Audio—D27:F0)

Address Offset: 10h-13h                      Attribute: R/W, RO  
 Default Value: 00000004h                      Size: 32 bits

Bit	Description
31:14	<b>Lower Base Address (LBA)</b> — R/W. Base address for the Intel HD Audio controller's memory mapped configuration registers. 16 Kbytes are requested by hardwiring bits 13:4 to 0s.
13:4	Reserved.
3	Prefetchable (PREF) — RO. Hardwired to 0 to indicate that this BAR is NOT prefetchable
2:1	<b>Address Range (ADDRNG)</b> — RO. Hardwired to 10b, indicating that this BAR can be located anywhere in 64-bit address space.
0	<b>Space Type (SPTYP)</b> — RO. Hardwired to 0. Indicates this BAR is located in memory space.

### 18.1.13 HDBARU—Intel® HD Audio Upper Base Address Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 14h-17h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:0	<b>Upper Base Address (UBA)</b> — R/W. Upper 32 bits of the Base address for the Intel High Definition Audio controller's memory mapped configuration registers.

### 18.1.14 SVID—Subsystem Vendor Identification Register (Intel® High Definition Audio Controller—D27:F0)

Address Offset: 2Ch-2Dh                      Attribute: R/WO  
 Default Value: 0000h                      Size: 16 bits  
 Function Level Reset: No

The SVID register, in combination with the Subsystem ID register (D27:F0:2Eh), enable the operating environment to distinguish one audio subsystem from the other(s).

This register is implemented as write-once register. Once a value is written to it, the value can be read back. Any subsequent writes will have no effect.

This register is not affected by the D3<sub>H0T</sub> to D0 transition.

Bit	Description
15:0	<b>Subsystem Vendor ID</b> — R/WO.



### 18.1.15 SID—Subsystem Identification Register (Intel® High Definition Audio Controller—D27:F0)

Address Offset: 2Eh–2Fh                      Attribute: R/WO  
 Default Value: 0000h                      Size: 16 bits  
 Function Level Reset: No

The SID register, in combination with the Subsystem Vendor ID register (D27:F0:2Ch) make it possible for the operating environment to distinguish one audio subsystem from the other(s).

This register is implemented as write-once register. Once a value is written to it, the value can be read back. Any subsequent writes will have no effect.

This register is not affected by the D3<sub>HOT</sub> to D0 transition.

Bit	Description
15:0	<b>Subsystem ID</b> — R/WO.

### 18.1.16 CAPPTR—Capabilities Pointer Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 34h                      Attribute: RO  
 Default Value: 50h                      Size: 8 bits

This register indicates the offset for the capability pointer.

Bit	Description
7:0	<b>Capabilities Pointer (CAP_PTR)</b> — RO. This field indicates that the first capability pointer offset is offset 50h (Power Management Capability)

### 18.1.17 INTLN—Interrupt Line Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 3Ch                      Attribute: R/W  
 Default Value: 00h                      Size: 8 bits

Bit	Description
7:0	<b>Interrupt Line (INT_LN)</b> — R/W. This data is not used by the PCH. It is used to communicate to software the interrupt line that the interrupt pin is connected to.

### 18.1.18 INTPN—Interrupt Pin Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 3Dh                      Attribute: RO  
 Default Value: See Description                      Size: 8 bits

Bit	Description
7:4	Reserved.
3:0	<b>Interrupt Pin</b> — RO. This reflects the value of D27IP.ZIP (Chipset Config Registers: Offset 3110h:bits 3:0).











### 18.1.32 DEVC—Device Control Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 78h-79h                      Attribute: R/W, RO  
 Default Value: 0800h                      Size: 16 bits  
 Function Level Reset: No (Bit 11 Only)

Bit	Description
15	<b>Initiate FLR (IF)</b> — R/W. This bit is used to initiate FLR transition. 1 = A write of 1 initiates FLR transition. Since hardware does not respond to any cycles until FLR completion, the read value by software from this bit is 0.
14:12	Max Read Request Size — RO. Hardwired to 0 enabling 128B maximum read request size.
11	<b>No Snoop Enable (NSNPEN)</b> — R/W. 0 = The Intel HD Audio controller will not set the No Snoop bit. In this case, isochronous transfers will not use VC1 (VCi) even if it is enabled since VC1 is never snooped. Isochronous transfers will use VC0. 1 = The Intel® High Definition Audio controller is permitted to set the No Snoop bit in the Requester Attributes of a bus master transaction. In this case, VC0 or VC1 may be used for isochronous transfers.  <b>Note:</b> This bit is not reset on D3 <sub>HOT</sub> to D0 transition; however, it is reset by PLTRST#. This bit is not reset by Function Level Reset.
10	Auxiliary Power Enable — RO. Hardwired to 0, indicating that Intel HD Audio device does not draw AUX power
9	Phantom Function Enable — RO. Hardwired to 0 disabling phantom functions.
8	<b>Extended Tag Field Enable</b> — RO. Hardwired to 0 enabling 5-bit tag.
7:5	<b>Max Payload Size</b> — RO. Hardwired to 0 indicating 128B.
4	Enable Relaxed Ordering — RO. Hardwired to 0 disabling relaxed ordering.
3	Unsupported Request Reporting Enable — R/W. Not implemented.
2	Fatal Error Reporting Enable — R/W. Not implemented.
1	Non-Fatal Error Reporting Enable — R/W. Not implemented.
0	Correctable Error Reporting Enable — R/W. Not implemented.

### 18.1.33 DEVS—Device Status Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 7Ah-7Bh                      Attribute: RO  
 Default Value: 0010h                      Size: 16 bits

Bit	Description
15:6	Reserved
5	<b>Transactions Pending</b> — RO. 0 = Indicates that completions for all non-posted requests have been received 1 = Indicates that Intel High Definition Audio controller has issued non-posted requests which have not been completed.
4	<b>AUX Power Detected</b> — RO. Hardwired to 1 indicating the device is connected to resume power
3	Unsupported Request Detected — RO. Not implemented. Hardwired to 0.
2	Fatal Error Detected — RO. Not implemented. Hardwired to 0.
1	Non-Fatal Error Detected — RO. Not implemented. Hardwired to 0.
0	Correctable Error Detected — RO. Not implemented. Hardwired to 0.



**18.1.37 PVCCTL — Port VC Control Register (Intel® HD Audio Controller—D27:F0)**

Address Offset: 10Ch-10Dh                      Attribute: RO  
 Default Value: 0000h                              Size: 16 bits

Bit	Description
15:4	Reserved.
3:1	VC Arbitration Select — RO. Hardwired to 0. Normally these bits are R/W. However, these bits are not applicable since the Intel HD Audio controller reports a 0 in the Low Priority Extended VC Count bits in the PVCCAP1 register
0	Load VC Arbitration Table — RO. Hardwired to 0 since an arbitration table is not present.

**18.1.38 PVCSTS—Port VC Status Register (Intel® HD Audio Controller—D27:F0)**

Address Offset: 10Eh-10Fh                      Attribute: RO  
 Default Value: 0000h                              Size: 16 bits

Bit	Description
15:1	Reserved.
0	VC Arbitration Table Status — RO. Hardwired to 0 since an arbitration table is not present.

**18.1.39 VC0CAP—VC0 Resource Capability Register (Intel® HD Audio Controller—D27:F0)**

Address Offset: 110h-113h                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:24	Port Arbitration Table Offset — RO. Hardwired to 0 since this field is not valid for endpoint devices
23	Reserved.
22:16	Maximum Time Slots — RO. Hardwired to 0 since this field is not valid for endpoint devices
15	Reject Snoop Transactions — RO. Hardwired to 0 since this field is not valid for endpoint devices.
14	Advanced Packet Switching — RO. Hardwired to 0 since this field is not valid for endpoint devices
13:8	Reserved.
7:0	Port Arbitration Capability — RO. Hardwired to 0 since this field is not valid for endpoint devices



### 18.1.40 VCOCTL—VC0 Resource Control Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 114h-117h                      Attribute: R/W, RO  
 Default Value: 800000FFh                      Size: 32 bits  
 Function Level Reset: No

Bit	Description
31	VC0 Enable — RO. Hardwired to 1 for VC0.
30:27	Reserved.
26:24	VC0 ID — RO. Hardwired to 0 since the first VC is always assigned as VC0
23:20	Reserved.
19:17	Port Arbitration Select — RO. Hardwired to 0 since this field is not valid for endpoint devices
16	Load Port Arbitration Table — RO. Hardwired to 0 since this field is not valid for endpoint devices
15:8	Reserved.
7:0	<b>TC/VC0 Map</b> — R/W, RO. Bit 0 is hardwired to 1 since TCO is always mapped VC0. Bits [7:1] are implemented as R/W bits.

### 18.1.41 VCOSTS—VC0 Resource Status Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 11Ah-11Bh                      Attribute: RO  
 Default Value: 0000h                      Size: 16 bits

Bit	Description
15:2	Reserved.
1	VC0 Negotiation Pending — RO. Hardwired to 0 since this bit does not apply to the integrated Intel HD Audio device
0	Port Arbitration Table Status — RO. Hardwired to 0 since this field is not valid for endpoint devices

### 18.1.42 VCiCAP—VCi Resource Capability Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 11Ch-11Fh                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:24	Port Arbitration Table Offset — RO. Hardwired to 0 since this field is not valid for endpoint devices.
23	Reserved.
22:16	Maximum Time Slots — RO. Hardwired to 0 since this field is not valid for endpoint devices
15	Reject Snoop Transactions — RO. Hardwired to 0 since this field is not valid for endpoint devices
14	Advanced Packet Switching — RO. Hardwired to 0 since this field is not valid for endpoint devices
13:8	Reserved
7:0	Port Arbitration Capability — RO. Hardwired to 0 since this field is not valid for endpoint devices



### 18.1.43 VCICTL—VCi Resource Control Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 120h-123h                      Attribute: R/W, RO  
 Default Value: 00000000h                      Size: 32 bits  
 Function Level Reset: No

Bit	Description
31	<b>VCi Enable</b> — R/W. 0 = VCi is disabled 1 = VCi is enabled Note: This bit is not reset on D3 <sub>HOT</sub> to D0 transition; however, it is reset by PLTRST#.
30:27	Reserved.
26:24	<b>VCi ID</b> — R/W. This field assigns a VC ID to the VCi resource. This field is not used by the PCH hardware, but it is R/W to avoid confusing software.
23:20	Reserved.
19:17	Port Arbitration Select — RO. Hardwired to 0 since this field is not valid for endpoint devices
16	Load Port Arbitration Table — RO. Hardwired to 0 since this field is not valid for endpoint devices
15:8	Reserved.
7:0	<b>TC/VCi Map</b> — R/W, RO. This field indicates the TCs that are mapped to the VCi resource. Bit 0 is hardwired to 0 indicating that it cannot be mapped to VCi. Bits [7:1] are implemented as R/W bits. This field is not used by the PCH hardware, but it is R/W to avoid confusing software.

### 18.1.44 VCISTS—VCi Resource Status Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 126h-127h                      Attribute: RO  
 Default Value: 0000h                              Size: 16 bits

Bit	Description
15:2	Reserved.
1	VCi Negotiation Pending — RO. Does not apply. Hardwired to 0.
0	Port Arbitration Table Status — RO. Hardwired to 0 since this field is not valid for endpoint devices.

### 18.1.45 RCCAP—Root Complex Link Declaration Enhanced Capability Header Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 130h                              Attribute: RO  
 Default Value: 00010005h                      Size: 32 bits

Bit	Description
31:20	<b>Next Capability Offset</b> — RO. Hardwired to 0 indicating this is the last capability.
19:16	<b>Capability Version</b> — RO. Hardwired to 1h.
15:0	<b>PCI Express* Extended Capability ID</b> — RO. Hardwired to 0005h.



### 18.1.46 ESD—Element Self Description Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 134h-137h                      Attribute: RO  
 Default Value: 0F000100h                      Size: 32 bits

Bit	Description
31:24	<b>Port Number</b> — RO. Hardwired to 0Fh indicating that the Intel HD Audio controller is assigned as Port #15d.
23:16	<b>Component ID</b> — RO. This field returns the value of the ESD.CID field of the chip configuration section. ESD.CID is programmed by BIOS.
15:8	<b>Number of Link Entries</b> — RO. The Intel HD Audio only connects to one device, the PCH egress port. Therefore this field reports a value of 1h.
7:4	Reserved.
3:0	<b>Element Type (ELTYP)</b> — RO. The Intel HD Audio controller is an integrated Root Complex Device. Therefore, the field reports a value of 0h.

### 18.1.47 L1DESC—Link 1 Description Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 140h-143h                      Attribute: RO  
 Default Value: 00000001h                      Size: 32 bits

Bit	Description
31:24	<b>Target Port Number</b> — RO. The Intel HD Audio controller targets the PCH's Port 0.
23:16	<b>Target Component ID</b> — RO. This field returns the value of the ESD.CID field of the chip configuration section. ESD.CID is programmed by BIOS.
15:2	Reserved.
1	<b>Link Type</b> — RO. Hardwired to 0 indicating Type 0.
0	<b>Link Valid</b> — RO. Hardwired to 1.

### 18.1.48 L1ADDL—Link 1 Lower Address Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 148h-14Bh                      Attribute: RO  
 Default Value: See Register Description      Size: 32 bits

Bit	Description
31:14	<b>Link 1 Lower Address</b> — RO. Hardwired to match the RCBA register value in the PCI-LPC bridge (D31:F0:F0h).
13:0	Reserved.

### 18.1.49 L1ADDU—Link 1 Upper Address Register (Intel® HD Audio Controller—D27:F0)

Address Offset: 14Ch-14Fh                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:0	<b>Link 1 Upper Address</b> — RO. Hardwired to 00000000h.



## 18.2 Intel® HD Audio Memory Mapped Configuration Registers (Intel® HD Audio— D27:F0)

The base memory location for these memory mapped configuration registers is specified in the HDBAR register (D27:F0:offset 10h and D27:F0:offset 14h). The individual registers are then accessible at HDBAR + Offset as indicated in the following table.

These memory mapped registers must be accessed in byte, word, or DWord quantities.

**Note:** Address locations that are not shown should be treated as Reserved.

**Table 18-6. Intel® HD Audio PCI Register Address Map (Intel® HD Audio D27:F0) (Sheet 1 of 4)**

HDBAR + Offset	Mnemonic	Register Name	Default	Attribute
00h–01h	GCAP	Global Capabilities	4401h	RO
02h	VMIN	Minor Version	00h	RO
03h	VMAJ	Major Version	01h	RO
04h–05h	OUTPAY	Output Payload Capability	003Ch	RO
06h–07h	INPAY	Input Payload Capability	001Dh	RO
08h–0Bh	GCTL	Global Control	00000000h	R/W
0Ch–0Dh	WAKEEN	Wake Enable	0000h	R/W
0Eh–0Fh	STATESTS	State Change Status	0000h	R/WC
10h–11h	GSTS	Global Status	0000h	R/WC
12h–13h	Rsv	Reserved	0000h	RO
14h–17h	Rsv	Reserved	00000000h	RO
18h–19h	OUTSTRMPAY	Output Stream Payload Capability	0030h	RO
1Ah–1Bh	INSTRMPAY	Input Stream Payload Capability	0018h	RO
1Ch–1Fh	Rsv	Reserved	00000000h	RO
20h–23h	INTCTL	Interrupt Control	00000000h	R/W
24h–27h	INTSTS	Interrupt Status	00000000h	RO
30h–33h	WALCLK	Wall Clock Counter	00000000h	RO
34–37h	Rsv	Reserved	00000000h	RO
38h–3Bh	SSYNC	Stream Synchronization	00000000h	R/W
40h–43h	CORB LBASE	CORB Lower Base Address	00000000h	R/W, RO
44h–47h	CORBUBASE	CORB Upper Base Address	00000000h	R/W
48h–49h	CORBWP	CORB Write Pointer	0000h	R/W
4Ah–4Bh	CORB RP	CORB Read Pointer	0000h	R/W, RO
4Ch	CORBCTL	CORB Control	00h	R/W
4Dh	CORBST	CORB Status	00h	R/WC
4Eh	CORB SIZE	CORB Size	42h	RO
50h–53h	RIRBLBASE	RIRB Lower Base Address	00000000h	R/W, RO
54h–57h	RIRBUBASE	RIRB Upper Base Address	00000000h	R/W
58h–59h	RIRBWP	RIRB Write Pointer	0000h	R/W, RO
5Ah–5Bh	RINTCNT	Response Interrupt Count	0000h	R/W
5Ch	RIRBCTL	RIRB Control	00h	R/W


**Table 18-6. Intel® HD Audio PCI Register Address Map (Intel® HD Audio D27:F0) (Sheet 2 of 4)**

HDBAR + Offset	Mnemonic	Register Name	Default	Attribute
5Dh	RIRBSTS	RIRB Status	00h	R/WC
5Eh	RIRBSIZE	RIRB Size	42h	RO
60h–63h	IC	Immediate Command	00000000h	R/W
64h–67h	IR	Immediate Response	00000000h	RO
68h–69h	ICS	Immediate Command Status	0000h	R/W, R/WC
70h–73h	DPLBASE	DMA Position Lower Base Address	00000000h	R/W, RO
74h–77h	DPUBASE	DMA Position Upper Base Address	00000000h	R/W
80–82h	ISDOCTL	Input Stream Descriptor 0 (ISD0) Control	040000h	R/W, RO
83h	ISDOSTS	ISD0 Status	00h	R/WC, RO
84h–87h	ISD0LPIB	ISD0 Link Position in Buffer	00000000h	RO
88h–8Bh	ISDOCBL	ISD0 Cyclic Buffer Length	00000000h	R/W
8Ch–8Dh	ISD0LVI	ISD0 Last Valid Index	0000h	R/W
8Eh–8Fh	ISD0FIFOW	ISD0 FIFO Watermark	0004h	R/W
90h–91h	ISD0FIFOS	ISD0 FIFO Size	0077h	RO
92h–93h	ISD0FMT	ISD0 Format	0000h	R/W
98h–9Bh	ISD0BDPL	ISD0 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
9Ch–9Fh	ISD0BDPU	ISD0 Buffer Description List Pointer-Upper Base Address	00000000h	R/W
A0h–A2h	ISD1CTL	Input Stream Descriptor 1 (ISD01) Control	040000h	R/W, RO
A3h	ISD1STS	ISD1 Status	00h	R/WC, RO
A4h–A7h	ISD1LPIB	ISD1 Link Position in Buffer	00000000h	RO
A8h–ABh	ISD1CBL	ISD1 Cyclic Buffer Length	00000000h	R/W
ACh–ADh	ISD1LVI	ISD1 Last Valid Index	0000h	R/W
AEh–AFh	ISD1FIFOW	ISD1 FIFO Watermark	0004h	R/W
B0h–B1h	ISD1FIFOS	ISD1 FIFO Size	0077h	RO
B2h–B3h	ISD1FMT	ISD1 Format	0000h	R/W
B8h–BBh	ISD1BDPL	ISD1 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
BCh–BFh	ISD1BDPU	ISD1 Buffer Description List Pointer-Upper Base Address	00000000h	R/W
C0h–C2h	ISD2CTL	Input Stream Descriptor 2 (ISD2) Control	040000h	R/W, RO
C3h	ISD2STS	ISD2 Status	00h	R/WC, RO
C4h–C7h	ISD2LPIB	ISD2 Link Position in Buffer	00000000h	RO
C8h–CBh	ISD2CBL	ISD2 Cyclic Buffer Length	00000000h	R/W
CCh–CDh	ISD2LVI	ISD2 Last Valid Index	0000h	R/W
CEh–CFh	ISD2FIFOW	ISD2 FIFO Watermark	0004h	R/W
D0h–D1h	ISD2FIFOS	ISD2 FIFO Size	0077h	RO
D2h–D3h	ISD2FMT	ISD2 Format	0000h	R/W
D8h–DBh	ISD2BDPL	ISD2 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
DCh–DFh	ISD2BDPU	ISD2 Buffer Description List Pointer-Upper Base Address	00000000h	R/W



**Table 18-6. Intel® HD Audio PCI Register Address Map (Intel® HD Audio D27:F0) (Sheet 3 of 4)**

HDBAR + Offset	Mnemonic	Register Name	Default	Attribute
E0h–E2h	ISD3CTL	Input Stream Descriptor 3 (ISD3) Control	040000h	R/W, RO
E3h	ISD3STS	ISD3 Status	00h	R/WC, RO
E4h–E7h	ISD3LPIB	ISD3 Link Position in Buffer	00000000h	RO
E8h–EBh	ISD3CBL	ISD3 Cyclic Buffer Length	00000000h	R/W
ECh–EDh	ISD3LVI	ISD3 Last Valid Index	0000h	R/W
EEh–EFh	ISD3FIFOW	ISD3 FIFO Watermark	0004h	R/W
F0h–F1h	ISD3FIFOS	ISD3 FIFO Size	0077h	RO
F2h–F3h	ISD3FMT	ISD3 Format	0000h	R/W
F8h–FBh	ISD3BDPL	ISD3 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
FCh–FFh	ISD3BDPU	ISD3 Buffer Description List Pointer-Upper Base Address	00000000h	R/W
100h–102h	OSD0CTL	Output Stream Descriptor 0 (OSD0) Control	040000h	R/W, RO
103h	OSD0STS	OSD0 Status	00h	R/WC, RO
104h–107h	OSD0LPIB	OSD0 Link Position in Buffer	00000000h	RO
108h–10Bh	OSD0CBL	OSD0 Cyclic Buffer Length	00000000h	R/W
10Ch–10Dh	OSD0LVI	OSD0 Last Valid Index	0000h	R/W
10Eh–10Fh	OSD0FIFOW	OSD0 FIFO Watermark	0004h	R/W
110h–111h	OSD0FIFOS	OSD0 FIFO Size	00BFh	R/W
112–113h	OSD0FMT	OSD0 Format	0000h	R/W
118h–11Bh	OSD0BDPL	OSD0 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
11Ch–11Fh	OSD0BDPU	OSD0 Buffer Description List Pointer-Upper Base Address	00000000h	R/W
120h–122h	OSD1CTL	Output Stream Descriptor 1 (OSD1) Control	040000h	R/W, RO
123h	OSD1STS	OSD1 Status	00h	R/WC, RO
124h–127h	OSD1LPIB	OSD1 Link Position in Buffer	00000000h	RO
128h–12Bh	OSD1CBL	OSD1 Cyclic Buffer Length	00000000h	R/W
12Ch–12Dh	OSD1LVI	OSD1 Last Valid Index	0000h	R/W
12Eh–12Fh	OSD1FIFOW	OSD1 FIFO Watermark	0004h	R/W
130h–131h	OSD1FIFOS	OSD1 FIFO Size	00BFh	R/W
132h–133h	OSD1FMT	OSD1 Format	0000h	R/W
138h–13Bh	OSD1BDPL	OSD1 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
13Ch–13Fh	OSD1BDPU	OSD1 Buffer Description List Pointer-Upper Base Address	00000000h	R/W
140h–142h	OSD2CTL	Output Stream Descriptor 2 (OSD2) Control	040000h	R/W, RO
143h	OSD2STS	OSD2 Status	00h	R/WC, RO
144h–147h	OSD2LPIB	OSD2 Link Position in Buffer	00000000h	RO
148h–14Bh	OSD2CBL	OSD2 Cyclic Buffer Length	00000000h	R/W
14Ch–14Dh	OSD2LVI	OSD2 Last Valid Index	0000h	R/W
14Eh–14Fh	OSD2FIFOW	OSD2 FIFO Watermark	0004h	R/W
150h–151h	OSD2FIFOS	OSD2 FIFO Size	00BFh	R/W


**Table 18-6. Intel® HD Audio PCI Register Address Map (Intel® HD Audio D27:F0) (Sheet 4 of 4)**

HDBAR + Offset	Mnemonic	Register Name	Default	Attribute
152h–153h	OSD2FMT	OSD2 Format	0000h	R/W
158h–15Bh	OSD2BDPL	OSD2 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
15Ch–15Fh	OSD2BDPU	OSD2 Buffer Description List Pointer-Upper Base Address	00000000h	R/W
160h–162h	OSD3CTL	Output Stream Descriptor 3 (OSD3) Control	040000h	R/W, RO
163h	OSD3STS	OSD3 Status	00h	R/WC, RO
164h–167h	OSD3LPIB	OSD3 Link Position in Buffer	00000000h	RO
168h–16Bh	OSD3CBL	OSD3 Cyclic Buffer Length	00000000h	R/W
16Ch–16Dh	OSD3LVI	OSD3 Last Valid Index	0000h	R/W
16Eh–16Fh	OSD3FIFOW	OSD3 FIFO Watermark	0004h	R/W
170h–171h	OSD3FIFOS	OSD3 FIFO Size	00BFh	R/W
172h–173h	OSD3FMT	OSD3 Format	0000h	R/W
178h–17Bh	OSD3BDPL	OSD3 Buffer Descriptor List Pointer-Lower Base Address	00000000h	R/W, RO
17Ch–17Fh	OSD3BDPU	OSD3 Buffer Description List Pointer-Upper Base Address	00000000h	R/W

### 18.2.1 GCAP—Global Capabilities Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 00h                      Attribute:                      RO  
 Default Value:                      4401h                      Size:                      16 bits

Bit	Description
15:12	<b>Number of Output Stream Supported</b> — R/WO. 0100b indicates that the PCH's Intel® High Definition Audio controller supports 4 output streams.
11:8	<b>Number of Input Stream Supported</b> — R/WO. 0100b indicates that the PCH's Intel® High Definition Audio controller supports 4 input streams.
7:3	<b>Number of Bidirectional Stream Supported</b> — RO. Hardwired to 0 indicating that the PCH's Intel® High Definition Audio controller supports 0 bidirectional stream.
2:1	<b>Number of Serial Data Out Signals</b> — RO. Hardwired to 0 indicating that the PCH's Intel® High Definition Audio controller supports 1 serial data output signal.
0	<b>64-bit Address Supported</b> — R/WO. 1b indicates that the PCH's Intel® High Definition Audio controller supports 64-bit addressing for BDL addresses, data buffer addressees, and command buffer addresses.

### 18.2.2 VMIN—Minor Version Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 02h                      Attribute:                      RO  
 Default Value:                      00h                      Size:                      8 bits

Bit	Description
7:0	<b>Minor Version</b> — RO. Hardwired to 0 indicating that the PCH supports minor revision number 00h of the Intel HD Audio specification.



### 18.2.3 VMAJ—Major Version Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 03h                      Attribute:                      RO  
Default Value:     01h                                      Size:                                8 bits

Bit	Description
7:0	<b>Major Version</b> — RO. Hardwired to 01h indicating that the PCH supports major revision number 1 of the Intel HD Audio specification.

### 18.2.4 OUTPAY—Output Payload Capability Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 04h                      Attribute:                      RO  
Default Value:     003Ch                                      Size:                                16 bits

Bit	Description
15:7	Reserved.
6:0	<b>Output Payload Capability</b> — RO. Hardwired to 3Ch indicating 60 word payload. This field indicates the total output payload available on the link. This does not include bandwidth used for command and control. This measurement is in 16-bit word quantities per 48 MHz frame. The default link clock of 24.000 MHz (the data is double pumped) provides 1000 bits per frame, or 62.5 words in total. 40 bits are used for command and control, leaving 60 words available for data payload. 00h = 0 word 01h = 1 word payload. ..... FFh = 256 word payload.

### 18.2.5 INPAY—Input Payload Capability Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 06h                      Attribute:                      RO  
Default Value:     001Dh                                      Size:                                16 bits

Bit	Description
15:7	Reserved.
6:0	<b>Input Payload Capability</b> — RO. Hardwired to 1Dh indicating 29 word payload. This field indicates the total output payload available on the link. This does not include bandwidth used for response. This measurement is in 16-bit word quantities per 48 MHz frame. The default link clock of 24.000 MHz provides 500 bits per frame, or 31.25 words in total. 36 bits are used for response, leaving 29 words available for data payload. 00h = 0 word 01h = 1 word payload. ..... FFh = 256 word payload.



## 18.2.6 GCTL—Global Control Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 08h  
Default Value: 00000000h

Attribute:  
Size:

R/W  
32 bits

Bit	Description
31:9	Reserved.
8	<p><b>Accept Unsolicited Response Enable</b> — R/W. 0 = Unsolicited responses from the codecs are not accepted. 1 = Unsolicited response from the codecs are accepted by the controller and placed into the Response Input Ring Buffer.</p>
7:2	Reserved.
1	<p><b>Flush Control</b> — R/W. Writing a 1 to this bit initiates a flush. When the flush completion is received by the controller, hardware sets the Flush Status bit and clears this Flush Control bit. Before a flush cycle is initiated, the DMA Position Buffer must be programmed with a valid memory address by software, but the DMA Position Buffer bit 0 needs not be set to enable the position reporting mechanism. Also, all streams must be stopped (the associated RUN bit must be 0). When the flush is initiated, the controller will flush the pipelines to memory to ensure that the hardware is ready to transition to a D3 state. Setting this bit is not a critical step in the power state transition if the content of the FIFOs is not critical.</p>
0	<p><b>Controller Reset #</b> — R/W. 0 = Writing a 0 causes the Intel HD Audio controller to be reset. All state machines, FIFOs and non-resume well memory mapped configuration registers (not PCI configuration registers) in the controller will be reset. The Intel HD Audio link RESET# signal will be asserted, and all other link signals will be driven to their default values. After the hardware has completed sequencing into the reset state, it will report a 0 in this bit. Software must read a 0 from this bit to verify the controller is in reset. 1 = Writing a 1 causes the controller to exit its reset state and deassert the Intel HD Audio link RESET# signal. Software is responsible for setting/clearing this bit such that the minimum Intel HD Audio link RESET# signal assertion pulse width specification is met. When the controller hardware is ready to begin operation, it will report a 1 in this bit. Software must read a 1 from this bit before accessing any controller registers. This bit defaults to a 0 after Hardware reset, therefore, software needs to write a 1 to this bit to begin operation.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>1. The CORB/RIRB RUN bits and all stream RUN bits must be verified cleared to 0 before writing a 0 to this bit in order to assure a clean re-start.</li> <li>2. When setting or clearing this bit, software must ensure that minimum link timing requirements (minimum RESET# assertion time, and so forth) are met.</li> <li>3. When this bit is 0 indicating that the controller is in reset, writes to all Intel HD Audio memory mapped registers are ignored as if the device is not present. The only exception is this register itself. The Global Control register is write-able as a DWord, Word, or Byte even when CRST# (this bit) is 0 if the byte enable for the byte containing the CRST# bit (Byte Enable 0) is active. If Byte Enable 0 is not active, writes to the Global Control register will be ignored when CRST# is 0. When CRST# is 0, reads to Intel HD Audio memory mapped registers will return their default value except for registers that are not reset with PLTRST# or on a D3<sub>HOT</sub> to D0 transition.</li> </ol>



### 18.2.7 WAKEEN—Wake Enable Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 0Ch                      Attribute:                      R/W  
 Default Value:    0000h                              Size:                              16 bits  
 Function Level Reset: No

Bit	Description
15:4	Reserved.
3:0	<p><b>SDIN Wake Enable Flags</b> — R/W. These bits control which SDI signal(s) may generate a wake event. A 1b in the bit mask indicates that the associated SDIN signal is enabled to generate a wake.</p> <p>Bit 0 is used for SDI[0]            Bit 1 is used for SDI[1]            Bit 2 is used for SDI[2]            Bit 3 is used for SDI[3]</p> <p><b>Note:</b> These bits are in the resume well and only cleared on a power on reset. Software must not make assumptions about the reset state of these bits and must set them appropriately.</p>

### 18.2.8 STATESTS—State Change Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 0Eh                      Attribute:                      R/WC  
 Default Value:    0000h                              Size:                              16 bits  
 Function Level Reset: No

Bit	Description
15:4	Reserved.
3:0	<p><b>SDIN State Change Status Flags</b> — R/WC. Flag bits that indicate which SDI signal(s) received a state change event. The bits are cleared by writing 1s to them.</p> <p>Bit 0 = SDI[0]            Bit 1 = SDI[1]            Bit 2 = SDI[2]            Bit 3 = SDI[3]</p> <p>These bits are in the resume well and only cleared on a power on reset. Software must not make assumptions about the reset state of these bits and must set them appropriately.</p>

### 18.2.9 GSTS—Global Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 10h                      Attribute:                      R/WC  
 Default Value:    0000h                              Size:                              16 bits

Bit	Description
15:2	Reserved.
1	<p><b>Flush Status</b> — R/WC. This bit is set to 1 by hardware to indicate that the flush cycle initiated when the Flush Control bit (HDBAR + 08h, bit 1) was set has completed. Software must write a 1 to clear this bit before the next time the Flush Control bit is set to clear the bit.</p>
0	Reserved.



### 18.2.10 OUTSTRMPAY—Output Stream Payload Capability (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 18h                      Attribute:                      RO  
 Default Value:                      0030h                      Size:                      16 bits

Bit	Description
15:8	Reserved
7:0	<p><b>Output Stream Payload Capability (OUTSTRMPAY)</b>— RO: Indicates maximum number of words per frame for any single output stream. This measurement is in 16 bit word quantities per 48 kHz frame. 48 Words (96B) is the maximum supported, therefore a value of 30h is reported in this register. Software must ensure that a format which would cause more words per frame than indicated is not programmed into the Output Stream Descriptor register.</p> <p>00h: 0 words            01h: 1 word payload            ...            FFh: 255h word payload</p>

### 18.2.11 INSTRMPAY—Input Stream Payload Capability (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 1Ah                      Attribute:                      RO  
 Default Value:                      0018h                      Size:                      16 bits

Bit	Description
15:8	Reserved
7:0	<p><b>Input Stream Payload Capability (INSTRMPAY)</b>— RO: Indicates maximum number of words per frame for any single input stream. This measurement is in 16 bit word quantities per 48 kHz frame. 24 Words (48B) is the maximum supported, therefore a value of 18h is reported in this register. Software must ensure that a format which would cause more words per frame than indicated is not programmed into the Input Stream Descriptor register.</p> <p>00h: 0 words            01h: 1 word payload            ...            FFh: 255h word payload</p>

### 18.2.12 INTCTL—Interrupt Control Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: HDBAR + 20h                      Attribute:                      R/W  
 Default Value:                      0000000h                      Size:                      32 bits

Bit	Description
31	<p><b>Global Interrupt Enable (GIE)</b> — R/W. Global bit to enable device interrupt generation. 1 = When set to 1, the Intel HD Audio function is enabled to generate an interrupt. This control is in addition to any bits in the bus specific address space, such as the Interrupt Enable bit in the PCI configuration space.</p> <p><b>Note:</b> This bit is not affected by the D3<sub>HOT</sub> to D0 transition.</p>
30	<p><b>Controller Interrupt Enable (CIE)</b> — R/W. Enables the general interrupt for controller functions. 1 = When set to 1, the controller generates an interrupt when the corresponding status bit gets set due to a Response Interrupt, a Response Buffer Overrun, and State Change events.</p> <p><b>Note:</b> This bit is not affected by the D3<sub>HOT</sub> to D0 transition.</p>
29:8	Reserved



Bit	Description
7:0	<p><b>Stream Interrupt Enable (SIE)</b> — R/W. When set to 1, the individual streams are enabled to generate an interrupt when the corresponding status bits get set.</p> <p>A stream interrupt will be caused as a result of a buffer with IOC = 1 in the BDL entry being completed, or as a result of a FIFO error (underrun or overrun) occurring. Control over the generation of each of these sources is in the associated Stream Descriptor.</p> <p>The streams are numbered and the SIE bits assigned sequentially, based on their order in the register set.</p> <p>Bit 0 = input stream 1            Bit 1 = input stream 2            Bit 2 = input stream 3            Bit 3 = input stream 4            Bit 4 = output stream 1            Bit 5 = output stream 2            Bit 6 = output stream 3            Bit 7 = output stream 4</p>

### 18.2.13 INTSTS—Interrupt Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 24h  
 Default Value: 00000000h

Attribute: RO  
 Size: 32 bits

Bit	Description
31	<p><b>Global Interrupt Status (GIS)</b> — RO. This bit is an OR of all the interrupt status bits in this register.</p> <p><b>Note:</b> This bit is not affected by the D3<sub>HOT</sub> to D0 transition.</p>
30	<p><b>Controller Interrupt Status (CIS)</b> — RO. Status of general controller interrupt.</p> <p>1 = Interrupt condition occurred due to a Response Interrupt, a Response Buffer Overrun Interrupt, or a SDIN State Change event. The exact cause can be determined by interrogating other registers. This bit is an OR of all of the stated interrupt status bits for this register.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This bit is set regardless of the state of the corresponding interrupt enable bit, but a hardware interrupt will not be generated unless the corresponding enable bit is set.</li> <li>This bit is not affected by the D3<sub>HOT</sub> to D0 transition.</li> </ol>
29:8	Reserved
7:0	<p><b>Stream Interrupt Status (SIS)</b> — RO.</p> <p>1 = Interrupt condition occurred on the corresponding stream. This bit is an OR of all of the stream's interrupt status bits.</p> <p><b>Note:</b> These bits are set regardless of the state of the corresponding interrupt enable bits. The streams are numbered and the SIE bits assigned sequentially, based on their order in the register set.</p> <p>Bit 0 = input stream 1            Bit 1 = input stream 2            Bit 2 = input stream 3            Bit 3 = input stream 4            Bit 4 = output stream 1            Bit 5 = output stream 2            Bit 6 = output stream 3            Bit 7 = output stream 4</p>



### 18.2.14 WALCLK—Wall Clock Counter Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 30h                      Attribute:                      RO  
Default Value:                      00000000h                      Size:                      32 bits

Bit	Description
31:0	<b>Wall Clock Counter</b> — RO. A 32 bit counter that is incremented on each link Bit Clock period and rolls over from FFFF FFFFh to 0000 0000h. This counter will roll over to 0 with a period of approximately 179 seconds. This counter is enabled while the Bit Clock bit is set to 1. Software uses this counter to synchronize between multiple controllers. Will be reset on controller reset.

### 18.2.15 SSYNC—Stream Synchronization Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 38h                      Attribute:                      R/W  
Default Value:                      00000000h                      Size:                      32 bits

Bit	Description
31:8	Reserved
7:0	<b>Stream Synchronization (SSYNC)</b> — R/W. When set to 1, these bits block data from being sent on or received from the link. Each bit controls the associated stream descriptor (that is, bit 0 corresponds to the first stream descriptor, and so forth). To synchronously start a set of DMA engines, these bits are first set to 1. The RUN bits for the associated stream descriptors are then set to 1 to start the DMA engines. When all streams are ready (FIFORDY = 1), the associated SSYNC bits can all be set to 0 at the same time, and transmission or reception of bits to or from the link will begin together at the start of the next full link frame. To synchronously stop the streams, first these bits are set, and then the individual RUN bits in the stream descriptor are cleared by software. If synchronization is not desired, these bits may be left as 0, and the stream will simply begin running normally when the stream's RUN bit is set. The streams are numbered and the SIE bits assigned sequentially, based on their order in the register set. Bit 0 = input stream 1 Bit 1 = input stream 2 Bit 2 = input stream 3 Bit 3 = input stream 4 Bit 4 = output stream 1 Bit 5 = output stream 2 Bit 6 = output stream 3 Bit 7 = output stream 4

### 18.2.16 CORLBASE—CORB Lower Base Address Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 40h                      Attribute:                      R/W, RO  
Default Value:                      00000000h                      Size:                      32 bits

Bit	Description
31:7	<b>CORB Lower Base Address</b> — R/W. Lower address of the Command Output Ring Buffer, allowing the CORB base address to be assigned on any 128-B boundary. This register field must not be written when the DMA engine is running or the DMA transfer may be corrupted.
6:0	<b>CORB Lower Base Unimplemented Bits</b> — RO. Hardwired to 0. This required the CORB to be allocated with 128B granularity to allow for cache line fetch optimizations.



### 18.2.17 CORBUBASE—CORB Upper Base Address Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 44h                      Attribute:                      R/W  
 Default Value:    00000000h                      Size:                              32 bits

Bit	Description
31:0	<b>CORB Upper Base Address</b> — R/W. Upper 32 bits of the address of the Command Output Ring buffer. This register field must not be written when the DMA engine is running or the DMA transfer may be corrupted.

### 18.2.18 CORBWP—CORB Write Pointer Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 48h                      Attribute:                      R/W  
 Default Value:    0000h                                      Size:                              16 bits

Bit	Description
15:8	Reserved.
7:0	<b>CORB Write Pointer</b> — R/W. Software writes the last valid CORB entry offset into this field in DWord granularity. The DMA engine fetches commands from the CORB until the Read pointer matches the Write pointer. Supports 256 CORB entries (256x4B = 1 KB). This register field may be written when the DMA engine is running.

### 18.2.19 CORBRP—CORB Read Pointer Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: HDBAR + 4Ah                      Attribute:                      R/W, RO  
 Default Value:    0000h                                      Size:                              16 bits

Bit	Description
15	<b>CORB Read Pointer Reset</b> — R/W. Software writes a 1 to this bit to reset the CORB Read Pointer to 0 and clear any residual prefetched commands in the CORB hardware buffer within the Intel High Definition Audio controller. The hardware will physically update this bit to 1 when the CORB Pointer reset is complete. Software must read a 1 to verify that the reset completed correctly. Software must clear this bit back to 0 and read back the 0 to verify that the clear completed correctly. The CORB DMA engine must be stopped prior to resetting the Read Pointer or else DMA transfer may be corrupted.
14:8	Reserved.
7:0	<b>CORB Read Pointer (CORBRP)</b> — RO. Software reads this field to determine how many commands it can write to the CORB without over-running. The value read indicates the CORB Read Pointer offset in Dword granularity. The offset entry read from this field has been successfully fetched by the DMA controller and may be over-written by software. Supports 256 CORB entries (256 x 4B=1 KB). This field may be read while the DMA engine is running.



### 18.2.20 Using CORBCTL—CORB Control Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 4Ch                      Attribute:                      R/W  
 Default Value:                      00h                      Size:                      8 bits

Bit	Description
7:2	Reserved.
1	<b>Enable CORB DMA Engine</b> — R/W. 0 = DMA stop 1 = DMA run After software writes a 0 to this bit, the hardware may not stop immediately. The hardware will physically update the bit to 0 when the DMA engine is truly stopped. Software must read a 0 from this bit to verify that the DMA engine is truly stopped.
0	<b>CORB Memory Error Interrupt Enable</b> — R/W. If this bit is set the controller will generate an interrupt if the CMEI status bit (HDBAR + 4Dh: bit 0) is set.

### 18.2.21 CORBST—CORB Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 4Dh                      Attribute:                      R/WC  
 Default Value:                      00h                      Size:                      8 bits

Bit	Description
7:1	Reserved.
0	<b>CORB Memory Error Indication (CMEI)</b> — R/WC. 1 = Controller detected an error in the path way between the controller and memory. This may be an ECC bit error or any other type of detectable data error which renders the command data fetched invalid. Software can clear this bit by writing a 1 to it. However, this type of error leaves the audio subsystem in an un-viable state and typically requires a controller reset by writing a 0 to the Controller Reset # bit (HDBAR + 08h: bit 0).

### 18.2.22 CORBSIZE—CORB Size Register (Intel® HD Audio Controller—D27:F0 using)

Memory Address: HDBAR + 4Eh                      Attribute:                      RO  
 Default Value:                      42h                      Size:                      8 bits

Bit	Description
7:4	<b>CORB Size Capability</b> — RO. Hardwired to 0100b indicating that the PCH only supports a CORB size of 256 CORB entries (1024B)
3:2	Reserved.
1:0	<b>CORB Size</b> — RO. Hardwired to 10b which sets the CORB size to 256 entries (1024B)



### 18.2.23 RIRBLBASE—RIRB Lower Base Address Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 50h                      Attribute:                      R/W, RO  
Default Value:     00000000h                      Size:                              32 bits

Bit	Description
31:7	<b>RIRB Lower Base Address</b> — R/W. Lower address of the Response Input Ring Buffer, allowing the RIRB base address to be assigned on any 128-B boundary. This register field must not be written when the DMA engine is running or the DMA transfer may be corrupted.
6:0	RIRB Lower Base Unimplemented Bits — RO. Hardwired to 0. This required the RIRB to be allocated with 128-B granularity to allow for cache line fetch optimizations.

### 18.2.24 RIRBUBASE—RIRB Upper Base Address Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 54h                      Attribute:                      R/W  
Default Value:     00000000h                      Size:                              32 bits

Bit	Description
31:0	<b>RIRB Upper Base Address</b> — R/W. Upper 32 bits of the address of the Response Input Ring Buffer. This register field must not be written when the DMA engine is running or the DMA transfer may be corrupted.

### 18.2.25 RIRBWP—RIRB Write Pointer Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 58h                      Attribute:                      R/W, RO  
Default Value:     0000h                              Size:                              16 bits

Bit	Description
15	<b>RIRB Write Pointer Reset</b> — R/W. Software writes a 1 to this bit to reset the RIRB Write Pointer to 0. The RIRB DMA engine must be stopped prior to resetting the Write Pointer or else DMA transfer may be corrupted. This bit is always read as 0.
14:8	Reserved.
7:0	<b>RIRB Write Pointer (RIRBWP)</b> — RO. Indicates the last valid RIRB entry written by the DMA controller. Software reads this field to determine how many responses it can read from the RIRB. The value read indicates the RIRB Write Pointer offset in 2 DWord RIRB entry units (since each RIRB entry is 2 DWords long). Supports up to 256 RIRB entries (256 x 8 B = 2 KB). This register field may be written when the DMA engine is running.



### 18.2.26 RINTCNT—Response Interrupt Count Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 5Ah                      Attribute:                      R/W  
 Default Value: 0000h                              Size:                              16 bits

Bit	Description
15:8	Reserved.
7:0	<p><b>N Response Interrupt Count</b> — R/W.                      0000 0001b = 1 response sent to RIRB                      .....                      1111 1111b = 255 responses sent to RIRB                      0000 0000b = 256 responses sent to RIRB                      The DMA engine should be stopped when changing this field or else an interrupt may be lost.                      Note that each response occupies 2 DWords in the RIRB.                      This is compared to the total number of responses that have been returned, as opposed to the number of frames in which there were responses. If more than one codecs responds in one frame, then the count is increased by the number of responses received in the frame.</p>

### 18.2.27 RIRBCTL—RIRB Control Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 5Ch                      Attribute:                      R/W  
 Default Value: 00h                                      Size:                                      8 bits

Bit	Description
7:3	Reserved.
2	<p><b>Response Overrun Interrupt Control</b> — R/W. If this bit is set, the hardware will generate an interrupt when the Response Overrun Interrupt Status bit (HDBAR + 5Dh: bit 2) is set.</p>
1	<p><b>Enable RIRB DMA Engine</b> — R/W.                      0 = DMA stop                      1 = DMA run                      After software writes a 0 to this bit, the hardware may not stop immediately. The hardware will physically update the bit to 0 when the DMA engine is truly stopped. Software must read a 0 from this bit to verify that the DMA engine is truly stopped.</p>
0	<p><b>Response Interrupt Control</b> — R/W.                      0 = Disable Interrupt                      1 = Generate an interrupt after N number of responses are sent to the RIRB buffer OR when an empty Response slot is encountered on all SDI[x] inputs (whichever occurs first). The N counter is reset when the interrupt is generated.</p>



### 18.2.28 RIRBSTS—RIRB Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 5Dh                      Attribute:                      R/WC  
 Default Value: 00h                                      Size:                                8 bits

Bit	Description
7:3	Reserved.
2	<b>Response Overrun Interrupt Status</b> — R/WC. 1 = Software sets this bit to 1 when the RIRB DMA engine is not able to write the incoming responses to memory before additional incoming responses overrun the internal FIFO. When the overrun occurs, the hardware will drop the responses which overrun the buffer. An interrupt may be generated if the Response Overrun Interrupt Control bit is set. Note that this status bit is set even if an interrupt is not enabled for this event. Software clears this bit by writing a 1 to it.
1	Reserved.
0	<b>Response Interrupt</b> — R/WC. 1 = Hardware sets this bit to 1 when an interrupt has been generated after N number of Responses are sent to the RIRB buffer OR when an empty Response slot is encountered on all SDI[x] inputs (whichever occurs first). Note that this status bit is set even if an interrupt is not enabled for this event. Software clears this bit by writing a 1 to it.

### 18.2.29 RIRBSIZE—RIRB Size Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 5Eh                      Attribute:                      RO  
 Default Value: 42h                                      Size:                                8 bits

Bit	Description
7:4	<b>RIRB Size Capability</b> — RO. Hardwired to 0100b indicating that the PCH only supports a RIRB size of 256 RIRB entries (2048B)
3:2	Reserved.
1:0	<b>RIRB Size</b> — RO. Hardwired to 10b which sets the CORB size to 256 entries (2048B)

### 18.2.30 IC—Immediate Command Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 60h                      Attribute:                      R/W  
 Default Value: 00000000h                              Size:                                32 bits

Bit	Description
31:0	<b>Immediate Command Write</b> — R/W. The command to be sent to the codec using the Immediate Command mechanism is written to this register. The command stored in this register is sent out over the link during the next available frame after a 1 is written to the ICB bit (HDBAR + 68h: bit 0)



### 18.2.31 IR—Immediate Response Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 64h                      Attribute:                      RO  
 Default Value: 00000000h                      Size:                      32 bits

Bit	Description
31:0	<b>Immediate Response Read (IRR)</b> — RO. This register contains the response received from a codec resulting from a command sent using the Immediate Command mechanism. If multiple codecs responded in the same time, there is no assurance as to which response will be latched. Therefore, broadcast-type commands must not be issued using the Immediate Command mechanism.

### 18.2.32 ICS—Immediate Command Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 68h                      Attribute:                      R/W, R/WC  
 Default Value: 0000h                      Size:                      16 bits

Bit	Description
15:2	Reserved.
1	<b>Immediate Result Valid (IRV)</b> — R/WC. 1 = Set to 1 by hardware when a new response is latched into the Immediate Response register (HDBAR + 64). This is a status flag indicating that software may read the response from the Immediate Response register. Software must clear this bit by writing a 1 to it before issuing a new command so that the software may determine when a new response has arrived.
0	<b>Immediate Command Busy (ICB)</b> — R/W. When this bit is read as 0, it indicates that a new command may be issued using the Immediate Command mechanism. When this bit transitions from a 0 to a 1 (using software writing a 1), the controller issues the command currently stored in the Immediate Command register to the codec over the link. When the corresponding response is latched into the Immediate Response register, the controller hardware sets the IRV flag and clears the ICB bit back to 0. Software may write this bit to a 0 if the bit fails to return to 0 after a reasonable time out period.  <b>Note:</b> An Immediate Command must not be issued while the CORB/RIRB mechanism is operating, otherwise the responses conflict. This must be enforced by software.

### 18.2.33 DPLBASE—DMA Position Lower Base Address Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 70h                      Attribute:                      R/W, RO  
 Default Value: 00000000h                      Size:                      32 bits

Bit	Description
31:7	<b>DMA Position Lower Base Address</b> — R/W. Lower 32 bits of the DMA Position Buffer Base Address. This register field must not be written when any DMA engine is running or the DMA transfer may be corrupted. This same address is used by the Flush Control and must be programmed with a valid value before the Flush Control bit (HDBAR+08h:bit 1) is set.
6:1	DMA Position Lower Base Unimplemented bits — RO. Hardwired to 0 to force the 128-byte buffer alignment for cache line write optimizations.
0	<b>DMA Position Buffer Enable</b> — R/W. 1 = Controller will write the DMA positions of each of the DMA engines to the buffer in the main memory periodically (typically once per frame). Software can use this value to know what data in memory is valid data.



### 18.2.34 DPUBASE—DMA Position Upper Base Address Register (Intel® HD Audio Controller—D27:F0)

Memory Address: HDBAR + 74h                      Attribute:                      R/W  
 Default Value:    00000000h                      Size:                              32 bits

Bit	Description
31:0	<b>DMA Position Upper Base Address</b> — R/W. Upper 32 bits of the DMA Position Buffer Base Address. This register field must not be written when any DMA engine is running or the DMA transfer may be corrupted.

### 18.2.35 SDCTL—Stream Descriptor Control Register (Intel® HD Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 80h Attribute:    R/W, RO  
                           Input Stream[1]: HDBAR + A0h  
                           Input Stream[2]: HDBAR + C0h  
                           Input Stream[3]: HDBAR + E0h  
                           Output Stream[0]: HDBAR + 100h  
                           Output Stream[1]: HDBAR + 120h  
                           Output Stream[2]: HDBAR + 140h  
                           Output Stream[3]: HDBAR + 160h  
 Default Value:    040000h                      Size: 24 bits

Bit	Description
23:20	<b>Stream Number</b> — R/W. This value reflect the Tag associated with the data being transferred on the link. When data controlled by this descriptor is sent out over the link, it will have its stream number encoded on the SYNC signal. When an input stream is detected on any of the SDI signals that match this value, the data samples are loaded into FIFO associated with this descriptor. Note that while a single SDI input may contain data from more than one stream number, two different SDI inputs may not be configured with the same stream number. 0000 = Reserved 0001 = Stream 1 ..... 1110 = Stream 14 1111 = Stream 15
19	<b>Bidirectional Direction Control</b> — RO. This bit is only meaningful for bidirectional streams; therefore, this bit is hardwired to 0.
18	<b>Traffic Priority</b> — RO. Hardwired to 1 indicating that all streams will use VC1 if it is enabled through the PCI Express* registers.
17:16	<b>Stripe Control</b> — RO. This bit is only meaningful for input streams; therefore, this bit is hardwired to 0.
15:5	Reserved
4	<b>Descriptor Error Interrupt Enable</b> — R/W. 0 = Disable 1 = An interrupt is generated when the Descriptor Error Status bit is set.
3	<b>FIFO Error Interrupt Enable</b> — R/W. This bit controls whether the occurrence of a FIFO error (overflow for input or underflow for output) will cause an interrupt or not. If this bit is not set, bit 3 in the Status register will be set, but the interrupt will not occur. Either way, the samples will be dropped.



Bit	Description
2	<b>Interrupt on Completion Enable</b> — R/W. This bit controls whether or not an interrupt occurs when a buffer completes with the IOC bit set in its descriptor. If this bit is not set, bit 2 in the Status register will be set, but the interrupt will not occur.
1	<b>Stream Run (RUN)</b> — R/W. 0 = DMA engine associated with this input stream will be disabled. The hardware will report a 0 in this bit when the DMA engine is actually stopped. Software must read a 0 from this bit before modifying related control registers or restarting the DMA engine. 1 = DMA engine associated with this input stream will be enabled to transfer data from the FIFO to the main memory. The SSYNC bit must also be cleared in order for the DMA engine to run. For output streams, the cadence generator is reset whenever the RUN bit is set.
0	<b>Stream Reset (SRST)</b> — R/W. 0 = Writing a 0 causes the corresponding stream to exit reset. When the stream hardware is ready to begin operation, it will report a 0 in this bit. Software must read a 0 from this bit before accessing any of the stream registers. 1 = Writing a 1 causes the corresponding stream to be reset. The Stream Descriptor registers (except the SRST bit itself) and FIFOs for the corresponding stream are reset. After the stream hardware has completed sequencing into the reset state, it will report a 1 in this bit. Software must read a 1 from this bit to verify that the stream is in reset. The RUN bit must be cleared before SRST is asserted.

### 18.2.36 SDSTS—Stream Descriptor Status Register (Intel® HD Audio Controller—D27:F0)

Memory Address:	Input Stream[0]: HDBAR + 83h Input Stream[1]: HDBAR + A3h Input Stream[2]: HDBAR + C3h Input Stream[3]: HDBAR + E3h Output Stream[0]: HDBAR + 103h Output Stream[1]: HDBAR + 123h Output Stream[2]: HDBAR + 143h Output Stream[3]: HDBAR + 163h	Attribute: R/WC, RO
Default Value:	00h	Size: 8 bits

Bit	Description
7:6	Reserved.
5	<b>FIFO Ready (FIFORDY)</b> — RO. For output streams, the controller hardware will set this bit to 1 while the output DMA FIFO contains enough data to maintain the stream on the link. This bit defaults to 0 on reset because the FIFO is cleared on a reset. For input streams, the controller hardware will set this bit to 1 when a valid descriptor is loaded and the engine is ready for the RUN bit to be set.
4	<b>Descriptor Error</b> — R/WC. 1 = A serious error occurred during the fetch of a descriptor. This could be a result of a Master Abort, a parity or ECC error on the bus, or any other error which renders the current Buffer Descriptor or Buffer Descriptor list useless. This error is treated as a fatal stream error, as the stream cannot continue running. The RUN bit will be cleared and the stream will stopped. Software may attempt to restart the stream engine after addressing the cause of the error and writing a 1 to this bit to clear it.



Bit	Description
3	<p><b>FIFO Error</b> — R/WC. 1 = FIFO error occurred. This bit is set even if an interrupt is not enabled. The bit is cleared by writing a 1 to it.</p> <p>For an input stream, this indicates a FIFO overrun occurring while the RUN bit is set. When this happens, the FIFO pointers do not increment and the incoming data is not written into the FIFO, thereby being lost.</p> <p>For an output stream, this indicates a FIFO underrun when there are still buffers to send. The hardware should not transmit anything on the link for the associated stream if there is not valid data to send.</p>
2	<p><b>Buffer Completion Interrupt Status</b> — R/WC. This bit is set to 1 by the hardware after the last sample of a buffer has been processed, AND if the Interrupt on Completion bit is set in the command byte of the buffer descriptor. It remains active until software clears it by writing a 1 to it.</p>
1:0	Reserved.

### 18.2.37 SDLPB—Stream Descriptor Link Position in Buffer Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 84h                      Attribute: RO  
                           Input Stream[1]: HDBAR + A4h  
                           Input Stream[2]: HDBAR + C4h  
                           Input Stream[3]: HDBAR + E4h  
                           Output Stream[0]: HDBAR + 104h  
                           Output Stream[1]: HDBAR + 124h  
                           Output Stream[2]: HDBAR + 144h  
                           Output Stream[3]: HDBAR + 164h

Default Value: 00000000h                                      Size: 32 bits

Bit	Description
31:0	<p><b>Link Position in Buffer</b> — RO. Indicates the number of bytes that have been received off the link. This register will count from 0 to the value in the Cyclic Buffer Length register and then wrap to 0.</p>

### 18.2.38 SDCBL—Stream Descriptor Cyclic Buffer Length Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 88h                      Attribute: R/W  
                           Input Stream[1]: HDBAR + A8h  
                           Input Stream[2]: HDBAR + C8h  
                           Input Stream[3]: HDBAR + E8h  
                           Output Stream[0]: HDBAR + 108h  
                           Output Stream[1]: HDBAR + 128h  
                           Output Stream[2]: HDBAR + 148h  
                           Output Stream[3]: HDBAR + 168h

Default Value: 00000000h                                      Size: 32 bits

Bit	Description
31:0	<p><b>Cyclic Buffer Length</b> — R/W. Indicates the number of bytes in the complete cyclic buffer. This register represents an integer number of samples. Link Position in Buffer will be reset when it reaches this value.</p> <p>Software may only write to this register after Global Reset, Controller Reset, or Stream Reset has occurred. This value should be only modified when the RUN bit is 0. Once the RUN bit has been set to enable the engine, software must not write to this register until after the next reset is asserted, or transfer may be corrupted.</p>



### 18.2.39 SDLVI—Stream Descriptor Last Valid Index Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 8Ch                      Attribute: R/W  
                           Input Stream[1]: HDBAR + ACh  
                           Input Stream[2]: HDBAR + CCh  
                           Input Stream[3]: HDBAR + ECh  
                           Output Stream[0]: HDBAR + 10Ch  
                           Output Stream[1]: HDBAR + 12Ch  
                           Output Stream[2]: HDBAR + 14Ch  
                           Output Stream[3]: HDBAR + 16Ch

Default Value: 0000h    Size: 16 bits

Bit	Description
15:8	Reserved.
7:0	<p><b>Last Valid Index</b> — R/W. The value written to this register indicates the index for the last valid Buffer Descriptor in BDL. After the controller has processed this descriptor, it will wrap back to the first descriptor in the list and continue processing.</p> <p>This field must be at least 1; that is, there must be at least 2 valid entries in the buffer descriptor list before DMA operations can begin.</p> <p>This value should only modified when the RUN bit is 0.</p>

### 18.2.40 SDFIFOW—Stream Descriptor FIFO Watermark Register (Intel® HD Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 8Eh                      Attribute: R/W  
                           Input Stream[1]: HDBAR + AEh  
                           Input Stream[2]: HDBAR + CEh  
                           Input Stream[3]: HDBAR + EEh  
                           Output Stream[0]: HDBAR + 10Eh  
                           Output Stream[1]: HDBAR + 12Eh  
                           Output Stream[2]: HDBAR + 14Eh  
                           Output Stream[3]: HDBAR + 16Eh

Default Value: 0004h    Size: 16 bits

Bit	Description
15:3	Reserved.
2:0	<p><b>FIFO Watermark (FIFOW)</b> — RO. Indicates the minimum number of bytes accumulated/free in the FIFO before the controller will start a fetch/eviction of data. The HD Audio Controller hardwires the FIFO Watermark to either 32 B or 64 B based on the number of bytes per frame for the configured input stream.</p> <p>100 = 32B (Default)            101 = 64B            Others = Unsupported</p> <p><b>Note:</b> When the bit field is programmed to an unsupported size, the hardware sets itself to the default value.</p> <p>Software must read the bit field to test if the value is supported after setting the bit field.</p>





### 18.2.43 SDFMT—Stream Descriptor Format Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 92h                      Attribute: R/W  
 Input Stream[1]: HDBAR + B2h  
 Input Stream[2]: HDBAR + D2h  
 Input Stream[3]: HDBAR + F2h  
 Output Stream[0]: HDBAR + 112h  
 Output Stream[1]: HDBAR + 132h  
 Output Stream[2]: HDBAR + 152h  
 Output Stream[3]: HDBAR + 172h

Default Value: 0000h    Size: 16 bits

Bit	Description
15	Reserved.
14	<b>Sample Base Rate</b> — R/W 0 = 48 kHz 1 = 44.1 kHz
13:11	<b>Sample Base Rate Multiple</b> — R/W 000 = 48 kHz, 44.1 kHz or less 001 = x2 (96 kHz, 88.2 kHz, 32 kHz) 010 = x3 (144 kHz) 011 = x4 (192 kHz, 176.4 kHz) Others = Reserved.
10:8	<b>Sample Base Rate Divisor</b> — R/W. 000 = Divide by 1 (48 kHz, 44.1 kHz) 001 = Divide by 2 (24 kHz, 22.05 kHz) 010 = Divide by 3 (16 kHz, 32 kHz) 011 = Divide by 4 (11.025 kHz) 100 = Divide by 5 (9.6 kHz) 101 = Divide by 6 (8 kHz) 110 = Divide by 7 111 = Divide by 8 (6 kHz)
7	Reserved.
6:4	<b>Bits per Sample (BITS)</b> — R/W. 000 = 8 bits. The data will be packed in memory in 8-bit containers on 16-bit boundaries 001 = 16 bits. The data will be packed in memory in 16-bit containers on 16-bit boundaries 010 = 20 bits. The data will be packed in memory in 32-bit containers on 32-bit boundaries 011 = 24 bits. The data will be packed in memory in 32-bit containers on 32-bit boundaries 100 = 32 bits. The data will be packed in memory in 32-bit containers on 32-bit boundaries Others = Reserved.
3:0	Number of Channels (CHAN) — R/W. Indicates number of channels in each frame of the stream. 0000 = 1 0001 = 2 ..... 1111 = 16



### 18.2.44 SDBDPL—Stream Descriptor Buffer Descriptor List Pointer Lower Base Address Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 98h Attribute: R/W,RO  
 Input Stream[1]: HDBAR + B8h  
 Input Stream[2]: HDBAR + D8h  
 Input Stream[3]: HDBAR + F8h  
 Output Stream[0]: HDBAR + 118h  
 Output Stream[1]: HDBAR + 138h  
 Output Stream[2]: HDBAR + 158h  
 Output Stream[3]: HDBAR + 178h

Default Value: 00000000h Size: 32 bits

Bit	Description
31:7	<b>Buffer Descriptor List Pointer Lower Base Address</b> — R/W. Lower address of the Buffer Descriptor List. This value should only be modified when the RUN bit is 0, or DMA transfer may be corrupted.
6:0	Hardwired to 0 forcing alignment on 128-B boundaries.

### 18.2.45 SBDPU—Stream Descriptor Buffer Descriptor List Pointer Upper Base Address Register (Intel® High Definition Audio Controller—D27:F0)

Memory Address: Input Stream[0]: HDBAR + 9Ch Attribute: R/W  
 Input Stream[1]: HDBAR + BCh  
 Input Stream[2]: HDBAR + DCh  
 Input Stream[3]: HDBAR + FCh  
 Output Stream[0]: HDBAR + 11Ch  
 Output Stream[1]: HDBAR + 13Ch  
 Output Stream[2]: HDBAR + 15Ch  
 Output Stream[3]: HDBAR + 17Ch

Default Value: 00000000h Size: 32 bits

Bit	Description
31:0	<b>Buffer Descriptor List Pointer Upper Base Address</b> — R/W. Upper 32-bit address of the Buffer Descriptor List. This value should only be modified when the RUN bit is 0, or DMA transfer may be corrupted.

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### 19.1.2 DID—Device Identification Register (SMBus—D31:F3)

Address: 02h–03h Attribute: RO  
 Default Value: See bit description Size: 16 bits

Bit	Description
15:0	<b>Device ID</b> — RO. This is a 16-bit value assigned to the PCH's SMBus controller. Refer to the <i>Intel® C600 Series Chipset Specification Update</i> for the value of the Device ID Register.

### 19.1.3 PCICMD—PCI Command Register (SMBus—D31:F3)

Address: 04h–05h Attributes: RO, R/W  
 Default Value: 0000h Size: 16 bits

Bit	Description
15:11	Reserved
10	<b>Interrupt Disable</b> — R/W. 0 = Enable 1 = Disables SMBus to assert its PIRQ# signal.
9	Fast Back to Back Enable (FBE) — RO. Hardwired to 0.
8	<b>SERR# Enable (SERR_EN)</b> — R/W. 0 = Enables SERR# generation. 1 = Disables SERR# generation.
7	Wait Cycle Control (WCC) — RO. Hardwired to 0.
6	<b>Parity Error Response (PER)</b> — R/W. 0 = Disable 1 = Sets Detected Parity Error bit (D31:F3:06, bit 15) when a parity error is detected.
5	VGA Palette Snoop (VPS) — RO. Hardwired to 0.
4	Postable Memory Write Enable (PMWE) — RO. Hardwired to 0.
3	Special Cycle Enable (SCE) — RO. Hardwired to 0.
2	Bus Master Enable (BME) — RO. Hardwired to 0.
1	<b>Memory Space Enable (MSE)</b> — R/W. 0 = Disables memory mapped config space. 1 = Enables memory mapped config space.
0	<b>I/O Space Enable (IOSE)</b> — R/W. 0 = Disable 1 = Enables access to the SMBus I/O space registers as defined by the Base Address Register.











## 19.2 SMBus I/O and Memory Mapped I/O Registers

The SMBus registers (see Table 19-2) can be accessed through I/O BAR or Memory BAR registers in PCI configuration space. The offsets are the same for both I/O and Memory Mapped I/O registers.

**Table 19-2. SMBus I/O and Memory Mapped I/O Register Address Map**

SMB_BASE + Offset	Mnemonic	Register Name	Default	Attribute
00h	HST_STS	Host Status	00h	R/WC, RO
02h	HST_CNT	Host Control	00h	R/W, WO
03h	HST_CMD	Host Command	00h	R/W
04h	XMIT_SLVA	Transmit Slave Address	00h	R/W
05h	HST_D0	Host Data 0	00h	R/W
06h	HST_D1	Host Data 1	00h	R/W
07h	HOST_BLOCK_DB	Host Block Data Byte	00h	R/W
08h	PEC	Packet Error Check	00h	R/W
09h	RCV_SLVA	Receive Slave Address	44h	R/W
0Ah–0Bh	SLV_DATA	Receive Slave Data	0000h	RO
0Ch	AUX_STS	Auxiliary Status	00h	R/WC, RO
0Dh	AUX_CTL	Auxiliary Control	00h	R/W
0Eh	SMLINK_PIN_CTL	SMLink Pin Control (TCO Compatible Mode)	See register description	R/W, RO
0Fh	SMBus_PIN_CTL	SMBus Pin Control	See register description	R/W, RO
10h	SLV_STS	Slave Status	00h	R/WC
11h	SLV_CMD	Slave Command	00h	R/W
14h	NOTIFY_DADDR	Notify Device Address	00h	RO
16h	NOTIFY_DLOW	Notify Data Low Byte	00h	RO
17h	NOTIFY_DHIGH	Notify Data High Byte	00h	RO



### 19.2.1 HST\_STS—Host Status Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 00h                      Attribute: R/WC, RO  
 Default Value: 00h                                      Size: 8-bits

All status bits are set by hardware and cleared by the software writing a one to the particular bit position. Writing a 0 to any bit position has no effect.

Bit	Description
7	<p><b>Byte Done Status (DS)</b> — R/WC.            0 = Software can clear this by writing a 1 to it.            1 = Host controller received a byte (for Block Read commands) or if it has completed transmission of a byte (for Block Write commands) when the 32-byte buffer is not being used. Note that this bit will be set, even on the last byte of the transfer. This bit is not set when transmission is due to the LAN interface heartbeat.            This bit has no meaning for block transfers when the 32-byte buffer is enabled.</p> <p><b>Note:</b> When the last byte of a block message is received, the host controller will set this bit. However, it will not immediately set the INTR bit (bit 1 in this register). When the interrupt handler clears the DS bit, the message is considered complete, and the host controller will then set the INTR bit (and generate another interrupt). Thus, for a block message of n bytes, the PCH will generate n+1 interrupts. The interrupt handler needs to be implemented to handle these cases. When not using the 32 Byte Buffer, hardware will drive the SMBCLK signal low when the DS bit is set until SW clears the bit. This includes the last byte of a transfer. Software must clear the DS bit before it can clear the BUSY bit.</p>
6	<p><b>INUSE_STS</b> — R/W. This bit is used as semaphore among various independent software threads that may need to use the PCH's SMBus logic, and has no other effect on hardware.            0 = After a full PCI reset, a read to this bit returns a 0.            1 = After the first read, subsequent reads will return a 1. A write of a 1 to this bit will reset the next read value to 0. Writing a 0 to this bit has no effect. Software can poll this bit until it reads a 0, and will then own the usage of the host controller.</p>
5	<p><b>SMBALERT_STS</b> — R/WC.            0 = Interrupt or SMI# was not generated by SMBALERT#. Software clears this bit by writing a 1 to it.            1 = The source of the interrupt or SMI# was the SMBALERT# signal. This bit is only cleared by software writing a 1 to the bit position or by RSMRST# going low.            If the signal is programmed as a GPIO, then this bit will never be set.</p>
4	<p><b>FAILED</b> — R/WC.            0 = Software clears this bit by writing a 1 to it.            1 = The source of the interrupt or SMI# was a failed bus transaction. This bit is set in response to the KILL bit being set to terminate the host transaction.</p>
3	<p><b>BUS_ERR</b> — R/WC.            0 = Software clears this bit by writing a 1 to it.            1 = The source of the interrupt of SMI# was a transaction collision.</p>
2	<p><b>DEV_ERR</b> — R/WC.            0 = Software clears this bit by writing a 1 to it. The PCH will then deassert the interrupt or SMI#.            1 = The source of the interrupt or SMI# was due to one of the following:</p> <ul style="list-style-type: none"> <li>• Invalid Command Field,</li> <li>• Unclaimed Cycle (host initiated),</li> <li>• Host Device Time-out Error.</li> </ul>
1	<p><b>INTR</b> — R/WC. This bit can only be set by termination of a command. INTR is not dependent on the INTREN bit (offset SMB_BASE + 02h, bit 0) of the Host controller register (offset 02h). It is only dependent on the termination of the command. If the INTREN bit is not set, then the INTR bit will be set, although the interrupt will not be generated. Software can poll the INTR bit in this non-interrupt case.            0 = Software clears this bit by writing a 1 to it. The PCH then deasserts the interrupt or SMI#.            1 = The source of the interrupt or SMI# was the successful completion of its last command.</p>
0	<p><b>HOST_BUSY</b> — R/WC.            0 = Cleared by the PCH when the current transaction is completed.            1 = Indicates that the PCH is running a command from the host interface. No SMB registers should be accessed while this bit is set, except the BLOCK DATA BYTE Register. The BLOCK DATA BYTE Register can be accessed when this bit is set only when the SMB_CMD bits in the Host Control Register are programmed for Block command or I<sup>2</sup>C Read command. This is necessary in order to check the DONE_STS bit.</p>



## 19.2.2 HST\_CNT—Host Control Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 02h      Attribute: R/W, WO  
 Default Value: 00h      Size: 8-bits

**Note:** A read to this register will clear the byte pointer of the 32-byte buffer.

Bit	Description
7	<p><b>PEC_EN</b> — R/W.</p> <p>0 = SMBus host controller does not perform the transaction with the PEC phase appended.            1 = Causes the host controller to perform the SMBus transaction with the Packet Error Checking phase appended. For writes, the value of the PEC byte is transferred from the PEC Register. For reads, the PEC byte is loaded in to the PEC Register. This bit must be written prior to the write in which the <b>START</b> bit is set.</p>
6	<p><b>START</b> — WO.</p> <p>0 = This bit will always return 0 on reads. The HOST_BUSY bit in the Host Status register (offset 00h) can be used to identify when the PCH has finished the command.            1 = Writing a 1 to this bit initiates the command described in the SMB_CMD field. All registers should be setup prior to writing a 1 to this bit position.</p>
5	<p><b>LAST_BYTE</b> — WO. This bit is used for Block Read commands.</p> <p>1 = Software sets this bit to indicate that the next byte will be the last byte to be received for the block. This causes the PCH to send a NACK (instead of an ACK) after receiving the last byte.</p> <p><b>Note:</b> Once the SECOND_TO_STS bit in TCO2_STS register (D31:F0, TCOBASE+6h, bit 1) is set, the LAST_BYTE bit also gets set. While the SECOND_TO_STS bit is set, the LAST_BYTE bit cannot be cleared. This prevents the PCH from running some of the SMBus commands (Block Read/Write, I<sup>2</sup>C Read, Block I<sup>2</sup>C Write).</p>
4:2	<p><b>SMB_CMD</b> — R/W. The bit encoding below indicates which command the PCH is to perform. If enabled, the PCH will generate an interrupt or SMI# when the command has completed. If the value is for a non-supported or reserved command, the PCH will set the device error (DEV_ERR) status bit (offset SMB_BASE + 00h, bit 2) and generate an interrupt when the START bit is set. The PCH will perform no command, and will not operate until DEV_ERR is cleared.</p> <p>000 = <b>Quick</b>: The slave address and read/write value (bit 0) are stored in the transmit slave address register.</p> <p>001 = <b>Byte</b>: This command uses the transmit slave address and command registers. Bit 0 of the slave address register determines if this is a read or write command.</p> <p>010 = <b>Byte Data</b>: This command uses the transmit slave address, command, and DATA0 registers. Bit 0 of the slave address register determines if this is a read or write command. If it is a read, the DATA0 register will contain the read data.</p> <p>011 = <b>Word Data</b>: This command uses the transmit slave address, command, DATA0 and DATA1 registers. Bit 0 of the slave address register determines if this is a read or write command. If it is a read, after the command completes, the DATA0 and DATA1 registers will contain the read data.</p> <p>100 = <b>Process Call</b>: This command uses the transmit slave address, command, DATA0 and DATA1 registers. Bit 0 of the slave address register determines if this is a read or write command. After the command completes, the DATA0 and DATA1 registers will contain the read data.</p> <p>101 = <b>Block</b>: This command uses the transmit slave address, command, DATA0 registers, and the Block Data Byte register. For block write, the count is stored in the DATA0 register and indicates how many bytes of data will be transferred. For block reads, the count is received and stored in the DATA0 register. Bit 0 of the slave address register selects if this is a read or write command. For writes, data is retrieved from the first n (where n is equal to the specified count) addresses of the SRAM array. For reads, the data is stored in the Block Data Byte register.</p> <p>110 = <b>I<sup>2</sup>C Read</b>: This command uses the transmit slave address, command, DATA0, DATA1 registers, and the Block Data Byte register. The read data is stored in the Block Data Byte register. The PCH continues reading data until the NAK is received.</p> <p>111 = <b>Block Process</b>: This command uses the transmit slave address, command, DATA0 and the Block Data Byte register. For block write, the count is stored in the DATA0 register and indicates how many bytes of data will be transferred. For block read, the count is received and stored in the DATA0 register. Bit 0 of the slave address register always indicate a write command. For writes, data is retrieved from the first m (where m is equal to the specified count) addresses of the SRAM array. For reads, the data is stored in the Block Data Byte register.</p> <p><b>Note:</b> E32B bit in the Auxiliary Control register must be set for this command to work.</p>



Bit	Description
1	<b>KILL</b> — R/W. 0 = Normal SMBus host controller functionality. 1 = Kills the current host transaction taking place, sets the FAILED status bit, and asserts the interrupt (or SMI#). This bit, once set, must be cleared by software to allow the SMBus host controller to function normally.
0	<b>INTREN</b> — R/W. 0 = Disable. 1 = Enable the generation of an interrupt or SMI# upon the completion of the command.

### 19.2.3 HST\_CMD—Host Command Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 03h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:0	This 8-bit field is transmitted by the host controller in the command field of the SMBus protocol during the execution of any command.

### 19.2.4 XMIT\_SLVA—Transmit Slave Address Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 04h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

This register is transmitted by the host controller in the slave address field of the SMBus protocol.

Bit	Description
7:1	<b>Address</b> — R/W. This field provides a 7-bit address of the targeted slave.
0	<b>RW</b> — R/W. Direction of the host transfer. 0 = Write 1 = Read

### 19.2.5 HST\_D0—Host Data 0 Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 05h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:0	<b>Data0/Count</b> — R/W. This field contains the 8-bit data sent in the DATA0 field of the SMBus protocol. For block write commands, this register reflects the number of bytes to transfer. This register should be programmed to a value between 1 and 32 for block counts. A count of 0 or a count above 32 will result in unpredictable behavior. The host controller does not check or log invalid block counts.

### 19.2.6 HST\_D1—Host Data 1 Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 06h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:0	<b>Data1</b> — R/W. This 8-bit register is transmitted in the DATA1 field of the SMBus protocol during the execution of any command.



### 19.2.7 Host\_BLOCK\_DB—Host Block Data Byte Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 07h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:0	<p><b>Block Data (BDTA)</b> — R/W. This is either a register, or a pointer into a 32-byte block array, depending upon whether the E32B bit is set in the Auxiliary Control register. When the E32B bit (offset SMB_BASE + 0Dh, bit 1) is cleared, this is a register containing a byte of data to be sent on a block write or read from on a block read.</p> <p>When the E32B bit is set, reads and writes to this register are used to access the 32-byte block data storage array. An internal index pointer is used to address the array, which is reset to 0 by reading the HCTL register (offset 02h). The index pointer then increments automatically upon each access to this register. The transfer of block data into (read) or out of (write) this storage array during an SMBus transaction always starts at index address 0.</p> <p>When the E2B bit is set, for writes, software will write up to 32-bytes to this register as part of the setup for the command. After the Host controller has sent the Address, Command, and Byte Count fields, it will send the bytes in the SRAM pointed to by this register.</p> <p>When the E2B bit is cleared for writes, software will place a single byte in this register. After the host controller has sent the address, command, and byte count fields, it will send the byte in this register. If there is more data to send, software will write the next series of bytes to the SRAM pointed to by this register and clear the DONE_STS bit. The controller will then send the next byte. During the time between the last byte being transmitted to the next byte being transmitted, the controller will insert wait-states on the interface.</p> <p>When the E2B bit is set for reads, after receiving the byte count into the Data0 register, the first series of data bytes go into the SRAM pointed to by this register. If the byte count has been exhausted or the 32-byte SRAM has been filled, the controller will generate an SMI# or interrupt (depending on configuration) and set the DONE_STS bit. Software will then read the data. During the time between when the last byte is read from the SRAM to when the DONE_STS bit is cleared, the controller will insert wait-states on the interface.</p>

### 19.2.8 PEC—Packet Error Check (PEC) Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 08h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

Bit	Description
7:0	<p><b>PEC_DATA</b> — R/W. This 8-bit register is written with the 8-bit CRC value that is used as the SMBus PEC data prior to a write transaction. For read transactions, the PEC data is loaded from the SMBus into this register and is then read by software. Software must ensure that the INUSE_STS bit is properly maintained to avoid having this field over-written by a write transaction following a read transaction.</p>

### 19.2.9 RCV\_SLVA—Receive Slave Address Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 09h      Attribute: R/W  
 Default Value: 44h      Size: 8 bits  
 Lockable: No      Power Well: Resume

Bit	Description
7	Reserved
6:0	<p><b>SLAVE_ADDR</b> — R/W. This field is the slave address that the PCH decodes for read and write cycles. The default is not 0, so the SMBus Slave Interface can respond even before the processor comes up (or if the processor is dead). This register is cleared by RSMRST#, but not by PLTRST#.</p>



### 19.2.10 SLV\_DATA—Receive Slave Data Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 0Ah–0Bh      Attribute: RO  
 Default Value: 0000h                      Size: 16 bits  
 Lockable: No                                  Power Well: Resume

This register contains the 16-bit data value written by the external SMBus master. The processor can then read the value from this register. This register is reset by RSMRST#, but not PLTRST#.

Bit	Description
15:8	<b>Data Message Byte 1 (DATA_MSG1)</b> — RO. See Section 5.22.9 for a discussion of this field.
7:0	<b>Data Message Byte 0 (DATA_MSG0)</b> — RO. See Section 5.22.9 for a discussion of this field.

### 19.2.11 AUX\_STS—Auxiliary Status Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 0Ch              Attribute: R/WC, RO  
 Default Value: 00h                              Size: 8 bits  
 Lockable: No                                  Power Well: Resume

Bit	Description
7:2	Reserved
1	<b>SMBus TCO Mode (STCO)</b> — RO. This bit reflects the strap setting of TCO compatible mode vs. Advanced TCO mode. 0 = The PCH is in the compatible TCO mode. 1 = The PCH is in the advanced TCO mode.
0	<b>CRC Error (CRCE)</b> — R/WC. 0 = Software clears this bit by writing a 1 to it. 1 = This bit is set if a received message contained a CRC error. When this bit is set, the DERR bit of the host status register will also be set. This bit will be set by the controller if a software abort occurs in the middle of the CRC portion of the cycle or an abort happens after the PCH has received the final data bit transmitted by an external slave.

### 19.2.12 AUX\_CTL—Auxiliary Control Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 0Dh              Attribute: R/W  
 Default Value: 00h                              Size: 8 bits  
 Lockable: No                                  Power Well: Resume

Bit	Description
7:2	Reserved
1	<b>Enable 32-Byte Buffer (E32B)</b> — R/W. 0 = Disable. 1 = Enable. When set, the Host Block Data register is a pointer into a 32-byte buffer, as opposed to a single register. This enables the block commands to transfer or receive up to 32-bytes before the PCH generates an interrupt.
0	<b>Automatically Append CRC (AAC)</b> — R/W. 0 = The PCH will Not automatically append the CRC. 1 = The PCH will automatically append the CRC. This bit must not be changed during SMBus transactions or undetermined behavior will result. It should be programmed only once during the lifetime of the function.



### 19.2.13 SMLINK\_PIN\_CTL—SMLink Pin Control Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 0Eh      Attribute: R/W, RO  
 Default Value: See below      Size: 8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

This register is only applicable in the TCO compatible mode.

Bit	Description
7:3	Reserved
2	<b>SMLINK_CLK_CTL</b> — R/W. 0 = The PCH will drive the SMLOCLK pin low, independent of what the other SMLink logic would otherwise indicate for the SMLOCLK pin. 1 = The SMLOCLK pin is <b>not</b> overdriven low. The other SMLink logic controls the state of the pin. (Default)
1	<b>SMLODATA_CUR_STS</b> — RO. This read-only bit has a default value that is dependent on an external signal level. This pin returns the value on the SMLODATA pin. This allows software to read the current state of the pin. 0 = Low 1 = High
0	<b>SMLOCLK_CUR_STS</b> — RO. This read-only bit has a default value that is dependent on an external signal level. This pin returns the value on the SMLOCLK pin. This allows software to read the current state of the pin. 0 = Low 1 = High

### 19.2.14 SMBus\_PIN\_CTL—SMBus Pin Control Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 0Fh      Attribute: R/W, RO  
 Default Value: See below      Size: 8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

Bit	Description
7:3	Reserved
2	<b>SMBCLK_CTL</b> — R/W. 1 = The SMBCLK pin is <b>not</b> overdriven low. The other SMBus logic controls the state of the pin. 0 = The PCH drives the SMBCLK pin low, independent of what the other SMB logic would otherwise indicate for the SMBCLK pin. (Default)
1	<b>SMBDATA_CUR_STS</b> — RO. This read-only bit has a default value that is dependent on an external signal level. This pin returns the value on the SMBDATA pin. This allows software to read the current state of the pin. 0 = Low 1 = High
0	<b>SMBCLK_CUR_STS</b> — RO. This read-only bit has a default value that is dependent on an external signal level. This pin returns the value on the SMBCLK pin. This allows software to read the current state of the pin. 0 = Low 1 = High



### 19.2.15 SLV\_STS—Slave Status Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 10h      Attribute: R/WC  
 Default Value: 00h      Size: 8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

All bits in this register are implemented in the 64 kHz clock domain. Therefore, software must poll this register until a write takes effect before assuming that a write has completed internally.

Bit	Description
7:1	Reserved
0	<b>HOST_NOTIFY_STS</b> — R/WC. The PCH sets this bit to a 1 when it has completely received a successful Host Notify Command on the SMBus pins. Software reads this bit to determine that the source of the interrupt or SMI# was the reception of the Host Notify Command. Software clears this bit after reading any information needed from the Notify address and data registers by writing a 1 to this bit. Note that the PCH will allow the Notify Address and Data registers to be over-written once this bit has been cleared. When this bit is 1, the PCH will NACK the first byte (host address) of any new "Host Notify" commands on the SMBus pins. Writing a 0 to this bit has no effect.

### 19.2.16 SLV\_CMD—Slave Command Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 11h      Attribute: R/W  
 Default Value: 00h      Size: 8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

Bit	Description
7:2	Reserved
2	<b>SMBALERT_DIS</b> — R/W. 0 = Allows the generation of the interrupt or SMI#. 1 = Software sets this bit to block the generation of the interrupt or SMI# due to the SMBALERT# source. This bit is logically inverted and ANDed with the SMBALERT_STS bit (offset SMB_BASE + 00h, bit 5). The resulting signal is distributed to the SMI# and/or interrupt generation logic. This bit does not effect the wake logic.
1	<b>HOST_NOTIFY_WKEN</b> — R/W. Software sets this bit to 1 to enable the reception of a Host Notify command as a wake event. When enabled this event is "OR'd" in with the other SMBus wake events and is reflected in the SMB_WAK_STS bit of the General Purpose Event 0 Status register. 0 = Disable 1 = Enable
0	<b>HOST_NOTIFY_INTREN</b> — R/W. Software sets this bit to 1 to enable the generation of interrupt or SMI# when HOST_NOTIFY_STS (offset SMB_BASE + 10h, bit 0) is 1. This enable does not affect the setting of the HOST_NOTIFY_STS bit. When the interrupt is generated, either PIRQB# or SMI# is generated, depending on the value of the SMB_SMI_EN bit (D31:F3:40h, bit 1). If the HOST_NOTIFY_STS bit is set when this bit is written to a 1, then the interrupt (or SMI#) will be generated. The interrupt (or SMI#) is logically generated by AND'ing the STS and INTREN bits. 0 = Disable 1 = Enable



### 19.2.17 NOTIFY\_DADDR—Notify Device Address Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 14h                      Attribute:                      RO  
 Default Value:    00h                                      Size:                              8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

Bit	Description
7:1	<b>DEVICE_ADDRESS</b> — RO. This field contains the 7-bit device address received during the Host Notify protocol of the SMBus 2.0 Specification. Software should only consider this field valid when the HOST_NOTIFY_STS bit (D31:F3:SMB_BASE +10, bit 0) is set to 1.
0	Reserved

### 19.2.18 NOTIFY\_DLOW—Notify Data Low Byte Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 16h                      Attribute:                      RO  
 Default Value:    00h                                      Size:                              8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

Bit	Description
7:0	<b>DATA_LOW_BYTE</b> — RO. This field contains the first (low) byte of data received during the Host Notify protocol of the SMBus 2.0 specification. Software should only consider this field valid when the HOST_NOTIFY_STS bit (D31:F3:SMB_BASE +10, bit 0) is set to 1.

### 19.2.19 NOTIFY\_DHIGH—Notify Data High Byte Register (SMBus—D31:F3)

Register Offset: SMB\_BASE + 17h                      Attribute:                      RO  
 Default Value:    00h                                      Size:                              8 bits

**Note:** This register is in the resume well and is reset by RSMRST#.

Bit	Description
7:0	<b>DATA_HIGH_BYTE</b> — RO. This field contains the second (high) byte of data received during the Host Notify protocol of the SMBus 2.0 specification. Software should only consider this field valid when the HOST_NOTIFY_STS bit (D31:F3:SMB_BASE +10, bit 0) is set to 1.

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# 20 PCI Express\* Configuration Registers

## 20.1 PCI Express\* Configuration Registers (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

**Note:** Register address locations that are not shown in Table 20-1, should be treated as Reserved.

**Note:** This section assumes the default PCI Express\* Function Number-to-Root Port mapping is used. Function numbers for a given root port are assignable through the “Root Port Function Number and Hide for PCI Express\* Root Ports” registers (RCBA+0404h).

**Table 20-1. PCI Express\* Configuration Registers Address Map (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7/) (Sheet 1 of 3)**

Offset	Mnemonic	Register Name	Function 0–5 Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	00h	RO
0Ah	SCC	Sub Class Code	04h	RO
0Bh	BCC	Base Class Code	06h	RO
0Ch	CLS	Cache Line Size	00h	R/W
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	81h	RO
18h–1Ah	BNUM	Bus Number	000000h	R/W
1Bh	SLT	Secondary Latency Timer	00h	RO
1Ch–1Dh	IOBL	I/O Base and Limit	0000h	R/W, RO
1Eh–1Fh	SSTS	Secondary Status Register	0000h	R/WC
20h–23h	MBL	Memory Base and Limit	00000000h	R/W
24h–27h	PMBL	Prefetchable Memory Base and Limit	00010001h	R/W, RO
28h–2Bh	PMBU32	Prefetchable Memory Base Upper 32 Bits	00000000h	R/W
2Ch–2Fh	PMLU32	Prefetchable Memory Limit Upper 32 Bits	00000000h	R/W
34h	CAPP	Capabilities List Pointer	40h	RO
3Ch–3Dh	INTR	Interrupt Information	See bit description	R/W, RO
3Eh–3Fh	BCTRL	Bridge Control Register	0000h	R/W
40h–41h	CLIST	Capabilities List	8010	RO
42h–43h	XCAP	PCI Express* Capabilities	0042	R/WO, RO



**Table 20-1. PCI Express\* Configuration Registers Address Map (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7/) (Sheet 2 of 3)**

Offset	Mnemonic	Register Name	Function 0–5 Default	Attribute
44h–47h	DCAP	Device Capabilities	00008000h	RO
48h–49h	DCTL	Device Control	0000h	R/W, RO
4Ah–4Bh	DSTS	Device Status	0010h	R/WC, RO
4Ch–4Fh	LCAP	Link Capabilities	See bit description	R/W, RO, R/WO
50h–51h	LCTL	Link Control	0000h	R/W, WO, RO
52h–53h	LSTS	Link Status	See bit description	RO
54h–57h	SLCAP	Slot Capabilities Register	00040060h	R/WO, RO
58h–59h	SLCTL	Slot Control	0000h	R/W, RO
5Ah–5Bh	SLSTS	Slot Status	0000h	R/WC, RO
5Ch–5Dh	RCTL	Root Control	0000h	R/W
60h–63h	RSTS	Root Status	00000000h	R/WC, RO
64h–67h	DCAP2	Device Capabilities 2 Register	00000016h	RO
68h–69h	DCTL2	Device Control 2 Register	0000h	R/W, RO
70h–71h	LCTL2	Link Control 2 Register	0002h	RO
72h–73h	LSTS2	Link Status 2 Register	0000h	RO
80h–81h	MID	Message Signaled Interrupt Identifiers	9005h	RO
82h–83h	MC	Message Signaled Interrupt Message Control	0000h	R/W, RO
84h–87h	MA	Message Signaled Interrupt Message Address	00000000h	R/W
88h–89h	MD	Message Signaled Interrupt Message Data	0000h	R/W
90h–91h	SVCAP	Subsystem Vendor Capability	A00Dh	RO
94h–97h	SVID	Subsystem Vendor Identification	00000000h	R/WO
A0h–A1h	PMCAP	Power Management Capability	0001h	RO
A2h–A3h	PMC	PCI Power Management Capability	C802h	RO
A4–A7h	PMCS	PCI Power Management Control and Status	00000000h	R/W, RO
D4–D7h	MPC2	Miscellaneous Port Configuration 2	00000000h	R/W, RO
D8–DBh	MPC	Miscellaneous Port Configuration	08110000h	R/W
DC–DFh	SMSCS	SMI/SCI Status Register	00000000h	R/WC
E1h	RPDCGEN	Root Port Dynamic Clock Gating Enable	00h	R/W
E8–EBh	PECR1	PCI Express* Configuration Register 1	00000020h	R/W
EC–EFh	PECR3	PCI Express* Configuration Register 3	00000000h	R/W
11Ch–143h	—	Reserved	—	—
104h–107h	UES	Uncorrectable Error Status	See bit description	R/WC, RO
108h–10Bh	UEM	Uncorrectable Error Mask	00000000h	R/WO, RO
10Ch–10Fh	UEV	Uncorrectable Error Severity	00060011h	RO
110h–113h	CES	Correctable Error Status	00000000h	R/WC
114h–117h	CEM	Correctable Error Mask	00002000h	R/WO





### 20.1.3 PCICMD—PCI Command Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7/F6/F7)

Address Offset: 04h–05h  
Default Value: 0000h

Attribute: R/W, RO  
Size: 16 bits

Bit	Description
15:11	Reserved
10	<p><b>Interrupt Disable</b> — R/W. This disables pin-based INTx# interrupts on enabled Hot-Plug and power management events. This bit has no effect on MSI operation.</p> <p>0 = Internal INTx# messages are generated if there is an interrupt for Hot-Plug or power management and MSI is not enabled.</p> <p>1 = Internal INTx# messages will not be generated.</p> <p>This bit does not affect interrupt forwarding from devices connected to the root port. Assert_INTx and Deassert_INTx messages will still be forwarded to the internal interrupt controllers if this bit is set.</p>
9	Fast Back to Back Enable (FBE) — Reserved per the <i>PCI Express* Base Specification</i> .
8	<p><b>SERR# Enable (SEE)</b> — R/W.</p> <p>0 = Disable.</p> <p>1 = Enables the root port to generate an SERR# message when PSTS.SSE is set.</p>
7	Wait Cycle Control (WCC) — Reserved per the <i>PCI Express* Base Specification</i> .
6	<p><b>Parity Error Response (PER)</b> — R/W.</p> <p>0 = Disable.</p> <p>1 = Indicates that the device is capable of reporting parity errors as a master on the backbone.</p>
5	VGA Palette Snoop (VPS) — Reserved per the <i>PCI Express* Base Specification</i> .
4	Postable Memory Write Enable (PMWE) — Reserved per the <i>PCI Express* Base Specification</i> .
3	Special Cycle Enable (SCE) — Reserved per the <i>PCI Express* Base Specification</i> .
2	<p><b>Bus Master Enable (BME)</b> — R/W.</p> <p>0 = Disable. Memory and I/O requests received at a Root Port must be handled as Unsupported Requests</p> <p>1 = Enable. Allows the root port to forward cycles onto the backbone from a PCI Express* device.</p> <p><b>Note:</b> This bit does not affect forwarding of completions in either upstream or downstream direction nor controls forwarding of requests other than memory or I/O.PCI Express</p>
1	<p><b>Memory Space Enable (MSE)</b> — R/W.</p> <p>0 = Disable. Memory cycles within the range specified by the memory base and limit registers are master aborted on the backbone.</p> <p>1 = Enable. Allows memory cycles within the range specified by the memory base and limit registers can be forwarded to the PCI Express* device.</p>
0	<p><b>I/O Space Enable (IOSE)</b> — R/W. This bit controls access to the I/O space registers.</p> <p>0 = Disable. I/O cycles within the range specified by the I/O base and limit registers are master aborted on the backbone.</p> <p>1 = Enable. Allows I/O cycles within the range specified by the I/O base and limit registers can be forwarded to the PCI Express* device.</p>





















## 20.1.28 LCAP—Link Capabilities Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 4Ch–4Fh                      Attribute: R/WO, RO  
 Default Value: See bit description              Size: 32 bits

Bit	Description																											
31:24	<b>Port Number (PN)</b> — RO. Indicates the port number for the root port. This value is different for each implemented port:																											
	<table border="0"> <thead> <tr> <th>Function</th> <th>Port #</th> <th>Value of PN Field</th> </tr> </thead> <tbody> <tr> <td>D28:F0</td> <td>1</td> <td>01h</td> </tr> <tr> <td>D28:F1</td> <td>2</td> <td>02h</td> </tr> <tr> <td>D28:F2</td> <td>3</td> <td>03h</td> </tr> <tr> <td>D28:F3</td> <td>4</td> <td>04h</td> </tr> <tr> <td>D28:F4</td> <td>5</td> <td>05h</td> </tr> <tr> <td>D28:F5</td> <td>6</td> <td>06h</td> </tr> <tr> <td>D28:F6</td> <td>7</td> <td>07h</td> </tr> <tr> <td>D28:F7</td> <td>8</td> <td>08h</td> </tr> </tbody> </table>	Function	Port #	Value of PN Field	D28:F0	1	01h	D28:F1	2	02h	D28:F2	3	03h	D28:F3	4	04h	D28:F4	5	05h	D28:F5	6	06h	D28:F6	7	07h	D28:F7	8	08h
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D28:F5	6	06h																										
D28:F6	7	07h																										
D28:F7	8	08h																										
23:21	Reserved																											
20	<b>Link Active Reporting Capable (LARC)</b> — RO. Hardwired to 1 to indicate that this port supports the optional capability of reporting the DL_Active state of the Data Link Control and Management State Machine.																											
19:18	Reserved																											
17:15	<b>L1 Exit Latency (EL1)</b> — RO. 000b = Less than 1 us 001b = 1 us to less than 2 us 010b = 2 us to less than 4 us 011b = 4 us to less than 8 us 100b = 8 us to less than 16 us 101b = 16 us to less than 32 us 110b = 32 us to 64 us 111b = more than 64 us																											
	14:12	<b>L0s Exit Latency (ELO)</b> — R/WO. Indicates as exit latency based upon common-clock configuration.																										
		<table border="0"> <thead> <tr> <th>LCLT.CCC</th> <th>Value of ELO (these bits)</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>MPC.UCEL (D28:F0/F1/F2/F3:D8h:bits20:18)</td> </tr> <tr> <td>1</td> <td>MPC.CCEL (D28:F0/F1/F2/F3:D8h:bits17:15)</td> </tr> </tbody> </table>	LCLT.CCC	Value of ELO (these bits)	0	MPC.UCEL (D28:F0/F1/F2/F3:D8h:bits20:18)	1	MPC.CCEL (D28:F0/F1/F2/F3:D8h:bits17:15)																				
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	<b>Note:</b> LCLT.CCC is at D28:F0/F1/F2/F3/F4/F5/F6/F7:50h:bit 6																											



Bit	Description																																								
11:10	<p><b>Active State Link PM Support (APMS)</b> — R/WO. Indicates what level of active state link power management is supported on the root port.</p> <table border="1" data-bbox="649 367 1218 556"> <thead> <tr> <th data-bbox="649 367 730 399">Bits</th> <th data-bbox="730 367 1218 399">Definition</th> </tr> </thead> <tbody> <tr> <td data-bbox="649 409 730 441">00b</td> <td data-bbox="730 409 1218 441">Neither L0s nor L1 are supported</td> </tr> <tr> <td data-bbox="649 451 730 483">01b</td> <td data-bbox="730 451 1218 483">L0s Entry Supported</td> </tr> <tr> <td data-bbox="649 493 730 525">10b</td> <td data-bbox="730 493 1218 525">L1 Entry Supported</td> </tr> <tr> <td data-bbox="649 535 730 567">11b</td> <td data-bbox="730 535 1218 567">Both L0s and L1 Entry Supported</td> </tr> </tbody> </table>	Bits	Definition	00b	Neither L0s nor L1 are supported	01b	L0s Entry Supported	10b	L1 Entry Supported	11b	Both L0s and L1 Entry Supported																														
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9:4	<p><b>Maximum Link Width (MLW)</b> — RO. For the root ports, several values can be taken, based upon the value of the chipset config register field RPC.PC1 (Chipset Config Registers: Offset 0224h:bits1:0) for Ports 1-4 and RPC.PC2 (Chipset Config Registers: Offset 0224h:bits1:0) for Ports 5 and 6.</p> <table border="1" data-bbox="649 661 1218 1081"> <thead> <tr> <th colspan="4" data-bbox="649 661 1218 693">Value of MLW Field</th> </tr> <tr> <th data-bbox="649 703 730 735">Port #</th> <th data-bbox="730 703 893 735">RPC.PC1=00b</th> <th colspan="2" data-bbox="893 703 1218 735">RPC.PC1=11b</th> </tr> </thead> <tbody> <tr> <td data-bbox="649 745 730 777">1</td> <td data-bbox="730 745 893 777">01h</td> <td colspan="2" data-bbox="893 745 1218 777">04h</td> </tr> <tr> <td data-bbox="649 787 730 819">2</td> <td data-bbox="730 787 893 819">01h</td> <td colspan="2" data-bbox="893 787 1218 819">01h</td> </tr> <tr> <td data-bbox="649 829 730 861">3</td> <td data-bbox="730 829 893 861">01h</td> <td colspan="2" data-bbox="893 829 1218 861">01h</td> </tr> <tr> <td data-bbox="649 871 730 903">4</td> <td data-bbox="730 871 893 903">01h</td> <td colspan="2" data-bbox="893 871 1218 903">01h</td> </tr> <tr> <th data-bbox="649 913 730 945">Port #</th> <th data-bbox="730 913 893 945">RPC.PC2=00b</th> <th colspan="2" data-bbox="893 913 1218 945">RPC.PC2=11b</th> </tr> <tr> <td data-bbox="649 955 730 987">5</td> <td data-bbox="730 955 893 987">01h</td> <td colspan="2" data-bbox="893 955 1218 987">04h</td> </tr> <tr> <td data-bbox="649 997 730 1029">6</td> <td data-bbox="730 997 893 1029">01h</td> <td colspan="2" data-bbox="893 997 1218 1029">01h</td> </tr> <tr> <td data-bbox="649 1039 730 1071">7</td> <td data-bbox="730 1039 893 1071">01h</td> <td colspan="2" data-bbox="893 1039 1218 1071">01h</td> </tr> </tbody> </table>	Value of MLW Field				Port #	RPC.PC1=00b	RPC.PC1=11b		1	01h	04h		2	01h	01h		3	01h	01h		4	01h	01h		Port #	RPC.PC2=00b	RPC.PC2=11b		5	01h	04h		6	01h	01h		7	01h	01h	
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5	01h	04h																																							
6	01h	01h																																							
7	01h	01h																																							
3:0	<p><b>Maximum Link Speed (MLS)</b> — RO.</p> <p>0001b = indicates the link speed is 2.5 Gb/s</p> <p>0010b = 5.0 Gb/s and 2.5Gb/s link speeds supported</p> <p>These bits report a value of 0001b if Gen2 disable bit 14 is set in the MPC register, else the value reported is 0010b.</p>																																								















### 20.1.38 LCTL2—Link Control 2 Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 70h–71h                      Attribute: RO  
Default Value: 0002h                      Size: 16 bits

Bit	Description
15:13	Reserved
12	<p><b>Compliance De-Emphasis (CD)</b> — R/W.</p> <p>This bit sets the de-emphasis level in Polling.Compliance state if the entry occurred due to the Enter Compliance bit being 1b.</p> <p>Encodings: 0 = 6 dB 1 = 3.5 dB</p> <p>When the Link is operating at 2.5 GT/s, the setting of this bit has no effect. The default value of this bit is 0b.</p> <p>This bit is intended for debug, compliance testing purposes. System firmware and software are allowed to modify this bit only during debug or compliance testing.</p>
11:5	Reserved
4	<p><b>Enter Compliance (EC)</b> — R/W.</p> <p>Software is permitted to force a Link to enter Compliance mode at the speed indicated in the Target Link Speed field by setting this bit to 1b in both components on a Link and then initiating a hot reset on the Link.</p>
3:0	<p><b>Target Link Speed (TLS)</b>— RO. This field sets an upper limit on Link operational speed by restricting the values advertised by the upstream component in its training sequences.</p> <p>0001b = 2.5 GT/s Target Link Speed 0010b = 5.0 GT/s and 2.5 GT/s Target Link Speeds All other values reserved</p>

### 20.1.39 LSTS2—Link Status 2 Register (PCI Express\*— D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 72h–73h                      Attribute: RO  
Default Value: 0000h                      Size: 16 bits

Bit	Description
15:1	Reserved
0	<p><b>Current De-emphasis Level (CDL)</b> — RO.</p> <p>When the Link is operating at 5 GT/s speed, this bit reflects the level of de-emphasis.</p> <p>Encodings: 0 = 6 dB 1 = 3.5 dB</p> <p>The value in this bit is undefined when the Link is operating at 2.5 GT/s speed.</p>

### 20.1.40 MID—Message Signaled Interrupt Identifiers Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 80h–81h                      Attribute: RO  
Default Value: 9005h                      Size: 16 bits

Bit	Description
15:8	<b>Next Pointer (NEXT)</b> — RO. Indicates the location of the next pointer in the list.
7:0	<b>Capability ID (CID)</b> — RO. Capabilities ID indicates MSI.









Bit	Description
3:2	<b>ASPM Control Override (ASPMO)</b> — R/W. Provides BIOS control of whether root port should enter L0s or L1 or both. 00 = Disabled 01 = L0s Entry Enabled 10 = L1 Entry Enabled 11 = L0s and L1 Entry Enabled.
1	<b>EOI Forwarding Disable (EOIFD)</b> — R/W. When set, EOI messages are not claimed on the backbone by this port and will not be forwarded across the PCIe link. 0 = EOI forwarding is enabled. 1 = EOI forwarding is disabled.
0	<b>L1 Completion Timeout Mode (LICTM)</b> — R/W. 0 = PCI Express* Specification Compliant. Completion timeout is disabled during software initiated L1, and enabled during ASPM initiate L1. 1 = Completion timeout is enabled during L1, regardless of how L1 entry was initiated.

### 20.1.50 MPC—Miscellaneous Port Configuration Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: D8h-DBh                      Attribute: R/W, RO  
 Default Value: 08110000h                    Size: 32 bits

Bit	Description
31	<b>Power Management SCI Enable (PMCE)</b> — R/W. 0 = SCI generation based on a power management event is disabled. 1 = Enables the root port to generate SCI whenever a power management event is detected.
30	<b>Hot-Plug SCI Enable (HPCE)</b> — R/W. 0 = SCI generation based on a Hot-Plug event is disabled. 1 = Enables the root port to generate SCI whenever a hot-plug event is detected.
29	<b>Link Hold Off (LHO)</b> — R/W. 1 = Port will not take any TLP. This is used during loopback mode to fill up the downstream queue.
28	<b>Address Translator Enable (ATE)</b> — R/W. This bit is used to enable address translation using the AT bits in this register during loopback mode. 0 = Disable 1 = Enable
27	<b>Reserved</b>
26	<b>Invalid Receive Bus Number Check Enable (IRBNCE)</b> — R/W. When set, the receive transaction layer will signal an error if the bus number of a Memory request does not fall within the range between SCBN and SBBN. If this check is enabled and the request is a memory write, it is treated as an Unsupported Request. If this check is enabled and the request is a non-posted memory read request, the request is considered a Malformed TLP and a fatal error. Messages, I/O, Config, and Completions are never checked for valid bus number.
25	<b>Invalid Receive Range Check Enable (IRRCE)</b> — R/W. When set, the receive transaction layer will treat the TLP as an Unsupported Request error if the address range of a Memory request does not outside the range between prefetchable and non-prefetchable base and limit. Messages, I/O, Configuration, and Completions are never checked for valid address ranges.
24	<b>BME Receive Check Enable (BMERCE)</b> — R/W. When set, the receive transaction layer will treat the TLP as an Unsupported Request error if a memory read or write request is received and the Bus Master Enable bit is not set. Messages, IO, Config, and Completions are never checked for BME.
23	Reserved
22	<b>Detect Override (FORCEDET)</b> — R/W. 0 = Normal operation. Detected output from AFE is sampled for presence detection. 1 = Override mode. Ignores AFE detect output and link training proceeds as if a device were detected.



Bit	Description																		
21	<p><b>Flow Control During L1 Entry (FCDL1E)</b> — R/W.                      0 = No flow control update DLLPs sent during L1 Ack transmission.                      1 = Flow control update DLLPs sent during L1 Ack transmission as required to meet the 30 μs periodic flow control update.</p>																		
20:18	<p><b>Unique Clock Exit Latency (UCCEL)</b> — R/W. This value represents the L0s Exit Latency for unique-clock configurations (LCTL.CCC = 0) (D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 50h: bit 6). It defaults to 512 ns to less than 1 μs, but may be overridden by BIOS.</p>																		
17:15	<p><b>Common Clock Exit Latency (CCEL)</b> — R/W. This value represents the L0s Exit Latency for common-clock configurations (LCTL.CCC = 1) (D28:F0/F1/F2/F3/F4/F5/F6/F7: Offset 50h: bit 6). It defaults to 128 ns to less than 256 ns, but may be overridden by BIOS.</p>																		
14:8	Reserved																		
7	<p><b>Port I/OxApic Enable (PAE)</b> — R/W.                      0 = Hole is disabled.                      1 = A range is opened through the bridge for the following memory addresses:</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>Port #</th> <th>Address</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>FEC1_0000h – FEC1_7FFFh</td> </tr> <tr> <td>2</td> <td>FEC1_8000h – FEC1_FFFFh</td> </tr> <tr> <td>3</td> <td>FEC2_0000h – FEC2_7FFFh</td> </tr> <tr> <td>4</td> <td>FEC2_8000h – FEC2_FFFFh</td> </tr> <tr> <td>5</td> <td>FEC3_0000h – FEC3_7FFFh</td> </tr> <tr> <td>6</td> <td>FEC3_8000h – FEC3_FFFFh</td> </tr> <tr> <td>7</td> <td>FEC4_0000h – FEC4_7FFFh</td> </tr> <tr> <td>8</td> <td>FEC4_8000h – FEC4_FFFFh</td> </tr> </tbody> </table>	Port #	Address	1	FEC1_0000h – FEC1_7FFFh	2	FEC1_8000h – FEC1_FFFFh	3	FEC2_0000h – FEC2_7FFFh	4	FEC2_8000h – FEC2_FFFFh	5	FEC3_0000h – FEC3_7FFFh	6	FEC3_8000h – FEC3_FFFFh	7	FEC4_0000h – FEC4_7FFFh	8	FEC4_8000h – FEC4_FFFFh
Port #	Address																		
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5	FEC3_0000h – FEC3_7FFFh																		
6	FEC3_8000h – FEC3_FFFFh																		
7	FEC4_0000h – FEC4_7FFFh																		
8	FEC4_8000h – FEC4_FFFFh																		
6:3	Reserved																		
2	<p><b>Bridge Type (BT)</b> — RO. This register can be used to modify the Base Class and Header Type fields from the default P2P bridge to a Host Bridge. Having the root port appear as a Host Bridge is useful in some server configurations.                      0 = The root port bridge type is a P2P Bridge, Header Sub-Class = 04h, and Header Type = Type 1.                      1 = The root port bridge type is a P2P Bridge, Header Sub-Class = 00h, and Header Type = Type 0.</p>																		
1	<p><b>Hot Plug SMI Enable (HPME)</b> — R/W.                      0 = SMI generation based on a Hot-Plug event is disabled.                      1 = Enables the root port to generate SMI whenever a Hot-Plug event is detected.</p>																		
0	<p><b>Power Management SMI Enable (PMME)</b> — R/W.                      0 = SMI generation based on a power management event is disabled.                      1 = Enables the root port to generate SMI whenever a power management event is detected.</p>																		





### 20.1.52 RPDCGEN—Root Port Dynamic Clock Gating Enable (PCI Express-D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: E1h Attribute: R/W  
 Default Value: 00h Size: 8-bits

Bits	Description
7:4	Reserved. RO
3	<b>Shared Resource Dynamic Link Clock Gating Enable (SRDLCGEN)</b> — R/W. 0 = Disables dynamic clock gating of the shared resource link clock domain. 1 = Enables dynamic clock gating on the root port shared resource link clock domain. Only the value from Port 1 is used for ports 1–4. Only the value from Port 5 is used for ports 5-8.
2	<b>Shared Resource Dynamic Backbone Clock Gate Enable (SRDBCEN)</b> — R/W. 0 = Disables dynamic clock gating of the shared resource backbone clock domain. 1 = Enables dynamic clock gating on the root port shared resource backbone clock domain. Only the value from Port 1 is used for ports 1–4. Only the value from Port 5 is used for ports 5-8.
1	<b>Root Port Dynamic Link Clock Gate Enable (RPDLCGEN)</b> — R/W. 0 = Disables dynamic clock gating of the root port link clock domain. 1 = Enables dynamic clock gating on the root port link clock domain.
0	<b>Root Port Dynamic Backbone Clock Gate Enable (RPDBCEN)</b> — R/W. 0 = Disables dynamic clock gating of the root port backbone clock domain. 1 = Enables dynamic clock gating on the root port backbone clock domain.

### 20.1.53 PECR1—PCI Express\* Configuration Register 1 (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: E8h–EBh Attribute: R/W  
 Default Value: 00000020h Size: 32 bits

Bit	Description
31:2	Reserved
1	<b>PECR1 Field 2</b> — R/W. BIOS may set this bit to 1.
0	Reserved.

### 20.1.54 PECR3—PCI Express\* Configuration Register 3 (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: ECh–EFh Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:2	Reserved
1	<b>Subtractive Decode Compatibility Device ID (SDCDID)</b> — R/W. 0 = This function reports the device Device ID value assigned to the PCI Express* Root Ports listed in the <i>Intel® C600 Series Chipset and Intel® X79 Express Chipset Specification Update</i> 1 = This function reports a Device ID of 244Eh. If subtractive decode (SDE) is enabled, having this bit as '0' allows the function to present a Device ID that is recognized by the OS.
0	<b>Subtractive Decode Enable (SDE)</b> — R/W. 0 = Subtractive decode is disabled this function and will only claim transactions positively. 1 = This port will subtractively forward transactions across the PCIe link downstream memory and IO transactions that are not positively claimed any internal device or bridge. Software must ensure that only one PCH device is enabled for Subtractive decode at a time.



## 20.1.55 UES—Uncorrectable Error Status Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 104h–107h Attribute: R/WC, RO  
Default Value: 0000000000x0xxx0x0x0000000x0000bSize: 32 bits

This register maintains its state through a platform reset. It loses its state upon suspend.

Bit	Description
31:21	Reserved
20	<b>Unsupported Request Error Status (URE)</b> — R/WC. Indicates an unsupported request was received.
19	ECRC Error Status (EE) — RO. ECRC is not supported.
18	<b>Malformed TLP Status (MT)</b> — R/WC. Indicates a malformed TLP was received.
17	<b>Receiver Overflow Status (RO)</b> — R/WC. Indicates a receiver overflow occurred.
16	<b>Unexpected Completion Status (UC)</b> — R/WC. Indicates an unexpected completion was received.
15	<b>Completion Abort Status (CA)</b> — R/WC. Indicates a completer abort was received.
14	<b>Completion Timeout Status (CT)</b> — R/WC. Indicates a completion timed out. This bit is set if Completion Timeout is enabled and a completion is not returned within the time specified by the Completion Timeout Value
13	Flow Control Protocol Error Status (FCPE) — RO. Flow Control Protocol Errors not supported.
12	<b>Poisoned TLP Status (PT)</b> — R/WC. Indicates a poisoned TLP was received.
11:5	Reserved
4	<b>Data Link Protocol Error Status (DLPE)</b> — R/WC. Indicates a data link protocol error occurred.
3:1	Reserved
0	<b>Training Error Status (TE)</b> — RO. Training Errors not supported.





### 20.1.57 UEV – Uncorrectable Error Severity (PCI Express\*–D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 10Ch–10Fh                      Attribute: RO, R/W  
 Default Value: 00060011h                      Size: 32 bits

Bit	Description
31:21	Reserved
20	<b>Unsupported Request Error Severity (URE)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
19	<b>ECRC Error Severity (EE)</b> — RO. ECRC is not supported.
18	<b>Malformed TLP Severity (MT)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
17	<b>Receiver Overflow Severity (RO)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
16	Reserved
15	<b>Completion Abort Severity (CA)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
14	Reserved
13	<b>Flow Control Protocol Error Severity (FCPE)</b> — RO. Flow Control Protocol Errors not supported.
12	<b>Poisoned TLP Severity (PT)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
11:5	Reserved
4	<b>Data Link Protocol Error Severity (DLPE)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
3:1	Reserved
0	Training Error Severity (TE) — R/W. TE is not supported.

### 20.1.58 CES – Correctable Error Status Register (PCI Express\*–D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 110h–113h                      Attribute: R/WC  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:14	Reserved
13	<b>Advisory Non-Fatal Error Status (ANFES)</b> — R/WC. 0 = Advisory Non-Fatal Error did not occur. 1 = Advisory Non-Fatal Error did occur.
12	<b>Replay Timer Timeout Status (RTT)</b> — R/WC. Indicates the replay timer timed out.
11:9	Reserved
8	<b>Replay Number Rollover Status (RNR)</b> — R/WC. Indicates the replay number rolled over.
7	<b>Bad DLLP Status (BD)</b> — R/WC. Indicates a bad DLLP was received.





### 20.1.61 RES – Root Error Status Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 130h–133h                      Attribute: R/WC, RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:27	<b>Advanced Error Interrupt Message Number (AEMN)</b> — RO. There is only one error interrupt allocated.
26:7	Reserved
6	<b>Fatal Error Messages Received (FEMR)</b> — RO. Set when one or more Fatal Uncorrectable Error Messages have been received.
5	<b>Non-Fatal Error Messages Received (NFEMR)</b> — RO. Set when one or more Non-Fatal Uncorrectable error messages have been received
4	<b>First Uncorrectable Fatal (FUF)</b> — RO. Set when the first Uncorrectable Error message received is for a fatal error.
3	<b>Multiple ERR_FATAL/NONFATAL Received (MENR)</b> — RO. For the PCH, only one error will be captured.
2	<b>ERR_FATAL/NONFATAL Received (ENR)</b> — R/WC. 0 = No error message received. 1 = Either a fatal or a non-fatal error message is received.
1	<b>Multiple ERR_COR Received (MCR)</b> — RO. For the PCH, only one error will be captured.
0	<b>ERR_COR Received (CR)</b> — R/WC. 0 = No error message received. 1 = A correctable error message is received.

### 20.1.62 PEETM – PCI Express\* Extended Test Mode Register (PCI Express\*—D28:F0/F1/F2/F3/F4/F5/F6/F7)

Address Offset: 324h-327h                      Attribute: RO  
 Default Value: See Description                      Size: 32 bits

Bit	Description
31:5	Reserved
4	<b>Lane Reversal (LR)</b> — RO. This register reads the setting of the PCIELR1 soft strap for port 1 and the PCIELR2 soft strap for port 5. 0 = No Lane reversal (default). 1 = PCI Express* lanes 0–3 (register in port 1) or lanes 4–7 (register in port 5) are reversed. <b>Notes:</b> 1. The port configuration straps must be set such that Port 1 or Port 5 is configured as a x4 port using lanes 0–3, or 4–7 when Lane Reversal is enabled. x2 lane reversal is not supported. 2. This register is only valid on port 1 (for ports 1–4) or port 5 (for ports 5–8).
3	Reserved
2	<b>Scrambler Bypass Mode (BAU)</b> — R/W. 0 = Normal operation. Scrambler and descrambler are used. 1 = Bypasses the data scrambler in the transmit direction and the data de-scrambler in the receive direction. <b>Note:</b> This functionality intended for debug/testing only. <b>Note:</b> If bypassing scrambler with the PCH root port 1 in x4 configuration, each PCH root port must have this bit set.
1:0	Reserved

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# 21 High Precision Event Timer Registers

The timer registers are memory-mapped in a non-indexed scheme. This allows the processor to directly access each register without having to use an index register. The timer register space is 1024 bytes. The registers are generally aligned on 64-bit boundaries to simplify implementation with IA64 processors. There are four possible memory address ranges beginning at 1) FED0\_0000h, 2) FED0\_1000h, 3) FED0\_2000h, 4) FED0\_3000h. The choice of address range will be selected by configuration bits in the High Precision Timer Configuration Register (Chipset Config Registers: Offset 3404h).

Behavioral Rules:

1. Software must not attempt to read or write across register boundaries. For example, a 32-bit access should be to offset x0h, x4h, x8h, or xCh. 32-bit accesses should not be to 01h, 02h, 03h, 05h, 06h, 07h, 09h, 0Ah, 0Bh, 0Dh, 0Eh, or 0Fh. Any accesses to these offsets will result in an unexpected behavior, and may result in a master abort. However, these accesses should not result in system hangs. 64-bit accesses can only be to x0h and must not cross 64-bit boundaries.
2. Software should not write to read-only registers.
3. Software should not expect any particular or consistent value when reading reserved registers or bits.

## 21.1 Memory Mapped Registers

**Table 21-1. Memory-Mapped Registers (Sheet 1 of 2)**

Offset	Mnemonic	Register	Default	Type
000–007h	GCAP_ID	General Capabilities and Identification	0429B17F80 86A201h	RO
008–00Fh	—	Reserved	—	—
010–017h	GEN_CONF	General Configuration	00000000 00000000h	R/W
018–01Fh	—	Reserved	—	—
020–027h	GINTR_STA	General Interrupt Status	00000000 00000000h	R/WC, R/W
028–0EFh	—	Reserved	—	—
0F0–0F7h	MAIN_CNT	Main Counter Value	N/A	R/W
0F8–0FFh	—	Reserved	—	—
100–107h	TIM0_CONF	Timer 0 Configuration and Capabilities	N/A	R/W, RO
108–10Fh	TIM0_COMP	Timer 0 Comparator Value	N/A	R/W
110–11Fh	—	Reserved	—	—
120–127h	TIM1_CONF	Timer 1 Configuration and Capabilities	N/A	R/W, RO
128–12Fh	TIM1_COMP	Timer 1 Comparator Value	N/A	R/W
130–13Fh	—	Reserved	—	—
140–147h	TIM2_CONF	Timer 2 Configuration and Capabilities	N/A	R/W, RO
148–14Fh	TIM2_COMP	Timer 2 Comparator Value	N/A	R/W





## 21.1.2 GEN\_CONF—General Configuration Register

Address Offset: 010h Attribute: R/W  
 Default Value: 00000000 00000000h Size: 64 bits

Bit	Description
63:2	Reserved. These bits return 0 when read.
1	<p><b>Legacy Replacement Rout (LEG_RT_CNF)</b> — R/W. If the ENABLE_CNF bit and the LEG_RT_CNF bit are both set, then the interrupts will be routed as follows:</p> <ul style="list-style-type: none"> <li>• Timer 0 is routed to IRQ0 in 8259 or IRQ2 in the I/O APIC</li> <li>• Timer 1 is routed to IRQ8 in 8259 or IRQ8 in the I/O APIC</li> <li>• Timer 2-n is routed as per the routing in the timer n config registers.</li> <li>• If the Legacy Replacement Rout bit is set, the individual routing bits for Timers 0 and 1 (APIC) will have no impact.</li> <li>• If the Legacy Replacement Rout bit is not set, the individual routing bits for each of the timers are used.</li> <li>• This bit will default to 0. BIOS can set it to 1 to enable the legacy replacement routing, or 0 to disable the legacy replacement routing.</li> </ul>
0	<p><b>Overall Enable (ENABLE_CNF)</b> — R/W. This bit must be set to enable any of the timers to generate interrupts. If this bit is 0, then the main counter will halt (will not increment) and no interrupts will be caused by any of these timers. For level-triggered interrupts, if an interrupt is pending when the ENABLE_CNF bit is changed from 1 to 0, the interrupt status indications (in the various Txx_INT_STS bits) will not be cleared. Software must write to the Txx_INT_STS bits to clear the interrupts.</p> <p><b>Note:</b> This bit will default to 0. BIOS can set it to 1 or 0.</p>

## 21.1.3 GINTR\_STA—General Interrupt Status Register

Address Offset: 020h Attribute: R/W, R/WC  
 Default Value: 00000000 00000000h Size: 64 bits

Bit	Description
63:8	Reserved. These bits will return 0 when read.
7	<b>Timer 7 Interrupt Active (T07_INT_STS)</b> — R/WC. Same functionality as Timer 0.
6	<b>Timer 6 Interrupt Active (T06_INT_STS)</b> — R/WC. Same functionality as Timer 0.
5	<b>Timer 5 Interrupt Active (T05_INT_STS)</b> — R/WC. Same functionality as Timer 0.
4	<b>Timer 4 Interrupt Active (T04_INT_STS)</b> — R/WC. Same functionality as Timer 0.
3	<b>Timer 3 Interrupt Active (T03_INT_STS)</b> — R/WC. Same functionality as Timer 0.
2	<b>Timer 2 Interrupt Active (T02_INT_STS)</b> — R/WC. Same functionality as Timer 0.
1	<b>Timer 1 Interrupt Active (T01_INT_STS)</b> — R/WC. Same functionality as Timer 0.
0	<p><b>Timer 0 Interrupt Active (T00_INT_STS)</b> — R/WC. The functionality of this bit depends on whether the edge or level-triggered mode is used for this timer. (default = 0)</p> <p>If set to level-triggered mode:        This bit will be set by hardware if the corresponding timer interrupt is active. Once the bit is set, it can be cleared by software writing a 1 to the same bit position. Writes of 0 to this bit will have no effect.</p> <p>If set to edge-triggered mode:        This bit should be ignored by software. Software should always write 0 to this bit.</p> <p><b>Note:</b> Defaults to 0. In edge triggered mode, this bit will always read as 0 and writes will have no effect.</p>





Bit	Description
14	<p><b>Timer n Processor Message Interrupt Enable (Tn_PROCMSG_EN_CNF)</b> — R/W / RO. If the Tn_PROCMSG_INT_DEL_CAP bit is set for this timer, then the software can set the Tn_PROCMSG_EN_CNF bit to force the interrupts to be delivered directly as processor messages, rather than using the 8259 or I/O (x) APIC. In this case, the Tn_INT_ROUT_CNF field in this register will be ignored. The Tn_PROCMSG_ROUT register will be used instead.</p> <p>Timer 0, 1, 2, 3 Specific: This bit is a read/write bit.</p> <p>Timer 4, 5, 6, 7 Specific: This bit is always Read Only '1' as interrupt from these timers can only be delivered using direct processor interrupt messages.</p>
13:9	<p><b>Timer n Interrupt Rout (Tn_INT_ROUT_CNF)</b> — R/W / RO. This 5-bit field indicates the routing for the interrupt to the 8259 or I/O (x) APIC. Software writes to this field to select which interrupt in the 8259 or I/O (x) will be used for this timer's interrupt. If the value is not supported by this particular timer, then the value read back will not match what is written. The software must only write valid values.</p> <p>Timer 4, 5, 6, 7: This field is Read-only and reads will return 0.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>If the interrupt is handled using the 8259, only interrupts 0-15 are applicable and valid. Software must not program any value other than 0-15 in this field.</li> <li>If the Legacy Replacement Rout bit is set, then Timers 0 and 1 will have a different routing, and this bit field has no effect for those two timers.</li> <li>Timer 0, 1: Software is responsible to make sure it programs a valid value (20, 21, 22, or 23) for this field. The PCH logic does not check the validity of the value written.</li> <li>Timer 2: Software is responsible to make sure it programs a valid value (11, 20, 21, 22, or 23) for this field. The PCH logic does not check the validity of the value written.</li> <li>Timer 3: Software is responsible to make sure it programs a valid value (12, 20, 21, 22, or 23) for this field. The PCH logic does not check the validity of the value written.</li> <li>Timers 4, 5, 6, 7: This field is always Read Only 0 as interrupts from these timers can only be delivered using direct processor interrupt messages.</li> </ol>
8	<p><b>Timer n 32-bit Mode (TIMERn_32MODE_CNF)</b> — R/W or RO. Software can set this bit to force a 64-bit timer to behave as a 32-bit timer.</p> <p>Timer 0: Bit is read/write (default to 0). 0 = 64 bit; 1 = 32 bit</p> <p>Timers 1, 2, 3, 4, 5, 6, 7: Hardwired to 0. Writes have no effect (since these seven timers are 32-bits).</p> <p><b>Note:</b> When this bit is set to '1', the hardware counter will do a 32-bit operation on comparator match and rollovers, thus the upper 32-bit of the Timer 0 Comparator Value register is ignored. The upper 32-bit of the main counter is not involved in any rollover from lower 32-bit of the main counter and becomes all zeros.</p>
7	Reserved. This bit returns 0 when read.
6	<p><b>Timer n Value Set (TIMERn_VAL_SET_CNF)</b> — R/W. Software uses this bit only for Timer 0 if it has been set to periodic mode. By writing this bit to a 1, the software is then allowed to directly set the timer's accumulator. Software does <b>not</b> have to write this bit back to 1 (it automatically clears).</p> <p>Software should not write a 1 to this bit position if the timer is set to non-periodic mode.</p> <p><b>Note:</b> This bit will return 0 when read. Writes will only have an effect for Timer 0 if it is set to periodic mode. Writes will have no effect for Timers 1, 2, 3, 4, 5, 6, 7.</p>
5	<p><b>Timer n Size (TIMERn_SIZE_CAP)</b> — RO. This read only field indicates the size of the timer.</p> <p>Timer 0: Value is 1 (64-bits).</p> <p>Timers 1, 2, 3, 4, 5, 6, 7.: Value is 0 (32-bits).</p>
4	<p><b>Periodic Interrupt Capable (TIMERn_PER_INT_CAP)</b> — RO. If this bit is 1, the hardware supports a periodic mode for this timer's interrupt.</p> <p>Timer 0: Hardwired to 1 (supports the periodic interrupt).</p> <p>Timers 1, 2, 3, 4, 5, 6, 7.: Hardwired to 0 (does not support periodic interrupt).</p>
3	<p><b>Timer n Type (TIMERn_TYPE_CNF)</b> — R/W or RO.</p> <p>Timer 0: Bit is read/write. 0 = Disable timer to generate periodic interrupt; 1 = Enable timer to generate a periodic interrupt.</p> <p>Timers 1, 2, 3, 4, 5, 6, 7.: Hardwired to 0. Writes have no affect.</p>



Bit	Description
2	<b>Timer n Interrupt Enable (TIMERn_INT_ENB_CNF)</b> — R/W. This bit must be set to enable timer n to cause an interrupt when it times out. 0 = Disable (Default). The timer can still count and generate appropriate status bits, but will not cause an interrupt. 1 = Enable.
1	<b>Timer Interrupt Type (TIMERn_INT_TYPE_CNF)</b> — R/W. 0 = The timer interrupt is edge triggered. This means that an edge-type interrupt is generated. If another interrupt occurs, another edge will be generated. 1 = The timer interrupt is level triggered. This means that a level-triggered interrupt is generated. The interrupt will be held active until it is cleared by writing to the bit in the General Interrupt Status Register. If another interrupt occurs before the interrupt is cleared, the interrupt will remain active. Timer 4, 5, 6, 7: This bit is Read-Only, and will return 0 when read
0	Reserved. These bits will return 0 when read.

**Note:** Reads or writes to unimplemented timers should not be attempted. Read from any unimplemented registers will return an undetermined value.

### 21.1.6 TIMn\_COMP—Timer n Comparator Value Register

Address Offset: Timer 0: 108h–10Fh,  
Timer 1: 128h–12Fh,  
Timer 2: 148h–14Fh,  
Timer 3: 168h–16Fh,  
Timer 4: 188h – 18Fh,  
Timer 5: 1A8h – 1AFh,  
Timer 6: 1C8h – 1CFh,  
Timer 7: 1E8h – 1EFh

Attribute: R/W  
Default Value: N/A  
Size: 64 bit

Bit	Description
63:0	<b>Timer Compare Value</b> — R/W. Reads to this register return the current value of the comparator if Timers n are configured to non-periodic mode: Writes to this register load the value against which the main counter should be compared for this timer. <ul style="list-style-type: none"> <li>When the main counter equals the value last written to this register, the corresponding interrupt can be generated (if so enabled).</li> <li>The value in this register does not change based on the interrupt being generated.</li> </ul> Timer 0 is configured to periodic mode: <ul style="list-style-type: none"> <li>When the main counter equals the value last written to this register, the corresponding interrupt can be generated (if so enabled).</li> <li>After the main counter equals the value in this register, the value in this register is increased by the value last written to the register.</li> </ul> For example, if the value written to the register is 00000123h, then <ol style="list-style-type: none"> <li>An interrupt will be generated when the main counter reaches 00000123h.</li> <li>The value in this register will then be adjusted by the hardware to 00000246h.</li> <li>Another interrupt will be generated when the main counter reaches 00000246h</li> <li>The value in this register will then be adjusted by the hardware to 00000369h</li> </ol> <ul style="list-style-type: none"> <li>As each periodic interrupt occurs, the value in this register will increment. When the incremented value is greater than the maximum value possible for this register (FFFFFFFFh for a 32-bit timer or FFFFFFFFFFFFFFFFh for a 64-bit timer), the value will wrap around through 0. For example, if the current value in a 32-bit timer is FFFF0000h and the last value written to this register is 20000h, then after the next interrupt the value will change to 00010000h</li> </ul> Default value for each timer is all 1s for the bits that are implemented. For example, a 32-bit timer has a default value of 00000000FFFFFFFFh. A 64-bit timer has a default value of FFFFFFFFFFFFFFFFh.



### 21.1.7 TIMERN\_PROCMSG\_ROUT— Timer n Processor Message Interrupt Rout Register

Address Offset: Timer 0: 110–117h,      Attribute:      R/W  
 Timer 1: 130–137h,  
 Timer 2: 150–157h,  
 Timer 3: 170–177h,  
 Timer 4: 190–197h,  
 Timer 5: 1B0–1B7h,  
 Timer 6: 1D0–1D7h,  
 Timer 7: 1F0–1F7h,  
 Default Value: N/A      Size:      64 bit

**Note:** The letter n can be 0, 1, 2, 3, 4, 5, 6, or 7 referring to Timer 0, 1, 2, 3, 4, 5, 6, or 7.

Software can access the various bytes in this register using 32-bit or 64-bit accesses. 32-bit accesses can be done to offset 1x0h or 1x4h. 64-bit accesses can be done to 1x0h. 32-bit accesses must not be done to offsets 1x1h, 1x2h, 1x3h, 1x5h, 1x6h, or 1x7h.

Bit	Description
63:32	<b>Tn_PROCMSG_INT_ADDR — R/W.</b> Software sets this 32-bit field to indicate the location that the direct processor interrupt message should be written.
31:0	<b>Tn_PROCMSG_INT_VAL — R/W.</b> Software sets this 32-bit field to indicate that value that is written during the direct processor interrupt message.

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## 22 Serial Peripheral Interface (SPI)

The Serial Peripheral Interface resides in memory mapped space. This function contains registers that allow for the setup and programming of devices that reside on the SPI interface.

**Note:** All registers in this function (including memory-mapped registers) must be addressable in byte, word, and DWord quantities. The software must always make register accesses on natural boundaries (that is, DWord accesses must be on DWord boundaries; word accesses on word boundaries, and so forth) In addition, the memory-mapped register space must not be accessed with the LOCK semantic exclusive-access mechanism. If software attempts exclusive-access mechanisms to the SPI memory-mapped space, the results are undefined.

### 22.1 Serial Peripheral Interface Memory Mapped Configuration Registers

The SPI Host Interface registers are memory-mapped in the RCRB (Root Complex Register Block) Chipset Register Space with a base address (SPIBAR) of 3800h and are located within the range of 3800h to 39FFh. The address for RCRB can be found in RCBA Register see [Section 13.1.40](#). The individual registers are then accessible at SPIBAR + Offset as indicated in the following table.

These memory mapped registers must be accessed in byte, word, or DWord quantities.

**Table 22-1. Serial Peripheral Interface (SPI) Register Address Map (SPI Memory Mapped Configuration Registers) (Sheet 1 of 2)**

SPIBAR + Offset	Mnemonic	Register Name	Default
00h–03h	BFPR	BIOS Flash Primary Region	00000000h
04h–05h	HSFS	Hardware Sequencing Flash Status	0000h
06h–07h	HSFC	Hardware Sequencing Flash Control	0000h
08h–0Bh	FADDR	Flash Address	00000000h
10h–13h	FDATA0	Flash Data 0	00000000h
14h–4Fh	FDATAN	Flash Data N	00000000h
50h–53h	FRAP	Flash Region Access Permissions	00000202h
54h–57h	FREG0	Flash Region 0	00000000h
58h–5Bh	FREG1	Flash Region 1	00000000h
5Ch–5F	FREG2	Flash Region 2	00000000h
60h–63h	FREG3	Flash Region 3	00000000h
64h–67h	FREG4	Flash Region 4	00000000h
68h–73h	Reserved	Reserved for Future Flash Regions	00000000h
74h–77h	PR0	Protected Range 0	00000000h
78h–7Bh	PR1	Protected Range 1	00000000h
7Ch–7Fh	PR2	Protected Range 2	00000000h
80–83h	PR3	Protected Range 3	00000000h
84h–87h	PR4	Protected Range 4	00000000h



**Table 22-1. Serial Peripheral Interface (SPI) Register Address Map (SPI Memory Mapped Configuration Registers) (Sheet 2 of 2)**

SPIBAR + Offset	Mnemonic	Register Name	Default
90h	SSFS	Software Sequencing Flash Status	00h
91h–93h	SSFC	Software Sequencing Flash Control	F80000h
94h–95h	PREOP	Prefix Opcode Configuration	0000h
96h–97h	OPTYPE	Opcode Type Configuration	0000h
98h–9Fh	OPMENU	Opcode Menu Configuration	00000000 00000000h
A0h–A3h	BBAR	BIOS Base Address Configuration	00000000h
B0h–B3h	FDOC	Flash Descriptor Observability Control	00000000h
B4h–B7h	FDOD	Flash Descriptor Observability Data	00000000h
C0h–C3h	AFC	Additional Flash Control	00000000h
C4–C7h	LVSCC	Lower Vendor Specific Component Capabilities	00000000h
C8–CBh	UVSCC	Upper Vendor Specific Component Capabilities	00000000h
D0–D3h	FPB	Flash Partition Boundary	00000000h
F0–F3H	SRDL	Soft Reset Data Lock	00000000h
F4–F7H	SRDC	Soft Reset Data Control	00000000h
F8–FBH	SRD	Soft Reset Data	00000000h

### 22.1.1 BFPR –BIOS Flash Primary Region Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 00h                      Attribute:                      RO  
 Default Value: 00000000h                      Size:                      32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:29	Reserved
28:16	<b>BIOS Flash Primary Region Limit (PRL)</b> — RO. This specifies address bits 24:12 for the Primary Region Limit. The value in this register loaded from the contents in the Flash Descriptor.FLREG1.Region Limit
15:13	Reserved
12:0	<b>BIOS Flash Primary Region Base (PRB)</b> — RO. This specifies address bits 24:12 for the Primary Region Base The value in this register is loaded from the contents in the Flash Descriptor.FLREG1.Region Base



## 22.1.2 HSFS—Hardware Sequencing Flash Status Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 04h Attribute: RO, R/WC, R/W  
 Default Value: 0000h Size: 16 bits

Bit	Description
15	<b>Flash Configuration Lock-Down (FLOCKDN)</b> — R/WL. When set to 1, those Flash Program Registers that are locked down by this FLOCKDN bit cannot be written. Once set to 1, this bit can only be cleared by a hardware reset due to a global reset or host partition reset in an Intel ME-enabled system.
14	<b>Flash Descriptor Valid (FDV)</b> — RO. This bit is set to a 1 if the Flash Controller read the correct Flash Descriptor Signature. If the Flash Descriptor Valid bit is not 1, software cannot use the Hardware Sequencing registers, but must use the software sequencing registers. Any attempt to use the Hardware Sequencing registers will result in the FCERR bit being set.
13	<b>Flash Descriptor Override Pin-Strap Status (FDOPSS)</b> — RO: This bit indicates the condition of the Flash Descriptor Security Override / Intel ME Debug Mode Pin-Strap. 0 = The Flash Descriptor Security Override / Intel ME Debug Mode strap is set using external pull-up on HDA_SDO 1 = No override
12:6	Reserved
5	<b>SPI Cycle In Progress (SCIP)</b> — RO. Hardware sets this bit when software sets the Flash Cycle Go (FGO) bit in the Hardware Sequencing Flash Control register. This bit remains set until the cycle completes on the SPI interface. Hardware automatically sets and clears this bit so that software can determine when read data is valid and/or when it is safe to begin programming the next command. Software must only program the next command when this bit is 0. <b>Note:</b> This field is only applicable when in Descriptor mode and Hardware sequencing is being used.
4:3	<b>Block/Sector Erase Size (BERASE)</b> — RO. This field identifies the erasable sector size for all Flash components. Valid Bit Settings: 00 = 256 Byte 01 = 4 K Byte 10 = 8 K Byte 11 = 64 K Byte If the FLA is less than FPBA then this field reflects the value in the LVSCC.LBES register. If the FLA is greater or equal to FPBA then this field reflects the value in the UVSCC.UBES register. <b>Note:</b> This field is only applicable when in Descriptor mode and Hardware sequencing is being used.
2	<b>Access Error Log (AEL)</b> — R/WC. Hardware sets this bit to a 1 when an attempt was made to access the BIOS region using the direct access method or an access to the BIOS Program Registers that violated the security restrictions. This bit is simply a log of an access security violation. This bit is cleared by software writing a 1. <b>Note:</b> This field is only applicable when in Descriptor mode and Hardware sequencing is being used.
1	<b>Flash Cycle Error (FCERR)</b> — R/WC. Hardware sets this bit to 1 when a program register access is blocked to the FLASH due to one of the protection policies or when any of the programmed cycle registers is written while a programmed access is already in progress. This bit remains asserted until cleared by software writing a 1 or until hardware reset occurs due to a global reset or host partition reset in an Intel ME enabled system. Software must clear this bit before setting the FLASH Cycle GO bit in this register. <b>Note:</b> This field is only applicable when in Descriptor mode and Hardware sequencing is being used.
0	<b>Flash Cycle Done (FDONE)</b> — R/WC. The PCH sets this bit to 1 when the SPI Cycle completes after software previously set the FGO bit. This bit remains asserted until cleared by software writing a 1 or hardware reset due to a global reset or host partition reset in an Intel ME enabled system. When this bit is set and the SPI SMI# Enable bit is set, an internal signal is asserted to the SMI# generation block. Software must make sure this bit is cleared prior to enabling the SPI SMI# assertion for a new programmed access. <b>Note:</b> This field is only applicable when in Descriptor mode and Hardware sequencing is being used.



### 22.1.3 HSFC—Hardware Sequencing Flash Control Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 06h Attribute: R/W, R/WS  
 Default Value: 0000h Size: 16 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
15	<b>Flash SPI SMI# Enable (FSMIE)</b> — R/W. When set to 1, the SPI asserts an SMI# request whenever the Flash Cycle Done bit is 1.
14	Reserved
13:8	<b>Flash Data Byte Count (FDBC)</b> — R/W. This field specifies the number of bytes to shift in or out during the data portion of the SPI cycle. The contents of this register are 0s based with 0b representing 1 byte and 111111b representing 64 bytes. The number of bytes transferred is the value of this field plus 1. This field is ignored for the Block Erase command.
7:3	Reserved
2:1	<b>FLASH Cycle (FCYCLE)</b> — R/W. This field defines the Flash SPI cycle type generated to the FLASH when the FGO bit is set as defined below: 00 = Read (1 up to 64 bytes by setting FDBC) 01 = Reserved 10 = Write (1 up to 64 bytes by setting FDBC) 11 = Block Erase
0	<b>Flash Cycle Go (FGO)</b> — R/W/S. A write to this register with a 1 in this bit initiates a request to the Flash SPI Arbiter to start a cycle. This register is cleared by hardware when the cycle is granted by the SPI arbiter to run the cycle on the SPI bus. When the cycle is complete, the FDONE bit is set. Software is forbidden to write to any register in the HSFLCTL register between the FGO bit getting set and the FDONE bit being cleared. Any attempt to violate this rule will be ignored by hardware. Hardware allows other bits in this register to be programmed for the same transaction when writing this bit to 1. This saves an additional memory write. This bit always returns 0 on reads.

### 22.1.4 FADDR—Flash Address Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 08h Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:25	Reserved
24:0	<b>Flash Linear Address (FLA)</b> — R/W. The FLA is the starting byte linear address of a SPI Read or Write cycle or an address within a Block for the Block Erase command. The Flash Linear Address must fall within a region for which BIOS has access permissions. Hardware must convert the FLA into a Flash Physical Address (FPA) before running this cycle on the SPI bus.



### 22.1.5 FDATA0—Flash Data 0 Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 10h Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:0	<p><b>Flash Data 0 (FD0)</b> — R/W. This field is shifted out as the SPI Data on the Master-Out Slave-In Data pin during the data portion of the SPI cycle.</p> <p>This register also shifts in the data from the Master-In Slave-Out pin into this register during the data portion of the SPI cycle.</p> <p>The data is always shifted starting with the least significant byte, msb to lsb, followed by the next least significant byte, msb to lsb, etc. Specifically, the shift order on SPI in terms of bits within this register is: 7-6-5-4-3-2-1-0-15-14-13-...-8-23-22-...-16-31...24 Bit 24 is the last bit shifted out/in. There are no alignment assumptions; byte 0 always represents the value specified by the cycle address.</p> <p>Note that the data in this register may be modified by the hardware during any programmed SPI transaction. Direct Memory Reads do not modify the contents of this register.</p>

### 22.1.6 FDATAN—Flash Data [N] Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 14h Attribute: R/W  
 SPIBAR + 18h  
 SPIBAR + 1Ch  
 SPIBAR + 20h  
 SPIBAR + 24h  
 SPIBAR + 28h  
 SPIBAR + 2Ch  
 SPIBAR + 30h  
 SPIBAR + 34h  
 SPIBAR + 38h  
 SPIBAR + 3Ch  
 SPIBAR + 40h  
 SPIBAR + 44h  
 SPIBAR + 48h  
 SPIBAR + 4Ch  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:0	<p><b>Flash Data N (FD[N])</b> — R/W. Similar definition as Flash Data 0. However, this register does not begin shifting until FD[N-1] has completely shifted in/out.— R/W.</p>



## 22.1.7 FRAP—Flash Regions Access Permissions Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 50h Attribute: RO, R/W  
 Default Value: 00000202h Size: 32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:24	<b>BIOS Master Write Access Grant (BMWAG)</b> — R/W. Each bit [31:29] corresponds to Master[7:0]. BIOS can grant one or more masters write access to the BIOS region 1 overriding the permissions in the Flash Descriptor. Master[1] is Host processor/BIOS, Master[2] is Intel ME, Master[3] is Host processor/GbE. Master[0] and Master[7:4] are reserved. The contents of this register are locked by the FLOCKDN bit.
23:16	<b>BIOS Master Read Access Grant (BMRAG)</b> — R/W. Each bit [28:16] corresponds to Master[7:0]. BIOS can grant one or more masters read access to the BIOS region 1 overriding the read permissions in the Flash Descriptor. Master[1] is Host processor/BIOS, Master[2] is Intel ME, Master[3] is Host processor/GbE. Master[0] and Master[7:4] are reserved. The contents of this register are locked by the FLOCKDN bit
15:8	<b>BIOS Region Write Access (BRWA)</b> — RO. Each bit [15:8] corresponds to Regions [7:0]. If the bit is set, this master can erase and write that particular region through register accesses. The contents of this register are that of the Flash Descriptor. Flash Master 1 Master Region Write Access OR a particular master has granted BIOS write permissions in their Master Write Access Grant register or the Flash Descriptor Security Override strap is set.
7:0	<b>BIOS Region Read Access (BRR)</b> — RO. Each bit [7:0] corresponds to Regions [7:0]. If the bit is set, this master can read that particular region through register accesses. The contents of this register are that of the Flash Descriptor. Flash Master 1 Master Region Write Access OR a particular master has granted BIOS read permissions in their Master Read Access Grant register or the Flash Descriptor Security Override strap is set.

## 22.1.8 FREG0—Flash Region 0 (Flash Descriptor) Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 54h Attribute: RO  
 Default Value: 00000000h Size: 32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 0 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG0.Region Limit
15:13	Reserved
12:0	<b>Region Base (RB) / Flash Descriptor Base Address Region (FDBAR)</b> — RO. This specifies address bits 24:12 for the Region 0 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG0.Region Base.



### 22.1.9 FREG1—Flash Region 1 (BIOS Descriptor) Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 58h Attribute: RO  
 Default Value: 00000000h Size: 32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 1 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG1.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 1 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG1.Region Base.

### 22.1.10 FREG2—Flash Region 2 (Intel® ME) Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 5Ch Attribute: RO  
 Default Value: 00000000h Size: 32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 2 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG2.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 2 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG2.Region Base.

### 22.1.11 FREG3—Flash Region 3 (GbE) Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 60h Attribute: RO  
 Default Value: 00000000h Size: 32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 3 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG3.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 3 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG3.Region Base.



### 22.1.12 FREG4—Flash Region 4 (Platform Data) Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 64h                      Attribute:                      RO  
 Default Value: 00000000h                      Size:                      32 bits

**Note:** This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 4 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG4.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 4 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG4.Region Base.

### 22.1.13 PR0—Protected Range 0 Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 74h                      Attribute:                      R/W  
 Default Value: 00000000h                      Size:                      32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.



### 22.1.14 PR1—Protected Range 1 Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 78h                      Attribute:              R/W  
 Default Value:    00000000h                      Size:                      32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.

### 22.1.15 PR2—Protected Range 2 Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 7Ch                      Attribute:              R/W  
 Default Value:    00000000h                      Size:                      32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.



### 22.1.16 PR3—Protected Range 3 Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 80h                      Attribute:                      R/W  
Default Value: 00000000h                      Size:                      32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.

### 22.1.17 PR4—Protected Range 4 Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 84h                      Attribute:                      R/W  
Default Value: 00000000h                      Size:                      32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.



## 22.1.18 SSFS—Software Sequencing Flash Status Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 90h  
 Default Value: 00h

Attribute: RO, R/WC  
 Size: 8 bits

**Note:** The Software Sequencing control and status registers are reserved if the hardware sequencing control and status registers are used.

Bit	Description
7	<b>Fast Read Supported</b> — RO. This bit reflects the value of the Fast Read Support bit in the flash Descriptor Component Section.
6	<b>Dual Output Fast Read Supported</b> — RO. This bit reflects the value of the Dual Output Fast Read support bit in the Flash Descriptor Component Section
5	Reserved
4	<b>Access Error Log (AEL)</b> — RO. This bit reflects the value of the Hardware Sequencing Status AEL register.
3	<b>Flash Cycle Error (FCERR)</b> — R/WC. Hardware sets this bit to 1 when a programmed access is blocked from running on the SPI interface due to one of the protection policies or when any of the programmed cycle registers is written while a programmed access is already in progress. This bit remains asserted until cleared by software writing a 1 or hardware reset due to a global reset or host partition reset in an Intel® ME enabled system.
2	<b>Cycle Done Status</b> — R/WC. The PCH sets this bit to 1 when the SPI Cycle completes (that is, SCIP bit is 0) after software sets the GO bit. This bit remains asserted until cleared by software writing a 1 or hardware reset due to a global reset or host partition reset in an Intel® ME enabled system. When this bit is set and the SPI SMI# Enable bit is set, an internal signal is asserted to the SMI# generation block. Software must make sure this bit is cleared prior to enabling the SPI SMI# assertion for a new programmed access.
1	Reserved
0	<b>SPI Cycle In Progress (SCIP)</b> — RO. Hardware sets this bit when software sets the SPI Cycle Go bit in the Command register. This bit remains set until the cycle completes on the SPI interface. Hardware automatically sets and clears this bit so that software can determine when read data is valid and/or when it is safe to begin programming the next command. Software must only program the next command when this bit is 0.



## 22.1.19 SSFC—Software Sequencing Flash Control Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 91h                      Attribute:                      R/W  
 Default Value:    F80000h                              Size:                              24 bits

Bit	Description
23:19	Reserved - BIOS must set this field to '11111'b
18:16	<p><b>SPI Cycle Frequency (SCF)</b> — R/W. This register sets frequency to use for all SPI software sequencing cycles (write, erase, fast read, read status, etc.) except for the read cycle which always run at 20 MHz.</p> <p>000 = 20 MHz            001 = 33 MHz            100 = 50 MHz            All other values reserved.            This register is locked when the SPI Configuration Lock-Down bit is set.</p>
15	<p><b>SPI SMI# Enable (SME)</b> — R/W. When set to 1, the SPI asserts an SMI# request whenever the Cycle Done Status bit is 1.</p>
14	<p><b>Data Cycle (DS)</b> — R/W. When set to 1, there is data that corresponds to this transaction. When 0, no data is delivered for this cycle, and the DBC and data fields themselves are don't cares.</p>
13:8	<p><b>Data Byte Count (DBC)</b> — R/W. This field specifies the number of bytes to shift in or out during the data portion of the SPI cycle. The valid settings (in decimal) are any value from 0 to 63. The number of bytes transferred is the value of this field plus 1.            Note that when this field is 00_0000b, then there is 1 byte to transfer and that 11_1111b means there are 64 bytes to transfer.</p>
7	Reserved
6:4	<p><b>Cycle Opcode Pointer (COP)</b> — R/W. This field selects one of the programmed opcodes in the Opcode Menu to be used as the SPI Command/Opcode. In the case of an Atomic Cycle Sequence, this determines the second command. — R/W.</p>
3	<p><b>Sequence Prefix Opcode Pointer (SPOP)</b> — R/W. This field selects one of the two programmed prefix opcodes for use when performing an Atomic Cycle Sequence. A value of 0 points to the opcode in the least significant byte of the Prefix Opcodes register. By making this programmable, the PCH supports flash devices that have different opcodes for enabling writes to the data space vs. status register.</p>
2	<p><b>Atomic Cycle Sequence (ACS)</b> — R/W. When set to 1 along with the SCGO assertion, the PCH will execute a sequence of commands on the SPI interface without allowing the LAN component to arbitrate and interleave cycles. The sequence is composed of:</p> <ul style="list-style-type: none"> <li>• Atomic Sequence Prefix Command (8-bit opcode only)</li> <li>• Primary Command specified below by software (can include address and data)</li> <li>• Polling the Flash Status Register (opcode 05h) until bit 0 becomes 0b.</li> </ul> <p>The SPI Cycle in Progress bit remains set and the Cycle Done Status bit remains unset until the Busy bit in the Flash Status Register returns 0.</p>
1	<p><b>SPI Cycle Go (SCGO)</b> — R/WS. This bit always returns 0 on reads. However, a write to this register with a 1 in this bit starts the SPI cycle defined by the other bits of this register. The "SPI Cycle in Progress" (SCIP) bit gets set by this action. Hardware must ignore writes to this bit while the Cycle In Progress bit is set.            Hardware allows other bits in this register to be programmed for the same transaction when writing this bit to 1. This saves an additional memory write.</p>
0	Reserved



### 22.1.20 PREOP—Prefix Opcode Configuration Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 94h Attribute: R/W  
 Default Value: 0000h Size: 16 bits

Bit	Description
15:8	<b>Prefix Opcode 1</b> — R/W. Software programs an SPI opcode into this field that is permitted to run as the first command in an atomic cycle sequence.
7:0	<b>Prefix Opcode 0</b> — R/W. Software programs an SPI opcode into this field that is permitted to run as the first command in an atomic cycle sequence.

**Note:** This register is not writable when the Flash Configuration Lock-Down bit (SPIBAR + 04h:15) is set.

### 22.1.21 OPTYPE—Opcode Type Configuration Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 96h Attribute: R/W  
 Default Value: 0000h Size: 16 bits

Entries in this register correspond to the entries in the Opcode Menu Configuration register.

**Note:** The definition below only provides write protection for opcodes that have addresses associated with them. Therefore, any erase or write opcodes that do not use an address should be avoided (for example, “Chip Erase” and “Auto-Address Increment Byte Program”)

Bit	Description
15:14	<b>Opcode Type 7</b> — R/W. See the description for bits 1:0
13:12	<b>Opcode Type 6</b> — R/W. See the description for bits 1:0
11:10	<b>Opcode Type 5</b> — R/W. See the description for bits 1:0
9:8	<b>Opcode Type 4</b> — R/W. See the description for bits 1:0
7:6	<b>Opcode Type 3</b> — R/W. See the description for bits 1:0
5:4	<b>Opcode Type 2</b> — R/W. See the description for bits 1:0
3:2	<b>Opcode Type 1</b> — R/W. See the description for bits 1:0
1:0	<b>Opcode Type 0</b> — R/W. This field specifies information about the corresponding Opcode 0. This information allows the hardware to 1) know whether to use the address field and 2) provide BIOS and Shared Flash protection capabilities. The encoding of the two bits is: 00 = No address associated with this Opcode; Read cycle type 01 = No address associated with this Opcode; Write cycle type 10 = Address required; Read cycle type 11 = Address required; Write cycle type

**Note:** This register is not writable when the SPI Configuration Lock-Down bit (SPIBAR + 00h:15) is set.



### 22.1.22 OPMENU—Opcode Menu Configuration Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + 98h                      Attribute:                      R/W  
Default Value:    0000000000000000h                      Size:                              64 bits

Eight entries are available in this register to give BIOS a sufficient set of commands for communicating with the flash device, while also restricting what malicious software can do. This keeps the hardware flexible enough to operate with a wide variety of SPI devices.

**Note:** It is recommended that BIOS avoid programming Write Enable opcodes in this menu. Malicious software could then perform writes and erases to the SPI flash without using the atomic cycle mechanism. This could cause functional failures in a shared flash environment. Write Enable opcodes should only be programmed in the Prefix Opcodes.

Bit	Description
63:56	<b>Allowable Opcode 7</b> — R/W. See the description for bits 7:0
55:48	<b>Allowable Opcode 6</b> — R/W. See the description for bits 7:0
47:40	<b>Allowable Opcode 5</b> — R/W. See the description for bits 7:0
39:32	<b>Allowable Opcode 4</b> — R/W. See the description for bits 7:0
31:24	<b>Allowable Opcode 3</b> — R/W. See the description for bits 7:0
23:16	<b>Allowable Opcode 2</b> — R/W. See the description for bits 7:0
15:8	<b>Allowable Opcode 1</b> — R/W. See the description for bits 7:0
7:0	<b>Allowable Opcode 0</b> — R/W. Software programs an SPI opcode into this field for use when initiating SPI commands through the Control Register.

This register is not writable when the SPI Configuration Lock-Down bit (SPIBAR + 00h:15) is set.

### 22.1.23 FDOC—Flash Descriptor Observability Control Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + B0h                      Attribute:                      R/W  
Default Value:    00000000h                      Size:                              32 bits

**Note:** This register that can be used to observe the contents of the Flash Descriptor that is stored in the PCH Flash Controller. This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:15	Reserved
14:12	<b>Flash Descriptor Section Select (FDSS)</b> — R/W. Selects which section within the loaded Flash Descriptor to observe. 000 = Flash Signature and Descriptor Map 001 = Component 010 = Region 011 = Master 111 = Reserved
11:2	<b>Flash Descriptor Section Index (FDSI)</b> — R/W. Selects the DW offset within the Flash Descriptor Section to observe.
1:0	Reserved



### 22.1.24 FDOD—Flash Descriptor Observability Data Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + B4h                      Attribute:                      RO  
 Default Value:                      00000000h                      Size:                      32 bits

**Note:** This register that can be used to observe the contents of the Flash Descriptor that is stored in the PCH Flash Controller.

Bit	Description
31:0	<b>Flash Descriptor Section Data (FDSD)</b> — RO. Returns the DW of data to observe as selected in the Flash Descriptor Observability Control.

### 22.1.25 AFC—Additional Flash Control Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + C0h                      Attribute:                      RO, R/W  
 Default Value:                      00000000h                      Size:                      32 bits.

Bit	Description
31:3	Reserved.
2:1	<b>Flash Controller Interface Dynamic Clock Gating Enable</b> — R/W. 0 = Flash Controller Interface Dynamic Clock Gating is Disabled 1 = Flash Controller Interface Dynamic Clock Gating is Enabled Other configurations are Reserved.
0	<b>Flash Controller Core Dynamic Clock Gating Enable</b> — R/W. 0 = Flash Controller Core Dynamic Clock Gating is Disabled 1 = Flash Controller Core Dynamic Clock Gating is Enabled

### 22.1.26 LVSCC— Host Lower Vendor Specific Component Capabilities Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + C4h                      Attribute:                      RO, R/WL  
 Default Value:                      00000000h                      Size:                      32 bits

**Note:** All attributes described in LVSCC must apply to all flash space below the FPBA, even if it spans between two separate flash parts. This register is only applicable when SPI device is in descriptor mode.

Bit	Description
31:24	Reserved.
23	<b>Vendor Component Lock (LVCL)</b> — R/W. This register locks itself when set. 0 = The lock bit is not set 1 = The Vendor Component Lock bit is set. <b>Note:</b> This bit applies to both UVSCC and LVSCC registers.
22:16	Reserved
15:8	<b>Lower Erase Opcode (LEO)</b> — R/W. This register is programmed with the Flash erase instruction opcode required by the vendor's Flash component. This register is locked by the Vendor Component Lock (LVCL) bit.
7:5	Reserved



Bit	Description
4	<p><b>Write Enable on Write Status (LWEWS)</b> — R/W. This register is locked by the Vendor Component Lock (LVCL) bit.            0 = No automatic write of 00h will be made to the SPI flash's status register)            1 = A write of 00h to the SPI flash's status register will be sent on EVERY write and erase to the SPI flash. 06h 01h 00h is the opcode sequence used to unlock the Status register.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This bit should not be set to '1' if there are non volatile bits in the SPI flash's status register. This may lead to premature flash wear out</li> <li>This is not an atomic sequence. If the SPI component's status register is non-volatile, then BIOS should issue an atomic software sequence cycle to unlock the flash part.</li> <li>Bit 3 and bit 4 should NOT be both set to '1'.</li> </ol>
3	<p><b>Lower Write Status Required (LWSR)</b> — R/W. This register is locked by the Vendor Component Lock (LVCL) bit.            0 = No automatic write of 00h will be made to the SPI flash's status register)            1 = A write of 00h to the SPI flash's status register will be sent on EVERY write and erase to the SPI flash. 50h 01h 00h is the opcode sequence used to unlock the Status register.</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>This bit should not be set to '1' if there are non volatile bits in the SPI flash's status register. This may lead to premature flash wear out.</li> <li>This is not an atomic sequence. If the SPI component's status register is non-volatile, then BIOS should issue an atomic software sequence cycle to unlock the flash part.</li> <li>Bit 3 and bit 4 should NOT be both set to '1'.</li> </ol>
2	<p><b>Lower Write Granularity (LWG)</b> — R/W. This register is locked by the Vendor Component Lock (LVCL) bit.            0 = 1 Byte            1 = 64 Byte</p> <p><b>Notes:</b></p> <ol style="list-style-type: none"> <li>If more than one Flash component exists, this field must be set to the lowest common write granularity of the different Flash components.</li> <li>If using 64 B write, BIOS must ensure that multiple byte writes do not occur over 256 B boundaries. This will lead to corruption as the write will wrap around the page boundary on the SPI flash part. This is a a feature page writable SPI flash.</li> </ol>
1:0	<p><b>Lower Block/Sector Erase Size (LBES)</b>— R/W. This field identifies the erasable sector size for all Flash components.            00 = 256 Byte            01 = 4 KB            10 = 8 KB            11 = 64 KB</p> <p>This register is locked by the Vendor Component Lock (LVCL) bit.            Hardware takes no action based on the value of this register. The contents of this register are to be used only by software and can be read in the HSFSTS.BERASE register in both the BIOS and the GbE program registers if FLA is less than FPBA.</p>

### 22.1.27 UVSCC— Host Upper Vendor Specific Component Capabilities Register (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + C8h                      Attribute: RO, R/WL  
 Default Value: 00000000h                      Size: 32 bits

**Note:** All attributes described in UVSCC must apply to all flash space equal to or above the FPBA, even if it spans between two separate flash parts. This register is only applicable when SPI device is in descriptor mode.

**Note:** To prevent this register from being modified you must use LVSCC.VCL bit.

Bit	Description
31:16	Reserved.
15:8	<p><b>Upper Erase Opcode (UEO)</b>— R/W. This register is programmed with the Flash erase instruction opcode required by the vendor's Flash component.            This register is locked by the Vendor Component Lock (UVCL) bit.</p>
7:5	Reserved





### 22.1.29 SRDL – Soft Reset Data Lock (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + F0h      Attribute: R/WL  
 Default Value: 00000000h      Size: 32 bits

Bit	Description
31:1	Reserved.
0	<b>Set_Strap Lock (SSL)</b> — R/WL. 0 = The SRDL (this register), SRDC (SPIBAR+F4h), and SRD (SPIBAR+F4h) registers are writable. 1 = The SRDL (this register), SRDC (SPIBAR+F4h), and SRD (SPIBAR+F4h) registers are locked. <b>Note:</b> That this bit is reset to '0' on CF9h resets.

### 22.1.30 SRDC – Soft Reset Data Control (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + F4h      Attribute: R/WL  
 Default Value: 00000000h      Size: 32 bits

Bit	Description
31:1	Reserved.
0	<b>Soft Reset Data Select (SRDS)</b> — R/WL. 0 = The Set_Strap data sends the default processor configuration data. 1 = The Set_Strap message bits come from the Set_Strap Msg Data register. <b>Notes:</b> <ol style="list-style-type: none"> <li>This bit is reset by the RSMRST# or when the Resume well loses power.</li> <li>This bit is locked by the SSL bit (SPIBAR+F0h:bit 0).</li> </ol>

### 22.1.31 SRD – Soft Reset Data (SPI Memory Mapped Configuration Registers)

Memory Address: SPIBAR + F8h      Attribute: R/WL  
 Default Value: 00000000h      Size: 32 bits

Bit	Description
31:14	Reserved.
13:0	<b>Set_Stap Data (SSD)</b> — R/WL. <b>Notes:</b> <ol style="list-style-type: none"> <li>These bits are reset by the RSMRST#, or when the Resume well loses power.</li> <li>These bits are locked by the SSL bit (SPIBAR+F0h:bit 0).</li> </ol>

## 22.2 Flash Descriptor Records

The following sections describe the data structure of the Flash Descriptor on the SPI device. These are not registers within the PCH.

### 22.3 OEM Section

Memory Address: F00h      Default Value:      Size: 256 Bytes



256 Bytes are reserved at the top of the Flash Descriptor for use by the OEM. The information stored by the OEM can only be written during the manufacturing process as the Flash Descriptor read/write permissions must be set to Read Only when the computer leaves the manufacturing floor. The PCH Flash controller does not read this information. FFh is suggested to reduce programming time.

## 22.4 GbE SPI Flash Program Registers

The GbE Flash registers are memory-mapped with a base address MBARB found in the GbE LAN register chapter Device 25: Function 0: Offset 14h. The individual registers are then accessible at MBARB + Offset as indicated in the following table.

These memory mapped registers must be accessed in byte, word, or DWord quantities.

**Note:** These registers are only applicable when SPI flash is used in descriptor mode.

**Table 22-2. Gigabit LAN SPI Flash Program Register Address Map (GbE LAN Memory Mapped Configuration Registers)**

MBARB + Offset	Mnemonic	Register Name	Default	Attribute
00h–03h	GLFPR	Gigabit LAN Flash Primary Region	00000000h	RO
04h–05h	HSFS	Hardware Sequencing Flash Status	0000h	RO, R/WC, R/W
06h–07h	HSFC	Hardware Sequencing Flash Control	0000h	R/W, R/WS
08h–0Bh	FADDR	Flash Address	00000000h	R/W
0Ch–0Fh	Reserved	Reserved	00000000h	
10h–13h	FDATA0	Flash Data 0	00000000h	R/W
14h–4Fh	Reserved	Reserved	00000000h	
50h–53h	FRAP	Flash Region Access Permissions	0000088h	RO, R/W
54h–57h	FREG0	Flash Region 0	00000000h	RO
58h–5Bh	FREG1	Flash Region 1	00000000h	RO
5Ch–5Fh	FREG2	Flash Region 2	00000000h	RO
60h–63h	FREG3	Flash Region 3	00000000h	RO
64h–73h	Reserved	Reserved for Future Flash Regions		
74h–77h	PR0	Protected Range 0	00000000h	R/W
78h–7Bh	PR1	Protected Range 1	00000000h	R/W
7Ch–8Fh	Reserved	Reserved		
90h	SSFS	Software Sequencing Flash Status	00h	RO, R/WC
91h–93h	SSFC	Software Sequencing Flash Control	000000h	R/W
94h–95h	PREOP	Prefix Opcode Configuration	0000h	R/W
96h–97h	OPTYPE	Opcode Type Configuration	0000h	R/W
98h–9Fh	OPMENU	Opcode Menu Configuration	00000000 00000000h	R/W
A0h–DFh	Reserved	Reserved		



### 22.4.1 GLFPR –Gigabit LAN Flash Primary Region Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 00h                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:29	Reserved
28:16	<b>GbE Flash Primary Region Limit (PRL)</b> — RO. This specifies address bits 24:12 for the Primary Region Limit. The value in this register loaded from the contents in the Flash Descriptor.FLREG3.Region Limit
15:13	Reserved
12:0	<b>GbE Flash Primary Region Base (PRB)</b> — RO. This specifies address bits 24:12 for the Primary Region Base The value in this register is loaded from the contents in the Flash Descriptor.FLREG3.Region Base

### 22.4.2 HSFS—Hardware Sequencing Flash Status Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 04h                      Attribute: RO, R/WC, R/W  
 Default Value: 0000h                      Size: 16 bits

Bit	Description
15	<b>Flash Configuration Lock-Down (FLOCKDN)</b> — R/W. When set to 1, those Flash Program Registers that are locked down by this FLOCKDN bit cannot be written. Once set to 1, this bit can only be cleared by a hardware reset due to a global reset or host partition reset in an Intel® ME enabled system.
14	<b>Flash Descriptor Valid (FDV)</b> — RO. This bit is set to a 1 if the Flash Controller read the correct Flash Descriptor Signature. If the Flash Descriptor Valid bit is not '1', software cannot use the Hardware Sequencing registers, but must use the software sequencing registers. Any attempt to use the Hardware Sequencing registers will result in the FCERR bit being set.
13	<b>Flash Descriptor Override Pin Strap Status (FDOPSS)</b> — RO. his bit indicates the condition of the Flash Descriptor Security Override / Intel ME Debug Mode Pin-Strap. 0 = The Flash Descriptor Security Override / Intel ME Debug Mode strap is set using external pull-up on HDA_SDO 1 = No override
12:6	Reserved
5	<b>SPI Cycle In Progress (SCIP)</b> — RO. Hardware sets this bit when software sets the Flash Cycle Go (FGO) bit in the Hardware Sequencing Flash Control register. This bit remains set until the cycle completes on the SPI interface. Hardware automatically sets and clears this bit so that software can determine when read data is valid and/or when it is safe to begin programming the next command. Software must only program the next command when this bit is 0.
4:3	<b>Block/Sector Erase Size (BERASE)</b> — RO. This field identifies the erasable sector size for all Flash components. 00 = 256 Byte 01 = 4 K Byte 10 = 8 K Byte 11 = 64 K Byte If the Flash Linear Address is less than FPBA then this field reflects the value in the LVSCC.LBES register. If the Flash Linear Address is greater or equal to FPBA then this field reflects the value in the UVSCC.UBES register.





### 22.4.5 FDATA0—Flash Data 0 Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 10h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:0	<p><b>Flash Data 0 (FD0)</b> — R/W. This field is shifted out as the SPI Data on the Master-Out Slave-In Data pin during the data portion of the SPI cycle.</p> <p>This register also shifts in the data from the Master-In Slave-Out pin into this register during the data portion of the SPI cycle.</p> <p>The data is always shifted starting with the least significant byte, msb to lsb, followed by the next least significant byte, msb to lsb, etc. Specifically, the shift order on SPI in terms of bits within this register is: 7-6-5-4-3-2-1-0-15-14-13-...8-23-22-...16-31...24 Bit 24 is the last bit shifted out/in. There are no alignment assumptions; byte 0 always represents the value specified by the cycle address.</p> <p>Note that the data in this register may be modified by the hardware during any programmed SPI transaction. Direct Memory Reads do not modify the contents of this register.</p>

### 22.4.6 FRAP—Flash Regions Access Permissions Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 50h                      Attribute: RO, R/W  
 Default Value: 00000808h                      Size: 32 bits

Bit	Description
31:24	<p><b>GbE Master Write Access Grant (GMWAG)</b> — R/W. Each bit 31:24 corresponds to Master[7:0]. GbE can grant one or more masters write access to the GbE region 3 overriding the permissions in the Flash Descriptor.</p> <p>Master[1] is Host Processor/BIOS, Master[2] is Intel® Management Engine, Master[3] is Host processor/GbE. Master[0] and Master[7:4] are reserved.</p> <p>The contents of this register are locked by the FLOCKDN bit.</p>
23:16	<p><b>GbE Master Read Access Grant (GMRAG)</b> — R/W. Each bit 23:16 corresponds to Master[7:0]. GbE can grant one or more masters read access to the GbE region 3 overriding the read permissions in the Flash Descriptor.</p> <p>Master[1] is Host processor/BIOS, Master[2] is Intel® Management Engine, Master[3] is GbE. Master[0] and Master[7:4] are reserved.</p> <p>The contents of this register are locked by the FLOCKDN bit</p>
15:8	<p><b>GbE Region Write Access (GRWA)</b> — RO. Each bit 15:8 corresponds to Regions 7:0. If the bit is set, this master can erase and write that particular region through register accesses.</p> <p>The contents of this register are that of the Flash Descriptor. Flash Master 3.Master Region Write Access OR a particular master has granted GbE write permissions in their Master Write Access Grant register OR the Flash Descriptor Security Override strap is set.</p>
7:0	<p><b>GbE Region Read Access (GRRR)</b> — RO. Each bit 7:0 corresponds to Regions 7:0. If the bit is set, this master can read that particular region through register accesses.</p> <p>The contents of this register are that of the Flash Descriptor. Flash Master 3.Master Region Write Access OR a particular master has granted GbE read permissions in their Master Read Access Grant register.</p>



### 22.4.7 FREG0—Flash Region 0 (Flash Descriptor) Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: M<sub>BARB</sub> + 54h                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 0 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG0.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 0 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG0.Region Base.

### 22.4.8 FREG1—Flash Region 1 (BIOS Descriptor) Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: M<sub>BARB</sub> + 58h                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 1 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG1.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 1 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG1.Region Base.

### 22.4.9 FREG2—Flash Region 2 (Intel® ME) Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: M<sub>BARB</sub> + 5Ch                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 2 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG2.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 2 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG2.Region Base.



### 22.4.10 FREG3—Flash Region 3 (GbE) Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 60h                      Attribute: RO  
Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:29	Reserved
28:16	<b>Region Limit (RL)</b> — RO. This specifies address bits 24:12 for the Region 3 Limit. The value in this register is loaded from the contents in the Flash Descriptor.FLREG3.Region Limit.
15:13	Reserved
12:0	<b>Region Base (RB)</b> — RO. This specifies address bits 24:12 for the Region 3 Base. The value in this register is loaded from the contents in the Flash Descriptor.FLREG3.Region Base.

### 22.4.11 PR0—Protected Range 0 Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 74h                      Attribute: R/W  
Default Value: 00000000h                      Size: 32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.



### 22.4.12 PR1—Protected Range 1 Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 78h                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bits

**Note:** This register can not be written when the FLOCKDN bit is set to 1.

Bit	Description
31	<b>Write Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that writes and erases directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
30:29	Reserved
28:16	<b>Protected Range Limit</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the upper limit of the protected range. Address bits 11:0 are assumed to be FFFh for the limit comparison. Any address greater than the value programmed in this field is unaffected by this protected range.
15	<b>Read Protection Enable</b> — R/W. When set, this bit indicates that the Base and Limit fields in this register are valid and that read directed to addresses between them (inclusive) must be blocked by hardware. The base and limit fields are ignored when this bit is cleared.
14:13	Reserved
12:0	<b>Protected Range Base</b> — R/W. This field corresponds to FLA address bits 24:12 and specifies the lower base of the protected range. Address bits 11:0 are assumed to be 000h for the base comparison. Any address less than the value programmed in this field is unaffected by this protected range.

### 22.4.13 SSFS—Software Sequencing Flash Status Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 90h                      Attribute: RO, R/WC  
 Default Value: 00h                      Size: 8 bits

**Note:** The Software Sequencing control and status registers are reserved if the hardware sequencing control and status registers are used.

Bit	Description
7	<b>Fast Read Supported</b> — RO. This bit reflects the value of the Fast Read Support bit in the flash Descriptor Component Section.
6	<b>Dual Output Fast Read Supported</b> — RO. This bit reflects the value of the Dual Output Fast Read support bit in the Flash Descriptor Component Section.
5	Reserved
4	<b>Access Error Log (AEL)</b> — RO. This bit reflects the value of the Hardware Sequencing Status AEL register.
3	<b>Flash Cycle Error (FCERR)</b> — R/WC. Hardware sets this bit to 1 when a programmed access is blocked from running on the SPI interface due to one of the protection policies or when any of the programmed cycle registers is written while a programmed access is already in progress. This bit remains asserted until cleared by software writing a 1 or hardware reset due to a global reset or host partition reset in an Intel ME enabled system.



Bit	Description
2	<b>Cycle Done Status</b> — R/WC. The PCH sets this bit to 1 when the SPI Cycle completes (that is, SCIP bit is 0) after software sets the GO bit. This bit remains asserted until cleared by software writing a 1 or hardware reset due to a global reset or host partition reset in an Intel® ME enabled system. When this bit is set and the SPI SMI# Enable bit is set, an internal signal is asserted to the SMI# generation block. Software must make sure this bit is cleared prior to enabling the SPI SMI# assertion for a new programmed access.
1	Reserved
0	<b>SPI Cycle In Progress (SCIP)</b> — RO. Hardware sets this bit when software sets the SPI Cycle Go bit in the Command register. This bit remains set until the cycle completes on the SPI interface. Hardware automatically sets and clears this bit so that software can determine when read data is valid and/or when it is safe to begin programming the next command. Software must only program the next command when this bit is 0.

### 22.4.14 SSFC—Software Sequencing Flash Control Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 91h Attribute: R/W  
 Default Value: 000000h Size: 24 bits

Bit	Description
23:19	Reserved
18:16	<b>SPI Cycle Frequency (SCF)</b> — R/W. This register sets frequency to use for all SPI software sequencing cycles (write, erase, fast read, read status, etc.) except for the read cycle which always run at 20 MHz. 000 = 20 MHz 001 = 33 MHz All other values = Reserved. This register is locked when the SPI Configuration Lock-Down bit is set.
15	Reserved
14	<b>Data Cycle (DS)</b> — R/W. When set to 1, there is data that corresponds to this transaction. When 0, no data is delivered for this cycle, and the DBC and data fields themselves are don't cares.
13:8	<b>Data Byte Count (DBC)</b> — R/W. This field specifies the number of bytes to shift in or out during the data portion of the SPI cycle. The valid settings (in decimal) are any value from 0 to 3. The number of bytes transferred is the value of this field plus 1. Note that when this field is 00b, then there is 1 byte to transfer and that 11b means there are 4 bytes to transfer.
7	Reserved
6:4	<b>Cycle Opcode Pointer (COP)</b> — R/W. This field selects one of the programmed opcodes in the Opcode Menu to be used as the SPI Command/Opcode. In the case of an Atomic Cycle Sequence, this determines the second command.
3	<b>Sequence Prefix Opcode Pointer (SPOP)</b> — R/W. This field selects one of the two programmed prefix opcodes for use when performing an Atomic Cycle Sequence. A value of 0 points to the opcode in the least significant byte of the Prefix Opcodes register. By making this programmable, the PCH supports flash devices that have different opcodes for enabling writes to the data space vs. status register.



Bit	Description
2	<p><b>Atomic Cycle Sequence (ACS)</b> — R/W. When set to 1 along with the SCGO assertion, the PCH will execute a sequence of commands on the SPI interface without allowing the LAN component to arbitrate and interleave cycles. The sequence is composed of:</p> <ul style="list-style-type: none"> <li>• Atomic Sequence Prefix Command (8-bit opcode only)</li> <li>• Primary Command specified below by software (can include address and data)</li> <li>• Polling the Flash Status Register (opcode 05h) until bit 0 becomes 0b.</li> </ul> <p>The SPI Cycle in Progress bit remains set and the Cycle Done Status bit remains unset until the Busy bit in the Flash Status Register returns 0.</p>
1	<p><b>SPI Cycle Go (SCGO)</b> — R/WS. This bit always returns 0 on reads. However, a write to this register with a '1' in this bit starts the SPI cycle defined by the other bits of this register. The "SPI Cycle in Progress" (SCIP) bit gets set by this action. Hardware must ignore writes to this bit while the Cycle In Progress bit is set.</p> <p>Hardware allows other bits in this register to be programmed for the same transaction when writing this bit to 1. This saves an additional memory write.</p>
0	Reserved

### 22.4.15 PREOP—Prefix Opcode Configuration Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 94h                      Attribute: R/W  
 Default Value: 0000h                              Size: 16 bits

Bit	Description
15:8	<b>Prefix Opcode 1</b> — R/W. Software programs an SPI opcode into this field that is permitted to run as the first command in an atomic cycle sequence.
7:0	<b>Prefix Opcode 0</b> — R/W. Software programs an SPI opcode into this field that is permitted to run as the first command in an atomic cycle sequence.

**Note:** This register is not writable when the SPI Configuration Lock-Down bit (MBARB + 00h:15) is set.

### 22.4.16 OPTYPE—Opcode Type Configuration Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 96h                      Attribute: R/W  
 Default Value: 0000h                              Size: 16 bits

Entries in this register correspond to the entries in the Opcode Menu Configuration register.

**Note:** The definition below only provides write protection for opcodes that have addresses associated with them. Therefore, any erase or write opcodes that do not use an address should be avoided (for example, "Chip Erase" and "Auto-Address Increment Byte Program").

Bit	Description
15:14	<b>Opcode Type 7</b> — R/W. See the description for bits 1:0
13:12	<b>Opcode Type 6</b> — R/W. See the description for bits 1:0
11:10	<b>Opcode Type 5</b> — R/W. See the description for bits 1:0
9:8	<b>Opcode Type 4</b> — R/W. See the description for bits 1:0
7:6	<b>Opcode Type 3</b> — R/W. See the description for bits 1:0



Bit	Description
5:4	<b>Opcode Type 2</b> — R/W. See the description for bits 1:0
3:2	<b>Opcode Type 1</b> — R/W. See the description for bits 1:0
1:0	<b>Opcode Type 0</b> — R/W. This field specifies information about the corresponding Opcode 0. This information allows the hardware to 1) know whether to use the address field and 2) provide BIOS and Shared Flash protection capabilities. The encoding of the two bits is: 00 = No address associated with this Opcode; Read cycle type 01 = No address associated with this Opcode; Write cycle type 10 = Address required; Read cycle type 11 = Address required; Write cycle type

**Note:** This register is not writable when the SPI Configuration Lock-Down bit (MBARB + 00h:15) is set.

### 22.4.17 OPMENU—Opcode Menu Configuration Register (GbE LAN Memory Mapped Configuration Registers)

Memory Address: MBARB + 98h                      Attribute: R/W  
 Default Value: 0000000000000000h              Size: 64 bits

Eight entries are available in this register to give GbE a sufficient set of commands for communicating with the flash device, while also restricting what malicious software can do. This keeps the hardware flexible enough to operate with a wide variety of SPI devices.

**Note:** It is recommended that GbE avoid programming Write Enable opcodes in this menu. Malicious software could then perform writes and erases to the SPI flash without using the atomic cycle mechanism. This could cause functional failures in a shared flash environment. Write Enable opcodes should only be programmed in the Prefix Opcodes.

Bit	Description
63:56	<b>Allowable Opcode 7</b> — R/W. See the description for bits 7:0
55:48	<b>Allowable Opcode 6</b> — R/W. See the description for bits 7:0
47:40	<b>Allowable Opcode 5</b> — R/W. See the description for bits 7:0
39:32	<b>Allowable Opcode 4</b> — R/W. See the description for bits 7:0
31:24	<b>Allowable Opcode 3</b> — R/W. See the description for bits 7:0
23:16	<b>Allowable Opcode 2</b> — R/W. See the description for bits 7:0
15:8	<b>Allowable Opcode 1</b> — R/W. See the description for bits 7:0
7:0	<b>Allowable Opcode 0</b> — R/W. Software programs an SPI opcode into this field for use when initiating SPI commands through the Control Register.

**Note:** This register is not writable when the SPI Configuration Lock-Down bit (MBARB + 00h:15) is set.

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# 23 Thermal Sensor Registers (D31:F6)

## 23.1 PCI Bus Configuration Registers

Table 23-1. Thermal Sensor Register Address Map

Offset	Mnemonic	Register Name	Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	1D24h	RO
04h–05h	CMD	Command Register	0000h	R/W, RO
06h–07h	STS	Device Status	0010h	R/WC, RO
08h	RID	Revision ID	00h	RO
09h	PI	Programming Interface	00h	RO
0Ah	SCC	Sub Class Code	80h	RO
0Bh	BCC	Base Class Code	11h	RO
0Ch	CLS	Cache Line Size	00h	RO
0Dh	LT	Latency Timer	00h	RO
0Eh	HTYPE	Header Type	00h	RO
0Fh	BIST	Built-in Self Test	00h	RO
10h–13h	TBAR	Thermal Base Address (Memory)	00000004h	R/W, RO
14h–17h	TBARH	Thermal Base Address High DWord	00000000h	RO
2Ch–2Dh	SVID	Subsystem Vendor Identifier	0000h	R/WO
2Eh–2Fh	SID	Subsystem Identifier	0000h	R/WO
34h	CAP_PTR	Capabilities Pointer	50h	RO
3Ch	INTLN	Interrupt Line	00h	R/W
3Dh	INTPN	Interrupt Pin	03h	RO
40h–43h	TBARB	BIOS Assigned Thermal Base Address	00000004h	R/W, RO
44h–47h	TBARBH	BIOS Assigned Thermal Base High DWord	00000000h	R/W
50h–51h	PID	Power Management Identifiers	8001h	RO
52h–53h	PC	Power Management Capabilities	0023h	RO
54-57h	PCS	Power Management Control and Status	0008h	R/W, RO



### 23.1.1 VID—Vendor Identification Register

Offset Address: 00h–01h                      Attribute: RO  
 Default Value: 8086h                      Size: 16 bit  
 Lockable: No                      Power Well: Core

Bit	Description
15:0	<b>Vendor ID</b> — RO. This is a 16-bit value assigned to Intel. Intel VID = 8086h

### 23.1.2 DID—Device Identification Register

Offset Address: 02h–03h                      Attribute: RO  
 Default Value: 1D24h                      Size: 16 bits

Bit	Description
15:0	<b>Device ID (DID)</b> — RO. Indicates the device number assigned by the SIG.

### 23.1.3 CMD—Command Register

Address Offset: 04h–05h                      Attribute: RO, R/W  
 Default Value: 0000h                      Size: 16 bits

Bit	Description
15:11	Reserved
10	<b>Interrupt Disable (ID)</b> — R/W. Enables the device to assert an INTx#. 0 = When cleared, the INTx# signal may be asserted. 1 = When set, the Thermal logic's INTx# signal will be deasserted.
9	<b>FBE (Fast Back to Back Enable)</b> — RO. Not implemented. Hardwired to 0.
8	<b>SEN (SERR Enable)</b> — RO. Not implemented. Hardwired to 0.
7	<b>WCC (Wait Cycle Control)</b> — RO. Not implemented. Hardwired to 0.
6	<b>PER (Parity Error Response)</b> — RO. Not implemented. Hardwired to 0.
5	<b>VPS (VGA Palette Snoop)</b> — RO. Not implemented. Hardwired to 0.
4	<b>MWI (Memory Write and Invalidate Enable)</b> — RO. Not implemented. Hardwired to 0.
3	<b>SCE (Special Cycle Enable)</b> — RO. Not implemented. Hardwired to 0.
2	<b>BME (Bus Master Enable)</b> — R/W. 0 = Function disabled as bus master. 1 = Function enabled as bus master.
1	<b>Memory Space Enable (MSE)</b> — R/W. 0 = Disable 1 = Enable. Enables memory space accesses to the Thermal registers.
0	<b>IOS (I/O Space)</b> — RO. The Thermal logic does not implement IO Space; therefore, this bit is hardwired to 0.

















### 23.2.2 TSE—Thermal Sensor Enable Register

Offset Address: TBARB+01h                      Attribute: R/W  
Default Value: 00h                                Size: 8 bit

Bit	Description
7:0	<b>Thermal Sensor Enable (TSE)</b> — R/W BIOS programs this register to enable the thermal sensor.

### 23.2.3 TSS—Thermal Sensor Status Register

Offset Address: TBARB+02h                      Attribute: RO  
Default Value: 00h                                Size: 8 bit

Bit	Description
7	<b>Catastrophic Trip Indicator (CTI)</b> — RO. 0 = The temperature is below the catastrophic setting. 1 = The temperature is above the catastrophic setting.
6	<b>Hot Trip Indicator (HTI)</b> — RO. 0 = The temperature is below the Hot setting. 1 = The temperature is above the Hot setting.
5	<b>Auxiliary Trip Indicator (ATI)</b> — RO. 0 = The temperature is below the Auxiliary setting. 1 = The temperature is above the Auxiliary setting.
4	Reserved
3	<b>Auxiliary2 Trip Indicator (ATI)</b> — RO. 0 = The temperature is below the Auxiliary2 setting. 1 = The temperature is above the Auxiliary2 setting.
2:0	Reserved

### 23.2.4 TSTR — Thermal Sensor Thermometer Read Register

Offset Address: TBARB+03h                      Attribute: RO  
Default Value: yFh (y = x111b)                      Size: 8 bit

This register generally provides the current calibrated temperature from the thermometer circuit when the thermometer is enabled.

Bit	Description
7	Reserved
6:0	<b>Thermometer Reading (TR)</b> — R/O. Value corresponds to the thermal sensor temperature. A value of 00h means the hottest temperature and 7Fh is the lowest. The range is approximately between 40 °C to 130 °C. Temperature below 40 °C will be truncated to 40 °C.



## 23.2.5 TSTTP—Thermal Sensor Temperature Trip Point Register

Offset Address: TBARB+04h Attribute: R/W  
 Default Value: 00000000h Size: 32 bit

Bit	Description
31:24	<b>Auxiliary2 Trip Point Setting (A2TPS)</b> — R/W. These bits set the Auxiliary2 trip point. These bits are lockable by programming the policy-lock down bit (bit 7) of TSPC register. These bits may only be programmed from 0h to 7Fh. Setting bit 31 is illegal.
23:16	<b>Auxiliary Trip Point Setting (ATPS)</b> — R/W. These bits set the Auxiliary trip point. These bits are lockable using programming the policy-lock down bit (bit 7) of TSPC register. These bits may only be programmed from 0h to 7Fh. Setting bit 23 is illegal.
15:8	<b>Hot Trip Point Setting (HTPS)</b> — R/W. These bits set the Hot trip point. These bits are lockable by programming the policy-lock down bit (bit 7) of TSPC register. These bits may only be programmed from 0h to 7Fh. Setting bit 15 is illegal. BIOS should program to 3Ah for setting Hot Trip Point to 108 °C.
7:0	<b>Catastrophic Trip Point Setting (CTPS)</b> — R/W. These bits set the catastrophic trip point. These bits are lockable using TSCO.bit 7. These bits may only be programmed from 0h to 7Fh. Setting bit 7 is illegal. BIOS should program to 2Bh for setting Catastrophic Trip Point to 120 °C.

## 23.2.6 TSCO—Thermal Sensor Catastrophic Lock-Down Register

Offset Address: TBARB+08h Attribute: R/W  
 Default Value: 00h Size: 8 bit

Bit	Description
7	<b>Lock bit for Catastrophic (LBC)</b> — R/W 0 = Catastrophic programming interface is unlocked 1 = Locks the Catastrophic programming interface including TSTTP.bits[7:0]. This bit may only be set to a 0 by a host partitioned reset (note that CF9 warm reset is a host partitioned reset). Writing a 0 to this bit has no effect. TSCO.[7] is unlocked by default and can be locked through BIOS.
6:0	Reserved

## 23.2.7 TSES—Thermal Sensor Error Status Register

Offset Address: TBARB+0Ch Attribute: R/WC  
 Default Value: 00h Size: 8 bit

Bit	Description
7	<b>Auxiliary2 High-to-LowEvent</b> — R/WC. 0 = No trip occurs. 1 = Indicates that an Auxiliary2 Thermal Sensor trip event occurred based on a higher to lower temperature transition through the trip point. Software must write a 1 to clear this status bit.
6	<b>Catastrophic High-to-LowEvent</b> — R/WC. 0 = No trip occurs. 1 = Indicates that a Catastrophic Thermal Sensor trip event occurred based on a higher to lower temperature transition through the trip point. Software must write a 1 to clear this status bit.
5	<b>Hot High-to-LowEvent</b> — R/WC. 0 = No trip occurs. 1 = Indicates that a Hot Thermal Sensor trip event occurred based on a higher to lower temperature transition through the trip point. Software must write a 1 to clear this status bit.



Bit	Description
4	<b>Auxiliary High-to-Low Event</b> — R/WC. 0 = No trip occurs. 1 = Indicates that an Auxiliary Thermal Sensor trip event occurred based on a higher to lower temperature transition through the trip point. Software must write a 1 to clear this status bit.
3	<b>Auxiliary2 Low-to-High Event</b> — R/WC. 0 = No trip occurs. 1 = Indicates that an Auxiliary2 Thermal Sensor trip event occurred based on a lower to higher temperature transition through the trip point. Software must write a 1 to clear this status bit.
2	<b>Catastrophic Low-to-High Event</b> — R/WC. 0 = No trip occurs. 1 = Indicates that a Catastrophic Thermal Sensor trip event occurred based on a lower to higher temperature transition through the trip point. Software must write a 1 to clear this status bit.
1	<b>Hot Low-to-High Event</b> — R/WC. 0 = No trip occurs. 1 = Indicates that a hot Thermal Sensor trip event occurred based on a lower to higher temperature transition through the trip point. Software must write a 1 to clear this status bit.
0	<b>Auxiliary Low-to-High Event</b> — R/WC. 0 = No trip occurs. 1 = Indicates that an Auxiliary Thermal Sensor trip event occurred based on a lower to higher temperature transition through the trip point. Software must write a 1 to clear this status bit.

### 23.2.8 TSGPEN—Thermal Sensor General Purpose Event Enable Register

Offset Address: TBARB+0Dh                      Attribute: R/W  
 Default Value: 00h                              Size: 8 bit

This register controls the conditions that result in General Purpose Events to be signalled from Thermal Sensor trip events.

Bit	Description
7	<b>Auxiliary2 High-to-Low Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.
6	<b>Catastrophic High-to-Low Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.
5	<b>Hot High-to-Low Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.
4	<b>Auxiliary High-to-Low Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.
3	<b>Auxiliary2 Low-to-High Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.



Bit	Description
2	<b>Catastrophic Low-to-High Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.
1	<b>Hot Low-to-High Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.
0	<b>Auxiliary Low-to-High Enable</b> — R/W. 0 = Corresponding status bit does not result in General Purpose event. 1 = General purpose event is signaled when the corresponding status bit is set in the Thermal Error Status Register.

### 23.2.9 TSPC—Thermal Sensor Policy Control Register

Offset Address: TBARB+0Eh                      Attribute: R/W, RO  
 Default Value: 00h                              Size: 8 bit

Bit	Description
7	<b>Policy Lock-Down Bit</b> — R/W. 0 = This register can be programmed and modified. 1 = Prevents writes to this register and TSTTP.bits [31:16] (offset 04h).  <b>Note:</b> TSCO.bit 7 (offset 08h) and TSLOCK.bit2 (offset 83h) must also be 1 when this bit is set to 1. This bit is reset to 0 by a host partitioned reset (note that CF9 warm reset is a host partitioned reset). Writing a 0 to this bit has no effect.
6	<b>Catastrophic Power-Down Enable</b> — R/W. When set to 1, the power management logic unconditionally transitions to the S5 state when a catastrophic temperature is detected by the sensor.  <b>Note:</b> BIOS should set this bit to 1 to enable Catastrophic power-down.
5:4	Reserved
3	<b>SMI Enable on Auxiliary2 Thermal Sensor Trip</b> — R/W. 0 = Disables SMI# assertion for Auxiliary2 Thermal Sensor events. 1 = Enables SMI# assertions on Auxiliary2 Thermal Sensor events for either low-to-high or high-to-low events. (Both edges are enabled by this bit.)
2	<b>SMI Enable on Catastrophic Thermal Sensor Trip</b> — R/W. 0 = Disables SMI# assertion for Catastrophic Thermal Sensor events. 1 = Enables SMI# assertions on Catastrophic Thermal Sensor events for either low-to-high or high-to-low events. (Both edges are enabled by this bit.)
1	<b>SMI Enable on Hot Thermal Sensor Trip</b> — R/W. 0 = Disables SMI# assertion for Hot Thermal Sensor events. 1 = Enables SMI# assertions on Hot Thermal Sensor events for either low-to-high or high-to-low events. (Both edges are enabled by this bit.)
0	<b>SMI Enable on Auxiliary Thermal Sensor Trip</b> — R/W. 0 = Disables SMI# assertion for Auxiliary Thermal Sensor events. 1 = Enables SMI# assertions on Auxiliary Thermal Sensor events for either low-to-high or high-to-low events. (Both edges are enabled by this bit.)



### 23.2.10 PTA—PCH Temperature Adjust Register

Offset Address: TBARB+14h                      Attribute: R/W  
 Default Value: 0000h                      Size: 16 bit

Bit	Description
15:8	<b>PCH Slope (PSLOPE)</b> — R/W. This field contains the PCH slope for calculating PCH temperature. The bits are locked by AE.bit7 (offset 3Fh). <b>Note:</b> When thermal reporting is enabled, BIOS must write DEh into this field.
7:0	<b>Offset (POFFSET)</b> — R/W This field contains the PCH offset for calculating PCH temperature. The bits are locked by AE.bit7 (offset 3Fh). <b>Note:</b> When thermal reporting is enabled, BIOS must write 87h into this field.

### 23.2.11 TRC—Thermal Reporting Control Register

Offset Address: TBARB+1Ah                      Attribute: R/W  
 Default Value: 0000h                      Size: 16 bit

Bit	Description
15:13	Reserved
12	<b>SMBUS Thermal Data Reporting Enable</b> — R/W. 0 = Disable 1 = Enable
11:6	Reserved
5	<b>PCH Temperature Read Enable</b> — R/W. 0 = Disables reads of the PCH temperature. 1 = Enables reads of the PCH temperature.
4	Reserved - This bit must be set to 0.
3	<b>DIMM4 Temperature Read Enable</b> — R/W 0 = Disables reads of DIMM4 temperature. 1 = Enables reads of DIMM4 temperature.
2	<b>DIMM3 Temperature Read Enable</b> —R/W 0 = Disables reads of DIMM3 temperature. 1 = Enables reads of DIMM3 temperature.
1	<b>DIMM2 Temperature Read Enable</b> —R/W 0 = Disables reads of DIMM2 temperature. 1 = Enables reads of DIMM2 temperature.
0	<b>DIMM1 Temperature Read Enable</b> —R/W. 0 = Disables reads of DIMM1 temperature. 1 = Enables reads of DIMM1 temperature.



### 23.2.12 AE—Alert Enable Register

Offset Address: TBARB+3Fh                      Attribute: R/W  
 Default Value: 00h                              Size: 8 bit

Bit	Description
7	<b>Lock Enable</b> — R/W. 0 = Lock Disabled. 1 = Lock Enabled. This will lock this register (including this bit) This bit is reset by a Host Partitioned Reset. Note that CF9 warm reset is a Host Partitioned Reset.
6:5	Reserved
4	<b>PCH Alert Enable</b> — R/W. 0 = Alert Disabled 1 = Alert Enabled When this bit is set, it will assert the PCH's TEMP_ALERT# signal if the PCH temperature is outside the temperature limits. This bit is lockable by bit 7 in this register.
3	<b>DIMM 1-4 Alert Enable</b> — R/W. 0 = Alert Disabled 1 = Alert Enabled When this bit is set, it will assert the PCH's TEMP_ALERT# signal if DIMM1-4 temperature is outside of the temperature limits. Note that the actual DIMMs that are read and used for the alert are enabled in the TRC register (offset 1Ah). This bit is lockable by bit 7 in this register. <b>Note:</b> Same Upper and Lower limits for triggering TEMP_ALERT# are used for all enabled DIMMs in the system.
2:0	Reserved.

### 23.2.13 PTL—Processor Temperature Limit Register

Offset Address: TBARB+56h                      Attribute: R/W  
 Default Value: 0000h                              Size: 16 bit

Bit	Description
15:0	<b>Processor Temperature Limit</b> — R/W. These bits are programmed by BIOS

### 23.2.14 PTV—Processor Temperature Value Register

Offset Address: TBARB+60h                      Attribute: RO  
 Default Value: 0000h                              Size: 16 bit

Bit	Description
15:8	Reserved
7:0	<b>Processor Temperature Value</b> — RO. These bits contain the processor package temperature.

### 23.2.15 TT—Thermal Throttling Register

Offset Address: TBARB+6Ch                      Attribute: R/W  
 Default Value: 00000000h                      Size: 32 bit

Bit	Description
31:0	BIOS must program this field to 05201B16h



### 23.2.16 PHL—PCH Hot Level Register

Offset Address: TBARB+70h                      Attribute: R/W  
 Default Value: 00h                                Size: 8 bit

Bit	Description
7:0	<p>PCH Hot Level (PHL)— R/W.            When temperature reading in Thermal Sensor Thermometer Read (TSTR) is less than PHL programmed here, this will assert PCHHOT# (active low). (Note that TSTR reading of 00h is the hottest temperature and 7Fh is the lowest temperature.)            Default state for this register is PHL disabled (00h). For utilizing the PCHHOT# functionality, a soft strap has to be configured and BIOS programs this PHL value. Please refer to the Intel ME FW collaterals for information on enabling PCHHOT#.</p>

### 23.2.17 TSPIEN—Thermal Sensor PCI Interrupt Enable Register

Offset Address: TBARB+82h                      Attribute: R/W  
 Default Value: 00h                                Size: 8 bit

This register controls the conditions that result in PCI interrupts to be signalled from Thermal Sensor trip events. Software (device driver) needs to ensure that it can support PCI interrupts, even though BIOS may enable PCI interrupt capability through this register.

Bit	Description
7	<p><b>Auxiliary2 High-to-Low Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
6	<p><b>Catastrophic High-to-Low Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
5	<p><b>Hot High-to-Low Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
4	<p><b>Auxiliary High-to-Low Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
3	<p><b>Auxiliary2 Low-to-High Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
2	<p><b>Catastrophic Low-to-High Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
1	<p><b>Hot Low-to-High Enable</b>— R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>
0	<p><b>Auxiliary Low-to-High Enable</b> — R/W.            0 = Corresponding status bit does not result in PCI interrupt.            1 = PCI interrupt is signalled when the corresponding status bit is set in the Thermal Error Status Register.</p>



### 23.2.18 TSLOCK—Thermal Sensor Register Lock Control Register

Offset Address: TBARB+83h                      Attribute:              R/W  
 Default Value: 00h                                Size:                     8 bit

Bit	Description
7:3	Reserved
2	<b>Lock Control</b> — R/W. This bit can only be set to a 0 by a host-partitioned reset. Writing a 0 to this bit has no effect. 1 = Hot Trip programming interface (bits [15:8] of TSTTP) is locked. <b>Note:</b> CF9 warm reset is a host-partitioned reset.
1:0	Reserved

### 23.2.19 TTC2—Thermal Compares 2 Register

Offset Address: TBARB+ACH                      Attribute:              RO  
 Default Value: 00000000h                      Size:                     32 bit

Bits [31:16] of this register are set when an external controller (for example, EC) does the Write DIMM Temp Limits Command. Refer to [Section 5.22.2](#) for more info.

Bits [15:0] of this register are set when an external controller (for example, EC) does the Write PCH Temp Limits Command. Refer to [Section 5.22.2](#) for more information.

Bit	Description
31:24	<b>DIMM Thermal Compare Upper Limit</b> — RO. This is the upper limit used to compare against the DIMM's temperature. If the DIMM's temperature is greater than this value, then the PCH's alert GPIO is asserted if enabled.
23:16	<b>DIMM Thermal Compare Lower Limit</b> — RO. This is the lower limit used to compare against the DIMM's temperature. If the DIMM's temperature is lower than this value, then the PCH's alert GPIO is asserted if enabled.
15:8	<b>PCH Thermal Compare Upper Limit</b> — RO. This is the upper limit used to compare against the PCH temperature. If the PCH temperature is greater than this value, then the PCH's alert GPIO is asserted if enabled.
7:0	<b>PCH Thermal Compare Lower Limit</b> — RO. This is the lower limit used to compare against the PCH temperature. If the PCH temperature is lower than this value, then the PCH's alert GPIO is asserted if enabled.

### 23.2.20 DTV—DIMM Temperature Values Register

Offset Address: TBARB+B0h                      Attribute:              RO  
 Default Value: 00000000h                      Size:                     32 bit

Bit	Description
31:24	<b>DIMM3 Temperature</b> — RO The bits contain DIMM3 temperature data in absolute degrees Celsius. These bits are data byte 8 provided to the external controller when it does a read over SMLink1. Refer to <a href="#">Section 5.23.2</a> for more details
23:16	<b>DIMM2 Temperature</b> — RO The bits contain DIMM2 temperature data in absolute degrees Celsius. These bits are data byte 7 provided to the external controller when it does a read over SMLink1. Refer to <a href="#">Section 5.23.2</a> for more details.
15:8	<b>DIMM1 Temperature</b> — RO The bits contain DIMM1 temperature data in absolute degrees Celsius. These bits are data byte 6 provided to the external controller when it does a read over SMLink1. Refer to <a href="#">Section 5.23.2</a> for more details.





# 24 Intel® Management Engine Subsystem Registers (D22:F[3:0])

**Note:** The HEDT SKU Only supports D22:F0.

## 24.1 First Intel® Management Engine Interface (Intel MEI) Configuration Registers (Intel MEI 1 – D22:F0)

### 24.1.1 PCI Configuration Registers (Intel MEI 1– D22:F0)

**Table 24-1. Intel MEI 1 Configuration Registers Address Map (Intel MEI 1 –D22:F0) (Sheet 1 of 2)**

Offset	Mnemonic	Register Name	Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	RO
08h	RID	Revision Identification	See register description	RO
09h–0Bh	CC	Class Code	078000h	RO
0Ch	CLS	Cache Line Size	00h	RO
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HTYPE	Header Type	80h	RO
10h–17h	MEIO_MBAR	MEIO MMIO Base Address	00000000 00000004h	R/W, RO
2Ch–2Dh	SVID	Subsystem Vendor ID	0000h	R/WO
2Eh–2Fh	SID	Subsystem ID	0000h	R/WO
34h	CAPP	Capabilities List Pointer	50h	RO
3Ch–3Dh	INTR	Interrupt Information	0000h	R/W, RO
40h–43h	HFS	Host Firmware Status	00000000h	RO
44h–47h	ME_UMA	Intel ME UMA Register	8000000h	RO
48–4Bh	GMES	General Intel ME Status	00000000h	RO
4Ch–4Fh	H_GS	Host General Status	00000000h	RO
50h–51h	PID	PCI Power Management Capability ID	6001h	RO
52h–53h	PC	PCI Power Management Capabilities	C803h	RO
54h–55h	PMCS	PCI Power Management Control and Status	0008h	R/WC, R/W, RO
8Ch–8Dh	MID	Message Signaled Interrupt Identifiers	0005h	RO
8Eh–8Fh	MC	Message Signaled Interrupt Message Control	0080h	R/W, RO











### 24.1.1.15 GMES—General Intel® ME Status (Intel MEI 1—D22:F0)

Address Offset: 48h–4Bh                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:0	<b>General Intel ME Status (ME_GS)</b> — RO. This field is populated by Intel ME.

### 24.1.1.16 H\_GS—Host General Status (Intel MEI 1—D22:F0)

Address Offset: 4Ch–4Fh                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:0	<b>Host General Status(H_GS)</b> — RO. General Status of Host, this field is not used by Hardware

### 24.1.1.17 PID—PCI Power Management Capability ID Register (Intel MEI 1—D22:F0)

Address Offset: 50h–51h                      Attribute: RO  
 Default Value: 6001h                              Size: 16 bits

Bit	Description
15:8	<b>Next Capability (NEXT)</b> — RO. Value of 8Ch indicates the location of the next pointer.
7:0	<b>Capability ID (CID)</b> — RO. Indicates the linked list item is a PCI Power Management Register.

### 24.1.1.18 PC—PCI Power Management Capabilities Register (Intel MEI 1—D22:F0)

Address Offset: 52h–53h                      Attribute: RO  
 Default Value: C803h                              Size: 16 bits

Bit	Description
15:11	<b>PME_Support (PSUP)</b> — RO. This five-bit field indicates the power states in which the function may assert PME#. Intel MEI can assert PME# from any D-state except D1 or D2 which are not supported by Intel MEI.
10	<b>D2_Support (D2S)</b> — RO. The D2 state is not supported.
9	<b>D1_Support (D1S)</b> — RO. The D1 state is not supported.
8:6	<b>Aux_Current (AC)</b> — RO. Reports the maximum Suspend well current required when in the D3 <sub>cold</sub> state. Value of 00b is reported.
5	<b>Device Specific Initialization (DSI)</b> — RO. Indicates whether device-specific initialization is required.
4	Reserved
3	<b>PME Clock (PMEC)</b> — RO. Indicates that PCI clock is not required to generate PME#.
2:0	<b>Version (VS)</b> — RO. Hardwired to 011b to indicate support for <i>Revision 1.2 of the PCI Power Management Specification</i> .



### 24.1.1.19 PMCS—PCI Power Management Control and Status Register (Intel MEI 1—D22:F0)

Address Offset: 54h–55h Attribute: R/WC, R/W, RO  
 Default Value: 0008h Size: 16 bits

Bit	Description
15	<b>PME Status (PMES)</b> — R/WC. Bit is set by Intel ME Firmware. Host software clears bit by writing '1' to bit. This bit is reset when CL_RST0# asserted.
14:9	Reserved
8	<b>PME Enable (PMEE)</b> — R/W. This bit is read/write and is under the control of host SW. It does not directly have an effect on PME events. However, this bit is shadowed so Intel ME FW can monitor it. Intel ME FW will not cause the PMES bit to transition to '1' while the PMEE bit is '0', indicating that host SW had disabled PME. This bit is reset when PLTRST# asserted.
7:4	Reserved
3	<b>No_Soft_Reset (NSR)</b> — RO. This bit indicates that when the Intel MEI host controller is transitioning from D3 <sub>hot</sub> to D0 due to a power state command, it does not perform an internal reset. Configuration context is preserved.
2	Reserved
1:0	<b>Power State (PS)</b> — R/W. This field is used both to determine the current power state of the Intel MEI host controller and to set a new power state. The values are: 00 – D0 state (default) 11 – D3 <sub>hot</sub> state The D1 and D2 states are not supported for the Intel MEI host controller. When in the D3 <sub>hot</sub> state, the Intel MEI's configuration space is available, but the register memory spaces are not. Additionally, interrupts are blocked.

### 24.1.1.20 MID—Message Signaled Interrupt Identifiers Register (Intel MEI 1—D22:F0)

Address Offset: 8Ch–8Dh Attribute: RO  
 Default Value: 0005h Size: 16 bits

Bit	Description
15:8	<b>Next Pointer (NEXT)</b> — RO. Value of 00h indicates that this is the last item in the list.
7:0	<b>Capability ID (CID)</b> — RO. Capabilities ID indicates MSI.

### 24.1.1.21 MC—Message Signaled Interrupt Message Control Register (Intel MEI 1—D22:F0)

Address Offset: 8Eh–8Fh Attribute: R/W, RO  
 Default Value: 0080h Size: 16 bits

Bit	Description
15:8	Reserved.
7	<b>64 Bit Address Capable (C64)</b> — RO. Specifies that function is capable of generating 64-bit messages.
6:4	Multiple Message Enable (MME) — RO. Not implemented, hardwired to 0.
3:1	Multiple Message Capable (MMC) — RO. Not implemented, hardwired to 0.
0	<b>MSI Enable (MSIE)</b> — R/W. If set, MSI is enabled and traditional interrupt pins are not used to generate interrupts.







## 24.1.2 MEIO\_MBAR—MEI 1MMIO Registers (SRV/WS SKUs Only)

These MMIO registers are accessible starting at the Intel MEI 1 MMIO Base Address (MEIO\_MBAR) which gets programmed into D22:F0:Offset 10-17h. These registers are reset by PLTRST# unless otherwise noted.

Table 24-2. Intel MEI 1 MMIO Register Address Map

MEIO_MBAR + Offset	Mnemonic	Register Name	Default	Attribute
00–03h	H_CB_WW	Host Circular Buffer Write Window	00000000h	RO
04h–07h	H_CSR	Host Control Status	02000000h	R/W, R/WC, RO
08h–0Bh	ME_CB_RW	Intel ME Circular Buffer Read Window	FFFFFFFFh	RO
0Ch–0Fh	ME_CSR_HA	Intel ME Control Status Host Access	02000000h	RO

### 24.1.2.1 H\_CB\_WW—Host Circular Buffer Write Window Register (Intel MEI 1 MMIO Register)

Address Offset: MEIO\_MBAR + 00h      Attribute: RO  
 Default Value: 00000000h      Size: 32 bits

Bit	Description
31:0	<b>Host Circular Buffer Write Window Field (H_CB_WWF):</b> This bit field is for host to write into its circular buffer. The host's circular buffer is located at the Intel ME subsystem address specified in the Host CB Base Address register. This field is write only, reads will return arbitrary data. Writes to this register will increment the H_CBWP as long as ME_RDY is 1. When ME_RDY is 0, writes to this register have no effect and are not delivered to the H_CB, nor is H_CBWP incremented.

### 24.1.2.2 H\_CSR—Host Control Status Register (Intel MEI 1 MMIO Register)

Address Offset: MEIO\_MBAR + 04h      Attribute: RO, R/W, R/WC  
 Default Value: 02000000h      Size: 32 bits

Bit	Description
31:24	<b>Host Circular Buffer Depth (H_CBD) — RO.</b> This field indicates the maximum number of 32 bit entries available in the host circular buffer (H_CB). Host software uses this field along with the H_CBRP and H_CBWP fields to calculate the number of valid entries in the H_CB to read or # of entries available for write.  This field is implemented with a "1-hot" scheme. Only one bit will be set to a "1" at a time. Each bit position represents the value n of a buffer depth of (2^n). For example, when bit# 1 is 1, the buffer depth is 2; when bit#2 is 1, the buffer depth is 4, etc. The allowed buffer depth values are 2, 4, 8, 16, 32, 64 and 128.
23:16	<b>Host CB Write Pointer (H_CBWP) — RO.</b> Points to next location in the H_CB for host to write the data. Software uses this field along with H_CBRP and H_CBD fields to calculate the number of valid entries in the H_CB to read or number of entries available for write.
15:8	<b>Host CB Read Pointer (H_CBRP) — RO.</b> Points to next location in the H_CB where a valid data is available for embedded controller to read. Software uses this field along with H_CBWP and H_CBD fields to calculate the number of valid entries in the host CB to read or number of entries available for write.
7:5	Reserved <b>Note:</b> For writes to this register, these bits shall be written as 000b.
4	<b>Host Reset (H_RST) — R/W.</b> Setting this bit to 1 will initiate a Intel MEI reset sequence to get the circular buffers into a known good state for host and Intel ME communication. When this bit transitions from 0 to 1, hardware will clear the H_RDY and ME_RDY bits.
3	<b>Host Ready (H_RDY) — R/W.</b> This bit indicates that the host is ready to process messages.



Bit	Description
2	<b>Host Interrupt Generate (H_IG)</b> — R/W. Once message(s) are written into its CB, the host sets this bit to one for the HW to set the ME_IS bit in the ME_CSR and to generate an interrupt message to Intel ME. HW will send the interrupt message to Intel ME only if the ME_IE is enabled. HW then clears this bit to 0.
1	<b>Host Interrupt Status (H_IS)</b> — R/WC. Hardware sets this bit to 1 when ME_IG bit is set to 1. Host clears this bit to 0 by writing a 1 to this bit position. H_IE has no effect on this bit.
0	<b>Host Interrupt Enable (H_IE)</b> — R/W. Host sets this bit to 1 to enable the host interrupt (INTR# or MSI) to be asserted when H_IS is set to 1.

### 24.1.2.3 ME\_CB\_RW—ME Circular Buffer Read Window Register (Intel MEI 1 MMIO Register)

Address Offset: MEIO\_MBAR + 08h      Attribute: RO  
 Default Value: FFFFFFFFh      Size: 32 bits

Bit	Description
31:0	Intel ME Circular Buffer Read Window Field (ME_CB_RWF): This bit field is for host to read from the Intel ME Circular Buffer. The Intel ME's circular buffer is located at the Intel ME subsystem address specified in the Intel ME CB Base Address register. This field is read only, writes have no effect. Reads to this register will increment the ME_CBRP as long as ME_RDY is 1. When ME_RDY is 0, reads to this register have no effect, all 1s are returned, and ME_CBRP is not incremented.

### 24.1.2.4 Intel® ME\_CSR\_HA—ME Control Status Host Access Register (Intel MEI 1 MMIO Register)

Address Offset: MEIO\_MBAR + 0Ch      Attribute: RO  
 Default Value: 02000000h      Size: 32 bits

Bit	Description
31:24	Intel ME Circular Buffer Depth Host Read Access (ME_CBD_HRA) Host read only access to ME_CBD.
23:16	Intel ME CB Write Pointer Host Read Access (ME_CBWP_HRA) Host read only access to ME_CBWP.
15:8	Intel ME CB Read Pointer Host Read Access (ME_CBRP_HRA) Host read only access to ME_CBRP.
7:5	Reserved
4	Intel ME Reset Host Read Access (ME_RST_HRA) Host read access to ME_RST.
3	Intel ME Ready Host Read Access (ME_RDY_HRA) Host read access to ME_RDY.
2	Intel ME Interrupt Generate Host Read Access (ME_IG_HRA) Host read only access to ME_IG.
1	Intel ME Interrupt Status Host Read Access (ME_IS_HRA) Host read only access to ME_IS.
0	Intel ME Interrupt Enable Host Read Access (ME_IE_HRA) Host read only access to ME_IE.



## 24.2 Second Host Embedded Controller Interface (Intel MEI 2) Configuration Registers (Intel MEI 2—D22:F1)

### 24.2.1 PCI Configuration Registers (Intel MEI 2 — D22:F0)

Table 24-3. Intel MEI 2 Configuration Registers Address Map (Intel MEI 2—D22:F1)

Offset	Mnemonic	Register Name	Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	RO
08h	RID	Revision Identification	See register description	RO
09h–0Bh	CC	Class Code	0C8000h	RO
0Ch	CLS	Cache Line Size	00h	RO
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HTYPE	Header Type	80h	RO
10h–17h	MEI1_MBAR	MEI1 MMIO Base Address	00000000 00000004h	R/W, RO
2Ch–2Dh	SVID	Subsystem Vendor ID	0000h	R/WO
2Eh–2Fh	SID	Subsystem ID	0000h	R/WO
34h	CAPP	Capabilities List Pointer	50h	RO
3Ch–3Dh	INTR	Interrupt Information	0000h	R/W, RO
40h–43h	HFS	Host Firmware Status	00000000h	RO
48–4Bh	GMES	General Intel ME Status	00000000h	RO
4Ch–4Fh	H_GS	Host General Status	00000000h	RO
50h–51h	PID	PCI Power Management Capability ID	6001h	RO
52h–53h	PC	PCI Power Management Capabilities	C803h	RO
54h–55h	PMCS	PCI Power Management Control and Status	0008h	R/WC, R/W, RO
8Ch–8Dh	MID	Message Signaled Interrupt Identifiers	0005h	RO
8Eh–8Fh	MC	Message Signaled Interrupt Message Control	0080h	R/W, RO
90h–93h	MA	Message Signaled Interrupt Message Address	00000000h	R/W, RO
94h–97h	MUA	Message Signaled Interrupt Upper Address	00000000h	R/W
98h–99h	MD	Message Signaled Interrupt Message Data	0000h	R/W
A0h	HIDM	Intel MEI Interrupt Delivery Mode	00h	R/W
BC–BF	HERS	Intel MEI Extended Register Status	40000000h	RO
CO–DF	HER[1:8]	Intel MEI Extended Register DW[1:8]	00000000h	RO











### 24.2.1.17 PC—PCI Power Management Capabilities Register (Intel MEI 2—D22:F1)

Address Offset: 52h–53h Attribute: RO  
 Default Value: C803h Size: 16 bits

Bit	Description
15:11	<b>PME_Support (PSUP)</b> — RO. This five-bit field indicates the power states in which the function may assert PME#. Intel MEI can assert PME# from any D-state except D1 or D2 which are not supported by Intel MEI.
10	<b>D2_Support (D2S)</b> — RO. The D2 state is not supported.
9	<b>D1_Support (D1S)</b> — RO. The D1 state is not supported.
8:6	<b>Aux_Current (AC)</b> — RO. Reports the maximum Suspend well current required when in the D3 <sub>cold</sub> state. Value of 00b is reported.
5	<b>Device Specific Initialization (DSI)</b> — RO. Indicates whether device-specific initialization is required.
4	Reserved
3	<b>PME_Clock (PMEC)</b> — RO. Indicates that PCI clock is not required to generate PME#.
2:0	<b>Version (VS)</b> — RO. Hardwired to 011b to indicate support for <i>Revision 1.2 of the PCI Power Management Specification</i> .

### 24.2.1.18 PMCS—PCI Power Management Control and Status Register (Intel MEI 2—D22:F1)

Address Offset: 54h–55h Attribute: R/WC, R/W, RO  
 Default Value: 0008h Size: 16 bits

Bit	Description
15	<b>PME_Status (PMES)</b> — R/WC. Bit is set by Intel ME Firmware. Host software clears bit by writing '1' to bit. This bit is reset when CL_RST0# asserted.
14:9	Reserved
8	<b>PME_Enable (PMEE)</b> — R/W. This bit is read/write and is under the control of host SW. It does not directly have an effect on PME events. However, this bit is shadowed so Intel ME FW can monitor it. Intel ME FW will not cause the PMES bit to transition to '1' while the PMEE bit is '0', indicating that host SW had disabled PME. This bit is reset when PLTRST# asserted.
7:4	Reserved
3	<b>No_Soft_Reset (NSR)</b> — RO. This bit indicates that when the Intel MEI host controller is transitioning from D3 <sub>hot</sub> to D0 due to a power state command, it does not perform an internal reset. Configuration context is preserved.
2	Reserved
1:0	<b>Power State (PS)</b> — R/W. This field is used both to determine the current power state of the Intel MEI host controller and to set a new power state. The values are: 00 – D0 state (default) 11 – D3 <sub>hot</sub> state The D1 and D2 states are not supported for the Intel MEI host controller. When in the D3 <sub>hot</sub> state, the Intel MEI's configuration space is available, but the register memory spaces are not. Additionally, interrupts are blocked.









### 24.2.2.2 H\_CSR—Host Control Status (Intel MEI 2 MMIO Register)

Address Offset: MEI1\_MBAR + 04h      Attribute: RO, R/W, R/WC  
 Default Value: 02000000h      Size: 32 bits

Bit	Description
31:24	Host Circular Buffer Depth (H_CBD) — RO. This field indicates the maximum number of 32 bit entries available in the host circular buffer (H_CB). Host software uses this field along with the H_CBRP and H_CBWP fields to calculate the number of valid entries in the H_CB to read or # of entries available for write.  <b>Note:</b> This field is implemented with a "1-hot" scheme. Only one bit will be set to a "1" at a time. Each bit position represents the value n of a buffer depth of (2^n). For example, when bit#1 is 1, the buffer depth is 2; when bit#2 is 1, the buffer depth is 4, etc. The allowed buffer depth values are 2, 4, 8, 16, 32, 64 and 128.
23:16	<b>Host CB Write Pointer (H_CBWP)</b> — RO. Points to next location in the H_CB for host to write the data. Software uses this field along with H_CBRP and H_CBD fields to calculate the number of valid entries in the H_CB to read or number of entries available for write.
15:8	<b>Host CB Read Pointer (H_CBRP)</b> — RO. Points to next location in the H_CB where a valid data is available for embedded controller to read. Software uses this field along with H_CBWR and H_CBD fields to calculate the number of valid entries in the host CB to read or number of entries available for write.
7:5	Reserved <b>Note:</b> For writes to this register, these bits shall be written as 000b.
4	<b>Host Reset (H_RST)</b> — R/W. Setting this bit to 1 will initiate a Intel MEI reset sequence to get the circular buffers into a known good state for host and Intel ME communication. When this bit transitions from 0 to 1, hardware will clear the H_RDY and ME_RDY bits.
3	<b>Host Ready (H_RDY)</b> — R/W. This bit indicates that the host is ready to process messages.
2	<b>Host Interrupt Generate (H_IG)</b> — R/W. Once message(s) are written into its CB, the host sets this bit to one for the HW to set the ME_IS bit in the ME_CSR and to generate an interrupt message to Intel ME. HW will send the interrupt message to Intel ME only if the ME_IE is enabled. HW then clears this bit to 0.
1	<b>Host Interrupt Status (H_IS)</b> — R/WC. Hardware sets this bit to 1 when ME_IG bit is set to 1. Host clears this bit to 0 by writing a 1 to this bit position. H_IE has no effect on this bit.
0	<b>Host Interrupt Enable (H_IE)</b> — R/W. Host sets this bit to 1 to enable the host interrupt (INTR# or MSI) to be asserted when H_IS is set to 1.

### 24.2.2.3 ME\_CB\_RW—ME Circular Buffer Read Window (Intel MEI 2 MMIO Register)

Address Offset: MEI1\_MBAR + 08h      Attribute: RO  
 Default Value: FFFFFFFFh      Size: 32 bits

Bit	Description
31:0	Intel ME Circular Buffer Read Window Field (ME_CB_RWF): This bit field is for host to read from the Intel ME Circular Buffer. The Intel ME's circular buffer is located at the Intel ME subsystem address specified in the Intel ME CB Base Address register. This field is read only, writes have no effect. Reads to this register will increment the ME_CBRP as long as ME_RDY is 1. When ME_RDY is 0, reads to this register have no effect, all 1s are returned, and ME_CBRP is not incremented.



### 24.2.2.4 Intel® ME CSR\_HA—ME Control Status Host Access (Intel MEI 2 MMIO Register)

Address Offset: MEI1\_MBAR + 0Ch      Attribute: RO  
 Default Value: 02000000h      Size: 32 bits

Bit	Description
31:24	Intel ME Circular Buffer Depth Host Read Access (ME_CBD_HRA) Host read only access to ME_CBD.
23:16	Intel ME CB Write Pointer Host Read Access (ME_CBWP_HRA) Host read only access to ME_CBWP.
15:8	Intel ME CB Read Pointer Host Read Access (ME_CBRP_HRA) Host read only access to ME_CBRP.
7:5	Reserved
4	Intel ME Reset Host Read Access (ME_RST_HRA) Host read access to ME_RST.
3	Intel ME Ready Host Read Access (ME_RDY_HRA) Host read access to ME_RDY.
2	Intel ME Interrupt Generate Host Read Access (ME_IG_HRA) Host read only access to ME_IG.
1	Intel ME Interrupt Status Host Read Access (ME_IS_HRA) Host read only access to ME_IS.
0	Intel ME Interrupt Enable Host Read Access (ME_IE_HRA) Host read only access to ME_IE.

## 24.3 IDE Function for Remote Boot and Installations PT IDER Registers (IDER – D22:F2)

### 24.3.1 PCI Configuration Registers (IDER—D22:f2)

Table 24-5. IDE Function for remote boot and Installations PT IDER Register Address Map

Address Offset	Register Symbol	Register Name	Default Value	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	RO, R/W
06h–07h	PCISTS	PCI Status	00B0h	RO
08h	RID	Revision ID	See register description	RO
09–0Bh	CC	Class Codes	010185h	RO
0Ch	CLS	Cache Line Size	00h	RO
0Dh	PLT	Primary Latency Timer	00h	RO
10–13h	PCMDBA	Primary Command Block IO Bar	00000001h	RO, R/W
14–17h	PCTLBA	Primary Control Block Base Address	00000001h	RO, R/W
18–1Bh	SCMDBA	Secondary Command Block Base Address	00000001h	RO, R/W
1C–1Fh	SCTLBA	Secondary Control Block base Address	00000001h	RO, R/W







**24.3.1.11 SCTLBA—Secondary Control Block base Address Register (IDER—D22:F2)**

Address Offset: 1C–1Fh                      Attribute:                      RO, R/W  
 Default Value: 00000001h                      Size:                      32 bits

Bit	Description
31:16	Reserved
15:2	<b>Base Address (BAR)</b> —R/W. Base Address of the I/O space (4 consecutive I/O locations).
1	Reserved
0	<b>Resource Type Indicator (RTE)</b> —RO. This bit indicates a request for I/O space.

**24.3.1.12 LBAR—Legacy Bus Master Base Address Register (IDER—D22:F2)**

Address Offset: 20–23h                      Attribute:                      RO, R/W  
 Default Value: 00000001h                      Size:                      32 bits

Bit	Description
31:16	Reserved
15:4	<b>Base Address (BA)</b> —R/W. Base Address of the I/O space (16 consecutive I/O locations).
3:1	Reserved
0	<b>Resource Type Indicator (RTE)</b> —RO. This bit indicates a request for I/O space.

**24.3.1.13 SVID—Subsystem Vendor ID Register (IDER—D22:F2)**

Address Offset: 2Ch–2Dh                      Attribute:                      R/WO  
 Default Value: 0000h                      Size:                      16 bits

Bit	Description
15:0	<b>Subsystem Vendor ID (SSVID)</b> — R/WO. Indicates the sub-system vendor identifier. This field should be programmed by BIOS during boot-up. Once written, this register becomes Read Only. This field can only be cleared by PLTRST#.

**Note:** Register must be written as a DWord write with SID register.

**24.3.1.14 SID—Subsystem ID Register (IDER—D22:F2)**

Address Offset: 2Eh–2Fh                      Attribute:                      R/WO  
 Default Value: 8086h                      Size:                      16 bits

Bit	Description
15:0	<b>Subsystem ID (SSID)</b> — R/WO. Indicates the sub-system identifier. This field should be programmed by BIOS during boot-up. Once written, this register becomes Read Only. This field can only be cleared by PLTRST#.

**Note:** Register must be written as a DWord write with SVID register.



**24.3.1.15 CAPP—Capabilities List Pointer Register (IDER—D22:F2)**

Address Offset: 34h Attribute: RO  
 Default Value: C8h Size: 8 bits

Bit	Description
7:0	<b>Capability Pointer (CP)</b> — R/WO. This field indicates that the first capability pointer is offset C8h (the power management capability).

**24.3.1.16 INTR—Interrupt Information Register (IDER—D22:F2)**

Address Offset: 3C–3Dh Attribute: R/W, RO  
 Default Value: 0200h Size: 16 bits

Bit	Description
15:8	<b>Interrupt Pin (IPIN)</b> — RO. A value of 1h/2h/3h/4h indicates that this function implements legacy interrupt on INTA/INTB/INTC/INTD, respectively. The upper 4 bits are hardwired to 0 and the lower 4 bits are programmed by the IDERIP bits (RCBA+3124:bits 11:8).
7:0	<b>Interrupt Line (ILINE)</b> — R/W. The value written in this register indicates which input of the system interrupt controller, the device’s interrupt pin is connected to. This value is used by the OS and the device driver, and has no affect on the hardware.

**24.3.1.17 PID—PCI Power Management Capability ID Register (IDER—D22:F2)**

Address Offset: C8–C9h Attribute: RO  
 Default Value: D001h Size: 16 bits

Bit	Description
15:8	<b>Next Capability (NEXT)</b> — RO. Its value of D0h points to the MSI capability.
7:0	<b>Cap ID (CID)</b> — RO. This field indicates that this pointer is a PCI power management.

**24.3.1.18 PC—PCI Power Management Capabilities Register (IDER—D22:F2)**

Address Offset: CA–CBh Attribute: RO  
 Default Value: 0023h Size: 16 bits

Bit	Description
15:11	<b>PME_Support (PSUP)</b> — RO. This five-bit field indicates the power states in which the function may assert PME#. IDER can assert PME# from any D-state except D1 or D2 which are not supported by IDER.
10:9	Reserved
8:6	<b>Aux_Current (AC)</b> — RO. Reports the maximum Suspend well current required when in the D3 <sub>cold</sub> state. Value of 00b is reported.
5	<b>Device Specific Initialization (DSI)</b> — RO. Indicates whether device-specific initialization is required.









Bit	Description
7:0	<b>IDE Error Data (IDEED)</b> — R/W. Drive reflects its error/ diagnostic code to the host using this register at different times.

### 24.3.2.3 IDEERD0—IDE Error Register DEV0 (IDER—D22:F2)

Address Offset:	01h	Attribute:	R/W
Default Value:	00h	Size:	8 bits

This register implements the Error register of the command block of the IDE function. This register is read only by the HOST interface when DEV = 0 (master device).

Bit	Description
7:0	<b>IDE Error Data (IDEED)</b> — R/W. Drive reflects its error/ diagnostic code to the host using this register at different times.

### 24.3.2.4 IDEFR—IDE Features Register (IDER—D22:F2)

Address Offset:	01h	Attribute:	R/W
Default Value:	00h	Size:	8 bits

This register implements the Feature register of the command block of the IDE function. This register can be written only by the Host.

When the HOST reads the same address, it reads the Error register of Device 0 or Device 1 depending on the device\_select bit (bit 4 of the drive/head register).

Bit	Description
7:0	<b>IDE Feature Data (IDEFD)</b> — R/W. IDE drive specific data written by the Host











### 24.3.2.17 IDEHIR—IDE Drive/Head In Register (IDER—D22:F2)

Address Offset: 06h Attribute: R/W  
Default Value: 00h Size: 8 bits

This register implements the Drive/Head register of the command block of the IDE. This register can be written only by the Host. When host writes to this register, all 3 registers (IDEDHIR, IDEDHOR0, IDEDHOR1) are updated with the written value.

Host read to this register address reads the IDE Drive/Head Out Register (IDEDHOR0) if DEV=0 or IDEDHOR1 if DEV=1.

Bit 4 of this register is the DEV (master/slave) bit. This bit is cleared by hardware on IDE software reset (S\_RST toggles to '1') in addition to Host system reset and D3->D0 transition of the function.

Bit	Description
7:0	<b>IDE Drive/Head Data (IDEDHD)</b> — R/W. Register defines the drive number, head number and addressing mode.

### 24.3.2.18 IDDHOR1—IDE Drive Head Out Register Device 1 Register (IDER—D22:F2)

Address Offset: 06h Attribute: R/W  
Default Value: 00h Size: 8 bits

This register is read only by the Host. Host read to this Drive/head In register address reads the IDE Drive/Head Out Register (IDEDHOR0) if DEV=1

Bit 4 of this register is the DEV (master/slave) bit. This bit is cleared by hardware on IDE software reset (S\_RST toggles to '1') in addition to the Host system reset and D3 to D0 transition of the IDE function.

When the host writes to this address, it updates the value of the IDEHIR register.

Bit	Description
7:0	<b>IDE Drive Head Out DEV 1 (IDEDHO1)</b> — R/W. Drive/Head Out register of Slave device.

### 24.3.2.19 IDDHOR0—IDE Drive Head Out Register Device 0 Register (IDER—D22:F2)

Address Offset: 06h Attribute: R/W  
Default Value: 00h Size: 8 bits

This register is read only by the Host. Host read to this Drive/head In register address reads the IDE Drive/Head Out Register (IDEDHOR0) if DEV=0.

Bit 4 of this register is the DEV (master/slave) bit. This bit is cleared by hardware on IDE software reset (S\_RST toggles to 1) in addition to the Host system reset and D3 to D0 transition of the IDE function.

When the host writes to this address, it updates the value of the IDEHIR register.

Bit	Description
7:0	<b>IDE Drive Head Out DEV 0 (IDEDHO0)</b> — R/W. Drive/Head Out register of Master device.

















## 24.4 Serial Port for Remote Keyboard and Text (KT) Redirection (KT – D22:F3)

### 24.4.1 PCI Configuration Registers (KT – D22:F3)

**Table 24-9. Serial Port for Remote Keyboard and Text (KT) Redirection Register Address Map**

Address Offset	Register Symbol	Register Name	Default Value	Attribute
00–01h	VID	Vendor Identification	8086h	RO
02–03h	DID	Device Identification	See Register description	RO
04–05h	CMD	Command Register	0000h	RO, R/W
06–07h	STS	Device Status	00B0h	RO
08h	RID	Revision ID	See Register description	RO
09–0Bh	CC	Class Codes	070002h	RO
0Ch	CLS	Cache Line Size	00h	RO
10–13h	KTIBA	KT IO Block Base Address	00000001h	RO, R/W
14–17h	KT MBA	KT Memory Block Base Address	00000000h	RO, R/W
2C–2Fh	SS	Sub System Identifiers	00008086h	R/WO
30–33h	EROM	Expansion ROM Base Address	00000000h	RO
34h	CAP	Capabilities Pointer	C8h	RO
3C–3Dh	INTR	Interrupt Information	0200h	R/W, RO
C8–C9h	PID	PCI Power Management Capability ID	D001h	RO
CA–CBh	PC	PCI Power Management Capabilities	0023h	RO
CC–CFh	PMCS	PCI Power Management Control and Status	00000000h	RO, R/W
D0–D1h	MID	Message Signaled Interrupt Capability ID	0005h	RO
D2–D3h	MC	Message Signaled Interrupt Message Control	0080h	RO, R/W
D4–D7h	MA	Message Signaled Interrupt Message Address	00000000h	RO, R/W
D8–DBh	MAU	Message Signaled Interrupt Message Upper Address	00000000h	RO, R/W
DC–DDh	MD	Message Signaled Interrupt Message Data	0000h	R/W

#### 24.4.1.1 VID—Vendor Identification Register (KT–D22:F3)

Address Offset: 00–01h  
 Default Value: 8086h

Attribute: RO  
 Size: 16 bits

Bit	Description
15:0	<b>Vendor ID (VID)</b> — RO. This is a 16-bit value assigned by Intel.























# 25 PCI Express\* UpStream Configuration Registers (PCH) (SRV/WS SKUs only)

## 25.1 PCI Express\* Upstream Configuration Registers (PCI Express\*—D0:F0)

**Note:** Register address locations that are not shown in Table 25-1 and should be treated as Reserved.

**Table 25-1. PCI Express\* UpStream Configuration Registers Address Map (PCI Express\*—D0:F0) (Sheet 1 of 3)**

Offset	Mnemonic	Register Name	Function 0-5 Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09–0Bh	PI	Programming Interface Register	see description	RO
0Ch	CLS	Cache Line Size	00h	R/W
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	81h	RO
10–13h	EXPPTMBAR	Express Port Memory Base Address		RO, R/W
18h	PRINUM	Primary Bus Number	00h	R/W
19h	SECBUS	Secondary Bus Number	00h	R/W
1Ah	SUBBUS	Subordinate Bus Number	00h	R/w
1Bh	SLT	Secondary Latency Timer	00h	RO
1Chh	IOBL	I/O Base	00h	R/W, RO
1D	IOBL	I/O Limit Register	00h	R/W, RO
1Eh–1Fh	SSTS	Secondary Status Register	0000h	R/WC
20h–21h	MBL	Memory Base	0000h	R/W
22–23h	MBL	Memory Limit	0000h	R/W
24h–27h	PMBL	Prefetchable Memory Base	0001h	R/W, RO
26–27h	PMBL	Prefetchable Limit	0001h	R/W, RO
28h–2Bh	PMBU32	Prefetchable Memory Base Upper 32 Bits	00000000h	R/W
2Ch–2Fh	PMLU32	Prefetchable Memory Limit Upper 32 Bits	00000000h	R/W
34h	CAPP	Capabilities List Pointer	40h	RO
3Ch–3Dh	INTR	Interrupt Information	See bit description	R/W, RO
3Eh–3Fh	BCTRL	Bridge Control Register	0000h	R/W



**Table 25-1. PCI Express\* UpStream Configuration Registers Address Map (PCI Express\*—D0:F0) (Sheet 2 of 3)**

Offset	Mnemonic	Register Name	Function 0-5 Default	Attribute
40h–41h	CLIST	Capabilities List	8010	RO
42h–43h	XCAP	PCI Express* Capabilities	0052	R/WO, RO
44h–47h	DCAP	Device Capabilities	00008001h	RO
48h–49h	DCTL	Device Control	2000h	R/W, RO
4Ah–4Bh	DSTS	Device Status	0000h	R/WC, RO
4Ch–4Fh	LCAP	Link Capabilities	See bit description	R/W, RO, R/WO
50h–51h	LCTL	Link Control	0000h	R/W, WO, RO
52h–53h	LSTS	Link Status	See bit description	RO
64h–67h	DCAP2	Device Capabilities 2 Register	00000016h	RO
68h–69h	DCTL2	Device Control 2 Register	0000h	R/W, RO
6A–6B	DEVSTS2	Device Status 2 Register	0000	RO
70h–71h	LCTL2	Link Control 2 Register	0003h	RO
72–73h	LINKSTS2	Link Status 2	0000	RO
80h–81h	PMCAP	Power Management Capability	0001	RO
82h–83h	PMC	PCI Power Management Capabilities	C803	R/W, RO
84h–85h	PMCSR	PCI Power Management Control and Status	0004	R/W, RO
86h	PMBSE	Power Management Bridge Support Extensions	00	RO
88–89h	SVCAP	Subsystem Capability List	000D	RO
8C–8D	SVID	Subsystem Vendor Identification	8086	R/WO
8E–8F	SVID	Subsystem ID Register	0000	R/WO
100–103h	AERCAPHDR	Advanced Error Reporting Capabilities	see description	RO, R/WO
104h–107h	UES	Uncorrectable Error Status	See bit description	R/WC, RO
108h–10Bh	UEM	Uncorrectable Error Mask	00000000h	R/WO, RO
10Ch–10Fh	UEV	Uncorrectable Error Severity	See Description	RO
110h–113h	CES	Correctable Error Status	00000000h	R/WC
114h–117h	CEM	Correctable Error Mask	00000000h	R/WO
118h–11Bh	AECC	Advanced Error Capabilities and Control	00000000h	RO
11C–11Fh	AEHRDLOG1	Advanced Header Log	0000h	RO
120–123h	AEHRDLOG2	Advanced Header Log	0000h	RO
124–127h	AEHRDLOG3	Advanced Header Log	0000h	RO
128–12Bh	AEHRDLOG4	Advanced Header Log	0000h	RO
140h–143h	ERRUNCDETMASK	Uncorrectable Error Detect Mask	00000000h	R/WO, RO
144h–147h	ERRCORDETMASK	Correctable Error Detect Mask	00000000	R/WO, RO
150–153	MCSTCAPHDR	Multicast Extended Capability Header	00010012	RO, R/WO
154–155h	MCSTCAP	Multicast Capability Register	8000	RO
156–157	MCSTCTL	Multicast Control Register	0000	RO,R/W





### 25.1.3 PCICMD—PCI Command Register (PCI Express\*—D0:F0)

Address Offset: 04h–05h                      Attribute: R/W, RO  
 Default Value: 0000h                      Size: 16 bits

Bit	Description
15:11	Reserved
10	<p><b>Interrupt Disable</b> — R/W.</p> <p>This bit controls the ability of the PCI-Express Function to generate legacy INTx interrupt message</p> <p>0 = Internal INTx# messages are generated for PCI-Express errors detected internally in this port (for example, Malformed TLP, CRC error, completion time out etc.) or when receiving root port error messages or interrupts due to HP/PM events generated in legacy mode.</p> <p>1 = Internal INTx# messages will not be generated.</p> <p>This bit does not affect interrupt forwarding from devices connected to the root port. Assert_INTx and Deassert_INTx messages will still be forwarded to the internal interrupt controllers if this bit is set.</p>
9	Fast Back to Back Enable (FBE) — Reserved per the <i>PCI Express* Base Specification</i> .
8	<p><b>SERR# Enable (SEE)</b> — R/W.</p> <p>0 = Disable.</p> <p>1 = this bit enables reporting of Non-Fatal and Fatal errors detected by the Function of the Root Complex. For Type 1 Configuration Space headers, this bit controls transmission by the primary interface of ERR_NONFATAL and ERR_FATAL error messages forwarded from the secondary interface. ERR_COR messages are not affected by this bit...</p>
7	Wait Cycle Control (WCC) — Reserved per the <i>PCI Express* Base Specification</i> .
6	<p><b>Parity Error Response (PER)</b> — R/W.</p> <p>0 = Disable.</p> <p>1 = This bit controls the setting of the master data parity error bit in the Status Register in response to a parity error received on the PCI Express interface.</p>
5	VGA Palette Snoop (VPS) — Reserved per the <i>PCI Express* Base Specification</i> .
4	Postable Memory Write Enable (PMWE) — Reserved per the <i>PCI Express* Base Specification</i> .
3	Special Cycle Enable (SCE) — Reserved per the <i>PCI Express* Base Specification</i> .
2	<p><b>Bus Master Enable (BME)</b> — R/W.</p> <p>0 = Disable. memory and I/O requests received at the root port or downstream side of a switch port (secondary side) must be handled as an Unsupported Request (UR). For Non-posted requests, a completion with UR completion status must be returned</p> <p>1 = Enable. Allows the root port or switch to forward memory and I/O read or write requests in the upstream direction.</p>
1	<p><b>Memory Space Enable (MSE)</b> — R/W.</p> <p>0 = Disable. The function will handle memory transactions targeting the Function as an Unsupported Request (UR).</p> <p>1 = Enable. Allows memory cycles within the range specified by the memory base and limit registers can be forwarded.</p>
0	<p><b>I/O Space Enable (IOSE)</b> — R/W. This bit controls access to the I/O space registers.</p> <p>0 = Disable. The function will handle I/O transactions targeting the Function as an Unsupported Request (UR).</p> <p>1 = Enable. Allows I/O cycles within the range specified by the I/O base and limit registers can be forwarded.</p>





### 25.1.5 RID—Revision Identification Register (PCI Express\*—D0:F0)

Offset Address: 08h Attribute: RO  
Default Value: See bit description Size: 8 bits

Bit	Description
7:0	<b>Revision ID</b> — RO. Refer to the <i>Intel® C600 Series Chipset Specification Update</i> for the value of the Revision ID Register

### 25.1.6 PI—Programming Interface Register (PCI Express\*—D0:F0)

Address Offset: 09h Attribute: RO  
Default Value: 060400h Size: 24 bits

Bit	Description
23:16	<b>Base Class</b> — RO. 06h = This is a bridge device.
15:8	<b>SubClass Interface</b> — RO 04h = this device is a PCI to PCI bridge
7:0	<b>Programming Interface</b> — RO. 00h = No specific register level programming interface defined.

### 25.1.7 CLS—Cache Line Size Register (PCI Express\*—D0:F0)

Address Offset: 0Ch Attribute: R/W  
Default Value: 00h Size: 8 bits

Bit	Description
7:0	<b>Cache Line Size (CLS)</b> — R/W. This is read/write but contains no functionality, per the <i>PCI Express* Base Specification</i> .

### 25.1.8 PLT—Primary Latency Timer Register (PCI Express\*—D0:F0)

Address Offset: 0Dh Attribute: RO  
Default Value: 00h Size: 8 bits

Bit	Description
7:3	Latency Count. Reserved per the <i>PCI Express* Base Specification</i> .
2:0	Reserved









### 25.1.17 MEMBASE—Memory Base Register (PCI Express\*—D0:F0)

Address Offset: 20h–21h                      Attribute: R/W  
Default Value: 0000h                      Size: 16 bits

Bit	Description
15:4	<b>Memory Base (MB)</b> — R/W. These bits are compared with bits[31:20] of the incoming address to determine the lower 1 MB-aligned value (inclusive) of the range. The incoming address must be greater than or equal to this value.
3:0	Reserved

### 25.1.18 MEMLIMIT—Memory Limit Register (PCI Express\*—D0:F0)

Address Offset: 22h–23h                      Attribute: R/W  
Default Value: 0000h                      Size: 16 bits

Bit	Description
15:4	<b>Memory Limit (ML)</b> — R/W. These bits are compared with bits[31:20] of the incoming address to determine the upper 1 MB-aligned value (exclusive) of the range. The incoming address must be less than this value.
3:0	Reserved

### 25.1.19 PFBASE—Prefetchable Memory Base (PCI Express\*—D0:F0)

Address Offset: 24h–25h                      Attribute: R/W, RO  
Default Value: 0001h                      Size: 16 bits

Bit	Description
15:4	<b>Prefetchable Memory Base (PMB)</b> — R/W. These bits are compared with bits[31:20] of the incoming address to determine the lower 1 MB-aligned value (inclusive) of the range. The incoming address must be greater than or equal to this value.
3:0	<b>64-bit Indicator (I64B)</b> — RO 0 = 32-bit Prefetchable Memory addressing. 1 = 64-bit Prefetchable Memory addressing. This field indicates that 64-bit addressing is supported for the limit.

### 25.1.20 PFLIMIT—Prefetchable Limit Register (PCI Express\*—D0:F0)

Address Offset: 26h–27h                      Attribute: R/W, RO  
Default Value: 0001h                      Size: 16 bits

Bit	Description
15:4	<b>Prefetchable Memory Limit (PML)</b> — R/W. These bits are compared with bits[31:20] of the incoming address to determine the upper 1 MB-aligned value (inclusive) of the range. The incoming address must be less than this value.
3:0	<b>64-bit Indicator (I64L)</b> — RO. Indicates support for 64-bit addressing





## 25.1.25 BCTRL—Bridge Control Register (PCI Express\*—D0:F0)

Address Offset: 3Eh–3Fh  
 Default Value: 0000h

Attribute: R/W  
 Size: 16 bits

Bit	Description
15:12	Reserved
11	Discard Timer SERR# Enable (DTSE): Reserved per <i>PCI Express* Base Specification</i> , Revision 2.1
10	Discard Timer Status (DTS): Reserved per <i>PCI Express* Base Specification</i> , Revision 2.1.
9	Secondary Discard Timer (SDT): Reserved per <i>PCI Express* Base Specification</i> , Revision 2.1.
8	Primary Discard Timer (PDT): Reserved per <i>PCI Express* Base Specification</i> , Revision 2.1.
7	Fast Back to Back Enable (FBE): Reserved per <i>PCI Express* Base Specification</i> , Revision 2.1.
6	<p><b>Secondary Bus Reset (SBR)</b> — R/W.</p> <p>Setting this bit triggers a hot reset on the downstream link for the corresponding PCI Express* port and the PCI Express* hierarchy domain subordinate to the port. Software must ensure a minimum reset duration of 1 us as defined in the <i>PCI Local Bus Specification</i>, Revision 3.0. Hardware will continue to maintain the hot reset state as long as the SBR bit is set.</p> <p>For Root Ports/switch, it is recommended that software assert this field for a minimum of 2 ms to ensure that all downstream links enters hot reset state.</p> <p>For a Switch, the following must cause a hot reset to be sent on all Downstream Ports:</p> <ul style="list-style-type: none"> <li>Setting the Secondary Bus Reset bit of the Bridge Control register associated with the Upstream Port</li> <li>The Data Link Layer of the Upstream Port reporting DL_Down status 30</li> <li>Receiving a hot reset on the Upstream Port</li> </ul> <p>A secondary bus reset will not reset any register of a Type 1 configuration space header function.</p>
5	Master Abort Mode (MAM): Reserved per Express specification.
4	<p><b>VGA 16-Bit Decode (V16)</b> — R/W.</p> <p>This bit enables the bridge to provide 16-bit decoding of VGA I/O address precluding the decoding of VGA alias addresses every 1 KB. This bit requires the VGA enable bit (bit 3 of this register) to be set to 1.</p> <p>0 = execute 10-bit address decode on VGA I/O accesses          1 = execute 16-bit address decode on VGA I/O accesses</p>
3	<p><b>VGA Enable (VE)</b>— R/W.</p> <p>0 = The ranges below will not be claimed off the backbone by the root port.          1 = This bit modifies the response to VGA-compatible addresses. When set to 1b, the bridge positively decodes and forwards the following transactions from primary side to secondary side regardless of the value of the I/O base and limit registers. The transactions are qualified by the memory enable and I/O enable in the command register.</p> <p><b>Memory addresses:</b> 000A 0000h–000B FFFFh  <b>I/O addresses:</b> 3B0h–3BBh and 3C0h–3DFh in first 64 KB of I/O address space (Inclusive of ISA address aliases when IO address bits[15:10] are not decoded)</p> <p>The following ranges will be claimed off the backbone by the root port:</p> <ul style="list-style-type: none"> <li>Memory ranges A0000h–BFFFFh</li> <li>I/O ranges 3B0h – 3BBh and 3C0h – 3DFh, and all aliases of bits 15:10 in any combination of 1s</li> </ul>





### 25.1.28 DCAP—Device Capabilities Register (PCI Express\*—D0:F0)

Address Offset: 44h–47h                      Attribute: RO  
 Default Value: 00008001h                      Size: 32 bits

Bit	Description
31:28	Reserved
27:26	<b>Captured Slot Power Limit Scale (CSPS)</b> — RO-V In combination with the Slot Power Limit value (bits[25:18]), this field specifies the upper limit of the power supplied by slot. The power limit (in Watts) is calculated by multiplying the value in this field by the value in the Slot Power Limit Value field. This value is set by the Set_Slot_Power_Limit message.
25:18	<b>Captured Slot Power Limit Value (CSPV)</b> — RO-V In combination with the Slot Power Limit Scale value (bits[27:26]), this field specifies the upper limit of the power supplied by slot. The power limit (in Watts) is calculated by multiplying the value in this field by the value in the Slot Power Limit Scale field. This value is set by the Set_Slot_Power_Limit message.
17:16	Reserved
15	<b>Role Based Error Reporting (RBER)</b> — RO. Indicates that this device implements the functionality defined in the Error Reporting ECN as required by the PCI Express* 1.1 spec.
14:12	Reserved
11:9	<b>Endpoint L1 Acceptable Latency (E1AL)</b> — RO. This field is reserved with a setting of 000b for devices other than Endpoints, per the PCI Express* 1.1 Spec.
8:6	<b>Endpoint L0s Acceptable Latency (E0AL)</b> — RO. This field is reserved with a setting of 000b for devices other than Endpoints, per the PCI Express* 1.1 Spec.
5	<b>Extended Tag Field Supported (ETFS)</b> — RO. Indicates that a 5-bit tag fields are supported.
4:3	<b>Phantom Functions Supported (PFS)</b> — RO. No phantom functions supported.
2:0	<b>Max Payload Size Supported (MPS)</b> — RO. Indicates the maximum payload size supported is 256B.

### 25.1.29 DCTL—Device Control Register (PCI Express\*—D0:F0)

Address Offset: 48h–49h                      Attribute: R/W, RO  
 Default Value: 2000h                      Size: 16 bits

Bit	Description
15	Reserved
14:12	<b>Max Read Request Size (MRRS)</b> — R/W. 512Bytes is the maximum read request size.
11	<b>Enable No Snoop (ENS)</b> — RO. Not supported. The root port will never issue non-snoop requests.
10	<b>Aux Power PM Enable (APME)</b> — RO. Not supported, hardwired to 0.
9	<b>Phantom Functions Enable (PFE)</b> — RO. Not supported.
8	<b>Extended Tag Field Enable (ETFE)</b> — RO. Not supported.
7:5	<b>Max Payload Size (MPS)</b> — R/W. 128 bytes is the default, but 256 is also supported. Not other sizes are supported.
4	<b>Enable Relaxed Ordering (ERO)</b> — RO. Not supported.
3	<b>Unsupported Request Reporting Enable (URE)</b> — R/W. 0 = The root port will ignore unsupported request errors. 1 = Allows signaling ERR_NONFATAL, ERR_FATAL, or ERR_COR to the Root Control register when detecting an unmasked Unsupported Request (UR). An ERR_COR is signaled when a unmasked Advisory Non-Fatal UR is received. An ERR_FATAL, ERR_or NONFATAL, is sent to the Root Control Register when an uncorrectable non-Advisory UR is received with the severity set by the Uncorrectable Error Severity register.





Bit	Description
20	<b>Data Link Layer Active Error Reporting Capable (DLLERC):</b> RO. Not supported, hardwired to 0
19	<b>Surprise Link Down Error Reporting Capable (SLDERC):</b> RO. Hardwired to 0
18	<b>Clock Power Management Capable (CPMC):</b> RO. Hardwired to 0
17:15	<b>L1 Exit Latency (EL1)</b> — R/WL. Set to 010b to indicate an exit latency of 2 $\mu$ s to 4 $\mu$ s.
14:12	<b>L0s Exit Latency (ELO)</b> — R/WL. Set to 100 to indicate an exit latency of 512 ns to less than 1 $\mu$ s
11:10	<b>Active State Link PM Support (APMS)</b> — R/WL. Indicates what level of active state link power management is supported on the root port. Default is both L1 and L0s supported
9:4	<b>Maximum Link Width (MLW)</b> — RO default is 04, indicating the maximum width is a x4.
3:1	Reserved
0	<b>Maximum Link Speed (MLS)</b> — RO. 1b: 2.5 Gb/s link speed is supported

### 25.1.32 LCTL—Link Control Register (PCI Express\*—D:F0)

Address Offset: 50h–51h  
Default Value: 0000h

Attribute: R/W, RO  
Size: 16 bits

Bit	Description
15:12	Reserved
11	<b>Link Autonomous Bandwidth Interrupt Enable (LABIE):</b> RO. Hardwired to 0 as not applicable
10	<b>Link Bandwidth Management Interrupt Enable (LBMIE):</b> RO. Hardwired to 0 as not applicable
9	<b>Hardware Autonomous Width Disable</b> – RO. Components that do not implement the ability such as (Upstream Ports, Virtual Switch Ports) to autonomously change link width are permitted to hardwire this bit to 0b
8	Reserved
7	<b>Extended Synch (ES)</b> — R/W. 0 = Extended synch disabled. 1 = Forces extended transmission of FTS ordered sets in FTS and extra TS2 at exit from L1 prior to entering L0.
6	<b>Common Clock Configuration (CCC)</b> — R/W. 0 = The PCH and device are not using a common reference clock. 1 = The PCH and device are operating with a distributed common reference clock. After changing the value in this bit in both components on a link, software must trigger the link to retrain by writing a 1b to the Retrain Link bit of the Downstream Port.
5	<b>Retrain Link (RL)</b> — RO. Hardwired to 0. For the upstream port or virtual switch port, it is Read-only
4	<b>Link Disable (LD)</b> — RO. hardwired to 0. This bit is reserved on Endpoints, PCI Express* to PCI/PCI-X bridges, and Upstream Ports of Switches





## 25.1.34 DCAP2—Device Capabilities 2 Register (PCI Express\*—D0:F0)

Address Offset: 64h–67h                      Attribute: RO  
 Default Value: 00000000h                    Size: 32 bits

Bit	Description
31:5	Reserved
19:18	<b>OBFF Supported (OBFFS)</b> 00b = OBFF Not Supported Applicable only to Root Ports, Switch Ports, and Endpoints that support this capability. Must be 00b for other function types.
17:14	Reserved
13:12	<b>TPH Completer Supported (TPHCS)</b> Applicable only to Root Ports and Endpoints. Must be 00b for other function types
11	<b>LTBWR Mechanism Supported (LTBWRMS)</b> This bit must be hardwired to 0b for function that do not implement this capability.
10	<b>No RO-enabled PR-PR Passing (NROEPRPASS)</b> Hardwired to 0b. This bit applies only for Switches and RCs that support peer-to-peer traffic between ports
9	<b>AD128 CAS Completer Supported (AD128ACS)</b> hardwired to 0b
8	<b>AD64-bit AtomicOp Completer Supported (AD64ACS)</b> Hardwired to 0b
7	<b>AD32 bit AtomicOp Completer Supported (AD32ACS)</b> Hardwired to 0b
6	<b>AtomicOp Routing Supported (ARS) – R/WO</b> Default is 0b
5	<b>Alternative RID Interpretation Capable (ARI)</b> Does not apply to endpoints and upstream ports and is hardwired to 0.
4	<b>Completion Timeout Disable Supported (CTDS) – RO.</b> Hardwired to 0.
3:0	<b>Completion Timeout Ranges Supported (CTRS) – RO.</b> Hardwired to 0000b













## 25.1.47 UES—Uncorrectable Error Status Register (PCI Express\*—D0:F0)

Address Offset: 104h–107h                      Attribute: R/WC, RO  
 Default Value: 00000000h                      Size: 32 bits

This register maintains its state through a platform reset. It loses its state upon suspend.

Bit	Description
31:25	Reserved, hardwired to 0
24	<b>Atomic Egress Blocked Error (AEBE) — R/WC</b> This bit is set whenever an Atomic OP TLP is blocked on any egress port.
23	<b>MC Blocked TLP Error (MCE) — R/WC</b> This bit is set whenever a Multicast TLP is blocked.
22	<b>Uncorrectable Internal Error (UIE) — R/WC</b> This bit is set whenever an uncorrectable internal error is detected.
21	<b>ACS Violation Error (ACSE) — RO</b> This bit is set whenever an ACS violation is detected by the PCI Express* port.
20	<b>Unsupported Request Error Status (URE) — R/WC.</b> Indicates an unsupported request was received.
19	ECRC Error Status (EE) — RO. ECRC is not supported.
18	<b>Malformed TLP Status (MT) — R/WC.</b> Indicates a malformed TLP was received.
17	<b>Receiver Overflow Status (RO) — R/WC.</b> Indicates a receiver overflow occurred.
16	<b>Unexpected Completion Status (UC) — R/WC.</b> This bit is set whenever a completion is received with a requestor ID that does not match side A or side B, or when a completion is received with a matching requestor ID but an unexpected tag field. Header logging is performed.
15	<b>Completion Abort Status (CA) — R/WC.</b> The bridge sets this bit and logs the header associated with the request when the configuration unit signals a completer abort.
14	<b>Completion Timeout Status (CT) — R/WC.</b> For Switch Ports, this bit is set if the Switch Port issues Non-Posted Requests on its own behalf (vs. only forwarding such as Requests generated by other devices).
13	<b>Flow Control Error (FCE) — R/WC</b> This bit is set when a flow control protocol error is detected.
12	<b>Poisoned TLP Error (PTLPE) — R/WC</b> This bit is set and the bridge logs the header when a poisoned TLP is received from PCI Express.
11:6	Reserved
5	<b>Surprise Link Down Error (SLDE) — RO.</b> This bit is set when a surprise link down error is detected. This bit does not apply to upstream ports so it is hardwired to 0
4	<b>Data Link Protocol Error Status (DLPE) — R/WC.</b> Indicates a data link protocol error occurred.
3:1	Reserved
0	<b>Training Error Status (TE) — RO.</b> Training Errors not supported.





Bit	Description
19	<b>ECRC Error Severity (EE)</b> — RO. ECRC is not supported.
18	<b>Malformed TLP Severity (MT)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
17	<b>Receiver Overflow Severity (RO)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
16	<b>Unexpected Completion Error Severity (UCES)</b> 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
15	<b>Completion Abort Severity (CA)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
14	<b>Completion Timeout Error Severity (CTES)</b> — RO. Hardwired to 0
13	<b>Flow Control Protocol Error Severity (FCPE)</b> 0 = Error considered non-fatal. 1 = Error is fatal (Default).
12	<b>Poisoned TLP Severity (PT)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
11:6	Reserved
5	<b>Surprise Link Down Severity (SLDES)</b> — RO. Hardwired to 0.
4	<b>Data Link Protocol Error Severity (DLPE)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
3:0	Reserved

### 25.1.50 CES—Correctable Error Status Register (PCI Express\*—D0:F0)

Address Offset: 110h–113h  
Default Value: 00000000h

Attribute: R/WC  
Size: 32 bits

Bit	Description
31:16	Reserved
15	<b>Header Log Overflow Error (HLOE)</b> — R/WC. Indicates a Header Log Overflow occurred
14	<b>Correctable Internal Error (CIE)</b> — R/WC. Indicates a correctable Internal Error occurred
13	<b>Advisory Non-Fatal Error Status (ANFES)</b> — R/WC. 0 = Advisory Non-Fatal Error did not occur. 1 = Advisory Non-Fatal Error did occur.
12	<b>Replay Timer Timeout Status (RTT)</b> — R/WC. Indicates the replay timer timed out.
11:9	Reserved
8	<b>Replay Number Rollover Status (RNR)</b> — R/WC. Indicates the replay number rolled over.
7	<b>Bad DLLP Status (BD)</b> — R/WC. Indicates CRC Error on a DLLP was received.
6	<b>Bad TLP Status (BT)</b> — R/WC. Indicates a CRC error on a TLP was received.
5:1	Reserved
0	<b>Receiver Error Status (RE)</b> — R/WC. Indicates a receiver error occurred.





### 25.1.53 AEHRDLOG [1–4]— Advanced Error Header Log (PCI Express\*—D0:F0)

Address Offset: 11Ch–128hFh      Attribute: RRO  
 Default Value: 0000h              Size: 32 bits

Bit	Description
31:0	<b>TLP Header Log (TLPHDRLOG)</b> As soon as an error is logged in this register, it remains locked for further error-logging until the software clears the status bit that caused the header log (in other words, until the error pointer is re-armed for logging again).

### 25.1.54 ERRUNCDETMSK— Uncorrectable Error Detect Mask Register (PCI Express\*—D0:F0)

Address Offset: 140h–143h      Attribute: R/WC, RO  
 Default Value: 00000000h      Size: 32 bits

Bit	Description
31:25	<b>Reserved</b>
24	<b>AtomicOp Egress Blocked Error Detect Mask (AEBEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
23	<b>MC Blocked TLP Error Detect Mask (MCEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
22	<b>Uncorrectable Internal Error Detect Mask (UIEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
21	<b>ACS Violation Error Detect Mask (ACSEDM)</b> RO - hardwired to 0
20	<b>Unsupported Request Error Detect Mask (URED M) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
19	<b>ECRC Check Error Mask (ECRCEDM). Not supported</b> RO - hardwired to 0
18	<b>Malformed TLP Error Detect Mask (MTLPEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
17	<b>Receiver Overflow Error Detect Mask (ROEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
16	<b>Unexpected Completion Error Detect Mask (UCEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
15	<b>Completer Abort Error Detect Mask (CAEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
14	<b>Completion Timeout Error Detect Mask (CTEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
13	<b>Flow Control Error Detect Mask (FCEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled





### 25.1.56 MCSTCAPHDR—Multicast Extended Capability Header (PCI Express\*—D0:F0)

Address Offset: 150–153h                      Attribute: RO, R/WO  
Default Value: 00010012h                      Size: 32 bits

Bit	Description
31:20	<b>Next Capability Offset (NCO) – R/WL</b> Contains the offset of the next structure in the Extended Capabilities list for endpoint.
19:16	<b>Capability Version (CV) – RO</b> Indicates the version of the Capability structure present.
15:0	<b>Extended Capability ID (EXCAPID) – RO</b> Identifies the function as Advanced Error Reporting capable.

### 25.1.57 MCSTCAP—Multicast Capability Register (PCI Express\*—D0:F0)

Address Offset: 154–155h                      Attribute: RO  
Default Value: 8000h                              Size: 16 bits

Bit	Description
15	<b>MC Overlay Supported (MCOS)</b> If set to 1b, this bit indicates that the MC Overlay mechanism is supported.
14	<b>MC ECRC Regeneration supported (MCERS)</b> Set to 0b, ECRC regeneration is not supported.
13:6	Reserved
5:0	<b>MC Max Group (MCMG)</b> This field indicates the maximum number of Multicast Groups that the component supports, encoded as M-1. A value of 00h indicates that one multicast Group is supported.

### 25.1.58 MCSTCTL—Multicast Control Register (PCI Express\*—D0:F0)

Address Offset: 156–157h                      Attribute: RO, R/W  
Default Value: 0000h                              Size: 16 bits

Bit	Description
15	<b>MC Enable (MCEN) – R/W</b> 0 = Indicates the Multicast Capability is NOT enabled for the component 1 = Indicates the Multicast Capability is enabled for the component.
14:6	Reserved. RO
5:0	<b>MC Max Group (MCMG) – R/W</b> This field indicates the number of Multicast Groups configured for use, encoded as N-1. A value of 00h indicates that one Multicast Group is configured for use. Behavior is undefined if value exceeds MC Max Group. This parameter indirectly defines the upper limit of the Multicast address range. This field is ignored if MC Enable is Clear.





### 25.1.63 MCSTBLKALL—Multicast Block All Register (PCI Express\*—D0:F0)

Address Offset: 168–16Bh      Attribute: RO, R/W  
Default Value: 00000000h      Size: 32 bits

Bit	Description
31:1	<b>Reserved. RO</b>
0	<b>MC Block All (MCBA) — R/W</b> For each bit that is set, this function is blocked from sending TLPs to the associated Multicast Group. Bits above MC Number Groups are ignored by hardware.

### 25.1.64 MCSTBLKALL2—Multicast Block All 2 Register (PCI Express\*—D0:F0)

Address Offset: 16C–16Fh      Attribute: RO  
Default Value: 00000000h      Size: 32 bits

Bit	Description
31:0	<b>Reserved. RO</b>

### 25.1.65 MCSTBLKUT—Multicast Block Untranslated Register (PCI Express\*—D0:F0)

Address Offset: 170–173h      Attribute: RO  
Default Value: 00000000h      Size: 32 bits

Bit	Description
31:1	<b>Reserved. RO</b>
0	<b>MC Block Untranslated (MCBUT) — R/W</b> For each bit that is Set, this device/function is blocked from sending TLPs containing Untranslated Addresses to the associated MCG. Bits above MC_Num_Group (See MCCAP.MCMG) are ignored by hardware.

### 25.1.66 MCSTBLKUT2—Multicast Block Untranslated 2 Register (PCI Express\*—D0:F0)

Address Offset: 174–177h      Attribute: RO  
Default Value: 00000000h      Size: 32 bits

Bit	Description
31:0	<b>Reserved. RO</b>





***PCI Express\* UpStream Configuration Registers (PCH) (SRV/WS SKUs only)***



# 26 PCI Express\* Virtual Root Port/ Virtual Switch Port Configuration Registers (SRV/WS SKUs Only)

## 26.1 PCI Express\* Virtual Root Port/ Virtual Switch Port Configuration Registers (PCI Express\*—B0:D17:F0/Bn+1:D8:F0)

The Virtual root port and virtual switch port are the same port, but configured somewhat differently based upon how PCH is configured. If the PCH has an upstream PCIe port, then this port becomes a virtual switch port that connects the SCUs and MFDs downstream to the Upstream port. If there is no upstream port, then this port becomes a virtual root port and connects those devices downstream with the backbone of the PCH that routes the data upstream using the DMI2 bus.

## 26.2 PCI Express\* Virtual Root Port/ Virtual Switch Port Configuration Registers (PCI Express\*—B0:D17:F0/Bn+1:D8:F0)

**Note:** Register address locations that are not shown in [Table 20-1](#) and should be treated as Reserved.

Offset	Mnemonic	Register Name	Function 0–5 Default	Attribute
00h–01h	VID	Vendor Identification	8086h	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0010h	R/WC, RO
08h	RID	Revision Identification	See register description	RO
09–0Bh	PI	Programming Interface Register	see description	RO
0Ch	CLS	Cache Line Size	00h	R/W
0Dh	PLT	Primary Latency Timer	00h	RO
0Eh	HEADTYP	Header Type	81h	RO
18h	PRINUM	Primary Bus Number	00h	R/W
19h	SECBUS	Secondary Bus Number	00h	R/W
1Ah	SUBBUS	Subordinate Bus Number	00h	R/w
1Chh	IOBL	I/O Base	00h	R/W, RO
1D	IOBL	I/O Limit Register	00h	R/W, RO
1Eh–1Fh	SSTS	Secondary Status Register	0000h	R/WC
20h–21h	MBL	Memory Base	0000h	R/W
22–23h	MBL	Memory Limit	0000h	R/W



Offset	Mnemonic	Register Name	Function 0-5 Default	Attribute
24h-25h	PMBL	Prefetchable Memory Base	0001h	R/W, RO
26-27h	PMBL	Prefetchable Limit	0001h	R/W, RO
28h-2Bh	PMBU32	Prefetchable Memory Base Upper 32 Bits	00000000h	R/W
2Ch-2Fh	PMLU32	Prefetchable Memory Limit Upper 32 Bits	00000000h	R/W
34h	CAPP	Capabilities List Pointer	40h	RO
3Ch-3Dh	INTR	Interrupt Information	See bit description	R/W, RO
3Eh-3Fh	BCTRL	Bridge Control Register	0000h	R/W
40h-41h	CLIST	Capabilities List	8010	RO
42h-43h	XCAP	PCI Express* Capabilities	See Description	R/WO, RO
44h-47h	DCAP	Device Capabilities	00008001h	RO
48h-49h	DCTL	Device Control	2000h	R/W, RO
4Ah-4Bh	DSTS	Device Status	0000h	R/WC, RO
4Ch-4Fh	LCAP	Link Capabilities	See bit description	R/W, RO, R/WO
50h-51h	LCTL	Link Control	0000h	R/W, WO, RO
52h-53h	LSTS	Link Status	See bit description	RO
5C-5Dh	ROOTCTL	Root control	00000000	RO, R/W
5E-FFh	ROOTCAP	Root Capabilities	0000	RO
60-63h	ROOTSTS	Root Status	00000000	RO, R/WC
64h-67h	DCAP2	Device Capabilities 2 Register	00000016h	RO
68h-69h	DCTL2	Device Control 2 Register	0000h	R/W, RO
6A-6Bh	DEVSTS2	Device Status 2 Register	0000	RO
70h-71h	LCTL2	Link Control 2 Register	0003h	RO
72-73h	LINKSTS2	Link Status 2	0000	RO
80h-81h	PMCAP	Power Management Capability	0001	RO
82h-83h	PMC	PCI Power Management Capabilities	C803	R/W, RO
84h-85h	PMCSR	PCI Power Management Control and Status	0004	R/W, RO
86h	PMBSE	Power Management Bridge Support Extensions	00	RO
88-89h	SVCAP	Subsystem Capability List	000D	RO
8C-8Dh	SVID	Subsystem Vendor Identification	8086	R/WO
8E-8F	SVID	Subsystem ID Register	0000	R/WO
90-91h	MSICAPLST	MSI Capability List	0005	RO
92-93h	MSICTL	MSI Message Control	0000h	RO, R/W
94-97h	MSIADDR	MSI Message Address Register	00000000	RO, R/W
98-99h	MSIDATA	MIS Message Data Register	0000	R/W
100-103h	AERCAPHDR	Advanced Error Reporting Capabilities	see description	RO, R/WO
104h-107h	UES	Uncorrectable Error Status	See bit description	R/WC, RO
108h-10Bh	UEM	Uncorrectable Error Mask	00000000h	R/WO, RO
10Ch-10Fh	UEV	Uncorrectable Error Severity	See Description	RO
110h-113h	CES	Correctable Error Status	00000000h	R/WC





### 26.2.3 PCICMD—PCI Command Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port— BN+1:D8:F0)

Address Offset: 04h–05h  
Default Value: 0000h

Attribute: R/W, RO  
Size: 16 bits

Bit	Description
15:11	Reserved
10	<p><b>Interrupt Disable</b> — R/W.</p> <p>This bit controls the ability of the PCI-Express Function to generate legacy INTx interrupt message</p> <p>0 = Internal INTx# messages are generated for PCI-Express errors detected internally in this port (for example, Malformed TLP, CRC error, completion time out etc.) or when receiving root port error messages or interrupts due to HP/PM events generated in legacy mode.</p> <p>1 = Internal INTx# messages will not be generated.</p> <p>1 = This bit does not affect interrupt forwarding from devices connected to the root port. Assert_INTx and Deassert_INTx messages will still be forwarded to the internal interrupt controllers if this bit is set.</p>
9	Fast Back to Back Enable (FBE) — Reserved per the <i>PCI Express* Base Specification</i> .
8	<p><b>SERR# Enable (SEE)</b> — R/W.</p> <p>0 = Disable.</p> <p>1 = this bit enables reporting of Non-Fatal and Fatal errors detected by the Function of the Root Complex. For Type 1 Configuration Space headers, this bit controls transmission by the primary interface of ERR_NONFATAL and ERR_FATAL error messages forwarded from the secondary interface. ERR_COR messages are not affected by this bit...</p>
7	Wait Cycle Control (WCC) — Reserved per the <i>PCI Express* Base Specification</i> .
6	<p><b>Parity Error Response (PER)</b> — R/W.</p> <p>0 = Disable.</p> <p>1 = This bit controls the setting of the master data parity error bit in the Status Register in response to a parity error received on the PCI Express interface.</p>
5	VGA Palette Snoop (VPS) — Reserved per the <i>PCI Express* Base Specification</i> .
4	Postable Memory Write Enable (PMWE) — Reserved per the <i>PCI Express* Base Specification</i> .
3	Special Cycle Enable (SCE) — Reserved per the <i>PCI Express* Base Specification</i> .
2	<p><b>Bus Master Enable (BME)</b> — R/W.</p> <p>0 = Disable. memory and I/O requests received at the root port or downstream side of a switch port (secondary side) must be handled as an Unsupported Request (UR). For Non-posted requests, a completion with UR completion status must be returned.</p> <p>1 = Enable. Allows the root port or switch to forward memory and I/O read or write requests in the upstream direction.</p>
1	<p><b>Memory Space Enable (MSE)</b> — R/W.</p> <p>0 = Disable. The function will handle memory transactions targeting the Function as an Unsupported Request (UR).</p> <p>1 = Enable. Allows memory cycles within the range specified by the memory base and limit registers can be forwarded.</p>
0	<p><b>I/O Space Enable (IOSE)</b> — R/W. This bit controls access to the I/O space registers.</p> <p>0 = Disable. The function will handle I/O transactions targeting the Function as an Unsupported Request (UR).</p> <p>1 = Enable. Allows I/O cycles within the range specified by the I/O base and limit registers can be forwarded.</p>



## 26.2.4 PCISTS—PCI Status Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port— BN+1:D8:F0)

Address Offset: 06h–07h  
Default Value: 0010h

Attribute: R/WC, RO  
Size: 16 bits

Bit	Description
15	<b>Detected Parity Error (DPE)</b> — R/WC. 0 = No parity error detected. 1 = This bit is set when a poisoned TLP is received from PCI Express. This bit is set even when the parity error response enable bit (bit[6] of the PCICMD Register) is not set. On Type 1 configuration header functions, the bit is set when the poisoned TLP is received on the primary side. Set when the...
14	<b>Signaled System Error (SSE)</b> — R/WC. 0 = No system error signaled. 1 = This bit is set when ERR_FATAL or ERR_NONFATAL messages are sent to the root complex and the SERR enable bit in the PCICMD Register is set.
13	<b>Received Master Abort (RMA)</b> — R/WC. 0 = Port has not received a completion with unsupported request status. 1 = This bit is set when the requester receives a completion with an UR completion status. On Type 1 configuration header functions, the bit is set when a UR completions status is received on the primary side.
12	<b>Received Target Abort (RTA)</b> — R/WC. 0 = Port has not received a completion with completer abort. 1 = This bit is set when a requester receives a CA completions status. On Type 1 configuration header functions, the bit is set when a "Completer Abort" is received on the primary side.
11	<b>Signaled Target Abort (STA)</b> — R/WC. 0 = No target abort received. <b>Signaled Target Abort (STA):</b> 1 = This bit is Set when the port completes a Posted or Non-Posted Request as a Completer Abort error. This applies to a Function with a Type 1 Configuration header when the Completer Abort was generated by its Primary Side.
10:9	DEVSEL# Timing Status (DEV_STS) — Reserved per the <i>PCI Express* Base Specification</i> .
8	<b>Master Data Parity Error Detected (DPED)</b> — R/WC. 0 = No data parity error received. 1 = This bit is set by a requester (primary side for type1 configuration header functions) if the parity error response enable bit (PERE) in the Command Register is set and either of the following two conditions occur: •Requester receives a completion marked poisoned. •Requester sends a poisoned request (includes writes and messages) If the parity error bit is 0b, this bit is never set.
7	Fast Back to Back Capable (FB2BC) — Reserved per the <i>PCI Express* Base Specification</i> .
6	Reserved
5	66 MHz Capable — Reserved per the <i>PCI Express* Base Specification</i> .
4	<b>Capabilities List</b> — RO. Hardwired to 1. Indicates the presence of a capabilities list.
3	<b>Interrupt Status</b> — RO. 0 = Interrupt is deasserted. 1 = this bit indicates that an INTx emulation interrupt is pending internally in this function. For Type 1 configuration header functions, forwarded INTx messages are not reflected in this bit, unless the INTx messages is being generated from the Type 1 configuration header functioned.
2:0	Reserved











### 26.2.18 PMBL—Prefetchable Memory Base (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 24h–25h Attribute: R/W, RO  
 Default Value: 0001h Size: 16 bits

Bit	Description
15:4	<b>Prefetchable Memory Base (PMB)</b> — R/W. These bits are compared with bits[31:20] of the incoming address to determine the lower 1 MB-aligned value (inclusive) of the range. The incoming address must be greater than or equal to this value.
3:0	<b>64-bit Indicator (I64B)</b> — RO 0: 32-bit Prefetchable Memory addressing. 1: 64-bit Prefetchable Memory addressing. This field indicates that 64-bit addressing is supported for the limit.

### 26.2.19 PMBL—Prefetchable Limit Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 26h–27h Attribute: R/W, RO  
 Default Value: 0001h Size: 32 bits

Bit	Description
15:4	<b>Prefetchable Memory Limit (PML)</b> — R/W. These bits are compared with bits[31:20] of the incoming address to determine the upper 1 MB-aligned value (inclusive) of the range. The incoming address must be less than this value.
3:0	<b>64-bit Indicator (I64L)</b> — RO. Indicates support for 64-bit addressing

### 26.2.20 PMBU32—Prefetchable Memory Base Upper 32 Bits Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 28h–2Bh Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:0	<b>Prefetchable Memory Base Upper Portion (PMBU)</b> — R/W. Lower 32-bits of the prefetchable address base.

### 26.2.21 PMLU32—Prefetchable Memory Limit Upper 32 Bits Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 2Ch–2Fh Attribute: R/W  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:0	<b>Prefetchable Memory Limit Upper Portion (PMLU)</b> — R/W. Upper 32-bits of the prefetchable address limit.





Bit	Description
6	<p><b>Secondary Bus Reset (SBR)</b> — R/W.</p> <p>Setting this bit triggers a hot reset on the downstream link for the corresponding PCIe Express port and the PCI Express* hierarchy domain subordinate to the port. Software must ensure a minimum reset duration of 1us as defined in the PCI Local Bus Specification, Revision 3.0. Hardware will continue to maintain the hot reset state as long as the SBR bit is set.</p> <p>For Root Ports/switch, it is recommended that software assert this field for a minimum of 2 ms to ensure that all downstream links enters hot reset state.</p> <p>For a Switch, the following must cause a hot reset to be sent on all Downstream Ports:</p> <ul style="list-style-type: none"> <li>• Setting the Secondary Bus Reset bit of the Bridge Control register associated with the Upstream Port</li> <li>• The Data Link Layer of the Upstream Port reporting DL_Down status 30</li> <li>• Receiving a hot reset on the Upstream Port</li> </ul> <p>A secondary bus reset will not reset any register of a Type 1 configuration space header function.</p>
5	<p><b>Master Abort Mode (MAM)</b>: Reserved per Express specification.</p>
4	<p><b>VGA 16-Bit Decode (V16)</b> — R/W.</p> <p>This bit enables the bridge to provide 16-bit decoding of VGA I/O address precluding the decoding of VGA alias addresses every 1 KB. This bit requires the VGA enable bit (bit 3 of this register) to be set to 1.</p> <p>0: execute 10-bit address decode on VGA I/O accesses            1: execute 16-bit address decode on VGA I/O accesses</p>
3	<p><b>VGA Enable (VE)</b>— R/W.</p> <p>0 = The ranges below will not be claimed off the backbone by the root port.            1 = This bit modifies the response to VGA-compatible addresses. When set to 1b, the bridge positively decodes and forwards the following transactions from primary side to secondary side regardless of the value of the I/O base and limit registers. The transactions are qualified by the memory enable and I/O enable in the command register.</p> <p><b>Memory addresses:</b> 000A 0000h–000B FFFFh  <b>I/O addresses:</b> 3B0h–3BBh and 3C0h–3DFh in first 64 KB of I/O address space (Inclusive of ISA address aliases when IO address bits[15:10] are not decoded)</p> <p>The following ranges will be claimed off the backbone by the root port:</p> <ul style="list-style-type: none"> <li>• Memory ranges A0000h-BFFFFh</li> <li>• I/O ranges 3B0h – 3BBh and 3C0h – 3DFh, and all aliases of bits 15:10 in any combination of 1s</li> </ul>
2	<p><b>ISA Enable (IE)</b> — R/W.</p> <p>This bit modifies the response by the bridge to ISA I/O addresses. This field applies only to I/O addresses that are enabled by the I/O base and I/O limit registers and are in the first 64 KB of PCI I/O space. When this bit is set, the bridge blocks all forwarding from primary to secondary of I/O transactions addressing the last 768 bytes in each 1 KB block (offsets 100h to 3FFh).</p> <p>In the opposite direction (secondary to primary), I/O transactions will be forwarded if they address the last 768B in each 1 KB block.</p> <p>1: Forward upstream ISA I/O addresses in the address range defined by the I/O Base and I/O Limit registers that are in the firsts 64KB of PCI I/O address space (Top 768B of each 1K block).            0: Forward downstream all I/O addresses in the address range defined by the I/O Base and I/O Limit registers.</p>
1	<p><b>SERR# Enable (SE)</b> — R/W.</p> <p>This bit controls the forwarding of PCI Express ERR_COR, ERR_NONFATAL and ERR_FATAL messages to the primary side.</p> <p>1: Enables forwarding of ERR_COR, ERR_NONFATAL, ERR_FATAL messages.            0: Disables forwarding of ERR_COR, ERR_NONFATAL, ERR_FATAL messages.</p>
0	<p><b>Parity Error Response Enable (PERE)</b> — R/W.,</p> <p>This bit controls the response to poisoned TLPs in the PCI Express* port.</p> <p>1: Enables reporting of poisoned TLP errors.            0: Disables reporting of poisoned TLP errors</p>





Bit	Description
11:9	Endpoint L1 Acceptable Latency (E1AL) — RO. This field is reserved with a setting of 000b for devices other than Endpoints, per the PCI Express* 1.1 Spec.
8:6	Endpoint L0s Acceptable Latency (E0AL) — RO. This field is reserved with a setting of 000b for devices other than Endpoints, per the PCI Express* 1.1 Spec.
5	<b>Extended Tag Field Supported (ETFS)</b> — RO. Indicates that a 5-bit tag fields are supported.
4:3	<b>Phantom Functions Supported (PFS)</b> — RO. No phantom functions supported.
2:0	<b>Max Payload Size Supported (MPS)</b> — RO. Indicates the maximum payload size VRP: 000 = 128B VSP: 001 = 256B

## 26.2.28 DCTL—Device Control Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 48h–49h  
Default Value: 2000h

Attribute: R/W, RO  
Size: 16 bits

Bit	Description
15	Reserved
14:12	Max Read Request Size (MRRS) — R/W. 512Bytes is the maximum read request size.
11	Enable No Snoop (ENS) — RO. Not supported. The root port will never issue non-snoop requests.
10	<b>Aux Power PM Enable (APME)</b> — RO. Not supported, hardwired to 0.
9	Phantom Functions Enable (PFE) — RO. Not supported.
8	Extended Tag Field Enable (ETFE) — RO. Not supported.
7:5	<b>Max Payload Size (MPS)</b> — R/W. 128 bytes is the default, but 256 is also supported. Not other sizes are supported.
4	Enable Relaxed Ordering (ERO) — RO. Not supported.
3	<b>Unsupported Request Reporting Enable (URE)</b> — R/W. 0 = The root port will ignore unsupported request errors. 1 = Allows signaling ERR_NONFATAL, ERR_FATAL, or ERR_COR to the Root Control register when detecting an unmasked Unsupported Request (UR). An ERR_COR is signaled when a unmasked Advisory Non-Fatal UR is received. An ERR_FATAL, ERR_or NONFATAL, is sent to the Root Control Register when an uncorrectable non-Advisory UR is received with the severity set by the Uncorrectable Error Severity register.
2	<b>Fatal Error Reporting Enable (FEE)</b> — R/W. 0 = The root port will ignore fatal errors. 1 = Enables signaling of ERR_FATAL to the Root Control register due to internally detected errors or error messages received across the link. Other bits also control the full scope of related error reporting.
1	<b>Non-Fatal Error Reporting Enable (NFE)</b> — R/W. 0 = The root port will ignore non-fatal errors. 1 = Enables signaling of ERR_NONFATAL to the Root Control register due to internally detected errors or error messages received across the link. Other bits also control the full scope of related error reporting.
0	<b>Correctable Error Reporting Enable (CEE)</b> — R/W. 0 = The root port will ignore correctable errors. 1 = Enables signaling of ERR_CORR to the Root Control register due to internally detected errors or error messages received across the link. Other bits also control the full scope of related error reporting.





Bit	Description
11:10	<b>Active State Link PM Support (APMS)</b> — RO. 11b Indicates both L1 and L0s supported
9:4	<b>Maximum Link Width (MLW)</b> — RO 01h indicating the maximum width is a x1.
3:1	Reserved
0	<b>Maximum Link Speed (MLS)</b> — RO. 1b = 2.5 Gb/s link speed is supported

### 26.2.31 LCTL—Link Control Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 50h-51h  
Default Value: 0000h

Attribute: R/W, RO  
Size: 16 bits

Bit	Description										
15:12	Reserved										
11	<b>Link Autonomous Bandwidth Interrupt Enable (LABIE)</b> — RO Hardwired to 0 as not applicable										
10	<b>Link Bandwidth Management Interrupt Enable (LBMIE)</b> — RO Hardwired to 0 as not applicable										
9	<b>Hardware Autonomous Width Disable</b> — RO. Components that do not implement the ability such as (Upstream Ports, Virtual Switch Ports) to autonomously change link width are permitted to hardwire this bit to 0b										
8	Reserved										
7	<b>Extended Synch (ES)</b> — R/W. 0 = Extended synch disabled. 1 = Forces extended transmission of FTS ordered sets in FTS and extra TS2 at exit from L1 prior to entering L0.										
6	<b>Common Clock Configuration (CCC)</b> — R/W. 0 = The PCH and device are not using a common reference clock. 1 = The PCH and device are operating with a distributed common reference clock. After changing the value in this bit in bother components on a link, software must trigger the link to retrain by writing a 1b to the Retrain Link bit of the Downstream Port.										
5	<b>Retrain Link (RL)</b> — RO. Hardwired to 0. For the upstream port or virtual switch port, it is Read-only										
4	<b>Link Disable (LD)</b> — R/W. This bit disables the link when set.										
3	<b>Read Completion Boundary Control (RCBC)</b> — RO. Indicates the read completion boundary is 64 bytes.										
2	Reserved										
1:0	<b>Active State Link PM Control (APMC)</b> — R/W. Indicates whether the upstream port should enter L0s or L1 or both. <table border="1"> <thead> <tr> <th>Bits</th> <th>Definition</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>Disabled</td> </tr> <tr> <td>01</td> <td>L0s Entry Enabled</td> </tr> <tr> <td>10</td> <td>L1 Entry Enabled</td> </tr> <tr> <td>11</td> <td>L0s and L1 Entry Enabled</td> </tr> </tbody> </table>	Bits	Definition	00	Disabled	01	L0s Entry Enabled	10	L1 Entry Enabled	11	L0s and L1 Entry Enabled
Bits	Definition										
00	Disabled										
01	L0s Entry Enabled										
10	L1 Entry Enabled										
11	L0s and L1 Entry Enabled										









Bit	Description
9	<b>IDO Completion Enable (IDOCE) — RO</b> Hardwired to 0b. Applicable only to Endpoints including RC integrated Endpoints and Root Ports.
8	<b>IDO Request Enable (IDORE) — RO</b> Hardwired to 0b. Applicable only to Endpoints including RC integrated Endpoints and Root Ports.
7	<b>AtomicOp Egress Blocking (AEB) — R/W</b> 0 = AtomicOp requests that target this out going Egress port are permitted 1 = AtomicOp requests that target this out going Egress port must be blocked.
6	<b>AtomicOp Requester Enable (ARE)</b> Applicable only to Endpoints and Root Ports; must be hardwired to 0b for other Function types.
5	<b>Alternative RID Interpretation Enable (ARIE) — R/W</b> When set to 1b, ARI is enabled for the downstream port or root ports.
4	<b>Completion Timeout Disable (CTD) — RO.</b> Hardwired to 0b 1 = Disable the completions timeout mechanism for all NP transactions. 0 = Completion timeout is enabled for all NP transactions.
3:0	<b>Completion Timeout Value (CTV) — RO</b> Hardwired to 0000b.

### 26.2.38 DEVSTS2—Device Status 2 Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 6Ah–6Bh                      Attribute: RO  
 Default Value: 0000h                      Size: 16 bits

Bit	Description
15:0	Reserved

### 26.2.39 L2—Link Control 2 Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 70h–71h                      Attribute: RO, R/WS  
 Default Value: 0001h                      Size: 16 bits

Bit	Description
15:13	Reserved. Hardwired to 00b
12	<b>Compliance De-emphasis (CD) — RO.</b> This bit sets the de-emphasis level in Polling.Compliance state if the entry occurred due to the Enter Compliance bit (EC) (bit 4) in this register being 1b. 1b = -3.5 dB 0b = -6 dB When the link is operating at 2.5 Gb/s, the setting of this bit has no effect. Only cleared to default with a power good reset
11	<b>Compliance SOS (CSOS) — RO.</b> Set to 0b
10	<b>Enter Modified Compliance (EMC) — RO.</b> Set to 0b
9:7	<b>Transmit Margin (TM) — RO</b> - set to 000b
6	<b>Selectable De-emphasis (SD) — RO.</b> Hardwired to 0b This bit is not applicable and reserved for Endpoints, PCI Express* to PCI/PCI-X bridges, and upstream ports of switches.













## 26.2.53 UES—Uncorrectable Error Status Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port— BN+1:D8:F0)

Address Offset: 104h–107h                      Attribute: R/WC, RO  
 Default Value: 00000000h                      Size: 32 bits

This register maintains its state through a platform reset. It loses its state upon suspend.

Bit	Description
31:25	<b>Reserved</b> , hardwired to 0
24	<b>Atomic Egress Blocked Error (AEBE): R/WC. default 0b</b> This bit is set whenever an Atomic OP TLP is blocked on any egress port
23	<b>MC Blocked TLP Error (MCE): RO</b> Not supported, set to 0b
22	<b>Uncorrectable Internal Error (UIE):R/WC. default 0b</b> This bit is set whenever an uncorrectable internal error is detected.
21	<b>ACS Violation Error (ACSE): R/WC. Default 0b</b> This bit is set whenever an ACS violation is detected by the PCI Express* port.
20	<b>Unsupported Request Error Status (URE) — R/WC. Default 0b</b> Indicates an unsupported request was received.
19	ECRC Error Status (EE) — RO. ECRC is not supported.
18	<b>Malformed TLP Status (MT) — R/WC. Default 0b</b> Indicates a malformed TLP was received.
17	<b>Receiver Overflow Status (RO) — R/WC. Default 0b</b> Indicates a receiver overflow occurred.
16	<b>Unexpected Completion Status (UC) — R/WC. Default 0b</b> This bit is set whenever a completion is received with a requestor ID that does not match side A or side B, or when a completion is received with a matching requestor ID but an unexpected tag field. Header logging is performed.
15	<b>Completion Abort Status (CA) — R/WC. Default 0b</b> The bridge sets this bit and logs the header associated with the request when the configuration unit signals a completer abort.
14	<b>Completion Timeout Status (CT) — RO.</b> Not supported, set to 0b
13	<b>Flow Control Error (FCE):R/WC. default is 0b</b> This bit is set when a flow control protocol error is detected.
12	<b>Poisoned TLP Error (PTLPE): R/WC Default is 0b</b> This bit is set and the bridge logs the header when a poisoned TLP is received from PCI Express.
11:6	<b>Reserved</b> Software must write 0 to these bits
5	<b>Surprise Link Down Error (SLDE): R/WC: Default is 0b</b> This bit is set when a surprise link down error is detected.
4	<b>Data Link Protocol Error Status (DLPE) — R/WC.</b> Indicates a data link protocol error occurred.
3:0	<b>Reserved</b> Set to 0h





## 26.2.55 UEV – Uncorrectable Error Severity (Virtual Root Port–B0:D17:F0, Virtual Switch Port– BN+1:D8:F0)

Address Offset: 10Ch–10Fh  
Default Value: 00462030h

Attribute: RO, R/W  
Size: 32 bits

Bit	Description
31:25	Reserved
24	<b>AtomicOp Egress Blocked Severity (AEBES)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
23	<b>MC Blocked TLP Error Severity (MCES): RO hardwired to 0b</b>
22	<b>Uncorrectable Internal Error Severity (UIES)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (default)
21	<b>ACS Violation Error Severity (ACES)</b> — RO 0 = Error considered non-fatal. (default) 1 = Error is fatal.
20	<b>Unsupported Request Error Severity (URE)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
19	<b>ECRC Error Severity (EE)</b> — RO. ECRC is not supported.
18	<b>Malformed TLP Severity (MT)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
17	<b>Receiver Overflow Severity (RO)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
16	<b>Unexpected Completion Error Severity (UCES)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
15	<b>Completion Abort Severity (CA)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
14	<b>Completion Timeout Error Severity (CTES)</b> — RO - hardwired to 0
13	<b>Flow Control Protocol Error Severity (FCPE)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal (Default).
12	<b>Poisoned TLP Severity (PT)</b> — R/W. 0 = Error considered non-fatal. (Default) 1 = Error is fatal.
11:6	Reserved
5	<b>Surprise Link Down Severity (SLDES)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
4	<b>Data Link Protocol Error Severity (DLPE)</b> — R/W. 0 = Error considered non-fatal. 1 = Error is fatal. (Default)
3:0	Reserved





Bit	Description
6	<b>Bad TLP Mask (BT)</b> — RO. Mask for bad TLP reception.
5:1	Reserved
0	<b>Receiver Error Mask (RE)</b> — RO. Mask for receiver errors.

### 26.2.58 AECC—Advanced Error Capabilities and Control Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 118h–11Bh                      Attribute: RO  
 Default Value: 00000000h                      Size: 32 bits

Bit	Description
31:11	Reserved
10	<b>Multiple Header Recording Enable (MHRE)</b> :RO- Not supported, hardwired to 0b
9	<b>Multiple Header Recording Capable (MHRC)</b> : RO - Not supported, hardwired to 0b
8	ECRC Check Enable (ECE) — RO. ECRC is not supported. Hardwired to 0b
7	ECRC Check Capable (ECC) — RO. ECRC is not supported. Hardwired to 0b
6	ECRC Generation Enable (EGE) — RO. ECRC is not supported. Hardwired to 0b
5	ECRC Generation Capable (EGC) — RO. ECRC is not supported. Hardwired to 0b
4:0	First Error Pointer (FEP) — RO. This field identifies the bit position of the first error reported in the Uncorrectable Error Status Register (xref). This register re-arms itself (which does not change its current value) as soon as the error status bit indicated by the pointer is cleared by the software by writing a 1 to that status bit.

### 26.2.59 AEHRDLOG [1-4]—Advanced Error Header Log (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 11Ch–128hFh                      Attribute: RRO  
 Default Value: 0000h                              Size: 32 bits

Bit	Description
31:00	<b>TLP Header Log (TLPHDRLOG):</b> As soon as an error is logged in this register, it remains locked for further error-logging until the software clears the status bit that caused the header log (in other words, until the error pointer is re-armed for logging again).





### 26.2.62 ERRSRCID— Error Source Identification Register (Virtual Root Port—B0:D17:F0)

Address Offset: 134h Attribute: RO  
 Default Value: 00000000h Size: 32 bits

Bit	Description
31:16	<b>Fatal/Non-Fatal Error Source ID (EFSID)</b> Requester ID of the source when a Fatal or Non-Fatal error is received
15:0	<b>Correctable Error Source ID (ECSID)</b> Requester ID of the source when a correctable error is received

### 26.2.63 ACSCAPHDR—Access Control Services Extended Capabilities Header (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 138–13Bh Attribute: RO  
 Default Value: 0001000Dh Size: 32 bits

Bit	Description
31:20	<b>Next Capability Offset (NCO):R/WL</b> A value of 000h indicates that this is the last capability
19:16	<b>Capability Version (CV):RO</b> Indicates the version of the Capability structure present.
15:0	<b>Extended Capability ID (EXCAPID): RO</b> Identifies the function as Access control services capable

### 26.2.64 ACSCAP— Access Control Services Capability Register (Virtual Root Port—B0:D17:F0, Virtual Switch Port—BN+1:D8:F0)

Address Offset: 13Ch Attribute: RO  
 Default Value: 005Fh Size: 16 bits

Bit	Description
15:8	<b>Egress Control Vector Size (ECVS)</b> Indicates the number of bits in the Egress Control Vector. This is set to 00h as the ACS P2P Egress Control (ACSP2PEC) bit 5 in this register is 0b
7	<b>Reserved -</b>
6	<b>ACS Direct Translated P2P (T) (ACSDTP2P)</b> Indicates that the component does implement ACS Direct Translated P2P
5	<b>ACS P2P Egress Control (E) (ACSP2PEC)</b> Hardwired to 0, this component does not implement ACS P2P Egress Control.
4	<b>ACS Upstream Forwarding U (ACSUF)</b> Indicates that the component implements ACS Upstream Forwarding
3	<b>xACS P2P Completion Redirect (C) (ACSP2PRR)</b> Indicates the component implements ACS P2P Completion redirect.





Bit	Description
22	<b>Uncorrectable Internal Error Detect Mask (UIEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
21	<b>ACS Violation Error Detect Mask (ACSEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
20	<b>Unsupported Request Error Detect Mask (URED M) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
19	<b>ECRC Check Error Mask (ECRCEDM) — Not supported</b> RO - hardwired to 0
18	<b>Malformed TLP Error Detect Mask (MTLPEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
17	<b>Receiver Overflow Error Detect Mask (ROEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
16	<b>Unexpected Completion Error Detect Mask (UCEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
15	<b>Completer Abort Error Detect Mask (CAEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
14	<b>Completion Timeout Error Detect Mask (CTEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
13	<b>Flow Control Error Detect Mask (FCEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
12	<b>Poisoned TLP Error Detect Mask (PTLPEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
11-6	<b>Reserved</b>
5	<b>Surprise Link Down Error Detect Mask (SLDEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
4	<b>Data Link Protocol Error Detect Mask (DLPEDM) — R/WS</b> 0 = Detection and logging enabled 1 = Detection and logging disabled
3-0	<b>Reserved</b>







# 27 Integrated Device Fabric (IDF) SMBus Controller Function (SRV/WS SKUs Only)

## 27.1 IDF SMBus Registers

### 27.1.1 SMBus Function Configuration Space Registers

Table 27-2. SMBus PCI Function 3,4,5 Configuration Map

Offset	Mnemonic	Register Name	Default	Attributes
00h–01h	VID	Vendor Identification	8086	RO
02h–03h	DID	Device Identification	See register description	RO
04h–05h	PCICMD	PCI Command	0000h	R/W, RO
06h–07h	PCISTS	PCI Status	0280h	RO
08h	RID	Revision Identification	See register description	RO
09h	PI	Programming Interface	00h	RO
0Ah	SCC	Sub Class Code	05h	RO
0Bh	BCC	Base Class Code	0Ch	RO
0Ch	CLS	Cacheline Size	00h	R/W
0Eh	HDR	Header Type	80h	RO
10h	SMBMBARO	Memory Base Address Register	0000h	R/W
20h–23h	SMBIOBAR	SMBus IO BAR	00000001h	R/W, RO
2Ch–2Dh	SVID	Subsystem Vendor Identification	0000h	RO
2Eh–2Fh	SID	Subsystem Identification	0000h	R/WO
34h	CAPPTR	Capabilities Pointer	90h	RO
3Ch	INT_LN	Interrupt Line	00h	R/W
3Dh	INT_PN	Interrupt Pin	See register description	RO
40h	HOSTC	Host Configuration	00h	R/W
64–67h	HSTTCTL	Host Timing Control	08000000h	R/WS
7C–7Fh	SDWMPSTL	Shadowed Max Payload Size Control	00000000h	R/W
80–83h	SMBMODE	SMBus Mode Control	00000000h	R/WS, RO
E4–E5h	DEVCLKGCTL	Device Clock Gate Control	0010h	R/W
E6–E7h	SBDEVCLKGCTL	Sideband Device Clock Gate Control	0010h	R/W
E8–E9h	PLKCTL	Personality Lock Key Control	0000h	R/W
FC–FFh	CFGAGTERR	Configuration Agent Error	00000000h	R/WS
100–103h	ARICAPHDR	Alternative Routing-ID Extended Capability Header	000100Eh	RO, R/W
104–105h	ARICAP	Alternative Routing_ID Interpretation Capability	0400h 0500h 0600h	R/W, RO
106–107	ARICTL	Alternative Routing-ID Interpretation Control	0000h	RO
110–113h	ERRUNCSTS	Uncorrectable Error Status	00000000h	RO, R/W
114–117h	ERRUNCDETMSK	Uncorrectable Error Detect Mask	00000000h	RO, R/WS



## 27.1.2 PCI Standard Header Registers

This section describes the PCI Configuration Space registers that make up the standard Type 1 header for PCI to PCI Bridges. Some information from the specification is repeated here as an aid to the reader or to describe implementation choice. Please refer to the *PCI Express® Base Specification 2.0*, *PCI-to-PCI Bridge Architecture Specification* and *PCI Local Bus Specification* for the full register descriptions and additional information regarding their operation.

### 27.1.2.1 Vendor ID Register (VID)

<b>VID</b>			
Bus: X Device: 0 Function: 3 Offset: 00h;			
Bus: X Device: 0 Function: 4 Offset: 00h;			
Bus: X Device: 0 Function: 5 Offset: 00h;			
Bit	Attr	Default	Description
15:0	RO	8086h	<b>Vendor ID (VID):</b> This field identifies Intel as the manufacturer of the device.

### 27.1.2.2 Device ID Register (DID)

<b>DID</b>			
Bus: X Device: 0 Function: 3 Offset: 02h;			
Bus: X Device: 0 Function: 4 Offset: 02h;			
Bus: X Device: 0 Function: 5 Offset: 02h;			
Bit	Attr	Default	Description
15:0	RO-V	0000h	<b>Device ID</b> — RO. This is a 16-bit value assigned to the PCH IDF SMBus controller. Refer to the <i>Intel® C600 Series Chipset Specification Update</i> for the value of the Device ID Register.

### 27.1.2.3 PCI Command Register (PCICMD)

<b>PCICMD</b>			
Bus: X Device: 0 Function: 3 Offset: 04h;			
Bus: X Device: 0 Function: 4 Offset: 04h;			
Bus: X Device: 0 Function: 5 Offset: 04h;			
Bit	Attr	Default	Description
15:11	RV	00h	Reserved
10	R/W	0b	Interrupt Disable (Nixed): This bit controls the ability of the PCI-Express Function to generate INTx interrupt message. When set, functions are prevented from asserting INTx interrupt messages. Any INTx emulation interrupts already asserted by the function must be deserted when this bit is set by generating a Deassert_INTx message(s).  This bit has no effect on interrupts that pass through the port from the secondary side of root ports, switch ports, and bridges.
9	RO	0b	<b>Fast Back-to-back enable (FBE):</b> Not applicable to PCI-Express. Hardwired to 0.



<b>PCICMD</b> <b>Bus: X Device: 0 Function: 3 Offset: 04h;</b> <b>Bus: X Device: 0 Function: 4 Offset: 04h;</b> <b>Bus: X Device: 0 Function: 5 Offset: 04h;</b>			
Bit	Attr	Default	Description
8	R/W	0b	<p><b>SERR# Enable (SEE):</b>                      When set, this bit enables reporting of Non-Fatal and Fatal errors detected by the Function of the Root Complex. For Type 1 Configuration Space headers, this bit controls transmission by the primary interface of ERR_NONFATAL and ERR_FATAL error messages forwarded from the secondary interface. ERR_COR messages are not affected by this bit.</p> <p><b>Note:</b> Errors are reported when enabled either through this bit or through the PCI Express-specific bits in the Device Control Register (“<a href="#">Device Control Register (DEVCTL)</a>” on page 931).</p>
7	RO	0b	<p><b>Wait Cycle Control (WCC):</b>                      Not applicable to PCI-Express. Hardwired to 0.</p>
6	R/W	0b	<p><b>Parity Error Response Enable (PERE):</b>                      This bit controls the setting of the master data parity error bit in the Status Register (“<a href="#">PCI Status Register (PCISTS)</a>” on page 926) in response to a parity error received on the PCI Express interface (poisoned TLP).</p>
5	RO	0b	<p><b>VGA Palette Snoop Enable (VGA_PSE):</b>                      Not applicable to PCI-Express. Hardwired to 0.</p>
4	RO	0b	<p><b>Memory Write and Invalidate Enable (MWIE):</b>                      Not applicable to PCI-Express. Hardwired to 0.</p>
3	RO	0b	<p><b>Special Cycle Enable (SCE):</b>                      Not applicable to PCI-Express. Hardwired to 0.</p>
2	R/W	0b	<p><b>Bus Master Enable (BME):</b>                      This bit controls the ability of the Function to issue Memory and I/O read or write requests, and the ability of Root or Switch port to forward memory and I/O read or write requests in the upstream direction. When this bit is 0b, memory and I/O requests received at the root port or downstream side of a switch port (secondary side) must be handled as an Unsupported Request (UR). For Non-posted requests, a completion with UR completion status must be returned.</p> <p>The forwarding of requests other than memory or I/O requests is not controlled by this bit.</p> <p><b>Note:</b> MSI interrupts are inband memory writes and are blocked when this bit is 0b.</p>
1	R/W	0b	<p><b>Memory Space Enable (MSE):</b>                      This bit controls the function’s response to Memory Space accesses. When this bit is 0b, the function will handle memory transactions targeting the Function as an Unsupported request (UR). For Type 1 Configuration Space headers, this bit controls the primary side response to memory space accesses targeting the secondary side. When this bit is 0b, every memory transaction targeting a secondary interface is handled as an Unsupported Request (UR). For Non-posted requests, a completion with UR completion status must be returned.</p>
0	R/W	0b	<p><b>I/O Space Enable (IOSE):</b>                      This bit controls the function’s response to IO Space accesses. When this bit is 0b, the function will handle memory transactions targeting the Function as an Unsupported request (UR). For Type 1 Configuration Space headers, this bit controls the primary side response to IO Space accesses targeting the secondary side. When this bit is 0b, every memory transaction targeting a secondary interface is handled as an Unsupported Request (UR). For Non-posted requests, a completion with UR completion status must be returned.</p>

This register controls how the device behaves on the primary interface (PCI Express).



### 27.1.2.4 PCI Status Register (PCISTS)

<b>PCISTS</b> <b>Bus: X Device: 0 Function: 3 Offset: 06h;</b> <b>Bus: X Device: 0 Function: 4 Offset: 06h;</b> <b>Bus: X Device: 0 Function: 5 Offset: 06h;</b>			
Bit	Attr	Default	Description
15	R/W1C	0b	<b>Detected Parity Error (DPE):</b> This bit is set when a poisoned TLP is received from PCI Express. This bit is set even when the parity error response enable bit (bit[6] of the PCICMD Register— <a href="#">“PCI Command Register (PCICMD)” on page 924</a> ) is not set. On Type 1 configuration header functions, the bit is set when the poisoned TLP is received on the primary side.
14	R/W1C	0b	<b>Signaled System Error (SSE):</b> This bit is set when ERR_FATAL or ERR_NONFATAL messages are sent to the root complex and the SERR enable bit in the PCICMD Register ( <a href="#">“PCI Command Register (PCICMD)” on page 924</a> ) is set.
13	RO	0b	<b>Received Master Abort (RMA):</b> This bit is set when the requester receives a completion with an UR completion status. On Type 1 configuration header functions, the bit is set when a UR completions status is received on the primary side.
12	RO	0b	<b>Received Target Abort (RTA):</b> This bit is set when a requester receives a CA completions status. On Type 1 configuration header functions, the bit is set when a “Completer Abort” is received on the primary side.
11	R/W1C	0b	<b>Signaled Target Abort (STA):</b> This bit is set when the switch generates a completion packet with Completer Abort (CA) status is generated by its primary side.
10:9	RO	00b	<b>DEVSEL# Timing (DVT):</b> These bits have no meaning on PCI Express. Fast decode timing is reported.
8	R/W1C	0b	<b>Master Data Parity Error Detected (MDPD):</b> This bit is set by a requester (primary side for type1 configuration header functions) if the parity error response enable bit (PERE) in the Command Register ( <a href="#">“PCI Command Register (PCICMD)” on page 924</a> ) is set and either of the following two conditions occur: <ul style="list-style-type: none"> <li>Requester receives a completion marked poisoned.</li> <li>Requester poisons a write requests.</li> </ul> If the parity error bit is 0b, this bit is never set.
7	RO	0b	<b>Fast Back-to-Back Capable (FBC):</b> This bit has no meaning on PCI Express.
6	RV	0b	Reserved
5	RO	0b	<b>66 MHz Capable (C66):</b> This bit has no meaning on PCI Express.
4	RO	1b	<b>Capabilities List Enable (CAPE):</b> This bit indicates the presence of an Extended capabilities list items. Offset 34H indicates the offset for the first entry in the linked list of capabilities. All PCI Express* Functions are required to have a PCI Express* Capability Structure. So this bit must be hardwired to 1b.
3	RO-V	0b	<b>Interrupt Status (INTS):</b> When set, this bit indicates that an INTx emulation interrupt is pending internally in this function. For Type 1 configuration header functions, forwarded INTx messages are not reflected in this bit. unless the INTx messages is being generated from the Type 1 configuration header function.
2:0	RV	0h	Reserved



### 27.1.2.5 Revision ID Register (RID)

<b>RID</b> Bus: X Device: 0 Function: 3 Offset: 08h; Bus: X Device: 0 Function: 4 Offset: 08h; Bus: X Device: 0 Function: 5 Offset: 08h;			
Bit	Attr	Default	Description
7:0	ROS-V	00h	<b>Revision ID</b> — RO. Refer to the <i>Intel® C600 Series Chipset Specification Update</i> for the value of the Revision ID Register.

### 27.1.2.6 Class Code Register (CC)

<b>CC</b> Bus: X Device: 0 Function: 3 Offset: 09h; Bus: X Device: 0 Function: 4 Offset: 09h; Bus: X Device: 0 Function: 5 Offset: 09h;			
Bit	Attr	Default	Description
23:16	RO	0Ch	<b>Base Class (BC):</b> The value of 0Ch indicates that this is a serial bus controller device.
15:8	RO	05h	<b>Sub-Class (SC):</b> This 8-bit value indicates that this device is a SMBus Controller.
7:0	RO	00h	<b>Register-Level Programming Interface (RLPI):</b>

### 27.1.2.7 Cacheline Size Register (CLS)

<b>CLS</b> Bus: X Device: 0 Function: 3 Offset: 0Ch; Bus: X Device: 0 Function: 4 Offset: 0Ch; Bus: X Device: 0 Function: 5 Offset: 0Ch;			
Bit	Attr	Default	Description
7:0	R/W	00h	<b>Cache Line Size (CLS):</b> These bits specify the system cache-line size in units of DWords. This field is implemented by PCI Express* devices but has no effect on device behavior.

### 27.1.2.8 Header Type Register (HDR)

<b>HDR</b> Bus: X Device: 0 Function: 3 Offset: 0Eh; Bus: X Device: 0 Function: 4 Offset: 0Eh; Bus: X Device: 0 Function: 5 Offset: 0Eh;			
Bit	Attr	Default	Description
7	RO	1b	<b>Multi-function device (MFD):</b> Reserved as 1 to indicate that the switch is a multi-function device.
6:0	RO	00h	<b>Header Type (HTYPE):</b> These bits define the layout of addresses 10h through 3Fh in the configuration space.



### 27.1.2.9 SMBUS Memory Base Address Register (SMBMBAR)

SMBMBAR			
Bus: X Device: 0 Function: 3 Offset: 10h;			
Bus: X Device: 0 Function: 4 Offset: 10h;			
Bus: X Device: 0 Function: 5 Offset: 10h;			
Bit	Attr	Default	Description
31:12	R/W	0h	<b>Memory Base Address (MBA):</b>
11:4	RO	0h	<b>Memory Size (MSIZE):</b> Hardwired to 0h.
3	RO	0b	<b>Prefetchable Memory (PFMEM):</b> Not prefetchable memory space.
2:1	RO	00b	<b>Memory Type (MTYPE):</b> Indicates 32-bit address space.
0	RO	0b	<b>Memory Space Indicator (MSI):</b> 0b: Memory space 1b: IO space

### 27.1.2.10 SMBUS IO BAR Register (SMBIOBAR)

SMBIOBAR			
Bus: X Device: 0 Function: 3 Offset: 20h;			
Bus: X Device: 0 Function: 4 Offset: 20h;			
Bus: X Device: 0 Function: 5 Offset: 20h;			
Bit	Attr	Default	Description
31:16	RV	0h	Reserved.
15:5	R/W	0h	<b>IO Base Address (IOBA):</b>
4:1	RV	0h	Reserved.
0	RO	1b	<b>IO Space Indicator (IOSI):</b> 0b: Memory space 1b: IO space

### 27.1.2.11 Subsystem Vendor ID Register (SVID)

SVID			
Bus: X Device: 0 Function: 3 Offset: 2Ch;			
Bus: X Device: 0 Function: 4 Offset: 2Ch;			
Bus: X Device: 0 Function: 5 Offset: 2Ch;			
Bit	Attr	Default	Description
15:0	R/WL PRST	8086h	<b>Subsystem Vendor ID (SVID):</b> This field identifies Intel as the manufacturer of the device.



### 27.1.2.12 Subsystem ID Register (SID)

<b>SID</b> Bus: X Device: 0 Function: 3 Offset: 2Eh; Bus: X Device: 0 Function: 4 Offset: 2Eh; Bus: X Device: 0 Function: 5 Offset: 2Eh;			
Bit	Attr	Default	Description
15:0	R/WL PRST	0000h	<b>Subsystem ID (SID):</b> This field identifies the particular function as allocated by Intel.

### 27.1.2.13 Capabilities Pointer Register (CAPPTR)

<b>CAPPTR</b> Bus: X Device: 0 Function: 3 Offset: 34h; Bus: X Device: 0 Function: 4 Offset: 34h; Bus: X Device: 0 Function: 5 Offset: 34h;			
Bit	Attr	Default	Description
7:0	RO	90h	<b>Capabilities Pointer (CPTR):</b> Contains the offset of the first item in the list of capabilities. (EXPCAPLST)

### 27.1.2.14 Interrupt Line Register (INTL)

<b>INTL</b> Bus: X Device: 0 Function: 3 Offset: 3Ch; Bus: X Device: 0 Function: 4 Offset: 3Ch; Bus: X Device: 0 Function: 5 Offset: 3Ch;			
Bit	Attr	Default	Description
7:0	R/W	00h	<b>Interrupt Line (INTL):</b> This register is used to communicate interrupt line routing information. The device itself does not use this value, rather it is used by device drivers and operating systems.

### 27.1.2.15 Interrupt Pin Register (INTP)

<b>INTP</b> Bus: X Device: 0 Function: 3 Offset: 3Dh; Bus: X Device: 0 Function: 4 Offset: 3Dh; Bus: X Device: 0 Function: 5 Offset: 3Dh;			
Bit	Attr	Default	Description
7:0	RO	Func ? 3: 03h 4: 03h 5: 04h	<b>Interrupt Pin (INTP):</b> This register tells which interrupt pin the function uses. 01h: Generate INTA 02h: Generate INTB 03h: Generate INTC 04h: Generate INTD Others: Reserved

## 27.1.3 PCI Express\* Capability Structure

This section describes the PCI Configuration Space registers that make up the PCI Express\* Capability Structure. These registers are first in the capabilities list, so they are discovered through the [Capabilities Pointer Register \(CAPPTR\)](#).



Some information from the specification is repeated here as an aid to the reader or to describe implementation choice. Please refer to the *PCI Express® Base Specification 2.0* for the full register descriptions and additional information regarding their operation.

### 27.1.3.1 PCI Express\* Capability List Register (EXPCAPLST)

Bit	Attr	Default	Description
<b>EXPCAPLST</b> Bus: X Device: 0 Function: 3 Offset: 90h; Bus: X Device: 0 Function: 4 Offset: 90h; Bus: X Device: 0 Function: 5 Offset: 90h;			
15:8	R/WL	CCh	<b>Next Pointer (NP):</b> Contains the offset of the next item in the capabilities list. (PMCAPLST)
7:0	RO	10h	<b>Capability ID (CAPID):</b> Identifies the function as PCI Express* capable.

### 27.1.3.2 PCI Express\* Capabilities Register (EXPCAP)

Bit	Attr	Default	Description
<b>EXPCAP</b> Bus: X Device: 0 Function: 3 Offset: 92h; Bus: X Device: 0 Function: 4 Offset: 92h; Bus: X Device: 0 Function: 5 Offset: 92h;			
15:14	RV	0h	Reserved
13:9	RO	0h	<b>Interrupt Message Number (IMN):</b> This field indicates the interrupt message number that is generated from the PCI Express* port. When there is more than one MSI interrupt number, this register is required to contain the offset between the base Message Data and the MSI Message that is generated when the status bits in the slot status register or root port status registers are set. The chipset us required to update this field if the number of MSI messages change.
8	RO	0	<b>Slot Implemented (SI):</b> Indicates the PCI Express* link associated with this port is connected to a slot. Indicates no slot is connected to this port.
7:4	RO	0h	<b>Device/Port Type (DT):</b> 0h: PCI Express* Endpoint 4h: Root Port of a PCIe Root Complex 5h: Upstream port of a PCIe switch. 6h: Downstream port of a PCIe switch.
3:0	RO	2h	<b>Version Number (VN):</b> These bits indicate the version number of the PCI Express capability structure.

This register stores the version number of the capability item and other base information contained in the capability structure.

### 27.1.3.3 Device Capabilities Register (DEVCAP)

Bit	Attr	Default	Description
<b>DEVCAP</b> Bus: X Device: 0 Function: 3 Offset: 94h; Bus: X Device: 0 Function: 4 Offset: 94h; Bus: X Device: 0 Function: 5 Offset: 94h;			
31:29	RV	0h	Reserved



<b>DEVCAP</b> Bus: X Device: 0 Function: 3 Offset: 94h; Bus: X Device: 0 Function: 4 Offset: 94h; Bus: X Device: 0 Function: 5 Offset: 94h;			
Bit	Attr	Default	Description
28	RO	0b	Function Level Reset Capability (FLR): This field when set indicates this function supports optional function Level Reset mechanism. This field applies to Endpoints only. For all other function types this bit must be hardwired to 0b.
27:26	RO	00b	<b>Captured Slot Power Limit Scale (CSPLS):</b> In combination with the Slot Power Limit value (bits[25:18]), this field specifies the upper limit of the power supplied by slot. The power limit (in Watts) is calculated by multiplying the value in this field by the value in the Slot Power Limit Value field. This value is set by the Set_Slot_Power_Limit message.
25:18	RO	0h	<b>Captured Slot Power Limit Value (CSPLV):</b> In combination with the Slot Power Limit Scale value (bits[27:26]), this field specifies the upper limit of the power supplied by slot. The power limit (in Watts) is calculated by multiplying the value in this field by the value in the Slot Power Limit Scale field. This value is set by the Set_Slot_Power_Limit message.
17:16	RV	00b	Reserved
15	RO	1b	<b>Role-Based Error Reporting (RBER):</b>
14:12	RO	0h	Undefined
11:9	RO	000b	<b>Endpoint L1 Acceptable Latency (EPL1AL):</b> The least latency possible out of L1 is supported.
8:6	RO	000b	<b>Endpoint L0s Acceptable Latency (EPL0AL):</b> The least latency possible out of L0s is supported.
5	RO	0b	<b>Extended Tag Field Supported (ETFG):</b> Only a 5-bit tag is supported.
4:3	RO	00b	<b>Phantom Functions Supported (PFS):</b> Not supported
2:0	RO	001b	<b>Supported Max Payload sizes (MPSS):</b> 256-byte packets are the maximum supported.

### 27.1.3.4 Device Control Register (DEVCTL)

<b>DEVCTL</b> Bus: X Device: 0 Function: 3 Offset: 98h; Bus: X Device: 0 Function: 4 Offset: 98h; Bus: X Device: 0 Function: 5 Offset: 98h;			
Bit	Attr	Default	Description
15	RV	0b	<b>Reserved.</b>
14:12	RO	000b	<b>Max_Read_Request_Size (MRRS):</b> This field sets the maximum Read Requests size for the function as a requester. The Function must not generate read requests with size exceeding the set value. 000b: 128 bytes maximum Read Request size 001b: 256 bytes maximum Read Request size 010b: 512 bytes maximum Read Request size 011b: 1024 bytes maximum Read Request size 100b: 2048 bytes maximum Read Request size 101b: 4096 bytes maximum Read Request size Others: Reserved Functions that do not generate Read Requests larger than 128B and functions that do not generate Read Requests on their own behalf are permitted to implement this field as Read Only (RO) with a value of 000b.



<b>DEVCTL</b> <b>Bus: X Device: 0 Function: 3 Offset: 98h;</b> <b>Bus: X Device: 0 Function: 4 Offset: 98h;</b> <b>Bus: X Device: 0 Function: 5 Offset: 98h;</b>			
Bit	Attr	Default	Description
11	RO	0b	<b>Enable No Snoop (ENOSNP):</b> If this bit this is set, the function is permitted to set the No Snoop bit in the Requester attributes of transactions it initiates that do not require hardware enforced cache coherency. This bit is permitted to be hardwired to 0b if a function would never set the No Snoop attribute in transactions it initiates.
10	RO	0b	<b>Auxiliary Power PM Enable (AUXPME):</b> Not supported
9	RO	0b	<b>Phantom Function Enable (PFE):</b> When set, this bit enables a function to user unclaimed functions as phantom functions to extend the number of outstanding transaction identifiers. Functions that do not implement this capability hardware this bit to 0b.
8	RO	0b	<b>Extended Tag Field Enable (ETFE):</b> When set, this bit enables a function to use an 8-bit tag field as a Requester. Functions that do not implement this capability hardwire this bit to 0b.
7:5	R/W	000b	<b>Maximum Payload Size (MPS):</b> This field sets maximum TLP payload size for the function. As a receiver, the function must handle TLPs as larger as the set value. As a Transmitter, the function must not generate TLPs exceeding the set value. 000b: 128 bytes maximum payload size 001b: 256 bytes maximum payload size 010b: 512 bytes maximum payload size (Unsupported) 011b: 1024 bytes maximum payload size (Unsupported) 100b: 2048 bytes maximum payload size (Unsupported) 101b: 4096 bytes maximum payload size (Unsupported) Others: Reserved
4	RO	0b	<b>Enable Relaxed Ordering (ENRO):</b> When set, the function is permitted to set the relaxed ordering bit in the attribute field of transactions it initiates that do not require strong write ordering. A function is permitted to hardwire this bit to 0b if it never sets the Relaxed ordering attribute in transactions it initiates as a requester.
3	R/W	0b	<b>Unsupported Request Reporting Enable (URRE):</b> This bit controls the enabling of ERR_CORR, ERR_NONFATAL or ERR_FATAL messages on PCI Express for reporting "Unsupported Request" errors.
2	R/W	0b	<b>Fatal Error Reporting Enable (FERE):</b> When this bit is set, generation of the ERR_FATAL message is enabled.
1	R/W	0b	<b>NonFatal Error Reporting Enable (NFERE):</b> When this bit is set, generation of the ERR_NONFATAL message is enabled.
0	R/W	0b	<b>Correctable Error Reporting Enable (CERE):</b> When this bit is set, generation of the ERR_CORR message is enabled.



### 27.1.3.5 Device Status Register (DEVSTS)

DEVSTS				
Bus: X		Device: 0	Function: 3	Offset: 9Ah;
Bus: X		Device: 0	Function: 4	Offset: 9Ah;
Bus: X		Device: 0	Function: 5	Offset: 9Ah;
Bit	Attr	Default	Description	
15:6	RV	000h	<b>Reserved Zero:</b> Software must always write a 0 to these bits.	
5	RO	0b	<b>Transactions Pending (TP):</b> When set, this bit indicates that the function has issued Non-Posted REquests that have not been completed. For Root or Switch port, it applies to Non-Posted Requests the port has issued on its own behalf (Port's Request ID). A function reports this bit cleared only when all outstanding Non-Posted Requests have completed. Functions that do not issue Non-Posted requests on their own behalf hardwire this bit to 0b.	
4	RO	0b	<b>Auxiliary Power Detected (APD):</b> Auxiliary Power is not supported.	
3	R/W1C	0b	<b>Unsupported Request Detected (URD):</b> This bit indicates that this function received an unsupported request from PCI Express link. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register.	
2	R/W1C	0b	<b>Fatal Error Detected (FED):</b> This bit indicates that this function has detected a Fatal error. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register.	
1	R/W1C	0b	<b>Non-Fatal Error Detected (NFED):</b> This bit indicates that this function has detected a Non-Fatal error. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register.	
0	R/W1C	0b	<b>Correctable Error Detected (CED):</b> This bit indicates that this function has detected a Correctable error. Errors are logged in this register regardless of whether error reporting is enabled or not in the Device Control register.	

### 27.1.3.6 Link Capabilities Register (LINKCAP)

LINKCAP				
Bus: X		Device: 0	Function: 3	Offset: 9Ch;
Bus: X		Device: 0	Function: 4	Offset: 9Ch;
Bus: X		Device: 0	Function: 5	Offset: 9Ch;
Bit	Attr	Default	Description	
31:24	RO	00h	<b>Port Number (PN):</b> This field indicates the PCI Express* port number assigned to this link.  <b>Note:</b> Applicable to the downstream ports only. Read-only for upstream port.	
23:22	RV	00h	Reserved	
21	RO	0b	Link Bandwidth Notification Capability (LBNC):	
20	RO	0b	Data Link Layer Active Error Reporting Capable (DLLERC):	
19	RO	0b	Surprise Link Down Error Reporting Capable (SLDERC):	
18	RO	0b	Clock Power Management Capable (CPMC):	



<b>LINKCAP</b> <b>Bus: X Device: 0 Function: 3 Offset: 9Ch;</b> <b>Bus: X Device: 0 Function: 4 Offset: 9Ch;</b> <b>Bus: X Device: 0 Function: 5 Offset: 9Ch;</b>			
Bit	Attr	Default	Description
17:15	RO	000b	<b>L1 Exit Latency(L1EL):</b> This field indicates the L1 exit latency for the given PCI-Express Link. It indicates the length of time this port requires to complete transition from L1 to L0. 000: Less than 1us 001: 1 us to less than 2 us 010: 2 us to less than 4 us 011: 4 us to less than 8 us 100: 8 us to less than 16 us 101: 16 us to less than 32 us 110: 32 us to less than 64 us 111: More than 64 us
14:12	RO	000b	<b>L0s Exit Latency(L0sEL):</b> This field indicates the L0s exit latency for the given PCI Express Link. It indicates the length of time this port requires to complete transition from L0s to L0. 000b: Less than 64 ns 001b: 64 ns to less than 128 ns 010b: 128 ns to less than 256 ns 011b: 256 ns to less than 1 us 101b: 1 us to less than 2 us 110b: 2 us to less than 4 us 111b: More than 4 us
11:10	RO	11b	<b>ASPM Support (ASPMSUP):</b> This field indicates the level of ASPM supported on the given PCI Express* Link. 00b: Reserved 01b: L0s Entry Supported 10b: Reserved 11b: L0s and L1 Supported
9:4	RO	01h	<b>Maximum Link Width (MLW):</b> This field indicates the maximum link width implemented by the given PCI Express* Link. 00h: Reserved 01h: x1 02h: x2 04h: x4 08h: x8 10h: x16 20h: x32 (Unsupported) Others Reserved
3:0	RO	1h	<b>Maximum Link Speed (MLS):</b> This field indicates the supported link speed(s) for the associated port. 0001b: 2.5 Gb/s link speed is supported 0010b: 5.0 Gb/s and 2.5 Gb/s link speed supported Others: Reserved.



### 27.1.3.7 Link Control Register (LINKCTL)

LINKCTL				
Bus: X		Device: 0	Function: 3	Offset: A0h;
Bus: X		Device: 0	Function: 4	Offset: A0h;
Bus: X		Device: 0	Function: 5	Offset: A0h;
Bit	Attr	Default	Description	
15:12	RV	0h	Reserved	
11	RO	0b	<b>Link Autonomous Bandwidth Interrupt Enable (LABIE):</b> When Set, this bit enables the generation of an interrupt to indicate that the Link Autonomous Bandwidth Status bit has been set. Functions that do not implement the Link Bandwidth Notification Capability must hardwire this bit to 0b.	
10	RO	0b	<b>Link Bandwidth Management Interrupt Enable (LBMIE):</b> When set, this bit enables the generation of an interrupt to indicate that the Link Bandwidth Management Status bit has been set. Functions that do not implement the Link Bandwidth Notification Capability must hardwire this bit to 0b.	
9	RO	0b	<b>Hardware Autonomous Width Disable (HAWD):</b> When set, this bit disables hardware from changing the Link Width for reasons other than attempting to correct unreliable Link operation by reducing Link width. Components that do not implement the ability to autonomously change link width are permitted to hardwire this bit to 0b.	
8	RO	0b	<b>Enable Clock Power Management (ECPM):</b> Not Applicable.	
7	R/W	0b	<b>Extended Synch (ES):</b> When set, this bit forces extended transmission of 4096 FTS ordered sets in FTS and an extra 1024 TS1 at exit from L1 prior to entering L0. This mode provides external devices monitoring the link time to achieve bit and symbol lock before the link enters L0 state and resumes communication. Default value for this bit is 0.	
6	R/W	1b	<b>Common Clock Configuration (CCCFG):</b> When set, this bit indicates that this component and the component at the opposite end of this link are operating with distributed common reference clocks. A value of 0b indicates that this component and the component at the opposite end of this link are operating with asynchronous reference clock. After changing the value in this bit in bother components on a link, software must trigger the link to retrain by writing a 1b to the Retrain Link bit of the Downstream Port.	
5	RO	0b	<b>Retrain Link (RL):</b> When set, this bit initiates link retraining by directing the physical layer LTSSM to recovery state. If the LTSSM is already in REcovery or configuration, re-entering Recovery is permitted but not required. Reads of this bit always return 0b. This is used by the downstream ports only. For the upstream port, it is Read-only.	
4	RO	0b	<b>Link Disable (LD):</b> When set, this bit disables the link by directing the LTSSM to the disabled state when set. This bit is reversed on Endpoints, for the given PCI Express* port. This is used by the downstream ports only. For the upstream port, it is Read-only.	
3	RO	0b	<b>Read Completion Boundary (RCB):</b> This bit indicates the RCB value for Root Port, Endpoints and Bridges. 0b: 64 byte 1b: 128 byte Not applicable to switch ports - must be hardwire the bit to 0b.	
2	RV	0b	Reserved	
1:0	R/W	00b	<b>ASPM Control (ASPMCTL):</b> This field controls the level of ASPM supported on a given PCI Express* Link. 00b: Disabled 01b: L0s Entry Enabled 10b: L1 Entry Enabled 11b: L0s and L1 Entry Enabled	



### 27.1.3.8 Link Status Register (LINKSTS)

LINKSTS			
Bus: X Device: 0 Function: 3 Offset: A2h;			
Bus: X Device: 0 Function: 4 Offset: A2h;			
Bus: X Device: 0 Function: 5 Offset: A2h;			
Bit	Attr	Default	Description
15	RO	0b	<p><b>Link Autonomous Bandwidth Status (LABS):</b>            This bit is set by hardware to indicate that hardware has autonomously changes link or width, without the port transitioning through DL_Down status, for reason other than to attempt to correct unreliable link operation.            This bit is not applicable and is reserved for endpoints, PCI Express-to-PCI/PCI-X bridges, and upstream ports of switches.            Functions that do not implement the Link Bandwidth Notification Capability must hardwire this bit to 0b.</p>
14	RO	0b	<p><b>Link Bandwidth Management Status (LBMS):</b>            This bit is set by hardware to indicate that either of the following has occurred without the port transitioning through DL_Down status:</p> <ul style="list-style-type: none"> <li>• A link retraining has completed following a write of 1b to the Retrain link bit.</li> <li>• Hardware has changed link speed or width to attempt to correct unreliable link operation, either through an LTSSM timeout or a higher level process.</li> </ul> <p>This bit is not applicable and is reserved for endpoints, PCI Express-to-PCI/PCI-X bridges, and upstream ports of switches.            Functions that do not implement the Link Bandwidth Notification Capability must hardwire this bit to 0b.</p>
13	RO	0b	<p><b>Data Link Layer Link Active (DLLLA):</b>            This bit indicates the status of the Data Link Control and Management Status Machine. It returns a 1b to indicate the DL_Active state, 0b otherwise.</p>
12	RO	1b	<p><b>Slot Clock Configuration (SCC):</b>            When the <b>X</b> is on a PCI Express connector, this bit indicates whether it is using the same reference clock that is provided at the connector.            Indicates independent reference clock            Indicates same reference clock.</p>
11	RO	0	<p><b>Link Training (LT):</b>            This bit indicates that the Physical Layer LTSSM is in the Configuration or Recovery state, or a 1b was written to the Retrain Link bit but the Link training has not yet begun. Hardware clears this bit when the LTSSM exits the Configuration/Recovery state.            This field is not applicable and reserved for the upstream port, and must be hardwired to 0b.</p>
10	RO	0	<p><b>Undefined:</b> Not applicable</p>
9:4	RO	1h	<p><b>Negotiated Link Width (NLW):</b>            This field indicates the negotiated width of the PCI Express link.            00 0001b: x1            00 0010b: X2            00 0100b: x4            00 1000b: X8            00 1100b: X12—not supported            01 0000b: X16            10 0000b: X32—not supported            All other values are reserved.</p>
3:0	RO	1h	<p><b>Current Link Speed (CLS):</b>            This field indicates the negotiated link speed of the given PCI Express link.            0001b: 2.5 Gb/s PCI Express Link            0010b: 5.0 Gb/s PCI Express Link            Others: Reserved            The value in this field is undefined when the link is not up.</p>



### 27.1.3.9 Device Capabilities 2 Register (DEVCAP2)

DEVCAP2			
Bus: X Device: 0 Function: 3 Offset: B4h;			
Bus: X Device: 0 Function: 4 Offset: B4h;			
Bus: X Device: 0 Function: 5 Offset: B4h;			
Bit	Attr	Default	Description
31:6	RV	0	Reserved.
5	RO	0b	<b>Alternative RID Interpretation Capable (ARI):</b> This bit is set to 1b when indicating that the switch downstream or root port supports this capability. Must be 0b for all other types of functions.
4	RO	0b	<b>Completion Timeout Disable Support (CTDS):</b> A value of 1b indicates support for the completion Timeout Disable Mechanism. Support of completion timeout disable is optional for Root Ports. The port supports completions timeout disable.
3:0	RO	0h	<b>Completion Timeout Range Supported (CTRS):</b> This field indicates device support for the optional Completion Timeout programmability mechanism. This mechanism allows system software to modify the Completion Timeout value. This field is applicable only to Root Ports, Endpoints that issue requests on their own behalf, and PCI Express* to PCI/PCI-X Bridges that take ownership of request issues on PCI Express. For all other devices this field is reserved and maybe be hardwired to 0000b. Four time values ranges are defined: Range A: 50 us to 10 ms Range B: 10 ms to 250 ms Range C: 250 ms to 4 s Range D: 4 s to 64 s Bits are set according to table below to show timeout value ranges supported. 0000b: Completions Timeout programming not supported -- values is fixed by implementation in the range 50us to 50ms. 0001b: Range A 0010b: Range B 0011b: Range A & B 0110b: Range B & C 0111b: Range A, B, & C 1111b: Range A, B, C & D All other values are reserved.



### 27.1.3.10 Device Control 2 Register (DEVCTL2)

DEVCTL2			
Bus: X Device: 0 Function: 3 Offset: B8h;			
Bus: X Device: 0 Function: 4 Offset: B8h;			
Bus: X Device: 0 Function: 5 Offset: B8h;			
Bit	Attr	Default	Description
15:6	RV	0h	Reserved.
5	RO	0b	<b>Alternative RID Interpretation Enable (ARIE):</b> When set to 1b, ARI is enabled for the downstream or root ports. Must be 0b for all other types of functions.
4	RO	0b	Completion Timeout Disable (CTD): 1: disable the completions timeout mechanism for all NP tx. 0: completion timeout is enabled for all NP tx
3:0	RO	0h	<b>Completion Timeout Value (CTV):</b> In devices that support completion timeout programmability, this field allows system software to modify the completion timeout range. The following encodings and corresponding timeout ranges are defined: 0000b: 50 us to 50 ms (16.3 ms - 24.6 ms based on core clk period) 0001b: 50 us to 100 us (61.4 us - 92.4 us based on core clk period) 0010b: 1 ms to 10 ms (2.6 ms - 3.9 ms based on core clk period) 0101b: 16 ms to 55 ms (16.3 ms - 24.6 ms based on core clk period) 0110b: 65 ms to 210 ms (83.8 ms - 126.1 ms based on core clk period) 1001b: 260 ms to 900 ms (335.5 ms - 504.5 ms based on core clk period) 1010b: 1s to 3.5 s (1.3 s - 2.1 s based on core clk period) All others are reserved. 1111b: 256 core clock cycles for SV debug. <b>Note:</b> It is highly recommended that the completion timeout value not be less than 10ms. A small completion timeout value may result in premature completion timeout for slower responding devices. If a greater than 25 ms timeout value is required.

### 27.1.3.11 Device Status 2 Register (DEVSTS2)

DEVSTS2			
Bus: X Device: 0 Function: 3 Offset: BAh;			
Bus: X Device: 0 Function: 4 Offset: BAh;			
Bus: X Device: 0 Function: 5 Offset: BAh;			
Bit	Attr	Default	Description
15:0	RV	0h	Reserved.

### 27.1.3.12 Link Capabilities 2 Register (LINKCAP2)

LINKCAP2			
Bus: X Device: 0 Function: 3 Offset: BCh;			
Bus: X Device: 0 Function: 4 Offset: BCh;			
Bus: X Device: 0 Function: 5 Offset: BCh;			
Bit	Attr	Default	Description
15:0	RV	0h	Reserved.



### 27.1.3.13 Link Control 2 Register (LINKCTL2)

LINKCTL2 Bus: X Device: 0 Function: 3 Offset: C0h; Bus: X Device: 0 Function: 4 Offset: C0h; Bus: X Device: 0 Function: 5 Offset: C0h;			
Bit	Attr	Default	Description
15:13	RV	0h	Reserved.
12	RO	0b	<p><b>Compliance De-emphasis (CD):</b> This bit sets the de-emphasis level in Polling.Compliance state if the entry occurred due to the Enter Compliance bit being 1b. 1b: -3.5 dB 0b: -6 dB When the link is operating at 2.5 Gb/s, the setting of this bit has no effect.</p>
11	RO	0b	<p><b>Compliance SOS (CSOS):</b> When set to 1b, the LTSSM is required to send Skip Ordered Sets periodically in between the (modified) compliance patterns. This bit has no affect on hardware.</p>
10	RO	0b	<p><b>Enter Modified Compliance (EMC):</b> When set to 1b, the device transmits Modified Compliance Pattern if the LTSSM enters Polling.Compliance substate. This bit has no affect on hardware.</p>
9:7	RO	000b	<p><b>Transmit Margin (TM):</b> This field controls the value of the non-deemphasized voltage level at the transmitter pins. This field is reset to 000b on entry to the LTSSM Polling.Configuration substate. 000b: Normal operating range 001b: 800-1200 mV for full swing and 400-700 mV for half-swing 010b-110b: TBD Others: Reserved This field has no affect on hardware.</p>
6	RO	0b	<p><b>Selectable De-emphasis (SD):</b> When the link is operating at 5 Gb/s speed, this bit selects the level of de-emphasis for an upstream component. This bit is not applicable and reserved for Endpoints, PCI Express* to PCI/PCI-X bridges, and upstream ports of switches.</p>
5	RO	0b	<p><b>Hardware Autonomous Speed Disable (HASD):</b> When set, this bit disables hardware from changing the link speed for device specific reasons other than attempting to correct unreliable link operation by reducing link speed for device-specific reasons other than attempting to correct unreliable link operations by reducing link speed. Initial transition to the highest supported common link speed is not blocked by this bit.</p>
4	RO	0b	<p><b>Enter Compliance (EC):</b> Software is permitted to force a link to enter compliance mode at the speed indicated in the Target Link Speed field by setting this bit to 1b in both components on a link and then initiating a hot reset on the link. This bit has no affect on hardware.</p>
3:0	RO	0h	<p><b>Target Link Speed (TLS):</b> For downstream ports, this field sets an upper limit on link operational speed by restricting the values advertised by the upstream component in its training sequences.  0001b: 2.5 Gb/s Target Link Speed 0010b: 5.0 Gb/s Target Link Speed Others: Reserved</p>



### 27.1.3.14 Link Status 2 Register (LINKSTS2)

LINKSTS2			
Bus: X	Device: 0	Function: 3	Offset: C2h;
Bus: X	Device: 0	Function: 4	Offset: C2h;
Bus: X	Device: 0	Function: 5	Offset: C2h;
Bit	Attr	Default	Description
15:1	RV	0	Reserved.
0	RO	0	Current De-emphasis Level (CDL): When the link is operating at 5 Gb/s speed, this bit reflects the level of de-emphasis. 1b: -3.5 dB 0b: -6 dB

## 27.1.4 Power Management Capability Structure

This section describes the PCI Configuration Space registers that make up the PCI Power Management Capability Structure. These registers are second in the capabilities list, so they are discovered through the prior [PCI Express\\* Capability List Register \(EXPCAPLST\)](#).

Some information from the specification is repeated here as an aid to the reader or to describe implementation choice. Please refer to the *PCI Express® Base Specification 2.0* and *PCI Bus Power Management Interface Specification* for the full register descriptions and additional information regarding their operation.

### 27.1.4.1 Power Management Capability List Register (PMCAPLST)

PMCAPLST			
Bus: X	Device: 0	Function: 3	Offset: CCh;
Bus: X	Device: 0	Function: 4	Offset: CCh;
Bus: X	Device: 0	Function: 5	Offset: CCh;
Bit	Attr	Default	Description
15:8	R/WL	D4h	<b>Next Pointer (NP):</b> Contains the offset of the next item in the capabilities list. ( <a href="#">MSICAPLST</a> )
7:0	RO	01h	<b>Capability ID (CAPID):</b> Identifies the function as PCI Power Management capable.



### 27.1.4.2 Power Management Capabilities Register (PMCAP)

<b>PMCAP</b> <b>Bus: X Device: 0 Function: 3 Offset: CEh;</b> <b>Bus: X Device: 0 Function: 4 Offset: CEh;</b> <b>Bus: X Device: 0 Function: 5 Offset: CEh;</b>			
Bit	Attr	Default	Description
15:11	RO	19h	<b>PME_Support (PMES):</b> PME assertion is supported when in D3hot. PME assertion from D3cold is not supported.
10	RO	0b	<b>D2 Support (D2S):</b> Not supported
9	RO	0b	<b>D1 Support (D1S):</b> Not supported
8:6	RO	000b	<b>Auxiliary Current (AC):</b> Auxiliary power is not supported.
5	RO	0b	<b>Device Specific Initialization (DSI):</b> Device-specific initialization is not required when transitioning to D0 from D3hot state. This bit is zero.
4	RV	0b	Reserved
3	RO	0b	<b>PME Clock (PMECLK):</b> Does not apply to PCI Express. Hard-wired to 0.
2:0	RO	3h	<b>Version (VER):</b> PM implementation is compliant with <i>PCI Bus Power Management Interface Specification</i> , Revision 1.2.

### 27.1.4.3 Power Management Control / Status Register (PMCSR)

<b>PMCSR</b> <b>Bus: X Device: 0 Function: 3 Offset: D0h;</b> <b>Bus: X Device: 0 Function: 4 Offset: D0h;</b> <b>Bus: X Device: 0 Function: 5 Offset: D0h;</b>			
Bit	Attr	Default	Description
15	R/W1CS	0	<b>PME Status (PMESTS):</b>
14:13	RO	0h	<b>Data Scale (DC):</b> Not supported
12:9	RO	0h	<b>Data Select (DS):</b> Not supported
8	R/WS	0	<b>PME Enable (PMEEN):</b> Gates assertion of the PME message.
7:2	RV	0h	Reserved
1:0	R/W-R	0h	<b>Power State (PS):</b> This field is used both to determine the current power state of a function and to set the function into a new power state. The definition of the supported values is given below: 0h = D0 3h = D3hot If software attempts to write an unsupported, optional state to this field, the write operation must complete normally; however, the data is discarded and no state change occurs.



## 27.1.5 MSI Capability Structure

This section describes the PCI Configuration Space registers that make up the Message Signaled Interrupts Capability Structure.

Some information from the specification is repeated here as an aid to the reader or to describe implementation choice. Please refer to the *PCI Local Bus Specification* for the full register descriptions and additional information regarding their operation.

### 27.1.5.1 MSI Capability List Register (MSICAPLST)

MSICAPLST			
Bus: X Device: 0 Function: 3 Offset: D4h;			
Bus: X Device: 0 Function: 4 Offset: D4h;			
Bus: X Device: 0 Function: 5 Offset: D4h;			
Bit	Attr	Default	Description
15:8	R/WL	0h	<b>Next Pointer (NP):</b> Contains the offset of the next item in the capabilities list. A null value is used to indicate that this is the last capability.
7:0	RO	05h	<b>Capability ID (CAPID):</b> Identifies the function as MSI capable.

### 27.1.5.2 MSI Message Control Register (MSICTL)

MSICTL			
Bus: X Device: 0 Function: 3 Offset: D6h;			
Bus: X Device: 0 Function: 4 Offset: D6h;			
Bus: X Device: 0 Function: 5 Offset: D6h;			
Bit	Attr	Default	Description
15:8	RV	00h	Reserved
7	RO	0b	<b>Address 64-Bit Capable (AD64C):</b> When set, this bit indicates that the function is capable of generating a 64-bit message address.
6:4	R/W	000b	<b>Multiple Message Enable (MMEN):</b> Only one message is supported. These bits are R/W for software compatibility.
3:1	RO	000b	<b>Multiple Message Capable (MMC):</b> Only one message is supported.
0	R/W	0b	<b>MSI Enable (MSIE):</b> When set, MSI is enabled and traditional interrupt pins are not used to generate interrupts.

### 27.1.5.3 MSI Message Address Register (MSIADDR)

MSIADDR			
Bus: X Device: 0 Function: 3 Offset: D8h;			
Bus: X Device: 0 Function: 4 Offset: D8h;			
Bus: X Device: 0 Function: 5 Offset: D8h;			
Bit	Attr	Default	Description
31:2	R/W	0h	<b>Address:</b> Message address specified by the system, always DWORD aligned
1:0	RV	00b	Reserved



### 27.1.5.4 MSI Message Data Register (MSIDATA)

MSIDATA			
Bus: X Device: 0 Function: 3 Offset: DCh;			
Bus: X Device: 0 Function: 4 Offset: DCh;			
Bus: X Device: 0 Function: 5 Offset: DCh;			
Bit	Attr	Default	Description
15:0	R/W	0000h	<b>Data:</b> This 16-bit field is programmed by system software when MSI is enabled. Its content is driven onto the lower word (D[15:0]) of the MSI memory write transaction.

## 27.1.6 Implementation Specific Registers

This section describes the PCI Express\* Configuration Space registers that are specific to the PCH implementation. These registers are unique to the device and are only discovered by being listed in the Component Specification.

### 27.1.6.1 Host Configuration Register (HSTCFG)

HSTCFG			
Bus: X Device: 0 Function: 3 Offset: 40h;			
Bus: X Device: 0 Function: 4 Offset: 40h;			
Bus: X Device: 0 Function: 5 Offset: 40h;			
Bit	Attr	Default	Description
7:4	RV	0h	Reserved
3	R/W	0h	<b>Soft SMBus Reset (SSRESET):</b> When set to 1b, the SMBus state machine and logic in SMBus is reset. The hardware will reset this bit to 0 when reset operation is completed.
2	R/WS	0h	<b>I<sup>2</sup>C Enable:</b> When set to 1b, the SMBus controller communicates with I <sup>2</sup> C devices. This will change the formatting of some commands. The controller behaves as an SMBus controller otherwise.
1	RO	0h	<b>SMI Enable:</b> When set to 1b, any source of an SMB interrupt will instead be routed to generate an SMI#. This feature is not supported for the SMBus controllers.
0	R/WS	0h	<b>Host Enable:</b> When set to 1b, the SMBus Host controller interface is enabled to execute commands. The HSTCTL.Interrupt Enable bit needs to be enabled in order for the SMB host Controller to interrupt. Additionally, the SMBus Host controller will not respond to any new requests until all interrupt requests have been cleared.



### 27.1.6.2 Host Timing Control Register (HSTTCTL)

HSTTCTL			
Bus: X Device: 0 Function: 3 Offset: 64h;			
Bus: X Device: 0 Function: 4 Offset: 64h;			
Bus: X Device: 0 Function: 5 Offset: 64h;			
Bit	Attr	Default	Description
31:24	R/WS	08h	<b>THIGH Value:</b> This field determines the time value to added/subtracted to the nominal Thigh timing parameter as defined in the SMB 2.0 spec.  00h: -7 clocks (-840 ns) 01h: -6 clocks (-720 ns) ... 07h: -1 clock (-120 ns) 08h: 0 clock (0 ns) 09h: 1 clock (120 ns) ... FFh: 247 clocks (29640 ns)
23:16	R/WS	00h	<b>TLOW Value:</b> This field determines the time value to add/subtract to the nominal Thigh timing parameter as defined in the SMB 2.0 spec.  Refer to THIGH Value field for defined values.
15:12	R/WS	0h	<b>THDSTA Value:</b> This field determines the time value to add/subtract to the nominal Thdsta timing parameter as defined in the SMB 2.0 spec. Fh: -7 clocks (-840 ns) Eh: -6 clocks (-720 ns) ... 9h: -1 clock (-120 ns) 8h: 0 clock (0 ns) 7h: 7 clocks (840 ns) ... 1h: 1 clock (120 ns) 0h: 0 clock (0 ns)
11:8	R/WS	0h	<b>TSUSTA Value:</b> This field determines the time value to add/subtract to the nominal Thdsta timing parameter as defined in the SMB 2.0 spec. Refer to THDSTA Value field for defined values.
7:4	R/WS	0h	<b>TBUF Value:</b>
3:0	R/WS	0h	<b>TTSUSTO Value:</b> This field determines the time value to add/subtract to the nominal Thdsta timing parameter as defined in the SMB 2.0 spec. Refer to THDSTA Value field for defined values.

This register affects the SMBus master timing parameters. Values should only be changed when the SMBus is idle.

### 27.1.6.3 Shadowed Max Payload Size Control Register (SDWMPCTL)

SDWMPCTL			
Bus: X Device: 0 Function: 3 Offset: 7Ch;			
Bus: X Device: 0 Function: 4 (Alias:);			
Bus: X Device: 0 Function: 5 (Alias:);			
Bus: X Device: 0 Function: 6 (Alias:);			
Bit	Attr	Default	Description
31:8	RV	0h	Reserved



SDWMPCTL			
Bus: X Device: 0 Function: 3 Offset: 7Ch;			
Bus: X Device: 0 Function: 4 (Alias:);			
Bus: X Device: 0 Function: 5 (Alias:);			
Bus: X Device: 0 Function: 6 (Alias:);			
Bit	Attr	Default	Description
7:5	R/W	0b	<p><b>Shadowed Max Payload Size (SMPS):</b>                      This field is the shadowed copy of the Function 0's MPS register to support ARI Functions. The Multi-function Glue will update this register. Software should not write to this register. Hardware should use this register field instead of the DEVCTL.MPS field as the max payload size.</p> <p>000b: 128 bytes maximum payload size                      001b: 256 bytes maximum payload size                      010b: 512 bytes maximum payload size (Unsupported)                      011b: 1024 bytes maximum payload size (Unsupported)                      100b: 2048 bytes maximum payload size (Unsupported)                      101b: 4096 bytes maximum payload size (Unsupported)                      Others: Reserved</p>
4:0	RV	0h	Reserved.

**27.1.6.4 SMBus Mode Control Register (SMBMODE)**

SMBMODE			
Bus: X Device: 0 Function: 3 Offset: 80h;			
Bus: X Device: 0 Function: 4 Offset: 80h;			
Bus: X Device: 0 Function: 5 Offset: 80h;			
Bit	Attr	Default	Description
31:16	RV	0h	Reserved
15:8	R/WS	00b	Unused0
7	R/WS	00b	<p>I<sup>2</sup>C Operating Frequency Mode (I2COFM):                      This bit set the operating frequency for the IO buffers when operating in I<sup>2</sup>C mode.                      0b: Standard &amp; Fast Modes                      1b: Fast Mode Plus</p> <p><b>Note:</b> This bit control the ogioi2ccfg signal to the IO buffers.</p>
6	R/WS	00b	<p>I<sup>2</sup>C Mode Disable (I2CMD):                      This bit when set to 1 disable i2C mode in the IO buffers.                      0b: I<sup>2</sup>C/SMB interface                      1b: Cmos interface mode</p> <p><b>Note:</b> This bit control the ogioi2cenb signal to the IO buffers.</p>
5	RO	0b	<p><b>Slave Auto Clock Stretch Enable (SACSE):</b>                      Setting this bit to 1b will cause HW to start stretching SMBus clock even if it is not the target of the SMBus transaction.  <b>Note:</b> Field has no effect because slave mode not used.</p>
4	RO	0b	<p><b>Watchdog Timer Read Policy (WTRP):</b>                      Setting this bit to 1b will select the legacy behavior when reading SMB slave register 3 for the watchdog timer (bit 5 is logically the OR of timer bits 9:5, bits 4:0 mapped to bits 4:0 of the timer. When this bit is 0b, reads to the SMBus slave register 3 returns 3Fh if the watchdog timer is equal or greater than the 6-bit value 3Fh.  <b>Note:</b> Field has no effect because slave mode not used.</p>
3	RV	0b	Reserved
2	R/WS	0b	<p><b>Block Write Interrupt Policy (BWIP):</b>                      Setting this bit to 1b will enable the SMBus host to always generate n+1 interrupts for a block write of n bytes (with e32b disabled).</p>



Bit	Attr	Default	Description
<b>SMBMODE</b> Bus: X Device: 0 Function: 3 Offset: 80h; Bus: X Device: 0 Function: 4 Offset: 80h; Bus: X Device: 0 Function: 5 Offset: 80h;			
1	R/W	0b	<b>Block Read Interrupt Policy (BRIP):</b> Setting this bit will enable the SMB host to always generate n+1 interrupts for a block read of n bytes (with e32b disabled)
0	RO	0b	<b>Repeat Policy:</b> Setting this bit will revert back to the legacy behavior of ignoring the R/W bit field during a repeat start for any SMBus read protocol as a slave. <b>Note:</b> Field has no effect because slave mode not used.

### 27.1.6.5 Device Clock Gate Control Register (DEVCLKGCTL)

Bit	Attr	Default	Description
<b>DEVCLKGCTL</b> Bus: X Device: 0 Function: 3 Offset: E4h; Bus: X Device: 0 Function: 4 (Alias:); Bus: X Device: 0 Function: 5 (Alias:); Bus: X Device: 0 Function: 6 (Alias:);			
15	R/W PRST	0b	<b>Idle Clock Gate Enable (ICGE):</b> This bit when set enables clock gating to occur when the IP block is idle longer than the Idle Clock Timer.
14:8	RV	000b	Reserved
7:0	R/W PRST	10h	<b>Idle Clock Timer (ICT):</b> This field indicates the number of oclocks that the IP block must be idle before the clock disable process begins. <b>Note:</b> 16 (default value) is the minimum number of clocks recommended.

IDF NVSRAM Device Clock Gate Control Register is defined here.

### 27.1.6.6 Sideband Device Clock Gate Control Register (SBDEVCLKGCTL)

Bit	Attr	Default	Description
<b>SBDEVCLKGCTL</b> Bus: X Device: 0 Function: 3 Offset: E6h; Bus: X Device: 0 Function: 4 (Alias:); Bus: X Device: 0 Function: 5 (Alias:); Bus: X Device: 0 Function: 6 (Alias:);			
15	R/W PRST	0b	<b>Idle Clock Gate Enable (ICGE):</b> This bit when set enables clock gating to occur when the IP block is idle longer than the Idle Clock Timer.
14:8	RV	000b	Reserved
7:0	R/W PRST	10h	<b>Idle Clock Timer (ICT):</b> This field indicates the number of oclocks that the IP block must be idle before the clock disable process begins. <b>Note:</b> 16 (default value) is the minimum number of clocks recommended.

IDF NVSRAM Sideband Device Clock Gate Control Register is defined here.



### 27.1.6.7 Personality Lock Key Control Register (PLKCTL)

<b>PLKCTL</b> Bus: X Device: 0 Function: 3 Offset: E8h; Bus: X Device: 0 Function: 4 Offset: E8h; Bus: X Device: 0 Function: 5 Offset: E8h;			
Bit	Attr	Default	Description
15:1	RV	0h	Reserved
0	R/W-KL PRST	0b	<b>Capability Lock (CL):</b> Lock key bit for all R/WL bits (capabilities, next capability pointer, SSID/SVID, slot register, etc) bits for the function. 1b: Lock 0b: Unlocked  <b>Note:</b> This bit is self-locking. Once this bit is set to a 1b, this key bit can not be unlocked. Writing a 0b has no affect on this bit.

### 27.1.6.8 Configuration Agent Error Register (CFGAGTERR)

<b>CFGAGTERR</b> Bus: X Device: 0 Function: 3 Offset: FCh; Bus: X Device: 0 Function: 4 (Alias:); Bus: X Device: 0 Function: 5 (Alias:); Bus: X Device: 0 Function: 6 (Alias:);			
Bit	Attr	Default	Description
31:14	RV	0h	Reserved.
13	R/W1CS	0b	<b>Command Parity Error Status (CPES):</b>
12	R/W1CS	0b	<b>Data Parity Error Status (DPES):</b>
11	R/W1CS	0b	<b>Poisoned TLP Error Status (PTES):</b>
10	R/W1CS	0b	<b>SMBus0 Internal Parity Error Status (S0IPES):</b>
9	R/W1CS	0b	<b>SMBus1 Internal Parity Error Status (S1IPES):</b>
8	R/W1CS	0b	<b>SMBus2 Internal Parity Error Status (S2IPES):</b>
7	R/W1CS	0b	<b>NVSRAM Internal Parity Error Status (NIPES):</b>
6	R/WS	0b	<b>Command Parity Error Mask (CPEM):</b>
5	R/WS	0b	<b>Data Parity Error Mask (DPEM):</b>
4	R/WS	0b	<b>Poisoned TLP Error Mask (PTEM):</b>
3	R/WS	0b	<b>SMBus0 Internal Parity Error Mask (S0IPEM):</b>
2	R/WS	0b	<b>SMBus1 Internal Parity Error Mask (S1IPEM):</b>
1	R/WS	0b	<b>SMBus2 Internal Parity Error Mask (S2IPEM):</b>
0	R/WS	0b	<b>NVSRAM Internal Parity Error Mask (NIPEM):</b>



### 27.1.6.9 Uncorrectable Error Status Register (ERRUNCSTS)

ERRUNCSTS			
Bus: X Device: 0 Function: 3 Offset: 110h;			
Bus: X Device: 0 Function: 4 (Alias:);			
Bus: X Device: 0 Function: 5 (Alias:);			
Bit	Attr	Default	Description
31:25	RV	000h	Reserved
24	RO	0b	<b>Atomic Egress Blocked Error (AEBE):</b> This bit is set whenever an AtomicOP TLP is blocked on any egress port Not Applicable.
23	RO	0b	<b>MC Blocked TLP Error (MCE):</b> This bit is set whenever a Multicast TLP is blocked. Not Applicable.
22	R/W1CS	0b	<b>Uncorrectable Internal Error (UIE):</b> This bit is set whenever a uncorrectable internal error is detected.
21	RO	0b	<b>ACS Violation Error (ACSE):</b> This bit is set whenever an ACS violation is detected by the PCI Express* port. Not Applicable.
20	R/W1CS	0b	<b>Unsupported Request Error (URE):</b> This bit is set whenever an unsupported request is detected on PCI Express.
19	RO	0b	<b>ECRC Check Error (ECRCE):</b> PCH does not do ECRC checking, and this bit is never set. Not Applicable.
18	R/W1CS	0b	<b>Malformed TLP Error (MTLPE):</b> This bit is set when it receives a malformed TLP. Header logging is performed.
17	RO	0b	<b>Receiver Overflow Error (ROE):</b> This bit is set when the PCI Express interface unit receive buffers overflow. Not supported.
16	R/W1CS	0b	<b>Unexpected Completion Error (UCE):</b> This bit is set whenever a completion is received with a requestor ID that does not match side A or side B, or when a completion is received with a matching requestor ID but an unexpected tag field. Header logging is performed. <b>Note:</b> This bit will never be set for the SMBus functions.
15	R/W1CS	0b	<b>Completer Abort Error (CAE):</b> The bridge sets this bit and logs the header associated with the request when the configuration unit signals a completer abort.
14	RO	0b	<b>Completion Timeout Error (CTE):</b> This bit is set when upstream memory configuration I/O reads do not receive completions within 16–32 ms. Not supported.
13	RO	0b	<b>Flow Control Error (FCE):</b> This bit is set when a flow control protocol error is detected. Not supported.
12	R/W1CS	0b	<b>Poisoned TLP Error (PTLPE):</b> This bit is set and the bridge logs the header when a poisoned TLP is received from PCI Express.
11:6	RV	00h	<b>Reserved Zero:</b> Software must write 0 to these bits.
5	RO	0b	<b>Surprise Link Down Error (SLDE):</b> This bit is set when a surprise link down error is detected. Not supported.
4	RO	0b	<b>Data Link Protocol Error (DLPE):</b> This bit is set when a data link protocol error is detected.
3:0	RV	000b	Reserved

This is implementation specific register.



### 27.1.6.10 Uncorrectable Error Detect Mask Register (ERRUNCDETMSK)

<b>ERRUNCDETMSK</b> Bus: X Device: 0 Function: 3 Offset: 114h; Bus: X Device: 0 Function: 4 (Alias:); Bus: X Device: 0 Function: 5 (Alias:);			
Bit	Attr	Default	Description
31:25	RV	000h	Reserved
24	RO	0b	<b>AtomicOp Egress Blocked Error Detect Mask (AEBEDM):</b> Not Applicable.
23	RO	0b	MC Blocked TLP Error Detect Mask (MCEDM): Not Applicable.
22	R/WS	0b	Uncorrectable Internal Error Detect Mask (UIEDM):
21	RO	0b	ACS Violation Error Detect Mask (ACSEDM): Not Applicable.
20	R/WS	0b	<b>Unsupported Request Error Detect Mask (UREDMD):</b>
19	RO	0b	<b>ECRC Check Error Mask (ECRCEDM):</b> Not supported
18	R/WS	0b	<b>Malformed TLP Error Detect Mask (MTLPEDM):</b>
17	RO	0b	<b>Receiver Overflow Error Detect Mask (ROEDM):</b> Not Applicable.
16	R/WS	0b	<b>Unexpected Completion Error Detect Mask (UCEDM):</b>
15	R/WS	0b	<b>Completer Abort Error Detect Mask (CAEDM):</b>
14	RO	0b	<b>Completion Timeout Error Detect Mask (CTEDM):</b> Not Applicable.
13	RO	0b	<b>Flow Control Error Detect Mask (FCEDM):</b> Not Applicable.
12	R/WS	0b	<b>Poisoned TLP Error Detect Mask (PTLPEDM):</b>
11:6	RV	00h	Reserved
5	RO	0b	<b>Surprise Link Down Error Detect Mask (SLDEDM):</b> Not Supported.
4	RO	0b	<b>Data Link Protocol Error Detect Mask (DLPEDM):</b> Not Supported.
3:1	RV	000b	Reserved
0	RO	0b	<b>Training Error Mask:</b> Not supported



## 27.1.7 Alternative Routing-ID Interpretation Extended Capability Structure

This section describes the PCI Express\* Extended Configuration Space registers that make up the Alternative Routing-ID Interpretation Extended Capability Structure. These registers are first in the extended capabilities list, so they are located at the base of Extended Configuration Space (100h).

### 27.1.7.1 Alternative Routing-ID Interpretation Extended Capability Header (ARICAPHDR)

Bit	Attr	Default	Description
<b>ARICAPHDR</b> Bus: X Device: 0 Function:3 Offset: 100h; Bus: X Device: 0 Function:4 Offset: 100h; Bus: X Device: 0 Function:5 Offset: 100h;			
31:20	RO	000h	<b>Next Capability Offset (NCO):</b> Contains the offset of the next structure in the Extended Capabilities list. <b>Note:</b> Lock Key bit is located in the Personality Lock Key Control Register ("PLKCTL").
19:16	RO	1h	<b>Capability Version (CV):</b> Indicates the version of the Capability structure present.
15:0	RO	000Eh	<b>Extended Capability ID (ECID):</b> Identifies the function as Alternative Routing-ID Interpretation capable.

### 27.1.7.2 Alternative Routing-ID Interpretation Capability Register (ARICAP)

Bit	Attr	Default	Description
<b>ARICAP</b> Bus: X Device: 0 Function:3 Offset: 104h; Bus: X Device: 0 Function:4 Offset: 104h; Bus: X Device: 0 Function:5 Offset: 104h;			
15:8	R/WL PRST	Func? 3: 04h 4: 05h 5: 06h	<b>Next Function Number (NFN):</b> This field indicates the next highest function number in this device, or 00h if there are not higher numbered function. Function 0 starts the linked list of functions. <b>Note:</b> Lock Key bit is located in the Personality Lock Key Control Register ("PLKCTL").
7:2	RV	0h	Reserved.
1	RO	0b	<b>ACS Function Group Capability (ACSFGC):</b> Indicates the version of the Capability structure present.
0	RO	0b	<b>MFVC Function Group Capability (MFVCFG):</b> Contains the offset of the next structure in the Extended Capabilities list.

### 27.1.7.3 Alternative Routing-ID Interpretation Control Register (ARICTL)

Bit	Attr	Default	Description
<b>ARICTL</b> Bus: X Device: 0 Function:3 Offset: 106h; Bus: X Device: 0 Function:4 Offset: 106h; Bus: X Device: 0 Function:5 Offset: 106h;			
15:7	RO	0h	Reserved.
6:4	RO	000b	Function Number (FN):
3:2	RV	00b	Reserved.



<b>ARICTL</b>			
<b>Bus: X</b>	<b>Device: 0</b>	<b>Function:3</b>	<b>Offset: 106h;</b>
<b>Bus: X</b>	<b>Device: 0</b>	<b>Function:4</b>	<b>Offset: 106h;</b>
<b>Bus: X</b>	<b>Device: 0</b>	<b>Function:5</b>	<b>Offset: 106h;</b>
Bit	Attr	Default	Description
1	RO	0b	<b>ACS Function Group Enable (ACSFGE):</b>
0	RO	0b	MFVC Function Group Enable (MFVCFGE):

## 27.2 SMBus IO and Memory Space Registers

The SMBus registers can be access through the IO BAR or Memory BAR registers in PCI configuration space. The Offset are same for both I/O and Memory Mapped I/O registers.

### 27.2.1 SMBus Function IO and MEM BAR Space Registers

Table 27-3. SMBus I/O and Memory Mapped I/O Register Address Map

SMB_BASE + Offset	Mnemonic	Register Name	Default	Attribute
00h	HST_STS	Host Status	00h	R/WC, RO
02h	HST_CNT	Host Control	00h	R/W, WO
03h	HST_CMD	Host Command	00h	R/W
04h	TSLVADR	Transmit Slave Address	00h	R/W
05h	HST_D0	Host Data 0	00h	R/W
06h	HST_D1	Host Data 1	00h	R/W
07h	HSTBKDATA	Host Block Data Byte	00h	R/W
08h	PECDAT	Packet Error Check	00h	R/W
09h	RCV_SLVA	Receive Slave Address	44h	R/W
0Ah-0Bh	SLV_DATA	Receive Slave Data	0000h	RO
0Ch	AUX_STS	Auxiliary Status	00h	R/WC, RO
0Dh	AUX_CTL	Auxiliary Control	00h	R/W
0Eh	SMLINK_PIN_CTL	SMLink Pin Control (TCO Compatible Mode)	See register description	R/W, RO
0Fh	SMBus_PIN_CTL	SMBus Pin Control	See register description	R/W, RO



### 27.2.1.1 Host Status Register (HSTSTS)

<b>HSTSTS</b> Base: SMBMBAR      Offset: 00h; IO Base: SMBIOBAR    (Alias:)			
Bit	Attr	Default	Description
7	R/W1C	0	<b>Byte Done Status (BDS):</b> This bit is set to 1b when the host controller has received a byte (for Block Read commands) or if it has completed transmission of a byte (for Block Write commands) when the 32-byte buffer is not being used. This bit has no meaning for block transfers when the 32-byte buffer is enabled. Note: When the last byte of a block message is received, the host controller will set this bit. However, it will not immediately set the INTR bit (bit 1 in HSTSTS register). when the interrupt handler clears the Byte Done Status bit, the messages is considered complete, and the host controller will then set the INTR bit (and generate another interrupt). Thus, for a block message of n bytes, the Intel PCH will generate n+1 interrupts. The interrupt handler needs to be implemented to handle these cases.
6	RO	0	<b>In Use Status (IUS):</b> This host SMBus controller does not support multiple independent software threads using this host controller. <b>Note:</b> This bit has no effect on the host controller.
5	RO	0	<b>SMBAlert Status:</b> This bit when set to 1b indicates the interrupt was due to the SMBAlert# signal. <b>Note:</b> Not used in this SMBus controller. No SMBAlert# pin.
4	R/W1C	0	<b>Failed:</b> This bit when set to 1b indicates the interrupt was due to a failed bus transaction. This bit is also set in response to a HSTCTL.Kill command.
3	R/W1C	0	<b>Bus Error:</b> This bit when set to 1b indicates that the source of the interrupt was due to a transaction collision.
2	R/W1C	0	<b>Device Error:</b> This bit when set to 1b indicates that the source of the interrupt was due to one of the following: Illegal command Field, Unclaimed Cycle (host master initiated), Host Device Time-out Error, CRC Error.
1	R/W1C	0	<b>Interrupt:</b> This bit when set to 1b indicates that the source of the interrupt was the successful completion of its last command.
0	R/W1C	0	<b>Host Busy:</b> This bit when set to 1b indicates the controller is running a command from the host interface. No SMBus register should be accessed while this bit is set. The only exception is when controller is programmed for block command or I <sup>2</sup> C read command. The Block Data Register can be accessed. This is necessary in order to check the Byte Done Status (BDS) bit in this register.

### 27.2.1.2 Host Control Register (HSTCTL)

<b>HSTCTL</b> Base: SMBMBAR      Offset: 02h; IO Base: SMBIOBAR    (Alias:)			
Bit	Attr	Default	Description
7	R/W	0	<b>PEC Enable:</b> When set to a 1b, the controller will perform a Packet Error Checking phase append on SMBus transaction. For writes, the value of the PECDAT register is used for the PEC byte. For reads, the PEC byte is loaded in the PECDAT register.



<b>HSTCTL</b> Base: SMBMBAR      Offset: 02h; IO Base: SMBIOBAR      (Alias:)			
Bit	Attr	Default	Description
6	R/W-V	0	<b>Start:</b> This bit is used to initiate the command programmed in the SMBus Command field. All registers should be setup prior to writing a 1b to this bit. The Controller will auto-clear this bit after software writes a 1b. The HSTSTS.Busy register bit can be used to identify when the SMBus has finished the command.
5	R/W	0	<b>Last Byte:</b> This bit is for software to indicate the controller that the next byte will be the last one to be received for that block. The algorithm and usage model for this bit will be as follows: 1. When the software sees the BYTE_DONE_STS bit set (bit 7 of HSTSTS register) for each of bytes 1 through n-2 of the message, the software should then read the block HSTBLKDAT to get the byte that was just received. 2. After reading each of bytes 1 to n-2 of the message, the software sill then clear the BYTE_DONE_STS bit. 3. After receiving byte n-1 of the message, the software will then set the "LAST BYTE" bit. The software will then clear the BYTE_DONE_STS bit. 4. The controller will the receive the las byte of the message (Byte N) However the controller state machine will see the last byte bit set. It will send a ACK after receiving the last byte instead of a NAK. 5. After receiving the last byte n, software will still clear the BYTE_DONE_STS bit. However the LAST_BYTE bit will be irrelevant at that point.
4:2	R/W	0	<b>SMBus Command:</b> This field indicates which command the e controller is to perform. If enabled, the controller will generate an interrupt when the command has been completed. If the value is for a non-supported or reserved command, the controller will set a device error status bit and generate an interrupt. The controller will not operate until DEV_ERR is cleared. 000b: Quick - The slave address and read/write value (bit 0) are stored in the Tx slave address register. 001b: Byte - This command uses the transmit slave address and command register. 010b: Bye Data - This command uses the transmit slave address, command, and DATA0 register. If command was a read, the DATA0 register will contain the data. 011b: Word Data - This command uses the transmit slave address, command, Data0, and Data1 register. If command was a read, the Data0 and Data1 registers will contain the read data. 100b: Process Call - This command uses the transmit slave address, command, Data0, and Data1 registers. If command was a read, the Data0 and Data1 registers will contain the read data. 101b: Block - This command uses the transmit slave address, command, Data0 register and the block Data Byte register. The count is stored in the Data0 register and indicates how many bytes of data will be transferred. For writes, write data must be serially written into the block data byte register before starting the controller. For reads, the data is stored in the data byte register. 110b: I2C read - This command uses the transmit slave address, command, Data0, Data1 and the block data byte register. The read is stored in the block data byte register. The Intel PCH will continue reading until the NAK is received. 111b: Block-process - This command uses the transmit slave address, command Data0 and the block data byte register. The count is stored in the data0 register and indicates how many bytes the data will be transferred. For writes, write data must be serially written into the block data byte register. before starting the controller. For reads, the data is stored in the data byte register.
1	R/W	0	<b>Kill:</b> When set to 1b, the controller will stop the current transaction taking place and set the failed status bit. An interrupt will be asserted. Once set, this bit must be cleared by software to allow the controller to function normally.
0	R/W	0	<b>Interrupt Enable:</b> Enable the generation of an interrupt upon the completion of the command.



### 27.2.1.3 Host Command Register (HSTCMD)

<b>HSTCMD</b> Base: SMBMBAR      Offset: 03h; IO Base: SMBIOBAR    (Alias:)			
Bit	Attr	Default	Description
7:0	R/W	0	<b>Command:</b> Eight bit field that is transmitted by the controller in the command field of the SMBus protocol during the execution of any command.

### 27.2.1.4 Transmit Slave Address Register (TSLVADR)

<b>TSLVADR</b> Base: SMBMBAR      Offset: 04h; IO Base: SMBIOBAR    (Alias:)			
Bit	Attr	Default	Description
7:1	R/W	0	Target Address: 7-bit address of the targeted slave device.
0	R/W	0	<b>RW:</b> Direction of host transfer. 1b: read 0b: write

### 27.2.1.5 Host Data 0 Register (HSTDATA0)

<b>HSTDATA0</b> Base: SMBMBAR      Offset: 05h; IO Base: SMBIOBAR    (Alias:)			
Bit	Attr	Default	Description
7:0	R/W-V	0	<b>Data0:</b> This register contains the eight bit data sent in the DATA0 field of the SMBus protocol. For block writes commands, this register reflects the number of bytes to transfer. This register should be programmed to a value between 1 and 32 for block counts. Other values will result in unpredictable behavior. The controller does not check or log illegal block counts.

### 27.2.1.6 Host Data 1 Register (HSTDATA1)

<b>HSTDATA1</b> Base: SMBMBAR      Offset: 06h; IO Base: SMBIOBAR    (Alias:)			
Bit	Attr	Default	Description
7:0	R/W-V	0	<b>Data1:</b> This register contains the eight bit data sent in the DATA1 field of the SMBus protocol during the execution of any command.



### 27.2.1.7 Host Block Data Register (HSTBKDATA)

<b>HSTBKDATA</b> Base: SMBMBAR Offset: 07h; IO Base: SMBIOBAR (Alias:)			
Bit	Attr	Default	Description
7:0	R/W-V	0	<b>Block Data:</b> This register is the block data register used when the controller issues block writes or block reads. When the E32B bit is set in the AUXCTL register, reads and writes to this registers are used to access the 32-byte block data storage array. An internal index pointer is used to address the array, which is reset to 0 by reading the HSTCTL register. The index pointer then increments automatically upon each access to this register. the transfer of block transaction always starts at index address 0. Software can write up to 32-bytes to this register as part of the setup for the command. After the controller has sent the address, command, and byte count fields, it will send the bytes in the SRAM pointed to by this register. When the E2B bit is set for reads, the read data is stored into the 32-byte storage array until filled. An interrupt will be generated and the Done_STS bit will be set. When the E32B bit is not set in the AUXCTL register, software places a single byte in this register. After the controller has sent the address, command, and byte count fields, it will send the byte in this register. If there is more data to send, software will write the next byte in series to this register and clear the DONE_STS bit. The controller will send the next byte. The controller will insert wait-states on the SMBus interface waiting for data until the last byte has been transmitted.

### 27.2.1.8 Packet Error Check Data Register (PECDAT)

<b>PECDAT</b> Base: SMBMBAR Offset: 08h; IO Base: SMBIOBAR (Alias:)			
Bit	Attr	Default	Description
7:0	R/W-V	0	<b>PEC DATA:</b> This 8-bit register field is written with the SMBus PEC data prior to a write transaction. For read transactions, the PEC data is loaded from the SMBus controller into this register to allow software to read Packet Error check data. Software must ensure that the INUSE Status bit is properly maintained to avoid having this field over-written by a write transaction following a read.

This register contains the 8-bit CRC value that is used as the Packet Error Check on SMBus. For writes, this register is written by software prior to running the command. For reads, this register is read by software after the read command is completed on the SMBus.

### 27.2.1.9 Auxiliary Status Register (AUXSTS)

<b>AUXSTS</b> Base: SMBMBAR Offset: 0Ch; IO Base: SMBIOBAR (Alias:)			
Bit	Attr	Default	Description
7:1	RV	0	Reserved
0	R/W1C	0	<b>CRC Error (CRCE):</b> This bit when set to 1b indicates that a received message contained a CRC error. When this bit is set, the DERR bit of the Host Status Register will also be set. This bet will be set by the controller if a software abort occurs in the middle of the CRC portion of the cycle or an abort happens after the controller has received the final data bit transmitted by external slave.



### 27.2.1.10 Auxiliary Control Register (AUXCTL)

<b>AUXCTL</b> <b>Base: SMBMBAR</b> <b>Offset: 0Dh;</b> <b>IO Base: SMBIOBAR</b> <b>(Alias:)</b>			
Bit	Attr	Default	Description
7:2	RV	0	Reserved
1	R/W	0	<b>Enable 32-byte Buffer (E32B):</b> This bit when set to 1b will enable Host Block Data Register to reference a 32-byte buffer, as opposed to a single register. This enables the block command to transfer or receive up to 32-bytes before the SMBus controller generates an interrupt.
0	R/W	0	<b>Auto Append CRC Enable (AACRCE):</b> This bit when set to 1b will enable the controller to automatically append the CRC.

### 27.2.1.11 SMBus Pin Control Register (SMBPINCTL)

<b>SMBPINCTL</b> <b>Base: SMBMBAR</b> <b>Offset: 0Fh;</b> <b>IO Base: SMBIOBAR</b> <b>(Alias:)</b>			
Bit	Attr	Default	Description
7:3	RV	0	Reserved
2	R/W	1	<b>SMBus Clock Force Disable (CFLD):</b> This bit control the Clock pin over drive logic to drive the clock pin low. 1b: SMBus Clock pin is not driven low 0b: SMBus clock pin is driven low
1	RO-V	0	<b>SMBus Data Pin Current Status (DPCS):</b> This bit allows software to read the current state of the data pin on SMBus. A 1b indicates a high pin state and a 0b indicates a low pin state.
0	RO-V	0	<b>SMBus Clock Pin Current Status (CPCS):</b> This bit allows software to read the current state of the Clock pin on SMBus. A 1b indicates a high pin state and a 0b indicates a low pin state.



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