# dsPIC33FJ12MC201/202
# Data Sheet

## High-Performance,
## 16-bit Digital Signal Controllers

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# dsPIC33FJ12MC201/202

## High-Performance, 16-bit Digital Signal Controllers

### Operating Range:

- Up to 40 MIPS operation (at 3.0-3.6V):
  - Industrial temperature range (-40°C to +85°C)
  - Extended temperature range (-40°C to +125°C)

### High-Performance DSC CPU:

- Modified Harvard architecture
- C compiler optimized instruction set
- 16-bit-wide data path
- 24-bit-wide instructions
- Linear program memory addressing up to 4M instruction words
- Linear data memory addressing up to 64 Kbytes
- 83 base instructions: mostly one word/one cycle
- Two 40-bit accumulators with rounding and saturation options
- Flexible and powerful addressing modes:
  - Indirect
  - Modulo
  - Bit-Reversed
- Software stack
- 16 x 16 fractional/integer multiply operations
- 32/16 and 16/16 divide operations
- Single-cycle multiply and accumulate:
  - Accumulator write back for DSP operations
  - Dual data fetch
- Up to ±16-bit shifts for up to 40-bit data

### Timers/Capture/Compare/PWM:

- Timer/Counters, up to three 16-bit timers
  - Can pair up to make one 32-bit timer
  - One timer runs as Real-Time Clock with external 32.768 kHz oscillator
  - Programmable prescaler
- Input Capture (up to four channels):
  - Capture on up, down, or both edges
  - 16-bit capture input functions
  - 4-deep FIFO on each capture
- Output Compare (up to two channels):
  - Single or Dual 16-bit Compare mode
  - 16-bit Glitchless PWM mode

### Interrupt Controller:

- 5-cycle latency
- Up to 26 available interrupt sources
- Up to three external interrupts
- Seven programmable priority levels
- Four processor exceptions

### Digital I/O:

- Peripheral pin Select functionality
- Up to 21 programmable digital I/O pins
- Wake-up/Interrupt-on-Change for up to 21 pins
- Output pins can drive from 3.0V to 3.6V
- Up to 5V output with open drain configurations on 5V tolerant pins
- 4 mA sink on all I/O pins

### On-Chip Flash and SRAM:

- Flash program memory (12 Kbytes)
- Data SRAM (1024 bytes)
- Boot and General Security for program Flash

### System Management:

- Flexible clock options:
  - External, crystal, resonator, internal RC
  - Fully integrated Phase-Locked Loop (PLL)
  - Extremely low-jitter PLL
- Power-up Timer
- Oscillator Start-up Timer/Stabilizer
- Watchdog Timer with its own RC oscillator
- Fail-Safe Clock Monitor
- Reset by multiple sources

### Power Management:

- On-chip 2.5V voltage regulator
- Switch between clock sources in real time
- Idle, Sleep, and Doze modes with fast wake-up

## Motor Control Peripherals:

- 6-channel 16-bit Motor Control PWM:
  - Three duty cycle generators
  - Independent or Complementary mode
  - Programmable dead time and output polarity
  - Edge-aligned or center-aligned
  - Manual output override control
  - One Fault input
  - Trigger for ADC conversions
  - PWM frequency for 16-bit resolution (@ 40 MIPS) = 1220 Hz for Edge-Aligned mode, 610 Hz for Center-Aligned mode
  - PWM frequency for 11-bit resolution (@ 40 MIPS) = 39.1 kHz for Edge-Aligned mode, 19.55 kHz for Center-Aligned mode
- 2-channel 16-bit Motor Control PWM:
  - One duty cycle generator
  - Independent or Complementary mode
  - Programmable dead time and output polarity
  - Edge-aligned or center-aligned
  - Manual output override control
  - One Fault input
  - Trigger for ADC conversions
  - PWM frequency for 16-bit resolution (@ 40 MIPS) = 1220 Hz for Edge-Aligned mode, 610 Hz for Center-Aligned mode
  - PWM frequency for 11-bit resolution (@ 40 MIPS) = 39.1 kHz for Edge-Aligned mode, 19.55 kHz for Center-Aligned mode
- Quadrature Encoder Interface module:
  - Phase A, Phase B, and index pulse input
  - 16-bit up/down position counter
  - Count direction status
  - Position Measurement (x2 and x4) mode
  - Programmable digital noise filters on inputs
  - Alternate 16-bit Timer/Counter mode
  - Interrupt on position counter rollover/underflow

## Analog-to-Digital Converters (ADCs):

- 10-bit, 1.1 Msps or 12-bit, 500 Ksps conversion:
  - Two and four simultaneous samples (10-bit ADC)
  - Up to six input channels with auto-scanning
  - Conversion start can be manual or synchronized with one of four trigger sources
  - Conversion possible in Sleep mode
  - ±2 LSb max integral nonlinearity
  - ±1 LSb max differential nonlinearity

## CMOS Flash Technology:

- Low-power, high-speed Flash technology
- Fully static design
- 3.3V (±10%) operating voltage
- Industrial and Extended temperature
- Low power consumption

## Communication Modules:

- 4-wire SPI:
  - Framing supports I/O interface to simple codecs
  - Supports 8-bit and 16-bit data
  - Supports all serial clock formats and sampling modes
- $I^2C$™:
  - Full Multi-Master Slave mode support
  - 7-bit and 10-bit addressing
  - Bus collision detection and arbitration
  - Integrated signal conditioning
  - Slave address masking
- UART:
  - Interrupt on address bit detect
  - Interrupt on UART error
  - Wake-up on Start bit from Sleep mode
  - 4-character TX and RX FIFO buffers
  - LIN bus support
  - IrDA® encoding and decoding in hardware
  - High-Speed Baud mode
  - Hardware Flow Control with CTS and RTS

## Packaging:

- 20-pin PDIP/SOIC/SSOP
- 28-pin SPDIP/SOIC/SSOP/QFN

**Note:** See Table 1 for the exact peripheral features per device.


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## dsPIC33FJ12MC201/202 PRODUCT FAMILIES

The device names, pin counts, memory sizes, and peripheral availability of each device are listed in Table 1. The following pages show their pinout diagrams.

**TABLE 1: dsPIC33FJ12MC201/202 CONTROLLER FAMILIES**

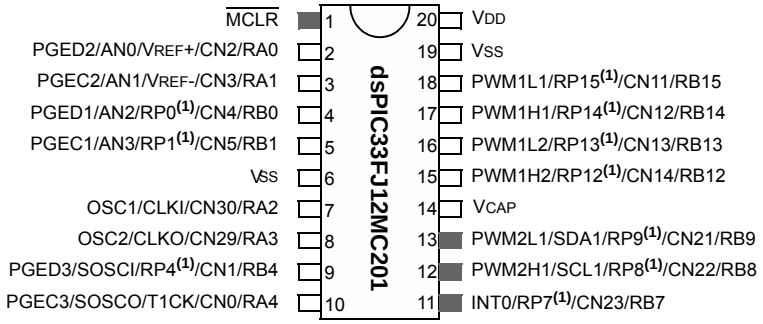
| Device | Pins | Program Flash Memory (Kbyte) | RAM (Kbyte) | Remappable Peripherals | | | | | | | | | 10-Bit/12-Bit ADC | $I^2C$™ | I/O Pins | Packages |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | | | | Remappable Pins | 16-bit Timer | Input Capture | Output Compare Standard PWM | Motor Control PWM | Quadrature Encoder Interface | UART | External Interrupts(3) | SPI | | | | |
| dsPIC33FJ12MC201 | 20 | 12 | 1 | 10 | 3(1) | 4 | 2 | 4ch(2)<br>2ch(2) | 1 | 1 | 3 | 1 | 1ADC, 4 ch | 1 | 15 | PDIP<br>SOIC<br>SSOP |
| dsPIC33FJ12MC202 | 28 | 12 | 1 | 16 | 3(1) | 4 | 2 | 6ch(2)<br>2ch(2) | 1 | 1 | 3 | 1 | 1ADC. 6 ch | 1 | 21 | SPDIP<br>SOIC<br>SSOP<br>QFN |

**Note 1:** Only two out of three timers are remappable.
**2:** Only PWM fault inputs are remappable.
**3:** Only two out of three interrupts are remappable.

## Pin Diagrams

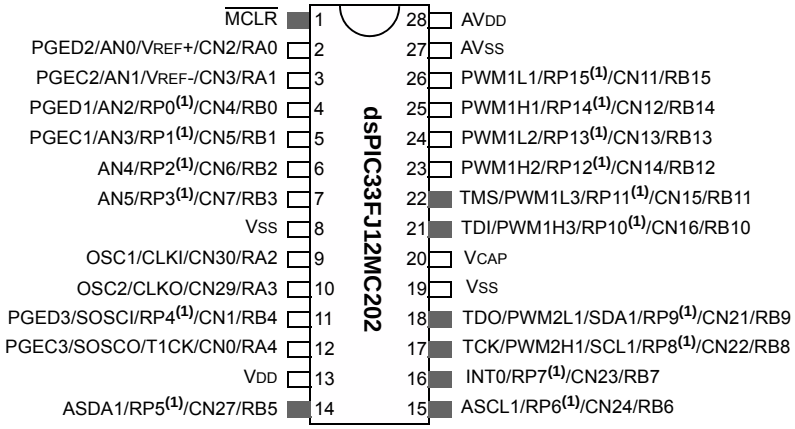
### 20-PIN PDIP, SOIC, SSOP

■ = Pins are up to 5V tolerant




### 28-PIN SPDIP, SOIC, SSOP

■ = Pins are up to 5V tolerant




**Note 1:** The RPn pins can be used by any remappable peripheral. See Table 1 for the list of available peripherals.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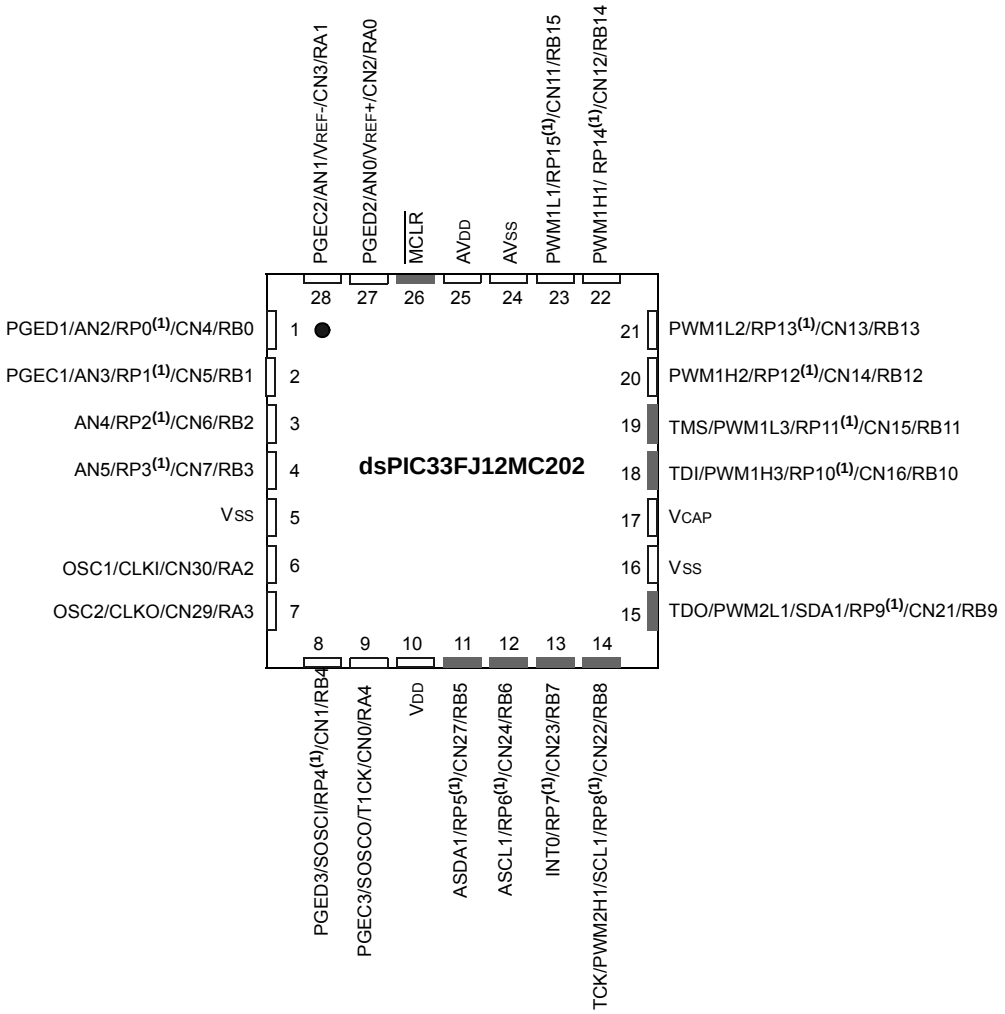
## Pin Diagrams (Continued)

**28-Pin QFN(2)**

■ = Pins are up to 5V tolerant




**Note 1:** The RPn pins can be used by any remappable peripheral. See Table 1 for the list of available peripherals.

**2:** The metal plane at the bottom of the device is not connected to any pins and is recommended to be connected to VSS externally.

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## 1.0 DEVICE OVERVIEW

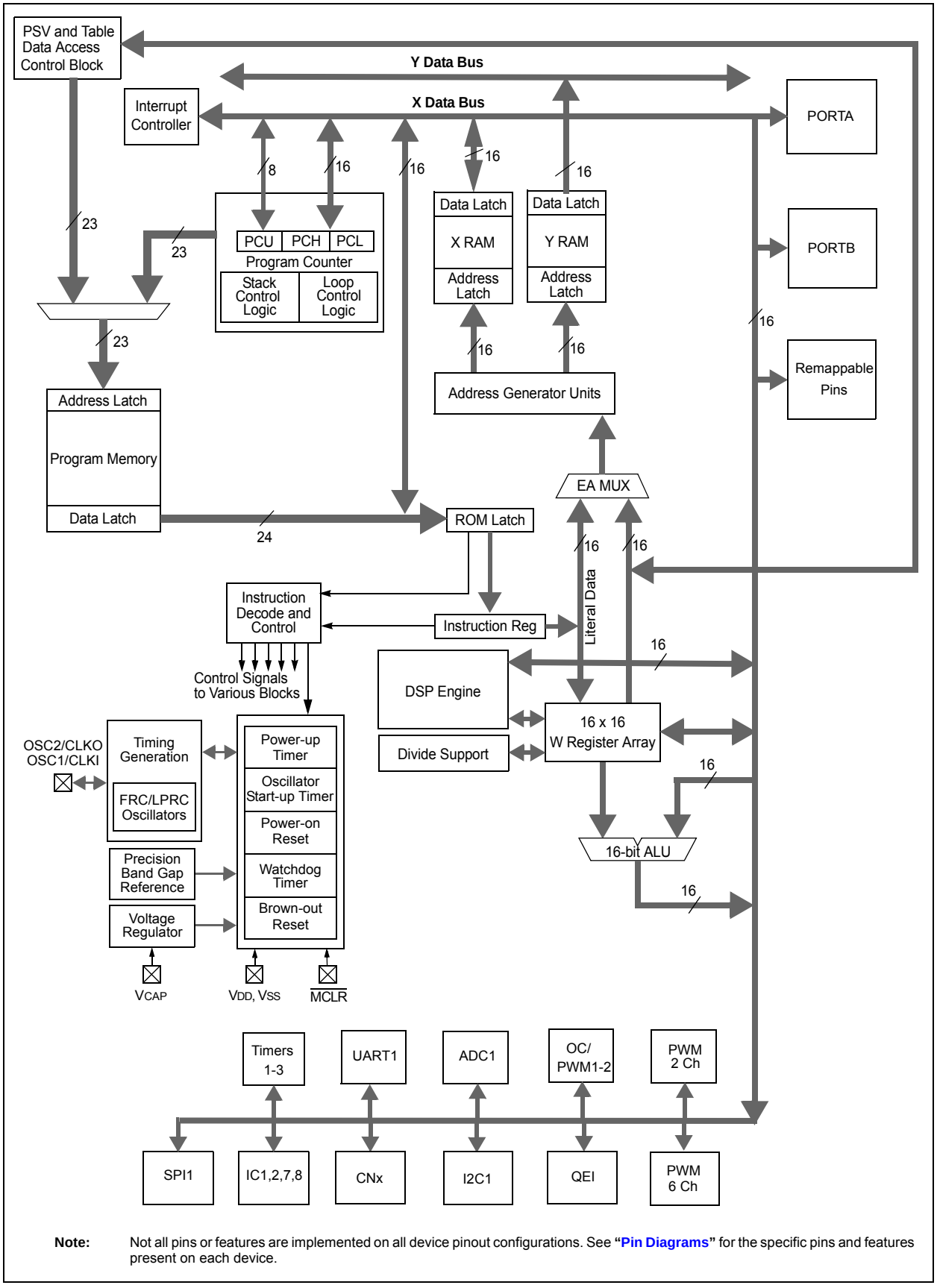
**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the *"dsPIC33F/PIC24H Family Reference Manual"*. Please see the Microchip web site (www.microchip.com) for the latest dsPIC33F/PIC24H Family Reference Manual sections.

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

This document contains device specific information for the dsPIC33FJ12MC201/202 Digital Signal Controller (DSC) Devices. The dsPIC33F devices contain extensive Digital Signal Processor (DSP) functionality with a high-performance, 16-bit microcontroller (MCU) architecture.

Figure 1-1 shows a general block diagram of the core and peripheral modules in the dsPIC33FJ12MC201/202 family of devices. Table 1-1 lists the functions of the various pins shown in the pinout diagrams.

**FIGURE 1-1: dsPIC33FJ12MC201/202 BLOCK DIAGRAM**




**Note:** Not all pins or features are implemented on all device pinout configurations. See **"Pin Diagrams"** for the specific pins and features present on each device.


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**TABLE 1-1: PINOUT I/O DESCRIPTIONS**

| Pin Name | Pin Type | Buffer Type | PPS | Description |
|---|---|---|---|---|
| AN0-AN5 | I | Analog | No | Analog input channels. |
| CLKI<br>CLKO | I<br>O | ST/CMOS<br>— | No<br>No | External clock source input. Always associated with OSC1 pin function.<br>Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes. Always associated with OSC2 pin function. |
| OSC1<br><br>OSC2 | I<br><br>I/O | ST/CMOS<br><br>— | No<br><br>No | Oscillator crystal input. ST buffer when configured in RC mode; CMOS otherwise.<br>Oscillator crystal output. Connects to crystal or resonator in Crystal Oscillator mode. Optionally functions as CLKO in RC and EC modes. |
| SOSCI<br>SOSCO | I<br>O | ST/CMOS<br>— | No<br>No | 32.768 kHz low-power oscillator crystal input; CMOS otherwise.<br>32.768 kHz low-power oscillator crystal output. |
| CN0-CN7<br>CN11-CN16<br>CN21-CN24<br>CN27<br>CN29-CN30 | I | ST | No<br>No<br>No<br>No<br>No | Change notification inputs.<br>Can be software programmed for internal weak pull-ups on all inputs. |
| IC1-IC2<br>IC7-IC8 | I<br>I | ST<br>ST | Yes<br>Yes | Capture inputs 1/2.<br>Capture inputs 7/8. |
| OCFA<br>OC1-OC2 | I<br>O | ST<br>— | Yes<br>Yes | Compare Fault A input (for Compare Channels 1 and 2).<br>Compare outputs 1 through 2. |
| INT0<br>INT1<br>INT2 | I<br>I<br>I | ST<br>ST<br>ST | No<br>Yes<br>Yes | External interrupt 0.<br>External interrupt 1.<br>External interrupt 2. |
| RA0-RA4 | I/O | ST | No | PORTA is a bidirectional I/O port. |
| RB0-RB15 | I/O | ST | No | PORTB is a bidirectional I/O port. |
| T1CK<br>T2CK<br>T3CK | I<br>I<br>I | ST<br>ST<br>ST | No<br>Yes<br>Yes | Timer1 external clock input.<br>Timer2 external clock input.<br>Timer3 external clock input. |
| $\overline{\text{U1CTS}}$<br>$\overline{\text{U1RTS}}$<br>U1RX<br>U1TX | I<br>O<br>I<br>O | ST<br>—<br>ST<br>— | Yes<br>Yes<br>Yes<br>Yes | UART1 clear to send.<br>UART1 ready to send.<br>UART1 receive.<br>UART1 transmit. |
| SCK1<br>SDI1<br>SDO1<br>$\overline{\text{SS1}}$ | I/O<br>I<br>O<br>I/O | ST<br>ST<br>—<br>ST | Yes<br>Yes<br>Yes<br>Yes | Synchronous serial clock input/output for SPI1.<br>SPI1 data in.<br>SPI1 data out.<br>SPI1 slave synchronization or frame pulse I/O. |
| SCL1<br>SDA1<br>ASCL1<br>ASDA1 | I/O<br>I/O<br>I/O<br>I/O | ST<br>ST<br>ST<br>ST | No<br>No<br>No<br>No | Synchronous serial clock input/output for I2C1.<br>Synchronous serial data input/output for I2C1.<br>Alternate synchronous serial clock input/output for I2C1.<br>Alternate synchronous serial data input/output for I2C1. |
| TMS<br>TCK<br>TDI<br>TDO | I<br>I<br>I<br>O | ST<br>ST<br>ST<br>— | No<br>No<br>No<br>No | JTAG Test mode select pin.<br>JTAG test clock input pin.<br>JTAG test data input pin.<br>JTAG test data output pin. |

**Legend:** CMOS = CMOS compatible input or output
Analog = Analog input
P = Power
ST = Schmitt Trigger input with CMOS levels
O = Output
I = Input
PPS = Peripheral Pin Select

**TABLE 1-1: PINOUT I/O DESCRIPTIONS (CONTINUED)**

| Pin Name | Pin Type | Buffer Type | PPS | Description |
|---|---|---|---|---|
| INDX | I | ST | Yes | Quadrature Encoder Index Pulse input. |
| QEA | I | ST | Yes | Quadrature Encoder Phase A input in QEI mode.<br>Auxiliary Timer External Clock/Gate input in Timer mode. |
| QEB | I | ST | Yes | Quadrature Encoder Phase A input in QEI mode.<br>Auxiliary Timer External Clock/Gate input in Timer mode. |
| UPDN | O | CMOS | Yes | Position Up/Down Counter Direction State. |
| $\overline{FLTA1}$ | I | ST | Yes | PWM1 Fault A input. |
| PWM1L1 | O | — | No | PWM1 Low output 1 |
| PWM1H1 | O | — | No | PWM1 High output 1 |
| PWM1L2 | O | — | No | PWM1 Low output 2 |
| PWM1H2 | O | — | No | PWM1 High output 2 |
| PWM1L3 | O | — | No | PWM1 Low output 3 |
| PWM1H3 | O | — | No | PWM1 High output 3 |
| $\overline{FLTA2}$ | I | ST | Yes | PWM2 Fault A input. |
| PWM2L1 | O | — | No | PWM2 Low output 1 |
| PWM2H1 | O | — | No | PWM2 High output 1 |
| PGED1 | I/O | ST | No | Data I/O pin for programming/debugging communication channel 1. |
| PGEC1 | I | ST | No | Clock input pin for programming/debugging communication channel 1. |
| PGED2 | I/O | ST | No | Data I/O pin for programming/debugging communication channel 2. |
| PGEC2 | I | ST | No | Clock input pin for programming/debugging communication channel 2. |
| PGED3 | I/O | ST | No | Data I/O pin for programming/debugging communication channel 3. |
| PGEC3 | I | ST | No | Clock input pin for programming/debugging communication channel 3. |
| $\overline{MCLR}$ | I/P | ST | No | Master Clear (Reset) input. This pin is an active-low Reset to the device. |
| $AV_{DD}$ | P | P | No | Positive supply for analog modules. This pin must be connected at all times. |
| $AV_{SS}$ | P | P | No | Ground reference for analog modules. |
| $V_{DD}$ | P | — | No | Positive supply for peripheral logic and I/O pins. |
| $V_{CAP}$ | P | — | No | CPU logic filter capacitor connection. |
| $V_{SS}$ | P | — | No | Ground reference for logic and I/O pins. |
| $V_{REF}+$ | I | Analog | No | Analog voltage reference (high) input. |
| $V_{REF}-$ | I | Analog | No | Analog voltage reference (low) input. |

**Legend:** CMOS = CMOS compatible input or output; Analog = Analog input; P = Power
ST = Schmitt Trigger input with CMOS levels; O = Output; I = Input
PPS = Peripheral Pin Select


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## 1.1 Referenced Sources

This device data sheet is based on the following individual chapters of the *"dsPIC33F/PIC24H Family Reference Manual"*. These documents should be considered as the general reference for the operation of a particular module or device feature.

**Note 1:** To access the documents listed below, browse to the documentation section of the dsPIC33FJ12MC202 product page of the Microchip web site (www.microchip.com) or select a family reference manual section from the following list.

In addition to parameters, features, and other documentation, the resulting page provides links to the related family reference manual sections.

- **Section 1. "Introduction"** (DS70197)
- **Section 2. "CPU"** (DS70204)
- **Section 3. "Data Memory"** (DS70202)
- **Section 4. "Program Memory"** (DS70202)
- **Section 5. "Flash Programming"** (DS70191)
- **Section 6. "Interrupts"** (DS70184)
- **Section 7. "Oscillator"** (DS70186)
- **Section 8. "Reset"** (DS70192)
- **Section 9. "Watchdog Timer and Power-Saving Modes"** (DS70196)
- **Section 10. "I/O Ports"** (DS70193)
- **Section 11. "Timers"** (DS70205)
- **Section 12. "Input Capture"** (DS70198)
- **Section 13. "Output Compare"** (DS70209)
- **Section 14. "Motor Control PWM"** (DS70187)
- **Section 15. "Quadrature Encoder Interface (QEI)"** (DS70208)
- **Section 16. "Analog-to-Digital Converter (ADC)"** (DS70183)
- **Section 17. "UART"** (DS70188)
- **Section 18. "Serial Peripheral Interface (SPI)"** (DS70206)
- **Section 19. "Inter-Integrated Circuit™ ($I^2C$™)"** (DS70195)
- **Section 23. "CodeGuard Security"** (DS70199)
- **Section 25. "Device Configuration"** (DS70194)

**NOTES:**


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# 2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT DIGITAL SIGNAL CONTROLLERS

**Note:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the *"dsPIC33F Family Reference Manual"*, which is available from the Microchip web site (www.microchip.com).

## 2.1 Basic Connection Requirements

Getting started with the dsPIC33FJ12MC201/202 family of 16-bit Digital Signal Controllers (DSC) requires attention to a minimal set of device pin connections before proceeding with development. The following is a list of pin names, which must always be connected:

- All VDD and VSS pins
  (see **Section 2.2 "Decoupling Capacitors"**)
- All AVDD and AVSS pins (regardless if ADC module is not used)
  (see **Section 2.2 "Decoupling Capacitors"**)
- VCAP
  (see **Section 2.3 "CPU Logic Filter Capacitor Connection (VCAP)"**)
- $\overline{\text{MCLR}}$ pin
  (see **Section 2.4 "Master Clear (MCLR) Pin"**)
- PGECx/PGEDx pins used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes
  (see **Section 2.5 "ICSP Pins"**)
- OSC1 and OSC2 pins when external oscillator source is used
  (see **Section 2.6 "External Oscillator Pins"**)

Additionally, the following pins may be required:

- VREF+/VREF- pins used when external voltage reference for ADC module is implemented

**Note:** The AVDD and AVSS pins must be connected independent of the ADC voltage reference source.

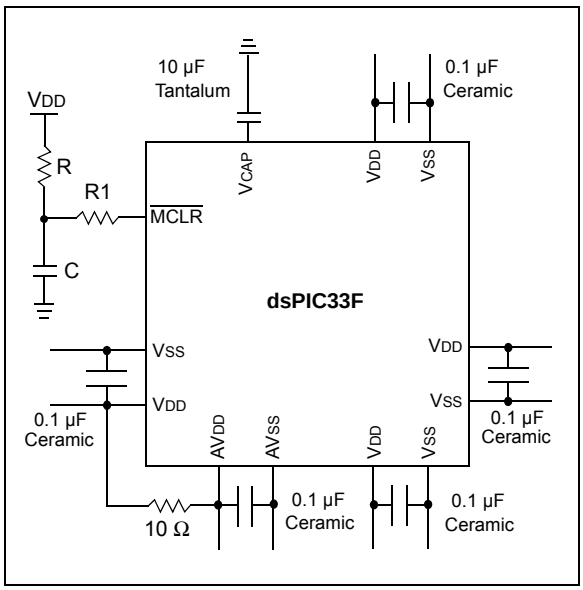
## 2.2 Decoupling Capacitors

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD, and AVSS is required.

Consider the following criteria when using decoupling capacitors:

- **Value and type of capacitor:** Recommendation of 0.1 µF (100 nF), 10-20V. This capacitor should be a low-ESR and have resonance frequency in the range of 20 MHz and higher. It is recommended that ceramic capacitors be used.
- **Placement on the printed circuit board:** The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is within one-quarter inch (6 mm) in length.
- **Handling high frequency noise:** If the board is experiencing high frequency noise, upward of tens of MHz, add a second ceramic-type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 µF to 0.001 µF. Place this second capacitor next to the primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible. For example, 0.1 µF in parallel with 0.001 µF.
- **Maximizing performance:** On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum thereby reducing PCB track inductance.

**FIGURE 2-1: RECOMMENDED MINIMUM CONNECTION**




### 2.2.1 TANK CAPACITORS

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits including DSCs to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device, and the maximum current drawn by the device in the application. In other words, select the tank capacitor so that it meets the acceptable voltage sag at the device. Typical values range from 4.7 µF to 47 µF.

## 2.3 CPU Logic Filter Capacitor Connection (VCAP)

A low-ESR (< 5 Ohms) capacitor is required on the VCAP pin, which is used to stabilize the voltage regulator output voltage. The VCAP pin must not be connected to VDD, and must have a capacitor between 4.7 µF and 10 µF, 16V connected to ground. The type can be ceramic or tantalum. Refer to **Section 24.0 "Electrical Characteristics"** for additional information.

The placement of this capacitor should be close to the VCAP. It is recommended that the trace length not exceed one-quarter inch (6 mm). Refer to **Section 21.2 "On-Chip Voltage Regulator"** for details.

## 2.4 Master Clear (MCLR) Pin

The MCLR pin provides for two specific device functions:

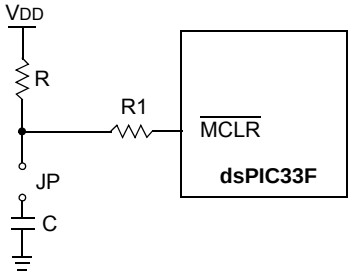
- Device Reset
- Device programming and debugging

During device programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the MCLR pin. Consequently, specific voltage levels (VIH and VIL) and fast signal transitions must not be adversely affected. Therefore, specific values of R and C will need to be adjusted based on the application and PCB requirements.

For example, as shown in Figure 2-2, it is recommended that the capacitor C, be isolated from the MCLR pin during programming and debugging operations.

Place the components shown in Figure 2-2 within one-quarter inch (6 mm) from the MCLR pin.

**FIGURE 2-2: EXAMPLE OF MCLR PIN CONNECTIONS**




**Note 1:** R ≤ 10 kΩ is recommended. A suggested starting value is 10 kΩ Ensure that the MCLR pin VIH and VIL specifications are met.

**2:** R1 ≤ 470Ω will limit any current flowing into MCLR from the external capacitor C, in the event of MCLR pin breakdown, due to Electrostatic Discharge (ESD) or Electrical Overstress (EOS). Ensure that the MCLR pin VIH and VIL specifications are met.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## 2.5 ICSP Pins

The PGECx and PGEDx pins are used for In-Circuit Serial Programming™ (ICSP™) and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of Ohms, not to exceed 100 Ohms.

Pull-up resistors, series diodes, and capacitors on the PGECx and PGEDx pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternately, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high ($V_{IH}$) and input low ($V_{IL}$) requirements.

Ensure that the "Communication Channel Select" (i.e., PGECx/PGEDx pins) programmed into the device matches the physical connections for the ICSP to MPLAB® ICD 2, MPLAB ICD 3, or MPLAB REAL ICE™.

For more information on ICD 2, ICD 3, and REAL ICE connection requirements, refer to the following documents that are available on the Microchip web site.

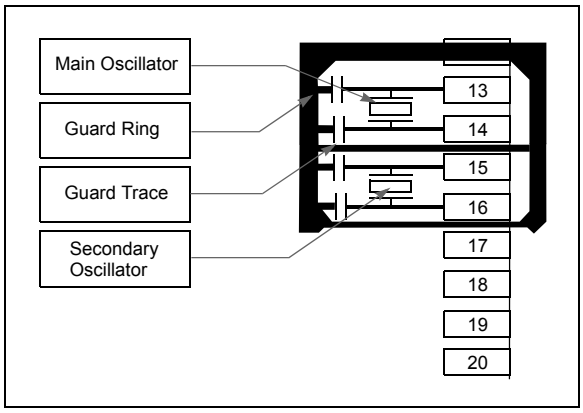
- *"MPLAB® ICD 2 In-Circuit Debugger User's Guide"* DS51331
- *"Using MPLAB® ICD 2"* (poster) DS51265
- *"MPLAB® ICD 2 Design Advisory"* DS51566
- *"Using MPLAB® ICD 3"* (poster) DS51765
- *"MPLAB® ICD 3 Design Advisory"* DS51764
- *"MPLAB® REAL ICE™ In-Circuit Debugger User's Guide"* DS51616
- *"Using MPLAB® REAL ICE™"* (poster) DS51749

## 2.6 External Oscillator Pins

Many DSCs have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator (refer to **Section 8.0 "Oscillator Configuration"** for details).

The oscillator circuit should be placed on the same side of the board as the device. Also, place the oscillator circuit close to the respective oscillator pins, not exceeding one-half inch (12 mm) distance between them. The load capacitors should be placed next to the oscillator itself, on the same side of the board. Use a grounded copper pour around the oscillator circuit to isolate them from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed. A suggested layout is shown in Figure 2-3.

**FIGURE 2-3: SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT**



## 2.7 Oscillator Value Conditions on Device Start-up

If the PLL of the target device is enabled and configured for the device start-up oscillator, the maximum oscillator source frequency must be limited to 4 MHz < FIN < 8 MHz to comply with device PLL start-up conditions. This means that if the external oscillator frequency is outside this range, the application must start-up in the FRC mode first. The default PLL settings after a POR with an oscillator frequency outside this range will violate the device operating speed.

Once the device powers up, the application firmware can initialize the PLL SFRs, CLKDIV, and PLLDBF to a suitable value, and then perform a clock switch to the Oscillator + PLL clock source. Note that clock switching must be enabled in the device Configuration word.

## 2.8 Configuration of Analog and Digital Pins During ICSP Operations

If MPLAB ICD 2, MPLAB ICD 3, or MPLAB REAL ICE in-circuit emulator is selected as a debugger, it automatically initializes all of the A/D input pins (ANx) as “digital” pins, by setting all bits in the AD1PCFGL register.

The bits in the register that correspond to the A/D pins that are initialized by MPLAB ICD 2, MPLAB ICD 3, or MPLAB REAL ICE in-circuit emulator, must not be cleared by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain A/D pins as analog input pins during the debug session, the user application must clear the corresponding bits in the AD1PCFGL register during initialization of the ADC module.

When MPLAB ICD 2, MPLAB ICD 3, or MPLAB REAL ICE in-circuit emulator is used as a programmer, the user application firmware must correctly configure the AD1PCFGL register. Automatic initialization of this register is only done during debugger operation. Failure to correctly configure the register(s) will result in all A/D pins being recognized as analog input pins, resulting in the port value being read as a logic ‘0’, which may affect user application functionality.

## 2.9 Unused I/Os

Unused I/O pins should be configured as outputs and driven to a logic-low state.

Alternately, connect a 1k to 10k resistor between VSS and unused pins and drive the output to logic low.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## 3.0 CPU

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 2. "CPU"** (DS70204) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 CPU module has a 16-bit (data) modified Harvard architecture with an enhanced instruction set, including significant support for DSP. The CPU has a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M x 24 bits of user program memory space. The actual amount of program memory implemented varies by device. A single-cycle instruction prefetch mechanism is used to help maintain throughput and provides predictable execution. All instructions execute in a single cycle, with the exception of instructions that change the program flow, the double-word move (`MOV.D`) instruction and the table instructions. Overhead-free program loop constructs are supported using the `DO` and `REPEAT` instructions, both of which are interruptible at any point.

The dsPIC33FJ12MC201/202 devices have sixteen, 16-bit working registers in the programmer's model. Each of the working registers can serve as a data, address, or address offset register. The 16th working register (W15) operates as a software Stack Pointer (SP) for interrupts and calls.

There are two classes of instruction in the dsPIC33FJ12MC201/202 devices: MCU and DSP. These two instruction classes are seamlessly integrated into a single CPU. The instruction set includes many addressing modes and is designed for optimum C compiler efficiency. For most instructions, dsPIC33FJ12MC201/202 devices are capable of executing a data (or program data) memory read, a working register (data) read, a data memory write, and a program (instruction) memory read per instruction cycle. As a result, three parameter instructions can be supported, allowing A + B = C operations to be executed in a single cycle.

A block diagram of the CPU is shown in Figure 3-1, and the programmer's model for the dsPIC33FJ12MC201/202 is shown in Figure 3-2.

### 3.1 Data Addressing Overview

The data space can be addressed as 32K words or 64 Kbytes and is split into two blocks, referred to as X and Y data memory. Each memory block has its own independent Address Generation Unit (AGU). The MCU class of instructions operates solely through the X memory AGU, which accesses the entire memory map as one linear data space. Certain DSP instructions operate through the X and Y AGUs to support dual operand reads, which splits the data address space into two parts. The X and Y data space boundary is device-specific.

Overhead-free circular buffers (Modulo Addressing mode) are supported in both X and Y address spaces. The Modulo Addressing removes the software boundary checking overhead for DSP algorithms. Furthermore, the X AGU circular addressing can be used with any of the MCU class of instructions. The X AGU also supports Bit-Reversed Addressing to greatly simplify input or output data reordering for radix-2 FFT algorithms.

The upper 32 Kbytes of the data space memory map can optionally be mapped into program space at any 16K program word boundary defined by the 8-bit Program Space Visibility Page (PSVPAG) register. The program-to-data-space mapping feature lets any instruction access program space as if it were data space.

### 3.2 DSP Engine Overview

The DSP engine features a high-speed 17-bit by 17-bit multiplier, a 40-bit ALU, two 40-bit saturating accumulators, and a 40-bit bidirectional barrel shifter. The barrel shifter is capable of shifting a 40-bit value up to 16 bits right or left, in a single cycle. The DSP instructions operate seamlessly with all other instructions and have been designed for optimal real-time performance. The `MAC` instruction and other associated instructions can concurrently fetch two data operands from memory, while multiplying two W registers and accumulating and optionally saturating the result in the same cycle. This instruction functionality requires that the RAM data space be split for these instructions and linear for all others. Data space partitioning is achieved in a transparent and flexible manner through dedicating certain working registers to each address space.

### 3.3 Special MCU Features

The dsPIC33FJ12MC201/202 features a 17-bit by 17-bit single-cycle multiplier that is shared by both the MCU ALU and DSP engine. The multiplier can perform signed, unsigned and mixed-sign multiplication. Using a 17-bit by 17-bit multiplier for 16-bit by 16-bit multiplication not only allows you to perform mixed-sign multiplication, it also achieves accurate results for special operations, such as (-1.0) x (-1.0).

The dsPIC33FJ12MC201/202 supports 16/16 and 32/16 divide operations, both fractional and integer. All divide instructions are iterative operations. They must be executed within a REPEAT loop, resulting in a total execution time of 19 instruction cycles. The divide operation can be interrupted during any of those 19 cycles without loss of data.

A 40-bit barrel shifter is used to perform up to a 16-bit left or right shift in a single cycle. The barrel shifter can be used by both MCU and DSP instructions.

**FIGURE 3-1: dsPIC33FJ12MC201/202 CPU CORE BLOCK DIAGRAM**

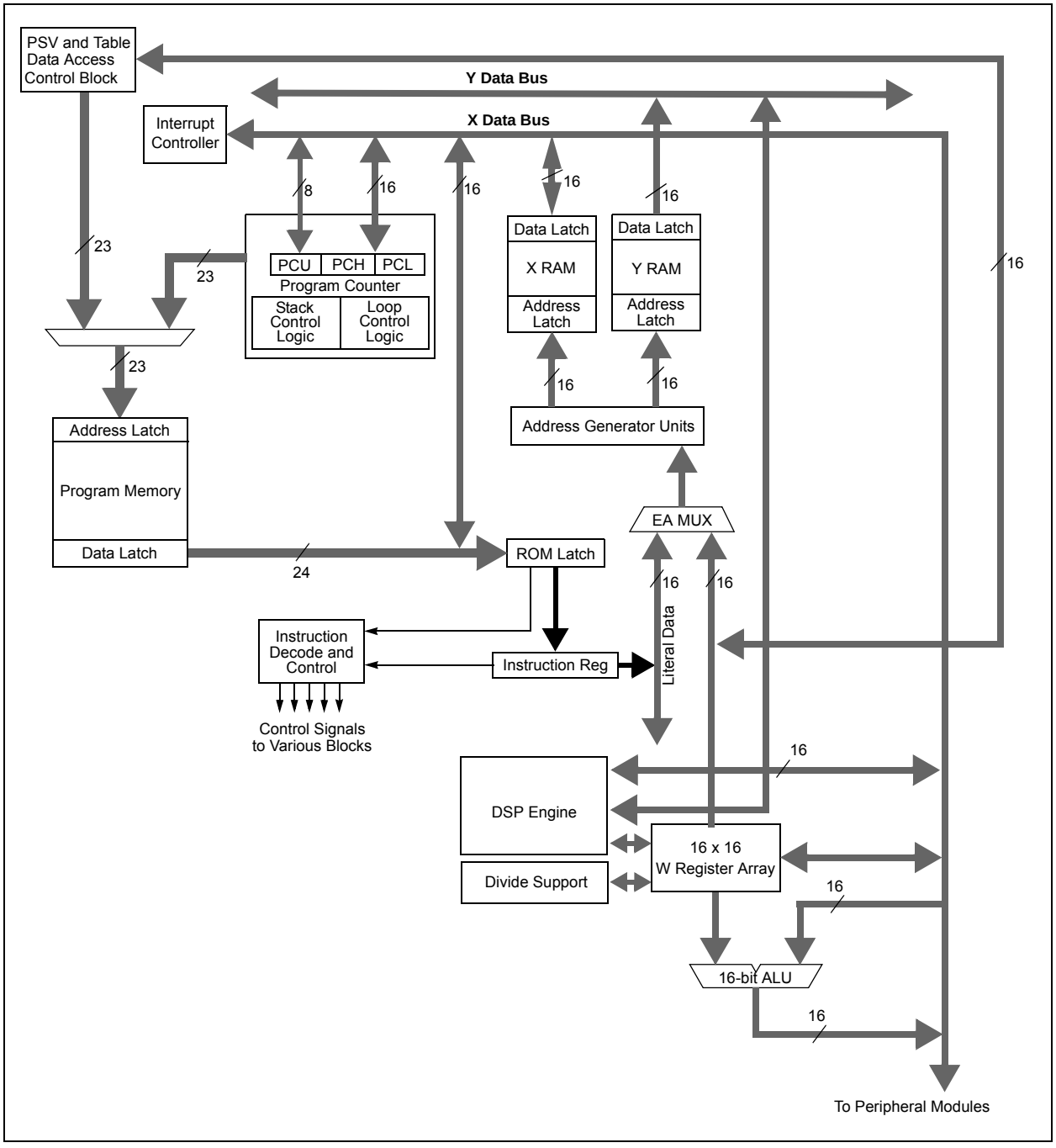



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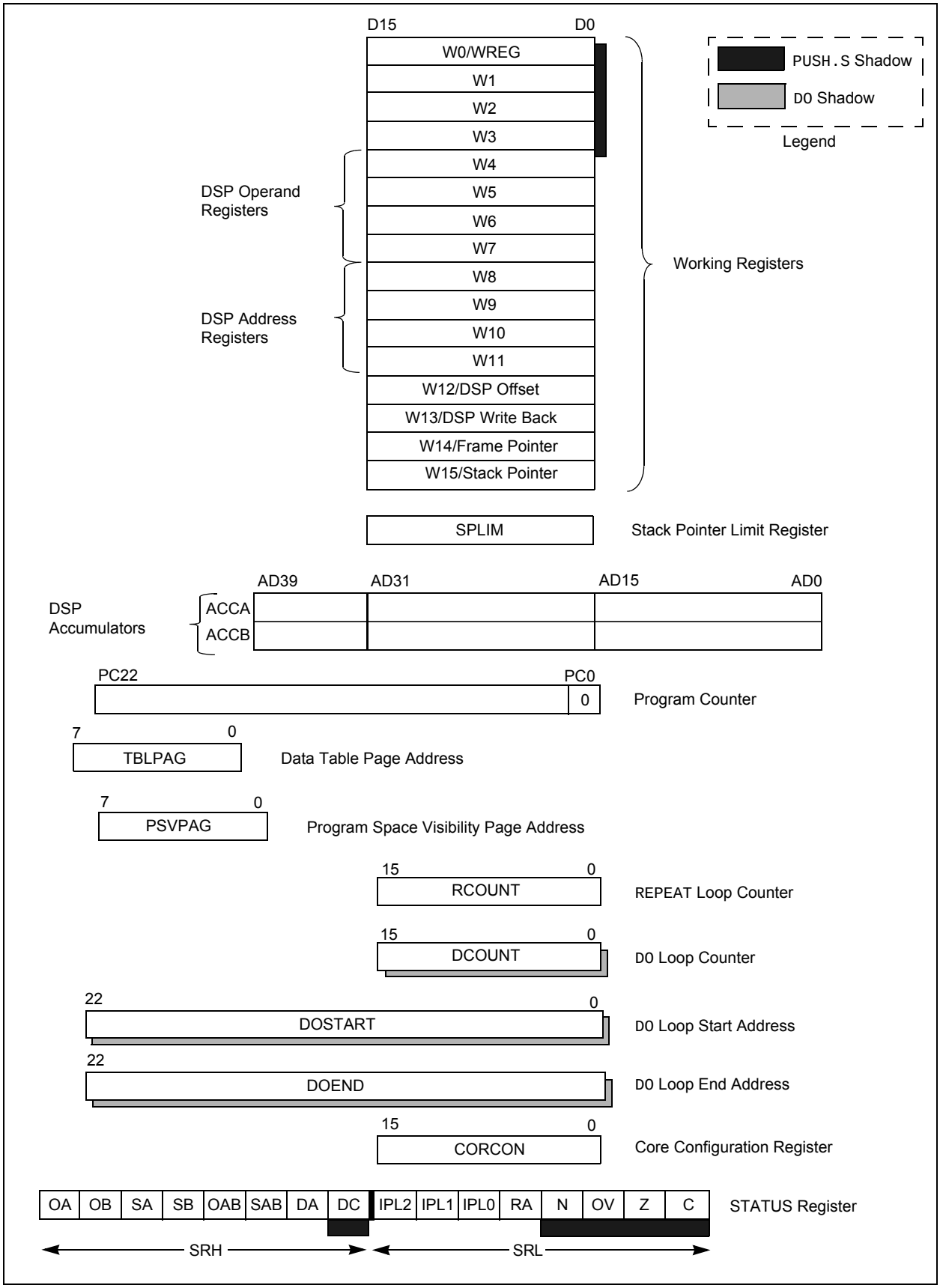
**FIGURE 3-2: dsPIC33FJ12MC201/202 PROGRAMMER'S MODEL**



## 3.4 CPU Control Registers

**REGISTER 3-1: SR: CPU STATUS REGISTER**

| R-0 | R-0 | R/C-0 | R/C-0 | R-0 | R/C-0 | R -0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| OA | OB | SA(1) | SB(1) | OAB | SAB | DA | DC |
| bit 15 | | | | | | | bit 8 |

| R/W-0(2) | R/W-0(3) | R/W-0(3) | R-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| IPL<2:0>(2) | | | RA | N | OV | Z | C |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | |
|---|---|---|
| C = Clear only bit | R = Readable bit | U = Unimplemented bit, read as '0' |
| S = Set only bit | W = Writable bit | -n = Value at POR |
| '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **OA:** Accumulator A Overflow Status bit
1 = Accumulator A overflowed
0 = Accumulator A has not overflowed

bit 14 **OB:** Accumulator B Overflow Status bit
1 = Accumulator B overflowed
0 = Accumulator B has not overflowed

bit 13 **SA:** Accumulator A Saturation 'Sticky' Status bit(1)
1 = Accumulator A is saturated or has been saturated at some time
0 = Accumulator A is not saturated

bit 12 **SB:** Accumulator B Saturation 'Sticky' Status bit(1)
1 = Accumulator B is saturated or has been saturated at some time
0 = Accumulator B is not saturated

bit 11 **OAB:** OA || OB Combined Accumulator Overflow Status bit
1 = Accumulators A or B have overflowed
0 = Neither Accumulators A or B have overflowed

bit 10 **SAB:** SA || SB Combined Accumulator 'Sticky' Status bit
1 = Accumulators A or B are saturated or have been saturated at some time in the past
0 = Neither Accumulator A or B are saturated
This bit may be read or cleared (not set). *Clearing this bit will clear SA and SB*.

bit 9 **DA:** DO Loop Active bit
1 = DO loop in progress
0 = DO loop not in progress

bit 8 **DC:** MCU ALU Half Carry/$\overline{\text{Borrow}}$ bit
1 = A carry-out from the 4th low-order bit (for byte-sized data) or 8th low-order bit (for word-sized data) of the result occurred
0 = No carry-out from the 4th low-order bit (for byte-sized data) or 8th low-order bit (for word-sized data) of the result occurred

**Note 1:** This bit can be read or cleared (not set).
**2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
**3:** The IPL<2:0> Status bits are read-only when NSTDIS = 1 (INTCON1<15>).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**REGISTER 3-1: SR: CPU STATUS REGISTER (CONTINUED)**

bit 7-5 **IPL<2:0>:** CPU Interrupt Priority Level Status bits(2)
111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled
110 = CPU Interrupt Priority Level is 6 (14)
101 = CPU Interrupt Priority Level is 5 (13)
100 = CPU Interrupt Priority Level is 4 (12)
011 = CPU Interrupt Priority Level is 3 (11)
010 = CPU Interrupt Priority Level is 2 (10)
001 = CPU Interrupt Priority Level is 1 (9)
000 = CPU Interrupt Priority Level is 0 (8)

bit 4 **RA:** REPEAT Loop Active bit
1 = REPEAT loop in progress
0 = REPEAT loop not in progress

bit 3 **N:** MCU ALU Negative bit
1 = Result was negative
0 = Result was non-negative (zero or positive)

bit 2 **OV:** MCU ALU Overflow bit
This bit is used for signed arithmetic (2's complement). It indicates an overflow of a magnitude that causes the sign bit to change state.
1 = Overflow occurred for signed arithmetic (in this arithmetic operation)
0 = No overflow occurred

bit 1 **Z:** MCU ALU Zero bit
1 = An operation that affects the Z bit has set it at some time in the past
0 = The most recent operation that affects the Z bit has cleared it (i.e., a non-zero result)

bit 0 **C:** MCU ALU Carry/$\overline{\text{Borrow}}$ bit
1 = A carry-out from the Most Significant bit of the result occurred
0 = No carry-out from the Most Significant bit of the result occurred

**Note 1:** This bit can be read or cleared (not set).
**2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
**3:** The IPL<2:0> Status bits are read-only when NSTDIS = 1 (INTCON1<15>).

**REGISTER 3-2: CORCON: CORE CONTROL REGISTER**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | US | EDT(1) | DL<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-1 | R/W-0 | R/C-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| SATA | SATB | SATDW | ACCSAT | IPL3(2) | PSV | RND | IF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | C = Clear only bit | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | -n = Value at POR | '1' = Bit is set |
| 0' = Bit is cleared | 'x = Bit is unknown | U = Unimplemented bit, read as '0' | |

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **US:** DSP Multiply Unsigned/Signed Control bit
1 = DSP engine multiplies are unsigned
0 = DSP engine multiplies are signed

bit 11 **EDT:** Early DO Loop Termination Control bit(1)
1 = Terminate executing DO loop at end of current loop iteration
0 = No effect

bit 10-8 **DL<2:0>:** DO Loop Nesting Level Status bits
111 = 7 DO loops active
•
•
•
001 = 1 DO loop active
000 = 0 DO loops active

bit 7 **SATA:** ACCA Saturation Enable bit
1 = Accumulator A saturation enabled
0 = Accumulator A saturation disabled

bit 6 **SATB:** ACCB Saturation Enable bit
1 = Accumulator B saturation enabled
0 = Accumulator B saturation disabled

bit 5 **SATDW:** Data Space Write from DSP Engine Saturation Enable bit
1 = Data space write saturation enabled
0 = Data space write saturation disabled

bit 4 **ACCSAT:** Accumulator Saturation Mode Select bit
1 = 9.31 saturation (super saturation)
0 = 1.31 saturation (normal saturation)

bit 3 **IPL3:** CPU Interrupt Priority Level Status bit 3(2)
1 = CPU interrupt priority level is greater than 7
0 = CPU interrupt priority level is 7 or less

bit 2 **PSV:** Program Space Visibility in Data Space Enable bit
1 = Program space visible in data space
0 = Program space not visible in data space

bit 1 **RND:** Rounding Mode Select bit
1 = Biased (conventional) rounding enabled
0 = Unbiased (convergent) rounding enabled

bit 0 **IF:** Integer or Fractional Multiplier Mode Select bit
1 = Integer mode enabled for DSP multiply ops
0 = Fractional mode enabled for DSP multiply ops

**Note 1:** This bit will always read as '0'.
**2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU interrupt priority level.


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## 3.5 Arithmetic Logic Unit (ALU)

The dsPIC33FJ12MC201/202 ALU is 16 bits wide and is capable of addition, subtraction, bit shifts, and logic operations. Unless otherwise mentioned, arithmetic operations are 2's complement in nature. Depending on the operation, the ALU can affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV), and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

Refer to the *"16-bit MCU and DSC Programmer's Reference Manual"* (DS70157) for information on the SR bits affected by each instruction.

The dsPIC33FJ12MC201/202 CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit-divisor division.

### 3.5.1 MULTIPLIER

Using the high-speed 17-bit x 17-bit multiplier of the DSP engine, the ALU supports unsigned, signed or mixed-sign operation in several MCU multiplication modes:

- 16-bit x 16-bit signed
- 16-bit x 16-bit unsigned
- 16-bit signed x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit unsigned
- 16-bit unsigned x 5-bit (literal) unsigned
- 16-bit unsigned x 16-bit signed
- 8-bit unsigned x 8-bit unsigned

### 3.5.2 DIVIDER

The divide block supports 32-bit/16-bit and 16-bit/16-bit signed and unsigned integer divide operations with the following data sizes:

1. 32-bit signed/16-bit signed divide
2. 32-bit unsigned/16-bit unsigned divide
3. 16-bit signed/16-bit signed divide
4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. 16-bit signed and unsigned `DIV` instructions can specify any W register for both the 16-bit divisor (Wn) and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

## 3.6 DSP Engine

The DSP engine consists of a high-speed 17-bit x 17-bit multiplier, a barrel shifter and a 40-bit adder/subtracter (with two target accumulators, round and saturation logic).

The dsPIC33FJ12MC201/202 is a single-cycle instruction flow architecture; therefore, concurrent operation of the DSP engine with MCU instruction flow is not possible. However, some MCU ALU and DSP engine resources can be used concurrently by the same instruction (e.g., `ED`, `EDAC`).

The DSP engine can also perform inherent accumulator-to-accumulator operations that require no additional data. These instructions are `ADD`, `SUB`, and `NEG`.

The DSP engine has options selected through bits in the CPU Core Control register (CORCON), as listed below:

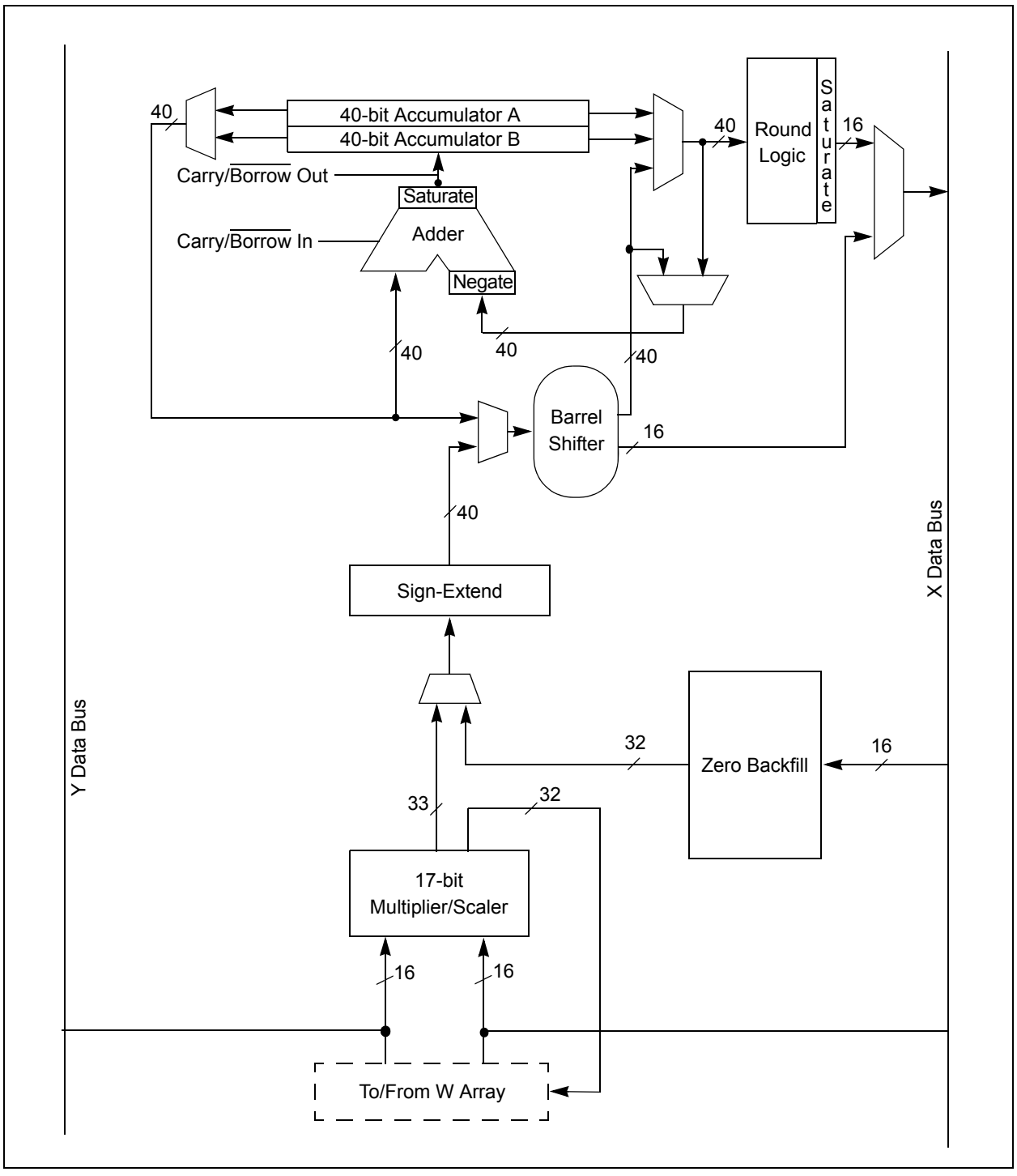
- Fractional or integer DSP multiply (IF)
- Signed or unsigned DSP multiply (US)
- Conventional or convergent rounding (RND)
- Automatic saturation on/off for ACCA (SATA)
- Automatic saturation on/off for ACCB (SATB)
- Automatic saturation on/off for writes to data memory (SATDW)
- Accumulator Saturation mode selection (ACCSAT)

A block diagram of the DSP engine is shown in Figure 3-3.

**TABLE 3-1: DSP INSTRUCTIONS SUMMARY**

| Instruction | Algebraic Operation | ACC Write Back |
|---|---|---|
| CLR | $A = 0$ | Yes |
| ED | $A = (x - y)^2$ | No |
| EDAC | $A = A + (x - y)^2$ | No |
| MAC | $A = A + (x * y)$ | Yes |
| MAC | $A = A + x^2$ | No |
| MOVSAC | No change in $A$ | Yes |
| MPY | $A = x * y$ | No |
| MPY | $A = x^2$ | No |
| MPY.N | $A = -x * y$ | No |
| MSC | $A = A - x * y$ | Yes |

**FIGURE 3-3: DSP ENGINE BLOCK DIAGRAM**





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### 3.6.1 MULTIPLIER

The 17-bit x 17-bit multiplier is capable of signed or unsigned operation and can multiplex its output using a scaler to support either 1.31 fractional (Q31) or 32-bit integer results. Unsigned operands are zero-extended into the 17th bit of the multiplier input value. Signed operands are sign-extended into the 17th bit of the multiplier input value. The output of the 17-bit x 17-bit multiplier/scaler is a 33-bit value that is sign-extended to 40 bits. Integer data is inherently represented as a signed 2's complement value, where the Most Significant bit (MSb) is defined as a sign bit. The range of an N-bit 2's complement integer is $-2^{N-1}$ to $2^{N-1} - 1$.

- For a 16-bit integer, the data range is -32768 (0x8000) to 32767 (0x7FFF) including 0.
- For a 32-bit integer, the data range is -2,147,483,648 (0x8000 0000) to 2,147,483,647 (0x7FFF FFFF).

When the multiplier is configured for fractional multiplication, the data is represented as a 2's complement fraction, where the MSb is defined as a sign bit and the radix point is implied to lie just after the sign bit (QX format). The range of an N-bit 2's complement fraction with this implied radix point is -1.0 to $(1 - 2^{1-N})$. For a 16-bit fraction, the Q15 data range is -1.0 (0x8000) to 0.999969482 (0x7FFF) including 0 and has a precision of $3.01518 \times 10^{-5}$. In Fractional mode, the 16 x 16 multiply operation generates a 1.31 product that has a precision of $4.65661 \times 10^{-10}$.

The same multiplier is used to support the MCU multiply instructions, which include integer 16-bit signed, unsigned and mixed sign multiply operations.

The `MUL` instruction can be directed to use byte- or word-sized operands. Byte operands will direct a 16-bit result, and word operands will direct a 32-bit result to the specified register(s) in the W array.

### 3.6.2 DATA ACCUMULATORS AND ADDER/SUBTRACTER

The data accumulator consists of a 40-bit adder/subtracter with automatic sign extension logic. It can select one of two accumulators (A or B) as its pre-accumulation source and post-accumulation destination. For the `ADD` and `LAC` instructions, the data to be accumulated or loaded can be optionally scaled using the barrel shifter prior to accumulation.

#### 3.6.2.1 Adder/Subtracter, Overflow and Saturation

The adder/subtracter is a 40-bit adder with an optional zero input into one side, and either true or complement data into the other input.

- In the case of addition, the Carry/$\overline{\text{Borrow}}$ input is active-high and the other input is true data (not complemented).
- In the case of subtraction, the Carry/$\overline{\text{Borrow}}$ input is active-low and the other input is complemented.

The adder/subtracter generates Overflow Status bits, SA/SB and OA/OB, which are latched and reflected in the STATUS register:

- Overflow from bit 39: this is a catastrophic overflow in which the sign of the accumulator is destroyed.
- Overflow into guard bits 32 through 39: this is a recoverable overflow. This bit is set whenever all the guard bits are not identical to each other.

The adder has an additional saturation block that controls accumulator data saturation, if selected. It uses the result of the adder, the Overflow Status bits described previously and the SAT<A:B> (CORCON<7:6>) and ACCSAT (CORCON<4>) mode control bits to determine when and to what value, to saturate.

Six STATUS register bits support saturation and overflow:

- OA: ACCA overflowed into guard bits
- OB: ACCB overflowed into guard bits
- SA: ACCA saturated (bit 31 overflow and saturation)

  *or*

  ACCA overflowed into guard bits and saturated (bit 39 overflow and saturation)
- SB: ACCB saturated (bit 31 overflow and saturation)

  *or*

  ACCB overflowed into guard bits and saturated (bit 39 overflow and saturation)
- OAB: Logical OR of OA and OB
- SAB: Logical OR of SA and SB

The OA and OB bits are modified each time data passes through the adder/subtracter. When set, they indicate that the most recent operation has overflowed into the accumulator guard bits (bits 32 through 39). The OA and OB bits can also optionally generate an arithmetic warning trap when OA and OB are set and the corresponding Overflow Trap Flag Enable bits (OVATE, OVBTE) in the INTCON1 register are set (refer to **Section 7.0 "Interrupt Controller"**). This allows the user application to take immediate action; for example, to correct system gain.

The SA and SB bits are modified each time data passes through the adder/subtracter, but can only be cleared by the user application. When set, they indicate that the accumulator has overflowed its maximum range (bit 31 for 32-bit saturation or bit 39 for 40-bit saturation) and will be saturated (if saturation is enabled). When saturation is not enabled, SA and SB default to bit 39 overflow, and therefore, indicate that a catastrophic overflow has occurred. If the COVTE bit in the INTCON1 register is set, the SA and SB bits will generate an arithmetic warning trap when saturation is disabled.

The Overflow and Saturation Status bits can optionally be viewed in the STATUS Register (SR) as the logical OR of OA and OB (in bit OAB) and the logical OR of SA and SB (in bit SAB). Programmers can check one bit in the STATUS register to determine whether either accumulator has overflowed, or one bit to determine whether either accumulator has saturated. This is useful for complex number arithmetic, which typically uses both accumulators.

The device supports three Saturation and Overflow modes:

- Bit 39 Overflow and Saturation:
  When bit 39 overflow and saturation occurs, the saturation logic loads the maximally positive 9.31 value (0x7FFFFFFFFF) or maximally negative 9.31 value (0x8000000000) into the target accumulator. The SA or SB bit is set and remains set until cleared by the user application. This condition is referred to as ‘super saturation’ and provides protection against erroneous data or unexpected algorithm problems (such as gain calculations).
- Bit 31 Overflow and Saturation:
  When bit 31 overflow and saturation occurs, the saturation logic then loads the maximally positive 1.31 value (0x007FFFFFFF) or maximally negative 1.31 value (0x0080000000) into the target accumulator. The SA or SB bit is set and remains set until cleared by the user application. When this Saturation mode is in effect, the guard bits are not used, so the OA, OB or OAB bits are never set.
- Bit 39 Catastrophic Overflow:
  The bit 39 Overflow Status bit from the adder is used to set the SA or SB bit, which remains set until cleared by the user application. No saturation operation is performed, and the accumulator is allowed to overflow, destroying its sign. If the COVTE bit in the INTCON1 register is set, a catastrophic overflow can initiate a trap exception.

### 3.6.3 ACCUMULATOR ‘WRITE BACK’

The MAC class of instructions (with the exception of MPY, MPY.N, ED, and EDAC) can optionally write a rounded version of the high word (bits 31 through 16) of the accumulator which is not targeted by the instruction into data space memory. The write is performed across the X bus into combined X and Y address space. The following addressing modes are supported:

- W13, Register Direct:
  The rounded contents of the non-target accumulator are written into W13 as a 1.15 fraction.
- [W13] + = 2, Register Indirect with Post-Increment:
  The rounded contents of the non-target accumulator are written into the address pointed to by W13 as a 1.15 fraction. W13 is then incremented by 2 (for a word write).


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#### 3.6.3.1 Round Logic

The round logic is a combinational block that performs a conventional (biased) or convergent (unbiased) round function during an accumulator write (store). The Round mode is determined by the state of the RND bit in the CORCON register. It generates a 16-bit, 1.15 data value that is passed to the data space write saturation logic. If rounding is not indicated by the instruction, a truncated 1.15 data value is stored and the least significant word (lsw) is simply discarded.

Conventional rounding will zero-extend bit 15 of the accumulator and will add it to the ACCxH word (bits 16 through 31 of the accumulator).

- If the ACCxL word (bits 0 through 15 of the accumulator) is between 0x8000 and 0xFFFF (0x8000 included), ACCxH is incremented.
- If ACCxL is between 0x0000 and 0x7FFF, ACCxH is left unchanged.

A consequence of this algorithm is that over a succession of random rounding operations, the value tends to be biased slightly positive.

Convergent (or unbiased) rounding operates in the same manner as conventional rounding, except when ACCxL equals 0x8000. In this case, the Least Significant bit (LSb), bit 16 of the accumulator, of ACCxH is examined:

- If it is '1', ACCxH is incremented.
- If it is '0', ACCxH is not modified.

Assuming that bit 16 is effectively random in nature, this scheme removes any rounding bias that may accumulate.

The SAC and SAC.R instructions store either a truncated (SAC), or rounded (SAC.R) version of the contents of the target accumulator to data memory via the X bus, subject to data saturation (see **Section 3.6.3.2 "Data Space Write Saturation"**). For the MAC class of instructions, the accumulator write-back operation functions in the same manner, addressing combined MCU (X and Y) data space though the X bus. For this class of instructions, the data is always subject to rounding.

#### 3.6.3.2 Data Space Write Saturation

In addition to adder/subtracter saturation, writes to data space can also be saturated, but without affecting the contents of the source accumulator. The data space write saturation logic block accepts a 16-bit, 1.15 fractional value from the round logic block as its input, together with overflow status from the original source (accumulator) and the 16-bit round adder. These inputs are combined and used to select the appropriate 1.15 fractional value as output to write to data space memory.

If the SATDW bit in the CORCON register is set, data (after rounding or truncation) is tested for overflow and adjusted accordingly:

- For input data greater than 0x007FFF, data written to memory is forced to the maximum positive 1.15 value, 0x7FFF.
- For input data less than 0xFF8000, data written to memory is forced to the maximum negative 1.15 value, 0x8000.

The MSb of the source (bit 39) is used to determine the sign of the operand being tested.

If the SATDW bit in the CORCON register is not set, the input data is always passed through unmodified under all conditions.

### 3.6.4 BARREL SHIFTER

The barrel shifter can perform up to 16-bit arithmetic or logic right shifts, or up to 16-bit left shifts, in a single cycle. The source can be either of the two DSP accumulators or the X bus (to support multi-bit shifts of register or memory data).

The shifter requires a signed binary value to determine both the magnitude (number of bits) and direction of the shift operation. A positive value shifts the operand right. A negative value shifts the operand left. A value of '0' does not modify the operand.

The barrel shifter is 40 bits wide, thereby obtaining a 40-bit result for DSP shift operations and a 16-bit result for MCU shift operations. Data from the X bus is presented to the barrel shifter between bit positions 16 and 31 for right shifts, and between bit positions 0 and 16 for left shifts.

**NOTES:**


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## 4.0 MEMORY ORGANIZATION

**Note:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 4. "Program Memory"** (DS70202) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

The dsPIC33FJ12MC201/202 architecture features separate program and data memory spaces and buses. This architecture also allows the direct access of program memory from the data space during code execution.

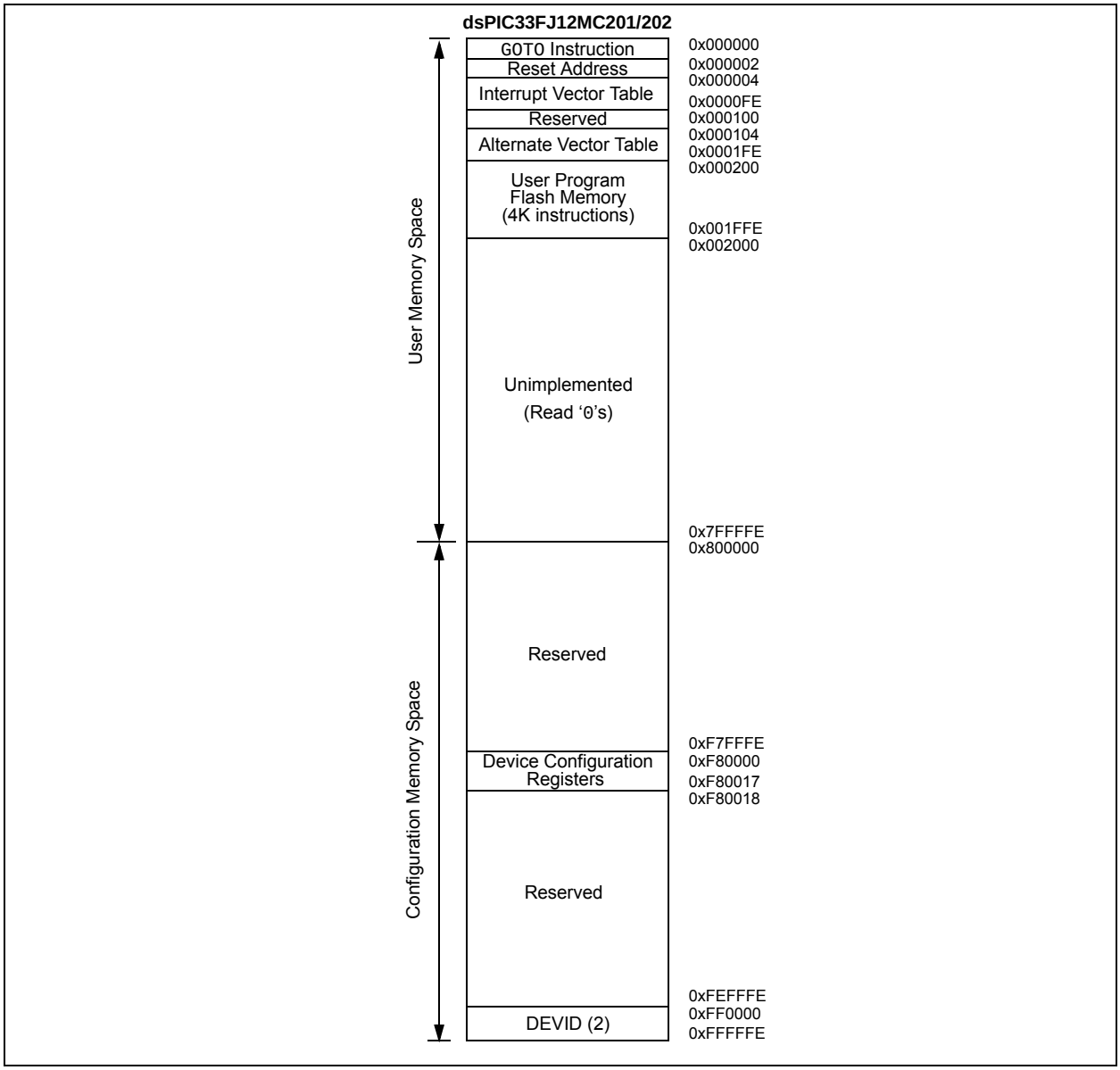
### 4.1 Program Address Space

The program address memory space of the dsPIC33FJ12MC201/202 devices is 4M instructions. The space is addressable by a 24-bit value derived either from the 23-bit Program Counter (PC) during program execution, or from table operation or data space remapping as described in **Section 4.6 "Interfacing Program and Data Memory Spaces"**.

User application access to the program memory space is restricted to the lower half of the address range (0x000000 to 0x7FFFFF). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

The memory map for the dsPIC33FJ12MC201/202 family of devices is shown in Figure 4-1.

**FIGURE 4-1: PROGRAM MEMORY MAP FOR dsPIC33FJ12MC201/202 DEVICES**



### 4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-2).

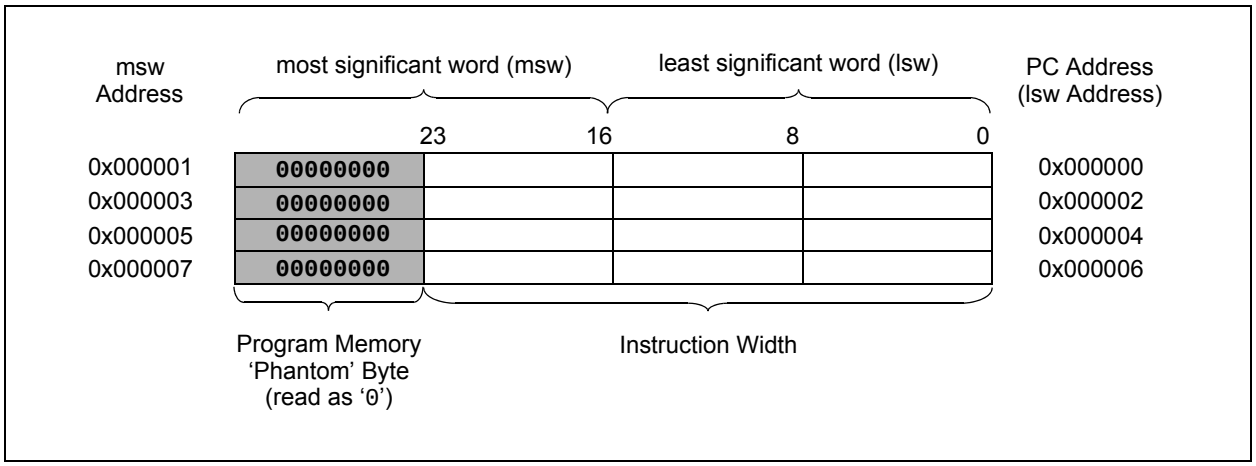
Program memory addresses are always word-aligned on the lower word, and addresses are incremented or decremented by two during code execution. This arrangement provides compatibility with data memory space addressing and makes data in the program memory space accessible.

### 4.1.2 INTERRUPT AND TRAP VECTORS

All dsPIC33FJ12MC201/202 devices reserve the addresses between 0x00000 and 0x000200 for hard-coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user application at 0x000000, with the actual address for the start of code at 0x000002.

dsPIC33FJ12MC201/202 devices also have two interrupt vector tables, located from 0x000004 to 0x0000FF and 0x000100 to 0x0001FF. These vector tables allow each of the device interrupt sources to be handled by separate Interrupt Service Routines (ISRs). A more detailed discussion of the interrupt vector tables is provided in **Section 7.1 "Interrupt Vector Table"**.

**FIGURE 4-2: PROGRAM MEMORY ORGANIZATION**





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## 4.2 Data Address Space

The dsPIC33FJ12MC201/202 CPU has a separate 16-bit-wide data memory space. The data space is accessed using separate Address Generation Units (AGUs) for read and write operations. The data memory maps is shown in Figure 4-3.

All Effective Addresses (EAs) in the data memory space are 16 bits wide and point to bytes within the data space. This arrangement gives a data space address range of 64 Kbytes or 32K words. The lower half of the data memory space (that is, when EA<15> = 0) is used for implemented memory addresses, while the upper half (EA<15> = 1) is reserved for the Program Space Visibility area (see **Section 4.6.3 "Reading Data from Program Memory Using Program Space Visibility"**).

Microchip dsPIC33FJ12MC201/202 devices implement up to 1 Kbyte of data memory. Should an EA point to a location outside of this area, an all-zero word or byte will be returned.

### 4.2.1 DATA SPACE WIDTH

The data memory space is organized in byte addressable, 16-bit wide blocks. Data is aligned in data memory and registers as 16-bit words, but all data space EAs resolve to bytes. The Least Significant Bytes (LSBs) of each word have even addresses, while the Most Significant Bytes (MSBs) have odd addresses.

### 4.2.2 DATA MEMORY ORGANIZATION AND ALIGNMENT

To maintain backward compatibility with PIC® MCU devices and improve data space memory usage efficiency, the dsPIC33FJ12MC201/202 instruction set supports both word and byte operations. As a consequence of byte accessibility, all effective address calculations are internally scaled to step through word-aligned memory. For example, the core recognizes that Post-Modified Register Indirect Addressing mode [Ws++] will result in a value of Ws + 1 for byte operations and Ws + 2 for word operations.

Data byte reads will read the complete word that contains the byte, using the LSB of any EA to determine which byte to select. The selected byte is placed onto the LSB of the data path. That is, data memory and registers are organized as two parallel byte-wide entities with shared (word) address decoding but separate write lines. Data byte writes only write to the corresponding side of the array or register that matches the byte address.

All word accesses must be aligned to an even address. Misaligned word data fetches are not supported, so care must be taken when mixing byte and word operations, or translating from 8-bit MCU code. If a misaligned read or write is attempted, an address error trap is generated. If the error occurred on a read, the instruction in progress is completed. If the error occurred on a write, the instruction is executed but the write does not occur. In either case, a trap is then executed, allowing the system and/or user application to examine the machine state prior to execution of the address Fault.

All byte loads into any W register are loaded into the LSB. The MSB is not modified.

A sign-extend instruction (SE) is provided to allow user applications to translate 8-bit signed data to 16-bit signed values. Alternately, for 16-bit unsigned data, user applications can clear the MSB of any W register by executing a zero-extend (ZE) instruction on the appropriate address.

### 4.2.3 SFR SPACE

The first 2 Kbytes of the Near Data Space, from 0x0000 to 0x07FF, is primarily occupied by Special Function Registers (SFRs). These are used by the dsPIC33FJ12MC201/202 core and peripheral modules for controlling the operation of the device.

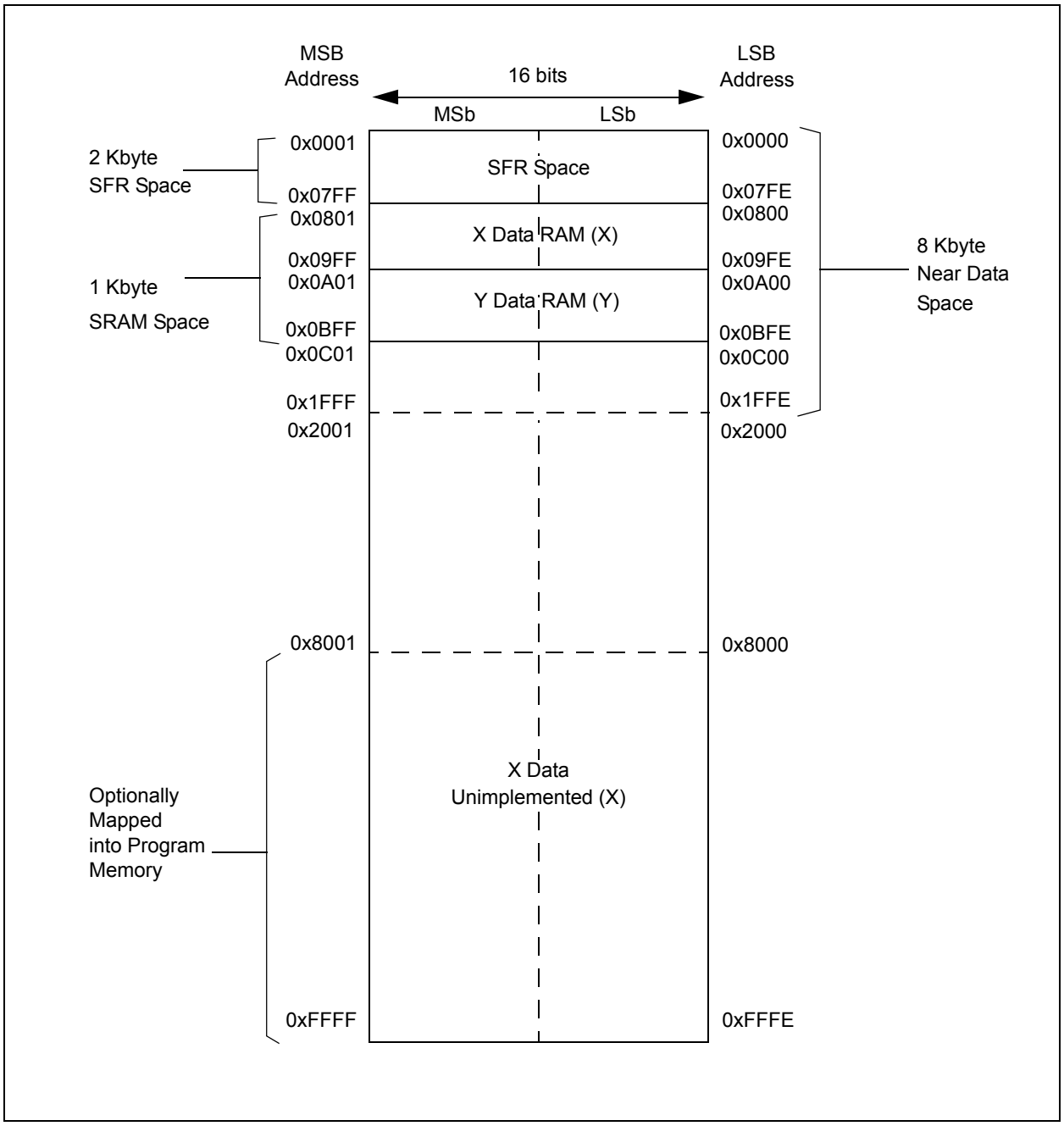
SFRs are distributed among the modules that they control, and are generally grouped together by module. Much of the SFR space contains unused addresses; these are read as '0'.

| **Note:** | The actual set of peripheral features and interrupts varies by the device. Refer to the corresponding device tables and pinout diagrams for device-specific information. |
|---|---|

### 4.2.4 NEAR DATA SPACE

The 8-Kbyte area between 0x0000 and 0x1FFF is referred to as the near data space. Locations in this space are directly addressable via a 13-bit absolute address field within all memory direct instructions. Additionally, the whole data space is addressable using MOV class of instructions, which support Memory Direct Addressing mode with a 16-bit address field, or by using Indirect Addressing mode with a working register as an address pointer.

**FIGURE 4-3: DATA MEMORY MAP FOR dsPIC33FJ12MC201/202 DEVICES WITH 1 KB RAM**





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### 4.2.5 X AND Y DATA SPACES

The core has two data spaces, X and Y. These data spaces can be considered either separate (for some DSP instructions), or as one unified linear address range (for MCU instructions). The data spaces are accessed using two Address Generation Units (AGUs) and separate data paths. This feature allows certain instructions to concurrently fetch two words from RAM, thereby enabling efficient execution of DSP algorithms such as Finite Impulse Response (FIR) filtering and fast Fourier transform (FFT).

The X data space is used by all instructions and supports all addressing modes. X data space has separate read and write data buses. The X read data bus is the read data path for all instructions that view data space as combined X and Y address space. It is also the X data prefetch path for the dual operand DSP instructions (MAC class).

The Y data space is used in concert with the X data space by the MAC class of instructions (CLR, ED, EDAC, MAC, MOVSAC, MPY, MPY.N, and MSC) to provide two concurrent data read paths.

Both the X and Y data spaces support Modulo Addressing mode for all instructions, subject to addressing mode restrictions. Bit-Reversed Addressing mode is only supported for writes to X data space.

All data memory writes, including in DSP instructions, view data space as combined X and Y address space. The boundary between the X and Y data spaces is device-dependent and is not user-programmable.

All effective addresses are 16 bits wide and point to bytes within the data space. Therefore, the data space address range is 64 Kbytes, or 32K words, although the implemented memory locations vary by device.

**TABLE 4-1: CPU CORE REGISTERS MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| WREG0 | 0000 | Working Register 0 | | | | | | | | | | | | | | | | 0000 |
| WREG1 | 0002 | Working Register 1 | | | | | | | | | | | | | | | | 0000 |
| WREG2 | 0004 | Working Register 2 | | | | | | | | | | | | | | | | 0000 |
| WREG3 | 0006 | Working Register 3 | | | | | | | | | | | | | | | | 0000 |
| WREG4 | 0008 | Working Register 4 | | | | | | | | | | | | | | | | 0000 |
| WREG5 | 000A | Working Register 5 | | | | | | | | | | | | | | | | 0000 |
| WREG6 | 000C | Working Register 6 | | | | | | | | | | | | | | | | 0000 |
| WREG7 | 000E | Working Register 7 | | | | | | | | | | | | | | | | 0000 |
| WREG8 | 0010 | Working Register 8 | | | | | | | | | | | | | | | | 0000 |
| WREG9 | 0012 | Working Register 9 | | | | | | | | | | | | | | | | 0000 |
| WREG10 | 0014 | Working Register 10 | | | | | | | | | | | | | | | | 0000 |
| WREG11 | 0016 | Working Register 11 | | | | | | | | | | | | | | | | 0000 |
| WREG12 | 0018 | Working Register 12 | | | | | | | | | | | | | | | | 0000 |
| WREG13 | 001A | Working Register 13 | | | | | | | | | | | | | | | | 0000 |
| WREG14 | 001C | Working Register 14 | | | | | | | | | | | | | | | | 0000 |
| WREG15 | 001E | Working Register 15 | | | | | | | | | | | | | | | | 0800 |
| SPLIM | 0020 | Stack Pointer Limit Register | | | | | | | | | | | | | | | | xxxx |
| ACCAL | 0022 | Accumulator A Low Word Register | | | | | | | | | | | | | | | | 0000 |
| ACCAH | 0024 | Accumulator A High Word Register | | | | | | | | | | | | | | | | 0000 |
| ACCAU | 0026 | Accumulator A Upper Word Register | | | | | | | | | | | | | | | | 0000 |
| ACCBL | 0028 | Accumulator B Low Word Register | | | | | | | | | | | | | | | | 0000 |
| ACCBH | 002A | Accumulator B High Word Register | | | | | | | | | | | | | | | | 0000 |
| ACCBU | 002C | Accumulator B Upper Word Register | | | | | | | | | | | | | | | | 0000 |
| PCL | 002E | Program Counter Low Word Register | | | | | | | | | | | | | | | | 0000 |
| PCH | 0030 | — | — | — | — | — | — | — | — | Program Counter High Byte Register | | | | | | | | 0000 |
| TBLPAG | 0032 | — | — | — | — | — | — | — | — | Table Page Address Pointer Register | | | | | | | | 0000 |
| PSVPAG | 0034 | — | — | — | — | — | — | — | — | Program Memory Visibility Page Address Pointer Register | | | | | | | | 0000 |
| RCOUNT | 0036 | Repeat Loop Counter Register | | | | | | | | | | | | | | | | xxxx |
| DCOUNT | 0038 | DCOUNT<15:0> | | | | | | | | | | | | | | | | xxxx |
| DOSTARTL | 003A | DOSTARTL<15:1> | | | | | | | | | | | | | | | 0 | xxxx |
| DOSTARTH | 003C | — | — | — | — | — | — | — | — | — | — | DOSTARTH<5:0> | | | | | | 00xx |
| DOENDL | 003E | DOENDL<15:1> | | | | | | | | | | | | | | | 0 | xxxx |
| DOENDH | 0040 | — | — | — | — | — | — | — | — | — | — | DOENDH | | | | | | 00xx |
| SR | 0042 | OA | OB | SA | SB | OAB | SAB | DA | DC | IPL2 | IPL1 | IPL0 | RA | N | OV | Z | C | 0000 |
| CORCON | 0044 | — | — | — | US | EDT | DL<2:0> | | | SATA | SATB | SATDW | ACCSAT | IPL3 | PSV | RND | IF | 0020 |
| MODCON | 0046 | XMODEN | YMODEN | — | — | BWM<3:0> | | | | YWM<3:0> | | | | XWM<3:0> | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



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**TABLE 4-1: CPU CORE REGISTERS MAP (CONTINUED)**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| XMODSRT | 0048 | XS<15:1> | | | | | | | | | | | | | | | 0 | xxxx |
| XMODEND | 004A | XE<15:1> | | | | | | | | | | | | | | | 1 | xxxx |
| YMODSRT | 004C | YS<15:1> | | | | | | | | | | | | | | | 0 | xxxx |
| YMODEND | 004E | YE<15:1> | | | | | | | | | | | | | | | 1 | xxxx |
| XBREV | 0050 | BREN | XB<14:0> | | | | | | | | | | | | | | | xxxx |
| DISICNT | 0052 | — | — | Disable Interrupts Counter Register | | | | | | | | | | | | | | xxxx |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-2: CHANGE NOTIFICATION REGISTER MAP FOR dsPIC33FJ12MC202**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| CNEN1 | 0060 | CN15IE | CN14IE | CN13IE | CN12IE | CN11IE | — | — | — | CN7IE | CN6IE | CN5IE | CN4IE | CN3IE | CN2IE | CN1IE | CN0IE | 0000 |
| CNEN2 | 0062 | — | CN30IE | CN29IE | — | CN27IE | — | — | CN24IE | CN23IE | CN22IE | CN21IE | — | — | — | — | CN16IE | 0000 |
| CNPU1 | 0068 | CN15PUE | CN14PUE | CN13PUE | CN12PUE | CN11PUE | — | — | — | CN7PUE | CN6PUE | CN5PUE | CN4PUE | CN3PUE | CN2PUE | CN1PUE | CN0PUE | 0000 |
| CNPU2 | 006A | — | CN30PUE | CN29PUE | — | CN27PUE | — | — | CN24PUE | CN23PUE | CN22PUE | CN21PUE | — | — | — | — | CN16PUE | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-3: CHANGE NOTIFICATION REGISTER MAP FOR dsPIC33FJ12MC201**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| CNEN1 | 0060 | — | CN14IE | CN13IE | CN12IE | CN11IE | — | — | — | — | — | CN5IE | CN4IE | CN3IE | CN2IE | CN1IE | CN0IE | 0000 |
| CNEN2 | 00C2 | — | CN30IE | CN29IE | — | — | — | — | — | CN23IE | CN22IE | CN21IE | — | — | — | — | — | 0000 |
| CNPU1 | 0068 | — | CN14PUE | CN13PUE | CN12PUE | CN11PUE | — | — | — | — | — | CN5PUE | CN4PUE | CN3PUE | CN2PUE | CN1PUE | CN0PUE | 0000 |
| CNPU2 | 006A | — | CN30PUE | CN29PUE | — | — | — | — | — | CN23PUE | CN22PUE | CN21PUE | — | — | — | — | — | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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**TABLE 4-4: INTERRUPT CONTROLLER REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| INTCON1 | 0080 | NSTDIS | OVAERR | OVBERR | COVAERR | COVBERR | OVATE | OVBTE | COVTE | SFTACERR | DIV0ERR | — | MATHERR | ADDRERR | STKERR | OSCFAIL | — | 0000 |
| INTCON2 | 0082 | ALTIVT | DISI | — | — | — | — | — | — | — | — | — | — | — | INT2EP | INT1EP | INT0EP | 0000 |
| IFS0 | 0084 | — | — | AD1IF | U1TXIF | U1RXIF | SPI1IF | SPI1EIF | T3IF | T2IF | OC2IF | IC2IF | — | T1IF | OC1IF | IC1IF | INT0IF | 0000 |
| IFS1 | 0086 | — | — | INT2IF | — | — | — | — | — | IC8IF | IC7IF | — | INT1IF | CNIF | — | MI2C1IF | SI2C1IF | 0000 |
| IFS3 | 008A | FLTA1IF | — | — | — | — | QEIIF | PWM1IF | — | — | — | — | — | — | — | — | — | 0000 |
| IFS4 | 008C | — | — | — | — | — | FLTA2IF | PWM2IF | — | — | — | — | — | — | — | U1EIF | — | 0000 |
| IEC0 | 0094 | — | — | AD1IE | U1TXIE | U1RXIE | SPI1IE | SPI1EIE | T3IE | T2IE | OC2IE | IC2IE | — | T1IE | OC1IE | IC1IE | INT0IE | 0000 |
| IEC1 | 0096 | — | — | INT2IE | — | — | — | — | — | IC8IE | IC7IE | — | INT1IE | CNIE | — | MI2C1IE | SI2C1IE | 0000 |
| IEC3 | 009A | FLTA1IE | — | — | — | — | QEIIE | PWM1IE | — | — | — | — | — | — | — | — | — | 0000 |
| IEC4 | 009C | — | — | — | — | — | FLTA2IE | PWM2IE | — | — | — | — | — | — | — | U1EIE | — | 0000 |
| IPC0 | 00A4 | — | T1IP<2:0> | | | — | OC1IP<2:0> | | | — | IC1IP<2:0> | | | — | INT0IP<2:0> | | | 4444 |
| IPC1 | 00A6 | — | T2IP<2:0> | | | — | OC2IP<2:0> | | | — | IC2IP<2:0> | | | — | — | — | — | 4440 |
| IPC2 | 00A8 | — | U1RXIP<2:0> | | | — | SPI1IP<2:0> | | | — | SPI1EIP<2:0> | | | — | T3IP<2:0> | | | 4444 |
| IPC3 | 00AA | — | — | — | — | — | — | — | — | — | AD1IP<2:0> | | | — | U1TXIP<2:0> | | | 0044 |
| IPC4 | 00AC | — | CNIP<2:0> | | | — | — | — | — | — | MI2C1IP<2:0> | | | — | SI2C1IP<2:0> | | | 4044 |
| IPC5 | 00AE | — | IC8IP<2:0> | | | — | IC7IP<2:0> | | | — | — | — | — | — | INT1IP<2:0> | | | 4404 |
| IPC7 | 00B2 | — | — | — | — | — | — | — | — | — | INT2IP<2:0> | | | — | — | — | — | 0040 |
| IPC14 | 00C0 | — | — | — | — | — | QEIIP<2:0> | | | — | PWM1IP<2:0> | | | — | — | — | — | 0440 |
| IPC15 | 00C2 | — | FLTA1IP<2:0> | | | — | — | — | — | — | — | — | — | — | — | — | — | 4000 |
| IPC16 | 00C4 | — | — | — | — | — | — | — | — | — | U1EIP<2:0> | | | — | — | — | — | 0040 |
| IPC18 | 00C8 | — | — | — | — | — | FLTA2IP<2:0> | | | — | PWM2IP<2:0> | | | — | — | — | — | 0440 |
| INTTREG | 00E0 | — | — | — | — | ILR<3:0> | | | | — | VECNUM<6:0> | | | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



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**TABLE 4-5: TIMER REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| TMR1 | 0100 | Timer1 Register | | | | | | | | | | | | | | | | 0000 |
| PR1 | 0102 | Period Register 1 | | | | | | | | | | | | | | | | FFFF |
| T1CON | 0104 | TON | — | TSIDL | — | — | — | — | — | — | TGATE | TCKPS<1:0> | | — | TSYNC | TCS | — | 0000 |
| TMR2 | 0106 | Timer2 Register | | | | | | | | | | | | | | | | 0000 |
| TMR3HLD | 0108 | Timer3 Holding Register (for 32-bit timer operations only) | | | | | | | | | | | | | | | | xxxx |
| TMR3 | 010A | Timer3 Register | | | | | | | | | | | | | | | | 0000 |
| PR2 | 010C | Period Register 2 | | | | | | | | | | | | | | | | FFFF |
| PR3 | 010E | Period Register 3 | | | | | | | | | | | | | | | | FFFF |
| T2CON | 0110 | TON | — | TSIDL | — | — | — | — | — | — | TGATE | TCKPS<1:0> | | T32 | — | TCS | — | 0000 |
| T3CON | 0112 | TON | — | TSIDL | — | — | — | — | — | — | TGATE | TCKPS<1:0> | | — | — | TCS | — | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-6: INPUT CAPTURE REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| IC1BUF | 0140 | Input 1 Capture Register | | | | | | | | | | | | | | | | xxxx |
| IC1CON | 0142 | — | — | ICSIDL | — | — | — | — | — | ICTMR | ICI<1:0> | | ICOV | ICBNE | ICM<2:0> | | | 0000 |
| IC2BUF | 0144 | Input 2 Capture Register | | | | | | | | | | | | | | | | xxxx |
| IC2CON | 0146 | — | — | ICSIDL | — | — | — | — | — | ICTMR | ICI<1:0> | | ICOV | ICBNE | ICM<2:0> | | | 0000 |
| IC7BUF | 0158 | Input 7 Capture Register | | | | | | | | | | | | | | | | xxxx |
| IC7CON | 015A | — | — | ICSIDL | — | — | — | — | — | ICTMR | ICI<1:0> | | ICOV | ICBNE | ICM<2:0> | | | 0000 |
| IC8BUF | 015C | Input 8Capture Register | | | | | | | | | | | | | | | | xxxx |
| IC8CON | 015E | — | — | ICSIDL | — | — | — | — | — | ICTMR | ICI<1:0> | | ICOV | ICBNE | ICM<2:0> | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-7: OUTPUT COMPARE REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| OC1RS | 0180 | Output Compare 1 Secondary Register | | | | | | | | | | | | | | | | xxxx |
| OC1R | 0182 | Output Compare 1 Register | | | | | | | | | | | | | | | | xxxx |
| OC1CON | 0184 | — | — | OCSIDL | — | — | — | — | — | — | — | — | OCFLT | OCTSEL | OCM<2:0> | | | 0000 |
| OC2RS | 0186 | Output Compare 2 Secondary Register | | | | | | | | | | | | | | | | xxxx |
| OC2R | 0188 | Output Compare 2 Register | | | | | | | | | | | | | | | | xxxx |
| OC2CON | 018A | — | — | OCSIDL | — | — | — | — | — | — | — | — | OCFLT | OCTSEL | OCM<2:0> | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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**TABLE 4-8: 6-OUTPUT PWM1 REGISTER MAP FOR dsPIC33FJ12MC202**

| SFR Name | Addr. | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Reset State |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| P1TCON | 01C0 | PTEN | — | PTSIDL | — | — | — | — | — | PTOPS<3:0> | | | | PTCKPS<1:0> | | PTMOD<1:0> | | 0000 0000 0000 0000 |
| P1TMR | 01C2 | PTDIR | PWM Timer Count Value Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1TPER | 01C4 | — | PWM Time Base Period Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1SECMP | 01C6 | SEVTDIR | PWM Special Event Compare Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| PWM1CON1 | 01C8 | — | — | — | — | — | PMOD3 | PMOD2 | PMOD1 | — | PEN3H | PEN2H | PEN1H | — | PEN3L | PEN2L | PEN1L | 0000 0000 1111 1111 |
| PWM1CON2 | 01CA | — | — | — | — | SEVOPS<3:0> | | | | — | — | — | — | — | IUE | OSYNC | UDIS | 0000 0000 0000 0000 |
| P1DTCON1 | 01CC | DTBPS<1:0> | | DTB<5:0> | | | | | | DTAPS<1:0> | | DTA<5:0> | | | | | | 0000 0000 0000 0000 |
| P1DTCON2 | 01CE | — | — | — | — | — | — | — | — | — | — | DTS3A | DTS3I | DTS2A | DTS2I | DTS1A | DTS1I | 0000 0000 0000 0000 |
| P1FLTACON | 01D0 | — | — | FAOV3H | FAOV3L | FAOV2H | FAOV2L | FAOV1H | FAOV1L | FLTAM | — | — | — | — | FAEN3 | FAEN2 | FAEN1 | 0000 0000 0000 0000 |
| P1OVDCON | 01D4 | — | — | POVD3H | POVD3L | POVD2H | POVD2L | POVD1H | POVD1L | — | — | POUT3H | POUT3L | POUT2H | POUT2L | POUT1H | POUT1L | 1111 1111 0000 0000 |
| P1DC1 | 01D6 | PWM Duty Cycle 1 Register | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1DC2 | 01D8 | PWM Duty Cycle 2 Register | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1DC3 | 01DA | PWM Duty Cycle 3 Register | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |

**Legend:** u = uninitialized bit, — = unimplemented, read as '0'

**TABLE 4-9: 4-OUTPUT PWM1 REGISTER MAP FOR dsPIC33FJ12MC201**

| SFR Name | Addr. | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Reset State |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| P1TCON | 01C0 | PTEN | — | PTSIDL | — | — | — | — | — | PTOPS<3:0> | | | | PTCKPS<1:0> | | PTMOD<1:0> | | 0000 0000 0000 0000 |
| P1TMR | 01C2 | PTDIR | PWM Timer Count Value Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1TPER | 01C4 | — | PWM Time Base Period Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1SECMP | 01C6 | SEVTDIR | PWM Special Event Compare Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| PWM1CON1 | 01C8 | — | — | — | — | — | — | PMOD2 | PMOD1 | — | — | PEN2H | PEN1H | — | — | PEN2L | PEN1L | 0000 0000 1111 1111 |
| PWM1CON2 | 01CA | — | — | — | — | SEVOPS<3:0> | | | | — | — | — | — | — | IUE | OSYNC | UDIS | 0000 0000 0000 0000 |
| P1DTCON1 | 01CC | DTBPS<1:0> | | DTB<5:0> | | | | | | DTAPS<1:0> | | DTA<5:0> | | | | | | 0000 0000 0000 0000 |
| P1DTCON2 | 01CE | — | — | — | — | — | — | — | — | — | — | — | — | DTS2A | DTS2I | DTS1A | DTS1I | 0000 0000 0000 0000 |
| P1FLTACON | 01D0 | — | — | — | — | FAOV2H | FAOV2L | FAOV1H | FAOV1L | FLTAM | — | — | — | — | — | FAEN2 | FAEN1 | 0000 0000 0000 0000 |
| P1OVDCON | 01D4 | — | — | — | — | POVD2H | POVD2L | POVD1H | POVD1L | — | — | — | — | POUT2H | POUT2L | POUT1H | POUT1L | 1111 1111 0000 0000 |
| P1DC1 | 01D6 | PWM Duty Cycle 1 Register | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P1DC2 | 01D8 | PWM Duty Cycle 2 Register | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |

**Legend:** u = uninitialized bit, — = unimplemented, read as '0'



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**TABLE 4-10: 2-OUTPUT PWM2 REGISTER MAP**

| SFR Name | Addr. | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Reset State |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| P2TCON | 05C0 | PTEN | — | PTSIDL | — | — | — | — | — | PTOPS<3:0> | | | | PTCKPS<1:0> | | PTMOD<1:0> | | 0000 0000 0000 0000 |
| P2TMR | 05C2 | PTDIR | PWM Timer Count Value Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P2TPER | 05C4 | — | PWM Time Base Period Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| P2SECMP | 05C6 | SEVTDIR | PWM Special Event Compare Register | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| PWM2CON1 | 05C8 | — | — | — | — | — | — | — | PMOD1 | — | — | — | PEN1H | — | — | — | PEN1L | 0000 0000 1111 1111 |
| PWM2CON2 | 05CA | — | — | — | — | SEVOPS<3:0> | | | | — | — | — | — | — | IUE | OSYNC | UDIS | 0000 0000 0000 0000 |
| P2DTCON1 | 05CC | DTBPS<1:0> | | DTB<5:0> | | | | | | DTAPS<1:0> | | DTA<5:0> | | | | | | 0000 0000 0000 0000 |
| P2DTCON2 | 05CE | — | — | — | — | — | — | — | — | — | — | — | — | — | — | DTS1A | DTS1I | 0000 0000 0000 0000 |
| P2FLTACON | 05D0 | — | — | — | — | — | — | FAOV1H | FAOV1L | FLTAM | — | — | — | — | — | — | FAEN1 | 0000 0000 0000 0000 |
| P2OVDCON | 05D4 | — | — | — | — | — | — | POVD1H | POVD1L | — | — | — | — | — | — | POUT1H | POUT1L | 1111 1111 0000 0000 |
| P2DC1 | 05D6 | PWM Duty Cycle 1 Register | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |

**Legend:** u = uninitialized bit, — = unimplemented, read as '0'

**TABLE 4-11: QEI1 REGISTER MAP**

| SFR Name | Addr. | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | Reset State |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| QEI1CON | 01E0 | CNTERR | — | QEISIDL | INDX | UPDN | QEIM<2:0> | | | SWPAB | PCDOUT | TQGATE | TQCKPS<1:0> | | POSRES | TQCS | UPDN_SRC | 0000 0000 0000 0000 |
| DFLT1CON | 01E2 | — | — | — | — | — | IMV<1:0> | | CEID | QEOUT | QECK<2:0> | | | — | — | — | — | 0000 0000 0000 0000 |
| POS1CNT | 01E4 | Position Counter<15:0> | | | | | | | | | | | | | | | | 0000 0000 0000 0000 |
| MAX1CNT | 01E6 | Maximum Count<15:0> | | | | | | | | | | | | | | | | 1111 1111 1111 1111 |

**Legend:** u = uninitialized bit, — = unimplemented, read as '0'

**TABLE 4-12: I2C1 REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| I2C1RCV | 0200 | — | — | — | — | — | — | — | — | Receive Register | | | | | | | | 0000 |
| I2C1TRN | 0202 | — | — | — | — | — | — | — | — | Transmit Register | | | | | | | | 00FF |
| I2C1BRG | 0204 | — | — | — | — | — | — | — | Baud Rate Generator Register | | | | | | | | | 0000 |
| I2C1CON | 0206 | I2CEN | — | I2CSIDL | SCLREL | IPMIEN | A10M | DISSLW | SMEN | GCEN | STREN | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN | 1000 |
| I2C1STAT | 0208 | ACKSTAT | TRSTAT | — | — | — | BCL | GCSTAT | ADD10 | IWCOL | I2COV | D_A | P | S | R_W | RBF | TBF | 0000 |
| I2C1ADD | 020A | — | — | — | — | — | — | Address Register | | | | | | | | | | 0000 |
| I2C1MSK | 020C | — | — | — | — | — | — | Address Mask Register | | | | | | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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**TABLE 4-13: UART1 REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| U1MODE | 0220 | UARTEN | — | USIDL | IREN | RTSMD | — | UEN1 | UEN0 | WAKE | LPBACK | ABAUD | URXINV | BRGH | PDSEL<1:0> | | STSEL | 0000 |
| U1STA | 0222 | UTXISEL1 | UTXINV | UTXISEL0 | — | UTXBRK | UTXEN | UTXBF | TRMT | URXISEL<1:0> | | ADDEN | RIDLE | PERR | FERR | OERR | URXDA | 0110 |
| U1TXREG | 0224 | — | — | — | — | — | — | — | UART Transmit Register | | | | | | | | | xxxx |
| U1RXREG | 0226 | — | — | — | — | — | — | — | UART Receive Register | | | | | | | | | 0000 |
| U1BRG | 0228 | Baud Rate Generator Prescaler | | | | | | | | | | | | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-14: SPI1 REGISTER MAP**

| SFR Name | SFR Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| SPI1STAT | 0240 | SPIEN | — | SPISIDL | — | — | — | — | — | — | SPIROV | — | — | — | — | SPITBF | SPIRBF | 0000 |
| SPI1CON1 | 0242 | — | — | — | DISSCK | DISSDO | MODE16 | SMP | CKE | SSEN | CKP | MSTEN | SPRE<2:0> | | | PPRE<1:0> | | 0000 |
| SPI1CON2 | 0244 | FRMEN | SPIFSD | FRMPOL | — | — | — | — | — | — | — | — | — | — | — | FRMDLY | — | 0000 |
| SPI1BUF | 0248 | SPI1 Transmit and Receive Buffer Register | | | | | | | | | | | | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



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**TABLE 4-15: ADC1 REGISTER MAP FOR dsPIC33FJ12MC202**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| ADC1BUF0 | 0300 | ADC Data Buffer 0 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF1 | 0302 | ADC Data Buffer 1 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF2 | 0304 | ADC Data Buffer 2 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF3 | 0306 | ADC Data Buffer 3 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF4 | 0308 | ADC Data Buffer 4 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF5 | 030A | ADC Data Buffer 5 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF6 | 030C | ADC Data Buffer 6 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF7 | 030E | ADC Data Buffer 7 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF8 | 0310 | ADC Data Buffer 8 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF9 | 0312 | ADC Data Buffer 9 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFA | 0314 | ADC Data Buffer 10 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFB | 0316 | ADC Data Buffer 11 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFC | 0318 | ADC Data Buffer 12 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFD | 031A | ADC Data Buffer 13 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFE | 031C | ADC Data Buffer 14 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFF | 031E | ADC Data Buffer 15 | | | | | | | | | | | | | | | | xxxx |
| AD1CON1 | 0320 | ADON | — | ADSIDL | — | — | AD12B | FORM<1:0> | | SSRC<2:0> | | | — | SIMSAM | ASAM | SAMP | DONE | 0000 |
| AD1CON2 | 0322 | VCFG<2:0> | | | — | — | CSCNA | CHPS<1:0> | | BUFS | — | SMPI<3:0> | | | | BUFM | ALTS | 0000 |
| AD1CON3 | 0324 | ADRC | — | — | SAMC<4:0> | | | | | ADCS<7:0> | | | | | | | | 0000 |
| AD1CHS123 | 0326 | — | — | — | — | — | CH123NB<1:0> | | CH123SB | — | — | — | — | — | CH123NA<1:0> | | CH123SA | 0000 |
| AD1CHS0 | 0328 | CH0NB | — | — | CH0SB<4:0> | | | | | CH0NA | — | — | CH0SA<4:0> | | | | | 0000 |
| AD1PCFGL | 032C | — | — | — | — | — | — | — | — | — | — | PCFG5 | PCFG4 | PCFG3 | PCFG2 | PCFG1 | PCFG0 | 0000 |
| AD1CSSL | 0330 | — | — | — | — | — | — | — | — | — | — | CSS5 | CSS4 | CSS3 | CSS2 | CSS1 | CSS0 | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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**TABLE 4-16: ADC1 REGISTER MAP FOR dsPIC33FJ12MC201**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| ADC1BUF0 | 0300 | ADC Data Buffer 0 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF1 | 0302 | ADC Data Buffer 1 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF2 | 0304 | ADC Data Buffer 2 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF3 | 0306 | ADC Data Buffer 3 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF4 | 0308 | ADC Data Buffer 4 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF5 | 030A | ADC Data Buffer 5 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF6 | 030C | ADC Data Buffer 6 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF7 | 030E | ADC Data Buffer 7 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF8 | 0310 | ADC Data Buffer 8 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUF9 | 0312 | ADC Data Buffer 9 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFA | 0314 | ADC Data Buffer 10 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFB | 0316 | ADC Data Buffer 11 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFC | 0318 | ADC Data Buffer 12 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFD | 031A | ADC Data Buffer 13 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFE | 031C | ADC Data Buffer 14 | | | | | | | | | | | | | | | | xxxx |
| ADC1BUFF | 031E | ADC Data Buffer 15 | | | | | | | | | | | | | | | | xxxx |
| AD1CON1 | 0320 | ADON | — | ADSIDL | — | — | AD12B | FORM<1:0> | | SSRC<2:0> | | | — | SIMSAM | ASAM | SAMP | DONE | 0000 |
| AD1CON2 | 0322 | VCFG<2:0> | | | — | — | CSCNA | CHPS<1:0> | | BUFS | — | SMPI<3:0> | | | | BUFM | ALTS | 0000 |
| AD1CON3 | 0324 | ADRC | — | — | SAMC<4:0> | | | | | ADCS<7:0> | | | | | | | | 0000 |
| AD1CHS123 | 0326 | — | — | — | — | — | CH123NB<1:0> | | CH123SB | — | — | — | — | — | CH123NA<1:0> | | CH123SA | 0000 |
| AD1CHS0 | 0328 | CH0NB | — | — | CH0SB<4:0> | | | | | CH0NA | — | — | CH0SA<4:0> | | | | | 0000 |
| AD1PCFGL | 032C | — | — | — | — | — | — | — | — | — | — | — | — | PCFG3 | PCFG2 | PCFG1 | PCFG0 | 0000 |
| AD1CSSL | 0330 | — | — | — | — | — | — | — | — | — | — | — | — | CSS3 | CSS2 | CSS1 | CSS0 | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



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**TABLE 4-17: PERIPHERAL PIN SELECT INPUT REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| RPINR0 | 0680 | — | — | — | INT1R<4:0> | | | | | — | — | — | — | — | — | — | — | 1F00 |
| RPINR1 | 0682 | — | — | — | — | — | — | — | — | — | — | — | INT2R<4:0> | | | | | 001F |
| RPINR3 | 0686 | — | — | — | T3CKR<4:0> | | | | | — | — | — | T2CKR<4:0> | | | | | 1F1F |
| RPINR7 | 068E | — | — | — | IC2R<4:0> | | | | | — | — | — | IC1R<4:0> | | | | | 1F1F |
| RPINR10 | 0694 | — | — | — | IC8R<4:0> | | | | | — | — | — | IC7R<4:0> | | | | | 1F1F |
| RPINR11 | 0696 | — | — | — | — | — | — | — | — | — | — | — | OCFAR<4:0> | | | | | 001F |
| RPINR12 | 0698 | — | — | — | — | — | — | — | — | — | — | — | FLTA1R<4:0> | | | | | 001F |
| RPINR13 | 069A | — | — | — | — | — | — | — | — | — | — | — | FLTA2R<4:0> | | | | | 001F |
| RPINR14 | 069C | — | — | — | QEB1R<4:0> | | | | | — | — | — | QEA1R<4:0> | | | | | 1F1F |
| RPINR15 | 069E | — | — | — | — | — | — | — | — | — | — | — | INDX1R<4:0> | | | | | 001F |
| RPINR18 | 06A4 | — | — | — | U1CTSR<4:0> | | | | | — | — | — | U1RXR<4:0> | | | | | 1F1F |
| RPINR20 | 06A8 | — | — | — | SCK1R<4:0> | | | | | — | — | — | SDI1R<4:0> | | | | | 1F1F |
| RPINR21 | 06AA | — | — | — | — | — | — | — | — | — | — | — | SS1R<4:0> | | | | | 001F |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-18: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP FOR dsPIC33FJ12MC202**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| RPOR0 | 06C0 | — | — | — | RP1R<4:0> | | | | | — | — | — | RP0R<4:0> | | | | | 0000 |
| RPOR1 | 06C2 | — | — | — | RP3R<4:0> | | | | | — | — | — | RP2R<4:0> | | | | | 0000 |
| RPOR2 | 06C4 | — | — | — | RP5R<4:0> | | | | | — | — | — | RP4R<4:0> | | | | | 0000 |
| RPOR3 | 06C6 | — | — | — | RP7R<4:0> | | | | | — | — | — | RP6R<4:0> | | | | | 0000 |
| RPOR4 | 06C8 | — | — | — | RP9R<4:0> | | | | | — | — | — | RP8R<4:0> | | | | | 0000 |
| RPOR5 | 06CA | — | — | — | RP11R<4:0> | | | | | — | — | — | RP10R<4:0> | | | | | 0000 |
| RPOR6 | 06CC | — | — | — | RP13R<4:0> | | | | | — | — | — | RP12R<4:0> | | | | | 0000 |
| RPOR7 | 06CE | — | — | — | RP15R<4:0> | | | | | — | — | — | RP14R<4:0> | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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**TABLE 4-19: PERIPHERAL PIN SELECT OUTPUT REGISTER MAP FOR dsPIC33FJ12MC201**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| RPOR0 | 06C0 | — | — | — | RP1R<4:0> | | | | | — | — | — | RP0R<4:0> | | | | | 0000 |
| RPOR2 | 06C4 | — | — | — | — | — | — | — | — | — | — | — | RP4R<4:0> | | | | | 0000 |
| RPOR3 | 06C6 | — | — | — | RP7R<4:0> | | | | | — | — | — | — | — | — | — | — | 0000 |
| RPOR4 | 06C8 | — | — | — | RP9R<4:0> | | | | | — | — | — | RP8R<4:0> | | | | | 0000 |
| RPOR6 | 06CC | — | — | — | RP13R<4:0> | | | | | — | — | — | RP12R<4:0> | | | | | 0000 |
| RPOR7 | 06CE | — | — | — | RP15R<4:0> | | | | | — | — | — | RP14R<4:0> | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-20: PORTA REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| TRISA | 02C0 | — | — | — | — | — | — | — | — | — | — | — | TRISA4 | TRISA3 | TRISA2 | TRISA1 | TRISA0 | 001F |
| PORTA | 02C2 | — | — | — | — | — | — | — | — | — | — | — | RA4 | RA3 | RA2 | RA1 | RA0 | xxxx |
| LATA | 02C4 | — | — | — | — | — | — | — | — | — | — | — | LATA4 | LATA3 | LATA2 | LATA1 | LATA0 | xxxx |
| ODCA | 02C6 | — | — | — | — | — | — | — | — | — | — | — | ODCA4 | ODCA3 | ODCA2 | ODCA1 | ODCA0 | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-21: PORTB REGISTER MAP FOR dsPIC33FJ12MC202**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| TRISB | 02C8 | TRISB15 | TRISB14 | TRISB13 | TRISB12 | TRISB11 | TRISB10 | TRISB9 | TRISB8 | TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 | FFFF |
| PORTB | 02CA | RB15 | RB14 | RB13 | RB12 | RB11 | RB10 | RB9 | RB8 | RB7 | RB6 | RB5 | RB4 | RB3 | RB2 | RB1 | RB0 | xxxx |
| LATB | 02CC | LATB15 | LATB14 | LATB13 | LATB12 | LATB11 | LATB10 | LATB9 | LATB8 | LATB7 | LATB6 | LATB5 | LATB4 | LATB3 | LATB2 | LATB1 | LATB0 | xxxx |
| ODCB | 02CE | ODCB15 | ODCB14 | ODCB13 | ODCB12 | ODCB11 | ODCB10 | ODCB9 | ODCB8 | ODCB7 | ODCB6 | ODCB5 | ODCB4 | ODCB3 | ODCB2 | ODCB1 | ODCB0 | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

**TABLE 4-22: PORTB REGISTER MAP FOR dsPIC33FJ12MC201**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| TRISB | 02C8 | TRISB15 | TRISB14 | TRISB13 | TRISB12 | — | — | TRISB9 | TRISB8 | TRISB7 | — | — | TRISB4 | — | — | TRISB1 | TRISB0 | F393 |
| PORTB | 02CA | RB15 | RB14 | RB13 | RB12 | — | — | RB9 | RB8 | RB7 | — | — | RB4 | — | — | RB1 | RB0 | xxxx |
| LATB | 02CC | LATB15 | LATB14 | LATB13 | LATB12 | — | — | LATB9 | LATB8 | LATB7 | — | — | LATB4 | — | — | LATB1 | LATB0 | xxxx |
| ODCB | 02CE | ODCB15 | ODCB14 | ODCB13 | ODCB12 | — | — | ODCB9 | ODCB8 | ODCB7 | — | — | ODCB4 | — | — | ODCB1 | ODCB0 | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal



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**TABLE 4-23: SYSTEM CONTROL REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| RCON | 0740 | TRAPR | IOPUWR | — | — | — | — | CM | VREGS | EXTR | SWR | SWDTEN | WDTO | SLEEP | IDLE | BOR | POR | xxxx(1) |
| OSCCON | 0742 | — | COSC<2:0> | | | — | NOSC<2:0> | | | CLKLOCK | IOLOCK | LOCK | — | CF | — | LPOSCEN | OSWEN | 0300(2) |
| CLKDIV | 0744 | ROI | DOZE<2:0> | | | DOZEN | FRCDIV<2:0> | | | PLLPOST<1:0> | | — | PLLPRE<4:0> | | | | | 3040 |
| PLLFBD | 0746 | — | — | — | — | — | — | — | PLLDIV<8:0> | | | | | | | | | 0030 |
| OSCTUN | 0748 | — | — | — | — | — | — | — | — | — | — | TUN<5:0> | | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
**Note 1:** RCON register Reset values dependent on type of Reset.
**2:** OSCCON register Reset values dependent on the FOSC Configuration bits and by type of Reset.

**TABLE 4-24: NVM REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| NVMCON | 0760 | WR | WREN | WRERR | — | — | — | — | — | — | ERASE | — | — | NVMOP<3:0> | | | | 0000(1) |
| NVMKEY | 0766 | — | — | — | — | — | — | — | — | NVMKEY<7:0> | | | | | | | | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
**Note 1:** Reset value shown is for POR only. Value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset.

**TABLE 4-25: PMD REGISTER MAP**

| File Name | Addr | Bit 15 | Bit 14 | Bit 13 | Bit 12 | Bit 11 | Bit 10 | Bit 9 | Bit 8 | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 | All Resets |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| PMD1 | 0770 | — | — | T3MD | T2MD | T1MD | QEIMD | PWM1MD | — | I2C1MD | — | U1MD | — | SPI1MD | — | — | AD1MD | 0000 |
| PMD2 | 0772 | IC8MD | IC7MD | — | — | — | — | IC2MD | IC1MD | — | — | — | — | — | — | OC2MD | OC1MD | 0000 |
| PMD3 | 0774 | — | — | — | — | — | — | — | — | — | — | — | PWM2MD | — | — | — | — | 0000 |

**Legend:** x = unknown value on Reset, — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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### 4.2.6 SOFTWARE STACK

In addition to its use as a working register, the W15 register in the dsPIC33FJ12MC201/202 devices is also used as a software Stack Pointer. The Stack Pointer always points to the first available free word and grows from lower to higher addresses. It pre-decrements for stack pops and post-increments for stack pushes, as shown in Figure 4-4. For a PC push during any CALL instruction, the MSb of the PC is zero-extended before the push, ensuring that the MSb is always clear.

| **Note:** | A PC push during exception processing concatenates the SRL register to the MSb of the PC prior to the push. |
|---|---|

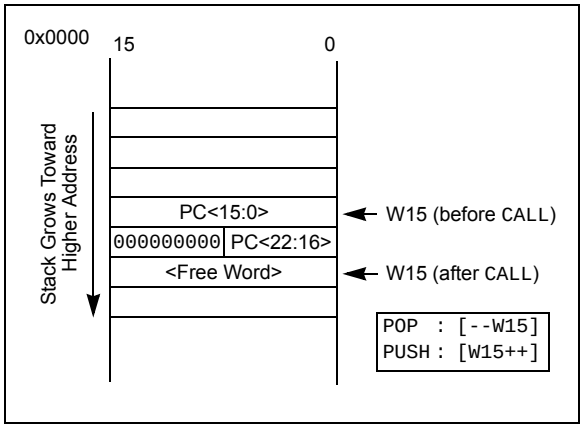
The Stack Pointer Limit register (SPLIM) associated with the Stack Pointer sets an upper address boundary for the stack. SPLIM is uninitialized at Reset. As is the case for the Stack Pointer, SPLIM<0> is forced to '0' because all stack operations must be word aligned.

Whenever an EA is generated using W15 as a source or destination pointer, the resulting address is compared with the value in SPLIM. If the contents of the Stack Pointer (W15) and the SPLIM register are equal and a push operation is performed, a stack error trap will not occur. However, the stack error trap will occur on a subsequent push operation. For example, to cause a stack error trap when the stack grows beyond address 0x0C00 in RAM, initialize the SPLIM with the value 0x0BFE.

Similarly, a Stack Pointer underflow (stack error) trap is generated when the Stack Pointer address is found to be less than 0x0800. This prevents the stack from interfering with the SFR space.

A write to the SPLIM register should not be immediately followed by an indirect read operation using W15.

**FIGURE 4-4: CALL STACK FRAME**




### 4.2.7 DATA RAM PROTECTION FEATURE

The dsPIC33F product family supports Data RAM protection features that enable segments of RAM to be protected when used in conjunction with Boot and Secure Code Segment Security. BSRAM (Secure RAM segment for BS) is accessible only from the Boot Segment Flash code, when enabled. SSRAM (Secure RAM segment for RAM) is accessible only from the Secure Segment Flash code, when enabled. See Table 4-1 for an overview of the BSRAM and SSRAM SFRs.

## 4.3 Instruction Addressing Modes

The addressing modes shown in Table 4-26 form the basis of the addressing modes that are optimized to support the specific features of individual instructions. The addressing modes provided in the MAC class of instructions differ from those provided in other instruction types.

### 4.3.1 FILE REGISTER INSTRUCTIONS

Most file register instructions use a 13-bit address field (f) to directly address data present in the first 8192 bytes of data memory (near data space). Most file register instructions employ a working register, W0, which is denoted as WREG in these instructions. The destination is typically either the same file register or WREG (with the exception of the MUL instruction), which writes the result to a register or register pair. The MOV instruction allows additional flexibility and can access the entire data space.

### 4.3.2 MCU INSTRUCTIONS

The three-operand MCU instructions are of the form:

Operand 3 = Operand 1 <function> Operand 2

where Operand 1 is always a working register (that is, the addressing mode can only be register direct), which is referred to as Wb. Operand 2 can be a W register, fetched from data memory, or a 5-bit literal. The result location can be either a W register or a data memory location. The following addressing modes are supported by MCU instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-Modified
- Register Indirect Pre-Modified
- 5-bit or 10-bit Literal

| **Note:** | Not all instructions support all the addressing modes given above. Individual instructions can support different subsets of these addressing modes. |
|---|---|


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**TABLE 4-26: FUNDAMENTAL ADDRESSING MODES SUPPORTED**

| Addressing Mode | Description |
|---|---|
| File Register Direct | The address of the file register is specified explicitly. |
| Register Direct | The contents of a register are accessed directly. |
| Register Indirect | The contents of Wn forms the Effective Address (EA). |
| Register Indirect Post-Modified | The contents of Wn forms the EA. Wn is post-modified (incremented or decremented) by a constant value. |
| Register Indirect Pre-Modified | Wn is pre-modified (incremented or decremented) by a signed constant value to form the EA. |
| Register Indirect with Register Offset (Register Indexed) | The sum of Wn and Wb forms the EA. |
| Register Indirect with Literal Offset | The sum of Wn and a literal forms the EA. |

### 4.3.3 MOVE AND ACCUMULATOR INSTRUCTIONS

Move instructions and the DSP accumulator class of instructions provide a greater degree of addressing flexibility than other instructions. In addition to the addressing modes supported by most MCU instructions, move and accumulator instructions also support Register Indirect with Register Offset Addressing mode, also referred to as Register Indexed mode.

**Note:** For the MOV instructions, the addressing mode specified in the instruction can differ for the source and destination EA. However, the 4-bit Wb (Register Offset) field is shared by both source and destination (but typically only used by one).

In summary, the following addressing modes are supported by move and accumulator instructions:

- Register Direct
- Register Indirect
- Register Indirect Post-modified
- Register Indirect Pre-modified
- Register Indirect with Register Offset (Indexed)
- Register Indirect with Literal Offset
- 8-bit Literal
- 16-bit Literal

**Note:** Not all instructions support all the addressing modes given above. Individual instructions may support different subsets of these addressing modes.

### 4.3.4 MAC INSTRUCTIONS

The dual source operand DSP instructions (CLR, ED, EDAC, MAC, MPY, MPY.N, MOVSAC, and MSC), also referred to as MAC instructions, use a simplified set of addressing modes to allow the user application to effectively manipulate the data pointers through register indirect tables.

The two-source operand prefetch registers must be members of the set {W8, W9, W10, W11}. For data reads, W8 and W9 are always directed to the X RAGU, and W10 and W11 are always directed to the Y AGU. The effective addresses generated (before and after modification) must, therefore, be valid addresses within X data space for W8 and W9 and Y data space for W10 and W11.

**Note:** Register Indirect with Register Offset Addressing mode is available only for W9 (in X space) and W11 (in Y space).

In summary, the following addressing modes are supported by the MAC class of instructions:

- Register Indirect
- Register Indirect Post-Modified by 2
- Register Indirect Post-Modified by 4
- Register Indirect Post-Modified by 6
- Register Indirect with Register Offset (Indexed)

### 4.3.5 OTHER INSTRUCTIONS

In addition to the addressing modes outlined previously, some instructions use literal constants of various sizes. For example, BRA (branch) instructions use 16-bit signed literals to specify the branch destination directly, whereas the DISI instruction uses a 14-bit unsigned literal field. In some instructions, such as ADD Acc, the source of an operand or result is implied by the opcode itself. Certain operations, such as NOP, do not have any operands.

## 4.4 Modulo Addressing

Modulo Addressing mode is a method of providing an automated means to support circular data buffers using hardware. The objective is to remove the need for software to perform data address boundary checks when executing tightly looped code, as is typical in many DSP algorithms.

Modulo Addressing can operate in either data or program space (since the data pointer mechanism is essentially the same for both). One circular buffer can be supported in each of the X (which also provides the pointers into program space) and Y data spaces. Modulo Addressing can operate on any W register pointer. However, it is not advisable to use W14 or W15 for Modulo Addressing since these two registers are used as the Stack Frame Pointer and Stack Pointer, respectively.

In general, any particular circular buffer can be configured to operate in only one direction as there are certain restrictions on the buffer start address (for incrementing buffers), or end address (for decrementing buffers), based upon the direction of the circular buffer.

The only exception to the usage restrictions is for buffers that have a power-of-two length. As these buffers satisfy the start and end address criteria, they can operate in a bidirectional mode (that is, address boundary checks are performed on both the lower and upper address boundaries).

### 4.4.1 START AND END ADDRESS

The Modulo Addressing scheme requires that a starting and ending address be specified and loaded into the 16-bit Modulo Buffer Address registers: XMODSRT, XMODEND, YMODSRT, and YMODEND (see Table 4-1).

| **Note:** | Y space Modulo Addressing EA calculations assume word-sized data (LSb of every EA is always clear). |
|---|---|

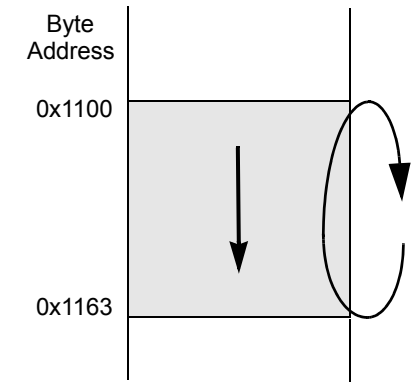
The length of a circular buffer is not directly specified. It is determined by the difference between the corresponding start and end addresses. The maximum possible length of the circular buffer is 32K words (64 Kbytes).

### 4.4.2 W ADDRESS REGISTER SELECTION

The Modulo and Bit-Reversed Addressing Control register, MODCON<15:0>, contains enable flags as well as a W register field to specify the W Address registers. The XWM and YWM fields select the registers that will operate with Modulo Addressing:

- If XWM = 15, X RAGU and X WAGU Modulo Addressing is disabled.
- If YWM = 15, Y AGU Modulo Addressing is disabled.

**FIGURE 4-5: MODULO ADDRESSING OPERATION EXAMPLE**




```
MOV     #0x1100, W0
MOV     W0, XMODSRT     ;set modulo start address
MOV     #0x1163, W0
MOV     W0, MODEND      ;set modulo end address
MOV     #0x8001, W0
MOV     W0, MODCON      ;enable W1, X AGU for modulo

MOV     #0x0000, W0     ;W0 holds buffer fill value

MOV     #0x1110, W1     ;point W1 to buffer

DO      AGAIN, #0x31    ;fill the 50 buffer locations
MOV     W0, [W1++]      ;fill the next location
AGAIN:  INC  W0, W0     ;increment the fill value
```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#### 4.4.3 MODULO ADDRESSING APPLICABILITY

Modulo Addressing can be applied to the Effective Address (EA) calculation associated with any W register. Address boundaries check for addresses equal to:

- The upper boundary addresses for incrementing buffers
- The lower boundary addresses for decrementing buffers

It is important to realize that the address boundaries check for addresses less than or greater than the upper (for incrementing buffers) and lower (for decrementing buffers) boundary addresses (not just equal to). Address changes can, therefore, jump beyond boundaries and still be adjusted correctly.

| | |
|---|---|
| **Note:** | The modulo corrected effective address is written back to the register only when Pre-Modify or Post-Modify Addressing mode is used to compute the effective address. When an address offset (such as [W7 + W2]) is used, Modulo Address correction is performed, but the contents of the register remain unchanged. |

### 4.5 Bit-Reversed Addressing

Bit-Reversed Addressing mode is intended to simplify data reordering for radix-2 FFT algorithms. It is supported by the X AGU for data writes only.

The modifier, which can be a constant value or register contents, is regarded as having its bit order reversed. The address source and destination are kept in normal order. Thus, the only operand requiring reversal is the modifier.

#### 4.5.1 BIT-REVERSED ADDRESSING IMPLEMENTATION

Bit-Reversed Addressing mode is enabled in any of these situations:

- BWM bits (W register selection) in the MODCON register are any value other than ‘15’ (the stack cannot be accessed using Bit-Reversed Addressing)
- The BREN bit is set in the XBREV register
- The addressing mode used is Register Indirect with Pre-Increment or Post-Increment

If the length of a bit-reversed buffer is $M = 2^N$ bytes, the last ‘N’ bits of the data buffer start address must be zeros.

XB<14:0> is the Bit-Reversed Address modifier, or ‘pivot point,’ which is typically a constant. In the case of an FFT computation, its value is equal to half of the FFT data buffer size.

| | |
|---|---|
| **Note:** | All bit-reversed EA calculations assume word-sized data (LSb of every EA is always clear). The XB value is scaled accordingly to generate compatible (byte) addresses. |

When enabled, Bit-Reversed Addressing is executed only for Register Indirect with Pre-Increment or Post-Increment Addressing, and word-sized data writes. It will not function for any other addressing mode or for byte-sized data, and normal addresses are generated instead. When Bit-Reversed Addressing is active, the W Address Pointer is always added to the address modifier (XB), and the offset associated with the Register Indirect Addressing mode is ignored. In addition, as word-sized data is a requirement, the LSb of the EA is ignored (and always clear).

| | |
|---|---|
| **Note:** | Modulo Addressing and Bit-Reversed Addressing should not be enabled together. If an application attempts to do so, Bit-Reversed Addressing will assume priority, when active, for the X WAGU, and X WAGU, Modulo Addressing will be disabled. However, Modulo Addressing will continue to function in the X RAGU. |

If Bit-Reversed Addressing has already been enabled by setting the BREN (XBREV<15>) bit, a write to the XBREV register should not be immediately followed by an indirect read operation using the W register that has been designated as the bit-reversed pointer.

**FIGURE 4-6: BIT-REVERSED ADDRESS EXAMPLE**

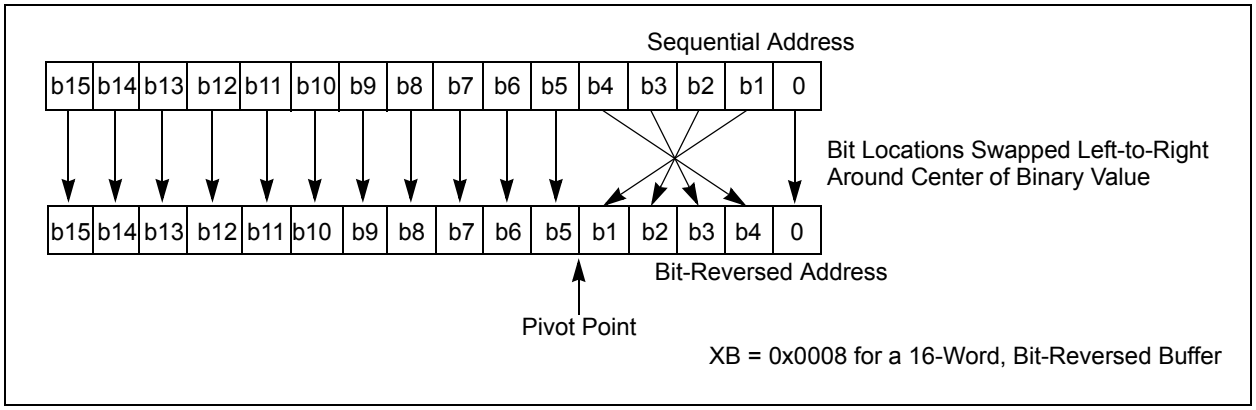


**TABLE 4-27: BIT-REVERSED ADDRESS SEQUENCE (16-ENTRY)**

| Normal Address | | | | | Bit-Reversed Address | | | | |
|---|---|---|---|---|---|---|---|---|---|
| **A3** | **A2** | **A1** | **A0** | **Decimal** | **A3** | **A2** | **A1** | **A0** | **Decimal** |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 8 |
| 0 | 0 | 1 | 0 | 2 | 0 | 1 | 0 | 0 | 4 |
| 0 | 0 | 1 | 1 | 3 | 1 | 1 | 0 | 0 | 12 |
| 0 | 1 | 0 | 0 | 4 | 0 | 0 | 1 | 0 | 2 |
| 0 | 1 | 0 | 1 | 5 | 1 | 0 | 1 | 0 | 10 |
| 0 | 1 | 1 | 0 | 6 | 0 | 1 | 1 | 0 | 6 |
| 0 | 1 | 1 | 1 | 7 | 1 | 1 | 1 | 0 | 14 |
| 1 | 0 | 0 | 0 | 8 | 0 | 0 | 0 | 1 | 1 |
| 1 | 0 | 0 | 1 | 9 | 1 | 0 | 0 | 1 | 9 |
| 1 | 0 | 1 | 0 | 10 | 0 | 1 | 0 | 1 | 5 |
| 1 | 0 | 1 | 1 | 11 | 1 | 1 | 0 | 1 | 13 |
| 1 | 1 | 0 | 0 | 12 | 0 | 0 | 1 | 1 | 3 |
| 1 | 1 | 0 | 1 | 13 | 1 | 0 | 1 | 1 | 11 |
| 1 | 1 | 1 | 0 | 14 | 0 | 1 | 1 | 1 | 7 |
| 1 | 1 | 1 | 1 | 15 | 1 | 1 | 1 | 1 | 15 |


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## 4.6 Interfacing Program and Data Memory Spaces

The dsPIC33FJ12MC201/202 architecture uses a 24-bit-wide program space and a 16-bit-wide data space. The architecture is also a modified Harvard scheme, meaning that data can also be present in the program space. To use this data successfully, it must be accessed in a way that preserves the alignment of information in both spaces.

Aside from normal execution, the dsPIC33FJ12MC201/202 architecture provides two methods by which program space can be accessed during operation:

- Using table instructions to access individual bytes, or words, anywhere in the program space
- Remapping a portion of the program space into the data space (Program Space Visibility)

Table instructions allow an application to read or write to small areas of the program memory. This capability makes the method ideal for accessing data tables that need to be updated periodically. It also allows access to all bytes of the program word. The remapping method allows an application to access a large block of data on a read-only basis, which is ideal for lookups from a large table of static data. The application can only access the lsw of the program word.

### 4.6.1 ADDRESSING PROGRAM SPACE

Since the address ranges for the data and program spaces are 16 and 24 bits, respectively, a method is needed to create a 23-bit or 24-bit program address from 16-bit data registers. The solution depends on the interface method to be used.

For table operations, the 8-bit Table Page register (TBLPAG) is used to define a 32K word region within the program space. This is concatenated with a 16-bit EA to arrive at a full 24-bit program space address. In this format, the MSb of TBLPAG is used to determine if the operation occurs in the user memory (TBLPAG<7> = 0) or the configuration memory (TBLPAG<7> = 1).

For remapping operations, the 8-bit Program Space Visibility register (PSVPAG) is used to define a 16K word page in the program space. When the MSb of the EA is '1', PSVPAG is concatenated with the lower 15 bits of the EA to form a 23-bit program space address. Unlike table operations, this limits remapping operations strictly to the user memory area.

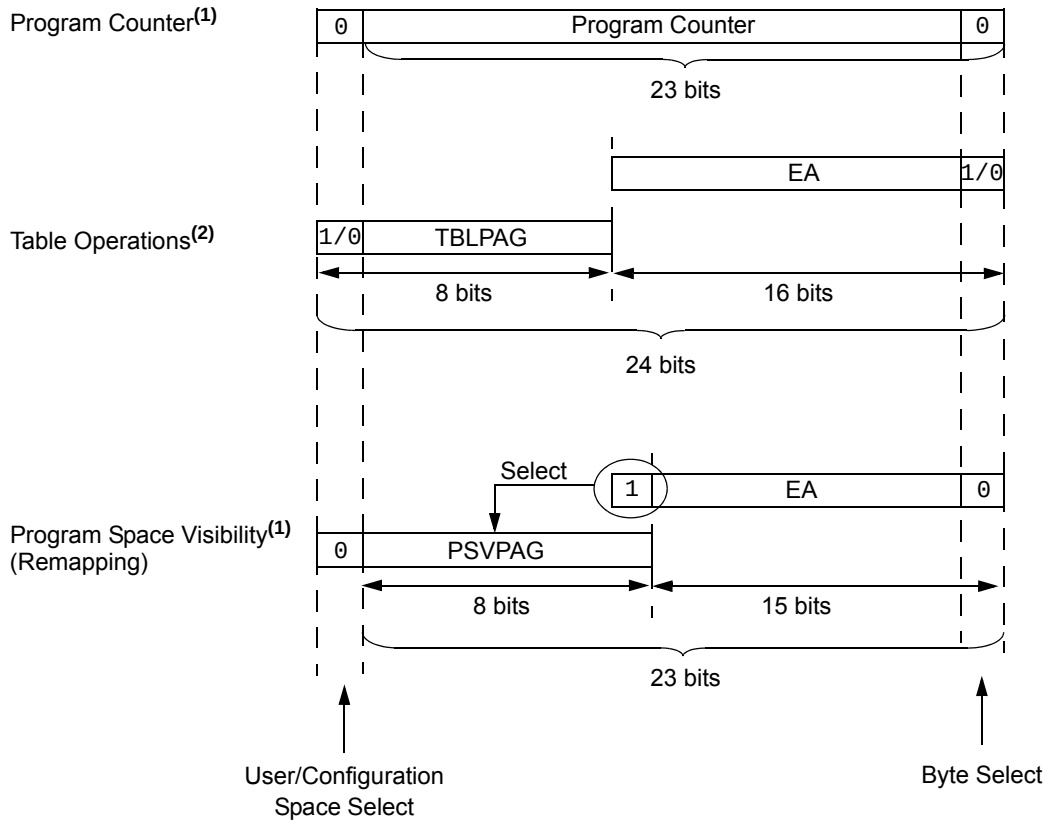
Table 4-28 and Figure 4-7 show how the program EA is created for table operations and remapping accesses from the data EA.

**TABLE 4-28: PROGRAM SPACE ADDRESS CONSTRUCTION**

| Access Type | Access Space | Program Space Address | | | | |
|---|---|---|---|---|---|---|
| | | <23> | <22:16> | <15> | <14:1> | <0> |
| Instruction Access (Code Execution) | User | 0 | PC<22:1> | | | 0 |
| | | 0xx xxxx xxxx xxxx xxxx xxx0 | | | | |
| TBLRD/TBLWT (Byte/Word Read/Write) | User | TBLPAG<7:0> | | Data EA<15:0> | | |
| | | 0xxx xxxx | | xxxx xxxx xxxx xxxx | | |
| | Configuration | TBLPAG<7:0> | | Data EA<15:0> | | |
| | | 1xxx xxxx | | xxxx xxxx xxxx xxxx | | |
| Program Space Visibility (Block Remap/Read) | User | 0 | PSVPAG<7:0> | | Data EA<14:0>(1) | |
| | | 0 | xxxx xxxx | | xxx xxxx xxxx xxxx | |

**Note 1:** Data EA<15> is always '1' in this case, but is not used in calculating the program space address. Bit 15 of the address is PSVPAG<0>.

**FIGURE 4-7: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION**




**Note 1:** The Least Significant bit of program space addresses is always fixed as '0' to maintain word alignment of data in the program and data spaces.

**2:** Table operations are not required to be word aligned. Table read operations are permitted in the configuration memory space.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### 4.6.2 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The TBLRDL and TBLWTL instructions offer a direct method of reading or writing the lower word of any address within the program space without going through data space. The TBLRDH and TBLWTH instructions are the only method to read or write the upper 8 bits of a program space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to data space addresses. Program memory can thus be regarded as two 16-bit-wide word address spaces, residing side by side, each with the same address range. TBLRDL and TBLWTL access the space that contains the least significant data word. TBLRDH and TBLWTH access the space that contains the upper data byte.

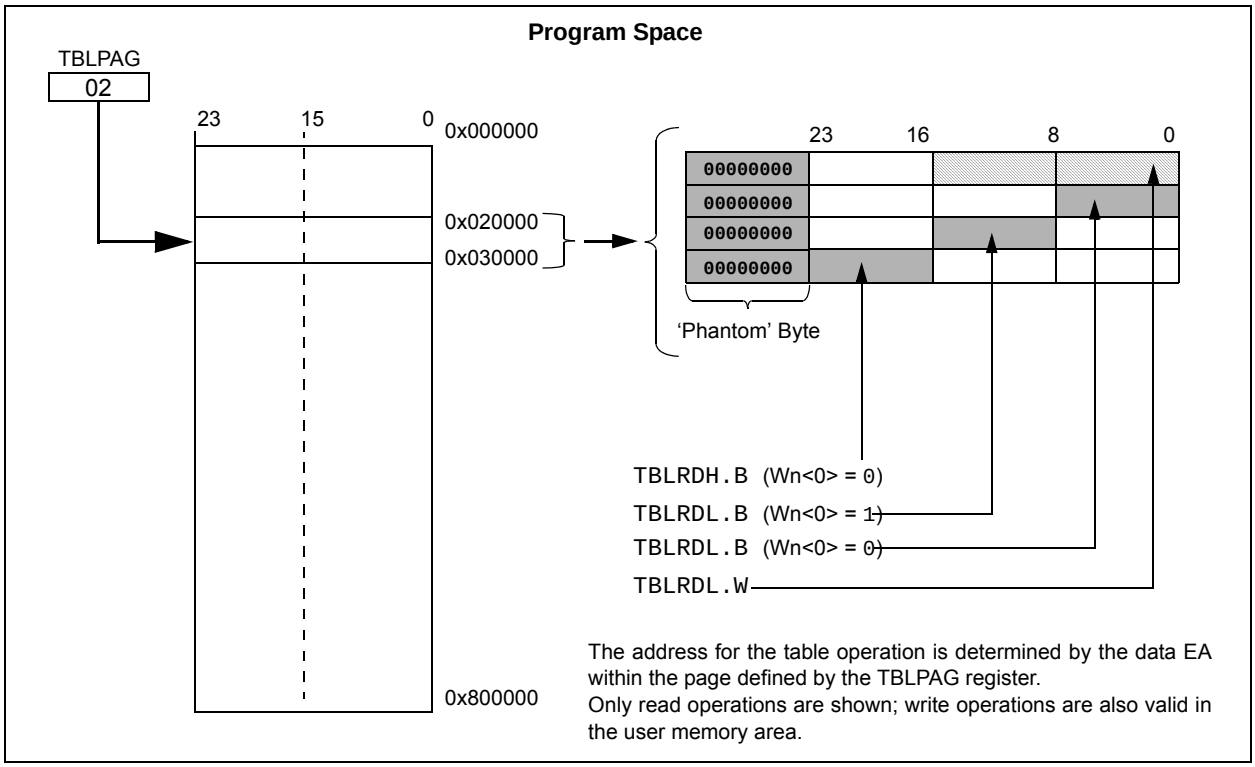
Two table instructions are provided to move byte or word-sized (16-bit) data to and from program space. Both function as either byte or word operations.

- TBLRDL (Table Read Low):
  - In Word mode, this instruction maps the lower word of the program space location (P<15:0>) to a data address (D<15:0>).
  - In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when Byte Select is '1'; the lower byte is selected when it is '0'.
- TBLRDH (Table Read High):
  - In Word mode, this instruction maps the entire upper word of a program address (P<23:16>) to a data address. Note that D<15:8>, the 'phantom byte', will always be '0'.
  - In Byte mode, this instruction maps the upper or lower byte of the program word to D<7:0> of the data address, in the TBLRDL instruction. The data is always '0' when the upper 'phantom' byte is selected (Byte Select = 1).

In a similar fashion, two table instructions, TBLWTH and TBLWTL, are used to write individual bytes or words to a program space address. The details of their operation are explained in **Section 5.0 "Flash Program Memory"**.

For all table operations, the area of program memory space to be accessed is determined by the Table Page register (TBLPAG). TBLPAG covers the entire program memory space of the device, including user and configuration spaces. When TBLPAG<7> = 0, the table page is located in the user memory space. When TBLPAG<7> = 1, the page is located in configuration space.

**FIGURE 4-8: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS**



### 4.6.3 READING DATA FROM PROGRAM MEMORY USING PROGRAM SPACE VISIBILITY

The upper 32 Kbytes of data space may optionally be mapped into any 16K word page of the program space. This option provides transparent access to stored constant data from the data space without the need to use special instructions (such as TBLRDL and TBLRDH).

Program space access through the data space occurs if the MSb of the data space EA is '1' and program space visibility is enabled by setting the PSV bit in the Core Control register (CORCON<2>). The location of the program memory space to be mapped into the data space is determined by the Program Space Visibility Page register (PSVPAG). This 8-bit register defines any one of 256 possible pages of 16K words in program space. In effect, PSVPAG functions as the upper 8 bits of the program memory address, with the 15 bits of the EA functioning as the lower bits. By incrementing the PC by 2 for each program memory word, the lower 15 bits of data space addresses directly map to the lower 15 bits in the corresponding program space addresses.

Data reads to this area add a cycle to the instruction being executed, since two program memory fetches are required.

Although each data space address 0x8000 and higher maps directly into a corresponding program memory address (see Figure 4-9), only the lower 16 bits of the 24-bit program word are used to contain the data. The upper 8 bits of any program space location used as data should be programmed with '1111 1111' or '0000 0000' to force a NOP. This prevents possible issues should the area of code ever be accidentally executed.

| **Note:** | PSV access is temporarily disabled during table reads/writes. |
|---|---|

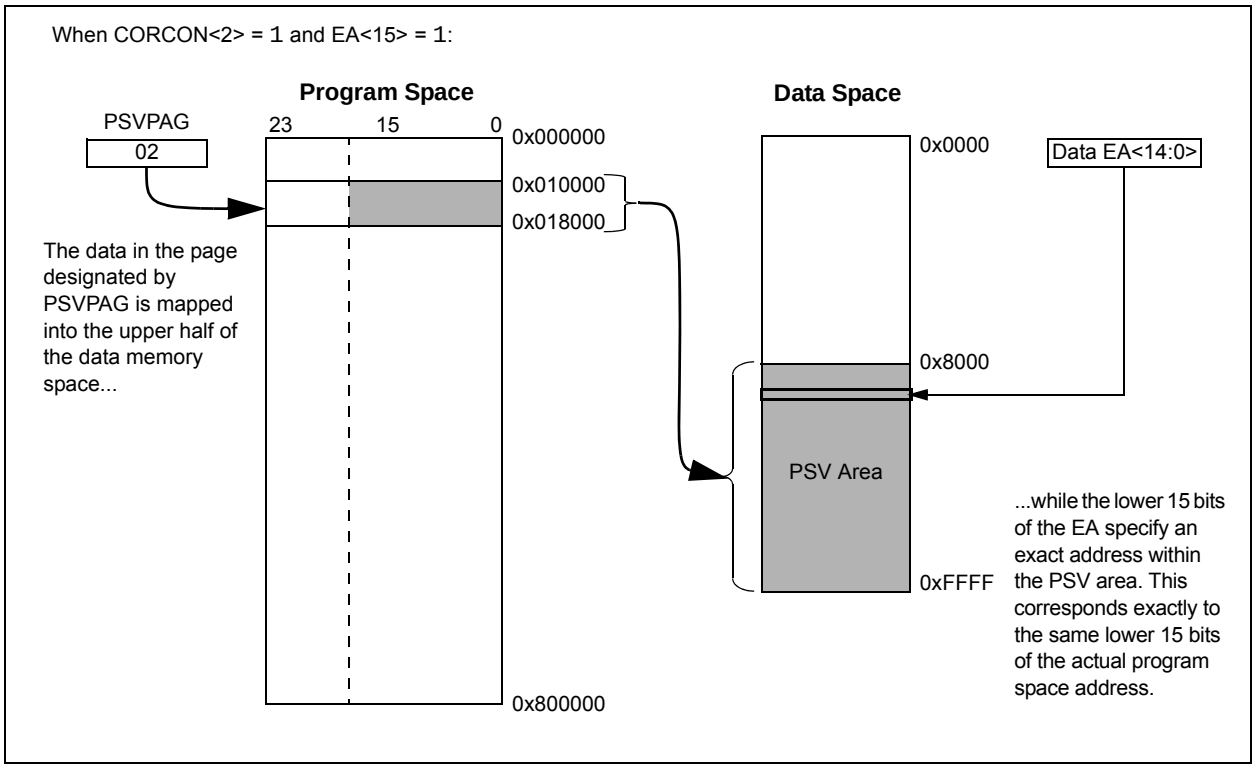
For operations that use PSV and are executed outside a REPEAT loop, the MOV and MOV.D instructions require one instruction cycle in addition to the specified execution time. All other instructions require two instruction cycles in addition to the specified execution time.

For operations that use PSV, and are executed inside a REPEAT loop, these instances require two instruction cycles in addition to the specified execution time of the instruction:

- Execution in the first iteration
- Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the REPEAT loop will allow the instruction using PSV to access data, to execute in a single cycle.

**FIGURE 4-9: PROGRAM SPACE VISIBILITY OPERATION**





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## 5.0 FLASH PROGRAM MEMORY

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 5. "Flash Programming"** (DS70191) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 devices contain internal Flash program memory for storing and executing application code. The memory is readable, writable, and erasable during normal operation over the entire VDD range.

Flash memory can be programmed in two ways:

- In-Circuit Serial Programming™ (ICSP™) programming capability
- Run-Time Self-Programming (RTSP)

ICSP allows a dsPIC33FJ12MC201/202 device to be serially programmed while in the end application circuit. This is done with two lines for programming clock and programming data (one of the alternate programming pin pairs: PGECx/PGEDx), and three other lines for power (VDD), ground (VSS) and Master Clear (MCLR). This allows users to manufacture boards with unprogrammed devices, and then program the digital signal controller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

RTSP is accomplished using TBLRD (table read) and TBLWT (table write) instructions. With RTSP, the user application can write program memory data either in blocks or 'rows' of 64 instructions (192 bytes) or a single program memory word, and erase program memory in blocks or 'pages' of 512 instructions (1536 bytes).

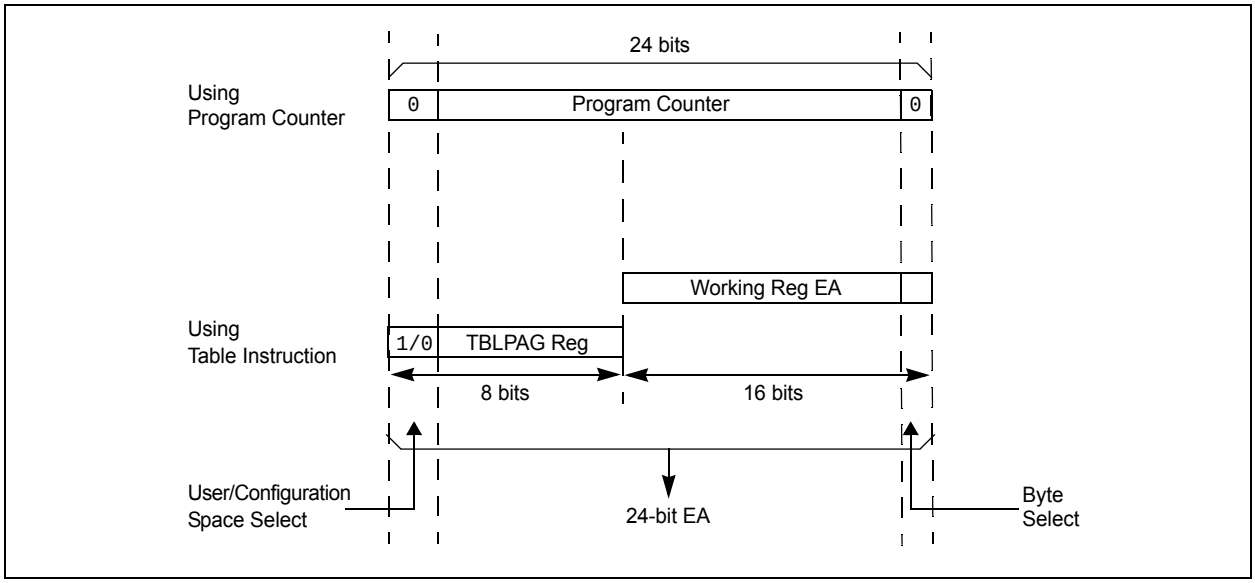
### 5.1 Table Instructions and Flash Programming

Regardless of the method used, all programming of Flash memory is done with the table-read and table-write instructions. These allow direct read and write access to the program memory space from the data memory while the device is in normal operating mode. The 24-bit target address in the program memory is formed using bits <7:0> of the TBLPAG register and the Effective Address (EA) from a W register specified in the table instruction, as shown in Figure 5-1.

The TBLRDL and the TBLWTL instructions are used to read or write to bits <15:0> of program memory. TBLRDL and TBLWTL can access program memory in both Word and Byte modes.

The TBLRDH and TBLWTH instructions are used to read or write to bits <23:16> of program memory. TBLRDH and TBLWTH can also access program memory in Word or Byte mode.

**FIGURE 5-1: ADDRESSING FOR TABLE REGISTERS**



## 5.2 RTSP Operation

The dsPIC33FJ12MC201/202 Flash program memory array is organized into rows of 64 instructions or 192 bytes. RTSP allows the user application to erase a page of memory, which consists of eight rows (512 instructions); and to program one row or one word. Table 24-12 shows typical erase and programming times. The 8-row erase pages and single row write rows are edge-aligned from the beginning of program memory, on boundaries of 1536 bytes and 192 bytes, respectively.

The program memory implements holding buffers that can contain 64 instructions of programming data. Prior to the actual programming operation, the write data must be loaded into the buffers sequentially. The instruction words loaded must always be from a group of 64 boundary.

The basic sequence for RTSP programming is to set up a Table Pointer, then do a series of TBLWT instructions to load the buffers. Programming is performed by setting the control bits in the NVMCON register. A total of 64 TBLWTL and TBLWTH instructions are required to load the instructions.

All of the table write operations are single-word writes (two instruction cycles) because only the buffers are written. A programming cycle is required for programming each row.

## 5.3 Programming Operations

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. The processor stalls (waits) until the operation is finished.

The programming time depends on the FRC accuracy (see Table 24-18) and the value of the FRC Oscillator Tuning register (see Register 8-4). Use the following formula to calculate the minimum and maximum values for the Row Write Time, Page Erase Time, and Word Write Cycle Time parameters (see Table 24-12).

**EQUATION 5-1: PROGRAMMING TIME**

$$\frac{T}{7.37\ MHz \times (FRC\ Accuracy)\% \times (FRC\ Tuning)\%}$$

For example, if the device is operating at +125°C, the FRC accuracy will be ±5%. If the TUN<5:0> bits (see Register 8-4) are set to 'b111111, the minimum row write time is equal to Equation 5-2.

**EQUATION 5-2: MINIMUM ROW WRITE TIME**

$$T_{RW} = \frac{11064\ Cycles}{7.37\ MHz \times (1 + 0.05) \times (1 - 0.00375)} = 1.435ms$$

The maximum row write time is equal to Equation 5-3.

**EQUATION 5-3: MAXIMUM ROW WRITE TIME**

$$T_{RW} = \frac{11064\ Cycles}{7.37\ MHz \times (1 - 0.05) \times (1 - 0.00375)} = 1.586ms$$

Setting the WR bit (NVMCON<15>) starts the operation, and the WR bit is automatically cleared when the operation is finished.

## 5.4 Control Registers

Two SFRs are used to read and write the program Flash memory: NVMCON and NVMKEY.

The NVMCON register (Register 5-1) controls which blocks are to be erased, which memory type is to be programmed, and the start of the programming cycle.

NVMKEY is a write-only register that is used for write protection. To start a programming or erase sequence, the user application must consecutively write 0x55 and 0xAA to the NVMKEY register. Refer to **Section 5.3 "Programming Operations"** for further details.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**REGISTER 5-1: NVMCON: FLASH MEMORY CONTROL REGISTER**

| R/SO-0(1) | R/W-0(1) | R/W-0(1) | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| WR | WREN | WRERR | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-0(1) | U-0 | U-0 | R/W-0(1) | R/W-0(1) | R/W-0(1) | R/W-0(1) |
|---|---|---|---|---|---|---|---|
| — | ERASE | — | — | NVMOP<3:0>(2) | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | SO = Settable only bit | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **WR:** Write Control bit
- 1 = Initiates a Flash memory program or erase operation. The operation is self-timed and the bit is cleared by hardware once operation is complete
- 0 = Program or erase operation is complete and inactive

bit 14 **WREN:** Write Enable bit
- 1 = Enable Flash program/erase operations
- 0 = Inhibit Flash program/erase operations

bit 13 **WRERR:** Write Sequence Error Flag bit
- 1 = An improper program or erase sequence attempt or termination has occurred (bit is set automatically on any set attempt of the WR bit)
- 0 = The program or erase operation completed normally

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **ERASE:** Erase/Program Enable bit
- 1 = Perform the erase operation specified by NVMOP<3:0> on the next WR command
- 0 = Perform the program operation specified by NVMOP<3:0> on the next WR command

bit 5-4 **Unimplemented:** Read as '0'

bit 3-0 **NVMOP<3:0>:** NVM Operation Select bits(2)

If ERASE = 1:
- 1111 = Memory bulk erase operation
- 1101 = Erase General Segment
- 1100 = Erase Secure Segment
- 0011 = No operation
- 0010 = Memory page erase operation
- 0001 = No operation
- 0000 = Erase a single Configuration register byte

If ERASE = 0:
- 1111 = No operation
- 1101 = No operation
- 1100 = No operation
- 0011 = Memory word program operation
- 0010 = No operation
- 0001 = Memory row program operation
- 0000 = Program a single Configuration register byte

**Note 1:** These bits can only be reset on POR.

**2:** All other combinations of NVMOP<3:0> are unimplemented.

**REGISTER 5-2: NVMKEY: NONVOLATILE MEMORY KEY REGISTER**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| W-0 | W-0 | W-0 | W-0 | W-0 | W-0 | W-0 | W-0 |
|---|---|---|---|---|---|---|---|
| NVMKEY<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | SO = Settable only bit | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-8 **Unimplemented:** Read as ‘0’

bit 7-0 **NVMKEY<7:0>:** Key Register (write-only) bits


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### 5.4.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

Programmers can program one row of program Flash memory at a time. To do this, it is necessary to erase the 8-row erase page that contains the desired row. The general process is:

1. Read eight rows of program memory (512 instructions) and store in data RAM.
2. Update the program data in RAM with the desired new data.
3. Erase the block (see Example 5-1):
   a) Set the NVMOP bits (NVMCON<3:0>) to '0010' to configure for block erase. Set the ERASE (NVMCON<6>) and WREN (NVMCON<14>) bits.
   b) Write the starting address of the page to be erased into the TBLPAG and W registers.
   c) Write 0x55 to NVMKEY.
   d) Write 0xAA to NVMKEY.
   e) Set the WR bit (NVMCON<15>). The erase cycle begins and the CPU stalls for the duration of the erase cycle. When the erase is done, the WR bit is cleared automatically.
4. Write the first 64 instructions from data RAM into the program memory buffers (see Example 5-2).
5. Write the program block to Flash memory:
   a) Set the NVMOP bits to '0001' to configure for row programming. Clear the ERASE bit and set the WREN bit.
   b) Write 0x55 to NVMKEY.
   c) Write 0xAA to NVMKEY.
   d) Set the WR bit. The programming cycle begins and the CPU stalls for the duration of the write cycle. When the write to Flash memory is done, the WR bit is cleared automatically.
6. Repeat steps 4 and 5, using the next available 64 instructions from the block in data RAM by incrementing the value in TBLPAG, until all 512 instructions are written back to Flash memory.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user application must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPs, as shown in Example 5-3.

**EXAMPLE 5-1: ERASING A PROGRAM MEMORY PAGE**

```
; Set up NVMCON for block erase operation
        MOV     #0x4042, W0                 ;
        MOV     W0, NVMCON                  ; Initialize NVMCON
; Init pointer to row to be ERASED
        MOV     #tblpage(PROG_ADDR), W0     ;
        MOV     W0, TBLPAG                  ; Initialize PM Page Boundary SFR
        MOV     #tbloffset(PROG_ADDR), W0   ; Initialize in-page EA[15:0] pointer
        TBLWTL  W0, [W0]                    ; Set base address of erase block
        DISI    #5                          ; Block all interrupts with priority <7
                                            ; for next 5 instructions
        MOV     #0x55, W0
        MOV     W0, NVMKEY                  ; Write the 55 key
        MOV     #0xAA, W1                   ;
        MOV     W1, NVMKEY                  ; Write the AA key
        BSET    NVMCON, #WR                 ; Start the erase sequence
        NOP                                 ; Insert two NOPs after the erase
        NOP                                 ; command is asserted
```

**EXAMPLE 5-2: LOADING THE WRITE BUFFERS**

```
; Set up NVMCON for row programming operations
       MOV     #0x4001, W0               ;
       MOV     W0, NVMCON                ; Initialize NVMCON
; Set up a pointer to the first program memory location to be written
; program memory selected, and writes enabled
       MOV     #0x0000, W0               ;
       MOV     W0, TBLPAG                ; Initialize PM Page Boundary SFR
       MOV     #0x6000, W0               ; An example program memory address
; Perform the TBLWT instructions to write the latches
; 0th_program_word
       MOV     #LOW_WORD_0, W2           ;
       MOV     #HIGH_BYTE_0, W3          ;
       TBLWTL  W2, [W0]                  ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                ; Write PM high byte into program latch
; 1st_program_word
       MOV     #LOW_WORD_1, W2           ;
       MOV     #HIGH_BYTE_1, W3          ;
       TBLWTL  W2, [W0]                  ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                ; Write PM high byte into program latch
;  2nd_program_word
       MOV     #LOW_WORD_2, W2           ;
       MOV     #HIGH_BYTE_2, W3          ;
       TBLWTL  W2, [W0]                  ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                ; Write PM high byte into program latch
       •
       •
       •
; 63rd_program_word
       MOV     #LOW_WORD_31, W2          ;
       MOV     #HIGH_BYTE_31, W3         ;
       TBLWTL  W2, [W0]                  ; Write PM low word into program latch
       TBLWTH  W3, [W0++]                ; Write PM high byte into program latch
```

**EXAMPLE 5-3: INITIATING A PROGRAMMING SEQUENCE**

```
       DISI    #5                        ; Block all interrupts with priority <7
                                         ; for next 5 instructions
       MOV     #0x55, W0
       MOV     W0, NVMKEY                ; Write the 55 key
       MOV     #0xAA, W1                 ;
       MOV     W1, NVMKEY                ; Write the AA key
       BSET    NVMCON, #WR               ; Start the erase sequence
       NOP                               ; Insert two NOPs after the
       NOP                               ; erase command is asserted
```


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## 6.0 RESETS

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 8. "Reset"** (DS70192) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Reset module combines all Reset sources and controls the device Master Reset Signal, $\overline{SYSRST}$. The following is a list of device Reset sources:

- POR: Power-on Reset
- BOR: Brown-out Reset
- $\overline{MCLR}$: Master Clear Pin Reset
- SWR: RESET Instruction
- WDTO: Watchdog Timer Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- IOPUWR: Illegal Condition Device Reset
  - Illegal Opcode Reset
  - Uninitialized W Register Reset
  - Security Reset

A simplified block diagram of the Reset module is shown in Figure 6-1.

Any active source of Reset will make the $\overline{SYSRST}$ signal active. On system Reset, some of the registers associated with the CPU and peripherals are forced to a known Reset state, and some are unaffected.

**Note:** Refer to the specific peripheral section or **Section 3.0 "CPU"** of this manual for register Reset states.

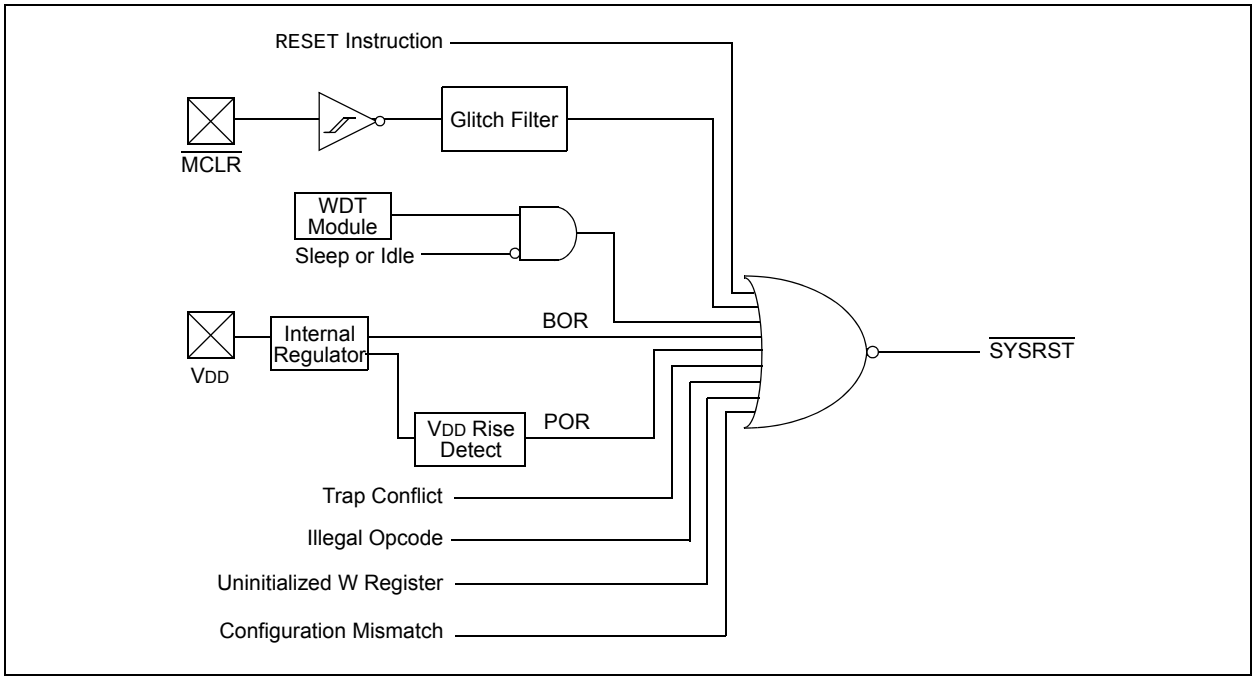
All types of device Reset set a corresponding status bit in the RCON register to indicate the type of Reset (see Register 6-1).

All bits that are set, with the exception of the POR bit (RCON<0>), are cleared during a POR event. The user application can set or clear any bit at any time during code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software does not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this data sheet.

**Note:** The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset is meaningful.

**FIGURE 6-1: RESET SYSTEM BLOCK DIAGRAM**



**REGISTER 6-1: RCON: RESET CONTROL REGISTER(1)**

| R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| TRAPR | IOPUWR | — | — | — | — | CM | VREGS |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| EXTR | SWR | SWDTEN(2) | WDTO | SLEEP | IDLE | BOR | POR |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **TRAPR:** Trap Reset Flag bit
1 = A Trap Conflict Reset has occurred
0 = A Trap Conflict Reset has not occurred

bit 14 **IOPUWR:** Illegal Opcode or Uninitialized W Access Reset Flag bit
1 = An illegal opcode detection, an illegal address mode or uninitialized W register used as an Address Pointer caused a Reset
0 = An illegal opcode or uninitialized W Reset has not occurred

bit 13-10 **Unimplemented:** Read as '0'

bit 9 **CM:** Configuration Mismatch Flag bit
1 = A configuration mismatch Reset has occurred
0 = A configuration mismatch Reset has not occurred

bit 8 **VREGS:** Voltage Regulator Standby During Sleep bit
1 = Voltage regulator is active during Sleep
0 = Voltage regulator goes into Standby mode during Sleep

bit 7 **EXTR:** External Reset ($\overline{MCLR}$) Pin bit
1 = A Master Clear (pin) Reset has occurred
0 = A Master Clear (pin) Reset has not occurred

bit 6 **SWR:** Software Reset (Instruction) Flag bit
1 = A RESET instruction has been executed
0 = A RESET instruction has not been executed

bit 5 **SWDTEN:** Software Enable/Disable of WDT bit(2)
1 = WDT is enabled
0 = WDT is disabled

bit 4 **WDTO:** Watchdog Timer Time-out Flag bit
1 = WDT time-out has occurred
0 = WDT time-out has not occurred

bit 3 **SLEEP:** Wake-up from Sleep Flag bit
1 = Device has been in Sleep mode
0 = Device has not been in Sleep mode

bit 2 **IDLE:** Wake-up from Idle Flag bit
1 = Device was in Idle mode
0 = Device was not in Idle mode

**Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

**2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.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**REGISTER 6-1: RCON: RESET CONTROL REGISTER(1) (CONTINUED)**

bit 1 **BOR:** Brown-out Reset Flag bit
1 = A Brown-out Reset has occurred
0 = A Brown-out Reset has not occurred

bit 0 **POR:** Power-on Reset Flag bit
1 = A Power-on Reset has occurred
0 = A Power-on Reset has not occurred

**Note 1:** All of the Reset status bits can be set or cleared in software. Setting one of these bits in software does not cause a device Reset.

**2:** If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.

## 6.1 System Reset

The dsPIC33FJ12MC201/202 family of devices have two types of Reset:

- Cold Reset
- Warm Reset

A cold Reset is the result of a POR or a BOR. On a cold Reset, the FNOSC configuration bits in the FOSC device configuration register selects the device clock source.

A warm Reset is the result of all other Reset sources, including the RESET instruction. On warm Reset, the device will continue to operate from the current clock source as indicated by the Current Oscillator Selection (COSC<2:0>) bits in the Oscillator Control (OSCCON<14:12>) register.

The device is kept in a Reset state until the system power supplies have stabilized at appropriate levels and the oscillator clock is ready. The sequence in which this occurs is detailed below and is shown in Figure 6-2.

**TABLE 6-1: OSCILLATOR DELAY**

| Oscillator Mode | Oscillator Startup Delay | Oscillator Startup Timer | PLL Lock Time | Total Delay |
|---|---|---|---|---|
| FRC, FRCDIV16, FRCDIVN | TOSCD | — | — | TOSCD |
| FRCPLL | TOSCD | — | TLOCK | TOSCD + TLOCK |
| XT | TOSCD | TOST | — | TOSCD + TOST |
| HS | TOSCD | TOST | — | TOSCD + TOST |
| EC | — | — | — | — |
| XTPLL | TOSCD | TOST | TLOCK | TOSCD + TOST + TLOCK |
| HSPLL | TOSCD | TOST | TLOCK | TOSCD + TOST + TLOCK |
| ECPLL | — | — | TLOCK | TLOCK |
| SOSC | TOSCD | TOST | — | TOSCD + TOST |
| LPRC | TOSCD | — | — | TOSCD |

**Note 1:** TOSCD = Oscillator Start-up Delay (1.1 μs max for FRC, 70 μs max for LPRC). Crystal Oscillator start-up times vary with crystal characteristics, load capacitance, etc.

**2:** TOST = Oscillator Start-up Timer Delay (1024 oscillator clock period). For example, TOST = 102.4 μs for a 10 MHz crystal and TOST = 32 ms for a 32 kHz crystal.

**3:** TLOCK = PLL lock time (1.5 ms nominal), if PLL is enabled.


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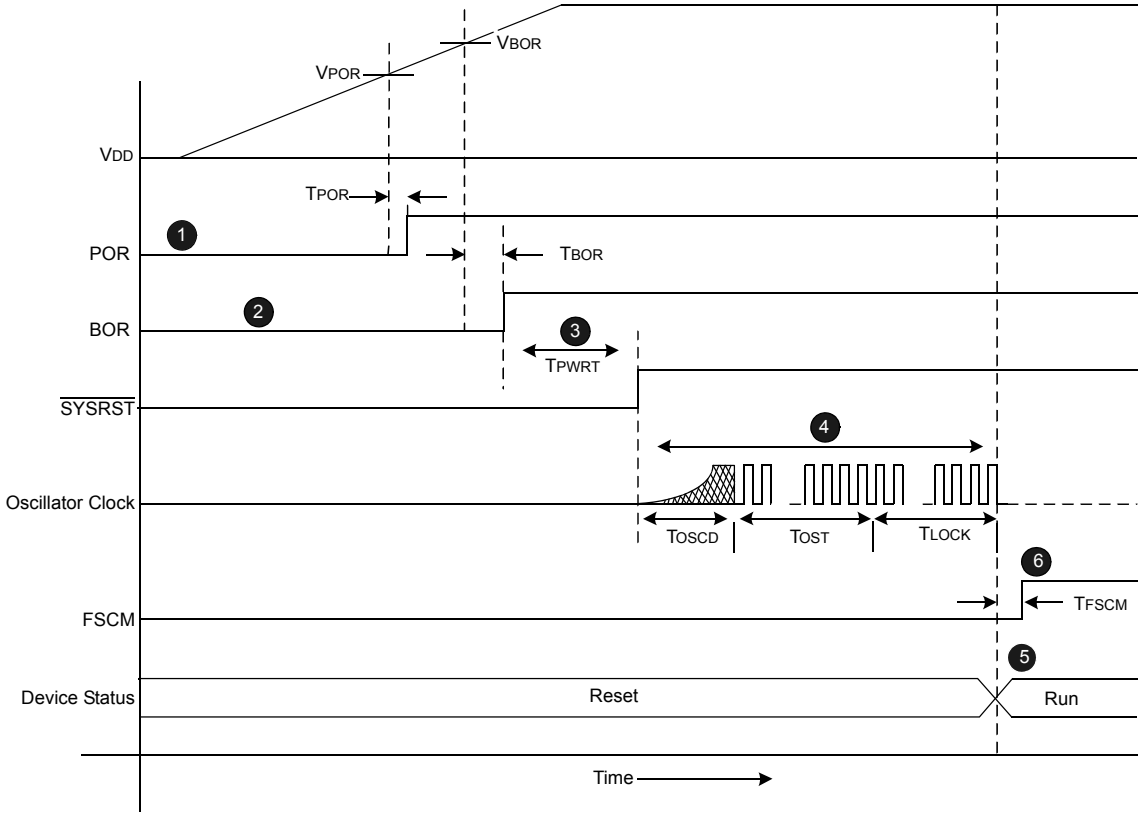
**FIGURE 6-2: SYSTEM RESET TIMING**




1. **POR:** A POR circuit holds the device in Reset when the power supply is turned on. The POR circuit is active until VDD crosses the VPOR threshold and the delay TPOR has elapsed.
2. **BOR:** The on-chip voltage regulator has a BOR circuit that keeps the device in Reset until VDD crosses the VBOR threshold and the delay TBOR has elapsed. The delay TBOR ensures the voltage regulator output becomes stable.
3. **PWRT Timer:** The programmable power-up timer continues to hold the processor in Reset for a specific period of time (TPWRT) after a BOR. The delay TPWRT ensures that the system power supplies have stabilized at the appropriate level for full-speed operation. After the delay TPWRT has elapsed, the SYSRST becomes inactive, which in turn enables the selected oscillator to start generating clock cycles.
4. **Oscillator Delay:** The total delay for the clock to be ready for various clock source selections are given in Table 6-1. Refer to **Section 8.0 "Oscillator Configuration"** for more information.
5. When the oscillator clock is ready, the processor begins execution from location 0x000000. The user application programs a GOTO instruction at the Reset address, which redirects program execution to the appropriate start-up routine.
6. The Fail-safe clock monitor (FSCM), if enabled, begins to monitor the system clock when the system clock is ready and the delay TFSCM elapsed.

**TABLE 6-2: OSCILLATOR PARAMETERS**

| Symbol | Parameter | Value |
|---|---|---|
| VPOR | POR threshold | 1.8V nominal |
| TPOR | POR extension time | 30 μs maximum |
| VBOR | BOR threshold | 2.5V nominal |
| TBOR | BOR extension time | 100 μs maximum |
| TPWRT | Programmable power-up time delay | 0-128 ms nominal |
| TFSCM | Fail-safe Clock Monitor Delay | 900 μs maximum |

**Note:** When the device exits the Reset condition (begins normal operation), the device operating parameters (voltage, frequency, temperature, etc.) must be within their operating ranges, otherwise the device may not function correctly. The user application must ensure that the delay between the time power is first applied, and the time SYSRST becomes inactive, is long enough to get all operating parameters within specification.

## 6.2 POR

A POR circuit ensures the device is reset from power-on. The POR circuit is active until VDD crosses the VPOR threshold and the delay TPOR has elapsed. The delay TPOR ensures the internal device bias circuits become stable.

The device supply voltage characteristics must meet the specified starting voltage and rise rate requirements to generate the POR. Refer to **Section 24.0 "Electrical Characteristics"** for details.

The POR status (POR) bit in the Reset Control (RCON<0>) register is set to indicate the Power-on Reset.

## 6.3 BOR and PWRT

The on-chip regulator has a BOR circuit that resets the device when the VDD is too low (VDD < VBOR) for proper device operation. The BOR circuit keeps the device in Reset until VDD crosses the VBOR threshold and the delay TBOR has elapsed. The delay TBOR ensures the voltage regulator output becomes stable.

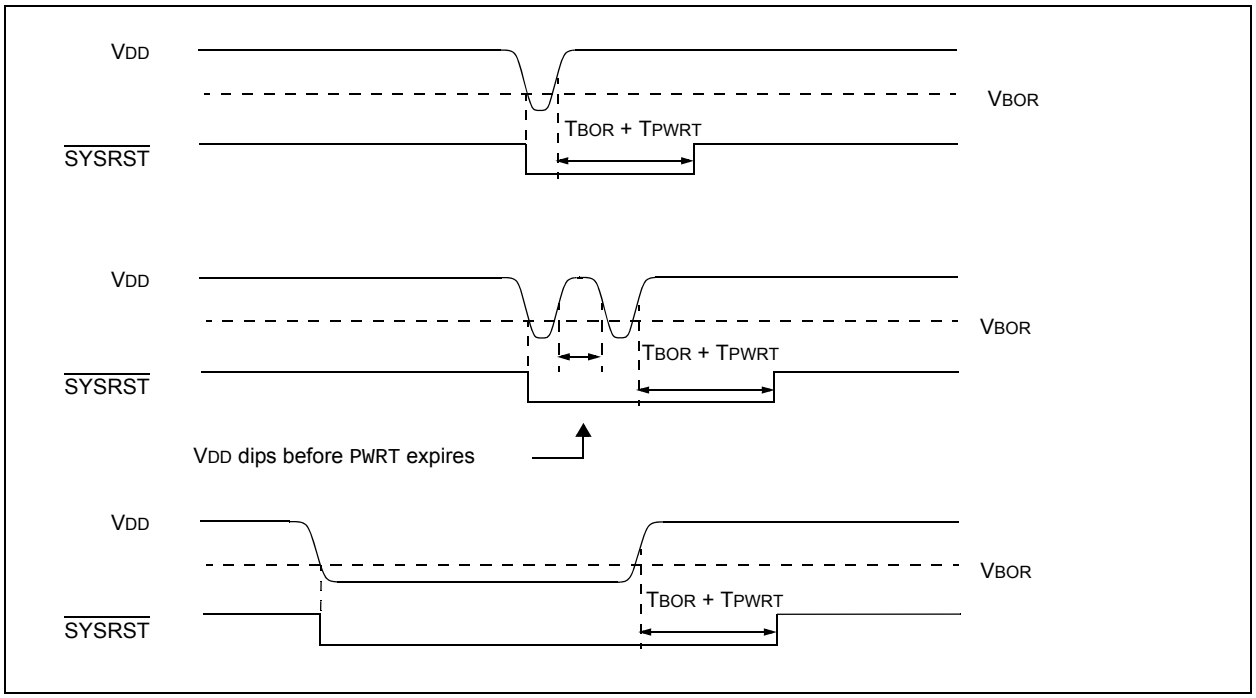
The BOR status (BOR) bit in the Reset Control (RCON<1>) register is set to indicate the Brown-out Reset.

The device will not run at full speed after a BOR as the VDD should rise to acceptable levels for full-speed operation. The PWRT provides power-up time delay (TPWRT) to ensure that the system power supplies have stabilized at the appropriate levels for full-speed operation before the SYSRST is released.

The power-up timer delay (TPWRT) is programmed by the Power-on Reset Timer Value Select (FPWRT<2:0>) bits in the POR Configuration (FPOR<2:0>) register, which provides eight settings (from 0 ms to 128 ms). Refer to **Section 21.0 "Special Features"** for further details.

Figure 6-3 shows the typical brown-out scenarios. The Reset delay (TBOR + TPWRT) is initiated each time VDD rises above the VBOR trip point.

**FIGURE 6-3: BROWN-OUT SITUATIONS**





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## 6.4 External Reset (EXTR)

The external Reset is generated by driving the MCLR pin low. The MCLR pin is a Schmitt trigger input with an additional glitch filter. Reset pulses that are longer than the minimum pulse width will generate a Reset. Refer to **Section 24.0 "Electrical Characteristics"** for minimum pulse width specifications. The External Reset (MCLR) Pin (EXTR) bit in the Reset Control (RCON) register is set to indicate the MCLR Reset.

### 6.4.1 EXTERNAL SUPERVISORY CIRCUIT

Many systems have external supervisory circuits that generate Reset signals to Reset multiple devices in the system. This external Reset signal can be directly connected to the MCLR pin to Reset the device when the rest of system is Reset.

### 6.4.2 INTERNAL SUPERVISORY CIRCUIT

When using the internal power supervisory circuit to Reset the device, the external Reset pin (MCLR) should be tied directly or resistively to VDD. In this case, the MCLR pin will not be used to generate a Reset. The external Reset pin (MCLR) does not have an internal pull-up and must not be left unconnected.

## 6.5 Software RESET Instruction (SWR)

Whenever the RESET instruction is executed, the device will assert SYSRST, placing the device in a special Reset state. This Reset state will not re-initialize the clock. The clock source in effect prior to the RESET instruction will remain. SYSRST is released at the next instruction cycle, and the Reset vector fetch will commence.

The Software Reset (Instruction) Flag (SWR) bit in the Reset Control (RCON<6>) register is set to indicate the software Reset.

## 6.6 Watchdog Time-out Reset (WDTO)

Whenever a Watchdog Time-out occurs, the device will asynchronously assert SYSRST. The clock source will remain unchanged. A WDT time-out during Sleep or Idle mode will wake-up the processor, but will not reset the processor.

The Watchdog Timer Time-out Flag (WDTO) bit in the Reset Control (RCON<4>) register is set to indicate the Watchdog Reset. Refer to **Section 21.4 "Watchdog Timer (WDT)"** for more information on Watchdog Reset.

## 6.7 Trap Conflict Reset

If a lower-priority hard trap occurs while a higher-priority trap is being processed, a hard trap conflict Reset occurs. The hard traps include exceptions of priority level 13 through level 15, inclusive. The address error (level 13) and oscillator error (level 14) traps fall into this category.

The Trap Reset Flag (TRAPR) bit in the Reset Control (RCON<15>) register is set to indicate the Trap Conflict Reset. Refer to **Section 7.0 "Interrupt Controller"** for more information on trap conflict Resets.

## 6.8 Configuration Mismatch Reset

To maintain the integrity of the peripheral pin select control registers, they are constantly monitored with shadow registers in hardware. If an unexpected change in any of the registers occur (such as cell disturbances caused by ESD or other external events), a configuration mismatch Reset occurs.

The Configuration Mismatch Flag (CM) bit in the Reset Control (RCON<9>) register is set to indicate the configuration mismatch Reset. Refer to **Section 10.0 "I/O Ports"** for more information on the configuration mismatch Reset.

| **Note:** | The configuration mismatch feature and associated Reset flag is not available on all devices. |
|---|---|

## 6.9 Illegal Condition Device Reset

An illegal condition device Reset occurs due to the following sources:

- Illegal Opcode Reset
- Uninitialized W Register Reset
- Security Reset

The Illegal Opcode or Uninitialized W Access Reset Flag (IOPUWR) bit in the Reset Control (RCON<14>) register is set to indicate the illegal condition device Reset.

### 6.9.1 ILLEGAL OPCODE RESET

A device Reset is generated if the device attempts to execute an illegal opcode value that is fetched from program memory.

The illegal opcode Reset function can prevent the device from executing program memory sections that are used to store constant data. To take advantage of the illegal opcode Reset, use only the lower 16 bits of each program memory section to store the data values. The upper 8 bits should be programmed with 3Fh, which is an illegal opcode value.

### 6.9.2 UNINITIALIZED W REGISTER RESET

Any attempts to use the uninitialized W register as an address pointer will Reset the device. The W register array (with the exception of W15) is cleared during all Resets and is considered uninitialized until written to.

### 6.9.3 SECURITY RESET

If a Program Flow Change (PFC) or Vector Flow Change (VFC) targets a restricted location in a protected segment (Boot and Secure Segment), that operation will cause a security Reset.

The PFC occurs when the Program Counter is reloaded as a result of a Call, Jump, Computed Jump, Return, Return from Subroutine, or other form of branch instruction.

The VFC occurs when the Program Counter is reloaded with an Interrupt or Trap vector.

Refer to **Section 21.8 "Code Protection and CodeGuard™ Security"** for more information on Security Reset.

## 6.10 Using the RCON Status Bits

The user application can read the Reset Control (RCON) register after any device Reset to determine the cause of the Reset.

| **Note:** | The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset will be meaningful. |
|---|---|

Table 6-3 provides a summary of Reset flag bit operation.

**TABLE 6-3: RESET FLAG BIT OPERATION**

| Flag Bit | Set by: | Cleared by: |
|---|---|---|
| TRAPR (RCON<15>) | Trap conflict event | POR, BOR |
| IOPWR (RCON<14>) | Illegal opcode or uninitialized W register access or Security Reset | POR, BOR |
| CM (RCON<9>) | Configuration Mismatch | POR, BOR |
| EXTR (RCON<7>) | $\overline{\text{MCLR}}$ Reset | POR |
| SWR (RCON<6>) | RESET instruction | POR, BOR |
| WDTO (RCON<4>) | WDT Time-out | PWRSAV instruction, CLRWDT instruction, POR, BOR |
| SLEEP (RCON<3>) | PWRSAV #SLEEP instruction | POR, BOR |
| IDLE (RCON<2>) | PWRSAV #IDLE instruction | POR, BOR |
| BOR (RCON<1>) | POR, BOR | — |
| POR (RCON<0>) | POR | — |

**Note:** All Reset flag bits can be set or cleared by user software.


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## 7.0 INTERRUPT CONTROLLER

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 6. "Interrupts"** (DS70184) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the dsPIC33FJ12MC201/202 CPU. It has the following features:

- Up to eight processor exceptions and software traps
- Seven user-selectable priority levels
- Interrupt Vector Table (IVT) with up to 118 vectors
- A unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Alternate Interrupt Vector Table (AIVT) for debug support
- Fixed interrupt entry and return latencies

### 7.1 Interrupt Vector Table

The Interrupt Vector Table (IVT) is shown in Figure 7-1. The IVT resides in program memory, starting at location 000004h. The IVT contains 126 vectors consisting of eight non-maskable trap vectors, plus up to 118 sources of interrupt. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit-wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority. This priority is linked to their position in the vector table. Lower addresses generally have a higher natural priority. For example, the interrupt associated with vector 0 will take priority over interrupts at any other vector address.

dsPIC33FJ12MC201/202 devices implement up to 26 unique interrupts and 4 nonmaskable traps. These are summarized in Table 7-1 and Table 7-2.

#### 7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT) is located after the IVT, as shown in Figure 7-1. Access to the AIVT is provided by the ALTIVT control bit (INTCON2<15>). If the ALTIVT bit is set, all interrupt and exception processes use the alternate vectors instead of the default vectors. The alternate vectors are organized in the same manner as the default vectors.

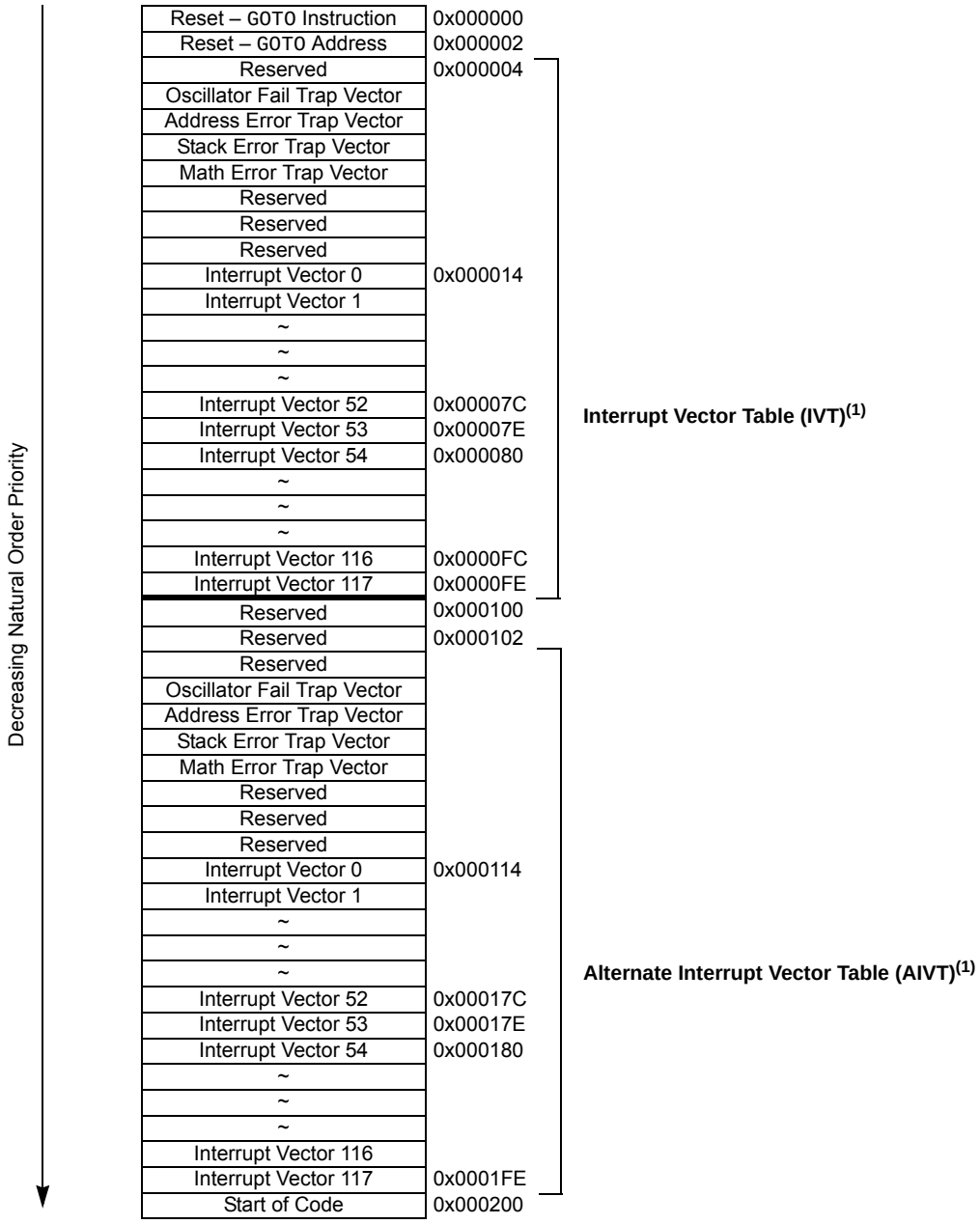
The AIVT supports debugging by providing a way to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications to facilitate evaluation of different software algorithms at run time. If the AIVT is not needed, the AIVT should be programmed with the same addresses used in the IVT.

### 7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The dsPIC33FJ12MC201/202 device clears its registers in response to a Reset, forcing the PC to zero. The digital signal controller then begins program execution at location 0x000000. A GOTO instruction at the Reset address can redirect program execution to the appropriate start-up routine.

**Note:** Any unimplemented or unused vector locations in the IVT and AIVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

**FIGURE 7-1: dsPIC33FJ12MC201/202 INTERRUPT VECTOR TABLE**




**Note 1:** See Table 7-1 for the list of implemented interrupt vectors.


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**TABLE 7-1: INTERRUPT VECTORS**

| Vector Number | Interrupt Request (IRQ) Number | IVT Address | AIVT Address | Interrupt Source |
|---|---|---|---|---|
| 8 | 0 | 0x000014 | 0x000114 | INT0 – External Interrupt 0 |
| 9 | 1 | 0x000016 | 0x000116 | IC1 – Input Capture 1 |
| 10 | 2 | 0x000018 | 0x000118 | OC1 – Output Compare 1 |
| 11 | 3 | 0x00001A | 0x00011A | T1 – Timer1 |
| 12 | 4 | 0x00001C | 0x00011C | Reserved |
| 13 | 5 | 0x00001E | 0x00011E | IC2 – Input Capture 2 |
| 14 | 6 | 0x000020 | 0x000120 | OC2 – Output Compare 2 |
| 15 | 7 | 0x000022 | 0x000122 | T2 – Timer2 |
| 16 | 8 | 0x000024 | 0x000124 | T3 – Timer3 |
| 17 | 9 | 0x000026 | 0x000126 | SPI1E – SPI1 Error |
| 18 | 10 | 0x000028 | 0x000128 | SPI1 – SPI1 Transfer Done |
| 19 | 11 | 0x00002A | 0x00012A | U1RX – UART1 Receiver |
| 20 | 12 | 0x00002C | 0x00012C | U1TX – UART1 Transmitter |
| 21 | 13 | 0x00002E | 0x00012E | ADC1 – ADC1 |
| 22 | 14 | 0x000030 | 0x000130 | Reserved |
| 23 | 15 | 0x000032 | 0x000132 | Reserved |
| 24 | 16 | 0x000034 | 0x000134 | SI2C1 – I2C1 Slave Events |
| 25 | 17 | 0x000036 | 0x000136 | MI2C1 – I2C1 Master Events |
| 26 | 18 | 0x000038 | 0x000138 | Reserved |
| 27 | 19 | 0x00003A | 0x00013A | Change Notification Interrupt |
| 28 | 20 | 0x00003C | 0x00013C | INT1 – External Interrupt 1 |
| 29 | 21 | 0x00003E | 0x00013E | Reserved |
| 30 | 22 | 0x000040 | 0x000140 | IC7 – Input Capture 7 |
| 31 | 23 | 0x000042 | 0x000142 | IC8 – Input Capture 8 |
| 32 | 24 | 0x000044 | 0x000144 | Reserved |
| 33 | 25 | 0x000046 | 0x000146 | Reserved |
| 34 | 26 | 0x000048 | 0x000148 | Reserved |
| 35 | 27 | 0x00004A | 0x00014A | Reserved |
| 36 | 28 | 0x00004C | 0x00014C | Reserved |
| 37 | 29 | 0x00004E | 0x00014E | INT2 – External Interrupt 2 |
| 38 | 30 | 0x000050 | 0x000150 | Reserved |
| 39 | 31 | 0x000052 | 0x000152 | Reserved |
| 40 | 32 | 0x000054 | 0x000154 | Reserved |
| 41 | 33 | 0x000056 | 0x000156 | Reserved |
| 42 | 34 | 0x000058 | 0x000158 | Reserved |
| 43 | 35 | 0x00005A | 0x00015A | Reserved |
| 44 | 36 | 0x00005C | 0x00015C | Reserved |
| 45 | 37 | 0x00005E | 0x00015E | Reserved |
| 46 | 38 | 0x000060 | 0x000160 | Reserved |
| 47 | 39 | 0x000062 | 0x000162 | Reserved |
| 48 | 40 | 0x000064 | 0x000164 | Reserved |
| 49 | 41 | 0x000066 | 0x000166 | Reserved |
| 50 | 42 | 0x000068 | 0x000168 | Reserved |
| 51 | 43 | 0x00006A | 0x00016A | Reserved |
| 52 | 44 | 0x00006C | 0x00016C | Reserved |
| 53 | 45 | 0x00006E | 0x00016E | Reserved |

**TABLE 7-1: INTERRUPT VECTORS (CONTINUED)**

| Vector Number | Interrupt Request (IRQ) Number | IVT Address | AIVT Address | Interrupt Source |
|---|---|---|---|---|
| 54 | 46 | 0x000070 | 0x000170 | Reserved |
| 55 | 47 | 0x000072 | 0x000172 | Reserved |
| 56 | 48 | 0x000074 | 0x000174 | Reserved |
| 57 | 49 | 0x000076 | 0x000176 | Reserved |
| 58 | 50 | 0x000078 | 0x000178 | Reserved |
| 59 | 51 | 0x00007A | 0x00017A | Reserved |
| 60 | 52 | 0x00007C | 0x00017C | Reserved |
| 61 | 53 | 0x00007E | 0x00017E | Reserved |
| 62 | 54 | 0x000080 | 0x000180 | Reserved |
| 63 | 55 | 0x000082 | 0x000182 | Reserved |
| 64 | 56 | 0x000084 | 0x000184 | Reserved |
| 65 | 57 | 0x000086 | 0x000186 | PWM1 – PWM1 Period Match |
| 66 | 58 | 0x000088 | 0x000188 | QEI – Position Counter Compare |
| 67 | 59 | 0x00008A | 0x00018A | Reserved |
| 68 | 60 | 0x00008C | 0x00018C | Reserved |
| 69 | 61 | 0x00008E | 0x00018E | Reserved |
| 70 | 62 | 0x000090 | 0x000190 | Reserved |
| 71 | 63 | 0x000092 | 0x000192 | $\overline{\text{FLTA1}}$ – PWM1 Fault A |
| 72 | 64 | 0x000094 | 0x000194 | Reserved |
| 73 | 65 | 0x000096 | 0x000196 | U1E – UART1 Error |
| 74 | 66 | 0x000098 | 0x000198 | Reserved |
| 75 | 67 | 0x00009A | 0x00019A | Reserved |
| 76 | 68 | 0x00009C | 0x00019C | Reserved |
| 77 | 69 | 0x00009E | 0x00019E | Reserved |
| 78 | 70 | 0x0000A0 | 0x0001A0 | Reserved |
| 79 | 71 | 0x0000A2 | 0x0001A2 | Reserved |
| 80 | 72 | 0x0000A4 | 0x0001A4 | Reserved |
| 81 | 73 | 0x0000A6 | 0x0001A6 | PWM2 – PWM2 Period Match |
| 82 | 74 | 0x0000A8 | 0x0001A8 | $\overline{\text{FLTA2}}$ – PWM2 Fault A |
| 83-125 | 75-117 | 0x0000AA-0x0000FE | 0x0001AA-0x0001FE | Reserved |

**TABLE 7-2: TRAP VECTORS**

| Vector Number | IVT Address | AIVT Address | Trap Source |
|---|---|---|---|
| 0 | 0x000004 | 0x000104 | Reserved |
| 1 | 0x000006 | 0x000106 | Oscillator Failure |
| 2 | 0x000008 | 0x000108 | Address Error |
| 3 | 0x00000A | 0x00010A | Stack Error |
| 4 | 0x00000C | 0x00010C | Math Error |
| 5 | 0x00000E | 0x00010E | Reserved |
| 6 | 0x000010 | 0x000110 | Reserved |
| 7 | 0x000012 | 0x000112 | Reserved |


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## 7.3 Interrupt Control and Status Registers

The dsPIC33FJ12MC201/202 devices implement a total of 22 registers for the interrupt controller:

- INTCON1
- INTCON2
- IFSx
- IECx
- IPCx
- INTTREG

### 7.3.1 INTCON1 AND INTCON2

Global interrupt control functions are controlled from INTCON1 and INTCON2. INTCON1 contains the Interrupt Nesting Disable (NSTDIS) bit as well as the control and status flags for the processor trap sources. The INTCON2 register controls the external interrupt request signal behavior and the use of the Alternate Interrupt Vector Table.

### 7.3.2 IFSx

The IFS registers maintain all of the interrupt request flags. Each source of interrupt has a status bit, which is set by the respective peripherals or external signal and is cleared via software.

### 7.3.3 IECx

The IEC registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals.

### 7.3.4 IPCx

The IPC registers are used to set the interrupt priority level for each source of interrupt. Each user interrupt source can be assigned to one of eight priority levels.

### 7.3.5 INTTREG

The INTTREG register contains the associated interrupt vector number and the new CPU interrupt priority level, which are latched into vector number (VECNUM<6:0>) and interrupt level (ILR<3:0>) bit fields in the INTTREG register. The new interrupt priority level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the same sequence that they are listed in Table 7-1. For example, the INT0 (External Interrupt 0) is shown as having vector number 8 and a natural order priority of 0. Thus, the INT0IF bit is found in IFS0<0>, the INT0IE bit in IEC0<0>, and the INT0IP bits in the first positions of IPC0 (IPC0<2:0>).

### 7.3.6 STATUS/CONTROL REGISTERS

Although they are not specifically part of the interrupt control hardware, two of the CPU Control registers contain bits that control interrupt functionality.

- The CPU STATUS register, SR, contains the IPL<2:0> bits (SR<7:5>). These bits indicate the current CPU interrupt priority level. The user application can change the current CPU priority level by writing to the IPL bits.
- The CORCON register contains the IPL3 bit which, together with IPL<2:0>, also indicates the current CPU priority level. IPL3 is a read-only bit so that trap events cannot be masked by the user software.

All Interrupt registers are described in Register 7-1 through Register 7-24 in the following pages.

**REGISTER 7-1: SR: CPU STATUS REGISTER(1)**

| R-0 | R-0 | R/C-0 | R/C-0 | R-0 | R/C-0 | R -0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| OA | OB | SA | SB | OAB | SAB | DA | DC |
| bit 15 | | | | | | | bit 8 |

| R/W-0(3) | R/W-0(3) | R/W-0(3) | R-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| **IPL2(2)** | **IPL1(2)** | **IPL0(2)** | RA | N | OV | Z | C |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | |
|---|---|---|
| C = Clear only bit | R = Readable bit | U = Unimplemented bit, read as '0' |
| S = Set only bit | W = Writable bit | -n = Value at POR |
| '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 7-5 **IPL<2:0>:** CPU Interrupt Priority Level Status bits(1)
111 = CPU Interrupt Priority Level is 7 (15), user interrupts disabled
110 = CPU Interrupt Priority Level is 6 (14)
101 = CPU Interrupt Priority Level is 5 (13)
100 = CPU Interrupt Priority Level is 4 (12)
011 = CPU Interrupt Priority Level is 3 (11)
010 = CPU Interrupt Priority Level is 2 (10)
001 = CPU Interrupt Priority Level is 1 (9)
000 = CPU Interrupt Priority Level is 0 (8)

**Note 1:** For complete register details, see **Register 3-1: "SR: CPU Status Register"**.
**2:** The IPL<2:0> bits are concatenated with the IPL<3> bit (CORCON<3>) to form the CPU Interrupt Priority Level. The value in parentheses indicates the IPL if IPL<3> = 1. User interrupts are disabled when IPL<3> = 1.
**3:** The IPL<2:0> Status bits are read-only when NSTDIS (INTCON1<15>) = 1.

**REGISTER 7-2: CORCON: CORE CONTROL REGISTER(1)**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | US | EDT | DL<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-1 | R/W-0 | R/C-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| SATA | SATB | SATDW | ACCSAT | **IPL3(2)** | PSV | RND | IF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | C = Clear only bit | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | -n = Value at POR | '1' = Bit is set |
| 0' = Bit is cleared | 'x = Bit is unknown | U = Unimplemented bit, read as '0' | |

bit 3 **IPL3:** CPU Interrupt Priority Level Status bit 3(2)
1 = CPU interrupt priority level is greater than 7
0 = CPU interrupt priority level is 7 or less

**Note 1:** For complete register details, see **Register 3-2: "CORCON: Core Control Register"**.
**2:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU Interrupt Priority Level.


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**REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| NSTDIS | OVAERR | OVBERR | COVAERR | COVBERR | OVATE | OVBTE | COVTE |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| SFTACERR | DIV0ERR | — | MATHERR | ADDRERR | STKERR | OSCFAIL | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **NSTDIS:** Interrupt Nesting Disable bit
1 = Interrupt nesting is disabled
0 = Interrupt nesting is enabled

bit 14 **OVAERR:** Accumulator A Overflow Trap Flag bit
1 = Trap was caused by overflow of Accumulator A
0 = Trap was not caused by overflow of Accumulator A

bit 13 **OVBERR:** Accumulator B Overflow Trap Flag bit
1 = Trap was caused by overflow of Accumulator B
0 = Trap was not caused by overflow of Accumulator B

bit 12 **COVAERR:** Accumulator A Catastrophic Overflow Trap Flag bit
1 = Trap was caused by catastrophic overflow of Accumulator A
0 = Trap was not caused by catastrophic overflow of Accumulator A

bit 11 **COVBERR:** Accumulator B Catastrophic Overflow Trap Flag bit
1 = Trap was caused by catastrophic overflow of Accumulator B
0 = Trap was not caused by catastrophic overflow of Accumulator B

bit 10 **OVATE:** Accumulator A Overflow Trap Enable bit
1 = Trap overflow of Accumulator A
0 = Trap disabled

bit 9 **OVBTE:** Accumulator B Overflow Trap Enable bit
1 = Trap overflow of Accumulator B
0 = Trap disabled

bit 8 **COVTE:** Catastrophic Overflow Trap Enable bit
1 = Trap on catastrophic overflow of Accumulator A or B enabled
0 = Trap disabled

bit 7 **SFTACERR:** Shift Accumulator Error Status bit
1 = Math error trap was caused by an invalid accumulator shift
0 = Math error trap was not caused by an invalid accumulator shift

bit 6 **DIV0ERR:** Arithmetic Error Status bit
1 = Math error trap was caused by a divide by zero
0 = Math error trap was not caused by a divide by zero

bit 5 **Unimplemented:** Read as ‘0’

bit 4 **MATHERR:** Arithmetic Error Status bit
1 = Math error trap has occurred
0 = Math error trap has not occurred

bit 3 **ADDRERR:** Address Error Trap Status bit
1 = Address error trap has occurred
0 = Address error trap has not occurred

**REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1 (CONTINUED)**

bit 2 **STKERR:** Stack Error Trap Status bit
1 = Stack error trap has occurred
0 = Stack error trap has not occurred

bit 1 **OSCFAIL:** Oscillator Failure Trap Status bit
1 = Oscillator failure trap has occurred
0 = Oscillator failure trap has not occurred

bit 0 **Unimplemented:** Read as '0'


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**REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2**

| R/W-0 | R-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| ALTIVT | DISI | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | INT2EP | INT1EP | INT0EP |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **ALTIVT:** Enable Alternate Interrupt Vector Table bit
1 = Use alternate vector table
0 = Use standard (default) vector table

bit 14 **DISI:** DISI Instruction Status bit
1 = DISI instruction is active
0 = DISI instruction is not active

bit 13-3 **Unimplemented:** Read as ‘0’

bit 2 **INT2EP:** External Interrupt 2 Edge Detect Polarity Select bit
1 = Interrupt on negative edge
0 = Interrupt on positive edge

bit 1 **INT1EP:** External Interrupt 1 Edge Detect Polarity Select bit
1 = Interrupt on negative edge
0 = Interrupt on positive edge

bit 0 **INT0EP:** External Interrupt 0 Edge Detect Polarity Select bit
1 = Interrupt on negative edge
0 = Interrupt on positive edge

**REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0**

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | AD1IF | U1TXIF | U1RXIF | SPI1IF | SPI1EIF | T3IF |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| T2IF | OC2IF | IC2IF | — | T1IF | OC1IF | IC1IF | INT0IF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **AD1IF:** ADC1 Conversion Complete Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 12 **U1TXIF:** UART1 Transmitter Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 11 **U1RXIF:** UART1 Receiver Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 10 **SPI1IF:** SPI1 Event Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 9 **SPI1EIF:** SPI1 Fault Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 8 **T3IF:** Timer3 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 7 **T2IF:** Timer2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 6 **OC2IF:** Output Compare Channel 2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 5 **IC2IF:** Input Capture Channel 2 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 4 **Unimplemented:** Read as '0'

bit 3 **T1IF:** Timer1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 2 **OC1IF:** Output Compare Channel 1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred


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**REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0 (CONTINUED)**

bit 1 **IC1IF:** Input Capture Channel 1 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 0 **INT0IF:** External Interrupt 0 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

**REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1**

| U-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | INT2IF | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| IC8IF | IC7IF | — | INT1IF | CNIF | — | MI2C1IF | SI2C1IF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **INT2IF:** External Interrupt 2 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 12-8 **Unimplemented:** Read as '0'

bit 7 **IC8IF:** Input Capture Channel 8 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 6 **IC7IF:** Input Capture Channel 7 Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 5 **Unimplemented:** Read as '0'

bit 4 **INT1IF:** External Interrupt 1 Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 3 **CNIF:** Input Change Notification Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 2 **Unimplemented:** Read as '0'

bit 1 **MI2C1IF:** I2C1 Master Events Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 0 **SI2C1IF:** I2C1 Slave Events Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred


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**REGISTER 7-7: IFS3: INTERRUPT FLAG STATUS REGISTER 3**

| R/W-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| FLTA1IF | — | — | — | — | QEIIF | PWM1IF | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **FLTA1IF:** PWM1 Fault A Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 14-11 **Unimplemented:** Read as ‘0’

bit 10 **QEIIF:** QEI Event Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 9 **PWM1IF:** PWM1 Error Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 8-0 **Unimplemented:** Read as ‘0’

**REGISTER 7-8: IFS4: INTERRUPT FLAG STATUS REGISTER 4**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | FLTA2IF | PWM2IF | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | U1EIF | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as '0'

bit 10 **FLTA2IF:** PWM2 Fault A Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 9 **PWM2IF:** PWM2 Error Interrupt Enable bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 8-2 **Unimplemented:** Read as '0'

bit 1 **U1EIF:** UART1 Error Interrupt Flag Status bit
1 = Interrupt request has occurred
0 = Interrupt request has not occurred

bit 0 **Unimplemented:** Read as '0'


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**REGISTER 7-9: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0**

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | AD1IE | U1TXIE | U1RXIE | SPI1IE | SPI1EIE | T3IE |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| T2IE | OC2IE | IC2IE | — | T1IE | OC1IE | IC1IE | INT0IE |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **AD1IE:** ADC1 Conversion Complete Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 12 **U1TXIE:** UART1 Transmitter Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 11 **U1RXIE:** UART1 Receiver Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 10 **SPI1IE:** SPI1 Event Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 9 **SPI1EIE:** SPI1 Event Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 8 **T3IE:** Timer3 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 7 **T2IE:** Timer2 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 6 **OC2IE:** Output Compare Channel 2 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 5 **IC2IE:** Input Capture Channel 2 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 4 **Unimplemented:** Read as '0'

bit 3 **T1IE:** Timer1 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 2 **OC1IE:** Output Compare Channel 1 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

**REGISTER 7-9: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0 (CONTINUED)**

bit 1 **IC1IE:** Input Capture Channel 1 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 0 **INT0IE:** External Interrupt 0 Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled


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**REGISTER 7-10: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1**

| U-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | INT2IE | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| IC8IE | IC7IE | — | INT1IE | CNIE | — | MI2C1IE | SI2C1IE |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **INT2IE:** External Interrupt 2 Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 12-8 **Unimplemented:** Read as '0'

bit 7 **IC8IE:** Input Capture Channel 8 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 6 **IC7IE:** Input Capture Channel 7 Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 5 **Unimplemented:** Read as '0'

bit 4 **INT1IE:** External Interrupt 1 Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 3 **CNIE:** Input Change Notification Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 2 **Unimplemented:** Read as '0'

bit 1 **MI2C1IE:** I2C1 Master Events Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 0 **SI2C1IE:** I2C1 Slave Events Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

**REGISTER 7-11: IEC3: INTERRUPT ENABLE CONTROL REGISTER 3**

| R/W-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| FLTA1IE | — | — | — | — | QEIIE | PWM1IE | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **FLTA1IE:** PWM1 Fault A Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 14-11 **Unimplemented:** Read as '0'

bit 10 **QEIIE:** QEI Event Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 9 **PWM1IE:** PWM1 Error Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 8-0 **Unimplemented:** Read as '0'


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**REGISTER 7-12: IEC4: INTERRUPT ENABLE CONTROL REGISTER 4**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | FLA2IE | PWM2IE | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | U1EIE | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as ‘0’

bit 10 **FLA2IE:** PWM2 Fault A Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 9 **PWM2IE:** PWM2 Error Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 8-2 **Unimplemented:** Read as ‘0’

bit 1 **U1EIE:** UART1 Error Interrupt Enable bit
1 = Interrupt request enabled
0 = Interrupt request not enabled

bit 0 **Unimplemented:** Read as ‘0’

**REGISTER 7-13: IPC0: INTERRUPT PRIORITY CONTROL REGISTER 0**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | T1IP<2:0> | | | — | OC1IP<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | IC1IP<2:0> | | | — | INT0IP<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **T1IP<2:0>:** Timer1 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **OC1IP<2:0>:** Output Compare Channel 1 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **IC1IP<2:0>:** Input Capture Channel 1 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **INT0IP<2:0>:** External Interrupt 0 Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled


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**REGISTER 7-14: IPC1: INTERRUPT PRIORITY CONTROL REGISTER 1**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | T2IP<2:0> | | | — | OC2IP<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-1 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | IC2IP<2:0> | | | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as ‘0’

bit 14-12 **T2IP<2:0>:** Timer2 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as ‘0’

bit 10-8 **OC2IP<2:0>:** Output Compare Channel 2 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as ‘0’

bit 6-4 **IC2IP<2:0>:** Input Capture Channel 2 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as ‘0’

**REGISTER 7-15: IPC2: INTERRUPT PRIORITY CONTROL REGISTER 2**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | U1RXIP<2:0> | | | — | SPI1IP<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | SPI1EIP<2:0> | | | — | T3IP<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **U1RXIP<2:0>:** UART1 Receiver Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **SPI1IP<2:0>:** SPI1 Event Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **SPI1EIP<2:0>:** SPI1 Error Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **T3IP<2:0>:** Timer3 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled


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**REGISTER 7-16: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | AD1IP<2:0> | | | — | U1TXIP<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-7 **Unimplemented:** Read as ‘0’

bit 6-4 **AD1IP<2:0>:** ADC1 Conversion Complete Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as ‘0’

bit 2-0 **U1TXIP<2:0>:** UART1 Transmitter Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

**REGISTER 7-17: IPC4: INTERRUPT PRIORITY CONTROL REGISTER 4**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | CNIP<2:0> | | | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | MI2C1IP<2:0> | | | — | SI2C1IP<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **CNIP<2:0>:** Change Notification Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11-7 **Unimplemented:** Read as '0'

bit 6-4 **MI2C1IP<2:0>:** I2C1 Master Events Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **SI2C1IP<2:0>:** I2C1 Slave Events Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled


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**REGISTER 7-18: IPC5: INTERRUPT PRIORITY CONTROL REGISTER 5**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | IC8IP<2:0> | | | — | IC7IP<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-1 | U-0 | U-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | INT1IP<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **IC8IP<2:0>:** Input Capture Channel 8 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **IC7IP<2:0>:** Input Capture Channel 7 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7-3 **Unimplemented:** Read as '0'

bit 2-0 **INT1IP<2:0>:** External Interrupt 1 Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

**REGISTER 7-19: IPC7: INTERRUPT PRIORITY CONTROL REGISTER 7**

| U-0 | U-1 | U-0 | U-0 | U-0 | U-1 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | INT2IP<2:0> | | | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-7 **Unimplemented:** Read as ‘0’

bit 6-4 **INT2IP<2:0>:** External Interrupt 2 Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as ‘0’


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**REGISTER 7-20: IPC14: INTERRUPT PRIORITY CONTROL REGISTER 14**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-1 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | QEIIP<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | PWM1IP<2:0> | | | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-12 **Unimplemented:** Read as ‘0’

bit 10-8 **QEIIP<2:0>:** QEI Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 7 **Unimplemented:** Read as ‘0’

bit 6-4 **PWM1IP<2:0>:** PWM1 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as ‘0’

**REGISTER 7-21: IPC15: INTERRUPT PRIORITY CONTROL REGISTER 15**

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | FLTA1IP<2:0> | | | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **FLTA1IP<2:0>:** PWM1 Fault A Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 11-0 **Unimplemented:** Read as '0'

**REGISTER 7-22: IPC16: INTERRUPT PRIORITY CONTROL REGISTER 16**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | U1EIP<2:0> | | | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-7 **Unimplemented:** Read as '0'

bit 6-4 **U1EIP<2:0>:** UART1 Error Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as '0'


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**REGISTER 7-23: IPC18: INTERRUPT PRIORITY CONTROL REGISTER 18**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | FLTA2IP<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | PWM2IP<2:0> | | | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as ‘0’

bit 8-10 **FLTA2IP<2:0>:** PWM2 Fault A Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 6-4 **PWM2IP<2:0>:** PWM2 Interrupt Priority bits
111 = Interrupt is priority 7 (highest priority interrupt)
•
•
•
001 = Interrupt is priority 1
000 = Interrupt source is disabled

bit 3-0 **Unimplemented:** Read as ‘0’

**REGISTER 7-24: INTTREG: INTERRUPT CONTROL AND STATUS REGISTER**

| U-0 | U-0 | U-0 | U-0 | R-0 | R-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | ILR<3:0> | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | VECNUM<6:0> | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-12 **Unimplemented:** Read as '0'

bit 11-8 **ILR<3:0>:** New CPU Interrupt Priority Level bits
1111 = CPU Interrupt Priority Level is 15
•
•
•
0001 = CPU Interrupt Priority Level is 1
0000 = CPU Interrupt Priority Level is 0

bit 7 **Unimplemented:** Read as '0'

bit 6-0 **VECNUM<6:0>:** Vector Number of Pending Interrupt bits
0111111 = Interrupt Vector pending is number 135
•
•
•
0000001 = Interrupt Vector pending is number 9
0000000 = Interrupt Vector pending is number 8


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## 7.4 Interrupt Setup Procedures

### 7.4.1 INITIALIZATION

To configure an interrupt source at initialization:

1. Set the NSTDIS bit (INTCON1<15>) if nested interrupts are not desired.
2. Select the user-assigned priority level for the interrupt source by writing the control bits into the appropriate IPCx register. The priority level will depend on the specific application and type of interrupt source. If multiple priority levels are not desired, the IPCx register control bits for all enabled interrupt sources can be programmed to the same non-zero value.

   **Note:** At a device Reset, the IPCx registers are initialized such that all user interrupt sources are assigned to priority level 4.

3. Clear the interrupt flag status bit associated with the peripheral in the associated IFSx register.
4. Enable the interrupt source by setting the interrupt enable control bit associated with the source in the appropriate IECx register.

### 7.4.2 INTERRUPT SERVICE ROUTINE (ISR)

The method used to declare an Interrupt Service Routine (ISR) and initialize the IVT with the correct vector address depends on the programming language (C or assembler) and the language development tool suite used to develop the application.

In general, the user application must clear the interrupt flag in the appropriate IFSx register for the source of interrupt that the ISR handles. Otherwise, program will re-enter the ISR immediately after exiting the routine. If the ISR is coded in assembly language, it must be terminated using a `RETFIE` instruction to unstack the saved PC value, SRL value and old CPU priority level.

### 7.4.3 TRAP SERVICE ROUTINE (TSR)

A Trap Service Routine (TSR) is coded like an ISR, except that the appropriate trap status flag in the INTCON1 register must be cleared to avoid re-entry into the TSR.

### 7.4.4 INTERRUPT DISABLE

All user interrupts can be disabled using this procedure:

1. Push the current SR value onto the software stack using the `PUSH` instruction.
2. Force the CPU to priority level 7 by inclusive ORing the value OEh with SRL.

To enable user interrupts, the `POP` instruction can be used to restore the previous SR value.

**Note:** Only user interrupts with a priority level of 7 or lower can be disabled. Trap sources (level 8-level 15) cannot be disabled.

The `DISI` instruction provides a convenient way to disable interrupts of priority levels 1-6 for a fixed period of time. Level 7 interrupt sources are not disabled by the `DISI` instruction.

**NOTES:**


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## 8.0 OSCILLATOR CONFIGURATION

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 7. "Oscillator"** (DS70186) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

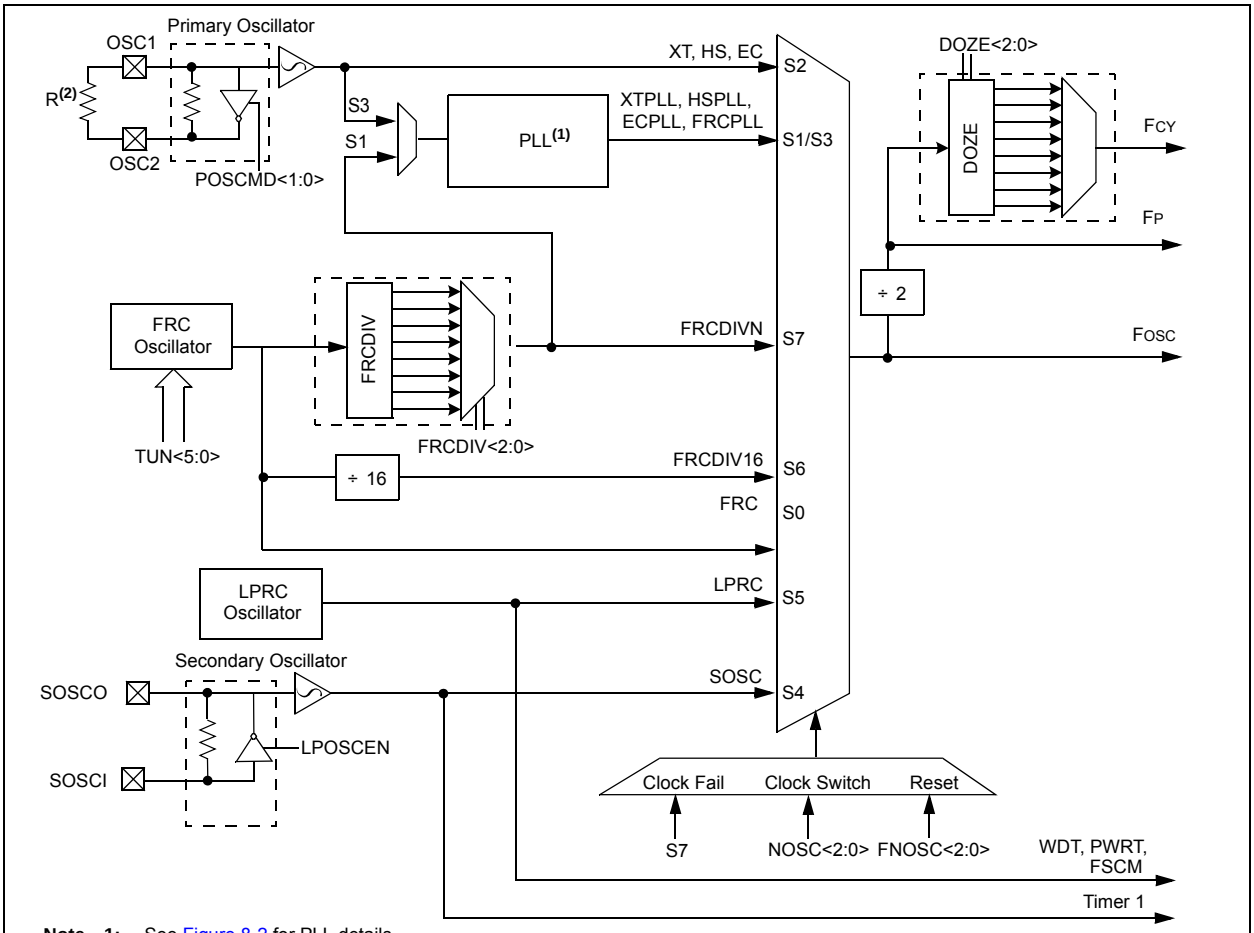
**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 oscillator system provides:

- External and internal oscillator options as clock sources
- An on-chip Phase-Locked Loop (PLL) to scale the internal operating frequency to the required system clock frequency
- An internal FRC oscillator that can also be used with the PLL, thereby allowing full-speed operation without any external clock generation hardware
- Clock switching between various clock sources
- Programmable clock postscaler for system power savings
- A Fail-Safe Clock Monitor (FSCM) that detects clock failure and takes fail-safe measures
- A Clock Control register (OSCCON)
- Nonvolatile Configuration bits for main oscillator selection

A simplified diagram of the oscillator system is shown in Figure 8-1.

**FIGURE 8-1: dsPIC33FJ12MC201/202 OSCILLATOR SYSTEM DIAGRAM**




**Note 1:** See Figure 8-2 for PLL details.

**2:** If the Oscillator is used with XT or HS modes, an extended parallel resistor with the value of 1 MΩ must be connected.

**3:** The term FP refers to the clock source for all peripherals, while FCY refers to the clock source for the CPU. Throughout this document, FCY and FP are used interchangeably, except in the case of Doze mode. FP and FCY will be different when Doze mode is used with a Doze ratio of 1:2 or lower.

## 8.1 CPU Clocking System

The dsPIC33FJ12MC201/202 devices provide seven system clock options:

- Fast RC (FRC) Oscillator
- FRC Oscillator with PLL
- Primary (XT, HS or EC) Oscillator
- Primary Oscillator with PLL
- Secondary (LP) Oscillator
- Low-Power RC (LPRC) Oscillator
- FRC Oscillator with postscaler

### 8.1.1 SYSTEM CLOCK SOURCES

#### 8.1.1.1 Fast RC

The Fast RC (FRC) internal oscillator runs at a nominal frequency of 7.37 MHz. User software can tune the FRC frequency. User software can optionally specify a factor (ranging from 1:2 to 1:256) by which the FRC clock frequency is divided. This factor is selected using the FRCDIV<2:0> (CLKDIV<10:8>) bits.

#### 8.1.1.2 Primary

The primary oscillator can use one of the following as its clock source:

- XT (Crystal): Crystals and ceramic resonators in the range of 3 MHz to 10 MHz. The crystal is connected to the OSC1 and OSC2 pins.
- HS (High-Speed Crystal): Crystals in the range of 10 MHz to 40 MHz. The crystal is connected to the OSC1 and OSC2 pins.
- EC (External Clock): The external clock signal is directly applied to the OSC1 pin.

#### 8.1.1.3 Secondary

The secondary (LP) oscillator is designed for low power and uses a 32.768 kHz crystal or ceramic resonator. The LP oscillator uses the SOSCI and SOSCO pins.

#### 8.1.1.4 Low-Power RC

The Low-Power RC (LPRC) internal oscIllator runs at a nominal frequency of 32.768 kHz. It is also used as a reference clock by the Watchdog Timer (WDT) and Fail-Safe Clock Monitor (FSCM).

#### 8.1.1.5 FRC

The clock signals generated by the FRC and primary oscillators can be optionally applied to an on-chip Phase-Locked Loop (PLL) to provide a wide range of output frequencies for device operation. PLL configuration is described in **Section 8.1.3 "PLL Configuration"**.

The FRC frequency depends on the FRC accuracy (see Table 24-18) and the value of the FRC Oscillator Tuning register (see Register 8-4).

### 8.1.2 SYSTEM CLOCK SELECTION

The oscillator source used at a device Power-on Reset event is selected using Configuration bit settings. The oscillator Configuration bit settings are located in the Configuration registers in the program memory. (Refer to **Section 21.1 "Configuration Bits"** for further details.) The Initial Oscillator Selection Configuration bits, FNOSC<2:0> (FOSCSEL<2:0>), and the Primary Oscillator Mode Select Configuration bits, POSCMD<1:0> (FOSC<1:0>), select the oscillator source that is used at a Power-on Reset. The FRC primary oscillator is the default (unprogrammed) selection.

The Configuration bits allow users to choose among 12 different clock modes, shown in Table 8-1.

The output of the oscillator (or the output of the PLL if a PLL mode has been selected) FOSC is divided by 2 to generate the device instruction clock (FCY) and the peripheral clock time base (FP). FCY defines the operating speed of the device, and speeds up to 40 MHz are supported by the dsPIC33FJ12MC201/202 architecture.

Instruction execution speed or device operating frequency, FCY, is given by:

**EQUATION 8-1: DEVICE OPERATING FREQUENCY**

$$FCY = \frac{FOSC}{2}$$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### 8.1.3 PLL CONFIGURATION

The primary oscillator and internal FRC oscillator can optionally use an on-chip PLL to obtain higher speeds of operation. The PLL provides significant flexibility in selecting the device operating speed. A block diagram of the PLL is shown in Figure 8-2.

The output of the primary oscillator or FRC, denoted as 'FIN', is divided down by a prescale factor (N1) of 2, 3, ... or 33 before being provided to the PLL's Voltage Controlled Oscillator (VCO). The input to the VCO must be selected in the range of 0.8 MHz to 8 MHz. The prescale factor 'N1' is selected using the PLLPRE<4:0> bits (CLKDIV<4:0>).

The PLL Feedback Divisor, selected using the PLLDIV<8:0> bits (PLLFBD<8:0>), provides a factor 'M,' by which the input to the VCO is multiplied. This factor must be selected such that the resulting VCO output frequency is in the range of 100 MHz to 200 MHz.

The VCO output is further divided by a postscale factor 'N2.' This factor is selected using the PLLPOST<1:0> bits (CLKDIV<7:6>). 'N2' can be either 2, 4, or 8, and must be selected such that the PLL output frequency (FOSC) is in the range of 12.5 MHz to 80 MHz, which generates device operating speeds of 6.25 to 40 MIPS.

For output 'FIN' on a primary oscillator, or FRC oscillator, the PLL output 'FOSC' is given by Equation 8-2.

**EQUATION 8-2: FOSC CALCULATION**

$$FOSC = FIN \cdot \left(\frac{M}{N1 \cdot N2}\right)$$

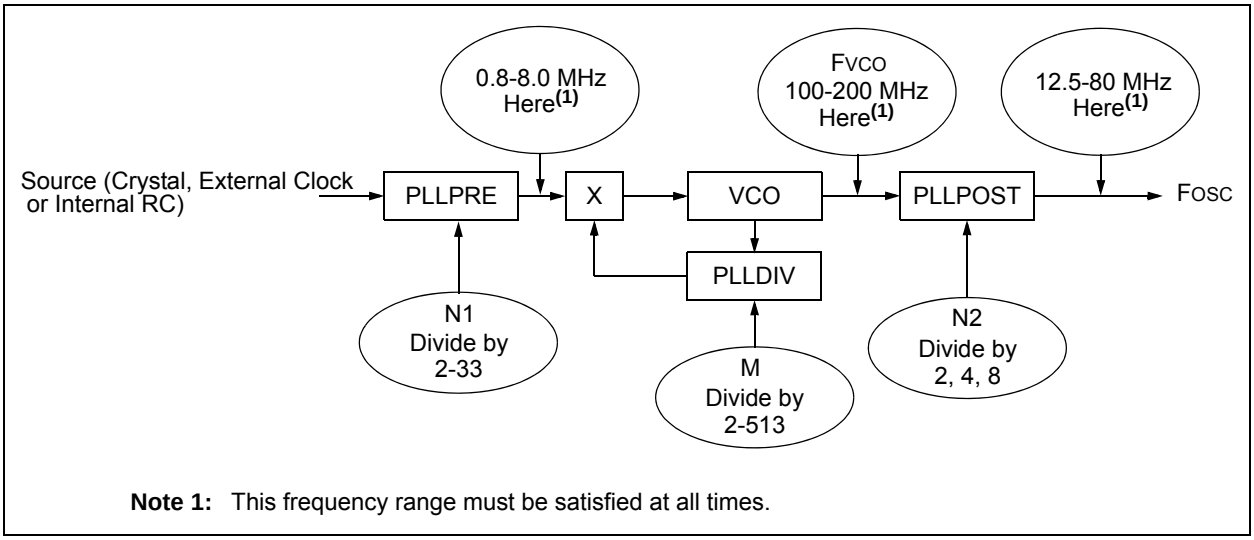
For example, suppose a 10 MHz crystal is being used with the selected oscillator mode of XT with PLL.

- If PLLPRE<4:0> = 0, then N1 = 2. This yields a VCO input of 10/2 = 5 MHz, which is within the acceptable range of 0.8-8 MHz.
- If PLLDIV<8:0> = 0x1E, then M = 32. This yields a VCO output of 5 x 32 = 160 MHz, which is within the 100-200 MHz ranged needed.
- If PLLPOST<1:0> = 0, then N2 = 2. This provides a Fosc of 160/2 = 80 MHz. The resultant device operating speed is 80/2 = 40 MIPS.

**EQUATION 8-3: XT WITH PLL MODE EXAMPLE**

$$FCY = \frac{FOSC}{2} = \frac{1}{2}\left(\frac{10000000 \cdot 32}{2 \cdot 2}\right) = 40 \text{ MIPS}$$

**FIGURE 8-2: dsPIC33FJ12MC201/202 PLL BLOCK DIAGRAM**




**Note 1:** This frequency range must be satisfied at all times.

**TABLE 8-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION**

| Oscillator Mode | Oscillator Source | POSCMD<1:0> | FNOSC<2:0> | Note |
|---|---|---|---|---|
| Fast RC Oscillator with Divide-by-N (FRCDIVN) | Internal | xx | 111 | **1, 2** |
| Fast RC Oscillator with Divide-by-16 (FRCDIV16) | Internal | xx | 110 | **1** |
| Low-Power RC Oscillator (LPRC) | Internal | xx | 101 | **1** |
| Secondary (Timer1) Oscillator (SOSC) | Secondary | xx | 100 | **1** |
| Primary Oscillator (HS) with PLL (HSPLL) | Primary | 10 | 011 | **—** |
| Primary Oscillator (XT) with PLL (XTPLL) | Primary | 01 | 011 | **—** |
| Primary Oscillator (EC) with PLL (ECPLL) | Primary | 00 | 011 | **1** |
| Primary Oscillator (HS) | Primary | 10 | 010 | **—** |
| Primary Oscillator (XT) | Primary | 01 | 010 | **—** |
| Primary Oscillator (EC) | Primary | 00 | 010 | **1** |
| Fast RC Oscillator with PLL (FRCPLL) | Internal | xx | 001 | **1** |
| Fast RC Oscillator (FRC) | Internal | xx | 000 | **1** |

**Note 1:** OSC2 pin function is determined by the OSCIOFNC Configuration bit.

**2:** This is the default oscillator mode for an unprogrammed (erased) device.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**REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER(1,3)**

| U-0 | R-0 | R-0 | R-0 | U-0 | R/W-y | R/W-y | R/W-y |
|---|---|---|---|---|---|---|---|
| — | COSC<2:0> | | | — | NOSC<2:0>(2) | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R-0 | U-0 | R/C-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| CLKLOCK | IOLOCK | LOCK | — | CF | — | LPOSCEN | OSWEN |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | y = Value set from Configuration bits on POR | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as '0'

bit 14-12 **COSC<2:0>:** Current Oscillator Selection bits (read-only)
111 = Fast RC oscillator (FRC) with Divide-by-n
110 = Fast RC oscillator (FRC) with Divide-by-16
101 = Low-Power RC oscillator (LPRC)
100 = Secondary oscillator (SOSC)
011 = Primary oscillator (XT, HS, EC) with PLL
010 = Primary oscillator (XT, HS, EC)
001 = Fast RC oscillator (FRC) with Divide-by-n plus PLL
000 = Fast RC oscillator (FRC)

bit 11 **Unimplemented:** Read as '0'

bit 10-8 **NOSC<2:0>:** New Oscillator Selection bits (2)
111 = Fast RC oscillator (FRC) with Divide-by-n
110 = Fast RC oscillator (FRC) with Divide-by-16
101 = Low-Power RC oscillator (LPRC)
100 = Secondary oscillator (SOSC)
011 = Primary oscillator (XT, HS, EC) with PLL
010 = Primary oscillator (XT, HS, EC)
001 = Fast RC oscillator (FRC) with Divide-by-n plus PLL
000 = Fast RC oscillator (FRC)

bit 7 **CLKLOCK:** Clock Lock Enable bit
If clock switching is enabled and FSCM is disabled, (FOSC<FCKSM> = 0b01)
1 = Clock switching is disabled, system clock source is locked
0 = Clock switching is enabled, system clock source can be modified by clock switching

bit 6 **IOLOCK:** Peripheral Pin Select Lock bit
1 = Peripherial pin select is locked, write to peripheral pin select registers not allowed
0 = Peripherial pin select is not locked, write to peripheral pin select registers allowed

bit 5 **LOCK:** PLL Lock Status bit (read-only)
1 = Indicates that PLL is in lock, or PLL start-up timer is satisfied
0 = Indicates that PLL is out of lock, start-up timer is in progress or PLL is disabled

bit 4 **Unimplemented:** Read as '0'

**Note 1:** Writes to this register require an unlock sequence. Refer to **Section 7. "Oscillator"** (DS70186) in the *"dsPIC33F/PIC24H Family Reference Manual"* (available from the Microchip web site) for details.

**2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

**3:** This register is reset only on a Power-on Reset (POR).

**REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER(1,3) (CONTINUED)**

bit 3 **CF:** Clock Fail Detect bit (read/clear by application)
1 = FSCM has detected clock failure
0 = FSCM has not detected clock failure

bit 2 **Unimplemented:** Read as '0'

bit 1 **LPOSCEN:** Secondary (LP) Oscillator Enable bit
1 = Enable secondary oscillator
0 = Disable secondary oscillator

bit 0 **OSWEN:** Oscillator Switch Enable bit
1 = Request oscillator switch to selection specified by NOSC<2:0> bits
0 = Oscillator switch is complete

**Note 1:** Writes to this register require an unlock sequence. Refer to **Section 7. "Oscillator"** (DS70186) in the *"dsPIC33F/PIC24H Family Reference Manual"* (available from the Microchip web site) for details.

**2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

**3:** This register is reset only on a Power-on Reset (POR).


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**REGISTER 8-2: CLKDIV: CLOCK DIVISOR REGISTER(2)**

| R/W-0 | R/W-0 | R/W-1 | R/W-1 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| ROI | DOZE<2:0> | | | DOZEN(1) | FRCDIV<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-1 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PLLPOST<1:0> | | — | PLLPRE<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **ROI:** Recover on Interrupt bit
1 = Interrupts will clear the DOZEN bit and the processor clock/peripheral clock ratio is set to 1:1
0 = Interrupts have no effect on the DOZEN bit

bit 14-12 **DOZE<2:0>:** Processor Clock Reduction Select bits
111 = FCY/128
110 = FCY/64
101 = FCY/32
100 = FCY/16
011 = FCY/8 (default)
010 = FCY/4
001 = FCY/2
000 = FCY/1

bit 11 **DOZEN:** DOZE Mode Enable bit(1)
1 = DOZE<2:0> field specifies the ratio between the peripheral clocks and the processor clocks
0 = Processor clock/peripheral clock ratio forced to 1:1

bit 10-8 **FRCDIV<2:0>:** Internal Fast RC Oscillator Postscaler bits
111 = FRC divide by 256
110 = FRC divide by 64
101 = FRC divide by 32
100 = FRC divide by 16
011 = FRC divide by 8
010 = FRC divide by 4
001 = FRC divide by 2
000 = FRC divide by 1 (default)

bit 7-6 **PLLPOST<1:0>:** PLL VCO Output Divider Select bits (also denoted as 'N2', PLL postscaler)
11 = Output/8
10 = Reserved
01 = Output/4 (default)
00 = Output/2

bit 5 **Unimplemented:** Read as '0'

bit 4-0 **PLLPRE<4:0>:** PLL Phase Detector Input Divider bits (also denoted as 'N1', PLL prescaler)
00000 = Input/2 (default)
00001 = Input/3
•
•
•
11111 = Input/33

**Note 1:** This bit is cleared when the ROI bit is set and an interrupt occurs.
**2:** This register is reset only on a Power-on Reset (POR).

**REGISTER 8-3: PLLFBD: PLL FEEDBACK DIVISOR REGISTER(1)**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0(1) |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | PLLDIV<8> |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-1 | R/W-1 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PLLDIV<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-9 **Unimplemented:** Read as '0'

bit 8-0 **PLLDIV<8:0>:** PLL Feedback Divisor bits (also denoted as 'M', PLL multiplier)

000000000 = 2
000000001 = 3
000000010 = 4
•
•
•
000110000 = 50 (default)
•
•
•
111111111 = 513

**Note 1:** This register is reset only on a Power-on Reset (POR).


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**REGISTER 8-4: OSCTUN: FRC OSCILLATOR TUNING REGISTER(2)**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | TUN<5:0>(1) | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-6 **Unimplemented:** Read as '0'

bit 5-0 **TUN<5:0>:** FRC Oscillator Tuning bits(1)

011111 = Center frequency +11.625% (8.23 MHz)
011110 = Center frequency +11.25% (8.20 MHz)
•
•
•
000001 = Center frequency +0.375% (7.40 MHz)
000000 = Center frequency (7.37 MHz nominal)
111111 = Center frequency -0.375% (7.345 MHz)
•
•
•
100001 = Center frequency -11.625% (6.52 MHz)
100000 = Center frequency -12% (6.49 MHz)

**Note 1:** OSCTUN functionality has been provided to help customers compensate for temperature effects on the FRC frequency over a wide range of temperatures. The tuning step size is an approximation and is neither characterized nor tested.

**2:** This register is reset only on a Power-on Reset (POR).

## 8.2 Clock Switching Operation

Applications are free to switch among any of the four clock sources (Primary, LP, FRC, and LPRC) under software control at any time. To limit the possible side effects of this flexibility, dsPIC33FJ12MC201/202 devices have a safeguard lock built into the switch process.

**Note:** Primary Oscillator mode has three different submodes (XT, HS, and EC), which are determined by the POSCMD<1:0> Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch among the different primary submodes without reprogramming the device.

### 8.2.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in the Configuration register must be programmed to '0'. (Refer to **Section 21.1 "Configuration Bits"** for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSC control bits (OSCCON<10:8>) do not control the clock selection when clock switching is disabled. However, the COSC bits (OSCCON<14:12>) reflect the clock source selected by the FNOSC Configuration bits.

The OSWEN control bit (OSCCON<0>) has no effect when clock switching is disabled. It is held at '0' at all times.

### 8.2.2 OSCILLATOR SWITCHING SEQUENCE

Performing a clock switch requires this basic sequence:

1. If desired, read the COSC bits (OSCCON<14:12>) to determine the current oscillator source.
2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
3. Write the appropriate value to the NOSC control bits (OSCCON<10:8>) for the new oscillator source.
4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
5. Set the OSWEN bit (OSCCON<0>) to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

1. The clock switching hardware compares the COSC status bits with the new value of the NOSC control bits. If they are the same, the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.
2. If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and the CF (OSCCON<3>) status bits are cleared.
3. The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware waits until the Oscillator Start-up Timer (OST) expires. If the new source is using the PLL, the hardware waits until a PLL lock is detected (LOCK = 1).
4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSC bit values are transferred to the COSC status bits.
6. The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or LP (if LPOSCEN remains set).

**Note 1:** The processor continues to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.

**2:** Direct clock switches between any primary oscillator mode with PLL and FRCPLL mode are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

**3:** Refer to **Section 7. "Oscillator"** (DS70186) in the *"dsPIC33F/PIC24H Family Reference Manual"* for details.

## 8.3 Fail-Safe Clock Monitor (FSCM)

The Fail-Safe Clock Monitor allows the device to continue to operate even in the event of an oscillator failure. The FSCM function is enabled by programming. If the FSCM function is enabled, the LPRC internal oscillator runs at all times (except during Sleep mode) and is not subject to control by the Watchdog Timer.

In the event of an oscillator failure, the FSCM generates a clock failure trap event and switches the system clock over to the FRC oscillator. Then the application program can either attempt to restart the oscillator or execute a controlled shutdown. The trap can be treated as a warm Reset by simply loading the Reset address into the oscillator fail trap vector.

If the PLL multiplier is used to scale the system clock, the internal FRC is also multiplied by the same factor on clock failure. Essentially, the device switches to FRC with PLL on a clock failure.


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## 9.0 POWER-SAVING FEATURES

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 9. "Watchdog Timer and Power-Saving Modes"** (DS70196) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 devices provide the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power. dsPIC33FJ12MC201/202 devices can manage power consumption in four different ways:

- Clock frequency
- Instruction-based Sleep and Idle modes
- Software-controlled Doze mode
- Selective peripheral control in software

Combinations of these methods can be used to selectively tailor an application's power consumption while still maintaining critical application features, such as timing-sensitive communications.

### 9.1 Clock Frequency and Clock Switching

dsPIC33FJ12MC201/202 devices allow a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC bits (OSCCON<10:8>). The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in **Section 8.0 "Oscillator Configuration"**.

### 9.2 Instruction-Based Power-Saving Modes

dsPIC33FJ12MC201/202 devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution. Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The assembler syntax of the PWRSAV instruction is shown in Example 9-1.

**Note:** SLEEP_MODE and IDLE_MODE are constants defined in the assembler include file for the selected device.

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to wake-up.

#### 9.2.1 SLEEP MODE

The following occur in Sleep mode:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption is reduced to a minimum, provided that no I/O pin is sourcing current
- The Fail-Safe Clock Monitor does not operate, since the system clock source is disabled
- The LPRC clock continues to run in Sleep mode if the WDT is enabled
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode
- Some device features or peripherals may continue to operate. This includes items such as the input change notification on the I/O ports, or peripherals that use an external clock input.
- Any peripheral that requires the system clock source for its operation is disabled

The device will wake-up from Sleep mode on any of the these events:

- Any interrupt source that is individually enabled
- Any form of device Reset
- A WDT time-out

On wake-up from Sleep mode, the processor restarts with the same clock source that was active when Sleep mode was entered.

**EXAMPLE 9-1: PWRSAV INSTRUCTION SYNTAX**

```
PWRSAV  #SLEEP_MODE    ; Put the device into Sleep mode
PWRSAV  #IDLE_MODE     ; Put the device into Idle mode
```

### 9.2.2 IDLE MODE

The following occur in Idle mode:

- The CPU stops executing instructions
- The WDT is automatically cleared
- The system clock source remains active. By default, all peripheral modules continue to operate normally from the system clock source, but can also be selectively disabled (see **Section 9.4 "Peripheral Module Disable"**).
- If the WDT or FSCM is enabled, the LPRC also remains active.

The device will wake from Idle mode on any of these events:

- Any interrupt that is individually enabled
- Any device Reset
- A WDT time-out

On wake-up from Idle mode, the clock is reapplied to the CPU and instruction execution will begin (2-4 clock cycles later), starting with the instruction following the PWRSAV instruction, or the first instruction in the ISR.

### 9.2.3 INTERRUPTS COINCIDENT WITH POWER-SAVE INSTRUCTIONS

Any interrupt that coincides with the execution of a PWRSAV instruction is held off until entry into Sleep or Idle mode has completed. The device then wakes up from Sleep or Idle mode.

## 9.3 Doze Mode

The preferred strategies for reducing power consumption are changing clock speed and invoking one of the power-saving modes. In some circumstances, this may not be practical. For example, it may be necessary for an application to maintain uninterrupted synchronous communication, even while it is doing nothing else. Reducing system clock speed can introduce communication errors, while using a power-saving mode can stop communications completely.

Doze mode is a simple and effective alternative method to reduce power consumption while the device is still executing code. In this mode, the system clock continues to operate from the same source and at the same speed. Peripheral modules continue to be clocked at the same speed, while the CPU clock speed is reduced. Synchronization between the two clock domains is maintained, allowing the peripherals to access the SFRs while the CPU executes code at a slower rate.

Doze mode is enabled by setting the DOZEN bit (CLKDIV<11>). The ratio between peripheral and core clock speed is determined by the DOZE<2:0> bits (CLKDIV<14:12>). There are eight possible configurations, from 1:1 to 1:128, with 1:1 being the default setting.

Programs can use Doze mode to selectively reduce power consumption in event-driven applications. This allows clock-sensitive functions, such as synchronous communications, to continue without interruption while the CPU idles, waiting for something to invoke an interrupt routine. An automatic return to full-speed CPU operation on interrupts can be enabled by setting the ROI bit (CLKDIV<15>). By default, interrupt events have no effect on Doze mode operation.

For example, suppose the device is operating at 20 MIPS and the UART module has been configured for 500 kbps based on this device operating speed. If the device is placed in Doze mode with a clock frequency ratio of 1:4, the UART module continues to communicate at the required bit rate of 500 kbps, but the CPU now starts executing instructions at a frequency of 5 MIPS.

## 9.4 Peripheral Module Disable

The Peripheral Module Disable (PMD) registers provide a method to disable a peripheral module by stopping all clock sources supplied to that module. When a peripheral is disabled using the appropriate PMD control bit, the peripheral is in a minimum power consumption state. The control and status registers associated with the peripheral are also disabled, so writes to those registers will have no effect and read values will be invalid.

A peripheral module is enabled only if both the associated bit in the PMD register is cleared and the peripheral is supported by the specific dsPIC® DSC variant. If the peripheral is present in the device, it is enabled in the PMD register by default.

| | |
|---|---|
| **Note:** | If a PMD bit is set, the corresponding module is disabled after a delay of one instruction cycle. Similarly, if a PMD bit is cleared, the corresponding module is enabled after a delay of one instruction cycle (assuming the module control registers are already configured to enable module operation). |


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**REGISTER 9-1: PMD1: PERIPHERAL MODULE DISABLE CONTROL REGISTER 1**

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | T3MD | T2MD | T1MD | QEIMD | PWM1MD | — |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | U-0 | R/W-0 | U-0 | R/W-0 | U-0 | U-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| I2C1MD | — | U1MD | — | SPI1MD | — | — | AD1MD(1) |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **T3MD:** Timer3 Module Disable bit
1 = Timer3 module is disabled
0 = Timer3 module is enabled

bit 12 **T2MD:** Timer2 Module Disable bit
1 = Timer2 module is disabled
0 = Timer2 module is enabled

bit 11 **T1MD:** Timer1 Module Disable bit
1 = Timer1 module is disabled
0 = Timer1 module is enabled

bit 10 **QEIMD:** QEI Module Disable bit
1 = QEI module is disabled
0 = QEI module is enabled

bit 9 **PWM1MD:** PWM1 Module Disable bit
1 = PWM1 module is disabled
0 = PWM1 module is enabled

bit 18 **Unimplemented:** Read as '0'

bit 7 **I2C1MD:** $I^2C1$ Module Disable bit
1 = $I^2C1$ module is disabled
0 = $I^2C1$ module is enabled

bit 6 **Unimplemented:** Read as '0'

bit 5 **U1MD:** UART1 Module Disable bit
1 = UART1 module is disabled
0 = UART1 module is enabled

bit 4 **Unimplemented:** Read as '0'

bit 3 **SPI1MD:** SPI1 Module Disable bit
1 = SPI1 module is disabled
0 = SPI1 module is enabled

bit 2-1 **Unimplemented:** Read as '0'

bit 0 **AD1MD:** ADC1 Module Disable bit(1)
1 = ADC1 module is disabled
0 = ADC1 module is enabled

**Note 1:** PCFGx bits have no effect if the ADC module is disabled by setting this bit. When the bit is set, all port pins that have been multiplexed with ANx will be in Digital mode.

**REGISTER 9-2: PMD2: PERIPHERAL MODULE DISABLE CONTROL REGISTER 2**

| R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| IC8MD | IC7MD | — | — | — | — | IC2MD | IC1MD |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | OC2MD | OC1MD |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **IC8MD:** Input Capture 8 Module Disable bit
1 = Input Capture 8 module is disabled
0 = Input Capture 8 module is enabled

bit 14 **IC7MD:** Input Capture 2 Module Disable bit
1 = Input Capture 7 module is disabled
0 = Input Capture 7 module is enabled

bit 13-10 **Unimplemented:** Read as '0'

bit 9 **IC2MD:** Input Capture 2 Module Disable bit
1 = Input Capture 2 module is disabled
0 = Input Capture 2 module is enabled

bit 8 **IC1MD:** Input Capture 1 Module Disable bit
1 = Input Capture 1 module is disabled
0 = Input Capture 1 module is enabled

bit 7-2 **Unimplemented:** Read as '0'

bit 1 **OC2MD:** Output Compare 2 Module Disable bit
1 = Output Compare 2 module is disabled
0 = Output Compare 2 module is enabled

bit 0 **OC1MD:** Output Compare 1 Module Disable bit
1 = Output Compare 1 module is disabled
0 = Output Compare 1 module is enabled


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**REGISTER 9-3: PMD3: PERIPHERAL MODULE DISABLE CONTROL REGISTER 3**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | PWM2MD | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4 **PWM2MD:** PWM2 Module Disable bit
1 = PWM2 module is disabled
0 = PWM2 module is enabled

bit 3-0 **Unimplemented:** Read as ‘0’

**NOTES:**


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## 10.0 I/O PORTS

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 10. "I/O Ports"** (DS70193) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

All of the device pins (except VDD, VSS, MCLR, and OSC1/CLKI) are shared among the peripherals and the parallel I/O ports. All I/O input ports feature Schmitt Trigger inputs for improved noise immunity.

### 10.1 Parallel I/O (PIO) Ports

Generally a parallel I/O port that shares a pin with a peripheral is subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port has ownership of the output data and control signals of the I/O pin. The logic also prevents "loop through," in which a port's digital output can drive the input of a peripheral that shares the same pin. Figure 10-1 shows how ports are shared with other peripherals and the associated I/O pin to which they are connected.

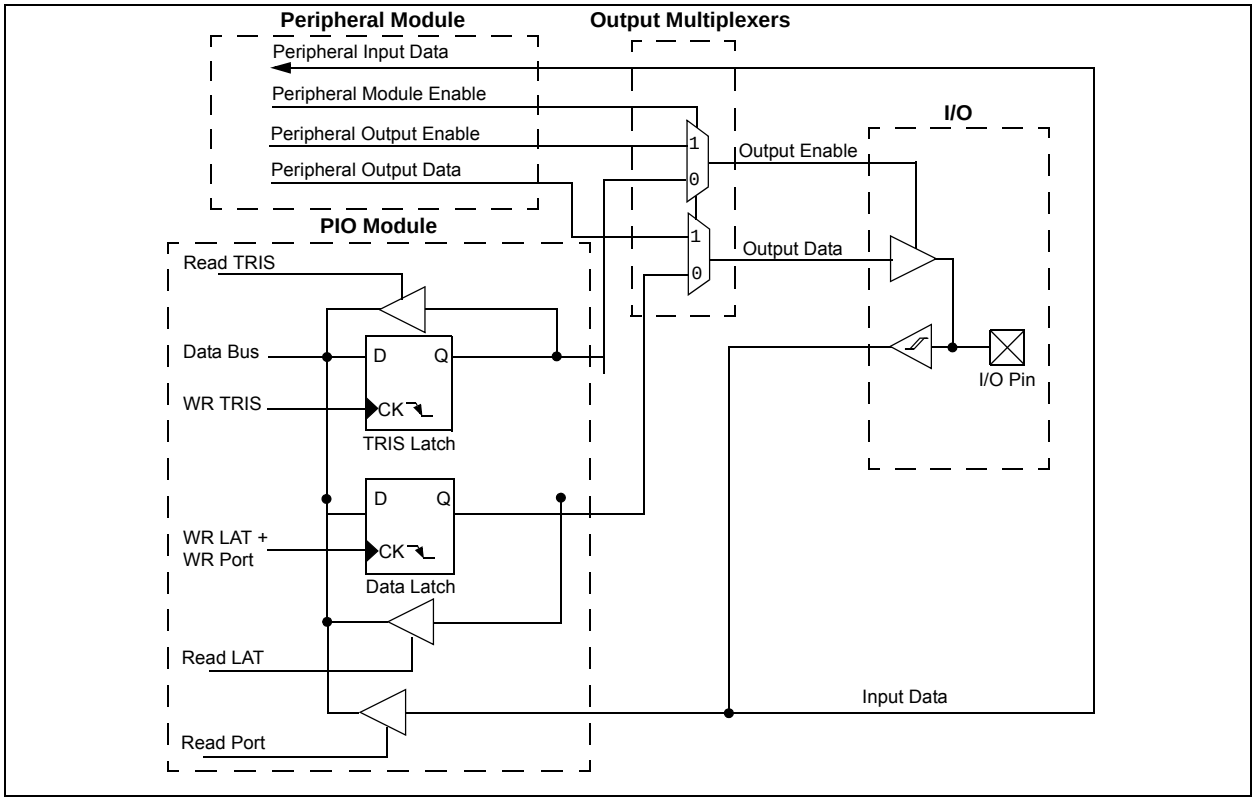
When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin can be read, but the output driver for the parallel port bit is disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin can be driven by a port.

All port pins have three registers directly associated with their operation as digital I/O. The data direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a '1', the pin is an input. All port pins are defined as inputs after a Reset. Reads from the latch (LATx) read the latch. Writes to the latch write the latch. Reads from the port (PORTx) read the port pins, while writes to the port pins write the latch.

Any bit and its associated data and control registers that are not valid for a particular device will be disabled. This means the corresponding LATx and TRISx registers and the port pin will read as zeros.

When a pin is shared with another peripheral or function that is defined as an input only, it is nevertheless regarded as a dedicated port because there is no other competing source of outputs.

**FIGURE 10-1: BLOCK DIAGRAM OF A TYPICAL SHARED PORT STRUCTURE**



#### 10.1.1 OPEN-DRAIN CONFIGURATION

In addition to the PORT, LAT, and TRIS registers for data control, some port pins can also be individually configured for either digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs higher than VDD (e.g., 5V) on any 5V-tolerant pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

See **"Pin Diagrams"** for the available pins and their functionality.

### 10.2 Configuring Analog Port Pins

The AD1PCFG and TRIS registers control the operation of the analog-to-digital (A/D) port pins. The port pins that are to function as analog inputs must have their corresponding TRIS bit set (input). If the TRIS bit is cleared (output), the digital output level (VOH or VOL) will be converted.

The AD1PCFGL register has a default value of 0x0000; therefore, all pins that share ANx functions are analog (not digital) by default.

When the PORT register is read, all pins configured as analog input channels will read as cleared (a low level).

Pins configured as digital inputs will not convert an analog input. Analog levels on any pin defined as a digital input (including the ANx pins) can cause the input buffer to consume current that exceeds the device specifications.

#### 10.2.1 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically this instruction would be an NOP. An demonstration is shown in Example 10-1.

### 10.3 Input Change Notification

The input change notification function of the I/O ports allows the dsPIC33FJ12MC201/202 devices to generate interrupt requests to the processor in response to a change-of-state on selected input pins. This feature can detect input change-of-states even in Sleep mode, when the clocks are disabled. Depending on the device pin count, up to 21 external signals (CNx pin) can be selected (enabled) for generating an interrupt request on a change-of-state.

Four control registers are associated with the CN module. The CNEN1 and CNEN2 registers contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin also has a weak pull-up connected to it. The pull-ups act as a current source connected to the pin, and eliminate the need for external resistors when push-button or keypad devices are connected. The pull-ups are enabled separately using the CNPU1 and CNPU2 registers, which contain the control bits for each of the CN pins. Setting any of the control bits enables the weak pull-ups for the corresponding pins.

| **Note:** | Pull-ups on change notification pins should always be disabled when the port pin is configured as a digital output. |
|---|---|

**EXAMPLE 10-1: PORT WRITE/READ EXAMPLE**

```
MOV   0xFF00, W0          ; Configure PORTB<15:8> as inputs
MOV   W0, TRISBB          ; and PORTB<7:0> as outputs
NOP                       ; Delay 1 cycle
btss  PORTB, #13          ; Next Instruction
```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## 10.4 Peripheral Pin Select

Peripheral pin select configuration enables peripheral set selection and placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, programmers can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The peripheral pin select configuration feature operates over a fixed subset of digital I/O pins. Programmers can independently map the input and/or output of most digital peripherals to any one of these I/O pins. Peripheral pin select is performed in software, and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping, once it has been established.

### 10.4.1 AVAILABLE PINS

The peripheral pin select feature is used with a range of up to 16 pins. The number of available pins depends on the particular device and its pin count. Pins that support the peripheral pin select feature include the designation “RPn” in their full pin designation, where “RP” designates a remappable peripheral and “n” is the remappable pin number.

### 10.4.2 CONTROLLING PERIPHERAL PIN SELECT

Peripheral pin select features are controlled through two sets of special function registers: one to map peripheral inputs, and one to map outputs. Because they are separately controlled, a particular peripheral’s input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral selectable pin is handled in two different ways, depending on whether an input or output is being mapped.

#### 10.4.2.1 Input Mapping

The inputs of the peripheral pin select options are mapped on the basis of the peripheral. A control register associated with a peripheral dictates the pin it will be mapped to. The RPINRx registers are used to configure peripheral input mapping (see Register 10-1 through Register 10-13). Each register contains sets of 5-bit fields, with each set associated with one of the remappable peripherals. Programming a given peripheral’s bit field with an appropriate 5-bit value maps the RPn pin with that value to that peripheral. For any given device, the valid range of values for any bit field corresponds to the maximum number of peripheral pin selections supported by the device.

Figure 10-2 Illustrates remappable pin selection for U1RX input.

| **Note:** | For input mapping only, the Peripheral Pin Select (PPS) functionality does not have priority over the TRISx settings. Therefore, when configuring the RPx pin for input, the corresponding bit in the TRISx register must also be configured for input (i.e., set to ‘1’). |
|---|---|

**FIGURE 10-2: REMAPPABLE MUX INPUT FOR U1RX**

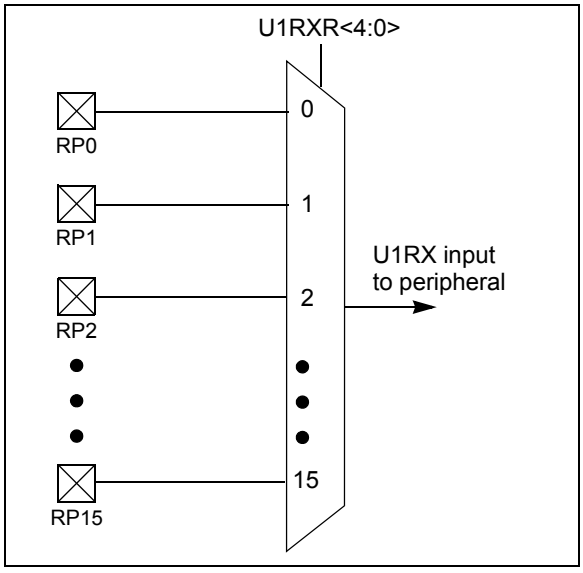

**TABLE 10-1: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)(1)**

| Input Name | Function Name | Register | Configuration Bits |
|---|---|---|---|
| External Interrupt 1 | INT1 | RPINR0 | INT1R<4:0> |
| External Interrupt 2 | INT2 | RPINR1 | INT2R<4:0> |
| Timer2 External Clock | T2CK | RPINR3 | T2CKR<4:0> |
| Timer3 External Clock | T3CK | RPINR3 | T3CKR<4:0> |
| Input Capture 1 | IC1 | RPINR7 | IC1R<4:0> |
| Input Capture 2 | IC2 | RPINR7 | IC2R<4:0> |
| Input Capture 7 | IC7 | RPINR10 | IC7R<4:0> |
| Input Capture 8 | IC8 | RPINR10 | IC8R<4:0> |
| Output Compare Fault A | OCFA | RPINR11 | OCFAR<4:0> |
| PWM1 Fault | $\overline{\text{FLTA1}}$ | RPINR12 | FLTA1R<4:0> |
| PWM2 Fault | $\overline{\text{FLTA2}}$ | RPINR13 | FLTA2R<4:0> |
| QEI1 Phase A | QEA | RPINR14 | QEA1R<4:0> |
| QEI1 Phase B | QEB | RPINR14 | QEB1R<4:0> |
| QEI1 Index | INDX | RPINR15 | INDX1R<4:0> |
| UART1 Receive | U1RX | RPINR18 | U1RXR<4:0> |
| UART1 Clear To Send | $\overline{\text{U1CTS}}$ | RPINR18 | U1CTSR<4:0> |
| SPI1 Data Input | SDI1 | RPINR20 | SDI1R<4:0> |
| SPI1 Clock Input | SCK1 | RPINR20 | SCK1R<4:0> |
| SPI1 Slave Select Input | $\overline{\text{SS1}}$ | RPINR21 | SS1R<4:0> |

**Note 1:** Unless otherwise noted, all inputs use the Schmitt input buffers.

### 10.4.2.2 Output Mapping

In contrast to inputs, the outputs of the peripheral pin select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Like the RPINRx registers, each register contains sets of 5-bit fields, with each set associated with one RPn pin (see Register 10-14 through Register 10-21). The value of the bit field corresponds to one of the peripherals, and that peripheral's output is mapped to the pin (see Table 10-2 and Figure 10-3).

The list of peripherals for output mapping also includes a null value of '00000' because of the mapping technique. This permits any given pin to remain unconnected from the output of any of the pin selectable peripherals.

**FIGURE 10-3: MULTIPLEXING OF REMAPPABLE OUTPUT FOR RPn**

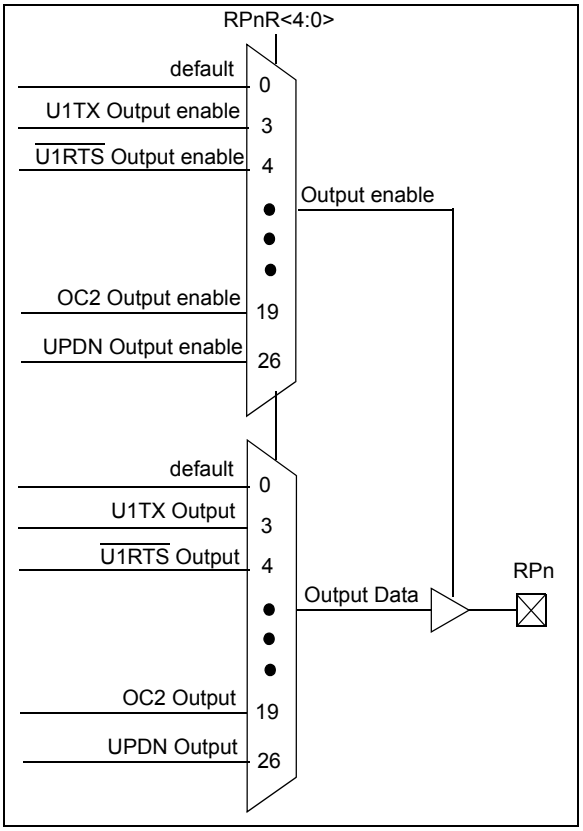



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**TABLE 10-2: OUTPUT SELECTION FOR REMAPPABLE PIN (RPn)**

| Function | RPnR<4:0> | Output Name |
|---|---|---|
| NULL | 00000 | RPn tied to default port pin |
| U1TX | 00011 | RPn tied to UART1 Transmit |
| $\overline{\text{U1RTS}}$ | 00100 | RPn tied to UART1 Ready To Send |
| SDO1 | 00111 | RPn tied to SPI1 Data Output |
| SCK1OUT | 01000 | RPn tied to SPI1 Clock Output |
| SS1OUT | 01001 | RPn tied to SPI1 Slave Select Output |
| OC1 | 10010 | RPn tied to Output Compare 1 |
| OC2 | 10011 | RPn tied to Output Compare 2 |
| UPDN | 11010 | RPn tied to QEI direction (UPDN) status |

### 10.4.3 CONTROLLING CONFIGURATION CHANGES

Because peripheral remapping can be changed during run time, some restrictions on peripheral remapping are needed to prevent accidental configuration changes. dsPIC33FJ12MC201/202 devices include three features to prevent alterations to the peripheral map:

- Control register lock sequence
- Continuous state monitoring
- Configuration bit pin select lock

#### 10.4.3.1 Control Register Lock

Under normal operation, writes to the RPINRx and RPORx registers are not allowed. Attempted writes appear to execute normally, but the contents of the registers remain unchanged. To change these registers, they must be unlocked in hardware. The register lock is controlled by the IOLOCK bit (OSCCON<6>). Setting IOLOCK prevents writes to the control registers; clearing IOLOCK allows writes.

To set or clear IOLOCK, a specific command sequence must be executed:

1. Write 0x46 to OSCCON<7:0>.
2. Write 0x57 to OSCCON<7:0>.
3. Clear (or set) IOLOCK as a single operation.

**Note:** MPLAB® C30 provides built-in C language functions for unlocking the OSCCON register:

```
__builtin_write_OSCCONL(value)
__builtin_write_OSCCONH(value)
```

See MPLAB IDE Help for more information.

Unlike the similar sequence with the oscillator's LOCK bit, IOLOCK remains in one state until changed. This allows all of the peripheral pin selects to be configured with a single unlock sequence followed by an update to all control registers, then locked with a second lock sequence.

#### 10.4.3.2 Continuous State Monitoring

In addition to being protected from direct writes, the contents of the RPINRx and RPORx registers are constantly monitored in hardware by shadow registers. If an unexpected change in any of the registers occurs (such as cell disturbances caused by ESD or other external events), a configuration mismatch Reset will be triggered.

#### 10.4.3.3 Configuration Bit Pin Select Lock

As an additional level of safety, the device can be configured to prevent more than one write session to the RPINRx and RPORx registers. The IOL1WAY (FOSC<IOL1WAY>) configuration bit blocks the IOLOCK bit from being cleared after it has been set once. If IOLOCK remains set, the register unlock procedure will not execute, and the peripheral pin select control registers cannot be written to. The only way to clear the bit and re-enable peripheral remapping is to perform a device Reset.

In the default (unprogrammed) state, IOL1WAY is set, restricting users to one write session. Programming IOL1WAY allows user applications unlimited access (with the proper use of the unlock sequence) to the peripheral pin select registers.

## 10.5 Peripheral Pin Select Registers

The dsPIC33FJ12MC201/202 family of devices implement 21 registers for remappable peripheral configuration:

- Input Remappable Peripheral Registers (13)
- Output Remappable Peripheral Registers (8)

**Note:** Input and Output Register values can only be changed if OSCCON<IOLOCK> = 0. See **Section 10.4.3.1 "Control Register Lock"** for a specific command sequence.

**REGISTER 10-1: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | INT1R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **INT1R<4:0>:** Assign External Interrupt 1 (INTR1) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-0 **Unimplemented:** Read as '0'


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**REGISTER 10-2: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | INT2R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4-0 **INT2R<4:0>:** Assign External Interrupt 2 (INTR2) to the corresponding RPn pin

11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-3: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | T3CKR<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | T2CKR<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **T3CKR<4:0>:** Assign Timer3 External Clock (T3CK) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **T2CKR<4:0>:** Assign Timer2 External Clock (T2CK) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0


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**REGISTER 10-4: RPINR7: PERIPHERAL PIN SELECT INPUT REGISTER 7**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | IC2R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | IC1R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **IC2R<4:0>:** Assign Input Capture 2 (IC2) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **IC1R<4:0>:** Assign Input Capture 1 (IC1) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-5: RPINR10: PERIPHERAL PIN SELECT INPUT REGISTER 10**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | IC8R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | IC7R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **IC8R<4:0>:** Assign Input Capture 8 (IC8) to the corresponding pin RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **IC7R<4:0>:** Assign Input Capture 7 (IC7) to the corresponding pin RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0


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**REGISTER 10-6: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | OCFAR<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4-0 **OCFAR<4:0>:** Assign Output Capture A (OCFA) to the corresponding RPn pin

11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-7: RPINR12: PERIPHERAL PIN SELECT INPUT REGISTER 12**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | FLTA1R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4-0 **FLTA1R<4:0>:** Assign PWM1 Fault ($\overline{\text{FLTA1}}$) to the corresponding RPn pin

11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-8: RPINR13: PERIPHERAL PIN SELECT INPUT REGISTER 13**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | FLTA2R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4-0 **FLTA2R<4:0>:** Assign PWM2 Fault ($\overline{\text{FLTA2}}$) to the corresponding RPn pin

11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0


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**REGISTER 10-9: RPINR14: PERIPHERAL PIN SELECT INPUT REGISTER 14**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | QEB1R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | QEA1R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **QEB1R<4:0>:** Assign B (QEB) to the corresponding pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **QEA1R<4:0>:** Assign A (QEA) to the corresponding pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-10: RPINR15: PERIPHERAL PIN SELECT INPUT REGISTER 15**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | INDX1R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4-0 **INDX1R<4:0>:** Assign QEI1 INDEX (INDX1) to the corresponding RPn pin

11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0


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**REGISTER 10-11: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | U1CTSR<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | U1RXR<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **U1CTSR<4:0>:** Assign UART1 Clear to Send ($\overline{\text{U1CTS}}$) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **U1RXR<4:0>:** Assign UART1 Receive (U1RX) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-12: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20**

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | SCK1R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | SDI1R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **SCK1R<4:0>:** Assign SPI1 Clock Input (SCK1IN) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **SDI1R<4:0>:** Assign SPI1 Data Input (SDI1) to the corresponding RPn pin
11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0


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**REGISTER 10-13: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | — | SS1R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-5 **Unimplemented:** Read as ‘0’

bit 4-0 **SS1R<4:0>:** Assign SPI1 Slave Select Input (SS1IN) to the corresponding RPn pin

11111 = Input tied Vss
01111 = Input tied to RP15
.
.
.
00001 = Input tied to RP1
00000 = Input tied to RP0

**REGISTER 10-14: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP1R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP0R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP1R<4:0>:** Peripheral Output Function is Assigned to RP1 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP0R<4:0>:** Peripheral Output Function is Assigned to RP0 Output Pin bits (see Table 10-2 for peripheral function numbers)

**REGISTER 10-15: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP3R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP2R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12-8 **RP3R<4:0>:** Peripheral Output Function is Assigned to RP3 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 **RP2R<4:0>:** Peripheral Output Function is Assigned to RP2 Output Pin bits (see Table 10-2 for peripheral function numbers)


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**REGISTER 10-16: RPOR2: PERIPHERAL PIN SELECT OUTPUT REGISTER 2**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP5R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP4R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as ‘0’

bit 12-8 **RP5R<4:0>:** Peripheral Output Function is Assigned to RP5 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **RP4R<4:0>:** Peripheral Output Function is Assigned to RP4 Output Pin bits (see Table 10-2 for peripheral function numbers)

**REGISTER 10-17: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP7R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP6R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as ‘0’

bit 12-8 **RP7R<4:0>:** Peripheral Output Function is Assigned to RP7 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **RP6R<4:0>:** Peripheral Output Function is Assigned to RP6 Output Pin bits (see Table 10-2 for peripheral function numbers)

**REGISTER 10-18: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP9R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP8R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as ‘0’

bit 12-8 **RP9R<4:0>:** Peripheral Output Function is Assigned to RP9 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **RP8R<4:0>:** Peripheral Output Function is Assigned to RP8 Output Pin bits (see Table 10-2 for peripheral function numbers)

**REGISTER 10-19: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP11R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP10R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as ‘0’

bit 12-8 **RP11R<4:0>:** Peripheral Output Function is Assigned to RP11 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **RP10R<4:0>:** Peripheral Output Function is Assigned to RP10 Output Pin bits (see Table 10-2 for peripheral function numbers)


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**REGISTER 10-20: RPOR6: PERIPHERAL PIN SELECT OUTPUT REGISTER 6**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP13R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP12R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as ‘0’

bit 12-8 **RP13R<4:0>:** Peripheral Output Function is Assigned to RP13 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **RP12R<4:0>:** Peripheral Output Function is Assigned to RP12 Output Pin bits (see Table 10-2 for peripheral function numbers)

**REGISTER 10-21: RPOR7: PERIPHERAL PIN SELECT OUTPUT REGISTER 7**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP15R<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | RP14R<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as ‘0’

bit 12-8 **RP15R<4:0>:** Peripheral Output Function is Assigned to RP15 Output Pin bits (see Table 10-2 for peripheral function numbers)

bit 7-5 **Unimplemented:** Read as ‘0’

bit 4-0 **RP14R<4:0>:** Peripheral Output Function is Assigned to RP14 Output Pin bits (see Table 10-2 for peripheral function numbers)

**NOTES:**


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## 11.0 TIMER1

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 11. "Timers"** (DS70205) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Timer1 module is a 16-bit timer, which can serve as the time counter for the real-time clock, or operate as a free-running interval timer/counter. Timer1 can operate in three modes:

- 16-bit Timer
- 16-bit Synchronous Counter
- 16-bit Asynchronous Counter

Timer1 also supports these features:

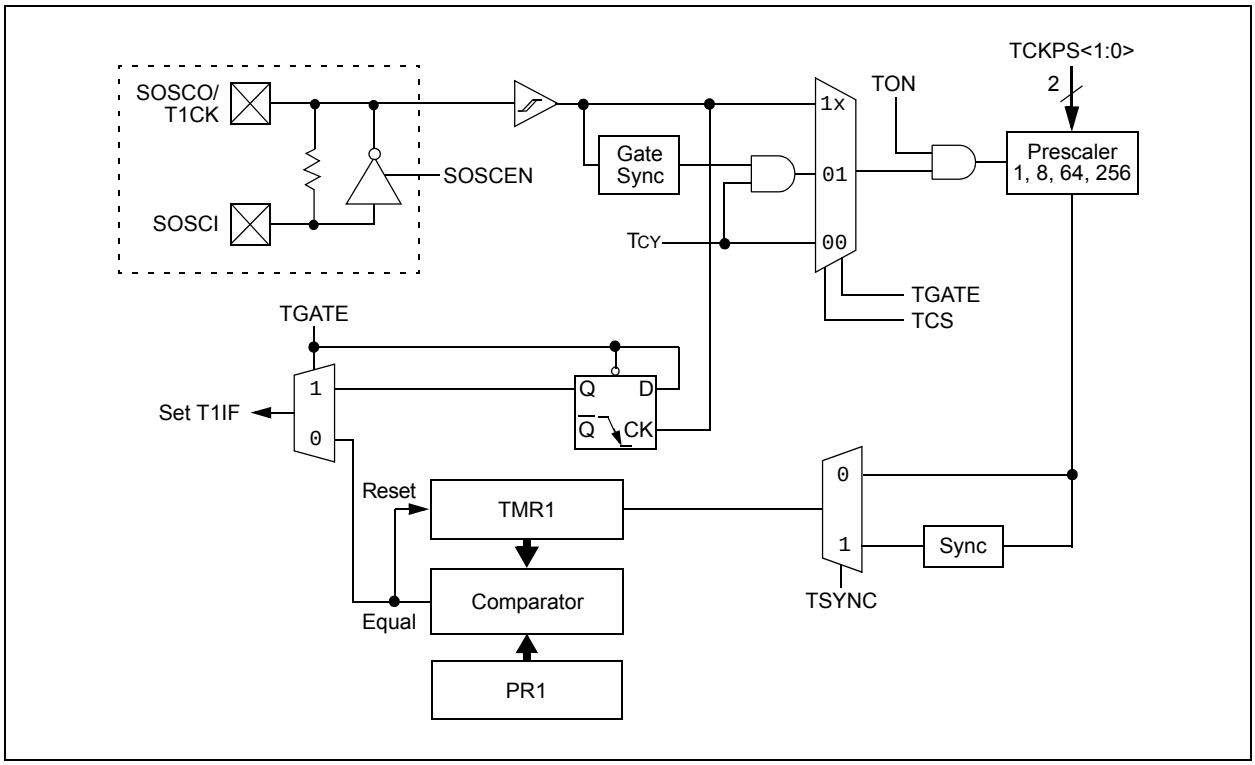
- Timer gate operation
- Selectable prescaler settings
- Timer operation during CPU Idle and Sleep modes
- Interrupt on 16-bit Period register match or falling edge of external gate signal

Figure 11-1 presents a block diagram of the 16-bit timer module.

To configure Timer1 for operation:

1. Set the TON bit (= 1) in the T1CON register.
2. Select the timer prescaler ratio using the TCKPS<1:0> bits in the T1CON register.
3. Set the Clock and Gating modes using the TCS and TGATE bits in the T1CON register.
4. Set or clear the TSYNC bit in T1CON to select synchronous or asynchronous operation.
5. Load the timer period value into the PR1 register.
6. If interrupts are required, set the interrupt enable bit, T1IE. Use the priority bits, T1IP<2:0>, to set the interrupt priority.

**FIGURE 11-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM**



**REGISTER 11-1: T1CON: TIMER1 CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| TON | — | TSIDL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | TGATE | TCKPS<1:0> | | — | TSYNC | TCS | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **TON:** Timer1 On bit
1 = Starts 16-bit Timer1
0 = Stops 16-bit Timer1

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timer1 Gated Time Accumulation Enable bit
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation enabled
0 = Gated time accumulation disabled

bit 5-4 **TCKPS<1:0>:** Timer1 Input Clock Prescale Select bits
11 = 1:256
10 = 1:64
01 = 1:8
00 = 1:1

bit 3 **Unimplemented:** Read as '0'

bit 2 **TSYNC:** Timer1 External Clock Input Synchronization Select bit
When TCS = 1:
1 = Synchronize external clock input
0 = Do not synchronize external clock input
When TCS = 0:
This bit is ignored.

bit 1 **TCS:** Timer1 Clock Source Select bit
1 = External clock from pin T1CK (on the rising edge)
0 = Internal clock (FCY)

bit 0 **Unimplemented:** Read as '0'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## 12.0 TIMER2/3 FEATURE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 11. "Timers"** (DS70205) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Timer2/3 feature has three 2-bit timers that can also be configured as two independent 16-bit timers with selectable operating modes.

As a 32-bit timer, the Timer2/3 feature permits operation in three modes:

- Two Independent 16-bit timers (e.g., Timer2 and Timer3) with all 16-bit operating modes (except Asynchronous Counter mode)
- Single 32-bit timer (Timer2/3)
- Single 32-bit synchronous counter (Timer2/3)

The Timer2/3 feature also supports:

- Timer gate operation
- Selectable prescaler settings
- Timer operation during Idle and Sleep modes
- Interrupt on a 32-bit period register match
- Time base for Input Capture and Output Compare modules (Timer2 and Timer3 only)
- ADC1 event trigger (Timer2/3 only)

Individually, all eight of the 16-bit timers can function as synchronous timers or counters. They also offer the features listed above, except for the event trigger. The operating modes and enabled features are determined by setting the appropriate bit(s) in the T2CON, T3CON registers. T2CON registers are shown in generic form in Register 12-1. T3CON registers are shown in Register 12-2.

For 32-bit timer/counter operation, Timer2 is the least significant word, and Timer3 is the msw of the 32-bit timers.

**Note:** For 32-bit operation, T3CON control bits are ignored. Only T2CON control bits are used for setup and control. Timer2 clock and gate inputs are used for the 32-bit timer modules, but an interrupt is generated with the Timer3 interrupt flags.

### 12.1 32-bit Operation

To configure the Timer2/3 feature timers for 32-bit operation:

1. Set the T32 control bit.
2. Select the prescaler ratio for Timer2 using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the corresponding TCS and TGATE bits.
4. Load the timer period value. PR3 contains the msw of the value, while PR2 contains the least significant word.
5. If interrupts are required, set the interrupt enable bit, T3IE. Use the priority bits, T3IP<2:0>, to set the interrupt priority. While Timer2 controls the timer, the interrupt appears as a Timer3 interrupt.
6. Set the corresponding TON bit.

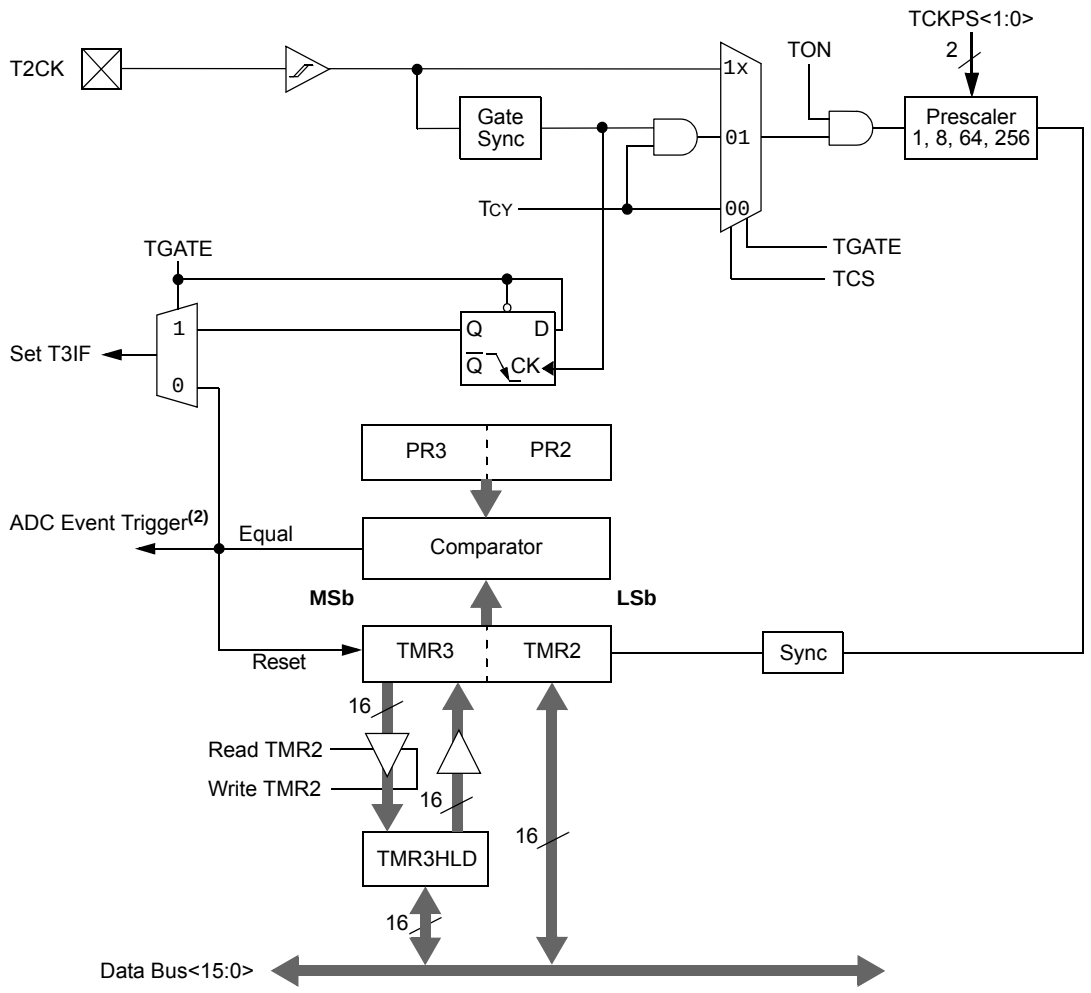
The timer value at any point is stored in the register pair, TMR3:TMR2, which always contains the msw of the count, while TMR2 contains the least significant word.

### 12.2 16-bit Operation

To configure any of the timers for individual 16-bit operation:

1. Clear the T32 bit corresponding to that timer.
2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
3. Set the Clock and Gating modes using the TCS and TGATE bits.
4. Load the timer period value into the PRx register.
5. If interrupts are required, set the interrupt enable bit, TxIE. Use the priority bits, TxIP<2:0>, to set the interrupt priority.
6. Set the TON bit.

**FIGURE 12-1: TIMER2/3 (32-BIT) BLOCK DIAGRAM(1)**




**Note 1:** The 32-bit timer control bit, T32, must be set for 32-bit timer/counter operation. All control bits are respective to the T2CON register.

**2:** The ADC event trigger is available only on Timer2/3.


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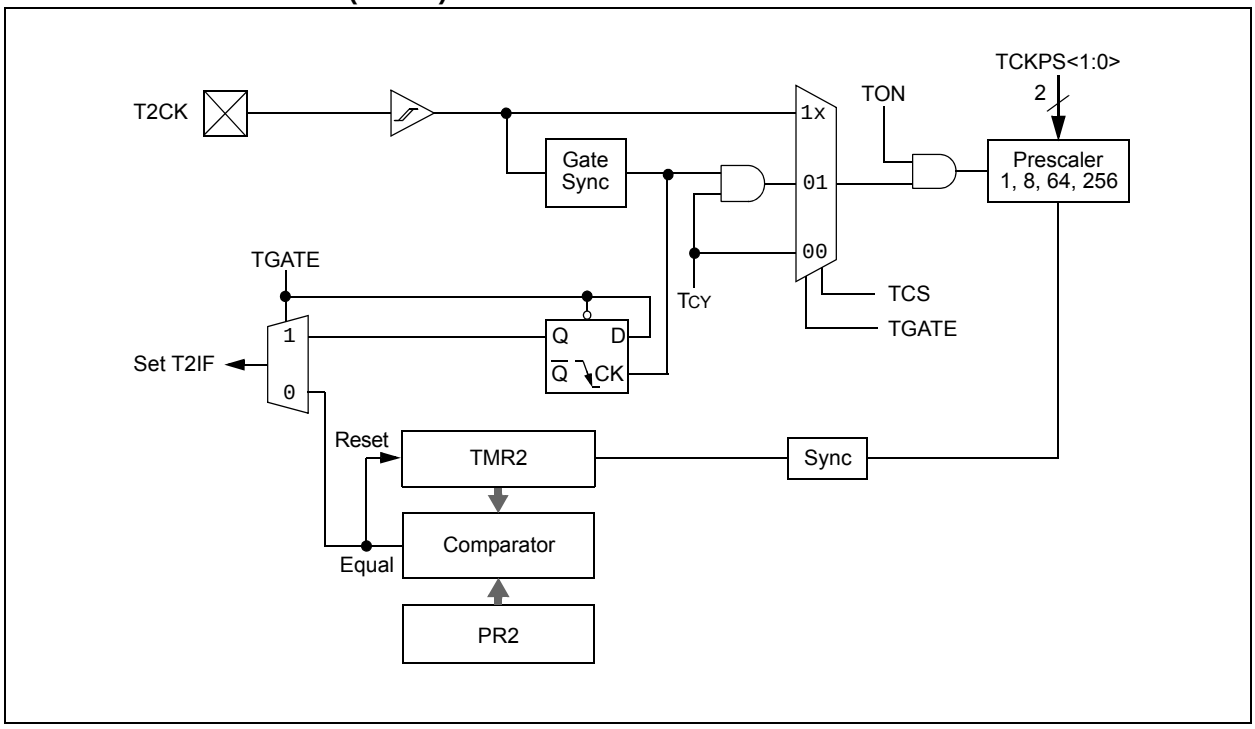
**FIGURE 12-2: TIMER2 (16-BIT) BLOCK DIAGRAM**



**REGISTER 12-1: T2CON CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| TON | — | TSIDL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | TGATE | TCKPS<1:0> | | T32 | — | TCS | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **TON:** Timer2 On bit
When T32 = 1:
1 = Starts 32-bit Timer2/3
0 = Stops 32-bit Timer2/3
When T32 = 0:
1 = Starts 16-bit Timer2
0 = Stops 16-bit Timer2

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timer2 Gated Time Accumulation Enable bit
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation enabled
0 = Gated time accumulation disabled

bit 5-4 **TCKPS<1:0>:** Timer2 Input Clock Prescale Select bits
11 = 1:256
10 = 1:64
01 = 1:8
00 = 1:1

bit 3 **T32:** 32-bit Timer Mode Select bit
1 = Timer2 and Timer3 form a single 32-bit timer
0 = Timer2 and Timer3 act as two 16-bit timers

bit 2 **Unimplemented:** Read as '0'

bit 1 **TCS:** Timer2 Clock Source Select bit
1 = External clock from pin T2CK (on the rising edge)
0 = Internal clock (FCY)

bit 0 **Unimplemented:** Read as '0'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**REGISTER 12-2: T3CON CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| TON(2) | — | TSIDL(1) | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | TGATE(2) | TCKPS<1:0>(2) | | — | — | TCS(2) | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **TON:** Timer3 On bit(2)
1 = Starts 16-bit Timer3
0 = Stops 16-bit Timer3

bit 14 **Unimplemented:** Read as '0'

bit 13 **TSIDL:** Stop in Idle Mode bit(1)
1 = Discontinue timer operation when device enters Idle mode
0 = Continue timer operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **TGATE:** Timer3 Gated Time Accumulation Enable bit(2)
When TCS = 1:
This bit is ignored.
When TCS = 0:
1 = Gated time accumulation enabled
0 = Gated time accumulation disabled

bit 5-4 **TCKPS<1:0>:** Timer3 Input Clock Prescale Select bits(2)
11 = 1:256 prescale value
10 = 1:64 prescale value
01 = 1:8 prescale value
00 = 1:1 prescale value

bit 3-2 **Unimplemented:** Read as '0'

bit 1 **TCS:** Timer3 Clock Source Select bit(2)
1 = External clock from T3CK pin
0 = Internal clock (FOSC/2)

bit 0 **Unimplemented:** Read as '0'

**Note 1:** When 32-bit timer operation is enabled (T32 = 1) in the Timer Control register (T2CON<3>), the TSIDL bit must be cleared to operate the 32-bit timer in Idle mode.

**2:** When the 32-bit timer operation is enabled (T32 = 1) in the Timer Control register (T2CON<3>), these bits have no effect.

**NOTES:**


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## 13.0 INPUT CAPTURE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 12. "Input Capture"** (DS70198) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Input Capture module is useful in applications requiring frequency (period) and pulse measurement. The dsPIC33FJ12MC201/202 devices support up to eight input capture channels.

The Input Capture module captures the 16-bit value of the selected Time Base register when an event occurs at the ICx pin. The events that cause a capture event are listed below in three categories:

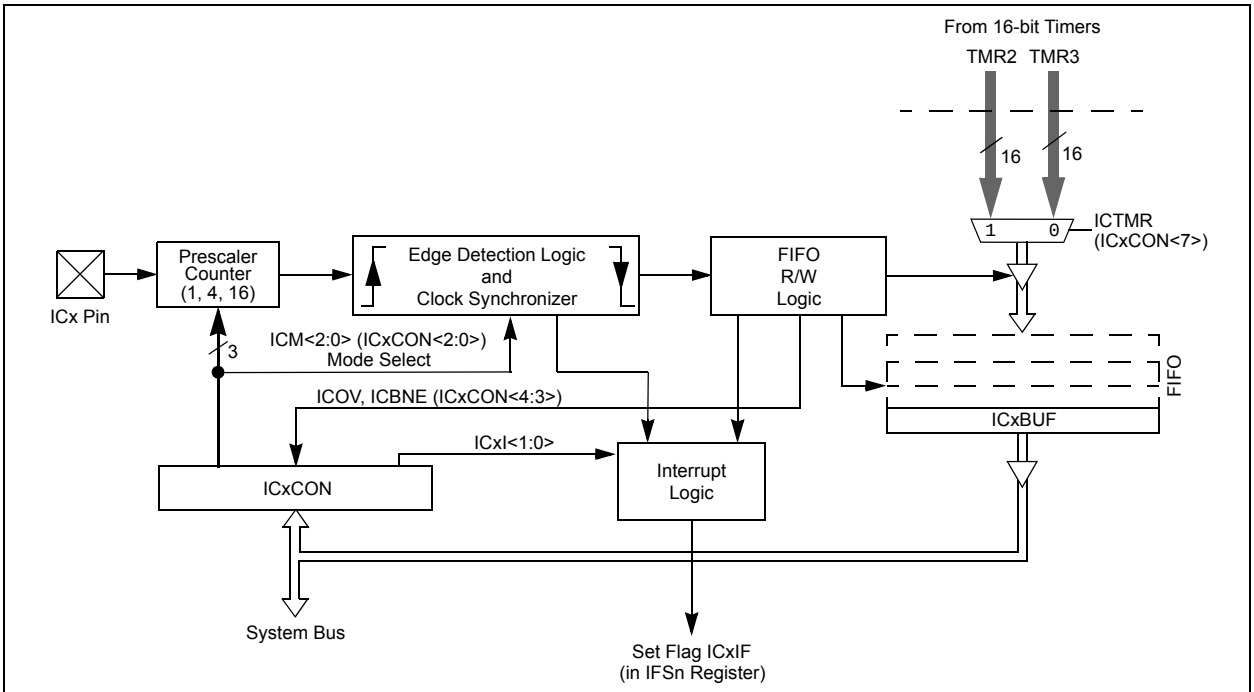
1. Simple Capture Event modes:
   - Capture timer value on every falling edge of input at ICx pin
   - Capture timer value on every rising edge of input at ICx pin
2. Capture timer value on every edge (rising and falling)
3. Prescaler Capture Event modes:
   - Capture timer value on every 4th rising edge of input at ICx pin
   - Capture timer value on every 16th rising edge of input at ICx pin

Each Input Capture channel can select one of two 16-bit timers (Timer2 or Timer3) for the time base. The selected timer can use either an internal or external clock.

Other operational features include:

- Device wake-up from capture pin during CPU Sleep and Idle modes
- Interrupt on Input Capture event
- 4-word FIFO buffer for capture values
  - Interrupt optionally generated after 1, 2, 3, or 4 buffer locations are filled
- Use of Input Capture to provide additional sources of external interrupts

**FIGURE 13-1: INPUT CAPTURE BLOCK DIAGRAM**




**Note:** An 'x' in a signal, register or bit name denotes the number of the capture channel.

## 13.1 Input Capture Registers

**REGISTER 13-1: ICxCON: INPUT CAPTURE x CONTROL REGISTER**

| U-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | ICSIDL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R-0, HC | R-0, HC | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| ICTMR | ICI<1:0> | | ICOV | ICBNE | ICM<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **ICSIDL:** Input Capture Module Stop in Idle Control bit
1 = Input capture module will halt in CPU Idle mode
0 = Input capture module will continue to operate in CPU Idle mode

bit 12-8 **Unimplemented:** Read as '0'

bit 7 **ICTMR:** Input Capture Timer Select bits
1 = TMR2 contents are captured on capture event
0 = TMR3 contents are captured on capture event

bit 6-5 **ICI<1:0>:** Select Number of Captures per Interrupt bits
11 = Interrupt on every fourth capture event
10 = Interrupt on every third capture event
01 = Interrupt on every second capture event
00 = Interrupt on every capture event

bit 4 **ICOV:** Input Capture Overflow Status Flag bit (read-only)
1 = Input capture overflow occurred
0 = No input capture overflow occurred

bit 3 **ICBNE:** Input Capture Buffer Empty Status bit (read-only)
1 = Input capture buffer is not empty, at least one more capture value can be read
0 = Input capture buffer is empty

bit 2-0 **ICM<2:0>:** Input Capture Mode Select bits
111 = Input capture functions as interrupt pin only when device is in Sleep or Idle mode
(Rising edge detect only, all other control bits are not applicable.)
110 = Unused (module disabled)
101 = Capture mode, every 16th rising edge
100 = Capture mode, every 4th rising edge
011 = Capture mode, every rising edge
010 = Capture mode, every falling edge
001 = Capture mode, every edge (rising and falling)
(ICI<1:0> bits do not control interrupt generation for this mode.)
000 = Input capture module turned off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## 14.0 OUTPUT COMPARE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 13. "Output Compare"** (DS70209) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip web-site (www.microchip.com).

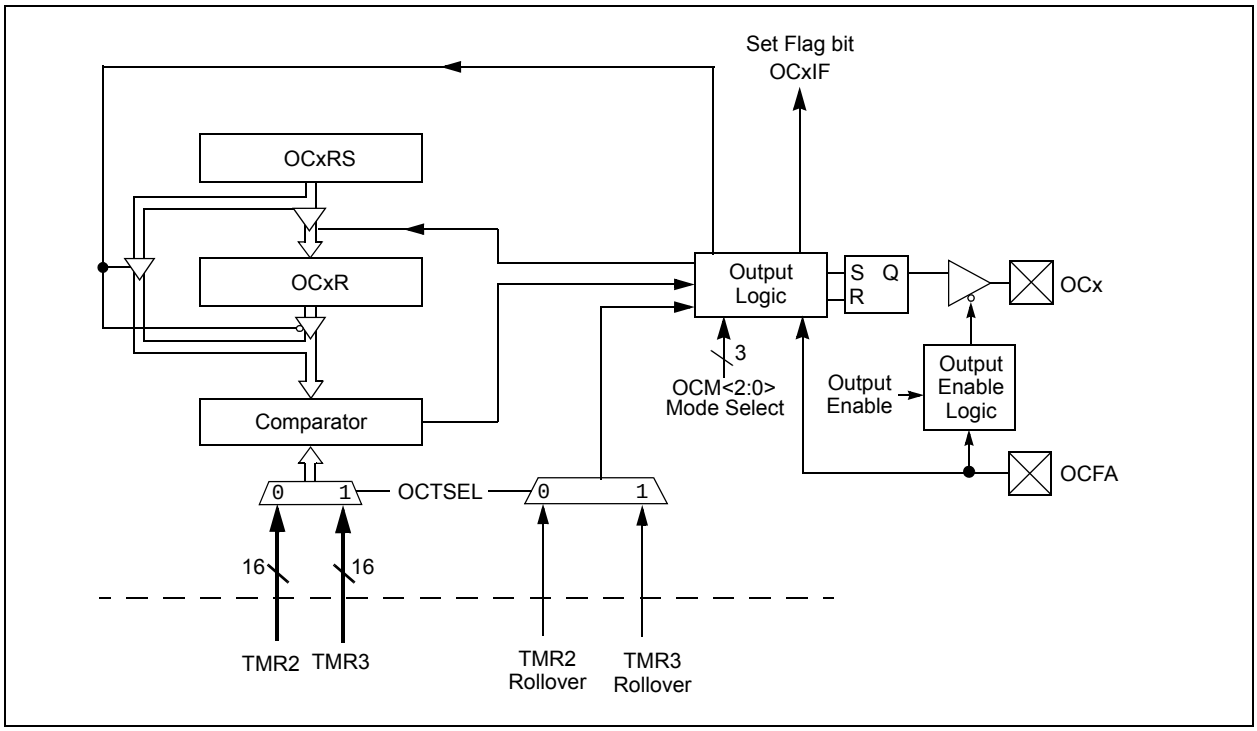
**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Output Compare module can select either Timer2 or Timer3 for its time base. The module compares the value of the timer with the value of one or two compare registers depending on the operating mode selected. The state of the output pin changes when the timer value matches the compare register value. The Output Compare module generates either a single output pulse or a sequence of output pulses, by changing the state of the output pin on the compare match events. The Output Compare module can also generate interrupts on compare match events.

The Output Compare module has multiple operating modes:

- Active-Low One-Shot mode
- Active-High One-Shot mode
- Toggle mode
- Delayed One-Shot mode
- Continuous Pulse mode
- PWM mode without fault protection
- PWM mode with fault protection

**FIGURE 14-1: OUTPUT COMPARE MODULE BLOCK DIAGRAM**



## 14.1 Output Compare Modes

Configure the Output Compare modes by setting the appropriate Output Compare Mode (OCM<2:0>) bits in the Output Compare Control (OCxCON<2:0>) register. Table 14-1 lists the different bit settings for the Output Compare modes. Figure 14-2 illustrates the output compare operation for various modes. The user application must disable the associated timer when writing to the output compare control registers to avoid malfunctions.

| **Note:** | See **Section 13. "Output Compare"** in the *"dsPIC33F/PIC24H Family Reference Manual"* (DS70209) for OCxR and OCxRS register restrictions. |
|---|---|

**TABLE 14-1: OUTPUT COMPARE MODES**

| OCM<2:0> | Mode | OCx Pin Initial State | OCx Interrupt Generation |
|---|---|---|---|
| 000 | Module Disabled | Controlled by GPIO register | — |
| 001 | Active-Low One-Shot | 0 | OCx Rising edge |
| 010 | Active-High One-Shot | 1 | OCx Falling edge |
| 011 | Toggle Mode | Current output is maintained | OCx Rising and Falling edge |
| 100 | Delayed One-Shot | 0 | OCx Falling edge |
| 101 | Continuous Pulse mode | 0 | OCx Falling edge |
| 110 | PWM mode without fault protection | 0, if OCxR is zero<br>1, if OCxR is non-zero | No interrupt |
| 111 | PWM mode with fault protection | 0, if OCxR is zero<br>1, if OCxR is non-zero | OCFA Falling edge for OC1 to OC4 |


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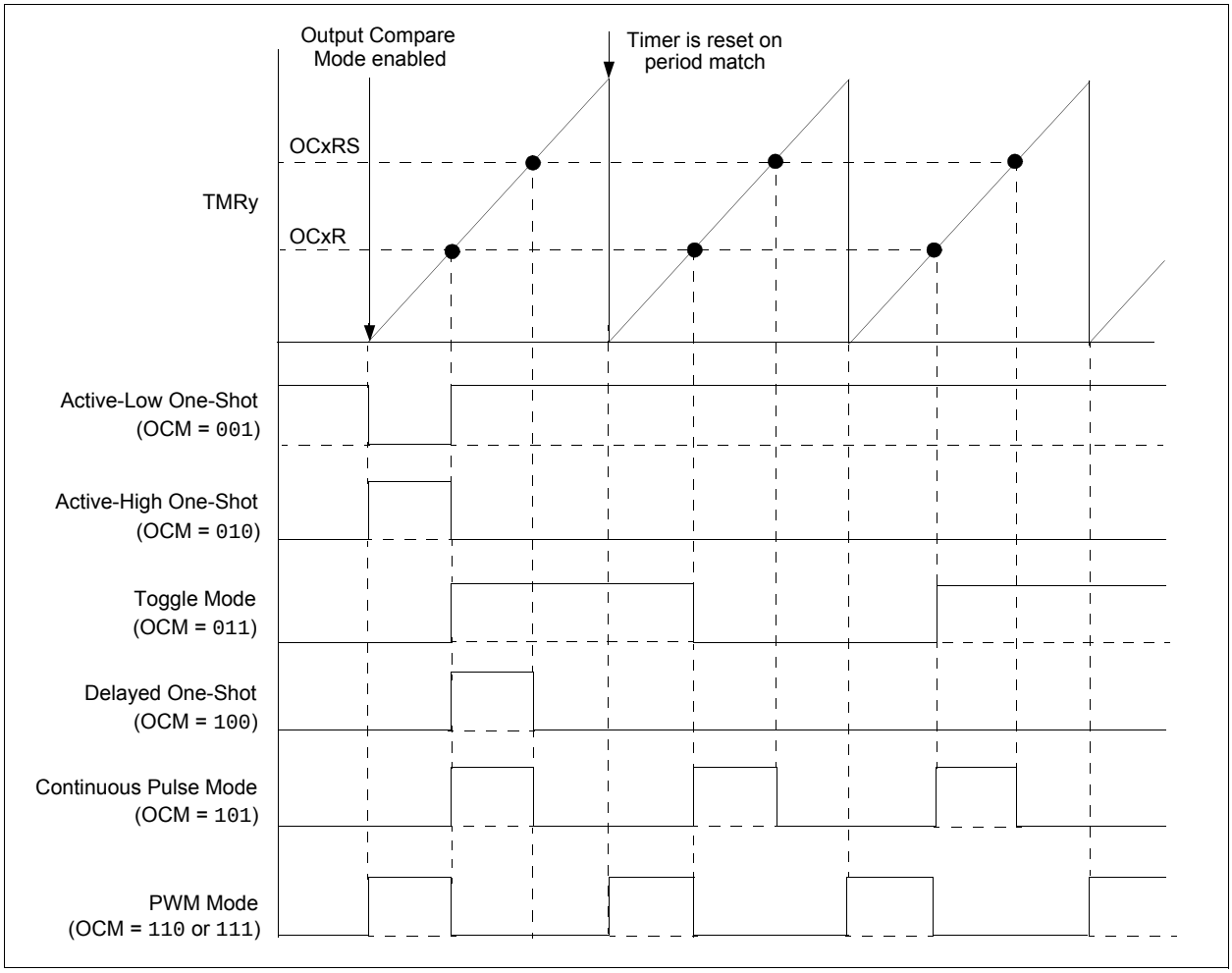
**FIGURE 14-2: OUTPUT COMPARE OPERATION**



**REGISTER 14-1: OCxCON: OUTPUT COMPARE x CONTROL REGISTER**

| U-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | OCSIDL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | R-0 HC | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | OCFLT | OCTSEL | OCM<2:0> | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | HC = Cleared in Hardware | HS = Set in Hardware | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13 **OCSIDL:** Stop Output Compare in Idle Mode Control bit
1 = Output Compare x will halt in CPU Idle mode
0 = Output Compare x will continue to operate in CPU Idle mode

bit 12-5 **Unimplemented:** Read as '0'

bit 4 **OCFLT:** PWM Fault Condition Status bit
1 = PWM Fault condition has occurred (cleared in hardware only)
0 = No PWM Fault condition has occurred
(This bit is only used when OCM<2:0> = 111.)

bit 3 **OCTSEL:** Output Compare Timer Select bit
1 = Timer3 is the clock source for Compare x
0 = Timer2 is the clock source for Compare x

bit 2-0 **OCM<2:0>:** Output Compare Mode Select bits
111 = PWM mode on OCx, Fault pin enabled
110 = PWM mode on OCx, Fault pin disabled
101 = Initialize OCx pin low, generate continuous output pulses on OCx pin
100 = Initialize OCx pin low, generate single output pulse on OCx pin
011 = Compare event toggles OCx pin
010 = Initialize OCx pin high, compare event forces OCx pin low
001 = Initialize OCx pin low, compare event forces OCx pin high
000 = Output compare channel is disabled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## 15.0 MOTOR CONTROL PWM MODULE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 14. "Motor Control PWM"** (DS70187) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 device supports up to two dedicated Pulse Width Modulation (PWM) modules. The PWM1 module is a 6-channel PWM generator, and the PWM2 module is a 2-channel PWM generator.

The PWM module has the following features:

- Up to 16-bit resolution
- On-the-fly PWM frequency changes
- Edge-Aligned and Center-Aligned Output modes
- Single Pulse Generation mode
- Interrupt support for asymmetrical updates in Center-Aligned mode
- Output override control for Electrically Commutative Motor (ECM) operation or BLDC
- Special Event comparator for scheduling other peripheral events
- Fault pins to optionally drive each of the PWM output pins to a defined state
- Duty cycle updates configurable to be immediate or synchronized to the PWM time base

### 15.1 PWM1: 6-Channel PWM Module

This module simplifies the task of generating multiple synchronized PWM outputs. The following power and motion control applications are supported by the PWM module:

- 3-Phase AC Induction Motor
- Switched Reluctance (SR) Motor
- Brushless DC (BLDC) Motor
- Uninterruptible Power Supply (UPS)

This module contains three duty cycle generators, numbered 1 through 3. The module has six PWM output pins, numbered PWM1H1/PWM1L1 through PWM1H3/PWM1L3. The six I/O pins are grouped into high/low numbered pairs, denoted by the suffix H or L, respectively. For complementary loads, the low PWM pins are always the complement of the corresponding high I/O pin.

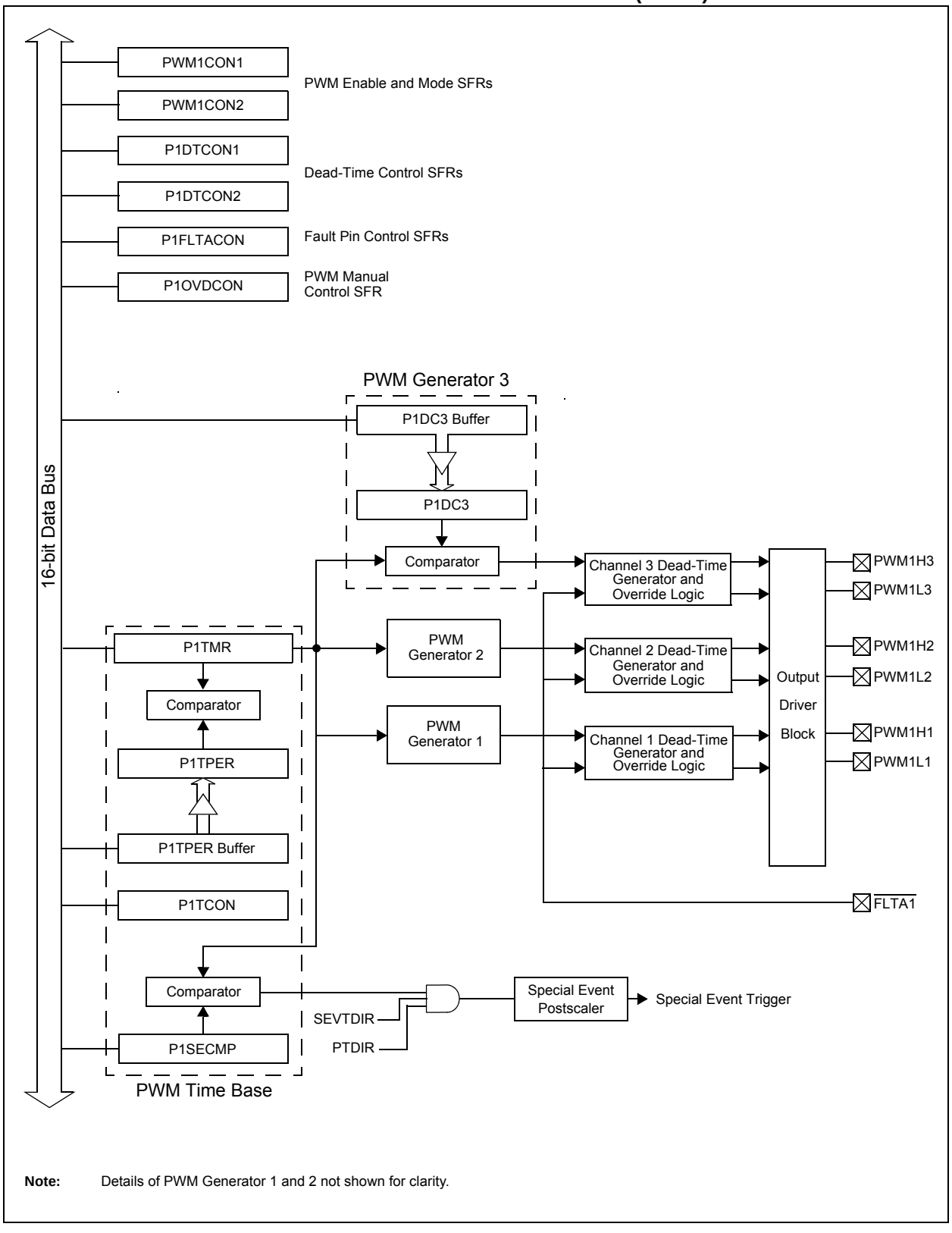
### 15.2 PWM2: 2-Channel PWM Module

This module provides an additional pair of complimentary PWM outputs that can be used for:

- Independent PFC correction in a motor system
- Induction cooking

This module contains a duty cycle generator that provides two PWM outputs, numbered PWM2H1/PWM2L1.

**FIGURE 15-1: 6-CHANNEL PWM MODULE BLOCK DIAGRAM (PWM1)**




**Note:** Details of PWM Generator 1 and 2 not shown for clarity.


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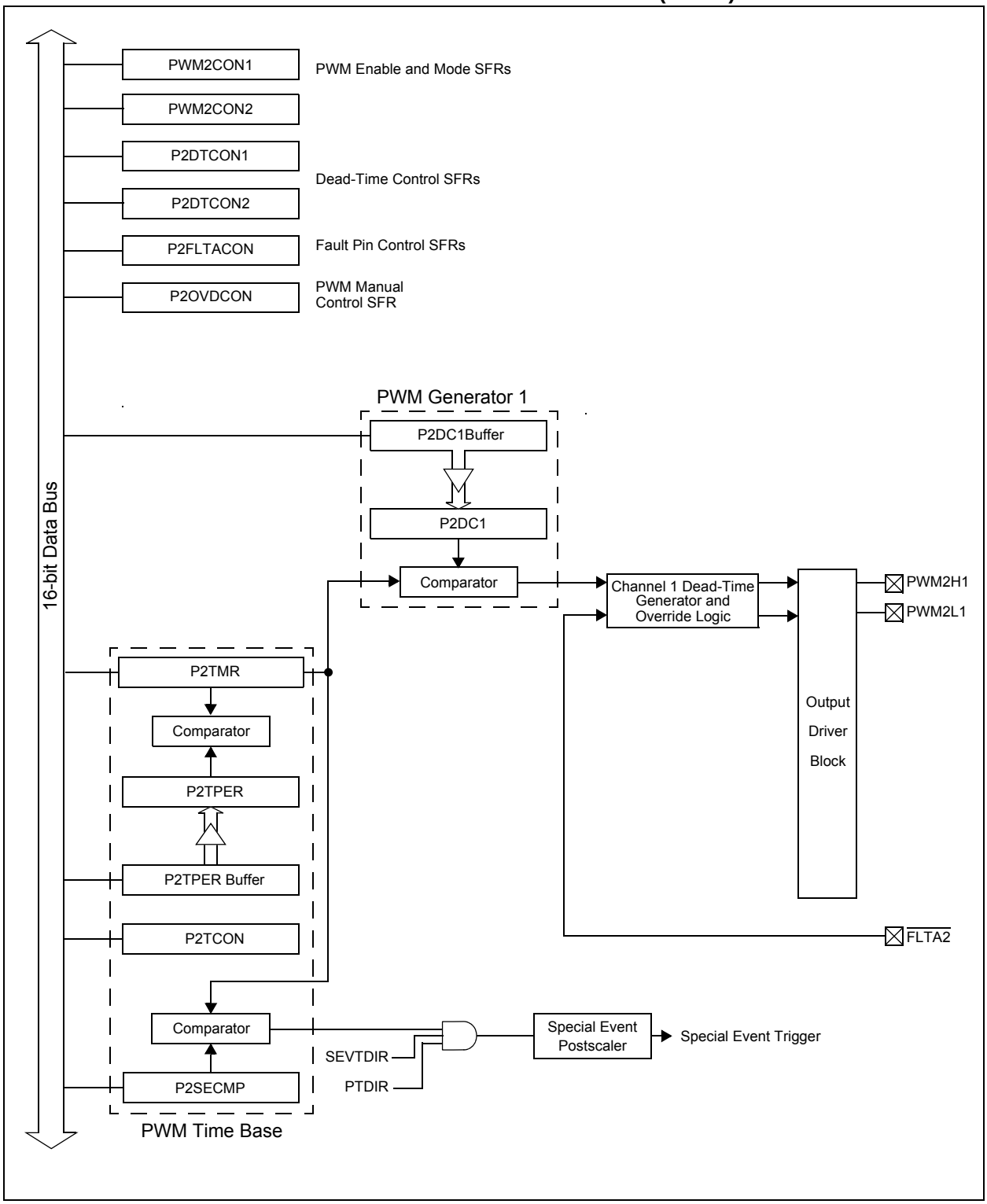
**FIGURE 15-2: 2-CHANNEL PWM MODULE BLOCK DIAGRAM (PWM2)**



**REGISTER 15-1: PxTCON: PWM TIME BASE CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| PTEN | — | PTSIDL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PTOPS<3:0> | | | | PTCKPS<1:0> | | PTMOD<1:0> | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **PTEN:** PWM Time Base Timer Enable bit
1 = PWM time base is on
0 = PWM time base is off

bit 14 **Unimplemented:** Read as ‘0’

bit 13 **PTSIDL:** PWM Time Base Stop in Idle Mode bit
1 = PWM time base halts in CPU Idle mode
0 = PWM time base runs in CPU Idle mode

bit 12-8 **Unimplemented:** Read as ‘0’

bit 7-4 **PTOPS<3:0>:** PWM Time Base Output Postscale Select bits
1111 = 1:16 postscale
•
•
•
0001 = 1:2 postscale
0000 = 1:1 postscale

bit 3-2 **PTCKPS<1:0>:** PWM Time Base Input Clock Prescale Select bits
11 = PWM time base input clock period is 64 TCY (1:64 prescale)
10 = PWM time base input clock period is 16 TCY (1:16 prescale)
01 = PWM time base input clock period is 4 TCY (1:4 prescale)
00 = PWM time base input clock period is TCY (1:1 prescale)

bit 1-0 **PTMOD<1:0>:** PWM Time Base Mode Select bits
11 = PWM time base operates in a Continuous Up/Down Count mode with interrupts for double PWM updates
10 = PWM time base operates in a Continuous Up/Down Count mode
01 = PWM time base operates in Single Pulse mode
00 = PWM time base operates in a Free-Running mode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**REGISTER 15-2: PxTMR: PWM TIMER COUNT VALUE REGISTER**

| R-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PTDIR | PTMR<14:8> | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PTMR<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **PTDIR:** PWM Time Base Count Direction Status bit (read-only)
1 = PWM time base is counting down
0 = PWM time base is counting up

bit 14-0 **PTMR <14:0>:** PWM Time Base Register Count Value bits

**REGISTER 15-3: PxTPER: PWM TIME BASE PERIOD REGISTER**

| U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | PTPER<14:8> | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PTPER<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **Unimplemented:** Read as ‘0’

bit 14-0 **PTPER<14:0>:** PWM Time Base Period Value bits

**REGISTER 15-4: PxSECMP: SPECIAL EVENT COMPARE REGISTER**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| SEVTDIR(1) | SEVTCMP<14:8>(2) | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| SEVTCMP<7:0>(2) | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15 **SEVTDIR:** Special Event Trigger Time Base Direction bit(1)
1 = A Special Event Trigger will occur when the PWM time base is counting down
0 = A Special Event Trigger will occur when the PWM time base is counting up

bit 14-0 **SEVTCMP<14:0>:** Special Event Compare Value bits(2)

**Note 1:** SEVTDIR is compared with PTDIR (PxTMR<15>) to generate the Special Event Trigger.
**2:** PxSECMP<14:0> is compared with PxTMR<14:0> to generate the Special Event Trigger.


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**REGISTER 15-5: PWMxCON1: PWM CONTROL REGISTER 1(2)**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | PMOD3 | PMOD2 | PMOD1 |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/W-1 | R/W-1 | R/W-1 | U-0 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | PEN3H(1) | PEN2H(1) | PEN1H(1) | — | PEN3L(1) | PEN2L(1) | PEN1L(1) |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as ‘0’

bit 10-8 **PMOD4:PMOD1:** PWM I/O Pair Mode bits
1 = PWM I/O pin pair is in the Independent PWM Output mode
0 = PWM I/O pin pair is in the Complementary Output mode

bit 7 **Unimplemented:** Read as ‘0’

bit 6-4 **PEN3H:PEN1H:** PWMxH I/O Enable bits(1)
1 = PWMxH pin is enabled for PWM output
0 = PWMxH pin disabled, I/O pin becomes general purpose I/O

bit 3 **Unimplemented:** Read as ‘0’

bit 2-0 **PEN3L:PEN1L:** PWMxL I/O Enable bits(1)
1 = PWMxL pin is enabled for PWM output
0 = PWMxL pin disabled, I/O pin becomes general purpose I/O

**Note 1:** Reset condition of the PENxH and PENxL bits depends on the value of the PWMPIN Configuration bit in the FPOR Configuration register.

**2:** PWM2 supports only one PWM I/O pin pair. PWM1 on dsPIC33FJ12MC201 devices supports only two PWM I/O pin pairs.

**REGISTER 15-6: PWMxCON2: PWM CONTROL REGISTER 2**

| U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | SEVOPS<3:0> | | | |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | IUE | OSYNC | UDIS |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-12 **Unimplemented:** Read as '0'

bit 11-8 **SEVOPS<3:0>:** PWM Special Event Trigger Output Postscale Select bits
1111 = 1:16 postscale
•
•
•
0001 = 1:2 postscale
0000 = 1:1 postscale

bit 7-3 **Unimplemented:** Read as '0'

bit 2 **IUE:** Immediate Update Enable bit
1 = Updates to the active PxDC registers are immediate
0 = Updates to the active PxDC registers are synchronized to the PWM time base

bit 1 **OSYNC:** Output Override Synchronization bit
1 = Output overrides via the PxOVDCON register are synchronized to the PWM time base
0 = Output overrides via the PxOVDCON register occur on next TCY boundary

bit 0 **UDIS:** PWM Update Disable bit
1 = Updates from Duty Cycle and Period Buffer registers are disabled
0 = Updates from Duty Cycle and Period Buffer registers are enabled


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**REGISTER 15-7: PxDTCON1: DEAD-TIME CONTROL REGISTER 1**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| DTBPS<1:0> | | DTB<5:0> | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| DTAPS<1:0> | | DTA<5:0> | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-14 **DTBPS<1:0>:** Dead-Time Unit B Prescale Select bits
11 = Clock period for Dead-Time Unit B is 8 TCY
10 = Clock period for Dead-Time Unit B is 4 TCY
01 = Clock period for Dead-Time Unit B is 2 TCY
00 = Clock period for Dead-Time Unit B is TCY

bit 13-8 **DTB<5:0>:** Unsigned 6-bit Dead-Time Value for Dead-Time Unit B bits

bit 7-6 **DTAPS<1:0>:** Dead-Time Unit A Prescale Select bits
11 = Clock period for Dead-Time Unit A is 8 TCY
10 = Clock period for Dead-Time Unit A is 4 TCY
01 = Clock period for Dead-Time Unit A is 2 TCY
00 = Clock period for Dead-Time Unit A is TCY

bit 5-0 **DTA<5:0>:** Unsigned 6-bit Dead-Time Value for Dead-Time Unit A bits

**REGISTER 15-8: PxDTCON2: DEAD-TIME CONTROL REGISTER 2(1)**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | DTS3A | DTS3I | DTS2A | DTS2I | DTS1A | DTS1I |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-6 **Unimplemented:** Read as '0'

bit 5 **DTS3A:** Dead-Time Select for PWM3 Signal Going Active bit
1 = Dead time provided from Unit B
0 = Dead time provided from Unit A

bit 4 **DTS3I:** Dead-Time Select for PWM3 Signal Going Inactive bit
1 = Dead time provided from Unit B
0 = Dead time provided from Unit A

bit 3 **DTS2A:** Dead-Time Select for PWM2 Signal Going Active bit
1 = Dead time provided from Unit B
0 = Dead time provided from Unit A

bit 2 **DTS2I:** Dead-Time Select for PWM2 Signal Going Inactive bit
1 = Dead time provided from Unit B
0 = Dead time provided from Unit A

bit 1 **DTS1A:** Dead-Time Select for PWM1 Signal Going Active bit
1 = Dead time provided from Unit B
0 = Dead time provided from Unit A

bit 0 **DTS1I:** Dead-Time Select for PWM1 Signal Going Inactive bit
1 = Dead time provided from Unit B
0 = Dead time provided from Unit A

**Note 1:** PWM2 supports only one PWM I/O pin pair.


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**REGISTER 15-9: PxFLTACON: FAULT A CONTROL REGISTER(1)**

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | FAOV3H | FAOV3L | FAOV2H | FAOV2L | FAOV1H | FAOV1L |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| FLTAM | — | — | — | — | FAEN3 | FAEN2 | FAEN1 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as ‘0’

bit 13-8 **FAOVxH<3:1>:FAOVxL<3:1>:** Fault Input A PWM Override Value bits
1 = The PWM output pin is driven active on an external Fault input event
0 = The PWM output pin is driven inactive on an external Fault input event

bit 7 **FLTAM:** Fault A Mode bit
1 = The Fault A input pin functions in the Cycle-by-Cycle mode
0 = The Fault A input pin latches all control pins to the programmed states in PxFLTACON<13:8>

bit 6-3 **Unimplemented:** Read as ‘0’

bit 2 **FAEN3:** Fault Input A Enable bit
1 = PWMxH3/PWMxL3 pin pair is controlled by Fault Input A
0 = PWMxH3/PWMxL3 pin pair is not controlled by Fault Input A

bit 1 **FAEN2:** Fault Input A Enable bit
1 = PWMxH2/PWMxL2 pin pair is controlled by Fault Input A
0 = PWMxH2/PWMxL2 pin pair is not controlled by Fault Input A

bit 0 **FAEN1:** Fault Input A Enable bit
1 = PWMxH1/PWMxL1 pin pair is controlled by Fault Input A
0 = PWMxH1/PWMxL1 pin pair is not controlled by Fault Input A

**Note 1:** PWM2 supports only one PWM I/O pin pair.

**REGISTER 15-10: PxOVDCON: OVERRIDE CONTROL REGISTER(1)**

| U-0 | U-0 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 | R/W-1 |
|---|---|---|---|---|---|---|---|
| — | — | POVD3H | POVD3L | POVD2H | POVD2L | POVD1H | POVD1L |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | POUT3H | POUT3L | POUT2H | POUT2L | POUT1H | POUT1L |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **POVDxH<3:1>:POVDxL<3:1>:** PWM Output Override bits
1 = Output on PWMx I/O pin is controlled by the PWM generator
0 = Output on PWMx I/O pin is controlled by the value in the corresponding POUTxH:POUTxL bit

bit 7-6 **Unimplemented:** Read as '0'

bit 5-0 **POUTxH<3:1>:POUTxL<3:1>:** PWM Manual Output bits
1 = PWMx I/O pin is driven active when the corresponding POVDxH:POVDxL bit is cleared
0 = PWMx I/O pin is driven inactive when the corresponding POVDxH:POVDxL bit is cleared

**Note 1:** PWM2 supports only one PWM I/O pin pair.


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**REGISTER 15-11: PxDC1: PWM DUTY CYCLE REGISTER 1**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PDC1<15:8> | | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PDC1<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-0 **PDC1<15:0>:** PWM Duty Cycle 1 Value bits

**REGISTER 15-12: P1DC2: PWM DUTY CYCLE REGISTER 2**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PDC2<15:8> | | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PDC2<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-0 **PDC2<15:0>:** PWM Duty Cycle 2 Value bits

**REGISTER 15-13: P1DC3: PWM DUTY CYCLE REGISTER 3**

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PDC3<15:8> | | | | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| PDC3<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-0 **PDC3<15:0>:** PWM Duty Cycle 3 Value bits

**NOTES:**


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## 16.0 QUADRATURE ENCODER INTERFACE (QEI) MODULE

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 15. "Quadrature Encoder Interface (QEI)"** (DS70208) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available from the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

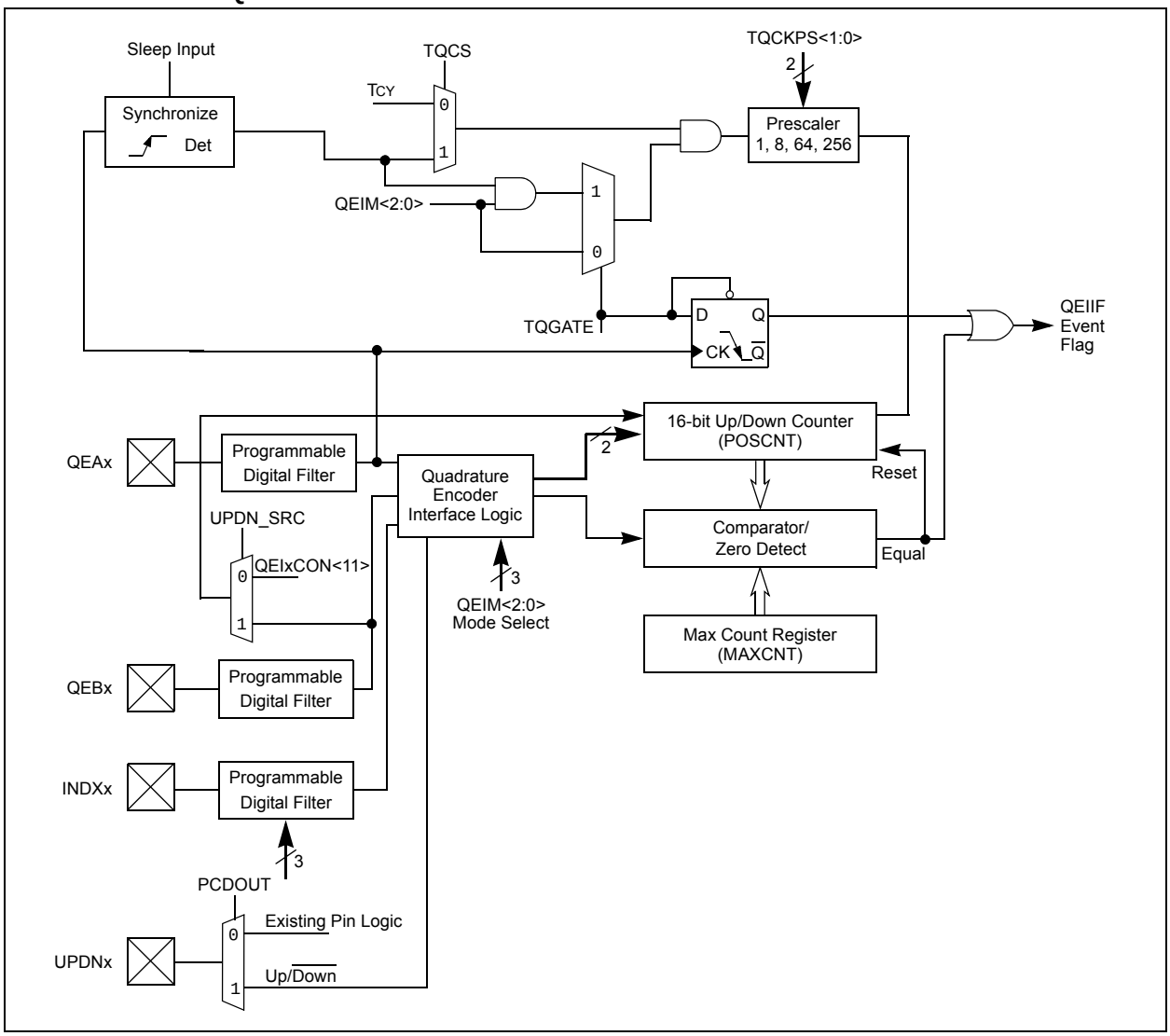
This section describes the Quadrature Encoder Interface (QEI) module and associated operational modes. The QEI module provides the interface to incremental encoders for obtaining mechanical position data.

The operational features of the QEI include:

- Three input channels for two phase signals and index pulse
- 16-bit up/down position counter
- Count direction status
- Position Measurement (x2 and x4) mode
- Programmable digital noise filters on inputs
- Alternate 16-bit Timer/Counter mode
- Quadrature Encoder Interface interrupts

These operating modes are determined by setting the appropriate bits, QEIM<2:0> in (QEIxCON<10:8>). Figure 16-1 depicts the Quadrature Encoder Interface block diagram.

**FIGURE 16-1: QUADRATURE ENCODER INTERFACE BLOCK DIAGRAM**



**REGISTER 16-1: QEIxCON: QEI CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | R-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| CNTERR | — | QEISIDL | INDEX | UPDN | QEIM<2:0> | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| SWPAB | PCDOUT | TQGATE | TQCKPS<1:0> | | POSRES | TQCS | UPDN_SRC |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **CNTERR:** Count Error Status Flag bit
1 = Position count error has occurred
0 = No position count error has occurred

**Note:** CNTERR flag only applies when QEIM<2:0> = '110' or '100'.

bit 14 **Unimplemented:** Read as '0'

bit 13 **QEISIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12 **INDEX:** Index Pin State Status bit (Read-Only)
1 = Index pin is High
0 = Index pin is Low

bit 11 **UPDN:** Position Counter Direction Status bit
1 = Position Counter Direction is positive (+)
0 = Position Counter Direction is negative (-)
(Read-only bit when QEIM<2:0> = '1XX')
(Read/Write bit when QEIM<2:0> = '001')

bit 10-8 **QEIM<2:0>:** Quadrature Encoder Interface Mode Select bits
111 = Quadrature Encoder Interface enabled (x4 mode) with position counter reset by match (MAXCNT)
110 = Quadrature Encoder Interface enabled (x4 mode) with Index Pulse reset of position counter
101 = Quadrature Encoder Interface enabled (x2 mode) with position counter reset by match (MAXCNT)
100 = Quadrature Encoder Interface enabled (x2 mode) with Index Pulse reset of position counter
011 = Unused (Module disabled)
010 = Unused (Module disabled)
001 = Starts 16-bit Timer
000 = Quadrature Encoder Interface/Timer off

bit 7 **SWPAB:** Phase A and Phase B Input Swap Select bit
1 = Phase A and Phase B inputs swapped
0 = Phase A and Phase B inputs not swapped

bit 6 **PCDOUT:** Position Counter Direction State Output Enable bit
1 = Position Counter Direction Status Output Enable (QEI logic controls state of I/O pin)
0 = Position Counter Direction Status Output Disabled (Normal I/O pin operation)

bit 5 **TQGATE:** Timer Gated Time Accumulation Enable bit
1 = Timer gated time accumulation enabled
0 = Timer gated time accumulation disabled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**REGISTER 16-1: QEIxCON: QEI CONTROL REGISTER (CONTINUED)**

bit 4-3 **TQCKPS<1:0>:** Timer Input Clock Prescale Select bits
11 = 1:256 prescale value
10 = 1:64 prescale value
01 = 1:8 prescale value
00 = 1:1 prescale value
(Prescaler utilized for 16-bit Timer mode only)

bit 2 **POSRES:** Position Counter Reset Enable bit
1 = Index Pulse resets Position Counter
0 = Index Pulse does not reset Position Counter

**Note:** Bit applies only when QEIM<2:0> = 100 or 110.

bit 1 **TQCS:** Timer Clock Source Select bit
1 = External clock from pin QEA (on the rising edge)
0 = Internal clock (TCY)

bit 0 **UPDN_SRC:** Position Counter Direction Selection Control bit
1 = QEB pin state defines position counter direction
0 = Control/Status bit, UPDN (QEICON<11>), defines timer counter (POSCNT) direction

**Note:** When configured for QEI mode, control bit is a ‘don’t care’.

**REGISTER 16-2: DFLTxCON: DIGITAL FILTER CONTROL REGISTER**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | IMV<2:0> | | CEID |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|
| QEOUT | QECK<2:0> | — | — | — | — |
| bit 7 | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as '0'

bit 10-9 **IMV<1:0>:** Index Match Value bits – These bits allow the user application to specify the state of the QEA and QEB input pins during an Index pulse when the POSxCNT register is to be reset.
In x4 Quadrature Count Mode:
IMV1= Required State of Phase B input signal for match on index pulse
IMV0= Required State of Phase A input signal for match on index pulse
In x2 Quadrature Count Mode:
IMV1= Selects Phase input signal for Index state match (0 = Phase A, 1 = Phase B)
IMV0= Required state of the selected Phase input signal for match on index pulse

bit 8 **CEID:** Count Error Interrupt Disable bit
1 = Interrupts due to count errors are disabled
0 = Interrupts due to count errors are enabled

bit 7 **QEOUT:** QEA/QEB/INDX Pin Digital Filter Output Enable bit
1 = Digital filter outputs enabled
0 = Digital filter outputs disabled (normal pin operation)

bit 6-4 **QECK<2:0>:** QEA/QEB/INDX Digital Filter Clock Divide Select Bits
111 = 1:256 Clock Divide
110 = 1:128 Clock Divide
101 = 1:64 Clock Divide
100 = 1:32 Clock Divide
011 = 1:16 Clock Divide
010 = 1:4 Clock Divide
001 = 1:2 Clock Divide
000 = 1:1 Clock Divide

bit 3-0 **Unimplemented:** Read as '0'


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## 17.0 SERIAL PERIPHERAL INTERFACE (SPI)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 18. "Serial Peripheral Interface (SPI)"** (DS70206) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Serial Peripheral Interface (SPI) module is a synchronous serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices can be serial EEPROMs, shift registers, display drivers, analog-to-digital converters, etc. The SPI module is compatible with SPI and SIOP from Motorola®.

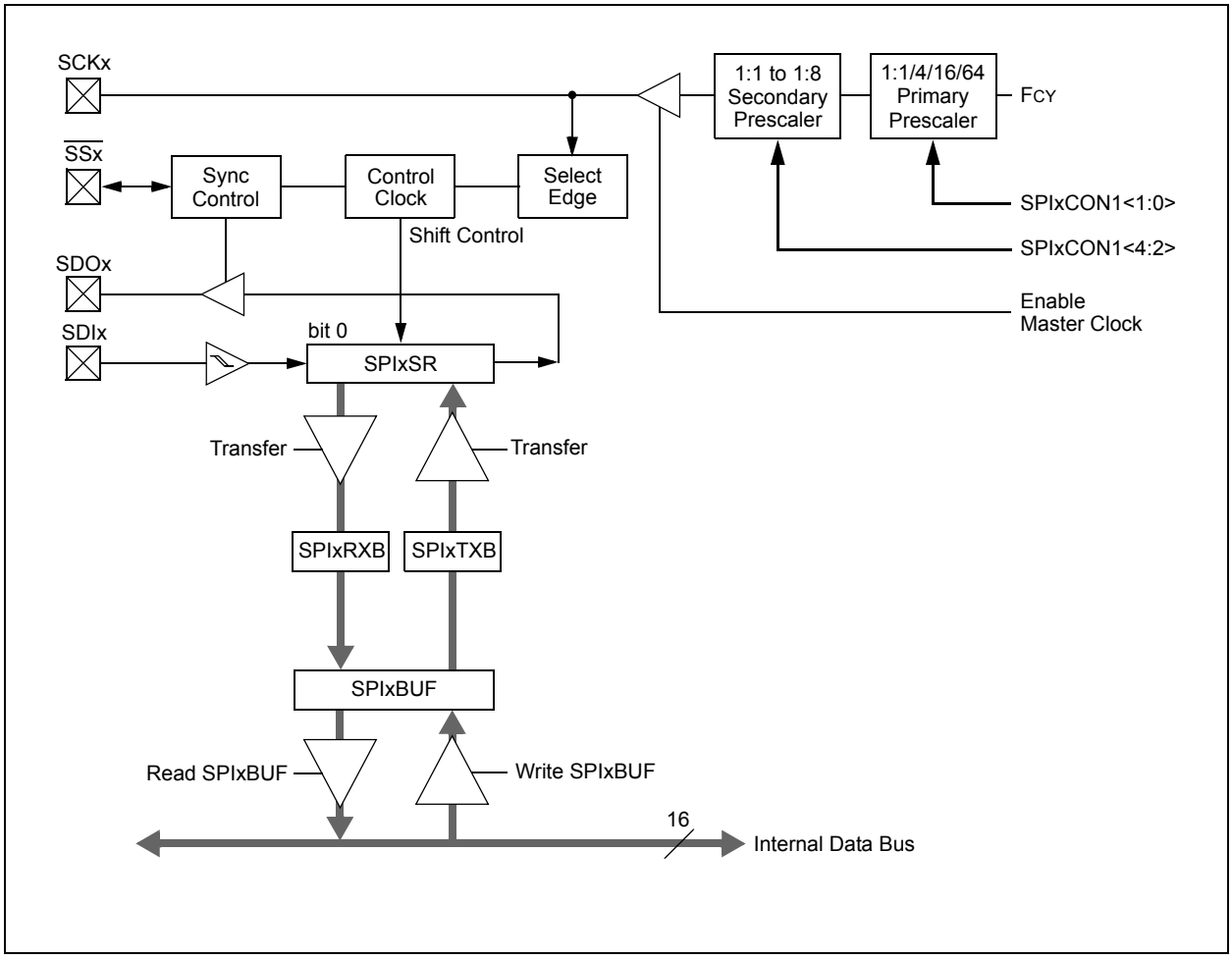
Each SPI module consists of a 16-bit shift register, SPIxSR (where x = 1 or 2), used for shifting data in and out, and a buffer register, SPIxBUF. A control register, SPIxCON, configures the module. Additionally, a status register, SPIxSTAT, indicates status conditions.

The serial interface consists of four pins:

- SDIx (serial data input)
- SDOx (serial data output)
- SCKx (shift clock input or output)
- $\overline{SSx}$ (active low slave select).

In Master mode operation, SCK is a clock output. In Slave mode, it is a clock input.

**FIGURE 17-1: SPI MODULE BLOCK DIAGRAM**



**REGISTER 17-1: SPIxSTAT: SPIx STATUS AND CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| SPIEN | — | SPISIDL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | R/C-0 | U-0 | U-0 | U-0 | U-0 | R-0 | R-0 |
|---|---|---|---|---|---|---|---|
| — | SPIROV | — | — | — | — | SPITBF | SPIRBF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | C = Clearable bit | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **SPIEN:** SPIx Enable bit
1 = Enables module and configures SCKx, SDOx, SDIx and $\overline{SS}$x as serial port pins
0 = Disables module

bit 14 **Unimplemented:** Read as '0'

bit 13 **SPISIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12-7 **Unimplemented:** Read as '0'

bit 6 **SPIROV:** Receive Overflow Flag bit
1 = A new byte/word is completely received and discarded. The user software has not read the previous data in the SPIxBUF register.
0 = No overflow has occurred.

bit 5-2 **Unimplemented:** Read as '0'

bit 1 **SPITBF:** SPIx Transmit Buffer Full Status bit
1 = Transmit not yet started, SPIxTXB is full
0 = Transmit started, SPIxTXB is empty
Automatically set in hardware when CPU writes SPIxBUF location, loading SPIxTXB
Automatically cleared in hardware when SPIx module transfers data from SPIxTXB to SPIxSR

bit 0 **SPIRBF:** SPIx Receive Buffer Full Status bit
1 = Receive complete, SPIxRXB is full
0 = Receive is not complete, SPIxRXB is empty
Automatically set in hardware when SPIx transfers data from SPIxSR to SPIxRXB
Automatically cleared in hardware when core reads SPIxBUF location, reading SPIxRXB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**REGISTER 17-2: SPIxCON1: SPIx CONTROL REGISTER 1**

| U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | DISSCK | DISSDO | MODE16 | SMP | CKE(1) |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| SSEN(2) | CKP | MSTEN | SPRE<2:0>(3) | | | PPRE<1:0>(3) | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **Unimplemented:** Read as '0'

bit 12 **DISSCK:** Disable SCKx pin bit (SPI Master modes only)
1 = Internal SPI clock is disabled, pin functions as I/O
0 = Internal SPI clock is enabled

bit 11 **DISSDO:** Disable SDOx pin bit
1 = SDOx pin is not used by module; pin functions as I/O
0 = SDOx pin is controlled by the module

bit 10 **MODE16:** Word/Byte Communication Select bit
1 = Communication is word-wide (16 bits)
0 = Communication is byte-wide (8 bits)

bit 9 **SMP:** SPIx Data Input Sample Phase bit
Master mode:
1 = Input data sampled at end of data output time
0 = Input data sampled at middle of data output time
Slave mode:
SMP must be cleared when SPIx is used in Slave mode.

bit 8 **CKE:** SPIx Clock Edge Select bit(1)
1 = Serial output data changes on transition from active clock state to Idle clock state (see bit 6)
0 = Serial output data changes on transition from Idle clock state to active clock state (see bit 6)

bit 7 **SSEN:** Slave Select Enable bit (Slave mode)(2)
1 = SSx pin used for Slave mode
0 = SSx pin not used by module. Pin controlled by port function.

bit 6 **CKP:** Clock Polarity Select bit
1 = Idle state for clock is a high level; active state is a low level
0 = Idle state for clock is a low level; active state is a high level

bit 5 **MSTEN:** Master Mode Enable bit
1 = Master mode
0 = Slave mode

**Note 1:** The CKE bit is not used in the Framed SPI modes. Program this bit to '0' for the Framed SPI modes (FRMEN = 1).

**2:** This bit must be cleared when FRMEN = 1.

**3:** Do not set both Primary and Secondary prescalers to a value of 1:1.

**REGISTER 17-2: SPIxCON1: SPIx CONTROL REGISTER 1 (CONTINUED)**

bit 4-2 **SPRE<2:0>:** Secondary Prescale bits (Master mode)(3)
111 = Secondary prescale 1:1
110 = Secondary prescale 2:1
.
.
.
000 = Secondary prescale 8:1

bit 1-0 **PPRE<1:0>:** Primary Prescale bits (Master mode)(3)
11 = Primary prescale 1:1
10 = Primary prescale 4:1
01 = Primary prescale 16:1
00 = Primary prescale 64:1

**Note 1:** The CKE bit is not used in the Framed SPI modes. Program this bit to '0' for the Framed SPI modes (FRMEN = 1).

**2:** This bit must be cleared when FRMEN = 1.

**3:** Do not set both Primary and Secondary prescalers to a value of 1:1.


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**REGISTER 17-3: SPIxCON2: SPIx CONTROL REGISTER 2**

| R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| FRMEN | SPIFSD | FRMPOL | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | FRMDLY | — |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **FRMEN:** Framed SPIx Support bit
1 = Framed SPIx support enabled ($\overline{SSx}$ pin used as frame sync pulse input/output)
0 = Framed SPIx support disabled

bit 14 **SPIFSD:** Frame Sync Pulse Direction Control bit
1 = Frame sync pulse input (slave)
0 = Frame sync pulse output (master)

bit 13 **FRMPOL:** Frame Sync Pulse Polarity bit
1 = Frame sync pulse is active-high
0 = Frame sync pulse is active-low

bit 12-2 **Unimplemented:** Read as '0'

bit 1 **FRMDLY:** Frame Sync Pulse Edge Select bit
1 = Frame sync pulse coincides with first bit clock
0 = Frame sync pulse precedes first bit clock

bit 0 **Unimplemented:** This bit must not be set to '1' by the user application.

**NOTES:**


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## 18.0 INTER-INTEGRATED CIRCUIT™ ($I^2C$™)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 19. "Inter-Integrated Circuit™ ($I^2C$™)"** (DS70195) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Inter-Integrated Circuit™ ($I^2C$™) module provides complete hardware support for both Slave and Multi-Master modes of the $I^2C$ serial communication standard, with a 16-bit interface.

The $I^2C$ module has a 2-pin interface:

- The SCLx pin is clock
- The SDAx pin is data

The $I^2C$ module offers the following key features:

- $I^2C$ interface supporting both Master and Slave modes of operation.
- $I^2C$ Slave mode supports 7-bit and 10-bit addresses
- $I^2C$ Master mode supports 7-bit and 10-bit addresses
- $I^2C$ port allows bidirectional transfers between master and slaves
- Serial clock synchronization for $I^2C$ port can be used as a handshake mechanism to suspend and resume serial transfer (SCLREL control)
- $I^2C$ supports multi-master operation, detects bus collision and arbitrates accordingly

### 18.1 Operating Modes

The hardware fully implements all the master and slave functions of the $I^2C$ Standard and Fast mode specifications, as well as 7-bit and 10-bit addressing.

The $I^2C$ module can operate either as a slave or a master on an $I^2C$ bus.

The following types of $I^2C$ operation are supported:

- $I^2C$ slave operation with 7-bit address
- $I^2C$ slave operation with 10-bit address
- $I^2C$ master operation with 7-bit or 10-bit address

For details about the communication sequence in each of these modes, refer to the Microchip web site (www.microchip.com) for the latest *"dsPIC33F/PIC24H Family Reference Manual"* sections.

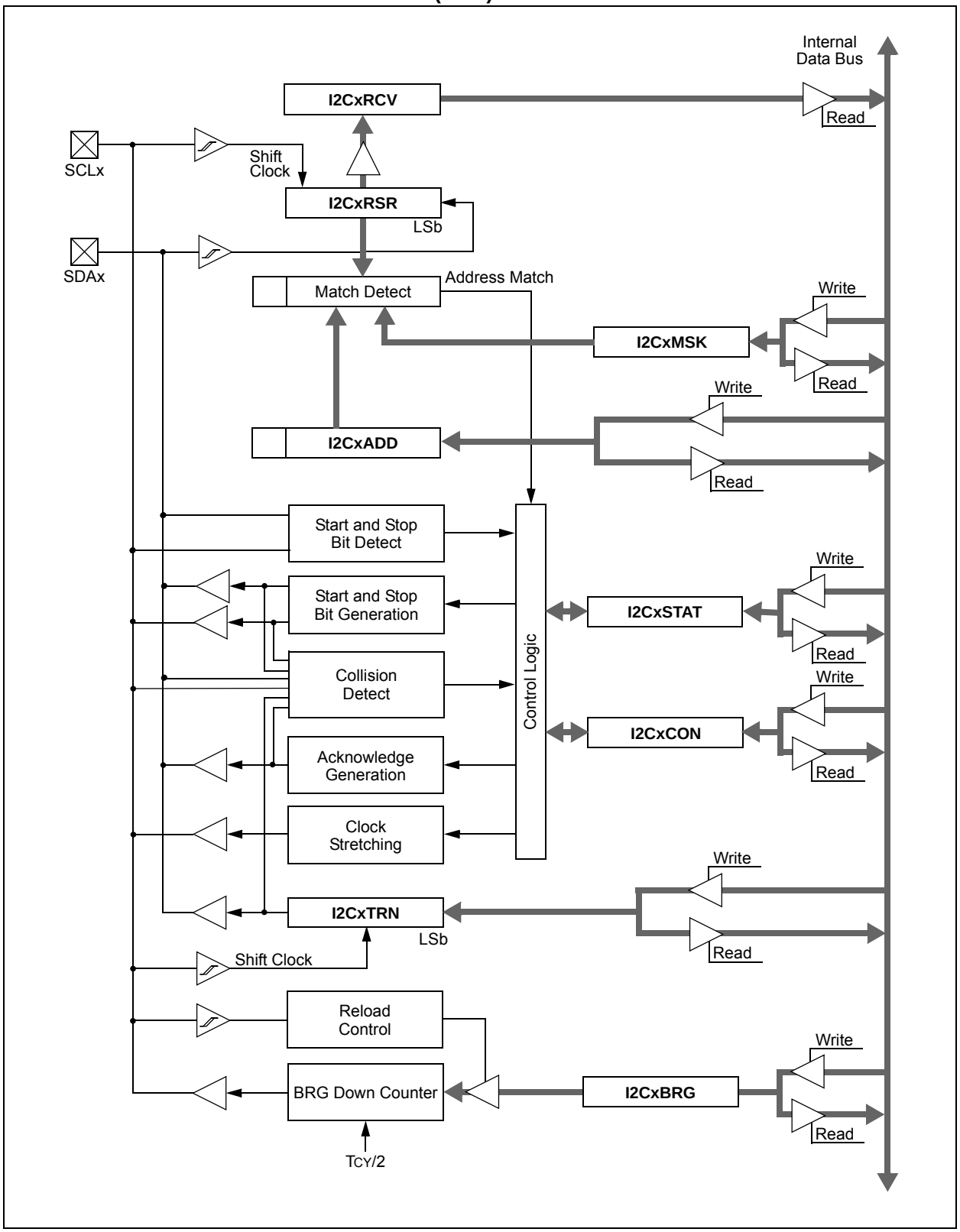
### 18.2 $I^2C$ Registers

I2CxCON and I2CxSTAT are control and status registers, respectively. The I2CxCON register is readable and writable. The lower six bits of I2CxSTAT are read-only. The remaining bits of the I2CSTAT are read/write:

- I2CxRSR is the shift register used for shifting data
- I2CxRCV is the receive buffer and the register to which data bytes are written, or from which data bytes are read
- I2CxTRN is the transmit register to which bytes are written during a transmit operation
- I2CxADD register holds the slave address
- ADD10 status bit indicates 10-bit Address mode
- I2CxBRG acts as the Baud Rate Generator (BRG) reload value

In receive operations, I2CxRSR and I2CxRCV together form a double-buffered receiver. When I2CxRSR receives a complete byte, it is transferred to I2CxRCV, and an interrupt pulse is generated.

**FIGURE 18-1: I²C™ BLOCK DIAGRAM (x = 1)**





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**REGISTER 18-1: I2CxCON: I2Cx CONTROL REGISTER**

| R/W-0 | U-0 | R/W-0 | R/W-1 HC | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| I2CEN | — | I2CSIDL | SCLREL | IPMIEN | A10M | DISSLW | SMEN |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 HC | R/W-0 HC | R/W-0 HC | R/W-0 HC | R/W-0 HC |
|---|---|---|---|---|---|---|---|
| GCEN | STREN | ACKDT | ACKEN | RCEN | PEN | RSEN | SEN |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | U = Unimplemented bit, read as '0' | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | HS = Set in hardware | HC = Cleared in hardware |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **I2CEN:** I2Cx Enable bit
1 = Enables the I2Cx module and configures the SDAx and SCLx pins as serial port pins
0 = Disables the I2Cx module. All $I^2C$ pins are controlled by port functions.

bit 14 **Unimplemented:** Read as '0'

bit 13 **I2CSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters an Idle mode
0 = Continue module operation in Idle mode

bit 12 **SCLREL:** SCLx Release Control bit (when operating as $I^2C$ slave)
1 = Release SCLx clock
0 = Hold SCLx clock low (clock stretch)
If STREN = 1:
Bit is R/W (i.e., software can write '0' to initiate stretch and write '1' to release clock). Hardware clear at beginning of slave transmission. Hardware clear at end of slave reception.
If STREN = 0:
Bit is R/S (i.e., software can only write '1' to release clock). Hardware clear at beginning of slave transmission.

bit 11 **IPMIEN:** Intelligent Peripheral Management Interface (IPMI) Enable bit
1 = IPMI mode is enabled; all addresses Acknowledged
0 = IPMI mode disabled

bit 10 **A10M:** 10-bit Slave Address bit
1 = I2CxADD is a 10-bit slave address
0 = I2CxADD is a 7-bit slave address

bit 9 **DISSLW:** Disable Slew Rate Control bit
1 = Slew rate control disabled
0 = Slew rate control enabled

bit 8 **SMEN:** SMBus Input Levels bit
1 = Enable I/O pin thresholds compliant with SMBus specification
0 = Disable SMBus input thresholds

bit 7 **GCEN:** General Call Enable bit (when operating as $I^2C$ slave)
1 = Enable interrupt when a general call address is received in the I2CxRSR
(module is enabled for reception)
0 = General call address disabled

bit 6 **STREN:** SCLx Clock Stretch Enable bit (when operating as $I^2C$ slave)
Used in conjunction with SCLREL bit.
1 = Enable software or receive clock stretching
0 = Disable software or receive clock stretching

**REGISTER 18-1: I2CxCON: I2Cx CONTROL REGISTER (CONTINUED)**

bit 5 **ACKDT:** Acknowledge Data bit (when operating as $I^2C$ master, applicable during master receive)
Value that will be transmitted when the software initiates an Acknowledge sequence.
1 = Send NACK during Acknowledge
0 = Send ACK during Acknowledge

bit 4 **ACKEN:** Acknowledge Sequence Enable bit
(when operating as $I^2C$ master, applicable during master receive)
1 = Initiate Acknowledge sequence on SDAx and SCLx pins and transmit ACKDT data bit. Hardware clear at end of master Acknowledge sequence.
0 = Acknowledge sequence not in progress

bit 3 **RCEN:** Receive Enable bit (when operating as $I^2C$ master)
1 = Enables Receive mode for $I^2C$. Hardware clear at end of eighth bit of master receive data byte.
0 = Receive sequence not in progress

bit 2 **PEN:** Stop Condition Enable bit (when operating as $I^2C$ master)
1 = Initiate Stop condition on SDAx and SCLx pins. Hardware clear at end of master Stop sequence.
0 = Stop condition not in progress

bit 1 **RSEN:** Repeated Start Condition Enable bit (when operating as $I^2C$ master)
1 = Initiate Repeated Start condition on SDAx and SCLx pins. Hardware clear at end of master Repeated Start sequence.
0 = Repeated Start condition not in progress

bit 0 **SEN:** Start Condition Enable bit (when operating as $I^2C$ master)
1 = Initiate Start condition on SDAx and SCLx pins. Hardware clear at end of master Start sequence.
0 = Start condition not in progress


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**REGISTER 18-2: I2CxSTAT: I2Cx STATUS REGISTER**

| R-0 HSC | R-0 HSC | U-0 | U-0 | U-0 | R/C-0 HS | R-0 HSC | R-0 HSC |
|---|---|---|---|---|---|---|---|
| ACKSTAT | TRSTAT | — | — | — | BCL | GCSTAT | ADD10 |
| bit 15 | | | | | | | bit 8 |

| R/C-0 HS | R/C-0 HS | R-0 HSC | R/C-0 HSC | R/C-0 HSC | R-0 HSC | R-0 HSC | R-0 HSC |
|---|---|---|---|---|---|---|---|
| IWCOL | I2COV | D_A | P | S | R_W | RBF | TBF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | U = Unimplemented bit, read as '0' | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | HS = Set in hardware | HSC = Hardware set/cleared |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **ACKSTAT:** Acknowledge Status bit
(when operating as $I^2C$ master, applicable to master transmit operation)
1 = NACK received from slave
0 = ACK received from slave
Hardware set or clear at end of slave Acknowledge.

bit 14 **TRSTAT:** Transmit Status bit (when operating as $I^2C$ master, applicable to master transmit operation)
1 = Master transmit is in progress (8 bits + ACK)
0 = Master transmit is not in progress
Hardware set at beginning of master transmission. Hardware clear at end of slave Acknowledge.

bit 13-11 **Unimplemented:** Read as '0'

bit 10 **BCL:** Master Bus Collision Detect bit
1 = A bus collision has been detected during a master operation
0 = No collision
Hardware set at detection of bus collision.

bit 9 **GCSTAT:** General Call Status bit
1 = General call address was received
0 = General call address was not received
Hardware set when address matches general call address. Hardware clear at Stop detection.

bit 8 **ADD10:** 10-bit Address Status bit
1 = 10-bit address was matched
0 = 10-bit address was not matched
Hardware set at match of 2nd byte of matched 10-bit address. Hardware clear at Stop detection.

bit 7 **IWCOL:** Write Collision Detect bit
1 = An attempt to write the I2CxTRN register failed because the $I^2C$ module is busy
0 = No collision
Hardware set at occurrence of write to I2CxTRN while busy (cleared by software).

bit 6 **I2COV:** Receive Overflow Flag bit
1 = A byte was received while the I2CxRCV register is still holding the previous byte
0 = No overflow
Hardware set at attempt to transfer I2CxRSR to I2CxRCV (cleared by software).

bit 5 **D_A:** Data/Address bit (when operating as $I^2C$ slave)
1 = Indicates that the last byte received was data
0 = Indicates that the last byte received was device address
Hardware clear at device address match. Hardware set by reception of slave byte.

bit 4 **P:** Stop bit
1 = Indicates that a Stop bit has been detected last
0 = Stop bit was not detected last
Hardware set or clear when Start, Repeated Start or Stop detected.

**REGISTER 18-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)**

bit 3 **S:** Start bit
1 = Indicates that a Start (or Repeated Start) bit has been detected last
0 = Start bit was not detected last
Hardware set or clear when Start, Repeated Start or Stop detected.

bit 2 **R_W:** Read/Write Information bit (when operating as $I^2C$ slave)
1 = Read – indicates data transfer is output from slave
0 = Write – indicates data transfer is input to slave
Hardware set or clear after reception of $I^2C$ device address byte.

bit 1 **RBF:** Receive Buffer Full Status bit
1 = Receive complete, I2CxRCV is full
0 = Receive not complete, I2CxRCV is empty
Hardware set when I2CxRCV is written with received byte. Hardware clear when software reads I2CxRCV.

bit 0 **TBF:** Transmit Buffer Full Status bit
1 = Transmit in progress, I2CxTRN is full
0 = Transmit complete, I2CxTRN is empty
Hardware set when software writes I2CxTRN. Hardware clear at completion of data transmission.


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**REGISTER 18-3: I2CxMSK: I2Cx SLAVE MODE ADDRESS MASK REGISTER**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | AMSK9 | AMSK8 |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| AMSK7 | AMSK6 | AMSK5 | AMSK4 | AMSK3 | AMSK2 | AMSK1 | AMSK0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ | |
| -n = Value at POR | ‘1’ = Bit is set | ‘0’ = Bit is cleared | x = Bit is unknown |

bit 15-10 **Unimplemented:** Read as ‘0’

bit 9-0 **AMSKx:** Mask for Address bit x Select bit

1 = Enable masking for bit x of incoming message address; bit match not required in this position

0 = Disable masking for bit x; bit match required in this position

**NOTES:**


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## 19.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 17. "UART"** (DS70188) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the dsPIC33FJ12MC201/202 device family. The UART is a full-duplex asynchronous system that can communicate with peripheral devices, such as personal computers, LIN, and RS-232, and RS-485 interfaces. The module also supports a hardware flow control option with the $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins and also includes an IrDA® encoder and decoder.

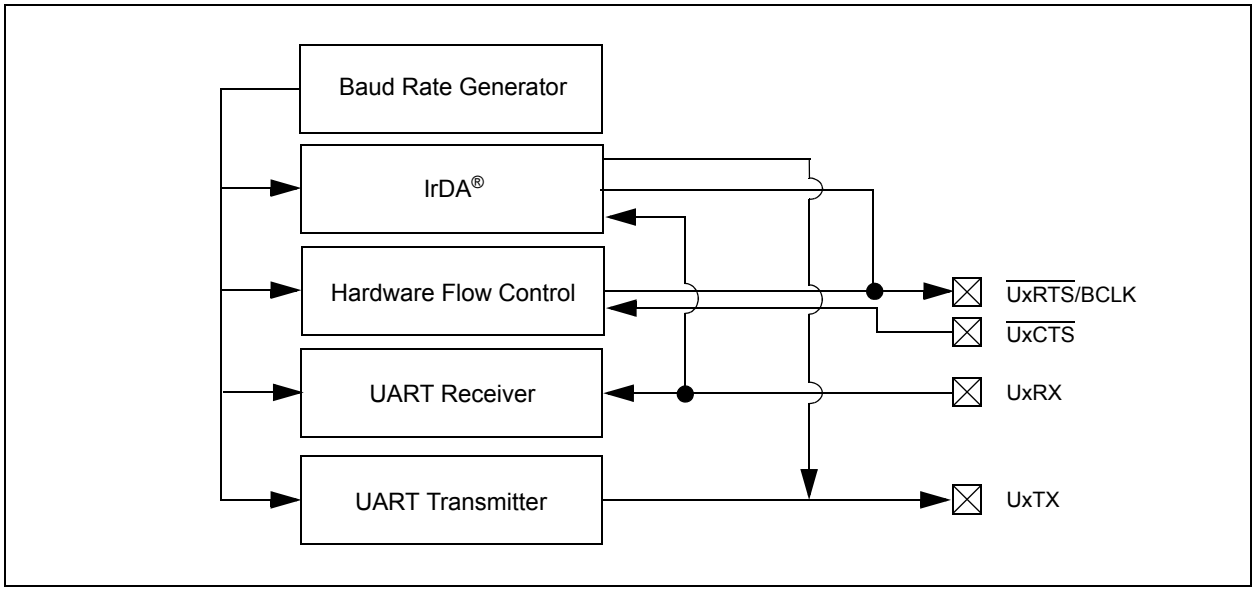
The primary features of the UART module are:

- Full-Duplex, 8-bit or 9-bit Data Transmission through the UxTX and UxRX pins
- Even, Odd, or No Parity Options (for 8-bit data)
- One or two stop bits
- Hardware flow control option with $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins
- Fully integrated Baud Rate Generator with 16-bit prescaler
- Baud rates ranging from 10 Mbps to 38 bps at 40 MIPS
- 4-deep First-In First-Out (FIFO) Transmit Data buffer
- 4-deep FIFO Receive Data buffer
- Parity, framing and buffer overrun error detection
- Support for 9-bit mode with Address Detect (9th bit = 1)
- Transmit and Receive interrupts
- A separate interrupt for all UART error conditions
- Loopback mode for diagnostic support
- Support for sync and break characters
- Support for automatic baud rate detection
- IrDA® encoder and decoder logic
- 16x baud clock output for IrDA® support

A simplified block diagram of the UART module is shown in Figure 19-1. The UART module consists of these key hardware elements:

- Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

**FIGURE 19-1: UART SIMPLIFIED BLOCK DIAGRAM**



**REGISTER 19-1: UxMODE: UARTx MODE REGISTER**

| R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| UARTEN(1) | — | USIDL | IREN(2) | RTSMD | — | UEN<1:0> | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 HC | R/W-0 | R/W-0 HC | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| WAKE | LPBACK | ABAUD | URXINV | BRGH | PDSEL<1:0> | | STSEL |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | HC = Hardware cleared | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **UARTEN:** UARTx Enable bit(1)
- 1 = UARTx is enabled; all UARTx pins are controlled by UARTx as defined by UEN<1:0>
- 0 = UARTx is disabled; all UARTx pins are controlled by port latches; UARTx power consumption minimal

bit 14 **Unimplemented:** Read as '0'

bit 13 **USIDL:** Stop in Idle Mode bit
- 1 = Discontinue module operation when device enters Idle mode
- 0 = Continue module operation in Idle mode

bit 12 **IREN:** IrDA® Encoder and Decoder Enable bit(2)
- 1 = IrDA encoder and decoder enabled
- 0 = IrDA encoder and decoder disabled

bit 11 **RTSMD:** Mode Selection for $\overline{\text{UxRTS}}$ Pin bit
- 1 = $\overline{\text{UxRTS}}$ pin in Simplex mode
- 0 = $\overline{\text{UxRTS}}$ pin in Flow Control mode

bit 10 **Unimplemented:** Read as '0'

bit 9-8 **UEN<1:0>:** UARTx Enable bits
- 11 = UxTX, UxRX and BCLK pins are enabled and used; $\overline{\text{UxCTS}}$ pin controlled by port latches
- 10 = UxTX, UxRX, $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ pins are enabled and used
- 01 = UxTX, UxRX and $\overline{\text{UxRTS}}$ pins are enabled and used; $\overline{\text{UxCTS}}$ pin controlled by port latches
- 00 = UxTX and UxRX pins are enabled and used; $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$/BCLK pins controlled by port latches

bit 7 **WAKE:** Wake-up on Start bit Detect During Sleep Mode Enable bit
- 1 = UARTx will continue to sample the UxRX pin; interrupt generated on falling edge; bit cleared in hardware on following rising edge
- 0 = No wake-up enabled

bit 6 **LPBACK:** UARTx Loopback Mode Select bit
- 1 = Enable Loopback mode
- 0 = Loopback mode is disabled

bit 5 **ABAUD:** Auto-Baud Enable bit
- 1 = Enable baud rate measurement on the next character – requires reception of a Sync field (55h) before other data; cleared in hardware upon completion
- 0 = Baud rate measurement disabled or completed

**Note 1:** Refer to **Section 17. "UART"** (DS70188) in the *"dsPIC33F/PIC24H Family Reference Manual"* for inormation on enabling the UART module for receive or transmit operation.

**2:** This feature is only available for the 16x BRG mode (BRGH = 0).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**REGISTER 19-1: UxMODE: UARTx MODE REGISTER (CONTINUED)**

bit 4 **URXINV:** Receive Polarity Inversion bit
1 = UxRX Idle state is '0'
0 = UxRX Idle state is '1'

bit 3 **BRGH:** High Baud Rate Enable bit
1 = BRG generates 4 clocks per bit period (4x baud clock, High-Speed mode)
0 = BRG generates 16 clocks per bit period (16x baud clock, Standard mode)

bit 2-1 **PDSEL<1:0>:** Parity and Data Selection bits
11 = 9-bit data, no parity
10 = 8-bit data, odd parity
01 = 8-bit data, even parity
00 = 8-bit data, no parity

bit 0 **STSEL:** Stop Bit Selection bit
1 = Two Stop bits
0 = One Stop bit

**Note 1:** Refer to **Section 17. "UART"** (DS70188) in the *"dsPIC33F/PIC24H Family Reference Manual"* for inormation on enabling the UART module for receive or transmit operation.
**2:** This feature is only available for the 16x BRG mode (BRGH = 0).

**REGISTER 19-2: UxSTA: UARTx STATUS AND CONTROL REGISTER**

| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 HC | R/W-0 | R-0 | R-1 |
|---|---|---|---|---|---|---|---|
| UTXISEL1 | UTXINV | UTXISEL0 | — | UTXBRK | UTXEN(1) | UTXBF | TRMT |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R-1 | R-0 | R-0 | R/C-0 | R-0 |
|---|---|---|---|---|---|---|---|
| URXISEL<1:0> | | ADDEN | RIDLE | PERR | FERR | OERR | URXDA |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | HC = Hardware cleared | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15,13 **UTXISEL<1:0>:** Transmission Interrupt Mode Selection bits
- 11 = Reserved; do not use
- 10 = Interrupt when a character is transferred to the Transmit Shift Register, and as a result, the transmit buffer becomes empty
- 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed
- 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)

bit 14 **UTXINV:** Transmit Polarity Inversion bit

If IREN = 0:
- 1 = UxTX Idle state is '0'
- 0 = UxTX Idle state is '1'

If IREN = 1:
- 1 = IrDA encoded UxTX Idle state is '1'
- 0 = IrDA encoded UxTX Idle state is '0'

bit 12 **Unimplemented:** Read as '0'

bit 11 **UTXBRK:** Transmit Break bit
- 1 = Send Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
- 0 = Sync Break transmission disabled or completed

bit 10 **UTXEN:** Transmit Enable bit(1)
- 1 = Transmit enabled, UxTX pin controlled by UARTx
- 0 = Transmit disabled, any pending transmission is aborted and buffer is reset. UxTX pin controlled by port.

bit 9 **UTXBF:** Transmit Buffer Full Status bit (read-only)
- 1 = Transmit buffer is full
- 0 = Transmit buffer is not full, at least one more character can be written

bit 8 **TRMT:** Transmit Shift Register Empty bit (read-only)
- 1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)
- 0 = Transmit Shift Register is not empty, a transmission is in progress or queued

bit 7-6 **URXISEL<1:0>:** Receive Interrupt Mode Selection bits
- 11 = Interrupt is set on UxRSR transfer making the receive buffer full (i.e., has 4 data characters)
- 10 = Interrupt is set on UxRSR transfer making the receive buffer 3/4 full (i.e., has 3 data characters)
- 0x = Interrupt is set when any character is received and transferred from the UxRSR to the receive buffer. Receive buffer has one or more characters.

**Note 1:** Refer to **Section 17. "UART"** (DS70188) in the *"dsPIC33F/PIC24H Family Reference Manual"* for information on enabling the UART module for transmit operation.


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**REGISTER 19-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)**

bit 5 **ADDEN:** Address Character Detect bit (bit 8 of received data = 1)
1 = Address Detect mode enabled. If 9-bit mode is not selected, this does not take effect
0 = Address Detect mode disabled

bit 4 **RIDLE:** Receiver Idle bit (read-only)
1 = Receiver is Idle
0 = Receiver is active

bit 3 **PERR:** Parity Error Status bit (read-only)
1 = Parity error has been detected for the current character (character at the top of the receive FIFO)
0 = Parity error has not been detected

bit 2 **FERR:** Framing Error Status bit (read-only)
1 = Framing error has been detected for the current character (character at the top of the receive FIFO)
0 = Framing error has not been detected

bit 1 **OERR:** Receive Buffer Overrun Error Status bit (read-only/clear-only)
1 = Receive buffer has overflowed
0 = Receive buffer has not overflowed. Clearing a previously set OERR bit (1 →0 transition) will reset the receiver buffer and the UxRSR to the empty state.

bit 0 **URXDA:** Receive Buffer Data Available bit (read-only)
1 = Receive buffer has data, at least one more character can be read
0 = Receive buffer is empty

**Note 1:** Refer to **Section 17. "UART"** (DS70188) in the *"dsPIC33F/PIC24H Family Reference Manual"* for information on enabling the UART module for transmit operation.

**NOTES:**


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## 20.0 10-BIT/12-BIT ANALOG-TO-DIGITAL CONVERTER (ADC)

**Note 1:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to **Section 16. "Analog-to-Digital Converter (ADC)"** (DS70183) of the *"dsPIC33F/PIC24H Family Reference Manual"*, which is available on the Microchip website (www.microchip.com).

**2:** Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 "Memory Organization"** in this data sheet for device-specific register and bit information.

The dsPIC33FJ12MC201/202 devices have up to six ADC module input channels.

The AD12B bit (ADxCON1<10>) allows each of the ADC modules to be configured as either a 10-bit, 4-sample-and-hold ADC (default configuration), or a 12-bit, 1 sample-and-hold ADC.

**Note:** The ADC module must be disabled before the AD12B bit can be modified.

### 20.1 Key Features

The 10-bit ADC configuration has the following key features:

- Successive Approximation (SAR) conversion
- Conversion speeds of up to 1.1 Msps
- Up to six analog input pins
- External voltage reference input pins
- Simultaneous sampling of up to four analog input pins
- Automatic Channel Scan mode
- Selectable conversion trigger source
- Selectable Buffer Fill modes
- Four result alignment options (signed/unsigned, fractional/integer)
- Operation during CPU Sleep and Idle modes
- 16-word conversion result buffer

The 12-bit ADC configuration supports all the above features, except:

- In the 12-bit configuration, conversion speeds of up to 500 ksps are supported
- There is only one sample-and-hold amplifier in the 12-bit configuration, so simultaneous sampling of multiple channels is not supported.

Depending on the particular device pinout, the ADC can have up to six analog input pins, designated AN0 through AN5. In addition, there are two analog input pins for external voltage reference connections. These voltage reference inputs can be shared with other analog input pins.

The actual number of analog input pins and external voltage reference input configuration will depend on the specific device.

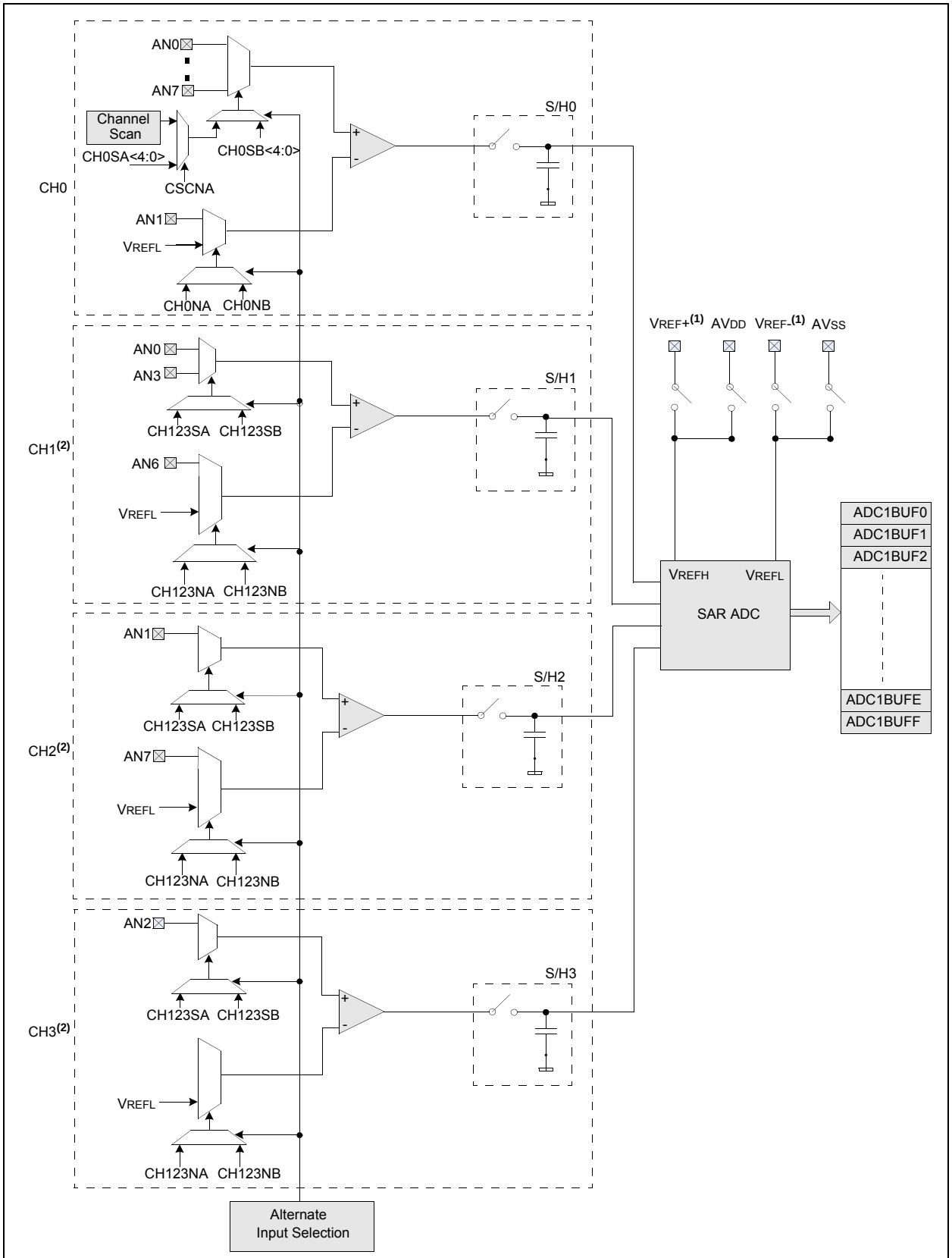
Block diagrams of the ADC module are shown in Figure 20-1 and Figure 20-2.

### 20.2 ADC Initialization

To configure the ADC module:

1. Select port pins as analog inputs (ADxPCFGH<15:0> or ADxPCFGL<15:0>).
2. Select voltage reference source to match expected range on analog inputs (ADxCON2<15:13>).
3. Select the analog conversion clock to match the desired data rate with the processor clock (ADxCON3<7:0>).
4. Determine how many sample-and-hold channels will be used (ADxCON2<9:8> and ADxPCFGH<15:0> or ADxPCFGL<15:0>).
5. Select the appropriate sample/conversion sequence (ADxCON1<7:5> and ADxCON3<12:8>).
6. Select the way conversion results are presented in the buffer (ADxCON1<9:8>).
7. Turn on the ADC module (ADxCON1<15>).
8. Configure ADC interrupt (if required):
   a) Clear the ADxIF bit.
   b) Select the ADC interrupt priority.

**FIGURE 20-1: ADC1 BLOCK DIAGRAM FOR dsPIC33FJ12MC201 DEVICES**




**Note 1:** VREF+, VREF- inputs can be multiplexed with other analog inputs.

**2:** Channels 1, 2, and 3 are not applicable for the 12-bit mode of operation.


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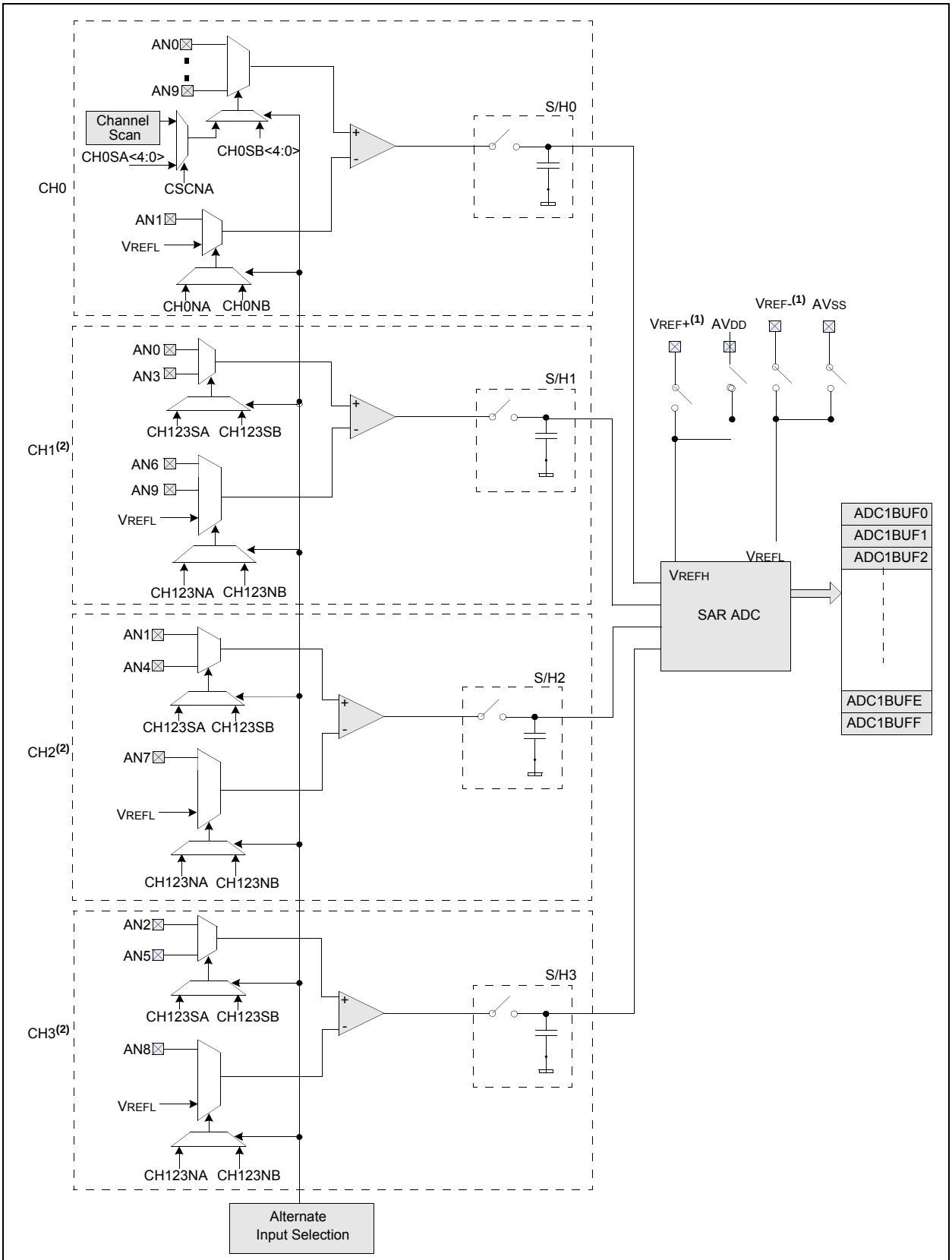
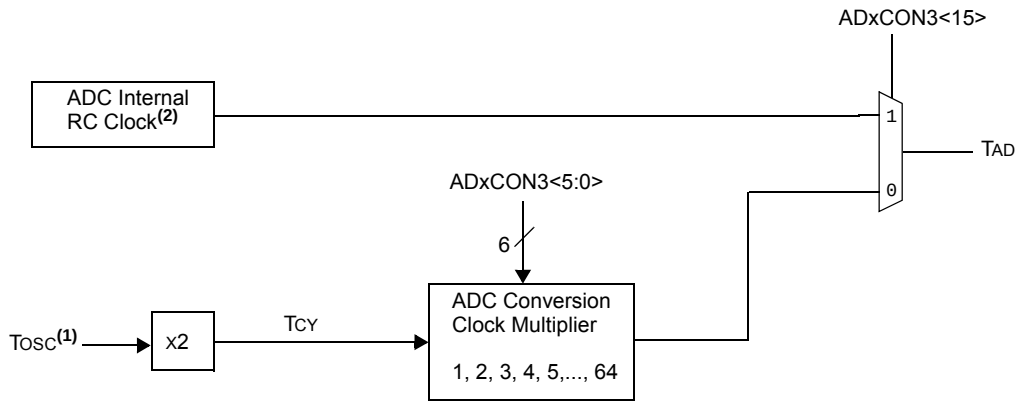
**FIGURE 20-2: ADC1 BLOCK DIAGRAM FOR dsPIC33FJ12MC202 DEVICES**




**Note 1:** VREF+, VREF- inputs can be multiplexed with other analog inputs.

**2:** Channels 1, 2, and 3 are not applicable for the 12-bit mode of operation.

**FIGURE 20-3: ADC CONVERSION CLOCK PERIOD BLOCK DIAGRAM**




**Note 1:** Refer to Figure 8-2 for the derivation of FOSC when the PLL is enabled. If the PLL is not used, FOSC is equal to the clock frequency. TOSC = 1/FOSC.

**2:** See the ADC Electrical Characteristics for the exact RC clock value.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**REGISTER 20-1: AD1CON1: ADC1 CONTROL REGISTER 1**

| R/W-0 | U-0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| ADON | — | ADSIDL | — | — | AD12B | FORM<1:0> | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | U-0 | R/W-0 | R/W-0 | R/W-0 HC,HS | R/C-0 HC, HS |
|---|---|---|---|---|---|---|---|
| SSRC<2:0> | | | — | SIMSAM | ASAM | SAMP | DONE |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | HC = Cleared by hardware | HS = Set by hardware | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **ADON:** ADC Operating Mode bit
1 = ADC module is operating
0 = ADC is off

bit 14 **Unimplemented:** Read as '0'

bit 13 **ADSIDL:** Stop in Idle Mode bit
1 = Discontinue module operation when device enters Idle mode
0 = Continue module operation in Idle mode

bit 12-11 **Unimplemented:** Read as '0'

bit 10 **AD12B:** 10-bit or 12-bit Operation Mode bit
1 = 12-bit, 1-channel ADC operation
0 = 10-bit, 4-channel ADC operation

bit 9-8 **FORM<1:0>:** Data Output Format bits
For 10-bit operation:
11 = Signed fractional (DOUT = sddd dddd dd00 0000, where s = .NOT.d<9>)
10 = Fractional (DOUT = dddd dddd dd00 0000)
01 = Signed integer (DOUT = ssss sssd dddd dddd, where s = .NOT.d<9>)
00 = Integer (DOUT = 0000 00dd dddd dddd)
For 12-bit operation:
11 = Signed fractional (DOUT = sddd dddd dddd 0000, where s = .NOT.d<11>)
10 = Fractional (DOUT = dddd dddd dddd 0000)
01 = Signed Integer (DOUT = ssss sddd dddd dddd, where s = .NOT.d<11>)
00 = Integer (DOUT = 0000 dddd dddd dddd)

bit 7-5 **SSRC<2:0>:** Sample Clock Source Select bits
111 = Internal counter ends sampling and starts conversion (auto-convert)
110 = Reserved
101 = Motor Control PWM2 interval ends sampling and starts conversion
100 = Reserved
011 = Motor Control PWM1 interval ends sampling and starts conversion
010 = GP timer 3 compare ends sampling and starts conversion
001 = Active transition on INT0 pin ends sampling and starts conversion
000 = Clearing sample bit ends sampling and starts conversion

bit 4 **Unimplemented:** Read as '0'

bit 3 **SIMSAM:** Simultaneous Sample Select bit (applicable only when CHPS<1:0> = 01 or 1x)
**When AD12B = 1, SIMSAM is: U-0, Unimplemented, Read as '0'**
1 = Samples CH0, CH1, CH2, CH3 simultaneously (when CHPS<1:0> = 1x); or
Samples CH0 and CH1 simultaneously (when CHPS<1:0> = 01)
0 = Samples multiple channels individually in sequence

**REGISTER 20-1: AD1CON1: ADC1 CONTROL REGISTER 1 (CONTINUED)**

bit 2 **ASAM:** ADC Sample Auto-Start bit

1 = Sampling begins immediately after last conversion. SAMP bit is auto-set.
0 = Sampling begins when SAMP bit is set

bit 1 **SAMP:** ADC Sample Enable bit

1 = ADC sample-and-hold amplifiers are sampling
0 = ADC sample-and-hold amplifiers are holding
If ASAM = 0, software can write '1' to begin sampling. Automatically set by hardware if ASAM = 1.
If SSRC = 000, software can write '0' to end sampling and start conversion. If SSRC ≠ 000, automatically cleared by hardware to end sampling and start conversion.

bit 0 **DONE:** ADC Conversion Status bit

1 = ADC conversion cycle is completed
0 = ADC conversion not started or in progress
Automatically set by hardware when ADC conversion is complete. Software can write '0' to clear DONE status (software not allowed to write '1'). Clearing this bit will NOT affect any operation in progress. Automatically cleared by hardware at start of a new conversion.


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**REGISTER 20-2: AD1CON2: ADC1 CONTROL REGISTER 2**

| R/W-0 | R/W-0 | R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| VCFG<2:0> | | | — | — | CSCNA | CHPS<1:0> | |
| bit 15 | | | | | | | bit 8 |

| R-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| BUFS | — | SMPI<3:0> | | | | BUFM | ALTS |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-13 **VCFG<2:0>:** Converter Voltage Reference Configuration bits

| | ADREF+ | ADREF- |
|---|---|---|
| 000 | AVDD | AVSS |
| 001 | External VREF+ | AVSS |
| 010 | AVDD | External VREF- |
| 011 | External VREF+ | External VREF- |
| 1xx | AVDD | AVSS |

bit 12-11 **Unimplemented:** Read as '0'

bit 10 **CSCNA:** Scan Input Selections for CH0+ during Sample A bit
1 = Scan inputs
0 = Do not scan inputs

bit 9-8 **CHPS<1:0>:** Select Channels Utilized bits
**When AD12B = 1, CHPS<1:0> is: U-0, Unimplemented, Read as '0'**
1x = Converts CH0, CH1, CH2 and CH3
01 = Converts CH0 and CH1
00 = Converts CH0

bit 7 **BUFS:** Buffer Fill Status bit (valid only when BUFM = 1)
1 = ADC is currently filling second half of buffer, user should access data in the first half
0 = ADC is currently filling first half of buffer, user application should access data in the second half

bit 6 **Unimplemented:** Read as '0'

bit 5-2 **SMPI<3:0>:** Sample/Convert Sequences Per Interrupt Selection bits
1111 = Interrupts at the completion of conversion for each 16th sample/convert sequence
1110 = Interrupts at the completion of conversion for each 15th sample/convert sequence
•
•
•
0001 = Interrupts at the completion of conversion for each 2nd sample/convert sequence
0000 = Interrupts at the completion of conversion for each sample/convert sequence

bit 1 **BUFM:** Buffer Fill Mode Select bit
1 = Starts filling first half of buffer on first interrupt and the second half of buffer on next interrupt
0 = Always starts filling buffer from the beginning

bit 0 **ALTS:** Alternate Input Sample Mode Select bit
1 = Uses channel input selects for Sample A on first sample and Sample B on next sample
0 = Always uses channel input selects for Sample A

**REGISTER 20-3: AD1CON3: ADC1 CONTROL REGISTER 3**

| R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| ADRC | — | — | SAMC<4:0>(1) | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| ADCS<7:0>(2) | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **ADRC:** ADC Conversion Clock Source bit
1 = ADC internal RC clock
0 = Clock derived from system clock

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **SAMC<4:0>:** Auto Sample Time bits(1)
11111 = 31 TAD
•
•
•
00001 = 1 TAD
00000 = 0 TAD

bit 7-0 **ADCS<7:0>:** ADC Conversion Clock Select bits(2)
11111111 = Reserved
•
•
•
•
01000000 = Reserved
00111111 = TCY · (ADCS<7:0> + 1) = 64 · TCY = TAD
•
•
•
00000010 = TCY · (ADCS<7:0> + 1) = 3 · TCY = TAD
00000001 = TCY · (ADCS<7:0> + 1) = 2 · TCY = TAD
00000000 = TCY · (ADCS<7:0> + 1) = 1 · TCY = TAD

**Note 1:** These bits are used only if the SSRC<2:0> bits (AD1CON1<7:5>) = 111.
**2:** These bits are not used if the ADRC bit (AD1CON3<15>) = 1.


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**REGISTER 20-4: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER**

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | CH123NB<1:0> | | CH123SB |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | U-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | CH123NA<1:0> | | CH123SA |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-11 **Unimplemented:** Read as '0'

bit 10-9 **CH123NB<1:0>:** Channel 1, 2, 3 Negative Input Select for Sample B bits

If AD12B = 1:
11 = Reserved
10 = Reserved
01 = Reserved
00 = Reserved

If AD12B = 0:
11 = Reserved
10 = Reserved
01 = CH1, CH2, CH3 negative input is VREF-
00 = CH1, CH2, CH3 negative input is VREF-

bit 8 **CH123SB:** Channel 1, 2, 3 Positive Input Select for Sample B bit

**dsPIC33FJ12MC201 devices only:**
If AD12B = 1:
1 = Reserved
0 = Reserved

If AD12B = 0:
1 = CH1 positive input is AN3, CH2 and CH3 positive inputs are not connected
0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

**dsPIC33FJ12MC202 devices only:**
If AD12B = 1:
1 = Reserved
0 = Reserved

If AD12B = 0:
1 = CH1 positive input is AN3, CH2 positive input is AN4, CH3 positive input is AN5
0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

bit 7-3 **Unimplemented:** Read as '0'

**REGISTER 20-4: AD1CHS123: ADC1 INPUT CHANNEL 1, 2, 3 SELECT REGISTER (CONTINUED)**

bit 2-1 **CH123NA<1:0>:** Channel 1, 2, 3 Negative Input Select for Sample A bits

If AD12B = 1:
11 = Reserved
10 = Reserved
01 = Reserved
00 = Reserved

If AD12B = 0:
11 = Reserved
10 = Reserved
01 = CH1, CH2, CH3 negative input is VREF-
00 = CH1, CH2, CH3 negative input is VREF-

bit 0 **CH123SA:** Channel 1, 2, 3 Positive Input Select for Sample A bit

**dsPIC33FJ12MC201 devices only:**

If AD12B = 1:
1 = Reserved
0 = Reserved

If AD12B = 0:
1 = CH1 positive input is AN3, CH2 and CH3 positive inputs are not connected
0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2

**dsPIC33FJ12MC202 devices only:**

If AD12B = 1:
1 = Reserved
0 = Reserved

If AD12B = 0:
1 = CH1 positive input is AN3, CH2 positive input is AN4, CH3 positive input is AN5
0 = CH1 positive input is AN0, CH2 positive input is AN1, CH3 positive input is AN2


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**REGISTER 20-5: AD1CHS0: ADC1 INPUT CHANNEL 0 SELECT REGISTER**

| R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| CH0NB | — | — | CH0SB<4:0> | | | | |
| bit 15 | | | | | | | bit 8 |

| R/W-0 | U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| CH0NA | — | — | CH0SA<4:0> | | | | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15 **CH0NB:** Channel 0 Negative Input Select for Sample B bit
1 = Channel 0 negative input is AN1
0 = Channel 0 negative input is VREF-

bit 14-13 **Unimplemented:** Read as '0'

bit 12-8 **CH0SB<4:0>:** Channel 0 Positive Input Select for Sample B bits
**dsPIC33FJ12MC201 devices only:**
00011 = Channel 0 positive input is AN3
00010 = Channel 0 positive input is AN2
00001 = Channel 0 positive input is AN1
00000 = Channel 0 positive input is AN0

**dsPIC33FJ12MC202 devices only:**
00101 = Channel 0 positive input is AN5
00100 = Channel 0 positive input is AN4
00011 = Channel 0 positive input is AN3
00010 = Channel 0 positive input is AN2
00001 = Channel 0 positive input is AN1
00000 = Channel 0 positive input is AN0

bit 7 **CH0NA:** Channel 0 Negative Input Select for Sample A bit
1 = Channel 0 negative input is AN1
0 = Channel 0 negative input is VREF-

bit 6-5 **Unimplemented:** Read as '0'

bit 4-0 **CH0SA<4:0>:** Channel 0 Positive Input Select for Sample A bits
**dsPIC33FJ12MC201 devices only:**
00011 = Channel 0 positive input is AN3
00010 = Channel 0 positive input is AN2
00001 = Channel 0 positive input is AN1
00000 = Channel 0 positive input is AN0

**dsPIC33FJ12MC202 devices only:**
00101 = Channel 0 positive input is AN5
00100 = Channel 0 positive input is AN4
00011 = Channel 0 positive input is AN3
00010 = Channel 0 positive input is AN2
00001 = Channel 0 positive input is AN1
00000 = Channel 0 positive input is AN0

**REGISTER 20-6: AD1CSSL: ADC1 INPUT SCAN SELECT REGISTER LOW(1,2)**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | CSS5 | CSS4 | CSS3 | CSS2 | CSS1 | CSS0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-6 **Unimplemented:** Read as '0'

bit 5-0 **CSS<5:0>:** ADC Input Scan Selection bits
1 = Select ANx for input scan
0 = Skip ANx for input scan

**Note 1:** On devices without 6 analog inputs, all AD1CSSL bits can be selected by user application. However, inputs selected for scan without a corresponding input on device converts VREFL.

**2:** CSSx = ANx, where x = 0 through 5.

**REGISTER 20-7: AD1PCFGL: ADC1 PORT CONFIGURATION REGISTER LOW(1,2,3)**

| U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | — | — | — |
| bit 15 | | | | | | | bit 8 |

| U-0 | U-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 | R/W-0 |
|---|---|---|---|---|---|---|---|
| — | — | PCFG5 | PCFG4 | PCFG3 | PCFG2 | PCFG1 | PCFG0 |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | | |
|---|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' | |
| -n = Value at POR | '1' = Bit is set | '0' = Bit is cleared | x = Bit is unknown |

bit 15-6 **Unimplemented:** Read as '0'

bit 5-0 **PCFG<5:0>:** ADC Port Configuration Control bits
1 = Port pin in Digital mode, port read input enabled, ADC input multiplexer connected to AVSS
0 = Port pin in Analog mode, port read input disabled, ADC samples pin voltage

**Note 1:** On devices without 6 analog inputs, all PCFG bits are R/W by user. However, PCFG bits are ignored on ports without a corresponding input on device.

**2:** PCFGx = ANx, where x = 0 through 5.

**3:** PCFGx bits have no effect if the ADC module is disabled by setting ADxMD bit in the PMDx register. When the bit is set, all port pins that have been multiplexed with ANx will be in Digital mode.


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## 21.0 SPECIAL FEATURES

**Note:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the *"dsPIC33F/PIC24H Family Reference Manual"*. Please see the Microchip web site (www.microchip.com) for the latest dsPIC33F/PIC24H Family Reference Manual sections.

dsPIC33FJ12MC201/202 devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible configuration
- Watchdog Timer (WDT)
- Code Protection and CodeGuard™ Security
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming™ (ICSP™)
- In-Circuit emulation

### 21.1 Configuration Bits

dsPIC33FJ12MC201/202 devices provide nonvolatile memory implementation for device configuration bits. Refer to **Section 25. "Device Configuration"** (DS70194) of the *"dsPIC33F/PIC24H Family Reference Manual"*, for more information on this implementation.

The Configuration bits can be programmed (read as '0'), or left unprogrammed (read as '1'), to select various device configurations. These bits are mapped starting at program memory location 0xF80000.

The individual Configuration bit descriptions for the Configuration registers are shown in Table 21-2.

Note that address 0xF80000 is beyond the user program memory space. It belongs to the configuration memory space (0x800000-0xFFFFFF), which can only be accessed using table reads and table writes.

The Device Configuration register map is shown in Table 21-1.

**TABLE 21-1: DEVICE CONFIGURATION REGISTER MAP**

| Address | Name | Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
|---|---|---|---|---|---|---|---|---|---|
| 0xF80000 | FBS | — | — | — | — | BSS<2:0> | | | BWRP |
| 0xF80002 | Reserved | — | — | — | — | — | — | — | — |
| 0xF80004 | FGS | — | — | — | — | — | GSS<1:0> | | GWRP |
| 0xF80006 | FOSCSEL | IESO | — | — | — | | FNOSC<2:0> | | |
| 0xF80008 | FOSC | FCKSM<1:0> | | IOL1WAY | — | — | OSCIOFNC | POSCMD<1:0> | |
| 0xF8000A | FWDT | FWDTEN | WINDIS | — | WDTPRE | WDTPOST<3:0> | | | |
| 0xF8000C | FPOR | PWMPIN | HPOL | LPOL | ALTI2C | — | FPWRT<2:0> | | |
| 0xF8000E | FICD | Reserved(1) | | JTAGEN | — | — | — | ICS<1:0> | |
| 0xF80010 | FUID0 | User Unit ID Byte 0 | | | | | | | |
| 0xF80012 | FUID1 | User Unit ID Byte 1 | | | | | | | |
| 0xF80014 | FUID2 | User Unit ID Byte 2 | | | | | | | |
| 0xF80016 | FUID3 | User Unit ID Byte 3 | | | | | | | |

**Legend:** — = unimplemented bit, read as '0'.

**Note 1:** These bits are reserved for use by development tools and must be programmed as '1'.

**TABLE 21-2: dsPIC33F CONFIGURATION BITS DESCRIPTION**

| Bit Field | Register | RTSP Effect | Description |
|---|---|---|---|
| BWRP | FBS | Immediate | Boot Segment Program Flash Write Protection<br>1 = Boot segment can be written<br>0 = Boot segment is write-protected |
| BSS<2:0> | FBS | Immediate | Boot Segment Program Flash Code Protection Size<br>X11 = No Boot program Flash segment<br><br>Boot space is 256 Instruction Words (except interrupt vectors)<br>110 = Standard security; boot program Flash segment ends at 0x0003FE<br>010 = High security; boot program Flash segment ends at 0x0003FE<br><br>Boot space is 768 Instruction Words (except interrupt vectors)<br>101 = Standard security; boot program Flash segment, ends at 0x0007FE<br>001 = High security; boot program Flash segment ends at 0x0007FE<br><br>Boot space is 1792 Instruction Words (except interrupt vectors)<br>100 = Standard security; boot program Flash segment ends at 0x000FFE<br>000 = High security; boot program Flash segment ends at 0x000FFE |
| GSS<1:0> | FGS | Immediate | General Segment Code-Protect bit<br>11 = User program memory is not code-protected<br>10 = Standard security<br>0x = High security |
| GWRP | FGS | Immediate | General Segment Write-Protect bit<br>1 = User program memory is not write-protected<br>0 = User program memory is write-protected |
| IESO | FOSCSEL | Immediate | Two-speed Oscillator Start-up Enable bit<br>1 = Start-up device with FRC, then automatically switch to the user-selected oscillator source when ready<br>0 = Start-up device with user-selected oscillator source |
| FNOSC<2:0> | FOSCSEL | If clock switch is enabled, RTSP effect is on any device Reset; otherwise, Immediate | Initial Oscillator Source Selection bits<br>111 = Internal Fast RC (FRC) oscillator with postscaler<br>110 = Internal Fast RC (FRC) oscillator with divide-by-16<br>101 = LPRC oscillator<br>100 = Secondary (LP) oscillator<br>011 = Primary (XT, HS, EC) oscillator with PLL<br>010 = Primary (XT, HS, EC) oscillator<br>001 = Internal Fast RC (FRC) oscillator with PLL<br>000 = FRC oscillator |
| FCKSM<1:0> | FOSC | Immediate | Clock Switching Mode bits<br>1x = Clock switching is disabled, Fail-Safe Clock Monitor is disabled<br>01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled<br>00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled |
| IOL1WAY | FOSC | Immediate | Peripheral pin select configuration<br>1 = Allow only one reconfiguration<br>0 = Allow multiple reconfigurations |
| OSCIOFNC | FOSC | Immediate | OSC2 Pin Function bit (except in XT and HS modes)<br>1 = OSC2 is clock output<br>0 = OSC2 is general purpose digital I/O pin |
| POSCMD<1:0> | FOSC | Immediate | Primary Oscillator Mode Select bits<br>11 = Primary oscillator disabled<br>10 = HS Crystal Oscillator mode<br>01 = XT Crystal Oscillator mode<br>00 = EC (External Clock) mode |


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**TABLE 21-2: dsPIC33F CONFIGURATION BITS DESCRIPTION (CONTINUED)**

| Bit Field | Register | RTSP Effect | Description |
|---|---|---|---|
| FWDTEN | FWDT | Immediate | Watchdog Timer Enable bit<br>1 = Watchdog Timer always enabled (LPRC oscillator cannot be disabled. Clearing the SWDTEN bit in the RCON register will have no effect.)<br>0 = Watchdog Timer enabled/disabled by user software (LPRC can be disabled by clearing the SWDTEN bit in the RCON register) |
| WINDIS | FWDT | Immediate | Watchdog Timer Window Enable bit<br>1 = Watchdog Timer in Non-Window mode<br>0 = Watchdog Timer in Window mode |
| WDTPRE | FWDT | Immediate | Watchdog Timer Prescaler bit<br>1 = 1:128<br>0 = 1:32 |
| WDTPOST<3:0> | FWDT | Immediate | Watchdog Timer Postscaler bits<br>1111 = 1:32,768<br>1110 = 1:16,384<br>•<br>•<br>•<br>0001 = 1:2<br>0000 = 1:1 |
| PWMPIN | FPOR | Immediate | Motor Control PWM Module Pin Mode bit<br>1 = PWM module pins controlled by PORT register at device Reset (tri-stated)<br>0 = PWM module pins controlled by PWM module at device Reset (configured as output pins) |
| HPOL | FPOR | Immediate | Motor Control PWM High Side Polarity bit<br>1 = PWM module high side output pins have active-high output polarity<br>0 = PWM module high side output pins have active-low output polarity |
| LPOL | FPOR | Immediate | Motor Control PWM Low Side Polarity bit<br>1 = PWM module low side output pins have active-high output polarity<br>0 = PWM module low side output pins have active-low output polarity |
| FPWRT<2:0> | FPOR | Immediate | Power-on Reset Timer Value Select bits<br>111 = PWRT = 128 ms<br>110 = PWRT = 64 ms<br>101 = PWRT = 32 ms<br>100 = PWRT = 16 ms<br>011 = PWRT = 8 ms<br>010 = PWRT = 4 ms<br>001 = PWRT = 2 ms<br>000 = PWRT = Disabled |
| ALTI2C | FPOR | Immediate | Alternate $I^2C$ pins<br>1 = $I^2C$ mapped to SDA1/SCL1 pins<br>0 = $I^2C$ mapped to ASDA1/ASCL1 pins |
| JTAGEN | FICD | Immediate | JTAG Enable bit<br>1 = JTAG enabled<br>0 = JTAG disabled |
| ICS<1:0> | FICD | Immediate | ICD Communication Channel Select bits<br>11 = Communicate on PGEC1 and PGED1<br>10 = Communicate on PGEC2 and PGED2<br>01 = Communicate on PGEC3 and PGED3<br>00 = Reserved, do not use |

## 21.2 On-Chip Voltage Regulator

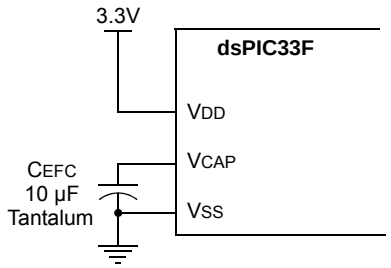
All of the dsPIC33FJ12MC201/202 devices power their core digital logic at a nominal 2.5V. This can create a conflict for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, all devices in the dsPIC33FJ12MC201/202 family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator provides power to the core from the other VDD pins. When the regulator is enabled, a low-ESR (less than 5 ohms) capacitor (such as tantalum or ceramic) must be connected to the VCAP pin (Figure 21-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor is provided in Table 24-13 located in **Section 24.1 "DC Characteristics"**.

| **Note:** | It is important for low-ESR capacitors to be placed as close as possible to the VCAP pin. |
|---|---|

On a POR, it takes approximately 20 µs for the on-chip voltage regulator to generate an output voltage. During this time, designated as TSTARTUP, code execution is disabled. TSTARTUP is applied every time the device resumes operation after any power-down.

**FIGURE 21-1: CONNECTIONS FOR THE ON-CHIP VOLTAGE REGULATOR(1,2,3)**




**Note 1:** These are typical operating voltages. Refer to **Section TABLE 24-13: "Internal Voltage Regulator Specifications"** located in **Section 24.1 "DC Characteristics"** for the full operating ranges of VDD and VCAP.

**2:** It is important for low-ESR capacitors to be placed as close as possible to the VCAP pin.

**3:** Typical VCAP pin voltage = 2.5V when VDD ≥ VDDMIN.

## 21.3 Brown-out Reset (BOR)

The Brown-out Reset (BOR) module is based on an internal voltage reference circuit that monitors the regulated supply voltage VCAP. The main purpose of the BOR module is to generate a device Reset when a brown-out condition occurs. Brown-out conditions are generally caused by glitches on the AC mains (for example, missing portions of the AC cycle waveform due to bad power transmission lines, or voltage sags due to excessive current draw when a large inductive load is turned on).

A BOR generates a Reset pulse, which resets the device. The BOR selects the clock source, based on the device Configuration bit values (FNOSC<2:0> and POSCMD<1:0>).

If an oscillator mode is selected, the BOR activates the Oscillator Start-up Timer (OST). The system clock is held until OST expires. If the PLL is used, the clock is held until the LOCK bit (OSCCON<5>) is '1'.

Concurrently, the PWRT time-out (TPWRT) is applied before the internal Reset is released. If TPWRT = 0 and a crystal oscillator is being used, then a nominal delay of TFSCM = 100 is applied. The total delay in this case is TFSCM.

The BOR Status bit (RCON<1>) is set to indicate that a BOR has occurred. The BOR circuit continues to operate while in Sleep or Idle modes and resets the device should VDD fall below the BOR threshold voltage.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## 21.4 Watchdog Timer (WDT)

For dsPIC33FJ12MC201/202 devices, the WDT is driven by the LPRC oscillator. When the WDT is enabled, the clock source is also enabled.

### 21.4.1 PRESCALER/POSTSCALER

The nominal WDT clock source from LPRC is 32 kHz. This feeds a prescaler than can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the WDTPRE Configuration bit. With a 32 kHz input, the prescaler yields a nominal WDT time-out period (TWDT) of 1 ms in 5-bit mode, or 4 ms in 7-bit mode.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPOST<3:0> Configuration bits (FWDT<3:0>), which allow the selection of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler, time-out periods ranging from 1 ms to 131 seconds can be achieved.

The WDT, prescaler, and postscaler are reset:

- On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSC bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

| **Note:** | The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed. |
|---|---|

### 21.4.2 SLEEP AND IDLE MODES

If the WDT is enabled, it will continue to run during Sleep or Idle modes. When the WDT time-out occurs, the device will wake the device and code execution will continue from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE bits (RCON<3> and RCON<2>, respectively) will need to be cleared in software after the device wakes up.

### 21.4.3 ENABLING WDT

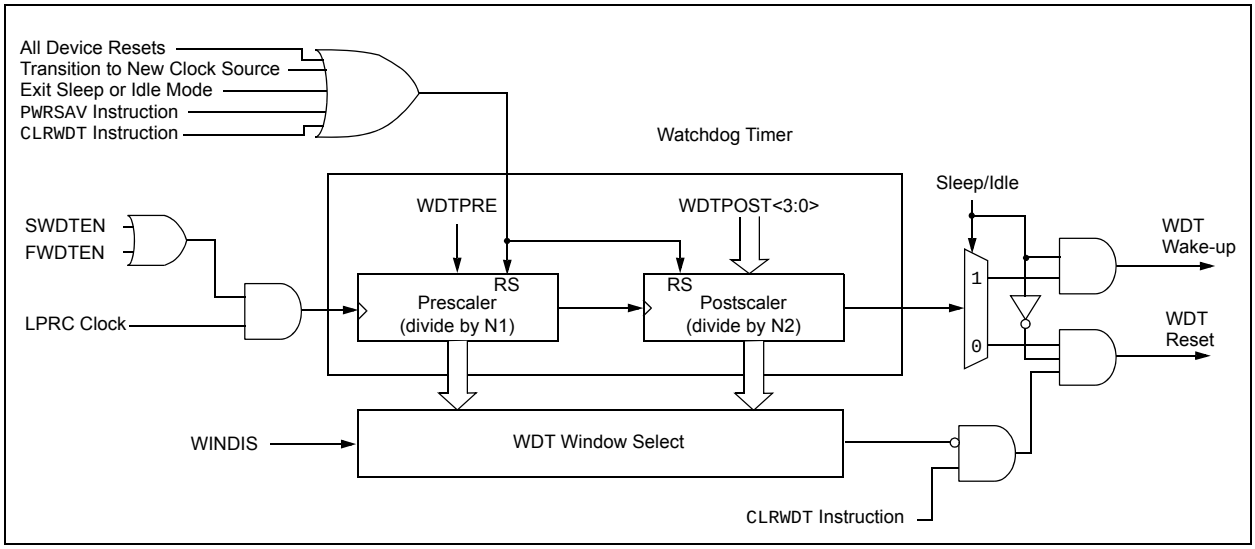
The WDT is enabled or disabled by the FWDTEN Configuration bit in the FWDT Configuration register. When the FWDTEN Configuration bit is set, the WDT is always enabled.

The WDT can be optionally controlled in software when the FWDTEN Configuration bit has been programmed to '0'. The WDT is enabled in software by setting the SWDTEN control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user application to enable the WDT for critical code segments and disable the WDT during non-critical segments for maximum power savings.

| **Note:** | If the WINDIS bit (FWDT<6>) is cleared, the CLRWDT instruction should be executed by the application software only during the last 1/4 of the WDT period. This CLRWDT window can be determined by using a timer. If a CLRWDT instruction is executed before this window, a WDT Reset occurs. |
|---|---|

The WDT flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

**FIGURE 21-2: WDT BLOCK DIAGRAM**



## 21.5 JTAG Interface

dsPIC33FJ12MC201/202 devices implement a JTAG interface, which supports boundary scan device testing, as well as in-circuit programming. Detailed information on this interface will be provided in future revisions of the document.

## 21.6 In-Circuit Serial Programming

The dsPIC33FJ12MC201/202 devices can be serially programmed while in the end application circuit. This is done with two lines for clock and data and three other lines for power, ground and the programming sequence. Serial programming allows customers to manufacture boards with unprogrammed devices and then program the digital signal controller just before shipping the product. Serial programming also allows the most recent firmware or a custom firmware to be programmed. Refer to the *dsPIC33F/PIC24H Flash Programming Specification* (DS70152) for details about In-Circuit Serial Programming (ICSP).

Any of the three pairs of programming clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

## 21.7 In-Circuit Debugger

When MPLAB® ICD 2 is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the PGECx (Emulation/Debug Clock) and PGEDx (Emulation/Debug Data) pin functions.

Any of the three pairs of debugging clock/data pins can be used:

- PGEC1 and PGED1
- PGEC2 and PGED2
- PGEC3 and PGED3

To use the in-circuit debugger function of the device, the design must implement ICSP connections to MCLR, VDD, VSS, and the PGECx/PGEDx pin pair. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins.

## 21.8 Code Protection and CodeGuard™ Security

The dsPIC33FJ12MC201/202 devices offer the intermediate implementation of CodeGuard Security. CodeGuard Security enables multiple parties to securely share resources (memory, interrupts and peripherals) on a single chip. This feature helps protect individual Intellectual Property in collaborative system designs.

When coupled with software encryption libraries, CodeGuard Security can be used to securely update Flash even when multiple IPs reside on the single chip. The code protection features vary depending on the actual dsPIC33F implemented. The following sections provide an overview of these features.

Secure segment and RAM protection is not implemented in dsPIC33FJ12MC201/202 devices.

**TABLE 21-3: CODE FLASH SECURITY SEGMENT SIZES FOR 12 KBYTE DEVICES**

| CONFIG BITS | |
|---|---|
| **BSS<2:0> = x11**<br>**0K** | VS = 256 IW<br>GS = 3840 IW<br>000000h 0001FEh 000200h 0003FEh 000400h 0007FEh 000800h 000FFEh 001000h 001FFEh |
| **BSS<2:0> = x10**<br>**256** | VS = 256 IW<br>BS = 256 IW<br>GS = 3584 IW<br>000000h 0001FEh 000200h 0003FEh 000400h 0007FEh 000800h 000FFEh 001000h 001FFEh |
| **BSS<2:0> = x01**<br>**768** | VS = 256 IW<br>BS = 768 IW<br>GS = 3072 IW<br>000000h 0001FEh 000200h 0003FEh 000400h 0007FEh 000800h 000FFEh 001000h 001FFEh |
| **BSS<2:0> = x00**<br>**1792** | VS = 256 IW<br>BS = 1792 IW<br>GS = 2048 IW<br>000000h 0001FEh 000200h 0003FEh 000400h 0007FEh 000800h 000FFEh 001000h 001FFEh |

**Note:** Refer to **Section 23. "CodeGuard™ Security"** (DS70199) of the *"dsPIC33F/PIC24H Family Reference Manual"* for further information on usage, configuration and operation of CodeGuard Security.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## 22.0 INSTRUCTION SET SUMMARY

**Note:** This data sheet summarizes the features of the dsPIC33FJ12MC201/202 devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to the *"dsPIC33F/PIC24H Family Reference Manual"*. Please see the Microchip web site (www.microchip.com) for the latest dsPIC33F/PIC24H Family Reference Manual sections.

The dsPIC33F instruction set is identical to that of the dsPIC30F.

Most instructions are a single program memory word (24 bits). Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word, divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction.

The instruction set is highly orthogonal and is grouped into five basic categories:

- Word or byte-oriented operations
- Bit-oriented operations
- Literal operations
- DSP operations
- Control operations

Table 22-1 shows the general symbols used in describing the instructions.

The dsPIC33F instruction set summary in Table 22-2 lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand, which is typically a register 'Wb' without any address modifier
- The second source operand, which is typically a register 'Ws' with or without an address modifier
- The destination of the result, which is typically a register 'Wd' with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- The file register specified by the value 'f'
- The destination, which could be either the file register 'f' or the W0 register, which is denoted as 'WREG'

Most bit-oriented instructions (including simple rotate/shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of 'Ws' or 'f')
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register 'Wb')

The literal instructions that involve data movement can use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by 'k')
- The W register or file register where the literal value is to be loaded (specified by 'Wb' or 'f')

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand, which is a register 'Wb' without any address modifier
- The second source operand, which is a literal value
- The destination of the result (only if not the same as the first source operand), which is typically a register 'Wd' with or without an address modifier

The MAC class of DSP instructions can use some of the following operands:

- The accumulator (A or B) to be used (required operand)
- The W registers to be used as the two operands
- The X and Y address space prefetch operations
- The X and Y address space prefetch destinations
- The accumulator write back destination

The other DSP instructions do not involve any multiplication and can include:

- The accumulator to be used (required)
- The source or destination operand (designated as Wso or Wdo, respectively) with or without an address modifier
- The amount of shift specified by a W register 'Wn' or a literal value

The control instructions can use some of the following operands:

- A program memory address
- The mode of the table read and table write instructions

Most instructions are a single word. Certain double-word instructions are designed to provide all the required information in these 48 bits. In the second word, the 8 MSbs are '0's. If this second word is executed as an instruction (by itself), it will execute as a NOP.

The double-word instructions execute in two instruction cycles.

Most single-word instructions are executed in a single instruction cycle, unless a conditional test is true, or the program counter is changed as a result of the instruction. In these cases, the execution takes two instruction cycles with the additional instruction cycle(s) executed as a NOP. Notable exceptions are the BRA (unconditional/computed branch), indirect CALL/GOTO, all table reads and writes and RETURN/RETFIE instructions, which are single-word instructions but take two or three cycles. Certain instructions that involve skipping over the subsequent instruction require either two or three cycles if the skip is performed, depending on whether the instruction being skipped is a single-word or two-word instruction. Moreover, double-word moves require two cycles.

**Note:** For more details on the instruction set, refer to the *"16-bit MCU and DSC Programmer's Reference Manual"* (DS70157).

**TABLE 22-1: SYMBOLS USED IN OPCODE DESCRIPTIONS**

| Field | Description |
|---|---|
| #text | Means literal defined by "text" |
| (text) | Means "content of text" |
| [text] | Means "the location addressed by text" |
| { } | Optional field or operation |
| <n:m> | Register bit field |
| .b | Byte mode selection |
| .d | Double-Word mode selection |
| .S | Shadow register select |
| .w | Word mode selection (default) |
| Acc | One of two accumulators {A, B} |
| AWB | Accumulator write back destination address register ∈ {W13, [W13]+ = 2} |
| bit4 | 4-bit bit selection field (used in word addressed instructions) ∈ {0...15} |
| C, DC, N, OV, Z | MCU Status bits: Carry, Digit Carry, Negative, Overflow, Sticky Zero |
| Expr | Absolute address, label or expression (resolved by the linker) |
| f | File register address ∈ {0x0000...0x1FFF} |
| lit1 | 1-bit unsigned literal ∈ {0,1} |
| lit4 | 4-bit unsigned literal ∈ {0...15} |
| lit5 | 5-bit unsigned literal ∈ {0...31} |
| lit8 | 8-bit unsigned literal ∈ {0...255} |
| lit10 | 10-bit unsigned literal ∈ {0...255} for Byte mode, {0:1023} for Word mode |
| lit14 | 14-bit unsigned literal ∈ {0...16384} |
| lit16 | 16-bit unsigned literal ∈ {0...65535} |
| lit23 | 23-bit unsigned literal ∈ {0...8388608}; LSb must be '0' |
| None | Field does not require an entry, can be blank |
| OA, OB, SA, SB | DSP Status bits: ACCA Overflow, ACCB Overflow, ACCA Saturate, ACCB Saturate |
| PC | Program Counter |
| Slit10 | 10-bit signed literal ∈ {-512...511} |
| Slit16 | 16-bit signed literal ∈ {-32768...32767} |
| Slit6 | 6-bit signed literal ∈ {-16...16} |
| Wb | Base W register ∈ {W0..W15} |
| Wd | Destination W register ∈ { Wd, [Wd], [Wd++], [Wd--], [++Wd], [--Wd] } |
| Wdo | Destination W register ∈<br>{ Wnd, [Wnd], [Wnd++], [Wnd--], [++Wnd], [--Wnd], [Wnd+Wb] } |
| Wm,Wn | Dividend, Divisor working register pair (direct addressing) |


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**TABLE 22-1: SYMBOLS USED IN OPCODE DESCRIPTIONS (CONTINUED)**

| Field | Description |
|---|---|
| Wm*Wm | Multiplicand and Multiplier working register pair for Square instructions ∈ {W4 * W4,W5 * W5,W6 * W6,W7 * W7} |
| Wm*Wn | Multiplicand and Multiplier working register pair for DSP instructions ∈ {W4 * W5,W4 * W6,W4 * W7,W5 * W6,W5 * W7,W6 * W7} |
| Wn | One of 16 working registers ∈ {W0..W15} |
| Wnd | One of 16 destination working registers ∈ {W0..W15} |
| Wns | One of 16 source working registers ∈ {W0..W15} |
| WREG | W0 (working register used in file register instructions) |
| Ws | Source W register ∈ { Ws, [Ws], [Ws++], [Ws--], [++Ws], [--Ws] } |
| Wso | Source W register ∈ { Wns, [Wns], [Wns++], [Wns--], [++Wns], [--Wns], [Wns+Wb] } |
| Wx | X data space prefetch address register for DSP instructions ∈ {[W8] + = 6, [W8] + = 4, [W8] + = 2, [W8], [W8] - = 6, [W8] - = 4, [W8] - = 2, [W9] + = 6, [W9] + = 4, [W9] + = 2, [W9], [W9] - = 6, [W9] - = 4, [W9] - = 2, [W9 + W12], none} |
| Wxd | X data space prefetch destination register for DSP instructions ∈ {W4..W7} |
| Wy | Y data space prefetch address register for DSP instructions ∈ {[W10] + = 6, [W10] + = 4, [W10] + = 2, [W10], [W10] - = 6, [W10] - = 4, [W10] - = 2, [W11] + = 6, [W11] + = 4, [W11] + = 2, [W11], [W11] - = 6, [W11] - = 4, [W11] - = 2, [W11 + W12], none} |
| Wyd | Y data space prefetch destination register for DSP instructions ∈ {W4..W7} |

**TABLE 22-2: INSTRUCTION SET OVERVIEW**

| Base Instr # | Assembly Mnemonic | Assembly Syntax | | Description | # of Words | # of Cycles | Status Flags Affected |
|---|---|---|---|---|---|---|---|
| 1 | ADD | ADD | Acc | Add Accumulators | 1 | 1 | OA,OB,SA,SB |
| | | ADD | f | f = f + WREG | 1 | 1 | C,DC,N,OV,Z |
| | | ADD | f,WREG | WREG = f + WREG | 1 | 1 | C,DC,N,OV,Z |
| | | ADD | #lit10,Wn | Wd = lit10 + Wd | 1 | 1 | C,DC,N,OV,Z |
| | | ADD | Wb,Ws,Wd | Wd = Wb + Ws | 1 | 1 | C,DC,N,OV,Z |
| | | ADD | Wb,#lit5,Wd | Wd = Wb + lit5 | 1 | 1 | C,DC,N,OV,Z |
| | | ADD | Wso,#Slit4,Acc | 16-bit Signed Add to Accumulator | 1 | 1 | OA,OB,SA,SB |
| 2 | ADDC | ADDC | f | f = f + WREG + (C) | 1 | 1 | C,DC,N,OV,Z |
| | | ADDC | f,WREG | WREG = f + WREG + (C) | 1 | 1 | C,DC,N,OV,Z |
| | | ADDC | #lit10,Wn | Wd = lit10 + Wd + (C) | 1 | 1 | C,DC,N,OV,Z |
| | | ADDC | Wb,Ws,Wd | Wd = Wb + Ws + (C) | 1 | 1 | C,DC,N,OV,Z |
| | | ADDC | Wb,#lit5,Wd | Wd = Wb + lit5 + (C) | 1 | 1 | C,DC,N,OV,Z |
| 3 | AND | AND | f | f = f .AND. WREG | 1 | 1 | N,Z |
| | | AND | f,WREG | WREG = f .AND. WREG | 1 | 1 | N,Z |
| | | AND | #lit10,Wn | Wd = lit10 .AND. Wd | 1 | 1 | N,Z |
| | | AND | Wb,Ws,Wd | Wd = Wb .AND. Ws | 1 | 1 | N,Z |
| | | AND | Wb,#lit5,Wd | Wd = Wb .AND. lit5 | 1 | 1 | N,Z |
| 4 | ASR | ASR | f | f = Arithmetic Right Shift f | 1 | 1 | C,N,OV,Z |
| | | ASR | f,WREG | WREG = Arithmetic Right Shift f | 1 | 1 | C,N,OV,Z |
| | | ASR | Ws,Wd | Wd = Arithmetic Right Shift Ws | 1 | 1 | C,N,OV,Z |
| | | ASR | Wb,Wns,Wnd | Wnd = Arithmetic Right Shift Wb by Wns | 1 | 1 | N,Z |
| | | ASR | Wb,#lit5,Wnd | Wnd = Arithmetic Right Shift Wb by lit5 | 1 | 1 | N,Z |
| 5 | BCLR | BCLR | f,#bit4 | Bit Clear f | 1 | 1 | None |
| | | BCLR | Ws,#bit4 | Bit Clear Ws | 1 | 1 | None |
| 6 | BRA | BRA | C,Expr | Branch if Carry | 1 | 1 (2) | None |
| | | BRA | GE,Expr | Branch if greater than or equal | 1 | 1 (2) | None |
| | | BRA | GEU,Expr | Branch if unsigned greater than or equal | 1 | 1 (2) | None |
| | | BRA | GT,Expr | Branch if greater than | 1 | 1 (2) | None |
| | | BRA | GTU,Expr | Branch if unsigned greater than | 1 | 1 (2) | None |
| | | BRA | LE,Expr | Branch if less than or equal | 1 | 1 (2) | None |
| | | BRA | LEU,Expr | Branch if unsigned less than or equal | 1 | 1 (2) | None |
| | | BRA | LT,Expr | Branch if less than | 1 | 1 (2) | None |
| | | BRA | LTU,Expr | Branch if unsigned less than | 1 | 1 (2) | None |
| | | BRA | N,Expr | Branch if Negative | 1 | 1 (2) | None |
| | | BRA | NC,Expr | Branch if Not Carry | 1 | 1 (2) | None |
| | | BRA | NN,Expr | Branch if Not Negative | 1 | 1 (2) | None |
| | | BRA | NOV,Expr | Branch if Not Overflow | 1 | 1 (2) | None |
| | | BRA | NZ,Expr | Branch if Not Zero | 1 | 1 (2) | None |
| | | BRA | OA,Expr | Branch if Accumulator A overflow | 1 | 1 (2) | None |
| | | BRA | OB,Expr | Branch if Accumulator B overflow | 1 | 1 (2) | None |
| | | BRA | OV,Expr | Branch if Overflow | 1 | 1 (2) | None |
| | | BRA | SA,Expr | Branch if Accumulator A saturated | 1 | 1 (2) | None |
| | | BRA | SB,Expr | Branch if Accumulator B saturated | 1 | 1 (2) | None |
| | | BRA | Expr | Branch Unconditionally | 1 | 2 | None |
| | | BRA | Z,Expr | Branch if Zero | 1 | 1 (2) | None |
| | | BRA | Wn | Computed Branch | 1 | 2 | None |
| 7 | BSET | BSET | f,#bit4 | Bit Set f | 1 | 1 | None |
| | | BSET | Ws,#bit4 | Bit Set Ws | 1 | 1 | None |
| 8 | BSW | BSW.C | Ws,Wb | Write C bit to Ws<Wb> | 1 | 1 | None |
| | | BSW.Z | Ws,Wb | Write Z bit to Ws<Wb> | 1 | 1 | None |
| 9 | BTG | BTG | f,#bit4 | Bit Toggle f | 1 | 1 | None |
| | | BTG | Ws,#bit4 | Bit Toggle Ws | 1 | 1 | None |


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**TABLE 22-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

| Base Instr # | Assembly Mnemonic | Assembly Syntax | Description | # of Words | # of Cycles | Status Flags Affected |
|---|---|---|---|---|---|---|
| 10 | BTSC | BTSC f,#bit4 | Bit Test f, Skip if Clear | 1 | 1 (2 or 3) | None |
| | | BTSC Ws,#bit4 | Bit Test Ws, Skip if Clear | 1 | 1 (2 or 3) | None |
| 11 | BTSS | BTSS f,#bit4 | Bit Test f, Skip if Set | 1 | 1 (2 or 3) | None |
| | | BTSS Ws,#bit4 | Bit Test Ws, Skip if Set | 1 | 1 (2 or 3) | None |
| 12 | BTST | BTST f,#bit4 | Bit Test f | 1 | 1 | Z |
| | | BTST.C Ws,#bit4 | Bit Test Ws to C | 1 | 1 | C |
| | | BTST.Z Ws,#bit4 | Bit Test Ws to Z | 1 | 1 | Z |
| | | BTST.C Ws,Wb | Bit Test Ws<Wb> to C | 1 | 1 | C |
| | | BTST.Z Ws,Wb | Bit Test Ws<Wb> to Z | 1 | 1 | Z |
| 13 | BTSTS | BTSTS f,#bit4 | Bit Test then Set f | 1 | 1 | Z |
| | | BTSTS.C Ws,#bit4 | Bit Test Ws to C, then Set | 1 | 1 | C |
| | | BTSTS.Z Ws,#bit4 | Bit Test Ws to Z, then Set | 1 | 1 | Z |
| 14 | CALL | CALL lit23 | Call subroutine | 2 | 2 | None |
| | | CALL Wn | Call indirect subroutine | 1 | 2 | None |
| 15 | CLR | CLR f | f = 0x0000 | 1 | 1 | None |
| | | CLR WREG | WREG = 0x0000 | 1 | 1 | None |
| | | CLR Ws | Ws = 0x0000 | 1 | 1 | None |
| | | CLR Acc,Wx,Wxd,Wy,Wyd,AWB | Clear Accumulator | 1 | 1 | OA,OB,SA,SB |
| 16 | CLRWDT | CLRWDT | Clear Watchdog Timer | 1 | 1 | WDTO,Sleep |
| 17 | COM | COM f | $f = \overline{f}$ | 1 | 1 | N,Z |
| | | COM f,WREG | $WREG = \overline{f}$ | 1 | 1 | N,Z |
| | | COM Ws,Wd | $Wd = \overline{Ws}$ | 1 | 1 | N,Z |
| 18 | CP | CP f | Compare f with WREG | 1 | 1 | C,DC,N,OV,Z |
| | | CP Wb,#lit5 | Compare Wb with lit5 | 1 | 1 | C,DC,N,OV,Z |
| | | CP Wb,Ws | Compare Wb with Ws (Wb – Ws) | 1 | 1 | C,DC,N,OV,Z |
| 19 | CP0 | CP0 f | Compare f with 0x0000 | 1 | 1 | C,DC,N,OV,Z |
| | | CP0 Ws | Compare Ws with 0x0000 | 1 | 1 | C,DC,N,OV,Z |
| 20 | CPB | CPB f | Compare f with WREG, with Borrow | 1 | 1 | C,DC,N,OV,Z |
| | | CPB Wb,#lit5 | Compare Wb with lit5, with Borrow | 1 | 1 | C,DC,N,OV,Z |
| | | CPB Wb,Ws | Compare Wb with Ws, with Borrow ($Wb – Ws – \overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| 21 | CPSEQ | CPSEQ Wb, Wn | Compare Wb with Wn, skip if = | 1 | 1 (2 or 3) | None |
| 22 | CPSGT | CPSGT Wb, Wn | Compare Wb with Wn, skip if > | 1 | 1 (2 or 3) | None |
| 23 | CPSLT | CPSLT Wb, Wn | Compare Wb with Wn, skip if < | 1 | 1 (2 or 3) | None |
| 24 | CPSNE | CPSNE Wb, Wn | Compare Wb with Wn, skip if ≠ | 1 | 1 (2 or 3) | None |
| 25 | DAW | DAW Wn | Wn = decimal adjust Wn | 1 | 1 | C |
| 26 | DEC | DEC f | f = f – 1 | 1 | 1 | C,DC,N,OV,Z |
| | | DEC f,WREG | WREG = f – 1 | 1 | 1 | C,DC,N,OV,Z |
| | | DEC Ws,Wd | Wd = Ws – 1 | 1 | 1 | C,DC,N,OV,Z |
| 27 | DEC2 | DEC2 f | f = f – 2 | 1 | 1 | C,DC,N,OV,Z |
| | | DEC2 f,WREG | WREG = f – 2 | 1 | 1 | C,DC,N,OV,Z |
| | | DEC2 Ws,Wd | Wd = Ws – 2 | 1 | 1 | C,DC,N,OV,Z |
| 28 | DISI | DISI #lit14 | Disable Interrupts for k instruction cycles | 1 | 1 | None |

**TABLE 22-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

| Base Instr # | Assembly Mnemonic | Assembly Syntax | Description | # of Words | # of Cycles | Status Flags Affected |
|---|---|---|---|---|---|---|
| 29 | DIV | DIV.S Wm,Wn | Signed 16/16-bit Integer Divide | 1 | 18 | N,Z,C,OV |
| | | DIV.SD Wm,Wn | Signed 32/16-bit Integer Divide | 1 | 18 | N,Z,C,OV |
| | | DIV.U Wm,Wn | Unsigned 16/16-bit Integer Divide | 1 | 18 | N,Z,C,OV |
| | | DIV.UD Wm,Wn | Unsigned 32/16-bit Integer Divide | 1 | 18 | N,Z,C,OV |
| 30 | DIVF | DIVF Wm,Wn | Signed 16/16-bit Fractional Divide | 1 | 18 | N,Z,C,OV |
| 31 | DO | DO #lit14,Expr | Do code to PC + Expr, lit14 + 1 times | 2 | 2 | None |
| | | DO Wn,Expr | Do code to PC + Expr, (Wn) + 1 times | 2 | 2 | None |
| 32 | ED | ED Wm*Wm,Acc,Wx,Wy,Wxd | Euclidean Distance (no accumulate) | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 33 | EDAC | EDAC Wm*Wm,Acc,Wx,Wy,Wxd | Euclidean Distance | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 34 | EXCH | EXCH Wns,Wnd | Swap Wns with Wnd | 1 | 1 | None |
| 35 | FBCL | FBCL Ws,Wnd | Find Bit Change from Left (MSb) Side | 1 | 1 | C |
| 36 | FF1L | FF1L Ws,Wnd | Find First One from Left (MSb) Side | 1 | 1 | C |
| 37 | FF1R | FF1R Ws,Wnd | Find First One from Right (LSb) Side | 1 | 1 | C |
| 38 | GOTO | GOTO Expr | Go to address | 2 | 2 | None |
| | | GOTO Wn | Go to indirect | 1 | 2 | None |
| 39 | INC | INC f | f = f + 1 | 1 | 1 | C,DC,N,OV,Z |
| | | INC f,WREG | WREG = f + 1 | 1 | 1 | C,DC,N,OV,Z |
| | | INC Ws,Wd | Wd = Ws + 1 | 1 | 1 | C,DC,N,OV,Z |
| 40 | INC2 | INC2 f | f = f + 2 | 1 | 1 | C,DC,N,OV,Z |
| | | INC2 f,WREG | WREG = f + 2 | 1 | 1 | C,DC,N,OV,Z |
| | | INC2 Ws,Wd | Wd = Ws + 2 | 1 | 1 | C,DC,N,OV,Z |
| 41 | IOR | IOR f | f = f .IOR. WREG | 1 | 1 | N,Z |
| | | IOR f,WREG | WREG = f .IOR. WREG | 1 | 1 | N,Z |
| | | IOR #lit10,Wn | Wd = lit10 .IOR. Wd | 1 | 1 | N,Z |
| | | IOR Wb,Ws,Wd | Wd = Wb .IOR. Ws | 1 | 1 | N,Z |
| | | IOR Wb,#lit5,Wd | Wd = Wb .IOR. lit5 | 1 | 1 | N,Z |
| 42 | LAC | LAC Wso,#Slit4,Acc | Load Accumulator | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 43 | LNK | LNK #lit14 | Link Frame Pointer | 1 | 1 | None |
| 44 | LSR | LSR f | f = Logical Right Shift f | 1 | 1 | C,N,OV,Z |
| | | LSR f,WREG | WREG = Logical Right Shift f | 1 | 1 | C,N,OV,Z |
| | | LSR Ws,Wd | Wd = Logical Right Shift Ws | 1 | 1 | C,N,OV,Z |
| | | LSR Wb,Wns,Wnd | Wnd = Logical Right Shift Wb by Wns | 1 | 1 | N,Z |
| | | LSR Wb,#lit5,Wnd | Wnd = Logical Right Shift Wb by lit5 | 1 | 1 | N,Z |
| 45 | MAC | MAC Wm*Wn,Acc,Wx,Wxd,Wy,Wyd, AWB | Multiply and Accumulate | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| | | MAC Wm*Wm,Acc,Wx,Wxd,Wy,Wyd | Square and Accumulate | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 46 | MOV | MOV f,Wn | Move f to Wn | 1 | 1 | None |
| | | MOV f | Move f to f | 1 | 1 | N,Z |
| | | MOV f,WREG | Move f to WREG | 1 | 1 | None |
| | | MOV #lit16,Wn | Move 16-bit literal to Wn | 1 | 1 | None |
| | | MOV.b #lit8,Wn | Move 8-bit literal to Wn | 1 | 1 | None |
| | | MOV Wn,f | Move Wn to f | 1 | 1 | None |
| | | MOV Wso,Wdo | Move Ws to Wd | 1 | 1 | None |
| | | MOV WREG,f | Move WREG to f | 1 | 1 | None |
| | | MOV.D Wns,Wd | Move Double from W(ns):W(ns + 1) to Wd | 1 | 2 | None |
| | | MOV.D Ws,Wnd | Move Double from Ws to W(nd + 1):W(nd) | 1 | 2 | None |
| 47 | MOVSAC | MOVSAC Acc,Wx,Wxd,Wy,Wyd,AWB | Prefetch and store accumulator | 1 | 1 | None |


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**TABLE 22-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

| Base Instr # | Assembly Mnemonic | Assembly Syntax | Description | # of Words | # of Cycles | Status Flags Affected |
|---|---|---|---|---|---|---|
| 48 | MPY | MPY Wm*Wn,Acc,Wx,Wxd,Wy,Wyd | Multiply Wm by Wn to Accumulator | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| | | MPY Wm*Wm,Acc,Wx,Wxd,Wy,Wyd | Square Wm to Accumulator | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 49 | MPY.N | MPY.N Wm*Wn,Acc,Wx,Wxd,Wy,Wyd | -(Multiply Wm by Wn) to Accumulator | 1 | 1 | None |
| 50 | MSC | MSC Wm*Wm,Acc,Wx,Wxd,Wy,Wyd, AWB | Multiply and Subtract from Accumulator | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 51 | MUL | MUL.SS Wb,Ws,Wnd | {Wnd + 1, Wnd} = signed(Wb) * signed(Ws) | 1 | 1 | None |
| | | MUL.SU Wb,Ws,Wnd | {Wnd + 1, Wnd} = signed(Wb) * unsigned(Ws) | 1 | 1 | None |
| | | MUL.US Wb,Ws,Wnd | {Wnd + 1, Wnd} = unsigned(Wb) * signed(Ws) | 1 | 1 | None |
| | | MUL.UU Wb,Ws,Wnd | {Wnd + 1, Wnd} = unsigned(Wb) * unsigned(Ws) | 1 | 1 | None |
| | | MUL.SU Wb,#lit5,Wnd | {Wnd + 1, Wnd} = signed(Wb) * unsigned(lit5) | 1 | 1 | None |
| | | MUL.UU Wb,#lit5,Wnd | {Wnd + 1, Wnd} = unsigned(Wb) * unsigned(lit5) | 1 | 1 | None |
| | | MUL f | W3:W2 = f * WREG | 1 | 1 | None |
| 52 | NEG | NEG Acc | Negate Accumulator | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| | | NEG f | f = $\bar{f}$ + 1 | 1 | 1 | C,DC,N,OV,Z |
| | | NEG f,WREG | WREG = $\bar{f}$ + 1 | 1 | 1 | C,DC,N,OV,Z |
| | | NEG Ws,Wd | Wd = $\overline{Ws}$ + 1 | 1 | 1 | C,DC,N,OV,Z |
| 53 | NOP | NOP | No Operation | 1 | 1 | None |
| | | NOPR | No Operation | 1 | 1 | None |
| 54 | POP | POP f | Pop f from Top-of-Stack (TOS) | 1 | 1 | None |
| | | POP Wdo | Pop from Top-of-Stack (TOS) to Wdo | 1 | 1 | None |
| | | POP.D Wnd | Pop from Top-of-Stack (TOS) to W(nd):W(nd + 1) | 1 | 2 | None |
| | | POP.S | Pop Shadow Registers | 1 | 1 | All |
| 55 | PUSH | PUSH f | Push f to Top-of-Stack (TOS) | 1 | 1 | None |
| | | PUSH Wso | Push Wso to Top-of-Stack (TOS) | 1 | 1 | None |
| | | PUSH.D Wns | Push W(ns):W(ns + 1) to Top-of-Stack (TOS) | 1 | 2 | None |
| | | PUSH.S | Push Shadow Registers | 1 | 1 | None |
| 56 | PWRSAV | PWRSAV #lit1 | Go into Sleep or Idle mode | 1 | 1 | WDTO,Sleep |
| 57 | RCALL | RCALL Expr | Relative Call | 1 | 2 | None |
| | | RCALL Wn | Computed Call | 1 | 2 | None |
| 58 | REPEAT | REPEAT #lit14 | Repeat Next Instruction lit14 + 1 times | 1 | 1 | None |
| | | REPEAT Wn | Repeat Next Instruction (Wn) + 1 times | 1 | 1 | None |
| 59 | RESET | RESET | Software device Reset | 1 | 1 | None |
| 60 | RETFIE | RETFIE | Return from interrupt | 1 | 3 (2) | None |
| 61 | RETLW | RETLW #lit10,Wn | Return with literal in Wn | 1 | 3 (2) | None |
| 62 | RETURN | RETURN | Return from Subroutine | 1 | 3 (2) | None |
| 63 | RLC | RLC f | f = Rotate Left through Carry f | 1 | 1 | C,N,Z |
| | | RLC f,WREG | WREG = Rotate Left through Carry f | 1 | 1 | C,N,Z |
| | | RLC Ws,Wd | Wd = Rotate Left through Carry Ws | 1 | 1 | C,N,Z |
| 64 | RLNC | RLNC f | f = Rotate Left (No Carry) f | 1 | 1 | N,Z |
| | | RLNC f,WREG | WREG = Rotate Left (No Carry) f | 1 | 1 | N,Z |
| | | RLNC Ws,Wd | Wd = Rotate Left (No Carry) Ws | 1 | 1 | N,Z |
| 65 | RRC | RRC f | f = Rotate Right through Carry f | 1 | 1 | C,N,Z |
| | | RRC f,WREG | WREG = Rotate Right through Carry f | 1 | 1 | C,N,Z |
| | | RRC Ws,Wd | Wd = Rotate Right through Carry Ws | 1 | 1 | C,N,Z |

**TABLE 22-2: INSTRUCTION SET OVERVIEW (CONTINUED)**

| Base Instr # | Assembly Mnemonic | Assembly Syntax | | Description | # of Words | # of Cycles | Status Flags Affected |
|---|---|---|---|---|---|---|---|
| 66 | RRNC | RRNC | f | f = Rotate Right (No Carry) f | 1 | 1 | N,Z |
| | | RRNC | f,WREG | WREG = Rotate Right (No Carry) f | 1 | 1 | N,Z |
| | | RRNC | Ws,Wd | Wd = Rotate Right (No Carry) Ws | 1 | 1 | N,Z |
| 67 | SAC | SAC | Acc,#Slit4,Wdo | Store Accumulator | 1 | 1 | None |
| | | SAC.R | Acc,#Slit4,Wdo | Store Rounded Accumulator | 1 | 1 | None |
| 68 | SE | SE | Ws,Wnd | Wnd = sign-extended Ws | 1 | 1 | C,N,Z |
| 69 | SETM | SETM | f | f = 0xFFFF | 1 | 1 | None |
| | | SETM | WREG | WREG = 0xFFFF | 1 | 1 | None |
| | | SETM | Ws | Ws = 0xFFFF | 1 | 1 | None |
| 70 | SFTAC | SFTAC | Acc,Wn | Arithmetic Shift Accumulator by (Wn) | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| | | SFTAC | Acc,#Slit6 | Arithmetic Shift Accumulator by Slit6 | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| 71 | SL | SL | f | f = Left Shift f | 1 | 1 | C,N,OV,Z |
| | | SL | f,WREG | WREG = Left Shift f | 1 | 1 | C,N,OV,Z |
| | | SL | Ws,Wd | Wd = Left Shift Ws | 1 | 1 | C,N,OV,Z |
| | | SL | Wb,Wns,Wnd | Wnd = Left Shift Wb by Wns | 1 | 1 | N,Z |
| | | SL | Wb,#lit5,Wnd | Wnd = Left Shift Wb by lit5 | 1 | 1 | N,Z |
| 72 | SUB | SUB | Acc | Subtract Accumulators | 1 | 1 | OA,OB,OAB, SA,SB,SAB |
| | | SUB | f | f = f – WREG | 1 | 1 | C,DC,N,OV,Z |
| | | SUB | f,WREG | WREG = f – WREG | 1 | 1 | C,DC,N,OV,Z |
| | | SUB | #lit10,Wn | Wn = Wn – lit10 | 1 | 1 | C,DC,N,OV,Z |
| | | SUB | Wb,Ws,Wd | Wd = Wb – Ws | 1 | 1 | C,DC,N,OV,Z |
| | | SUB | Wb,#lit5,Wd | Wd = Wb – lit5 | 1 | 1 | C,DC,N,OV,Z |
| 73 | SUBB | SUBB | f | f = f – WREG – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBB | f,WREG | WREG = f – WREG – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBB | #lit10,Wn | Wn = Wn – lit10 – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBB | Wb,Ws,Wd | Wd = Wb – Ws – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBB | Wb,#lit5,Wd | Wd = Wb – lit5 – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| 74 | SUBR | SUBR | f | f = WREG – f | 1 | 1 | C,DC,N,OV,Z |
| | | SUBR | f,WREG | WREG = WREG – f | 1 | 1 | C,DC,N,OV,Z |
| | | SUBR | Wb,Ws,Wd | Wd = Ws – Wb | 1 | 1 | C,DC,N,OV,Z |
| | | SUBR | Wb,#lit5,Wd | Wd = lit5 – Wb | 1 | 1 | C,DC,N,OV,Z |
| 75 | SUBBR | SUBBR | f | f = WREG – f – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBBR | f,WREG | WREG = WREG – f – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBBR | Wb,Ws,Wd | Wd = Ws – Wb – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| | | SUBBR | Wb,#lit5,Wd | Wd = lit5 – Wb – ($\overline{C}$) | 1 | 1 | C,DC,N,OV,Z |
| 76 | SWAP | SWAP.b | Wn | Wn = nibble swap Wn | 1 | 1 | None |
| | | SWAP | Wn | Wn = byte swap Wn | 1 | 1 | None |
| 77 | TBLRDH | TBLRDH | Ws,Wd | Read Prog<23:16> to Wd<7:0> | 1 | 2 | None |
| 78 | TBLRDL | TBLRDL | Ws,Wd | Read Prog<15:0> to Wd | 1 | 2 | None |
| 79 | TBLWTH | TBLWTH | Ws,Wd | Write Ws<7:0> to Prog<23:16> | 1 | 2 | None |
| 80 | TBLWTL | TBLWTL | Ws,Wd | Write Ws to Prog<15:0> | 1 | 2 | None |
| 81 | ULNK | ULNK | | Unlink Frame Pointer | 1 | 1 | None |
| 82 | XOR | XOR | f | f = f .XOR. WREG | 1 | 1 | N,Z |
| | | XOR | f,WREG | WREG = f .XOR. WREG | 1 | 1 | N,Z |
| | | XOR | #lit10,Wn | Wd = lit10 .XOR. Wd | 1 | 1 | N,Z |
| | | XOR | Wb,Ws,Wd | Wd = Wb .XOR. Ws | 1 | 1 | N,Z |
| | | XOR | Wb,#lit5,Wd | Wd = Wb .XOR. lit5 | 1 | 1 | N,Z |
| 83 | ZE | ZE | Ws,Wnd | Wnd = Zero-extend Ws | 1 | 1 | C,Z,N |


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## 23.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers and dsPIC® digital signal controllers are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB C Compiler for Various Device Families
  - HI-TECH C for Various Device Families
  - MPASM™ Assembler
  - MPLINK™ Object Linker/ MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
  - MPLAB SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers
  - MPLAB ICD 3
  - PICkit™ 3 Debug Express
- Device Programmers
  - PICkit™ 2 Programmer
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits, and Starter Kits

### 23.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16/32-bit microcontroller market. The MPLAB IDE is a Windows® operating system-based application that contains:

- A single graphical interface to all debugging tools
  - Simulator
  - Programmer (sold separately)
  - In-Circuit Emulator (sold separately)
  - In-Circuit Debugger (sold separately)
- A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- High-level source code debugging
- Mouse over variable inspection
- Drag and drop variables from source to watch windows
- Extensive on-line help
- Integration of select third party tools, such as IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either C or assembly)
- One-touch compile or assemble, and download to emulator and simulator tools (automatically updates all project information)
- Debug using:
  - Source files (C or assembly)
  - Mixed C and assembly
  - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

## 23.2 MPLAB C Compilers for Various Device Families

The MPLAB C Compiler code development systems are complete ANSI C compilers for Microchip's PIC18, PIC24 and PIC32 families of microcontrollers and the dsPIC30 and dsPIC33 families of digital signal controllers. These compilers provide powerful integration capabilities, superior code optimization and ease of use.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

## 23.3 HI-TECH C for Various Device Families

The HI-TECH C Compiler code development systems are complete ANSI C compilers for Microchip's PIC family of microcontrollers and the dsPIC family of digital signal controllers. These compilers provide powerful integration capabilities, omniscient code generation and ease of use.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

The compilers include a macro assembler, linker, preprocessor, and one-step driver, and can run on multiple platforms.

## 23.4 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel® standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code and COFF files for debugging.

The MPASM Assembler features include:

- Integration into MPLAB IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multi-purpose source files
- Directives that allow complete control over the assembly process

## 23.5 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler and the MPLAB C18 C Compiler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

## 23.6 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC devices. MPLAB C Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- Support for the entire device instruction set
- Support for fixed-point and floating-point data
- Command line interface
- Rich directive set
- Flexible macro language
- MPLAB IDE compatibility


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## 23.7 MPLAB SIM Software Simulator

The MPLAB SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC® DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB SIM Software Simulator fully supports symbolic debugging using the MPLAB C Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

## 23.8 MPLAB REAL ICE In-Circuit Emulator System

MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs PIC® Flash MCUs and dsPIC® Flash DSCs with the easy-to-use, powerful graphical user interface of the MPLAB Integrated Development Environment (IDE), included with each kit.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB IDE. In upcoming releases of MPLAB IDE, new devices will be supported, and new features will be added. MPLAB REAL ICE offers significant advantages over competitive emulators including low-cost, full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, a ruggedized probe interface and long (up to three meters) interconnection cables.

## 23.9 MPLAB ICD 3 In-Circuit Debugger System

MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost effective high-speed hardware debugger/programmer for Microchip Flash Digital Signal Controller (DSC) and microcontroller (MCU) devices. It debugs and programs PIC® Flash microcontrollers and dsPIC® DSCs with the powerful, yet easy-to-use graphical user interface of MPLAB Integrated Development Environment (IDE).

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

## 23.10 PICkit 3 In-Circuit Debugger/ Programmer and PICkit 3 Debug Express

The MPLAB PICkit 3 allows debugging and programming of PIC® and dsPIC® Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB Integrated Development Environment (IDE). The MPLAB PICkit 3 is connected to the design engineer's PC using a full speed USB interface and can be connected to the target via an Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the reset line to implement in-circuit debugging and In-Circuit Serial Programming™.

The PICkit 3 Debug Express include the PICkit 3, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

## 23.11 PICkit 2 Development Programmer/Debugger and PICkit 2 Debug Express

The PICkit™ 2 Development Programmer/Debugger is a low-cost development tool with an easy to use interface for programming and debugging Microchip's Flash families of microcontrollers. The full featured Windows® programming interface supports baseline (PIC10F, PIC12F5xx, PIC16F5xx), midrange (PIC12F6xx, PIC16F), PIC18F, PIC24, dsPIC30, dsPIC33, and PIC32 families of 8-bit, 16-bit, and 32-bit microcontrollers, and many Microchip Serial EEPROM products. With Microchip's powerful MPLAB Integrated Development Environment (IDE) the PICkit™ 2 enables in-circuit debugging on most PIC® microcontrollers. In-Circuit-Debugging runs, halts and single steps the program while the PIC microcontroller is embedded in the application. When halted at a breakpoint, the file registers can be examined and modified.

The PICkit 2 Debug Express include the PICkit 2, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

## 23.12 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages and a modular, detachable socket assembly to support various package types. The ICSP™ cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices and incorporates an MMC card for file storage and data applications.

## 23.13 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM™ and dsPICDEM™ demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ® security ICs, CAN, IrDA®, PowerSmart battery management, SEEVAL® evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page (www.microchip.com) for the complete list of demonstration, development and evaluation kits.


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## 24.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of dsPIC33FJ12MC201/202 electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the dsPIC33FJ12MC201/202 family are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these or any other conditions above the parameters indicated in the operation listings of this specification is not implied.

### Absolute Maximum Ratings(1)

Ambient temperature under bias ..... -40°C to +125°C
Storage temperature ..... -65°C to +150°C
Voltage on $V_{DD}$ with respect to $V_{SS}$ ..... -0.3V to +4.0V
Voltage on any pin that is not 5V tolerant with respect to $V_{SS}$(4) ..... -0.3V to ($V_{DD}$ + 0.3V)
Voltage on any 5V tolerant pin with respect to $V_{SS}$ when $V_{DD} \geq 3.0V$(4) ..... -0.3V to +5.6V
Voltage on any 5V tolerant pin with respect to $V_{SS}$ when $V_{DD} < 3.0V$(4) ..... -0.3V to ($V_{DD}$ + 0.3V)
Maximum current out of $V_{SS}$ pin ..... 300 mA
Maximum current into $V_{DD}$ pin(2) ..... 250 mA
Maximum output current sunk by any I/O pin(3) ..... 4 mA
Maximum output current sourced by any I/O pin(3) ..... 4 mA
Maximum current sunk by all ports ..... 200 mA
Maximum current sourced by all ports(2) ..... 200 mA

**Note 1:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

**2:** Maximum allowable current is a function of device maximum power dissipation (see Table 24-2).

**3:** Exceptions are CLKOUT, which is able to sink/source 25 mA, and the $V_{REF}$+, $V_{REF}$-, SCLx, SDAx, PGECx, and PGEDx pins, which are able to sink/source 12 mA.

**4:** See the **“Pin Diagrams”** section for 5V tolerant pins.

## 24.1 DC Characteristics

**TABLE 24-1: OPERATING MIPS VS. VOLTAGE**

| Characteristic | VDD Range (in Volts) | Temp Range (in °C) | Max MIPS |
|---|---|---|---|
| | | | dsPIC33FJ12MC201/202 |
| — | 3.0-3.6V | -40°C to +85°C | 40 |
| — | 3.0-3.6V | -40°C to +125°C | 40 |

**TABLE 24-2: THERMAL OPERATING CONDITIONS**

| Rating | Symbol | Min | Typ | Max | Unit |
|---|---|---|---|---|---|
| Industrial Temperature Devices | | | | | |
| Operating Junction Temperature Range | $T_J$ | -40 | — | +125 | °C |
| Operating Ambient Temperature Range | $T_A$ | -40 | — | +85 | °C |
| Extended Temperature Devices | | | | | |
| Operating Junction Temperature Range | $T_J$ | -40 | — | +140 | °C |
| Operating Ambient Temperature Range | $T_A$ | -40 | — | +125 | °C |
| Power Dissipation:<br>Internal chip power dissipation:<br>$P_{INT} = V_{DD} \times (I_{DD} - \Sigma I_{OH})$<br>I/O Pin Power Dissipation:<br>$I/O = \Sigma (\{V_{DD} - V_{OH}\} \times I_{OH}) + \Sigma (V_{OL} \times I_{OL})$ | $P_D$ | $P_{INT} + P_{I/O}$ | | | W |
| Maximum Allowed Power Dissipation | $P_{DMAX}$ | $(T_J - T_A)/\theta_{JA}$ | | | W |

**TABLE 24-3: THERMAL PACKAGING CHARACTERISTICS**

| Characteristic | Symbol | Typ | Max | Unit | Notes |
|---|---|---|---|---|---|
| Package Thermal Resistance, 20-pin PDIP | $\theta_{JA}$ | 45 | — | °C/W | **1** |
| Package Thermal Resistance, 28-pin SPDIP | $\theta_{JA}$ | 45 | — | °C/W | **1** |
| Package Thermal Resistance, 20-pin SOIC | $\theta_{JA}$ | 60 | — | °C/W | **1** |
| Package Thermal Resistance, 28-pin SOIC | $\theta_{JA}$ | 50 | — | °C/W | **1** |
| Package Thermal Resistance, 20-pin SSOP | $\theta_{JA}$ | 108 | — | °C/W | **1** |
| Package Thermal Resistance, 28-pin SSOP | $\theta_{JA}$ | 71 | — | °C/W | **1** |
| Package Thermal Resistance, 28-pin QFN | $\theta_{JA}$ | 35 | — | °C/W | **1** |

**Note 1:** Junction to ambient thermal resistance, Theta-JA ($\theta_{JA}$) numbers are achieved by package simulations.


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**TABLE 24-4: DC TEMPERATURE AND VOLTAGE SPECIFICATIONS**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| **Operating Voltage** | | | | | | | |
| DC10 | **Supply Voltage** | | | | | | |
| | VDD | | 3.0 | — | 3.6 | V | Industrial and Extended |
| DC12 | VDR | **RAM Data Retention Voltage(2)** | 1.8 | — | — | V | — |
| DC16 | VPOR | **VDD Start Voltage(3)** to ensure internal Power-on Reset signal | — | — | VSS | V | — |
| DC17 | SVDD | **VDD Rise Rate** to ensure internal Power-on Reset signal | 0.03 | — | — | V/ms | 0-3.0V in 0.1s |

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**2:** This is the limit to which VDD may be lowered without losing RAM data.

**3:** VDD voltage must remain at VSS for a minimum of 200 µs to ensure POR.

**TABLE 24-5: DC CHARACTERISTICS: OPERATING CURRENT (IDD)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Parameter No.** | **Typical(1)** | **Max** | **Units** | **Conditions** | | |
| **Operating Current (IDD)(2)** | | | | | | |
| DC20d | 24 | 30 | mA | -40°C | 3.3V | 10 MIPS(3) |
| DC20a | 27 | 30 | mA | +25°C | | |
| DC20b | 27 | 30 | mA | +85°C | | |
| DC20c | 27 | 35 | mA | +125°C | | |
| DC21d | 30 | 40 | mA | -40°C | 3.3V | 16 MIPS(3) |
| DC21a | 31 | 40 | mA | +25°C | | |
| DC21b | 32 | 45 | mA | +85°C | | |
| DC21c | 33 | 45 | mA | +125°C | | |
| DC22d | 35 | 50 | mA | -40°C | 3.3V | 20 MIPS(3) |
| DC22a | 38 | 50 | mA | +25°C | | |
| DC22b | 38 | 55 | mA | +85°C | | |
| DC22c | 39 | 55 | mA | +125°C | | |
| DC23d | 47 | 70 | mA | -40°C | 3.3V | 30 MIPS(3) |
| DC23a | 48 | 70 | mA | +25°C | | |
| DC23b | 48 | 70 | mA | +85°C | | |
| DC23c | 48 | 70 | mA | +125°C | | |
| DC24d | 56 | 90 | mA | -40°C | 3.3V | 40 MIPS |
| DC24a | 56 | 90 | mA | +25°C | | |
| DC24b | 54 | 90 | mA | +85°C | | |
| DC24c | 54 | 90 | mA | +125°C | | |

**Note 1:** Data in "Typical" column is at 3.3V, 25°C unless otherwise stated.

**2:** The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows: OSC1 driven with external square wave from rail to rail. All I/O pins are configured as inputs and pulled to VSS. MCLR = VDD, WDT and FSCM are disabled. CPU, SRAM, program memory and data memory are operational. No peripheral modules are operating; however, every peripheral is being clocked (PMD bits are all zeroed).

**3:** These parameters are characterized, but not tested in manufacturing.


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**TABLE 24-6: DC CHARACTERISTICS: IDLE CURRENT (IIDLE)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Parameter No.** | **Typical(1)** | **Max** | **Units** | **Conditions** | | |
| **Idle Current (IIDLE): Core OFF Clock ON Base Current(2)** | | | | | | |
| DC40d | 3 | 25 | mA | -40°C | 3.3V | 10 MIPS(3) |
| DC40a | 3 | 25 | mA | +25°C | | |
| DC40b | 3 | 25 | mA | +85°C | | |
| DC40c | 3 | 25 | mA | +125°C | | |
| DC41d | 4 | 25 | mA | -40°C | 3.3V | 16 MIPS(3) |
| DC41a | 4 | 25 | mA | +25°C | | |
| DC41b | 5 | 25 | mA | +85°C | | |
| DC41c | 5 | 25 | mA | +125°C | | |
| DC42d | 6 | 25 | mA | -40°C | 3.3V | 20 MIPS(3) |
| DC42a | 6 | 25 | mA | +25°C | | |
| DC42b | 7 | 25 | mA | +85°C | | |
| DC42c | 7 | 25 | mA | +125°C | | |
| DC43a | 9 | 25 | mA | +25°C | 3.3V | 30 MIPS(3) |
| DC43d | 9 | 25 | mA | -40°C | | |
| DC43b | 9 | 25 | mA | +85°C | | |
| DC43c | 9 | 25 | mA | +125°C | | |
| DC44d | 10 | 25 | mA | -40°C | 3.3V | 40 MIPS |
| DC44a | 10 | 25 | mA | +25°C | | |
| DC44b | 10 | 25 | mA | +85°C | | |
| DC44c | 10 | 25 | mA | +125°C | | |

**Note 1:** Data in “Typical” column is at 3.3V, 25°C unless otherwise stated.

**2:** Base IIDLE current is measured with core off, clock on and all modules turned off. Peripheral Module Disable SFR registers are zeroed. All I/O pins are configured as inputs and pulled to VSS.

**3:** These parameters are characterized, but not tested in manufacturing.

**TABLE 24-7: DC CHARACTERISTICS: POWER-DOWN CURRENT ($I_{PD}$)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Parameter No.** | **Typical(1)** | **Max** | **Units** | **Conditions** | | |
| **Power-Down Current ($I_{PD}$)(2)** | | | | | | |
| DC60d | 55 | 500 | µA | -40°C | 3.3V | Base Power-Down Current(3,4) |
| DC60a | 63 | 500 | µA | +25°C | | |
| DC60b | 85 | 500 | µA | +85°C | | |
| DC60c | 146 | 1000 | µA | +125°C | | |
| DC61d | 8 | 13 | µA | -40°C | 3.3V | Watchdog Timer Current: $\Delta I_{WDT}$(3,5) |
| DC61a | 10 | 15 | µA | +25°C | | |
| DC61b | 12 | 20 | µA | +85°C | | |
| DC61c | 13 | 25 | µA | +125°C | | |

**Note 1:** Data in the Typical column is at 3.3V, 25°C unless otherwise stated.

**2:** Base $I_{PD}$ is measured with all peripherals and clocks shut down. All I/Os are configured as inputs and pulled to $V_{SS}$. WDT, etc., are all switched off, and VREGS (RCON<8>) = 1.

**3:** The Δ current is the additional current consumed when the module is enabled. This current should be added to the base $I_{PD}$ current.

**4:** These currents are measured on the device containing the most memory in this family.

**5:** These parameters are characterized, but not tested in manufacturing.

**TABLE 24-8: DC CHARACTERISTICS: DOZE CURRENT ($I_{DOZE}$)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Parameter No.** | **Typical(1)** | **Max** | **Doze Ratio(2)** | **Units** | **Conditions** | | |
| DC73a | 11 | 35 | 1:2 | mA | -40°C | 3.3V | 40 MIPS |
| DC73f | 11 | 30 | 1:64 | mA | | | |
| DC73g | 11 | 30 | 1:128 | mA | | | |
| DC70a | 11 | 50 | 1:2 | mA | +25°C | 3.3V | 40 MIPS |
| DC70f | 11 | 30 | 1:64 | mA | | | |
| DC70g | 11 | 30 | 1:128 | mA | | | |
| DC71a | 12 | 50 | 1:2 | mA | +85°C | 3.3V | 40 MIPS |
| DC71f | 12 | 30 | 1:64 | mA | | | |
| DC71g | 12 | 30 | 1:128 | mA | | | |
| DC72a | 12 | 50 | 1:2 | mA | +125°C | 3.3V | 40 MIPS |
| DC72f | 12 | 30 | 1:64 | mA | | | |
| DC72g | 12 | 30 | 1:128 | mA | | | |

**Note 1:** Data in the Typical column is at 3.3V, 25°C unless otherwise stated.

**2:** Parameters with DOZE ratios of 1:2 and 1:64 are characterized, but are not tested in manufacturing.


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**TABLE 24-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| | VIL | **Input Low Voltage** | | | | | |
| DI10 | | I/O pins | VSS | — | 0.2 VDD | V | |
| DI15 | | $\overline{\text{MCLR}}$ | VSS | — | 0.2 VDD | V | |
| DI16 | | I/O Pins with OSC1 or SOSCI | VSS | — | 0.2 VDD | V | |
| DI18 | | SDA, SCL | VSS | — | 0.3 VDD | V | SMBus disabled |
| DI19 | | SDA, SCL | VSS | — | 0.8 | V | SMBus enabled |
| | VIH | **Input High Voltage(10)** | | | | | |
| DI20 | | I/O Pins Not 5V Tolerant(4) | 0.7 VDD | — | VDD | V | |
| | | I/O Pins 5V Tolerant(4) | 0.7 VDD | — | 5.5 | V | |
| DI21 | | I/O Pin with Schmitt Trigger Input | 0.7 VDD | — | 0.8 VDD | V | |
| DI25 | | $\overline{\text{MCLR}}$ | 0.8 VDD | — | VDD | V | |
| DI26 | | OSC1 (in XT, HS, and LP modes) | 0.7 VDD | — | VDD | V | |
| DI27 | | OSC1 (in RC mode) | 0.9 VDD | — | VDD | V | |
| DI28 | | SDAx, SCLx | 0.7 VDD | — | VDD | V | SMBus disabled |
| DI29 | | SDAx, SCLx | 2.1 | — | VDD | V | SMBus enabled |
| | ICNPU | **CNx Pull-up Current** | | | | | |
| DI30 | | | 50 | 250 | 400 | µA | VDD = 3.3V, VPIN = VSS |

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**2:** The leakage current on the $\overline{\text{MCLR}}$ pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

**3:** Negative current is defined as current sourced by the pin.

**4:** See **“Pin Diagrams”** for a list of 5V tolerant pins.

**5:** VIL source < (VSS – 0.3). Characterized but not tested.

**6:** Non-5V tolerant pins VIH source > (VDD + 0.3), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.

**7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.

**8:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**10:** These parameters are characterized, but not tested.

**TABLE 24-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| | IIL | **Input Leakage Current(2,3)** | | | | | |
| DI50 | | I/O Pins 5V Tolerant(4) | — | — | ±2 | µA | VSS ≤VPIN ≤VDD, Pin at high-impedance |
| DI51 | | I/O Pins Not 5V Tolerant(4) | — | — | ±1 | µA | VSS ≤VPIN ≤VDD, Pin at high-impedance, -40°C ≤TA ≤+85°C |
| DI51a | | I/O Pins Not 5V Tolerant(4) | — | — | ±2 | µA | Shared with external reference pins, -40°C ≤TA ≤+85°C |
| DI51b | | I/O Pins Not 5V Tolerant(4) | — | — | ±3.5 | µA | VSS ≤VPIN ≤VDD, Pin at high-impedance, -40°C ≤TA ≤+125°C |
| DI51c | | I/O Pins Not 5V Tolerant(4) | — | — | ±8 | µA | Analog pins shared with external reference pins, -40°C ≤TA ≤+125°C |
| DI55 | | $\overline{\text{MCLR}}$ | — | — | ±2 | µA | VSS ≤VPIN ≤VDD |
| DI56 | | OSC1 | — | — | ±2 | µA | VSS ≤VPIN ≤VDD, XT and HS modes |

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**2:** The leakage current on the $\overline{\text{MCLR}}$ pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

**3:** Negative current is defined as current sourced by the pin.

**4:** See **“Pin Diagrams”** for a list of 5V tolerant pins.

**5:** VIL source < (VSS – 0.3). Characterized but not tested.

**6:** Non-5V tolerant pins VIH source > (VDD + 0.3), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.

**7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.

**8:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**10:** These parameters are characterized, but not tested.


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**TABLE 24-9: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS (CONTINUED)**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| DI60a | IICL | **Input Low Injection Current** | 0 | — | -5(5,8) | mA | All pins except VDD, VSS, AVDD, AVSS, MCLR, VCAP, SOSCI, and SOSCO |
| DI60b | IICH | **Input High Injection Current** | 0 | — | +5(6,7,8) | mA | All pins except VDD, VSS, AVDD, AVSS, MCLR, VCAP, SOSCI, SOSCO, and digital 5V-tolerant designated pins |
| DI60c | ∑IICT | **Total Input Injection Current (sum of all I/O and control pins)** | -20(9) | — | +20(9) | mA | Absolute instantaneous sum of all ± input injection currents from all I/O pins<br>( \| IICL + \| IICH \| ) ≤ ∑IICT |

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**2:** The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.

**3:** Negative current is defined as current sourced by the pin.

**4:** See **“Pin Diagrams”** for a list of 5V tolerant pins.

**5:** VIL source < (VSS – 0.3). Characterized but not tested.

**6:** Non-5V tolerant pins VIH source > (VDD + 0.3), 5V tolerant pins VIH source > 5.5V. Characterized but not tested.

**7:** Digital 5V tolerant pins cannot tolerate any “positive” input injection current from input sources > 5.5V.

**8:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**9:** Any number and/or combination of I/O pins not excluded under IICL or IICH conditions are permitted provided the mathematical “absolute instantaneous” sum of the input injection currents from all pins do not exceed the specified limit. Characterized but not tested.

**10:** These parameters are characterized, but not tested.

**TABLE 24-10: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| | VOL | **Output Low Voltage** | | | | | |
| DO10 | | I/O ports | — | — | 0.4 | V | IOL = 2 mA, VDD = 3.3V |
| DO16 | | OSC2/CLKO | — | — | 0.4 | V | IOL = 2 mA, VDD = 3.3V |
| | VOH | **Output High Voltage** | | | | | |
| DO20 | | I/O ports | 2.40 | — | — | V | IOH = -2.3 mA, VDD = 3.3V |
| DO26 | | OSC2/CLKO | 2.41 | — | — | V | IOH = -1.3 mA, VDD = 3.3V |

**TABLE 24-11: ELECTRICAL CHARACTERISTICS: BOR**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min(1)** | **Typ** | **Max(1)** | **Units** | **Conditions** |
| BO10 | VBOR | BOR Event on VDD transition high-to-low | 2.40 | — | 2.55 | V | VDD |

**Note 1:** Parameters are for design guidance only and are not tested in manufacturing.


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**TABLE 24-12: DC CHARACTERISTICS: PROGRAM MEMORY**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(3)** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| | | **Program Flash Memory** | | | | | |
| D130a | EP | Cell Endurance | 10,000 | — | — | E/W | -40° C to +125° C |
| D131 | VPR | VDD for Read | VMIN | — | 3.6 | V | VMIN = Minimum operating voltage |
| D132B | VPEW | VDD for Self-Timed Write | VMIN | — | 3.6 | V | VMIN = Minimum operating voltage |
| D134 | TRETD | Characteristic Retention | 20 | — | — | Year | Provided no other specifications are violated |
| D135 | IDDP | Supply Current during Programming | — | 10 | — | mA | |
| D136a | TRW | Row Write Time | 1.32 | — | 1.74 | ms | TRW = 11064 FRC cycles, TA = +85°C, See **Note 2** |
| D136b | TRW | Row Write Time | 1.28 | — | 1.79 | ms | TRW = 11064 FRC cycles, TA = +125°C, See **Note 2** |
| D137a | TPE | Page Erase Time | 20.1 | — | 26.5 | ms | TPE = 168517 FRC cycles, TA = +85°C, See **Note 2** |
| D137b | TPE | Page Erase Time | 19.5 | — | 27.3 | ms | TPE = 168517 FRC cycles, TA = +125°C, See **Note 2** |
| D138a | TWW | Word Write Cycle Time | 42.3 | — | 55.9 | µs | TWW = 355 FRC cycles, TA = +85°C, See **Note 2** |
| D138b | TWW | Word Write Cycle Time | 41.1 | — | 57.6 | µs | TWW = 355 FRC cycles, TA = +125°C, See **Note 2** |

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**2:** Other conditions: FRC = 7.37 MHz, TUN<5:0> = b'011111 (for Min), TUN<5:0> = b'100000 (for Max). This parameter depends on the FRC accuracy (see Table 24-18) and the value of the FRC Oscillator Tuning register (see Register 8-4). For complete details on calculating the Minimum and Maximum time see **Section 5.3 "Programming Operations"**.

**3:** These parameters are ensured by design, but are not characterized or tested in manufacturing.

**TABLE 24-13: INTERNAL VOLTAGE REGULATOR SPECIFICATIONS**

| DC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristics** | **Min** | **Typ** | **Max** | **Units** | **Comments** |
| | CEFC | External Filter Capacitor Value(1) | 4.7 | 10 | — | µF | Capacitor must be low series resistance (< 5 ohms) |

**Note 1:** Typical VCAP pin voltage = 2.5V when VDD ≥ VDDMIN.

## 24.2 AC Characteristics and Timing Parameters

This section defines dsPIC33FJ12MC201/202 AC characteristics and timing parameters.

**TABLE 24-14: TEMPERATURE AND VOLTAGE SPECIFICATIONS – AC**

| | |
|---|---|
| **AC CHARACTERISTICS** | **Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)**<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended<br>Operating voltage VDD range as described in **Section 24.1 "DC Characteristics"**. |

**FIGURE 24-1: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS**

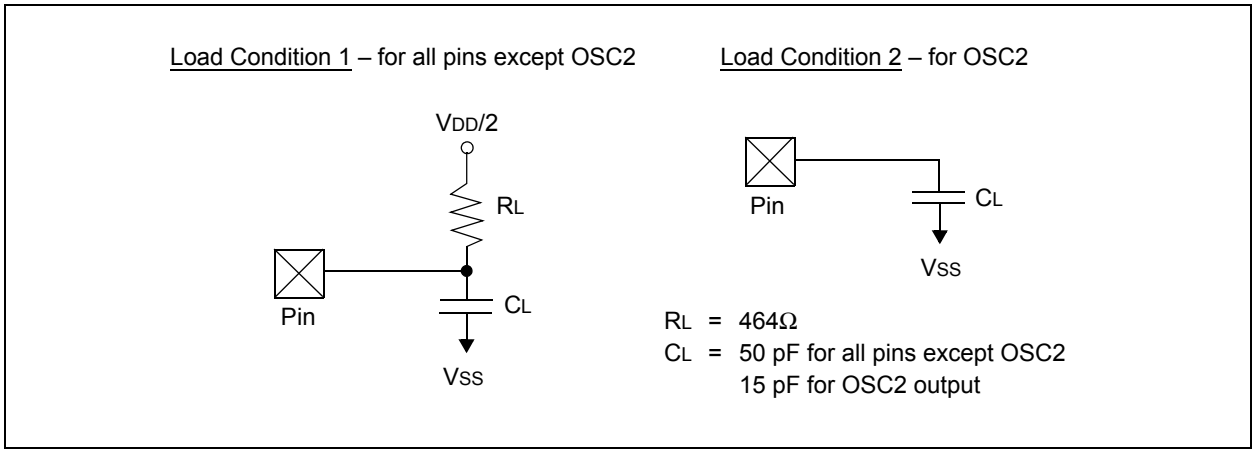


**TABLE 24-15: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS**

| Param No. | Symbol | Characteristic | Min | Typ | Max | Units | Conditions |
|---|---|---|---|---|---|---|---|
| DO50 | COSC2 | OSC2/SOSC2 pin | — | — | 15 | pF | In XT and HS modes when external clock is used to drive OSC1 |
| DO56 | CIO | All I/O pins and OSC2 | — | — | 50 | pF | EC mode |
| DO58 | CB | SCLx, SDAx | — | — | 400 | pF | In $I^2C$ mode |


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**FIGURE 24-2: EXTERNAL CLOCK TIMING**

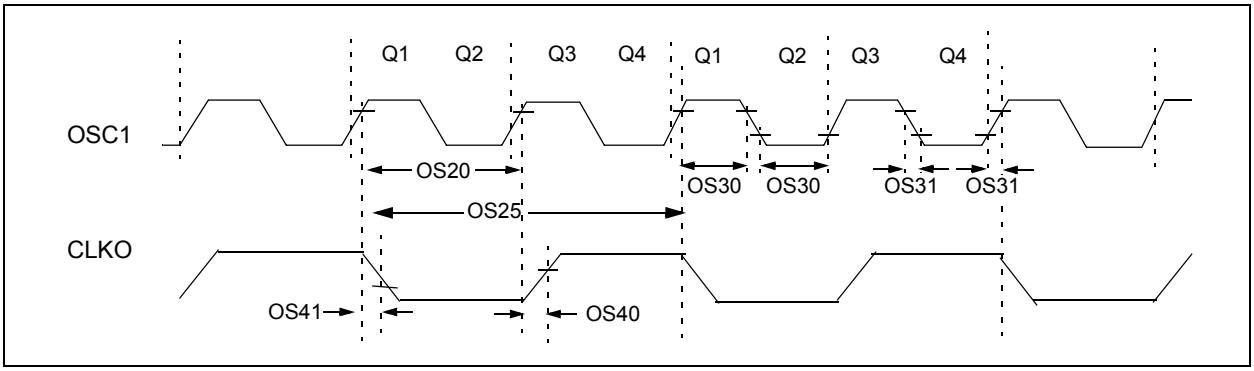


**TABLE 24-16: EXTERNAL CLOCK TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symb** | **Characteristic** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| OS10 | FIN | External CLKI Frequency (External clocks allowed only in EC and ECPLL modes) | DC | — | 40 | MHz | EC |
| | | Oscillator Crystal Frequency | 3.5<br>10<br>— | —<br>—<br>— | 10<br>40<br>33 | MHz<br>MHz<br>kHz | XT<br>HS<br>SOSC |
| OS20 | TOSC | TOSC = 1/FOSC | 12.5 | — | DC | ns | |
| OS25 | TCY | Instruction Cycle Time(2,4) | 25 | — | DC | ns | |
| OS30 | TosL, TosH | External Clock in (OSC1)(5) High or Low Time | 0.375 x TOSC | — | 0.625 x TOSC | ns | EC |
| OS31 | TosR, TosF | External Clock in (OSC1)(5) Rise or Fall Time | — | — | 20 | ns | EC |
| OS40 | TckR | CLKO Rise Time(3,5) | — | 5.2 | — | ns | — |
| OS41 | TckF | CLKO Fall Time(3,5) | — | 5.2 | — | ns | — |
| OS42 | GM | External Oscillator Transconductance(4) | 14 | 16 | 18 | mA/V | VDD = 3.3V<br>TA = +25ºC |

**Note 1:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**2:** Instruction cycle period (TCY) equals two times the input oscillator time-base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at “min.” values with an external clock applied to the OSC1/CLKI pin. When an external clock input is used, the “max.” cycle time limit is “DC” (no clock) for all devices.

**3:** Measurements are taken in EC mode. The CLKO signal is measured on the OSC2 pin.

**4:** These parameters are characterized by similarity, but are tested in manufacturing at FIN = 40 MHz only.

**5:** These parameters are characterized by similarity, but are not tested in manufacturing.

**6:** Data for this parameter is Preliminary. This parameter is characterized, but not tested in manufacturing.

**TABLE 24-17: PLL CLOCK TIMING SPECIFICATIONS (VDD = 3.0V TO 3.6V)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| OS50 | FPLLI | PLL Voltage Controlled Oscillator (VCO) Input Frequency Range | 0.8 | — | 8 | MHz | ECPLL, HSPLL, XTPLL modes |
| OS51 | FSYS | On-Chip VCO System Frequency | 100 | — | 200 | MHz | — |
| OS52 | TLOCK | PLL Start-up Time (Lock Time) | 0.9 | 1.5 | 3.1 | mS | — |
| OS53 | DCLK | CLKO Stability (Jitter)(2) | -3 | 0.5 | 3 | % | Measured over 100 ms period |

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing. This specification is based on clock cycle by clock cycle measurements. To calculate the effective jitter for individual time bases or communication clocks use this formula:

$$Peripheral\ Clock\ Jitter = \frac{DCLK}{\sqrt{\left(\frac{FOSC}{Peripheral\ Bit\ Rate\ Clock}\right)}}$$

For example: Fosc = 32 MHz, DCLK = 3%, SPI bit rate clock, (i.e., SCK) is 2 MHz.

$$SPI\ SCK\ Jitter = \left[\frac{DCLK}{\sqrt{\left(\frac{32\ MHz}{2\ MHz}\right)}}\right] = \left[\frac{3\%}{\sqrt{16}}\right] = \left[\frac{3\%}{4}\right] = 0.75\%$$

**TABLE 24-18: AC CHARACTERISTICS: INTERNAL RC ACCURACY**

| AC CHARACTERISTICS | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Characteristic** | **Min** | **Typ** | **Max** | **Units** | **Conditions** | |
| | **Internal FRC Accuracy @ 7.3728 MHz(1)** | | | | | | |
| F20a | FRC | -2 | — | +2 | % | -40°C ≤ TA ≤ +85°C | VDD = 3.0-3.6V |
| F20b | FRC | -5 | — | +5 | % | -40°C ≤ TA ≤ +125°C | VDD = 3.0-3.6V |

**Note 1:** Frequency calibrated at 25°C and 3.3V. TUN bits may be used to compensate for temperature drift.

**TABLE 24-19: INTERNAL RC ACCURACY**

| AC CHARACTERISTICS | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Characteristic** | **Min** | **Typ** | **Max** | **Units** | **Conditions** | |
| | **LPRC @ 32.768 kHz(1,2)** | | | | | | |
| F21a | LPRC | -20 | ±6 | +20 | % | -40°C ≤ TA ≤ +85°C | VDD = 3.0-3.6V |
| F21b | LPRC | -70 | — | +70 | % | -40°C ≤ TA ≤ +125°C | VDD = 3.0-3.6V |

**Note 1:** Change of LPRC frequency as VDD changes.

**2:** LPRC accuracy impacts the Watchdog Timer Time-out Period (TWDT1). See **Section 21.4 "Watchdog Timer (WDT)"** for more information.


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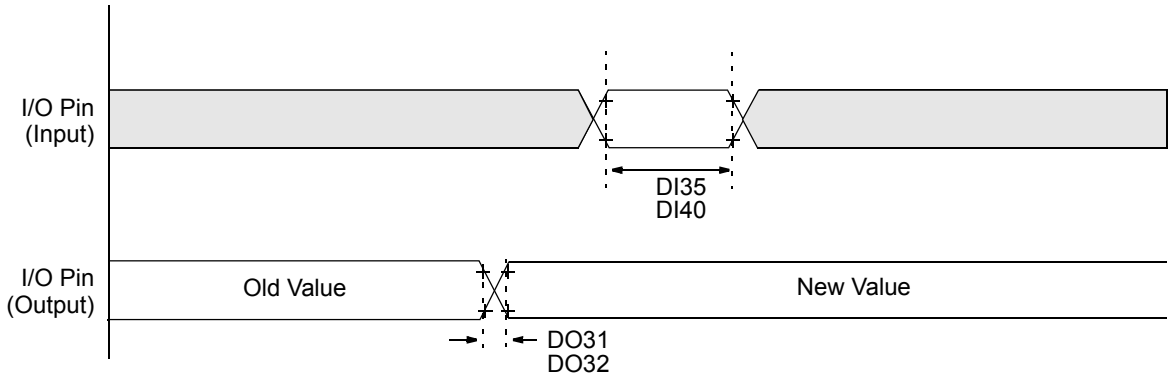
**FIGURE 24-3: CLKO AND I/O TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.

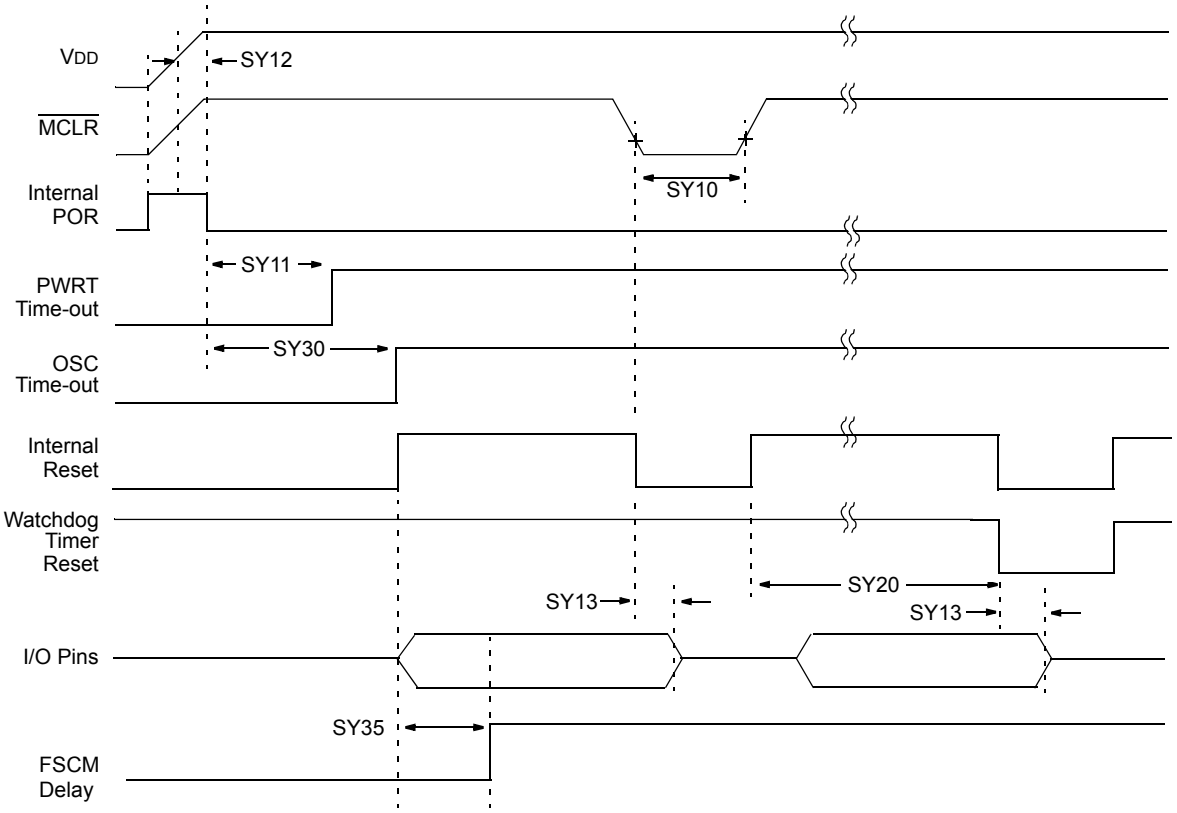
**TABLE 24-20: I/O TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(2)** | **Min** | **Typ(1)** | **Max** | **Units** | **Conditions** |
| DO31 | TIOR | Port Output Rise Time | — | 10 | 25 | ns | — |
| DO32 | TIOF | Port Output Fall Time | — | 10 | 25 | ns | — |
| DI35 | TINP | INTx Pin High or Low Time (input) | 25 | — | — | ns | — |
| DI40 | TRBP | CNx High or Low Time (input) | 2 | — | — | TCY | — |

**Note 1:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**2:** These parameters are characterized, but are not tested in manufacturing.

**FIGURE 24-4: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER AND POWER-UP TIMER TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-21: RESET, WATCHDOG TIMER, OSCILLATOR START-UP TIMER, POWER-UP TIMER TIMING REQUIREMENTS**

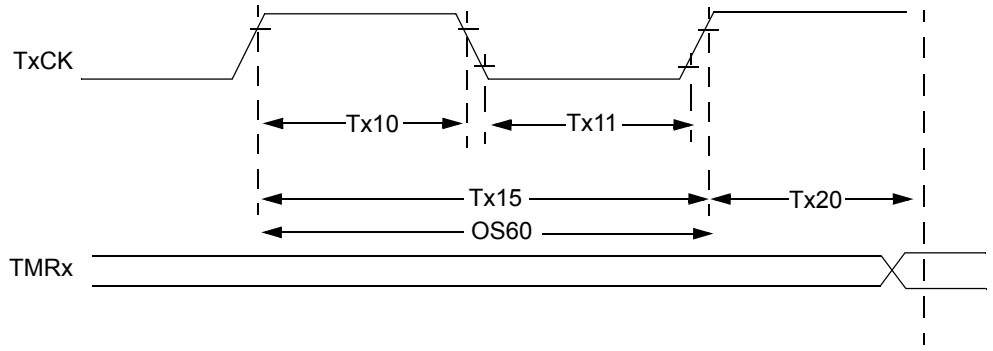
| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SY10 | TMCL | $\overline{\text{MCLR}}$ Pulse Width (low) | 2 | — | — | µs | -40°C to +85°C |
| SY11 | TPWRT | Power-up Timer Period(1) | — | 2<br>4<br>8<br>16<br>32<br>64<br>128 | — | ms | -40°C to +85°C<br>User programmable |
| SY12 | TPOR | Power-on Reset Delay(3) | 3 | 10 | 30 | µs | -40°C to +85°C |
| SY13 | TIOZ | I/O High-Impedance from $\overline{\text{MCLR}}$ Low or Watchdog Timer Reset(1) | 0.68 | 0.72 | 1.2 | µs | — |
| SY20 | TWDT1 | Watchdog Timer Time-out Period(1) | — | — | — | ms | See **Section 21.4 "Watchdog Timer (WDT)"** and LPRC parameter F21a (Table 24-19). |
| SY30 | TOST | Oscillator Start-up Time | — | 1024 TOSC | — | — | TOSC = OSC1 period |
| SY35 | TFSCM | Fail-Safe Clock Monitor Delay(1) | — | 500 | 900 | µs | -40°C to +85°C |

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** These parameters are characterized, but are not tested in manufacturing.

**FIGURE 24-5: TIMER1, 2, 3 AND 4 EXTERNAL CLOCK TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.

**TABLE 24-22: TIMER1 EXTERNAL CLOCK TIMING REQUIREMENTS(1)**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| TA10 | TTXH | TxCK High Time | Synchronous, no prescaler | TCY + 20 | — | — | ns | Must also meet parameter TA15. N = prescale value (1, 8, 64, 256) |
| | | | Synchronous, with prescaler | (TCY + 20)/N | — | — | ns | |
| | | | Asynchronous | 20 | — | — | ns | |
| TA11 | TTXL | TxCK Low Time | Synchronous, no prescaler | (TCY + 20) | — | — | ns | Must also meet parameter TA15. N = prescale value (1, 8, 64, 256) |
| | | | Synchronous, with prescaler | (TCY + 20)/N | — | — | ns | |
| | | | Asynchronous | 20 | — | — | ns | |
| TA15 | TTXP | TxCK Input Period | Synchronous, no prescaler | 2 TCY + 40 | — | — | ns | — |
| | | | Synchronous, with prescaler | Greater of: 40 ns or (2 TCY + 40)/ N | — | — | — | N = prescale value (1, 8, 64, 256) |
| | | | Asynchronous | 40 | — | — | ns | — |
| OS60 | Ft1 | SOSCI/T1CK Oscillator Input frequency Range (oscillator enabled by setting bit TCS (T1CON<1>)) | | DC | — | 50 | kHz | — |
| TA20 | TCKEXTMRL | Delay from External TxCK Clock Edge to Timer Increment | | 0.75 TCY + 40 | | 1.75 TCY + 40 | — | — |

**Note 1:** Timer1 is a Type A.


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**TABLE 24-23: TIMER2 AND TIMER4 EXTERNAL CLOCK TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| TB10 | TtxH | TxCK High Time | Synchronous mode | Greater of: 20 or (TCY + 20)/N | — | — | ns | Must also meet parameter TB15<br>N = prescale value (1, 8, 64, 256) |
| TB11 | TtxL | TxCK Low Time | Synchronous mode | Greater of: 20 or (TCY + 20)/N | — | — | ns | Must also meet parameter TB15<br>N = prescale value (1, 8, 64, 256) |
| TB15 | TtxP | TxCK Input Period | Synchronous mode | Greater of: 40 or (2 TCY + 40)/N | — | — | ns | N = prescale value (1, 8, 64, 256) |
| TB20 | TCKEXTMRL | Delay from External TxCK Clock Edge to Timer Increment | | 0.75 TCY + 40 | — | 1.75 TCY + 40 | ns | — |

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**TABLE 24-24: TIMER3 AND TIMER5 EXTERNAL CLOCK TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| TC10 | TtxH | TxCK High Time | Synchronous | TCY + 20 | — | — | ns | Must also meet parameter TC15 |
| TC11 | TtxL | TxCK Low Time | Synchronous | TCY + 20 | — | — | ns | Must also meet parameter TC15 |
| TC15 | TtxP | TxCK Input Period | Synchronous, with prescaler | 2 TCY + 40 | — | — | ns | N = prescale value (1, 8, 64, 256) |
| TC20 | TCKEXTMRL | Delay from External TxCK Clock Edge to Timer Increment | | 0.75 TCY + 40 | — | 1.75 TCY + 40 | ns | — |

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**FIGURE 24-6: TIMERQ (QEI MODULE) EXTERNAL CLOCK TIMING CHARACTERISTICS**

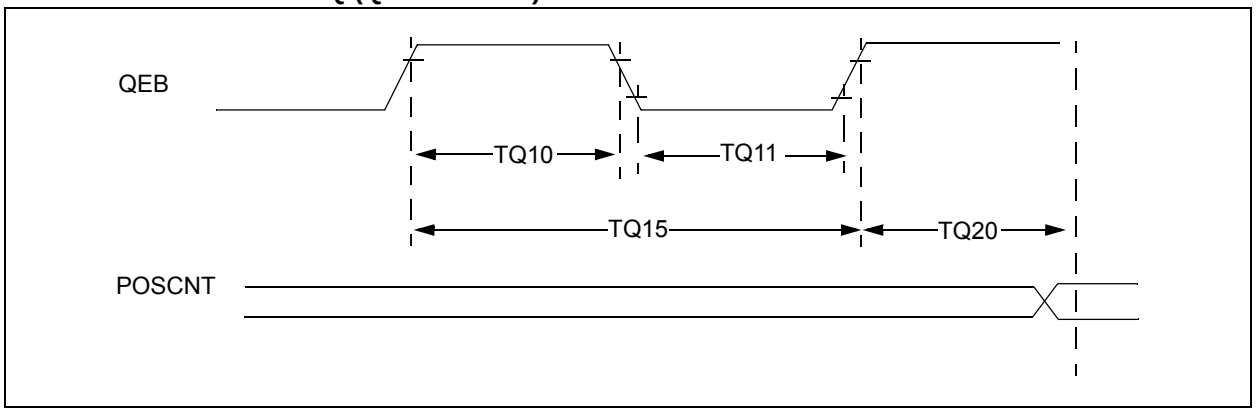
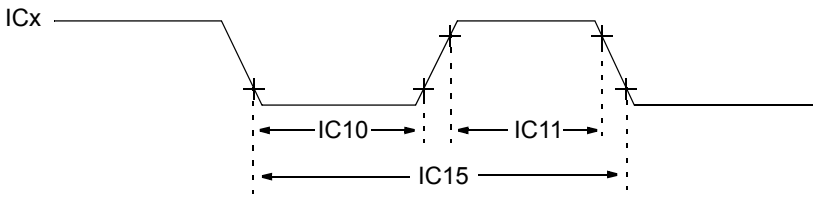



**TABLE 24-25: QEI MODULE EXTERNAL CLOCK TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| TQ10 | TtQH | TQCK High Time | Synchronous, with prescaler | TCY + 20 | | — | ns | Must also meet parameter TQ15 |
| TQ11 | TtQL | TQCK Low Time | Synchronous, with prescaler | TCY + 20 | | — | ns | Must also meet parameter TQ15 |
| TQ15 | TtQP | TQCP Input Period | Synchronous, with prescaler | 2 * TCY + 40 | | — | ns | — |
| TQ20 | TCKEXTMRL | Delay from External TxCK Clock Edge to Timer Increment | | 0.5 TCY | | 1.5 TCY | — | — |

**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**FIGURE 24-7: INPUT CAPTURE (CAPx) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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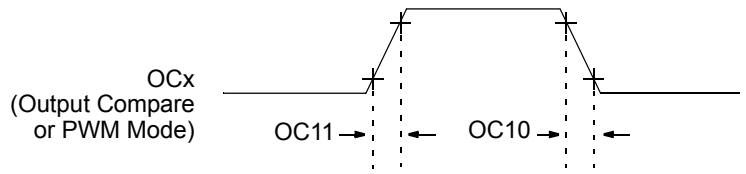
**TABLE 24-26: INPUT CAPTURE TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | | **Min** | **Max** | **Units** | **Conditions** |
| IC10 | TccL | ICx Input Low Time | No Prescaler | 0.5 TCY + 20 | — | ns | — |
| | | | With Prescaler | 10 | — | ns | |
| IC11 | TccH | ICx Input High Time | No Prescaler | 0.5 TCY + 20 | — | ns | — |
| | | | With Prescaler | 10 | — | ns | |
| IC15 | TccP | ICx Input Period | | (TCY + 40)/N | — | ns | N = prescale value (1, 4, 16) |

**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**FIGURE 24-8: OUTPUT COMPARE MODULE (OCx) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.

**TABLE 24-27: OUTPUT COMPARE MODULE TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| OC10 | TccF | OCx Output Fall Time | — | — | — | ns | See parameter D032 |
| OC11 | TccR | OCx Output Rise Time | — | — | — | ns | See parameter D031 |

**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**FIGURE 24-9: OC/PWM MODULE TIMING CHARACTERISTICS**

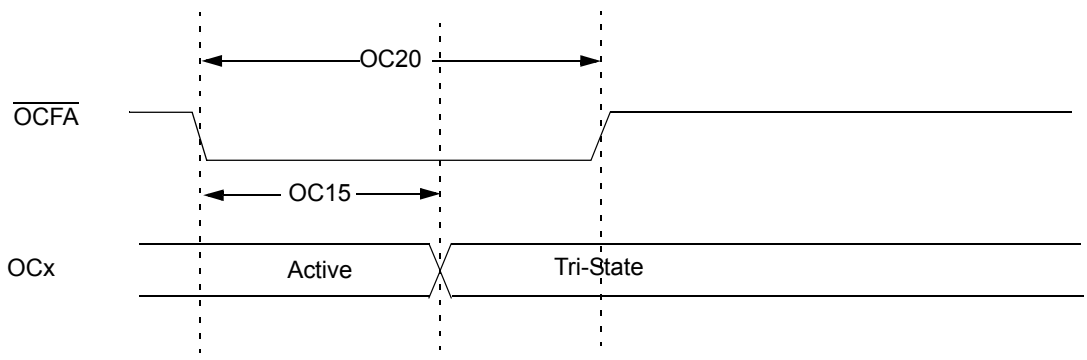


**TABLE 24-28: SIMPLE OC/PWM MODE TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| OC15 | TFD | Fault Input to PWM I/O Change | — | — | TCY + 20 | ns | — |
| OC20 | TFLT | Fault Input Pulse Width | TCY + 20 | — | — | ns | — |

**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**FIGURE 24-10: MOTOR CONTROL PWM MODULE FAULT TIMING CHARACTERISTICS**

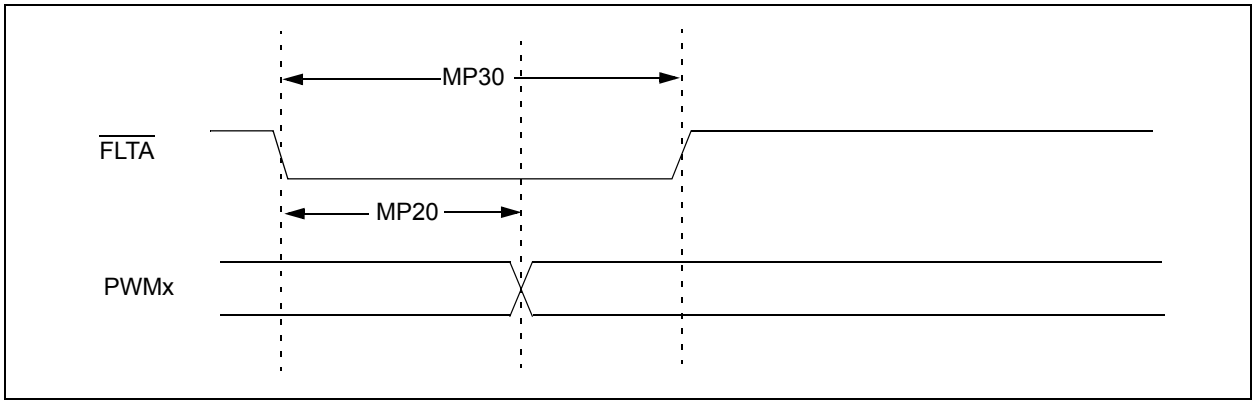
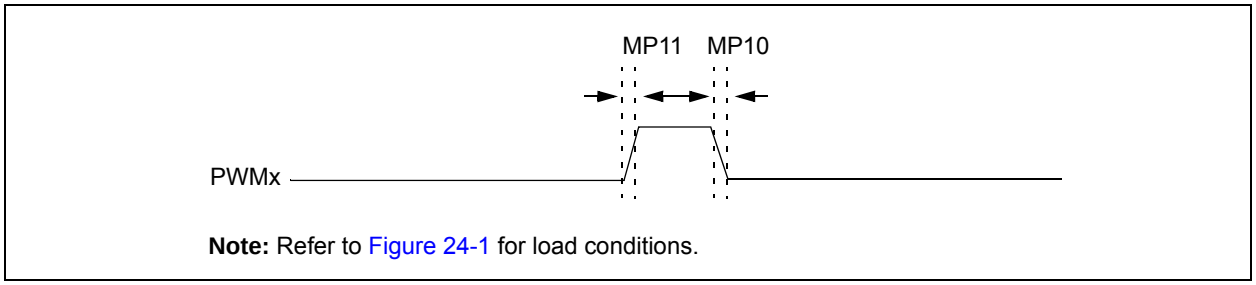



**FIGURE 24-11: MOTOR CONTROL PWM MODULE TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-29: MOTOR CONTROL PWM MODULE TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ** | **Max** | **Units** | **Conditions** |
| MP10 | TFPWM | PWM Output Fall Time | — | — | — | ns | See parameter D032 |
| MP11 | TRPWM | PWM Output Rise Time | — | — | — | ns | See parameter D031 |
| MP20 | TFD | Fault Input ↓ to PWM I/O Change | — | — | 50 | ns | — |
| MP30 | TFH | Minimum Pulse Width | 50 | — | — | ns | — |

**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**FIGURE 24-12: QEA/QEB INPUT CHARACTERISTICS**

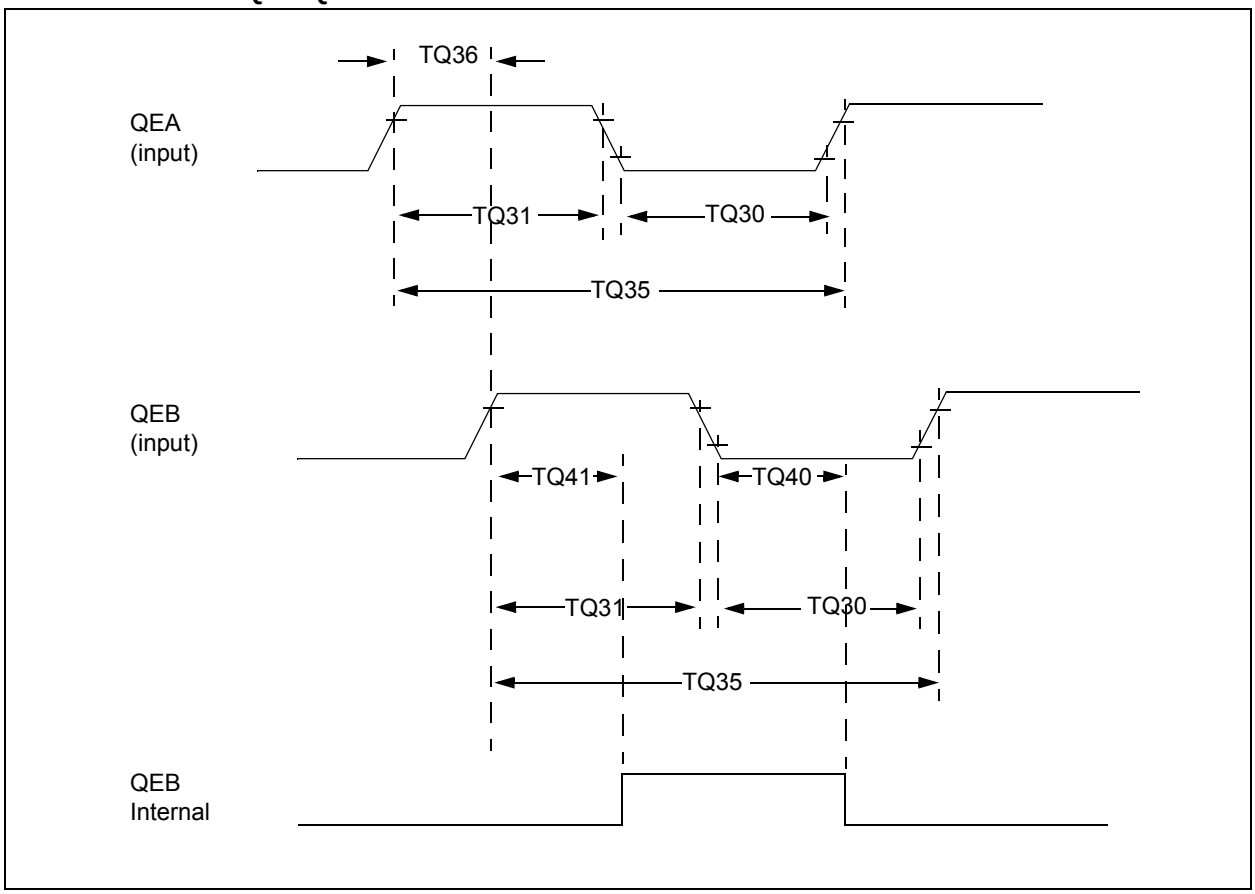

**TABLE 24-30: QUADRATURE DECODER TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| TQ30 | TQUL | Quadrature Input Low Time | 6 TCY | — | ns | — |
| TQ31 | TQUH | Quadrature Input High Time | 6 TCY | — | ns | — |
| TQ35 | TQUIN | Quadrature Input Period | 12 TCY | — | ns | — |
| TQ36 | TQUP | Quadrature Phase Period | 3 TCY | — | ns | — |
| TQ40 | TQUFL | Filter Time to Recognize Low, with Digital Filter | 3 * N * TCY | — | ns | N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)** |
| TQ41 | TQUFH | Filter Time to Recognize High, with Digital Filter | 3 * N * TCY | — | ns | N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 3)** |

**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

**3:** N = Index Channel Digital Filter Clock Divide Select bits. Refer to **Section 15. "Quadrature Encoder Interface (QEI)"** (DS70208) in the *dsPIC33F/PIC24H Family Reference Manual*. Please see the Microchip (www.microchip.com) web site for the latest family reference manual chapters.

**FIGURE 24-13: QEI MODULE INDEX PULSE TIMING CHARACTERISTICS**

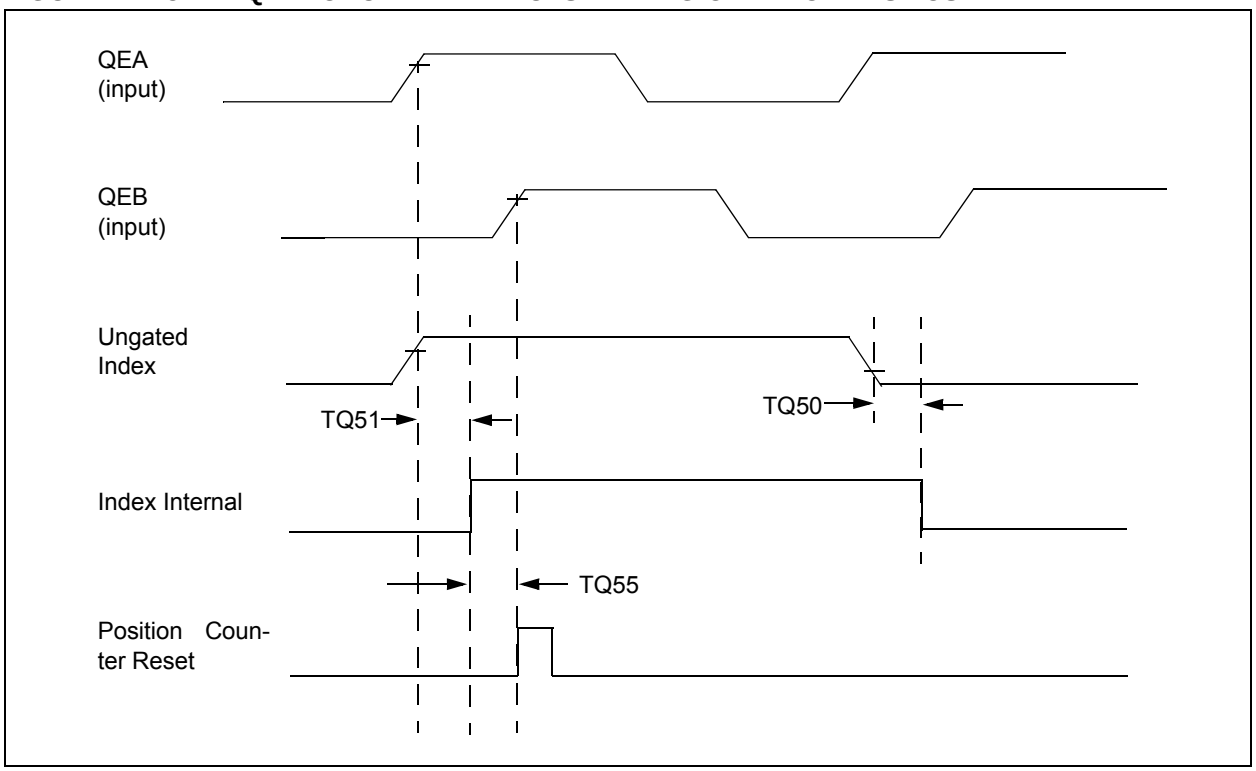



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**TABLE 24-31: QEI INDEX PULSE TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Max** | **Units** | **Conditions** |
| TQ50 | TqIL | Filter Time to Recognize Low, with Digital Filter | 3 * N * TCY | — | ns | N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 2)** |
| TQ51 | TqiH | Filter Time to Recognize High, with Digital Filter | 3 * N * TCY | — | ns | N = 1, 2, 4, 16, 32, 64, 128 and 256 **(Note 2)** |
| TQ55 | Tqidxr | Index Pulse Recognized to Position Counter Reset (ungated index) | 3 TCY | — | ns | — |

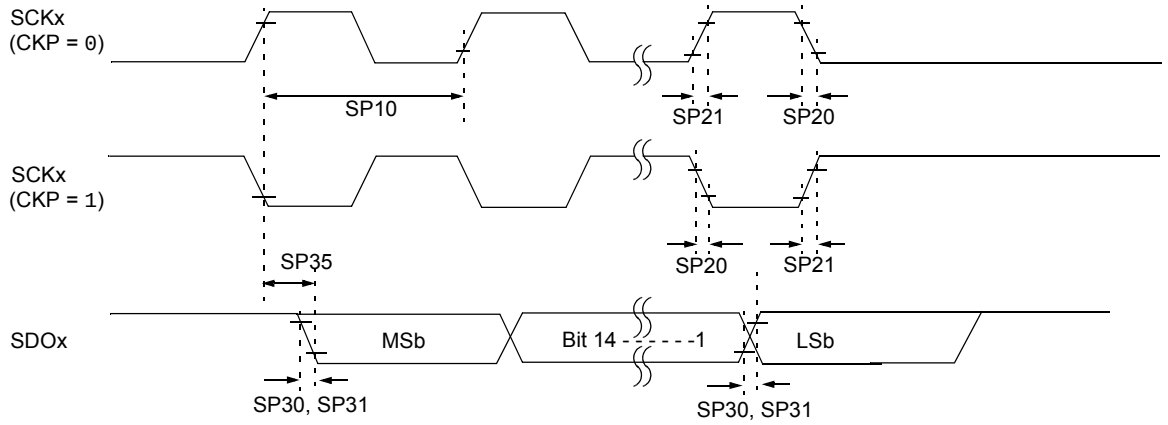
**Note 1:** These parameters are characterized by similarity, but are not tested in manufacturing.

**2:** Alignment of index pulses to QEA and QEB is shown for position counter Reset timing only. Shown for forward direction only (QEA leads QEB). Same timing applies for reverse direction (QEA lags QEB) but index pulse recognition occurs on falling edge.

**TABLE 24-32: SPIx MAXIMUM DATA/CLOCK RATE SUMMARY**

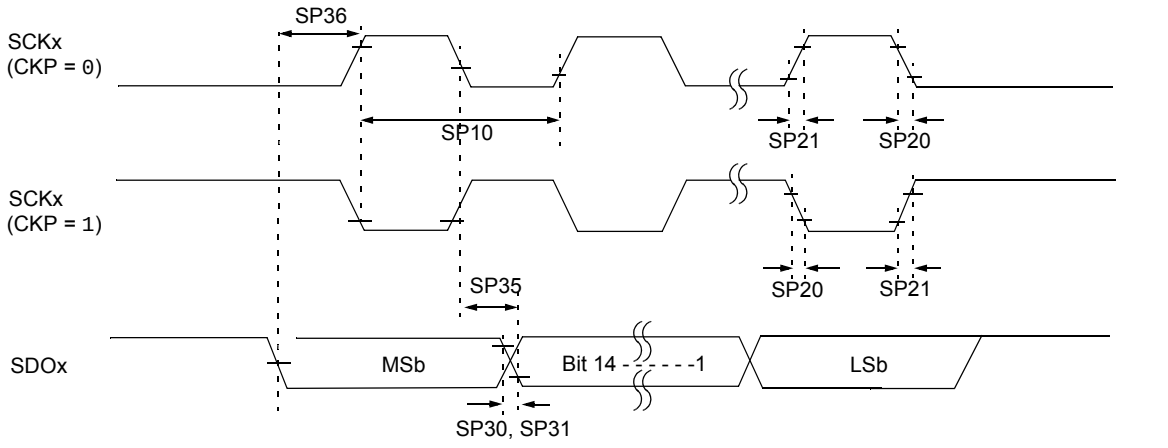
| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | |
|---|---|---|---|---|---|---|
| **Maximum Data Rate** | **Master Transmit Only (Half-Duplex)** | **Master Transmit/Receive (Full-Duplex)** | **Slave Transmit/Receive (Full-Duplex)** | **CKE** | **CKP** | **SMP** |
| 15 MHz | Table 24-33 | — | — | 0,1 | 0,1 | 0,1 |
| 9 MHz | — | Table 24-34 | — | 1 | 0,1 | 1 |
| 9 MHz | — | Table 24-35 | — | 0 | 0,1 | 1 |
| 15 MHz | — | — | Table 24-36 | 1 | 0 | 0 |
| 11 MHz | — | — | Table 24-37 | 1 | 1 | 0 |
| 15 MHz | — | — | Table 24-38 | 0 | 1 | 0 |
| 11 MHz | — | — | Table 24-39 | 0 | 0 | 0 |

**FIGURE 24-14: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY CKE = 0) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.

**FIGURE 24-15: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY CKE = 1) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-33: SPIx MASTER MODE (HALF-DUPLEX, TRANSMIT ONLY) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | [redacted]<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP10 | TscP | Maximum SCK Frequency | — | — | 15 | MHz | See **Note 3** |
| SP20 | TscF | SCKx Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP21 | TscR | SCKx Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdiV2scH, TdiV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |

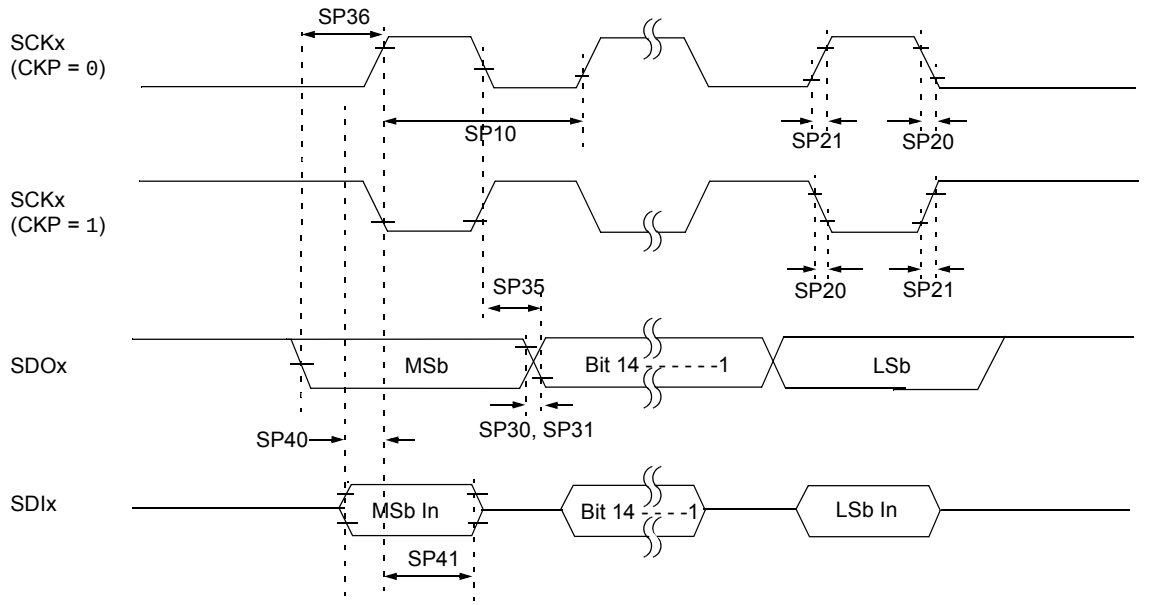
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in “Typ” column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 24-16: SPIx MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = X, SMP = 1) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.

**TABLE 24-34: SPIx MASTER MODE (FULL-DUPLEX, CKE = 1, CKP = x, SMP = 1) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP10 | TscP | Maximum SCK Frequency | — | — | 9 | MHz | See **Note 3** |
| SP20 | TscF | SCKx Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP21 | TscR | SCKx Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdoV2sc, TdoV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |

**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 111 ns. The clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.


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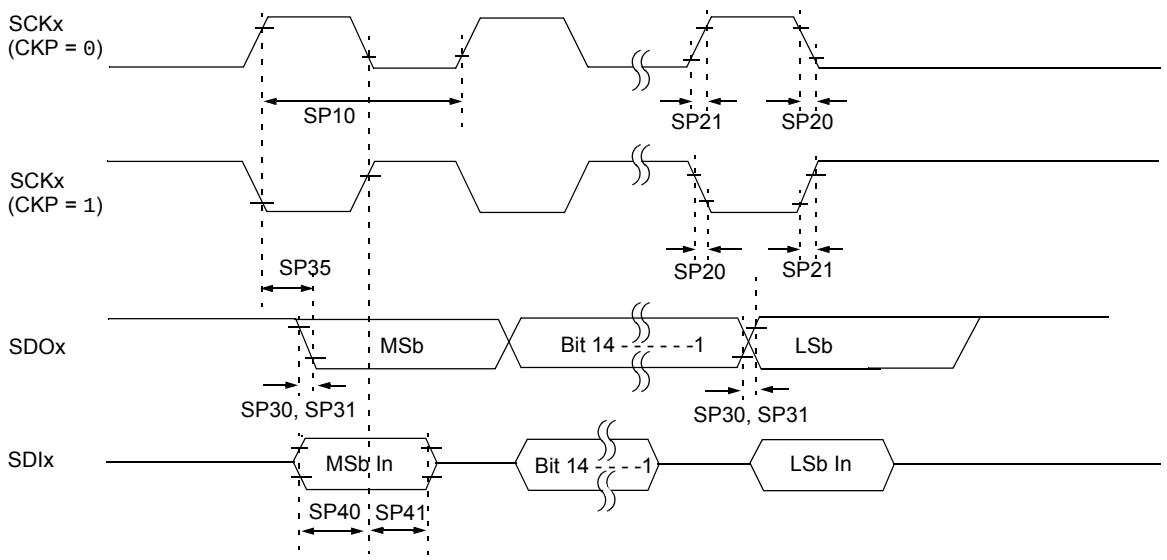
**FIGURE 24-17: SPIx MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = X, SMP = 1) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.

**TABLE 24-35: SPIx MASTER MODE (FULL-DUPLEX, CKE = 0, CKP = x, SMP = 1) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP10 | TscP | Maximum SCK Frequency | — | — | 9 | MHz | -40ºC to +125ºC and see **Note 3** |
| SP20 | TscF | SCKx Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP21 | TscR | SCKx Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdoV2scH, TdoV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |

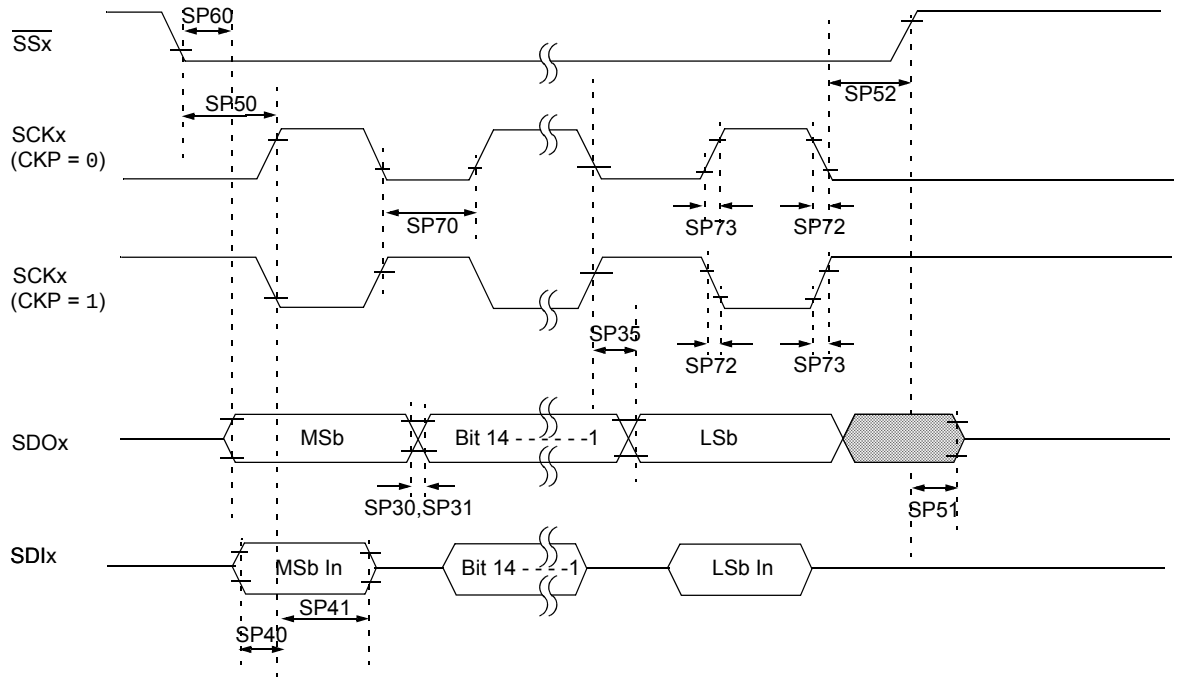
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 111 ns. The clock generated in Master mode must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 24-18: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-36: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 0, SMP = 0) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP70 | TscP | Maximum SCK Input Frequency | — | — | 15 | MHz | See **Note 3** |
| SP72 | TscF | SCKx Input Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP73 | TscR | SCKx Input Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdoV2scH, TdoV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP50 | TssL2scH, TssL2scL | $\overline{SSx}$ ↓to SCKx ↑ or SCKx Input | 120 | — | — | ns | — |
| SP51 | TssH2doZ | $\overline{SSx}$ ↑ to SDOx Output High-Impedance(4) | 10 | — | 50 | ns | — |
| SP52 | TscH2ssH TscL2ssH | $\overline{SSx}$ after SCKx Edge | 1.5 TCY + 40 | — | — | ns | See **Note 4** |
| SP60 | TssL2doV | $\overline{SDO}$x Data Output Valid after $\overline{SSx}$ Edge | — | — | 50 | ns | — |

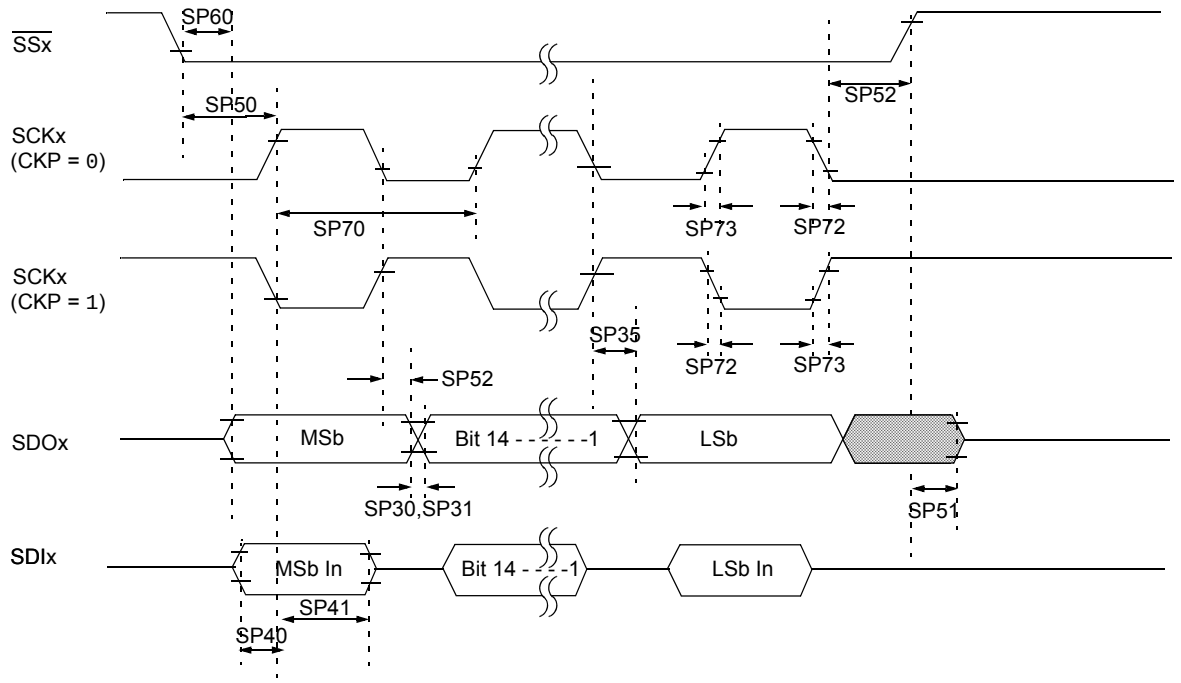
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 24-19: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-37: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 1, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP70 | TscP | Maximum SCK Input Frequency | — | — | 11 | MHz | See **Note 3** |
| SP72 | TscF | SCKx Input Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP73 | TscR | SCKx Input Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdoV2scH, TdoV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP50 | TssL2scH, TssL2scL | $\overline{SSx}$ ↓to SCKx ↑ or SCKx Input | 120 | — | — | ns | — |
| SP51 | TssH2doZ | $\overline{SSx}$ ↑ to SDOx Output High-Impedance(4) | 10 | — | 50 | ns | — |
| SP52 | TscH2ssH TscL2ssH | $\overline{SSx}$ after SCKx Edge | 1.5 TCY + 40 | — | — | ns | See **Note 4** |
| SP60 | TssL2doV | SDOx Data Output Valid after $\overline{SSx}$ Edge | — | — | 50 | ns | — |

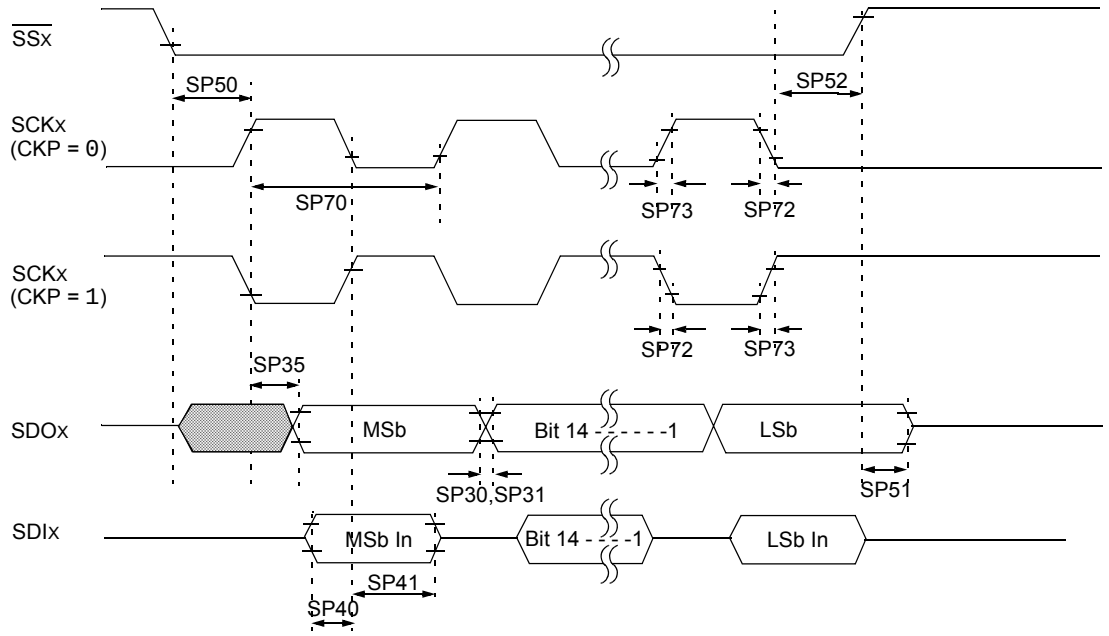
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 91 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 24-20: SPIx SLAVE MODE (FULL-DUPLEX CKE = 0, CKP = 1, SMP = 0) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-38: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP70 | TscP | Maximum SCK Input Frequency | — | — | 15 | MHz | See **Note 3** |
| SP72 | TscF | SCKx Input Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP73 | TscR | SCKx Input Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdoV2scH, TdoV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP50 | TssL2scH, TssL2scL | $\overline{SSx}$ ↓to SCKx ↑ or SCKx Input | 120 | — | — | ns | — |
| SP51 | TssH2doZ | $\overline{SSx}$ ↑ to SDOx Output High-Impedance(4) | 10 | — | 50 | ns | — |
| SP52 | TscH2ssH TscL2ssH | $\overline{SSx}$ after SCKx Edge | 1.5 TCY + 40 | — | — | ns | See **Note 4** |

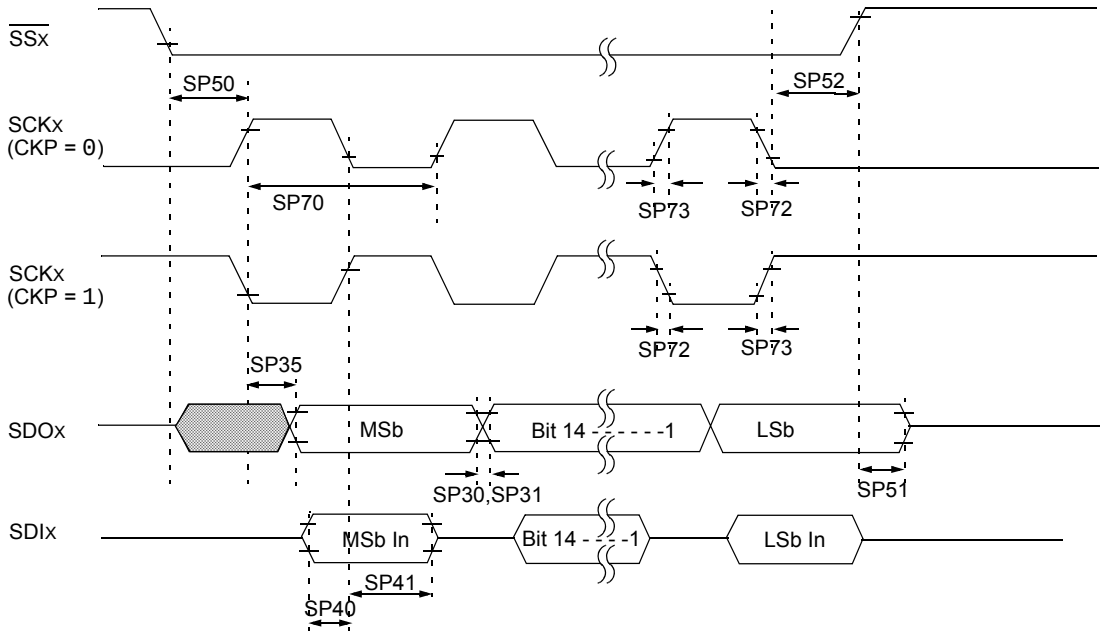
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 66.7 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 24-21: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING CHARACTERISTICS**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-39: SPIx SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 0, SMP = 0) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(1)** | **Min** | **Typ(2)** | **Max** | **Units** | **Conditions** |
| SP70 | TscP | Maximum SCK Input Frequency | — | — | 11 | MHz | See **Note 3** |
| SP72 | TscF | SCKx Input Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP73 | TscR | SCKx Input Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP30 | TdoF | SDOx Data Output Fall Time | — | — | — | ns | See parameter DO32 and **Note 4** |
| SP31 | TdoR | SDOx Data Output Rise Time | — | — | — | ns | See parameter DO31 and **Note 4** |
| SP35 | TscH2doV, TscL2doV | SDOx Data Output Valid after SCKx Edge | — | 6 | 20 | ns | — |
| SP36 | TdoV2scH, TdoV2scL | SDOx Data Output Setup to First SCKx Edge | 30 | — | — | ns | — |
| SP40 | TdiV2scH, TdiV2scL | Setup Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP41 | TscH2diL, TscL2diL | Hold Time of SDIx Data Input to SCKx Edge | 30 | — | — | ns | — |
| SP50 | TssL2scH, TssL2scL | $\overline{SSx}$ ↓to SCKx ↑ or SCKx Input | 120 | — | — | ns | — |
| SP51 | TssH2doZ | $\overline{SSx}$ ↑ to SDOx Output High-Impedance(4) | 10 | — | 50 | ns | — |
| SP52 | TscH2ssH TscL2ssH | $\overline{SSx}$ after SCKx Edge | 1.5 TCY + 40 | — | — | ns | See **Note 4** |

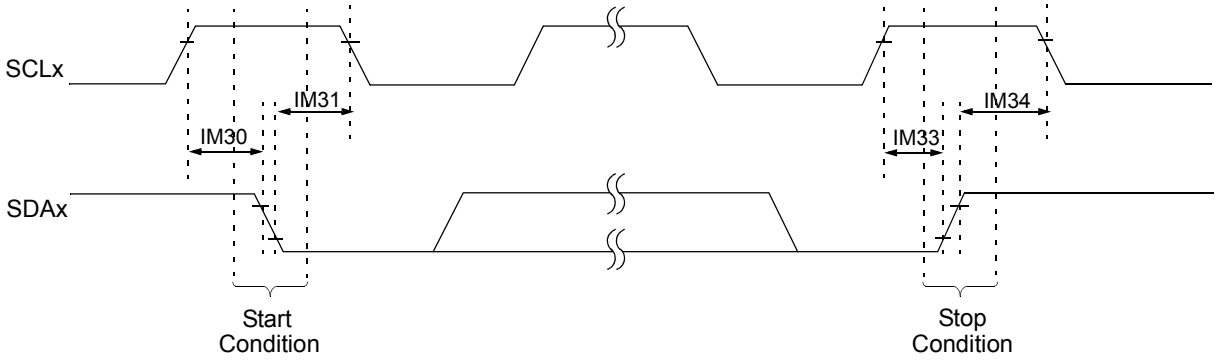
**Note 1:** These parameters are characterized, but are not tested in manufacturing.

**2:** Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

**3:** The minimum clock period for SCKx is 91 ns. Therefore, the SCK clock generated by the Master must not violate this specification.

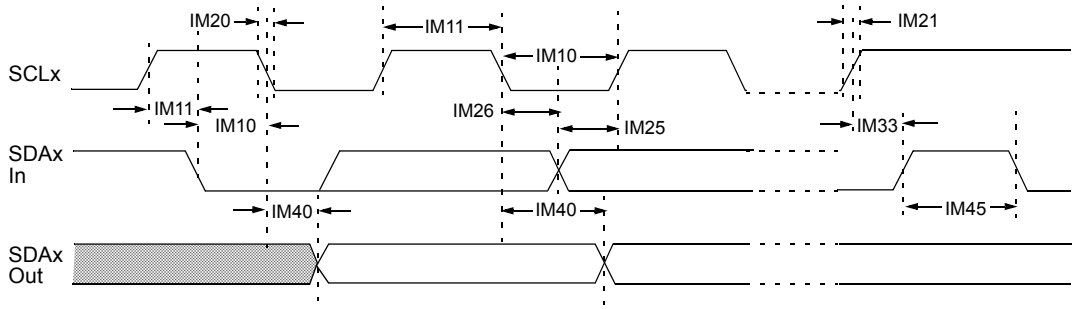
**4:** Assumes 50 pF load on all SPIx pins.

**FIGURE 24-22: I2Cx BUS START/STOP BITS TIMING CHARACTERISTICS (MASTER MODE)**




**Note:** Refer to Figure 24-1 for load conditions.

**FIGURE 24-23: I2Cx BUS DATA TIMING CHARACTERISTICS (MASTER MODE)**




**Note:** Refer to Figure 24-1 for load conditions.


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**TABLE 24-40: I2Cx BUS DATA TIMING REQUIREMENTS (MASTER MODE)**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic(3)** | | **Min(1)** | **Max** | **Units** | **Conditions** |
| IM10 | TLO:SCL | Clock Low Time | 100 kHz mode | TCY/2 (BRG + 1) | — | µs | — |
| | | | 400 kHz mode | TCY/2 (BRG + 1) | — | µs | — |
| | | | 1 MHz mode(2) | TCY/2 (BRG + 1) | — | µs | — |
| IM11 | THI:SCL | Clock High Time | 100 kHz mode | TCY/2 (BRG + 1) | — | µs | — |
| | | | 400 kHz mode | TCY/2 (BRG + 1) | — | µs | — |
| | | | 1 MHz mode(2) | TCY/2 (BRG + 1) | — | µs | — |
| IM20 | TF:SCL | SDAx and SCLx Fall Time | 100 kHz mode | — | 300 | ns | CB is specified to be from 10 to 400 pF |
| | | | 400 kHz mode | 20 + 0.1 CB | 300 | ns | |
| | | | 1 MHz mode(2) | — | 100 | ns | |
| IM21 | TR:SCL | SDAx and SCLx Rise Time | 100 kHz mode | — | 1000 | ns | CB is specified to be from 10 to 400 pF |
| | | | 400 kHz mode | 20 + 0.1 CB | 300 | ns | |
| | | | 1 MHz mode(2) | — | 300 | ns | |
| IM25 | TSU:DAT | Data Input Setup Time | 100 kHz mode | 250 | — | ns | — |
| | | | 400 kHz mode | 100 | — | ns | |
| | | | 1 MHz mode(2) | 40 | — | ns | |
| IM26 | THD:DAT | Data Input Hold Time | 100 kHz mode | 0 | — | µs | — |
| | | | 400 kHz mode | 0 | 0.9 | µs | |
| | | | 1 MHz mode(2) | 0.2 | — | µs | |
| IM30 | TSU:STA | Start Condition Setup Time | 100 kHz mode | TCY/2 (BRG + 1) | — | µs | Only relevant for Repeated Start condition |
| | | | 400 kHz mode | TCY/2 (BRG + 1) | — | µs | |
| | | | 1 MHz mode(2) | TCY/2 (BRG + 1) | — | µs | |
| IM31 | THD:STA | Start Condition Hold Time | 100 kHz mode | TCY/2 (BRG + 1) | — | µs | After this period the first clock pulse is generated |
| | | | 400 kHz mode | TCY/2 (BRG + 1) | — | µs | |
| | | | 1 MHz mode(2) | TCY/2 (BRG + 1) | — | µs | |
| IM33 | TSU:STO | Stop Condition Setup Time | 100 kHz mode | TCY/2 (BRG + 1) | — | µs | — |
| | | | 400 kHz mode | TCY/2 (BRG + 1) | — | µs | |
| | | | 1 MHz mode(2) | TCY/2 (BRG + 1) | — | µs | |
| IM34 | THD:STO | Stop Condition Hold Time | 100 kHz mode | TCY/2 (BRG + 1) | — | ns | — |
| | | | 400 kHz mode | TCY/2 (BRG + 1) | — | ns | |
| | | | 1 MHz mode(2) | TCY/2 (BRG + 1) | — | ns | |
| IM40 | TAA:SCL | Output Valid From Clock | 100 kHz mode | — | 3500 | ns | — |
| | | | 400 kHz mode | — | 1000 | ns | — |
| | | | 1 MHz mode(2) | — | 400 | ns | — |
| IM45 | TBF:SDA | Bus Free Time | 100 kHz mode | 4.7 | — | µs | Time the bus must be free before a new transmission can start |
| | | | 400 kHz mode | 1.3 | — | µs | |
| | | | 1 MHz mode(2) | 0.5 | — | µs | |
| IM50 | CB | Bus Capacitive Loading | | — | 400 | pF | — |
| IM51 | PGD | Pulse Gobbler Delay | | 65 | 390 | ns | See **Note 4** |

**Note 1:** BRG is the value of the $I^2C$ Baud Rate Generator. Refer to **Section 19. "Inter-Integrated Circuit ($I^2C$™)"** (DS70195) in the "*dsPIC33F/PIC24H Family Reference Manual*". Please see the Microchip web site (www.microchip.com) for the latest family reference manual sections.

**2:** Maximum pin capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

**3:** These parameters are characterized by similarity, but are not tested in manufacturing.

**4:** Typical value for this parameter is 130 ns.

**FIGURE 24-24: I2Cx BUS START/STOP BITS TIMING CHARACTERISTICS (SLAVE MODE)**

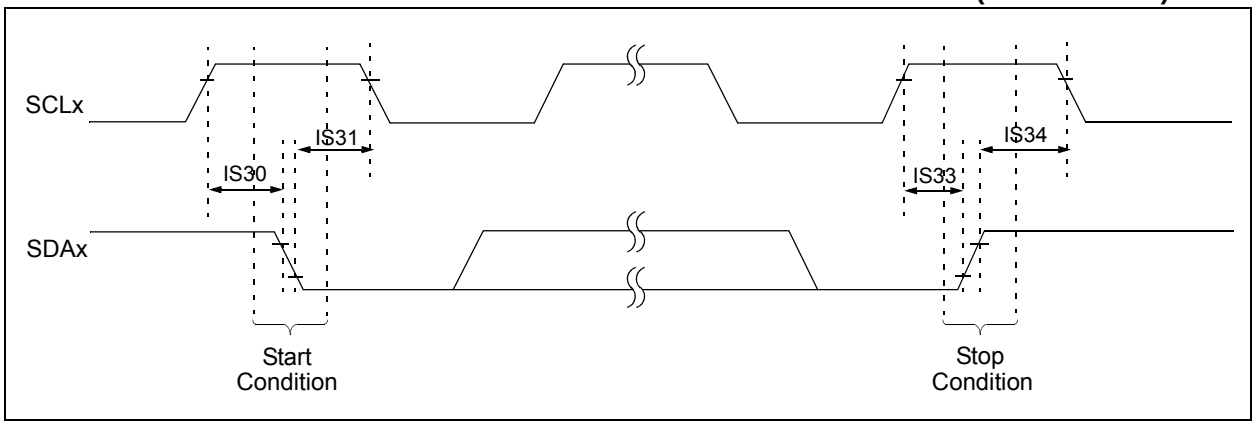


**FIGURE 24-25: I2Cx BUS DATA TIMING CHARACTERISTICS (SLAVE MODE)**

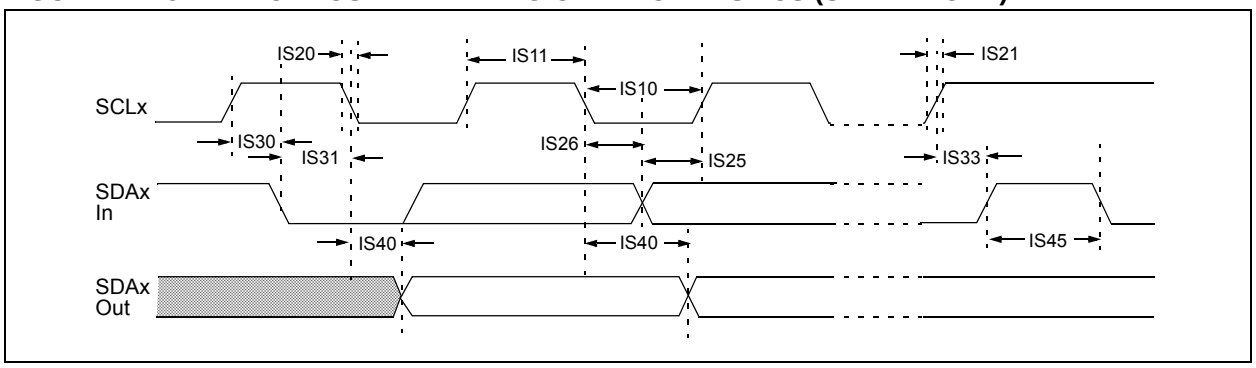



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**TABLE 24-41: I2Cx BUS DATA TIMING REQUIREMENTS (SLAVE MODE)**

| AC CHARACTERISTICS | | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | |
|---|---|---|---|---|---|---|---|
| **Param.** | **Symbol** | **Characteristic(2)** | | **Min** | **Max** | **Units** | **Conditions** |
| IS10 | TLO:SCL | Clock Low Time | 100 kHz mode | 4.7 | — | µs | Device must operate at a minimum of 1.5 MHz |
| | | | 400 kHz mode | 1.3 | — | µs | Device must operate at a minimum of 10 MHz |
| | | | 1 MHz mode(1) | 0.5 | — | µs | — |
| IS11 | THI:SCL | Clock High Time | 100 kHz mode | 4.0 | — | µs | Device must operate at a minimum of 1.5 MHz |
| | | | 400 kHz mode | 0.6 | — | µs | Device must operate at a minimum of 10 MHz |
| | | | 1 MHz mode(1) | 0.5 | — | µs | — |
| IS20 | TF:SCL | SDAx and SCLx Fall Time | 100 kHz mode | — | 300 | ns | CB is specified to be from 10 to 400 pF |
| | | | 400 kHz mode | 20 + 0.1 CB | 300 | ns | |
| | | | 1 MHz mode(1) | — | 100 | ns | |
| IS21 | TR:SCL | SDAx and SCLx Rise Time | 100 kHz mode | — | 1000 | ns | CB is specified to be from 10 to 400 pF |
| | | | 400 kHz mode | 20 + 0.1 CB | 300 | ns | |
| | | | 1 MHz mode(1) | — | 300 | ns | |
| IS25 | TSU:DAT | Data Input Setup Time | 100 kHz mode | 250 | — | ns | — |
| | | | 400 kHz mode | 100 | — | ns | |
| | | | 1 MHz mode(1) | 100 | — | ns | |
| IS26 | THD:DAT | Data Input Hold Time | 100 kHz mode | 0 | — | µs | — |
| | | | 400 kHz mode | 0 | 0.9 | µs | |
| | | | 1 MHz mode(1) | 0 | 0.3 | µs | |
| IS30 | TSU:STA | Start Condition Setup Time | 100 kHz mode | 4.7 | — | µs | Only relevant for Repeated Start condition |
| | | | 400 kHz mode | 0.6 | — | µs | |
| | | | 1 MHz mode(1) | 0.25 | — | µs | |
| IS31 | THD:STA | Start Condition Hold Time | 100 kHz mode | 4.0 | — | µs | After this period, the first clock pulse is generated |
| | | | 400 kHz mode | 0.6 | — | µs | |
| | | | 1 MHz mode(1) | 0.25 | — | µs | |
| IS33 | TSU:STO | Stop Condition Setup Time | 100 kHz mode | 4.7 | — | µs | — |
| | | | 400 kHz mode | 0.6 | — | µs | |
| | | | 1 MHz mode(1) | 0.6 | — | µs | |
| IS34 | THD:STO | Stop Condition Hold Time | 100 kHz mode | 4000 | — | ns | — |
| | | | 400 kHz mode | 600 | — | ns | |
| | | | 1 MHz mode(1) | 250 | | ns | |
| IS40 | TAA:SCL | Output Valid From Clock | 100 kHz mode | 0 | 3500 | ns | — |
| | | | 400 kHz mode | 0 | 1000 | ns | |
| | | | 1 MHz mode(1) | 0 | 350 | ns | |
| IS45 | TBF:SDA | Bus Free Time | 100 kHz mode | 4.7 | — | µs | Time the bus must be free before a new transmission can start |
| | | | 400 kHz mode | 1.3 | — | µs | |
| | | | 1 MHz mode(1) | 0.5 | — | µs | |
| IS50 | CB | Bus Capacitive Loading | | — | 400 | pF | — |

**Note 1:** Maximum pin capacitance = 10 pF for all I2Cx pins (for 1 MHz mode only).

**2:** These parameters are characterized by similarity, but are not tested in manufacturing.

**TABLE 24-42: ADC MODULE SPECIFICATIONS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤TA ≤+85°C for Industrial<br>-40°C ≤TA ≤+125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ** | **Max.** | **Units** | **Conditions** |
| **Device Supply** | | | | | | | |
| AD01 | AVDD | Module VDD Supply(2) | Greater of VDD – 0.3 or 3.0 | — | Lesser of VDD + 0.3 or 3.6 | V | — |
| AD02 | AVSS | Module VSS Supply(2) | VSS – 0.3 | — | VSS + 0.3 | V | — |
| **Reference Inputs** | | | | | | | |
| AD05 | VREFH | Reference Voltage High | AVSS + 2.5 | — | AVDD | V | See **Note 1** |
| AD05a | | | 3.0 | — | 3.6 | V | VREFH = AVDD<br>VREFL = AVSS = 0, see **Note 2** |
| AD06 | VREFL | Reference Voltage Low | AVSS | — | AVDD – 2.5 | V | See **Note 1** |
| AD06a | | | 0 | — | 0 | V | VREFH = AVDD<br>VREFL = AVSS = 0, see **Note 2** |
| AD07 | VREF | Absolute Reference Voltage(2) | 2.5 | — | 3.6 | V | VREF = VREFH - VREFL |
| AD08 | IREF | Current Drain | —<br>— | 250<br>— | 550<br>10 | μA<br>μA | ADC operating, See **Note 1**<br>ADC off, See **Note 1** |
| AD08a | IAD | Operating Current | —<br>— | 7.0<br>2.7 | 9.0<br>3.2 | mA<br>mA | 10-bit ADC mode, See **Note 2**<br>12-bit ADC mode, See **Note 2** |
| **Analog Input** | | | | | | | |
| AD12 | VINH | Input Voltage Range VINH(2) | VINL | — | VREFH | V | This voltage reflects Sample and Hold Channels 0, 1, 2, and 3 (CH0-CH3), positive input |
| AD13 | VINL | Input Voltage Range VINL(2) | VREFL | — | AVSS + 1V | V | This voltage reflects Sample and Hold Channels 0, 1, 2, and 3 (CH0-CH3), negative input |
| AD17 | RIN | Recommended Impedance of Analog Voltage Source(3) | —<br>— | —<br>— | 200<br>200 | Ω<br>Ω | 10-bit ADC<br>12-bit ADC |

**Note 1:** These parameters are not characterized or tested in manufacturing.

**2:** These parameters are characterized, but are not tested in manufacturing.

**3:** These parameters are assured by design, but are not characterized or tested in manufacturing.


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**TABLE 24-43: ADC MODULE SPECIFICATIONS (12-BIT MODE)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ** | **Max.** | **Units** | **Conditions** |
| **ADC Accuracy (12-bit Mode) – Measurements with external VREF+/VREF-(3)** | | | | | | | |
| AD20a | Nr | Resolution(4) | 12 data bits | | | bits | — |
| AD21a | INL | Integral Nonlinearity | -2 | — | +2 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD22a | DNL | Differential Nonlinearity | >-1 | — | <1 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD23a | GERR | Gain Error | — | 3.4 | 10 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD24a | EOFF | Offset Error | — | 0.9 | 5.0 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD25a | — | Monotonicity | — | — | — | — | Guaranteed(1) |
| **ADC Accuracy (12-bit Mode) – Measurements with internal VREF+/VREF-(3)** | | | | | | | |
| AD20a | Nr | Resolution(4) | 12 data bits | | | bits | — |
| AD21a | INL | Integral Nonlinearity | -2 | — | +2 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD22a | DNL | Differential Nonlinearity | >-1 | — | <1 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD23a | GERR | Gain Error | 2 | 10.5 | 20 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD24a | EOFF | Offset Error | 2 | 3.8 | 10 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD25a | — | Monotonicity | — | — | — | — | Guaranteed(1) |
| **Dynamic Performance (12-bit Mode)(2)** | | | | | | | |
| AD30a | THD | Total Harmonic Distortion | — | — | -75 | dB | — |
| AD31a | SINAD | Signal to Noise and Distortion | 68.5 | 69.5 | — | dB | — |
| AD32a | SFDR | Spurious Free Dynamic Range | 80 | — | — | dB | — |
| AD33a | FNYQ | Input Signal Bandwidth | — | — | 250 | kHz | — |
| AD34a | ENOB | Effective Number of Bits | 11.09 | 11.3 | — | bits | — |

**Note 1:** The A/D conversion result never decreases with an increase in the input voltage, and has no missing codes.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing.

**3:** These parameters are characterized, but are tested at 20 ksps only.

**4:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.

**TABLE 24-44: ADC MODULE SPECIFICATIONS (10-BIT MODE)**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ** | **Max.** | **Units** | **Conditions** |
| **ADC Accuracy (10-bit Mode) – Measurements with external VREF+/VREF-(3)** | | | | | | | |
| AD20b | Nr | Resolution(4) | 10 data bits | | | bits | — |
| AD21b | INL | Integral Nonlinearity | -1.5 | — | +1.5 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD22b | DNL | Differential Nonlinearity | >-1 | — | <1 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD23b | GERR | Gain Error | — | 3 | 6 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD24b | EOFF | Offset Error | — | 2 | 5 | LSb | VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3.6V |
| AD25b | — | Monotonicity | — | — | — | — | Guaranteed(1) |
| **ADC Accuracy (10-bit Mode) – Measurements with internal VREF+/VREF-(3)** | | | | | | | |
| AD20b | Nr | Resolution(4) | 10 data bits | | | bits | — |
| AD21b | INL | Integral Nonlinearity | -1 | — | +1 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD22b | DNL | Differential Nonlinearity | >-1 | — | <1 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD23b | GERR | Gain Error | — | 7 | 15 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD24b | EOFF | Offset Error | — | 3 | 7 | LSb | VINL = AVSS = 0V, AVDD = 3.6V |
| AD25b | — | Monotonicity | — | — | — | — | Guaranteed(1) |
| **Dynamic Performance (10-bit Mode)(2)** | | | | | | | |
| AD30b | THD | Total Harmonic Distortion | — | — | -64 | dB | — |
| AD31b | SINAD | Signal to Noise and Distortion | 57 | 58.5 | — | dB | — |
| AD32b | SFDR | Spurious Free Dynamic Range | 72 | — | — | dB | — |
| AD33b | FNYQ | Input Signal Bandwidth | — | — | 550 | kHz | — |
| AD34b | ENOB | Effective Number of Bits | 9.16 | 9.4 | — | bits | — |

**Note 1:** The A/D conversion result never decreases with an increase in the input voltage, and has no missing codes.

**2:** These parameters are characterized by similarity, but are not tested in manufacturing.

**3:** These parameters are characterized, but are tested at 20 ksps only.

**4:** Injection currents > | 0 | can affect the ADC results by approximately 4-6 counts.


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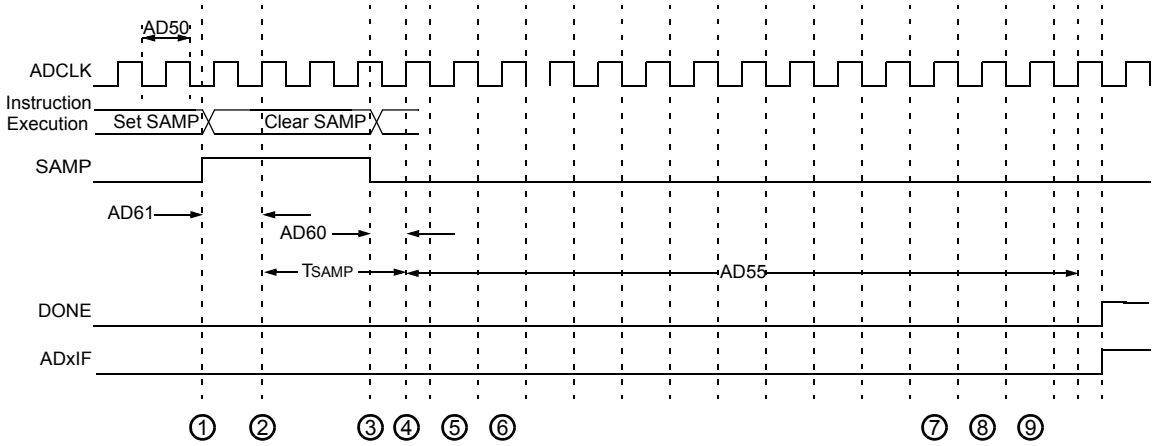
**FIGURE 24-26: ADC CONVERSION (12-BIT MODE) TIMING CHARACTERISTICS (ASAM = 0, SSRC<2:0> = 000)**




① – Software sets ADxCON. SAMP to start sampling.

② – Sampling starts after discharge period. TSAMP is described in **Section 16. "Analog-to-Digital Converter (ADC)"** (DS70183) in the *"dsPIC33F/PIC24H Family Reference Manual"*.

③ – Software clears ADxCON. SAMP to start conversion.

④ – Sampling ends, conversion sequence starts.

⑤ – Convert bit 11.

⑥ – Convert bit 10.

⑦ – Convert bit 1.

⑧ – Convert bit 0.

⑨ – One TAD for end of conversion.

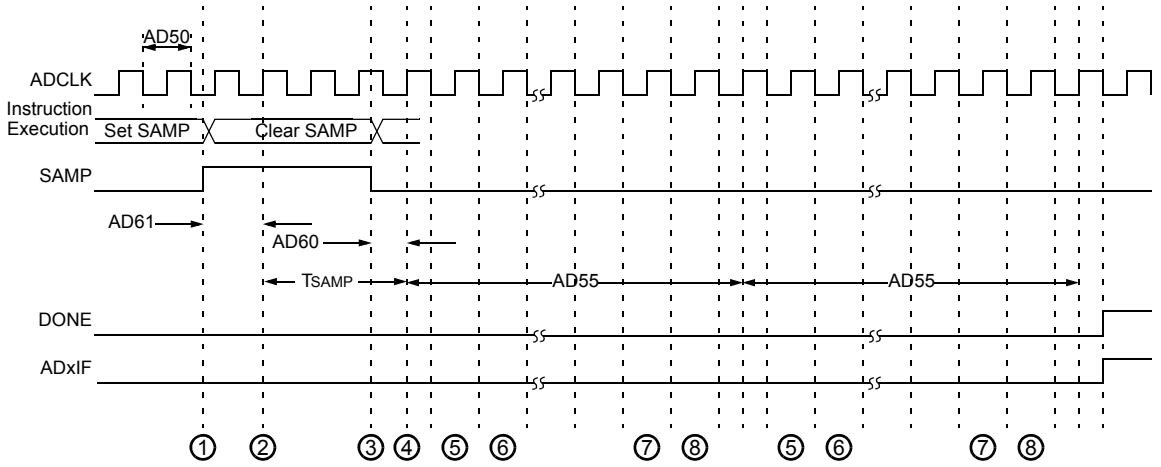
**TABLE 24-45: ADC CONVERSION (12-BIT MODE) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ(2)** | **Max.** | **Units** | **Conditions** |
| **Clock Parameters(1)** | | | | | | | |
| AD50 | TAD | ADC Clock Period | 117.6 | — | — | ns | — |
| AD51 | tRC | ADC Internal RC Oscillator Period | — | 250 | — | ns | — |
| **Conversion Rate** | | | | | | | |
| AD55 | tCONV | Conversion Time | — | 14 TAD | | ns | — |
| AD56 | FCNV | Throughput Rate | — | — | 500 | Ksps | — |
| AD57 | TSAMP | Sample Time | 3.0 TAD | — | — | — | — |
| **Timing Parameters** | | | | | | | |
| AD60 | tPCS | Conversion Start from Sample Trigger(2) | 2.0 TAD | — | 3.0 TAD | — | Auto-convert trigger not selected |
| AD61 | tPSS | Sample Start from Setting Sample (SAMP) bit(2) | 2.0 TAD | — | 3.0 TAD | — | — |
| AD62 | tCSS | Conversion Completion to Sample Start (ASAM = 1)(2) | — | 0.5 TAD | — | — | — |
| AD63 | tDPU | Time to Stabilize Analog Stage from ADC Off to ADC On(2) | — | — | 20 | μs | — |

**Note 1:** Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.

**2:** These parameters are characterized but not tested in manufacturing.

**FIGURE 24-27: ADC CONVERSION (10-BIT MODE) TIMING CHARACTERISTICS (CHPS<1:0> = 01, SIMSAM = 0, ASAM = 0, SSRC<2:0> = 000)**




1 – Software sets ADxCON. SAMP to start sampling.

2 – Sampling starts after discharge period. TSAMP is described in S**ection 16. "Analog-to-Digital Converter (ADC)"** (DS70183) in the *"dsPIC33F/PIC24H Family Reference Manual*".

3 – Software clears ADxCON. SAMP to start conversion.

4 – Sampling ends, conversion sequence starts.

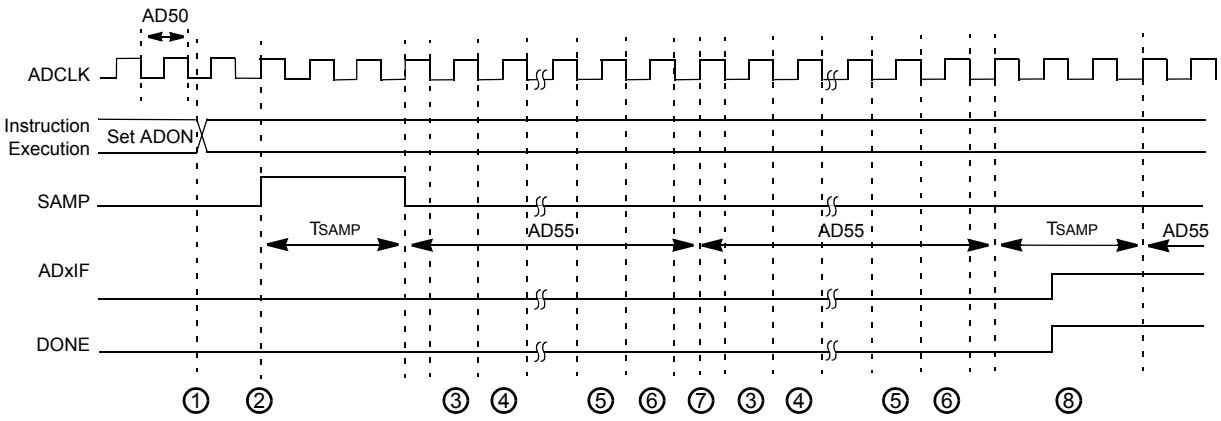
5 – Convert bit 9.

6 – Convert bit 8.

7 – Convert bit 0.

8 – One TAD for end of conversion.

**FIGURE 24-28: ADC CONVERSION (10-BIT MODE) TIMING CHARACTERISTICS (CHPS<1:0> = 01, SIMSAM = 0, ASAM = 1, SSRC<2:0> = 111, SAMC<4:0> = 00001)**




1 – Software sets ADxCON. ADON to start AD operation.

2 – Sampling starts after discharge period. TSAMP is described in S**ection 16. "Analog-to-Digital Converter (ADC)"** (DS70183) in the *'dsPIC33F/PIC24H Family Reference Manual"*.

3 – Convert bit 9.

4 – Convert bit 8.

5 – Convert bit 0.

6 – One TAD for end of conversion.

7 – Begin conversion of next channel.

8 – Sample for time specified by SAMC<4:0>.


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**TABLE 24-46: ADC CONVERSION (10-BIT MODE) TIMING REQUIREMENTS**

| AC CHARACTERISTICS | | | Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated)<br>Operating temperature -40°C ≤ TA ≤ +85°C for Industrial<br>-40°C ≤ TA ≤ +125°C for Extended | | | | |
|---|---|---|---|---|---|---|---|
| **Param No.** | **Symbol** | **Characteristic** | **Min.** | **Typ(1)** | **Max.** | **Units** | **Conditions** |
| **Clock Parameters(2)** | | | | | | | |
| AD50 | TAD | ADC Clock Period | 76 | — | — | ns | — |
| AD51 | tRC | ADC Internal RC Oscillator Period | — | 250 | — | ns | — |
| **Conversion Rate** | | | | | | | |
| AD55 | tCONV | Conversion Time | — | 12 TAD | — | — | — |
| AD56 | FCNV | Throughput Rate | — | — | 1.1 | Msps | — |
| AD57 | TSAMP | Sample Time | 2.0 TAD | — | — | — | — |
| **Timing Parameters** | | | | | | | |
| AD60 | tPCS | Conversion Start from Sample Trigger(1) | 2.0 TAD | — | 3.0 TAD | — | Auto-Convert Trigger (SSRC<2:0> = 111) not selected |
| AD61 | tPSS | Sample Start from Setting Sample (SAMP) bit(1) | 2.0 TAD | — | 3.0 TAD | — | — |
| AD62 | tCSS | Conversion Completion to Sample Start (ASAM = 1)(1) | — | 0.5 TAD | — | — | — |
| AD63 | tDPU | Time to Stabilize Analog Stage from ADC Off to ADC On(1) | — | — | 20 | μs | — |

**Note 1:** These parameters are characterized but not tested in manufacturing.

**2:** Because the sample caps will eventually lose charge, clock rates below 10 kHz may affect linearity performance, especially at elevated temperatures.

**NOTES:**


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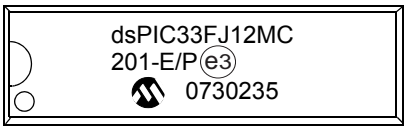
## 25.0 PACKAGING INFORMATION

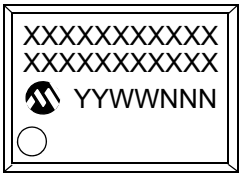
### 25.1 Package Marking Information

20-Lead PDIP

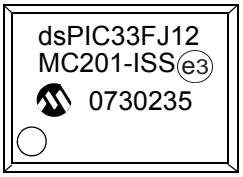
Example



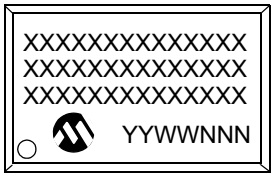

20-Lead SSOP



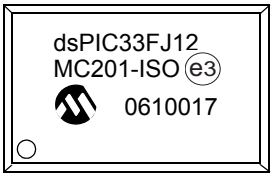

Example



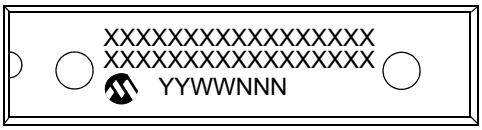

20-Lead SOIC



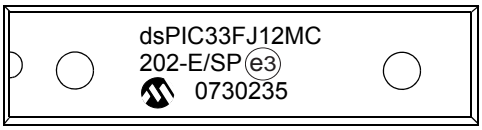

Example



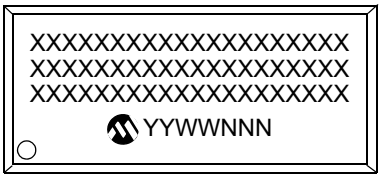

28-Lead SPDIP



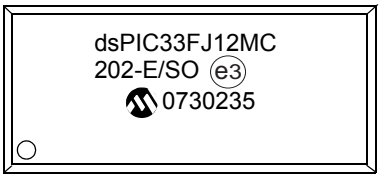

Example




28-Lead SOIC




Example



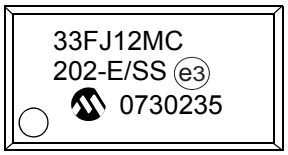

| | | |
|---|---|---|
| **Legend:** | XX...X | Customer-specific information |
| | Y | Year code (last digit of calendar year) |
| | YY | Year code (last 2 digits of calendar year) |
| | WW | Week code (week of January 1 is week ‘01’) |
| | NNN | Alphanumeric traceability code |
| | (e3) | Pb-free JEDEC designator for Matte Tin (Sn) |
| | * | This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package. |

**Note:** If the full Microchip part number cannot be marked on one line, it is carried over to the next line, thus limiting the number of available characters for customer-specific information.

### 25.1 Package Marking Information (Continued)

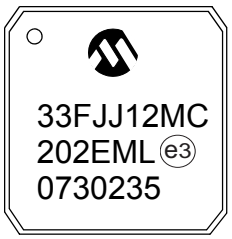
28-Lead SSOP

Example




28-Lead QFN

Example




| | | |
|---|---|---|
| **Legend:** | XX...X | Customer-specific information |
| | Y | Year code (last digit of calendar year) |
| | YY | Year code (last 2 digits of calendar year) |
| | WW | Week code (week of January 1 is week ‘01’) |
| | NNN | Alphanumeric traceability code |
| | (e3) | Pb-free JEDEC designator for Matte Tin (Sn) |
| | * | This package is Pb-free. The Pb-free JEDEC designator ((e3)) can be found on the outer packaging for this package. |

**Note:** If the full Microchip part number cannot be marked on one line, it is carried over to the next line, thus limiting the number of available characters for customer-specific information.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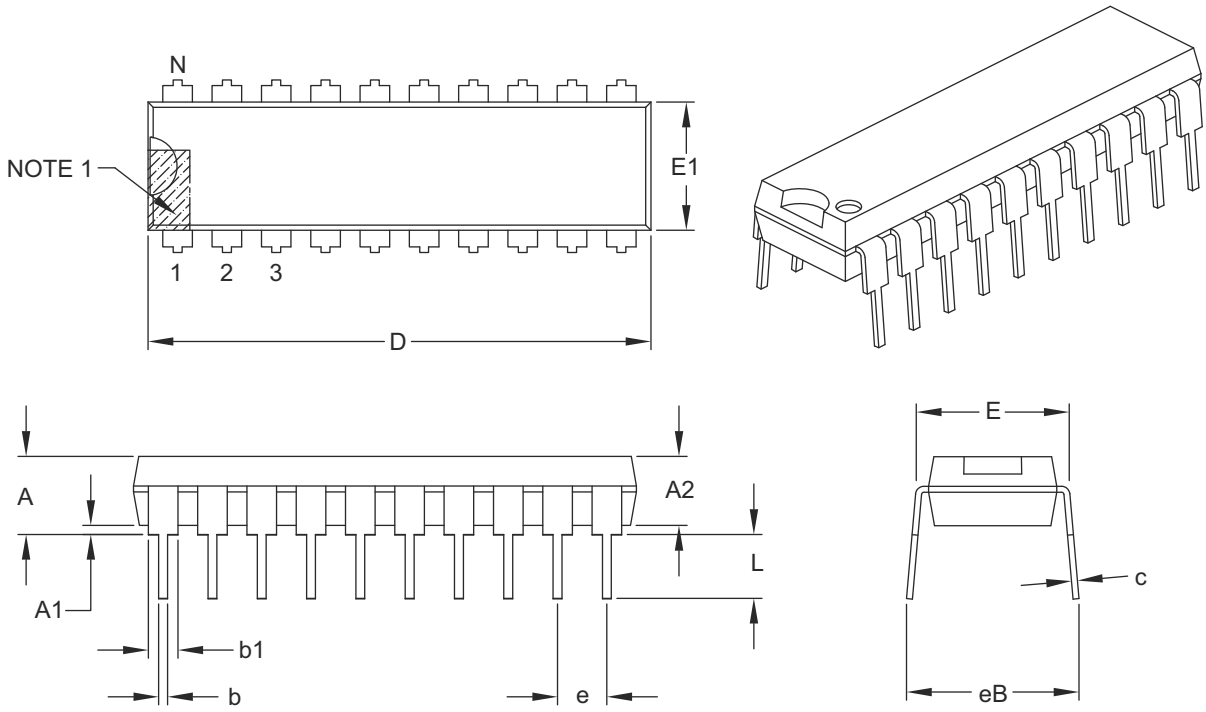
## 25.2 Package Details

### 20-Lead Plastic Dual In-Line (P) – 300 mil Body [PDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | INCHES | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 20 | |
| Pitch | e | | .100 BSC | |
| Top to Seating Plane | A | – | – | .210 |
| Molded Package Thickness | A2 | .115 | .130 | .195 |
| Base to Seating Plane | A1 | .015 | – | – |
| Shoulder to Shoulder Width | E | .300 | .310 | .325 |
| Molded Package Width | E1 | .240 | .250 | .280 |
| Overall Length | D | .980 | 1.030 | 1.060 |
| Tip to Seating Plane | L | .115 | .130 | .150 |
| Lead Thickness | c | .008 | .010 | .015 |
| Upper Lead Width | b1 | .045 | .060 | .070 |
| Lower Lead Width | b | .014 | .018 | .022 |
| Overall Row Spacing § | eB | – | – | .430 |

**Notes:**

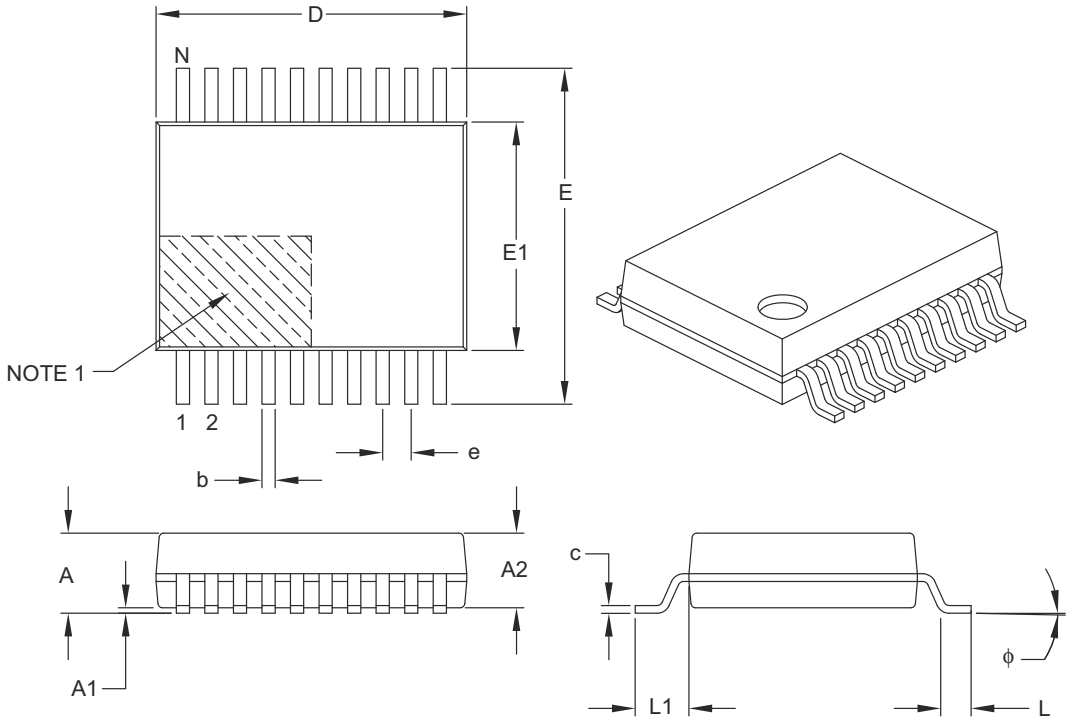
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-019B

### 20-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 20 | |
| Pitch | e | | 0.65 BSC | |
| Overall Height | A | – | – | 2.00 |
| Molded Package Thickness | A2 | 1.65 | 1.75 | 1.85 |
| Standoff | A1 | 0.05 | – | – |
| Overall Width | E | 7.40 | 7.80 | 8.20 |
| Molded Package Width | E1 | 5.00 | 5.30 | 5.60 |
| Overall Length | D | 6.90 | 7.20 | 7.50 |
| Foot Length | L | 0.55 | 0.75 | 0.95 |
| Footprint | L1 | | 1.25 REF | |
| Lead Thickness | c | 0.09 | – | 0.25 |
| Foot Angle | ϕ | 0° | 4° | 8° |
| Lead Width | b | 0.22 | – | 0.38 |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-072B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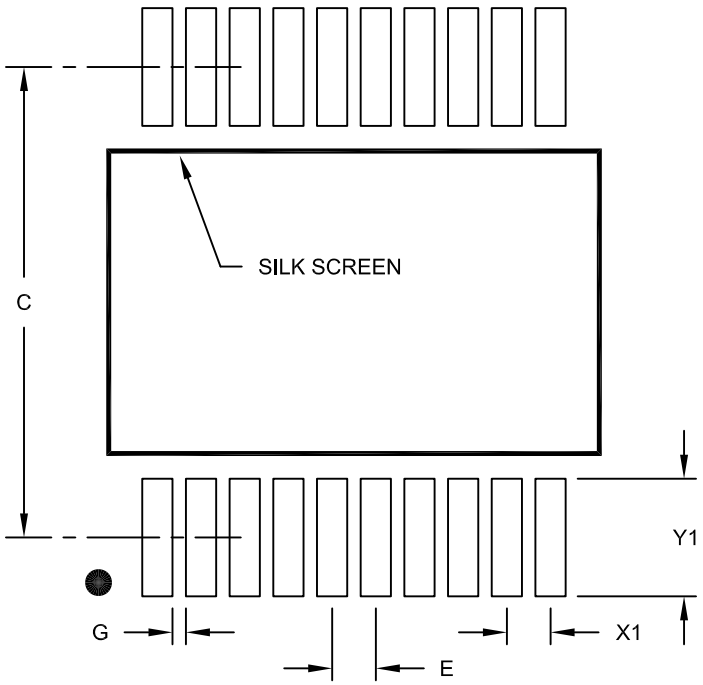
20-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | 0.65 BSC | | |
| Contact Pad Spacing | C | | 7.20 | |
| Contact Pad Width (X20) | X1 | | | 0.45 |
| Contact Pad Length (X20) | Y1 | | | 1.75 |
| Distance Between Pads | G | 0.20 | | |

Notes:

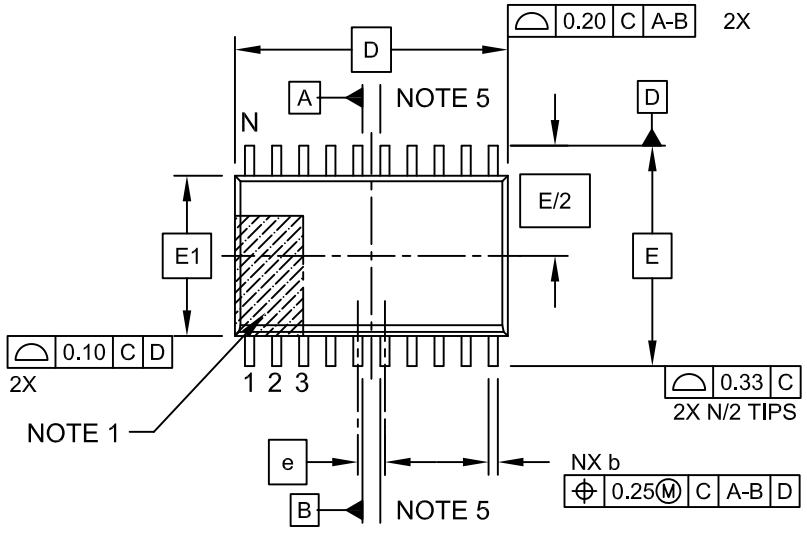
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

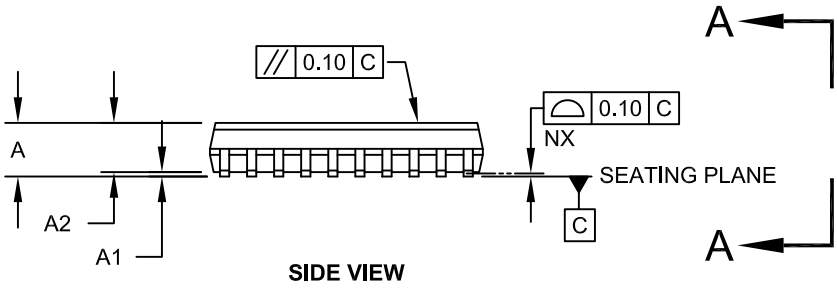
Microchip Technology Drawing No. C04-2072A

### 20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

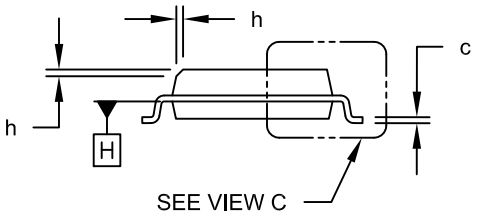
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




**TOP VIEW**




**SIDE VIEW**




**VIEW A-A**

Microchip Technology Drawing C04-094C Sheet 1 of 2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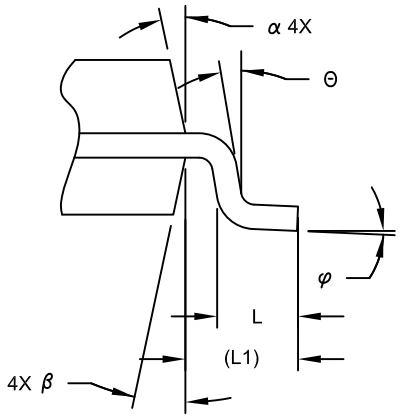
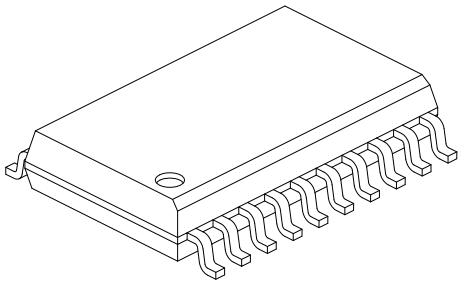
## 20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




VIEW C



| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 20 | |
| Pitch | e | | 1.27 BSC | |
| Overall Height | A | - | - | 2.65 |
| Molded Package Thickness | A2 | 2.05 | - | - |
| Standoff § | A1 | 0.10 | - | 0.30 |
| Overall Width | E | | 10.30 BSC | |
| Molded Package Width | E1 | | 7.50 BSC | |
| Overall Length | D | | 12.80 BSC | |
| Chamfer (Optional) | h | 0.25 | - | 0.75 |
| Foot Length | L | 0.40 | - | 1.27 |
| Footprint | L1 | | 1.40 REF | |
| Lead Angle | Θ | 0° | - | - |
| Foot Angle | φ | 0° | - | 8° |
| Lead Thickness | c | 0.20 | - | 0.33 |
| Lead Width | b | 0.31 | - | 0.51 |
| Mold Draft Angle Top | α | 5° | - | 15° |
| Mold Draft Angle Bottom | β | 5° | - | 15° |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic
3. Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M

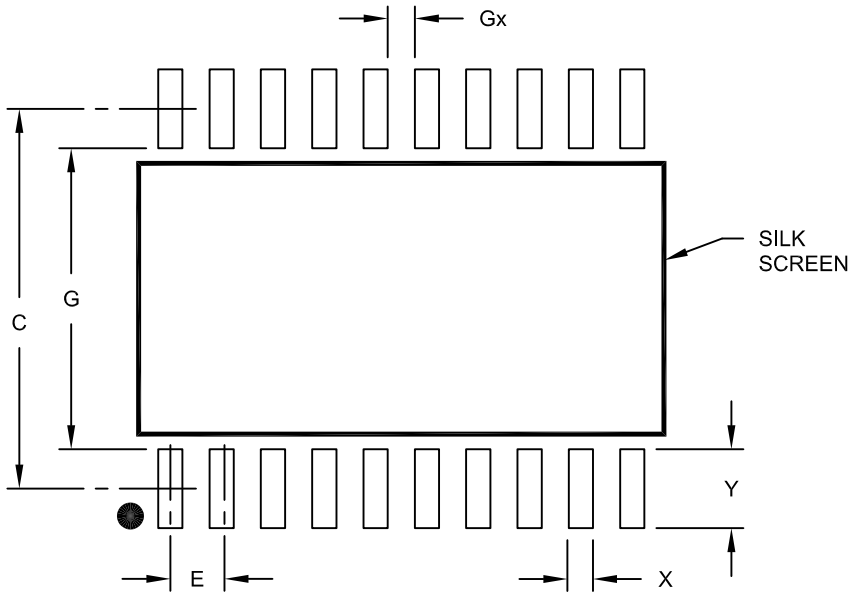
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

   REF: Reference Dimension, usually without tolerance, for information purposes only.
5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-094C Sheet 2 of 2

20-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | | 1.27 BSC | |
| Contact Pad Spacing | C | | 9.40 | |
| Contact Pad Width (X20) | X | | | 0.60 |
| Contact Pad Length (X20) | Y | | | 1.95 |
| Distance Between Pads | Gx | 0.67 | | |
| Distance Between Pads | G | 7.45 | | |

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2094A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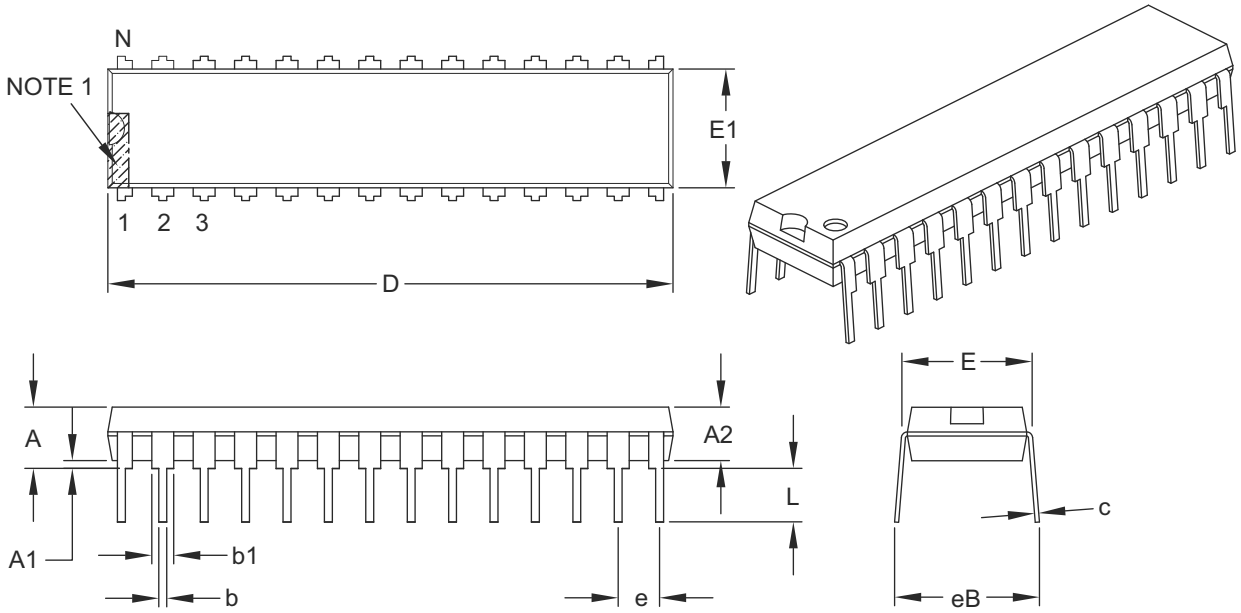
## 28-Lead Skinny Plastic Dual In-Line (SP) – 300 mil Body [SPDIP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | INCHES | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | |
| Pitch | e | | .100 BSC | |
| Top to Seating Plane | A | – | – | .200 |
| Molded Package Thickness | A2 | .120 | .135 | .150 |
| Base to Seating Plane | A1 | .015 | – | – |
| Shoulder to Shoulder Width | E | .290 | .310 | .335 |
| Molded Package Width | E1 | .240 | .285 | .295 |
| Overall Length | D | 1.345 | 1.365 | 1.400 |
| Tip to Seating Plane | L | .110 | .130 | .150 |
| Lead Thickness | c | .008 | .010 | .015 |
| Upper Lead Width | b1 | .040 | .050 | .070 |
| Lower Lead Width | b | .014 | .018 | .022 |
| Overall Row Spacing § | eB | – | – | .430 |

**Notes:**

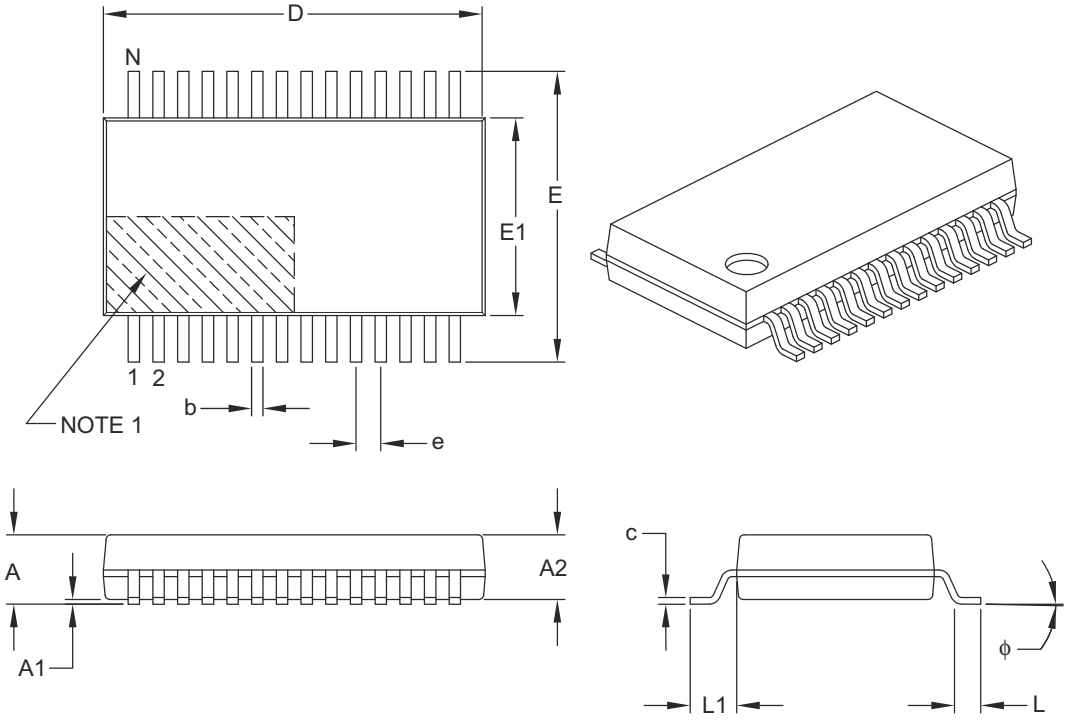
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic.
3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
4. Dimensioning and tolerancing per ASME Y14.5M.

   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-070B

### 28-Lead Plastic Shrink Small Outline (SS) – 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | |
| Pitch | e | | 0.65 BSC | |
| Overall Height | A | – | – | 2.00 |
| Molded Package Thickness | A2 | 1.65 | 1.75 | 1.85 |
| Standoff | A1 | 0.05 | – | – |
| Overall Width | E | 7.40 | 7.80 | 8.20 |
| Molded Package Width | E1 | 5.00 | 5.30 | 5.60 |
| Overall Length | D | 9.90 | 10.20 | 10.50 |
| Foot Length | L | 0.55 | 0.75 | 0.95 |
| Footprint | L1 | | 1.25 REF | |
| Lead Thickness | c | 0.09 | – | 0.25 |
| Foot Angle | ϕ | 0° | 4° | 8° |
| Lead Width | b | 0.22 | – | 0.38 |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20 mm per side.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-073B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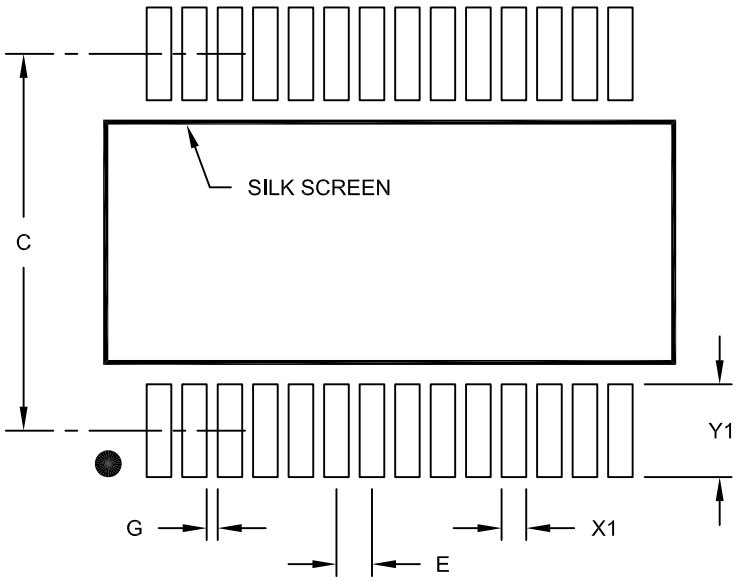
28-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | | 0.65 BSC | |
| Contact Pad Spacing | C | | 7.20 | |
| Contact Pad Width (X28) | X1 | | | 0.45 |
| Contact Pad Length (X28) | Y1 | | | 1.75 |
| Distance Between Pads | G | 0.20 | | |

Notes:

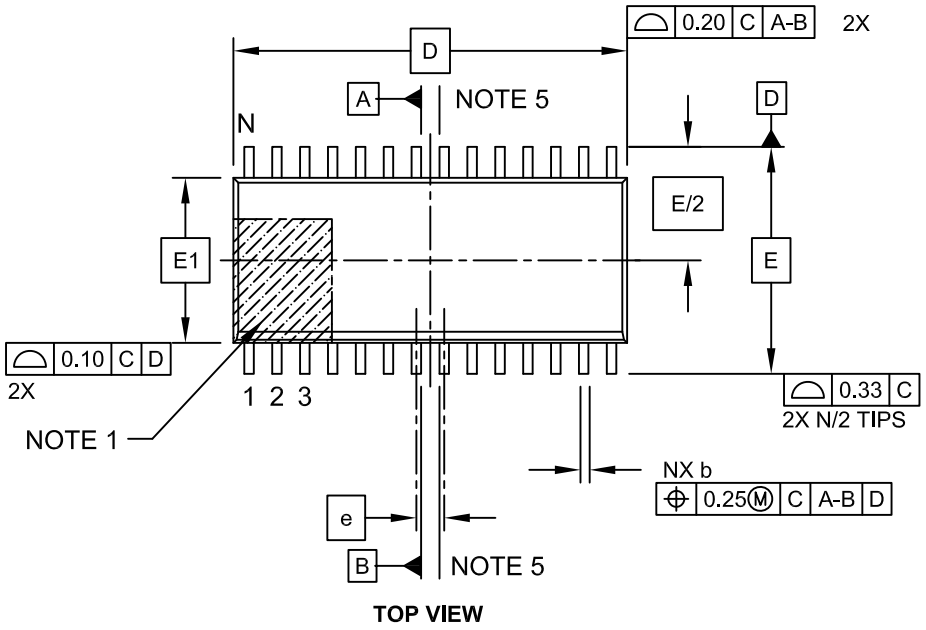
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

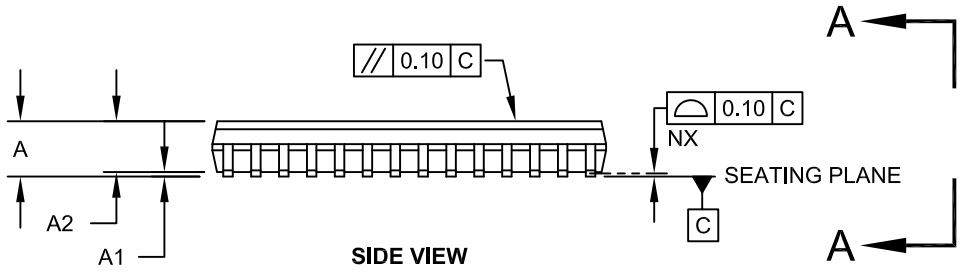
Microchip Technology Drawing No. C04-2073A

### 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

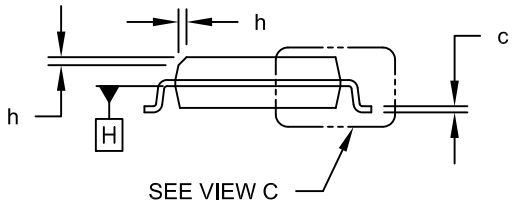
**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




**TOP VIEW**




**SIDE VIEW**




**VIEW A-A**

Microchip Technology Drawing C04-052C Sheet 1 of 2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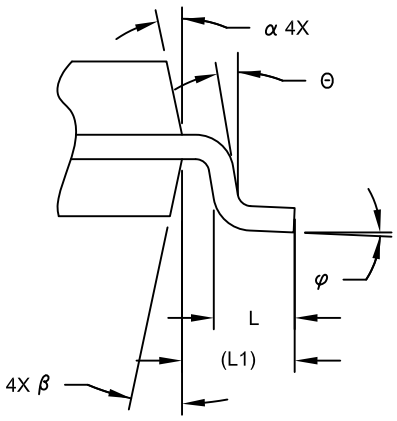
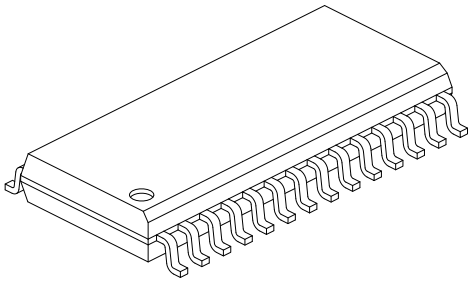
## 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




VIEW C



| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | |
| Pitch | e | | 1.27 BSC | |
| Overall Height | A | - | - | 2.65 |
| Molded Package Thickness | A2 | 2.05 | - | - |
| Standoff § | A1 | 0.10 | - | 0.30 |
| Overall Width | E | | 10.30 BSC | |
| Molded Package Width | E1 | | 7.50 BSC | |
| Overall Length | D | | 17.90 BSC | |
| Chamfer (Optional) | h | 0.25 | - | 0.75 |
| Foot Length | L | 0.40 | - | 1.27 |
| Footprint | L1 | | 1.40 REF | |
| Lead Angle | Θ | 0° | - | - |
| Foot Angle | φ | 0° | - | 8° |
| Lead Thickness | c | 0.18 | - | 0.33 |
| Lead Width | b | 0.31 | - | 0.51 |
| Mold Draft Angle Top | α | 5° | - | 15° |
| Mold Draft Angle Bottom | β | 5° | - | 15° |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic
3. Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M

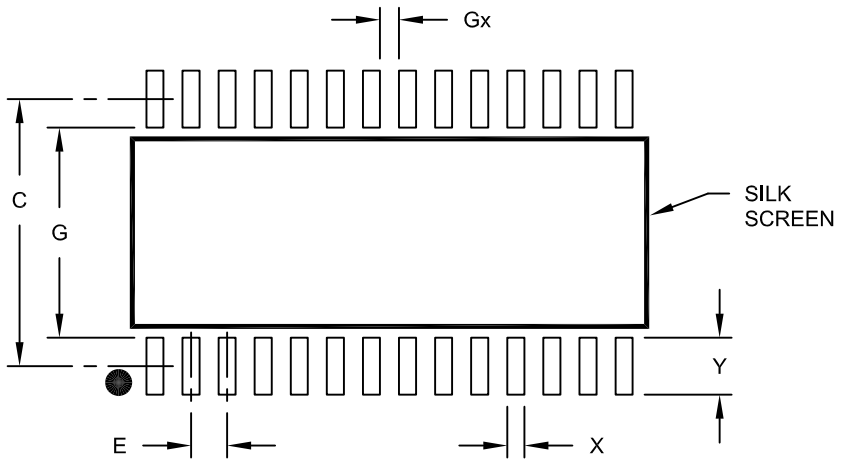
   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

   REF: Reference Dimension, usually without tolerance, for information purposes only.
5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2

28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | 1.27 BSC | | |
| Contact Pad Spacing | C | | 9.40 | |
| Contact Pad Width (X28) | X | | | 0.60 |
| Contact Pad Length (X28) | Y | | | 2.00 |
| Distance Between Pads | Gx | 0.67 | | |
| Distance Between Pads | G | 7.40 | | |

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2052A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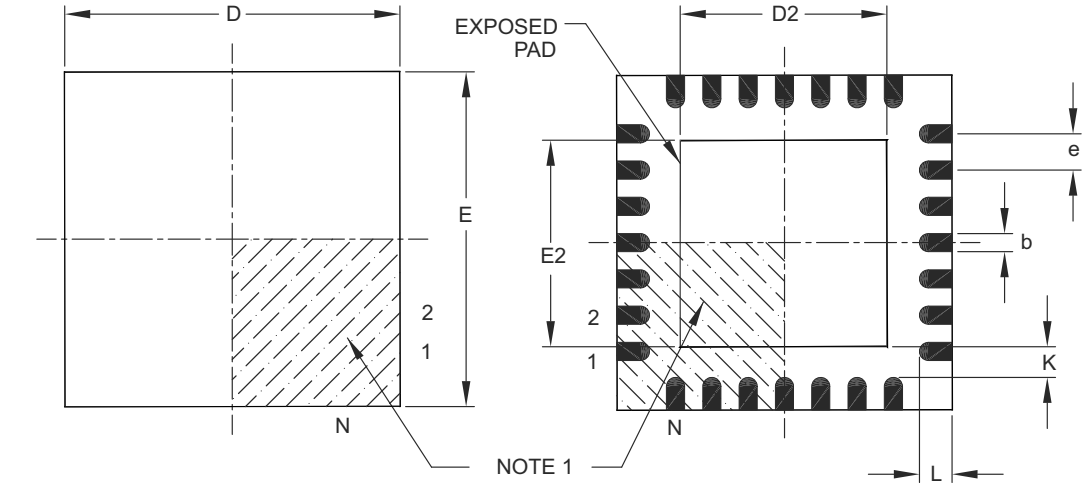
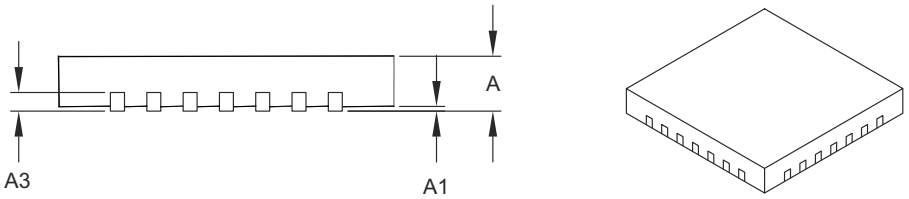
## 28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | | 28 | |
| Pitch | e | | 0.65 BSC | |
| Overall Height | A | 0.80 | 0.90 | 1.00 |
| Standoff | A1 | 0.00 | 0.02 | 0.05 |
| Contact Thickness | A3 | | 0.20 REF | |
| Overall Width | E | | 6.00 BSC | |
| Exposed Pad Width | E2 | 3.65 | 3.70 | 4.20 |
| Overall Length | D | | 6.00 BSC | |
| Exposed Pad Length | D2 | 3.65 | 3.70 | 4.20 |
| Contact Width | b | 0.23 | 0.30 | 0.35 |
| Contact Length | L | 0.50 | 0.55 | 0.70 |
| Contact-to-Exposed Pad | K | 0.20 | – | – |

**Notes:**

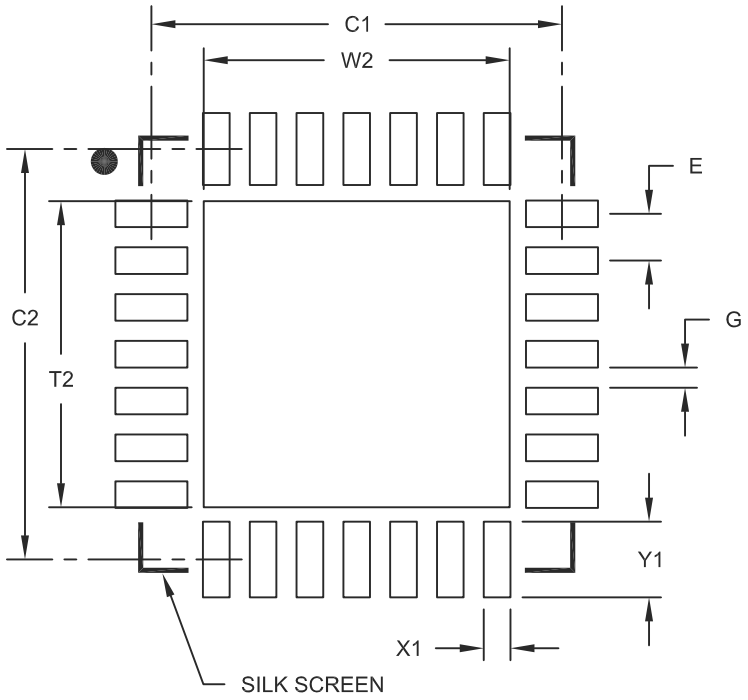
1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated.
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105B

### 28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging




RECOMMENDED LAND PATTERN

| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Contact Pitch | E | | 0.65 BSC | |
| Optional Center Pad Width | W2 | | | 4.25 |
| Optional Center Pad Length | T2 | | | 4.25 |
| Contact Pad Spacing | C1 | | 5.70 | |
| Contact Pad Spacing | C2 | | 5.70 | |
| Contact Pad Width (X28) | X1 | | | 0.37 |
| Contact Pad Length (X28) | Y1 | | | 1.00 |
| Distance Between Pads | G | 0.20 | | |

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2105A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# APPENDIX A: REVISION HISTORY

## Revision A (January 2007)

This is the initial released version of this document.

## Revision B (May 2007)

This revision includes the following corrections and updates:

- Minor typographical and formatting corrections throughout the data sheet text.
- New content:
  - Addition of bullet item (16-word conversion result buffer) (see **Section 19.1 “Key Features”**)
- Figure update:
  - Oscillator System Diagram (see Figure 7-1)
  - WDT Block Diagram (see Figure 20-2)
- Equation update:
  - Serial Clock Rate (see Equation 17-1)
- Register updates:
  - Clock Divisor Register (see Register 7-2)
  - PLL Feedback Divisor Register (see Register 7-3)
  - Peripheral Pin Select Input Registers (see Register 9-1 through Register 9-13)
  - Note 2 in PWM Control Register 1 (see Register 14-5)
  - ADC1 Input Channel 1, 2, 3 Select Register (see Register 19-4)
  - ADC1 Input Channel 0 Select Register (see Register 19-5)
- Table updates:
  - AD1CON3 (see Table 3-15 and Table 3-16)
  - RPINR15 (see Table 3-17)
  - TRISA (see Table 3-20)
  - TRISB (see Table 3-22)
  - Reset Flag Bit Operation (see Table 5-1)
  - Configuration Bit Values for Clock Operation (see Table 7-1)
- Operation value update:
  - IOLOCK set/clear operation (see **Section 9.4.3.1 “Control Register Lock”**)
- The following tables in **Section 23.0 “Electrical Characteristics”** have been updated with preliminary values:
  - Updated Max MIPS for -40°C to +125°C Temp Range (see Table 23-1)
  - Updated parameter DC18 (see Table 23-4)
  - Added new parameters for +125°C, and updated Typical and Max values for most parameters (see Table 23-5)
  - Added new parameters for +125°C, and updated Typical and Max values for most parameters (see Table 23-6)
  - Added new parameters for +125°C, and updated Typical and Max values for most parameters (see Table 23-7)
  - Added new parameters for +125°C, and updated Typical and Max values for most parameters (see Table 23-8)
  - Updated parameter DI51, added parameters DI51a, DI51b, and DI51c (see Table 23-9)
  - Added Note 1 (see Table 23-11)
  - Updated parameter OS30 (see Table 23-16)
  - Updated parameter OS52 (see Table 23-17)
  - Updated parameter F20, added Note 2 (see Table 23-18)
  - Updated parameter F21 (see Table 23-19)
  - Updated parameter TA15 (see Table 23-22)
  - Updated parameter TB15 (see Table 23-23)
  - Updated parameter TC15 (see Table 23-24)
  - Updated parameter IC15 (see Table 23-26)
  - Updated parameters AD05, AD06, AD07, AD08, AD10, and AD11; added parameters AD05a and AD06a; added Note 2; modified ADC Accuracy headings to include measurement information (see Table 23-38)
  - Separated the ADC Module Specifications table into three tables (see Table 23-38, Table 23-39, and Table 23-40)
  - Updated parameter AD50 (see Table 23-41)
  - Updated parameters AD50 and AD57 (see Table 23-42)

## Revision C (June 2008)

This revision includes minor typographical and formatting changes throughout the data sheet text.

The major changes are referenced by their respective section in the following table.

**TABLE 25-1: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **"High-Performance, 16-bit Digital Signal Controllers"** | Added SSOP to list of available 28-pin packages (see **"Packaging:"** and Table 1).<br><br>Added External Interrupts column to Remappable Peripherals in the Controller Families table and Note 2 (see Table 1).<br><br>Added Note 1 to all pin diagrams, which references RPn pin usage by remappable peripherals (see **"Pin Diagrams"**). |
| **Section 1.0 "Device Overview"** | Changed Capture Input pin names from IC0-IC1 to IC1-IC2 and updated description for AVDD (see Table 1-1). |
| **Section 3.0 "Memory Organization"** | Added SFR definitions (ACCAL, ACCAH, ACCAU, ACCBL, ACCBH, and ACCBU) to the CPU Core Register Map (see Table 3-1).<br><br>Updated Reset values for the following SFRs: IPC0, IPC2-IPC7, IPC16, and INTTREG (see Table 3-4).<br><br>Updated all SFR names in QEI1 Register Map (see Table 3-11).<br><br>The following changes were made to the ADC1 Register Maps:<br>• Updated the bit range for AD1CON3 from ADCS<**5**:0> to ADCS<**7**:0>) (see Table 3-15 and Table 3-16).<br>• Added Bit 6 (PCFG7) and Bit 7 (PCFG6) names to AD1PCFGL (Table 3-15).<br>• Added Bit 6 (CSS7) and Bit 7 (CSS6) names to AD1CSSL (see Table 3-15).<br>• Changed Bit 5 and Bit 4 in AD1CSSL to unimplemented (see Table 3-15).<br><br>Updated the Reset value for CLKDIV in the System Control Register Map (see Table 3-23). |
| **Section 4.0 "Flash Program Memory"** | Updated **Section 4.3 "Programming Operations"** with programming time formula. |
| **Section 5.0 "Resets"** | Entire section was replaced to maintain consistency with other dsPIC33F data sheets. |
| **Section 7.0 "Oscillator Configuration"** | Removed the first sentence of the third clock source item (External Clock) in **Section 7.1.1 "System Clock sources"**<br><br>Updated the default bit values for DOZE and FRCDIV in the Clock Divisor Register (see Register 7-2).<br><br>Added the center frequency in the OSCTUN register for the FRC Tuning bits (TUN<5:0>) value 011111 and updated the center frequency for bits value 011110 (see Register 7-4) |
| **Section 8.0 "Power-Saving Features"** | Added the following three registers:<br>• **PMD1: Peripheral Module Disable Control Register 1**<br>• **PMD2: Peripheral Module Disable Control Register 2**<br>• **PMD3: Peripheral Module Disable Control Register 3** |


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**TABLE 25-1: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **Section 9.0 "I/O Ports"** | Added paragraph and Table 9-1 to **Section 9.1.1 "Open-Drain Configuration"**, which provides details on I/O pins and their functionality.<br><br>Removed the following sections, which are now available in the related section of the dsPIC33F Family Reference Manual:<br>• 9.4.2 "Available Peripherals"<br>• 9.4.3.3 "Mapping"<br>• 9.4.5 "Considerations for Peripheral Pin Selection" |
| **Section 13.0 "Output Compare"** | Replaced sections 13.1, 13.2, and 13.3 and related figures and tables with entirely new content. |
| **Section 14.0 "Motor Control PWM Module"** | Removed the following sections, which are now available in the related section of the dsPIC33F Family Reference Manual:<br>• 14.3 "PWM Time Base<br>• 14.4 "PWM Period"<br>• 14.5 "Edge-Aligned PWM"<br>• 14.6 "Center-Aligned PWM"<br>• 14.7 "PWM Duty Cycle Comparison Units"<br>• 14.8 "Complementary PWM Operation"<br>• 14.9 "Dead-Time Generators"<br>• 14.10 "Independent PWM Output"<br>• 14.11 "Single Pulse PWM Operation"<br>• 14.12 "PWM Output Override"<br>• 14.13 "PWM Output and Polarity Control<br>• 14.14 "PWM Fault Pins"<br>• 14.15 "PWM Update Lockout"<br>• 14.16 "PWM Special Event Trigger"<br>• 14.17 "PWM Operation During CPU Sleep Mode"<br>• 14.18 "PWM Operation During CPU Idle Mode |
| **Section 15.0 "Quadrature Encoder Interface (QEI) Module"** | Removed the following sections, which are now available in the related section of the dsPIC33F Family Reference Manual:<br>• 15.1 "Quadrature Encoder Interface Logic"<br>• 15.2 "16-bit Up/Down Position Counter Mode"<br>• 15.3 "Position Measurement Mode"<br>• 15.4 "Programmable Digital Noise Filters"<br>• 15.5 "Alternate 16-bit Timer/Counter"<br>• 15.6 QEI Module Operation During CPU Sleep Mode"<br>• 15.7 "QEI Module Operation During CPU Idle Mode"<br>• 15.8 "Quadrature Encoder Interface Interrupts" |
| **Section 16.0 "Serial Peripheral Interface (SPI)"** | Removed the following sections, which are now available in the related section of the dsPIC33F Family Reference Manual:<br>• 16.1 "Interrupts"<br>• 16.2 "Receive Operations"<br>• 16.3 "Transmit Operations"<br>• 16.4 "SPI Setup: Master Mode"<br>• 16.5 "SPI Setup: Slave Mode" (retained Figure 16-1: SPI Module Block Diagram) |

**TABLE 25-1: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **Section 17.0 "Inter-Integrated Circuit™ ($I^2C$™)"** | Removed the following sections, which are now available in the related section of the dsPIC33F Family Reference Manual:<br>• 17.3 "$I^2C$ Interrupts"<br>• 17.4 "Baud Rate Generator" (retained Figure 17-1: $I^2C$ Block Diagram)<br>• 17.5 "$I^2C$ Module Addresses<br>• 17.6 "Slave Address Masking"<br>• 17.7 "IPMI Support"<br>• 17.8 "General Call Address Support"<br>• 17.9 "Automatic Clock Stretch"<br>• 17.10 "Software Controlled Clock Stretching (STREN = 1)"<br>• 17.11 "Slope Control"<br>• 17.12 "Clock Arbitration"<br>• 17.13 "Multi-Master Communication, Bus Collision, and Bus Arbitration<br>• 17.14 "Peripheral Pin Select Limitations |
| **Section 18.0 "Universal Asynchronous Receiver Transmitter (UART)"** | Removed the following sections, which are now available in the related section of the dsPIC33F Family Reference Manual:<br>• 18.1 "UART Baud Rate Generator"<br>• 18.2 "Transmitting in 8-bit Data Mode<br>• 18.3 "Transmitting in 9-bit Data Mode<br>• 18.4 "Break and Sync Transmit Sequence"<br>• 18.5 "Receiving in 8-bit or 9-bit Data Mode"<br>• 18.6 "Flow Control Using $\overline{\text{UxCTS}}$ and $\overline{\text{UxRTS}}$ Pins"<br>• 18.7 "Infrared Support"<br><br>Removed IrDA references and Note 1, and updated the bit and bit value descriptions for UTXINV (UxSTA<14>) in the UARTx Status and Control Register (see Register 18-2). |


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**TABLE 25-1: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **Section 19.0 "10-bit/12-bit Analog-to-Digital Converter (ADC)"** | Updated ADC Conversion Clock Select bits in the AD1CON3 register from ADCS<**5**:0> to ADCS<**7**:0>. Any references to these bits have also been updated throughout this data sheet (Register 19-3).<br><br>Replaced Figure 19-1 (ADC1 Module Block Diagram for dsPIC33FJ12MC201) and added Figure 19-2 (ADC1 Block Diagram for dsPIC33FJ12MC202).<br><br>Removed Equation 19-1: ADC Conversion Clock Period and Figure 19-2: ADC Transfer Function (10-Bit Example).<br><br>Added Note 2 to Figure 19-2: ADC Conversion Clock Period Block Diagram.<br><br>Updated ADC1 Input Channel 1, 2, 3 Select Register (see Register 19-4) as follows:<br>• Changed bit 10-9 (CH123NB - dsPIC33FJ12MC201 devices only) description for bit value of `10` (if AD12B = `0`).<br>• Updated bit 8 (CH123SB) to reflect device-specific information.<br>• Updated bit 0 (CH123SA) to reflect device-specific information.<br>• Changed bit 2-1 (CH123NA - dsPIC33FJ12MC201 devices only) description for bit value of `10` (if AD12B = `0`).<br><br>Updated ADC1 Input Channel 0 Select Register (see Register 19-5) as follows:<br>• Changed bit value descriptions for bits 12-8<br>• Changed bit value descriptions for bits 4-0 (dsPIC33FJ12MC201 devices)<br><br>Modified Notes 1 and 2 in the ADC1 Input Scan Select Register Low (see Register 19-6)<br><br>Modified Notes 1 and 2 in the ADC1 Port Configuration Register Low (see Register 19-7) |
| **Section 20.0 "Special Features"** | Added FICD register information for address 0xF8000E in the Device Configuration Register Map (see Table 20-1).<br><br>Added FICD register content (BKBUG, COE, JTAGEN, and ICS<1:0> to the dsPIC33FJ12MC201/202 Configuration Bits Description (see Table 20-2).<br><br>Added a note regarding the placement of low-ESR capacitors, after the second paragraph of **Section 20.2 "On-Chip Voltage Regulator"** and to Figure 20-2.<br><br>Removed the words "if enabled" from the second sentence in the fifth paragraph of **Section 20.3 "BOR: Brown-out Reset"** |

**TABLE 25-1: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **Section 23.0 "Electrical Characteristics"** | Updated Max MIPS value for -40ºC to +125ºC temperature range in Operating MIPS vs. Voltage (see Table 23-1).<br><br>Added 20-pin SOIC and 28-pin SSOP package information to Thermal Packaging Characteristics and updated Typical values for all devices (see Table 23-3).<br><br>Removed Typ value for parameter DC12 (see Table 23-4).<br><br>Updated Note 2 in Table 23-7: DC Characteristics: Power-Down Current (IPD).<br><br>Updated MIPS conditions for parameters DC24c, DC44c, DC72a, DC72f, and DC72g (see Table 23-5, Table 23-6, and Table 23-8).<br><br>Added Note 4 (reference to new table containing digital-only and analog pin information to I/O Pin Input Specifications (see Table 23-9).<br><br>Updated Program Memory parameters (D136a, D136b, D137a, D137b, D138a, and D138b) and added Note 2 (see Table 23-12).<br><br>Updated Max value for Internal RC Accuracy parameter F21 for -40°C ≤TA ≤ +125°C condition and added Note 2 (see Table 23-19).<br><br>Removed all values for Reset, Watchdog Timer, Oscillator Start-up Timer, and Power-up Timer parameter SY20 and updated conditions, which now refers to **Section 20.4 "Watchdog Timer (WDT)"** and LPRC parameter F21 (Table 23-21).<br><br>Updated Min value for Input Capture Timing Requirements parameter IC15 (see Table 23-26).<br><br>The following changes were made to the ADC Module Specifications (Table 23-38):<br>• Updated Min value for ADC Module Specification parameter AD07.<br>• Updated Typ value for parameter AD08<br>• Added references to Note 1 for parameters AD12 and AD13<br>• Removed Note 2.<br><br>The following changes were made to the ADC Module Specifications (12-bit Mode) (Table 23-39):<br>• Updated Min and Max values for both AD21a parameters (measurements with *internal* and *external* VREF+/VREF-).<br>• Updated Min, Typ, and Max values for parameter AD24a.<br>• Updated Max value for parameter AD32a.<br>• Removed Note 1.<br>• Removed VREFL from Conditions for parameters AD21a, AD22a, AD23a, and AD24a (measurements with *internal* VREF+/VREF-).<br><br>The following changes were made to the ADC Module Specifications (10-bit Mode) (Table 23-40):<br>• Updated Min and Max values for parameter AD21b (measurements with *external* VREF+/VREF-).<br>• Removed ± symbol from Min, Typ, and Max values for parameters AD23b and AD24b (measurements with *internal* VREF+/VREF-).<br>• Updated Typ and Max values for parameter AD32b.<br>• Removed Note 1.<br>• Removed VREFL from Conditions for parameters AD21a, AD22a, AD23a, and AD24a (measurements with *internal* VREF+/VREF-).<br>Updated Min and Typ values for parameters AD60, AD61, AD62, and AD63 and removed Note 3 (see Table 23-41 and Table 23-42). |


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**TABLE 25-1: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **Section 24.0 “Packaging Information”** | Added 28-lead SSOP package marking information. |
| **“Product Identification System”** | Added Plastic Shrink Small Outline (SSOP) package information. |

## Revision D (June 2009)

This revision includes minor typographical and formatting changes throughout the data sheet text.

Global changes include:

- Changed all instances of OSCI to OSC1 and OSCO to OSC2
- Changed all instances of PGCx/EMUCx and PGDx/EMUDx (where x = 1, 2, or 3) to PGECx and PGEDx

Changed all instances of VDDCORE and VDDCORE/VCAP to VCAP/VDDCORE

All other major changes are referenced by their respective section in the following table.

**TABLE 25-2: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **“High-Performance, 16-bit Digital Signal Controllers”** | Added Note 2 to the 28-Pin QFN-S and 44-Pin QFN pin diagrams, which references pin connections to VSS. |
| **Section 2.0 “Guidelines for Getting Started with 16-bit Digital Signal Controllers”** | Added new section to the data sheet that provides guidelines on getting started with 16-bit Digital Signal Controllers. |
| **Section 8.0 “Oscillator Configuration”** | Updated the Oscillator System Diagram (see Figure 8-1).<br><br>Added Note 1 to the Oscillator Tuning (OSCTUN) register (see Register 8-4). |
| **Section 10.0 “I/O Ports”** | Removed Table 10-1 and added reference to pin diagrams for I/O pin availability and functionality. |
| **Section 17.0 “Serial Peripheral Interface (SPI)”** | Added Note 2 to the SPIx Control Register 1 (see Register 17-2). |
| **Section 19.0 “Universal Asynchronous Receiver Transmitter (UART)”** | Updated the UTXINV bit settings in the UxSTA register and added Note 1 (see Register 19-2). |
| **Section 24.0 “Electrical Characteristics”** | Updated the Min value for parameter DC12 (RAM Retention Voltage) and added Note 4 to the DC Temperature and Voltage Specifications (see Table 24-4).<br><br>Updated the Min value for parameter DI35 (see Table 24-20).<br><br>Updated AD08 and added reference to Note 2 for parameters AD05a, AD06a, and AD08a (see Table 24-38). |

## Revision E (July 2011)

This revision includes formatting changes and minor typographical throughout the data sheet text.

Global changes include:

- Removed Preliminary marking from the footer
- Updated all family reference manual information in the note boxes located at the beginning of most chapters
- Changed all instances of VCAP/VDDCORE to VCAP

All other major changes are referenced by their respective section in the following table.

**TABLE 25-3: MAJOR SECTION UPDATES**

| Section Name | Update Description |
|---|---|
| **Section 2.0 "Guidelines for Getting Started with 16-bit Digital Signal Controllers"** | Changed the title of section 2.3 to **Section 2.3 "CPU Logic Filter Capacitor Connection (VCAP)"**.<br><br>Updated the second paragraph in **Section 2.9 "Unused I/Os"**. |
| **Section 4.0 "Memory Organization"** | Revised the data memory implementation value in the third paragraph of **Section 4.2 "Data Address Space"**.<br><br>Updated the All Resets values for TMR1, TMR2, and TMR3 in the Timer Register Map (see Table 4-5). |
| **Section 8.0 "Oscillator Configuration"** | Added Note 3 to the Oscillator Control Register (see Register 8-1).<br><br>Added Note 2 to the Clock Divisor Register (see Register 8-2).<br><br>Added Note 1 to the PLL Feedback Divisor Register (see Register 8-3).<br><br>Added Note 2 to the FRC Oscillator Tuning Register (see Register 8-4). |
| **Section 10.0 "I/O Ports"** | Revised the second paragraph in **Section 10.1.1 "Open-Drain Configuration"**. |
| **Section 14.0 "Output Compare"** | Updated the Output Compare Module Block Diagram (see Figure 14-1). |
| **Section 19.0 "Universal Asynchronous Receiver Transmitter (UART)"** | Revised the UART module Baud Rate features, replacing both items with "Baud rates ranging from 10 Mbps to 38 bps at 40 MIPS". |
| **Section 21.0 "Special Features"** | Revised all paragraphs in **Section 21.1 "Configuration Bits"**.<br><br>Updated the Device Configuration Register Map (see Table 21-1).<br><br>Added the RTSP Effect column in the Configuration Bits Description (see Table 21-2). |


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**TABLE 25-3: MAJOR SECTION UPDATES (CONTINUED)**

| Section Name | Update Description |
|---|---|
| **Section 24.0 "Electrical Characteristics"** | Updated the following Absolute Maximum Ratings:<br>• Storage temperature<br>• Voltage on any pin that is not 5V tolerant with respect to VSS<br>• Voltage on any 5V tolerant pin with respect to VSS when VDD ≥ 3.0V<br>• Voltage on any 5V tolerant pin with respect to VSS when VDD < 3.0V<br>• Added Note 4<br><br>Revised parameters DI18, DI19, DI50, and DI51, added parameters DI21, DI25, DI26, DI27, DI28, DI29, DI60a, DI60b, and DI60c, and added Notes 5, 6, 7, 8, and 9 to the I/O Pin Input Specifications (see Table 24-9).<br><br>Removed Note 2 from the AC Characteristics: Internal RC Accuracy (see Table 24-19).<br><br>Updated the maximum value for parameter OC15 and the minimum value for parameter OC20 in the Simple OC/PWM Mode Timing Requirements (see Table 24-28).<br><br>Updated *all* SPI specifications (see Table 24-32 through Table 24-39 and Figure 24-14 through Figure 24-21).<br><br>Updated the minimum values for parameters AD05 and AD07, and the maximum value for parameter AD06 in the ADC Module Specifications (see Table 24-42).<br><br>Added Note 4 regarding injection currents to the ADC Module Specifications (12-bit mode) (see Table 24-43).<br><br>Added Note 4 regarding injection currents to the ADC Module Specifications (10-bit mode) (see Table 24-44). |

**NOTES:**


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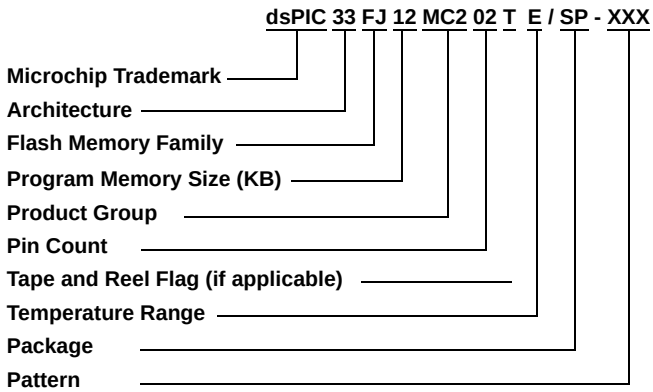


| | | | |
|---|---|---|---|
| Architecture: | 33 | = | 16-bit Digital Signal Controller |
| Flash Memory Family: | FJ | = | Flash program memory, 3.3V |
| Product Group: | MC2 | = | Motor Control family |
| Pin Count: | 01 | = | 20-pin |
| | 02 | = | 28-pin |
| Temperature Range: | I | = | -40° C to+85° C (Industrial) |
| | E | = | -40° C to+125° C (Extended) |
| Package: | P | = | Plastic Dual In-Line - 300 mil body (PDIP) |
| | SP | = | Skinny Plastic Dual In-Line - 300 mil body (SPDIP) |
| | SO | = | Plastic Small Outline - Wide, 7.50 mil body (SOIC) |
| | ML | = | Plastic Quad, No Lead Package - 6x6 mm body (QFN) |
| | SS | = | Plastic Shrink Small Outline - 5.3 mm body (SSOP) |

**Examples:**

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