

## DESCRIPTION

Demonstration circuit 2520A shows the proper way to drive the LTC<sup>®</sup>2344 ADC. The LTC2344 is a low noise, high speed, simultaneous sampling 16-/18-bit successive approximation register (SAR) ADC. The LTC2344 has a flexible SoftSpan™ interface that allows conversion-by-conversion control of the input voltage span on a per-channel basis. An internal 2.048V reference and 2× buffer simplify basic operation while an external reference can be used to increase the input range and the SNR of the ADC.

The DC2520A demonstrates the DC and AC performance of the LTC2344 in conjunction with the DC590/DC2026 and DC890 data collection boards. Use the DC590/DC2026 to

demonstrate DC performance such as peak-to-peak noise and DC linearity. Use the DC890 if precise sampling rates are required or to demonstrate AC performance such as SNR, THD, SINAD and SFDR. The DC2520A is intended to demonstrate recommended grounding, component placement and selection, routing and bypassing for this ADC. A suggested driver circuit for the analog inputs is also presented.

**Design files for this circuit board including the schematic, layout and BOM are available at**

<http://www.linear.com/demo/DC2520A>

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## BOARD PHOTO

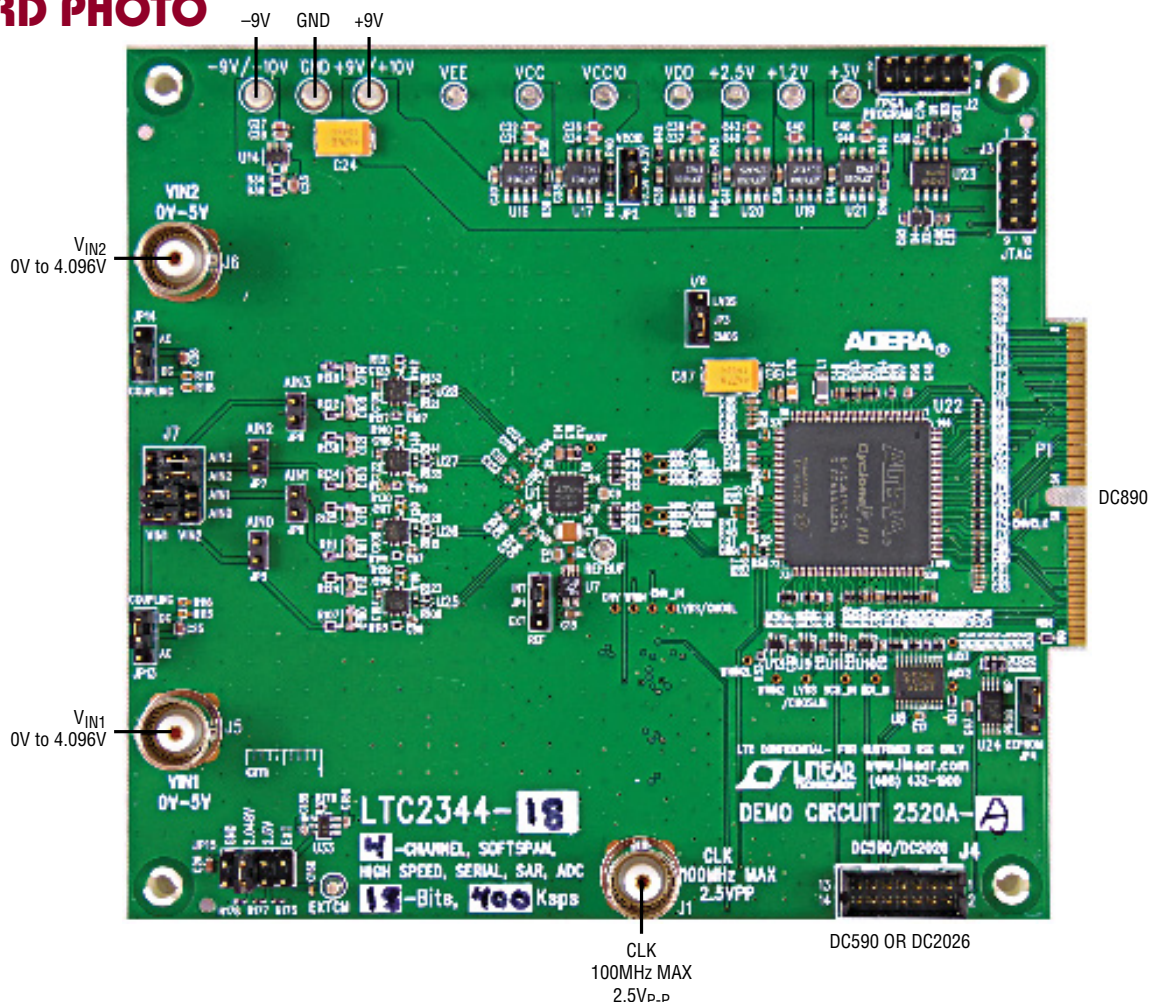


Figure 1. DC2520A Connection Diagram

dc2520af

## ASSEMBLY OPTIONS

| Assembly Version | U1 Part Number | Max Conversion Rate | Number of Channels | Number of Bits | Max CLK IN Frequency | CLK IN/fs Ratio |
|------------------|----------------|---------------------|--------------------|----------------|----------------------|-----------------|
| DC2520A-A        | LTC2344-18     | 400ksps             | 4                  | 18             | 68.8MHz              | 172             |
| DC2520A-B        | LTC2344-16     | 400ksps             | 4                  | 16             | 68.8MHz              | 172             |

## DC890 QUICK START PROCEDURE

Check to make sure that all jumpers are set to their default settings as described in the DC2520A Jumpers section of this manual. The default connections configure the ADC to use the onboard reference and regulators to generate all the required bias voltages. The analog inputs by default are DC coupled. Connect the DC2520A to a DC890 USB High Speed Data Collection Board using connector P1. Then, connect the DC890 to a host PC with a standard USB A/B cable. Apply  $\pm 9V$  to the indicated terminals. Then apply a low jitter signal source to J5 and J6. Use J7 to route the signal sources of J5 and J6 to the desired AIN0-AIN3 inputs. Observe the recommended input voltage range for each analog input. Connect a low jitter 2.5V<sub>P-P</sub> sine wave or square wave to connector J1. See the Assembly Options table for the appropriate clock frequency. Note that J1 has a 50 $\Omega$  termination resistor to ground.

Run the PScope™ software (Pscope.exe version K86 or later) which can be downloaded from [www.linear.com/designtools/software](http://www.linear.com/designtools/software).

Complete software documentation is available from the Help menu. Updates can be downloaded from the Tools menu. Check for updates periodically as new features may be added.

The PScope software should recognize the DC2520A and configure itself automatically.

Click the Collect button (See Figure 3) to begin acquiring data. The Collect button then changes to Pause, which can be clicked to stop data acquisition.

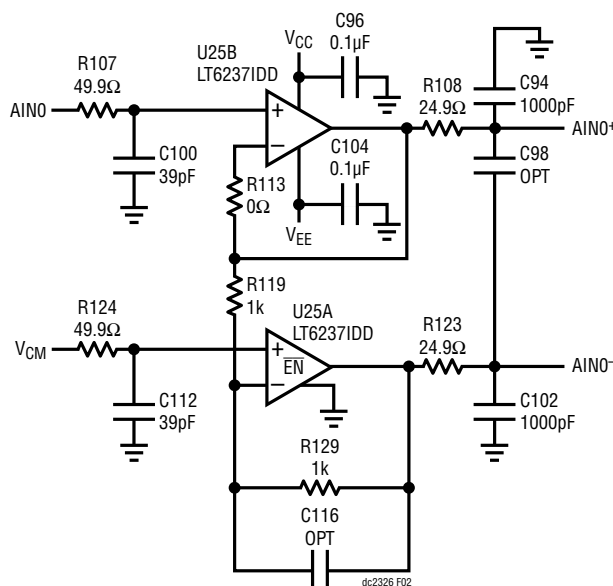
## DC590/DC2026 QUICK START PROCEDURE

**IMPORTANT! To avoid damage to the DC2520A, make sure that VCCIO (JP6 of the DC590, JP3 of the DC2026) of the DC590/DC2026 is set to 3.3V before connecting the DC590/DC2026 to the DC2520A.**

To use the DC590/DC2026 with the DC2520A, it is necessary to apply  $\pm 9V$  and ground to the  $\pm 9V$  and GND terminals of the DC2520A. Connect the DC590/DC2026 to a host PC with a standard USB A/B cable. Connect the DC2520A to a DC590/DC2026 USB serial controller using the supplied 14-conductor ribbon cable. Apply a signal source to J5

and J6. Use J7 to route the signal sources of J5 and J6 to the desired AIN0-AIN3 inputs. No Clock is required on J1 when using the DC590/DC2026. The clock signal is provided by the DC590/DC2026.

Run the QuikEval software (quikeval.exe version K110 or later) which is available from [www.linear.com/designtools/software](http://www.linear.com/designtools/software). The correct control panel will be loaded automatically. Click the COLLECT button (Figure 6) to begin reading the ADC.



## DC2520A SETUP

### Reference

The default reference is the LTC2344 internal 4.096V reference. Alternatively, if a higher reference voltage is desired, the LTC6655-5 reference (U7) can be used by setting the REF jumper (JP1) to the EXT position and installing a  $0\Omega$  resistor in the R7 position. This should result in better SNR performance but may slightly degrade the THD performance of the LTC2345.

### Analog Inputs

All eight inputs have the same driver circuitry. The circuit of Figure 2 shows the driver for AIN0. It provides a DC coupled single-ended to fully differential output to the analog inputs of the LTC2344 with a maximum 0V-4.096V input signal.

### DC890 Data Collection

For SINAD, THD or SNR testing a low noise, low distortion generator such as the B&K Type 1051 or Stanford Research SR1 should be used. A low jitter RF oscillator such as the Rohde & Schwarz SMB100A is used to drive the clock input. This demo board is tested in house by attempting to duplicate the FFT plot shown in Typical Performance Characteristics section of the LTC2344 data sheet. This involves using a 68.8MHz clock source, along with a sinusoidal generator at a frequency of approximately 2kHz. The input signal level is approximately -1dBFS. A typical FFT obtained with DC2520A is shown in Figure 3. Note that to calculate the real SNR, the signal level (F1 amplitude = -1.081dB) has to be added back to the SNR that PScope displays. With the example shown in Figure 3 this means that the actual SNR would be 93.59dB instead of the 92.51dB that PScope displays. Taking the RMS sum of the recalculated SNR and the THD yields a SINAD of 93.50dB which is fairly close to the typical number for this ADC.

To change the default settings for the LTC2344 in PScope, click on the Set Demo Bd Options button in the PScope tool bar shown in Figure 4. This will open the Configure Channels menu of Figure 5. In this menu it is possible to set the input signal range setting for each channel. There is also a button to return PScope to the default DC2520A settings which are optimized for the default hardware settings of the DC2520A.

There are a number of scenarios that can produce misleading results when evaluating an ADC. One that is common is feeding the converter with an input frequency that is a sub-multiple of the sample rate, and which will only exercise a small subset of the possible output codes. The proper method is to pick an M/N frequency for the input sine wave frequency. N is the number of samples in the FFT. M is a prime number between one and N/2. Multiply M/N by the sample rate to obtain the input sine wave frequency. Another scenario that can yield poor results is if you do not have a signal generator capable of ppm frequency accuracy or if it cannot be locked to the clock frequency. You can use an FFT with windowing to reduce the “leakage” or spreading of the fundamental, to get a close approximation of the ADC performance. If an amplifier or clock source with poor phase noise is used, the windowing will not improve the SNR.

### DC590/DC2026 Data Collection

Due to the relatively low and somewhat unpredictable sample rate of the DC590/DC2026 its usefulness is limited to noise measurement and data collection of slowly moving signals. A typical data capture and histogram are shown in Figure 6. To change the default settings for the LTC2344 in QuikEval, click on the Sequence Config button. This will open the Config Dialog menu of Figure 7. In this menu it is possible to set the input signal range for each sequence. There is also a button to return QuikEval to the default DC2520A settings which are optimized for the default hardware settings of the DC2520A.

## DC2520A SETUP

### Layout

As with any high performance ADC, this part is sensitive to layout. The area immediately surrounding the ADC on the DC2520A should be used as a guideline for placement, and routing of the various components associated with the ADC. Here are some things to remember when laying out a board for the LTC2344. A ground plane is necessary to obtain maximum performance. Keep bypass capacitors as close to supply pins as possible. Use individual low impedance returns for all bypass capacitors. Use of a symmetrical layout around the analog inputs will minimize the effects of parasitic elements. Shield analog input traces with ground to minimize coupling from other traces. Keep traces as short as possible.

### Component Selection

When driving a low noise, low distortion ADC such as the LTC2344, component selection is important so as to not degrade performance. Resistors should have low values to minimize noise and distortion. Metal film resistors are recommended to reduce distortion caused by self heating. Because of their low voltage coefficients, to further reduce distortion NPO or silver mica capacitors should be used. Any buffer used to drive the LTC2344 should have low distortion, low noise and a fast settling time such as the LT6237.

DC2520A SETUP

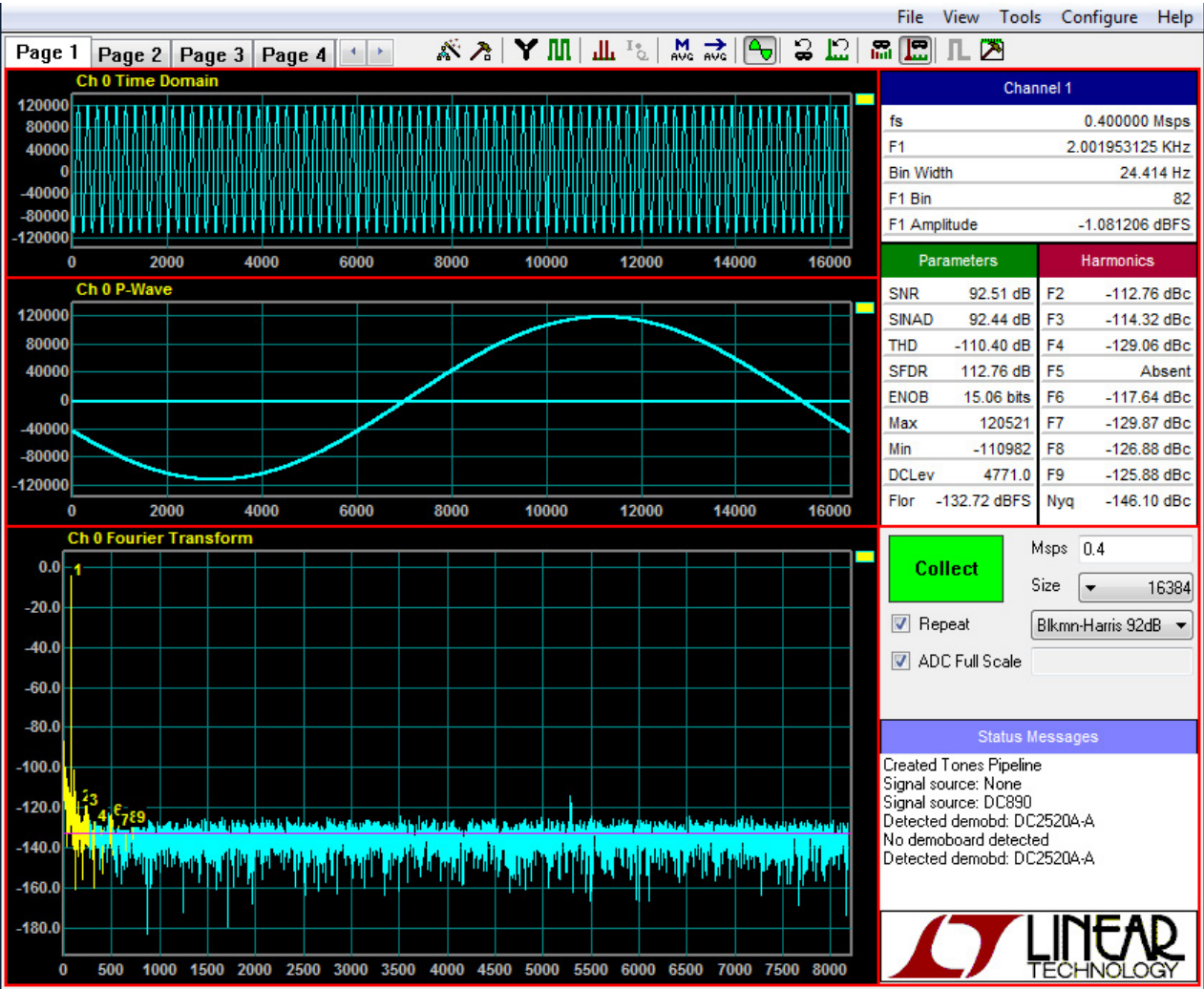


Figure 3. PScope Screen Shot

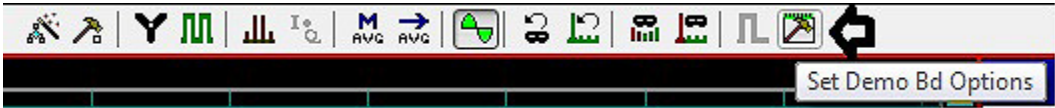


Figure 4. PScope Tool Bar

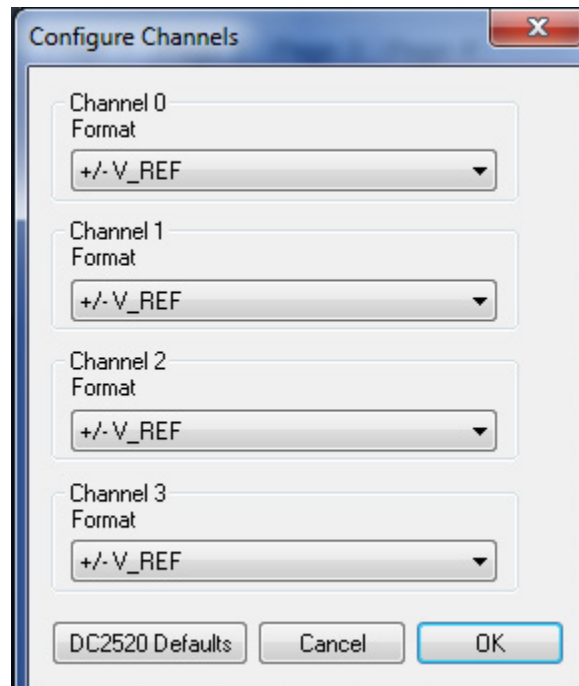
**DC2520A SETUP**

Figure 5. PScope Configuration Menu

DC2520A SETUP

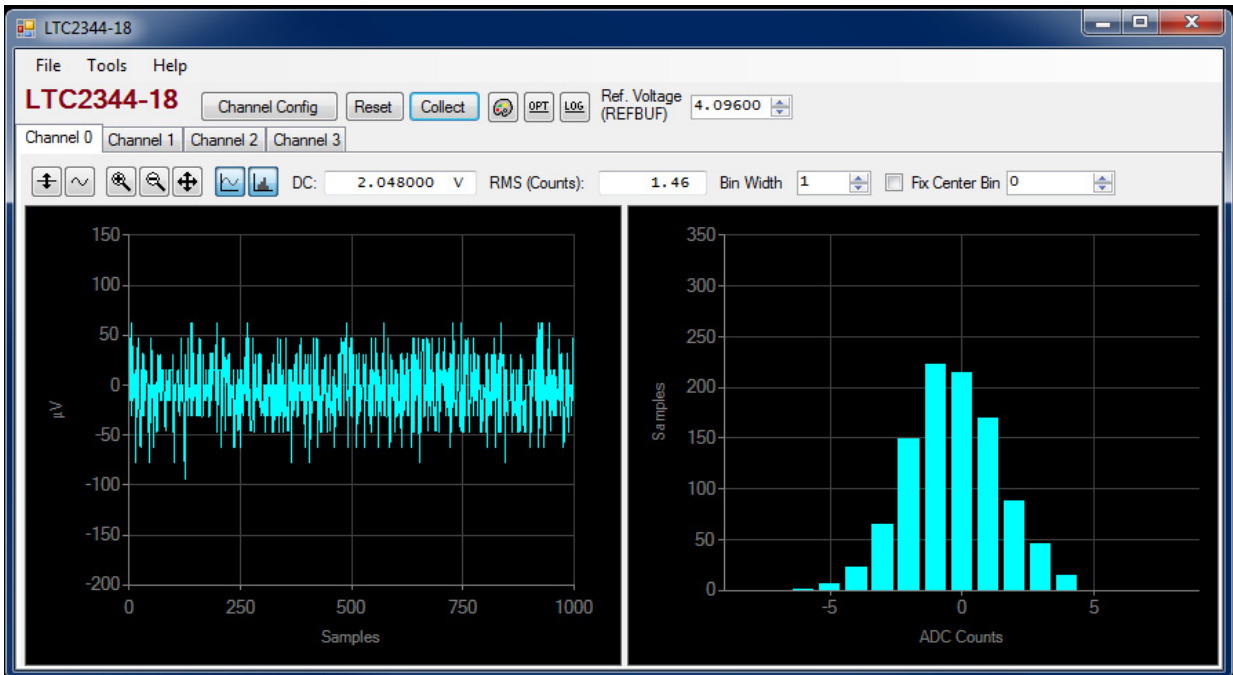


Figure 6. QuikEval Screen Shot

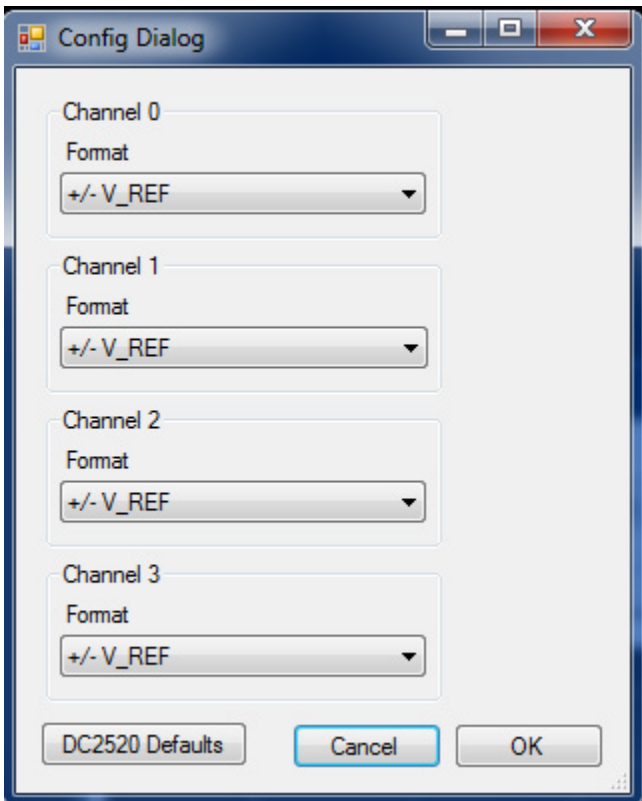


Figure 7. QuikEval Configuration Menu

## DC2520A JUMPERS

### Definitions

**JP1:** REF selects INT or EXT reference for the ADC. The default setting is INT.

**JP2:** VCCIO sets the output levels at P1 to either 3.3V or 2.5V. Use 2.5V to interface to the DC890 which is the default setting. Use 3.3V to interface to the DC2026.

**JP3:** I/O selects LVDS or CMOS logic levels. The default setting is CMOS. Only CMOS is currently supported.

**JP4:** EEPROM is for factory use only. The default position is WP.

**JP5-JP6:** AIN0-AIN3 can be used to short individual AIN inputs to ground or can be used drive the individual AIN inputs. The default is to leave these open.

**JP13-JP14:** Coupling selects AC or DC coupling for  $V_{IN1}$  and  $V_{IN2}$ . Default setting is DC.

**JP15:** Sets  $V_{CM}$  for the single-end to differential drivers of AIN0-AIN3

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## DC2520A CONNECTORS

### Definitions

**P1:** DC890 interface is used to communicate with the DC890 controller.

**J1:** CLK provides the master clock for the DC2520A when interfaced to the DC890.

**J2:** FPGA PROGRAM is used to program the FPGA. This is for factory use only.

**J3:** JTAG is for factory use only.

**J4:** DC590/DC2026 interface is used to communicate with the DC2026 Linduino controller or DC590.

**J5 and J6:** Provide analog input voltages to AIN0-AIN3 of the ADC.

**J7:** Routes the signals of J5 and J6 to AIN0-AIN3.

# DEMO MANUAL DC2520A

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