

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### General Description

The MAX7370 I<sup>2</sup>C-interfaced peripheral provides micro-processors with management of up to 64 key switches, with optional GPIO and PWM-controlled LED drivers.

The key-switch drivers interface with metallic or resistive switches with on-resistances up to 5k $\Omega$ . Key inputs are monitored statically, not dynamically, to ensure low-EMI operation. The IC features autosleep and autowake modes to further minimize the power consumption of the device. The autosleep feature puts the device in a low-power state (1 $\mu$ A typ) after a timeout period. The autowake feature configures the device to return to normal operating mode from sleep upon a keypress.

The key controller debounces and maintains a FIFO buffer of keypress and release events (including auto-repeat, if enabled). An interrupt ( $\overline{\text{INT}}$ ) output can be configured to alert keypresses, as they occur, or at the maximum rate.

The same index rows and columns in the device can be used as a direct logic-level translator.

If the device is not used for key-switch control, all keyboard pins can be used as GPIOs. Each GPIO can be programmed to one of the two externally applied logic voltage levels. Four column ports (COL7–COL4) can also be configured as LED drivers that feature constant-current and PWM intensity control. The maximum constant-current level for each open-drain LED port is 20mA. The intensity of the LED on each open-drain port can be individually adjusted through a 256-step PWM control.

The device is offered in a 24-pin (3.5mm x 3.5mm) TQFN package with an exposed pad, and small 25-bump (2.159mm x 2.159mm) wafer-level package (WLP) for cell phones, pocket PCs, and other portable consumer electronic applications.

The device operates over the -40°C to +85°C extended temperature range.

### Applications

- Cell Phones
- Notebooks
- PDA's
- Handheld Games
- Portable Consumer Electronics

For related parts and recommended products to use with this part, refer to [www.maximintegrated.com/MAX7370.related](http://www.maximintegrated.com/MAX7370.related).

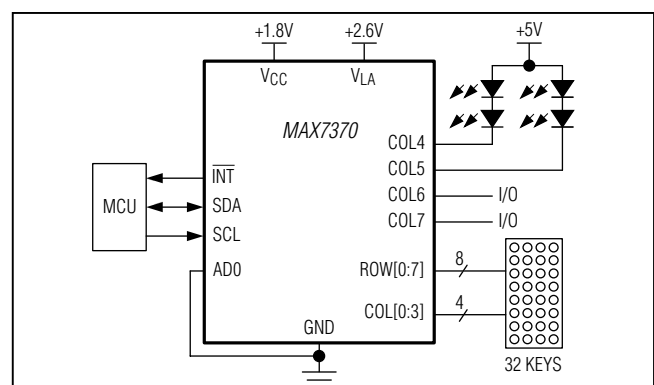
**For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at [www.maximintegrated.com](http://www.maximintegrated.com).**

### Features

- ◆ Monitors Up to 64 Keys
- ◆ Integrated High-ESD Protection
  - ±8kV IEC 61000-4-2 Contact Discharge
  - ±15kV IEC 61000-4-2 Air-Gap Discharge
- ◆ Keyscan Uses Static Matrix Monitoring for Low-EMI Operation
- ◆ Four LED Driver Pins on COL7–COL4
- ◆ 5V Tolerant, Open-Drain I/O Ports Capable of Constant-Current LED Drive
- ◆ 256-Step PWM Individual LED Intensity-Control Accuracy
- ◆ Individual LED Blink Rates and Common LED Fade In/Out Rates from 256ms to 4096ms
- ◆ FIFO Queues Up to 16 Debounced Key Events
- ◆ User-Configurable Keypress and Release Debounce Time (2ms to 32ms)
- ◆ Key-Switch Interrupt ( $\overline{\text{INT}}$ ) on Each Debounced Event/FIFO Level, or End-of-Definable Time Period
- ◆ 1.62V to 3.6V Operating Supply Voltage
- ◆ Individually Programmable GPIOs to Two Logic Levels
- ◆ 8-Channel Individual Programmable Level Translators
- ◆ Provides Optional GPIOs on all ROW\_ and COL\_ Pins
- ◆ Supports Hot Insertion
- ◆ 400kbps, 5.5V Tolerant I<sup>2</sup>C Serial Interface with Selectable Bus Timeout

*Ordering Information appears at end of data sheet.*

### Typical Operating Circuit



# MAX7370

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### ABSOLUTE MAXIMUM RATINGS

|  |                                   |
|--|-----------------------------------|
| V <sub>CC</sub> , V <sub>LA</sub> to GND                             | -0.3V to +4V                      |
| COL3–COL0, ROW7–ROW0 to GND  | -0.3V to (V <sub>CC</sub> + 0.3V) |
| COL7–COL4 to GND   | -0.3V to +6V                      |
| SDA, SCL, AD0, $\overline{\text{INT}}$ to GND                        | -0.3V to +6V                      |
| V <sub>LA</sub> to V <sub>CC</sub>                                   | -0.3V to +2.3V                    |
| DC Current on COL7–COL4 to GND                                       | 25mA                              |
| DC Current on COL3–COL0, ROW7–ROW0 to GND                            | 7mA                               |
| V <sub>CC</sub> , V <sub>LA</sub> , GND Current                      | 80mA                              |
| DC Current V <sub>CC</sub> , V <sub>LA</sub> to COL3–COL0, ROW7–ROW0 | 5mA                               |

|   |                 |
|---|-----------------|
| Continuous Power Dissipation (T <sub>A</sub> = +70°C) |                 |
| 24-Pin TQFN (derate 15.4mW/°C above +70°C)            | 1229mW          |
| 25-Bump WLP (derate 19.2mW/°C above +70°C)            | 850mW           |
| Operating Temperature Range                           | -40°C to +85°C  |
| Junction Temperature                                  | +150°C          |
| Storage Temperature Range                             | -65°C to +150°C |
| Lead Temperature (TQFN) (soldering, 10s)              | +300°C          |
| Soldering Temperature (reflow)                        | +260°C          |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### PACKAGE THERMAL CHARACTERISTICS (Note 1)

|   |          |        |
|---|----------|--------|
| 24 TQFN   | 25 WLP   |        |
| Junction-to-Ambient Thermal Resistance (θ <sub>JA</sub> ) | 65.1°C/W | 52°C/W |
| Junction-to-Case Thermal Resistance (θ <sub>JC</sub> )    | 5.4°C/W  |        |

**Note 1:** Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to [www.maximintegrated.com/thermal-tutorial](http://www.maximintegrated.com/thermal-tutorial).

### ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = 1.62V to 3.6V, T<sub>A</sub> = -40°C to +85°C, unless otherwise noted. Typical values are at V<sub>CC</sub> = 3.3V, T<sub>A</sub> = +25°C.) (Notes 2, 3)

| PARAMETER                                       | SYMBOL             | CONDITIONS   | MIN             | TYP         | MAX  | UNITS |
|---|--------------------|--|-----------------|-------------|------|-------|
| Operating Supply Voltage                        | V <sub>CC</sub>    |  | 1.62            | 3.3         | 3.6  | V     |
| Second Logic Supply                             | V <sub>LA</sub>    |  | V <sub>CC</sub> | 3.3         | 3.6  | V     |
| Operating Supply Current                        | I <sub>CC</sub>    | All key switches open, oscillator running  |                 | 50          | 65   | μA    |
|   |                    | N keys pressed   |                 | 50 + 28 x N |      |       |
| Sleep-Mode Supply Current                       | I <sub>SL</sub>    | Not using GPO or LED configuration   |                 | 1.8         | 3    | μA    |
| POR Threshold                                   | V <sub>POR</sub>   |  |                 | 1.2         |      | V     |
| <b>KEY-SWITCH SPECIFICATIONS</b>                |                    |  |                 |             |      |       |
| Key-Switch Source Current                       | I <sub>KEY</sub>   |  |                 | 28          | 40   | μA    |
| Key-Switch Source Voltage                       | V <sub>KEY</sub>   |  |                 | 0.45        | 0.5  | V     |
| Key-Switch Resistance                           | R <sub>KEY</sub>   | (Note 4)   |                 |             | 5    | kΩ    |
| Startup Time from Sleep                         | t <sub>START</sub> |  |                 | 2           | 2.7  | ms    |
| <b>GPIO SPECIFICATIONS</b>                      |                    |  |                 |             |      |       |
| External Supply Voltage COL7–COL4 (LED Drivers) | V <sub>LED</sub>   |  |                 |             | 5    | V     |
| LED Port-to-Port Sink Current Variation         |                    | V <sub>CC</sub> = 3.3V, V <sub>OL</sub> = 1V, T <sub>A</sub> = +25°C, 10mA output mode |                 | ±1.5        | ±2.4 | %     |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### ELECTRICAL CHARACTERISTICS (continued)

(V<sub>CC</sub> = 1.62V to 3.6V, T<sub>A</sub> = -40°C to +85°C, unless otherwise noted. Typical values are at V<sub>CC</sub> = 3.3V, T<sub>A</sub> = +25°C.) (Notes 2, 3)

| PARAMETER  | SYMBOL               | CONDITIONS  | MIN   | TYP                     | MAX                   | UNITS |    |
|--|----------------------|---|---|-------------------------|-----------------------|-------|----|
| 10mA Port Sink Current<br>COL7–COL4                        | I <sub>OL</sub>      | V <sub>OL</sub> = 1V  | T <sub>A</sub> = +25°C                            | 8.6                     |                       | 11.4  | mA |
|  |                      |   | V <sub>CC</sub> = 3.3V                            | 9.04                    | 10                    | 10.96 |    |
|  |                      | V <sub>OL</sub> = 0.5V  | V <sub>CC</sub> = 3.6V,<br>T <sub>A</sub> = +25°C |                         | 9.5                   |       |    |
| 20mA Port Sink Current<br>COL7–COL4                        | I <sub>OL</sub>      | V <sub>OL</sub> = 1V  | T <sub>A</sub> = +25°C                            | 18.13                   |                       | 21.52 | mA |
|  |                      |   | V <sub>CC</sub> = 3.3V                            | 18.47                   | 20                    | 21.34 |    |
|  |                      | V <sub>OL</sub> = 0.5V  | V <sub>CC</sub> = 3.6V,<br>T <sub>A</sub> = +25°C |                         | 19.05                 |       |    |
| Input High Voltage<br>COL_, ROW_                           | V <sub>IH</sub>      | V <sub>S</sub> = V <sub>CC</sub> or V <sub>LA</sub> depending on<br>reference logic level setting | 0.7 x V <sub>S</sub>                              |                         |                       | V     |    |
| Input Low Voltage<br>COL_, ROW_                            | V <sub>IL</sub>      |   |   | 0.3 x V <sub>S</sub>    |                       | V     |    |
| Input Leakage Current<br>COL3–COL0, ROW_                   | I <sub>LEAKAGE</sub> | Input voltage = V <sub>CC</sub> or V <sub>GND</sub>   | -2  |                         | +2                    | μA    |    |
| Input Leakage Current<br>COL7–COL4                         | I <sub>LEAKAGE</sub> | Input voltage = 5V  | -1  |                         | +1                    | μA    |    |
| Input Capacitance<br>COL_, ROW_                            | C <sub>IN</sub>      |   |   | 20                      |                       | pF    |    |
| Maximum Allowable Load Capacitance<br>for Keyscan Function |                      | N keys pressed simultaneously   |   | 500                     |                       | pF    |    |
| Output Low Voltage<br>COL_, ROW_                           | V <sub>OL</sub>      | V <sub>CC</sub> = 1.62V and I <sub>SINK</sub> = 2.5mA   |   | 50                      | 100                   | mV    |    |
|  |                      | V <sub>CC</sub> = 1.62V and I <sub>SINK</sub> = 5mA   |   | 80                      | 250                   |       |    |
| Output High Voltage<br>COL3–COL0, ROW_                     | V <sub>OH</sub>      | V <sub>CC</sub> = 1.62V and I <sub>SOURCE</sub> = 2.5mA   | V <sub>CC</sub> -<br>120                          | V <sub>CC</sub> -<br>40 |                       | mV    |    |
|  |                      | V <sub>CC</sub> = 1.62V and I <sub>SOURCE</sub> = 5mA   | V <sub>CC</sub> -<br>250                          | V <sub>CC</sub> -<br>70 |                       |       |    |
| Output Logic-Low Voltage<br>(INT)                          | V <sub>OL</sub>      | I <sub>SINK</sub> = 6mA   |   |                         | 0.6                   | V     |    |
| PWM Frequency  | f <sub>PWM</sub>     | Derived from oscillator clock   |   | 500                     |                       | Hz    |    |
| <b>SERIAL-INTERFACE SPECIFICATIONS</b>                     |                      |   |   |                         |                       |       |    |
| Input High Voltage<br>SDA, SCL, AD0                        | V <sub>IH</sub>      |   | 0.7 x V <sub>CC</sub>                             |                         |                       | V     |    |
| Input Low Voltage<br>SDA, SCL, AD0                         | V <sub>IL</sub>      |   |   |                         | 0.3 x V <sub>CC</sub> | V     |    |
| Input Leakage Current<br>SDA, SCL, AD0                     | I <sub>LEAKAGE</sub> | Input voltage = 5.5V or V <sub>GND</sub>  | -1  |                         | +1                    | μA    |    |
| Output Logic-Low Voltage<br>SDA                            | V <sub>OL</sub>      | I <sub>SINK</sub> = 6mA   |   |                         | 0.6                   | V     |    |
| Input Capacitance<br>SDA, SCL, AD0                         | C <sub>IN</sub>      | (Notes 4, 5)  |   |                         | 10                    | pF    |    |

# MAX7370

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### ELECTRICAL CHARACTERISTICS (continued)

(V<sub>CC</sub> = 1.62V to 3.6V, T<sub>A</sub> = -40°C to +85°C, unless otherwise noted. Typical values are at V<sub>CC</sub> = 3.3V, T<sub>A</sub> = +25°C.) (Notes 2, 3)

| PARAMETER  | SYMBOL               | CONDITIONS                      | MIN  | TYP                       | MAX | UNITS |
|--|----------------------|---------------------------------|------|---------------------------|-----|-------|
| <b>I<sup>2</sup>C TIMING SPECIFICATIONS</b>      |                      |                                 |      |                           |     |       |
| SCL Serial-Clock Frequency                       | f <sub>SCL</sub>     | Bus timeout enabled             | 0.05 |                           | 400 | kHz   |
|  |                      | Bus timeout disabled            | 0    |                           | 400 |       |
| Bus Free Time Between a STOP and START Condition | t <sub>BUF</sub>     |                                 | 1.3  |                           |     | μs    |
| Hold Time (Repeated) START Condition             | t <sub>HD, STA</sub> |                                 | 0.6  |                           |     | μs    |
| Repeated START Condition Setup Time              | t <sub>SU, STA</sub> |                                 | 0.6  |                           |     | μs    |
| STOP Condition Setup Time                        | t <sub>SU, STO</sub> |                                 | 0.6  |                           |     | μs    |
| Data Hold Time                                   | t <sub>HD, DAT</sub> | (Note 6)                        |      |                           | 0.9 | μs    |
| Data Setup Time                                  | t <sub>SU, DAT</sub> |                                 | 100  |                           |     | ns    |
| SCL Clock Low Period                             | t <sub>LOW</sub>     |                                 | 1.3  |                           |     | μs    |
| SCL Clock High Period                            | t <sub>HIGH</sub>    |                                 | 0.7  |                           |     | μs    |
| Rise Time of Both SDA and SCL Signals, Receiving | t <sub>R</sub>       | (Notes 4, 5)                    |      | 20 +<br>0.1C <sub>B</sub> | 300 | ns    |
| Fall Time of Both SDA and SCL Signals, Receiving | t <sub>F</sub>       | (Notes 4, 5)                    |      | 20 +<br>0.1C <sub>B</sub> | 300 | ns    |
| Fall Time of SDA Signal, Transmitting            | t <sub>F, TX</sub>   | (Notes 4, 7)                    |      | 20 +<br>0.1C <sub>B</sub> | 250 | ns    |
| Pulse Width of Spike Suppressed                  | t <sub>SP</sub>      | (Notes 4, 8)                    |      |                           | 50  | ns    |
| Capacitive Load for Each Bus Line                | C <sub>B</sub>       | (Note 4)                        |      |                           | 400 | pF    |
| Bus Time Out                                     | t <sub>TIMEOUT</sub> |                                 | 14   | 19                        | 27  | ms    |
| <b>ESD PROTECTION</b>                            |                      |                                 |      |                           |     |       |
| ROW7–ROW0, COL7–COL0                             |                      | IEC 61000-4-2 Air-Gap Discharge |      | ±15                       |     | kV    |
|  |                      | IEC 61000-4-2 Contact Discharge |      | ±8                        |     |       |
| All Other Pins                                   |                      | Human Body Model                |      | ±2.5                      |     | kV    |

**Note 2:** All parameters are tested at T<sub>A</sub> = +25°C. Specifications over temperature are guaranteed by design.

**Note 3:** All digital inputs at V<sub>CC</sub> or GND.

**Note 4:** Guaranteed by design.

**Note 5:** C<sub>B</sub> = total capacitance of one bus line in pF. t<sub>R</sub> and t<sub>F</sub> measured between 0.8V and 2.1V.

**Note 6:** A master device must provide a hold time of at least 300ns for the SDA signal (referred to V<sub>IL</sub> of the SCL signal) to bridge the undefined region of SCL's falling edge.

**Note 7:** I<sub>SINK</sub> = 6mA. C<sub>B</sub> = total capacitance of one bus line in pF. t<sub>R</sub> and t<sub>F</sub> measured between 0.8V and 2.1V.

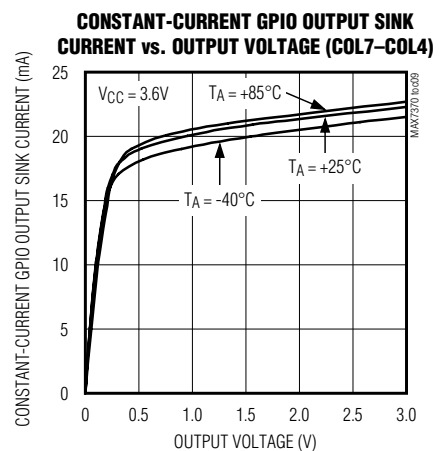
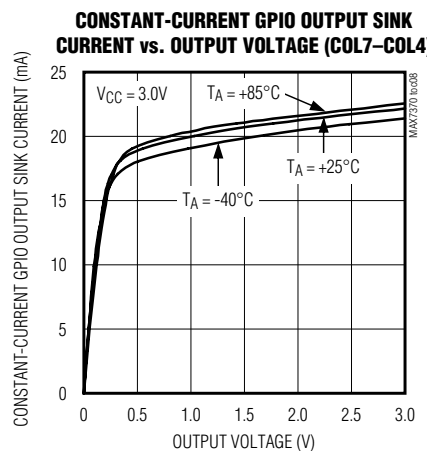
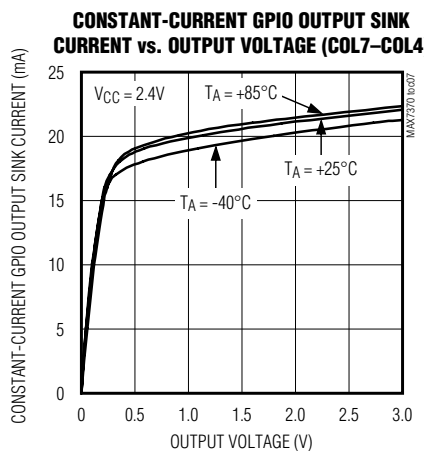
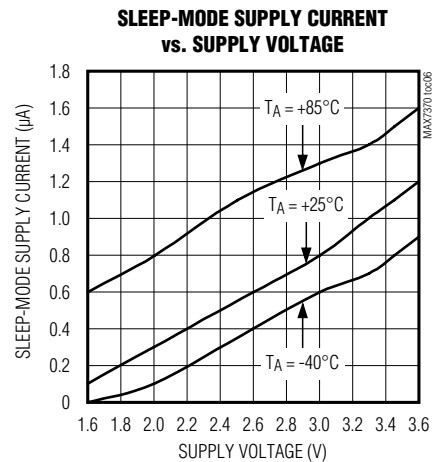
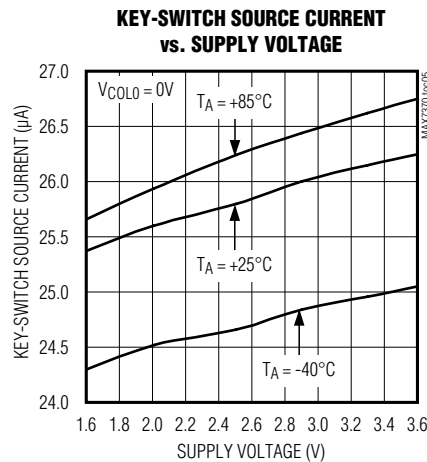
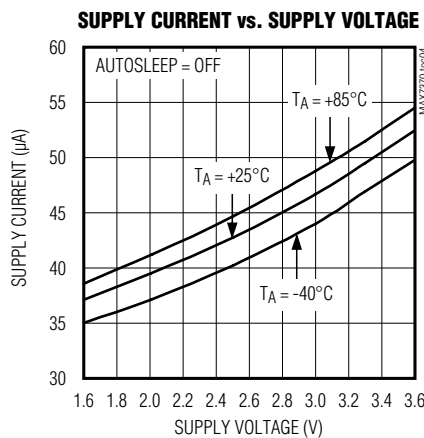
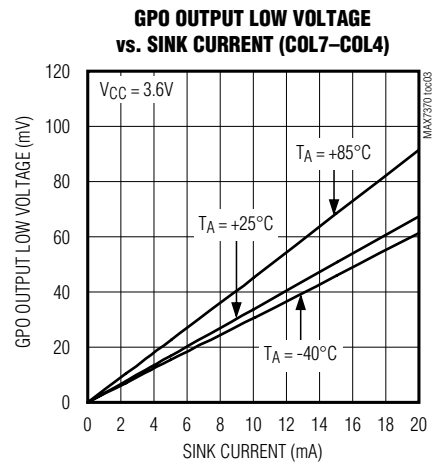
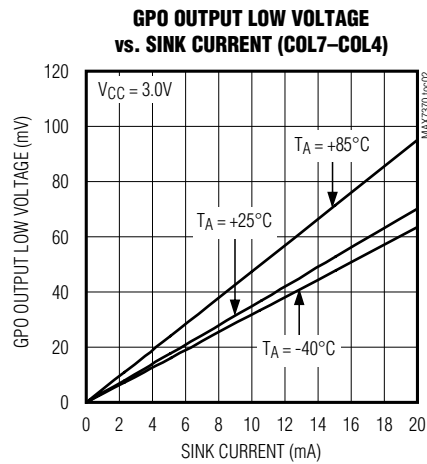
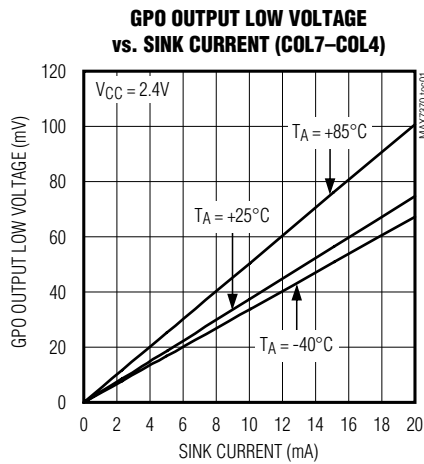
**Note 8:** Input filters on the SDA, SCL, and ADO inputs suppress noise spikes less than 50ns.

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Typical Operating Characteristics

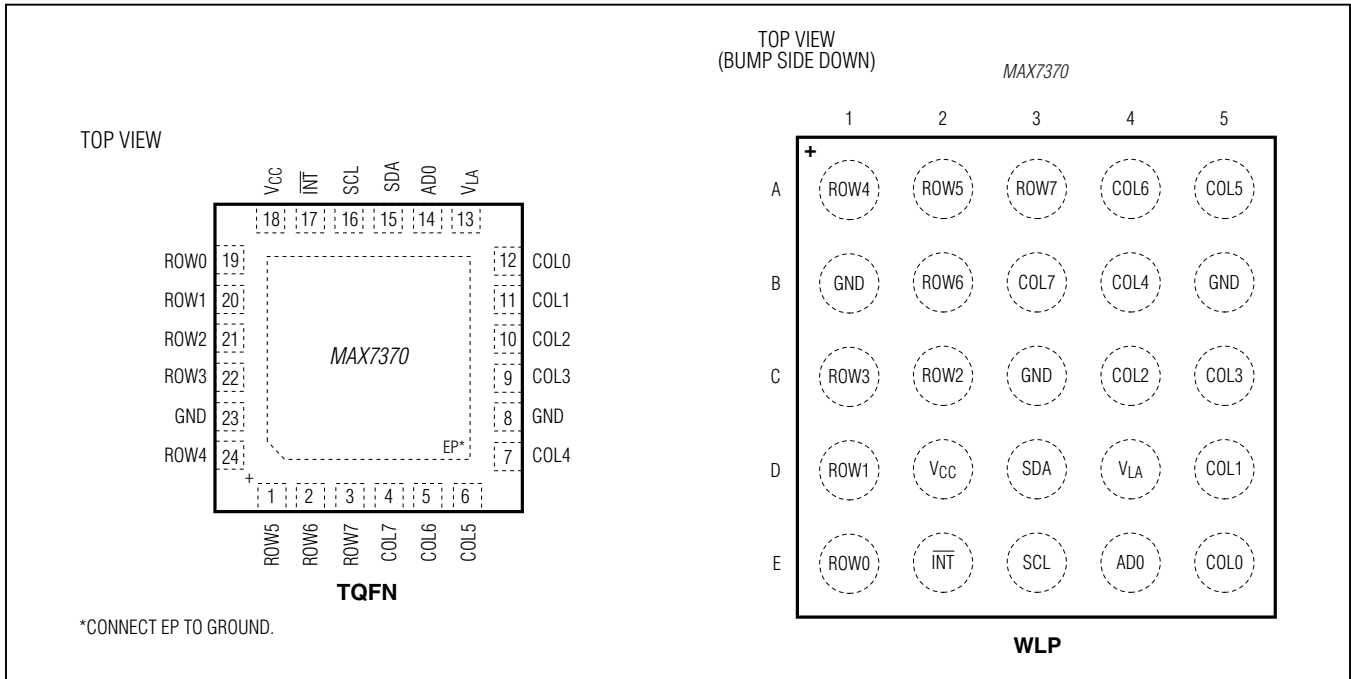
(V<sub>CC</sub> = 2.5V, V<sub>LA</sub> = 2.5V, T<sub>A</sub> = +25°C, unless otherwise noted.)



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Pin/Bump Configurations



### Pin/Bump Description

| PIN   | BUMP       | NAME | FUNCTION  |
|-------|------------|------|---|
| TQFN  | WLP        |      |   |
| 1     | A2         | ROW5 | Row 5 Input from Key Matrix or GPIO Port  |
| 2     | B2         | ROW6 | Row 6 Input from Key Matrix or GPIO Port  |
| 3     | A3         | ROW7 | Row 7 Input from Key Matrix or GPIO Port  |
| 4     | B3         | COL7 | Column 7 Output from Key Matrix or Open-Drain GPIO Port. COL7 can be configured as a constant-current sink. |
| 5     | A4         | COL6 | Column 6 Output from Key Matrix or Open-Drain GPIO Port. COL6 can be configured as a constant-current sink. |
| 6     | A5         | COL5 | Column 5 Output from Key Matrix or Open-Drain GPIO Port. COL5 can be configured as a constant-current sink. |
| 7     | B4         | COL4 | Column 4 Output from Key Matrix or Open-Drain GPIO Port. COL4 can be configured as a constant-current sink. |
| 8, 23 | B1, B5, C3 | GND  | Ground  |
| 9     | C5         | COL3 | Column 3 Output from Key Matrix or GPIO Port  |
| 10    | C4         | COL2 | Column 2 Output from Key Matrix or GPIO Port  |
| 11    | D5         | COL1 | Column 1 Output from Key Matrix or GPIO Port  |
| 12    | E5         | COL0 | Column 0 Output from Key Matrix or GPIO Port  |

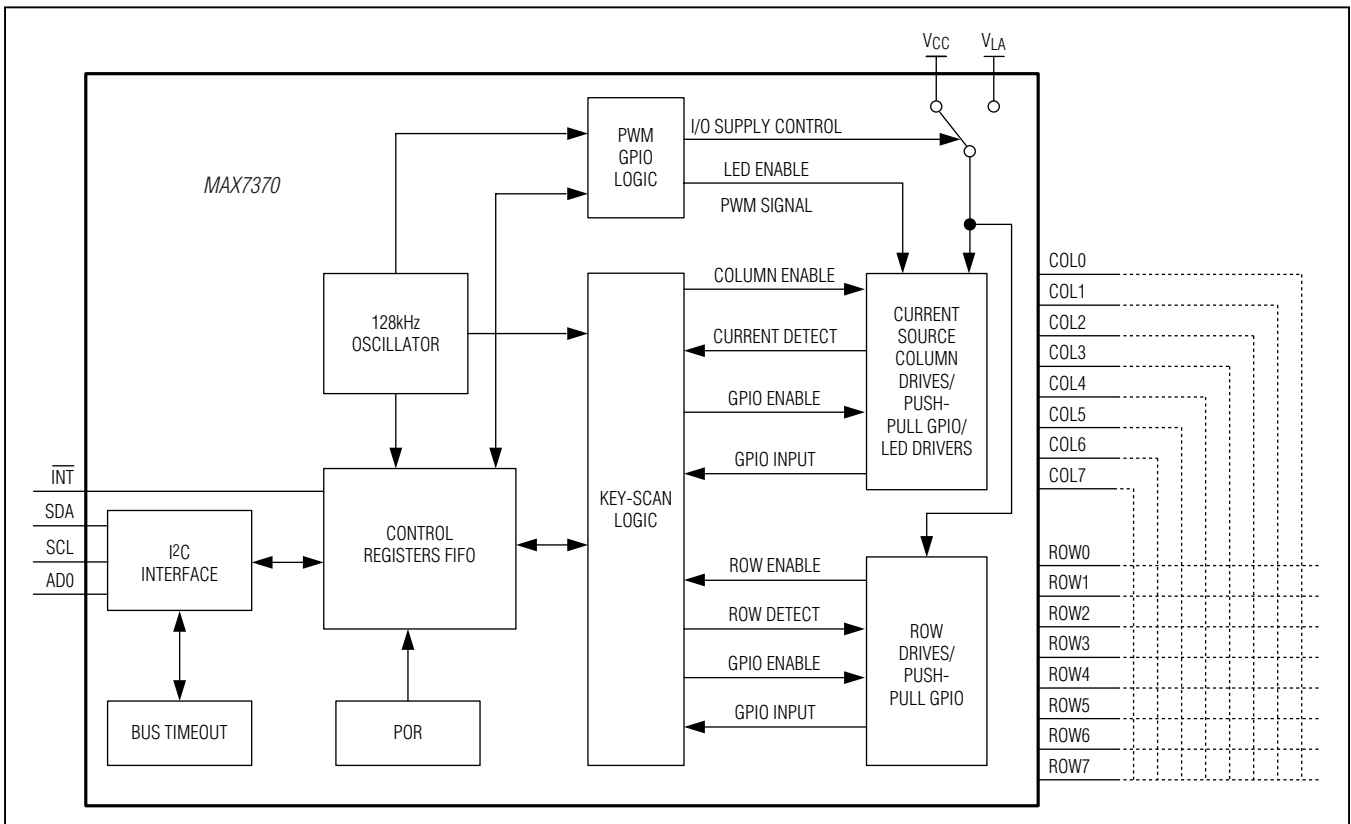
# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Pin Description (continued)

| PIN  |     | NAME                    | FUNCTION   |
|------|-----|-------------------------|--|
| TQFN | WLP |                         |  |
| 13   | D4  | V <sub>LA</sub>         | Second Logic Level for GPIO Level Shifting (where V <sub>CC</sub> ≤ V <sub>LA</sub> ≤ 3.6V)  |
| 14   | E4  | AD0                     | Address Input. Selects up to four device slave addresses (Table 3).  |
| 15   | D3  | SDA                     | I <sup>2</sup> C-Compatible, Serial-Data I/O   |
| 16   | E3  | SCL                     | I <sup>2</sup> C-Compatible, Serial-Clock Input  |
| 17   | E2  | $\overline{\text{INT}}$ | Active-Low Key-Switch Interrupt Output. $\overline{\text{INT}}$ is open-drain and requires a pullup resistor.  |
| 18   | D2  | V <sub>CC</sub>         | Positive Supply Voltage. Bypass to GND with a 0.1μF capacitor as close as possible to the device.  |
| 19   | E1  | ROW0                    | Row 0 Input from Key Matrix or GPIO Port   |
| 20   | D1  | ROW1                    | Row 1 Input from Key Matrix or GPIO Port   |
| 21   | C2  | ROW2                    | Row 2 Input from Key Matrix or GPIO Port   |
| 22   | C1  | ROW3                    | Row 3 Input from Key Matrix or GPIO Port   |
| 24   | A1  | ROW4                    | Row 4 Input from Key Matrix or GPIO Port   |
| —    | —   | EP                      | Exposed Pad (TQFN Only). Internally connected to GND. Connect to a large ground plane to maximize thermal performance. Not intended as an electrical connection point. |

### Functional Block Diagram



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Detailed Description

The MAX7370 is a microprocessor peripheral low-noise key-switch controller that monitors up to 64 key switches with optional autorepeat, and key events that are presented in a 16-byte FIFO. Key-switch functionality can be traded to provide up to 16 logic inputs. The device also features 12 push-pull GPOs configured for digital I/O and four open-drain GPOs configurable as constant-current outputs for LED applications up to 5V. The device supports a second 1.62V to 3.6V power supply for level translation. The second logic supply voltage (V<sub>LA</sub>) must be set equal to or higher than V<sub>CC</sub>.

The device features an automatic sleep mode and automatic wakeup that further reduce supply current consumption. The device can be configured to enter sleep mode after a programmable time following a key event. The FIFO content is maintained and can be read in sleep mode. The device does not enter autosleep when a key is held down. The autowake feature takes the device out of sleep mode following a keypress. Autosleep and

autowake are enabled/disabled by programming the configuration register (0x01).

To prevent overloading the microprocessor with too many interrupts, interrupt requests can be triggered after a programmable number of FIFO entries have been exceeded, and/or after a set period of time (0x05). The key-switch status is checked by reading the key-switch FIFO. A 1-byte read access returns both the next key event in the FIFO (if there is one) and the FIFO status.

Up to four of the key-switch outputs function as open-drain GPOs capable of driving additional LEDs when the application requires fewer keys to be scanned. For each key-switch output used as a GPO, the number of monitored key switches reduces by eight.

The device meets ESD requirements for ±8kV contact discharge and 15kV Air-Gap Discharge on all key-switch pins.

### Initial Power-Up

On power-up, all control registers are set to power-up values (Table 1) and the device is in sleep mode.

**Table 1. Register Address Map and Power-Up Conditions**

| ADDRESS CODE (hex) | READ/WRITE | POWER-UP VALUE (hex) | REGISTER FUNCTION | DESCRIPTION   |
|--------------------|------------|----------------------|-------------------|---|
| 0x00               | Read only  | 0x3F                 | Keys FIFO         | Read FIFO keyscan data out  |
| 0x01               | R/W        | 0x0B                 | Configuration     | Power-down, key-release enable, autowake, and I <sup>2</sup> C timeout enable |
| 0x02               | R/W        | 0xFF                 | Debounce          | Key debounce time setting   |
| 0x03               | R/W        | 0x00                 | Interrupt         | Key-switch interrupt and INT frequency setting                                |
| 0x05               | R/W        | 0x00                 | Key repeat        | Delay and frequency for key repeat  |
| 0x06               | R/W        | 0x07                 | Sleep             | Idle time to autosleep  |
| 0x30               | R/W        | 0xFF                 | Key-switch size   | Keyscan switch array size   |
| 0x31               | R/W        | 0x00                 | LED driver enable | LED driver enable register  |
| 0x32               | R/W        | 0xFF                 | GPI enable        | GPI enable for ROW7–ROW0  |
| 0x33               | R/W        | 0xFF                 | GPI enable        | GPI enable for COL7–COL0  |
| 0x34               | R/W        | 0x00                 | GPIO direction 1  | GPIO input/output control register 1 for ROW7–ROW0                            |
| 0x35               | R/W        | 0x00                 | GPIO direction 2  | GPIO input/output control register 2 for COL7–COL0                            |
| 0x36               | R/W        | 0xFF                 | GPO output mode 1 | GPO open-drain/push-pull output setting for ROW7–ROW0                         |
| 0x37               | R/W        | 0x0F                 | GPO output mode 2 | GPO open-drain/push-pull output setting for COL7–COL0                         |



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 1. Register Address Map and Power-Up Conditions (continued)

| ADDRESS CODE (hex) | READ/WRITE       | POWER-UP VALUE (hex) | REGISTER FUNCTION             | DESCRIPTION  |
|--------------------|------------------|----------------------|-------------------------------|--|
| 0x38               | R $\overline{W}$ | 0x00                 | GPIO supply voltage 1         | GPIO voltages supplied by V <sub>CC</sub> or V <sub>LA</sub> for ROW7–ROW0 |
| 0x39               | R $\overline{W}$ | 0x00                 | GPIO supply voltage 2         | GPIO voltages supplied by V <sub>CC</sub> or V <sub>LA</sub> for COL7–COL0 |
| 0x3A               | R $\overline{W}$ | 0xFF                 | GPIO values 1                 | Debounced input or output values of ROW7–ROW0                              |
| 0x3B               | R $\overline{W}$ | 0xFF                 | GPIO values 2                 | Debounced input or output values of COL7–COL0                              |
| 0x3C               | R $\overline{W}$ | 0x00                 | GPIO level-shifter enable     | GPIO direct level-shifter pair enable                                      |
| 0x40               | R $\overline{W}$ | 0x00                 | GPIO global configuration     | GPIO global enable, GPIO reset, LED fade enable                            |
| 0x42               | R $\overline{W}$ | 0x00                 | GPIO debounce                 | ROW7–ROW0 debounce time setting  |
| 0x43               | R $\overline{W}$ | 0xC0                 | LED constant-current setting  | COL7–COL4 constant-current output setting                                  |
| 0x45               | R $\overline{W}$ | 0x00                 | Common PWM                    | Common PWM duty-cycle setting  |
| 0x48               | Read only        | 0x00                 | I <sup>2</sup> C timeout flag | I <sup>2</sup> C timeout since last POR                                    |
| 0x50               | R $\overline{W}$ | 0x00                 | COL4 PWM ratio                | COL4 individual duty-cycle setting   |
| 0x51               | R $\overline{W}$ | 0x00                 | COL5 PWM ratio                | COL5 individual duty-cycle setting   |
| 0x52               | R $\overline{W}$ | 0x00                 | COL6 PWM ratio                | COL6 individual duty-cycle setting   |
| 0x53               | R $\overline{W}$ | 0x00                 | COL7 PWM ratio                | COL7 individual duty-cycle setting   |
| 0x54               | R $\overline{W}$ | 0x00                 | COL4 LED configuration        | COL4 interrupt, PWM mode control, and blink-period settings                |
| 0x55               | R $\overline{W}$ | 0x00                 | COL5 LED configuration        | COL5 interrupt, PWM mode control, and blink-period settings                |
| 0x56               | R $\overline{W}$ | 0x00                 | COL6 LED configuration        | COL6 interrupt, PWM mode control, and blink-period settings                |
| 0x57               | R $\overline{W}$ | 0x00                 | COL7 LED configuration        | COL7 interrupt, PWM mode control, and blink-period settings                |
| 0x58               | R $\overline{W}$ | 0xFF                 | Interrupt mask 1              | Interrupt mask for ROW7–ROW0   |
| 0x59               | R $\overline{W}$ | 0xFF                 | Interrupt mask 2              | Interrupt mask for COL7–COL0   |
| 0x5A               | R $\overline{W}$ | 0x00                 | GPI trigger mode 1            | GPI edge-triggered detection setting for ROW7–ROW0                         |
| 0x5B               | R $\overline{W}$ | 0x00                 | GPI trigger mode 2            | GPI edge-triggered detection setting for COL7–COL0                         |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Keyscan Controller

Key inputs are scanned statically, not dynamically, to ensure low-EMI operation. Since inputs only toggle in response to switch changes, the key matrix can be routed closer to sensitive circuit nodes.

The keyscan controller debounces and maintains a FIFO buffer of keypress and release events (including auto-repeated keypresses, if autorepeat is enabled). [Table 2](#) shows the key-switch order. The user-programmable key-switch debounce time and autosleep timer are derived from the 64kHz clock, which in turn is derived from the 128kHz oscillator. Time delay for autorepeat and key-switch interrupt is based on the key-switch debounce time. There is no limitation for the number of keys pressed simultaneously as long as no ghost keys are generated. If the application requires fewer keys to be scanned, the unused key-switch ports can be configured as GPIOs.

### Keys FIFO Register (0x00)

The Keys FIFO register contains the information pertaining to the status of the keys FIFO, as well as the key events that have been debounced. See [Table 7](#). Bits D[5:0] denote which of the 64 keys have been debounced and the keys are numbered as shown in [Table 2](#).

Bit D7 indicates if there is more data in the FIFO, except when D[5:0] indicate key 63 or key 62. When D[5:0] indicate key 63 or key 62, the host should read the FIFO one more time to determine whether there is more data in the FIFO. Use key 62 and key 63 for rarely used keys. D6 indicates if it is a keypress or release event, except when D[5:0] indicate key 63 or key 62.

Reading the keyscan FIFO clears the interrupt ( $\overline{\text{INT}}$ ), depending on the setting of bit D5 in the configuration register (0x01).

### Configuration Register (0x01)

The Configuration register controls the I<sup>2</sup>C bus time-out feature, enables key-release detection, enables autowake, and determines how  $\overline{\text{INT}}$  is deasserted. Write to bit D7 to put the device into sleep mode or operating mode. Autosleep and autowake, when enabled, also change the status of D7. See [Table 8](#).

### Debounce Register (0x02)

The Debounce register sets the keypress and key-release time for each debounce cycle. Bits D[3:0] set the debounce time for keypresses, while bits D[7:4] set the debounce time for key releases. Both debounce times are configured in increments of 2ms starting at 2ms and ending at 32ms. See [Table 9](#).

### Interrupt Register (0x03)

The Interrupt register contains information related to the settings of the interrupt request function, as well as the status of the  $\overline{\text{INT}}$  output. If bits D[7:0] are set to 0x00, the  $\overline{\text{INT}}$  is disabled. There are two types of interrupts, the FIFO-based interrupt and time-based interrupt. Set bits D[4:0] to assert interrupts at the end of the selected number of debounce cycles following a key event. See [Table 10](#). This number ranges from 1–31 debounce cycles. Setting bits D[5:7] set the FIFO-based interrupt when there are 2–14 key events stored in the FIFO. Both interrupts can be configured simultaneously and  $\overline{\text{INT}}$  asserts depending on which condition is met first.  $\overline{\text{INT}}$  deasserts depending on the status of bit D5 in the configuration register.

### Autorepeat Register (0x05)

The device autorepeat feature notifies the host that at least one key has been pressed for a continuous period. The Autorepeat register enables or disables this feature, sets the time delay after the last key event before the key-repeat code (0x7E) is entered into the FIFO, and sets

**Table 2. Key-Switch Mapping**

| PIN  | COL0  | COL1   | COL2   | COL3   | COL4   | COL5   | COL6   | COL7   |
|------|-------|--------|--------|--------|--------|--------|--------|--------|
| ROW0 | KEY 0 | KEY 8  | KEY 16 | KEY 24 | KEY 32 | KEY 40 | KEY 48 | KEY 56 |
| ROW1 | KEY 1 | KEY 9  | KEY 17 | KEY 25 | KEY 33 | KEY 41 | KEY 49 | KEY 57 |
| ROW2 | KEY 2 | KEY 10 | KEY 18 | KEY 26 | KEY 34 | KEY 42 | KEY 50 | KEY 58 |
| ROW3 | KEY 3 | KEY 11 | KEY 19 | KEY 27 | KEY 35 | KEY 43 | KEY 51 | KEY 59 |
| ROW4 | KEY 4 | KEY 12 | KEY 20 | KEY 28 | KEY 36 | KEY 44 | KEY 52 | KEY 60 |
| ROW5 | KEY 5 | KEY 13 | KEY 21 | KEY 29 | KEY 37 | KEY 45 | KEY 53 | KEY 61 |
| ROW6 | KEY 6 | KEY 14 | KEY 22 | KEY 30 | KEY 38 | KEY 46 | KEY 54 | KEY 62 |
| ROW7 | KEY 7 | KEY 15 | KEY 23 | KEY 31 | KEY 39 | KEY 47 | KEY 55 | KEY 63 |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

the frequency at which the key-repeat code is entered into the FIFO thereafter. The key being pressed is not entered again into the FIFO. Bit D7 specifies whether the autorepeat function is enabled with 0, denoting autorepeat disabled, and 1, denoting autorepeat enabled. Bits D[3:0] specify the autorepeat delay in terms of debounce cycles, ranging from eight debounce cycles to 128 debounce cycles. See [Table 11](#). Bits D[6:4] specify the autorepeat rate or frequency ranging from 4–32 debounce cycles.

Only one autorepeat code is entered into the FIFO, regardless of the number of keys pressed. The autorepeat code continues to be entered in the FIFO at the frequency set by bits D[3:0] until another key event is recorded. Following the key-release event, if any keys are still pressed, the device restarts the autorepeat sequence.

### **Autosleep Register (0x06)**

Autosleep puts the device in sleep mode to draw minimal current. When enabled, the device enters sleep mode if no keys are pressed for the autosleep time. See [Table 12](#).

### **Key-Switch Array Size Register (0x30)**

Bits D[7:4] set the row size of the key-switch array, and bits D[3:0] set the column size of the key-switch array. See [Table 13](#). Set the bits to 0 if no key switches are used. The key-switch array should be connected beginning at ROW0 and COL0. If not used as a key-switch matrix pin, then the pin can function as a GPIO port.

### **Key-Switch Sleep Mode**

In sleep mode, the device draws minimal current. Switch-matrix current sources are turned off and pulled up to VCC. When autosleep is enabled, key-switch inactivity for a period longer than the autosleep time puts the part into sleep mode (FIFO data is maintained). Writing a 1 to D7 or a keypress can take the device out of sleep mode. Bit D7 in the configuration register gives the sleep-mode status and can be read any time.

### **Autowake**

Keypresses initiate autowake and the device goes into operating mode. Keypresses that autowake the device are not lost. When a key is pressed while the device is in sleep mode, all analog circuitry, including switch-matrix

current sources, turn on in 2ms. The initial key needs to be pressed for 2ms plus the debounce time to be stored in the FIFO. Write a 0 to bit D1 in the configuration register (0x01) to disable autowake.

### **FIFO Overflow**

The FIFO overflow status occurs when the FIFO is full (16 bytes) and additional events occur. If key release is disabled, then the FIFO overflow status occurs when the FIFO is full and not upon additional key events. When the FIFO is overflowed, the first byte read from the FIFO buffer is the overflow byte (0x7F). The order of the original 16 bytes of event data is preserved, but further events could be lost. When the FIFO is full, if the 18th key event is a key release, then the FIFO overflow status is removed.

### **GPIOs**

The device has 16 GPIO ports, four of which have LED control functions. The ports can be used as logic inputs or logic outputs. COL7–COL4 are also configurable as constant-current PWM LED drivers. Each port's logic level is referenced to VCC or V<sub>LA</sub>. The GPIO ports' inputs can also be debounced. When in PWM mode, the ports are set up to start their PWM cycle in 45° phase increments. This prevents large current spikes on the LED supply voltage when driving multiple LEDs.

### **LED Driver Enable Register (0x31)**

Bits D[3:0] correspond to COL7–COL4 on the device. Set the corresponding bit to 1 for enabling the LED driver circuitry and 0 for normal GPIO function. See [Table 14](#).

### **GPIO Direction 1 and 2 Registers (0x34, 0x35)**

These registers configure the pins as an input or an output port. GPIO Direction 1 register bits D[7:0] correspond with ROW7–ROW0. See [Table 15](#). GPIO Direction 2 register bits D[7:0] correspond with COL7–COL0. See [Table 16](#). Set the corresponding bit to 0 to configure as input and 1 to configure as output.

When the port is initially programmed as an input, there is a delay of one debounce period prior to detecting a transition on the input port. This is to prevent a false interrupt from occurring when changing a port from an output to an input.

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### **GPO Output Mode 1 and 2 Registers (0x36, 0x37)**

These registers configure the pin as an open-drain or push-pull output. GPO Output Mode 1 register bits D[7:0] correspond with ROW7–ROW0. See [Table 17](#). GPO Output Mode 2 register bits D[7:0] correspond with COL7–COL0. See [Table 18](#). Set the corresponding bit to 0 to configure the output mode as open-drain and 1 to configure the output mode as push-pull.

### **GPIO Supply Voltage 1 and 2 Registers (0x38, 0x39)**

These registers configure input and output voltages to be referenced to VCC or V<sub>LA</sub>. GPIO Supply Voltage 1 register bits D[7:0] correspond with ROW7–ROW0. See [Table 19](#). GPIO Supply Voltage 2 register bits D[7:0] correspond with COL7–COL0. See [Table 20](#). Set the bit to 0 for input/output voltages referenced to VCC or set the bit to 1 for the input/output voltage referenced to V<sub>LA</sub>.

### **GPIO Values 1 and 2 Registers (0x3A, 0x3B)**

The GPIO Values 1 and 2 registers contain the debounced input data for all the GPIOs for ROW7–ROW0 and COL7–COL0, respectively. See [Tables 21](#) and [22](#). There is one debounce period delay prior to detecting a transition on the input port. This prevents a false interrupt from occurring when changing a port from an output to an input. The GPIO Values 1 and 2 registers report the state of all input ports regardless of any interrupt mask settings.

When writing to the GPIO Values 1 and 2 registers, the corresponding port voltage is set high when written 1 or cleared when written 0. Reading the port when configured as an output always returns the value 0 for the corresponding port regardless of the output value.

### **GPIO Level-Shifter Enable Register (0x3C)**

Enabling bit D<sub>n</sub> in this register enables the direct level shifter between GPIO pins COL<sub>n</sub> and ROW<sub>n</sub>. See [Table 23](#). As an example, setting D5 to logic-high enables level shifting between COL5 and ROW5. The direction of the level shifter is controlled by the GPIO Direction 2 register (0x35). When setting the corresponding bit in the GPIO Direction 2 register to 0, COL<sub>n</sub> are inputs, and ROW<sub>n</sub> are outputs. When setting the bit to 1, ROW<sub>n</sub> become inputs and COL<sub>n</sub> become outputs.

### **GPIO Global Configuration Register (0x40)**

The GPIO Global Configuration register controls the main settings for the GPIO ports. See [Table 24](#). Bit D5 enables

interrupt generation for I<sup>2</sup>C timeouts. D4 is the main enable/shutdown bit for the GPIOs. Bit D3 functions as a software reset for the GPIO registers (0x31 to 0x5B). Bits D[2:0] set the fade-in/out time for the LED drivers.

### **GPIO Debounce Configuration Register (0x42)**

The GPIO Debounce Configuration Register sets the amount of time a GPIO must be held in order for the device to register a logic transition. See [Table 25](#). The GPIO debounce setting is independent of the key-switch debounce setting. Five bits (D[4:0]) set 32 possible debounce times from 9ms up to 40ms.

### **LED Constant-Current Setting Register (0x43)**

The LED Constant-Current Setting register sets the global constant-current amount. See [Table 26](#). Bit D0 selects the global current values between 10mA and 20mA. This setting only applies to the LED driver-enabled pins, COL7–COL4.

### **Common PWM Ratio Register (0x45)**

The Common PWM Ratio register stores the common constant-current output PWM duty cycle. See [Table 27](#). The values stored in this register translate over to a PWM ratio in the same manner as the individual PWM ratio registers (0x50 to 0x53). Ports can use their own individual PWM value or the common PWM value. Write to this register to change the PWM ratio of several ports at once.

### **I<sup>2</sup>C Timeout Flag Register (0x48) (Read Only)**

The I<sup>2</sup>C Timeout Flag register contains a single bit (D0) that indicates if an I<sup>2</sup>C timeout has occurred. See [Table 28](#). Read this register to clear an I<sup>2</sup>C timeout-initiated interrupt.

### **COL4–COL7 Individual PWM Ratio Registers (0x50 to 0x53)**

Each LED driver port has an individual PWM ratio register, 0x50 to 0x53. See [Table 29](#). Use values 0x00 to 0xFE in these registers to configure the number of cycles out of 256 the output sinks current (LED is on), from 0 cycles to 254 cycles. Use 0xFF to have an output continuously sink current (always on). For applications requiring multiple ports to have the same intensity, program a particular port's configuration register (0x54 to 0x57) to use the Common PWM Ratio register (0x45). New PWM settings take place at the beginning of a PWM cycle, to allow changes from common intensity to individual intensity with no interruption in the PWM cycle.

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### **COL4–COL7 LED Configuration Registers (0x54 to 0x57)**

Registers 0x54 to 0x57 set individual configurations for each port. See [Table 30](#). D5 sets the port's PWM setting to either the common or individual PWM setting. Bits D[4:2] enable and set the port's individual blink period from 0 to 4096ms. Bits D[1:0] set a port's blink duty cycle.

### **Interrupt Mask 1 and 2 Registers (0x58, 0x59)**

The Interrupt Mask 1 and 2 registers control which ports trigger an interrupt for ROW7–ROW0 and COL7–COL0, respectively. See [Tables 31](#) and [32](#). Set the bit to 0 to enable the interrupt. Set the bit to 1 to mask the interrupt.

If the port that has generated the interrupt is not masked, the interrupt causes the  $\overline{\text{INT}}$  signal to assert. A read of the GPIO Values 1 and 2 registers (0x3A, 0x3B) is required to deassert the  $\overline{\text{INT}}$  pin. Note that transitions that occur while the  $\overline{\text{INT}}$  signal is asserted, but before the read of the GPIO Values 1 and 2 registers, set the appropriate bit of the GPIO Values 1 and 2 registers only, but has no effect on the  $\overline{\text{INT}}$  pin as it is already asserted. However, transitions that occur when the I<sup>2</sup>C is active cannot be latched into the GPIO Values 1 and 2 registers until after the read has taken place. If there are transitions that cause the  $\overline{\text{INT}}$  signal to assert, during the time of an I<sup>2</sup>C read, they cause the  $\overline{\text{INT}}$  signal to reassert once the read transaction has taken place. Note that the interrupt configurations only apply when a port is configured as an input.

### **GPI Trigger Mode 1 and 2 Registers (0x5A, 0x5B)**

The GPI Trigger Mode 1 and 2 registers control how ports can trigger an interrupt for ROW7–ROW0 and COL7–COL0, respectively. See [Tables 33](#) and [34](#). Set the bit to 0 for rising-edge triggering. Set the bit to 1 for rising- and falling-edge triggering.

The inputs are debounced (if enabled) by taking a snapshot of the port state when the transition occurs, and another after the debounce time has elapsed—ensuring that the state of the port is stable prior to triggering the interrupt. After the debounce cycle, an interrupt is generated and the  $\overline{\text{INT}}$  pin asserted if it is not masked for that particular port. Regardless of whether or not the  $\overline{\text{INT}}$  signal is masked, the GPIO Values 1 and 2 registers (0x3A, 0x3B) report the state of all input ports.

### **Sleep Mode**

The device is put into sleep mode by clearing bit D7 in the Configuration register, or after power-on reset (POR). In sleep mode, the keyscan controller is disabled and the device draws minimal current. No additional supply current is drawn if no keys are pressed. All switch-matrix current sources are turned off, and row outputs ROW7–ROW0 are low and column outputs COL7–COL0 become high.

The device is taken out of sleep mode and put into operating mode by setting bit D7 in the configuration register. The keyscan controller FIFO buffers are cleared and key monitoring starts. Note that rewriting the configuration register with bit D7 high, when bit D7 was already high, does not clear the FIFOs. The FIFOs are only cleared when the device is changing state from sleep mode to operating mode.

In sleep mode, the internal oscillator is disabled and I<sup>2</sup>C timeout features are disabled. The GPO or LED ports consume current even in sleep mode. The part does not enter sleep mode if any of the GPIOs or LED drivers are enabled.

### **LED Fade**

Set the fade cycle time in the GPIO Global Configuration register (0x40) to a non-zero value to enable fade in/out. See [Table 24](#). Fade in increases an LED's PWM intensity in 16 even steps, from zero to its stored value. Fade out decreases an LED's PWM intensity in 16 even steps from its current value to zero. Fading occurs automatically in any of the following scenarios:

- Change the common PWM register value from any value to zero to cause all ports using the common PWM register settings to fade out. No ports using individual PWM settings are affected.
- Change the common PWM register value to any value from zero to cause all ports using the common PWM register settings to fade in. No ports using individual PWM settings are affected.
- Take the part out of sleep mode to cause all ports to fade in. Changing an individual PWM intensity during fade in automatically cancels that port's fade and immediately outputs at its newly programmed intensity.

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

- Put the part into sleep mode to cause all ports to fade out. Changing an individual PWM intensity during fade out automatically cancels that port's fade and immediately turns off.

### LED PWM

Each port has an individual PWM ratio register. The value stored in this register configures the number of cycles out of 255 that the output is sinking current (LED is on). Setting a value of 0xFF in an individual intensity register sets the output to continuously sink current (always on). Conversely, setting a value of 0x00 in an individual intensity register sets the output in a high-impedance state (always off).

For applications requiring multiple ports to have the same intensity, the common PWM ratio intensity setting can be used in lieu of the individual intensity setting. To use the common intensity setting, program bit D5 of the corresponding port's configuration register to logic-high. Setting a port to use the common PWM ratio setting copies the value of the common intensity register into the individual intensity register at the beginning of each PWM cycle. This allows an output port to be seamlessly changed from common intensity to individual intensity with no interruption in the PWM cycle.

Outputs are configured to sink a constant current of either 10mA or 20mA during the period of time when the output is on. The setting in the individual GPIO constant-current setting register (0x43) controls the value of the current.

### LED Blink

Each LED driver-supported port has its own blink-control settings through registers 0x54 to 0x57. See [Table 30](#). The blink period ranges from 0 (blink disabled) to 4.096s. Settable blink duty cycles range from 6.25% to 50%. All blink periods start at the same PWM cycle for synchronized blinking between multiple ports.

Each port has its own counter to generate blink timing. The blink counter can be programmed to cause the output to gate off and on at a programmable rate. The blink period can be set to 256ms, 512ms, 1.024s, 2.048s, or 4.096s using D[4:2] of the port's individual configuration register. The percentage of time that the LED is on for one blink cycle is set to 50%, 25%, 12.5%, or 6.25% by D[1:0] of the individual configuration register.

### Interrupts

Three possible sources generate  $\overline{\text{INT}}$ : key-switch FIFO level/debounce cycle settings, I<sup>2</sup>C timeout, or GPIOs configured as inputs (registers 0x03, 0x48, 0x5A, and 0x5B). Read the respective data/status registers for each type of interrupt to clear  $\overline{\text{INT}}$ . If multiple sources generate the interrupt, all the related status registers must be read to clear  $\overline{\text{INT}}$ .

### Serial Interface

[Figure 1](#) shows the two-wire serial interface timing details.

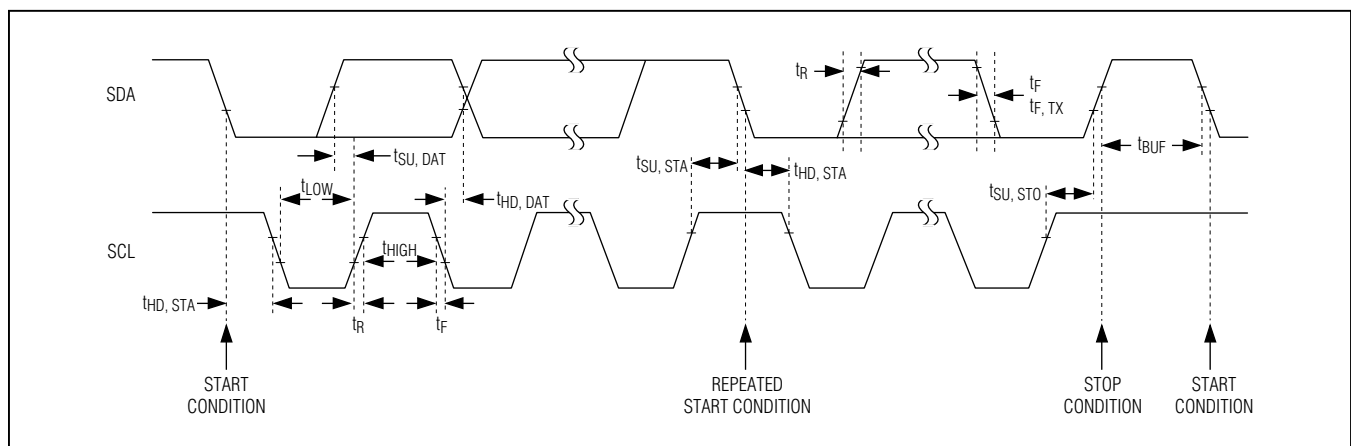


Figure 1. Two-Wire Serial Interface Timing Details

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Serial Addressing

The device operates as a slave that sends and receives data through an I<sup>2</sup>C-compatible two-wire interface. The interface uses a serial-data line (SDA) and a serial-clock line (SCL) to achieve bidirectional communication between master(s) and slave(s). A master (typically a microcontroller) initiates all data transfers to and from the device and generates the SCL clock that synchronizes the data transfer.

The device's SDA line operates as both an input and an open-drain output. A pullup resistor, typically 4.7k $\Omega$ , is required on SDA. The device's SCL line operates only as an input. A pullup resistor is required on SCL if there are multiple masters on the two-wire interface, or if the master in a single-master system has an open-drain SCL output.

Each transmission consists of a START (S) condition (Figure 2) sent by a master, followed by the device's 7-bit slave address plus R/W bit, a register address byte, one or more data bytes, and finally, a STOP (P) condition.

### START and STOP Conditions

Both SCL and SDA remain high when the interface is not busy. A master signals the beginning of a transmission

with a START condition by transitioning SDA from high to low while SCL is high. When the master has finished communicating with the slave, it issues a STOP condition by transitioning SDA from low to high while SCL is high. The bus is then free for another transmission.

### Bit Transfer

One data bit is transferred during each clock pulse (Figure 3). The data on SDA must remain stable while SCL is high.

### Acknowledge

The acknowledge bit is a clocked 9th bit (Figure 4), which the recipient uses to handshake receipt of each byte of data. Thus, each byte transferred effectively requires 9 bits. The master generates the 9th clock pulse, and the recipient pulls down SDA during the acknowledge clock pulse; therefore, the SDA line is stable low during the high period of the clock pulse. When the master is transmitting to the device, the device generates the acknowledge bit because the device is the recipient. When the device is transmitting to the master, the master generates the acknowledge bit because the master is the recipient.

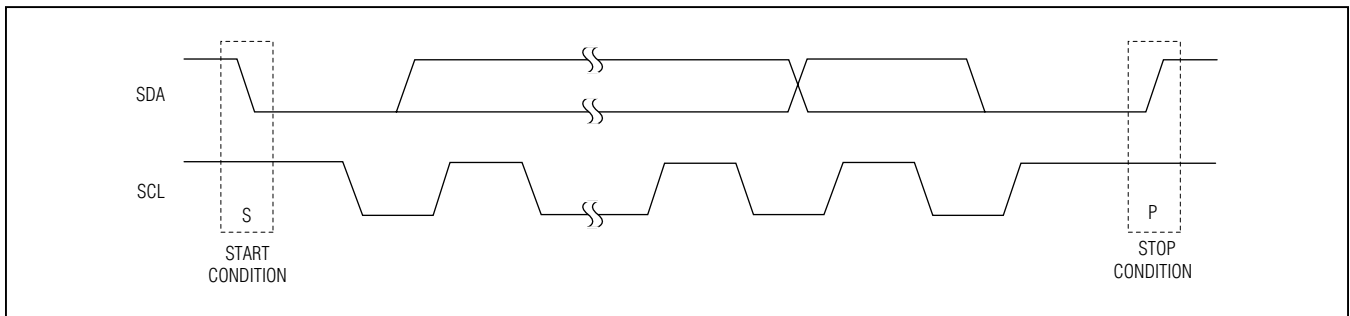


Figure 2. START and STOP Conditions

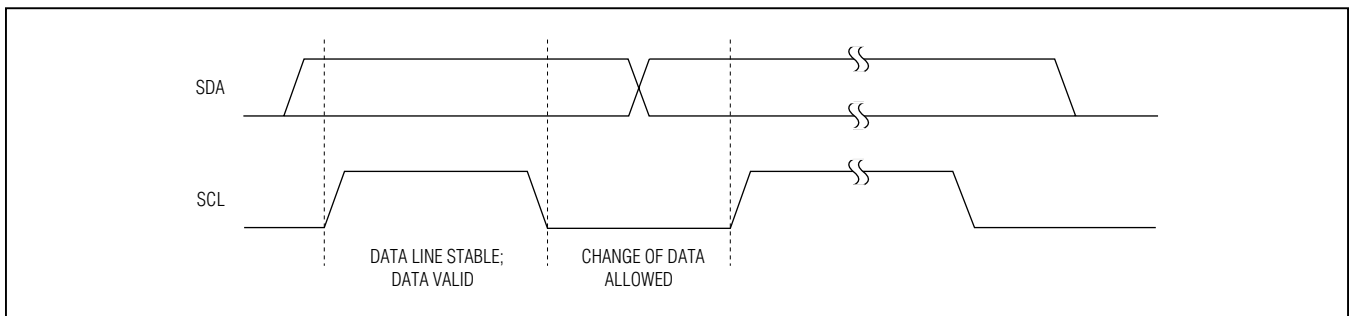


Figure 3. Bit Transfer

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

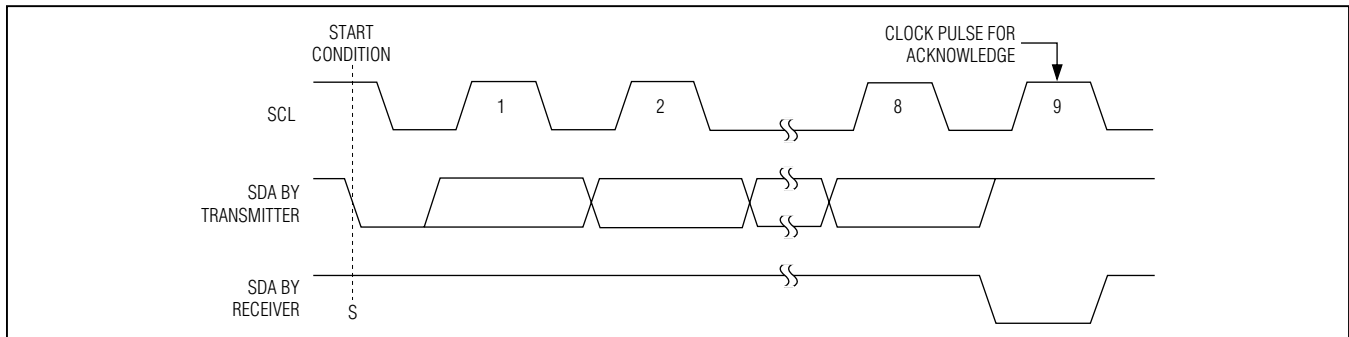


Figure 4. Acknowledge

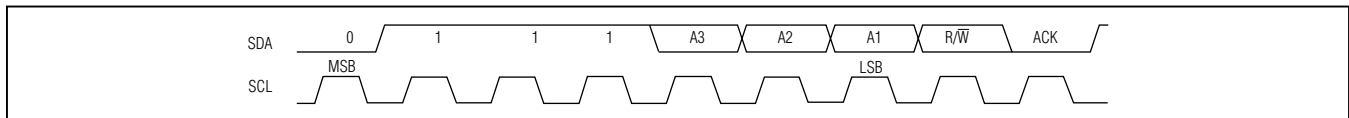


Figure 5. Slave Address

**Table 3. Two-Wire Interface Address Map**

| AD0 PIN         | DEVICE ADDRESS |    |    |    |    |    |    |     |
|-----------------|----------------|----|----|----|----|----|----|-----|
|                 | A7             | A6 | A5 | A4 | A3 | A2 | A1 | A0  |
| GND             | 0              | 1  | 1  | 1  | 0  | 0  | 0  | R/W |
| V <sub>CC</sub> |                |    |    |    | 0  | 1  |    |     |
| SDA             |                |    |    |    | 1  | 0  |    |     |
| SCL             |                |    |    |    | 1  | 1  |    |     |

### Slave Addresses

The device has two 7-bit long slave addresses. The bit following a 7-bit slave address is the R/W bit, which is low for a write command and high for a read command.

The first 4 bits (MSBs) of the device slave addresses are always 0111. Slave address bits A[3:1] correspond, by the matrix in [Table 3](#), to the states of the device address input pin AD0, and A0 corresponds to the R/W bit ([Figure 5](#)). The AD0 input can be connected to any of four signals: GND, V<sub>CC</sub>, SDA, or SCL, giving four possible slave-address pairs, allowing up to four devices to share the same bus. Because SDA and SCL are dynamic signals, care must be taken to ensure that AD0 transitions no sooner than the signals on SDA and SCL.

The device monitors the bus continuously, waiting for a START condition, followed by its slave address. When the device recognizes its slave address, it acknowledges and is then ready for continued communication.

### Bus Timeout

The device features a 20ms (min) bus timeout on the two-wire serial interface, largely to prevent the device from holding the SDA I/O low during a read transaction should the SCL lock up for any reason before a serial transaction is completed. Bus timeout operates by causing the device to internally terminate a serial transaction, either read or write, if the time between adjacent edges on SCL exceeds 20ms. After a bus timeout, the device waits for a valid START condition before responding to a consecutive transmission. This feature can be enabled or disabled under user control by writing to the configuration register.

### Message Format for Writing the Keyscan Controller

A write to the device comprises the transmission of the slave address with the R/W bit set to zero, followed by at least one byte of information. The first byte of information is the command byte. The command byte determines which register of the device is to be written by the next byte, if received. If a STOP condition is detected after the command byte is received, the device takes no further action ([Figure 6](#)) beyond storing the command byte.

Any bytes received after the command byte are data bytes. The first data byte goes into the internal register of the device selected by the command byte ([Figure 7](#)).

If multiple data bytes are transmitted before a STOP condition is detected, these bytes are generally stored in subsequent internal registers of the device, because the command-byte address generally autoincrements ([Table 4](#)).



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

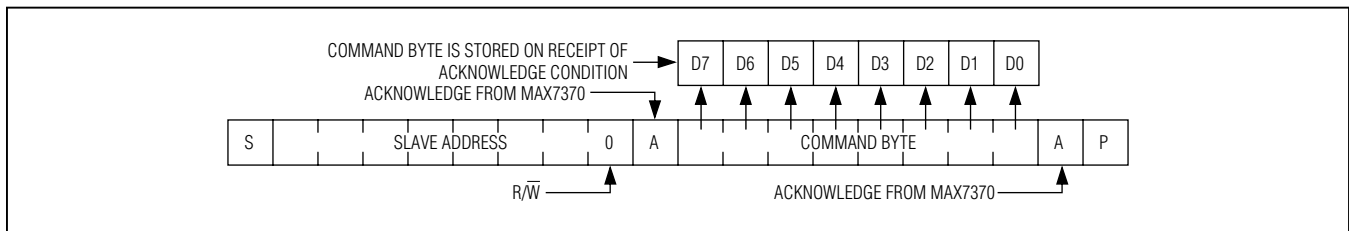


Figure 6. Command Byte Received

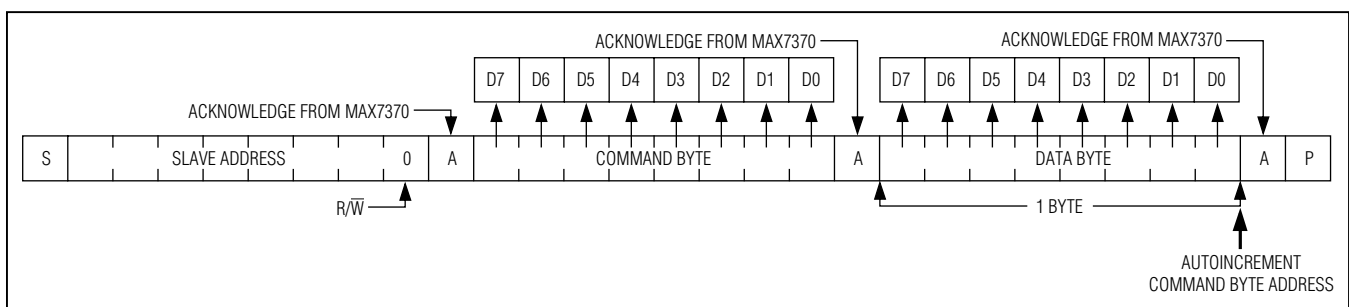


Figure 7. Command and Single Data Byte Received

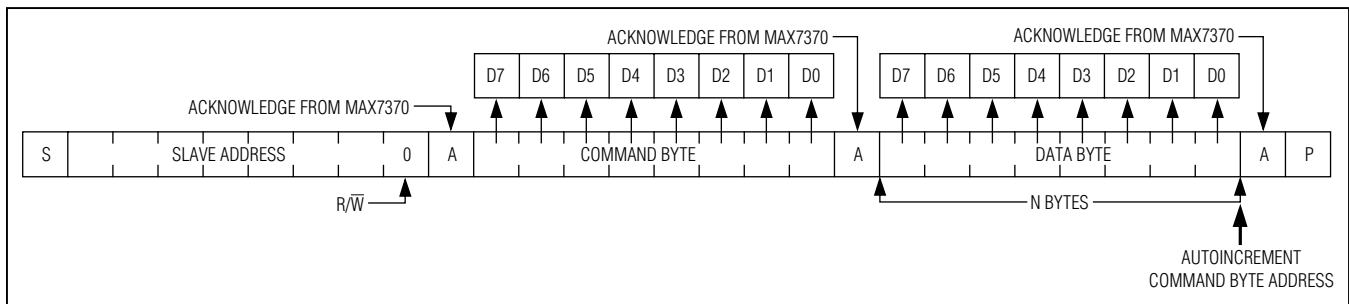


Figure 8. N Data Bytes Received

### Message Format for Reading the Keyscan Controller

The device is read using the internally stored command byte as an address pointer, the same way the stored command byte is used as an address pointer for a write. The pointer generally autoincrements after each data byte is read using the same rules as for a write ([Table 4](#)). Thus, a read is initiated by first configuring the device's command byte by performing a write ([Figure 6](#)). The master can now read N consecutive bytes from the device, with the first data byte being read from the register addressed by the initialized command byte. When performing read-after-write verification, remember to reset the command byte's address because the stored command byte address is generally autoincremented after the write ([Figure 8](#), [Table 4](#)).

Table 4. Autoincrement Rules

| REGISTER FUNCTION      | ADDRESS CODE (hex) | AUTOINCREMENT ADDRESS (hex) |
|------------------------|--------------------|-----------------------------|
| Keys FIFO              | 0x00               | 0x00                        |
| Autosleep              | 0x06               | 0x00                        |
| All other key switches | 0x01 to 0x05       | Addr + 0x01                 |
| All other GPIOs        | 0x30 to 0x5B       | Addr + 0x01                 |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Operation with Multiple Masters

When the device is operated on a two-wire interface with multiple masters, a master reading the device uses a repeated start between the write that sets the device's address pointer, and the read(s) that takes the data from the location(s). This is because it is possible for master 2 to take over the bus after master 1 has set up the device's address pointer but before master 1 has read the data. If master 2 subsequently resets the device's address pointer, master 1's read can be from an unexpected location.

### Command Address Autoincrementing

Address autoincrementing allows the device to be configured with fewer transmissions by minimizing the number of times the command address needs to be sent. The command address stored in the device generally increments after each data byte is written or read (Table 4). Autoincrement only functions when doing a multiburst read or write.

## Applications Information

### Reset from I<sup>2</sup>C

After a catastrophic event such as ESD discharge or microcontroller reset, use bit D7 of the configuration register (0x01) as a software reset for the key switches. Use bit D4 of the GPIO global configuration register (0x40) as a software reset for the GPIOs.

### Ghost-Key Elimination

Ghost keys are a phenomenon inherent with key-switch matrices. When three switches located at the corners of a matrix rectangle are pressed simultaneously, the

switch that is located at the last corner of the rectangle (the ghost key) also appears to be pressed. This occurs because the potentials at the two sides of the ghost-key switch are identical due to the other three connections—the switch is electrically shorted by the combination of the other three switches (Figure 9). Because the key appears to be pressed electrically, it is impossible to detect which of the four keys is the ghost key.

The device employs a proprietary scheme that detects any three-key combination that generates a fourth ghost key, and does not report the third key that causes a ghost-key event. This means that although ghost keys are never reported, many combinations of three keys are effectively ignored when pressed at the same time. Applications requiring three-key combinations (such as <Ctrl><Alt><Del>) must ensure that the three keys are not wired in positions that define the vertices of a rectangle (Figure 10). There is no limit on the number of keys that can be pressed simultaneously as long as the keys do not generate ghost-key events and the FIFO is not full.

### Low-EMI Operation

The device uses two techniques to minimize EMI radiating from the key-switch wiring. First, the voltage across the switch matrix never exceeds 0.5V if not in sleep mode, independent of supply voltage V<sub>CC</sub>. This reduces the voltage swing at any node when a switch is pressed to 0.5V (max). Second, the keys are not dynamically scanned, which would cause the key-switch wiring to continuously radiate interference. Instead, the keys are monitored for current draw (only occurs when pressed), and debounce circuitry only operates when one or more keys are actually pressed.

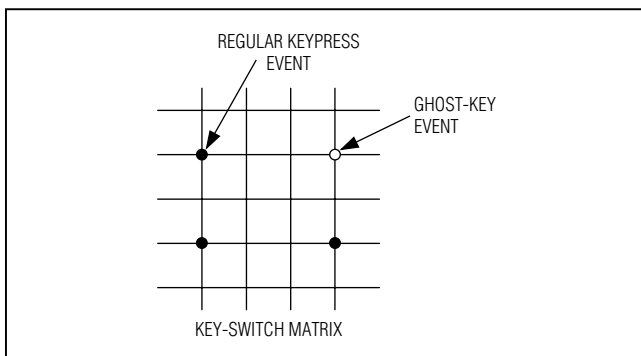


Figure 9. Ghost-Key Phenomenon

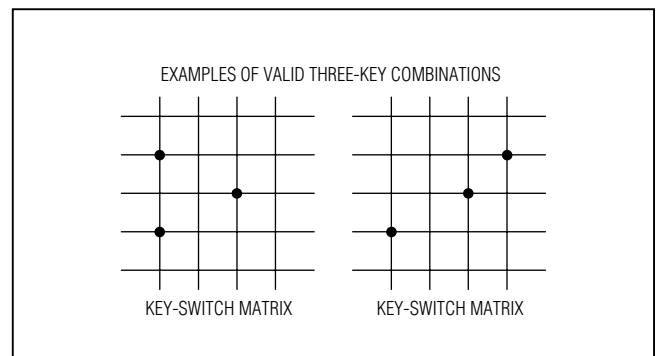


Figure 10. Valid Three-Key Combinations

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Switch On-Resistance

The device is designed to be insensitive to resistance, either in the key switches, or the switch routing to and from the appropriate COL\_ and ROW\_ up to 5kΩ (max). These controllers are therefore compatible with low-cost membrane and conductive carbon switches.

### Hot Insertion

The  $\overline{\text{INT}}$ , SCL, and AD0 inputs and SDA remain high impedance with up to 5.5V asserted on them when the device powers down ( $V_{CC} = 0V$ ). I/O ports remain high impedance with up to 5.5V asserted on them when not powered. Use the device in hot-swap applications.

### Staggered PWM

The LED's on-time in each PWM cycle is phase delayed by 45° into four evenly spaced start positions. Optimize phasing, when using fewer than four ports as constant-current

outputs, by allocating the ports with the most appropriate start positions. For example, if using two constant-current outputs, choose COL4 and COL6 because their PWM start positions are evenly spaced. In general, choose the ports that spread the current demand from the ports' load supply.

### Power-Supply Considerations

The device operates with a 1.62V to 3.6V power-supply voltage. Bypass the power supply ( $V_{CC}$ ) to GND with a 0.1μF or higher ceramic capacitor as close as possible to the device. Bypass the logic power supply ( $V_{LA}$ ) to GND with a 0.1μF or higher ceramic capacitor as close as possible to the device.

### ESD Protection

All the device pins meet the ±2.5kV Human Body Model ESD tolerances. Key-switch inputs and GPIOs meet IEC 61000-4-2 ESD protection. The IEC test stresses consist of 10 consecutive ESD discharges per polarity at the maximum specified level and below (per IEC 61000-4-2). Test criteria include:

- The powered device does not latch up during the ESD discharge event.
- The device subsequently passes the final test used for prescreening.

Tables 5 and 6 are taken from the IEC 61000-4-2: Edition 1.1 1999-05: *Electromagnetic compatibility (EMC) Testing and measurement techniques—Electrostatic discharge immunity test*.

**Table 5. ESD Test Levels**

| 1A—CONTACT DISCHARGE |                   | 1B—AIR DISCHARGE |                   |
|----------------------|-------------------|------------------|-------------------|
| LEVEL                | TEST VOLTAGE (kV) | LEVEL            | TEST VOLTAGE (kV) |
| 1                    | 2                 | 1                | 2                 |
| 2                    | 4                 | 2                | 4                 |
| 3                    | 6                 | 3                | 8                 |
| 4                    | 8                 | 4                | 15                |
| X                    | Special           | X                | Special           |

X = Open level. The level has to be specified in the dedicated equipment specification. If higher voltages than those shown are specified, special test equipment might be needed.

**Table 6. ESD Waveform Parameters**

| LEVEL | INDICATED VOLTAGE (kV) | FIRST PEAK OF CURRENT DISCHARGE ±10% (A) | RISE TIME ( $t_r$ ) WITH DISCHARGE SWITCH (ns) | CURRENT (±30%) AT 30ns (A) | CURRENT (±30%) AT 60ns (A) |
|-------|------------------------|--|--|----------------------------|----------------------------|
| 1     | 2                      | 7.5                                      | 0.7 to 1                                       | 4                          | 2                          |
| 2     | 4                      | 15                                       | 0.7 to 1                                       | 8                          | 4                          |
| 3     | 6                      | 22.5                                     | 0.7 to 1                                       | 12                         | 6                          |
| 4     | 8                      | 30                                       | 0.7 to 1                                       | 16                         | 8                          |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Register Tables

**Table 7. Keys FIFO Register Format (0x00)**

| SPECIAL FUNCTION   | KEYS FIFO REGISTER DATA |                  |                      |    |    |    |    |    |
|--|-------------------------|------------------|----------------------|----|----|----|----|----|
|  | D7                      | D6               | D5                   | D4 | D3 | D2 | D1 | D0 |
| The key number indicated by D[5:0] is a key event. D7 is always for a keypress of key 62 and key 63. When D7 is 0, the key read is the last data in the FIFO. When D7 is 1, there is more data in the FIFO. When D6 is 1, key data read from the FIFO is a key release. When D6 is 0, key data read from the FIFO is a keypress. | FIFO not-empty flag     | Key-release flag | Key number/key event |    |    |    |    |    |
| FIFO is empty.   | 0                       | 0                | 1                    | 1  | 1  | 1  | 1  | 1  |
| FIFO is overflow. Continue to read data in the FIFO.   | 0                       | 1                | 1                    | 1  | 1  | 1  | 1  | 1  |
| Key 63 is pressed. Read one more time to determine whether there is more data in the FIFO.   | 1                       | 0                | 1                    | 1  | 1  | 1  | 1  | 1  |
| Key 63 is released. Read one more time to determine whether there is more data in the FIFO.  | 1                       | 1                | 1                    | 1  | 1  | 1  | 1  | 1  |
| Key repeat. Indicates the last data in the FIFO.   | 0                       | 0                | 1                    | 1  | 1  | 1  | 1  | 0  |
| Key repeat. Indicates more data in the FIFO.   | 0                       | 1                | 1                    | 1  | 1  | 1  | 1  | 0  |
| Key 62 is pressed. Read one more time to determine whether there is more data in the FIFO.   | 1                       | 0                | 1                    | 1  | 1  | 1  | 1  | 0  |
| Key 62 is released. Read one more time to determine whether there is more data in the FIFO.  | 1                       | 1                | 1                    | 1  | 1  | 1  | 1  | 0  |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 8. Configuration Register (0x01)

| REGISTER BIT | DESCRIPTION        | VALUE                      | FUNCTION   | DEFAULT VALUE |
|--------------|--------------------|----------------------------|--|---------------|
| D7           | Sleep              | X<br>(when 0x40<br>D4 = 1) | Key-switch operating mode. Key switches always remain active when constant-current PWM is enabled (bit 4 of register 0x40 is high), regardless of autosleep, autowake, or an I <sup>2</sup> C write to this bit.   | 0             |
|              |                    | 0<br>(when 0x40<br>D4 = 0) | Key-switch sleep mode. The entire chip is shut down.   |               |
|              |                    | 1<br>(when 0x40<br>D4 = 0) | Key-switch operating mode.<br>When constant-current PWM is disabled (bit 4 of register 0x40 is low), I <sup>2</sup> C write, autosleep, and autowake all can change this bit. This bit can be read back by I <sup>2</sup> C any time for current status. |               |
| D6           | Reserved           | 0                          | —  | 0             |
| D5           | Interrupt          | 0                          | $\overline{\text{INT}}$ cleared when the FIFO is empty.  | 0             |
|              |                    | 1                          | $\overline{\text{INT}}$ cleared after host read. In this mode, I <sup>2</sup> C should read the FIFO until interrupt condition is removed or further $\overline{\text{INT}}$ could be lost.  |               |
| D4           | Reserved           | 0                          | —  | 0             |
| D3           | Key-release enable | 0                          | Disable key releases.  | 1             |
|              |                    | 1                          | Enable key releases.   |               |
| D2           | Reserved           | 0                          | —  | 0             |
| D1           | Autowake enable    | 0                          | Disable keypress wakeup.   | 1             |
|              |                    | 1                          | Enable keypress wakeup.  |               |
| D0           | Timeout disable    | 0                          | I <sup>2</sup> C timeout enabled.  | 1             |
|              |                    | 1                          | I <sup>2</sup> C timeout disabled.   |               |

X = Don't care.

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 9. Key-Switch Debounce Register (0x02)**

| REGISTER DESCRIPTION           | REGISTER DATA                |          |          |          |                            |          |          |          |
|--------------------------------|------------------------------|----------|----------|----------|----------------------------|----------|----------|----------|
|                                | D7                           | D6       | D5       | D4       | D3                         | D2       | D1       | D0       |
| <b>DEBOUNCE TIME</b>           | <b>RELEASE DEBOUNCE TIME</b> |          |          |          | <b>PRESS DEBOUNCE TIME</b> |          |          |          |
| 2ms                            | X                            |          |          |          | 0                          | 0        | 0        | 0        |
| 4ms                            |                              |          |          |          | 0                          | 0        | 0        | 1        |
| 6ms                            |                              |          |          |          | 0                          | 0        | 1        | 0        |
| ⋮                              |                              |          |          |          |                            |          |          |          |
| 28ms                           | X                            |          |          |          | 1                          | 1        | 0        | 1        |
| 30ms                           |                              |          |          |          | 1                          | 1        | 1        | 0        |
| 32ms                           |                              |          |          |          | 1                          | 1        | 1        | 1        |
| 2ms                            | 0                            | 0        | 0        | 0        | X                          |          |          |          |
| 4ms                            | 0                            | 0        | 0        | 1        |                            |          |          |          |
| 6ms                            | 0                            | 0        | 1        | 0        |                            |          |          |          |
| ⋮                              |                              |          |          |          |                            |          |          |          |
| 28ms                           | 1                            | 1        | 0        | 1        | X                          |          |          |          |
| 30ms                           | 1                            | 1        | 1        | 0        |                            |          |          |          |
| 32ms                           | 1                            | 1        | 1        | 1        |                            |          |          |          |
| <b>Power-on default (32ms)</b> | <b>1</b>                     | <b>1</b> | <b>1</b> | <b>1</b> | <b>1</b>                   | <b>1</b> | <b>1</b> | <b>1</b> |

X = Don't care.

**Table 10. Key-Switch Interrupt Register (0x03)**

| REGISTER DESCRIPTION  | REGISTER DATA                      |          |          |                                    |          |          |          |          |
|---|------------------------------------|----------|----------|------------------------------------|----------|----------|----------|----------|
|   | D7                                 | D6       | D5       | D4                                 | D3       | D2       | D1       | D0       |
|   | FIFO-BASED $\overline{\text{INT}}$ |          |          | TIME-BASED $\overline{\text{INT}}$ |          |          |          |          |
| <b>Power-up default setting</b><br>All $\overline{\text{INT}}$ disabled | <b>0</b>                           | <b>0</b> | <b>0</b> | <b>0</b>                           | <b>0</b> | <b>0</b> | <b>0</b> | <b>0</b> |
| Time-based $\overline{\text{INT}}$ disabled                             | X                                  |          |          | 0                                  | 0        | 0        | 0        | 0        |
| $\overline{\text{INT}}$ asserts every debounce cycle                    |                                    |          |          | 0                                  | 0        | 0        | 0        | 1        |
| $\overline{\text{INT}}$ asserts every 2 debounce cycles                 |                                    |          |          | 0                                  | 0        | 0        | 1        | 0        |
| ⋮   |                                    |          |          |                                    |          |          |          |          |
| $\overline{\text{INT}}$ asserts every 29 debounce cycles                | X                                  |          |          | 1                                  | 1        | 1        | 0        | 1        |
| $\overline{\text{INT}}$ asserts every 30 debounce cycles                |                                    |          |          | 1                                  | 1        | 1        | 1        | 0        |
| $\overline{\text{INT}}$ asserts every 31 debounce cycles                |                                    |          |          | 1                                  | 1        | 1        | 1        | 1        |
| FIFO-based $\overline{\text{INT}}$ disabled                             | 0                                  | 0        | 0        | X                                  |          |          |          |          |
| $\overline{\text{INT}}$ asserts when the FIFO has 2 key events          | 0                                  | 0        | 1        |                                    |          |          |          |          |
| $\overline{\text{INT}}$ asserts when the FIFO has 4 key events          | 0                                  | 1        | 0        |                                    |          |          |          |          |
| ⋮   |                                    |          |          |                                    |          |          |          |          |
| $\overline{\text{INT}}$ asserts when the FIFO has 10 key events         | 1                                  | 0        | 1        | X                                  |          |          |          |          |
| $\overline{\text{INT}}$ asserts when the FIFO has 12 key events         | 1                                  | 1        | 0        |                                    |          |          |          |          |
| $\overline{\text{INT}}$ asserts when the FIFO has 14 key events         | 1                                  | 1        | 1        |                                    |          |          |          |          |
| Both time-based and FIFO-based interrupts active                        | Not all zero                       |          |          | Not all zero                       |          |          |          |          |

X = Don't care.

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 11. Key-Switch Autorepeat Register (0x05)

| REGISTER DESCRIPTION                       | REGISTER DATA |                 |          |          |                  |          |          |          |
|--|---------------|-----------------|----------|----------|------------------|----------|----------|----------|
|  | D7            | D6              | D5       | D4       | D3               | D2       | D1       | D0       |
|  | ENABLE        | AUTOREPEAT RATE |          |          | AUTOREPEAT DELAY |          |          |          |
| Autorepeat is disabled                     | 0             | X               | X        | X        | X                | X        | X        | X        |
| Autorepeat is enabled                      | 1             | Autorepeat rate |          |          | Autorepeat delay |          |          |          |
| Autorepeat delay is 8 debounce cycles      | 1             | X               |          |          | 0                | 0        | 0        | 0        |
| Autorepeat delay is 16 debounce cycles     | 1             |                 |          |          | 0                | 0        | 0        | 1        |
| Autorepeat delay is 24 debounce cycles     | 1             |                 |          |          | 0                | 0        | 1        | 0        |
| ⋮  |               |                 |          |          |                  |          |          |          |
| Autorepeat delay is 112 debounce cycles    | 1             | X               |          |          | 1                | 1        | 0        | 1        |
| Autorepeat delay is 120 debounce cycles    | 1             |                 |          |          | 1                | 1        | 0        |          |
| Autorepeat delay is 128 debounce cycles    | 1             |                 |          |          | 1                | 1        | 1        |          |
| Autorepeat frequency is 4 debounce cycles  | 1             | 0               | 0        | 0        | X                |          |          |          |
| Autorepeat frequency is 8 debounce cycles  | 1             | 0               | 0        | 1        |                  |          |          |          |
| Autorepeat frequency is 12 debounce cycles | 1             | 0               | 1        | 0        |                  |          |          |          |
| ⋮  |               |                 |          |          |                  |          |          |          |
| Autorepeat frequency is 24 debounce cycles | 1             | 1               | 0        | 1        | X                |          |          |          |
| Autorepeat frequency is 28 debounce cycles | 1             | 1               | 1        | 0        |                  |          |          |          |
| Autorepeat frequency is 32 debounce cycles | 1             | 1               | 1        | 1        |                  |          |          |          |
| <b>Power-on default setting</b>            | <b>0</b>      | <b>0</b>        | <b>0</b> | <b>0</b> | <b>0</b>         | <b>0</b> | <b>0</b> | <b>0</b> |

X = Don't care.

Table 12. Autosleep Register (0x06)

| REGISTER DESCRIPTION<br>AUTOSLEEP (ms) | REGISTER DATA |          |          |          |                   |          |          |          |
|--|---------------|----------|----------|----------|-------------------|----------|----------|----------|
|  | RESERVED      |          |          |          | AUTOSHUTDOWN TIME |          |          |          |
|  | D7            | D6       | D5       | D4       | D3                | D2       | D1       | D0       |
| Autosleep disabled                     | 0             | 0        | 0        | 0        | 0                 | 0        | 0        | 0        |
| 8192                                   | 0             | 0        | 0        | 0        | 0                 | 0        | 0        | 1        |
| 4096                                   | 0             | 0        | 0        | 0        | 0                 | 0        | 1        | 0        |
| 2048                                   | 0             | 0        | 0        | 0        | 0                 | 0        | 1        | 1        |
| 1024                                   | 0             | 0        | 0        | 0        | 0                 | 1        | 0        | 0        |
| 512                                    | 0             | 0        | 0        | 0        | 0                 | 1        | 0        | 1        |
| 256                                    | 0             | 0        | 0        | 0        | 0                 | 1        | 1        | 0        |
| 256                                    | 0             | 0        | 0        | 0        | 0                 | 1        | 1        | 1        |
| <b>Power-up default settings</b>       | <b>0</b>      | <b>0</b> | <b>0</b> | <b>0</b> | <b>0</b>          | <b>1</b> | <b>1</b> | <b>1</b> |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 13. Key-Switch Array Size Register (0x30)**

| REGISTER DESCRIPTION            | REGISTER DATA |          |          |          |          |          |          |          |
|---------------------------------|---------------|----------|----------|----------|----------|----------|----------|----------|
|                                 | D7            | D6       | D5       | D4       | D3       | D2       | D1       | D0       |
|                                 | ROWS          |          |          |          | COLUMNS  |          |          |          |
| No rows are key switches        | 0             | 0        | 0        | 0        | X        |          |          |          |
| ROW0 is a key switch            | 0             | 0        | 0        | 1        |          |          |          |          |
| ROW0 to ROW1 are key switches   | 0             | 0        | 1        | 0        |          |          |          |          |
| ROW0 to ROW2 are key switches   | 0             | 0        | 1        | 1        |          |          |          |          |
| ROW0 to ROW3 are key switches   | 0             | 1        | 0        | 0        |          |          |          |          |
| ROW0 to ROW4 are key switches   | 0             | 1        | 0        | 1        |          |          |          |          |
| ROW0 to ROW5 are key switches   | 0             | 1        | 1        | 0        |          |          |          |          |
| ROW0 to ROW6 are key switches   | 0             | 1        | 1        | 1        |          |          |          |          |
| ROW0 to ROW7 are key switches   | 1             | X        | X        | X        |          |          |          |          |
| No columns are key switches     | X             |          |          |          | 0        | 0        | 0        | 0        |
| COL0 is a key switch            |               |          |          |          | 0        | 0        | 0        | 1        |
| COL0 to COL1 are key switches   |               |          |          |          | 0        | 0        | 1        | 0        |
| COL0 to COL2 are key switches   |               |          |          |          | 0        | 0        | 1        | 1        |
| COL0 to COL3 are key switches   |               |          |          |          | 0        | 1        | 0        | 0        |
| COL0 to COL4 are key switches   |               |          |          |          | 0        | 1        | 0        | 1        |
| COL0 to COL5 are key switches   |               |          |          |          | 0        | 1        | 1        | 0        |
| COL0 to COL6 are key switches   |               |          |          |          | 0        | 1        | 1        | 1        |
| COL0 to COL7 are key switches   |               |          |          |          | 1        | X        | X        | X        |
| <b>Power-up default setting</b> | <b>1</b>      | <b>1</b> | <b>1</b> | <b>1</b> | <b>1</b> | <b>1</b> | <b>1</b> | <b>1</b> |

X = Don't care.

**Table 14. LED Driver Enable Register (0x31)**

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION          | DEFAULT VALUE |
|--------------|-------------|-------|-------------------|---------------|
| D[7:4]       | Reserved    | 0000  | —                 | 0000          |
| D3           | COL7        | 0     | GPIO function     | 0             |
|              |             | 1     | LED driver enable |               |
| D2           | COL6        | 0     | GPIO function     | 0             |
|              |             | 1     | LED driver enable |               |
| D1           | COL5        | 0     | GPIO function     | 0             |
|              |             | 1     | LED driver enable |               |
| D0           | COL4        | 0     | GPIO function     | 0             |
|              |             | 1     | LED driver enable |               |



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 15. GPIO Direction 1 Register (0x34)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION          | DEFAULT VALUE |
|--------------|-------------|-------|-------------------|---------------|
| D7           | ROW7        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D6           | ROW6        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D5           | ROW5        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D4           | ROW4        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D3           | ROW3        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D2           | ROW2        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D1           | ROW1        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D0           | ROW0        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |

Table 16. GPIO Direction 2 Register (0x35)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION          | DEFAULT VALUE |
|--------------|-------------|-------|-------------------|---------------|
| D7           | COL7        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D6           | COL6        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D5           | COL5        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D4           | COL4        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D3           | COL3        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D2           | COL2        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D1           | COL1        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |
| D0           | COL0        | 0     | Set as input pin  | 0             |
|              |             | 1     | Set as output pin |               |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 17. GPO Output Mode 1 Register (0x36)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                     | DEFAULT VALUE |
|--------------|-------------|-------|------------------------------|---------------|
| D7           | ROW7        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D6           | ROW6        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D5           | ROW5        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D4           | ROW4        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D3           | ROW3        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D2           | ROW2        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D1           | ROW1        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D0           | ROW0        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |

Table 18. GPO Output Mode 2 Register (0x37)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                     | DEFAULT VALUE |
|--------------|-------------|-------|------------------------------|---------------|
| D7           | COL7        | 0     | Port is an open-drain output | 0             |
| D6           | COL6        | 0     | Port is an open-drain output | 0             |
| D5           | COL5        | 0     | Port is an open-drain output | 0             |
| D4           | COL4        | 0     | Port is an open-drain output | 0             |
| D3           | COL3        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D2           | COL2        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D1           | COL1        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |
| D0           | COL0        | 0     | Port is an open-drain output | 1             |
|              |             | 1     | Port is a push-pull output   |               |

**Note:** When programmed as GPO, COL7–COL4 are always open drain and bits D[7:4] are not writable.

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 19. GPIO Supply Voltage 1 Register (0x38)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                         | DEFAULT VALUE |
|--------------|-------------|-------|----------------------------------|---------------|
| D7           | ROW7        | 0     | ROW7 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW7 supplied by V <sub>LA</sub> |               |
| D6           | ROW6        | 0     | ROW6 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW6 supplied by V <sub>LA</sub> |               |
| D5           | ROW5        | 0     | ROW5 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW5 supplied by V <sub>LA</sub> |               |
| D4           | ROW4        | 0     | ROW4 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW4 supplied by V <sub>LA</sub> |               |
| D3           | ROW3        | 0     | ROW3 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW3 supplied by V <sub>LA</sub> |               |
| D2           | ROW2        | 0     | ROW2 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW2 supplied by V <sub>LA</sub> |               |
| D1           | ROW1        | 0     | ROW1 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW1 supplied by V <sub>LA</sub> |               |
| D0           | ROW0        | 0     | ROW0 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | ROW0 supplied by V <sub>LA</sub> |               |

Table 20. GPIO Supply Voltage 2 Register (0x39)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                         | DEFAULT VALUE |
|--------------|-------------|-------|----------------------------------|---------------|
| D7           | COL7        | 0     | COL7 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL7 supplied by V <sub>LA</sub> |               |
| D6           | COL6        | 0     | COL6 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL6 supplied by V <sub>LA</sub> |               |
| D5           | COL5        | 0     | COL5 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL5 supplied by V <sub>LA</sub> |               |
| D4           | COL4        | 0     | COL4 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL4 supplied by V <sub>LA</sub> |               |
| D3           | COL3        | 0     | COL3 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL3 supplied by V <sub>LA</sub> |               |
| D2           | COL2        | 0     | COL2 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL2 supplied by V <sub>LA</sub> |               |
| D1           | COL1        | 0     | COL1 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL1 supplied by V <sub>LA</sub> |               |
| D0           | COL0        | 0     | COL0 supplied by V <sub>CC</sub> | 0             |
|              |             | 1     | COL0 supplied by V <sub>LA</sub> |               |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 21. GPIO Values 1 Register (0x3A)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION       | DEFAULT VALUE |
|--------------|-------------|-------|----------------|---------------|
| D7           | ROW7        | 0     | Clear ROW7 low | 1             |
|              |             | 1     | Set ROW7 high  |               |
| D6           | ROW6        | 0     | Clear ROW6 low | 1             |
|              |             | 1     | Set ROW6 high  |               |
| D5           | ROW5        | 0     | Clear ROW5 low | 1             |
|              |             | 1     | Set ROW5 high  |               |
| D4           | ROW4        | 0     | Clear ROW4 low | 1             |
|              |             | 1     | Set ROW4 high  |               |
| D3           | ROW3        | 0     | Clear ROW3 low | 1             |
|              |             | 1     | Set ROW3 high  |               |
| D2           | ROW2        | 0     | Clear ROW2 low | 1             |
|              |             | 1     | Set ROW2 high  |               |
| D1           | ROW1        | 0     | Clear ROW1 low | 1             |
|              |             | 1     | Set ROW1 high  |               |
| D0           | ROW0        | 0     | Clear ROW0 low | 1             |
|              |             | 1     | Set ROW0 high  |               |

Table 22. GPIO Values 2 Register (0x3B)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION       | DEFAULT VALUE |
|--------------|-------------|-------|----------------|---------------|
| D7           | COL7        | 0     | Clear COL7 low | 1             |
|              |             | 1     | Set COL7 high* |               |
| D6           | COL6        | 0     | Clear COL6 low | 1             |
|              |             | 1     | Set COL6 high* |               |
| D5           | COL5        | 0     | Clear COL5 low | 1             |
|              |             | 1     | Set COL5 high* |               |
| D4           | COL4        | 0     | Clear COL4 low | 1             |
|              |             | 1     | Set COL4 high* |               |
| D3           | COL3        | 0     | Clear COL3 low | 1             |
|              |             | 1     | Set COL3 high  |               |
| D2           | COL2        | 0     | Clear COL2 low | 1             |
|              |             | 1     | Set COL2 high  |               |
| D1           | COL1        | 0     | Clear COL1 low | 1             |
|              |             | 1     | Set COL1 high  |               |
| D0           | COL0        | 0     | Clear COL0 low | 1             |
|              |             | 1     | Set COL0 high  |               |

\*Open-drain output, pullup resistor required.

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 23. GPIO Level-Shifter Enable Register (0x3C)**

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION  | DEFAULT VALUE |
|--------------|-------------|-------|---|---------------|
| D7           | COL7        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL7 and ROW7 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D6           | COL6        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL6 and ROW6 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D5           | COL5        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL5 and ROW5 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D4           | COL4        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL4 and ROW4 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D3           | COL3        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL3 and ROW3 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D2           | COL2        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL2 and ROW2 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D1           | COL1        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL1 and ROW1 enabled; direction controlled by GPIO direction 2 register (0x35) |               |
| D0           | COL0        | 0     | Level shifting disabled   | 0             |
|              |             | 1     | Level shift between COL0 and ROW0 enabled; direction controlled by GPIO direction 2 register (0x35) |               |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 24. GPIO Global Configuration Register (0x40)**

| REGISTER BIT | DESCRIPTION                               | VALUE | FUNCTION  | DEFAULT VALUE |
|--------------|---|-------|---|---------------|
| D[7:6]       | Reserved                                  | 0     | —   | 00            |
| D5           | I <sup>2</sup> C timeout interrupt enable | 0     | Disabled  | 0             |
|              |   | 1     | $\overline{\text{INT}}$ is asserted when I <sup>2</sup> C bus times out. $\overline{\text{INT}}$ is deasserted when a read is performed on the I <sup>2</sup> C timeout flag register (0x48).   |               |
| D4           | GPIO enable                               | 0     | PWM, constant-current circuits, and GPIOs are shut down. GPO values depend on their setting. Register 0x31 to 0x5B values are stored and cannot be changed. The entire part is shut down if the key switches are in sleep mode (D7 of register 0x01).                               | 0             |
|              |   | 1     | Normal GPIO operation. PWM, constant-current circuits, and GPIOs are enabled regardless of key-switch sleep-mode state (see Table 8).   |               |
| D3           | GPIO reset                                | 0     | Normal operation  | 0             |
|              |   | 1     | Return all GPIO registers (registers 0x31 to 0x5B) to their POR value. This bit is momentary and resets itself to 0 after the write cycle.  |               |
| D[2:0]       | Fade-in/out time                          | 000   | No fading   | 000           |
|              |   | XXX   | PWM intensity ramps up (down) between the common PWM value and 0% duty cycle in 16 steps over the following time period:<br>D[2:0] = 001 = 256ms<br>D[2:0] = 010 = 512ms<br>D[2:0] = 011 = 1024ms<br>D[2:0] = 100 = 2048ms<br>D[2:0] = 101 = 4096ms<br>D[2:0] = 110/111 = Undefined |               |

**Table 25. GPIO Debounce Configuration Register (0x42)**

| REGISTER DESCRIPTION                                    | REGISTER DATA |    |    |               |    |    |    |    |
|---|---------------|----|----|---------------|----|----|----|----|
|   | D7            | D6 | D5 | D4            | D3 | D2 | D1 | D0 |
|   | RESERVED      |    |    | DEBOUNCE TIME |    |    |    |    |
| <b>Power-up default setting</b><br>Debounce time is 9ms | 0             | 0  | 0  | 0             | 0  | 0  | 0  | 0  |
| Debounce time is 10ms                                   | 0             | 0  | 0  | 0             | 0  | 0  | 0  | 1  |
| Debounce time is 11ms                                   | 0             | 0  | 0  | 0             | 0  | 0  | 1  | 0  |
| Debounce time is 12ms                                   | 0             | 0  | 0  | 0             | 0  | 0  | 1  | 1  |
|   |               |    |    |               |    |    |    |    |
|   |               |    |    |               |    |    |    |    |
| Debounce time is 37ms                                   | 0             | 0  | 0  | 1             | 1  | 1  | 0  | 0  |
| Debounce time is 38ms                                   | 0             | 0  | 0  | 1             | 1  | 1  | 0  | 1  |
| Debounce time is 39ms                                   | 0             | 0  | 0  | 1             | 1  | 1  | 1  | 0  |
| Debounce time is 40ms                                   | 0             | 0  | 0  | 1             | 1  | 1  | 1  | 1  |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 26. LED Constant-Current Setting Register (0x43)**

| REGISTER BIT | DESCRIPTION              | VALUE | FUNCTION                 | DEFAULT VALUE |
|--------------|--------------------------|-------|--------------------------|---------------|
| D[7:6]       | Reserved                 | 11    | Set always as 11         | 11            |
| D[5:1]       | Reserved                 | 00000 | —                        | 00000         |
| D0           | Constant-current setting | 0     | Constant current is 20mA | 0             |
|              |                          | 1     | Constant current is 10mA |               |

**Table 27. Common PWM Register (0x45)**

| REGISTER DESCRIPTION   | REGISTER DATA |    |    |    |    |    |    |    |
|--|---------------|----|----|----|----|----|----|----|
|  | D7            | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|  | COMMON PWM    |    |    |    |    |    |    |    |
| <b>Power-up default setting</b><br>Common PWM ratio is 0/256 | 0             | 0  | 0  | 0  | 0  | 0  | 0  | 0  |
| Common PWM ratio is 1/256                                    | 0             | 0  | 0  | 0  | 0  | 0  | 0  | 1  |
| Common PWM ratio is 2/256                                    | 0             | 0  | 0  | 0  | 0  | 0  | 1  | 0  |
| Common PWM ratio is 3/256                                    | 0             | 0  | 0  | 0  | 0  | 0  | 1  | 1  |
|  | ⋮             |    |    |    |    |    |    |    |
| Common PWM ratio is 252/256                                  | 1             | 1  | 1  | 1  | 1  | 1  | 0  | 0  |
| Common PWM ratio is 253/256                                  | 1             | 1  | 1  | 1  | 1  | 1  | 0  | 1  |
| Common PWM ratio is 254/256                                  | 1             | 1  | 1  | 1  | 1  | 1  | 1  | 0  |
| Common PWM ratio is <b>256/256</b> (100% duty cycle)         | 1             | 1  | 1  | 1  | 1  | 1  | 1  | 1  |

**Table 28. I<sup>2</sup>C Timeout Flag Register (0x48) (Read Only)**

| REGISTER BIT | DESCRIPTION                   | VALUE   | FUNCTION  | DEFAULT VALUE |
|--------------|-------------------------------|---------|---|---------------|
| D[7:1]       | Reserved                      | 0000000 | —   | 0000000       |
| D0           | I <sup>2</sup> C timeout flag | 0       | No I <sup>2</sup> C timeout has occurred since last read or POR.  | 0             |
|              |                               | 1       | I <sup>2</sup> C timeout has occurred since last read or POR. This bit is reset to zero when a read is performed on this register. I <sup>2</sup> C timeouts must be enabled for this function to work (see Table 8). |               |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 29. COL4–COL7 Individual PWM Ratio Registers (0x50 to 0x53)**

| REGISTER DESCRIPTION                                       | REGISTER DATA |    |    |    |    |    |    |    |
|--|---------------|----|----|----|----|----|----|----|
|  | D7            | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|  | PORT PWM      |    |    |    |    |    |    |    |
| <b>Power-up default setting</b><br>PORT PWM ratio is 0/256 | 0             | 0  | 0  | 0  | 0  | 0  | 0  | 0  |
| PORT PWM ratio is 1/256                                    | 0             | 0  | 0  | 0  | 0  | 0  | 0  | 1  |
| PORT PWM ratio is 2/256                                    | 0             | 0  | 0  | 0  | 0  | 0  | 1  | 0  |
| PORT PWM ratio is 3/256                                    | 0             | 0  | 0  | 0  | 0  | 0  | 1  | 1  |
|  | ⋮             |    |    |    |    |    |    |    |
| PORT PWM ratio is 252/256                                  | 1             | 1  | 1  | 1  | 1  | 1  | 0  | 0  |
| PORT PWM ratio is 253/256                                  | 1             | 1  | 1  | 1  | 1  | 1  | 0  | 1  |
| PORT PWM ratio is 254/256                                  | 1             | 1  | 1  | 1  | 1  | 1  | 1  | 0  |
| PORT PWM ratio is <b>256/256</b> (100% duty cycle)         | 1             | 1  | 1  | 1  | 1  | 1  | 1  | 1  |

**Table 30. COL4–COL7 LED Configuration Registers (0x54 to 0x57)**

| REGISTER BIT | DESCRIPTION   | VALUE   | FUNCTION   | DEFAULT VALUE |
|--------------|---------------|---------|--|---------------|
| D[7:6]       | Don't care    | 00      | —  | 00            |
| D5           | Common PWM    | 0       | Port uses individual PWM intensity register to set the PWM ratio | 0             |
|              |               | 1       | Port uses common PWM intensity register to set the PWM ratio     |               |
| D[4:2]       | Blink period  | 000     | Port does not blink  | 000           |
|              |               | 001     | Port blink period is 256ms                                       |               |
|              |               | 010     | Port blink period is 512ms                                       |               |
|              |               | 011     | Port blink period is 1024ms                                      |               |
|              |               | 100     | Port blink period is 2048ms                                      |               |
|              |               | 101     | Port blink period is 4096ms                                      |               |
|              |               | 110/111 | Undefined  |               |
| D[1:0]       | Blink-on time | 00      | LED is on for 50% of the blink period                            | 00            |
|              |               | 01      | LED is on for 25% of the blink period                            |               |
|              |               | 10      | LED is on for 12.5% of the blink period                          |               |
|              |               | 11      | LED is on for 6.25% of the blink period                          |               |



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

**Table 31. Interrupt Mask 1 Register (0x58)**

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                | DEFAULT VALUE |
|--------------|-------------|-------|-------------------------|---------------|
| D7           | ROW7        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D6           | ROW6        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D5           | ROW5        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D4           | ROW4        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D3           | ROW3        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D2           | ROW2        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D1           | ROW1        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D0           | ROW0        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |

**Table 32. Interrupt Mask 2 Register (0x59)**

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                | DEFAULT VALUE |
|--------------|-------------|-------|-------------------------|---------------|
| D7           | COL7        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D6           | COL6        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D5           | COL5        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D4           | COL4        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D3           | COL3        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D2           | COL2        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D1           | COL1        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |
| D0           | COL0        | 0     | Interrupt is not masked | 1             |
|              |             | 1     | Interrupt is masked     |               |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

Table 33. GPI Trigger Mode 1 Register (0x5A)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                                      | DEFAULT VALUE |
|--------------|-------------|-------|---|---------------|
| D7           | ROW7        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D6           | ROW6        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D5           | ROW5        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D4           | ROW4        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D3           | ROW3        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D2           | ROW2        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D1           | ROW1        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D0           | ROW0        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |

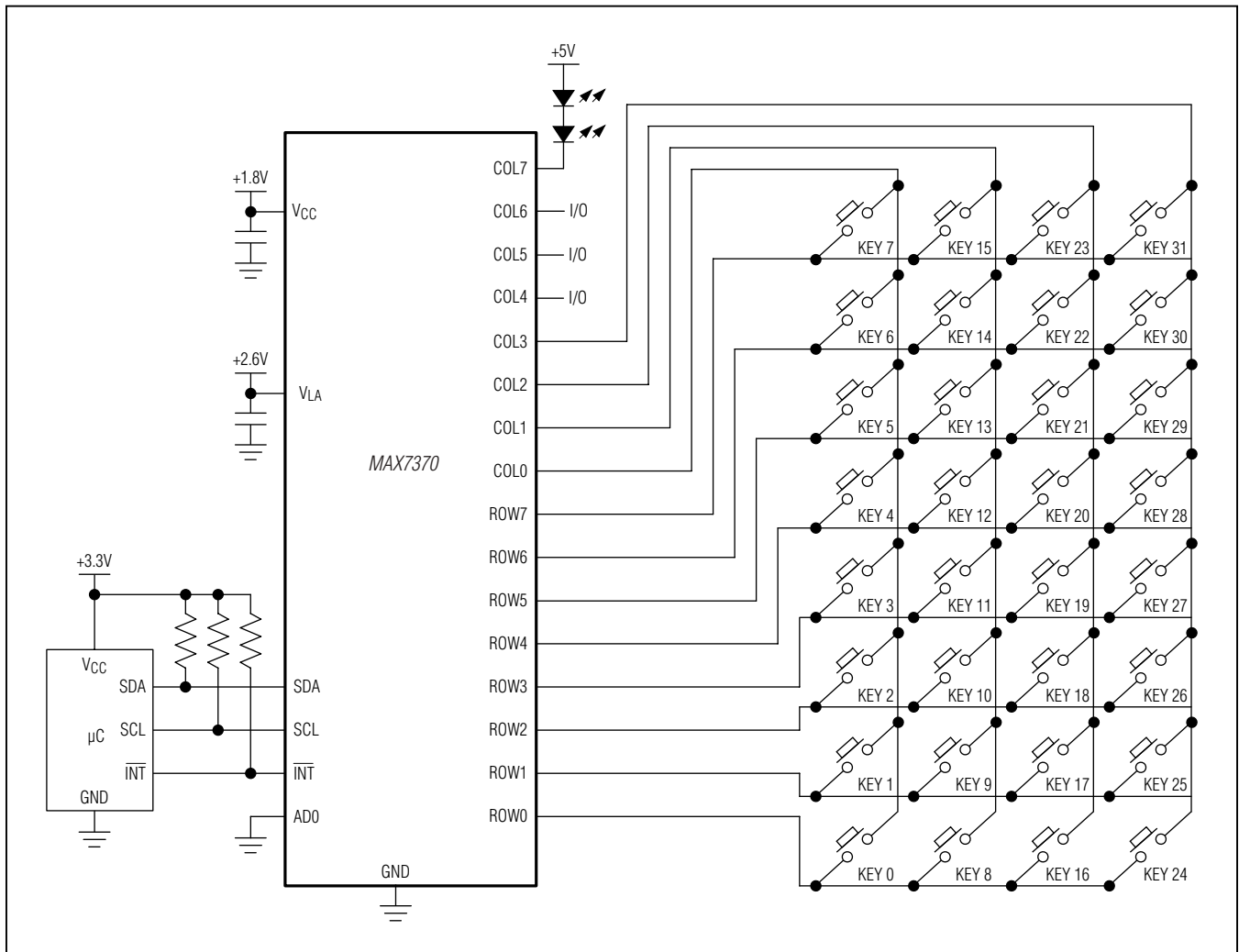
Table 34. GPI Trigger Mode 2 Register (0x5B)

| REGISTER BIT | DESCRIPTION | VALUE | FUNCTION                                      | DEFAULT VALUE |
|--------------|-------------|-------|---|---------------|
| D7           | COL7        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D6           | COL6        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D5           | COL5        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D4           | COL4        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D3           | COL3        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D2           | COL2        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D1           | COL1        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |
| D0           | COL0        | 0     | Rising-edge-triggered interrupts              | 0             |
|              |             | 1     | Rising- and falling-edge-triggered interrupts |               |

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Typical Application Circuit



# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### Wafer-Level Packaging (WLP) Applications Information

For the latest application details on WLP construction, dimensions, tape-carrier information, PCB techniques, bump-pad layout, and recommended reflow temperature profile, as well as the latest information on reliability testing results, refer to Application Note 1891: *Wafer-Level Packaging (WLP) and Its Applications*, available at [www.maximintegrated.com](http://www.maximintegrated.com).

### Package Information

For the latest package outline information and land patterns (footprints), go to [www.maximintegrated.com/packages](http://www.maximintegrated.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

| PACKAGE TYPE | PACKAGE CODE | OUTLINE NO.             | LAND PATTERN NO.                               |
|--------------|--------------|-------------------------|--|
| 24 TQFN-EP   | T243A3+1     | <a href="#">21-0188</a> | <a href="#">90-0122</a>                        |
| 25 WLP       | W252F2+1     | <a href="#">21-0453</a> | <a href="#">Refer to Application Note 1891</a> |

### Chip Information

PROCESS: BiCMOS

### Ordering Information

| PART          | TEMP RANGE     | PIN-PACKAGE |
|---------------|----------------|-------------|
| MAX7370ETG+   | -40°C to +85°C | 24 TQFN-EP* |
| MAX7370EWA+** | -40°C to +85°C | 25 WLP      |

+Denotes a lead(Pb)-free/RoHS-compliant package.

\*EP = Exposed. pad.

\*\*Future product—contact factory for availability.

# MAX7370

## 8 x 8 Key-Switch Controller and LED Driver/GPIOs with I<sup>2</sup>C Interface and High Level of ESD Protection

### *Revision History*

| REVISION NUMBER | REVISION DATE | DESCRIPTION                           | PAGES CHANGED |
|-----------------|---------------|---------------------------------------|---------------|
| 0               | 6/11          | Initial release                       | —             |
| 1               | 3/12          | Updated ESD protection specifications | 1, 4, 8, 19   |
| 2               | 5/15          | Updated Table 1                       | 8             |



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**Maxim Integrated 160 Rio Robles, San Jose, CA 95134 USA 1-408-601-1000**

37

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- Специальные условия для постоянных клиентов.
- Подбор аналогов.
- Поставку компонентов в любых объемах, удовлетворяющих вашим потребностям.
- Приемлемые сроки поставки, возможна ускоренная поставка.
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- Наличие сертификата ISO.

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- Техническую поддержку проекта.
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Тел: +7 (812) 336 43 04 (многоканальный)  
Email: [org@lifeelectronics.ru](mailto:org@lifeelectronics.ru)