

TOSHIBA CDMOS Integrated Circuit Silicon Monolithic

## TC62D749CFNAG

### 16-Output Constant Current LED Driver (Output switching high-speed version)

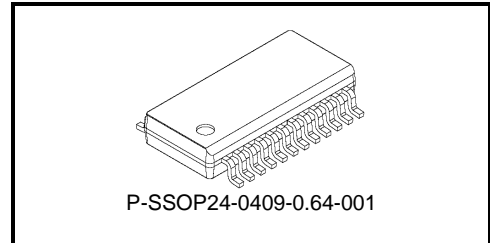
The TC62D749CFNAG is a constant-current driver for LED and LED display lighting applications.

The output current is constant-current controlled by a single external resistor.

The TC62D749CFNAG contains a 16-channel shift register, a 16-channel latch, a 16-channel AND gate and a 16-channel constant-current output.

Fabricated with a CMOS process, the TC62D749CFNAG allows high-speed data transfer.

It operates with a 3.3- or 5-V power supply.



Weight: 0.14 g (Typ.)

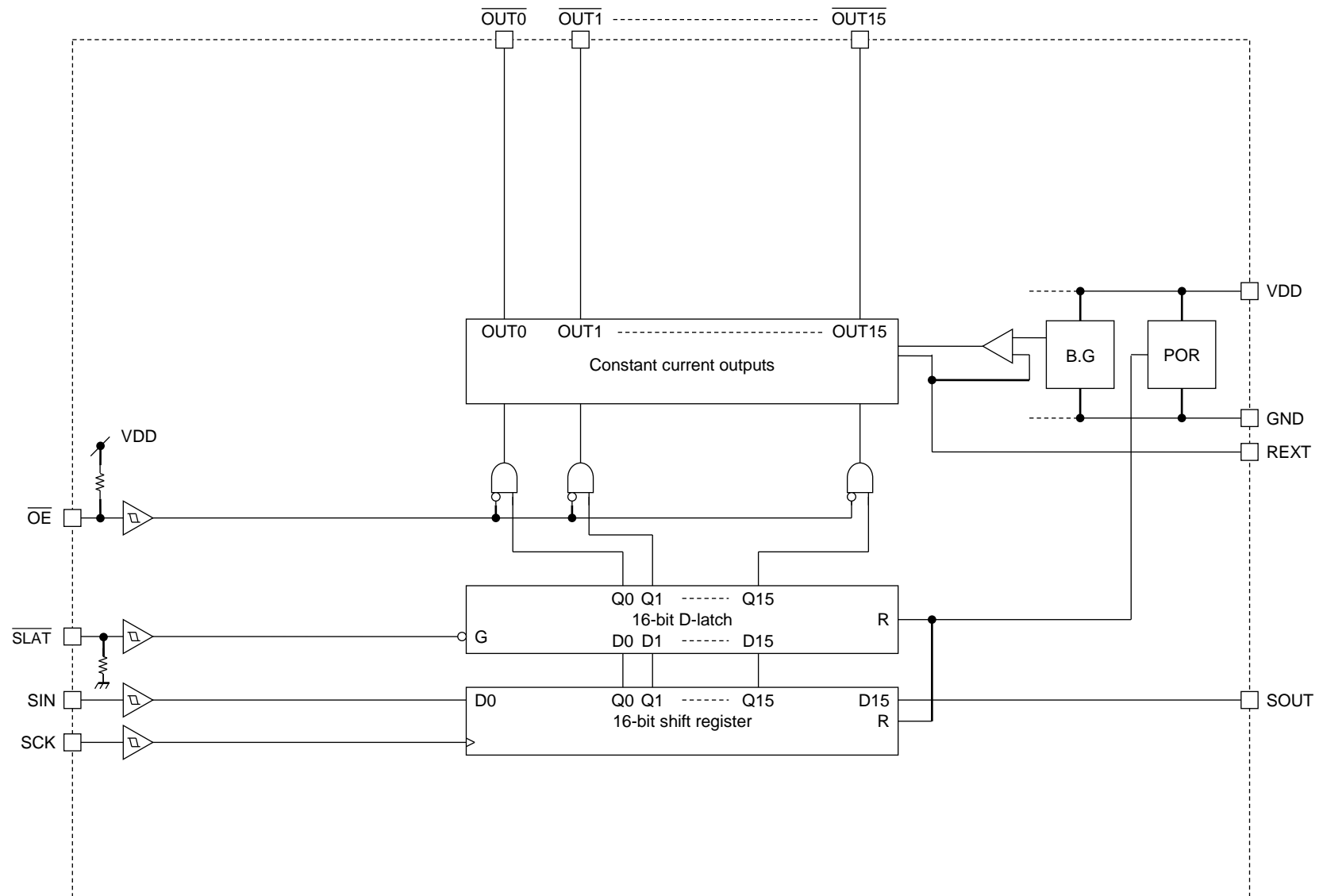
### Features

- Supply voltages :  $V_{DD} = 3.0\text{ V to }5.5\text{ V}$
- 16-output built-in
- Output current setup range :  $I_{OUT} = 1.5\text{ to }90\text{ mA}$
- Constant current output accuracy (@  $R_{EXT} = 1.2\text{ k}\Omega$ ,  $V_{OUT} = 1.0\text{ V}$ ,  $V_{DD} = 3.3\text{ V}, 5.0\text{ V}$ )
  - : S rank: between outputs  $\pm 1.5\%$  (max)
  - : S rank: between devices:  $\pm 1.5\%$  (max)
  - : N rank: between outputs  $\pm 2.5\%$  (max)
  - : N rank: between devices:  $\pm 2.5\%$  (max)
- Output voltage :  $V_{OUT} = 17\text{ V (max)}$
- High-speed output switching :  $t_{wOE} = 25\text{ ns (min)}$ ,  $t_{or} = 10\text{ ns (typ.)}$ ,  $t_{of} = 10\text{ ns (typ.)}$   
 There is TC62D748 as an output switching standard-speed version of this product.
- I/O interface : CMOS interfaces (Schmitt trigger input)
- Data transfer frequency :  $f_{SCK} = 25\text{ MHz (max)}$
- Operation temperature range :  $T_{opr} = -40\text{ to }85\text{ }^{\circ}\text{C}$
- Power-on-reset function built-in. (When the power supply is turned on, internal data is reset)
- Package : P-SSOP24-0409-0.64-001

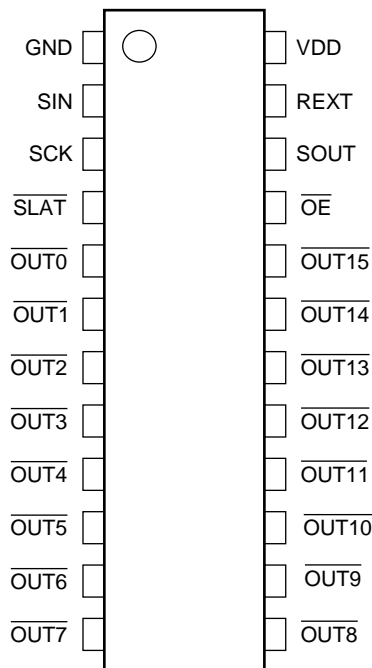
For detailed part naming conventions, contact your local Toshiba sales representative or distributor.

When the LED driver of high-speed output switching is used, back EMF may occur at the time of output OFF, and output terminal voltage may rise. Please be careful. It is necessary to reduce inductance to prevent the back EMF. It is possible to reduce inductance of a substrate by making the power supply for LED wiring shorter and wider designing the layout pattern.

## Block Diagram



## Pin Assignment (top view)



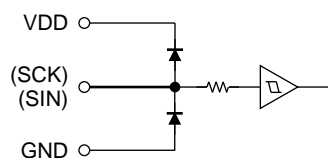
Short circuiting an output pin to a power supply pin (Power-supply voltage  $V_{DD}$  and LED anode power supply), or short-circuiting the REXT pin to the GND pin will likely exceed the rating, which in turn may result in smoldering and/or permanent damage. Please keep this in mind when determining the wiring layout for the power supply and GND pins.

## Pin Functions

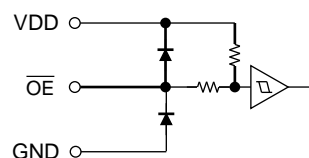
Pin No	Pin Name	I/O	Function
1	GND	—	GND terminal
2	SIN	I	Serial data input terminal
3	SCK	I	Serial data transfer clock input terminal
4	SLAT	I	Latch signal input pin.
5	OUT0	O	Constant-current output terminal
6	OUT1	O	Constant-current output terminal
7	OUT2	O	Constant-current output terminal
8	OUT3	O	Constant-current output terminal
9	OUT4	O	Constant-current output terminal
10	OUT5	O	Constant-current output terminal
11	OUT6	O	Constant-current output terminal
12	OUT7	O	Constant-current output terminal
13	OUT8	O	Constant-current output terminal
14	OUT9	O	Constant-current output terminal
15	OUT10	O	Constant-current output terminal
16	OUT11	O	Constant-current output terminal
17	OUT12	O	Constant-current output terminal
18	OUT13	O	Constant-current output terminal
19	OUT14	O	Constant-current output terminal
20	OUT15	O	Constant-current output terminal
21	OE	I	An output current enable signal input terminal In "H" level input, outputs are turned off compulsorily. In "L" level input, outputs are ON/OFF controlled according to serial data.
22	SOUT	O	Serial data output terminal.
23	REXT	—	An external resistance for an output current setup is connected between this terminal and ground.
24	VDD	—	Power supply terminal

## I/O Equivalent Circuits

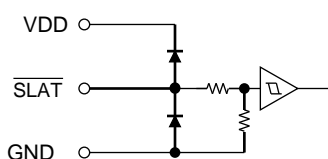
### 1. SCK, SIN



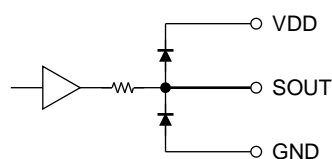
### 2. $\overline{\text{OE}}$



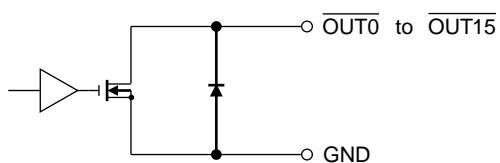
### 3. $\overline{\text{SLAT}}$



### 4. SOUT



### 5. $\overline{\text{OUT0}}$ to $\overline{\text{OUT15}}$



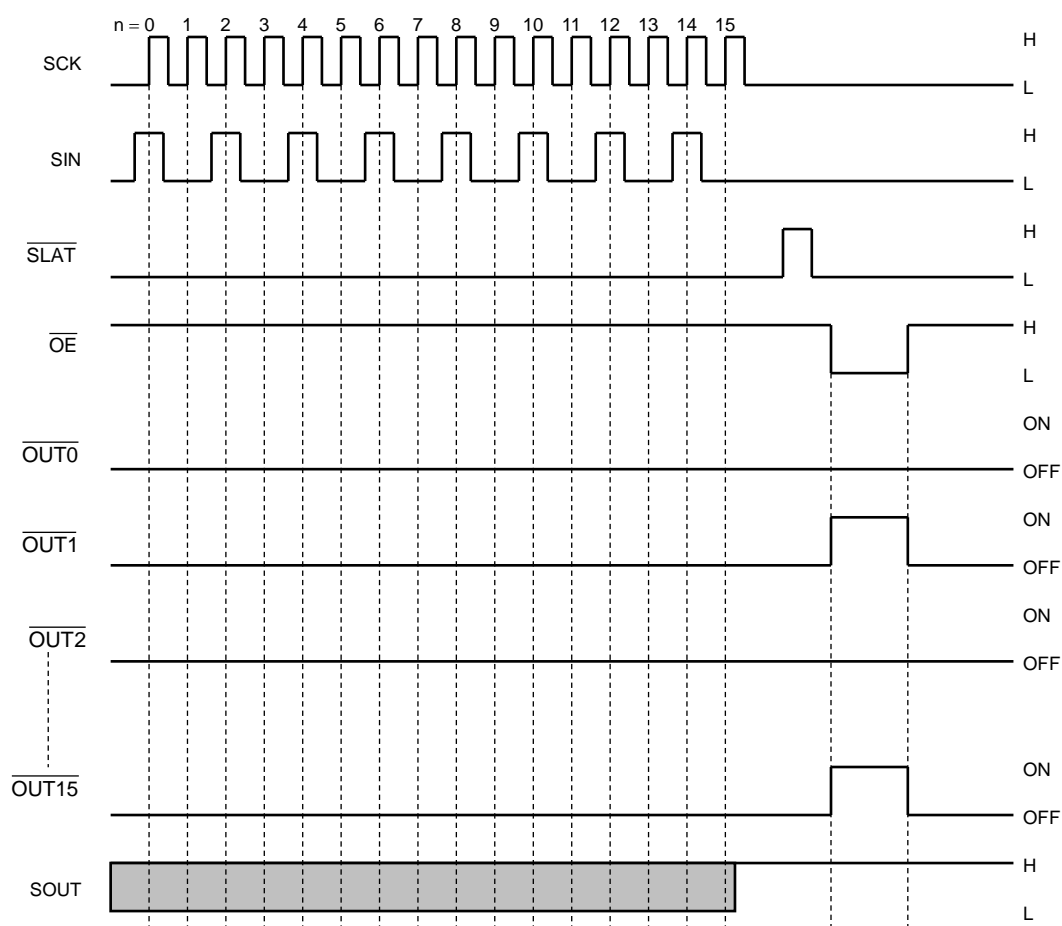
## Truth Table

SCK	$\overline{\text{SLAT}}$	$\overline{\text{OE}}$	SIN	$\overline{\text{OUT0}}$ ... $\overline{\text{OUT7}}$ ... $\overline{\text{OUT15}}$ (Note1)	SOUT
	H	L	Dn	Dn ... Dn - 7 ... Dn - 15	Dn - 15
	L	L	Dn + 1	No Change	Dn - 14
	H	L	Dn + 2	Dn + 2 ... Dn - 5 ... Dn - 13	Dn - 13
	– (Note2)	L	Dn + 3	Dn + 2 ... Dn - 5 ... Dn - 13	Dn - 13
	– (Note2)	H	Dn + 3	OFF	Dn - 13

Note1: When  $\overline{\text{OUT0}}$  to  $\overline{\text{OUT15}}$  output pins are set to "H" the respective output will be ON and when set to "L" the respective output will be OFF.

Note2: "–" is irrelevant to the truth table.

## Timing Diagram



- The latch circuit is a leveled-latch circuit. Please exercise precaution as it is not triggered-latch circuit.
- Keep the  $\overline{\text{SLAT}}$  pin is set to "L" to enable the latch circuit to hold data. In addition, when the  $\overline{\text{SLAT}}$  pin is set to "H" the latch circuit does not hold data. The data will instead pass onto output. When the  $\overline{\text{OE}}$  pin is set to "L" the  $\overline{\text{OUT0}}$  to  $\overline{\text{OUT15}}$  output pins will go ON and OFF in response to the data. In addition, when the  $\overline{\text{OE}}$  pin is set to "H" all the output pins will be forced OFF regardless of the data.
- This product can use 3.3V and 5.0V power supply, but power supply and input (SCK/SIN/ $\overline{\text{SLAT}}$  /  $\overline{\text{OE}}$ ) must use same voltage.

Absolute Maximum Ratings ( $T_a = 25^\circ\text{C}$ )

Characteristics	Symbol	Rating (Note1)	Unit
S u p p l y   v o l t a g e	$V_{DD}$	-0.3 to 6.0	V
O u t p u t   c u r r e n t	$I_{OUT}$	95	mA
L o g i c   i n p u t   v o l t a g e	$V_{IN}$	-0.3 to $V_{DD} + 0.3$ (Note2)	V
O u t p u t   v o l t a g e	$V_{OUT}$	-0.3 to 17	V
O p e r a t i n g   t e m p e r a t u r e	$T_{opr}$	-40 to 85	$^\circ\text{C}$
S t o r a g e   t e m p e r a t u r e	$T_{stg}$	-55 to 150	$^\circ\text{C}$
T h e r m a l   r e s i s t a n c e	$R_{th(j-a)}$	80.07	$^\circ\text{C/W}$
P o w e r   d i s s i p a t i o n	$P_D$	1.56 (Note3)	W

Note1: Voltage is ground referenced.

Note2: Do not exceed 6.0V.

Note3: The power dissipation decreases the reciprocal of the saturated thermal resistance ( $1/R_{th(j-a)}$ ) for each degree ( $1^\circ\text{C}$ ) that the ambient temperature is exceeded ( $T_a = 25^\circ\text{C}$ ).

## Operating Conditions

DC Items (Unless otherwise specified,  $V_{DD} = 3.0$  to  $5.5$  V,  $T_a = -40^\circ\text{C}$  to  $85^\circ\text{C}$ )

Characteristics	Symbol	Test Conditions	Min	Typ.	Max	Unit
S u p p l y   v o l t a g e	$V_{DD}$	—	3.0	—	5.5	V
High level logic input voltage	$V_{IH}$	Test terminal are SIN, SCK, $\overline{SLAT}$ , $\overline{OE}$	$0.7 \times V_{DD}$	—	$V_{DD}$	V
Low level logic input voltage	$V_{IL}$	Test terminal are SIN, SCK, $\overline{SLAT}$ , $\overline{OE}$	GND	—	$0.3 \times V_{DD}$	V
High level SOUT output current	$I_{OH}$	—	—	—	-1	mA
Low level SOUT output current	$I_{OL}$	—	—	—	1	mA
O u t p u t   c u r r e n t	$I_{OUT}$	Test terminal is $\overline{OUTn}$	1.5	—	90	mA

AC Items (Unless otherwise specified,  $V_{DD} = 3.0$  to  $5.5$  V,  $T_a = -40^\circ\text{C}$  to  $85^\circ\text{C}$ )

Characteristics	Symbol	Test Circuits	Test Conditions	Min	Typ.	Max	Unit
Serial data transfer frequency	$f_{SCK}$	6	—	—	—	25	MHz
Serial data Hold time	$t_{HOLD1}$	6	—	5	—	—	ns
	$t_{HOLD2}$	6	—	5	—	—	ns
Serial data Setup time	$t_{SETUP1}$	6	—	5	—	—	ns
	$t_{SETUP2}$	6	—	5	—	—	ns
Maximum clock rise time	$t_r$	6	(Note1)	—	—	500	ns
Maximum clock fall time	$t_f$	6	(Note1)	—	—	500	ns

Note1: If the device is connected in a cascade and the  $t_r/t_f$  of the clock waveform increases due to deceleration of the clock waveform, it may not be possible to achieve the timing required for data transfer. Please keep these timing conditions in mind when designing your application.

Electrical Characteristics (Unless otherwise specified,  $V_{DD} = 3.3V$ ,  $T_a = 25^\circ C$ )

Characteristics	Symbol	Test Circuits	Test Conditions	Min	Typ.	Max	Unit
H i g h l e v e l S O U T output voltage	$V_{OH}$	1	$I_{OH} = -1\text{ mA}$	$V_{DD} - 0.4$	—	—	V
L o w l e v e l S O U T output voltage	$V_{OL}$	1	$I_{OL} = +1\text{ mA}$	—	—	0.4	V
High level logic input current	$I_{IH}$	2	$V_{IN} = V_{DD}, \overline{OE}, \text{SIN}, \text{SCK}$	—	—	1	$\mu A$
Low level logic input current	$I_{IL}$	3	$V_{IN} = \text{GND}, \overline{SLAT}, \text{SIN}, \text{SCK}$	—	—	-1	$\mu A$
Power supply current	$I_{DD}$	4	$R_{EXT} = 1.2\text{ k}\Omega$ , All output on	—	—	8.0	mA
O u t p u t c u r r e n t	$I_{OUT}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 1.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	14.4	—	mA
Output current error(Ch to Ch) ( S r a n k )	$\Delta I_{OUT(Ch)}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 1.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	—	$\pm 1.5$	%
Output current error(IC to IC) ( S r a n k )	$\Delta I_{OUT(IC)}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 1.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	—	$\pm 1.5$	%
Output current error(Ch to Ch) ( N r a n k )	$\Delta I_{OUT(Ch)}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 1.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	—	$\pm 2.5$	%
Output current error(IC to IC) ( N r a n k )	$\Delta I_{OUT(IC)}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 1.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	—	$\pm 2.5$	%
Output OFF leak current	$I_{OK}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 17\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$	—	—	0.5	$\mu A$
Constant current output power supply v o l t a g e r e g u l a t i o n	$\%V_{DD}$	5	$V_{DD} = 3.0\text{ to }3.6\text{ V}$ , $V_{OUT} = 1.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	$\pm 1$	$\pm 5$	%/V
Constant current output voltage r e g u l a t i o n	$\%V_{OUT}$	5	$V_{DD} = 3.3\text{ V}$ , $V_{OUT} = 1.0\text{ to }3.0\text{ V}$ , $R_{EXT} = 1.2\text{ k}\Omega$ , 1 output on	—	$\pm 0.1$	$\pm 0.5$	%/V
P u l l - u p r e s i s t o r	$R_{(Up)}$	3	$\overline{OE}$	400	500	600	$k\Omega$
P u l l - d o w n r e s i s t o r	$R_{(Down)}$	2	$\overline{SLAT}$	400	500	600	$k\Omega$

Electrical Characteristics (Unless otherwise specified,  $V_{DD} = 5.0V$ ,  $T_a = 25^\circ C$ )

Characteristics	Symbol	Test Circuits	Test Conditions	Min	Typ.	Max	Unit
H i g h l e v e l S O U T o u t p u t v o l t a g e	$V_{OH}$	1	$I_{OH} = -1 \text{ mA}$	$V_{DD} - 0.4$	—	—	V
L o w l e v e l S O U T o u t p u t v o l t a g e	$V_{OL}$	1	$I_{OL} = +1 \text{ mA}$	—	—	0.4	V
High level logic input current	$I_{IH}$	2	$V_{IN} = V_{DD}, \overline{OE}, \text{SIN}, \text{SCK}$	—	—	1	$\mu A$
Low level logic input current	$I_{IL}$	3	$V_{IN} = \text{GND}, \overline{SLAT}, \text{SIN}, \text{SCK}$	—	—	-1	$\mu A$
Power supply current	$I_{DD}$	4	$R_{EXT} = 1.2 \text{ k}\Omega$ , All output on	—	—	8.0	mA
O u t p u t c u r r e n t	$I_{OUT}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 1.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	14.4	—	mA
Output current error(Ch to Ch) ( S r a n k )	$\Delta I_{OUT(Ch)}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 1.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	—	$\pm 1.5$	%
Output current error(IC to IC) ( S r a n k )	$\Delta I_{OUT(IC)}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 1.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	—	$\pm 1.5$	%
Output current error(Ch to Ch) ( N r a n k )	$\Delta I_{OUT(Ch)}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 1.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	—	$\pm 2.5$	%
Output current error(IC to IC) ( N r a n k )	$\Delta I_{OUT(IC)}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 1.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	—	$\pm 2.5$	%
Output OFF leak current	$I_{OK}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 17 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$	—	—	0.5	$\mu A$
Constant current output power supply v o l t a g e r e g u l a t i o n	% $V_{DD}$	5	$V_{DD} = 4.5 \text{ to } 5.5 \text{ V}$ , $V_{OUT} = 1.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	$\pm 1$	$\pm 5$	%/V
Constant current output voltage r e g u l a t i o n	% $V_{OUT}$	5	$V_{DD} = 5.0 \text{ V}$ , $V_{OUT} = 1.0 \text{ to } 3.0 \text{ V}$ , $R_{EXT} = 1.2 \text{ k}\Omega$ , 1 output on	—	$\pm 0.1$	$\pm 0.5$	%/V
P u l l - u p r e s i s t o r	R (Up)	3	$\overline{OE}$	400	500	600	$\text{k}\Omega$
P u l l - d o w n r e s i s t o r	R (Down)	2	$\overline{SLAT}$	400	500	600	$\text{k}\Omega$



**Switching Characteristics (Unless otherwise specified,  $V_{DD} = 3.3V$ ,  $T_a = 25^\circ C$ )**

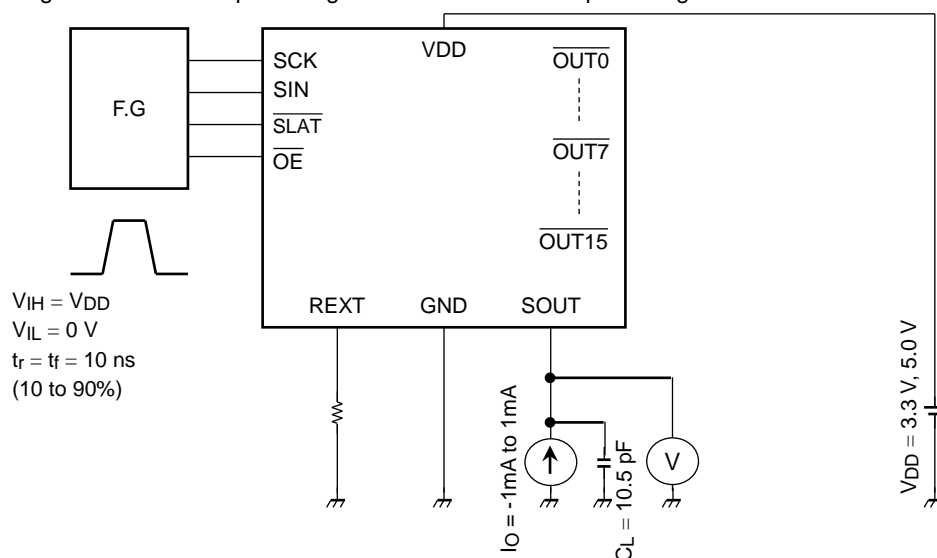
Characteristics		Symbol	Test Circuits	Test Conditions	Min	Typ.	Max	Unit
Propagation delay time	$SCK - \overline{OUT0}$	$t_{pLH1}$	6	$\overline{SLAT} = "H", \overline{OE} = "L"$	—	50	65	ns
	$\overline{SLAT} - \overline{OUT0}$	$t_{pLH2}$	6	$\overline{OE} = "L"$	—	50	65	ns
	$\overline{OE} - \overline{OUT0}$	$t_{pLH3}$	6	$\overline{SLAT} = "H"$	—	50	65	ns
	$SCK - SOUT$	$t_{pLH}$	6	$C_L = 10.5 \text{ pF}$	10	20	35	ns
	$SCK - \overline{OUT0}$	$t_{pHL1}$	6	$\overline{SLAT} = "H", \overline{OE} = "L"$	—	30	40	ns
	$\overline{SLAT} - \overline{OUT0}$	$t_{pHL2}$	6	$\overline{OE} = "L"$	—	30	40	ns
	$\overline{OE} - \overline{OUT0}$	$t_{pHL3}$	6	$\overline{SLAT} = "H"$	—	30	40	ns
	$SCK - SOUT$	$t_{pHL}$	6	$C_L = 10.5 \text{ pF}$	10	20	35	ns
Output rise time		$t_{or}$	6	10 to 90% of voltage waveform	—	10	20	ns
Output fall time		$t_{of}$	6	90 to 10% of voltage waveform	—	10	20	ns
Enable pulse width		$t_{wOE}$	6	$\overline{OE} = "H" \text{ or } "L"$	25	—	—	ns
Clock pulse width		$t_{wSCK}$	6	$SCK = "H" \text{ or } "L"$	20	—	—	ns
Latch pulse width		$t_{wSLAT}$	6	$\overline{SLAT} = "H"$	20	—	—	ns

**Switching Characteristics (Unless otherwise specified,  $V_{DD} = 5.0V$ ,  $T_a = 25^\circ C$ )**

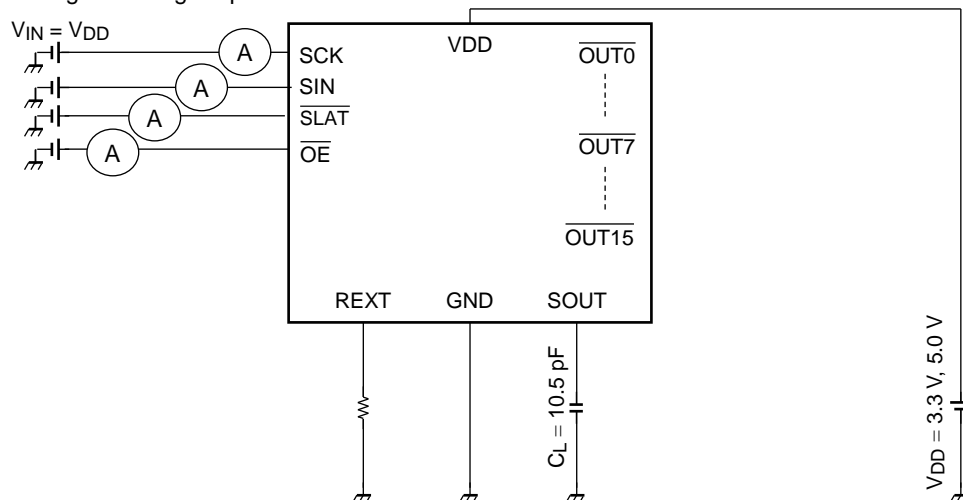
Characteristics		Symbol	Test Circuits	Test Conditions	Min	Typ.	Max	Unit
Propagation delay time	$SCK - \overline{OUT0}$	$t_{pLH1}$	6	$\overline{SLAT} = "H", \overline{OE} = "L"$	—	50	65	ns
	$\overline{SLAT} - \overline{OUT0}$	$t_{pLH2}$	6	$\overline{OE} = "L"$	—	50	65	ns
	$\overline{OE} - \overline{OUT0}$	$t_{pLH3}$	6	$\overline{SLAT} = "H"$	—	50	65	ns
	$SCK - SOUT$	$t_{pLH}$	6	$C_L = 10.5 \text{ pF}$	10	20	35	ns
	$SCK - \overline{OUT0}$	$t_{pHL1}$	6	$\overline{SLAT} = "H", \overline{OE} = "L"$	—	30	40	ns
	$\overline{SLAT} - \overline{OUT0}$	$t_{pHL2}$	6	$\overline{OE} = "L"$	—	30	40	ns
	$\overline{OE} - \overline{OUT0}$	$t_{pHL3}$	6	$\overline{SLAT} = "H"$	—	30	40	ns
	$SCK - SOUT$	$t_{pHL}$	6	$C_L = 10.5 \text{ pF}$	10	20	35	ns
Output rise time		$t_{or}$	6	10 to 90% of voltage waveform	—	10	20	ns
Output fall time		$t_{of}$	6	90 to 10% of voltage waveform	—	10	20	ns
Enable pulse width		$t_{wOE}$	6	$\overline{OE} = "H" \text{ or } "L"$	25	—	—	ns
Clock pulse width		$t_{wSCK}$	6	$SCK = "H" \text{ or } "L"$	20	—	—	ns
Latch pulse width		$t_{wSLAT}$	6	$\overline{SLAT} = "H"$	20	—	—	ns

## Test Circuits

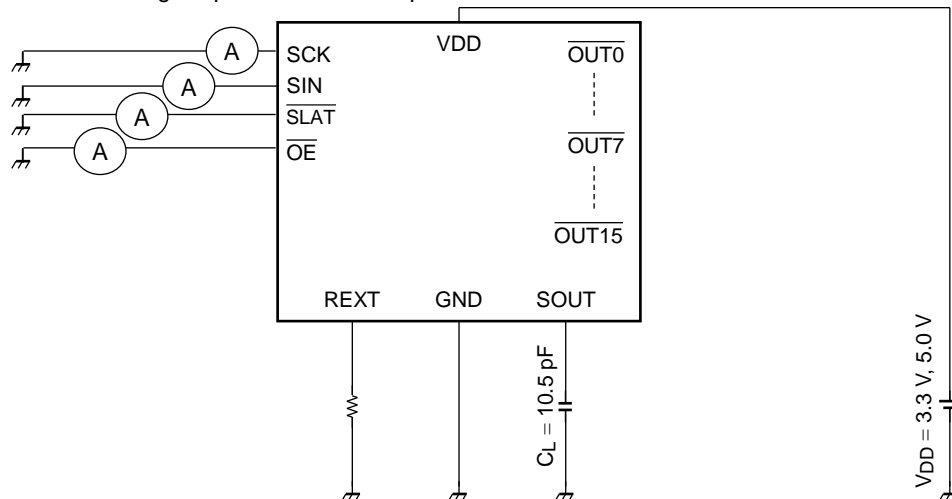
Test Circuit1: High level SOUT output voltage / Low level SOUT output voltage



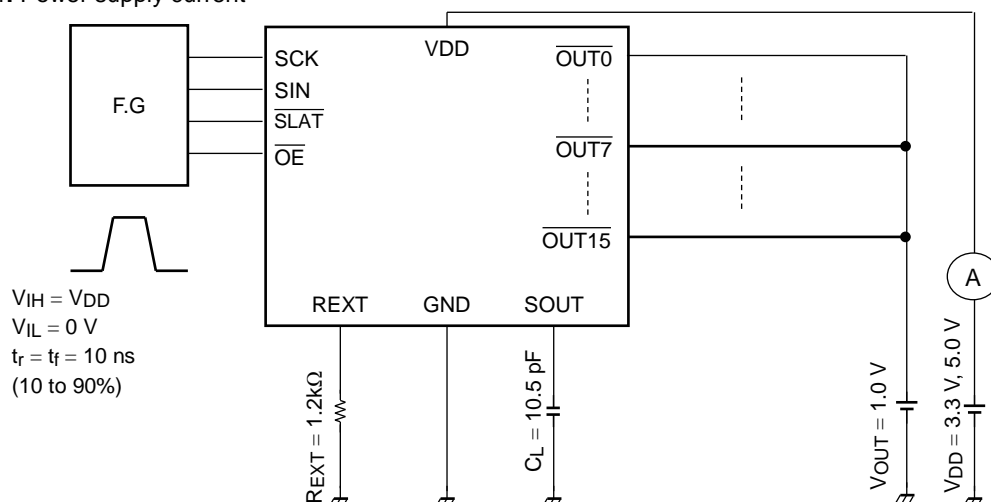
Test Circuit2: High level logic input current / Pull-down resistor



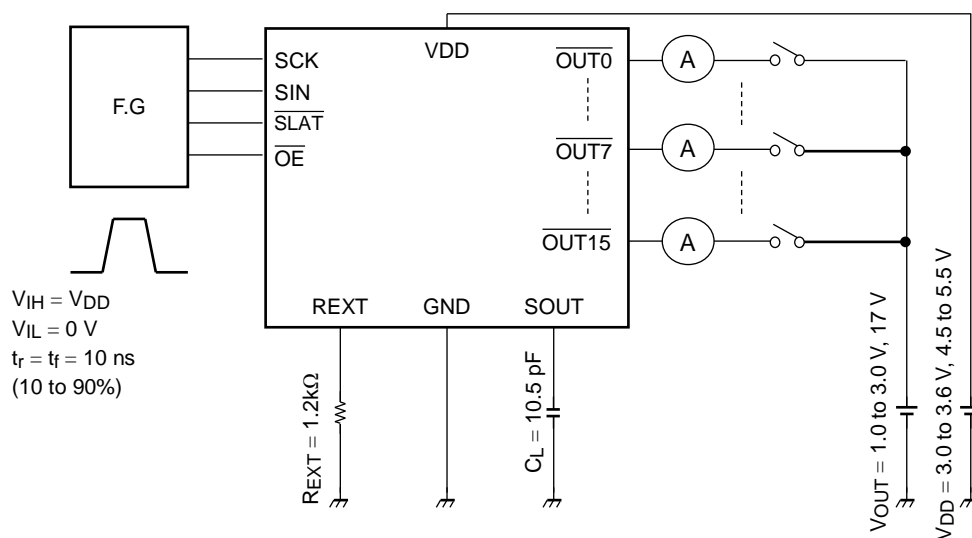
Test Circuit3: Low level logic input current / Pull-up resistor



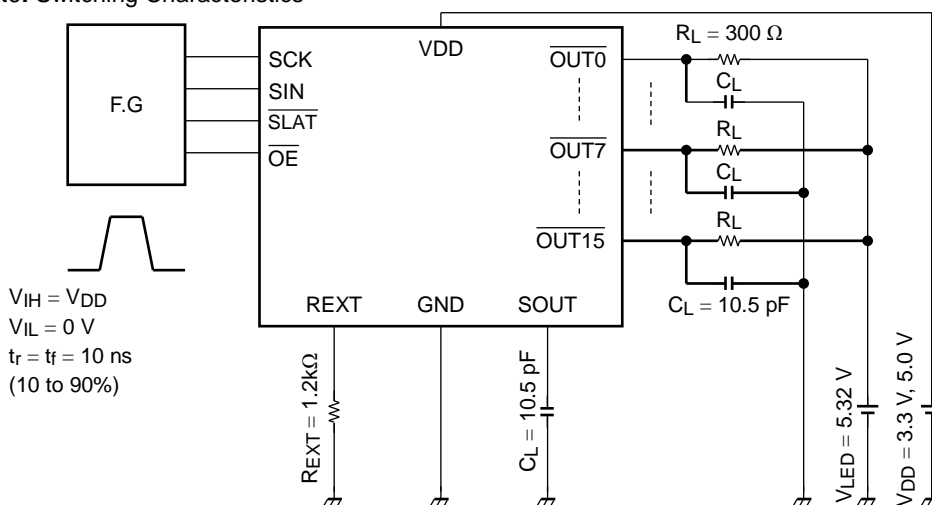
Test Circuit4: Power supply current



Test Circuit5: Constant current output / Output OFF leak current / Constant current error  
Constant current output power supply voltage regulation  
Constant current output output voltage regulation

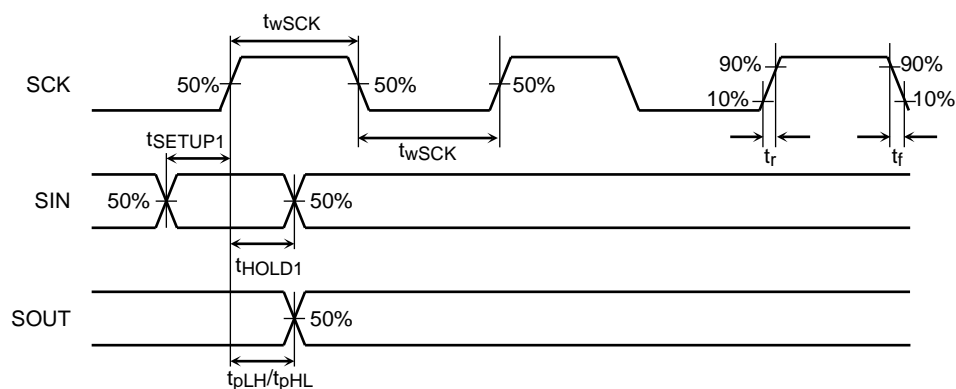


Test Circuit6: Switching Characteristics

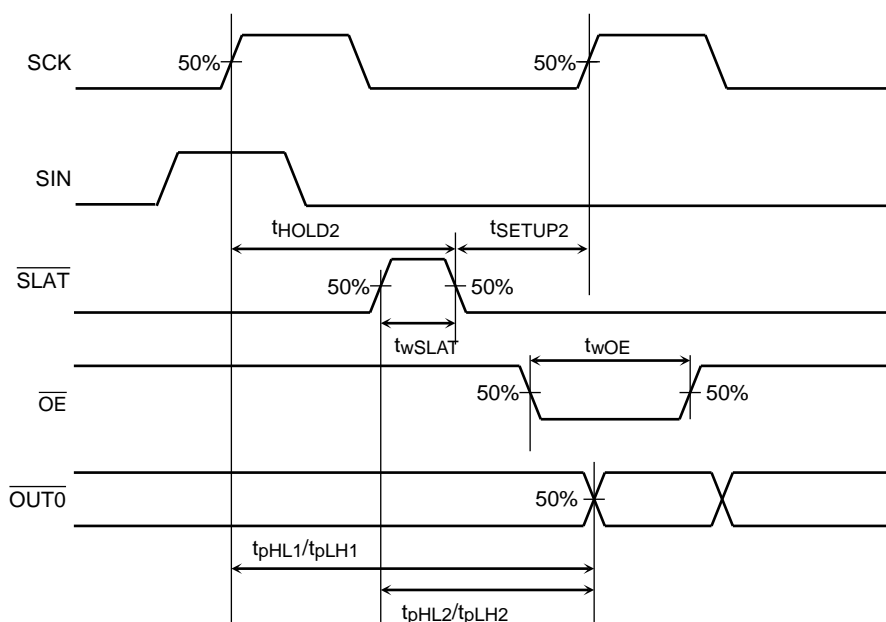


## Timing Waveforms

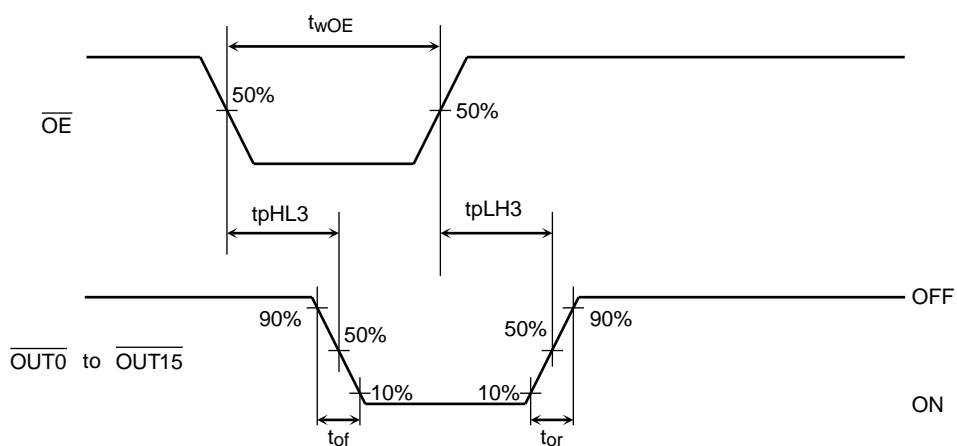
### 1. SCK, SIN, SOUT



### 2. SCK, SIN, $\overline{SLAT}$ , $\overline{OE}$ , and $\overline{OUT0}$



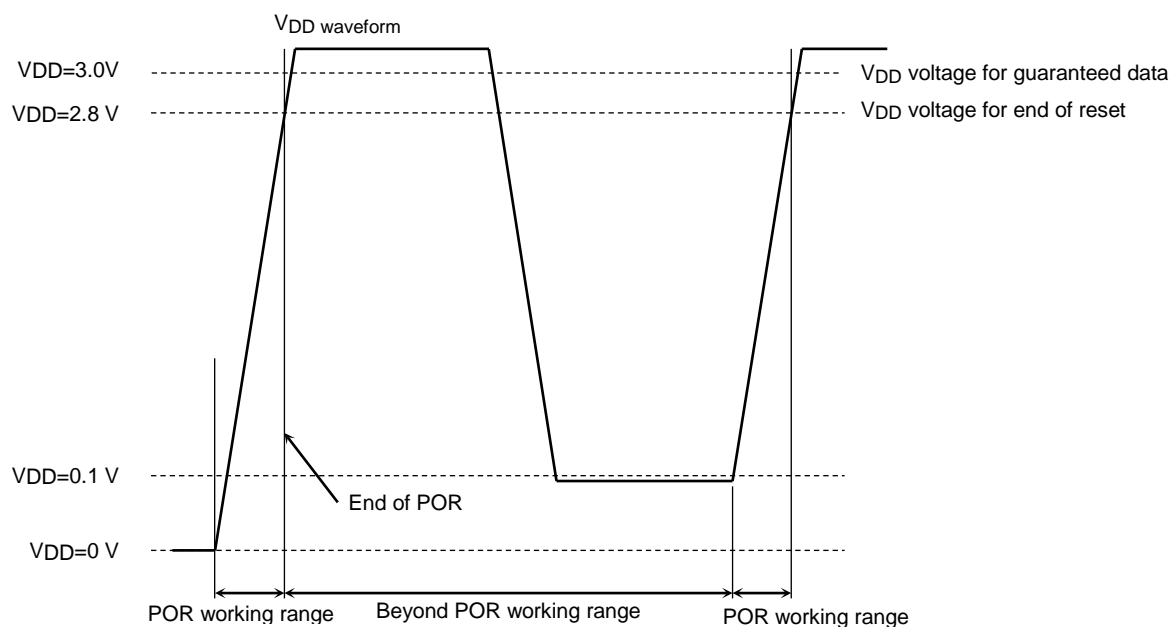
### 3. $\overline{OE}$ , $\overline{OUT0}$ to $\overline{OUT15}$



### Power on reset (POR)

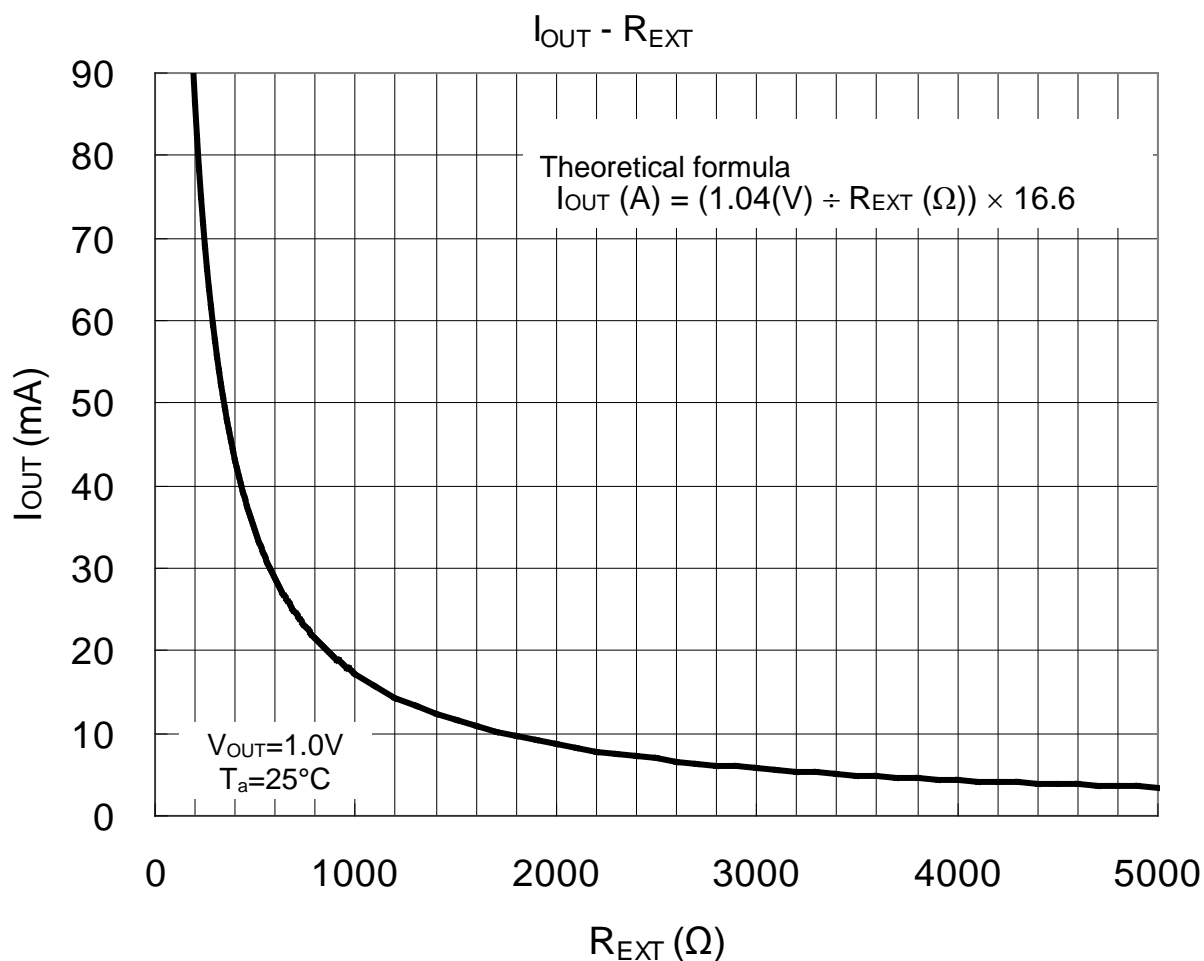
The TC62D749CFNAG provides a power-on reset to reset all internal data in order to prevent malfunctions.

The POR circuitry works properly only when  $V_{DD}$  rises from 0 V. To re-activate the POR circuitry,  $V_{DD}$  must be brought to less than 0.1 V. Internal data is guaranteed to be retained after  $V_{DD}$  exceeds 3.0 V.



**Reference data**

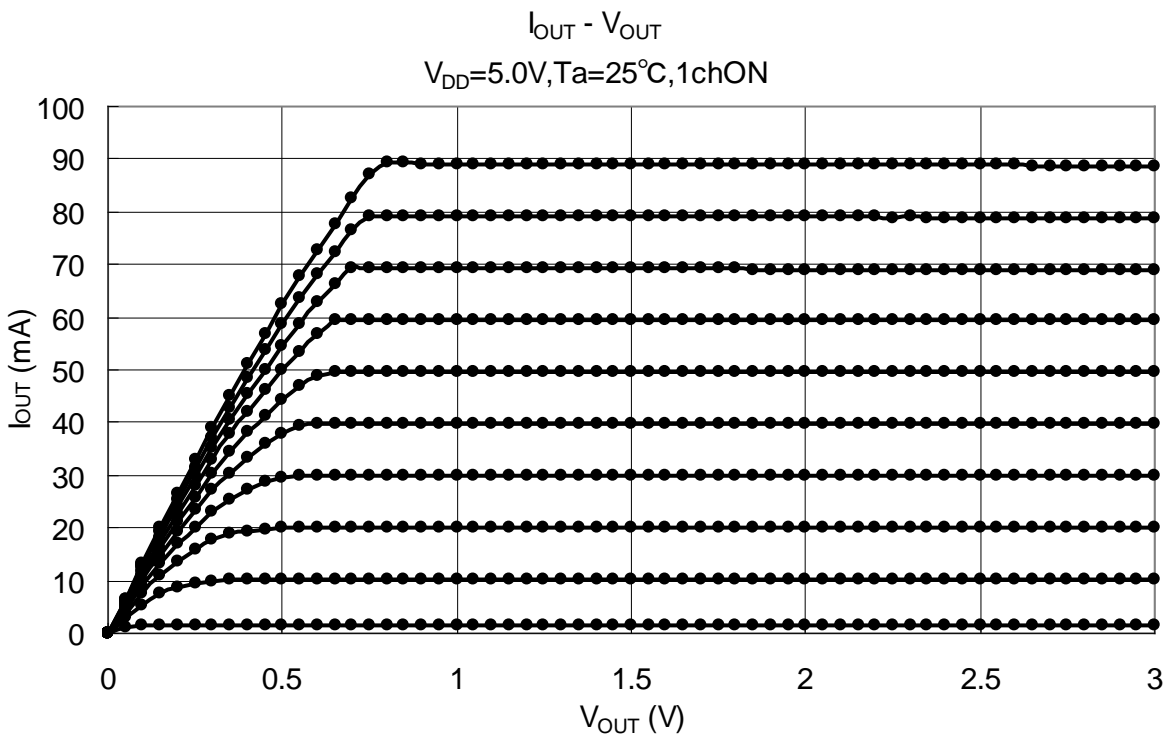
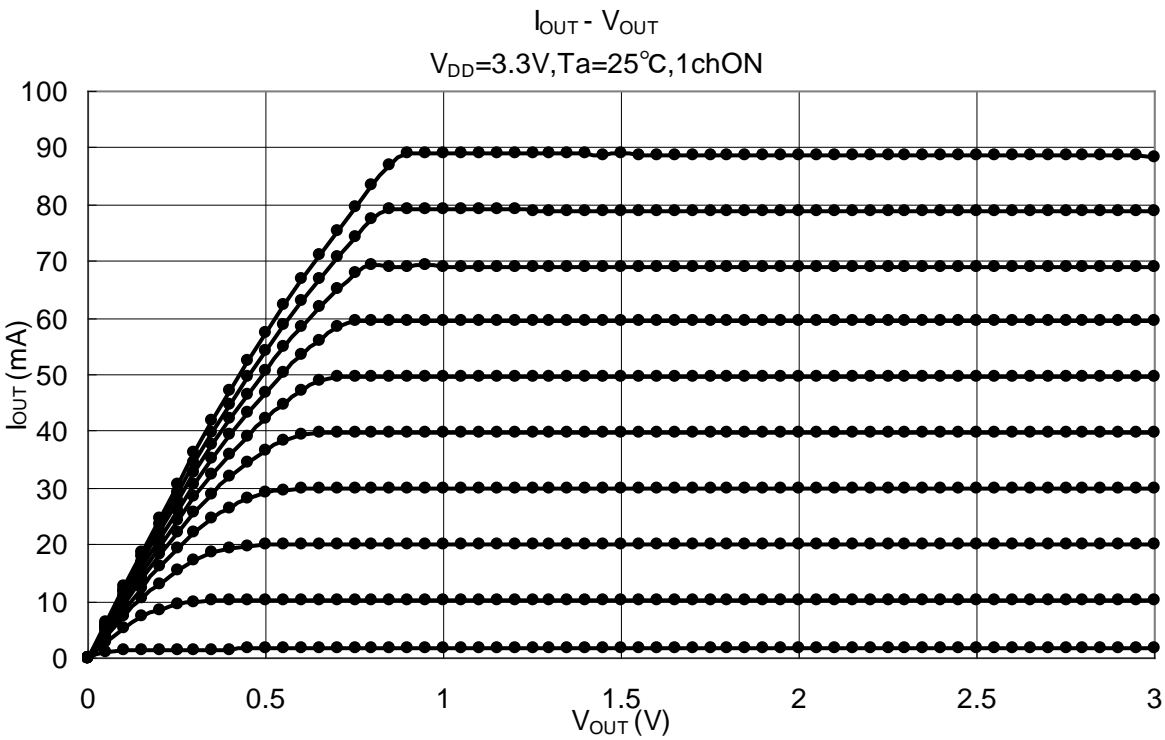
The above data is for reference only, not guaranteed. Careful evaluation is required prior to creating a production design.

**Output Current ( $I_{OUT}$ ) – Output current setting resistance ( $R_{EXT}$ )**

Reference data

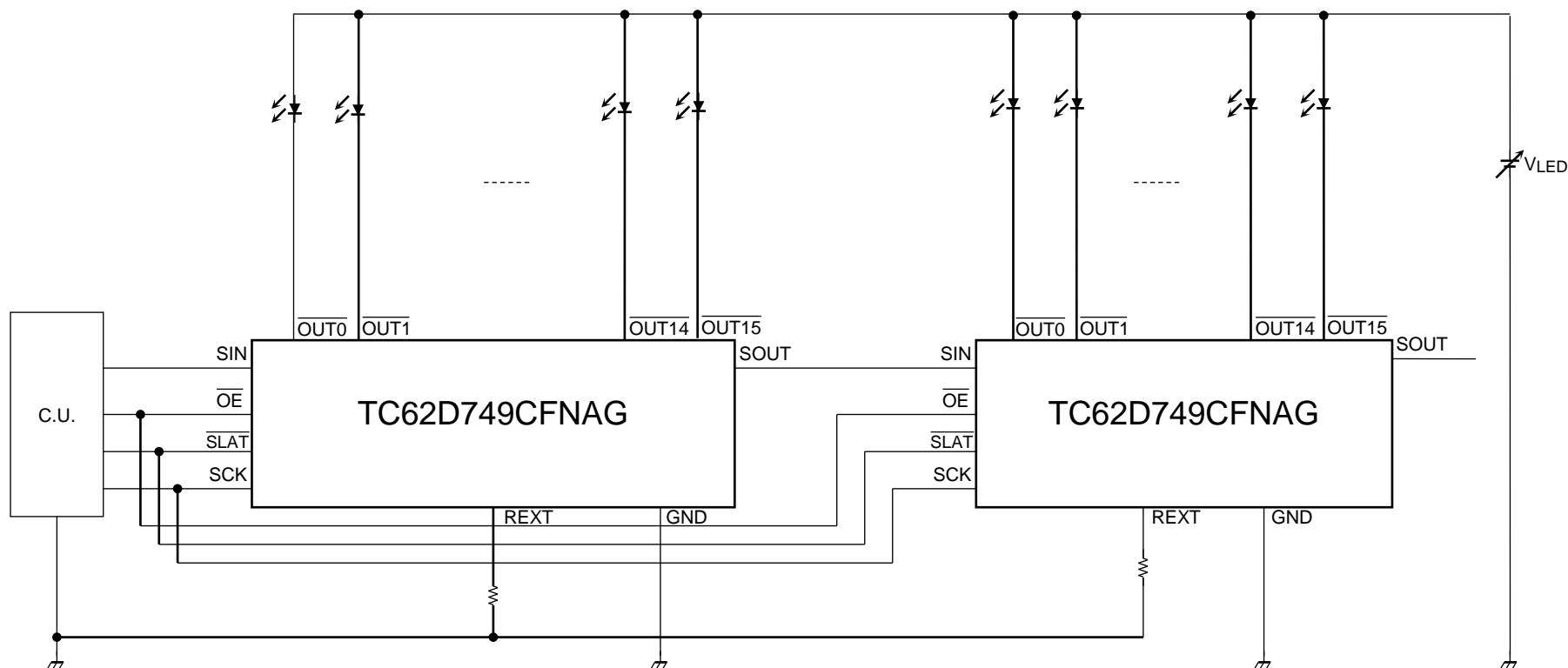
The above data is for reference only, not guaranteed. Careful evaluation is required prior to creating a production design.

Output current (I<sub>OUT</sub>) – Output voltage (V<sub>OUT</sub>)



## Application Circuit: General Composition for Static Lighting of LEDs

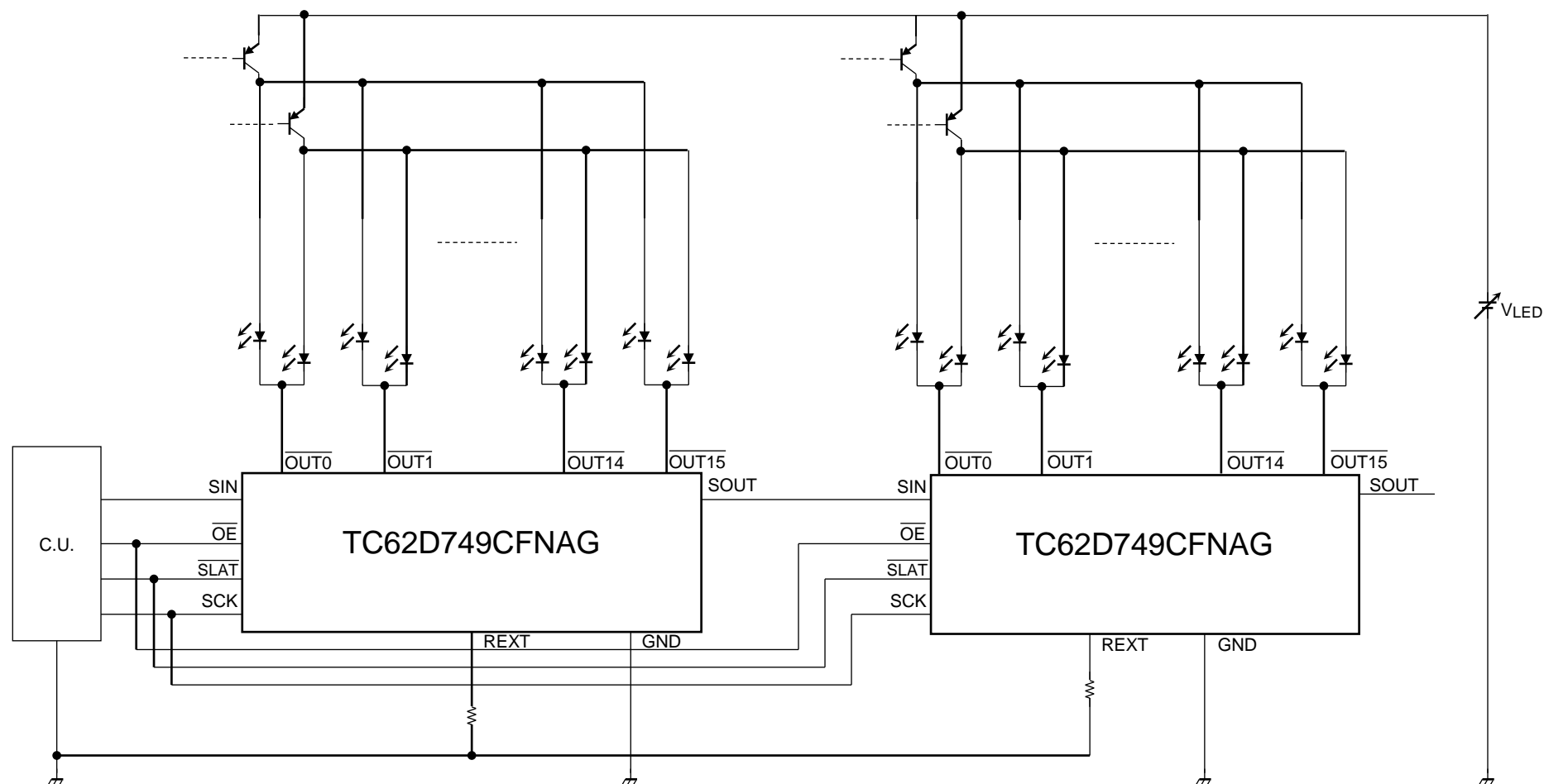
In the following diagram, it is recommended that the LED supply voltage ( $V_{LED}$ ) be equal to or greater than the sum of  $V_f$  (max) of all LEDs plus 1.0 V.





## Application Circuit: General Composition for Dynamic Lighting of LEDs

In the following diagram, it is recommended that the LED supply voltage ( $V_{LED}$ ) be equal to or greater than the sum of  $V_f$  (max) of all LEDs plus 1.0 V.



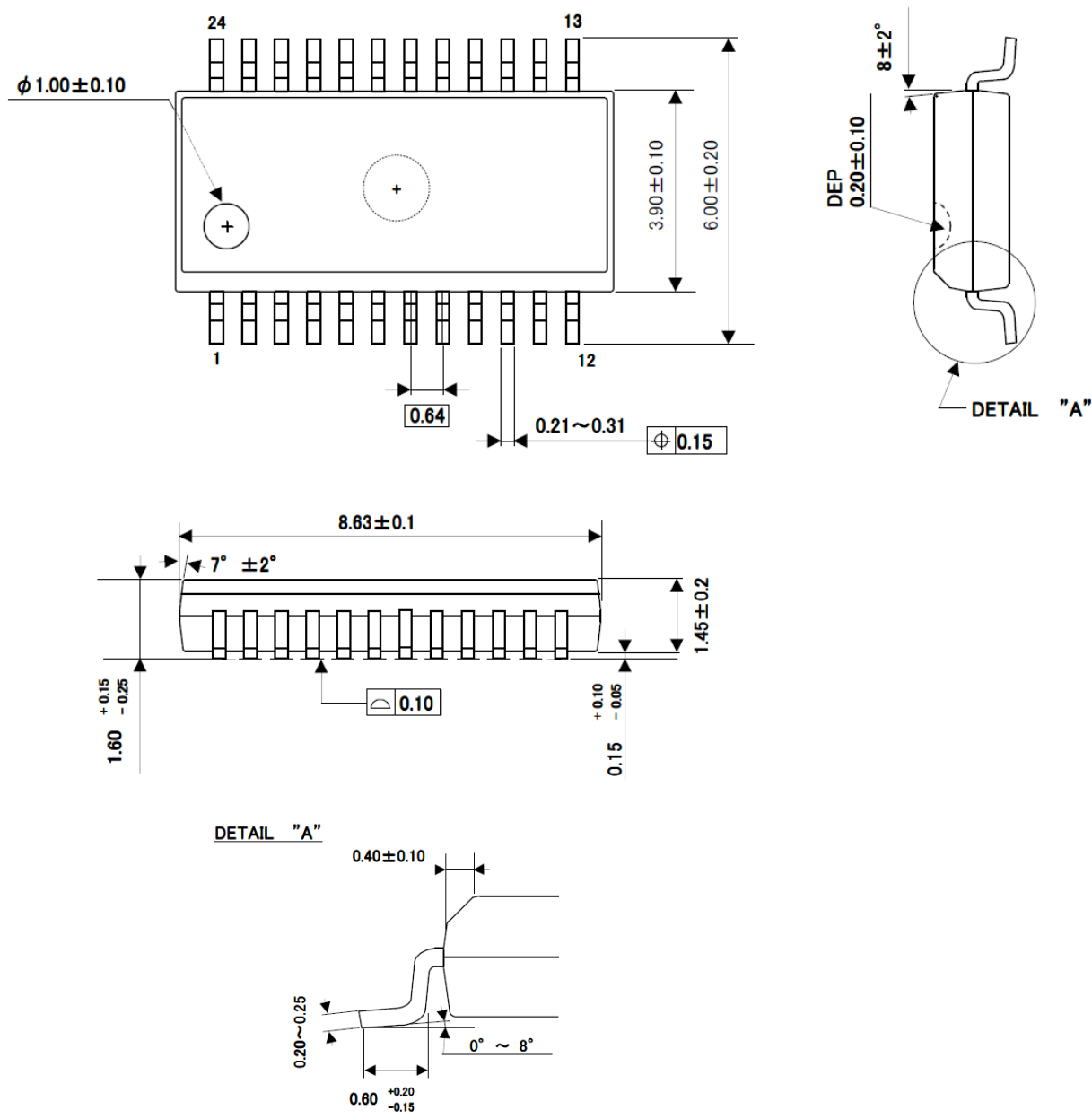
**Notes on design of ICs**

1. Decoupling capacitors between power supply and GND  
It is recommended to place decoupling capacitors between power supply and GND as close to the IC as possible.
2. Output current setting resistors  
When the output current setting resistors ( $R_{EXT}$ ) are shared among multiple ICs, production design should be evaluated carefully.
3. Board layout  
Ground noise generated by output switching might cause the IC to malfunction if the ground line exhibits inductance and resistance due to PC board traces and wire leads. Also, the inductance between the IC output pins and the LED cathode pins might cause large surge voltage, damaging LEDs and the IC outputs. To avoid this situation, PC board traces and wire leads should be carefully laid out.
4. Consult the latest technical information for mass production.

Package Dimensions

CFNAG Type  
P-SSOP24-0409-0.64-001

Unit: mm



Weight: 0.14 g (typ.)

**Notes on Contents****1. Block Diagrams**

Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

**2. Equivalent Circuits**

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

**3. Timing Charts**

Timing charts may be simplified for explanatory purposes.

**4. Application Circuits**

The application circuits shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage.

Toshiba does not grant any license to any industrial property rights by providing these examples of application circuits.

**5. Test Circuits**

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

## IC Usage Considerations

### Notes on handling of ICs

- [1] The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.  
Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
- [2] Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
- [3] If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition.  
Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.
- [4] Do not insert devices in the wrong orientation or incorrectly.  
Make sure that the positive and negative terminals of power supplies are connected properly.  
Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.  
In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.
- [5] Carefully select external components (such as inputs and negative feedback capacitors) and load components (such as speakers), for example, power amp and regulator.  
If there is a large amount of leakage current such as input or negative feedback condenser, the IC output DC voltage will increase. If this output voltage is connected to a speaker with low input withstand voltage, overcurrent or IC failure can cause smoke or ignition. (The over current can cause smoke or ignition from the IC itself.) In particular, please pay attention when using a Bridge Tied Load (BTL) connection type IC that inputs output DC voltage to a speaker directly.

### Points to remember on handling of ICs

- (1) Heat Radiation Design  
In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature ( $T_J$ ) at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into consideration the effect of IC heat radiation with peripheral components.
- (2) Back-EMF  
When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond absolute maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

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