# 74HC191

# Presettable synchronous 4-bit binary up/down counter Rev. 5 — 13 August 2019 Product data sheet

# 1. General description

The 74HC191 is an asynchronously presettable 4-bit binary up/down counter. It contains four master/slave flip-flops with internal gating and steering logic to provide asynchronous preset and synchronous count-up and count-down operation. Asynchronous parallel load capability permits the counter to be preset to any desired value. Information present on the parallel data inputs (D0 to D3) is loaded into the counter and appears on the outputs when the parallel load (PL) input is LOW. This operation overrides the counting function. Counting is inhibited by a HIGH level on the count enable (CE) input. When CE is LOW internal state changes are initiated synchronously by the LOW-to-HIGH transition of the clock input. The up/down  $(\overline{U}/D)$  input signal determines the direction of counting as indicated in the function table. The CE input may go LOW when the clock is in either state, however, the LOW-to-HIGH CE transition must occur only when the clock is HIGH. Also, the  $\overline{U}/D$  input should be changed only when either  $\overline{CE}$  or CP is HIGH. Overflow/underflow indications are provided by two types of outputs, the terminal count (TC) and ripple clock (RC). The TC output is normally LOW and goes HIGH when a circuit reaches zero in the count-down mode or reaches '15' in the count-up-mode. The TC output will remain HIGH until a state change occurs, either by counting or presetting, or until  $\overline{U}/D$  is changed. Do not use the TC output as a clock signal because it is subject to decoding spikes. The TC signal is used internally to enable the RC output. When TC is HIGH and CE is LOW, the RC output follows the clock pulse (CP). This feature simplifies the design of multistage counters as shown in Fig. 5 and Fig. 6. In Fig. 5, each RC output is used as the clock input to the next higher stage. It is only necessary to inhibit the first stage to prevent counting in all stages, since a HIGH on CE inhibits the RC output pulse. The timing skew between state changes in the first and last stages is represented by the cumulative delay of the clock as it ripples through the preceding stages. This can be a disadvantage of this configuration in some applications. Fig. 6 shows a method of causing state changes to occur simultaneously in all stages. The RC outputs propagate the carry/borrow signals in ripple fashion and all clock inputs are driven in parallel. In this configuration the duration of the clock LOW state must be long enough to allow the negative-going edge of the carry/borrow signal to ripple through to the last stage before the clock goes HIGH. Since the RC output of any package goes HIGH shortly after its CP input goes HIGH there is no such restriction on the HIGH-state duration of the clock. In Fig. 7, the configuration shown avoids ripple delays and their associated restrictions. Combining the TC signals from all the preceding stages forms the CE input for a given stage. An enable must be included in each carry gate in order to inhibit counting. The TC output of a given stage it not affected by its own CE signal therefore the simple inhibit scheme of Fig. 5 and Fig. 6 does not apply. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V<sub>CC</sub>.

#### 2. Features and benefits

- · Complies with JEDEC standard no. 7A
- CMOS input levels:
- Synchronous reversible counting
- · Asynchronous parallel load
- Count enable control for synchronous expansion
- Single up/down control input
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-A exceeds 200 V
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



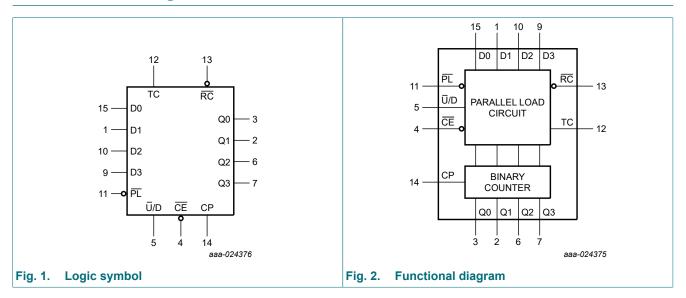
#### Presettable synchronous 4-bit binary up/down counter

# 3. Ordering information

**Table 1. Ordering information** 

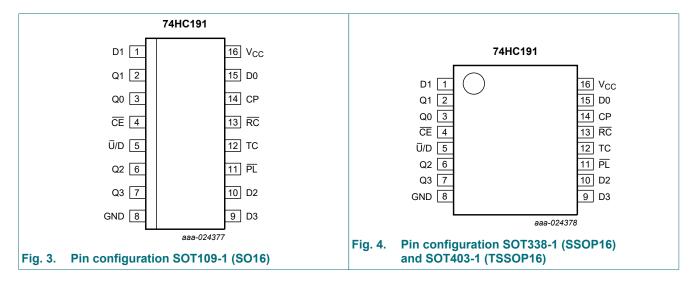
Type number	Package			
	Temperature range	Name	Description	Version
74HC191D	-40 °C to +125 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1
74HC191DB	-40 °C to +125 °C	SSOP16	plastic shrink small outline package; 16 leads; body width 5.3 mm	SOT338-1
74HC191PW	-40 °C to +125 °C	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1

# 4. Functional diagram



# 5. Pinning information

### 5.1. Pinning



#### Presettable synchronous 4-bit binary up/down counter

# 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
D0, D1, D2, D3	15, 1, 10, 9	data input
Q0, Q1, Q2, Q3	3, 2, 6, 7	flip-flop output
CE	4	count enable input (active LOW)
Ū/D	5	up/down input
GND	8	ground (0 V)
PL	11	parallel load input (active LOW)
TC	12	terminal count output
RC	13	ripple clock output (active LOW)
СР	14	clock input (LOW-to-HIGH, edge-triggered)
V <sub>CC</sub>	16	supply voltage

# 6. Functional description

#### Table 3. Function table

H = HIGH voltage level; L = LOW voltage level;

I = LOW voltage level one set-up time prior to the LOW-to-HIGH clock transition; X = don't care;

<sup>↑ =</sup> LOW-to-HIGH clock transition

Operating mode		Output				
	PL	Ū/D	CE	СР	Dn	Qn
parallel load	L	Х	Х	Х	L	L
	L	X	Х	Х	Н	Н
count up	Н	L	I	<b>↑</b>	X	count up
count down	Н	Н	I	<b>↑</b>	X	count down
Hold (do nothing)	Н	X	Н	Х	X	no change

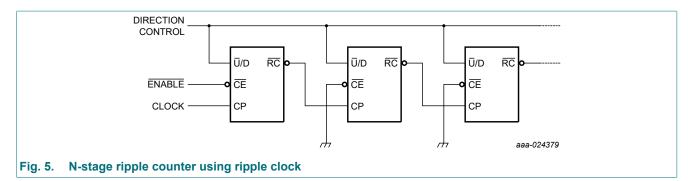
#### Table 4. TC and RC Function table

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care; \ \coprod = one \ LOW \ level \ pulse;$ 

L = TC goes LOW on a LOW-to-HIGH clock transition.

Input			Terminal count state				Output		
<del>U</del> /D	CE	СР	Q0	Q1	Q2	Q3	TC	RC	
Н	Н	Х	Н	Н	Н	Н	L	Н	
L	Н	Х	Н	Н	Н	Н	Н	Н	
L	L	Ъ	Н	Н	Н	Н	l	Ц	
L	Н	Х	L	L	L	L	L	Н	
Н	Н	Х	L	L	L	L	Н	Н	
Н	L	T	L	L	L	L	1	Image: control of the	

### Presettable synchronous 4-bit binary up/down counter



DIRECTION CONTROL Ū/D RC Ū/D  $\overline{\mathsf{RC}}$ Ū/D  $\overline{\mathsf{RC}}$ ENABLE -Œ CE Œ СР СР СР CLOCK aaa-024380 Fig. 6. Synchronous n-stage counter using ripple carry/borrow

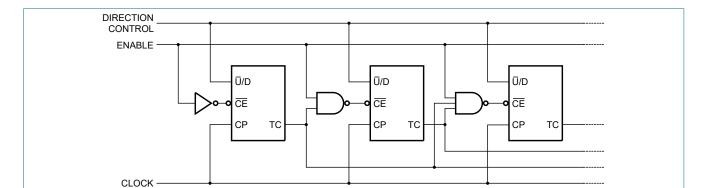
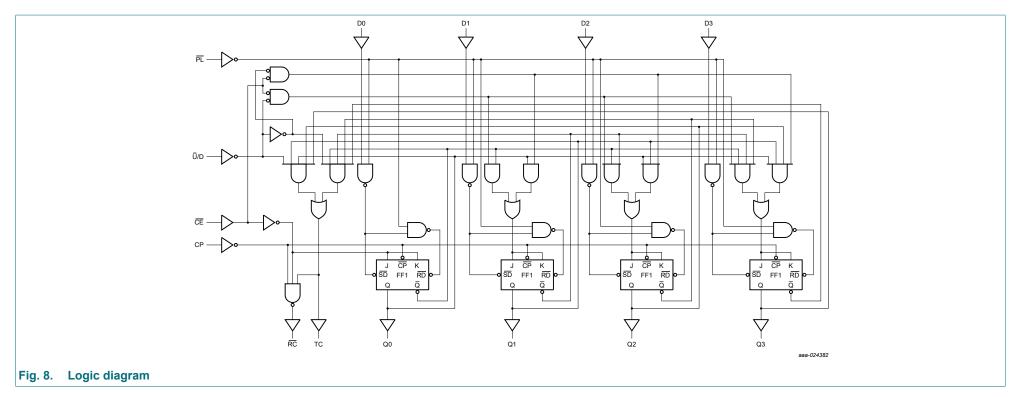


Fig. 7. Synchronous n-stage counter with parallel gated carry/borrow

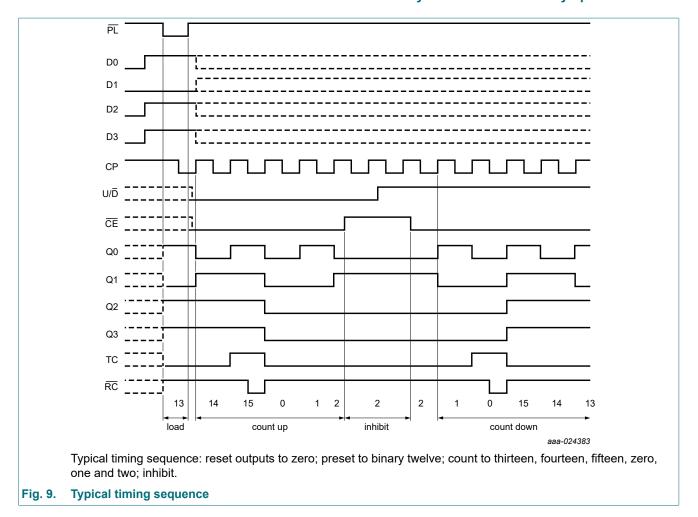
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### Presettable synchronous 4-bit binary up/down counter



5 / 19

### Presettable synchronous 4-bit binary up/down counter



# 7. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC</sub>	supply voltage		-0.5	+7.0	V
I <sub>IK</sub>	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{CC} + 0.5 \text{ V}$	-	±20	mA
I <sub>OK</sub>	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{CC} + 0.5 \text{ V}$	-	±20	mA
I <sub>O</sub>	output current	$V_{O} = -0.5 \text{ V to } V_{CC} + 0.5 \text{ V}$	-	±25	mA
I <sub>CC</sub>	supply current		-	50	mA
I <sub>GND</sub>	ground current		-50	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	[1]	-	500	mW

<sup>[1]</sup> For SOT109-1 (SO16) packages: P<sub>tot</sub> derates linearly with 12.4 mW/K above 110 °C. For SOT338-1 (SSOP16) packages: P<sub>tot</sub> derates linearly with 8.5 mW/K above 91 °C. For SOT403-1 (TSSOP16) packages: P<sub>tot</sub> derates linearly with 8.5 mW/K above 91 °C.

### Presettable synchronous 4-bit binary up/down counter

# 8. Recommended operating conditions

#### Table 6. Recommended operating conditions

Voltages are referenced to GND (ground = 0 V)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>CC</sub>	supply voltage		2.0	5.0	6.0	V
VI	input voltage		0	-	V <sub>CC</sub>	V
Vo	output voltage		0	-	V <sub>CC</sub>	V
T <sub>amb</sub>	ambient temperature		-40	+25	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CC</sub> = 2.0 V	-	-	625	ns/V
		V <sub>CC</sub> = 4.5 V	-	1.67	139	ns/V
		V <sub>CC</sub> = 6.0 V	-	-	83	ns/V

# 9. Static characteristics

#### **Table 7. Static characteristics**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		25 °C		-40 °C to	o +85 °C	-40 °C to	+125 °C	Unit
			Min	Тур	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	V <sub>CC</sub> = 2.0 V	1.5	1.2	-	1.5	-	1.5	-	V
	input voltage	V <sub>CC</sub> = 4.5 V	3.15	2.4	-	3.15	-	3.15	-	V
		V <sub>CC</sub> = 6.0 V	4.2	3.2	-	4.2	-	4.2	-	V
V <sub>IL</sub>	LOW-level input voltage	V <sub>CC</sub> = 2.0 V	-	0.8	0.5	-	0.5	-	0.5	V
		V <sub>CC</sub> = 4.5 V	-	2.1	1.35	-	1.35	-	1.35	V
		V <sub>CC</sub> = 6.0 V	-	2.8	1.8	-	1.8	-	1.8	V
V <sub>OH</sub> HIGH-level	V <sub>I</sub> = V <sub>IH</sub> or V <sub>IL</sub>									
	output voltage	I <sub>O</sub> = -20 μA; V <sub>CC</sub> = 2.0 V	1.9	2.0	-	1.9	-	1.9	-	V
		I <sub>O</sub> = -20 μA; V <sub>CC</sub> = 4.5 V	4.4	4.5	-	4.4	-	4.4	-	V
		I <sub>O</sub> = -20 μA; V <sub>CC</sub> = 6.0 V	5.9	6.0	-	5.9	-	5.9	-	V
		I <sub>O</sub> = -4.0; V <sub>CC</sub> = 4.5 V	3.98	4.32	-	3.84	-	3.7	-	V
		I <sub>O</sub> = -5.2; V <sub>CC</sub> = 6.0 V	5.48	5.81	-	5.34	-	5.2	-	V
V <sub>OL</sub>	LOW-level	V <sub>I</sub> = V <sub>IH</sub> or V <sub>IL</sub>								
	output voltage	I <sub>O</sub> = 20 μA; V <sub>CC</sub> = 2.0 V	-	0	0.1	-	0.1	-	0.1	V
		I <sub>O</sub> = 20 μA; V <sub>CC</sub> = 4.5 V	-	0	0.1	-	0.1	-	0.1	V
		I <sub>O</sub> = 20 μA; V <sub>CC</sub> = 6.0 V	-	0	0.1	-	0.1	-	0.1	V
		I <sub>O</sub> = 4.0 mA; V <sub>CC</sub> = 4.5 V	-	0.15	0.26	-	0.33	-	0.4	V
		I <sub>O</sub> = 5.2 mA; V <sub>CC</sub> = 6.0 V	-	0.16	0.26	-	0.33	-	0.4	V
I <sub>I</sub>	input leakage current	$V_I = V_{CC}$ or GND; $V_{CC} = 6.0 \text{ V}$	-	-	±0.1	-	±1.0	-	±1.0	μΑ
I <sub>CC</sub>	supply current	$V_I = V_{CC}$ or GND; $I_O = 0$ A; $V_{CC} = 6.0 \text{ V}$	-	-	8.0	-	80.0	-	160.0	μΑ
C <sub>I</sub>	input capacitance		-	3.5	-	-	-	-	-	pF

### Presettable synchronous 4-bit binary up/down counter

# 10. Dynamic characteristics

**Table 8. Dynamic characteristics** 

Voltages are referenced to GND (ground = 0 V);  $C_L$  = 50 pF unless otherwise specified; for test circuit see Fig. 18.

Symbol	Parameter	Conditions		25 °C		-40 °C to	+85 °C	-40 °C to +125 °C		Unit
			Min	Тур	Max	Min	Max	Min	Max	
t <sub>pd</sub>	propagation	CP to Qn; see Fig. 10 [1]								
	delay	V <sub>CC</sub> = 2.0 V	-	72	220	-	275	-	330	ns
		V <sub>CC</sub> = 4.5 V	-	26	44	-	55	-	66	ns
		V <sub>CC</sub> = 5.0 V; C <sub>L</sub> = 15 pF	-	22	-	-	-	-	-	ns
		V <sub>CC</sub> = 6.0 V	-	21	37	-	47	-	56	ns
		CP to TC; see Fig. 10								
		V <sub>CC</sub> = 2.0 V	-	83	255	-	320	-	395	ns
		V <sub>CC</sub> = 4.5 V	-	30	51	-	64	-	77	ns
		V <sub>CC</sub> = 6.0 V	-	24	43	-	54	-	65	ns
		CP to RC; see Fig. 11								
		V <sub>CC</sub> = 2.0 V	-	47	150	-	190	-	225	ns
		V <sub>CC</sub> = 4.5 V	-	17	30	-	38	-	45	ns
		V <sub>CC</sub> = 6.0 V	-	14	26	-	33	-	38	ns
		CE to RC; see Fig. 11								
		V <sub>CC</sub> = 2.0 V	-	33	130	-	165	-	195	ns
		V <sub>CC</sub> = 4.5 V	-	12	26	-	33	-	39	ns
		V <sub>CC</sub> = 6.0 V	-	10	22	-	28	-	33	ns
		Dn to Qn; see Fig. 12								
		V <sub>CC</sub> = 2.0 V	-	61	220	-	275	-	330	ns
		V <sub>CC</sub> = 4.5 V	-	22	44	-	55	-	66	ns
		V <sub>CC</sub> = 6.0 V	-	18	37	-	47	-	56	ns
		PL to Qn; see Fig. 13								
		V <sub>CC</sub> = 2.0 V	-	61	220	-	275	-	330	ns
		V <sub>CC</sub> = 4.5 V	-	22	44	-	55	-	66	ns
		V <sub>CC</sub> = 6.0 V	-	18	37	-	47	-	56	ns
		Ū/D to TC; see <u>Fig. 14</u>								
		V <sub>CC</sub> = 2.0 V	-	44	190	-	240	-	285	ns
		V <sub>CC</sub> = 4.5 V	-	16	38	-	48	-	57	ns
		V <sub>CC</sub> = 6.0 V	-	13	32	-	41	-	48	ns
		Ū/D to RC; see <u>Fig. 14</u>								
		V <sub>CC</sub> = 2.0 V	-	50	210	-	265	-	315	ns
		V <sub>CC</sub> = 4.5 V	-	18	42	-	53	-	63	ns
		V <sub>CC</sub> = 6.0 V	-	14	36	-	45	-	54	ns
t <sub>t</sub>	transition	see <u>Fig. 15</u> [2]								
	time	V <sub>CC</sub> = 2.0 V	-	19	75	-	95	-	110	ns
		V <sub>CC</sub> = 4.5 V	-	7	15	-	19	-	22	ns
		V <sub>CC</sub> = 6.0 V	-	6	13	-	16	-	19	ns

# Presettable synchronous 4-bit binary up/down counter

Symbol	Parameter	Conditions		25 °C		-40 °C to	+85 °C	-40 °C to +125 °C		Unit
			Min	Тур	Max	Min	Max	Min	Max	1
t <sub>W</sub>	pulse width	CP; HIGH or LOW; see Fig. 10								
		V <sub>CC</sub> = 2.0 V	125	28	-	155	-	195	-	ns
		V <sub>CC</sub> = 4.5 V	25	10	-	31	-	39	-	ns
		V <sub>CC</sub> = 6.0 V	21	8	-	26	-	33	-	ns
		PL; LOW; see Fig. 15								
		V <sub>CC</sub> = 2.0 V	100	22	-	125	-	150	-	ns
		V <sub>CC</sub> = 4.5 V	20	8	-	25	-	30	-	ns
		V <sub>CC</sub> = 6.0 V	17	6	-	21	-	26	-	ns
t <sub>rec</sub>	recovery	PL to CP; see Fig. 15								
	time	V <sub>CC</sub> = 2.0 V	35	8	-	45	-	55	-	ns
		V <sub>CC</sub> = 4.5 V	7	3	-	9	-	11	-	ns
		V <sub>CC</sub> = 6.0 V	6	2	-	8	-	9	-	ns
t <sub>su</sub>	t <sub>su</sub> set-up time	Ū/D to CP; see <u>Fig. 16</u>								
		V <sub>CC</sub> = 2.0 V	205	50	-	255	-	310	-	ns
		V <sub>CC</sub> = 4.5 V	41	18	-	51	-	62	-	ns
		V <sub>CC</sub> = 6.0 V	35	14	-	43	-	53	-	ns
		Dn to PL; see Fig. 17								
		V <sub>CC</sub> = 2.0 V	100	19	-	125	-	150	-	ns
		V <sub>CC</sub> = 4.5 V	20	7	-	25	-	30	-	ns
		V <sub>CC</sub> = 6.0 V	17	6	-	21	-	26	-	ns
		CE to CP; see Fig. 16								
		V <sub>CC</sub> = 2.0 V	140	44	-	175	-	210	-	ns
		V <sub>CC</sub> = 4.5 V	28	16	-	35	-	42	-	ns
		V <sub>CC</sub> = 6.0 V	24	13	-	30	-	36	-	ns
t <sub>h</sub>	hold time	Ū/D to CP; see <u>Fig. 16</u>								
		V <sub>CC</sub> = 2.0 V	0	-39	-	0	-	0	-	ns
		V <sub>CC</sub> = 4.5 V	0	-14	-	0	-	0	-	ns
		V <sub>CC</sub> = 6.0 V	0	-11	-	0	-	0	-	ns
		Dn to PL; see Fig. 17								
		V <sub>CC</sub> = 2.0 V	0	-11	-	0	-	0	-	ns
		V <sub>CC</sub> = 4.5 V	0	-4	-	0	-	0	-	ns
		V <sub>CC</sub> = 6.0 V	0	-3	-	0	-	0	-	ns
		CE to CP; see Fig. 16								
		V <sub>CC</sub> = 2.0 V	0	-28	-	0	-	0	-	ns
		V <sub>CC</sub> = 4.5 V	0	-10	-	0	-	0	-	ns
		V <sub>CC</sub> = 6.0 V	0	-8	-	0	-	0	-	ns
f <sub>max</sub>	maximum	CP; see Fig. 10								
	frequency	V <sub>CC</sub> = 2.0 V	4.0	11	-	3.2	-	2.6	-	MHz
		V <sub>CC</sub> = 4.5 V	20	33	-	16	-	13	-	MHz
		V <sub>CC</sub> = 5.0 V; C <sub>L</sub> = 15 pF	-	36	-	-	-	-	-	MHz
		V <sub>CC</sub> = 6.0 V	24	39	-	19	-	15	-	MHz

#### Presettable synchronous 4-bit binary up/down counter

Symbol	Parameter	Conditions	25 °C		-40 °C to +85 °C		-40 °C to +125 °C		Unit	
			Min	Тур	Max	Min	Max	Min	Max	
C <sub>PD</sub>		$V_I = GND \text{ to } V_{CC}; V_{CC} = 5 \text{ V};$ [3] $f_i = 1 \text{ MHz}$	-	31	-	-	-	-	-	pF

- [1]  $t_{pd}$  is the same as  $t_{PHL}$  and  $t_{PLH}$ .
- [2] t<sub>t</sub> is the same as t<sub>THL</sub> and t<sub>TLH</sub>.
- [3]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu$ W):

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \sum (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

f<sub>o</sub> = output frequency in MHz;

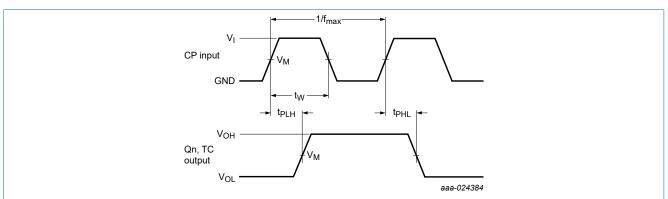
C<sub>L</sub> = output load capacitance in pF;

V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\sum (C_L \times V_{CC}^2 \times f_o) = \text{sum of outputs.}$ 

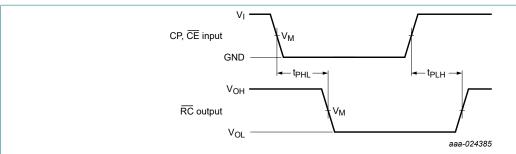
#### 10.1. Waveforms and test circuit



Measurement points are given in Table 9.

Logic levels  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig. 10. The clock input (CP) to outputs (Qn, TC) propagation delays, clock pulse width and maximum clock frequency

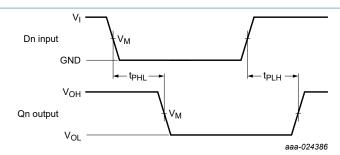


Measurement points are given in Table 9.

Logic levels  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig. 11. The clock and count enable inputs (CP,  $\overline{\text{CE}}$ ) to ripple clock output ( $\overline{\text{RC}}$ ) propagation delays

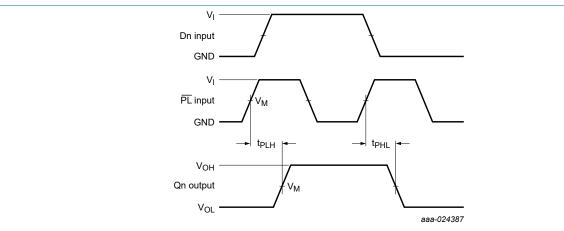
#### Presettable synchronous 4-bit binary up/down counter



Measurement points are given in Table 9.

Logic levels  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

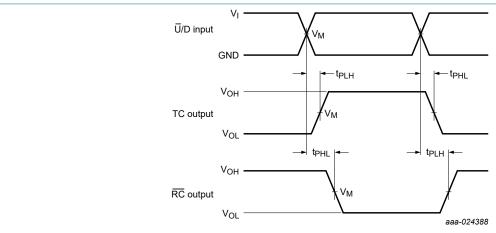
Fig. 12. The input (Dn) to output (Qn) propagation delays



Measurement points are given in Table 9.

Logic levels  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig. 13. The parallel load input (PL) to output (Qn) propagation delays

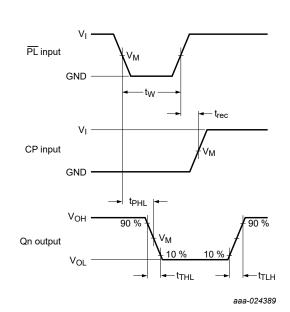


Measurement points are given in Table 9.

Logic levels V<sub>OL</sub> and V<sub>OH</sub> are typical output voltage levels that occur with the output load.

Fig. 14. The up/down count input (U/D) to terminal count and ripple clock output (TC, RC) propagation delays

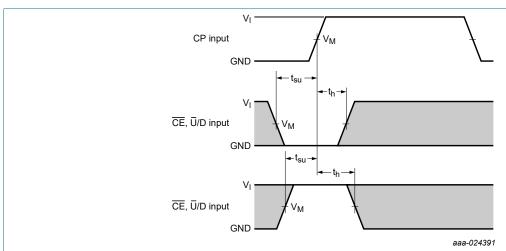
### Presettable synchronous 4-bit binary up/down counter



Measurement points are given in Table 9.

Logic levels  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig. 15. The parallel load input (PL) to clock (CP) recovery times, parallel load pulse width and output (Qn) transition times

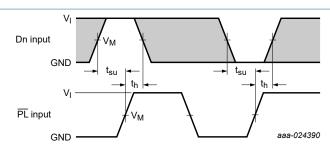


Measurement points are given in Table 9.

The shaded areas indicate when the input is permitted to change for predictable output performance.

Fig. 16. The count enable and up/down count inputs ( $\overline{CE}$ ,  $\overline{U}/D$ ) to clock input (CP) set-up and hold times

#### Presettable synchronous 4-bit binary up/down counter



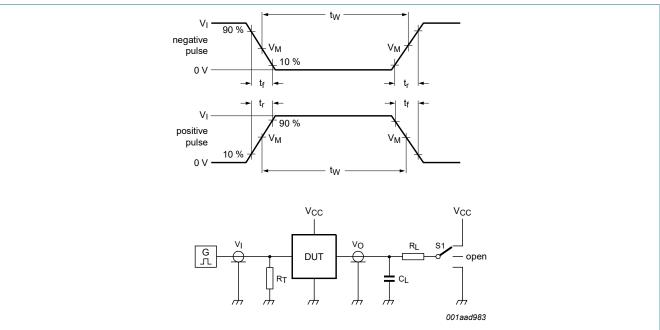
Measurement points are given in Table 9.

The shaded areas indicate when the input is permitted to change for predictable output performance.

Fig. 17. The parallel load input (PL) to data input (Dn) set-up and hold times

**Table 9. Measurement points** 

Input	Output	
V <sub>M</sub>	V <sub>I</sub>	V <sub>M</sub>
0.5 x V <sub>CC</sub>	GND to V <sub>CC</sub>	0.5 x V <sub>CC</sub>



Test data is given in Table 10.

Test circuit definitions:

 $R_T$  = Termination resistance should be equal to output impedance  $Z_o$  of the pulse generator

 $C_L$  = Load capacitance including jig and probe capacitance

R<sub>L</sub> = Load resistance.

S1 = Test selection switch

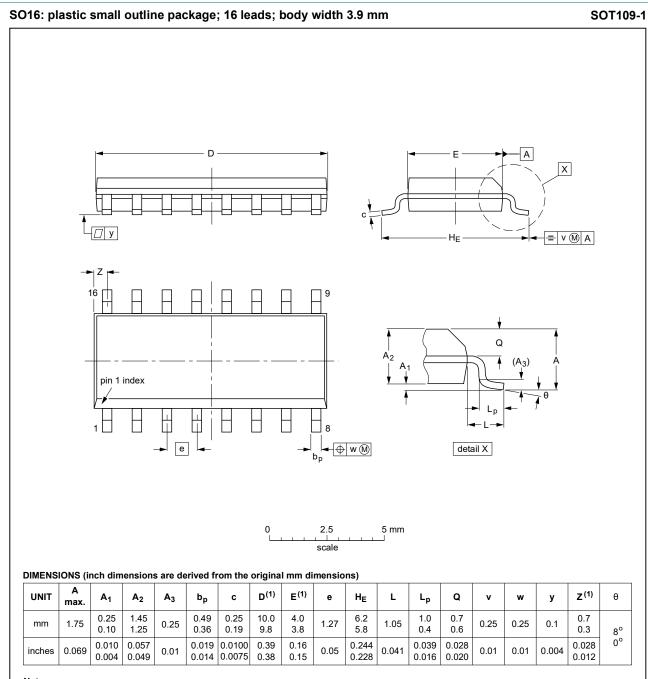
Fig. 18. Test circuit for measuring switching times

#### Table 10. Test data

Input		Load	S1 position	
V <sub>I</sub>	t <sub>r</sub> , t <sub>f</sub>	C <sub>L</sub> R <sub>L</sub> t		t <sub>PHL</sub> , t <sub>PLH</sub>
$V_{CC}$	6 ns	15 pF, 50 pF	1 kΩ	open

#### Presettable synchronous 4-bit binary up/down counter

# 11. Package outline



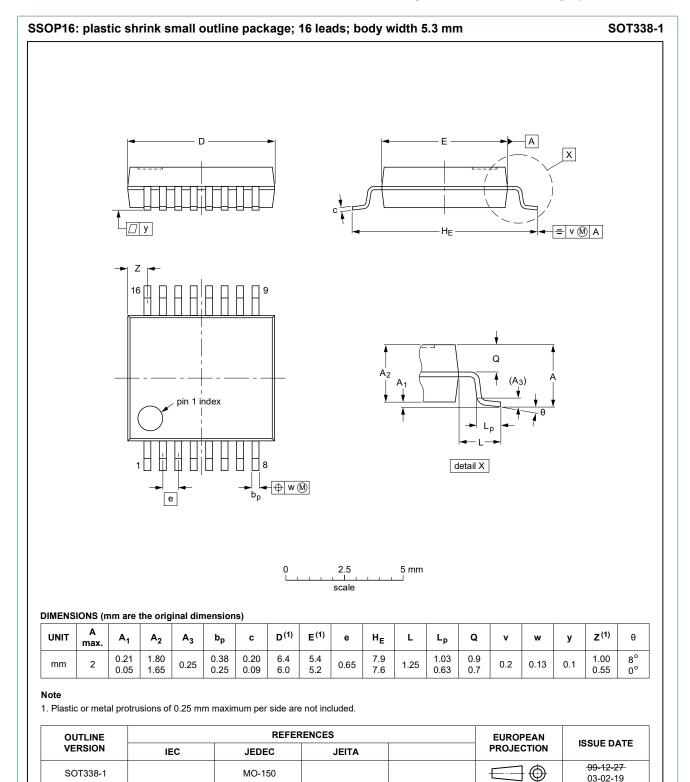
#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE	REFERENCES				EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT109-1	076E07	MS-012				<del>99-12-27</del> 03-02-19

Fig. 19. Package outline SOT109-1 (SO16)

## Presettable synchronous 4-bit binary up/down counter

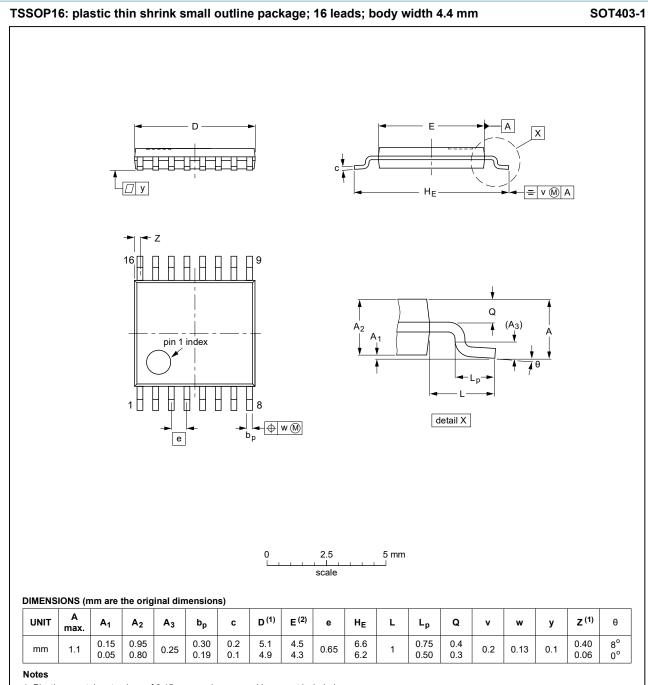


### Fig. 20. Package outline SOT338-1 (SSOP16)

15 / 19

03-02-19

### Presettable synchronous 4-bit binary up/down counter



- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFERENCES				EUROPEAN	ISSUE DATE
VERSIO	N	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT403	-1		MO-153				<del>99-12-27</del> 03-02-18

Fig. 21. Package outline SOT403-1 (TSSOP16)

### Presettable synchronous 4-bit binary up/down counter

# 12. Abbreviations

#### **Table 11. Abbreviations**

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model

# 13. Revision history

### Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes	
74HC191 v.5	20190813	Product data sheet	-	74HC191 v.4	
Modifications:	<ul> <li>Type number 74HC191DB (SOT338-1 / SSOP16) added.</li> <li>Table 5: Derating values for P<sub>tot</sub> total power dissipation updated</li> </ul>				
74HC191 v.4	20181005	Product data sheet	-	74HC191 v.3	
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type number 74HC191DB (SOT338-1 / SSOP16) removed.</li> </ul>				
74HC191 v.3	20170103	Product data sheet	-	74HC_HCT191 v.2	
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type numbers 74HCT191D, 74HCT191DB, 74HCT191PW removed.</li> </ul>				
74HC_HCT191_CNV v.2	19901201	Product specification	-	-	

#### Presettable synchronous 4-bit binary up/down counter

# 14. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <a href="https://www.nexperia.com">https://www.nexperia.com</a>.

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### Presettable synchronous 4-bit binary up/down counter

# **Contents**

1. General description	1
2. Features and benefits	1
3. Ordering information	2
4. Functional diagram	2
5. Pinning information	2
5.1. Pinning	2
5.2. Pin description	3
6. Functional description	3
7. Limiting values	6
8. Recommended operating conditions	7
9. Static characteristics	
10. Dynamic characteristics	8
10.1. Waveforms and test circuit	10
11. Package outline	14
12. Abbreviations	
13. Revision history	
14. Legal information	
-	

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