

#### FEATURES

- Low Noise:  
-128.9dBu (1.9nV/√Hz) EIN@60dB gain
- Low THD+N:  
0.001% ≤ 40 dB gain  
0.006% @ 60 dB gain
- Low Current: 7.0 mA typ
- Wide Bandwidth: 1.7MHz @40dB gain
- High Slew Rate: 50 V/μs
- Wide Output Signal Swing: > +28dBu
- Gain adjustable from 0 to >60 dB
- Differential output
- Small 4 x 4mm QFN16 package
- Mates with THAT's family of Digital Pre-amplifier Controller ICs

#### APPLICATIONS

- Microphone Preamplifiers
- Digitally-Controlled Microphone Preamplifiers
- Differential Low-Noise Preamplifiers
- Differential Summing Amplifiers
- Differential Variable-Gain Amplifiers
- Moving-Coil Transducer Amplifiers
- Line Input Stages
- Audio
- Sonar
- Instrumentation

#### Description

The THAT 1583 is a versatile, high performance current-feedback amplifier suitable for differential microphone preamplifier and bus summing applications. It improves on previous, traditional current-feedback designs (viz. THAT's 1510 & 1512) by offering a more versatile configuration that can yield lower noise at low gains, lower distortion overall, and higher slew rate.

Amplifier gain is determined by three external resistors ( $R_A$ ,  $R_B$ , and  $R_G$ ). This makes it possible to optimize noise and bandwidth over a wide range of gains, as well as optimize the taper of gain vs. rotation in variable-gain, pot-controlled applications.

The 1583's differential output simplifies connections to differential input devices such as A/D converters. When required, designers are free to

optimize the output differential amplifier to suit the specific application.

In analog variable-gain applications the part supports the traditional approach using fixed  $R_A$  and  $R_B$  and a single-section variable element for  $R_G$ . But, it also supports a dual-element alternative that offers improved performance.

In addition to analog-controlled applications, the 1583 is designed to mate perfectly with THAT's series of Digital Preamplifier Controller ICs to produce an optimized, digitally controlled preamplifier.

The 1583 operates from as little as  $\pm 5$  V up through  $\pm 18$  V supplies. It accepts greater than +28 dBu input signals at unity gain when operated from  $\pm 18$  V supplies.

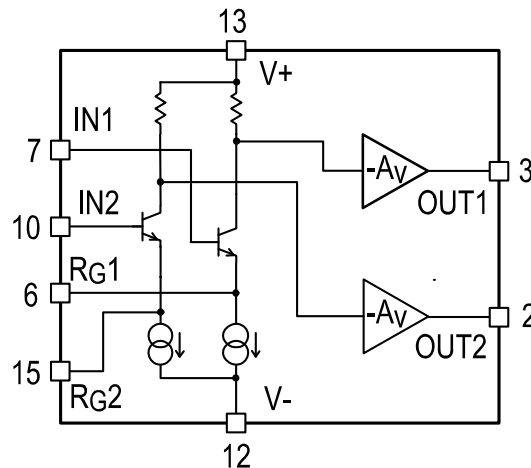


Figure 1. THAT1583 Block Diagram

**SPECIFICATIONS<sup>1</sup>****Absolute Maximum Ratings<sup>2</sup>**

Supply Voltage (V+) - (V-)	40 V	Output Short-Circuit Duration,	
Maximum Input Voltage (V <sub>IMax</sub> )	(V+) +0.5V to (V-) -0.5V	between outputs and/or GND (t <sub>SH</sub> )	Continuous
Storage Temperature Range (T <sub>STG</sub> )	-40 to +125 °C	Junction Temperature (T <sub>JMAX</sub> )	+125 °C
Operating Temperature Range (T <sub>OP</sub> )	-40 to +85 °C		

**Electrical Characteristics<sup>3,4,5</sup>**

Parameter	Symbol	Conditions	Min	Typ	Max	Units
<b>Power Supply</b>						
Supply Voltage	V+; -(V-)	Referenced to GND	5	—	18	V
Supply Current	I+; -(I-)	No Signal	—	7.0	10	mA
<b>Input Characteristics</b>						
Input Bias Current	I <sub>B</sub>	No signal; either input connected to GND	—	2.0	4.4	μA
Input Offset Current	I <sub>B-OFF</sub>	No signal;	-440	—	+440	nA
Differential Input Offset Voltage	V <sub>OS</sub>	No signal, Inputs connected to GND				
		0 dB gain	-15	—	+15	mV
		+60 dB gain	-450	—	+450	μV
Input Common Mode Voltage Range	V <sub>IN-CM</sub>	Common Mode	(V-) + 1.5	—	(V+) - 4	V
Maximum Differential Input Level	V <sub>IN-BAL</sub>	R <sub>G</sub> = ∞	—	26.4	—	dBu
		Supply Voltage ±18V	—	28.0	—	dBu
<b>Output Characteristics</b>						
Differential Output Offset		G = gain	-(15+0.45*G)	—	(15+0.45*G)	mV
Common Mode Offset Voltage	V <sub>OSCM</sub>	No signal	—	-630	—	mV
		IN1 and IN2 connected to GND				
Maximum Single Output Voltage	V <sub>OUT-SINGLE</sub>	G=20dB; R <sub>L</sub> = 2 kΩ	(V-) + 1.2	—	(V+) - 2	V
Differential Short Circuit Current	I <sub>SC</sub>	R <sub>L</sub> = 0 Ω	—	±70	—	mA
Maximum Capacitive Load	C <sub>L-MAX</sub>	Over entire temperature range	—	—	30	pF
		Stable operation 30% overshoot	—	75	—	pF
Maximum Differential Output Level	V <sub>OUT</sub>	R <sub>L</sub> = 2 kΩ	28	—	—	dBu
		Gain > 2 dB				

1. All specifications are subject to change without notice.

2. Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only; the functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

3. Unless otherwise noted, T<sub>A</sub> = 25°C, V+ = +15V, V- = -15V.

4. 0 dBu = 0.775 V<sub>rms</sub>

5. Unless otherwise noted, feedback resistors = 2.21 kΩ; C<sub>L</sub> = 10 pF. Circuit is as shown in Figure 12.

<b>Electrical Characteristics (con't)</b> <sup>3,4,5</sup>						
Parameter	Symbol	Conditions	Min	Typ	Max	Units
<b>AC Characteristics</b>						
Feedback Impedance	$R_A = R_B$	Refer to Figure 12	2	—	—	k $\Omega$
Differential Gain	$A_V$	Programmed by $R_A, R_B, R_G$ Refer to Figure 12	0	—	70	dB
Power Supply Rejection Ratio	PSRR	$V_+ = -(V_-); \pm 5V$ to $\pm 18V$	—	105	—	dB
		0 dB gain	—	116	—	dB
		20 dB gain	—	140	—	dB
		40 dB gain	—	140	—	dB
Bandwidth -3dB	$f_{-3dB}$	Small signal; $R_A=R_B=2.21k\Omega$ ; Refer to Figure 5	—	14	—	MHz
		0 dB gain	—	9	—	MHz
		20 dB gain	—	1.7	—	MHz
		40 dB gain	—	192	—	kHz
		Small signal; $R_G=\infty$ (0 dB gain)	—	16	—	MHz
		$R_A = R_B = 2 k\Omega$	—	4	—	MHz
		$R_A = R_B = 5 k\Omega$	—	1.6	—	MHz
Slew Rate	SR	$V_{OUT} = 10V_{P-P}; R_L=2k\Omega$ $C_L=30pF; G=20dB$	—	50	—	V/ $\mu$ s
Total Harmonic Distortion + Noise	THD + N	$V_{OUT} = 5V_{RMS}; R_L=2k\Omega; f=1kHz; BW=22kHz$	—	0.0006	—	%
		0 dB gain	—	0.0008	—	%
		20 dB gain	—	0.001	—	%
		40 dB gain	—	0.006	—	%
Equivalent Input Noise Voltage	$e_N$	Inputs connected to GND; $f=1kHz$ $R_A = R_B = 2.21k\Omega$ ; Refer to Figure 12	—	40	—	nV/ $\sqrt{Hz}$
		0 dB gain	—	5.7	—	nV/ $\sqrt{Hz}$
		20 dB gain	—	2.3	—	nV/ $\sqrt{Hz}$
		40 dB gain	—	1.9	—	nV/ $\sqrt{Hz}$
		60 dB gain	—	—	—	nV/ $\sqrt{Hz}$
		BW = 22kHz	—	—	—	dBu
		60 dB gain	—	-128.9	—	dBu
		A - weighted ; BW = 22kHz	—	-131.2	—	dBu
		60 dB gain	—	-126.5	—	dBu
Inputs connected to 150 $\Omega$ ; BW = 22kHz	—	—	—	dBu		
60 dB gain	—	-126.5	—	dBu		
Inputs connected to 150 $\Omega$ ; A - weighted	—	—	—	dBu		
60 dB gain	—	-129.3	—	dBu		
Equivalent Input Noise Current	$i_N$	$f = 1kHz; 60 dB$ gain	—	0.8	—	pA/ $\sqrt{Hz}$
Noise Figure	NF	60 dB gain; Source impedance = 150 $\Omega$	—	3.9	—	dB

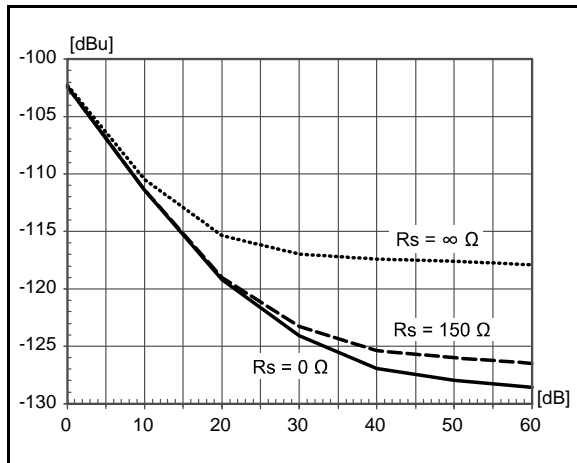


Figure 2. Equivalent Input Noise vs Gain and Source Impedance; BW: 22Hz to 22kHz

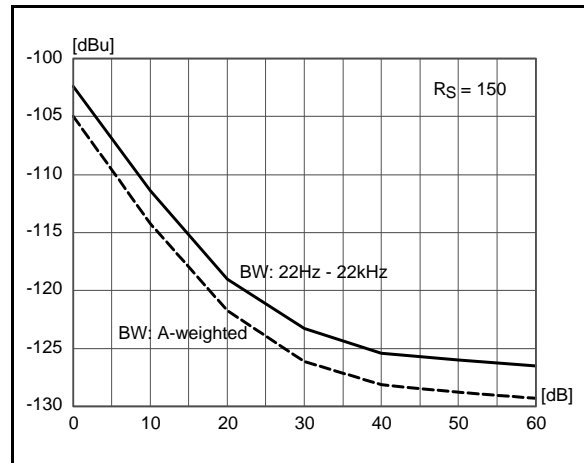


Figure 3. Equivalent Input Noise vs Gain and Bandwidth; Source Impedance 150Ω

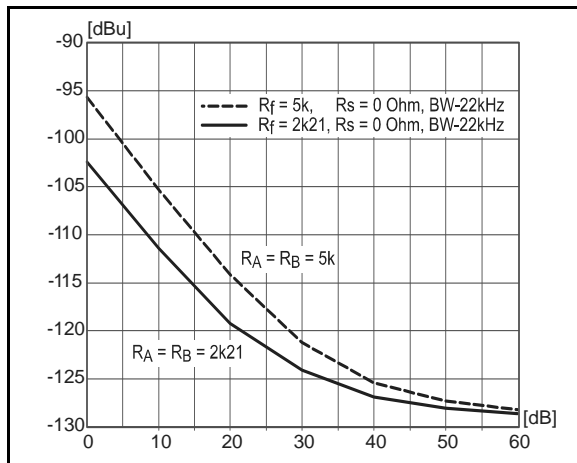


Figure 4. Equivalent Input Noise vs Gain and Feedback Impedance; BW: 22Hz to 22kHz

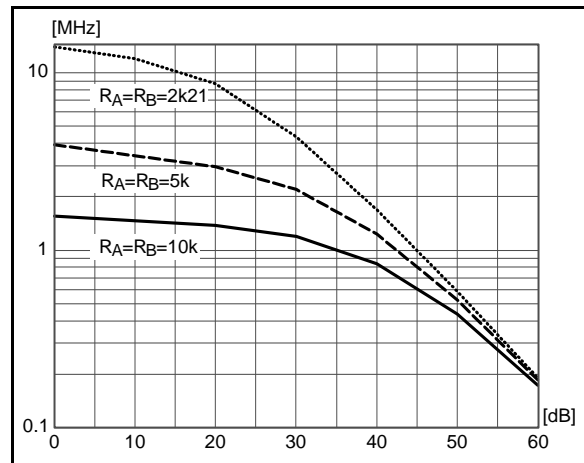


Figure 5. Bandwidth vs Gain and Feedback Impedance

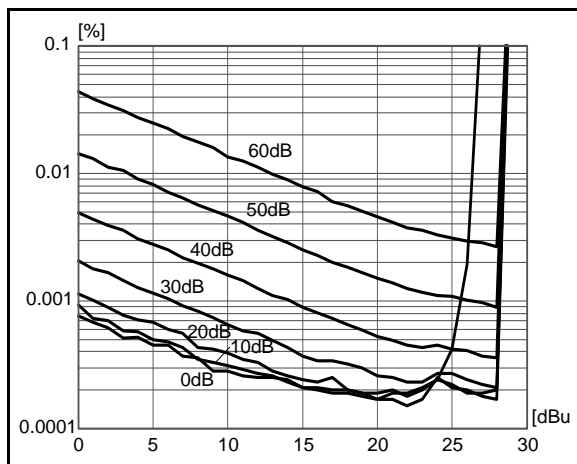


Figure 6. THD+ Noise vs Level

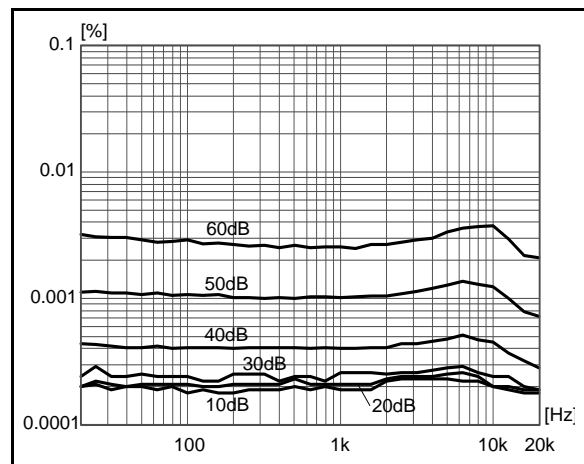


Figure 7. THD + Noise vs Frequency;  $V_{out} = 27\text{dBu}$ ,  $R_L = 10\text{k}\Omega$

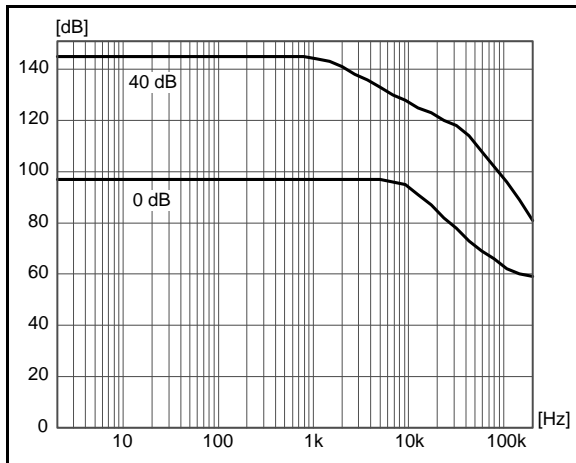


Figure 8. Power Supply Rejection vs Frequency

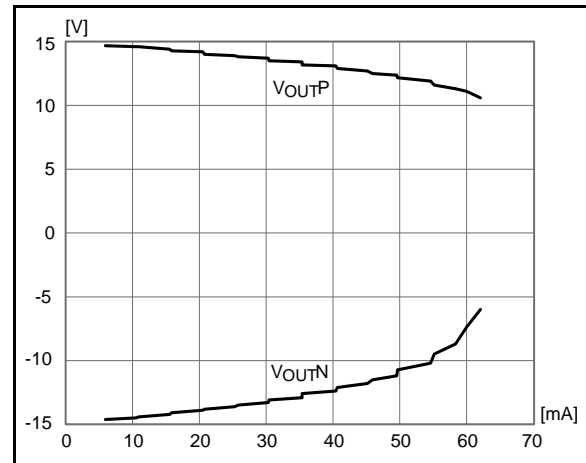


Figure 9. Maximum Output Voltage vs Output Current

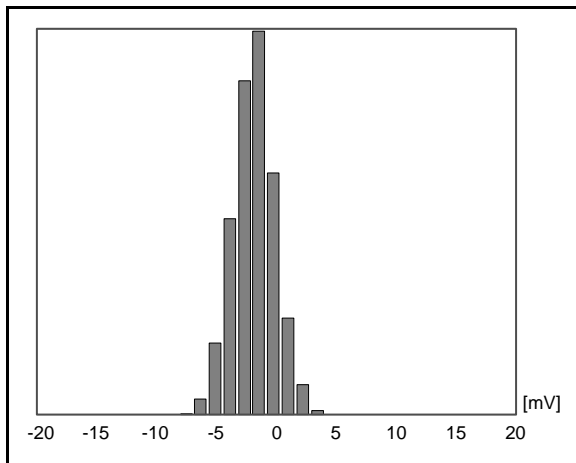


Figure 10. Representative Output Offset Voltage  
Distribution, 0dB Gain

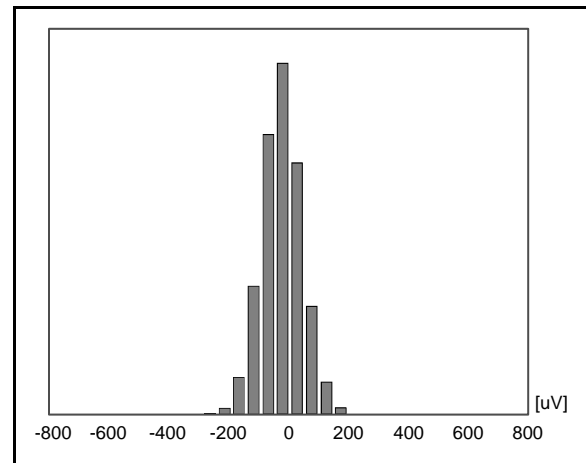


Figure 11. Representative Input Offset Voltage  
Distribution, 60dB Gain

## Theory of Operation

### Amplifier Overview

Referring to Figure 12, the THAT1583's differential voltage gain ( $G$ ) is set by the feedback resistors ( $R_A$  and  $R_B$ ) and  $R_G$ , as shown in the following equation. The amplifier's minimum gain is unity (0 dB), which occurs with infinite  $R_G$ . The feedback resistors should nominally be equal, though tight tolerance matching is not required.

$$G = 1 + \frac{R_A + R_B}{R_G}$$

In low-noise current-feedback amplifiers like the 1583, many performance characteristics depend critically on the impedance of the feedback network ( $R_A$ ,  $R_B$ , and  $R_G$ ).

The 1583 (and 1570) offers a novel approach to an integrated microphone preamplifier in that all three gain resistors are external. This gives the designer freedom to select the optimal values for the best noise performance at the desired gain setting(s).

### Noise versus Gain

The noise performance of a preamplifier based on the 1583 is determined as the sum of several noise sources. These are as follows (refer to Figure 12 for component reference designators):

1. the amplifier's own input voltage noise;
2. the voltage noise of the gain-setting resistor network ( $R_G$  in parallel with  $R_A$  and  $R_B$ );
3. the voltage noise of the external source impedance, connected to the 1583's input ( $R_M$  in parallel with  $R_1 + R_2$ );
4. the current noise from IN+ and IN-, developed across the source impedance ( $R_M$  in parallel with  $R_1 + R_2$ ), and
5. the current noise from  $R_{G1}$  and  $R_{G2}$ , translated to a voltage when drawn across the equivalent impedance of the external gain-setting resistor network ( $R_G$  in parallel with  $R_A$  and  $R_B$ ).

Since all these sources are uncorrelated, mostly random (Gaussian) noise, these sources all add in root-mean-square fashion. But which one is most important changes with gain, so predicting how noise varies can be complex.

A complete discussion of these sources and their interaction is beyond the scope of this data sheet. For more information, see "De-Integrating Integrated Circuit Preamps", available from THAT Corporation's web site, especially pages 13 through 20. Look for more details in a forthcoming application note as well. However, the following discussion covers the highlights.

At high gains (above 40dB or so), the system noise is typically dominated by the first three factors in the above list. At high gains, for practical values of  $R_A$ ,  $R_B$ , and  $R_G$  (where  $R_G$  is typically less 100 $\Omega$ ) and typical external source impedances (microphones are

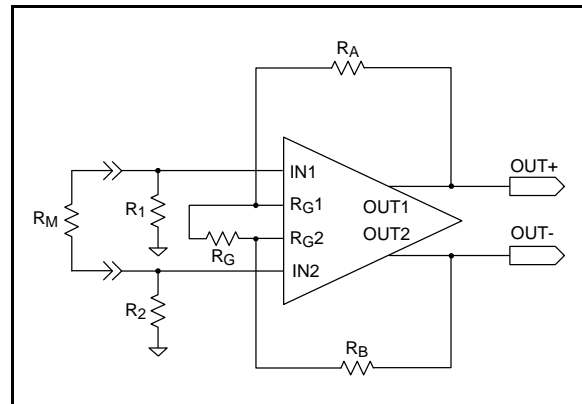


Figure 12. Simple THAT1583 Amplifier Circuit

generally around 150 $\Omega$ ), the amplifier's input voltage noise will be the largest contributor. However, at 1.9nV/ $\sqrt{\text{Hz}}$  (-128.9dBu unweighted, 22kHz bandwidth) the amplifier's own input noise is only 1.5dB higher than that of a 150 $\Omega$  microphone (-130.4dBu). So, the external source impedance  $R_M$  is a significant contributor to the total noise of the system.

At low gains (under about 20dB), the dominant noise sources are factors 2 and 5. An important case occurs at 0dB (unity) differential gain. In order to reach 0dB gain,  $R_G$  is open (infinite resistance). In this case, the current noise in  $R_{G1}$  and  $R_{G2}$  is drawn across the highest possible impedance ( $R_A$  and  $R_B$  alone, without any shunting effect of  $R_G$ ). The only way to mitigate this noise is to use lower values for  $R_A$  and  $R_B$ .

Of course, there is a continuum of relative importances here as gain goes from minimum (0dB) to maximum (over 70dB). As gain varies, the importance of each factor will vary in its own way, each contributing a different relative amount to the total. In general, to minimize low-gain noise, we suggest to keep  $R_A$  and  $R_B$  as small as possible.

Another perspective on noise performance is gained by measuring the noise using an A-weighting filter. Figure 3 compares equivalent input noise for various gains in a 22kHz bandwidth vs. using an A-weighting filter. The A-weighting filter improves input noise performance by about 3dB.

### Bandwidth

An important characteristic of current-feedback amplifiers is that the amplifier bandwidth is inversely proportional to the feedback resistance  $R_A$  and  $R_B$ . The bandwidth decreases with increasing feedback resistance. As mentioned before, the minimum value of  $R_A$  and  $R_B$  is determined by the amplifier's stability and can not be under any condition lower than 2k $\Omega$ . Figure 5 shows typical bandwidth versus gain for a few selected values of feedback resistance.

Note that the widest bandwidth may not always be the optimum condition. In digitally controlled applications using CMOS switches to vary gain, high bandwidth may allow charge injected by the switches to be amplified and sharp voltage spikes to appear at the output. Lower bandwidth can reduce this effect.

### Common Mode Gain

The amplifier common-mode gain is always unity (0 dB), regardless of the differential gain. So, any common-mode input signal, along with the amplifier's own common-mode dc offset, will be transferred faithfully without gain or attenuation to the output. The common-mode rejection ratio (CMRR) of the part will equal the differential gain, since differential signals are amplified while common-mode signals are not.

The largest impact of significant common-mode signals is to limit 1583's dynamic range, since they can cause premature clipping of the input and outputs. The same will be true for subsequent stages.

The 1583 output has a typical dc common mode offset of about -600mV. This constrains output headroom on negative signal peaks by 600mV. At high power supplies, the 600mV reduction of output swing may not matter. However, it has a more significant effect at the minimum power supply. If desired, a common-mode servo amplifier can be added to drive the outputs' common-mode voltage to 0V by lifting the inputs' bias to approximately +600mV. Note that it is more important to adjust the output to zero bias than the input, because the 1583's input voltage range is typically less than that for its output.

### Limiting Differential dc Gain

In the circuit of Figure 12, the amplifier's differential gain (G) extends to dc. As a result, the differential dc offset at the outputs will vary with gain. This can produce audible "thumps" when gain is varied quickly, and can produce significant and undesirable output dc offset at maximum gain. Any such offset will reduce the output voltage swing.

To see how important this is, suppose a particular 1583 has an input offset of 400  $\mu$ V and an output offset of 10mV. The output offset of that part would be 10.4mV at unity (0dB) gain. But, at 60dB gain, the output dc offset will be 410mV. If the gain is varied quickly, this ~400mV dc shift will be audible.

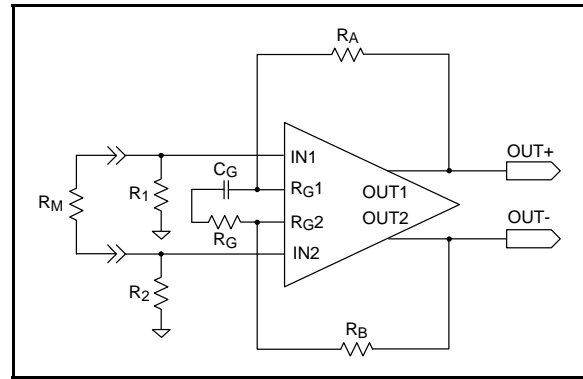


Figure 13. Simple THAT1583 Circuit with  $C_G$

This issue can be addressed by ac coupling  $R_G$  as shown in Figure 13 with capacitor  $C_G$ . The capacitor forces dc gain to unity regardless of the amplifier differential gain. This means the output's differential dc offset will not vary with gain. In the example above, adding  $C_G$  will set the output dc offset at 10.4mV regardless of the differential gain.

Note that the  $R_G$ - $C_G$  network forms a high-pass filter. The high-pass filter's -3dB corner frequency is determined by the following equation.

$$F_C = \frac{1}{2\pi R_G C_G}$$

Note that the cutoff varies with  $R_G$  and therefore with gain. It is highest with lowest  $R_G$  (which occurs at the highest gain). This can be a desirable effect in that at high gains it can significantly reduce the low frequency rumble and noise from wind or microphone handling.

Consider the circuits shown in Figure 14, which has a fixed and variable  $R_G$  ( $R_{GF}$  and  $R_{GV}$ ). At maximum gain (60dB),  $R_G = 10$  ohm. With  $C_G = 3,300\mu$ F, the high-pass corner frequency is approximately 5Hz. But, at minimum gain (6dB),  $R_G = 10$ k $\Omega$ . This drives the cutoff down to 0.005Hz. It may well be acceptable to reduce  $C_G$  by a factor of 10, to 330  $\mu$ F. In this case the high-pass corner would vary from 50Hz at 60dB gain to 0.05 Hz at 6 dB gain.

The dc voltage appearing across  $C_G$  is very small, less than 450  $\mu$ V, though its polarity will vary from sample to sample.  $C_G$  is usually a low voltage electrolytic type; 6.3V is generally sufficient. Since polarized electrolytic capacitors normally can withstand some small reverse bias,  $C_G$  can be a polarized capacitor.

## Applications

### Analog Gain Control

Traditional integrated microphone preamplifiers include the feedback resistors (e.g., the THAT1510 and THAT1512) and allow gain to be varied using an external single-element potentiometer. The 1583 supports a similar configuration in that the designer may select fixed feedback resistors ( $R_A$  and  $R_B$ ), and vary  $R_G$  as shown in Figure 14. This circuit provides a maximum gain of 60 dB (when  $R_G = 10\Omega$  because  $R_{GV} = 0\Omega$ ) and a minimum gain of 6 dB (when  $R_G = 10,010\Omega$  because  $R_{GV} = 10k\Omega$ ).

Refer to Figure 4 for typical noise versus gain with 5 k $\Omega$  feedback resistors ( $R_A$  and  $R_B$ ). Other minimum and maximum gains, and noise versus gain performance, can be accommodated by selecting different values of  $R_A$ ,  $R_B$ ,  $R_{GV}$  and  $R_{GF}$ . Typically, reverse log (audio) taper elements offer the desired behavior in gain versus rotation wherein gain increases with clockwise rotation.

An interesting and novel technique permitted by the 1583's "deconstructed" topology is to vary all three resistors simultaneously, as shown in Figure 15. Here, we use a dual-element potentiometer as the gain control. High gain occurs by decreasing  $R_G$  while simultaneously increasing the feedback resistances. There are a few advantages of this approach. First, the feedback resistances (and their associated noise contribution) will be reduced at low gains. Second, the value of  $R_G$  required to achieve high gains is higher. The larger resistance of  $R_G$  at maximum gain allows a smaller  $C_G$  for a given cutoff

at maximum gain than with a single-element control. This may also relax requirements for end resistance in the pot used. Third, the dual-element approach can improve the linearity of gain vs. pot rotation compared to a single-element solution, assuming the same taper in the pot. Fourth, the dual-element approach lends itself to a lower low-gain limit.

The circuit in Figure 14 has a gain range of 6dB to 60dB while the circuit shown in Figure 15 provides a gain range of 4.4dB to 60dB. The noise behavior of the two circuits is compared in Figure 16. Note the superior low-gain noise performance with the dual-element approach.

Again, other minimum and maximum gains and noise versus gain performance can be accommodated by selecting different values of gain resistances.

### Potentiometer Limitations and Gain Accuracy

Overall gain accuracy depends on the tolerance of the external gain resistors and especially the potentiometer. Theoretically, when the variable portion of  $R_G$  is zero for maximum gain, the gain is determined by the feedback resistors and fixed portion of  $R_G$ . However, in many instances the minimum resistance of the potentiometer (commonly specified as end resistance) will be greater than zero and can vary from part to part. Reducing the fixed portion of  $R_G$  by the amount of the end resistance may be appropriate if the potentiometer end-resistance is consistent. It may be easier to maintain consistency at high gains

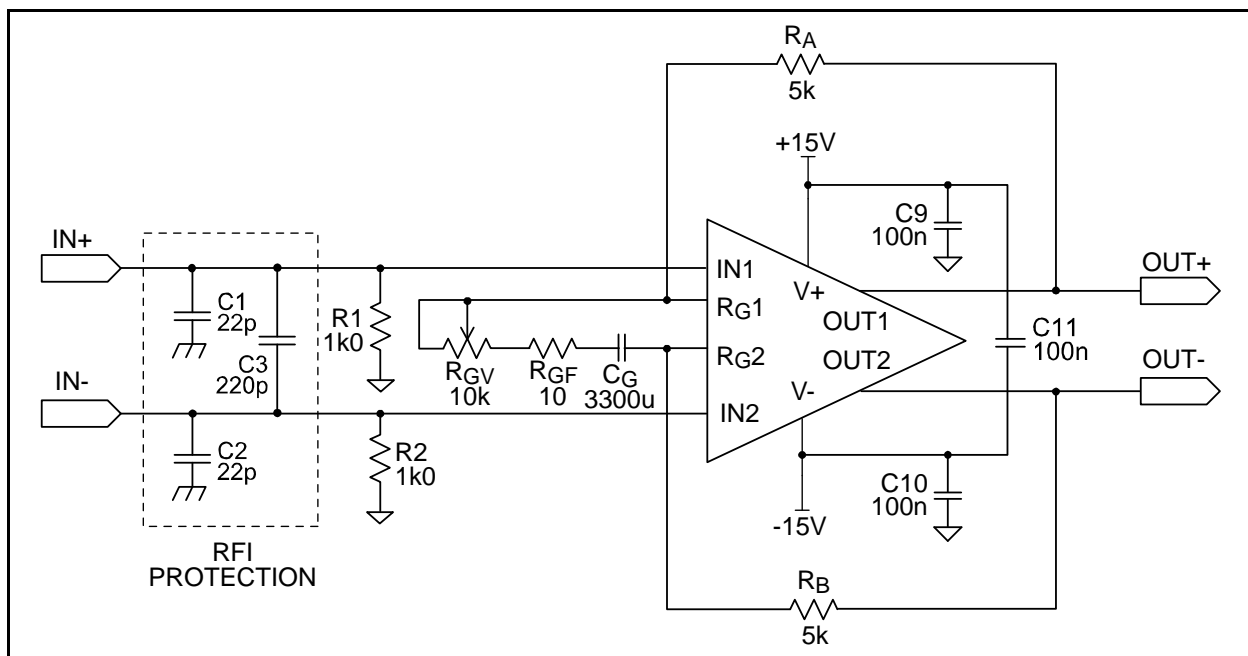


Figure 14. Basic Application Circuit With Variable  $R_G$  for Gain Control, ac-Coupled  $R_G$



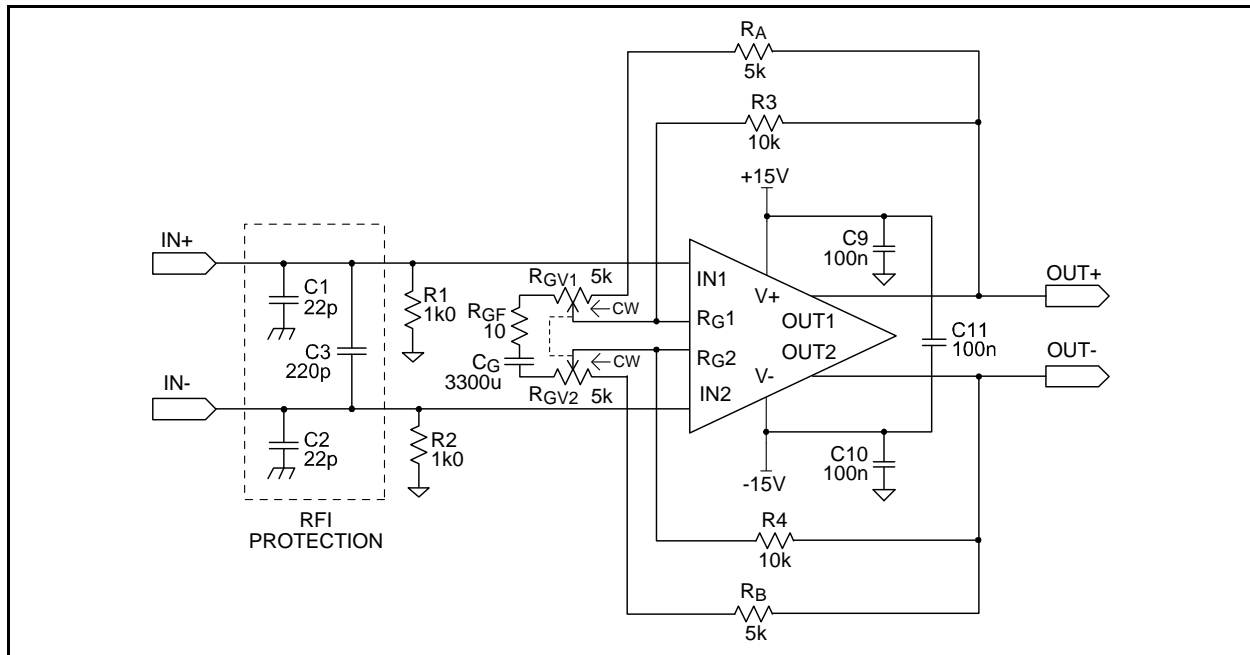


Figure 15. Basic Application Circuit With Variable Feedback Resistors and  $R_G$  for Gain Control, ac-Coupled  $R_G$

with larger values of feedback resistances, since this makes the required value of  $R_G$  proportionately larger for any given gain, and minimizes the effects of end resistance. For high-accuracy applications, consider discrete, switched resistors for  $R_A$ ,  $R_B$  and  $R_G$ .

As well, take care to specify the potentiometer's element construction to avoid excess noise.

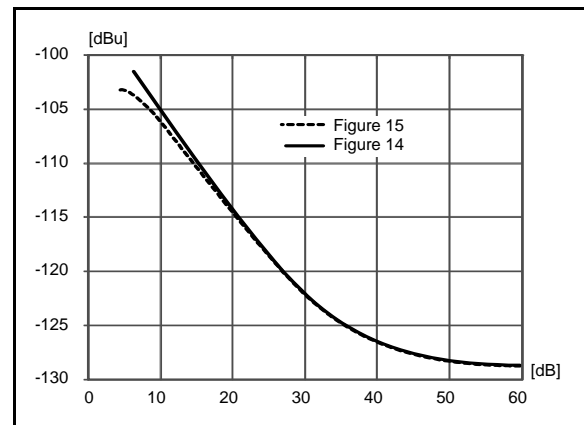


Figure 16. Noise vs Gain of circuits in Figures 14 and 15

### Digitally Controlled Gain

In addition to analog- controlled applications, the 1583 has been designed to mate perfectly with THAT's family of Digital Preamplifier Controller ICs to produce an optimized, digitally controlled audio preamplifier. THAT's digital controllers are intended primarily for use in the feedback loop of differential, current-feedback gain stages, such as the 1583.

Figure 17 shows a THAT5171 or 5173 Digital Controller connected to the 1583. The controller varies  $R_A$ ,  $R_B$  and  $R_G$  (from Figure 12) to produce the desired gain based on the gain command provided via the SPI control interface. The feedback network

impedances in these controller ICs have been chosen to minimize noise and distortion within the combined amplifier and controller at each gain step.

The controllers also include a differential servo amplifier which minimizes the differential dc offset at the output. The servo generates a correction voltage at the 1583 inputs which in turn reduces the output offset voltage. The output dc offset is controlled by the servo amplifier inside the controller, making  $C_G$  unnecessary, and enabling a more compact PCB design.

Please refer to the 5171 and 5173 data sheets for more information.

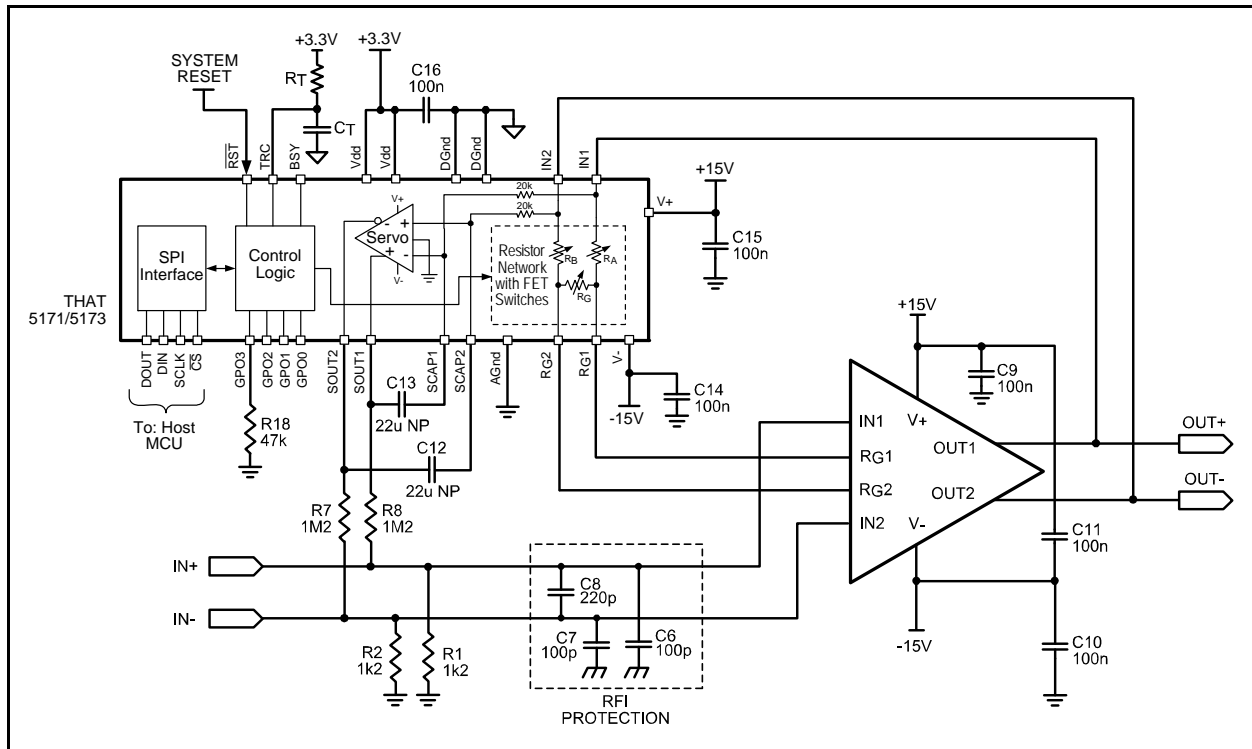


Figure 17. Basic Application Circuit With THAT 5171/5173 Digital Controller

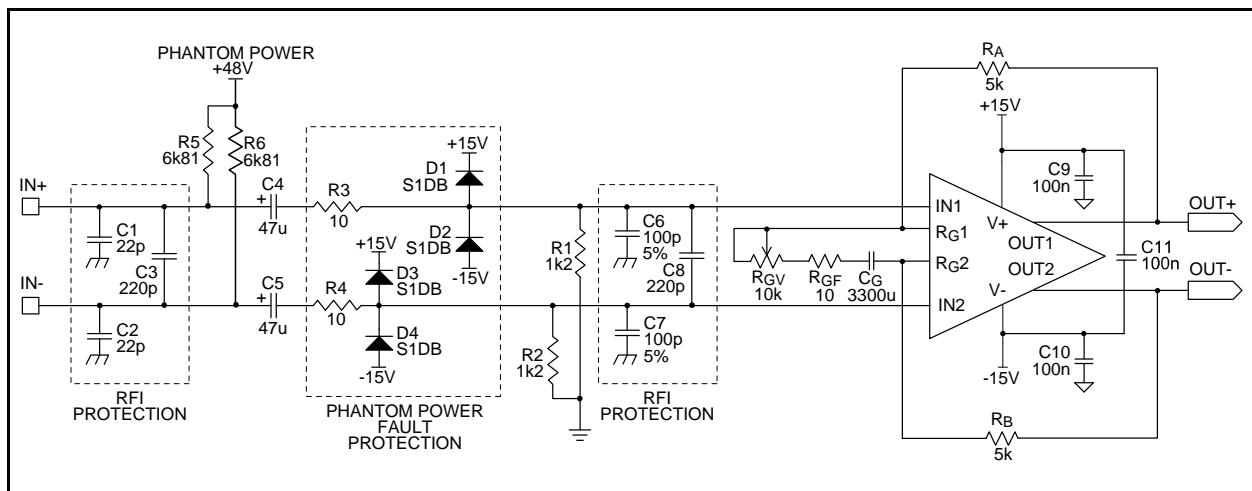


Figure 18. Typical Phantom Power Application Circuit with Variable  $R_G$  for Gain Control, AC-Coupled  $R_G$

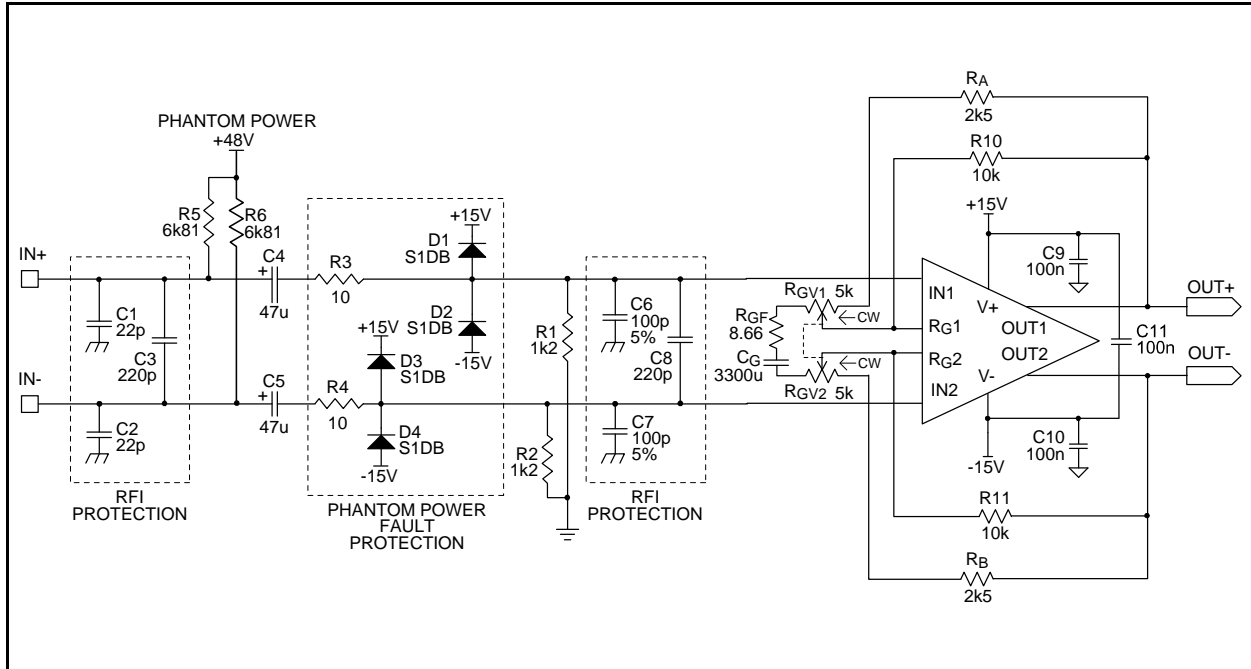


Figure 19. Typical Phantom Power Application Circuit With Variable  $R_A$ ,  $R_B$  and  $R_G$  for Gain Control, ac-Coupled  $R_G$

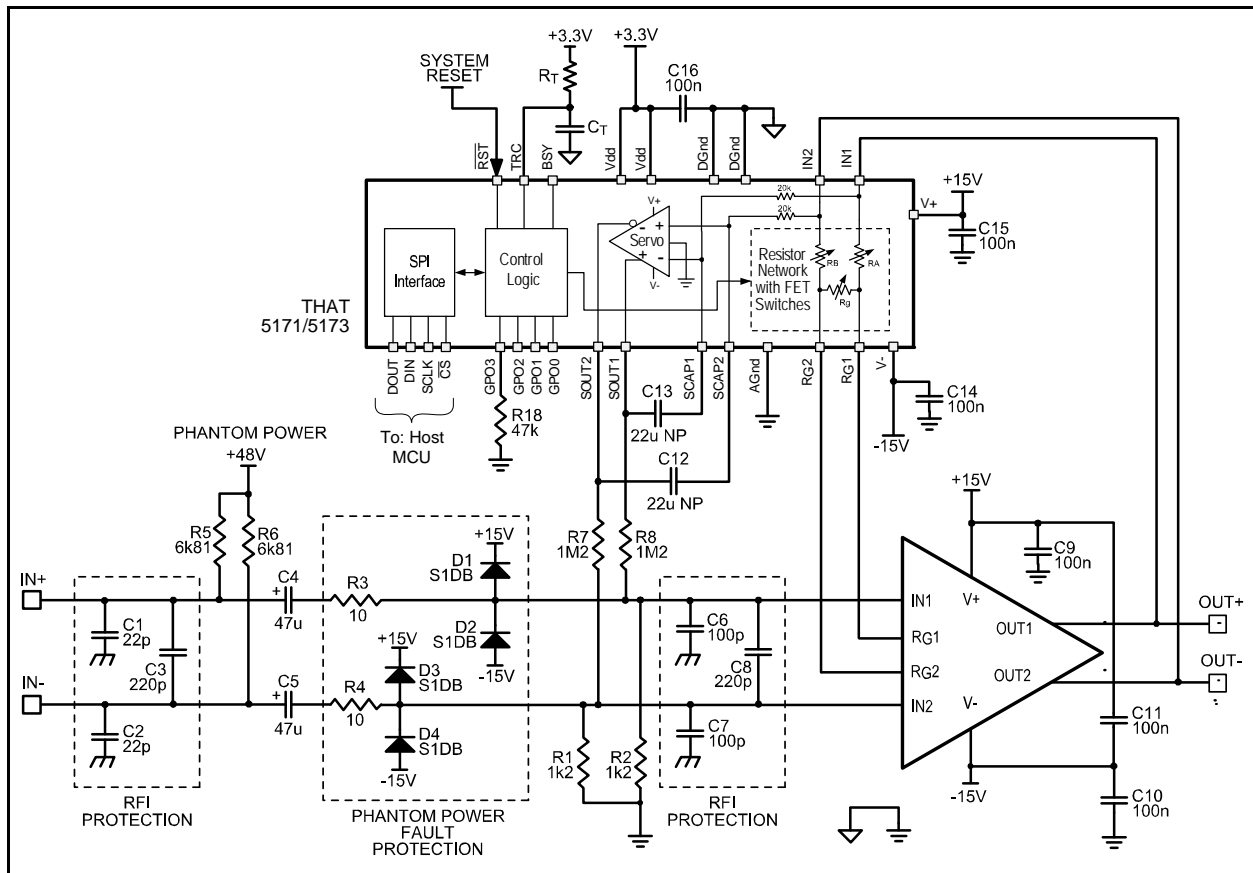


Figure 20. Typical Phantom Power Application Circuit With Digital Gain Control

## Output Circuit Recommendations

As mentioned earlier, the THAT1583 has common-mode gain of unity, regardless of its differential gain. It also has a common-mode offset of approximately one diode drop. Common-mode input signals are presented at the output, along with the common-mode dc offset. If these common-mode signals are not removed, they may limit dynamic range of subsequent stages.

If a single-ended output is desired, the THAT1246 offers a convenient way to remove common mode offset, convert to single-ended, and match the headroom of the 1583's output to a single-ended drive. See Figure 21.

See DN140 which contains much additional information and many alternative recommended solutions.

## Additional Resources

THAT's engineers have spent years investigating and documenting circuit topology options, component selection and reliability issues related to microphone preamplifiers. We recommend the following design notes and technical papers, which offer additional insights into microphone preamp design.

1. THAT Design Note 140 (DN140) "Input and Output Circuits for THAT Preamplifier ICs"
2. "The 48 Volt Phantom Menace," by Gary K. Hebert and Frank W. Thomas, presented at the 110th Audio Engineering Society (AES) Convention
3. "The Phantom Menace Returns" by Rosalfonso Bortoni and Wayne Kirkwood, presented at the 127th AES Convention.

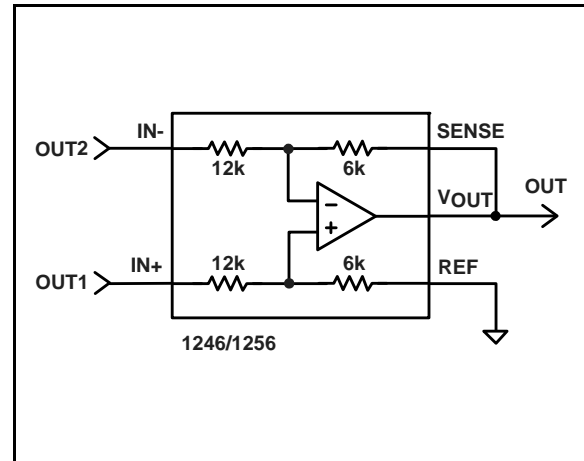


Figure 21. Simple single-ended output

4. "De-Integrating Integrated Circuit Preamps" by Les Tyler, presented at the 131st AES Convention.

DN140 is of particular interest in that this design note was intended to cover the diverse and multifaceted topic of integrating an amplifier/controller combination into a fully functioning microphone preamplifier. DN140 was written before the 1583 was released. All the circuits in DN140 reference the THAT 1570 differential preamplifier, but all the circuits and notes can be applied to the 1583 as well. The circuits presented in DN140 address common applications requirements, performance enhancements, component selection, and fault protection. DN140 should be considered an addendum to this data sheet.

## PCB Layout Information

The QFN package includes a metal thermal pad which should be soldered to the PCB. Five thermal vias should be arranged in the configuration shown in Figure 22 to provide uniform heat distribution between the top layer of the PCB to the bottom layer. The thermal pad can be left electrically floating. However if it is not electrically floating, it should be connected only to V-.

For current feedback amplifiers, stray capacitance from the R<sub>G</sub> pins (inverting inputs) to ground or power planes result in higher gains at high frequencies. This compromises common-mode rejection at high frequencies and, in extreme cases, can even lead to oscillation. Take care to avoid ground and power planes under and near R<sub>A</sub>, R<sub>B</sub>, R<sub>G</sub>, their associated pins and traces.

The input signal lines are susceptible to magnetic pickup from power supply currents, which often take the form of half-wave rectified versions of the signal. Voltage fluctuations on the supply lines can couple capacitively as well. For this reason, take care not to run power and input signal lines close and/or parallel to each other.

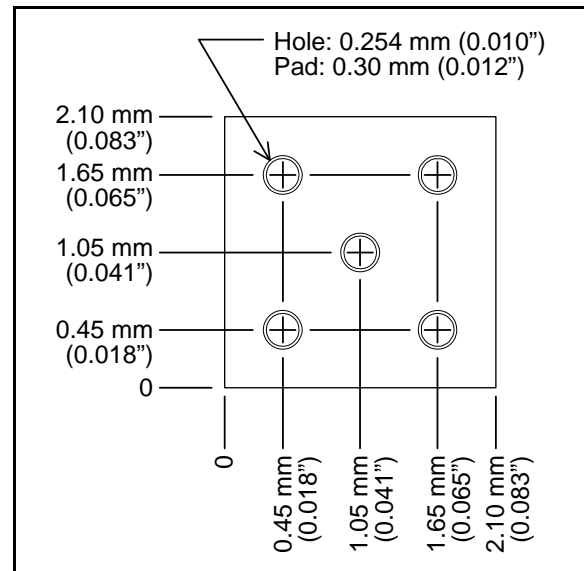


Figure 22. QFN-16 Thermal Solder Pad

### Package and Soldering Information

<b>Package Characteristics</b>						
Parameter	Symbol	Conditions	Min	Typ	Max	Units
Package Style		See Figure 23 for dimensions		16 Pin QFN		
Thermal Resistance	$\theta_{JA}$	QFN package soldered to board		110		°C/W
Environmental Regulation Compliance		Complies with January 27, 2003 RoHS requirements				
Soldering Reflow Profile		JEDEC JESD22-A113-D (250 °C)				
Moisture Sensitivity Level		MSL Above-referenced JEDEC soldering profile		3		

Pin	Pin Name	Pin Description
1	N/C*	No Internal Connection
2	OUT2	Output 2
3	OUT1	Output 1
4	N/C*	No Internal Connection
5	N/C*	No Internal Connection
6	R <sub>G</sub> 1	R <sub>G</sub> 1
7	IN1	Input 1
8	N/C*	No Internal Connection
9	N/C*	No Internal Connection
10	IN2	Input 2
11	N/C*	No Internal Connection
12	V-	Negative Supply Voltage
13	V+	Positive Supply Voltage
14	N/C*	No Internal Connection
15	R <sub>G</sub> 2	R <sub>G</sub> 2
16	N/C*	No Internal Connection
Thermal Pad	V-	Thermal Pad, Internally connected to the negative supply voltage.

Table 1. Pin Assignments

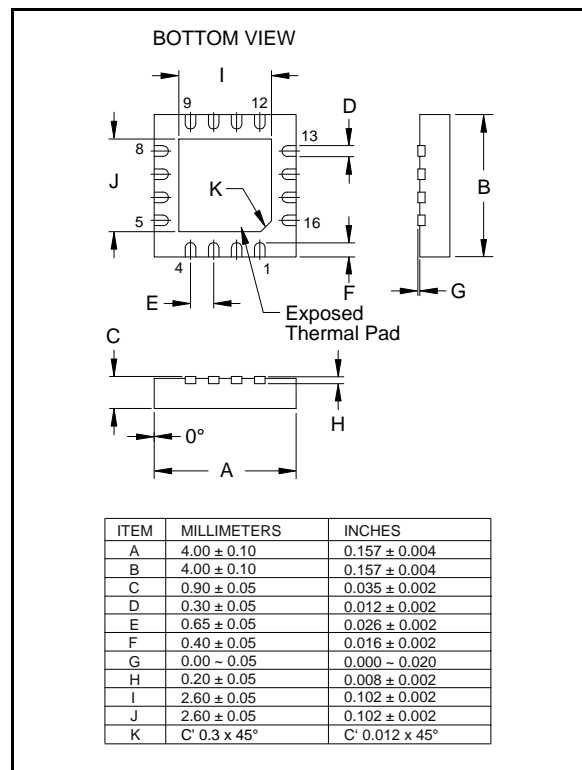


Figure 23. QFN-16 Surface Mount Package

Package	Order Number
16 pin QFN	1583N16-U

Table 2. Ordering information

\* N/C pins should be left open and not connect to other traces on the PCB.

### **Revision History**

<b>Revision</b>	<b>Date</b>	<b>Changes</b>	<b>Page</b>
00	10/24/12	Initial release	—
01	10/1/13	Added footnote to pin assignment chart.	14
02	01/26/15	Corrected the moisture sensitivity level specification.	—

## **Notes**



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