High Speed Low Power CAN Transceiver

Description

The NCV7349 CAN transceiver is the interface between a controller area network (CAN) protocol controller and the physical bus. The transceiver provides differential transmit capability to the bus and differential receive capability to the CAN controller.

The NCV7349 is a new addition to the CAN high–speed transceiver family complementing NCV734x CAN family and previous generations of CAN transceivers such as AMIS42665, AMIS3066x, etc.

Due to the wide common-mode voltage range of the receiver inputs and other design features, the NCV7349 is able to reach outstanding levels of electromagnetic susceptibility (EMS). Similarly, very low electromagnetic emission (EME) is achieved by the excellent matching of the output signals.

Features

- Compatible with the ISO 11898–5 Standard
- High Speed (up to 1 Mbps)
- V_{IO} Pin on NCV7349–3 Version Allowing Direct Interfacing with 3 V to 5 V Microcontrollers
- Very Low Current Standby Mode with Wake-up via the Bus
- Low Electromagnetic Emission (EME) and Extremely High Electromagnetic Immunity
- Very Low EME without Common-mode (CM) Choke
- No Disturbance of the Bus Lines with an Un-powered Node
- Transmit Data (TxD) Dominant Time-out Function
- Under All Supply Conditions the Chip Behaves Predictably
- Very High ESD Robustness of Bus Pins, >10 kV System ESD Pulses
- Thermal Protection
- Bus Pins Short Circuit Proof to Supply Voltage and Ground
- Bus Pins Protected Against Transients in an Automotive
- These are Pb-Free Devices

Quality

• NCV Prefix for Automotive and Other Applications Requiring Unique Site and Control Change Requirements; AEC-Q100 Qualified and PPAP Capable

Typical Applications

- Automotive
- Industrial Networks



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(*Note: Microdot may be in either location)



ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 10 of this data sheet.

Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC}	Power supply voltage	(Note 1)	4.75 (4.5)	5.25 (5.5)	V
V _{UV}	Undervoltage detection voltage on pin Vcc		2	4	V
V _{CANH}	DC voltage at pin CANH	0 < V _{CC} < 5.5 V; no time limit	-50	+50	V
V _{CANL}	DC voltage at pin CANL	0 < V _{CC} < 5.5 V; no time limit	-50	+50	V
V _{CANH,Lmax}	DC voltage at pin CANH and CANL during load dump condition	0 < V _{CC} < 5.5 V, less than one second	-	+58	V
V _{ESD}	Electrostatic discharge voltage	IEC 61000-4-2 at pins CANH and CANL	-15	15	kV
V _{O(dif)(bus_dom)}	Differential bus output voltage in dominant state	45 Ω < R _{LT} < 65 Ω	1.5	3	V
CM-range	Input common-mode range for comparator	Guaranteed differential receiver threshold and leakage current	-35	+35	V
Cload	Load capacitance on IC outputs		-	15	pF
t _{pd0}	Propagation delay (NCV7349-0 version)	See Figure 7	-	245	ns
t _{pd3}	Propagation delay (NCV7349-3 version)	See Figure 7	-	250	ns
TJ	Junction temperature		-40	150	°C

Table 1. KEY TECHNICAL CHARACTERISTICS AND OPERATING RANGES

1. In the range of 4.5 V to 4.75 V and from 5.25 V to 5.5 V the chip is fully functional; some parameters may be outside of the specification.



BLOCK DIAGRAM

*On NCV7349–0 version pin 5 is not connected. V_{IO} supply is provided by $V_{\text{CC}}.$

Figure 1. Block Diagram

TYPICAL APPLICATION







Figure 3. Application Diagram, NCV7349-3

Table 2. PIN FUNCTION DESCRIPTION

Pin	Name	Description
1	TxD	Transmit data input; low input \rightarrow Driving dominant on bus; internal pull-up current
2	GND	Ground
3	V _{CC}	Supply voltage
4	RxD	Receive data output; bus in dominant → low output
5	NC	Not connected. On NCV7349–0 only.
5	V _{IO}	Input / Output pins supply voltage. On NCV7349-3 only
6	CANL	Low-level CAN bus line (low in dominant mode)
7	CANH	High-level CAN bus line (high in dominant mode)
8	STB	Standby mode control input; internal pull-up current

FUNCTIONAL DESCRIPTION

NCV7349 has two versions which differ from each other only by function of pin 5.

NCV7349-0: Pin 5 is not connected. (see Figure 2)

NCV7349–3: Pin 5 is V_{IO} pin, which is supply pin for transceiver digital inputs/output (supplying pins TxD, RxD, STB) The V_{IO} pin should be connected to microcontroller supply pin. By using V_{IO} supply pin shared with microcontroller the I/O levels between microcontroller and transceiver are properly adjusted. This adjustment allows in applications with microcontroller supply down to 3 V to easy communicate with the transceiver. (See Figure 3)

Operating Modes

NCV7349 provides two modes of operation as illustrated in Table 3. These modes are selectable through pin STB.

Pin		Pin RxD				
STB	Mode	Low	High			
Low	Normal	Bus dominant	Bus recessive			
High	Standby	Wake-up request detected	No wake-up request detected			

Table 3. OPERATING MODES

Normal Mode

In the normal mode, the transceiver is able to communicate via the bus lines. The signals are transmitted and received to the CAN controller via the pins TxD and RxD. The slopes on the bus lines outputs are optimized to give low EME.

Standby Mode

In standby mode both the transmitter and receiver are disabled and a very low-power differential receiver monitors the bus lines for CAN bus activity. The bus lines are terminated to ground and supply current is reduced to a minimum, typically 10 μ A. When a wake-up request is detected by the low-power differential receiver, the signal is first filtered and then verified as a valid wake signal after a time period of t_{wake}, the RxD pin is driven low by the transceiver to inform the controller of the wake-up request.

V_{IO} Supply pin

The V_{IO} pin available only on NCV7349–3 version should be connected to microcontroller supply pin. By using V_{IO} supply pin shared with microcontroller the I/O levels between microcontroller and transceiver are properly adjusted. See Figure 3. Pin V_{IO} on NCV7349–3 does not provide the internal supply voltage for low–power differential receiver of the transceiver. Detection of wake–up request is not possible when there is no supply voltage on pin V_{CC}.

Wake-up

When a valid wake–up (dominant state longer than t_{wake}) is received during the standby mode the RxD pin is driven low. The wake–up detection is not latched: RxD returns to High state after $t_{dwakedr}$ when the bus signal is released back to recessive – see Figure 4.



Figure 4. NCV7349 Wake-up Behavior

Over-temperature Detection

A thermal protection circuit protects the IC from damage by switching off the transmitter if the junction temperature exceeds a value of approximately 170°C. Because the transmitter dissipates most of the power, the power dissipation and temperature of the IC is reduced. All other IC functions continue to operate. The transmitter off–state resets when the temperature decreases below the shutdown threshold and pin TxD goes high. The thermal protection circuit is particularly needed when a bus line short circuits.

TxD Dominant Time-out Function

A TxD dominant time–out timer circuit prevents the bus lines being driven to a permanent dominant state (blocking all network communication) if pin TxD is forced permanently low by a hardware and/or software application failure. The timer is triggered by a negative edge on pin TxD. If the duration of the low–level on pin TxD exceeds the internal timer value $t_{dom(TxD)}$, the transmitter is disabled, driving the bus into a recessive state. The timer is reset by a positive edge on pin TxD.

This TxD dominant time–out time $(t_{dom(TxD)})$ defines the minimum possible bit rate to 15 kbps.

Fail Safe Features

A current–limiting circuit protects the transmitter output stage from damage caused by accidental short circuit to either positive or negative supply voltage, although power dissipation increases during this fault condition.

Undervoltage on V_{CC} pin prevents the chip sending data on the bus when there is not enough V_{CC} supply voltage. After supply is recovered TxD pin must be first released to high to allow sending dominant bits again. Recovery time from undervoltage detection is equal to $t_{d(stb-nm)}$ time.

 V_{IO} supply dropping below V_{UVDVIO} undervoltage detection level will cause the transceiver to disengage from the bus (no bus loading) until the V_{IO} voltage recovers (NCV7349–3 version only).

The pins CANH and CANL are protected from automotive electrical transients (according to ISO 7637; see Figure 7). Pins TxD and STB are pulled high internally should the input become disconnected. Pins TxD, STB and RxD will be floating, preventing reverse supply should the V_{IO} supply be removed.

ELECTRICAL CHARACTERISTICS

Definitions

All voltages are referenced to GND (pin 2). Positive currents flow into the IC. Sinking current means the current is flowing into the pin; sourcing current means the current is flowing out of the pin.

ABSOLUTE MAXIMUM RATINGS

Table 4. ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Conditions	Min.	Max.	Unit
V _{SUP}	Supply voltage V_{CC} , V_{IO}		-0.3	+6	V
V _{CANH}	DC voltage at pin CANH	0 < V _{CC} < 5.5 V; no time limit	-50	+50	V
V _{CANL}	DC voltage at pin CANL	$0 < V_{CC} < 5.5 V$; no time limit	-50	+50	V
V _{IO}	DC voltage at pin TxD, RxD, STB		-0.3	6	V
V _{esd}	Electrostatic discharge voltage at all pins	(Note 2) (Note 3)	-6 500	6 500	kV V
	Electrostatic discharge voltage at CANH and CANL pins	(Note 4)	-10	10	kV
V _{schaff}	Transient voltage	(Note 5)	-150	100	V
Latch-up	Static latch-up at all pins	(Note 6)		150	mA
T _{stg}	Storage temperature		-55	+150	°C
T _A	Ambient temperature		-40	+125	°C
TJ	Maximum junction temperature		-40	+170	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Standardized human body model electrostatic discharge (ESD) pulses in accordance to EIA–JESD22. Equivalent to discharging a 100 pF capacitor through a 1.5 kΩ resistor.

3. Standardized charged device model ESD pulses when tested according to ESD-STM5.3.1-1999.

4. System human body model electrostatic discharge (ESD) pulses. Equivalent to discharging a 150 pF capacitor through a 330 Ω resistor referenced to GND.

5. Pulses 1, 2a, 3a and 3b according to ISO 7637 part 3. Indicative values based on structural similarity to NCV7340 where results were verified by external test house.

6. Static latch-up immunity: Static latch-up protection level when tested according to EIA/JESD78.

Table 5. THERMAL CHARACTERISTICS

Symbol Parameter		Conditions	Value	Unit
$R_{\theta JA_1}$	Thermal Resistance Junction-to-Air, 1S0P PCB (Note 7)	Free air	125	K/W
$R_{\theta JA_2}$	Thermal Resistance Junction-to-Air, 2S2P PCB (Note 8)	Free air	75	K/W

7. Test board according to EIA/JEDEC Standard JESD51-3, signal layer with 10% trace coverage

8. Test board according to EIA/JEDEC Standard JESD51-7, signal layers with 10% trace coverage

ELECTRICAL CHARACTERISTICS

Table 6. CHARACTERISTICS (V_{CC} = 4.75 V to 5.25 V; V_{IO} = 2.8 V to 5.5 V (NCV7349–3 only); T_J = –40 to +150°C; R_{LT} = 60 Ω unless specified otherwise. On chip versions without V_{IO} pin, reference voltage for all digital inputs and outputs is V_{CC} instead of V_{IO} .)

Symbol	Parameter	Conditions	Min	Тур	Мах	Unit	
SUPPLY (Pin	SUPPLY (Pin V _{CC})						
I _{CC}	Supply current	Dominant; $V_{TxD} = 0 V$ Recessive; $V_{TxD} = V_{IO}$	-	48 6	75 10	mA	
Iccs	Supply current in standby mode	$T_J \le 100^{\circ}C$, (Note 9)	I	10	15	μΑ	
V _{UVDVCC}	Undervoltage detection voltage on V_{CC} pin		2	3	4	V	

9. Values based on design and characterization, not tested in production

Table 6. CHARACTERISTICS (V _{CC} = 4.75 V to 5.25 V; V _{IO} = 2.8 V to 5.5 V (NCV7349−3 only); T _J = −40 to +150°C; R _{LT} =	60 Ω
unless specified otherwise. On chip versions without V _{IO} pin, reference voltage for all digital inputs and outputs is V _{CC} instead o	of V _{IO} .)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
SUPPLY (pin	V _{IO}) on NCV7349–3 Version Only		•	•	•	
V _{IO}	Supply voltage on pin V _{IO}		2.8	-	5.5	V
I _{IOS}	Supply current on pin V_{IO} in standby mode	Standby mode	-	1	-	μΑ
I _{IONM}	Supply current on pin V _{IO} in normal mode	Dominant; $V_{TxD} = 0 V$ Recessive; $V_{TxD} = V_{IO}$	-	-	1 0.2	mA
VUVDVIO	Undervoltage detection voltage on V _{IO} pin		1.3	-	2.7	V
TRANSMITTE	R DATA INPUT (Pin TxD)					
V _{IH}	High-level input voltage	Output recessive	2.0	-	V _{IO}	V
V _{IL}	Low-level input voltage	Output dominant	-0.3	-	+0.8	V
I _{IH}	High-level input current	$V_{TxD} = V_{IO}$	-5	0	+5	μA
۱ _{۱L}	Low-level input current	$V_{TxD} = 0 V$	-350	-200	-	μA
Ci	Input capacitance	(Note 9)	-	5	10	pF
TRANSMITTE	R MODE SELECT (Pin STB)					
V _{IH}	High-level input voltage	Standby mode	2.0	-	V _{IO}	V
V _{IL}	Low-level input voltage	Normal mode	-0.3	-	+0.8	V
IIH	High-level input current	V _{STB} = V _{IO}	-5	0	+5	μA
Ι _{ΙL}	Low-level input current	V _{STB} = 0 V	-10	-4	-1	μA
Ci	Input capacitance	(Note 9)	-	5	10	pF
RECEIVER DA	ATA OUTPUT (Pin RxD)		_		-	-
I _{ОН}	High-level output current	Normal mode, V _{RxD} = V _{IO} – 0.4 V	-1	-0.4	-0.1	mA
I _{OL}	Low-level output current	V _{RxD} = 0.4 V	1.6	6	12	mA
V _{OH}	High-level output voltage	Standby mode, $I_{RxD} = -100 \ \mu A$	V _{IO} – 1.1	V _{IO} – 0.7	V _{IO} – 0.4	V
BUS LINES (F	Pins CANH and CANL)					
Vo(reces) (norm)	Recessive bus voltage on pins CANH and CANL	V _{TxD} = V _{IO} ; no load; normal mode	2.0	2.5	3.0	V
V _{o(reces)} (stby)	Recessive bus voltage on pins CANH and CANL	V _{TxD} = V _{IO} ; no load; standby mode	-100	0	100	mV
I _{o(reces)} (CANH)	Recessive output current at pin CANH	–35 V < V _{CANH} < +35 V; 0 V < V _{CC} < 5.25 V	-2.5	-	+2.5	mA
I _{o(reces)} (CANL)	Recessive output current at pin CANL	–35 V < V _{CANL} < +35 V; 0 V < V _{CC} < 5.25 V	-2.5	-	+2.5	mA
I _{LI(CANH)}	Input leakage current to pin CANH	$\begin{array}{l} 0 \; \Omega < R(V_{CC} \; to \; GND) < 1 \; M\Omega \\ V_{CANL} = V_{CANH} = 5 \; V \end{array}$	-10	0	10	μΑ
I _{LI(CANL)}	Input leakage current to pin CANL	$\begin{array}{l} 0 \; \Omega < R(V_{CC} \; \text{to GND}) < 1 \; M\Omega \\ V_{CANL} = V_{CANH} = 5 \; V \end{array}$	-10	0	10	μΑ
V _{o(dom)} (CANH)	Dominant output voltage at pin CANH	V _{TxD} = 0 V	3.0	3.6	4.25	V
V _{o(dom)} (CANL)	Dominant output voltage at pin CANL	V _{TxD} = 0 V	0.5	1.4	1.75	V
V _{o(dif)} (bus_dom)	Differential bus output voltage (V _{CANH} – V _{CANL})	V _{TxD} = 0 V; dominant; 45 Ω < R _{LT} < 65 Ω	1.5	2.25	3.0	V
Vo(dif) (bus_rec)	Differential bus output voltage (V _{CANH} - V _{CANL})	$V_{TxD} = V_{IO}$; recessive; no load	-120	0	+50	mV
I _{o(sc)} (CANH)	Short circuit output current at pin CANH	$V_{CANH} = 0 V; V_{TxD} = 0 V$	-100	-70	-45	mA

9. Values based on design and characterization, not tested in production

Symbol	Parameter	Conditions	Min	Тур	Мах	Unit	
BUS LINES (Pins CANH and CANL)							
I _{o(sc)} (CANL)	Short circuit output current at pin CANL	V _{CANL} = 36 V; V _{TxD} = 0 V	45	70	100	mA	
Vi(dif)R (th)	Differential receiver threshold voltage – Dominant to Recessive (see Figure 6)	-2 V < V _{CANL} < +7 V; -2 V < V _{CANH} < +7 V	0.5	0.6	0.7	V	
V _{i(dif)D (th)}	Differential receiver threshold voltage – Recessive to Dominant (see Figure 6)	-2 V < V _{CANL} < +7 V; -2 V < V _{CANH} < +7 V	0.7	0.8	0.9	V	
VihcmR(dif) (th)	Differential receiver threshold voltage – Dominant to Recessive (see Figure 6)	–35 V < V _{CANL} < +35 V; –35 V < V _{CANH} < +35 V	0.4	-	0.8	V	
V _{ihcmD(dif)} (th)	Differential receiver threshold voltage – Recessive to Dominant (see Figure 6)	–35 V < V _{CANL} < +35 V; –35 V < V _{CANH} < +35 V	0.6	-	1	V	
VihcmD12(dif) (th)	Differential receiver threshold voltage – Both transitions (see Figure 6)	–12 V < V _{CANL} < +12 V; –12 V < V _{CANH} < +12 V	0.5	-	0.9	V	
V _{i(dif)} (hys)	Differential receiver input voltage hys- teresis	-2 V < V _{CANL} < +7 V; -2 V < V _{CANH} < +7 V	100	200	300	mV	
V _{i(dif)} (th)_STDBY	Differential receiver threshold voltage in standby mode	–12 V < V _{CANL} < +12 V; –12 V < V _{CANH} < +12 V	0.4	0.8	1.15	V	
R _{i(cm)} (CANH)	Common-mode input resistance at pin CANH		15	26	37	kΩ	
R _{i(cm)} (CANL)	Common-mode input resistance at pin CANL		15	26	37	kΩ	
R _{i(cm) (m)}	Matching between pin CANH and pin CANL common mode input resistance	V _{CANH} = V _{CANL}	-3	0	+3	%	
R _{i(dif)}	Differential input resistance		25	50	75	k	
C _{i(CANH)}	Input capacitance at pin CANH	V _{TxD} = V _{IO} ; (Note 9)	-	-	30	pF	
C _{i(CANL)}	Input capacitance at pin CANL	V _{TxD} = V _{IO} ; (Note 9)	-	-	30	pF	
C _{i(dif)}	Differential input capacitance	V _{TxD} = V _{IO} ; (Note 9)	-	3.75	10	pF	
THERMAL SH	UTDOWN						
T _{J(sd)}	Shutdown junction temperature	Junction temperature rising	150	170	185	°C	
TIMING CHAR	ACTERISTICS (see Figure 5 and Figure 8	3)					
t _{d(TxD-BUSon)}	Delay TxD to bus active	C _i = 100 pF between CANH to CANL	_	50	-	ns	
t _{d(TxD-BUSoff)}	Delay TxD to bus inactive	C _i = 100 pF between CANH to CANL	_	60	-	ns	
t _{d(BUSon-RxD)}	Delay bus active to RxD	C _{RxD} = 15 pF	_	60	-	ns	
t _{d(BUSoff-RxD)}	Delay bus inactive to RxD	C _{RxD} = 15 pF	_	60	-	ns	
t _{pd}	Propagation delay TxD to RxD (NCV7349-0 version)	C _i = 100 pF between CANH to CANL	-	125	245	ns	
	Propagation delay TxD to RxD (NCV7349–3 version)	C _i = 100 pF between CANH to CANL	-	130	250	ns	
t _{d(stb-nm)}	Delay standby mode to normal mode		5	8	20	μs	
t _{wake}	Dominant time for wake-up via bus		0.5	2.5	5	μs	
t _{dwakerd}	Delay to flag wake event (recessive to dominant transitions)	Valid bus wake-up event, C _{RxD} = 15 pF	1	4.5	10	μs	
t _{dwakedr}	Delay to flag wake event (dominant to recessive transitions)	Valid bus wake-up event, C _{RxD} = 15 pF	0.5	3.3	7	μs	
t _{dom(TxD)}	TxD dominant time for time-out	V _{TxD} = 0 V	1.2	2.6	4	ms	

Table 6. CHARACTERISTICS (V_{CC} = 4.75 V to 5.25 V; V_{IO} = 2.8 V to 5.5 V (NCV7349–3 only); T_J = –40 to +150°C; R_{LT} = 60 Ω unless specified otherwise. On chip versions without V_{IO} pin, reference voltage for all digital inputs and outputs is V_{CC} instead of V_{IO} .)

9. Values based on design and characterization, not tested in production

MEASUREMENT SETUPS AND DEFINITIONS



*On NCV7349–3 V_{CC} is replaced by V_{IO}

Figure 5. Transceiver Timing Diagram



Figure 6. Hysteresis of the Receiver



Figure 7. Test Circuit for Automotive Transients



Figure 8. Test Circuit for Timing Characteristics

DEVICE ORDERING INFORMATION

Part Number	Description	Temperature Range	Package	Shipping [†]
NCV7349D10R2G	High Speed Low Power CAN Transceiver for the Japanese Market		SOIC 150 8 GREEN	3000 / Tape &
NCV7349D13R2G	High Speed Low Power CAN Transceiver for the Japanese Market with V _{IO} pin (available in 2015)	−40°C to +125°C	MS-012) (Pb-Free)	Reel

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

PACKAGE DIMENSIONS



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